## VGER

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## TIMER

Returns to task when timer decrements to zero16 bit timer with each tic $=1 / 60$ th of a second.Retains overflow time base when timer expires.
TIMER-ON
Turn on timer check
TIMER-OFF
Turn off timer check
TIMER! n --Store timer value n into VECTOR.
TIMER!-ON n --Turn on timer checkStore timer value n into VECTOR.
TIMER? ..... --- n
Returns boolean $n$, true if timer went to zero

## FLAG

Returns to task when contents of flag address is non zero. When flag is detected flag byte is zeroed.

```
FLAG-ON
    Turn on flag check.
FLAG-OFF
    Turn off flag check
FLAG! n ---
    Store flag address n into vector
FLAG!-ON n ---
    Turn on flag check
    Store flag address n into vector
```

FLAG?
--- n
Returns boolean $n$, true if flag was set

## LIMITS

Returns to task when vector hits limit. Normal limit - object coordinate set to limit Timebase is lost
Limit with Back Out - object is vectored back away from limit and Timebase is retained.
LTYRTK LIMITX-ON
Turn on limit check LImITY-ON
LIMITXY-ON
LIMITBOUT-ON ---
Turn on limit check with backout when limit attained.

Must seq Limit on for
Turn off limit check limit x -off
n-..
$\begin{array}{ll}\text { Must sext Limit on } \\ \text { limit check } & \text { Limit x -off } \\ & \text { Limit }-0 f f \\ n-\ldots & \text { Limitxy-off }\end{array}$
LIMHX!
$\begin{array}{ll}\text { Must sedgy limit on } \\ \text { limit check } & \text { Limit x -off } \\ & \text { Limit }- \text { off } \\ n-1 & \text { Limitxy-off }\end{array}$
tow ork

Store limit value n for high X into vector
LIME
n --
Store limit value n for low X into vector
LIMY!
n ---
Store limit value n for high Y into vector
LIMEY!
n ---
Store limit value n for low Y into vector
LIMHXLXHYLY! ab c d --
Store Limit value a for high X, b for low X, c for high Y and d for low $Y$ into vector.

LIMIT?
--- n
Return boolean $n$, true if any limit attained.
LIMITX?
-_- n
Return boolean $n$, true if high $X$ or low $X$ limit attained.
DIMITY?
--- n
Returns boolean $n$, true if high $Y$ or low $Y$ limit attained.
LIMITHX?
--- n
Returns boolean $n$, true if high $X$ limit attained.
LIMITLX?
--n $n$
Returns boolean $n$, true if low X limit attained.
LIMITHY? --- n
Returns boolean $n$, true if high $Y$ limit attained.
LIMITLY? --n
Returns boolean $n$, true if low $Y$ limit attained.

## LIMITS CONT.

LIMITHX@ n --- pRead from vector n and leave limit high X p
LIMITLX@ n --- pRead from vector n and leave limit low X p
LIMITHY $\quad n$--- p
Read from vector n and leave limit high Y p
LIMITLY@ n --- p
Read from vector $n$ and leave limit low $Y$ p
Returns to task when coordinates crosses destination value. Does not affect the position of the write.

```
DESTX-ON
```

    Turn on destination \(X\) check
    DESTX-OFF
Turn off destination $X$ check
DESTY-ON
---
Turn on destination $Y$ check
DESTY-OFF
---
Turn off destination $Y$ check
DESTX! n ---
Store destination $X$ coordinate $n$ into vector
DESTY! n ---
Store destination $Y$ coordinate $n$ into vector
DESTX!-ON
n --
Turn on destination X check
Store destination X coordinate n into vector
DESTY!-ON n ---
Turn on destination Y check
Store destination $Y$ coordinate $n$ into vector
DESTX?
--- n
Returns boolean $n$, true if object crossed destination $X$
DESTY?
--- n
Returns boolean $n$, true if object crossed destination $X$

DEST?
Returns boolean $n$, true if object crossed destination $X$ or $Y$
DESTX ..... n --- pRead from vector $n$ and leave destination $X p$
DESTY@ ..... n --- pRead from vector $n$ and leave destination Y p

## INTERCEPT

Return to task when intercept is detected during a write.
INTERCEPT-ON ..... ---
Turn on Intercept check
INTERCEPT-OFFTurn off intercept check
INTERCEPT? ..... n
Returns boolean $n$, true if intercept was detected

## USERS INTERUPT HOOK

User can put in a routine to run at vector management interruptlevel.Registers input and output from Hook routine.
$B=$ Timebase used
$C=$ Timebase not used$D E=$ new $X$
$H L=$ new $Y$$\quad$ ONCY If vectorIY $=$ vector addressIf used with wait only necessary to return IY.
HOOK-ON
Turn on hook check
HOOK-OFF---Turn off hook checkHOOK!n --Store address of hook routine $n$ into vector
HOOK!-ON n ---
Turn on hook check
Store address of hook routine $n$ into vector
A->DEST n ---Calculate the deltas less than n to travel from X Ycoordinate to X Y destination.
Use DESTX! DESTY!Delta maximum $n$ is represented by a hex word with the topbyte the whole number and the bottom byte the fraction.
Deltas can range from n to $\mathrm{n} / 2$
Stores new deltas into vector
Stores timer value into vector
Turns on timer check
Use TIMER? to determine if destination is reached
A->B p q n --
Calculates the deltas less than $n$, to travel from X Ycoordinate to p,q destination
Delta maximum $n$ is represented by a hex word with the topbyte the whole number and the bottom byte the fraction.
Deltas can range from $n$ to $n / 2$.
Stores new deltas into vector
Stores timer value into vector
Turns on timer check
Use TIMER? to determine if destination is reached

## GO AND WAIT

Leave task and stay in vector management at interrupt level until a state transition.
When a state transition is detected task interpreter continues at the following task verb.
GO
Start execution with vectoring and writing.
WAIT
Turn off vectoring and writing process
Start execution

## RECTANGULAR COORDINATE SYSTEM

The coordinate system is zero, centered with the positive x and positive $y$ quadrant in the upper right corner of the screen.

X Range is -160 to 159 or in hex -40 to $9 F$
Y Range is -100 to 99 or in hex -64 to 63
X!
n ---
Store X coordinate n into vector

## Y! n --

Store Y coordinate n into vector
XY! $\quad \mathrm{nm}-{ }^{-}$

Store X coordinate n and Y coordinate m into vector
X@ $n---p$
Read from vector $n$ and leave $X$ coordinate $p$
Y@ $n---p$
Read from vector $n$ and leave $Y$ coordinate $p$

## GETX n ---

Read X coordinate from vector n and store into vector

## GETY n --_

Read $Y$ coordinate from vector n and store into vector
GETXY n --_
Read X Y coordinate from vector n and store into vector

## ZEROXY

Zero X Y coordinates of vector

Velocity and acceleration must be entered as a hex word with the top byte the whole number and the bottom byte the faction.

DX! $n$---
Store $X$ delta $n$ into vector
DY!
n -
Store $Y$ delta n into vector
DXDY!
n --
Store X delta and Y delta n into vector
GETDXDY
n --
Read delta X and Y from vector n and store into vector.

RECTANGULAR COORDINATE SYSTEM cont.

AX!
n ---
Store X acceleration n into vector
AY!
n ---
Store $Y$ acceleration $n$ into vector
AXAY! $n$--
Store X acceleration and Y acceleration n into vector
DX@ $n--$ p
Read from vector n and leave delta x p
DY@ $n--p$
Read from vector $n$ and leave delta y $p$
AX@ $n$--- p
Read from vector $n$ and leave acceleration y p
AY@ $n--p$
Read from vector $n$ and leave acceleration y $p$
GETDXDYAXAY n --_
Read delta x delta y acceleration x acceleration y from vector n and store into vector.

ZERODXDYAXAY
Zero delta X, delta Y, acceleration X, and acceleration Y of vector

```
GETCOS s a --- d
    Calculates delta d from speed s and angle a.
ANGLE ---
    Calculates deltas and accelerations for X and Y using polar
        velocity, polar acceleration and angle.
TURN d t ---
    Creates a turn from the current angle to the current angle +d
        in time t. t is rounded off to the nearest power of 2.
    Uses rectangular acceleration and it's own timer.
RADIUSTURN d r --- t
    Creates a turn of angle difference d for a constant
        radius r.
    Computes turn time t and calls turn.
    t is returned. Speed is in VPLRVEL.
    Radius r is unsigned 8 bits (## of pixels)
Angles are represented by a value from 0 to 255 . Angle 0 is the direction of no y and positive x. Angle 64 is 90 degrees clockwise. Angles incremet in a clockwise direction.
```

ANGLE! n ---

```Store polar angle \(n\) into vector.
```

ANGLE@ v --- n
Read angle n from vecotr V .
Polar velocity and acceleration must be entered as a hex word

```with the top byte the whole number and the bottom bytethe fraction.
```

POLARVEL! n ---

```Store polar velocity \(n\) into vector.
```

POLARACC! ..... n --

```Store polar acceleration n into vector.
```

POLARVEL@ v --- n

```Read polar velocity \(n\) from vector \(v\).
```

POLARACC® ..... v --- n
Read polar acceleration $n$ from vector $v$.

## PATTERNS

PATTERN! n ---
Store pattern address $n$ into the current vector
All patterns must have a 4 byte header
$X$ offset $B$,
Y offset B, $X$ byte size $B$, Y line size B,
Followed by pattern source
If xpand is used the last 3 pixels of the pattern have to be 0 for flush. Non expanded patterns are automatically flushed.

Pattern creation helpers are provided.
PATTERN
--- n
Sets base to decimal, makes name n a data statement

Marks stack sets base

Store bytes on stack from ~ in RAM as pattern, resets base

## QUADPAT



Specifies base 4 to be used between ~ and ^
Does not change current base

## BINPAT

---
Specifies base 2 to be used between ~ and ${ }^{\wedge}$

- Does not change current base

Example: Base 4 pattern
PATTERN DEMO-PAT-QUAD $0 \mathrm{~B}, 0 \mathrm{~B}, 2 \mathrm{~B}, 2 \mathrm{~B}$, QUADPAT ~ 3321 1233 ^ ~ 3321 1233 ^
Each number represents a pixel with base 4

## Base 2 PATTERN

PATTERN DEMO-PAT-BIN O B, O B, $2 \mathrm{~B}, 2 \mathrm{~B}$, BINPAT
$\sim 1111100101101111$
~ $1111100101101111^{\text {の }}$
BASE 16 PATTERN
PATTERN DEMO-PAT-HEX $0 \mathrm{~B}, 0 \mathrm{~B}, 2 \mathrm{~B}, 2 \mathrm{~B}$, HEX F9 B, 6 F B, F9 B, 6 FB ,

All of the above examples represent the same pattern.
PDUMP
n -
Dump pattern $n$ in Pattern Base, (ie Quadpat or
Binpat) Assumes pattern has a header of
$x$ offset $B, y$ offset $B$, $x$ byte size $B, y$ line size $B$,

## ANIMATION TYPES

VGER supports animation, rotation and perspective alone or in combinations. All patterns are assumed to have a header of $x$ offset $B$, $y$ offset $B$, $x$ byte size $B$, $y$ line size $B$, .

## PERROTANM-OFF

---
Turn off all animation types
ROT!-ON n s --
Turn on rotation
Store rotation table address $n$ into current vector
Store rotation shift amount s into vector, shift value takes maximum angle (256) and shifts it down until it equals the number of rotation patterns.
128 patterns $=1$
64 patterns $=2$
32 patterns $=3$
16 patterns $=4$
8 patterns $=5$
4 patterns $=6$
Rotation Options
Flip
Flop $={ }^{-1}$
Flip-Flop $=0$
NoemAL
Rotation uses angle to determine rotation table index.
Example:
DATA ROT-TBL (Rotation table)
(Flip Flop Options) (Pattern address)

| NORMAL | B, |
| ---: | :--- |
| FLPOLLOP | ROT-PAT-1 |
| FLOP | B, |
| FLIP | ROT-PAT-2 |

ROT-TBL 6 ROT!-ON
ANIM! -ON $n--$
Turn on animaton
Store animation table address $n$ into current vector.

## Example:

DATA ANIM-TBL (animation table)
(timer in 1/60ths) (patterns)
5 B, PAT-1 ,
$10 \mathrm{~B}, \quad$ PAT-2,
0 B , ANIM-TBL,
( 0 timer signifies a jump to the next word to start table over)
ANIM-TBL ANIM!-ON

## ANIMATION TYPES cont.

$$
\text { PER! -ON } n--
$$

Turn on perspective
Store perspective table address n into current vector
PERINX!
n --
Store perspective table index number $n$ into vector. Used as an index into the perspective table.

Example:
DATA PER-TBL (perspective table)
PAT-1, PAT-2, PAT-3,

PER-TBL PER! -ON
You can use the animation types in combination by specifying more than one and then building proper tables.

Example
DATA ANIM-TBL-1
$5 \mathrm{~B}, \quad$ PAT-1 ,
10 B , PAT-2,
0 B , ANIM-TBL-1 ,
DATA ANIM-TBL-2
etc.
NOTE:
DATA ANIM-TBL-3
etc.
DATA ANIM-TBL-4
etc.
DATA ROT-ANIM-TBL Be the same size A change of ROT does not charge ANIm INDex \# $\qquad$

ANIM-TBL-1 ANIM! -ON
ROT-ANIM-TBL 6 ROT!-ON
This will rotate and animate. We can continue this with perspective also by including ROT-ANIM-TBL as an entry in a perspective table.

## WRITE OPTIONS

```
XPAND!
        n ---
    Store xpand color mask n into vector
    Xpand mask bits
        Bits 0,1 off color
        Bits 2,3 on color
        Bits 4,5,6,7, not used
XPAND-ON
    Turn on magic pattern xpand
XPAND -OFF X---
    Turn off magic pattern xpand
XPAND!-ON n ---
    Store xpand color mask n into vector
    Turn on magic pattern expand
OR-ON
    Turn on magic or write
XOR-ON ---
    Turn on magic xor write
PLOP-ON
    Turn on magic plop write
    Turns off XOR and OR
FLIP-ON
    Turn on magic pattern flip
FLIP-OFF
    Turn off magic pattern flip
FLOP-ON ---
    Turn on magic pattern flop
FLOP-OFF
Turn off magic pattern flop
FLIPFLOP-ON
Turn on magic pattern flip and flop
FLIPFLOP-OFF --
Turn off magic pattern flip and flop
```


## AREAFILL-ON

```
Fills the area defined by a pattern using only the first byte of the pattern.
```


## AREAFILL-OFF

```
Turns off the areafill function.
```


## MAGIC!

```
n -
Load vector magic whith value \(n\).
NOTE: used in place of above magic options)
```



To save RAM a vector of length SLENGTH can be used to display strings. Normal font has both upper and lower case.

BIN->ASC 1 m a s -.
Takes double precision binary number with least significant word 1 and most significant word $m$ converts it to an ASCII string of length $s$ and stores it at address a. 1st character of string at address a is a sign of the number followed by the ASCII string.
Length byte must be added by the user.
If the double precision $\# \mathrm{~m}$ and l is larger than size s will allow, all 9's are returned.

OSUPR
Suppress leading 0's of string address $s$ with blanks. Assumes 1st byte at string address $s$ is the string count followed by the ASCII string. If string is all 0's, the last 0 will be left.

USER VERBS
1STWRITEUse when introducing an object to the screen - guarantees screenwrite with no erase
ACTIVE? ..... n --- p
Returns boolean pTrue if vector $n$ is active in the system
BIT m n --- pChecks Bit m at address $n$
Returns boolean p true if bit on.
BREAK---
Runs in Background allows user to return control to the terminalby pressing a terminal key.
ERASEErase vector pattern from the screen through interrupt. Returnswhen erase accomplished.
EX n --
Execute verb at address $n$ (ie.' VERB EX)
FILL ..... n a l--
Fill memoy with constant $n$ starting at address a fpr bytelength 1
IMM! n ---Loads vector n as current vector
INVERT-OFF
Turn off Invert feature
INVERT-ON---INVERTS entire screen
(ie. for cocktail) coordinates all remain the same
NDUP ..... n ---
Duplicate top n elements of the stack
PUP
---
Power up routine.
does a MAP
intializes the system ques and interupts
sets horizontal color boundry at 28 h
sets vertical blank at c8h
sets colors
RANDOM ..... pReturns a 16 bit random \# p2 array RND\# is the seed
RES m n -- p
Reset bit $m$ at address $n$

USER VERBS cont．

## REVDLIM－－－ <br> Reverse $X$ delta if $X$ limit attained <br> Reverse $Y$ delta if $Y$ limit attained <br> Does nothing if no limit attained

REVDX
Reverse X delta of vector

## REVDY

－－－
Reverse Y delta of vector
RND
n－－－p
Returns a random \＃ p within the range $\mathrm{n}-1$ and 0 2 array RND $⿰ ⿰ 三 丨 ⿰ 丨 三 一$ is the seed

## SCRERASE

Fill screen memory area with zero＇s 4000 H to 7 FFF

## SELF

－－n
Returns current vector address $n$

## SET

m n－－－
Set bit m at address $n$
SHUTUP
Turns of $f$ sounds

## SLEEP

Puts current vector to sleep taking him out of the system until woken up by another vector．（See WAKEUP）

SLEEP？
v－－－f
Returns flag $f$ as true if vector $V$ is asleep
SPARKLES－OFF
Turns off card rack sparkle and stars．
SYNC
Stops TASK execution
Allows all other tasks to execute before resuming execution
SWAN
n－
Swap nibbles in low byte of $n$

## ；TASK：

Demarcates the following routine to be a vector task．
TASK－MASTER
Activates multi tasking background and starts interrupts （also defined as TT）

USER VERBS cont.
TIMEBMAX! ..... n ---Store maximum timebase into current vector $m$.Maximum timebase that vector is allowed to vector itself.If 0 it assumes no maximum.
TIME-BARS
--Turns on diagnostic time bars to the right of thehorizontal color boundry.
PUP sets horizontal color boundry to the far rightside of the screen.
Red - background
Green - vector management
Blue - screen update 1
White - screen update 2
Yellow - idle time
Black - changing processes
Rainbow of small colors - ERROR (see ERROR MESSAGES)
TIMEBSCALE! n ---Stores timebase scale factor $n$ into vector.Examble: If timebase scale $=2$ then object updated once every :2 timebases, timer would decrement once for every 2 timebases.If 0 it defaults to 1
TIMEBSCALE@ ..... --- n
Leaves timebase scale $n$ of current vector.
TTJoes MAP START-INTERRUPTS TASK-MASTERVDUMPn ---
Dump contents of vector $n$
WAKEUP ..... n --Wakes vector $n$, putting him back into the system to resumeexecution following where he was put to sleep.
WRITE
Writes vector pattern to the screen through interrupt.
Returns when write accomplished.
XADJ c --- pAdjust 0 centered $x$ coordinate $c$ to upper left centeredvalue $p$. (Note; vector contains upper leftcenter value, VGER interface expects 0 center.X! adjusts automatically.)
YADJ $\quad c-m p$
Adjust 0 centered y coordinate c to upper left centered value P. (Note; vector contains upper left center value. VGER interface expects 0 center Y! adjusts automatically)
ZEROTIMEBGives start over timebase for current vector.

```
<STKH
    Does <STK HEX
<STKD
    Does <STK DECIMAL
STK>
    Does STK> DECIMAL
XDI
    Does DI and resets interrupt mode to 0 for disks.
DED
    Does XDI DECIMAL EDIT
    .HOPS
        Gives message ".HOPS? Y or N" and waits for KEYBOARD entry.
        If y does .HOU .OPS
        Else does nothing
.COPS
    Does .CEN .OPS
.NLOPS
    Does CR CR CR CR PAGE PAGE
        .NOPS .NLIST
DV= --- vvvv
    Creates a double precision VARIABLE with name vvvv
NC= --- vvvv
    Does 1+DUP C= vvvv
    Use for table creation
SC=
    Does DUP C= vvvv
    Use for table creation
```


## USER SUBROUTINES

Subroutines that end in RET.

```
write write pattern with pattern board
    does not flush if expand set
    in- IX= pattern address (no header on pattern)
        B= xpand color
        C= magic with shift
        D= Y size
        E= X size
        HL= absolute screen address
        out - nothing
            (A,B,C,D,E,H,L,IX altered)
relabs relative X Y to magic absolute address conversion
        does not invert
    in- DE=X
    HL= Y
out- A= shift
HL= absolute magic screen address
(A, D, E,H,L altered)
bwrite write blow up pattern to screen does immediate software write from background
in- \(B=\) Blow up + Expand
Bit \(7=\) blow up *4
Bit \(6=\) blow up *2
Bits \(4,5=\) not used
Bits \(2,3=\) expand color on
Bits \(0,1=\) expand color off
C= Magic + shift
\(\mathrm{D}=\mathrm{Y}\) size
\(\mathrm{E}=\mathrm{X}\) size
HL= Screen addr
IX \(=\) Pattern addr
out- \(B C=\) same
\(\mathrm{E}=\) blow up factor
(A,D,E,H,L, IX,IY altered)
```

USER SUBROUTINES cont.
COMPEL2's compliment register set HL
saves pew
( $\mathrm{H}, \mathrm{L}$ altered)
COMPDE2's compliment register set DE
saves pew(D,E altered)
COMPBC
2's compliment register set $B C$
saves pow
( $\mathrm{B}, \mathrm{C}$ altered)
INDEXW
Index into a word table
(in- $\mathrm{HL}=$ table address $\mathrm{A}=$ index value)
(out- $D E=$ indexed value $H L=$ address of indexed value $A=$ index value)
(D, E,H,L altered)
divd16/8
Divides 16 bit dividend by an 8 bit divisor.
Returns 16 bit quotient.
(IN-HL = signed dividend, $\mathrm{C}=$ unsigned divisor)
(OUT-HL = signed quotient)
(A,B,H,L altered)
divd16/16
Divides 16 bit dividend by a 16 bit divisor.
Returns 16 bit unsigned.
(IN- A:C = dividend, $D E=$ divisor)
(OUT A:C quotient)
(A,B,C,H,L altered)
mult8*8
Unsigned 8 bit multiply
(IN H = operand 1, $\mathrm{E}=$ operand 2)
(OUT HL = product)
(B,D,H,L altered)
vrelotrrelabsROOT VEER

## QUEUES

QUEUE n --- vvvvDefines queue vvvv with $n$ entries.
EMPTY-QUEUE vvvv ---Empties queue vvvv. Must also be used after a queue definitionand before its use in order to initialize pointers.
QUEUE-IN d vvvv --- fPuts data d into queue vvvv and returns flag $f$ as true if thequeue did not have enough room.
QUEUE-OUT vvvv --- d f 1
Gets data d from queue vvvv if it exists. If the queue ..... is
empty only flag $f$ (set to true) is returned otherwise ..... data$d$ and flag $f$ (set to false) are returned.
QDUMP: ---
Dump contents of all VGER queues

## VECTOR RETURN STACK

Each vector can have its own return stack (ie. 8 O DO LOOP) First create a RAM area for the stack. The stack RAM can be attached to the end of a vector. (Note: CAUTION - there is no stack checking so if you overflow you can get into trouble.)

RSTACK!-ON s v ---
Loads vector return stack address s into vector v (Note: do before ;TASK:)

RSTACK-OFF v ---
Turn off vector return stack option for vector $v$ (Note: do before ;TASK:)

## ERROR MESSAGES

ERROR? ..... nReturns error number nUse when diagnostic colors go to rainbow
Error Messages

1. Playaction management queue overflow
2. Vector management queue overflow
3. Screen update queue 1 overflow
4. Screen update queue 2 overflow
User can add error messages.
error\# is byte variable containing error message numbers.
error-addr is a variable containing the address of errorhandler routine initialized at diagnostic rainbow loop.When error detected load error number in errorß and jumpto the contents of error-addr.

Look at PUP in Edible VGER to see how interrupts are set up.
There are 3 interrupts
line 50 BAKI (background)
line 100 SUI1 (screen update 1)
line 200 SUI2 (screen update 2)
To set up your own interrupt routine (ie. guarantee coin and I0 check) do so by loading your interrupt into one of the V variables (see PUP). Your routine must then jump to the appropriate VGER Interrupt routine.

Example:
SUBR MY-INTR
--
SUI2 JMP,
MY-INTR SUI1V!
This sets up user interrupt routine at line 200 without destroying VGER.

To change interrupt lines change L variables (see PUP)

## Example:

20 SUI2L B!
Changes background interrupt routine to line 20 from VGER default of 50 .

NOTE: Interrupt varables always contain line \# and vector address for the interrupt following there own.

Task Header Block
(W) TPAPC
(W) TOPAPC
(B) TSTAT

Bits:
(B) TPRI
(W) TVMR
(W) TSUR
(B) TSUCNT
(B) TTIMEB
(B) TSCALE
(W) TTIMER
(B) TVMROPT

Bits: $\quad 0=$ TBINTCPT-CHK (Intercept check)
$1=$ TBFLAG-CHK (Flag check)
2 = TBLIMIT-CHK (Limit check)
3 = TBDEST-CHK (Destination check)
$4=$ TBANGVECT (Angle vector)
$5=$ TBNOVECT (No vector)
$6=$ TBHOOK (Hook check)
7 = TBTIMER-CHK (Timer check)
(vmr options $H^{2}$ )
$0=$ TBLIMBOUT-imit with back out)
$1=$ TBDESTX - CHK (Destination x check)
$2=$ TBDESTY-CHK (Destination y check)
(state trans feedback)
$0=$ TBLIMIT (Limit attained)
$1=$ TBINTCPT (Intercept detected)
2 = TBDEST (Destination reached)
$3=$ TBTIMEDOUT (Timer went to 0 )
4 = TBFLAG (Flag detected)
(state trans feedback \# 2)
(B) TCHGSTAT2

Bits: $\quad 0=$ VBLIMHY (Limit $Y$ high attained)
$1=$ VBLIMLY (Limit Y low attained)
$2=$ TBLIMHX (Limit X high attained)
3 = VBLIMLX (Limit X low attained)
$4=$ TBDESTX (Destination X reached)
$5=$ TBDESTY (Destination Y reached)
(flag address)
(vmr hook address)
(return stack address)
(length of task header)

```
Motion Information Block
(B) VMAGIC Bits: (magic register)
    Bits: }0=\mathrm{ Shift amount
    1 = Shift amount
    2 = MRAREAFILL (Area fill)
    3 = MREXP (Expand)
    4 = MROR (OR)
    5 = MRXOR (XOR)
    6 = MRFLOP (FLOP)
    7 = MRFLIP (FLIP)
        (xpand color use bottom nibble)
```

(B) VXPAND
(W) VX
(W) VY
(W) VPAT SLENGTH
(B) VOMAGIC
(B) VOXPAND
(B) VLOGICSTAT (vector logic status byte)
$0=$ VBSUPDATE (Do screen update)
$1=$ VBNOWRITE (No write)
$2=$ VBNOEARSE (No erase)
$3=$ VBNOSU (No screen update)
(B) VLOGICSTAT2
(vector logic status byte \#2)
Bits: $\quad 0=$ VBANIM-CHK (Animation check)
$1=$ VBANIM (Animation)
$2=$ VBROT (Rotation)
3 = VBPERS (Perspective)
(max time base)
(B) VTBMAX
(W) VDX
( $x$ speed)
(W) VAX ( $x$ acceleration)
(W) VLIMX (x limit low)
(W) VLIMHX (x limit high)
(W) VDY
(W) VAY
(W) VLIMY
(W) VLIMHY
(W) VOPAT
(W) VSCRADR
( $y$ speed)
(screen address for write)
(W) VOSCRADR (screen address for erase)
(W) VDESTX (destination x )
(W) VDESTY (destination y)
(W) VPRATBL (per rot anm table)
(B) VANIMTIMER (animation timer)
(B) VANIMINX (animation index \#)
(B) VROTINXSHF (rotation inc shift amount)
(B) VPERINX (perspective index 非)
(W) VPLRVEL (polar velocity)
(W) VPLRACC (polar acceleration)
(B) VANGLE (polar angle)
(B) VPLRTIMER (polar angle timer) VLENGTH (length of motion vector)

## PORTS: PORT EQUATES

```
INFBK (Interupt feed back port)
INMOD
INLIN
MAGIC
XPAND
INCPT
VERBL
HORCB
(Interupt mode port)
(Interupt line port)
(Magic port)
(Expand color mask port)
(Intercept port)
(Vertical blanking line port)
(Horizontal color boundry port)
```

TASK EXAMPLE

```
<STK
        RAMMARK
        VLENGTH R= DEMOVECT
        RAMLEN C= DEMO-RAM-LENGTH
        VARHERE C= DEMO-RAM-START
: ZERO-DEMO-RAM O DEMO-RAM-START DEMO-RAM-LENGTH FILL ;
    PATTERN DEMO-PAT O B, O B, 2 B, 2 B, QUADPAT
    ~ 3322 1133
    ~ 3322 1133 ^
HEX ( set base to hex )
: DEMOPA ;TASK:
    DEMO-PAT PATTERN! ( set pattern)
    ZEROXY ( set coordinates at 0 center of screen)
    XOR-ON ( set magic for XOR)
    1STWRITE ( start writing with no erase)
    100 DX! ( set X delta to 1 pixel /60th of a sec.)
    50 RND ( get Random # between 0 and 49)
    TIMER!-ON ( store random # in timer and turn it on)
    WAIT ( start up timer and wait until it goes to 0)
    BEGIN ( start of loop)
    50 TIMER!-ON ( store 50 into timer and turn it on)
    GO ( start up timer, vectoring and writing)
        ( return when timer goes to 0)
    REVDX ( reverse delta x)
    O END ; ( go back to begin)
: TEST PUP ( power up)
    BREAK ( key board break)
    SCRERASE ( erase screen)
    ZERO-DEMO-RAM ( zero demo ram area )
    TIME-BARS ( turns on diagnostic time bars)
    DEMOVECT DEMOPA ( load vector in background que with task DEMOPA)
    TT ; ( start up system)
STK> ;S
(The above task will 1st wait a random period of time 0 -> 50/60
of a second then move, after each 50/60 of a second it will
reverse direction.)
```

