

## ASTMO-SCIENCE CORPORATION

## OPERATION AND MAINTENANCE

 INSTRUCTIONSFOR
MODEL RD-378/U
RECORDER/REPRODUCER
15 NOVEMBER 1972


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## SAFETY SUMMARY

The following are general safety precautions that are not related to any specific procedures and therefore do not appear elsewhere in this publication. These are recommended precautions that personnel must understand and apply during many phases of operation and maintenance.

## KEEP AWAY FROM LIVE CIRCUITS

Operating personnel must at all times observe all safety regulations. Do not replace components or make adjustments inside the equipment with the high voltage supply turned on. Under certain conditions, dangerous potentials may exist when the power control is in the off position, due to charges retained by capacitors. To avoid casualties, always remove power and discharge and ground a circuit before touching it.

## DO NOT SERVICE OR ADJUST ALONE

Under no circumstances should any person reach into or enter the enclosure for the purpose of servicing or adjusting the equipment except in the presence of someone who is capable of rendering aid.

RESUSCITATION
Personnel working with or near high voltages should be familiar with modern methods of resuscitation. Such information may be obtained from the Bureau of Medicine and Surgery.

The following warning appears in the text in this volume, and is repeated here for emphasis.

## WARNING

The unit operates at dangerous voltages. Turn off main circuit breaker for all procedures that do not require power to the unit. For those procedures that require power to the unit, observe all precautions normally followed in using and testing electronic equipment. (Page 4-1).


Figure 1-1. Magnetic Tape Recorder/Reproducer Model RD378/U.

## CHAPTER 1

## GENERAL INFORMATION

## 1-1. INTRODUCTION.

1-2. This technical manual provides installation, operation, and field level maintenance information for the Model RD378/U Magnetic Tape Recorder/ Reproducer, manufactured by AstroScience Corporation, South El Monte, California. The RD378/U is a selfcontained, 14 -track recorder/reproducer providing seven tape speeds of $1-7 / 8$ through $120-\mathrm{ips}$, and may be configured with either wideband direct/ analog ( 2.0 MHz at 120 ips ) or wideband Group I FM signal electronics, or any combination of both.

1-3. Signal electronics are provided in two overlapping speed ranges of $1-7 / 8,3-3 / 4,7-1 / 2,15,30$, and 60 ips or $3-3 / 4,7-1 / 2,15,30,60$, and 120 ips depending upon application requirements. The tape transport will operate at all seven electrically selectable tape speeds, without modification or mechanical component changes. Direct/analog and FM signal electronics are directly interchangeable, and may be intermixed in any combination of track assignments. Bi-directional tape metering is provided by a dualdifferential capstan drive and phaselocked capstan servo. Separate servooperated reel motors provide uniform tape tension, and gentle tape handling, in all modes of operation.

## 1-4. PURPOSE.

1-5. The RD378/U is a portable
recorder/reproducer designed for data acquisition and reproduction in semihostile environments encountered in sub-surface craft, shipboard, aircraft and land vehicle applications. Typical uses include communications, instrumentation, signal analysis, and similar uses requiring information storage on l-inch-wide magnetic tape.

## 1-6. SCOPE

1-7. Information in this technical manual is intended for use by U.S. Navy personnel engaged in operation and maintenance of the unit.

Chapter 2: Provides operating instructions.

Chapter 3: Provides functional information.

Chapter 4: Describes preventive maintenance to be performed on a scheduled basis.

Chapter 5: Provides troubleshooting information and procedures to be performed prior to corrective maintenance. (Functional dependency within the unit is the basis of troubleshooting procedures.)

Chapter 6: Describes field corrective maintenance.

Chapter 7: Parts List.
Chapter 8: Provides procedures and
supporting illustrations for installation of the unit.

1-8. SUPERSEDURE DATA.
1-9. This technical manual is the basic issue for the unit and does not supersede any prior publications.

## 1-10. APPLICABILITY.

1-11. This manual applies to the models, serial numbers, and configuration given below.

## 1-12. MODEL.

1-13. This technical manual applies to Astro-Science Corporation Magnetic Tape Recorder/Reproducer Model RD378/U.

## 1-14. SERIAL NUMBERS.

l-15. The unit serial numbers covered by this manual are Al through A7.

1-16. CONFIGURATIONS COVERED.
1-17. The units covered by this manual are all of the same configuration.

1-18. INTERFACE RELATIONSHIP OF TECHNICAL MANUAL TO OTHER PUBLICATIONS.

1-19. This technical manual is used with the technical manual for Sonar Receiving Set AN/SQR-15.

1-20. RELATIONSHIP OF UNIT TO SYSTEM OR OTHER EQUIPMENT.

1-21. This equipment functions
within Sonar Receiving Set AN/SQR-15, interfacing with Tape Recording Switching Unit, Chesapeake Instrument Corporation, Part No. 1083D5238.

## l-22. EQUIPMENT DESCRIPTION.

1-23. The RD378/U is designed for mounting within a standard 19 -inch electronic rack. The unit is selfcontained and requires only a power source and input data cabling for normal operation. The dust cover and tape transport assembly are hinged so that the unit can be opened for tape installation and maintenance. With the unit open, all parts are accessible for maintenance and testing purposes without removing the unit from the rack. The unit has an internal cooling fan. Overload protection is provided by fuses and a main power circuit breaker. Functionally, the unit is capable of operation in two modes: record and reproduce. The direct reproduce electronics are equalized for optimum phase response and amplitude equalized for flat response ( $\pm 3 \mathrm{db}$ ) over six operating speeds; 1-7/8 through 60 or $3-3 / 4$ through $120 \mathrm{ips}$. The dual differential capstan drive and a phase-lock capstan servo provide forward and reverse capability at all seven selectable tape speeds. The unit can be operated at $1-7 / 8,3-3 / 4,7-1 / 2,15,30,60$, and 120 ips. Fast wind and fast rewind are accomplished at 240 ips . Servooperated reel motors provide uniform tape tension and gentle tape handling in all modes of operation. All operator controls (except SPEED SELECT, located on the transport assembly) are conveniently located on the front panel of the reproduce amplifier module. These controls include RECORD, FORWARD, REVERSE, STOP, FAST WIND
FAST REWIND, TRANSPORT POWER,and MAIN POWER. The control panelalso has a tape supply indicator, andvoltage check control and meter. Thestatus panel indicates speed selected,end-of-tape, and tape break conditions.
1-24. REFERENCE DATA.
1-25. The following tables provide descriptive and functional character- istic data.
Table 1-1. Nameplate Data
Table 1-2. Functional Characteristics
Table 1-3. Capabilities and
Limitations
Table 1-4. Rated Outputs
Table 1-5. Environmental Character-istics
1-26. EQUIPMENT, ACCESSORIES,
AND DOCUMENTS SUPPLIED.
1-27. Table 1-6 provides the equip-ment, accessories, and documentssupplied with the unit.
1-28. EQUIPMENT AND PUBLICA- TIONS REQUIRED BUT NOT SUPPLIED.
1-29. Table 1-7 provides a listing ofall tools, test equipment, and pub-lications required but not supplied tooperate the unit.
1-30. FIELD AND/OR FACTORY
CHANGES.
1-31. No field or factory changesare applicable to the unit.

TABLE 1-1. NAMEPLATE DATA

| MANUFACTURER | TYPE | MODEL | $\begin{array}{c}\text { COMPONENT } \\ \text { IDENTIFICATION }\end{array}$ |
| :---: | :---: | :---: | :---: |
| ASTRO-SCIENCE CORPORATION | $\begin{array}{l}\text { RECORDER- } \\ \text { REPRODUCER, }\end{array}$ | RD378/U | 95002661 |
| MAGNETIC |  |  |  |
| TAPE |  |  |  |$] .$|  |
| :--- |

TABLE 1-2. FUNCTIONAL CHARACTERISTICS


TABLE 1-3. CAPABILITIES AND LIMITATIONS

## Tape Speeds

Operating

FAST WIND/REWIND
Data Record/Reproduce Channels
Recording Methods

Tape Type

Operational Direction

Start Time
Stop Time
Jitter

Speed Accuracy
End-of-Tape,
Tape Remaining,
Tape Break Sensors

Local Controls
$1-7 / 8,3-3 / 4,7-1 / 2,15,30$, 60 , and $120 \mathrm{ips} /$

240 ips.

## 14

Direct and FM (Digital available as an option).

3 M type $888 / 900$ or equivalent; 9200 ft . of one-inch-wide tape per 14-inch reel.

Operates in either forward or reverse direction.

Less than 5 seconds at 60 ips .
Less than 3 seconds from 60 ips .
Less than 0.5 usec in a 200 usec interval on any track at 60 ips , without tape servo.
$\pm 0.2 \%$ of nominal.
Photoelectric sensors which stop transport in event of tape breakage or end of tape. Indicators show amount of tape remaining on supply reel and tape break or end-of-tape condition.

MAIN POWER on/off, TRANSPORT POWER on/off, SPEED SELECT, FORWARD, REVERSE, RECORD, FAST WIND, FAST REWIND, STOP.

TABLE 1-3. CAPABILITIES AND LIMITATIONS (Cont'd)

## Remote Controls

Magnetic Heads Track Geometry

Provision for all local control functions via J102. Customer supplies remote control panel and switching circuitry.

Width, 0.050 inches +0.005 inches Spacing, 0.070 inches, Interlace distance, 1.500 inches $\pm 0.001$ inches.

## TABLE 1-4. RATED OUTPUTS

| Data Signal Input Level |  |
| :---: | :--- |
| Direct | 0.20 to 10 volts rms, adjustable, <br> 1.0 volt rms nominal. |
| FM | 1.0 to 10.0 volts peak-to-peak, <br> 1.0 volts rms nominal |
| Data Signal Output Level | Direct |
| (1.0 to volt rms nominal at normal <br> record level). |  |
| FM Adjustable (2 to 4 volts peak-to- |  |
| peak with full deviation). |  |$\quad$| 500 watts (normal). |
| :--- |

## TABLE 1-5. ENVIRONMENTAL CHARACTERISTICS

| Operating Temperature: | $-18^{\circ} \mathrm{C}$ to $+54^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Relative Humidity: | $15 \%$ to $95 \%$ |
| Mechanical Shock: |  |
| Operating: | $15 \mathrm{~g}, 11 \mathrm{~ms}$ |
| Crash Safety: | 30 g |
| Operating Vibration: | $(0.8 \%$ peak-to-peak flutter at  <br>  60 ips). <br> 5 to $15 \mathrm{~Hz}:$ 0.06 inches double amplitude <br> 16 to $25 \mathrm{~Hz}:$ 0.04 inches double amplitude <br> 26 to $35 \mathrm{~Hz}:$ 0.02 inches double amplitude |

TABLE 1-6. EQUIPMENT, ACCESSORIES, AND DOCUMENTS SUPPLIED


TABLE 1-7. EQUIPMENT AND PUBLICATIONS
REQUIRED BUT NOT SUPPLIED

| Category | Recommended Equipment | Alternate Equipment | Equipment Test <br> Parameters | Application |
| :---: | :---: | :---: | :---: | :---: |
| Sine Wave Signal Generator | $\begin{aligned} & \text { TS-382-D/U } \\ & \text { (FSC80058) } \end{aligned}$ | $\begin{gathered} \text { HP651A } \\ (\text { FSC80104) } \end{gathered}$ | 0-2 MHz | Corrective maintenance and troubleshooting. |
| Harmonic Wave Analyzer | $\begin{aligned} & \text { TS-723-C/U } \\ & (\text { FSC80058) } \end{aligned}$ | $\begin{gathered} \text { HP310A } \\ (\text { F'SC80104) } \end{gathered}$ | $\begin{aligned} & 3.125 \mathrm{kHz}- \\ & 300 \mathrm{kHz} \end{aligned}$ | Corrective maintenance and troubleshooting. |
| Vacuum Tube Voltmeter | ME-30-A/U <br> (FSC80058) | $\begin{aligned} & \text { HP400E } \\ & \text { (FSC80104) } \end{aligned}$ | $\begin{aligned} & 0-10 \mathrm{~V} \mathrm{ac} \\ & (\mathrm{rms}) \text { to } \\ & 2 \mathrm{MHz} \end{aligned}$ | Corrective maintenance and troubleshooting. |
| Square Wave Signal Generator | SG-299 C/U | $\begin{aligned} & \text { HP211A } \\ & (\text { FSC80104) } \end{aligned}$ | 50 kHz | Corrective maintenance and troubleshooting. |
| Digital DC <br> Vacuum Tube Voltmeter |  | $\begin{gathered} \text { HP3439A } \\ \text { (FSC80104) } \end{gathered}$ | $0- \pm 30 \mathrm{Vdc}$ | Corrective maintenance |
| Frequency Counter | AN/USM-245 | $\begin{gathered} \text { HP5216A } \\ \text { (FSC80104) } \end{gathered}$ | $\begin{aligned} & 2 \mathrm{kHz}- \\ & 605 \mathrm{kHz} \end{aligned}$ | Corrective maintenance |
| Oscilloscope | AN/USM-105A | Tektronix 545 with CA plug-in (FSC80009) | Display 100 kHz square wave | Corrective maintenance |
| Reference <br> Power Supply, | SCAT 4115 | HP6113A | $0-10 \mathrm{Vac}$ | Corrective maintenance |

## CHAPTER 2

## OPERATION

## 2-1. INTRODUCTION.

2-2. This chapter provides procedures for operating the RD378/U under normal and emergency conditions.

## 2-3. CONTROLS AND INDICATORS.

2-4. All local controls, except the tape SPEED SELECT switch, are located on the front panel of the reproduce amplifier module (RAM), directly below the tape transport (Figure 2-1). The tape SPEED SELECT switch is located on the left-hand side of the transport, and is accessible when the transport dust cover-door is opened (Figure 2-2). Table 2-1 lists all controls and indicators, and briefly describs the operation of each. An optional remote control unit may also be connected to the rear connector panel (J-102) to provide selection of all operational modes.

## 2-5. CIRCUIT BREAKER AND FUSE LOCATION.

2-6. The main power circuit breaker, which controls application of primary $A C$ input power to the equipment, is located directly behind the swing-out transport (Figure 2-3). Circuit protection fuses are located on the left-hand side of the tape transport, and at the rear of the RAM, as shown in Figure 2-2. Table 2-2 lists and describes the function of all fuses and circuit breakers.

## 2-7. PRELIMINARY NOTES AND PRECAUTIONS.

2-8. DIRTY HEADS OR TAPE PATH. Contamination of either the tape or the head by dust, dirt, oxide, or other foreigh substances will affect recorder performance in three ways, all of which degrade the quality of the recorded data. These ways are:

1. By lifting the tape away from the head, causing temporary signal "dropouts".
2. By becoming imbeded in the oxide surface of the tape, resulting in permanent damage to the tape. The overall effect will be the same as above, but the dropout will be permanent.
3. By accumulating at, and eventually shunting, the head gaps, causing complete and total loss of the signal.

2-9. MAGNETIZED HEADS. Data degradation resulting from magnetized record/reproduce heads is characterized by any, or all, of the following indications.

1. Reduced signal-to-noise ratio.
2. Loss of high-frequency response.
3. Increased signal distortion (especially 2 nd order harmonic distortion).
4. Permanent loss of recorded data,


Figure 2-1. Operator's Controls and Indicators


Fuse 2-2. Fuse Location (Sheet 1 of 2).


Figure 2-2. Fuse Location (Sheet 2 of 2)


Figure 2-3. Circuit Breaker and Elapsed Time Meter.

TABLE 2-1. OPERATOR CONTROLS AND INDICATORS

| Panel Designation | Position and Operating Function | Indicator Normal Operating Condition |
| :---: | :---: | :---: |
| MAIN POWER (pushbutton switch and indicator lamp) | ON -applies 117 V ac input power to unit and energizes cooling fan. <br> OFF-removes 117 V ac Power from unit and cooling fan. | Lighted Off |
| TRANSPORT POWER (pushbutton switch and indicator lamp) | ON-applies +28 V dc input power, placing unit in standby mode. OFF-removes +28 V dc power from unit. | Lighted Off |
| STOP (pushbutton switch and indicator lamp) | ON-stops tape motion by resetting memory cells for all other operating modes. OFF-occurs when another operating mode is selected | Lighted, other mode indicators off. <br> OFF. Indicator for selected mode lights. |
| FORWARD (pushbutton switch and indicator lamp) | ON-Activates transport to move tape in the forward position at selected speed. Reproduce electronics are activated for monitoring previously recorded data. OFF-occurs when STOP switch is pressed. | Lighted <br> Off. STOP indicator is lighted. |

TABLE 2-1. OPERATOR CONTROLS AND INDICATORS (CONT'D)

| Panel Designation | Position and Operating Function | Indicator Normal Operating Condition |
| :---: | :---: | :---: |
| RECORD (pushbutton switch and indicator lamp) | ON-must be pressed simultaneously with FORWARD switch. Activates record electronics to record data on tape. Reproduce electronics also are activated for monitoring of data while recording OFF-occurs when STOP switch is pressed. | Lighted <br> Off. STOP indicator is lighted. |
| REVERSE (pushbutton switch and indicator lamp) | ON-activates transport to move tape in reverse direction at selected speed. Reproduce electronics are activated for monitoring previously recorded data. OFF-occurs when STOP switch is pressed. | Lighted <br> Off. STOP indicator is lighted. |
| FAST WIND (pushbutton switch and indicator lamp) | ON-activates transport to move tape in forward direction at approximately 240 ips. <br> OFF-occurs when STOP switch is pressed. | Lighted <br> Off. STOP indicator is lighted. |
| FAST REWIND (pushbutton switch and indicator lamp) | ON-activates transport to move tape in reverse direction at approximately 240 ips <br> OFF-occurs when STOP switch is pressed. | Lighted <br> Off. STOP indicator is lighted. |

TABLE 2-1. OPERATOR CONTROLS AND INDICATORS (CONT'D)

| Panel Designation | Position and Operating Function. | Indicator Normal Operating Condition |
| :---: | :---: | :---: |
| SPEED SELECT <br> (eight-position rotary switch on tap transport) | Selects tape speeds of $1-7 / 8,3-3 / 4,7-1 / 2$, $15,30,60$, or 120 ips . Eighth position permits selection of tape speed from remote control unit. | Selected speed is displayed on STATUS INDICATOR. |
| VOLTA GE CHECK <br> (five position rotary switch, volt meter, and two test points) | Switch selects transport operating voltage of 5 V dc, 15 V dc , 18.5 V dc, 20 V dc and 28 V dc for readout on meter. Test points permit attachment of external DC voltmeter for more accurate readouts. | Meter displays selected voltage within $\pm 5 \%$. |
| STATUS INDICATOR (back-lighted display panel) | Displays selected tape speed and end-of-tape or broken tape conditions. | Lighted display of $1-7 / 8,3-3 / 4$, $7-1 / 2,15,30,60$, or 120 ips . Also displays END OF TAPE and BROKEN TAPE when those conditions exist. |
| TAPE SUPPLY (meter) | Provides visual indication of approximate amount of tape remaining on supply reel. | Displays Full, 3/4, 1/2, 1/4 or EMPTY on linear scale. <br> NOTE <br> TAPE SUPPLY meter is accurat only when using 14 -inchdiameter tape reels. |
| ELAPSED TIME (meter) | Indicates total number of hours tape has been in motion across headstack. | Digital display of total operating hours. Indicator operates only when transport is in FORWARD, RECORD, REVERSE, FAST WIND, and FAST REWIND mode of operation. |

TABLE 2-2. PROTECTIVE DEVICES

| Protective Device | Reference Designation | Location | Rating | Circuit <br> Protected |
| :---: | :---: | :---: | :---: | :---: |
| Circuit Breaker | CB1 | Inside of enclosure | 7. 5A | Overall protection |
| Fuse | 1A3F1 | Rear panel of RAM | 5.0 A | Record/reproduce amplifiers |
| Fuse | 1A3F2 | Rear panel of RAM | 5.0A | Front panel indicators; DC/DC converter; \& speed change logic |
| Fuse | 1 A 2 A 1 F 1 | Front of transport | 5.0A | Regulator |
| Fuse | 1 A 2 A 1 F 2 | Front of transport | 2.0 A | Logic |
| Fuse | 1 A 2 A 1 F 3 | Front of transport | 5.0A | Capstan |
| Fuse | 1A2A1F4 | Front of transport | 7.0A | Reel Drive |

due to tape erasure, by the magnetized headstack.

2-10. IMPROPER TAPE TYPE. The overall quality of recorded data depends, to a considerable extent, upon the type of magnetic tape utilized. To ensure optimum data quality, the manufacturer recommends the use of 3M888 tape for all direct/analog or FM recording. For applications requiring extended recording time, 3M990 tape is recommended. For digital recording, where bit packing density exceeds 10 KBI , 3 M 988 tape is recommended.

## CAUTION

Thin-base tape recommended for extended recording time is extremely fragile. Damage to tape ends may result if allowed to wind completely off reel while in the FAST WIND or FAST REWIND modes.

## 2-11. PRELIMINARY PROCEDURES.

2-12. Before proceeding to the operating procedures, a general inspection of the equipment should be made, and the following preliminary procedures performed.

1. Clean heads and tape path as described in Chapter 4, paragraph 4-8.
2. Degauss heads as described in Chapter 4, paragraph 4-9.

2-13. TAPE THREADING.
CAUTION
TRANSPORT POWER should be

OFF when loading and unloading tape, to prevent sudden reel rotation.

1. Turn transport power OFF by depressing the TRANSPORT POWER pushbutton on the front panel of the RAM.
2. Loosen the reel retainer expansion rings by rotating both reel lockingknobs CCW.
3. Manually rotate the inner supply reel hub CCW, until the small, springloaded reel alignment pin is at the top of the hub.
4. Rotate the outer take-up reel hub $C W$, until one of the three fixed turntable tabs is aligned with the springloaded alignment pin of the supply reel hub.
5. Place a full reel of tape on the supply reel hub. Guide the alignment slots on the inside center of the tape reel past the three tabs on the outer take-up reel hub, until it rests against the reel-stop flanges on the inner supply hub.
6. If necessary, rotate the reel until the spring-loaded alighment pin is positioned into one of the slots at the center of the tape reel.
7. Hold the reel firmly against the supply stop flange, and turn the inner locking knob CW, until the reel is firmly secured.
8. Remove several turns of tape from the supply reel and thread it through the transport as shown in Figure 3-16.
9. Place an empty reel on the outer take-up hub, centering one of the reel slots over the red spring-loaded alighment pin of the take-up reel hub.
10. Hold reel firmly against the three fixed turntable tabs, and turn the outer locking knob CW, until reel is firmly secured.
11. Wind several turns of tape around the hub of the empty take-up reel, being careful to avoid folding or creasing the tape.
12. Turn transport power ON by depressing the TRANSPORT POWER pushbutton.

## 2-14. OPERATING PROCEDURES.

2-15. The procedures in Table 2-3 describe initial turn on, tape speed selection, the seven operational modes, and turn off of the RD378/U Recorder/ Reproducer, and the action required by the operator. The descriptions also include the visual indications which denote proper operation. See Figure 2-1 for locations of controls.

## 2-16. EMERGENCY PROCEDURES.

2-17. Should the RD378/U develop a serious malfunction during operation, such as overheating, erratic operation, etc., the unit should be immediately de-energized by depressing the STOP, TRANSPORT POWER and MAIN POWER pushbuttons - in that order. If another unit is available, operations should be transferred to that equipment until the cause of the malfunction can be determined and corrected.

TABLE 2-3. OPERATING PROCEDURES


TABLE 2-3. OPERATING PROCEDURES (CONT'D)

| PROCEDURE | DESCRIPTION | STEPS |
| :---: | :---: | :---: |
| c. Standby Mode | The STANDBY mode disables the transport while loading and unloading tape. In this mode, all transport functions are inoperative, and the mechanical brakes are engaged to prevent reel rotation. | (continued) <br> 1. Open the dust cover-door to gain access to the tape SPEED SELECT switch, located at the upper left-hand corner of the tape transport. (Fig. 2-2) <br> 2. Select the desired tape speed (1-7/8 through 120 ips ) <br> NOTE <br> When SPEED SELECT switch is positioned to the REMOTE setting, tape speed may be selected from a remote control unit, connected to J102 at the rear of the equipment. <br> 1. Momentarily depress the MAIN POWER pushbutton. Pushbutton should light. (main crkt breaker, inside enclosure, must be ON) <br> 2. All other mode indicators, including TRANSPORT POWER, should be OFF. If not, momentarily depress the TRANSPORT POWER pushbutton. |

TABLE 2-3. OPERATING PROCEDURES (CONT'D)


TABLE 2-3. OPERATING PROCEDURES (CONT'D)

| PROCEDURE | DESCRIPTION | STEPS |
| :---: | :---: | :---: |
| f. RECORD Mode | The RECORD mode is selected to record data on tape. In the RECORD mode, tape will move in the forward direction at a fixed speed, selected by the TAPE SPEED select switch. Reproduce electronics are energized to permit monitoring during record operations. | 1. The STOP mode should be selected prior to selecting the RECORD mode. The RD$378 / \mathrm{U}$ will not record data in the REVERSE mode. <br> 2. Simultaneously depress both the FORWARD and RECORD pushbuttons. Both indicators will light, and all other mode indicators will be extinguished. Both TRANSPORT POWER and MAIN POWER indicators will remain lighted. |
| g. REVERSE Mode | The REVERSE mode is used primarily as an aid to search a pre-recorded tape for a specific signal data, which may have been passed over in the FORWARD mode. In the REVERSE mode, tape will move in the reverse direction at a fixed speed, selected by the TAPE SPEED select switch. | 1. The STOP mode should be selected, prior to selecting the REVERSE mode. <br> 2. Momentarily depress the REVERSE pushbutton. The REVERSE indicator will light, and all other mode indicators will be extinguished. Both the TRANSPORT POWER and MAIN POWER indicators will remain lighted. |

TABLE 2-3. OPERATING PROCEDURES (CONT'D)

| PROCEDURE | DESCRIPTION | STEPS |
| :---: | :---: | :---: |
| h. FAST WIND | When the FAST WIND mode is selected, tape will be wound from the SUPPLY reel to the TAKE-UP reel at approximately $240-$ IPS. The tape will stop automatically before running completely off the supply reel, to preclude the necessity of rethreading the transport. | 1. The STOP mode should be selected, prior to selecting the FAST WIND mode. <br> 2. Momentarily depress the FAST WIND pushbutton. The FAST WIND indicator will light, and all other mode indicators will be extinguished. Both the TRANSPORT POWER and MAIN POWER indicators will remain lighted. |
| i. FAST REWIND | When the FAST REWIND mode is selected, tape will be wound from the TAKE-UP reel to the SUPPLY reel at approximately 240-IPS. The tape will not stop automatically, before running completely off the take-up reel. | 1. The STOP mode should be selected, prior to selecting the FAST REWIND mode, to ensure gentle tape handling. <br> 2. Momentarily depress the FAST REWIND pushbutton. The FAST REWIND indicator will light, and all other mode indicators will be extinguished. Both the TRANSPORT POWER and MAIN POWER indicators will remain lighted. |

TABLE 2-3. OPERATING PROCEDURES (CONT'D)

| PROCEDURE | DESCRIPTION | STEPS |
| :---: | :---: | :---: |
| j. Equipment Turn Off | This procedure describes the steps to be taken when turning off the Recorder/Reproducer. | 1. Press the STOP pushbutton The tape should come to a smooth stop, with tension maintained across the heads. The STOP indicator should be lighted. |
|  |  | 2. Press the TRANSPORT POWER pushbutton. The TRANSPORT POWER indicator and STOP indicator should both go out. <br> 3. To completely de-energize the unit ( $i_{0}$ e., remove power from the 28 V power supply and blower fan) press the MAIN POWER pushbutton. <br> 4. Open the dust cover-door, loosen the two transport latches (see NOTE, para 2-11), swing the transport to the fully open position, and position the main power circuit breaker to the OFF position. |

## CHAPTER 3

## FUNCTIONAL DESCRIPTION

## 3-1. INTRODUCTION.

3-2. This chapter provides a functional description of the various circuits and components utilized by the RD378/U Magnetic Tape Recorder/ Reproducer (see Paragraph 3-3). For purposes of explanation, the operation of the unit has been divided into five major catagories (see Paragraph 3-5). Additionally, each of the five functional catagories has been further sub-divided to the circuit function level, to provide a complete description of the unit. Both functional and schematic diagrams are provided to support the technical discussions. Figure 3-1 is a functional diagram of the entire unit.

## 3-3. GENERAL DESCRIPTION.

3-4. The RD378/U Recorder/Reproducer consists of the following circuits and components (see Figure 3-1).
a. A record/reproduce headstack assembly to record signals on, or reproduce signals from, the magnetic tape.
b. Record amplifiers (one for each of the 14 channels) which amplify the input data signals to a level suitable for driving the record heads.
c. Reproduce amplifiers (one for each of the 14 channels) which amplify the data signals from the reproduce head to a level suitable to operate external monitors, or other readout equipments.
d. Control logic assembly which controls and monitors all transport functions.
e. Capstan drive system which moves tape across the heads at a selected, constant velocity.
f. Reel drive system which provides a constant supply of tape to the magnetic heads, and maintains uniform tape tension outside of the immediate head area.
g. Tape break sensor which stops the tape transport in the event of tape breakage.
h. Tape supply sensors which provide a readout of the approximate amount of tape remaining on the supply reel.
j. Voltage regulator to convert +28 V dc primary power to lower voltage levels required by the various electronic circuits.
k. Status panel with indicators to indicate mode of operation, selected tape speed, and tape break or end-of-tape conditions.

1. Control panel with pushbutton switches to control all operating modes except speed selection. Speed selection is made by a rotary switch located on the tape transport assembly.

speed seiect



Figure 3-1. Recorder/Reproducer Functional Diagram.

## 3-5. UNIT FUNCTIONAL DESCRIPTION.

3-6. The M-14G is a self-contained, 14-track recorder/reproducer providing 7 tape speeds of $1-7 / 8$ through 120 ips , and may be configured with either wideband direct/analog (2.0 MHz at 120 ips ) or wideband Group I FM signal electronics, or any combination of the two. Signal electronics are provided in 2 overlapping speed ranges of $1-7 / 8$, $3-3 / 4,7-1 / 2,15,30$ and 60 ips ; or $3-3 / 4,7-1 / 2,15,30,60$ and 120 ips , depending upon application requirements. The tape transport will operate at all 7 electrically selectable tape speeds without modification or mechanical component changes. Tape speed is selected by a rotary SPEEDSELECT switch, located on the tape transport assembly. All other operational controls are located on the front panel of the reproduce amplifier module (RAM). For purposes of explanation, the operation of the unit has been classified into 5 basic functional categories, as follows:
a. Control function.
b. Record function.
c. Reproduce function.
d. Power distribution.
e. Mechanical function.

3-7. CONTROL FUNCTION.
3-8. CONTROL LOGIC. Recorder modes are operator selected by momentarily depressing pushbutton switches, located on the front panel of the RAM. Each pushbutton, when selected, grounds
one of the control lines to the control logic PWB, activating integrated circuit logic gates which, in turn, control the transport mechanism. The operator selected modes include: FORWARD, RECORD, REVERSE, FAST WIND, FAST REWIND, and STOP. Separate "memory cells" are provided on the control logic PWB for each mode. These memory cells act as latching circuits to hold the recorder in the selected mode until another mode is selected, or unless overridden by one of the recorder protection circuits. Each memory cell consists of one dual-input NAND gate and one quad-input NAND gate, wired in a flip-flop configuration, and interconnected for automatic reset when another mode is selected. Since the recorder is designed to record only in the FORWARD direction, it is necessary to simultaneously depress both the FORWARD and RECORD pushbuttons when selecting the RECORD mode of operation. In addition to the six operator selected inputs, the control logic also receives inputs from the tape break sensor and from the end-of-tape sensor to automatically stop the transport mechanism whenever the tapesupply is nearly exhausted, or in the event tape breaks during operation.

3-9. CONTROL LOGIC FUNCTIONAL DESCRIPTION. Refer to Figure 3-2 and Figure 5-19. The function of the control logic is to control and monitor the operation of the tape transport, in accordance with the mode commands initiated by the operator. Such commands are initiated when the operator manually depresses one or more of the pushbutton mode switches, on the front panel of the RAM. The modes available for selection are: FORW ARD, RECORD, REVERSE, WIND, REWIND

and STOP. The control logic also monitors the outputs from the end-oftape and tape break sensors, and automatically stops transport operation when either of these conditions exist.

3-10. Mode Command Storage. With the exception of the STOP mode, each of the operational modes selected from the front panel of the RAM provides a ground (zero-volts) input to an integrated circuit storage element, on the control logic PWB, whenever the associated pushbutton switch is depressed. The storage elements consist of NAND gate pairs, which are connected in a flig-flop configuration, and which function as memory cells to enable the associated control circuits. The memory cells for each selected mode are: U1A and U2A for the RECORD mode, U1B and U2B for the FORWARD mode, U4D and U5A for the REWIND mode, U4A and U5B for the WIND mode, and U1D and U3B for the REVERSE mode. The memory cells are interconnected so that only one mode of operation may exist at any given time. Whenever a mode is initiated, the previously selected mode is automatically reset, except for the RECORD mode which must be selected simultaneously with the FORWARD mode. The STOP mode, when selected, resets all memory cells, which stops transport operation.

3-11. Control Circuits. The control logic contains seven control circuits which determine transport operation, for any given mode selected. These control circuits include: a start/ stop control, a direction control, a fast speed control, a speed select control, a tape break control, and an end-of-tape (EOT) control. Each of the control circuits serve to either enable or disable
specifjc transport functions necessary to perform the selected operation.

3-12. Start/Stop Control. The start ${ }^{\prime}$ stop control circuit consists of NAND gate U3A, NAND gate U1C (connected as an inverter), transistor Q7, and diode CR5, which control the operation of the ramp generator (Q7, Q8, Q9) on the capstan servo PWB. The ramp generator, in turn, controls the operation of the capstan motor, by controlling the output of the compensation amplifier (AR3).
Whenever a motion command is initiated, (FORWARD, REVERSE, FAST WIND, of FAST REWIND) the output of NAND gate U3A will go high, causing CR5 to conduct, which turns on the rampgenerator on the capstan servo PWB. The turn-on voltage to the ramp generator, through CR5, is delayed for approximately $1 / 2$ second by a one-shot multivibrator made up of NAND gate U4B and U4C and transistor Q10, which is also triggered by the receipt of a motion command through diodes CR14 thru CR17. This prevents erratic transport operation resulting from abrupt mode changes. A STOP command, whether initiated by the operator or by the tape break or EOT sensors, will reset all command memory cells. NAND gate U3A monitors the memory cells and provides a low (ground) output when all cells are reset. Thisgenerates a high output from NAND gate inverter U1C, which turns Q7 on to operate the STOP indicator on the front panel of the RAM. The low outpat of U3A also provides reverse bias to CR5, which stops the capstan motor. Transistors Q1 and Q2 form a delay circuit which resets all memory cells when transport power is first turned on.

3-13. Record Control. The RECORD mode is controlled by transistors Q3 and Q4, and the record memory cell consisting of UIA and U2A. When a RECORD command is initiated, the output of U2A, goes low, which turns Q3 off and enables the +18.5 V dc supply in the voltage regulator circuits, to operate the record amplifiers. The same low output from U2A causes a high output from U1A, which causes Q4 to conduct and light the RECORD indicator on the front panel of the RAM. The return line from the RECORD pushbutton is connected in series with the FORWARD pushbutton so that both a FORWARD and a RECORD command must be initiated to place the unit in the RECORD mode.

3-14. Direction Control. The direction control circuit consists of diodes CRIl and CR12, and transistor Q8。 Diode CRll monitors the output of the REVERSE memory cell (UID and U3B), and CRI2 monitors the output of the rewind memory cell (U4D and U5A).
When either memory cell is set, the associated diode will conduct and turn Q8 on. Q8 will, in turn, activate the reverse relay in the capstan motor amplifier circuit, to reverse the direction of motor rotation. Whenever the REVERSE mode is selected, the output of UID will be high, causing Q9 to conduct to light the REVERSE indicator. Likewise, when the FAST REWIND mode is selected, the output of U4D will go high to light the FAST REWIND indicator through transistor Q12.

3-15. Fast Speed Control. The fast speed control circuit consists of diodes CR30 and CR31, and transistor Q11.
Diode CR30 monitors the output of the fast rewind memory cell (U4D and U5A), and CR31 monitors the output of the
fast wind memory cell (U4A and U5B). When either memory cell is set, the associated diode will conduct and turn Qll on. Qll will, in turn, ground the input to the capstan servo phase comparator (U4A, pin l, on the capstan servo PWB), causing full accelerating voltage to be applied to the capstan motor. Whenever the FAST REWIND mode is selected, the output of U4D will be high, causing Q12 to conduct, lighting the FAST REWIND indicator lamp on the front panel of the RAM. Likewise, when the FAST WIND mode is selected, the output of U4A will be high, causing Q13 to conduct, lighting the FAST WIND indicator lamp.

3-16. Tape Break Control. The tape break control circuit consists of transistors Q14 thru Q17. The circuit monitors the tape break sensor, and initiates a stop command to the control logic in the event of tape breakage. Under normal conditions, transistor Q16 is biased on through resistor R43. This causes Q17 to conduct, providing current flow through the brake solenoid, keeping the mechanical brakes released. Under a tape break condition, a positive input from the tape break sensor turns Q14 and Q15 on. This causes Q16 and Q17 to turn off, removing power from the reel solenoid, and causing engagement of the reel brakes. When Q15 conducts, diode CR9 conducts, initiating a stop command (ground) input to all mode memory cells. Q15 also provides a ground return path, through R42, to light the TAPE BREAK indicator, on the front panel of the RAM.

3-17. End-of- Tape Control. The end-of-tape control circuit consists of transistors Q18 thru Q20. The circuit monthe end-of-tape sensor, and initiates a stop command to the control logic, just
prior to tape being completely wound off the supply reel. When activated, the EOT sensor provides a positivegoing input to the base of transistor Q18, causing it to turn on, This turns unijunction transistor Q19 on, which activates Q20 to light the EOT indicator lamps, on the front panel of the RAM. When Q18 is activated, the negativegoing transition at its collector is coupled through capacitor Cl 9 , which initiates a stop command (ground) input to all mode memory cells.

3-18. CAPSTAN SERVO CONTROL.
3-19. Reference Oscillator. Refer to Figure 3-3. The reference signal for the capstan servo is provided by crystal-controlled oscillator AR1, operating at 1.6 MHz . The oscillator consists of integrated circuit amplifier ARl, with positive feedback provided by crystal Yl and capacitor C4. The crystal is operated in the series-resonant mode, making the frequency of oscillation independent of other circuit components, or changes in operating voltages. Oscillator output is coupled to buffer/amplifier Q2, which drives the first stage of the frequency divider.

3-20. Reference Frequency Divider. Refer to Figure 3-4. The reference frequency divider consists of two 4-bit binary counters (ul, U2); one 2 -bit binary counter ( $1 / 2$ of 4 -bit binary counter U3); and associated speed control gates (U5 through U8) which form part of the speed control logic. The 1.6 MHz reference oscillator signal from buffer/ amplifier Q2 is applied to the input (pin 8) of the first binary countdown (Ul), to provide servo reference frequencies of $800 \mathrm{kHz}, 400 \mathrm{kHz}, 200 \mathrm{kHz}$, and

100 kHz . The first two initial countdowns ( 800 kHz and 400 kHz ) are not utilized. The next countdown frequency ( 200 kHz ) is utilized to control capstan motor speed at 120 ips . This frequency appears at pin 2 of Ul, where it is routed to the first speed select gate (U5B). The fourth countdown ( 100 kHz ) appears at pin 12 of Ul , where it is routed to the second speed select gate (U5A). This output is also used to drive the next binary counter (U2), which provides the next four successive countdowns, and so on. Reference frequency selection is controlled by the SPEED SELECT switch(Sl), which provides a ground at the input of one of the NAND gate inverters (U7, U8). A low (ground) at the input of the NAND gate inverters results in a high output, which enables the corresponding speed select gate to pass the selected reference frequency. Table 3-1 lists the available reference frequencies from the frequency divider, the associated tape speed, and the corresponding speed select gate.

3-21. The selected reference frequency is routed through limiting resistor R36, and appears at pins (F) and (6) of the capstan servo PWB for routing to the reference frequency sinewave converter (Figure 5-17). Since the capstan motor tachometer output signal frequency is equal to one-half the corresponding IRIG standard frequency, for any given tape speed, the reference frequency is counted down once more by U3, before being routed to the capstan speed control circuits.

3-22. Tachometer Amplifier. Refer to Figure 3-5. The tachometer amplifier amplifies and squares the sinewave

TABLE 3-1. REFERENCE FREQUENCY OUTPUT VS TAPE SPEED

| Tape Speed | Reference Frequency | Speed Select <br> Gate |
| :---: | :---: | :---: |
| 120 ips | 200.000 kHz | U5B |
| 60 ips | 100.000 kHz | U5A |
| 30 ips | 50.000 kHz | U6C |
| 15 ips | 25.000 kHz | U6B |
| $7-1 / 2 \mathrm{ips}$ | 12.500 kHz | U5C |
| $3-3 / 4 \mathrm{ips}$ | 6.250 kHz | U5D |
| $1-7 / 8 \mathrm{ips}$ | 3.125 kHz | U6A |

signal from the capstan motor tachometer, before applying it to the capstan speed control circuits, for comparison with the fixed reference frequency from the frequency dividers. The signal from the tachometer ranges in frequency from 1.562 kHz at $1-7 / 8 \mathrm{ips}$, to 100 kHz at 120 ips , at a level greater than l. $0 \mathrm{~V} \mathrm{rms}$. amplified by Q1, and routed to the squaring amplifier (AR2), where it is converted to a squarewave before being applied to the pulse synchronizer through buffer/amplifier Q3.

3-23. Pulse Synchronizer. If both a reference and tachometer pulse occur at the same time, the phase comparator (immediately following the pulse synchronizer) would become erratic, and lose phase-lock. To avoid this, the reference and tachometer are alternately gated through the pulse synchronizer (U4, Q4, Q5), before being applied to the comparator circuit. A
negative-going reference pulse applied to pin 12 of U4D will cause the synchronizer to change states, applying a high ( +5 V dc ) to the "reference input" of the phase comparator, and a low (ground) to the "tachometer input." The synchronizer will remain in this state, until a negative-going tachometer pulse appears at pin 2 of U4A, causing the circuit to change state. The comparator will now receive a low at the "reference input," and a high at the 'tachometer input."

3-24. Phase Comparator. Refer to Figure 3-6. The phase comparator (Ul0, Ull, Ul2) alternately accepts reference and tachometer pulses from the pulse synchronizer, and produces pulse-width modulate, constant amplitude pulses equivalent to the difference in phase between the two signals. The phase comparator functions as a three stage up-down counter, in which four possible states may exist - (-)l, 0 .


Figure 3-3. Reference Oscillator Functional Diagram.


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Figure 3-4. Frequency Divider Funct: nal Diagram


Figure 3-5. Capstan Speed Control Functional Diagram.


Figure 3-6. Phase Comparator and Compensation Amplifier Outputs.
$(+) 1$, and (+)2. During operation, the reference signal clocks the circuit on, and the tachometer signal clocks the circuit off. During phase-lock, the counter alternates between a count of 0 and 1 , with only U11 changing state. If the capstan motor is running too slow, the frequency of the tachometer signal becomes less than that of the fixed reference signal. As a result, the comparator would receive two or more reference pulses before receiving the next tachometer pulse. The second successive pulse from the reference input, prior to receipt of a tachometer pulse, will cause the phase comparator to switch to the (-) 1 state, with U11 held in the 0 state (pin 7 low). This causes the capstan motor amplifier to apply full power to the motor, thereby increasing the tachometer frequency and re-establishing a phase-lock condition. Conversely, if the capstan motor is running too fast, the comparator would receive two or more tachometer pulses, before receiving the next reference pulse. This will cause the comparator to switch to the (+) 2 state, with U11 held in the 1 state (pin 7 high), turning the capstan motor amplifier completely off. Normal friction then slows the motor until the tachometer frequency once again equals the reference frequency, and phase-lock is re-established. Figure 3-6illustrates the output of the phase comparator for the three possible tape-speed conditions. The output of the phase comparator is applied to a phase-lock test point through limiting resistor R38, and through NAND-gate inverter U6D to buffer/amplifier Q6, which provides a low impedance to drive the compensation amplifier.

3-25. Compensation Amplifier. Reffer to Figure 3-7. The compensation amplifier is comprised of a low-pass filter, an operational amplifier, anda frequency-sensitive $R / C$ feedback loop. The low-pass filter, consisting of L3, L4, C24, C25, C26 and C27, provides a rolloff at approximately 1.5 kHz . The remaining lower frequencies, representing the output duty-cycle of the phase comparator, are integrated by R42 and C28, and the feedback loop, to provide a quasi-static dc voltage input to the operational amplifier (AR3). The feedback loop (R44, R45, R46, C29, C30, and C31) around AR3 also stabilizes the amplifier to prevent servo overshoot in the motordrive amplifier stages which follow.

3-26. Ramp Generator. The ramp generator (Q7, Q8, Q9) serves to apply power gradually to the capstan motor after an operational mode has been selected. This ensures gentle tape handling by the transport, during the critical period when tape is being accelerated. Before the receipt of a start command, transistor Q9 is cutoff, which removes operating voltage from amplifier AR3. With AR3 inoperative, there is no drive to the motor-drive stages, and the capstan motor is stopped. Upon arrival of a start command, Q9 gradually starts to conduct, increasing the voltage applied to AR3, which starts the capstan motor. The ramp introduced by the ramp generator may be adjusted by variable resistor R51.

3-27. Servo Power Amplifier. Refer to Figure 3-8. The servo power amplifier consists of buffer/amplifier Q10 on the capstan servo PWB, and Q6 through Q9 on the servo heatsink


Figure 3-7. Compensation Amplifier and Ramp Generator.



Figure 3-8. Capstan Servo Control Functional Diagram.
assembly. • Output power transistors Q8 and Q9 form a quasi-complementary class B output stage, driven by transistors Q6 and Q7. Amplifier output is routed through the contacts of relay K1, which reverses the polarity of the output voltage to the dc capstan motor during REVERSE and REWIND modes of operation.

3-28. REFERENCE FREQUENCY SINEWAVE CONVERTER. Refer to Figure 3-9. The function of the reference frequency sinewave converter is to convert the selected squarewave signal, from the frequency divider, to a more suitable sinewave signal for recording on tape. Sinewave converter circuitry consists of a zero-crossing detector (U1), seven sharp-cutoff, low-pass filters, and an output amplifier stage (U2). Selection of the appropriate filter is accomplished by grounding one of the speed-selectlines (J57, pins 15 thru 21), through diodes CR4 thru CR10. Proper filter selection occurs automatically with tape speed selection.

3-29. Zero-Crossing Detector. The input stage (U1) of the sinewave converter consists of an integrated circuit voltage comparator/buffer, configured as a zero-crossing detector, which provides waveform shaping, amplitude limiting, and isolation between the frequency divider and the converter filters.

3-30. Filter Section. Each of the seven low-pass filters correspond to one of the squarewave reference frequencies selected by the tape SPEED SELECT switch. By effectively suppressing all harmonic components from the input squarewave signal, only the
fundamental sinewave frequency appears at the filter outputs.

3-31. Filter Select Circuit. FET transistors Q1 thru Q7 serve as on/off switching elements in series with each of the seven filter outputs. In the off (non-selected) state, the FET's are cutoff, preventing signal flow to the output amplifier (U2). Whenever a tape speed is selected, a ground is provided at the cathode of one of the switching diodes (CR4 thru CR10), through the associated series resistor. This causes the selected FET to conduct, allowing the output of the associated filter to pass on to the output amplifier.

3-32. Output Amplifier. Output amplifier U2 amplifies the output of the selected filter to a nominal 1.0 V rms level, and provides a low-impedance output to drive one or more of the record amplifiers. Output level may be adjusted between 0.0 and $2.0 \mathrm{~V} \mathrm{rms}$, with the OUTPUT LEVEL ADJ. control (R27).

3-33. REEL DRIVE SYS'TEM. The reel drive system consists of two dc reel motors, driven by separate closedloop servo amplifiers; two electromechanical tension sensors; and a failsafe mechanical brake system, which halts reel rotation in the event of power interruption. The motors are bi-directional, and are connected to provide opposing torque to maintain a nominal 9 ounces of tension throughout the reel of tape, regardless of tape speed, or direction of tape travel.

3-34. Tension Sensors. Refer to Figure 3-10. Compliance arms (tension sensors), one for each reel, are mounted in the tape path to sense

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Figure 3-9. Sine Wave Reference Frequency Converter Functional Diagram.


Figure 3-10. Tape Tension Control Functional Diagram.
tape-tension and control operation of the reel servos. Mechanically, each compliance-arm consists of two rollers mounted on a pivot-arm, loadedby spring tension. The spring is adjusted to provide 14 to 15 ounces of tension, when the pivot-arm is centered between its two mechanical stops. The arm is coupled to a light shutter, mounted between a pair of photocells and their associated light sources, so that with tape tension at its nominal value, the shutter is positioned to provide equal illumination to both photocells. If tape tension increases or decreases, the shutter changes position and one photocell is illuminated more than the other. This generates an error signal to the servo amplifier, which increases or decreases motor voltage to correct the error.

3-35. Servo Amplifier. Refer to Figure 3-11. There are two identical reel servo-amplifiers utilized in the RD378/U, although only one is shown in the referenced figure. One servo controls the supply reel motor, and the other controls the take-up reel motor. Since the operation of both is identical, only the supply reel servo is described. The servo amplifier consists of a high-gain amplifier (AR1), a free-running multivibrator (Q1, Q2), a ramp generator (AR4), a comparator stage (AR2, AR3), a bi-stable switch (U1), and a bridge connected power amplifier to drive the reel motor.

3-36. Input Amplifier. The servo amplifier input signal is a quasi-static dc voltage level obtained from the supply reel tension sensor, and applied to pin 3 of AR1. A reference voltage, determined by R10, R11, R7, and CR2 is applied to pin 2. The output of linear
amplifier AR1 is, therefore, proportional to the difference between the two inputs. To prevent overloading the comparator circuits which follow, a diode clamp (CR4, CR5, CR9 and CR10) is provided to limit output amplitude to $\pm 1.5 \mathrm{~V}$ peak, relative to the input reference voltage.

## 3-37. Multivibrator and Ramp

 Generator. Q1 and Q2 form a freerunning multivibrator, operating at a frequency between 8 and 10 kHz . The squarewave output is applied to linear amplifier AR4, through an integrator network consisting of C9 and R19, which together constitute a ramp generator. The resulting sawtooth output signal is capacitively coupled to the comparator circuit (AR2, AR3).3-38. Comparator and Steering Flip-Flop. The output of the ramp generator (AR4) and input amplifier AR1 are applied to the inputs of comparators AR2 and AR3. The operation of the two comparators is identical, except for the fixed bias levels applied to the non-inverting inputs (pin 3). The ramp signal from AR4 is applied to the non-inverting input of AR2 (pin 3), while the output of AR1 is applied to the inverting input (pin 2). Whenever the input voltage at pin 2 exceeds the voltage at pin 3 (instantaneous ramp voltage plus fixed bias voltage), the output of AR2 will be zero (ground). When the voltage at pin 2 is less than at pin 3 , the output will be positive. The resulting output will be a pulse-width modulated (PWM) signal, in which the duration of the pulses represent the magnitude of the error from the tension sensor. The PWM output of AR2 is applied to pins 4 and 5 of the steering flip-flop (U1), through inverter Q33. The PWM output




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S REEL SUPPIY CIRCUIT
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Figure 3-11. Reel Servo Amplifior Functional Diagram.
of AR3 is applied to pins 1 and 2 of U1, through inverters Q5 and Q7. The fixed bias levels at pin 3 of AR2 and AR3 are selected so that only one comparator is acti ve at any given time while the other is switching at the ramp rate. A high at the input to the steering flip-flop will produce a high at the corresponding output. The circuit will remain in this state until a high appears at the opposite input, causing the circuit to switch. Ul thus controls the conduction of the current switches driving the reel motor, and hence the direction of motor rotation.

3-39. Servo Power Amplifier. When the output of AR2 is high, (no PWM) the signal applied to Ul, pins $4 \& 5$, is low, as a result of inverter Q33. Pin 8 of Ul is, therefore, low; Q12 is off; Q21 is off; and Q27 (one leg of the output bridge) is off. At the same time, the high output of AR2 holds Q9 and Qll on. The conduction of Qll holds Q25 (in the opposite leg of the output bridge) off. With Q25 and Q27 off, the only remaining path for current is from ground, through Q26, through the motor, and through Q28 to the +28 V dc supply. The magnitude of the voltage applied to the motor will depend upon the drive available at the base of Q28, which is determined by the magnitude of the error signal from the tension sensor. As the error signal varies and AR2 begins to provide PWM signal, the first negative-going transition produces a corresponding positive-going transition at Ul, pins 4 and 5. Ul switches state, producing a high at pin 8, causing Q12 to turn on. Q12 turns Q21 and Q27 on. At the same instant, the negative-going transition turns Q9 off, along with Q11, which turns Q25 on. With Q25 and Q27 on (Q26 and Q28 off), the direction of
current flow through the motor will reverse, causing rotation in the opposite direction.

3-40. Fail-Safe Brakes. Refer to
Figure 3-21. The reel motors are provided with solenoid actuated brake bands that engage to prevent tape spillage whenever input power to the recorder is lost, whenever tape is wound off either tape reel, or if the tape breaks. The brake solenoid is controlled by Q17 in the control logic. The brake solenoid requires approximately $l \mathrm{amp}$ for actuation. Once actuated, a relatively low current is required. The transition from actuating current to holding current is accomplished by the brake control circuit, located in the reel motor housing.

3-41. Refer to Figure 3-13. When Q17 (in the control logic) turns on, +28 V dc is applied across the brake solenoid and series resistor Rl. At the instant power is first applied to the circuit, capacitor Cl begins to charge through resistor Rl, placing a positive potential at the base of transistor Q1. Q1 turns on, causing Q2 to turn on. Current now flows from ground through Q2 and through the solenoid to +28 V dc. Capacitor Cl reaches full charge, reducing the current flow through Rl and causing Q1 and Q2 to turn off. The solenoid remains energized, due to the path to ground provided by Rl , but at a reduced current level.

3-42. TAPE BREAK SENSOR. REfer to Figure 3-14. The tape break sensor consists of a photocell (Vl) and lamp (DSl) assembly, located in the tape path and connected to switching circuits in the control logic. During normal


Figure 3-12. Reel Braking System Functional Diagram.


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Figure 3-13. Delay and Control System.


Figure 3-14. Tape Break Sensor Functional Diagram.
operation, tape is threaded through the assembly to prevent light from striking the photocell. With light from DSI blocked by the tape, Vl has high resistance and prevents zener diode CR35 (in the control logic) from conducting. When tape breaks, or is wound completely off either the take-up or supply reel, the photocell is illuminated, causing its resistance to decrease, and the voltage applied to CR35 to increase. CR35 fires, applying a positive voltage to switch-circuit Q14- Q16, which grounds the base of transistor Q17. Q17 turns off, removing the +28 V dc from the brake solenoid which, in turn, applies the mechanical brakes. The switch-circuit (Q14-Q16) is also used to provide a stop command to the control logic, which deactivates the capstan drive and also lights the TAPE BREAK indicator on the front panel of the RAM.

3-43. TAPE REMAINING AND END-OF-TAPE SENSORS. Refer to Figure 3-15 and 3-16. Photoelectric circuits are used to sense the approximate amount of tape remaining on the supply reel, to operate the TAPE SUPPLY meter on the front panel of the RAM. An end-of-tape sensor is also provided, to stop the unit just prior to tape winding completely off the supply reel.

3-44. Tape Remaining Sensor. The tape remaining sensor consists of photocell assemblies positioned at the lower right (V1 thru V9), and upper left (V10 thru V18) corners of the tape transport (see Figure 3-16). The photocells are illuminated by lamp DSI, located above and to the right of the take-up compliance arm. This lamp is lighted whenever power is applied to the transport. The sensors are positioned so that
light from DSI is directed between the supply reel flanges to strike the photocells. When the supply reel is FULL, the tape pack blocks light from DSI, and the photocells provide a high resistance between the +20 V dc source and the TAPE SUPPLY meter. As tape is spooled from the supply reel, the diameter of the tape pack diminishes, and the photocells are progressively illuminated, causing their resistances to decrease. The photocells are connected in parallel, so that as their total resistance decreases more current is allowed to flow through the meter. Potentiometers R33 and R35 are provided for meter calibration.

3-45. End-of-Tape Sensor. The end-of-tape sensor (V19) is located in the tape supply sensor assembly located at the upper left-hand corner of the transport, and is so positioned that it becomes the last of the photocells to be illuminated, as tape is spooled from the supply reel. Once activated, V19 provides a positive voltage to the end-oftape switching circuit (Q18 thru Q20) in the control logic circuits. The positive input turns transistor Q18 on, which provides a negative-going transition to the stop logic, through capacitor Q19, causing the transport to stop. Q18 also turns on Q19 and Q20, to provide a ground return for the EOT indicator lamp, on the front panel of the RAM.

## 3-46. RECORD FUNCTION.

$3-47$. The RD378/U will record and reproduce in either the direct/analog or FM record modes, depending upon the type of signal electronics installed. The direct/analog and FM signal electronics are directly interchangeable, to permit simultaneous recording, or reproducing. in both modes.


Figure 3-15. End-of-Tape and Tape Supply Sensors Functional Diagram.

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Figure 3-16. End-of-Tape and Tape Break Sensor.

3-48. DIRECT/ANALOG RECORD ELECTRONICS. Refer to Figure 6-2. The direct record electronics consist of up to 14 record amplifier cards (one for each direct channel) and 1 bias oscillator card. The record amplifier cards plug into a motherboard assembly, located in the record amplifier housings directly adjacent to the headstack, and are accessible from the front of the unit. Two motherboards are used, one for all even-numbered, and one for all odd-numbered record amplifiers, with each containing seven amplifier cards. The bias oscillator is located in the amplifier housing containing the even-numbered record amplifiers. Conventional constant-flux direct/analog recording techniques are employed to record data signals in the frequency range of 400 Hz to 2.0 MHz , at 120 ips , with proportionately narrower bandwidths at lower tape speeds. At the record head, the data signal is linearly mixed with a high-frequency (7. 05 MHz ) bias signal to overcome the inherent nonlinear characteristics of the tape.

3-49. DIRECT/ANALOG RECORD AMPLIFIER. Refer to Figure 3-17. The direct/analog record amplifier consists of a data signal amplifier (Q1, Q2); a bias signal amplifier (Q3); and a bias trap network, to prevent the bias signal from entering the low-leveldata amplifier stages.

3-50. Data Signal Amplifier. Data signals to be recorded are applied across the RECORD LEVEL ADJ. control (R2), which permits adjusting the gain of the amplifier to produce normal record level ${ }^{1}$ output with input levels ranging between 0.2 and 10.0 V rms.

Transistors Q1 and Q2 form a complementary Darlington amplifier, which provides a low output impedance, and high current-gain to drive the record head. To compensate for head losses at high frequencies, a small amount of preemphasis is provided by R8 and C3.

3-51. Bias Signal Amplifier. The bias amplifier consists of a single class-C amplifier (Q3), followed by a harmonic filter to assure waveform purity of the output signal. Class- C operation of Q3 minimizes changes in bias amplitude, due to fluctuations in operating voltages. Current limiting resistor R12 limits the amount of bias current drawn from the bias oscillator, and ensures equal bias signal distribution to all channels. BIAS LEVEL ADJ. control (R9) permits adjusting the bias current level, through the record head, for optimum high-frequency response and lowest signal distortion (see Chapter 6).

3-52. Bias Trap. The bias signal (7. 05 MHz ) and data signal ( 400 Hz to 2. 0 MHz ) are mixed linearly (with no resulting modulation products) directly at the high side of the record head. The amplified bias signal, which has an amplitude approximately ten times that of the data signal, is prevented from entering the data amplifier stages by a bias trap consisting of $\mathrm{L}, \mathrm{C} 4, \mathrm{~L} 6$, and Cll.

1 Normal record level (NRL) is that level of input signal necessary to produce 2.0 percent 3 rd order harmonic distortion (due to tape overload) at the output of the reproduce amplifier.


Figure 3-17. Direct Record and Bias Amplifier Functional Diagram.

3-53. BIAS OSCILLATOR. Refer to Figure 3-17. The bias oscillator consists of amplifier Q1 with a 7.05 MHz crystal in a positive feedback loop, from collector to base. Oscillator output is coupled to a class-C amplifier (Q2), which acts as a buffer between the oscillator and the filter networks that follow. Class-C operation of Q2 minimizes changes in bias amplitude, due to fluctuations in operating voltages. The pi-configured filter at the output of Q2 removes the harmonics from the bias waveform, and transforms the high impedance collector output of Q2 to a low impedance to drive the bias stages of the record amplifiers. The filter provides two bias signal outputs, which are $180^{\circ}$ out of phase with each other. One phase provides bias for channels 1, 5, $9,13,4,8$, and 12 . The other phase provides bias for channels $2,3,6,7$, 10,11 , and 14. This helps to prevent bias crosstalk problems that might otherwise occur in the record heads.

3-54. FM RECORD ELECTRONICS. Refer to Figure 3-18. The FM record electronics consist of up to 14 record amplifier cards (one for each FM channel), which plug into a motherboard assembly, located in the record amplifier housings. These housings are located directly adjacent to the headstack, and are accessible from the front of the unit. Two motherboards are used, one for all evennumbered, and one for all odd- numbered record amplifiers, with each containing seven amplifier cards. The output of the FM record amplifiers is a squarewave signal which saturates the tape in both the positive and nega-tive-going directions, at a rate (frequency) determined by the amplitude
of the input data. Because of the saturation techniques used, the highfrequency bias signal, necessary for direct/analog recording, is not required.

3-55. FM RECORD AMPLIFIER. Refer to Figure 5-13. The FM record amplifier provides frequency modulated output signals at 8 separate IRIG center frequencies, determined by the associated speed-select circuitry. The amplifier consists of a high-impedance input amplifier, a voltage-controlled oscillator, a frequency divider, speedselect circuitry, and a head-current driver stage.

3-56. Input Amplifier. Integrated circuit ARI is a high-impedance, direct-coupled, non-saturating, amplifier, which serves to deviate the center frequency of the voltage- controlled oscillator (VCO). Variable resistors R2 (coarse) and R7 (fine) determine FM carrier deviation limits of $\pm 40$ percent ZERO ADJ. control R4 is used to balance oat residual dc at the amplifier input, which would otherwise cause offset center frequency deviation.

3-57. Voltage-Controlled Oscillator. The VCO circuit consists of a freerunning multivibrator (Q2, Q5), driven by constant-current drivers Q3 and Q4. Oscillatorfrequency is determined by the emitter currents of Q3 and Q4. With no imput signal to ARI, the FM center frequency is adjusted by CENTER FREQUENCY ADJ. control R33, which controls the fixed bias potential of the constant-current drivers. The output of AR1 is directly coupled to Q3 and Q4, causing the oscillator frequency to vary in accordance with the amplitude of the input data. With the


| SPEED <br> (1PS) | CENTER <br> FREQUENCY <br> $(K H z)$ | DEVIATION <br> (RREQUENCIES (KHZ) |  | SPEED SELECTION INPUT CODES |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $+40 \%$ | $-40 \%$ | CODING LINES <br> (PIN D) |  |  |  |
|  | 6.750 | 9.450 | 4.050 | 0 | 0 | 1 |
| 3314 | 13.500 | 18.900 | 8.100 | 0 | 1 | 0 |
| $71 / 2$ | 27.000 | 37.800 | 16.200 | 0 | 1 | 1 |
| 15 | 54.000 | 75.600 | 32.400 | 1 | 0 | 0 |
| 30 | 108.000 | 151.200 | 64.800 | 1 | 0 | 1 |
| 60 | 216.000 | 302.400 | 129.600 | 1 | 1 | 0 |
| 120 | 432.000 | 604.800 | 259.200 | 1 | 1 | 1 |

Figure 3-18. FM Record Amplifier Functional Diagram.
in put of the FM record amplifiers grounded, R33 is adjusted for a VCO center frequency of 432.0 kHz . Transistor Ql functions to ensure oscillator start-up, when power is turned on, by applying a negative-going voltage to the base of multivibrator transistor Q2.

3-58. Frequency Divider and SpeedSelect Circuits. The output of the VCO ( $432.0 \mathrm{kHz}+40$ percent) is taken from the collector of Q5 and applied to the input of level converter Q6. The output of Q6 is applied to a series of 8 frequency dividers (U1, U3), which provide output frequencies of $216,108,54$, $27,13.5,6.75$, and 3.125 kHz . All outputs from the frequency dividers are routed to the input of the 8 -channel digital switch (U2). The digital switch selects one of the eight inputs, depending upon the 3 -bit binary word from the speed-select circuitry, and applies
it to the input of the head driver stage (Q7 thru Q9). Table 3-2 provides a list of tape speeds, FM center frequencies, deviation limits, and speedselect codes required to operate the digital switch.

3-59. Head-Current Driver. The head- current driver is a complementary emitter-follower, consisting of transistors Q7, Q8 and Q9. The output is single-ended with the head connected to the high side of a 10 -ohm resistor (R30) to permit head current monitoring while conducting test and alignment procedures.

## 3-60. FM SPEED-SELECT

ENCODER. Refer to Figure 3-19. The FM speed-select (binary coded decimal (BCD) encoder is used in conjunction with the FM recorder amplifier to select the proper FM carrier frequency

TABLE 3-2. FM RECORD PARAMETERS

| Tape Speed ips | FM Cent. Freq. kHz | $\begin{aligned} & \quad \text { Devia } \\ & +40 \% \\ & \mathrm{kHz} \end{aligned}$ | $\begin{aligned} & \text { tion } \\ & -40 \% \\ & \mathrm{kHz} \\ & \hline \end{aligned}$ | Speed Select Code |
| :---: | :---: | :---: | :---: | :---: |
| 120 | 432.000 | 604. 8 | 259.2 | 111 |
| 60 | 216. 000 | 302.4 | 129.6 | 110 |
| 30 | 108.000 | 151. 2 | 64.8 | 101 |
| 15 | 54.000 | 75.6 | 32.4 | 100 |
| $7-1 / 2$ | 27.000 | 37.8 | 16.2 | 011 |
| 3-3/4 | 13. 500 | 18.9 | 8. 1 | 010 |
| 1-7/8 | 6. 750 | 9. 45 | 4. 05 | 001 |

for the particular tape speed selected. The encoder is contained on a single printed circuit card, which is installed at connector J26 in the electronic housing assembly at the rear of the transport (Figure 7-1).

3-61. The speed-select encoder produces a 3-bit binary output, which is determined by the tape speed selected. Whenever a particular speed is selected, a corresponding input to the encoder (pin 7, 8, $9,12,13,14$, or 15) is grounded. All other inputs remain open (high). If no tape speed is selected, all inputs are open, and the bases of Q1, Q2, and Q3 are biased to +5 V dc through resistors Rll, Rl2, and R13. This will forward bias CRl5 through CR20 and turn on transistors Q1 through Q3, causing their outputs (pins 4, 5, and 6) to go low ( 0 - volts). For example, assume a tape speed of 30 ips
is selected. Input pin 8 will be grounded through the SPEED SELECT switch on the transport. This will forward bias CR7 and CR8, and reverse bias CRl5 and CRl7. This low input turns Q1 and Q2 off, causing their collectors to go high ( +5 V ). The collector of Q3 remains low, thus producing a 3-bit binary output of "l-0-1." Table 3-3 lists the binary output for each tape speed selected.

## 3-62. REPRODUCE FUNCTION.

3-63. The RD378/U will record and reproduce in either the direct/analog or FM record modes, depending upon the type of signal electronics installed. The direct/analog and FM signal electronics are directly interchangeable, to permit simultaneous recording, or reproducing, in both modes.

TABLE 3-3. BINARY CODE

| Tape Speed <br> ips | (A) <br> Pin 4 | Outputs <br> (B) <br> Pin 5 | (C) <br> Pin 6 |
| :---: | :---: | :---: | :---: |
| 120 | 1 | 1 | 1 |
| 60 | 1 | 1 | 1 |
| 30 | 1 | 1 | 1 |
| 15 | 1 | 1 | 1 |
| $3-1 / 2$ | 0 | 1 | 1 |
| $1-7 / 8$ | 0 | 0 | 1 |



001-016

Figure 3-19. FM BCD Encoder Functional Diagram.

3-64. DIRECT/ANALOG REPRODUCE ELECTRONICS. The direct reproduce electronics consist of up to 14 reproduce preamplifiers (one for each channel), up to 14 reproduce amplifier cards, and 1 speed change logic card. The preamplifiers are encapsulated modules, and plug directly into the reproduce heads to minimize system noise, and signal loss due to cable capacitance. The reproduce amplifiers and speed change logic cards plug into the reproduce amplifier module (RAM), located directly below the tape transport, and are accessible fromthe front of the unit by opening the transport and lifting the hinged topcover of the RAM. Voltage-mode reproduce techniques are employed to reproduce pre-recorded data signals in the frequency range of 400 Hz to 2.0 MHz , at 120 ips , with proportionately narrower bandwidths at lower tape speeds.

3-65. Reproduce Preamplifier. Refer to Figure 3-20. The reproduce preamplifier is a three-stage, directcoupled amplifier circuit, providing approximately 30 dB of signal gain between the output of the reproduce head and the input of the reproduce amplifier. The amplifier is configured so as to present a high input impedance to the reproduce head, and a comparatively low output impedance to drive the reproduce amplifier which follows. For optimum signal-to-noise ratio, transistors Q1 and Q2 are operated at a very low collector current. With specified output cable capacitance, preamplifier frequency response is flat ( $\pm 3.0 \mathrm{~dB}$ ) from 100 Hz to 3.0 MHz .

3-66. DIRECT/ANALOG REPRODUCE AMPLIFIER. Refer to Figure 5-14. The Direct/analog reproduce
amplifier consists of a low-noise, common-base, input stage; several stages of intermediate amplification; electrically selected amplitude and phase equalization; and a low impedance output amplifier.

3-67. Input Stage. The output of the reproduce preamplifier is coupled to the input amplifier (Q2) through resistor R3 and capacitor C4. Transistor Q2 is connected in a common-base configuration, with operating bias derived through Q1 and R4. Q1 serves as a constant-current source to the base of Q2 which, in turn, supplies bias back to the base of Q1. Thus, any change in the dc collector current of either transistor is cancelled by the other. With the collector voltage of Q 2 held constant, the amplified ac data signal will be essentially free of distortion, and undesireable noise. Transistor Q3 serves as a ground return path for switching transistors Q4 through Q9, selected by the speed change logic, in the RAM. These switching transistors, when activated, select resistors (R9, 11, 13, 15, 17, or 19) to serve as ac load resistors for amplifier Q2, through series capacitor C3. In this manner, the gain of the input amplifier (Q2) is automatically adjusted for each tape speed selected.

3-68. Low- Frequency Equalization. At low frequencies, ( 400 Hz to approximately 2.0 kHz ), the reactance of capacitor C3 is large, compared to that of the load resistors selected by the speed change logic. Likewise, the reactance of capacitor C2, in parallel with Rl , will be large, providing maximum amplifier gain at low irequencies. As frequency increases, the parallel combination of C 2 and Rl , in series with Cl , begins to shunt the series


Figure 3-20. Reproduce Preamplifier Functional Diagram.
combination of Q1 and R2, thereby lowering amplifier gain. The reactance of C3 also decreases as frequency increases, which further reduces amplifier gain.

3-69. High-Frequency
Equalization. After the initial low frequency boost from the input stage, the data signal is coupled through capacitor C7 to the next stage, consisting of Q10 and Q11. Q10 is an emitterfollower providing isolation between the input stage (Q2) and equalization amplifier Q11. The load impedance of Q11 consists of a selected network that provides mid-band and bandedge equalization for the tape speed selected. A separate equalization network is used for each tape speed, and is connected across the output of Q11 by means of a diode switching matrix, controlledby the speed change logic. If, for example, a tape speed of $3-3 / 4 \mathrm{ips}$ is selected, the network consisting of R29, L1, C10, R31, and R30 is placed in series with the collector load resistor (R28) of transistor Q11. At mid-band frequencies, R29 and L1 present a rising impedance to Q11, thus increasing the stage gain. Near the upper bandedge frequency, C10 and L1 show a sharp increase in impedance, resulting from approaching resonance. The impedance then decreases sharply above the resonant frequency. R29 provides adjustment of mid-band frequency response, and R 31 permits adjustemnt of the high-frequency response, to provide a fully amplitudecompensated (flat) output, over the full frequency range.

3-70. Phase Equalization. The reactive elements used for frequency compensation in the second stage introduce nonlinear phase response
characteristics which must be corrected, if the output signal is to be a faithful reproduction of the original recorded data. From the amplitude equalization stage (Q11), the signal is routed through emitter-follower Q12, and then to the phase equalization stage (Q13). Transistor Q13 is a phase spliting amplifier providing two outputs of equal amplitude, but having a 180 degree difference in phase. By connecting a variable resistor (R53) and acitor (C21 thru C26) between the emitter and collector of Q13, it becomes possible to correct for phase nonlinearities introduced during the process of amplitude equalization. Switching diodes are used to automatically place the appropriate phase-equalization capacitor in the circuit, for the speed selected. The PHASE ADJ. control (R53) affects the response at all tape speeds.

3-71. Output Amplifier. From the phase equalization stage, the signal is routed through emitter-follower Q23 to a voltage amplifier consisting of transistors Q14 thru Q16, which provide a voltage gain of approximately 100 .
From the voltage amplifier, the signal is routed to emitter-follower Q18. The OUTPUT LEVEL ADJ. control (R76), in the emitter leg of Q18, controls the output amplitude of the reproduce amplifier. The output stage consists of driver amplifier Q22, bias control transistor Q19, and output transistors Q20 and Q21, connected in a complementarysymmetery configuration. Amplifier gain is normally adjusted to provide a 1.0 V rms output across a load impedance of $75-\mathrm{ohms}$.

3-72. FM REPRODUCE
AMPLIFIER. Refer to Figure 3-21.


Figure 3-21. FM Reproduce Amplifier Functional Diarram.

The FM reproduce amplifier utilizes an FM discriminator consisting of separate zero-crossing detectors (U5, U6), which detect both the positive- going and negative-going crossovers of the modulated carrier. The detector outputs are combined through a gating circuit (U7), and used to trigger a fixed pulse-width one-shot multivibrator (Y2). The FM signal is thus converted to a pulse-width-modulated (PWM) signal having a constant amplitude, but a varying duty cycle. The output of the one-shot is coupled to a selected lowpass filter (FL-1 through FL-6) which responds to the average duration of the input pulses, to extract the original data signal.

3-73. Normalizing Amplifier. From the preamplifier, the reproduce signal is routed to the normalization amplifier, consisting of Q3 through Q5. Signal normalizing is necessary to compensate for the increased output from the reproduce head as frequency increases at higher tape speeds. The amplifier normalizes the carrier amplitude to approximately $3.0 \mathrm{~V} \mathrm{p-p}$ at all tape speeds. Amplifier gain changing is accomplished by switching a resistor in the feedback attenuator (R1 through R6) such that as the resistance increases the feedback also increases, which decreases amplifier gain. A series capacitor ( C 1 through C 6 ) is also switched, along with the resistor, to provide rolloff at low frequencies. The resistor values increase by a factor of approximately two and the capacitor values decrease by a factor of approximately one-half for each lower tape speed selected. Thus, the low frequency cutoff remains constant. High-frequency rolloff is introduced by L5. As the series resistor values double, the high-frequency rolloff
point is also doubled. Switching of the feedback resistors and capacitors is accomplished by hex-inverter U1. Each inverter provides a low resistance to ground when the input is high, and an open-circuit when the input is low.

3-74. Squaring Amplifier. Squaring amplifier Q6 and Q7 is a two-stage amplifier which increases the signal slope at the zero-crossover points, and limits the amplitude of the output signal. Slope increase is provided by the high voltage gain of each stage, and amplitude limiting is provided by diodepairs connected from collector to base of each transistor. The output of the squaring amplifier is a squarewave signal having short rise and fall times, at an amplitude of approximately $1.0 \mathrm{Vp}-\mathrm{p}$.

3-75. Zero-Crossing Detectors. The zero-crossing detector consists of voltage comparators U5 and U6, and NAND gate inverters U7A, U7B, and U7C. As the output of the squaring amplifier passes through zero in the positivegoing direction, the output of U5 goes positive and is applied to the input of NAND gate inverter U7A. The nega-tive-going output of U7A is differentiated by C35 and R36, and inverted again by U7C to trigger the one- shot multivibrator (Y2). The output of voltage comparator U6 goes positive whenthe output of the squaring amplifier passes through zero in the negative-going direction. U6 output is inverted by U7B, differentiated by C36 and R37, and OR'ed wit'. the output of U7A (by U7C) to also trigger the one-shot multivibrator.

3-36. One-Shot Multivibrator. Refer to Figure 3-22. The output pulse-width of the monostable multivibrator (U1) is equal to one-half the cyclic period of the


001-074

Figure 3-22. One-Shot Timing Functional Diagram.

FM carrier frequency, when the carrier signal is unmodulated. The pulse-width is deter mined by capacitor Cl , resistor Rl , and variable resistor R 28 。 Capacitor Cl is actually the parallel combination of the 22 pF capacitor (Cl), within the one-shot module, and external capacitors located on the selected low-pass filter (FL-1 through FL-6). Variable resistor R28 is adjusted for a symmetrical squarewave output when the FM carrier is unmodulated. The output of Ul is routed to NAND gate inverters U2A and U2B, which provide the necessary current to drive the output switching transistors (Q3 and Q4). Transistors Q3 and Q4 are connected in a complementarysymmetry switching configuration, such that when the output of U2B is high Q4 is on, and when U2B output is low Q3 is on. This provides an output signal having both negative and posi-tive-going transitions, across the common load resistor R57. The average dc value of the squarewave output across R57 will be zero when the FM carrier is unmodulated. With modulation, the squarewave duty cycle will vary, and the average dc value will change in direct relation to the change in input frequency. To prevent multivibrator instability due to changes in ambient temperature, the entire circuit is housed in a temperaturecontrolled module. Temperature control is provided by temperaturesensitive resistor R4, which controls the conduction of Darlington- connected transistors Q1 and Q2. As temperature decreases, the resistance of R4 also decreases, causing Q1 and Q2 to conduct. The module is then heated by the power dissipated by resistors R2 and R3.

3-77. Demodulation Filters. Refer to Figure 3-23. The PWM squarewave signal developed across R 57 by the oneshot must be filtered to remove the FM carrier and extract the original modulating data. Since a different carrier frequency and bandwidth is used for each tape speed, a separate filter must be provided for each of these frequencies. Thus, each of the demodulation filters ( $F \mathrm{~L}-1$ through $F \mathrm{~F}-6$ ) provides the proper cut-off frequency for one particular tape speed. Each of the filters contain a relay (Kl) which, when energized, connects the filter to the common input bus (pin 7). The relay also connects the proper value timing capacitor to the one-shot multivibrator, which alters the output duty cycle to coincide with the cyclic period of the input FM carrier frequency. Filter relays are activated by hex-inverter U3, which provides a ground return path for the selected relay coil. U3 is activated by positive-going inputs from hex-inverter U2, which is activated by the speed change logic. Each filter contains a ZERO ADJ. control (Rl) to correct for any asymmetry in the unmodulated squarewave signal from the one-shot. Rl is adjusted to produce 0.000 V dc at the output of the reproduce amplifier, with an unmodulated FM carrier input corresponding to the tape speed (and filter frequency) selected. Each filter is also provided with an OUTPUT LEVEL ADJ. (R4) to normalize the output of the reproduce amplifier for all tape speeds. The outputs of all six filters are connected to a common output bus, and routed to the input of the output amplifier (U4).

3-78. Output Amplifier. The output amplifier consists of a direct-coupled, operational amplifier with a variable


Figure 3-23. 1.25 kHz Filter Schematic Diagram.
resistor (OUTPUT LEVEL, R14) in the feedback loop to vary the gain. ZERO ADJ. control R15 is provided to balance out residual dc at the output of the reproduce amplifier, with the inputs of all demodulation filters grounded. If desired, R15 may be adjusted to provide a dc offset in the output of the reproduce amplifier.

3-79. SPEED CHANGE LOGIC. Refer to Figure 3-24. The function of the speed change logic is to select the proper equalization network in the reproduce amplifiers, which correspond to the tape speed at which the recorded signals are to be reproduced, determined by the position of the SPEED SELECT switch on the tape transport. When a specific tape speed is selected, a corresponding relay (or combination of relays) on the speed logic card is energized. The only exception is the $3-3 / 4$ ips speed, in which case all speed select relays are de-energized, and a ground return signal is provided by the normally-closed contacts of K1, K 2 , and K 3 . For $7-1 / 2 \mathrm{ips}, \mathrm{K} 3$ is energized by 28 V dc across pins 5 and 6 , and a ground return path is provided through normally-closed contacts of K1 and K2, and throughK3A1/K3A2. For $15 \mathrm{ips}, \mathrm{K} 2$ is energized (across pins 6 and 14) and signal ground is supplied through normally-closed contacts of K1, through K2A1/K2A2, and norm-ally-closed contacts B2 and B3 of K3. For 30 ips, K2 and K3 are energized (across pins 6 and 9) and signal ground is supplied through K3B1/K3B2, K2A1/K2A2, and through the normallyclosed contacts of K1. For 60 ips , K1 is energized (across pins 6 and 11) and signal ground is supplied through the normally-closed contacts of K4 and K2, and through K1A1/K1A2. For 1-7/8
ips, or 120 ips (depending upon how the reproduce amplifiers are configured), relays K 1 and K 4 are energized (across pins 6 and 15) and signal ground is supplied through K4A1/K4A2, through the normally-closed contacts of K2 and through K1A1/K1A2. In each case, the ground return path provided by the speed change logic selects the proper equalization network on the reproduce amplifier for the speed selected.

## 3-80. POWER DISTRIBUTION FUNCTION.

3-81. Operation of the RD387/U requires a source of $117 \mathrm{~V} \mathrm{ac}, 60 \mathrm{~Hz}$, single-phase input power. Connection to this source is made through P101, located on the rear connector panel. Once line power is applied, internal power supplies provide all necessary dc voltages required to operate the unit. The paragraphs which follow describe the power distribution within the unit, and provide a functional description of the circuits and assemblies involved.

3-82. General Discussion. Refer to Figure 5-6. Input power is routed from J101. on the rear connector panel to the power distribution assembly through line filters FL-1 and FL-2, and circuit breaker CB-1, to the normally-open contacts of power relay K1. The hot side of the input power is also connected to the MAIN POWER switch (S9), located on the front panel of the reproduce amplifier module (RAM). When S9 is closed, K 1 is energized and applies 117 V ac primary power to the blower fan and to the +28 V dc power supply, via pins $A$ and $B$ of P155. The output of the 28 V power supply (P146 pins A and C) is applied to the tape transport via pins A and C of connector J147, located


Figure 3-24. Speed Change Relay Logic Schematic Diagram.
on the transport connector bracket. After passing through the dc line filter ( $\mathrm{FL}-1$ ), the +28 V dc is routed to the power switch assembly (TB5, terminal 1) which delays the application of full operating power to the recorder circuits, until proper bias levels have stabilized. Power relays in the power switch assembly must be activated by closing the TRANSPORT POWER switch (S1), on the front panel of the RAM, to fully energize the unit.

3-83. Once the TRANSPORT POWER switch has been closed, +28 V dc is routed from the power switch assembly (TB5, terminals 2 and 3 ) to the various transport circuits, through fuses F1 through F4. Diodes CR1 through CR4 provide reversevoltage protection in the event power supply polarity should become reversed. From the power switch, +28 V dc is also applied to the RAM, (P153, pins $F$ and $b$, and through fuses $F 1$ and F2) to operate the reproduce amplifiers, the dc-dc converter, and the various lamp indicators. The dc-dc converter provides regulated positive and negative 15 V dc to operate the FM signal electronics. The ELAPSED TIME meter, located on the transport connector bracket (Figure 2-3), is connected to +28 V dc through fuse F2. Ground return paths are provided by the control logic, through diodes CR5 through CR8, whenever the unit is placed in the FORWARD, REVERSE, FAST WIND, or FAST REWIND modes of operation. Thus, the ELAPSED TIME meter operates only during the time that tape is actually in motion acrọss the heads.

3-84. From fuse F4, the first leg of the 28 V primary power is routed
to the reel drive assembly (P33, pin 9), to operate the reel servo amplifier which, in turn, operates the reel motors. The second leg of the 28 V primary power is routed from fuse F 3 to the servo heatsink assembly (TB6, terminal 6) to operate the capstan motor power amplifier stages. Capstan motor power is applied through connector J34, pins $5(-)$ and $9(+)$. The third leg of the 28 V primary power is routed from fuse F2, through connector P20 (pin 3), to the BCD encoder (J26, pin W), and also to the control logic card (J24, pins 22 and $Z$ ), which serves to place the unit in the STOP mode when power is first applied. The fourth leg of the primary power is routed from fuse F1, through connector P20 (pin 1), to the voltage regulator (J25, pins 22 and Z) and to the reference frequency sinewave converter (J57, pin 1), via connector J59, pin 9 and P56, pin 32.

3-85. The voltage regulator provides regulated voltages of 24 V dc (J25, pins 19 and W), to operate the reproduce preamplifier regulator; 20 V dc ( J 25 , pins 20 and $Z$ ), to operate the tape break sensor, end-of-tape sensor, tape supply sensors, and circuits locatedin the logic, BCD encoder, capstan servo, and reel drive assemblies; 18.5 V dc (J25, pins 8 and J), to operate the record amplifiers; and 5 V dc (J25, pins 17 and U), to operate circuits in the logic, encoder, and capstan servo assemblies. The voltage regulator also supplies 10 V dc (J25, pins 18 and $V$ ) to the tachometer transducer, located in the capstan motor housing, via J34, pin 2.

3-86. Primary Power Supply. The +28 V dc power supply is a sealed unit, rated at 14 amperes full load, which
serves as the primary power source for the RD378/U. The specifications for this assembly are listed in Table 3-4, and a detailed schematic diagram is provided in Figure 5-6..

3-87. Power Switch Assembly. Refer to Figure 3-25. The power switch assembly permits proper bias levels to be established in the solid-stage circuits, before full operating voltage is applied to the unit. The +28 V dc input is applied through normallyclosed contacts of K1 to energize relay K2. With K2 energized, power is routed to the transport circuits through limiting resistor R2. From K2, power is also applied to relay K1, through limiting resistor R1. As a result of the time-constant provided by R1 and C1, activation of relay K1 is delayed for approximately 50 milliseconds, thus allowing circuit bias voltages to stabilize. After this brief delay, K1 energizes and applies full power to the unit. Once energized, K1 remains activated through resistors R1 andR2, now connected in series across the 28 V dc output of the power switch (TB4, terminals 2 and 3 ).

3-88. DC-DC Converter. The dcdc converter is used only when the FM record/reproduce signal electronics are installed. The converter accepts +28 V dc primary power input, and provides regulated $\pm 15 \mathrm{~V}$ dc outputs. The unit is an encapsulated, non-repairable module, which should be replaced as a complete assembly if a malfunction should develop.

3-89. VOLTAGE REGULATOR. Refer to schematic diagram, Figure 516. The voltage regulator operates directly from the +28 V dc primary
power to provide the following outputs.
a. +24 V dc for the reproduce preamplifier regulator.
b. +20 V dc for the capstan and reel drive circuits, control logic, BCD encoder, and sensor assemblies.
c. +18.5 V dc for the record amplifiers.
d. +10 V dc for the capstan tachometer.
e. +5 V dc for the capstan servo, BCD encoder, and control logic.

3-90. $\quad+24 \mathrm{~V}$ dc Regulator. The +24 V regulator is a series regulator, which consists of transistor Q5, zener diode CR8, and associated circuitry. This regulator supplies the reproduce preamplifiers regulator with +24 V dc input power. This regulator is not adjustable.

3-91. +18.5 V dc Regulator. The +18.5 V dc regulator provides operating voltage to the record amplifiers, and is only energized when the unit is in the RECORD mode of operation. The control amplifier (Q1) senses the output voltage across potentiometer $\mathrm{R} 8(+18.5$ V ADJUST), and compares this voltage to a reference voltage across zener diode CR1. Any variation in the output results in a correction voltage from the control amplifier to the base of Q1, on the servo heatsink assembly. The input 28 V dc is clamped by zener diode CR1 to operate the RECORD control circuit, in the control logic. Capacitor C2 is a timing capacitor which controls the turn-on/turn-off time of Q1, to

(1)1.1."

Figure 3-25. Power Switch Schematic Diagram.

TABLE 3-4. POWER SUPPLY SPECIFICATIONS
a. Input Voltage
b. Input Frequency
c. Output Voltage
d. Output Current
e. Regulation - Line and Load Combined
f. Ripple and Noise
g. Overload Protection
h. Magnetic Radiation
j. Operating Temp
k. Storage Temp

1. Maximum Weight

105-125V ac
$47-420 \mathrm{~Hz}$
28, $\pm 1.2 \mathrm{~V} \mathrm{dc}$
14.0 A, full load
$\pm 0.5 \%$, for worst case 105-125 V ac line and no-load to full-load change.

Less than 50 mV peak-to-peak for worst case $110-125 \mathrm{~V}$ ac line and no-load to full-load change. Less than 500 mV peak-to-peak for worst case 105 - 125 V ac line and noload to full-load change.

Greater than 20 A output.
Less than 0.5 gauss, 1 -inch from top surface.
$-20^{\circ} \mathrm{C}$ to $+55^{\circ} \mathrm{C}$ (circulated air)
$-55^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
15 lbs
permit a gradual build-up of the +18.5 V dc output, when the circuitis energized. This slow turn-on/turnoff prevents magnetization of the record heads, due to sudden voltage changes.

3-92. +20 V dc Regulator. The +20 V dc regulator consists of transistors Q3 and Q4, plus shunt regulator Q5, located on the servo heatsink assembly. The output of the +20 V regulator is adjusted by R15, located on the voltage regulator PWB.

3-93. +5 V dc Regulator. The +5 V dc required to operate the logic circuitry is developed by emitterfollower Q6. Base bias is established by zener diode CR10 and diode CR11, in the emitter leg, to maintain a constant +5 V dc output.

3-94. +10 V dc Regulator. The +10 V dc supply consists of zener diode CR7, inductor L1, and capacitor C4. CR7 limits the 20 V reference input to a 10 V level, which is supplied to the tachometer transducer in the capstan motor housing.

3-95. Preamplifier Regulator. Refer to Figure 5-6. The reproduce preamplifier regulator consists of an integrated circuit precision voltage regulator (U1) and associated components. The regulator is located on the interconnect PWB for the even numbered reproduce preamplifiers, and is used to supply +15 V dc preamplifier operating voltage.

3-96. MECHANICAL FUNCTION.
3-97. The two primary mechanical functions performed by the tape
transport are those performed by the capstan drive assembly and by the reel drive assembly. The function of the capstan drive is to drive the tape past the record/reproduce heads at a selected constant velocity, while maintaining uniform head-to-tape contact. The function of the reel drive is to unwind tape from the supply reel before it enters the head area, and wind it onto the take-up reel after it leaves the head area, while maintaining uniform tape tension at all times.

3-98. TAPE METERING. The tape metering function is accomplished by two elastomer-coated capstans having identical diameters, but driven at slightly different speeds, by a single servo-controlled dc motor. The capstans are driven such that the tape is controlled by the slower turning capstan as it enters the head area, and by the faster turning capstan as it leaves the head area. This creates a slight tension in the section of tape passing over the heads, and ensures uniform head-to-tape contact. The capstans are driven at slightly different velocities through the use of a two-diameter pulley, driven by the capstan motor, and coupled to the capstans by a pair of mylar drive-belts. Belt $A$ is threaded around both capstan pulleys and is driven by the smaller diameter of the two-diameter motor pulley. Belt B is also threaded around both capstan pulleys, but is driven by the larger motorpulley diameter. The capstans will turn at a velocity determined by the driving source which is "leading" the particular capstan pulley (i. e. ,the motor pulley which is PULLING the beltfrom around the capstan pulley). The tape is held in firm contact with the capstans by first passing around the wrap-rollers
which provide a wrap-angle of approximately 226 degrees around the capstans.

3-99. REEL DRIVE. The RD378/U uses separate dc motors to turn the supply and take-up reels, each of which is under the control of a separate closed-loop servo. The motors are mounted concentrically and are housed in a single reel motor assembly. The reel servos (and hence the reel motor torque) are controlled by two tension sensors located in the tape path. Refer to Paragraph 3-34 for description of sensor operation.

## CHAPTER 4

## SCHEDULED MAINTENANCE

## 4-1. INTRODUCTION.

4-2. Maintenance procedures described in this chapter are to be performed on a scheduled basis to reduce the possibility of catastrophic failure, and to maintain the unit at a satisfactory operating level.

4-3. PURPOSE.
4-4. The purpose of scheduled maintenance is to keep the unit operational at all times under all circumstances.

4-5. SCOPE.
4-6. The information provided in this chapter shall be used by all operator and maintenance personnel responsible for the unit. Operator and Maintenance personnel should have the rank of $\mathrm{E}-5$, or greater.

## 4-7. ARRANGEMENT OF SCHEDULED MAINTENANCE DATA.

## NOTE

The scheduled maintenance instructions in this manual are cancelled when the Planned Maintenance System (PMS) is implemented for this equipment aboard your ship or station.

4-8. The scheduled maintenance procedures are arranged in a logical sequence and are to be done as scheduled.

## 4-9. SCHEDULED MAINTENANCE ACTION INDEX.

4-10. Table 4-1 provides an index to scheduled maintenance. The table provides the period, required action, and appropriate paragraph to perform the action.

## 4-11. PREVENTIVE MAINTENANCE PROCEDURES.

4-12. The following information and procedures are to be used when performing scheduled maintenance. Be certain to observe all safety precautions and that all required tools and test equipment are available.

4-13. SAFETY PRECAUTIONS.

## CAU'TION

The unit operates at dangerous voltages. Turn off main circuit breaker for all procedures that do not require power to the unit. For those procedures that require power to the unit, observe all precautions normally followed in using and testing electronic equipment.

## 4-14. CLEANING MAGNETIC HEADS.

4-15. To minimize wear to the head surfaces, and to prevent signal degradation, it is very important to keep the magnetic heads clean at all times. This procedure should be performed daily.

TABLE 4-1. SCHEDULED MAINTENANCE ACTION INDEX

| Should be <br> Performed | Maintenance Action | Reference <br> Paragraph |
| :---: | :--- | :---: |
| Daily | Demagnetize Heads | $4-16$ |
| Monthly | Clean Heads | $4-14$ |
| Quarterly | Inspect and/or replace <br> Capstan Drive-belts | $4-18$ |
| Every 60 - <br> General Inspection for <br> damage or deterioration <br> of operation | Perform transport and <br> signal electronics adjust- <br> ments/alignments as <br> necessary. | Table 4-2 |

TABLE 4-2. ITEMS TO BE INSPECTED

| Item | Inspect For |
| :---: | :---: |
| Cabinet and Transport (General) | Physical damage. Illegible markings on controls and nameplates. Loose or missing hardware. |
| Controls, Indicators and Switches | Insecure mounting, missing lenses, loose knobs, proper operation. |
| Tapeguides and other rotating components | Smooth rotation. Damaged surfaces. |
| Heads | Dust, oxide or other foreign substances. Scratched tape surface. Damaged or excessive wear. |
| Connectors | Insecure mounting, bent or missing pins. Damaged shells. |
| Cables | Damaged insulation. Improper routing, kinks or twists. Loose clamps. |
| Printed Wiring Boards | Breaks, damaged components, proper seating in sockets. |
| Terminal Boards | Breaks, cracks, loose terminals. Insecure mounting. |
| Fuses | Damaged holders. Proper rating. |

## CAUTION

Avoid prolonged breathing of xylene fumes. Keep xylene away from open flame.
a. Tools, Parts, Material, and Test Equipment.

1. Xylene Federal Specification TT-X-916B.
2. Cotton swabs.
b. Procedure.

## 1. Refer to Figure 4-1.

2. Loosen two captive screws and remove headshield. Use extreme care so as not to scratch head surfaces.
3. Clean the face of the magnetic heads with a cotton swab dampened (not saturated) with Xylene, by wiping in the vertical direction along the head gaps.

## NOTE

Headstack should be degaussed after cleaning, while the headshield is still removed.
4. Reinstall headshield.

4-16. HEAD DEGAUSSING.
4-17. Heads should be degaussed (demagnetized) frequently to prevent loss of high-frequency data signals. Daily degaussing is recommended.
a. Tools, Parts, Material, and Test Equipment.

1. Head demagnetizer - Amplifier Corp. of America, Model 200-C.
b. Procedure.

## CAUTION

Do not turn off degausser while it is in the vicinity of the magnetic heads. Resulting directional magnetic field may remagnetize heads.

1. Refer to Figure 4-2.
2. Turn off recorder input power.
3. Remove tape and tape reels from transport.
4. Using a small pocket compass, check and degauss all tools which will be used near the head area.
5. Remove head cover and headshield, being extremely careful not to scratch the head surfaces.
6. Energize the degausser well away from the immediate head area (arms-length will suffice), and slowly bring the degausser into the head area.
7. Bring the degausser close enough to the headstack so that a definite strong attraction is felt. Do not permit physical contact between the degausser and the head surfaces.
8. Slowly move the degausser back and forth above the face of the headstack for 15 to 30 seconds.
9. Slowly remove the degausser from the head area, while at the same


Figure 4-1. Magnetic Head with Cover Removed.


Figure 4-2. Magnetic Head Degaussing.
time continuing a slow back-and-forth, or rotating, motion.
10. De-energize the degausser only after it is well away from the immediate head area.
11. Re-install head-cover and headshield.

4-18. CAPSTAN DRIVE-BELT REPLACEMENT.

4-19. After every 100 hours of operation or once each month, whichever occurs first, the capstan drive-belts should be inspected. If the belts do not show signs of wear or deterioration, simply clean and re-install. If cracks, nicks, or slippage are obvious replace belts as outlined in paragraph 6-53.

## CHAPTER 5

## TROUBLESHOOTING

## 5-1. INTRODUCTION.

5-2. This chapter provides troubleshooting instructions for the isolation of malfunctions in the recorder/reproducer. The troubleshooting instructions are limited to the isolation of faults to mechanical or dlectronic subassemblies. Replacement and repair instructions are provided in Chapter 6, Corrective Maintenance. Additional information which will be of value in troubleshooting may be found in Chapter 3, Functional Description. This chapter is divided into eight parts, which are interrelated. They are:

1. Troubleshooting index table.
2. Relay and lamp index table.
3. Protective device index table.
4. Troubleshooting procedures.
5. Maintenance turn-on procedure.
6. Troubleshooting diagrams.
7. Maintenance schematic diagrams.
8. Troubleshooting dependency diagram.

The troubleshooting index (Table 5-1) consists of the following:

1. Functional areas of the unit.
2. Troubleshooting paragraphs,
which serve as a help in isolating the malfunction.
3. Troubleshooting diagrams, which serve as an aid in isolating the malfunction.
4. Functional descriptions, which refer to paragraphs in Chapter 3 where the theory of functional areas is described.
5. Alignment/adjustment, which refers to paragraphs in Chapter 6.

5-3. The relay and lamp index (Table 5-2) consists of a table listing all the relays and lamps used in the recorder/ reproducer. Each relay and lamp is listed by its functional name and a troubleshooting diagram is provided to facilitate understanding of the function. The protective device index (Table 5-3) lists all fuses and circuit breakers in the unit and describes their functions. Toubleshooting procedures are contained in Table 5-4. This table presents a logical order of fault isolation through the use of measurements and indications of the unit. Maintenance turn- on procedure (Table 5-5) brings the unit from fully OFF to the ON condition and is described in a tabular form. Troubleshooting consist of signal flow (Figures 5-1 through 5-4), control diagram (Figure 5-5), and power distribution (Figure 5-6). These diagrams are presented using logical normal indications to isolate the fault. Figure $5-7$ is an intraunit interconnection diagram. Maintenance schematic
diagrams, which consist of the overall unit (Figure 5-8), transport assembly schematics (Figure 5-9), RAM assembly schematic (Figure 5-10), and subassemblies of the unit, (Figures 511 through 5-19) are provided. All the electronic components are identified. Troubleshooting dependency diagrams (Figure 5-20 through 5-23) show the functional dependency of a function or signal and also show a logical relationship of dependency to the next lower repairable level.

5-4. AC POWER. Power provided to the unit is 115 V ac 60 Hz . The 115 V ac is used to drive a cooling fan and utility lamp, and to supply input power to the +28 V dc power supply. For troubleshooting purposes refer to Table 5-4, step 1.

5-5. DC POWER. A +28 V dc power supply is used in the unit to provide power for all the lamps, relays, voltage regulator, and motors that are used in the transport section. Table 5-4, troubleshooting procedures, under step l, Power Distribution, gives a step-by-step troubleshooting sequence.

5-6. DIRECT RECORD. Should the unit record, a step-by-step procedure should be followed, as given in Table 5-4 troubleshooting procedure, step 3 , and Figure 5-20 troubleshooting dependency diagram.

5-7. DIRECT REPRODUCE. In the event that the unit will not reproduce, a systematic troubleshooting procedure is given in Table $5-4$, step 3. Also a dependency chart is given in Figure 5-22.

5-8. FAST WIND. Malfunctions of the fast wind mode are described in troubleshooting procedures, Table 5-4, step 2.

5-9. FAST REWIND. Malfunctions in the fast rewind mode are described in troubleshooting procedure, Table 5-4, step 2.

5-10. FM RECORD. A troubleshooting procedure in Table 5-4, step 4, and Figure 5-2l are provided for assistance in finding problems.

5-11. FM REPRODUCE. Table 5-4, troubleshooting procedures, step 4, describes a number of malfunctions that may correspond to FM reproduce problems. Also provided for assistance is Figure 5-23.

5-12. FORWARD. Table 5-4, troubleshooting procedures, step 2 , describes a number of malfunctions that may fit problems in this area.

5-13. REVERSE. Use Table 5-4, troubleshooting procedures, step 2, for assistance in rectifying problems.

5-14. INPUT SIGNAL. Refer to Table 5-4, step 3 (g.), and troublshooting dependency diagram for assistance in finding malfunctions.

5-15. OUT PUT SIGNAL. Refer to Table 5-4, step 3 (g.), and troubleshooting dependency diagram for assistance in finding malfunctions.

5-16. START. Refer to Table 5-4, troubleshooting procedures, step 2.

5-17. STOP. Refer to Table 5-4, troubleshooting procedures, step 2.

5-18. TAPE SPEED CONTROL. Refer to Table 5-4, troubleshooting procedures, step 2.

5-19. TAPE SPEED INDICATOR. Refer to Table 5-4, step 2.

5-20. Relay and Lamp Index is shown in Table 5-2, Protective Device Index is shown in Table 5-3. Troubleshooting Procedures are shown in Table 5-4, and Maintenance Turn-On Procedure is shown in Table 5-5.

## NOTE

Before consulting Table 5-4, check all voltages, using the VOLTAGE CHECK meter and control on the front panel of the RAM (except in cases where a known or obvious malfunction exists). This check may provide clues to the location of the malfunction.


Figure 5-1. Direct Record and Bias Amplifier Signal Flow Diagram.



Figure 5-2. FM Record Amplifier Signal Flow Diagram.


Figure 5-4. FM Reproduce Amplifier Signal Flow Diagram.




Figure 5-5. Control Diagram.











Figure 5-7. Intremit Intorconnection IVAmem.


Figure 5-8. Magnetic Tape Recorder/Reproducer Unit Schematic Diagram.







Figure 5-9. Transport Assembly Schematic Diagram.

## $\sqrt{\text { nemion }}$ <br>  <br> Nex <br>  <br> 




Figure 5-11. Preamplifier Schematic Diagram.


NOTES: UNLESS OTHERWISE SPECIFIED
A. RESISTOR VALUES ARE IN OHMS, 1/8W. : $5 \%$
B. CAPACITOR VALUES ARE IN MICROFARAOS, $100 \mathrm{~V}, \pm 10 \%$
C. ALL DIODES ARE 1 N914
D. All TRANSISTORS ARE $2 N 3227$
E. Ul AND U3 ARE DM7533D

PARTS LOCATION INDEX

| REf |  | REF |  | REF |  | REF |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DES | ZONE | DES | ZONE | DES | ZONE | DES | ZONE |
| ARI | 70 | 11 | 37 | R12 | 60 | TPl | 1 C |
| Cl | 7 E | 12 | 44 | R13 | 68 | 41 | 55 |
| C2 | 70 | QI | 78 | R14 | ${ }_{6} \mathrm{C}$ | U2 | 40 |
| C3 | 7 E | Q2 | 6 B | R15 | 60 | 43 | 3 F |
| C4 | 8 C | Q3 | 6 C | R16 | 50 |  |  |
| C5 | 7 C | Q4 | 6 C | R17 | 68 |  |  |
| C6 | 68 | Q5 | 58 | R18 | 5 C |  |  |
| C7 | 6 C | 06 | 5 C | R19 | 6A |  |  |
| C8 | 50 | Q1 | 20 | R20 | 4 C |  |  |
| C9 | 20 | Q8 | 20 | R21 | 4 A |  |  |
| C10 | 10 | 09 | 20 | R22 | 50 |  |  |
| Cl | 4 C |  |  | R23 | 50 |  |  |
|  |  | R1 | 8 E | R24 | 2 F |  |  |
| CR1 | 6 C | R2 | 8E | R25 | 2 F |  |  |
| CR2 | 08 | R3 | 碞 | P20 | 30 |  |  |
| CR3 | 68 | R4 | $7 E$ | R27 | 3 C |  |  |
| CR4 | 68 | R6 | 70 | R28 | 2 E |  |  |
| CRS | 5B | R7 | 70 | R29 | 20 |  |  |
| CR6 | 5 C | R8 | 7 E | R30 | 2 C |  |  |
| CR7 | 50 | R9 | 70 | R31 | 6 A |  |  |
| CR8 | 58 | R10 | 7 A | R32 | 78 |  |  |
| CR9 | 6 A | RII | $7 C$ | R33 | 48 |  |  |

$$
\begin{aligned}
& \text { MESS OTHERMISE SPECIFED }
\end{aligned}
$$



NOTES: UNLESS OTHER WISE SPECIFIED.
A. RESISTOR VALUES ARE IN OHMS. $\pm 5 \%$ : $/ 8 \%$
B. CAPACITOR VALUES ARE IN MICROFARADS.
C. clodes are janinalis.
0. Last reference designations used are-

> C42, CR16. FL6, L11, Q7. R60, U7. Y2.
E. REFERENCE DESIG:ATIONS NOT USED:

C16 THRU C2O Q1, Q2, R2O THRU R25, R29. R39 THRU R 22 . 12. 14. AND Y1.
[F. SEE TABLE A FOR values.
G. REFERENCE DRAWINOUS: ASSEMBLY 85006-1-1
$8500641-2$

| $\begin{aligned} & \text { REF } \\ & \text { DES } \end{aligned}$ | ZONE | REF | ZONE | $\begin{aligned} & \text { REF } \\ & \text { DES } \end{aligned}$ | ZONE | REF DES | 203E | $\begin{aligned} & \text { REF } \\ & \text { DES } \end{aligned}$ | ZOAE | $\begin{aligned} & \text { REF } \\ & \text { DES } \end{aligned}$ | ZONE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Cl | 13F | C30 | 5 C | CRII | 68 | Q4 | \% | R21 | 10 C | R52 | 3 A |
| C2 | 12 F | C31 | 68 | CR12 | 5 A | Q5 | 8 | R22 | 88 | R53 | 3 A |
| C3 | 12 F | C32 | 5 C | CR13 | 3 C | Q6 | \% | R23 | 7C | R54 | 2 C |
| C4 | 12F | C33 | 4A | CR14 | 2 A | Q1 | 48 | R26 | 4 C | R55 | 18 |
| CS | $11 \%$ | C34 | 4 A | CR15 | 10 C |  |  | R27 | 3 C | R56 | 1B |
| C6 | 11F | C35 | 3 B | CR16 | 5 C | R1 | 1F | R23 | 2 C | R57 | 1A |
| C7 | $3 F$ | C36 | 38 | F! | 95 | R2 | W | R30 | 98 | R58 | 45 |
| C8 | 3 E | C37 | $2 B$ | Fll | 8 C | R3 | 125 | R31 | 88 | R59 | 4E |
| C9 | 3 F | C38 | 2 A | Fl2 | 8 | R4 | 227 | R32 | 88 | R60 | 9A |
| Cl0 | 35 | C39 | 18 | FL3 | 7 | R5 | 3 F | R33 | 7B |  |  |
| Cll | 4E | C40 | 18 | Fld | 65 | R6 | IIF | R34 | 68 | U1 | 135 |
| $\mathrm{Cl2}$ | 7 C | C41 | 10 | F15 | 6 F | R7 | 3 BC | R35 | 58 | U2 | 130 |
| C13 | 6 C | CQ | 8 A | Fto | 55 | R8. | 1 BC | R36 | 3 C | U3 | 10 E |
| C14 | 7 C |  |  | 11 | 40 | R9 | 1 LC | 837 | 3 C | 1 | 4 C |
| C15 | 30 | CR1 | 130 | L3 | 30 | 910 | me | 23: | 30 |  | 58 |
| C21 | 11 C | CR2 | 12 C | 15 | 98 | R11 | MIT | R43 | 8 A | 17A | S8 |
| C22 | 108 | CR3 | 12 C | 16 | 98 | R12 | IL | Re4 | 8 A | U7P | 48 |
| C23 | 98 | CR4 | 12 C | 17 | 9 C | R13 | 45 | R45 | 8A | 17 C | 38 |
| C24 | 8A | CRS | 11 C | 18 | 8 C | R14 | 37 | R40 | 8A | 170 | 3 A |
| C25 | 8 B | CR6 | 11 C | 19 | 4A | R15 | 4 E | R47 | 7A | U70 | 3 A |
| C26 | 88. | CR7 | 10 C | 110 | 20 | R16 | 4 | R48 | 7A | Y2 | $2 B$ |
| C27 | 7A | CR8 | 78 | [1] | 1 C | R17 | 37 | R49 | 7A |  |  |
| C28 | 6A | CR9 | 78 |  |  | R18 | 31 | R50 | 6 A |  |  |
| C29 | 6 A | CR10 | 68 | Q3 | 98 | R19 | 4 E | RSI | 58 |  |  |


| TABLE A |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { USED ON } \\ & \text { ASSESETY } \end{aligned}$ | R6 | C6 | 516 |  |
| 84, mat! | 10 | (5) 10\% $10 \%$ | 45s. 850042 | s-u. |
| Sucta: | 1.36 |  | A De Satat. |  |

NOTES: UNLESS OTHERWISE SPECIFIED
A. All RESISTOR VALUES ARE iN OHMS, $1 / 8 \mathrm{iv}, \pm 5 \%$.
8. ALL NONPOLARISED CAPAC:TOR VALUES ARE IN PICO FAREDS, $\pm 5 \%$. 5OV.

ALL POLARISED CAPACITORS ARE + KO\%
c. All diodes are jan liggla.
D. ALL IRANSISTORS ARE JAN325IA.
E. REFERENCE DRAWINGS: ASSEMBly DRA:HNOS 85006591-BSC ANO 85006591-1.
f. Last regerence designaturs used: C38, CR29, 16, Q23, R88, TP4.
G. All REACTOR VALUES ARE iN MICROHENERYS.
H. REFERENCE DESIG:ATIONS MT USED RS, 23, 25, 27. \& 78, CS, 9, 19, 20, 27, 31, \& 33

1. SEE TABLE A FOR VAlues (NOTE: RIG is a VARIABLE RESISIOR ON THE BSC ASSEMBIY AND A FIXED RESISTOR ON THE -I ASSEMBLY. 1

PARTS LOCATION, INDEX

| REF |  | REF |  | REF |  | REF |  | REF |  | REF |  | REF |  | REF |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DES | ZONE | DES | 20NE | DES | ZONE | DES | ZONE | DES | ZONE | DES | 20NE | DES | zone | DES | 20v5 |
| Cl | 157 | C30 | 3 E | CR17 | 6E | Q4 | 14F | R4 | 140 | 832 | 110 | 8.56 | 6 C | R81 | 3 C |
| C2 | $15 E$ | C32 | 30 | CR18 | 60 | Q5 | 145 | R6 | 14 C | R33 | IIC | R57 | 60 | R82 | 2 F |
| C3 | 14E | C34 | 20 | CR19 | 5 E | Q6 | 14F | R7 | 14 C | R34 | 100 | R58 | 6 C | R83 | 2E |
| C. | 140 | C35 | 20 | CR20 | 50 | Q7 | 13F | R8 | $14 E$ | R35 | 100 | R59 | 60 | R94 | 20 |
| Cl | 14 C | C36 | SE | CR21 | SE | Q8 | 13F | R9 | 148 | R36 | 10 C | R60 | 6 C | R85 | 2D |
| C7 | 120 | C37 | 4 E | CR22 | 50 | Q9 | 138. | R10 | 145 | R37 | 100 | R61 | 50 | R96 | 2C |
| C8 | 120 | C38 | 3C | CR23 | 5 E | Q10 | 12 E | R11 | $14 E$ | R38 | 90 | R62 | 5 C | R87 | 5 E |
| C10 | 110 |  |  | CR24 | 50 | Q11 | 12 E | R12 | 148 | R39 | 9 C | R63 | 50 | R88 | $6 E$ |
| Cll | 110 | CR1 | 110 | CR25 | 3 E | Q12 | 7 E | R13 | 148 | R40 | 90 | R64 | 5 C |  |  |
| Cl 2 | 100 | CR2 | 11 C | CR26 | 3 F | Q13 | $7 E$ | R14 | 135 | R41 | 90 | R65 | 50 | PP1 | 135 |
| Cl 3 | 90 | CR3 | 110 | CR27 | 3 E | Q14 | 4E | R15 | $13 E$ | R4? | 9 C | R66 | 5 F | TP2 | 50 |
| C14 | 90 | CR4 | 10 C | CR28 | 2 E | Q15 | $4 E$ | R16 | $13 E$ | R43 | 80 | R67 | SC | TP3 | 30 |
| Cl 5 | 80 | CR5 | 100 | CR29 | 20 | Q16 | 4 E | R17 | $13 E$ | R44 | 8 C | R68 | 4 | IP4 | 130 |
| Cl 6 | 8 C | CR6 | 10 C |  |  | Q17 | 35 | R18 | $13 E$ | R45 | 8 D | R69 | 40 |  |  |
| C17 | 8 C | CR7 | 90 | 11 | 110 | Q18 | 3 E | R19 | $13 E$ | R46 | 8C | R70 | 4 C |  |  |
| C18 | 7 C | Cob | 9 C | 12 | 110 | Q2. | 28 | 20 | 130 | 56 | 83 | R11 | $\therefore$ |  |  |
| C21 | 60 | CR9 | 90 | 13 | 100 | Q20 | 2 E | R21 | 127 | R48 | 7 | R72 | 4 C |  |  |
| C22 | 60 | CR10 | 8 C | 14 | 90 | Q21 | 20 | R22 | 12 | R49 | 7 C | R73 | 4 C |  |  |
| C23 | 60 | CRII | 8 D | 15 | 90 | Q22 | 30 | R24 | 12 C | R50 | 7 E | R74 | 3 E |  |  |
| C24 | 50 | CRI2 | 8 C | 16 | 80 | Q23 | 6 E | R26 | IIE. | R51 | 7 E | R75 | 30 |  |  |
| C25 | 50 | CRI3 | 7 E |  |  |  |  | R28 | 115 | R52 | 7 C | R76 | 30 |  |  |
| Q6 | 50 | CR14 | 70 | Q1 | 157 | R1 | $15 E$ | R29 | 110 | R53 | 70 | R77 | 30 |  |  |
| C28 | SE | CR15 | $6 E$ | Q2 | 140 | R2 | 157 | R30 | 11 C | RS4 | 1 C | R79 | 3 C |  |  |
| C29 | 4 C | CRI6 | 60 | Q3 | 14 C | R3 | 150 | R3! | 110 | R55 | 7C | R80 | 30 |  |  |
|  |  |  |  |  |  |  | ASIE |  |  |  |  |  |  |  |  |
|  |  |  |  |  | EMEIY |  |  | UUES |  |  |  |  |  |  |  |
|  |  |  |  |  | T NO. | 16 |  |  | C15 | C20 |  |  |  |  |  |
|  |  |  |  |  | 591-8SC | 514 |  |  | 11005 | 4ropt |  |  |  |  |  |
|  |  |  |  |  | 5n1-1 | Sor: | 2. | , | !? $=$ | 22: |  |  |  |  |  |






Figure 5-14. Direct Reproduco Amplifier Schematic Diagram.




NOTE: ALL RESISTORS 0.5W, 5\%
ALL CAPACITORS UF
unless otherwise specified.

001-090
Figure 5-16. Voltage Regulator Schematic Diagram.

NOTES: UNLESS OTHERWISE SPECIFIED
A. RESISTOR VALUES ARE IN OHMS, 1/4W. $\pm 5 \%$
B. CAPACITOR VALUES ARE IN MICROFARADS, IOV. $+20 \%$
C. All DIODES ARE TYPE INOIA
D. AlL TRANSISTORS ARE TYPE 2 N2222
E. U7 AND US ARE 848́a
F. US ANO UG ARE S8481A
G. PIN 7 ON UA THRU US IS GROUND
H. PIN 14 ON U4 THRU U8 IS 5VDC
l. 24 is S8880A
J. LAST REEERENCE DESIGNATIONS USED, TP2. AR3. C34, CRII, LA R56, QIO. U12 AND Yl
K. reference designation not used, c32 and ug

PARTS LOCATION INDEX

| REF |  | REF |  | REF |  | REF |  | REF |  | REF |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| des | ZONE | DES | ZONE | des | ZONE | DES | 20NE | DES | ZONE | DES | $20 N$ |
| ARI | HE | C23 | 12C | 13 | 50 | R13 | 118 | R38 | 6 C | UAA | 9 A |
| AR2 | 108 | C24 | 4 D | 14 | 4C | R14 | 11 A | R39 | 50 | U48 | 9 A |
| AR3 | 4 D | C25 | 5 C |  |  | R15 | 118 | R40 | 50 | U4C | 98 |
|  |  | C26 | 5 C | Q1. | 118 | R16 | 108 | R41 | 40 | U40 | 98 |
| Cl | 12 F | C27 | 4 C | Q2 | 11. | R17 | 108 | R42 | 4 D | U5A | 90 |
| C2 | 12 t | C28 | 40 | Q3 | 10 A | R18 | 118 | R43 | 40 | U5B | 100 |
| C3 | 127 | C29 | 40 | Q4 | 98 | R19 | IIA | R44 | 3 C | U5C | $7 C$ |
| C4 | 12 E | C30 | 4 C | Q5 | 9 9 | R20 | 10 A | R45 | 3 C | uso | 7 C |
| C5 | 12 E | C31 | $3 C$ | Q6 | 5 | R21 | 10A | R46 | 3 C | U6A | 68 |
| C6 | 112 | C33 | $3 E$ | Q1 | 2 F | R22 | 98 | R47 | $2 \varepsilon$ | U68 | 8 C |
| C8 | 12 A | C34 | 10 A | 9 | S | R23 | 98 | R48 | 2 E | U6C | 8 D |
| C9 | 118 |  |  | (10 | 3 | R24 | 9 A | R49 | 30 | U60 | ${ }_{6} \mathrm{C}$ |
|  | 18 | CRI | 120 | Q10 | 2 | R25 | 9A | RSO | $2 E$ | U7A | 110 |
| ClO | 118 | CR2 | 120 | R1 | 12E | R26 | 8A | R51 | 25 | UTE | 110 |
| Cll | 108 | CR3 | 120 | R2 | 12E | R27 | 8A | R52 | 6 C | UTC | 11. |
| C 12 | 98 | CR4 | 12 C | R3 | 115 | R28 | 120 | R53 | 20 | 070 | 110 |
| Cl 3 | 8A | CR5 | 12C | R4 | HE | P\% | 120 | 2.54 | 3 | 18. | :\% |
| C14 | 95 | CRS | 120 | R 5 | 116 | R30 | 120 | R55 | $3 E$ | U88 | IIC |
| C15 | 60 | CR7 | 12 C | RS |  |  |  | P56 | 35 | 180 |  |
| C16 | 10A | CR8 | 2 E | R6 | IIE | R31 | 120 | RS6 | 3 |  |  |
| Cl 17 | 120 | CR9 | $2 E$ | R7 | 10 E | R32 | 12 C | TP1 | 30 | Ulo | 8 A |
| C18 | 120 | CR10 | 35 | R8 | 128 | R33 | 12 C | TP2 | 5 C | UII | 7A |
| C19 | 120 | CRII | 30 | R9 | 12A | R34 | 128 |  |  | U12 | 7 A |
| C2O | 120 |  |  | R10 | 12 A | R35 | of | Ul | 10E |  |  |
| C21 | $12 C^{\prime}$ | 11 | 129 | R11 | 11A | R36 | 3 B | U2 | $9 E$ | Yl | 12 E |
| C22 | 120 |  |  | R12 | 128 | R37 | 50 | 43 | 76 |  |  |





Figure 5-17. Capstan Scrvo Schematic Diagram.


Figure 5-18. Servo Power Amplifier Schematic Diagram.

NOTES: UNLESS OTHERWISE SPECIFILO
A. RESISTOR Values are is OHMS, $1 / 4 \mathrm{~W}, \pm 5 \%$
B. CAPACITOR VALUES ARE IN MICORFARADS. $\pm 20 \%$
C. AlL DIODES ARE IW914
D. ALL TRANSISTORS ARE $2: 1711$
E. Ul AND U4 ARE 584304
F. U2, U3 AND US ARE SSAL6A
G. U6 is S8731A
H. PIN NO. 1 ON UG is connected to ground
I. PIN NO. 7 ON UI THRU US is CONNECTED TO GROUND
J. PIN NO. 14 ON UI THRU US is CONECTED TO 5VDC
K. LaSt REEERENCE DESIG:MIIONS USED ARE Q20, R58. R19, CR4O, UG AND LI. REERENCE DESIGNATIO: NS NOT USED ARE CR13, CR22 THRU CR29 A.V CR33
L. C19 NOT USED ON S400T81-1 ASSEMBLY
part location index

| REF |  | REF |  | REF |  | REF |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DES | ZONE | DES | ZONE | DES | ZONE | DES | 20N5 |
| Cl | 12 F | CR20 | 8 C | R3 | 2 E | R40 | 2 B |
| C2 | $11 F$ | CR21 | 8 F | R4 | 3 E | R41 | 2 C |
| C3 | 20 | CR30 | 10 C | R5 | $3 F$ | R42 | 28 |
| C4 | 45 | CR31 | 10 C | R6 | 40 | R43 | 38 |
| C5 | 57 | CR32 | 12 C | R7 | 4 E | R44 | 38 |
| C6 | $6 F$ | CR34 | 10F | R8 | 40 | R45 | 38 |
| C7 | 5 F | CR35 | 18 | R9 | 40 | R46 | 43 |
| C8 | 7 | CR36 | $2 B$ | R10 | $5 F$ | R47 | 18 |
| C9 | 9 C | CR37 | 3 B | RII | 50 | R48 | 5 C |
| C10 | 9 C | CR38 | 3 C | R12 | 6 C | R49 | $5 B$ |
| CII | 9 C | CR39 | 4 C | RI3 | 6 C | R50 | 58 |
| Cl 2 | 10 C | CR40 | 6 F | R14 | 50 | R51 | 5B |
| ${ }^{C 13}$ | 8 A | 11 | 12 | R15 | 5 F | R52 | SB |
| Cl 4 | 8 C | [1 | 12 | R16 | 6 C | R53 | 8 C |
| ${ }^{C 15}$ | $8{ }^{85}$ | O1 | 30 | R17 | 77 | RS4 | 120 |
| ${ }^{C 16}$ | 8 F | Q2 | - 3 E | R18 | 8 C | RS5 | 12 C |
| C17 | 105 | Q3 | 40 | R19 | 7 C | R56 | 6 C |
| C 18 | 10 F | Q4 | 40 | R20 | IC | Q 27 | 58 |
| C19 | 4 C | Q 0 | 12 | R23 | 90 | nos | 58 |
| CR1 | 30 | Q6 | 50 | R22 | 9 C |  |  |
| CR2 | 20 | 01 | 68 | R23 | 90 |  | 40 |
| CR3 | 3 E | 08 | 8 C | R24 | 10 C | U18 | 50 |
| CR4 | 7 C | Q9 | 7 C | R25 | 10 C | U1C | ${ }^{6} \mathrm{C}$ |
| CRS | 7 C | Q10 | 8 B | 226 | 108 | U10 | 70 |
| CR6 | 110 | Q11 | 10 C | 227 | 98 | U2A | 4 D |
| CR7 | 110 | Q12 | 110 | R28 | 8A | 1228 | 50 |
| CR8 | 50 | Q13 | 11 C | 829 | 85 | U3A | 60 |
| CR9 | 60 | Q14 | 28 | R30 | 7E | U38 | 60 |
| CR10 | 5 E | Q15 | 28 | \$31 | 10 C | 44 | 100 |
| CRII | 70 | Q16 | 38 | $R 32$ | 100 | 448 | 98 |
| CR12 | 80 | 017 | 45 | 233 | 100 | U4C | 88 |
| CR14 | 9 C | 018 | 5 C | R 34 | 10 C | 440 | 80 |
| CR15 | 9 C | Q19 | 58 | 295 | 10E | USA | 90 |
| CR16 | 9 C | Q20 | 5 A | \$36 | 11 C | USB | 100 |
| CR17 | 10 C |  |  | R37 | 11 C | UGA | 9 Q |
| CRIS | 98 | R1 | 30 | R 38 | 18 | U6B | 90 |
| CR19 | 88 | R2 | 32 | \$39 | 18 | USC | 75 |

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Figure 5-20. Direct Record and Bias Amplifier Dependency Diagram.


NOTE:
A. CORRESPONDS TO SIGNAL FLOW DIAGRAM FIG. 5-2 FM RECORD AMPLIFIER.

Figure 5-21. FM Record Amplifier Dependency Diagram.


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Figure 5-22. Direct Reproduce Amplifier Dependency Diagram.


Figure 5-23. FM Reproduce Amplifier Dependency Diagram.

TABLE 5-1. TROUBLESHOOTING INDEX

| Functional <br> Area | Trouble- <br> shooting <br> Paragraph | Trouble- <br> shooting <br> Diagram | Functional <br> Description <br> Paragraph | Alighment <br> Adjustment <br> Paragraph |
| :--- | :---: | :---: | :--- | :---: |
| AC Power | $5-4$ | $5-6$ | $3-79$ | Not Adjustabl، |
| DC Power | $5-5$ | $5-6$ | $3-80$ | $6-35$ |
| Direct Record | $5-6$ | $5-12$ | $3-48$ | $6-16$ |
| Direct Reproduce | $5-7$ | $5-14$ | $3-63$ | $6-19$ |
| Fast Wind | $5-8$ | $5-19$ | $3-15$. | Not adjustablt |
| Fast Rewind | $5-9$ | $5-19$ | $3-15$ | Not adjustabl |
| FM Record | $5-10$ | $5-13$ | $3-54$ | $6-26$ |
| FM Reproduce | $5-11$ | $5-15$ | $3-71$ | $6-30$ |
| Forward | $5-12$ | $5-19$ | $3-12$ | Not adjustabl |
| Reverse | $5-13$ | $5-19$ | $3-14$ | Not adjustabl |
| Input Signals | $5-14$ | $5-12,5-13$ | $3-50,3-54$ | Not adjustabl |
| Output Signals | $5-15$ | $5-14,5-15$ | $3-70,3-77$ | Not adjustabl |
| Start | $5-16$ | $5-19$ | $3-12$ | Not adjustabl |
| Stop | $5-17$ | $5-19$ | $3-12$ | Not adjustabl |
| Tape Speed Control | $5-18$ | $5-9,5-17$ | $3-20$ | Not adjustabl |
| Tape Supply Ind. | $5-19$ | $5-19$ | $3-43$ | $6-39$ |

TABLE 5-2. RELAY AND LAMP INDEX

| Reference <br> Designation | Functional Name | Energizing Voltage | Troubleshooting Diagram (Figure No.) |
| :---: | :---: | :---: | :---: |
| 1A3S9DS1 | MAIN POWER Indicator | +28 V dc | 5-10 |
| 1A3S1DS1 | TRANSPORT POWER Indicator | +28 V dc | 5-10 |
| 1A3S2DS1 | FORW ARD Indicator | +28 V dc | 5-10 |
| 1A3S3DS1 | RECORD Indicator | +28 V dc | 5-10 |
| 1A3S4DS1 | REVERSE Indicator | +28 V dc | 5-10 |
| 1A3S5DS1 | FAST REWIND Indicator | +28 V dc | 5-10 |
| 1A3S6DS1 | FAST WIND Indicator | +28 V dc | 5-10 |
| 1A3S7DS1 | STOP Indicator | +28 V dc | 5-10 |
| 1A1ADS2 | Service Lamp | 115 V ac | 5-6 |
| 1A3A2DS1 | STATUS Indicator (11 lamps) | +28 V dc | 5-10 |
| 1A3M1 | TAPE SUPPLY Indicator | +5 V dc | 5-10 |
| 1A2A1A2DS1 | Tape Supply Sensor Lamp | +28 V dc | 5-6 |
| 1A3M2 | VOLTAGE CHECK Indicator | Measured Voltage | 5-10 |
| 1A1PS1K1 | Power Distribution | 115 V ac | 5-6 |
| 1A3K1 | Power Switch Relay | +28 V dc | 3-26 |
| 1A3K2 | Power Switch Relay | +28 V dc | 3-26 |

TABLE 5-3. PROTECTIVE DEVICE INDEX

| Reference Designation | Front Panel Marking | Rating |  | Circuit Protected | Troubleshooting Diagram |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Volts | Amps |  |  |
| 1A1PS1CB1 | None | 115 | 20 | Unit Power | Figure 5-6 |
| 1A3F1 | None (Rear) | 28 | 5 | Reproduce Amps. | Figure 5-6 |
| 1 A 3 F 2 | None (Rear) | 28 | 5 | Indicator | Figure 5-6 |
| 1A2A1F1 | REGULATOR <br> F1 5 AMP | 28 | 5 | Regulator Circuits | Figure 5-6 |
| 1A2A1F2 | $\begin{aligned} & \text { LOGIC F2 } \\ & 2 \text { AMP } \end{aligned}$ | 28 | 2 | Logic Circuits | Figure 5-6 |
| 1A2AF3 | CAPSTAN F3 5 AMP | 28 | 5 | Capstan Circuits | Figure 5-6 |
| 1A2AF4 | REEL DRIVE F4 7 AMP | 28 | 7 | Reel Drive Circuits | Figure 5-6 |

TABLE 5-4. TROUBLESHOOTING PROCEDURE

| Trouble Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| 1. Power Distribution <br> a. No 115 V ac input to unit. | No input. | After switching CB1 On, switch the utility light On, using the service switch. | Figure 5-6 | Check continuity of interconnecting power cable. |
|  | Power <br> Relay malfunction. | Check pin A to B of P145 for 115 V ac after switching the MAIN POWER switch On. | Figure 5-6 | Replace power relay if the MAIN POWER switch indicator is On. |
| No +28 V dc on meter. | Defective fuse. | Check fuse 1A3F2 on back panel of RAM. | Figure 2-2 (sheet 2), and 5-6 | Replace defective fuse. |
|  | Probable Short. | Check circuit breaker CB1 for tripped condition (OFF). | Figure 5-6 | a. Ensure that all switches are Off. <br> b. Locate short and repair or replace as required. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)


TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)


TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| No +18.5 V dc when in the RECORD mode. | Defective control | Simultaneously press the RECORD and FORWARD switches, while checking that J25 pin 5 has zero volts. | Figure 5-16 | Replace control logic board. |
|  | Defective power amplifier heat sink. | Check regulated +28 V dc on P22 pin 1. | Figure 5-16 | Replace power amplifier heat sink. |
|  |  | Check for +18.0 V dc on P22 pin 2. | Figure 5-16 | Replace power amplifier heat sink. |
| No +15 V dc | Voltage regulator. | Check for +24 V dc on pin 19 of J 25. | Figure 5-6 | Replace voltage regulator. |
|  |  | Check for +15 V dc on E1 of J30. | Figure 5-6 | Replace the voltage regulator in the 15 V regulator and preamp interconnect assembly (even). |
| 2. Transport |  |  |  |  |
| a. Tape speed malfunction. | Defective servo amplifier. | Check if reference oscillation output at J105 is correct for speed selected, table 3-1. | Figure 3-3 | Replace capstan servo amplifier. |
|  |  | Check for +10 volts from the voltage regulator on J 25 pin 18. | Figure 5-16 | Replace voltage regulator. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
|  | Tachometer | Check tachometer lamp power from power amplifier servo heat sink on TB6-1 (+). and TB6-2 (-). | Figure 5-16 | Replace power amplifier heat sink. |
|  |  | Check for a tachometer signal output at pin Z. J26. | Figure 5-9 | Replace motor assembly per paragraph 6-37. |
|  |  | Check for a tachometer signal input to the capstan servo amplifier on J23 pin 16. | Figure 5-9 | Replace BCD encoder. |
| b. Transport Malfunction |  |  |  |  |
| Tape won't stop. | Defective logic control board. | Check J23 pins 5 and E for zero volts when STOP switch is pressed. | Figure 5-19 | Replace logic control board |
| Runs at high speed when not in FAST WIND mode. | Defective control. | Using a card extender, check if J 23 pins 11 or $M$ are at zero volts. | Figure 5-19 | Replace control logic board if reading is zero volts. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
|  | Defective <br> capstan servo board. | Check reference oscillator output at J105 or J23 pins $F$ or 6 for speed other than selected speed. Table 3-1. | Figure 5-17 | Replace capstan servo board |
|  | Defective tachometer. | Check for a tachometer signal input at capstan servo board J23 pins T or 16 . | Figure 5-16 |  |
|  |  | Check for a tachometer signal output on J26 pin Z. |  | Check step 2. a (tape speed malfunction) before replacing motor assembly per paragraph 6-53. |
| Improper tape tension. | Defective tape tension sensor lamp. | Check tape tension lamp | Figure 6-12 | Replace tape sensor lamp (paragraph 6-48). |
| Tape reel will not turn. | Defective control logic board. | Using a card extender, check J24 pins P or 13 for approximately +28 V dc . | Figure 5-19 | Replace control logic board. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
| Unit will not go into REVERSE mode. | Capstan servo board. | Check reference frequency oscillator for selected speed at J105. | Figure 5-17 | Replace capstan board. |
|  | Control logic board. | Check J24 pin 6 for zero volts. | Figure 5-19 | Replace control logic board. |
|  | Servo power amplifier. | Check relay K1 in servo power amplifier. | Figure 5-18 | Replace servo power amplifier. |
| Tape supply meter does not indicate proper tape level. | Tape sensors. | Refer to paragraph 6-39 for adjustment of tape sensors. | Figure 3-16 | Adjust or replace as required. |
| c. Flutter exceeds $0.45 \% \mathrm{P} / \mathrm{P}$ from 0.2 Hz to 2.5 Hz . | Tape-guide bearings. | Inspect bearings. Refer paragraph 6-49. | Figure 7-1 | Replace bearings as required. |
|  | Phase lock marginal. | Check capstan, servo phase-lock signal. Refer to paragraph 3-24. | Figure 3-6 | Replace capstan servo amplifier. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble <br> Symptom | Probable <br> Cause | Isolation Procedure | Reference | Corrective Action |
| :--- | :--- | :--- | :--- | :--- |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble <br> Symptom | Probable Cause | Isolation Procedure | Reference | Corrective Action |
| :---: | :---: | :---: | :---: | :---: |
|  | Head magnetized. | Demagnetize head paragraph 4-16. | Figure 4-2 | Demagnetize head. |
|  | Head worn. | If high-frequency response remains out of specification after the above two steps have been performed, and if the head has been in operation for 1,000 hours or more, replace the head. | Figure 6-14 | Replace head if required. See paragraph 6-51. |
| c. Signal-tonoise ratio is not within | Direct- <br> Reproduce amplifier. | Check reproduce amplifier. See paragraph 6-19. | Figure 6-3 | Adjust or replace reproduce amplifier if necessary. |
|  | Noisy tape. | Replace tape. |  | Degauss and retest removed tape. |
|  | Magnetized head. | Refer to paragraph 4-18. | Figure 4-2 | Degauss head. |
| 4. FM Record/Reproduce Functions |  |  |  |  |
| a. Improper center frequency deviation. | FM-record amplifier. | Check adjustments. Refer to paragraph 6-23. | Figure 6-6 | Adjust or replace FM-record board. |

TABLE 5-4. TROUBLESHOOTING PROCEDURE (Cont'd)

| Trouble <br> Symptom | Probable <br> Cause | Isolation Procedure | Reference | Corrective Action |
| :--- | :--- | :--- | :--- | :--- |
| b. Output | FM repro- <br> duce <br> amplifier. | Check reproduce ampli- <br> fier. Refer to paragraph <br> $6-30$. | Figure 6-8 | Replace FM repro- <br> duce amplifier if <br> required. |

TABLE 5-5. MAINTENANCE TURN-ON PROCEDURE

| STEP | OBSERVE | REFERENCE |
| :---: | :---: | :---: |
| 1. Preliminary procedure for turning power ON. <br> a. Open transport and turn circuit breaker to ON position. <br> b. Close and latch transport and press the MAIN POWER switch. <br> c. Press the TRANSPORT POWER switch. | Place service lamp switch (located immediately above circuit breaker) in ON position. Service lamp should light. Turn service lamp off. <br> MAIN POWER switch indicator will light and the fan will come on. <br> TRANSPORT POWER and STOP switch indicators will light. Selected speed is indicated on status indicator. (If the tape reels are not on the transport with the tape threaded, the TAPE BREAK and END-OFTAPE will light on the status indicator. | Refer to Table 5-4, Power Distribution |
| d. Position VOLTAGE check switch to 5 V . <br> e. Position VOLTAGE check switch to 15 V . | Meter should indicate +5 V dc. <br> Meter should indicate +15 V dc. | Refer to Table 5-4, Power Regulation |
| f. Position VOLTAGE check switch to 20 V . | Meter should indicate +20 V dc. |  |
| g. Position VOLTAGE check switch to 28 V . | Meter should indicate +28 V dc. |  |

TABLE 5-5. MAINTENANCE TURN-ON PROCEDURE (Cont'd)


## CHAPTER 6

CORRECTIVE MAINTENANCE

## 6-1. INTRODUCTION.

6-2. This chapter provides corrective maintenance information on the Magnetic Tape Recorder/Reproducer unit. The information is to be used by on-board maintenance personnel to return the unit to fully operational readiness condition after equipment failure.

## 6-3. PURPOSE.

6-4. The purpose of this chapter is to provide detailed procedures for adjustment and alignment of the unit and for removal, repair, and replacement of malfunctioning parts.

6-5. SCOPE.
6-6. Information in this chapter is to be used by the maintenance technician in the unit's operating environment. Corrective maintenance procedures do not require removal of the unit from the cabinet. The maintenance procedures are based on removal, replacement, adjustment, and alignment, rather than repair of malfunctioning assemblies. Since this manual is not intended to provide instructions for overhaul, defective assebmlies are to be sent through proper channels for depot or factory repair. Shipboard spares are to be used for replacement of defective components or assemblies.

## 6-7. ARRANGEMENT OF

 CORRECTIVE MAINTENANCE DATA.6-8. The main divisions in this chapter are: Section I, Adjustments; and Section II, Repairs and Replacements. Section I describes the detailed step-by-step adjustment procedures and the proper test equipment to perform the prescribed adjustments. Section II describes the disassembly, repair (if applicable), removal and replacement of components.

## SECTION 1

## ADJUSTMENTS AND ALIGNMENTS

## 6-9. INTRODUCTION.

6-10. This section contains all adjustments and alignments that are not normally performed by the operator. All procedures are supported with test setups and illustrations, as required. The procedures are given in step-by-step format, and describe how to adjust and align when minimum performance tests or scheduled maintenance conditions are not met.

## 6-11. PRELIMINARY PROCEDURES.

6-12. Before making any adjustments, perform the following steps.

1. Clean heads and tape path as described in paragraph 4-14.
2. Demagnetize the headstacks as described in paragraph 4-16.
3. Thread transport with a freshly degaussed reel of recommended tape.

6-13. DIRECT/ANALOG SIGNAL ELECTRONICS ADJUSTMENTS.

6-14. The following paragraphs describe the procedure for adjusting the direct/analog signal electronics. These adjustments should be checked, and readjusted if necessary, after every 60 to 100 hours of equipment operation.

6-15. TEST EQUIPMENT REQUIRED. The following test equipment (or equivalent) is required to check and adjust
the direct/analog signal electronics.

1. Sinewave Oscillator, H-P 651B.
2. Squarewave Generator, Wavetek Model 130.
3. Oscilloscope, Tektronix 545.
4. Wave Analyzer, H-P 310A.
5. AC VTVM, H-P 400E.

6-16. DIRECT/ANALOG RECORD AMPLIFIER ADJUSTMENTS. To adjust the direct/analog record amplifier, perform the procedures described in the following paragraphs.

1. Perform the preliminary procedures described in paragraph 6-6.
2. Connect test equipment as shown in Figure 6-1.
3. Loosen the four captive-screws and open the hinged covers of the record amplifier housings (Figure 6-2).

## NOTE

Odd channel record amplifiers ( $1,3,5$, etc.) are located in the right-hand amplifier housing. Even channel record amplifiers ( $2,4,6$, etc.) are located in the left-hand amplifier housing.

6-17. Bias Level Adjustment. To adjust the bias level, perform the following steps (Figure 6-3).

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Figure 6-1 Test Setup for Direct/Analog Signal Electronics Adjustment.


Figure 6-2. Record Amplifier Location.


001-029

Figure 6-3. Record and Bias Level Adjustments

## NOTE

BIAS and RECORD LEVEL controls are normally adjusted at 60 ips , to provide optimum performance at all tape speeds. If only a single tape speed will be used, adjust these controls at that speed, using input frequencies proportional to the tape speed utilized.

1. Place the unit in the RECORD mode at 60 ips .
2. Set the sinewave oscillator to a frequency of 1.0 MHz .
3. Adjust the sinewave oscillator output amplitude equal to 6.0 dB below the normal record level (NRL) that will be used in actual operation.

NOTE
An output amplitude that is 6.0 dB below NRL is equal to $1 / 2$ the value of the data signal amplitude that the unit will be required to record, in normal operation. (i. e., any signal level between 0.2 and 10.0 V rms.)
4. Locate the channel 1 record amplifier. Turn the BIAS LEVEL ADJ. control (R9) several turns CCW, while observing the output indication on the ac VTVM. The meter indication should DECREASE.
5. Turn the BIAS LEVEL ADJ. control slowly CW. The ac VTVM should indicate a steady increase in output level. Continue to turn R9 CW, until a peak reading is indicated, then still
further CW until the meter indication decreases 2.0 dB below the peak indication.

6-18. Record Level Adjustment. . To adjust the record level, perform the following steps.

1. Set the sinewave oscillator to the frequency equal to $1 / 10$ to upperbandedge frequency of the recorder. (i. e. , 100 kHz at 60 ips .)
2. Adjust the sinewave oscillator output amplitide equal to the normal record level that will be used in actual operation (usually 1.0 V rms ).

## NOTE

Any input level between 0.2 and 10.0 V rms may be used as the Normal Record Level. The actual level selected should correspond to the normal output level of the device used to drive the recorder under actual operating conditions. As a matter of convenience, the unit was adjusted to accept a record input signal level of 1.0 V rms, prior to shipment from the factory.
3. Adjust the wave analyzer to the same frequency as the sinewave oscillator. Adjust the analyzer gain for a 0.0 dB indication on the front panel level meter. The RD378/U reproduce output level should be maintained at I. 0 V rms, as indicated on the ac VTVM. Adjustment of the channel 1 reproduce amplifier OUTPUT LEVEL control (R76) will normally be required to maintain a constant 1.0 V rms output level (Figure 6-4).


001-099

Figure 6-4. Reproduce Amplifier Adjustment Guide.
4. Adjust the wave analyzer to read the 3 rd harmonic of the sinewave oscillator frequency (i. e. , 300 kHz ). Increase the analyzer sensitivity by 40 dB.
5. Adjust channel 1 RECORD LEVEL ADJ. (R2) for an indication of (-) 34.0 dB , as read on the wave analyzer meter, while maintaining a reading of 1. $0 \mathrm{~V} \mathrm{rms} \mathrm{on} \mathrm{the} \mathrm{ac} \mathrm{VTVM}$, adjustment of OUTPUT LEVEL control R76.
6. Adjust the wave analyzer to read the 2 nd harmonic of the sinewave oscillator frequency (i. e. , 200 kHz ). The 2nd order harmonic should be more than 40 dB below 1.0 V rms . Higher readings usually indicate a magnetized headstack. Degauss the heads in accordance with the procedure outlined in paragraph 4-16.
7. Repeat bias adjustment and record level adjustment for the remaining direct record channels.

6-19. DIRECT/ANALOG REPRODUCE AMPLIFIER ADJUSTMENTS. To adjust the direct/analog reproduce amplifier, perform the procedures described in the following paragraphs.

6-20. Preliminary Procedures. Before attempting adjustment of the direct/analog reproduce amplifiers, perform the following preliminary procedures.

1. Connect test equipment as shown in Figure 6-1.
2. Remove the dust-cover door loosen the transport latches,
and swing the transport out of the cabinet to the full open position.
3. Lift the hinged cover of the reproduce amplifier housing to gain access to the reproduce amplifiers.

6-21. Direct/Analog Reproduce Amplifier Adjustment Procedure. To adjust the direct/analog reproduce amplifiers, perform the following steps.

1. Place the unit in the RECORD mode at 60 ips .
2. Set the sinewave oscillator to a frequency of 100 kHz at an output level of 1.0 V rms .1
3. Refer to Figure 6-4. Adjust OUTPUT LEVEL ADJ. (R76) for 1.0 V rms, as indicated on the output ac VTVM.
4. Set the sinewave oscillator to a frequency of 2.0 kHz at an output level of 1.0 V rms. Adjust 60 ips MIDBAND GAIN ADJ. (R4I) for 1.0 V rms output.
5. While maintaining a 1.0 V rms oscillator output level, slowly sweep the frequency between 400 Hz and 100 kHz . While monitoring the output ac VTVM, note any dips or peaks in the output signal level.
6. NOTE: For purposes of explanation, 1.0 V rms is used at the normal record level (NRL). However, any input level between 0.2 and 10.0 V rms may be used as the NRL which best satisfies a particular system requirement.
a. If output dips - set oscillator to 2.0 kHz and adjust MIDBAND GAIN ADJ. (R41) for a 2.0 dB decrease in output level. Then, without changing oscillator frequency or amplitude, adjust OUTPUT LEVEL ADJ. (R76) for a 2.0 dB increase in output level.
b. If output peaks - set oscillator to 2.0 kHz and adjust MIDBAND ADJ. (R41) for a 2.0 dB increase in output level. Then, without changing oscillator frequency or amplitude, adjust OUTPUT LEVEL ADJ. (R76) for a 2.0 dB decrease in output level.
c. Recheck frequencies between 400 Hz and 100 kHz and continue to adjust R41 and R76 until frequency response, across this portion of the bandwidth, is flat within $\pm 2.0 \mathrm{~dB}$.
7. Set the sinewave oscillator to a frequency of 1.0 MHz at an output level of $1.0 \mathrm{~V} \mathrm{rms}$. BANDEDGE ADJ. control (R43) for an indication of 2.0 dB below 1.0 V rms , as measured on the output ac VTVM.
8. Disconnect the sinewave oscillator and connect the squarewave generator to the record input.
9. Set the squarewave generator to a frequency of 50 kHz at an output level of $3.0 \mathrm{~V} \mathrm{p-p}$.
10. While observing the output waveform on the monitor oscilloscope, adjust PHASE ADJ. control (R53) for proper leading and trailing edge overshoot, as shown in Figure 6-5.
11. Disconnect squarewave generator and reconnect sinewave oscillator.
12. Repeat steps (2) through (10) until both sinewave and squarewave response are correct, as indicated.
13. Place the unit in the RECORD mode at 120 ips .
14. Set the sinewave oscillator to a frequency of 2.0 kHz at an output level of $1.0 \mathrm{~V} \mathrm{rms}$. Adjust the 120 ips MIDBAND GAIN ADJ. (R45) for 1.0 V rms output, as measured on the output ac VTVM.
15. Set the sinewave oscillator to a frequency of 200 kHz at an output level of 1.0 V rms. Adjust the 120 ips COMPENSATION ADJ. control (R19) for $1.0 \mathrm{~V} \mathrm{rms} \mathrm{output}$, the output ac VTVM.
16. Set the sinewave oscillator to a frequemcy of 2.0 MHz at an output level of 1.0 Tms . Adjust the 120 ips BANDEDGE ADJ. control (R47) for an indication of 2.0 dB below 1.0 V rms , as measured on the output ac VTVM.
17. Sweep the sinewave oscillator between 400 Hz and 2.0 MHz , making adjustments as necessary for a flat overall frequency response $( \pm 3.0 \mathrm{~dB})$.
a. To increase midband gain, turn Rig CW.
b. To increase low frequency gain, tarn R45 CW.
c. To increase upper bandedge gain, barn R47 CW.
d. If there is a peak between midbamd and upper bandedge, turn R45 CW.


Figure 6-5. Phase Adjustment
17. Using Table 6-1 adjust equalization for the remaining tape speed.

6-22. SIGNAL-TO-NOISE RATIO MEASUREMENT. SNR measurements may be made at any tape speed, using the following procedure.

1. Set sinewave oscillator to a frequency equal to $1 / 10$ the upper-bandedge frequency for the particular tape speed selected. Adjust the oscillator output level equal to the NRL being utilized.
2. Note the output reading on the output ac VTVM.
3. Disconnect the sinewave oscillator and read SNR on the output ac VTVM.

6-23. FM SIGNAL ELECTRONICS ADJUSTMENT.

6-24. The following paragraphs describe the procedure for adjusting the FM signal electronics. These adjustments should be checked, and readjusted if necessary, after every 60 to 100
hours of equipment operation.
6-25. TEST EQUIPMENT REQUIRED. The following test equipment (or equivalent) is required to check and adjust the FM signal electronics.

1. Digital Voltmeter, H-P 3439 A.
2. Frequency Counter, H-P 5512.
3. Reference Power Supply, H-P 6113 A.
4. Oscilloscope, Tektronix 545.

6-26. FM RECORD AMPLIFIER ADJUSTMENTS. To adjust the FM record amplifier, perform the procedures described in the following paragraphs.

1. Perform the preliminary procedures described in paragraph 6-1l.
2. Connect test equipment as shown in Figure 6-6.

TABLE 6-1. EQUALIZATION ADJUSTMENTS

| Tape Speed | Osc. Freq. | Adjust | Output <br> Indication |
| :---: | ---: | :---: | :---: |
| 30 ips | 2 kHz | R38 | 1.0 V rms |
| 30 ips | 500 kHz | R40 | -2 dB |
| 15 ips | 2 kHz | R 35 | 1.0 V rms |
| 15 ips | 250 kHz | R 37 | -20 dB |
| $7-1 / 2 \mathrm{ips}$ | 2 kHz | R 32 | 1.0 V rms |
| $7-1 / 2 \mathrm{ips}$ | 125 kHz | R 34 | -2 dB |
| $3-3 / 4 \mathrm{ips}$ | 2 kHz | R 29 | 1.0 V rms |
| $3-3 / 4 \mathrm{ips}$ | 62.5 kHz | R 31 | -2 dB |
| $1-7 / 8 \mathrm{ips}$ | 2.0 kHz | $\mathrm{R45}$ | 1.0 V rms |
| $1-7 / 8 \mathrm{ips}$ | 31.2 kHz | R 47 | -2 dB |


(10) 1 2

Figure 6-6. Test Setup for FM Record Amplifier Adjustment.
3. Loosen the four captive-screws and open the hinged covers of the record amplifier module (Figure 6-2).

NOTE
Odd channel record amplifiers (1, 3, 5, etc.) are located in the right-hand amplifier housing. Even channel record amplifiers (2, 4, 6, etc.) are located in the lefthand amplifier housing.

6-27. Input Zero Adjustment.

## NOTE

Any inherent dc voltage present at the input of the FM Record Amplifier will deviate the VCO carrier frequency away from its center or resting point, causing non-linear distortion at the reproduce output. It is, therefore, important to balance out any residual dc before attempting to adjust the VCO center frequency, or carrier deviation.

1. Place the unit in the RECORD mode at 60 ips .
2. With the digital voltmeter connected to channel 1 Record Input connector, adjust DC ZERO ADJ. (R4) for 0.0 V $\mathrm{dc}, \pm 0.001 \mathrm{~V}$ dc (Figure 6-7).

6-28. FM Center Frequency Adjustment. To adjust the FM center frequency, perform the following steps.

1. Remove the digital voltmeter from channel 1 record input connector, and replace with a shorting connector.
2. Adjust FM CENTER FREQ. control (R33) for a reading of 216.0 kHz , as read on the frequency counter.

6-29. Deviation Adjustment. To adjust FM carrier deviation, perform the following steps.

1. Remove the shorting connector from the channel 1 record input connector.
2. Connect reference power supply to the channel l record input connector.
3. Adjust power supply for an output voltage of ( + )1. 414 V dc .
4. Adjust DEVIATION ADJ. controls (R2 - coarse and R7-fine) for +40 percent deviation ( $302.4 \mathrm{kHz}, \pm 0.01$ percent).
5. Adjust power supply for an output voltage of (-)l. 414 V dc.
6. Check FREQUENCY COUNTER for - 40 percent deviation ( 129.6 kHz , $\pm 0.01$ percent).
7. Repeat steps (2) through (5), as required.
8. Check center frequencies and deviation at remaining tape speeds, in accordance with Table 6-2.

6-30. FM REPRODUCE AMPLIFIER ADJUSTMENTS. To adjust the FM reproduce amplifiers, perform the procedures described in the following paragraphs.


Figure 6-7. FM Record Amplifier Adjustments.

TABLE 6-2. CENTER FREQUENCIES AND DEVIATIONS
Wideband Group I

| Tape Speed | Center Freq. $(\mathrm{kHz})$ | $+40 \%(\mathrm{kHz})$ | $-40 \%(\mathrm{kHz})$ |
| :---: | :---: | :---: | :---: |
|  |  |  |  |
| 120 ips | 432.000 | 604.8 | 259.2 |
| 60 ips | 216.000 | 302.4 | 129.6 |
| 30 ips | 108.000 | 151.2 | 64.8 |
| 15 ips | 54.000 | 75.6 | 32.4 |
| $7-1 / 2 \mathrm{ips}$ | 27.000 | 37.8 | 16.2 |
| $3-3 / 4 \mathrm{ips}$ | 13.500 | 18.9 | 8.1 |
| $1-7 / 8 \mathrm{ips}$ | 6.750 | 9.45 | 4.05 |

NOTE
Allow a 15-minute warmup period, to stabilize the oneshot oven, before attempting adjustments to the FM reproduce amplifiers.

## NOTE

The FM record amplifiers must be properly adjusted for carrier and deviation before performing adjustments to the FM reproduce amplifiers.

6-31. Preliminary Procedures. Before attempting adjustments to the FM reproduce amplifiers, perform the following preliminary procedures.

1. Connect test equipment as shown in Figure 6-8.
2. Remove the dust-cover door, loosen the transport latches, and swing the transport out of the cabinet to the full open position.
3. Lift the hinged cover of the reproduce amplifier housing to gain access to the reproduce amplifiers.

6-32. FM Reproduce Amplifier Adjustment Procedure. To adjust the FM reproduce amplifiers, perform the following steps (see Figure 6-3).

1. Place the unit in the STOP mode.
2. Remove the speed change logic board from the reproduce amplifier housing.
3. Connect the digital voltmeter to an FM reproduce output connector.
4. Adjust the OVERALL ZERO ADJ. (R14) for an output of 0.000 V dc , as measured on the digital voltmeter.
5. Repeat steps (3) and (4) for all FM channels.
6. Replace speed change logic board.
7. Place a shorting connector on record input connector.
8. Connect digital voltmeter to corresponding reproduce output connector.
9. Place the unit in the RECORD mode at 60 ips .


Figure 6-8. Test Setup for FM Reproduce Amplifier Adjustments.
10. Adjust 60 ips ZERO ADJ. control (R4) for 0.000 V dc , as measured on the digital voltmeter.
11. Place the unit in the STOP mode, and change transport speed to 30 ips .
12. Place the unit in the RECORD mode and adjust 30 ips ZERO ADJ. (R4) for 0.000 V dc , as measured on the digital voltmeter.
13. Repeat steps (11) and (12) for the four remaining tape speeds.
14. Repeat steps (9) through (13) for all remaining FM channels.
15. Remove the shorting connector from the record input connector.
16. Set sinewave oscillator to a frequency of 1.0 kHz , at a level of 1.0 V rms.
17. Place the unit in the RECORD mode at 60 ips .
18. Adjust the 60 ips OUTPUT LEVEL ADJ. (Rl) for desired output level between $2.0 \mathrm{~V} \mathrm{p-p}$ and $4.0 \mathrm{~V} \mathrm{p-p}$.
19. Repeat steps (17) and (18) for the remaining five tape speeds, adjusting the appropriate OUTPUT LEVEL ADJ. (Rl) for each speed.
20. Repeat steps (15) through (19) for all remaining FM channels (2 through 14).

6-33. REPRODUCE HEAD AZIMUTH ADJUSTMENT.

6-34. To ensure optimum highfrequency response during reproduce,
the reproduce head-gaps must be exactly parallel with the head-gaps of the record head. This is accomplished by adjusting the azimuth of the reproduce headstack to coincide with the fixed azimuth of the record head. To adjust the reproduce head azimuth, proceed as follows:

## NOTE

Direct/Analog signal electronics must be installed in the channels utilized to adjust reproduce head azimuth. FM signal electronics do not have sufficient bandwidth response for proper azimuth adjustment.

1. Connect test equipment as shown in Figure 6-9.
2. Remove transport head-cover to gain access to the reproduce head azimuth adjustment screws.
3. Adjust sinewave oscillator for a low-frequency output, between 1.0 kHz and 2.0 kHz , with an output amplitude of 1.0 V rms .
4. Adjust oscilloscope for an alternate display, and external triggering on track 1 reproduce output.
5. Place the unit in the RECORD mode at 60 ips .
6. Adjust oscilloscope to display 2 to 4 cycles of the output waveform on each trace. Using the vertical position controls, superimpose the two traces. Adjust the oscilloscope vertical gain controls so that both waveforms are of the same amplitude.


Figure 6-9. Test Setup for Azimuth Adjustment.
7. Using a small Allen-wrench, adjust the ODD CHANNELS AZIMUTH A ADJ. screw - located on the righthand side of the headstack - until the two reproduce waveforms are exactly in phase.

## CAUTION

To prevent magnetizing the headstack, degauss the Allenwrench before making azimuth adjustments.
8. Slowly increase the oscillator frequency until a phase difference is evident, then re-phase with the azimuth adjustment.

NOTE

It may be necessary to move one of the waveforms back and forth several cycles, before the proper "in-phase" condition is reached.
9. Continue to increase oscillator frequency, and oscilloscope sweep time, while maintaining 2 to 4 cycles on the screen.
10. As upper-bandedge frequency is approached, an increased amount of waveform jitter will be observed, and proper azimuth adjustment will become extremely critical. Carefully readjust the AZIMUTH screw to center the jittering waveform with the fixed (reference) waveform.

NOTE
It is not necessary to continue increasing oscillator frequency all the way to the upper-bandedge
limitations of the recorder. However, frequency should continue to increase well into the upper $1 / 3$ of the recorder bandwidth.
11. Now, slowly decrease the oscillator frequency, observing that the two superimposed waveforms remain in phase, all the way to the lower bandedge limit of the recorder.
12. Repeat steps (6) through (11) for the even channels, as follows:
a. Connect oscillator to track 2 and track 14 record inputs.
b. Connect oscilloscope to track 2 and track 14 reproduce outputs.
c. Adjust EVEN CHANNELS

AZIMUTH ADJ. screw - located on the left-hand side of the headstack.
13. Replace transport head-cover.

## 6-35. VOLTAGE REGULATOR

 ADJUSTMENT.6-36. Refer to Figure 6-1 0 for test equipment hook-up.

## 6-37. TEST EQUIPMENT REQUIRED.

1. Digital Voltmeter, H-P 3439 A.

## 6-38. PROCEDURE.

1. Connect the digital voltmeter to the voltage test points on the front panel of the RAM (Figure 6-10).
2. Open the tape transport and remove the coverplate from the electronic housing assembly.

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Figure 6-10. Voltage Regulator Test Setup.
3. Thread the transport with tape, and place unit in the RECORD mode at $3-3 / 4 \mathrm{ips}$.
4. Select the 18.5 V position of the VOLTAGE SELECT switch, on the front panel of the RAM.
5. Digital voltmeter should indicate $+18.5 \mathrm{~V} \mathrm{dc}, \pm 1 \%$. If not, adjust R8 on the voltage regulator (Figure 6-11). for an indication between +18.3 and 18.7 V dc.
6. Select the 20 V position of the VOLTAGE SELECT switch, on the front panel of the RAM.
7. Digital voltmeter should indicate $+20 \mathrm{~V} \mathrm{dc}, \pm 1 \%$. If not, adjust Rl5 on the voltage regulator for an indication between +19.8 and +20.2 V dc 。
8. Select the 5 V position of the VOLTAGE SELECT switch. Digital voltmeter should indicate +5.5 V dc, +0.5 V dc. This voltage is not adjustable. If voltage is not as specified, determine cause of malfunction.
9. Select the 15 V position of the VOLTAGE SELECT switch. Digital voltmeter should indicate $+15,+0.15$ V dc. This voltage is not adjustable. If voltage is not as specified, determine cause of malfunction.

6-39. TAPE SUPPLY SENSOR ADJUSTMENT.

6-40. Refer to Figure 3-12. The Tape Supply Sensor adjustments (R33 and R35) are located in the tape-supply/ EOT Sensor, at the upper left-hand corner of the tape transport. The current through these sensors should be
adjusted periodically, for proper indication on the Tape Supply Meter. To adjust sensors, proceed as follows:

6-41. TEST EQUIPMENT REQUIRED. No test equipment is required.

## 6-42. PROCEDURE.

1. Remove tape and tape reels from transport.
2. Turn transport power ON. The TAPE SUPPLY indicator meter, on the front panel of the RAM, should read close to empty; the EOT status indicator lamp should be lighted.
3. Adjust R33 until pointer of meter reads EMPTY, on the meter scale. If meter cannot be properly set, adjust R35 - then readjust R33.
4. Cover both tape supply sensor assemblies with masking tape. The TAPE SUPPLY indicator meter should read FULL. If not, adjust R35.
5. Repeat steps (3) and (4) until meter indicates properly for both the EMPTY and FULL conditions.

## NOTE

Ambient light may affect proper adjustment of the tape supply sensors. If so, adjustment should be made in a semidarkened location.


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Figure 6-11. Voltage Regulator Adjustment.

## SECTION II

## REPAIR

## 6-43. INTRODUCTION.

6-44. This section describes the removal and replacement of component parts and assemblies, but does not include procedures for their repair. Field repairs to major mechanical assemblies is not recommended. Rather, these assemblies should be serviced at the depot level, or returned to the manufacturer for repair at the factory. Electronic repairs described in this section consist only of isolating and replacing faulty printed wiring cards. Should there be a malfunction of one of the printed wiring cards, it should be replaced with a spare card and the defective card sent to the depot, or factory, for repair.

6-45. STATUS INDICATOR LAMP REPLACEMENT.

1. Refer to Figure 6-12. Remove the glass faceplate from the Status Indicator by depressing the two springloaded retaining clips, and gently pulling faceplate away from RAM.
2. Replace defective indicator bulb.
3. Replace glass faceplate.

6-46. PUSHBUTTON LAMP REPLACEMENT.

1. Refer to Figure 6-12. Grasp the edges of the pushbutton lens and gently pull straight out - away from RAM.
2. Replace defective bulb.
3. Replace the lens in the pushbutton assembly, and press in firmly until it latches in place.

6-47. TAPE SUPPLY LAMP REPLACEMENT.

1. Refer to Figure 3-16.

NOTE
Carefully note the position of the aperture in the metal shroud that protects the tape supply lamp. This aperture must be correctly repositioned, to properly illuminate the Tape Supply Sensors.
2. Loosen the small Allen screw securing the metal shroud covering the lamp.
3. Remove shroud by gently pulling straight out - away from the tape transport.
4. Replace defective bulb.
5. Replace shroud, reposition, and tighten setscrew.
6. Check tape supply sensor adjustment, paragraph 6-39.

6-48. TENSION SENSOR LAMP
REPLACEMIENT.

1. Refer to Figure 6-13.


Figure 6-12. Lamp Locations.


Figure 6-13. Tension Sensor Lamp Replacement.
2. Turn off transport power. Open transport to gain access to the tension sensor assemblies.
3. Remove the two Phillips head screws securing the photocell PWB to the sensor assembly (Figure 6-13, item A).
4. Carefully lift the PWB away from the sensor, and position to one side of the sensor assembly.
5. Remove the two Allen head screws securing the tension sensor assembly to the precision plate.
6. Taking card not to bend the light shutter, remove the sensor assembly, and position so as to gain access to the botton (i. e., side which is mounted to the precision plate).
7. Remove the nylon screw and spring clip assembly which holds the lamps in the sensor housing.
8. Replace defective bulb.
9. Reassemble and re-install tension sensor assembly, taking care not to damage the light shutter.
10. Replace the photocell PWB.

## 6-49. TAPE GUIDE REPLACEMENT.

6-50. Tape guides are secured to the tape transport with a single 8-32 mounting screw, and should be replaced as a complete component assembly. Guides are provided with a small alighment pin, on their mounting surface, which is used to properly position the component on the transport. Four of the tape guides are fitted with tape-holders,
which are not part of the guide assembly, and must be replaced separately.

1. Turn off transport power. Open transport to gain access to the tape guide mounting screws.

## NOTE

To replace the wrap rollers located near the capstans, first remove the capstan motor as oütlined in paragraph 6-53.
2. Remove tape guide mounting screw.
3. Remove tape guide.
4. Remove tape holder, if present.
5. Install tape holder on replacement guide.
6. Install replacement guide, taking care to align the mounting pin in the hole provided in the tape transport.
7. Reinstall capstan motor and transport connector mounting bracket, if previously removed.

## 6-51. MAGNETIC HEAD REPLACEMENT.

1. Refer to Figure 6-14, Remove head-cover and headshield.
2. Remove head-cover standoff mounts.
3. Disconnect 14 record signal cables.
4. Remove preamplifier interconnect board mounting screw (2 from each board), and unplug preamplifiers from head assembly. Preamplifiers should remain plugged into interconnect boards.


Figure 6-14. Magnetic Head Replacement.
5. Remove 4 head assembly mounting screws.
6. Carefully lift head assembly away from precision plate.
7. Remove interconnect board standoff mounts (4) from old head assembly, and reinstall on replacement head assembly.
8. Plug preamplifier into replacement head assembly, and secure interconnect boards with mounting screws.
9. Degauss replacement headstack as outlined in paragraph 4-16.
10. Install new head assembly on transport precision plate.
11. Reconnect record signal cables. Re-install head-cover standoffs and headshield.
12. Perform reproduce head azimuth adjustment, as outlined in paragraph 6-33.
13. Perform direct/analog signal electronics adjustment procedures, or FM signal electronics adjustment procedures (as appropriate), outlined in Section I of this chapter.

6-52. REEL MOTOR ASSEMBLY REPLACEMENT.

1. Turn off transport power. Remove tape and tape reels from transport.

2: Open transport and latch in the fully open position.
3. Disconnect reel motor connector P21.
4. Holding the rear of the motor, to prevent dropping, remove the 4 motor mounting screws from the front of the transport.
5. Remove motor assembly from the rear of the transport by pulling assembly straight out of the mounting flange.
6. Install replacement reel motor assembly; tighten mounting screws; reconnect P21.

6-53. CAPSTAN DRIVE-BELT REPLACEMENT.

## CAUTION

Be extremely careful not to nick or otherwise damage capstan surfaces when removing or replacing capstan motor.

1. Refer to Figure 6-15.
2. Remove tape and tape reels from transport.
3. Open transport and latch in the fully open position.
4. Remove screws securing the trans port connector mounting bracket. Position connector bracket so as to per mit capstan motor removal.
5. Remove 5 of the 6 screws securing the capstan motor to the precision plate assembly. (Two of the mounting screw are located inside the motor housing. )
6. Holding the capstan motor assembly with one hand, (to prevent dropping remove the last mounting screw.


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Figure 6-15. Capstan Motor Assembly.
7. With both hands, remove motor assembly by carefully pulling straight out, away from unit.
8. Loosen, but do not remove, the thiree screws securing each capstan assembly to the motor mounting plate.
9. Loosen, but do not remove, the four screws securing the motor to the motor mounting plate.
10. Remove old drive-belts. Clean pulley surfaces with xylene and cotton swabs.
11. Install new drive-belts. Position belts on pulleys, orienting as shown in Figure 6-15.
12. Apply a $10 \mathrm{lb}, \pm 2.0 \mathrm{oz}$ force on capstan assemblies, in direction shown. Center housing symmetrically on motor mounting plate, and tighten capstan mounting screws.
13. Position differential pulley equidistant between capstans and tighten motor mounting screws.
14. With the motor still removed from the transport, reconnect motor conmector J34 and run motor for oneminute in the FORWARD mode, to stabilize belts.

NOTE
To energize the capstan motor while still removed from the tape transport, proceed as follows:
a. Remove reel drive fuse (F4) (Figure 2-2).
b. Place a small piece of cardboard, or other opaque material, in the tape break sensor.
c. Select a tape speed of $7-1 / 2 \mathrm{ips}$, and operate the unit in the normal manner.
d. After performing step (15), secure transport power, remove material from tape break sensor, and re-install reel drive fuse.
15. Run motor in REVERSE direction. Belts should not shift position more than 0.03 -inch.
16. Re-install capstan motor and transport connector bracket.

CHAPTER 7
PARTS LIST

## 7-1. INTRODUCTION.

7-2. This parts list illustrates and describes assemblies, subassemblies and detailed parts to assist supply and maintenance personnel in identifying, ordering, and stocking replaceable parts at the organizational level.

7-3. MODEL AND SERIAL.
7-4. The Magnetic Tape RecorderReproducter Model RD378/U, serial numbers A1 through A7, is covered by this manual.

7-5. SPECIAL NOTES.
7-6. Not Applicable.
7-7. MAJOR COMPONENTS LIST.
7-8. The Magnetic Tape RecorderReproducer RD378/U is a unit of AN/ SQR-14A Sonar System.

## 7-9. MAJOR UNIT LIST.

7-10. The major Unit List consists of the Magnetic Tape Recorder-Reproducer unit. The list contains the unit number, nomencalture, name of unit, designation, and the page number of the Parts List where the unit parts listing start.
Unit Number

1 $\frac{$|  Magnetic Tape  |
| :--- |
|  Recorder-Re-  |
|  producer  |
|  RD  $378 / \mathrm{U}$ |}{Nomenclature} Page.

## 7-11. PARTS LIST.

7-12. Table 7-1 is a parts list, separated into groups by assemblies and keyed to associated assembly illustrations by figure and index number. The order of list is in reference designator order, with all parts attached to the unit first, followed by unit assemblies with parts, and subassemblies with parts. The relation of each part to its next higher assembly (NHA) is shown in the list by reference designator.

7-13. Parts listing is prepared in tabular form with columns headed as follows:
a. Column 1, Reference Designation. This column contains the reference designation of parts in accordance with USAS Y32. 16.
b. Column 2, Notes. Options to the basic Recorder-Reproducer are indicated in this column.
c. Column 3, Name and Description. This column includes description data to identify the parts of the equipment and aid in determining substitutes. Following the item description, the equipment contractor's part number, manufacturer's part number, part manufacturer's federal supply code number are shown.
d. Column 4, Figure and Item Number.

This column references the part location illustration by figure and item number. These numbers have two parts; a figure number which identifies the corresponding illustration, for example " $7-1$ " and an index number which appears on the illustration adjacent to the specific component in question, for example " -11 ". Thus the figure and index number 7-1 (11) would refer to the part connected by a leadline to index number 11, in figure 7-1.

7-14. COMMON ITEM DESCRIPTION. LIST.

7-15. Not Applicable.
7-16. ATTACHING HARDWARE
LIST.
7-17. Not Applicable.
7-18. MANUFACTURER'S LIST.
7-19. Manufacturers are given below in vendor code sequence. Manufacturer code numbers are in accordance with handbooks H4-1 and H4-2.

Vendor's Code Name and Address

| 05464 | Industrical Electronics <br> Engineers, Inc. |
| :---: | :--- |
|  | Van Nuys, Cal. |
| 13016 | Astro-Science Corp. <br>  <br>  <br>  <br> South Factorial Way <br> Sout Monte, Cal. |

82877 Rotron Inc.

74193

75915

8287
81349

Heinemann Electric Co. Trenton, New Jersey

Littlefuse, Inc. Des Plaines, Ill.

81349 Military Specification Promulgated by Standardization Division, Directorate of Logistic Service, DSA Burbank, Cal.

## 71744 Chicago Minature Lamp Works Chicago, Ill. <br>  <br> ,

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST

| Reference Designation | Notes | Name and Description | Figure $\underset{\text { (Item) }}{\text { Number }}$ |
| :---: | :---: | :---: | :---: |
| 1 |  | Recorder-Reproducer Magnetic Tape Assembly RD378/U, Dwg. 95002661 , Mfr. 13016 | 7-1 |
| 1MP1 |  | Reel, 14 inch precision less tape, taper flange, Dwg. 30004890-4, Mfr. 13016 | 7-1 (7) |
| 1MP2 |  | Reel, 14 inch precision with 3M888 tape Dwg. 30008031-2, Mfr. 13016 | 7-1 (8) |
| 1MP3 | Option | Reel, 14 inch precision with 3M988 tape Dwg. 30008031-9, Mfr. 13016 |  |
| 1A1 |  | Case Assembly, Dwg. 94001061, Mfr. 13016 | 7-1 |
| 1A1A1 |  | Power Distribution Assembly, Dwg. 85009531, Mfr. 13016 | 7-1 (37) |
| 1A1A/DS2 |  | $\begin{aligned} & \text { Lamp, } \underset{\text { 15579-6, }}{125 \mathrm{~V},} \underset{\mathrm{Mfr} .}{66906} \end{aligned}$ | 7-1 (38) |
| 1A1PS1 |  | Power Supply, input voltage 105-125 volts ac, frequency $47-420 \mathrm{~Hz}$, output voltage 28 porm 1.2 volts dc, 14 amps full load, Dwg. 85009521, Mfr. 13016 | 7-1 (27) |
| 1A1W1 |  | Cable Assembly, special purpose, electrical, Dwg. 50001391, Mfr. 13016 | 7-1 (36) |
| 1A1W2 |  | Cable Assembly, special purpose, electrical, Dwg. 50001421, Mfr. 13016 | 7-1 (28) |
| 1A1w3 |  | Cable Assembly, special purpose, electrical, Dwg. 50001431, Mfr. 13016 | 7-1 (29) |
| 1A1W4 |  | Cable Assembly, special purpose, electrical, Dwg. 50001451, Mfr. 13016 | 7-1 (30) |
| 1A2 |  | Basic Transport Assembly, Dwg. 94001041, Mfr. 13016 | 7-1 |
| 1A2B1 |  | Motor Assembly, Dwg. 85004481, Mfr. 13016 | 7-1(23) |

TABLE 7-1. RECORDER-REPRODUCER,MAGNETIC TAPE,RD378/U,PARTS LIST

| Reference Designation | Notes | Name and Description | Figure Number |
| :---: | :---: | :---: | :---: |
| 1A2A1 |  | Transport Chassis Assembly, Dwg. 85006691, Mfr. 13016 | 7-1 |
| 1A2A1F1 |  | Fuse, cartridge, 125 voltage rating, 5 amperes, Dwg. 11000060-23, Part No. 313005, Mfr. 75915 | 7-1 (6) |
| 1A2A1F2 |  | Fuse, cartridge, 250 voltage rating, 2 amperes, Dwg. 11000060-16, Part No. 312002, Mfr. 75915 | 7-1 (5) |
| 1A2A1F3 |  | Fuse, cartridge 125 voltage rating, 5 amperes, Dwg. 11000060-23, Part No. 313005, Mfr. 75915 | 7-1 (4) |
| 1A2A1F4 |  | Fuse, cartridge 32 voltage rating, 7 amperes, Dwg. 11000060-24, Part No. 313007, Mfr. 75915 | 7-1 (3) |
| 1A2A1A |  | Roller Guide Assembly Dwg. 84002701, Mfr. 13016 | 7-1 (2) |
| 1A2A1A2 |  | Lamp Assembly Dwg. 84007911, Mfr. 13016 | 7-1 |
| 1A2A1A2DS1 |  | Lamp, Incandescent, Dwg. 12000580-1 Part No. , Mfr. | 7-1 (9) |
| 1A2A1A3 |  | Tape Guide Assembly, Dwg. 84008041, Mfr. 13016 | 7-1 (1) |
| 1A2A2 |  | Circuit Card Assembly, control logic, Dwg. 84007981, Mfr. 13016 | 7-1 (20) |
| 1A2A3 |  | Circuit Card Assembly, capstan servo, Dwg. 84007961, Mfr. 13016 | 7-1 (21) |
| 1A2A4 |  | Circuit Card Assembly, voltage regulator, Dwg. 85004451-1, Mfr. 13016 | 7-1 (22) |

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST

| Reference Designation | Notes | Name and Description | Figure Number (Item) |
| :---: | :---: | :---: | :---: |
| 1A2A5 |  | Precision Plate Assembly, Dwg. 85004301, Mfr. 13016 | 7-1 |
| 1A2A5A1 |  | Sensor Assembly, Tape Break, Dwg. 84007891 Mfr. 13016 | 7-1 |
| 1A2A5A1DS1 |  | Lamp, 28 volts, Dwg. 12000500, Part No. 7387, Mfr. 71744 | 7-1 (10) |
| 1A2A5A4 |  | Roller Guide Assembly, Dwg. 84002701 Mfr. 13016 | $7-1{ }^{\text {i }}$ (11) |
| 1A2A5A2 |  | Capstan-Motor Assembly, Dwg. 84007831, Mfr. 13016 | 7-1 |
| 1A2A5A2MP1 |  | Belt, Mylar Dwg. 30007021, Mfr. 13016 | 7-1 (25) |
| 1A2A5A3 |  | Tape Tension, Amplifier Assembly, Dwg. 84002741, Mfr. 13016 | 7-1 |
| 1A2A5A3DS1 |  | Lamp, Incandescent, Dwg. 12000480, Part No. CM8-632, Mfr. 60640 | 7-1 (24) |
| 1A3 |  | Reproduce Amplifier Module Assembly, Dwg. 94001051, Mfr. 13016 | 7-1 (40) |
| $\begin{aligned} & \text { 1A3F1, } \\ & \text { 1A3F2 } \end{aligned}$ |  | Fuse, cartridge, Dwg. MS90078-12 Mfr. 96906 | 7-1 (35) |
| 1A3S1 |  | Switch, pushbutton, transport power, Dwg. 05000770-7, Part No.90E10A1C 4F3J1 (W) HINZR13, Mfr. 96182 | 7-1 |
| 1A3S2 |  | Switch, pushbutton, forward, Dwg. 05000770-2, Part No. 90E10A1C2F3J1 (G) HIN2R12, Mfr. 96182 | 7-1 |
| 1A3S3 |  | Switch, pushbutton, record, Dwg. 05000770-1, Part No. 90E10A1C2F3J1 (G) HIN2R12, Mfr. 96182 | 7-1 |

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST

| Reference Designation | Notes | Name and Description | Figure Number |
| :---: | :---: | :---: | :---: |
| 1A3S4 |  | Switch, pushbutton, reverse, Dwg. 05000770-3, Part No. 90E10A1C2 F3J1(G) HIN2R12, Mfr. 96182 | 7-1 |
| 1A3S5 |  | Switch, pushbutton, fast rewind, Dwg. 05000770-6, Part No. 90E10A1C2F3J1(G) HIN2R13, Mfr. 96182 | 7-1 |
| 1A3S6 |  | Switch, pushbutton, fast wind, Dwg. 05000770-5, Part No. 90E10A1C2F3J1(G) HIN2R13, Mfr. 96182 | 7-1 |
| 1A3S7 |  | Switch, pushbutton, stop Dwg. $05000770-$ 4, Part No. 90E10A1C2F3J1(Y)HIN2R12, Mfr. 96182 | 7-1 |
| 1A3S8 |  | Not illuminated |  |
| 1A3S9 |  | Switch, pushbutton, main power, Dwg. 05000770-8, Part No. 90E10A1C4F4J1 (W) HIN2R13, Mfr. 96182 | 7-1 |
| $\begin{aligned} & \text { 1A3S9FL1, } \\ & \text { 1A3S9FL2 } \end{aligned}$ |  | Lamp, glow, 28 volts, midget flanged base, Part No. F3, Mfr. 96182 | 7-1 (17) |
| 1A3A1 |  | Circuit Card Assembly, speed change logic, Dwg. 85002012, Mfr. 13016 | 7-1 (34) |
| 1A3A2 |  | Status Indicator Assembly, Dwg. 84003157, Mfr. 13016 | 7-1 |
| 1A3A2DS1 |  | Indicator, Status, 28 VDC, Dwg. 12000570-2, Part No. 0280-03-44601819, Mfr. 05464 | 7-1 |
| 1A3A2DS1 |  | Lamp, 28 VDC, Part No. 1819, Mfr. 05464 | 7-1 (16) |
| 1Ȧ3 | Option | Reproduce Amplifier Module, 2 channel, Dwg. 94001121, Mfr. 13016 |  |
| 1A4 |  | Circuit Card Assembly, speed select encoder, Dwg. 85004741, Mfr. 13016 | 7-1 (19) |

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST

| Reference Designation | Notes | Name and Description | Figure Number |
| :---: | :---: | :---: | :---: |
| 1A5 |  | Circuit Card Assembly, FM reproduce amplifier wideband, Dwg. 85006401-1, Mfr. 13016 | 7-1 (31) |
| 1A5 | Option | Circuit Card Assembly, FM reproduce amplifier wideband, Dwg. 85006401-2 |  |
| 1A5FL1 | Option | Electronic Component Board Assembly, 40.0 kHz , Dwg. 85006471, Mfr. 13016 |  |
| 1A5FL2 | Option | Electronic Component Board Assembly, 20.0 kHz , Dwg. 85006461, Mfr. 13016 |  |
| 1A5FL3 | Option | Electronic Component Board Assembly, 10 kHz , Dwg. 85006451, Mfr. 13016 |  |
| 1A5FL4 | Option | Electronic Component Board Assembly, 5 kHz , Dwg. 85006441, Mfr. 13016 |  |
| 1A5FL5 | Option | Electronic Component Board Assembly, 2.5 kHz , Dwg. 85006431, Mfr. 13016 |  |
| 1A5FL6 |  | Electronic Component Board Assembly 1.25 kHz , Dwg. 85006421, Mfr. 13016 | 7-1 (32) |
| 1A5FL6 | Option | Electronic Component Board Assembly, 80 kHz , Dwg. 85006481 , Mfr. 13016 |  |
| 1A6 |  | Circuit Card Assembly, reproduce amplifier, 1 MHz , Dwg. 85006591-1, Mfr. 13016 | 7-1 (33) |
| 1A6 | Option | Circuit Card Assembly, reproduce amplifier, 2 MHz , Dwg. 85006591, Mfr. 13016 |  |
| 1A7 |  | Circuit Card Assembly, FM record amplifier, 8 center frequencies, Dwg. 85004701, Mfr. 13016 | 7-1 (13) |
| 1A8 |  | Circuit Card Assembly, record-bias amplifer, 1000 ohm impedance, Dwg. 85003031-1, Mfr. 13016 | 7-1 (14) |

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST

| Reference Designation | Notes | Name and Description | Figure <br> $\underset{\text { (Item) }}{\text { Number }}$ |
| :---: | :---: | :---: | :---: |
| 1A8 | Option | Circuit Card Assembly, record-bias amplifier, 20, 000 ohm impedance, Dwg. 85003031-2, Mfr. 13016 |  |
| 1 A 9 |  | Circuit Card Assembly, 7.05 MHz bias oscillator, Dwg. 85001731, Mfr. 13016 | 7-1 (12) |
| 1 A 10 |  | Head Assembly, 1 MHz , Dwg. 19000701, Mfr. 13016 | 7-1 (15) |
| 1 A 10 | Option | Head Assembly, 14 track, 2 MHz , Dwg. 19000731, Mfr. 13016 |  |
| $1 \mathrm{Al1}$ |  | DC-DC Converter Kit, reproduce amplifier monitor, Dwg. 75002391, Mfr. 13016 | 7-1 |
| 1A11A1 |  | DC-DC Converter, Dwg. 84009680, Mfr. 13016 | 7-1 (18) |
| $1 \mathrm{A12}$ | Option | Accessory Service Kit, Dwg. 75001731, Mfr. 13016 |  |
| 1 A13 |  | Mating Connector Kit, Dwg. 75002221, Mfr. 13016 | 7-1 |
| 1A13P102 |  | Connector, Plug, electrical, Part No. MS3126F20-41P, Mfr. 96906 | 7-1 |
| 1A13P104, |  | Connector, Plug, electrical, Part No. MS3 9012-16-0001 Mfr 81349 | 7-1 |
| 1A13P107 |  | , |  |
| Through |  |  |  |
| 1A13P134 |  |  |  |
| 1A13W1 |  | Cable Assembly, special purpose, electrical, Dwg. 50001531, Mfr. 13016 | 7-1 |
| 1 A 14 | Option | Tape Lock Servo Kit, Dwg. 75002231-1 Mfr. 13016 |  |
| 1 A 15 | Option | Tape Lock BCD Encoder, Dwg. 75002.2312, Mfr. 13016 |  |

TABLE 7-1. RECORDER-REPRODUCER, MAGNETIC TAPE,RD378/U, PARTS LIST



Figure 7-1. Magnetic Tape Recorder/Reproducer Unit Parts Location (Sheet 1 of


001-069-2

Figure 7-2. Magnetic Tape Recorder/Reproducer Unit Parts Location (Sheet 2 of 3)


001-096
Figure 7-3. Magnetic Tape Recorder/Reproducer Unit Parts Location (Sheet 3 of 3)

## CHAPTER 8

INSTALLATION

8-1. INTRODUCTION.
8-2. This chapter contains instructions and procedures for unpacking, repacking, inspecting, installing, and checking out the Magnetic Tape Recorder/Reproducer unit. The unit is designed for installation in the vertical position within a standard 19 -inch wide electronic equipment rack. No special tools or materials are required for installation. Figure 8-1 show the Magnetic Tape Recorder/Reproducer unit. Figure 8-2 is an outline and mounting diagram, and Figure 8-3 is an interconnecting and cabling diagram.

## 8-3. SITE INFORMATION.

8-4. The unit is designed for installation in a standard 19 -inch electronic equipment rack. The unit must be installed in a location that is free of strong electrical or magnetic fields, which could affect the quality of recordings. The unit has a built-in blower for internal cooling and requires no external heating or cooling when operated between $0^{\circ}$ and $+54^{\circ} \mathrm{C}$. Installation in a rack with other units that generate excessive heat should be avoided. Attention should be given to placement of the equipment rack to ensure adequate ventilation.

8-5. REFERENCE PUBLICATIONS.
8-6. Refer to the technical manual for Sonar Receiving Set AN/SQR-15 for location of the Magnetic Tape Recorder/ Reproducer within the set.

8-7. UNPACKING AND REPACKING.

## WARNING

The unit weighs approximately 148 pounds. Two men, and preferably three, are required for removing the unit from the packing case to avoid injury to personnel.

8-8. The unit is packed in a reusable container. The unit is precision made and care should be taken not to drop it, or subject it to severe handling. Carefully remove the unit from the shipping container and check against the packing slip for shortages or damage. Refer to Table 8-1 for initial inspection details.

## NOTE

All packing materials, including the shipping container, are reusable. Replace all packing material in the container and store the container for future use.

## 8-9. INPUT REQUIREMENTS.

8-10. The unit requires single-phase, 115 ( +12 ) volt, 60 Hz power for operation. Power is supplied to the unit through J101 on the rear panel. Connector P101, which mates to J101, connects to the rack power supply to provide main power to the unit. The unit has an internal cooing fan that provides


Figure 8-1. Magnetic Tape Recorder/Reproducer Model RD378/U.


Figure 8-2. Outline and Mounting Drawing


Figure 8-3. Interconnecting and Cabling Diagram.

Wires, leads, connections,
insulation and protective
coating

Printed circuits

Mounting screws

Loose particles

Resistors and Capacitors

Power transistors

Solder joints

Connectors and receptacles

## Cables

Terminal boards

Panel controls

## Meter

Breaks, burns, corrosion, loosened connections or damage.

Cracked or inadequate protective coating.

Breaks, burnouts, corrosion, loosened eyelets and feedthrough terminals, shorts or lack of protective coating.

For looseness or stripped threads.

Conductive particles, jumper clippings, or solder drops.

Burnouts, bubbles, or lack of protective coating.

Missing mica washers, or lack of silicon grease under transsistor mountings.

Cold solder joints, excessive solder.

Insecure mounting, bent or missing pins, damaged shells.

Damaged insulation, improper routing, kinking, or twisting, loose or damaged cable clamps.

Breaks, cracks, or loose terminals, insecure mounting.

Loose or missing controls, improper switching action.

Cracked, broken, defaced, or missing readout.

TABLE 8-1. ITEMS TO BE INSPECTED (Cont'd)

| Panel, cover, and chassis | Loose or missing attaching hard- <br> ware, physical damage, illegible <br> markings on nameplates. |
| :--- | :--- |
| Transformers and chokes | Leaking potting compounds, wax, <br> or other signs of overheating, <br> damaged or broken connections, <br> insecure mounting. |
| Drive belts | Lack of tension or dirty belts. <br> Loose or broken connections, <br> insecure mounting. |
| Relays | Missing lamps, damaged sockets, <br> damaged or missing lenses, in- <br> secure mounting. |
| Indicator lamps and sockets |  |
| Switches | Damaged connections, insecure <br> mounting improper switching <br> action. |
| Heads | Dust, oxide, foreign material or <br> excessive wear. |
| Bearings | Smooth rotation with no sticking <br> or binding. |
| Mechanical parts | Obvious damage or wear. |

necessary cooling during operation. Additional cooling is not required as long as an adequate exhaust area is allowed for at the rear of the unit when mounted in the electronic rack.

8-11. INSTALLATION PROCEDURES.
8-12. UNIT ASSEMBLY. The unit requires no assembly other than the connection of the power cable to a power source (see paragraph 8-15).

8-13. UNIT MOUNTING. The unit is designed to install in a standard, 19inch electronic equipment rack. Mounting flanges are provided on both sides of the equipment case. Each flange is drilled with six holes for mounting the unit to the rack. Two men are required to lift and hold the unit in place while a third man installs and tightens the 12 mounting screws.

8-14. ELECTRICAL CONNECTIONS. All external electrical connections are made with connectors located on the rear connector panel (see Figure 8-2). Power input to the unit is made through J101 (POWER). All control and indicator functions are available through J102 (REMOTE) for control of the unit through a remote control panel (customer supplied). A jack (J103), RECORD TRANSFER, is also provided for transferring the record function from one recorder to another, if this option is installed in the recorder/reproducer. Tape servo input (if so equipped) is made through J104 (TAPE SERVO). Servo reference output is made through J105 (SER VO REF OUTPUT). Jacks J107 through J120 are provided for signal inputs to channel 1 through 14 record amplifiers. Amplified outputs from the reproduce heads
are through J121 through J134 for channels 1 through 14 respectively. A mating connector kit is supplied with the recorder/reproducer. This kit consists of a power cable for connecting 115 volts, single phase, 60 Hz power to J101, and connectors to be used in the construction of cables for other external connections. Thirty BNC connectors are provided for constructing cables for mating with J104, J105, and J107 through J134. These cables should be made of single conductor, shielded wire (type UG-88/U) of required length. If remote control is required in the installation, a cable may be fabricated from the supplied connector, and a 40-conductor shielded cable of the required length. Pin assignments are shown in Figure 8-4.

## 8-15. INTERCONNECTION INSTRUC-

 TIONS. All internal connections in the unit are made at the factory and no further interconnections are necessary.
## 8-16. SERVICING INSTRUCTIONS BEFORE OPERATION.

## NOTE

Most cleaning solvents are flammable and should be kept away from open flames and hot surfaces. They also should be used only in well-ventilated areas, as many emit toxic fumes. Failure to take these precautions can result in equipment damage and bodily harm or death to personnel.

8-17. Before attempting to operate the unit, it should be carefully inspected (see Table 8-1). The magnetic head assemblies should be cleaned with Xylene (Federal Specification TT-X916B) or equivalent, using a dampened
cotton swab. If the unit has been used previously at another location, or has been in storage for a long period, heads should be demagnetized as described in Chapter 4.

## CAUTION

Liquid cleaning solvents can cause damage to the polyurethane surfaces of the capstan shafts, and should not be used. If cleaning is required, use a soft, lint-free cloth.

## NOTE

All bearings within the unit are sealed and lubrication is not necessary during the life of the recorder.

8-18. GROUNDING INSTRUCTI ONS. The chassis of the unit is grounded through the ground wire of the power cable. No additional grounding or bonding is necessary.

8-19. INSTALLATION CHECKOUT.
8-20. PHASE 1- INSTALLATION INSPECTION AND PREENERGIZING PROCEDURE. The following procedure should be followed prior to energizing the unit.

## Step <br> Check

1. Visually check the unit for obvious faults, using Table 8-1 as a checklist.
2. Make certain that all plug-in printed wiring board assemblies (record reproduce amplifiers, etc.)

Step
are properly seated in the correct connectors.
3. Verify that J01 (POWER) is properly connected to a 115 volt, 60 Hz , single-phase power source, and that continuity exists in power transmission cable wires.
4. Check cables to input and output connectors on the rear connector panel for continuity and proper connections.
5. If provision for remote control is a part of the installation, ensure that continuity exists in all remote control cable wires and that the cable is properly connected to J02 and the remote control panel.
6. Verify that all test equipment listed in Chapter 1 is onboard, operating satisfactorily, and has been calibrated.

## 7. Verify that the Allow-

 ance Parts List (APL) is onboard and the Coordinated Shipboard Allowance List includes the equipment data.8. Verify that all field changes, shipalts, and mandatory retrofits, if any, have been accomplished.
9. Check for obstructions that might prevent proper rotation of reels and capstans. ( )


Figure 8-4. Rear Panel Connector and Pin Assignments.
Step Check
10. Verify that front dust cover and basic transport assembly move freely on their hinges and latch firmly into place.
ll. Ensure that the instructions in paragraph 8-16 have been complied with.
12. After steps 1 through 11 have been performed, it should be safe to turn on the unit.

8-21. PHASE 2 - INITIAL TURN- ON AND PRELIMINARY TEST. This procedure provides instructions for energizing the equipment for the first time. Refer to Chapter 2 and Figure 2-1 for a description of operator controls and indicators. The MAIN POWER switch should be off before starting procedure below.

1. Place a full reel of demagnetized tape (supply reel) over reel motor hub, guiding it past the three front mounting pads until it rests on the base of the lower hub.
2. Turn reel in either direction until locking detent locks into a slot on the inner surface of the reel.
3. Holding reel firmly against hub base, thread inner flange on hub and turn clockwise until supply reel is held firmly in place.
4. Place an empty reel (take-up reel) over upper hub, guide it toward inner knob, and allow bottom of reel to rest against three mounting pads.

Rotate reel to lock detent into slot on reel inner surface.
5. Thread outer flange on hub and turn clockwise until take-up reel is firmly secured.
6. Remove several turns of tape from supply reel and thread it through tape transport along top tape guides, around capstan drive, across heads, and along bottom tape guides, as shown in Figure 8-5.
7. Secure tape on take-up reel with approximately two turns of tape on the reel. Tape slack will be taken up gently when power is applied.
8. Verify that all steps of the procedure in paragraph 8-20 have been performed.

## CAUTION

If unit fails to operate properly at any of the steps in this procedure, press MAIN POWER switch to off and refer to troubleshooting procedures in Chapter 5. Locate symptoms and take corrective action before proceeding.
9. Press MAIN POWER and TRANSPORT POWER switch on. Indicator lamp should light.
10. Allow 15 minutes for warmup and stabilization. Then, using a VTVM connected to Test Points 1 and 2 (VOLTS and GND) on the RAM control panel (voltmeter on panel is accurate only to $\pm 10 \%$ ) and the VOLTAGE CHECK switch, check voltages at all five switch positions $(+5 \mathrm{~V},+15 \mathrm{~V},+18.5 \mathrm{~V},+20 \mathrm{~V}$, and +28 V ).


001-080

Figure 8-5. Tape Threading Diagram.

## NOTE

Tolerances for voltages are: $+5.5 \mathrm{~V}+10 \%$, $+15 \mathrm{~V}+5 \%$, +18.5 V $+1 \%,+\overline{20} \mathrm{~V}+1 \%$, and $+28 \mathrm{~V}+5 \%$. $\bar{T} h e+5 \mathrm{~V}$ and $\overline{\mathrm{d}}+15 \mathrm{~V}$ are fixed $\overline{\mathrm{V}}$ voltages and if not in tolerance the voltage regulator printed wiring board must be checked. The +18.5 voltage may be adjusted by R8 on the voltage regulator printed wiring board. The +20 voltages may be adjusted by Rl5. The +28 V power supply is not adjustable.
11. Press TRANSPORT POWER switch on. Indicator should light. Select 1-7/8 ips with transport SPEED SELECT switch. Status panel indicator should indicate $1-7 / 8$.
12. Press FORWARD and RECORD switches on. Indicator lamps should light. Tape should move forward at 1-7/8 ips from supply reel to take-up reel. Check that tape is tracking properly over tape guides, capstans, and head assembly.
13. Press STOP switch. Tape should stop smoothly with tension maintained across head assembly and STOP indicator lamp should light.
14. Provide $10 \mathrm{kHz}, 1.0 \mathrm{~V}$ rms signals to the inputs of all record channels (J107 through J120). Press FORWARD and RECORD switches.
15. Using a VTVM, check each output connector (J121 through J134) for an output signal.
16. Press FAST WIND switch. Indicator should light and tape speed should
accelerate rapidly to 240 ips . Press STOP. Tape should come to a smooth stop with tension maintained across head assembly.
17. Press FAST REWIND switch. Indicator should light and tape should accelerate rapidly to 240 ips. Allow tape to run completely off reel. Reels should come to a smooth stop. Status panel indicator should display END OF TAPE.
18. Repeat steps 12,13 and 16 for ther tape speeds. Observe status indicator for correct display of tape speed.

## NOTE

If installation includes a remote control panel with remote speed select, place SPEED SELECT switch in REMOTE position and repeat steps 12 through 17 from remote control position to verify that all switches are functioning properly.

## 8-22. PHASE III - INSTALLATION

 VERIFICATION TESTS. Equipment performance checks are contained in Chapter 6. It is not necessary, however, to perform all the tests to verify equipment operation. After the operational control check given in paragraph 8 - 21 has been completed, the following checks are sufficient to determine that the unit is functioning properly.a. Bias and record level check, paragraph 6-13.
b. FM deviation and center frequency check, paragraph 6-23.
c. Frequency response check, paragraph 6-19.

Following these checks, and any corrective action required, the unit should be fully operable.

8-23. INSTALLATION STANDARDS SUMMARY SHEET MAGNETIC TAPE RECORDER/REPRODUCER RD378/U NAVSHIPS.

INSTALLATION STANDARDS SUMMARY
Record on this summary sheet the test indications which have been obtained during the installation verification test.

Paragraph
Number
Ref. Std.
8-20

| 1 |
| :---: |
| 2 |
| 3 |
| 4 |
| 5 |
| 6 |
| 7 |
| 8 |
| 9 |
| 10 |
| 11 |

8-21

Paragraph Number

8-21 (cont'd)
$10+5 V$ $+15 \overline{\mathrm{~V}}$ $+18 . \overline{5 V}$ VDC +20 V -VDC +28 V VDC

```
11. check check
```

13 check
14 check
15 check
16 check
18
8 check

## Ref. Std

 check check check check17 check

17

18 $\qquad$

12 check
check

12

1315 VDC
VDC
VDC
VDC
VDC




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## APPENDIX A ADDENDUM TO OPERATION AND MAINTENANCE MANUAL AIRBORNE RECORDER/REPRODUCER MODEL M-14G

This addendum provides information covering a specially configured 28 -channel Model M-14G Reproduce System. This addendum should be used in conjunction with information contained in the basic $M-14 G$ operation and maintenance manual.

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## SECTION A-1

## INTRODUCTION AND DESCRIPTION

## Al.1 INTRODUCTION

A1.1.1 Scope. This appendix supplements information contained in the basic Model M14-G Operation and Maintenance Manual to provide coverage for the Model M14-G 28-Track Wideband Reproduce unit, referred to hereafter as the M14-G Reproducer.

Al.1. 2 General Description. The M14-G Reproducer (Figure A1-1) is designed to provide simultaneous 28 -channel reproduce capability at any of six electrically selectable tape speeds of $1-7 / 8,3-3 / 4,7-1 / 2,15,30$, and 60 inches-per-second. The M14-G Reproducer is identical to the M14-G Record/Reproduce system, except that the M-14G 28 -Track Reproducer contains a second Reproduce Amplifier Module (RAM) assembly, rack-mounted directly beneath the M14-G Reproducer housing, a 28 -Track. Magnetic Head Assembly, new Direct Reproduce Amplifiers, Preamplifiers, and voltage regulators. In addition, the original RAM shipped with the M14-G Record/Reproduce system was modified to the configuration of the additional RAM except for the retention of the local control function built into the original RAM. The original RAM was reidentified as part number 94001221-3 while the additional RAM is identified as part number 94001221-4.

A1.1.2.1 Whereas the reproduce preamplifiers are mounted directly beneath the magnetic head assembly on the M14-G Record/Reproduce system, the larger current mode preamplifiers are located within each RAM (-3 and -4). See Figure AI-2. In order to utilize the 28 -track head assembly in the M14-G Reproducer, the record amplifier connectors were removed from the standard M14-G. In place of the EVEN numbered record amplifier housing, a connector mounting plate has been installed with a connector to accommodate the new reproduce head outputs. (See Figure A1-1.)

Al.1.2.2 Operation and maintenance instructions for the modifications are contained in this addendum, as well as system interconnect information and parts listing.


Figure Al-1
28-TRACK MI4-G REPR ODUCE SYSTEM


Figure A1-2
Reproduce Amplifier Module (Sheet 1 of 2) P/N 94001221-4


Figure A1-2
Reproduce Amplifier Module (Sheet 2 of 2)
(Rear Pane1)

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## SECTION A-II

## INSTALLATION AND OPERATION

A2. 1 INTRODUCTION. This section provides instructions for installing and operating the M14-G 28-Track Reproduce. Amplifier Modules used in conjunction with the M-14G Recorder/Reproducer, and a table of functional characteristics of the M-14G Reproducer.

A2.2 UNPACKING. System components (including accessories) are packed for shipment in accordance with standard commercial practices for shipment by air freight, rail, or truck. The assemblies should be carefully removed from the shipping container, and the container, complete with all bracing, lining and padding, should be retained for use in the event of reshipment.

A2.2.1 Installation. The slide-mounted M14-G 28-Track Reproduce Amplifier Module (RAM) part number 94001221-4 is designed to be installed directly beneath the M14-G Reproducer in a rack-mounted position. The interconnect cables supplied with the RAM $(-4)$ were designed for this rack-mounted configuration in a standard 19-inch electronic equipment rack. Outline dimensions and mounting information are shown in Figure A2-1. System interconnection cables should be installed as shown in Figure A2-2. When mounting the unit, ensure that adequate space is provided for access to the connectors at the rear of the unit.

A2.2.2 Electrical Connections. Connector type and location are given in Figure A2-2. Connector pin assignments are given in Tables A2-1 through A2-5. Functional characteristics of the 28 -track M-14G Reproduce System are listed in Table A2-6.

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A2.3 OPERATION. The 28-track Reproduce Assembly has no local controls and is operated, automatically, by control signals from the $M-14 G$ control unit. The unit must be interconnected with the recorder for all operation and alignment purposes. For alignment and adjustment procedures, refer to Section A-IV of this addendum.


Figure A2-1
Outiine and Instailation


Figure A2-2
System Interconnection Diagram

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Table A2-1
28-track Reproduce Assembly Pin Assignments Signal Input Connectors J151, J156


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RAM 94001221-3
Table A2-3
28-Track Reproduce Assembly Pin Assignments
Control Connector J153
FUNCTION PIN NO.
Cable Shield
A
RecordB
Forward ..... C
Record ..... D
Common (Amplifier) ..... E
+28 vdc ..... F
Broken Tape ..... G
End of Tape ..... H
Forward ..... J
Spare ..... - K
Reverse
Fast WindL
Fast Rewind ..... NM
1-7/8 ips ..... P
Spare ..... Q
Remote Speed Select ..... R
Phase Lock Test Point ..... S
M1 (+) ..... T
Reverse ..... U
$+20 \mathrm{v}$ ..... V
$+18.5 \mathrm{v}$ ..... W
$+5 \mathrm{v}$ ..... X
$+15 \mathrm{v}$ ..... Y
M1 (-) ..... Z
Common (Indicators) ..... a
$+28 \vee$ (Indicators) ..... b
Stop ..... c
3-3/4 ips ..... d
7-1/2 ips ..... e
15 ips ..... f
ips
ips
120 ips ..... j
60 ips ..... h
30 jps ..... g

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## RAM 94001221-4

Table A2-4
28-Track Reproduce Assembly Pin Assignments
Control Connector Jl53

## FUNCTION

## Cable Shield

Spare
Common (Amplifier)
$+28 \vee$ (Amplifier)
Spare
1-7/8 ips
Spare
Spare
7-1/2 ips
15 ips
30 ips
60 ips

PIN NO.

## A

B thru D
E
F
G thru $N$
$P$
Q thru $Z$
a thru $d$
e
f
g
h

RAM 94001221-3
Table A2-5
28-Track Reproduce Assembly Pin Asignments
Power Input Connector J155
FUNCTION
115 vac (Hot)
Common (115 vac)
Power Relay
Chassis Ground (Cable Shield)

PIN NO.
A
B
C
D
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28-Track M14-G Reproduce System
Table A2-6. FUNCTIONAL CHARACTERISTICS
$115 \mathrm{vac}, \pm 10 \%, 50 / 60 \mathrm{~Hz} \pm 5 \%$ single phase
Reproduce - Forward/Reverse
28 channels of data, 400 Hz to 1.0 MHz at 60 ips for Direct/Analog reproducing.

Power Requirement:
Modes Of Operation:
Input/Output:

Frequency Response \& Signal-to-Noise Ratio:
Tape Speed (ips)
1-7/8
3-3/4
7-1/2
15
30
60

Frequency Response \& Signal-to-Noise Ratio:

Tape Speed (ips)
1-7/8
3-3/4
7-1/2
15
30
60

Direct Bandwidth $\pm 3 \mathrm{~dB} \quad \mathrm{~S} / \mathrm{N}$ Ratio

| $800 \mathrm{~Hz}-31.25 \mathrm{KHz}$ | 20 dB |  |
| :--- | :--- | :--- |
| $800 \mathrm{~Hz}-62.5 \mathrm{KHz}$ | 20 dB |  |
| $800 \mathrm{~Hz}-125$ | KHz | 20 dB |
| $800 \mathrm{~Hz}-250$ | KHz | 20 dB |
| $800 \mathrm{~Hz}-500$ | KHz | 20 dB |
| $800 \mathrm{~Hz}-1.0$ | MHz | 20 dB |

$\pm 3 \mathrm{~dB}$, all speeds

| Bandwidth $\pm 3 \mathrm{~dB}$ | SイN Rat |
| :--- | :--- |
|  |  |
| 400 Hz to 31.0 KHz | 18 dB |
| 400 Hz to 62.5 KHz | 18 dB |
| 400 Hz to 125 KHz | 18 dB |
| 400 Hz to 0.25 MHz | 18 dB |
| 400 Hz to 0.5 MHz | 18 dB |
| 400 Hz to 1.0 MHz | 18 dB |

Reproducing Tapes from
ASC GPAR/MARS-1428(LT) -3B

Tape Speed (ips)

| $1-7 / 8$ | $2.50 \%$ |
| :--- | :--- |
| $3-3 / 4$ | $1.50 \%$ |
| $7-1 / 2$ | $0.85 \%$ |
| 15 | $0.70 \%$ |
| 30 | $0.60 \%$ |
| 60 | $0.45 \%$ |.

Dynamic Skew Microseconds
(Adjacent tracks on same

$\pm 12.8$
16 hrs
$\pm 6.4$
$\pm 3.2$
$\pm 1.6$
$\pm 0.8$
$\pm 0.4$
8 hrs
4 hrs
2 hrs
1 hr
30 min

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28-Track M14-G Reproduce System
Table A2-6. FUNCTIONAL CHARACTERISTICS (Cont)
Tape Speeds:

Operating

FAST WIND/REWIND
Data Reproduce Channels:
Tape Type:

Operational Direction:
Start Time:
Stop Time:
Jitter:

Speed Accuracy:
End-of-Tape,
Tape Remaining,
Tape Break Sensors:

Local Controls

Remote Controls:

Magnetic Head Track Geometry: (28-Track Interlaced Reproduce)

1-7/8, 3-3/4, 7-1/2, 15, 30 and 60 inches-persecond.

240 ips
28
$3 M$ Type 888 or equivalent; 9200 ft . of one-inchwide tape per 14 -inch reel.

Operates in either forward or reverse direction.
Less than 5 seconds at 60 ips
Less than 3 seconds from 60 ips
Less than $0.5 \mu \mathrm{sec}$ in a $200 \mu \mathrm{sec}$ interval on any track at 60 ips , without tape servo.
$\pm 0.2 \%$ of nominal
Optical systems which stop transport in event of tape breakage or end of tape. Indicators show. amount of tape remaining on supply reel and tape break or end-of-tape condition.

MAIN POWER on/off, TRANSPORT POWER on/off, SPEED SELECT, FORWARD, REVERSE, RECORD, FAST WIND, FAST REWIND.

Provision for all local control functions except SPEED SELECT, via J102. Customer supplies remote control panel and switching circuitry.

Width; 0.025 inches; Spacing; 0.035 inches; Interlace distance, 1.500 inches $\pm 0.001$ inches.

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28-Track M14-G Reproduce System
Table A2-6. FUNCTIONAL CHARACTERISTICS (Cont)

## Data Signal Output Level:

## Direct

Normal Record Level:

Power Consumption:

## Operating Temperature:

Relative Humidity:
Mechanical Shock:
Operating:
Crash Safety:
Operating Vibration:
4 to 15 Hz
16 to 25 Hz
26 to 33 Hz

Adjustable ( 1.0 volt rms nominal at normal record level)

2\% Third Harmonic
Less than 400 watts
$0^{\circ} \mathrm{C}$ to $+54^{\circ} \mathrm{C}$
$15 \%$ to $95 \%$ without condensation
$\pm 15$ gravity, 11 ms
30 gravity
( $0.8 \%$ peak-to-peak flutter at 60 ips )
0.06 inches double amplitude
0.04 inches double amplitude
0.02 inches double amplitude

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SECTION A-III
THEORY OF OPERATION

A3.1 INTRODUCTION. Since the M14-G 28-Track Reproducer is identical to the basic M14-G Recorder/Reproducer except for differences within the magnetic head assembly and the Reproduce Amplifier Modules (RAM) ; theoretical discussions here in will be confined to the unique differences between RAM electronics supplied with the basic M14-G Record/Reproduce unit, and the differences between both RAM units supplied with the M14-G Reproducer, 94001221-3 and 94001221-4.

A3.1.1 Scope. The data in this section is presented to familiarize the user with the equipment and as an aid in isolating equipment malfunctions which may occur during operation. Functional subdivisions of the unit are covered separately. Refer to Figures AI-1 and A1-2 for location of major components.

A3.2 SYSTEM DESCRIPTION. Refer to Figure A3-1. The M14-G 28-Track Reproducer, with Reproduce Amplifier Modules 94001221-3 and 94001221-4, provide simultaneous 28 -channel reproduce capability at any of six electrically selectable tape speeds of $1-7 / 8,3-3 / 4,7-1 / 2,15,30$, and 60 inches-per-second. The basic M14-G Record/Reproduce unit provides only 14 channels of reproduction at each of the above tape speeds. Both the 94001221-3 and -4 RAM units contain 14 Reproduce Amplifiers (85004971) and seven Dual-Channel Preamplifiers (85004961) each. A +15 -Volt dc Voltage Regulator (85003001) and a $+20-$ Volt dc Voltage Regulator (85002601) are also contained in each RAM unit to provide operating voltages for the Reproduce Amplifiers and Preamplifiers. The larger current mode preamplifiers are located within the RAM (94001221-3 and -4) for the M14-G Reproducer (28-tracks). The 94001221-4 RAM unit . has no local controls, and is operated automatically by control signals from the M-14G Reproducer through the control unit 94001221-3. RAM 94001221-4 is separate from the M14-G Reproducer and is slide-mounted in a standard 19-inch rack directly beneath the M14-G Reproducer housing. Mating connector cables 50001721 (Monitor/Remote) and 5001731 (Remote/Power) provide system interconnect between the 94001221-4 and the M14-G Reproducer.
A.3.3 REPRODUCE PREAMPLIFIER (85004961). Refer to Figure A3-2. Each Reproduce Preamplifier consists of two separate preamplifier circuits mounted on a single plug-in printed wiring board. As shown, the output of the reproduce head is capacitor coupled to the base of amplifier Q2. The output of Q2 is directly coupled to the emitter of Q1, with degenerative feedback provided by resistor R1. The output of Q1 is directly coupled to the output emitter-follower (Q3), which provides current gain and impedance



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matching to drive the Reproduce Amplifier. Zener diode CRI and capacitor C6 provide stable operating voltage for output transistor Q3. Transistors Q4, Q5, and Q6 provide similar functions for the second reproduce channel.

## A3.4 REPRODUCE AMPLIFIER (85004971)

A3.4.1 General Description. Refer to Figure A3-3. The Reproduce Amplifier provides amplitude and phase equalization for the direct record/reproduce system. As shown, the circuit contains an overall LEVEL control (R1), and separate amplitude and phse equalization circuits for each tape speed (1-7/8 thru 60 ips ). Through the utilization of both fixed and variable circuit components, the gain of the amplifier is caused to decrease as input frequency increases. This rolloff occurs at the rate of approximately 6 dB /octave to compensate for the normal 6 dB /octave increase in output from the reproduce head.

A3.4.2 Input Stages. The output signal from the Reproduce Preamplifier is applied to the Reproduce Amplifier across the reproduce LEVEL control (RI), which serves as the overall gain control for the amplifier. After passing through the amplifier input stages (Q10Q4), the unequalized reproduce signal is applied to the amplitude equalization networks, through resistor RII, and through the high-frequency compensation network consisting of R110, C49, and the HIGH FREQ. ADJ. trimmer (C48). MID FREQ. ADJ. control (R28) serves to control the overall signal loss introduced by the reactive equalization components.

A3.4.3 Low-Frequency Equalization. At low-frequencies, when the recorder is operated at 30 or 60 ips , the capacitive reactance of C12 is high compared to the resistance of R29 and R30. Therefore, these resistors become the controlling element in determining low-frequency response. The low-frequency gain of the amplifier, at 30 and 60 ips , is therefore determined by the setting of the LF ADJ. control (R29). As frequency increases, the reactance of C 12 decreases, providing a progressive rolloff in amplifier gain, in proportion to input frequency. Separate low-frequency equalization networks are used for the high ( 60 and 30 ips ) and low ( 15 thru $1-7 / 8$ ips) tape speeds.

A3.4.4 High-Frequency Equalization. At approximately the midpoint in the recorder/reproducer bandwidth, a sharp rolloff ( -18 dB /octave) occurs, due to the characteristics of the reproduce head. To compensate for this rolloff, a parallel resonant LCR network, consisting of L1, C14, R33, R34, and R94, is utilized to increase the overall impedance of the equalization circuits, to these frequencies. BANDEDGE ADJ. contro! R3A serves to adjust the gain of the amplifier at high-frequencies, by controlling the reactance of the LCR network. Since the bandwidth of the recorder/reproducer doubles with each progressive increase in tape speed, a separate high-frequency equalization network is utilized for each speed.


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Figure A3-3. Reproduce Amplifier Schematic Diagram (85004971)

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A3.4.5 Equalization Select Circuits. Proper high-frequency equalization circuits are selected, automatically, with tape speed selection, by grounding one of the speed select lines (pins 5 thru 10). When the 60 ips tape speed is selected, for example, ground is provided at pin (7) of the Reproduce Amplifier. This causes transistor Q12 and Q13 to conduct, providing a ground return path to the 60 ips equalizer, through resistor R94. Transistors Q14 thru Q23 perform the same switching function for the 30 thru $1-7 / 8$ ips high-frequency equalization networks, when their respective speed select lines are grounded.

A3.4.6 Phase Equalization. The purpose of the phase equalization circuit is to compensate for the phase distortion introduced by the amplitude equalizers, and to restore proper phase relationships of the various signal frequency components. From the amplitude equalization networks, the signal is routed through capacitor C4 and emitter-follower Q4, to the phase splitter/amplifier Q5. Transistor Q5 provides two identical output signals that are $180^{\circ}$ out of phase with each other. The signals are then recombined through the phase restoration network consisting of R17, R18, C6 thru C11, and R21, to restore proper signal phase. Separate phasing capacitors ( $C 6$ thru $C 11$ ) are used for each tape speed, and are automatically connected into the circuit by switching transistors Q6 thru Q11, when one of the speed select lines (pins 5 thru 10) is grounded. Variable resistor R20 ( $2 / 3$ BANDEDGE ADJ.) serves to balance the amplitude of the two output signals from Q5. PHASE ADJ. control R18 permits adjusting circuit reactance for proper phase resoration.

A3.4.7 Output Stages. From the phase equalizer, the signal is routed through emitter-follower Q24 to a bank of low-pass filters, which remove high-frequency noise outside of the recorder bandwidth. Separate filters are used for each tape speed, and are automatically selected when one of the speed select lines are grounded. After filtering, the signal is amplified in the output amplifiers stages (Q31-Q36), and appears at the output connectors on the rear panel of the RAM.

A3.5 +15-VOLT VOLTAGE REGULATOR (85003001). Refer to Figure A3-4. $A+15 \mathrm{Vdc}$ Voltage Regulator is installed in each of the two RAM units to provide regulated operating voltage for the seven dual-channel preamplifiers. Power transistor Q1 is a series-regulator operating directly from the +28 Vdc primary power source, supplied to pin 10 of the regulator printed wiring board. The +15 Vdc output voltage is sensed across a voltage divider network consisting of resistors R5, R7, and variable resistor R6, and applied to the base of control transistor Q2. Transistor Q2 compares the sampled output voltage, from the center arm of R6, with a fixed reference voltage developed across zener diode CR3, and develops an output signal proportional to the difference, to drive the series regulator Q1. Zener diode CR3 and transistor Q2 have opposite temperature coefficients to compensate for changes in ope rating temperature. Diodes CR1 and CR2, connected between the emitter and base of transistor Q1, protect the transistor from current surges.


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Capacitor Cl provides filtering for the +15 Vdc output voltage, available at pin 9 of the regulator printed wiring board. Variable resistor R6 serves to adjust the output voltage to exactly +15 Vdc .

A3.6 +20-VOLT VOLTAGE REGULATOR (85002601). Refer to Figure A3-5. $A+20 \mathrm{Vdc}$ Voltage Regulator is installed in each of the two RAM units to provide regulated operating voltage for the 14 Reproduce Amplifiers. Power transistor Q2 is a seriesregulator operating directly from the +28 Vdc primary power source, supplied to pin 10 of the regulator printed wiring board. The +20 Vdc output voltage is sensed across a voltage divider network consisting of resistors R6, R8, and variable resistor R7, and applied to the base of control transistor Q3. Transistor Q3 compares the sampled output voltage, from the center arm of R7, with a fixed reference voltage developed across zener diode CR2, and develops an output signal proportional to the difference, to drive transistor Q1, which, in turn, controls conduction of the series-regulator Q2. Zener diode CR2 and transistor Q3 have opposite temperature coefficients to compensate for changes in operating temperature. The input $28 \dot{\mathrm{Vdc}}$ is clamped by zener diode CR1 to approximately 24 Vdc , to drive the control circuit. Capacitor $C 2$ provides filtering for the +20 Vdc output voltage, available at pins 1 and 2 of the regulator printed wiring board. Variable resistor $R 7$ is used to adjust the output voltage to exactly +20 Vdc .

A3.7 SPEED CHANGE LOGIC (85002012). Refer to Figure A3-6. The function of the Speed Change Logic is to select the proper equalization network in the Reproduce Amplifiers, which correspond to the tape speed at which the recorded signals are to be reproduced, determined by the position of the SPEED SELECT switch(s) on the recorder Control Unit. When a specific tape speed is selected, a corresponding relay (or combination of relays) on the Speed Logic card is energized. The only exception is the $3-3 / 4$ ips speed, in which case all speed select relays are de-energized, and a ground return path. is provided by the normally-closed contacts of $\mathrm{K} 1, \mathrm{~K} 2$, and K 3 . For $7-1 / 2 \mathrm{ips}, \mathrm{K} 3$ is energized by 28 Vdc across pins 5 and 6 , and a ground return path is provided through. normally-closed contacts of K 1 and K 2 , through $\mathrm{K} 3 \mathrm{AI} / \mathrm{K} 3 \mathrm{~A} 2$. For $15 \mathrm{ips}, \mathrm{K} 2$ is energized (across pins 6 and 14) and ground is supplied through normally-closed contacts of K1, through K2A1/K2A2, and normally-closed contacts B2 and B3 of K3. For 30 ips, K2 and K3 are energized (across pins 6 and 9) and ground is supplied through K3B1/K3B2, K2AI/ K2A2, and through the normally-closed contacts of K1. For $60 \mathrm{ips}, \mathrm{K} 1$ is energized (across pins 6 and 11) and ground is supplied through the normally-closed contacts of K4 and K2, and through KIA1/K1A2. For $1-7 / 8$ ips, relays $K 1$ and $K 4$ are energized (across pins 6 and 15 ) and ground is supplied through K4A1/K4A2, through the normally-closed contacts of K2, and through K1A1/K1A2. In each case, the ground return path provided by the Speed Change Logic selects the proper equalization networks on the Reproduce Amplifier, for the speed selected.








MOTES: 1. RESISTOR VALUES IN OFMS, $1 / 4 \therefore 5 \%$
2. CAPACITOR VALUES IN UF
3. REFERENCE DRATINGS: Recorder, Basic, 95002881 , Transport Housing Assy, 85007291, Wiring Diagram 85007293


NOTE:

## These harness wires are not used in this APPLICATION---THEY ARE TO BE TIED BACK.



APE SERVO INi':
CAELE SHIE:
Figure A3-7
Model M14-G 28-Track Reproducor Schematic Diagram

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## SECTION A-IV

SYSTEM TEST AND ALIGNMENT

## A4.1 INTRODUCTION

A4.1.1 Scope. This section contains subassembly adjustment procedures and system level test procedures which permit aligning the equipment for optimum performance. These tests should be performed prior to initial operation of the equipment, after any equipment repairs, and after every 60 to 100 hours of operation, as part of a regular scheduled Preventive Maintenance program. All testing is based on the use of the M-14G Reproducer. The information contained in this section is intended to supplement the test and alignment procedures contained in Section IV of the basic manual.

A4.1.2 Order of Precedence. Tests described in this section should be performed in the order listed, unless otherwise specified, or unless checking a specific parameter after repair or adjustment.

A4.2 Test Equipment Requirements. The following test equipment, or equivalent, is required to adjust the M14-G Reproducer (See Figure A4-1):

1. VOM
2. Sinewave Osc. $H-P 651$ B
3. Squarewave Gen. Wavetek Model 130
4. Oscilloscope Tektronix 545
5. AC VTVM H-P 400 E
6. 28-Track Recorder/ MARS/GPAR 1428 Reproducer
7. Bandpass Filter 400 Hz to 1 MHz
8. Frequency Counter

A4.3 + 15-VOLT REGULATOR ADJUSTMENT

1. With the equipment connected as shown in Figure A2-2, apply

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primary input power ( +28 Vdc ) to the system and place the recorder in the STOP mode.
2. Connect VOM between the +15 volt test-point on the ODD channels voltage regulator card and ground. Adjust R6 for an indication of +15 Vdc on the meter. (See Figure A6-3.)
3. Repeat steps (1) and (2) for the EVEN channels +15 volt regulator.

## A4. 4 +20-VOLT REGULATOR ADJUSTMENT

1. Secure system primary input power ( +28 Vdc ), and remove one of the Reproduce Amplifiers from the ODD channels RAM.
2. Reapply input power and connect VOM between pin (1) of the Reproduce Amplifier connector and ground. Adjust R7 for an indication of +20 Vdc on the meter. (See Figure A6-4.)
3. Secure system primary input power and replace Reproduce Amplifier in RAM.
4. Repeat sieps (1) thru (3) for the EVEN channels RAM.

## A4.5 REPRODUCE AMPLIFIER ALIGNMENT PROCEDURE

The following paragraphs describe the procedure for adjusting the Direct $\mathrm{Re}-$ produce Amplifier (85004971). These adjustments should be checked and, if necessary, readjusted after every 60 to 100 hours of equipment operation.

A4.5.1 Test Equipment Required. The following test equipment (or equivalent) is required to check and adjust the Direct Reproduce Amplifier.

1. Sinewave Oscillator H-P651 B
2. Squarewave Generator Wavetek Model 130
3. Frequency Counter
4. Oscilloscope Tektronix 545
5. AC VTVM H-P 400 E
6. M1428 Rec/Repro Astro-Science Corporation

A4.5.2 Preliminary Procedures. Before attempting to adjust the Direct Reproduce Amplifiers, perform the following preliminary procedures.

1. To facilitate testing and checkout procedures listed herein, it is recommended that a test tape be prepared using a compatible 28track recorder such as the MARS/GPAR 1428 under the following format:
a. Record an input signal of 1.0 Vrms simultaneously on all 28 tracks.

## NOTE

Record amplifiers shall be adjusted to produce 2.0\% third order harmonic distortion. Refer to Bias Level and Record Level adjustment procedures described in the basic O\&M Manual.
b. Record each frequency for a duration of two minutes at the following tape speeds and frequencies.

## NOTE

It is suggested that each tape segment be separated by a 5 -second pause. For ease of explanation, individual frequencies and tape speeds are tabulated as "EVENT NUMBERS".

EVENT
1 2
3
4
5
6
7
8
9
10
11
12

TAPE SPEED
60 ips
60 ips
60 ips
3-3/4 ips
$3-3 / 4$ ips
60 ips
60 ips
30 ips
30 ips
30 ips
15 ips
7-1/2 ips.

## FREQUENCY

| 10 KHz | sinewave |
| :--- | :--- |
| 100 KHz | sinewave |
| 1 MHz | sinewave |
| 62.5 KHz | sinewave |
| 42 KHz | sinewave |
| 100 KHz | sinewave |
| $200 \mathrm{KHz-1} \mathrm{MC}$ | sweep |
| 400 Hz | sinewave |
| 500 KHz | sinewave |
| 50 KHz | squarewave |
| 250 KHz | sinewave |
| 125 KHz | sinewave |

100 KHz sinewave 1 MHz sinewave 62.5 KHz sinewave 42 KHz sinewave 100 KHz sinewave $200 \mathrm{KHz}-1 \mathrm{MC}$ sweep 400 Hz sinewave 500 KHz sinewave 50 KHz squarewave 250 KHz sinewave 125 KHz . sinewave

| EVENT | TAPE SPEED |  | FREQUENCY |
| :--- | :--- | :--- | :--- |
| 13 | $3-3 / 4 \mathrm{ips}$ | 62.5 KHz | sinewave |
| 14 | $1-7 / 8 \mathrm{ips}$ | 31.2 KHz | sinewave |
| 15 | $1-7 / 8 \mathrm{ips}$ | 400 Hz | sinewave |

c. The test frequencies are followed by a series of sweep tones to be used to check overall frequency response after alignment procedures have been completed. Each sweep tone is recorded for a period of 1 minute. Tape speed and sweep tone frequencies are as follows:

| EVENT | TAPE SPEED | SWEEP FREQUENCY |
| :---: | :---: | :---: |
| 16 | 60 ips | 400 Hz to 1 MHz |
|  | 30 ips | 400 Hz to 500 KHz |
|  | 15 ips | 400 Hz to 250 KHz |
|  | 7-1/2 ips | 400 Hz to 125 KHz |
|  | 3-3/4 ips | 400 Hz to 62.5 KHz |
|  | 1-7/8 ips | 400 Hz to 31 KHz |

2. Clean heads and tape path as described in basic recorder $O \& M$ Manual.
3. Demagnetize the headstack as described in basic recorder O \& M Manual. .
4. Perform head azimuth adjustment as described in basic manual.

A4.5.3 Alignment Procedure. To adjust the Reproduce Amplifiers, proceed as follows:

1. Connect test equipment as shown in Figure A4-1.
2. Refer to Figure A4-2 for location of adjustment controls.
3. Place the Reproducer (unit) in the FORWARD mode at 60 ips .
4. Event No. $1(10 \mathrm{KHz})$ :

Adjust LEVEL ADJ. control (R1) for an indication of 1.0 Vrms as read on the output AC VTVM.

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5. Event No. $2(100 \mathrm{KHz})$ :

Adjust MID FREQ. ADJ. control (R28) for an output indication of 1.0 V rms.
6. Event No. 3 (1 MHz):

Adjust the 60 ips BANDEDGE ADJ. control (R34) for an output indication of 2.0 dB below 1.0 V rms.
7. Place unit in the STOP mode. Change tape speed to $3-3 / 4$ ips. Place unit in the FORW ARD mode at 3-3/4 ips.
8. Event No. 4 ( 62.5 KHz ):

Adjust 3-3/4 ips BANDEDGE ADJ. control (R61) for an output indication of 2.0 dB below 1.0 V rms.
9. Event No. $5(42 \mathrm{KHz})$ :

Adjust 2/3 BANDEDGE ADJ. control (R20) for an output indication as near as possible to 1.0 dB below 1.0 V rms.
10. Place unit in STOP mode. Change tape speed to 60 ips . Place unit in FORWARD mode at 60 ips .
11. Event No. $6(100 \mathrm{KHz})$ :

Repeat step 5.
12. Event No. 7 ( 200 KHz to 1 MHz sweep) :

Note any peaks in the response as indicated on the output AC VTVM. If the output exceeds 1.0 V rms by more than 3.0 dB , adjust the HIGH FREQ. ADJ. control (C48) for an output indication as near to 1.0 V rms as possible. Repeat steps (5) thru (9) using the prerecorded frequencies as required.
13. Place the unit in the STOP mode. Change tape speed to 30 ips . Place unit in the FORWARD mode at 30 ips.
14. Event No. $8(400 \mathrm{~Hz})$ :

Adjust LOW FREQ. ADJ. control (R29) (LF 30-60) for an output indication of 2.0 dB below.l. 0 V rms.
15. Event No. $9(500 \mathrm{KHz})$ :

Adjust the 30 ips BANDEDGE ADJ. control (R40) for an output indication of 2.0 dB below 1.0 V rms.
16. Event No. 10 ( 50 KHz squarewave at 2.8 V peak-to-peak):

Adjust PHASE ADJ. control (R18) for the best squarewave response.
17. Place unit in the STOP mode. Change tape speed to 15 ips . Place unit in the FORWARD mode at 15 ips.
18. Event No. 11 ( 250 KHz ):

Adjust the 15 ips BANDEDGE ADJ. control (R47) for an output indication of 2.0 dB below 1.0 V rms.
19. Place unit in the STOP mode. Change tape speed to $7-1 / 2 \mathrm{ips}$. Place unit in the FORW ARD mode at 7-1/2 ips.
20. Event No. 12 ( 125 KHz ):

Adjust the 7-1/2 ips BANDEDGE ADJ. contol (R54) for an output indication of 2.0 dB below 1.0 V rms.
21. Place the unit in the STOP mode. Change tape speed to $3-3 / 4$ ips. Place unit in the FORWARD mode at $3-3 / 4 \mathrm{ips}$.
22. Event No. $13(62.5 \mathrm{KHz})$ :

Adjust the 3-3/4 ips BANDEDGE ADJ. control (R61) for an output indication of 2.0 dB below 1.0 V rms.
23. Place unit in the STOP mode. Change tape speed to $1-7 / 8$ ips. Place unit in the FORWARD mode at 1-7/8 ips.
24. Event No. 14 (31.2 KHz):

Adjust $1-7 / 8$ ips BANDEDGE ADJ. control (R68) for an output indication of 2.0 dB below 1.0 V rms.
25. Event No. $15(400 \mathrm{~Hz})$ :

Adjust LOW FREQ. ADJ. control (R31) (LF1-7/8-15) for an

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output indication of 2.0 dB below I .0 V rms. Place unit in STOP mode.
26. Event No. 16 (sweep frequency):

Test the frequency response at all tape speeds from 400 Hz to the bandedge frequency to ascertain that the response is flat ( $\pm 3.0 \mathrm{~dB}$ ) over the entire bandwidth.
27. Change tape speed to $60 \mathrm{ips}$. Place unit in FORWARD mode. Note any bumps or dips on the output AC VTVM as frequency is swept between each segment of the response curve.

## NOTE

There is a pause on the test tape at the end of each frequency segment.
28. Repeat step 27 at $30,15,7-1 / 2,3-3 / 4$ and $1-7 / 8$ ips while reproducing appropriate segment of test tape.

A4.5.4 Signal-to-Noise Ratio Check

1. Connect a bandpass filter to the channel 1 reproduce output. Connect oscilloscope frequency counter, and AC VTVM to output of bandpass filter.
2. Adjust bandpass filter to pass a bandwidth from 400 Hz to 1.0 MHz .
3. Fast wind the tape to the 100 KHz segment of the test tape.
4. Place the unit in the FORWARD mode at 60 ips. Note indication on AC VTVM (should be 1.0 V rms).
5. Allow tape to pass the 100 KHz segment to a blank portion of tape, then again note AC VTVM reading. Note SNR reading.
6. Adjust bandpass filter to a bandwidth of 800 Hz to 1.0 MHz .
7. Repeat steps (3) thru (5). Note results.
8. Repeat steps (1) thru (7) for remaining channels.
9. Repeat steps (1) thru (8) for remaining tape speeds. Adjust bandwidth of filter to upper band edge for each speed. Note results. The 400 Hz band edge filtered signal should be a minimum of 18 dB at all tape speeds. The 800 Hz band edge should be a minimum of 20 dB at all tape speeds.

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## SECTION A-V

## SYSTEM MAINTENANCE

## A5.1 INTRODUCTION

This section contains an overall system schematic diagram for the two 14channel Reproduce Amplifier Modules and such other diagrams and maintenance information not covered elsewhere in this addendum. The information contained in this section is intended to supplement the maintenance information contained in Section $V$ of the basic manual.


1. NOT SHOWN:

| 117-3 | TO | J4-15 |
| :---: | :---: | :---: |
| J17-8 | T0 | 15-15 |
| J18-3 | TO | J6-15 |
| J18-8 | T0 | J7-15 |
| J19-3 | TO | J8-15 |
| J19-8 | T0 | J9-15 |
| J20-3 | T0 | J10-15 |
| J20-8 | TO | J11-15 |
| J21-3 | T0 | J12-15 |
| J21-8 | T0 | J13-15 |

## 2. SEE SHEET 2 OF 2 FOR REMAINDER OF 94001221-3 CIRCUITRY.


$(-3)(-4)$






Figure A5-1
Shey 2 of 2)
Schematic Diagram
Reproduce Amplifier

- Modula (94001221-3)

| Page A5-3 | 95002669 |
| :---: | :---: |
| Appendix A |  |



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Figure $15=2$
Reproduce Amplifier Schematic Diagram (85004971)



Figure A5-3
(Sheen 1 of 2)
M14-G Interconecting Diagram

$131021 P 102$



Figure A5-3
(fheet 2 of 2)
Mi4. O Inarconnecting Diagrom

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## SECTION A-VI <br> REPLACEMENT PARTS LIST

## A6. 1 <br> INTRODUCTION

This section contains a major components list for the 28 -track M-14G Reproduce System, and an illustrated and indexed parts list for use in locating and identifying replacement parts. For assemblies not listed in this section, refer to Section VI of the basic manual.



| ASTRO-SCIENCE CORPORATION |  |  |  |
| :---: | :---: | :---: | :---: |
|  |  | FLY-AWAY KIT (cont) |  |
|  | 85005181 | Reel Servo | (1) |
| $i$ | 85004451 | Voltage Ŗegulator | (1) |
|  | 84007981 | Control Logic | (1) |
|  | 84007961 | Capstan Servo | (1) |
|  | 84002701 | Roller Guide | (1) |
|  | 84003271-99 | Tape Tension Sensor | (1) |
|  | 84003271-98 | Tape Tension Sensor | (1) |
|  | 84008041 | Tape Guide | (1.) |
| - | 84007931 | Power Switch | (1) |
|  | 84007831 | Capstan Motor | (1) |
|  | 85004971 | Direct Reproduce Amplifier | (2) |
|  | 85004961 | Direct Reproduce Pre=Amplifier | (1) |
|  | 11000060-23 | Fuse, 3-Amp | (2) |
|  | 11000060-16 | Fuse, 2-Amp | (2) |
|  | 11000060-24 | Fuse, 7-Amp | (2) |
|  | 12000480 | Lamp | (1) |
|  | 75002221 | Mating Connector Kit <br> (Includes AC Power Cable) | (1) |
|  | 30008031-2 | Tape; 3M Type $888,9200 \mathrm{ft} \mathrm{x} 1 \mathrm{in}$ |  |
|  | 30008031-9 | Tape; 3 M Type 988, 9200 ft x 1 in |  |
|  | 30004890-4 | Reel, Precision, 14-inch (less tape) | (1) |
|  | 95.002669 | Operation and Maintenance Manual <br> (With Appendix A--28-Track Reproducer) | ) (1) |
|  | 13000030 | Shipping Container, Rẹuseable |  |



| ASTRO-SCIENCE CORPORATION a subiolahy of trancorizim |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FIG \& | PART |  | SCRIPTION |  | QTY PER |
| ITEM NO. | NUMBER | 1 | 234 | 5 | ASSY |
| Fig. A6-1 . |  |  |  |  |  |
| $41001070$ |  | - | INSULATOR, | TRANSISTOR | 4 |
| 41000110 |  |  | INSULATOR, | TRANSISTOR | 6 |
| 49005181 |  |  | PRINTED WIR | ING BOARD | 1 |

## ASTRO-SCIENCE CORPORATION



Figure A6-1
Reproduce Preamplifier (85004961)







| ASTRO-SCIENCE CORPORATION a subsidiary of trā̃con. Inc. |  |  |  |
| :---: | :---: | :---: | :---: |
| - |  |  |  |
| R60,67 | RC07GF511J | RESISTOR, FXD, Comp, 510 OHMS, $+5^{\%}, 1 / 4 \mathrm{~W}$ (MIL-R-11/8) | 2 |
| R61,68 | 01002080-11 | RESISTOR, Variable, 20K | 2 |
| R76 | RC07GF151J | RESISTOR, FXD, Comp, 150 OHMS, $\pm 5 \%, 1 / 4 \mathrm{~W}$ (MIL-R-11/8) | $\because 1$ |
| $\begin{aligned} & \text { R90, } \\ & 107 \end{aligned}$ | RC07GF682J | $\begin{aligned} & \text { RESISTOR, FXD, Comp } 6.8 \mathrm{~K}, \\ & \pm 5 \%, 1 / 4 \mathrm{~W}(\text { MII-R- } 11 / 8) \end{aligned}$ | 2 |
| R96 | RC0.7GF113J | RESISTOR, FXD, Comp, 11K, $\pm 5 \%, 1 / 4$ W (MLL-R-11/8). | 1 |
| $\begin{aligned} & R G 9 \\ & 105 \end{aligned}$ | RCG7GF100J | RESISTOR, FXD, Comp, 10 OHMS, $\pm 5 \%, 1 / 4 \mathrm{~W}(\mathrm{MIL}-\mathrm{R}-11 / 8)$ | 2 |
| R101 |  | RESISTOR; FXD, Comp, 47 OHMS, $\pm 5 \%, 1 / 4 \mathrm{~W}$ (MIL-R-11/8) | 1 |
| R104 | RC07GF220J | RESISTOR, FXD, Comp, 22 OHMS, $\pm 5 \%, 1 / 4 \mathrm{~W}$ (MIL-R-11/8) | 1 |
| R108 | RC07GF330J | RESISTOR, FXD, Comp, 33 OHMS, $\pm 5 \%, 1 / 4 \mathrm{~W}$ (MIL-R-11/8) | 1 |
| . -1 : | MS51957-2 | SCREW, Mach, 2-56x.19 LG | 4 |
|  | MS35338-134 | WASHER, Lock, No. 2 | 4 |
|  | MS15735-802 | WASHER, Flat, No. 2 | 4 |
| -2 | 35013381 | SHIELD, PWB | 1 |
| -3 | 49006011 . | BOARD, Printed Wiring | 1 |



Figure A6-2. Wideband Reprofuce Amplifier Assembly 85004971 (Sheet 1 of 2)




Figure A6-3
+15-Volt Voltage Regulator (85003001 C)




Figure A6-4
$+20-V o l t$ Voltage Regulator (85002601 B)



