## Technical

# Reference 

Options and Adapters Volume 1

## Technical

## Reference

## Options and Adapters Volume 1

## Revised Edition (April 1984)

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## Federal Communications Commission Radio Frequency Interference Statement

Warning: The equipment described herein has been certified to comply with the limits for a Class B computing device, pursuant to Subpart J of Part 15 of the FCC rules. Only peripherals (computer input/output devices, terminals printers, etc.) certified to comply with the Class B limits may be attached to the computer. Operation with non-certified peripherals is likely to result in interference to radio and TV reception. If peripherals not offered by IBM are used with the equipment, it is suggested to use shielded grounded cables with in-line filters if necessary.

## CAUTION

The product described herein is equipped with a grounded plug for the user's safety. It is to be used in conjunction with a properly grounded receptacle to avoid electrical shock.

## Preface

The options and adapters manual is the second part of the Technical Reference publication. It is designed to be used in conjunction with any of the Technical Reference system unit manuals.

The information in this publication is for reference, and is intended for hardware and program designers, programmers, engineers, and anyone else with a knowledge of electronics and/or programming who needs to understand the design and operation of the options and adapters available for the IBM Personal Computer family of products.

This manual is modular in format, with each module providing information about a specific option or adapter available for the IBM Personal Computer family of products. Modules having a large amount of text contain individual indexes.

The modules are grouped by type of device. To find a specific module:

1. Locate the full length hard tab with the type of device (Displays, Printers, Storage Devices, etc.) printed on it that describes the option or adapter you need information about.
2. Open the book to that section.
3. Leaf through that section to find the proper module.

The front matter of this manual also provides a "System to Adapter Compatibility Chart," to identify the adapters supported by each system, and an "Option to Adapter Compatibility Chart," to identify the options supported by each adapter.

Notes:

## System to Adapter Compatibility Chart

The following chart identifies the adapters supported by each system.

|  | IBM <br> Personal <br> Computer | IBM <br> Personal <br> Computer <br> XT | IBM <br> Portable <br> Personal <br> Computer | IBM <br> Personal <br> Computer <br> AT | IBM <br> Expansion <br> Unit |
| :--- | :---: | :---: | :---: | :---: | :---: |
| 64KB Memory <br> Module Kit | Yes | Yes | Yes | No | No |
| 64/256KB <br> Memory <br> Expansion <br> Option | Yes | Yes | Yes | No | No |
| $128 K B$ <br> Memory <br> Expansion <br> Option | No | No | No | Yes | No |
| 256KB <br> Memory <br> Expansion <br> Option | Yes | Yes | Yes | No | No |
| 512KB <br> Memory <br> Expansion <br> Option | No | No | No | Yes | No |
| Monochrome <br> Display and <br> Printer <br> Adapter | Yes | Yes | No | Yes | No |
| Color/Graphics <br> Monitor <br> Adapter | Yes | Yes | Yes | Yes | No |
| Printer <br> Adapter | Yes | Yes | Yes | No | Yes |
| $5 ~ 1 / 4$ inch <br> Diskette Drive <br> Adapter | Yes | Yes | Yes | No | No |
| Fixed Disk <br> Drive Adapter | Yes | Yes | No | No | Yes |
| Syy |  |  |  |  |  |

System to Adapter Compatibility Chart (Part 1 of 2)

|  | IBM <br> Personal <br> Computer | IBM <br> Personal <br> Computer <br> XT | IBM <br> Portable <br> Personal <br> Computer | IBM <br> Personal <br> Computer <br> AT | IBM <br> Expansion <br> Unit |
| :--- | :---: | :--- | :--- | :--- | :--- |
| Fixed Disk and <br> Diskette <br> Adapter | No | No | No | Yes | No |
| Asynchronous <br> Communications <br> Adapter | Yes | Yes | Yes | No | Yes |
| Serial/Parallel <br> Adapter | No | No | No | Yes | No |
| Binary <br> Synchronous <br> Communications <br> Adapter | Yes | Yes | Yes | Yes | Yes |
| Synchronous <br> Data Link <br> Control <br> (SDLC) <br> Adapter | Yes | Yes | Yes | Yes | Yes |
| Cluster <br> Adapter | Yes | Yes | Yes | Yes | Yes |
| Game Control <br> Adapter | Yes | Yes | Yes | Yes | Yes |
| Prototype Card | Yes | Yes | Yes | No | Yes |
| Prototype <br> Adapter | No | No | No | Yes | No |
| Enhanced <br> Graphics <br> Adapter | Yes | Yes | No | Yes | No |
| Professional <br> Graphics <br> Controller | No | Yes | No | Yes | Yes |
| GPIB Adapter | Yes | Yes | Yes | Yes | Yes |
| Data <br> Acquisition <br> Adapter | Yes | Yes | Yes | Yes | Yes |
| P C Network | Yes | No |  |  |  |
| Sys |  | Yes |  |  |  |
| Cos |  |  |  |  |  |

System to Adapter Compatibility Chart (Part 2 of 2)

## Option to Adapter Compatibility Chart

Because some adapters perform multiple functions, the following chart identifies the options supported by each adapter.

|  |  |  | $$ |  |  |  |  | $\begin{aligned} & \frac{\pi}{0} \\ & \frac{0}{n} \\ & 0 \\ & \frac{0}{0} \\ & 0 \end{aligned}$ | \# <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 |  |  |  |  |  | $\begin{aligned} & \text { U } \\ & \text { U } \\ & \text { N } \\ & \text { O } \end{aligned}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $51 / 4^{\prime \prime}$ <br> Diskette Drive Adapter | X |  | X |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Fixed Disk Drive Adapter |  |  |  |  | X |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Fixed Disk and Diskette Drive Adapter |  | X |  | X |  | X |  |  |  |  |  |  |  |  |  |  |  |  |
| Color Graphics Monitor Adapter |  |  |  |  |  |  |  | X |  |  |  |  | X | X |  |  |  |  |
| Monochrome <br> Display and Printer Adapter |  |  |  |  |  |  | X |  | X |  |  | X |  |  |  |  |  |  |
| Printer <br> Adapter |  |  |  |  |  |  |  |  | X |  |  | X |  |  |  |  |  |  |
| Asynchronous Communications Adapter |  |  |  |  |  |  |  |  |  | X |  |  |  |  |  |  |  |  |
| Serial/Parallel <br> Adapter |  |  |  |  |  |  |  |  | X | X |  | X |  |  |  |  |  |  |
| Game Control Adapter |  |  |  |  |  |  |  |  |  |  |  |  |  |  | X |  |  |  |
| Enhanced Graphics Adapter |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | X |  |  |
| Professional Graphics Controller |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | X |  |
| Data Acquisition and Control Adapter |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | X |
| X - Adapter compatib | w | h | ptio |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Option to Adapter Compatability Chart

Personal Computer Hardware Reference Library

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## Description

The IBM Expansion Unit option enhances the system unit by adding expansion slots in a separate unit. This option consists of an extender card, expansion unit cable, and the expansion unit. The expansion unit contains a power supply, an expansion board, and a receiver card. This option utilizes one expansion slot in the system unit to provide seven additional expansion slots in the expansion unit.

## Expansion Unit Cable

The expansion unit cable consists of a 56-wire, foil-shielded cable terminated on each end with a 62-pin D-shell male connector. Either end of the expansion unit cable can be plugged into the extender card or the receiver card.

## Expansion Board

The expansion board is a support board that carries the I/O channel signals from the option adapters and receiver card. These signals, except 'osc,' are carried over the expansion unit cable.
Because 'osc' is not sent over the expansion cable, a $14.31818-\mathrm{MHz}$ signal is generated on the expansion board. This signal may not be in phase with the 'osc' signal in the system unit.

Decoupling capacitors provided on the expansion board aid in noise filtering.

The following is a block diagram of the expansion board.


Expansion Board Block Diagram

2 Expansion Unit

## Power Supply

The expansion unit dc power supply is a 130 -watt, 4 voltage-level switching regulator. It is integrated into the expansion unit and supplies power for the expansion unit and its options. The dc output voltages for the power supply are listed in the following table:

| Voltage <br> (Vdc) | Current <br> (Amps) |  | Regulation <br> (Tolerance) |  |
| :---: | :---: | :---: | :---: | :---: |
| Nominal | Minimum | Maximum | $+\%$ | $-\%$ |
| +5.0 | 2.3 | 15.0 | 5 | 4 |
| -5.0 | 0.0 | 0.3 | 10 | 8 |
| +12.0 | 0.4 | 4.2 | 5 | 4 |
| -12.0 | 0.0 | 0.25 | 10 | 9 |

Vdc Output

All power levels are regulated with overvoltage and overcurrent protection. The input is fused and is either 120 Vac or 220/240 Vac. If dc overload or overvoltage conditions exist, the supply automatically shuts down until the condition is corrected. The supply is designed for continuous operation at 130 watts.

The power supply is located at the right rear of the expansion unit. It provides two separate connections for power to the fixed disk drives and supplies operating voltages to the expansion board through two "keyed" connectors that plug into a 12-pin male connector on the expansion board.

## Vac Output

The receptacle at the rear of the power supply is a nonstandard connector designed to be used only for the IBM Monochrome Display. The power supply provides a filtered ac output that is switched on and off with the main power switch. The maximum current available at this output is 1 ampere for the 120 -volt power supply and 0.5 amperes for the 220/240-volt power supply.

## Overvoltage and Overcurrent Protection

| Voltage Nominal Vac | Type Protection | Rating Amps |
| :---: | :---: | :---: |
| 110 | Fuse | 5 |
| 220 | Fuse | 3 |

Power On/Off Cycle: When the power supply is switched Off for a minimum of 1.0 second, and then switched On, the 'power good' signal is regenerated.

The 'power good' signal indicates that there is adequate power to continue processing. If the power goes below the specified levels, the 'power good' signal triggers a system shutdown.

This signal is the logical AND of the dc output-voltage 'sense' signal and the ac input-voltage 'fail' signal. This signal is TTL-compatible up-level for normal operation or down-level for fault conditions. The ac 'fail' signal causes 'power good' to go to a down-level when any output voltage falls below the regulation limits.

The dc output-voltage 'sense' signal holds the 'power good' signal at a down level (during power-on) until all output voltages have reached their respective minimum sense levels. The 'power good' signal has a turn-on delay of at least 100 ms but no greater than 500 ms .

The sense levels of the dc outputs are shown in the following table.

| Output <br> (Vdc) | Minimum <br> (Vdc) | Sense Voltage Nominal <br> (Vdc) | Maximum <br> (Vdc) |
| :---: | :---: | :---: | :---: |
| +5 | +4.5 | +5.0 | +5.5 |
| -5 | -4.3 | -5.0 | -5.5 |
| +12 | +10.8 | +12.0 | +13.2 |
| -12 | -10.2 | -12.0 | -13.2 |

## Extender Card

The extender card is a four-plane card. It re-drives the I/O channel to provide sufficient power to avoid capacitive effects of the cable. The extender card presents only one load per line of the I/O channel.

The extender card has a wait-state generator that inserts a wait state on memory-read and memory-write operations (except refreshing) for all memory contained in the expansion unit. The address range for wait-state generation is controlled by switch settings on the extender card.

The dual-in-line package (DIP) switch on the extender card should be set to indicate the maximum contiguous read/write memory in the system unit. The extender card switch settings are described under "Switch Settings" in the Guide to Operations manual. Switch positions 1 through 4 correspond to address bits hex A19 to hex A16.

The DIP-switch settings determine which address segments have a wait state inserted during memory-read and memory-write operations. Wait states are required for any memory, including ROM on option adapters, in the expansion unit. Wait states are not inserted in the highest segment, hex addresses F0000 to FFFFF (segment F).

The following is a block diagram of the extender card.


## Extender Card Block Diagram

## Receiver Card

The receiver card is a four-plane card that fits in expansion slot 8 of the expansion unit. It re-drives the I/O channel to provide sufficient power for additional options and to avoid capacitive effects. Directional control logic is contained on the receiver card to resolve contention and direct data flow on the I/O channel.
Steering signals are transmitted back through the expansion unit cable for use on the extender card.

The following is a block diagram of the receiver card.


[^0]
## Programming Considerations

Several registers associated with the Expansion Unit option are programmable and readable for diagnostic test purposes. The following figures indicate the locations and functions of the registers on the extender card and receiver card.

| Location | Function |
| :---: | :---: |
| Memory FXXXX(*) | Write to memory to latch address bits |
| Port 210 | Write to latch expansion bus data (EDO-ED7) |
| Port 210 | Read to verify expansion bus data (EDO-ED7) |
| Port 211 | Read high-order address bits (A8-A15) |
| Port 211 | Write to clear wait test latch |
| Port 212 | Read low-order address bits (AO-A7) |
| Port 213 | Write 00 to disable expansion unit |
| Port 213 | Write 01 to enable expansion unit |
| Port 213 | Read status of expansion unit |
|  | DO = enable/disable |
|  | D1 = wait-state request flag D2-D3 = not used |
|  | D4-D7 $=$ switch position |
|  | 1 = Off |
|  | $0=0 n$ |
| (*) Example: Write to memory location F123:4 $=00$ <br>  Read Port $211=12$ <br>  Read Port $212=34$ |  |
|  |  |
|  |  |
| (All values in hexadecimal) |  |

## Extender Card Registers

| Location | Function |
| :---: | :---: |
| Memory FXXXX(*) | Write to memory to latch address bits |
| Port 214 | Write to latch data bus bits (DO-D7) |
| Port 214 | Read data bus bits (DO-D7) |
| Port 215 | Read high-order address bits (A8-A15) |
| Port 216 | Read low-order address bits (AO-A7) |
| (*) Example: Write to memory location F123:4 $=00$ <br>  Read Port $215=12$ <br>  Read Port $216=34$ |  |
| (All values in hexadecimal) |  |

## Receiver Card Registers

The expansion unit is automatically enabled upon power-up. Both the extender card and receiver card will be written to, if the expansion unit is not disabled when writing to FXXXX.
However, the system unit and the expansion unit are read back separately.

## Interface

All signals found on the system unit's I/O channel will be provided to expansion slots in the expansion unit, with the exception of the 'osc' signal and the system unit's power supply voltages.

A 'ready' line on the expansion channel makes it possible to operate with slow I/O or memory devices. If the channel's I/O 'ch rdy' line is not activated by an addressed device, all microprocessor-generated memory cycles take five microprocessor clock cycles per byte for memory in the expansion unit.

The following table contains a list of all the signals that are re-driven by the extender and receiver cards, and their associated time delays. The delay times include the delay due to signal propagation in the expansion unit cable. Assume a nominal cable delay of 3 ns . As such, device access will be less than 260 ns .

|  | Signal | Nominal Delay (ns) | Maximum Delay (ns) | Direction (*) |
| :---: | :---: | :---: | :---: | :---: |
|  | AO-A19 | 27 | 39 | Out |
|  | AEN | 27 | 39 | Out |
|  | DACKO - DACK3 | 27 | 39 | Out |
|  | MEMR | 27 | 39 | Out |
|  | $\overline{\text { MEMW }}$ | 51 | 75 | Out |
|  | $\overline{\text { IOR }}$ | 51 | 75 | Out |
|  | IOW | 27 | 39 | Out |
|  | ALE | 27 | 39 | Out |
|  | CLK | 27 | 39 | Out |
|  | T/C | 27 | 39 | Out |
|  | RESET | 27 | 39 | Out |
|  | IRQ2-IRQ7 | 36 | (**) | In |
|  | DRQ1-DRQ3 | 36 | (**) | In |
|  | 1/0 CH RDY | 36 | 51 | In |
|  | I/OCHCK | 36 | 51 | In |
|  | DO-D7 (Read) | 84 | 133 | In |
|  | DO - D7 (Write) | 19 | 27 | Out |
| (*) With resepct to the system unit. <br> (**) Asynchronous nature of interrupts and other requests are more dependent on microprocessor recognition than electrical signal propagation through expansion logic. |  |  |  |  |
|  |  |  |  |  |

## Specifications

| Size |  |
| :--- | :--- |
| Height | $142 \mathrm{~mm}(5.5 \mathrm{in})$. |
| Width | $500 \mathrm{~mm}(19.6 \mathrm{in})$. |
| Depth | $410 \mathrm{~mm}(16.1 \mathrm{in})$. |
| Weight | $14.9 \mathrm{~kg}(33 \mathrm{lb})$ |
| Power Cable |  |
| Length | $1.83 \mathrm{~m} \mathrm{(6} \mathrm{ft)}$ |
| Size | 18 AWG |
| Signal Cable <br> Length |  |
| Size | $1 \mathrm{~m} \mathrm{(3.28} \mathrm{ft)}$ |

## Physical Specifications

| Voltage (Vac) |  | Frequency <br> $(\mathrm{Hz})$ | Current (Amps) |  |
| :--- | :--- | :--- | :--- | :--- |
| Nominal | Minimum | Maximum | $\pm 3 \mathrm{~Hz}$ | Maximum |
| 110 | 90 | 137 | 60 | 3 at 90 Vac |
| $220 / 240$ | 180 | 259 | 50 | 1.6 at 180 Vac |

## Input Requirements

| Environment <br> Air Temperature <br> System On |  |
| :--- | :--- |
| System Off | 15.6 to $32.2^{\circ} \mathrm{C}\left(60\right.$ to $\left.90^{\circ} \mathrm{F}\right)$ |
| Humidity | 10 to $43^{\circ} \mathrm{C}\left(50\right.$ to $\left.110^{\circ} \mathrm{F}\right)$ |
| System On | 8 to $80 \%$ |
| System Off | 20 to $80 \%$ |
| Heat Output | $717 \mathrm{BTU} / \mathrm{hr}$ |

## Additional Specifications

## Extender Card and Receiver Card

The extender card and receiver card rear-panel connectors are the same. Pin and signal assignments for the extender and receiver cards are shown below.

| 21 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Pin | Signal | Pin | Signal | Pin | Signal |
| 1 | + E IRQ6 | 22 | +ED5 | 43 | + E IRQ7 |
| 2 | + E DRQ2 | 23 | + E DRQ1 | 44 | +ED6 |
| 3 | + E DIR | 24 | + E DRQ3 | 45 | + E I/O CH RDY |
| 4 | +E ENABLE | 25 | RESERVED | 46 | +EIRO3 |
| 5 | + E CLK | 26 | +E ALE | 47 | +ED7 |
| 6 | - E MEM IN EXP | 27 | +E T/C | 48 | +ED1 |
| 7 | +EA17 | 28 | + ERESET | 49 | - El/O CHCK |
| 8 | +EA16 | 29 | +EAEN | 50 | + E IRO2 |
| 9 | +EA5 | 30 | +EA19 | 51 | +EDO |
| 10 | -E DACKO | 31 | +EA14 | 52 | +ED2 |
| 11 | +EA15 | 32 | +EA12 | 53 | +ED4 |
| 12 | +EA11 | 33 | + E A18 | 54 | + EIRO5 |
| 13 | +EA10 | 34 | - E MEMR | 55 | + E IRQ4 |
| 14 | +EA9 | 35 | - E MEMW | 56 | +ED3 |
| 15 | +EA1 | 36 | + E AO | 57 | GND |
| 16 | +EA3 | 37 | - E DACK3 | 58 | GND |
| 17 | -E DACK1 | 38 | +E A6 | 59 | GND |
| 18 | +EA4 | 39 | - EIOR | 60 | GND |
| 19 | - EDACK2 | 40 | + E A8 | 61 | GND |
| 20 | -EIOW | 41 | +EA2 | 62 | GND |
| 21 | +EA13 | 42 | +EA7 |  |  |

## Connector Specifications



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Extender Card (Sheet 2 of 3)


Extender Card (Sheet 3 of 3)


Receiver Card (Sheet 1 of 3)


Receiver Card (Sheet 2 of 3)


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August 15, 1984

## IBM Monochrome Display

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## Description

The high resolution IBM Monochrome Display connects to the system unit through two cables. One cable is a signal cable from the display adapter to the display, and the other provides power to the display from the system unit. This arrangement eliminates the need for a wall outlet and allows the system-unit Power switch to control power to the display. The display unit has a 28.3 cm ( 11.5 in .) diagonal, $90^{\circ}$ deflection cathode ray tube (CRT). The display may be placed on the system unit or on a nearby table or desk. Brightness and contrast controls are on the front surface and are easily accessible to the operator.

The characteristics of the display are as follows:

- Screen
- High-persistence, green phosphor (P39).
- Etched surface to reduce glare.
- Presentation of 80 characters wide by 25 rows deep.
- Characters are defined in a 14 PEL-high by 9 PEL-wide matrix.
- Video Signal
- Maximum bandwidth of 16.257 MHz at -3 dB
- Vertical Drive
- Screen refreshed at 50 Hz with 350 lines of vertical resolution and 720 lines of horizontal resolution
- Horizontal Drive
- Positive level, TTL-compatibility, at a frequency of 18.432 kHz

2 Monochrome Display

## Specifications

| Size |  |
| :--- | :--- |
| Height | $280 \mathrm{~mm}(11 \mathrm{in})$. |
| Length | $380 \mathrm{~mm}(14.9 \mathrm{in})$. |
| Depth | $350 \mathrm{~mm}(13.7 \mathrm{in})$. |
| Weight | $7.9 \mathrm{~kg}(17.3 \mathrm{lb})$ |
|  |  |
| Heat Output | $325 \mathrm{BTU} / \mathrm{hr}$ |
| Power Cable |  |
| Length $0.914 \mathrm{~m} \mathrm{(3} \mathrm{ft)}$ <br> Size 18 AWG <br> Signal Cable  <br> Length $1.22 \mathrm{~m} \mathrm{(4} \mathrm{ft)}$ <br> Size 22 AWG |  |

## Physical Specifications

## Logic Diagrams

The IBM Monochrome Display has two models: a 110-Vac model and a 220/240-Vac model. A logic diagram for each follows.

motes:

1. RESIITTOR VALUES ARE MI OMMI $a k=1000 \Omega m=1.000 .000 n$



Phase $=$ BLCC/ /BOWN WIRE
NEUTRAL $=$ WATIE/BLUE WIRE


110Vac Monochrome Display (Sheet 1 of 1)


220/240Vac Monochrome Display (Sheet 1 of 1)

## Notes:

8 Monochrome Display

## IBM Portable Personal Computer Display

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## Description

The IBM Portable Personal Computer Display attaches internally to the Color/Graphics Monitor Adapter in the system unit and to the power supply. A cable provides the composite drive signals from the Color/Graphics Monitor Adapter to the display. Another cable provides dc power to the display from the power supply.

The IBM Portable Personal Computer Display is designed to blank out the color-burst signal generated by the Color/Graphics Monitor Adapter. Blanking keeps the color-burst signal from appearing on the composite video screen.

The display is a 228.6 mm ( 9 in. ), amber cathode ray tube (CRT). Brightness and Contrast controls on the front panel are easily accessible.

The characteristics of the display are as follows:

## Screen

- Medium-persistence, amber phosphor (LA)
- Etched surface to reduce glare
- 80 -character by 25 -line image
- Characters are defined in a 8 PEL-high by 8 PEL-wide matrix

Composite Video Signal

- 1.5 Vdc (peak to peak)
- 60 Hz refresh rate
- 15.75 kHz horizontal scan rate


## Logic Diagrams

The following pages contain the logic diagrams for the IBM Portable Personal Computer Display.


Portable Personal Computer Display (Sheet 1 of 2)


Portable Personal Computer Display (Sheet 2 of 2)

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## Description

The IBM Color Display connects to the system unit with a signal cable of approximately 1.5 meters ( 5 feet) in length. This signal cable is a direct-drive interface from the Color/Graphics Monitor Adapter.

A second cable provides power to the display from an electrical outlet. The display unit has its own power control and indicator and will accept either $120-$ volt $60-\mathrm{Hz}$ or $220-$ volt $50-\mathrm{Hz}$ power. The power supply in the display automatically switches to match the applied power.

The display has a 340 -millimeter ( 13 -inch) CRT. The display may be placed on the system unit or on a nearby table or desk. The front panel of the display has a Power-On control, Power-On indicator, Brightness control, and Contrast control. The rear panel has the Vertical Hold and Vertical Size controls.

The characteristics of the IBM Color Display are as follows:

- Screen
- High contrast (black).
- Displays up to 16 colors when used with the IBM Color/Graphics Monitor Adapter.
- Presentation of 80 characters wide by 25 rows deep.
- Characters are defined in an 8 PEL-high by 8 PEL-wide matrix.
- Video Signal
- Red, green, and blue signals, and intensity are independent.
- Vertical Drive
- Positive synchronous, TTL-compatible
- Frequency $50 / 60 \mathrm{~Hz}$
- Non-interlaced operation
- Horizontal Drive
- Positive-level, TTL compatibility, at a frequency of 15.75 kHz.


## Specifications

| Size |  |
| :--- | :--- |
| Height | $297 \mathrm{~mm}(11.7 \mathrm{in})$. |
| Length | $392 \mathrm{~mm}(15.4 \mathrm{in})$. |
| Depth | $407 \mathrm{~mm}(15.6 \mathrm{in})$. |
| Weight | $11.8 \mathrm{~kg}(26 \mathrm{lb})$ |
| Heat Output | $240 \mathrm{BTU} / \mathrm{hr}$ |
| Power Cable |  |
| Length | $1.83 \mathrm{~m} \mathrm{(6} \mathrm{ft)}$ |
| Size | 18 AWG |
| Signal Cable <br> Length <br> Size | $1.5 \mathrm{~m} \mathrm{(5} \mathrm{ft)}$ |
|  | 22 AWG |

Physical Specifications

## Logic Diagram

The following pages contain the logic diagram for the IBM Color Display.

## DANGER <br> HAZARDOUS VOLTAGES UP TO 450 VOLTS EXIST ON THE PRINTED CIRCUIT BOARDS



Color Display (Sheet 1 of 1)

| DANGER |
| :--- |
| HAZARDOUS VOLTAGES |
| UP TO 450 VOLTS EXIST |
| ON THE PRINTED |
| CIRCUIT BOARDS |



Notes:

Personal Computer Hardware Reference Library

## IBM Enhanced Color Display

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## Description

The IBM Enhanced Color Display is an advanced color display capable of operating in two separate modes. Mode 1 is a 16 color 640 by 200 overscan mode with a horizontal scan frequency of 15.75 kHz . Mode 2 is a 64 color 640 by 350 mode with a horizontal scan frequency of 21.8 kHz . Both modes are non-interlaced. The monitor determines which mode to operate in by decoding the vertical sync polarity.

The IBM Enhanced Color Display attaches to the system unit by a signal cable that is approximately 3.5 feet ( 1.07 meters) in length. This signal cable provides a direct-drive interface from the IBM Personal Computer.

A second cable provides ac power to the display from a standard wall outlet. The display has its own power control and indicator. Three models are provided. Model 001 is for northern hemisphere operation and operates on 120 volts $50 / 60 \mathrm{~Hz}$. Model 002 is for northern hemisphere operation and operates on 220/240 volts $50 / 60 \mathrm{~Hz}$. Model 003 is for southern hemisphere operation and operates on $220 / 240$ volts $50 / 60 \mathrm{~Hz}$.

The display has a 13-inch, high-contrast CRT. The CRT and analog circuits are packaged in an enclosure so the display may sit either on top of the system unit or on a nearby tabletop or desk. Front panel controls and indicators include: Power-On control, Power-On indicator, Brightness and Contrast controls. Additional controls on the rear of the display are: Vertical Size 1 and Vertical Size 2. There are two service controls on the rear of the unit, black level adjustment and contrast default value adjustment.

## Operating Characteristics

## Screen

- Etched anti-glare screen
- $\quad 0.31 \mathrm{~mm}$ dot mask
- Displays 16 or 64 colors depending on the mode selected


## User Controls

- Brightness control affects the contribution of all input bits by controlling the gain of the video stages. The display contains a protection circuit which may overide this control.
- Contrast control affects the contribution of the least significant bits only. When pushed in, the contrast control is rendered inoperative and contrast is determined by the setting of the contrast default value adjustment on the rear of the display. Pulling the contrast control knob out engages the front contrast control.
- V. Size 1 control controls the vertical size of the screen in mode 1.
- V. Size 2 control controls the vertical size of the screen in mode 2.


## Service Controls

- Black level adjust control is adjusted to make the raster lines just disappear when black input signal is supplied.
- Contrast default value control is used to set the contrast value when the front contrast control is pushed in. Normally adjust for best brown color.


## Vertical Sync

- Uses polarity of Vertical Sync signal to automatically select Mode 1 or Mode 2 operation. Mode 1 is selected by a normally low positive going TTL pulse. Mode 2 is selected by a normally high negative going TTL pulse.
- Screen may be refreshed from 50 to 60 Hz . At 60 Hz there are either 200 or 350 vertical lines of resolution depending on the mode selected.
- $700 \mu \mathrm{sec}$ retrace time


## Horizontal Sync

- Normally low, positive going TTL pulse
- In Mode 1, 15.75 kHz .
- In Mode 2, 21.8 kHz .
- $6 \mu \mathrm{sec}$ retrace time

When operating in Mode 1, the display maps the 4 input bits into 16 of the possible 64 colors as shown in the following chart.

| $\mathbf{I}$ | $\mathbf{R}$ | $\mathbf{G}$ | $\mathbf{B}$ | Color | $\mathbf{R ~ r}$ | $\mathbf{G} \mathbf{g}$ | $\mathbf{B} \mathbf{b}$ |
| :---: | :---: | :---: | :---: | :--- | :--- | :--- | :--- |
| 0 | 0 | 0 | 0 | Black | 00 | 00 | 00 |
| 0 | 0 | 0 | 1 | Blue | 00 | 00 | 10 |
| 0 | 0 | 1 | 0 | Green | 00 | 10 | 00 |
| 0 | 0 | 1 | 1 | Cyan | 00 | 10 | 10 |
| 0 | 1 | 0 | 0 | Red | 10 | 00 | 00 |
| 0 | 1 | 0 | 1 | Magenta | 10 | 00 | 10 |
| 0 | 1 | 1 | 0 | Brown | 10 | 01 | 00 |
| 0 | 1 | 1 | 1 | Gray 1 | 10 | 10 | 10 |
| 1 | 0 | 0 | 0 | Gray 2 | 01 | 01 | 01 |
| 1 | 0 | 0 | 1 | Light Blue | 01 | 01 | 11 |
| 1 | 0 | 1 | 0 | Light Green | 01 | 11 | 01 |
| 1 | 0 | 1 | 1 | Light Cyan | 01 | 11 | 11 |
| 1 | 1 | 0 | 0 | Light Red | 11 | 01 | 01 |
| 1 | 1 | 0 | 1 | Light Magenta | 11 | 01 | 11 |
| 1 | 1 | 1 | 0 | Light Yellow | 11 | 11 | 01 |
| 1 | 1 | 1 | 1 | White | 11 | 11 | 11 |

Note: The R G and B are the most significant bits. The r g and $b$ are the least significant bits.

## Specifications

## Size:

Length - 15.4 in ( 392 mm )
Depth - 15.6 in ( 407 mm )
Height - 11.7 in ( 297 mm )

## Weight:

32 lbs

## Heat Output:

$300 \mathrm{BTU} / \mathrm{hr}$
Power Cable:
Length - $6 \mathrm{ft}(1.83 \mathrm{~m})$
Size-18 AWG

## Signal Cable:

Length - $3.5 \mathrm{ft}(1.07 \mathrm{~m})$

## Connector Information

The signals that are on the pins vary with the driver card being used and the mode in which it is operating. All signals are expected to be TTL levels supplied by totem pole drivers.

| Pin | Mode 1 (16 Color) | Mode 2 (64 Color) |
| :--- | :--- | :--- |
| 1 | Shield Gnd | Ground |
| 2 | Signal Gnd | r |
| 3 | Red | R |
| 4 | Green | G |
| 5 | Blue | B |
| 6 | Intensity | g |
| 7 | Unused | b |
| 8 | Horiz Sync | Horiz Sync |
| 9 | Vert Sync | Vert Sync |

Note: The R G and B are the most significant bits. The r g and $b$ are the least significant bits.

Personal Computer Hardware Reference Library

# IBM Personal Computer Professional Graphics Display Technical Reference 

## Contents

Description ..... 1
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## Description

The IBM Personal Computer Professional Graphics Display is a 640-by-480 PEL color raster display for medium- and high-function graphics and alphanumerics. It operates with separate red, green, and blue analog signals and is can support an infinite number of colors.

The Professional Graphics Display attaches to the system unit through a signal cable that is approximately 1.5 meters ( 4.9 feet) in length. This cable provides a direct-drive connection from the IBM Professional Graphics Controller. The cable consists of shielded, twisted-pair lines, and has a 9-pin, subminiature, D-shell connector at the system-unit end. The pins have the following functions:

|  | Signal Name/Description | Pin |  |
| :---: | :---: | :---: | :---: |
| Professional Graphics Display | Red Video | 1 | Professional <br> Graphics <br> Controller |
|  | Green Video | 2 |  |
|  | Blue Video | 3 |  |
|  | Horizontal and Vertical Sync | 4 |  |
|  | Mode Control | 5 |  |
|  | Ground for Pin 1 | 6 |  |
|  | Ground for Pin 2 | 7 |  |
|  | Ground for Pin 3 | 8 |  |
|  | Ground for Pins 4 and 5 | 9 |  |

A second cable provides power to the display from a standard wall outlet. The display has its own power control and indicator. Depending on the model number, it accepts either 100 to 127 Vac at 50 to 60 Hz , or 200 to 240 Vac at 50 to 60 Hz .

The display has a 340 -millimeter (13-inch) cathode ray tube (CRT). The CRT and analog circuits are enclosed so the display may be placed on top of the system unit or on a nearby tabletop or desk. Front-panel controls and indicators are the Power-On indicator, Power-On control, and Contrast and Brightness controls.

## Operating Characteristics

## Screen

- High-contrast, antireflection
- Displays an infinite number of colors
- 640 horizontal PELs by 480 vertical PELs


## Video Signal

- Maximum video bandwidth of 17 MHz
- Red, green, blue, and synchronization signals are all independent


## Synchronization

- Active low, TTL-compatible, at frequencies of 30.12 kHz horizontal, and 60.02 kHz vertical (non-interlaced)

Mode Control

- Active low
- Expands the screen capacity to 400 lines.


## Specifications

Size:
Length: 392 mm (15.4 in.)
Depth: 407 mm (15.6 in.)
Height: 297 mm (11.7 in.)
Weight: $14.5 \mathrm{~kg}(32 \mathrm{lb})$
Power Dissipation:
87 Watts Maximum
Power Cable:
Length: $1.8 \mathrm{~m}(6 \mathrm{ft})$
Size: 18 AWG
Signal Cable:
Length: $1.5 \mathrm{~m}(4.9 \mathrm{ft})$
Size: 28 AWG

Notes:

August 15, 1984

## Logic Diagrams

The following are the logic diagrams of the Professional Graphics Display:





August 15, 1984
8 Professional Graphics Display
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## Description

The IBM Graphics Printer is a self-powered, stand-alone, tabletop unit. It prints in two directions at 80 characters per second (cps).

A 9-wire print head is used to print characters in a 9-by-9 dot matrix. The IBM Graphics Printer can print in a compressed mode of 132 characters per line, in a standard mode of 80 characters per line, in a double-width compressed mode of 66 characters per line, and in a double-width mode of 40 characters per line. The printer can print double-size characters and double-strike characters.

Besides printing the standard ASCII 96-character uppercase and lowercase character sets, the IBM Graphics Printer has additional capabilities including: an extended character set for international languages, subscript, superscript, an underline mode, and programmable graphics. It can also accept commands setting the line-feed control desired for the application.

The printer unit obtains ac power from a standard $120-\mathrm{Vac}$ wall outlet. A 220-Vac model and a $240-\mathrm{Vac}$ model are also available. A $1.83 \mathrm{~m}(6 \mathrm{ft})$ signal cable connects the printer to the system unit's Printer Adapter or combination Monochrome Display and Printer Adapter. The cable is a 25 -lead shielded cable with a 25 -pin D-shell connector at the system unit end, and a 36-pin connector at the printer end.

## Programming Considerations

## Printer Control Codes

On the following pages you will find codes for printer characters, controls, and graphics. You may want to keep them handy for future reference. The examples given in the "Printer Function" descriptions are written in the BASIC language. The "Input" description is given when more information is needed for programming considerations.

ASCII decimal values for the printer control codes can be found under "Graphics Printer Character Set."

The descriptions that follow assume that the printer dual-in-line package (DIP) switches have not been changed from their factory settings.

| Printer Code | Printer Function |
| :---: | :---: |
| BEL | Bell <br> Sounds the printer buzzer for 1 second. <br> Example: <br> LPRINT CHR\$(7); |
| CAN | Cancel <br> Clears the printer buffer. Control codes, except SO, remain in effect. <br> Example: <br> LPRINT CHR\$(24); |
| CR | Carriage Return <br> Ends the line that the printer is on and prints the data remaining in the printer buffer. (No Line Feed operation takes place.) <br> Note: IBM Personal Computer BASIC adds a Line Feed unless CHR\$(128) is added; for example, CHR\$(141). <br> Example: <br> LPRINT CHR\$(13); |
| DC2 | Device Control 2 (Compressed Off) <br> Cancels the Compressed print mode. <br> Example: <br> LPRINT CHR\$(18); |
| DC4 | Device Control 4 (Double Width Off) <br> Cancels the Double Width print mode. <br> Example: <br> LPRINT CHR\$(20); |
| ESC | Escape <br> Signals the printer that the next data sent is a printer command. <br> Example: <br> LPRINT CHR\$(27); |

## 4 Graphics Printer

| Printer Code | Printer Function |
| :---: | :---: |
| ESC A | Escape A (Sets Variable Line Feeding) <br> Format: ESC A;n; <br> Escape A sets the line-feed to $n / 72$ inch. The example that follows sets line feeding to $24 / 72$ inch. ESC 2 must be sent to the printer before the line feeding will change. For example, ESC A;24 (text) ESC 2 (text). The text following ESC A;24 will be at the previously set line-feed increment. The text following ESC 2 will be printed with the new line-feed increment of $24 / 72$ inch. Any increment between $1 / 72$ and $85 / 72$ may be used. <br> Example: <br> LPRINT CHR\$(27);CHR\$(65);CHR\$(24); CHR\$(27);CHR\$(50); <br> Note: How to enter " $n$ ": When " $n$ " is actually transferred to the printer as data, it is transferred in the form of a 7-bit binary number. In the case of "ESC A+24," actual output to the printer is performed as $<1 \mathrm{~B}\rangle \mathrm{H}<41>\mathrm{H}<18>\mathrm{H}$ in hexadecimal code. |
| ESC C | Escape C (Set Lines per Page) <br> Format:ESC C;n; <br> Sets the page length. ESC C command must be followed by a value to specify the length of page desired. (Maximum form length for the printer is 127 lines.) The example below sets the page length to 55 lines. The printer defaults to 66 lines per page when powered on or reset. Example: <br> LPRINT CHR\$(27);CHR\$(67); CHR\$(55); <br> Escape C (Set Inches per Page) <br> Format:ESC C;n;m; <br> Escape $C$ sets the length of the page in inches (one inch is 25.4 millimeters). This command requires a value of 0 (zero) for n , and a value between 1 and 22 for m . <br> Example: <br> LPRINT CHR\$(27);CHR\$(67);CHR\$(0); CHR\$(12); |
| ESC D | Escape D (Set Horizontal Tab Stops) <br> Format: ESC D; $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \ldots \mathrm{n}_{\mathrm{k}} ; \mathrm{NUL}$; <br> Sets the horizontal tab stop positions. The example that follows sets the horizontal tab stop positions at printer columns 10,20 , and 40 . They are followed by $\mathrm{CHR} \$(0)$, the Null code. They must be given in ascending numeric order. Tab stops can be set between 1 and 80 . When the printer is in the Compressed print mode, tab stops can be set up to 132. The Graphics Printer can have a maximum of 28 tab stops. The HT Code (CHR\$(9)) is used to execute a tab operation. Example: <br> LPRINT CHR\$(27);CHR\$(68);CHR\$(10); <br> CHR $\$(20) ; \mathrm{CHR} \$(40) ; \mathrm{CHR} \$(0)$; |


| Printer <br> Code | $\quad$ Printer Function |
| :--- | :--- |
| ESC E | Escape E (Emphasized) <br> Sets the printer to the Emphasized print mode. The speed of <br> the printer is reduced to half speed during the Emphasized <br> print mode. <br> Example: <br> LPRINT CHR\$(27);CHR\$(69); <br> ESC F <br> Escape F (Emphasized Off) <br> Cancels the Emphasized print mode. <br> Example: <br> LPRINT CHR\$(27);CHR\$(70); <br> Escape G (Double Strike) <br> Sets the printer to the Double Strike print mode. The paper <br> is spaced 1/216 inch before the second pass of the <br> print head. <br> Example: <br> LPRINT CHR\$(27);CHR\$(71); <br> Escape H (Double Strike Off) <br> Cancels the Double Strike mode. <br> Example: <br> LPRINT CHR\$(27);CHR\$(72); <br> Escape J (Sets Variable Line Feeding) <br> Format: ESC J;n; <br> When ESC J is sent to the printer, the paper will advance in <br> increments of n/216 inch. The value of n must be between 1 <br> and 255. The example that follows sets the line feed to <br> $50 / 216$ inch. ESC J is canceled after the line feed takes <br> place. <br> Example: <br> LPRINT CHR\$(27);CHR\$(74);CHR\$(50); |



| Printer Code | Printer Function |
| :---: | :---: |
| ESC K Cont. | Data sent to the printer. <br> Note: Assume a total of 20 characters of text data (data A and data C). In Text mode, 20 characters correspond to 120 bit-image positions ( $20 \times 6=120$ ). The printable portion left for Bit-Image Graphics data (data B and data D ) is 360 bit-image positions (480-120=360). <br> Example: <br> 1 'OPEN PRINTER IN RANDOM MODE WITH LENGTH OF 255 <br> 2 WIDTH "LPT1:",255 <br> 3 OPEN "LPT1:" AS \#1 <br> 4 PRINT \#1,CHR\$(13);CHR\$(10); <br> 5 SLASH $\$=\mathrm{CHR} \$(1)+\mathrm{CHR} \$(02)+\mathrm{CHR} \$(04)+\mathrm{CHR} \$(08)$ <br> 6 SLASH $=$ SLASH\$+CHR\$(16)+CHR\$(32)+ <br> CHR\$(64)+CHR\$(128)+CHR\$(0) <br> $7 \mathrm{GAP}=\mathrm{CHR} \$(0)+\mathrm{CHR} \$(0)+\mathrm{CHR} \$(0)$ <br> 8 NDOTS $=480$ <br> 9 'ESC K N1 N2 <br> 10 PRINT \#1,CHR\$(27);"K";CHR\$(NDOTS MOD 256); <br> CHR\$ (FIX (NDOTS/256)); <br> 11 'SEND NDOTS NUMBER OF BIT IMAGE BYTES <br> 12 FOR I=1 TO NDOTS $/ 12$ 'NUMBER OF SLASHES TO PRINT <br> USING GRAPHICS <br> 13 PRINT \#1,SLASH\$;GAP\$; <br> 14 NEXT I <br> 15 CLOSE <br> 16 END <br> This example will give you a row of slashes printed in the Bit-Image Graphics mode. |

## 8 Graphics Printer

| Printer Code | Printer Function |
| :---: | :---: |
| ESC L | Escape L (960 Bit-Image Graphics Mode) <br> Format: ESC $L ; n_{1} ; n_{2} ; \mathrm{v}_{1} ; \mathrm{v}_{2} ; \ldots, \mathrm{v}_{\mathrm{k}}$; <br> Changes from the Text mode to the 960 Bit-Image Graphics mode. The input is similar to ESC K. The 960 Bit-Image Graphics mode prints at half the speed of the 480 Bit-Image Graphics mode, but can produce a denser graphic image. The number of bytes of bit-image data $(\mathrm{k})$ is $\mathrm{n}_{1}+256 \mathrm{n}_{2}$ but cannot exceed $960 . n_{1}$ is in the range of 0 to 255 . |
| ESC N | Escape N (Set Skip Perforation) <br> Format ESC N;n; <br> Sets the Skip Perforation function. The number following <br> ESC $N$ sets the value for the number of lines of Skip <br> Perforation. The example shows a 12 -line skip. This will print 54 lines and advance the paper 12 lines. The value of $n$ must be between 1 and 127. ESC $N$ must be reset anytime the page length (ESC C) is changed. <br> Example: <br> LPRINT CHR\$(27);CHR\$(78);CHR\$(12); |
| ESC 0 | Escape $O$ (Cancel Skip Perforation) <br> Cancels the Skip Perforation function. <br> Example: <br> LPRINT CHR\$(27);CHR\$(79); |
| ESC S | Escape S (Subscript/Superscript) <br> Format: ESC S;n; <br> Sets the printer to the Subscript print mode when ESC S is followed by a 1 , as in the example that follows. When ESC S is followed by a 0 (zero), the printer will print in the Superscript print mode. <br> Example: <br> LPRINT CHR\$(27);CHR\$(83);CHR\$(1); |
| ESC $T$ | Escape T (Subscript/Superscript Off) <br> Cancels printing in the Subscript or Superscript print mode. Example: <br> LPRINT CHR\$(27);CHR\$(84); |
| ESC U | Escape U (Unidirectional Printing) <br> Format: ESC U;n; <br> The printer will print from left to right when ESC $U$ is followed by a 1 . When ESC $U$ is followed by a 0 (zero), the left to right printing operation is canceled. The unidirectional printing (ESC U) ensures a more accurate print-start position for better print quality. <br> Example: <br> LPRINT CHR\$(27);CHR\$(85);CHR\$(1); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC W | Escape W (Double Width) <br> Format: ESC W;n; <br> Sets the printer to the Double Width print mode when ESC W is followed by a 1. This mode must be canceled with ESC W <br> followed by a 0 (zero) <br> Example: <br> LPRINT CHR\$(27);CHR\$(87);CHR\$(1); |
| ESC Y | Escape $\mathbf{Y}$ ( 960 Bit-Image Graphics Mode Normal Speed) Format: ESC Y $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \mathrm{v}_{1} ; \mathrm{v}_{2} ; \ldots \mathrm{v}_{\mathrm{k}}$; <br> Changes from the Text mode to the 960 Bit-Image Graphics mode, at normal speed. The printer cannot print dots on consecutive dot positions. The input of data is similar to ESC L. |
| ESC $Z$ | Escape Z (1920 Bit-Image Graphics Mode) <br> Format: ESC $Z ; n_{1} ; \mathrm{n}_{2} ; \mathrm{v}_{1} ; \mathrm{v}_{2} ; \ldots \mathrm{v}_{\mathrm{k}}$; <br> Changes from the Text mode to the 1920 Bit-Image Graphics mode. The input is similar to the other Bit-Image Graphics modes. ESC Z can print only every third dot position. |
| ESC 0 | Escape 0 (1/8-Inch Line Feeding) <br> Sets paper feeding to 3.175 mm ( $1 / 8 \mathrm{in}$.). <br> Example: <br> LPRINT CHR\$(27);CHR\$(48); |
| ESC 1 | Escape 1 (7/72-Inch Line Feeding) <br> Sets paper feeding to 2.47 mm ( $7 / 72 \mathrm{in}$.). <br> Example: <br> LPRINT CHR\$(27);CHR\$(49); |
| ESC 2 | Escape 2 (Start Variable Line Feeding) <br> ESC 2 is an execution command for ESC A. If no ESC A command is given, line feeding returns to 4.23 mm ( $1 / 6 \mathrm{in}$.). Example: <br> LPRINT CHR\$(27);CHR\$(50); |
| ESC 3 | Escape 3 (Variable Line Feeding) <br> Format: ESC 3;n; <br> Changes the paper feeding to $\mathrm{n} / 216$ inch. The example that follows sets the paper feeding to $1 / 4$ inch The value of $n$ must be between 1 and 255 . <br> Example: <br> LPRINT CHR\$(27) ;CHR\$(51);CHR\$(54); |
| ESC 6 | Escape 6 (Select Character Set 2) <br> Selects Character Set 2. (See "Graphics Printer Character Set 2" later in this section.) <br> Example: <br> LPRINT CHR\$(27);CHR\$(54); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC 7 | Escape 7 (Select Character Set 1) <br> Selects character set 1. (See "Graphics Printer Character <br> Set $1^{\prime \prime}$ later in this section.) Character set 1 is automatically selected when the printer is set to on or reset. Example: <br> LPRINT CHR\$(27);CHR\$(55); |
| ESC 8 | Escape 8 (Ignore Paper End) <br> Allows the printer to print to the end of the paper. The printer ignores the Paper End switch. <br> Example: <br> LPRINT CHR\$(27);CHR\$(56); |
| ESC 9 | Escape 9 (Cancel Ignore Paper End) <br> Cancels the Ignore Paper End command. ESC 9 is automatically selected when the printer is set to on or reset. <br> Example: <br> LPRINT CHR\$(27);CHR\$(57); |
| ESC - | Escape Minus (Underline) <br> Format: ESC -;n; <br> ESC - followed by a 1, prints all of the following data with an underline. <br> ESC - followed by a 0 (zero), cancels the Underline print mode. <br> Example: <br> LPRINT CHR\$(27);CHR\$(45);CHR\$(1); |
| ESC < | Escape Less Than (Home Head) <br> The print head will return to the left margin to print one line following ESC $<$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(60); |
| FF | Form Feed <br> Advances the paper to the top of the next page. |
|  | Note: The location of the paper when the printer is set to on, determines the top of the page. The next top of page is 279.4 mm (11 in.) from that position. ESC C can be used to change the page length. <br> Example: <br> LPRINT CHR\$(12); |
| HT | Horizontal Tab <br> Tabs to the next horizontal tab stop. Tab stops are set every 8 columns when the printer's power is applied and can be changed with ESC D. <br> Example: <br> LPRINT CHR\$(9); |


| Printer <br> Code | Printer Function |
| :--- | :--- |
| LF | Line Feed <br> Advances the paper up one line. Line spacing is 4.23 mm <br> (1/6 in.) unless reset by ESC A, ESC 0, ESC 1, ESC 2 or ESC 3. <br> Example: <br> LPRINT CHR\$(10); <br> NUL <br> Null <br> Used with ESC B and ESC D as a list terminator. <br> NUL also is used with other printer control codes to select <br> options (for example, ESC S). <br> Example: <br> LPRINT CHR\$(0); <br> Shift In (Compressed) <br> Changes the printer to the Compressed print mode. <br> Example: <br> LPRINT CHR\$(15); <br> Shift Out (Double Width) <br> Changes the printer to the Double Width print mode. |

## 12 Graphics Printer

## Printer Control Code Quick Reference

This is an alphabetic listing of the descriptions of the printer control codes. You will find it helpful to locate the code you need to perform a certain job, or determine the ASCII decimal value quickly, once you are familiar with the control codes.

Note: ASCII values greater than 27 must be preceded by the ESC code (ASCII value 27).

| Description | Code | ASCII <br> Value |
| :--- | :--- | :--- |
|  |  |  |
| Alarm | BEL | 7 |
| Audible alarm | BEL | 7 |
| Bell | BEL | 7 |
| Buzzer | BEL | 7 |
| Cancel | CAN | 24 |
| Cancel data | CAN | 24 |
| Cancel double-strike printing | ESC H | 72 |
| Cancel double-width by line | DC4 | 20 |
| Cancel double-width (lines) | ESC W | 87 |
| Cancel emphasized printing | ESC F | 70 |
| Cancel ignore paper end | ESC 9 | 57 |
| Cancel perforation skip | ESC O | 79 |
| Cancel subscript/superscript | ESC T | 84 |
| Carriage return | CR | 13 |
| Character set 1 select | ESC 7 | 55 |
| Character set 2 select | ESC 6 | 54 |
| Character spacing 10 per inch | DC2 | 18 |
| Character spacing 17.1 per inch | SI | 15 |
| Clear printer buffer | CAN | 24 |
| Command designator | ESC | 27 |
| Command end | NUL | 0 |
| Command prefix | ESC | 27 |
| Command start | ESC | 27 |
| Command terminator | NUL | 0 |
| Compressed On | SI | 15 |
| Compressed print | SI | 15 |
| Condensed print | SI | 15 |
| Data cancel | CAN | 24 |
| Double-strike printing | ESC G | 71 |
| Double-strike printing Off | ESC H | 72 |
|  |  |  |


| Description | Code | ASCI |
| :---: | :---: | :---: |
| Double-width-by-line Off | DC4 | 20 |
| Double-width-by-line On | SO | 14 |
| Double-width On (lines) | ESC W | 87 |
| Double-width printing (lines) | ESC W | 87 |
| Eject form | FF | 12 |
| Eject paper | FF | 12 |
| Emphasized printing | ESC E | 69 |
| Emphasized printing Off | ESC F | 70 |
| Escape | ESC | 27 |
| Feed line | LF | 10 |
| Form feed | FF | 12 |
| Graphics, 480 bit-image | ESC K | 75 |
| Graphics, 960 bit-image, $1 / 2$ speed | ESC L | 76 |
| Graphics, 960 bit-image, full speed | ESC Y | 89 |
| Graphics 1920 bit-image | ESC Z | 90 |
| Head, home | ESC < | 60 |
| Home head | ESC < | 60 |
| Horizontal tab | HT | 9 |
| Horizontal tab stops set | ESC D | 68 |
| Ignore paper end | ESC 8 | 56 |
| Ignore paper end, cancel | ESC 8 | 56 |
| Length-of-page set in inches | ESC C | 67 |
| Length-of-page set in lines | ESC C | 67 |
| Line-feed, set 1/6 inch | LF | 10 |
| Line-feed, set 1/8 inch | ESC 0 | 48 |
| Line-feed, set 7/72 inch | ESC 1 | 49 |
| Line-feed, set variable | ESC 3 | 51 |
| Line-feed, set variable | ESC A | 65 |
| Line-feed, set variable | ESC J | 74 |
| Line-feed, start variable | ESC 2 | 50 |
| Line-feed, set variable | ESC J | 74 |
| Null | NUL | 0 |
| Page eject | FF | 12 |
| Page length, set in inches | ESC C | 67 |
| Page length, set in lines | ESC C | 67 |
| Paper eject | FF | 12 |
| Paper end, ignore | ESC 8 | 56 |
| Perforation skip Off | ESC O | 79 |
| Perforation skip set | ESC N | 78 |


| Description | Code | ASCI <br> Value |
| :--- | :--- | :--- |
|  |  |  |
| Print double-width one line | SO | 14 |
| Print double-width multiple lines | ESC W | 87 |
| Print emphasized | ESC E | 69 |
| Print emphasized Off | ESC F | 70 |
| Print 10 characters per inch | DC2 | 18 |
| Print unidirectional On/Off | ESC U | 85 |
| Printer buffer, clear | CAN | 24 |
| Return carriage | CR | 13 |
| Select character set 1 | ESC 7 | 55 |
| Select character set 2 | ESC 6 | 54 |
| Set 1 (character set 1) | ESC 7 | 55 |
| Set 1/8-inch line feed | ESC 0 | 48 |
| Set 2 (character set 2) | ESC 6 | 54 |
| Set 7/72-inch line feed | ESC 1 | 49 |
| Set variable line feed | ESC 3 | 51 |
| Set horizontal tab stops | ESC D | 68 |
| Set page length in lines | ESC C | 67 |
| Set page length in inches | ESC C | 67 |
| Set perforation skip | ESC N | 78 |
| Set variable line feed | ESC A | 65 |
| Skip perforation Off | ESC O | 79 |
| Skip perforation On | ESC N | 78 |
| Start 7/72 inch line feed | ESC 1 | 49 |
| Start double-strike print | ESC G | 71 |
| Start double-width print by line | SO | 14 |
| Start double-width print (lines) | ESC W | 87 |
| Start emphasized print | ESC E | 69 |
| Start perforation skip | ESC N | 78 |
| Start subscript/superscript | ESC S | 83 |
| Start variable line feed | ESC 2 | 50 |
| Start underline | ESC - | 45 |
| Stop double-strike print | ESC H | 72 |
| Stop double-width by line | DC4 | 20 |
| Stop double-width print (lines) | ESC W | 87 |
| Stop emphasized print | ESC F | 70 |
| Stop perforation skip | ESC O | 79 |
| Stop subscript/superscript | ESC T | 84 |
| Stop superscript/subscript | ESC T | 84 |
| Stop underline | ESC - | 45 |
|  |  |  |


| Stops, horizontal tabs, set | ESC D | 68 |
| :--- | :--- | ---: |
| Subscript/superscript Off | ESC T | 84 |
| Subscript/superscript On | ESC S | 83 |
| Tab horizontal | HT | 9 |
| Tab stops, horizontal, set | ESC D | 68 |
| Tabs horizontal set | ESC D | 68 |
| Underline On | ESC - | 45 |
| Unidirectional printing Off | ESC U | 85 |
| Unidirectional printing On | ESC U | 85 |
| Variable line feed | ESC 3 | 54 |
| Variable line feed set | ESC 3 | 65 |
| Variable line feed set | ESC J | 74 |
| Vertical tabs set | ESC B | 66 |

## Print Mode Combinations

The IBM Graphics Printer can use any of the combinations of print modes listed in the following table. The print mode can be changed at any place within a line. Modes can be selected and combined if they are in the same vertical column.

| Printer Modes |  |  |  |  |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Normal | $x$ | $x$ | $x$ |  |  |  |  |  |  |  |  |
| Compressed |  |  |  |  | $x$ | $x$ | $x$ |  |  |  |  |
| Emphasized | $x$ |  |  | $x$ |  |  |  | $x$ | $x$ | $x$ |  |
| Double Strike |  |  | $x$ |  |  |  | $x$ |  |  |  | $x$ |
| Subscript |  |  |  |  |  |  |  |  |  |  |  |
| Superscript | $x$ |  |  |  | $x$ |  |  |  | $x$ |  |  |
| Double Width | $x$ | $x$ |  | $x$ | $x$ | $x$ |  | $x$ | $x$ | $x$ |  |
| Underline | $x$ | $x$ | $x$ |  | $x$ | $x$ | $x$ |  | $x$ | $x$ | $x$ |

## Graphics Printer Character Set

The tables on the following pages show each character with its respective ASCII value.


Graphics Printer Character Set 1 (Part 1 of 2)

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Graphics Printer Character Set 1 (Part 2 of 2)


Graphics Printer Character Set 2 (Part 1 of 2)


Graphics Printer Character Set (Part 2 of 2)

## DIP-Switch Settings

There are two DIP switches on the control circuit board. In order to satisfy the user's specific requirements, desired control modes are selectable by the DIP switches. The functions of the switches and their preset conditions at the time of shipment are as shown in the following figures.


Location of Printer DIP Switches

| Switch <br> Number | Function | On | Off | Factory-Set <br> Condition |
| :---: | :--- | :---: | :---: | :---: |
| $1-1$ | Not Applicable | - | - | On |
| $1-2$ | CR | Print Only |  <br> Line Feed | On |
| $1-3$ | Buffer Full | Print Only |  <br> Line Feed | Off |
| $1-4$ | Cancel Code | Invalid | Valid | Off |
| $1-5$ | Not Applicable | - | - | On |
| $1-6$ | Error Buzzer | Sound | Does Not <br> Sound | On |
| $1-7$ | Character Generator | Set 1 | Off |  |
| $1-8$ | SLCT IN Signal | Fixed <br> Internally | Not Fixed <br> Internally | On |

## Functions and Conditions of DIP Switch 1 (Graphics)

| Switch <br> Number | Function | On | Off | Factory-Set <br> Condition |
| :---: | :--- | :--- | :--- | :---: |
| $2-1$ | Form Length | 304.8 mm <br> $(12$ inches) $)$ | 279.4 mm <br> $(11$ inches) $)$ | Off |
| $2-2$ | Line Spacing | 3.175 mm <br> $(1 / 8$ inch $)$ | 4.23 mm <br> $(1 / 6$ inch $)$ | Off |
| $2-3$ | Auto Feed XT Signal | Fixed <br> Internally | Not Fixed <br> Internally | Off |
| $2-4$ | 1 Inch Skip Over Perforation | Valid | Not Valid | Off |

Functions and Conditions of DIP Switch 2 (Graphics)

## Interface

Specifications:

- Data transfer rate: 1000 cps (maximum)
- Synchronization: By externally-supplied -STROBE pulses.
- Handshaking -ACKNLG or BUSY signals.
- Logic level: Input data and all interface control signals are compatible with the TTL level.

Connector type: 57-30360 (Amphenol)
Data Transfer Sequence:


[^1]
## Specifications

| Size |  |
| :---: | :---: |
| Height | 107 mm (4.2 in.) |
| Width | 400 mm (15.7 in.) |
| Depth | 305 mm (12 in.) |
| Weight | 5.5 kg ( 12 lb ) |
| Power Cable |  |
| Length Size | $\begin{aligned} & 1.83 \mathrm{~m}(6 \mathrm{ft}) \\ & 18 \mathrm{AWG} \end{aligned}$ |
| Signal Cable |  |
| Length Size | $\begin{aligned} & 1.83 \mathrm{~m}(6 \mathrm{ft}) \\ & 22 \mathrm{AWG} \end{aligned}$ |

## Physical Specifications

| Voltage (Vac) |  | Frequency <br> $(\mathrm{Hz})$ | Current <br> $($ Amps $)$ | Power <br> (Watts) |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Nominal | Minimum | Maximum | $\pm 3 \mathrm{~Hz}$ | Maximum | Maximum |
| 120 | 104 | 127 | 60 | 1.0 | 100 |
| 220 | 198 | 242 | $50 / 60$ | 0.5 | 100 |
| 240 | 216 | 264 | $50 / 60$ | 0.5 | 100 |

Electrical Specifications

| Print Method | Serial-impact wire matrix |
| :---: | :---: |
| Print Speed | 80 cps |
| Print Direction | Bidirectional with logical seeking |
| Number of Pins in Head | 9 |
| Line Spacing | 4.23 mm (1/6 in.) or programmable |
| Printing Characteristics |  |
| Matrix | $9 \times 9$ |
| Graphic Character | See "Graphics Printer Character Set" tables. |
| Printing Sizes |  |
|  | Characters Maximum <br> characters <br> per inch per line |
| Normal | 1080 |
| Double Width | $5 \quad 40$ |
| Compressed | 17.1 |
| Double Width-Compressed | 8.25 66 |
| Subscript | 1080 |
| Superscript | 1080 |
| Media Handling |  |
| Paper Feed | Adjustable sprocket pin feed |
| Paper Width Range | 101.6 mm ( 4 in .) to 254 mm (10 in.) |
| Copies | One original plus two carbon copies (total thickness not to exceed 0.3 mm ( 0.012 in.)). Minimum paper thickness is 0.064 mm ( 0.0025 in .). |
| Paper Path | Rear |
| Interfaces |  |
| Standard | Parallel 8-bit <br> Data and Control Lines |
| Inked Ribbon |  |
| Color | Black |
| Type | Cartridge |
| Life Expectancy | 3 million characters |
| Environmental Conditions |  |
| Operating Temperature Operating Humidity | 5 to $35^{\circ} \mathrm{C}\left(41\right.$ to $\left.95^{\circ} \mathrm{F}\right)$ 10 to $80 \%$ non-condensing |
| Heat Output | 341 BTU/hr (maximum) |

## Printer Specifications

## Connector Pin Assignments

| Signal Pin No. | Return Pin No. | Signal | Direction | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | 19 | STROBE | In | STROBE pulse to read data in. Pulse width must be more than $0.5 \mu \mathrm{~s}$ at receiving terminal. The signal level is normally "high"; read-in of data is performed at the "low" level of this signal. |
| 2 | 20 | DATA 1 | In | These signals represent information of the 1 st to 8th bits of parallel data respectively. Each signal is at "high" level when data is logical " 1 " and "low" when logical " 0 :" |
| 3 | 21 | DATA 2 | In |  |
| 4 | 22 | DATA 3 | In |  |
| 5 | 23 | DATA 4 | In |  |
| 6 | 24 | DATA 5 | In |  |
| 7 | 25 | DATA 6 | In |  |
| 8 | 26 | DATA 7 | In |  |
| 9 | 27 | DATA 8 | In |  |
| 10 | 28 | $\overline{\text { ACKNLG }}$ | Out | Approximately $5 \mu$ s pulse; "low" indicates that data has been received and the printer is ready to accept other data. |
| 11 | 29 | BUSY | Out | A "high" signal indicates that the printer cannot receive data. The signal becomes "high" in the following cases: <br> 1. During data entry. <br> 2. During printing operation. <br> 3. In "offline" state. <br> 4. During printer error status. |

## Connector Pin Assignment and Descriptions of Interface Signals (Part 1 of 3)

| Signal Pin No. | Return Pin No. | Signal | Direction | Description |
| :---: | :---: | :---: | :---: | :---: |
| 12 | 30 | PE | Out | A "high" signal indicates that the printer is out of paper. |
| 13 | - | SLCT | Out | This signal indicates that the printer is in the selected state. |
| 14 | - | $\frac{\overline{\text { AUTO }}}{\overline{\text { FEED XT }}}$ | In | With this signal being at "low" level, the paper is automatically fed one line after printing. (The signal level can be fixed to "low" with DIP SW pin 2-3 provided on the control circuit board.) |
| 15 | - | NC |  | Not used. |
| 16 | - | OV |  | Logic GND level. |
| 17 | - | CHASSISGND | - | Printer chassis GND. In the printer, the chassis GND and the logic GND are isolated from each other. |
| 18 | - | NC | - | Not used. |
| 19-30 | - | GND | - | "'Twisted-Pair Return" signal; GND level. |
| 31 | - | $\overline{\text { INIT }}$ | In | When the level of this signal becomes "low" the printer controller is reset to its initial state and the print buffer is cleared. This signal is normally at "'high'" level, and its pulse width must be more than $50 \mu \mathrm{~s}$ at the receiving terminal. |

Connector Pin Assignment and Descriptions of Interface Signals
(Part 2 of 3)

| Signal Pin No | Return Pin No. | Signal | Direction | Description |
| :---: | :---: | :---: | :---: | :---: |
| 32 |  | $\overline{\text { ERROR }}$ | Out | The level of this signal becomes "low" when the printer is in "Paper End" state, "Offline" state and "Error" state. |
| 33 | - | GND | - | Same as with pin numbers 19 to 30. |
| 34 | - | NC | - | Not used. |
| 35 |  |  |  | Pulled up to +5 Vdc through 4.7 k -ohms resistance. |
| 36 | - | $\overline{\text { SLCTIN }}$ | In | Data entry to the printer is possible only when the level of this signal is "low!' (Internal fixing can be carried out with DIP SW 1-8. The condition at the time of shipment is set "low" for this signal.) |

Notes: 1. "Direction" refers to the direction of signal flow as viewed from the printer.
2. "Return" denoted "Twisted-Pair Return'" and is to be connected at signal-ground level.
When wiring the interface, be sure to use a twisted-pair cable for each signal and never fail to complete connection on the return side. To prevent noise effectively, these cables should be shielded and connected to the chassis of the system unit and printer, respectively.
3. All interface conditions are based on TTL level. Both the rise and fall times of each signal must be less than $0.2 \mu \mathrm{~s}$.
4. Data transfer must not be carried out by ignoring the $\overline{\mathrm{ACKNLG}}$ or BUSY signal. (Data transfer to this printer can be carried out only after confirming the $\overline{A C K N L G}$ signal or when the level of the BUSY signal is "low.'"

## Connector Pin Assignment and Descriptions of Interface Signals (Part 3 of 3)

## Logic Diagrams

The following page and foldout contain the logic diagrams for the the IBM Graphics Printer.


Graphics Printer (Sheet 1 of 2)

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Personal Computer Hardware Reference Library

## IBM Personal Computer Color Printer

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## Description

The IBM Personal Computer Color Printer is a tabletop, wire matrix, color printer. It attaches to the system unit's Printer Adapter or combination Monochrome Display and Printer Adapter through a standard printer cable, which has a 25 -pin connector on the system unit end and a $36-$ pin connector on the printer end.

When the Color Printer is ready to accept data, the system unit sends the data and control codes through the printer cable to the printer's input/output (I/O) board. The I/O board directs the data and control codes to a buffer. The 6803 Microprocessor on the printer's controller circuit board monitors the buffer constantly and decides when and how to print the information based on the control codes.

The 6803 Microprocessor takes a character from the buffer and compares the character against a table to determine what dots to print. If the character is a control character, the microprocessor compares the character against a control-character table so that it knows what action to take.

When the 6803 Microprocessor reads a line-ending character, it determines whether it would be faster to move to the right margin and print backwards or to the left margin to begin printing. This ability, called logic seeking, allows faster printer output.

The following block diagram shows the operation of the IBM Personal Computer Color Printer.


Color Printer Block Diagram

## Major Subsystems

The three major electromechanical subsystems of the printer are the I/O subsystem, controller subsystem, and print subsystem. Each subsystem is controlled by the 6803 Microprocessor mounted on the controller circuit board. The power-supply regulator circuits are an integrated portion of the controller card.

## The I/O Subsystem

The I/O circuit board contains the circuits needed to direct the parallel data from the computer and interface cable to the printer's controller circuit board for processing. The I/O board also contains the circuits for directing operational status signals between the printer and the system unit.

## Controller Subsystem

The controller subsystem consists of a 6803 Microprocessor and its peripheral interface and memory devices, which are mounted on the controller circuit board. The controller line buffer accepts data from the computer through the printer's I/O board. The controller decodes the data, then sends the data to the print subsystem for printing.

The controller also controls operation of the paper and ribbon feed. These circuits are activated by programming or by a function-select switch. Power regulation and distribution within the printer are also controlled by the controller board.

The power regulator circuit, which is part of the controller circuit board, receives 5,10 , and 40 volts ac from the power supply transformer. It rectifies and distributes the different voltages to the various circuits and motors in the printer.

## Print Subsystem

The print subsystem prints the data received from the controller. The subsystem consists of the following:

- Print head and carriage assembly
- Carriage drive motor and belt
- Left-margin sensor
- Paper feed assembly
- Ribbon drive assembly

The print head contains nine print wires. The print wires are staggered in two vertical columns with five wires in one column and four wires in the other. This arrangement is designed to allow overlapping of print dots. Selectively driving the wires against the ribbon and paper as the print head is moved across the platen, results in the printing of high-quality characters.

The print head is mounted on a carriage which is driven bidirectionally by the carriage drive stepper motor and drive belt. The left-margin sensor is used to signal the controller that the print head is at the home position.

The paper feed assembly is made up of a tractor assembly, paper stepper motor, and a paper-out sensor. It feeds the forms into position and holds the paper stationary while printing.
Continuous forms are fed by pin belts in the tractor assembly, and single sheets of paper are fed by pressure rolls in the paper path. The pin belts and pressure rolls are driven by a drive shaft, drive belt, and the paper stepper motor.

The ribbon feed assembly drives the ribbon between the paper and the print head at a constant speed. It consists of a ribbon cartridge, ribbon drive motor, and a ribbon feed path made up of two rollers, two fixed posts, and a print-head ribbon guide. The ribbon cartridge contains a continuous loop of pre-inked $19-\mathrm{mm}$ (3/4-in.) wide ribbon. The ribbon is pulled from the cartridge, around two guide posts, through the print-head ribbon guide, around two more ribbon posts, and "stuffed" back into the cartridge by two "stuffing" wheels.

In order to print different colors, the ribbon is shifted up and down by the color control mechanism, which is made up of a motor and cam assembly. The cam pivots the complete ribbon feed assembly to four different levels that match the four color bands on the ribbon.

## 6803 Microprocessor

The 6803 Microprocessor and its peripheral devices, which are mounted on the controller circuit board, direct all operations of the printer. This 8-bit single-chip microprocessor unit (MPU) functions as a monolithic MPU requiring one $+5-\mathrm{Vdc}$ power supply and is TTL-compatible. On-chip resources include parallel I/O and a three function programmable timer. Some of the other features include:

- Enhanced 6800 MPU instruction set
- $8 \times 8$ multiply instruction
- Upward-source and object-code compatibility with the 6800 MPU
- Expanded operation to 64 K -byte address space
- 29 parallel I/O and 2-handshake control lines
- Internal clock generator with divide-by-4 output

The program-controlled operating mode determines the configuration of 18 of the 40 MPU pins available, location (internal or external) of interrupt vectors, and type of external bus. The configuration of the remaining 22 pins is not dependent on the operating mode.

Twenty nine pins are organized as three 8 -bit ports and one 5 -bit port. Each port consists of at least a data register and a write-only data-direction register. The data-direction register is used to define whether corresponding bits in the data register are configured as an input (clear) or output (set).

When the port is used as a "data port" or "I/O port," it is controlled by the port data direction register and the programmer has direct access to the port pins using the port Data Register. Port pins are labeled as Pij, where " i " identifies one of four ports and " j " indicates the particular bit. The operating mode determines the configuration of Port 3, Port 4, SC1, SC2, and the physical location of the interrupt vectors.

The mode used by the 6803 MPU is called the Expanded Multiplexed mode. Expanded Multiplexed mode refers to the type of bus it supports. In this mode, Port 3 functions as a time-multiplexed address/data bus with address valid on the negative edge of Address Strobe (AS), and data valid while "E" (which is a timing signal), is high. Port 4 provides address lines A8 to A15.

## Programming Considerations

## Printer Control Codes

The following pages list, in alphabetic order, the printer control codes with a description of each. Some knowledge of BASIC programming is necessary to insert printer control codes in your program. An example of each code in BASIC is at the end of each description. The "Format" information is given where more information is needed for programming considerations.

> Note: All combinations of printing qualities, character spacings, and types are valid. For example, you can print in emphasized print, double-width, and underline all at the same time.

The printer can accept parameters for the ESC commands in either of two formats:

- Binary
- ASCII Character

Although the default format is binary (as used in all examples in the "Printer Control Codes" section), the command, ESC @; n ;, can be used to select either format.

This command affects only certain numeric parameters which follow ESC control codes. Parameters not affected by this command are those which select On or Off ( 1 or 0 ) because the Color Printer operates on only the least significant bit of $n$ in these commands. Therefore, any odd-numbered ASCII decimal value gives the same result as $\mathrm{n}=1$ and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$.

Parameters affected by this command are given in the following three examples:

1. A parameter defining numeric values.

In ASCII format these parameters must be stated as decimal characters, with each numeric field terminated with a non-numeric character (semicolon recommended). For example, to select the near letter quality type font, (ESC I3) the command is: LPRINT CHR\$(27); CHR\$(73);"3;";

In binary format the command is: LPRINT CHR \$(27); CHR\$(73); CHR\$(3);
2. A parameter defining lists of values ending in NUL.

In ASCII format these parameters must be stated as decimal numeric characters, with each numeric field terminated with a non-numeric character (semicolon recommended), with the final NUL being a second semicolon. For example, to set tabs at columns 10 and 40, (ESC D) the command is: LPRINT CHR\$(27); CHR\$(68);"10;40;;";

In binary format the command is: LPRINT CHR \$(27); CHR $(68)$; CHR $\$(10)$;CHR\$(40);CHR\$(0);
3. A two byte parameter ( $\mathrm{n} 1 ; \mathrm{n} 2 ;$ ) defining the amount of data to be printed after the command.

In ASCII format this parameter must be sent as a single decimal numeric value ( 0 to XXXX) terminated with a non-numeric character (semicolon recommended). For example, to print twenty eight bytes in bit-image graphics, (ESC K) the command is: LPRINT CHR $\$(27$ ); CHR $(75) ; " 28 ; ": F O R ~ X ~=~ 1 ~ T O ~ 28: ~ L P R I N T ~$ CHR ${ }^{(255)}$;: NEXT X

In binary format the command is: LPRINT CHR $\$(27)$; CHR $\$(75) ;$ CHR $\$(28) ;$ CHR $\$(0) ;:$ FOR X $=1$ TO 28: LPRINT CHR $\$(255)$;: NEXT X

| Printer Code | Printer Function |
| :---: | :---: |
| BEL | Audible Alarm <br> Sounds the printer buzzer for 1 second or less. The buzzer may be turned off with DIP Switch 8. <br> Example: <br> LPRINT CHR\$(7); |
| BS | Backspace <br> Moves the print head one character width to the left. The character width is determined by the selected character spacing. <br> Example: <br> LPRINT CHR\$(8); |
| CAN | Clear Data <br> Clears the printer memory of all data waiting to be printed following the last received line ending code. If the initialize function is set On by ESC ? (Set Initialize Signal Function), all control codes, except SO (Double-Width printing), remain in effect. If the initialize function is set Off by ESC ?, all control codes are cleared and the printer is set to the values set by the DIP switches. (See <br> "ESC ?" for more details about the initialize <br> function.) <br> Example: <br> LPRINT CHR\$(24); |
| CR | Carriage Return <br> Causes the printer to print the data that follows CR beginning at the left margin. No line-feed operation takes place unless DIP Switch 4 is On or ESC 5 (automatic line-feed) has been sent. <br> Note: IBM Personal Computer BASIC (and many other programs) automatically sends LF (line feed) with CR. If you do not want LF sent after CR, use ASCII decimal value 141 from Character Set 1 instead of ASCII decimal value 13 . <br> Example: <br> LPRINT CHR\$(13); |
| DC1 | Select Printer <br> Sets the printer to accept data from the system unit. Example: <br> LPRINT CHR\$(17); |
| DC2 | 10 Characters per Inch Print <br> Selects character spacing of 10 characters per inch. Example: <br> LPRINT CHR\$(18); |


| Printer Code | Printer Function |
| :---: | :---: |
| DC3 | Deselect Printer <br> Sets the Color Printer so it will not accept data from the system unit. A printer must be initialized by the system or control panel buttons or selected using DC1 (Select Printer) to accept data. <br> Example: <br> LPRINT CHR\$(19); |
| DC4 | Cancel Double-Width Printing by Line <br> Ends double-width printing by line which was started by SO. Example: <br> LPRINT CHR\$(20); |
| ESC | Command Prefix <br> Sets the printer to accept the next data sent as a printer command. (See the following list.) <br> Example: <br> LPRINT CHR\$(27); |
| ESC A | Store Text Line Spacing <br> Format: ESC A;n; <br> ESC A stores a line-feed value of $n / 72$ inch. ESC 2 <br> (Start Text Line Spacing) must then be sent before the line spacing will change. For example, to store a line-feed value of $24 / 72$ inch, the code is ESC A 24. However, until ESC 2 is sent, any text following the ESC A 24 will space at the previously set line-feed increment. The text following the ESC 2 will be printed with a new line-feed increment of $24 / 72$ inch. Any increment between 1/72 and 85/72 may be used. <br> Example: <br> LPRINT CHR\$(27);CHR\$(65);CHR\$(n); |
| ESC a | Select Automatic Ribbon-Band Shift <br> Causes the ribbon to shift one color band at the end of each page. This command is used with an all-black ribbon to extend the ribbon life. <br> Example: <br> LPRINT CHR\$(27);CHR\$(97); |
| ESC B | Set Vertical Tabs <br> Format: ESC B; $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \ldots \mathrm{n}_{64} ; \mathrm{NUL}$; <br> Sets the vertical tab-stop positions. The power-on default is without vertical tab stops set. $\mathrm{n}_{1}$ through $\mathrm{n}_{64}$ represent tab-stop positions by line number. The topmost line of the page is line 0 . Tab-stop positions must be received in ascending numeric order and cannot exceed the set page length. Up to 64 positions are recognized by the Color Printer. The positions do not take effect until NUL is received. |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC B. Cont. | Once vertical tab stops are set, they remain in effect until new ones are specified or all tab stops are set to the power-on defaults by ESC R (Set All Tabs to Power-On Defaults). If no vertical tab stops are set, the Vertical Tab (VT) command behaves as a Line Feed (LF) command. ESC B followed only by NUL cancels all vertical tab stops. <br> The form length must be set by the ESC C command (Set Page Length in Lines) prior to setting vertical tab stops. <br> Example: <br> LPRINT CHR\$(27);CHR\$(66);CHR\$( $\mathrm{n}_{1}$ ); CHR $\$\left(n_{2}\right) ; \ldots C H R \$\left(n_{64}\right) ; C H R \$(0)$; |
| ESC b | Select Band 4 <br> Selects ribbon band 4 (black). The printer will continue to print with band 4 until a command to change the ribbon band is received. <br> Example: <br> LPRINT CHR\$(27);CHR\$(98); |
| ESC C | Set Page Length in Lines <br> Format: ESC C;n; <br> Sets the page length in lines. The number of lines $n$ is converted to inches using the current line spacing. ESC C must be followed by a value, $n$, that specifies the desired length of page in lines. Maximum page length for this printer is 127 lines. This command also sets the current position of the paper as the top-of-form. <br> Note: Automatic perforation-skip (ESC N) and vertical tabs (ESC B) may need to be reset after changing the page length. <br> Example: <br> LPRINT CHR\$(27);CHR\$(67);CHR\$(n); |
| ESC C 0 | Set Page Length in Inches <br> Format: ESC C;0;n; <br> Sets the page length in inches. This command requires a value of $n$ between 1 and 22. The power-on default is set with DIP Switch 6. This command also sets the current position of the paper as the top-of-form. <br> Note: Automatic perforation-skip (ESC N) and vertical tabs (ESC B) may need to be reset after changing the page length. <br> Example: <br> LPRINT CHR\$(27);CHR\$(67);CHR\$(0); CHR\$(n); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC c | Select Band 3 <br> Selects ribbon band 3. The actual color printed will depend on the ribbon being used. The printer will continue to print with band 3 until a command to change the ribbon band is received. <br> Example: <br> LPRINT CHR\$(27);CHR\$(99); |
| ESC D | Set Horizontal Tabs <br> Format: ESC D; $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \ldots \mathrm{n}_{28} ; \mathrm{NUL}$; <br> Sets the horizontal tab-stop positions represented by $\mathrm{n}_{1}$ through $\mathrm{n}_{28}$. The power-on default is a tab stop set at column 8 and every eighth column thereafter. The printer recognizes up to 28 horizontal tab stops. They must be in ascending numeric order and followed by NUL. Tab stops can be set between 1 and the maximum column count for the character spacing in effect. ESC D immediately followed by NUL will clear all horizontal tabs. ESC R (Set All Tabs to Power-On Defaults) may be used to set horizontal tabs to the power-on default. <br> Note: Setting a tab at column 0 clears all tabs and the following tabs will be considered data. <br> Example: <br> LPRINT CHR\$(27);CHR\$(68);CHR\$( $n_{1}$ ); <br> CHR $\$\left(\mathrm{n}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{n}_{28}\right) ; \mathrm{CHR} \$(0)$; |
| ESC d | Variable Forward Space <br> Format: ESC $d ; n_{1} ; \mathrm{n}_{2}$; <br> Places the next printed character $n_{1} ; n_{2} / 120$ inch to the right of the last dot of the current character. The position may be beyond the right margin setting. If the position is beyond the physical end of the line, the next character will be printed at the left end of the printer. <br> $\mathrm{n}_{1}$ and $\mathrm{n}_{2}$ are binary numbers that specify the number of $1 / 120$-inch increments the next printed character is to be placed to the right. $n_{1}$ represents values from 0 to 255 , and $n_{2}$ represents values from 0 to 255 times 256 . Example: <br> LPRINT CHR\$(27);CHR\$(100);CHR\$( $\left.\mathrm{n}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{n}_{2}\right)$; |
| ESC E | Emphasized Printing <br> Changes the printer to emphasized printing. Characters are double struck with the smallest possible horizontal offset between strikes. <br> Example: <br> LPRINT CHR\$(27);CHR\$(69); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC e | Variable Backspace <br> Format: ESC e; $\mathrm{n}_{1} ; \mathrm{n}_{2}$; <br> Places the next printed character $n_{1} ; n_{2} / 120$ inch to the left of the last dot of the current character. The position may be beyond the left margin setting. If the specified position is beyond the physical left end of the printer, the next character will be printed at the left end of the printer. $n_{1}$ and $n_{2}$ are binary numbers that specify the number of $1 / 120$-inch increments the next printed character is to be placed to the left. $n_{1}$ represents values from 0 to 255 , and $n_{2}$ represents values from 0 to 255 times 256. <br> Example: <br> LPRINT CHR $\$(27) ; C H R \$(101) ; C H R \$\left(n_{1}\right) ; C H R \$\left(n_{2}\right)$; |
| ESC F | Cancel Emphasized Printing <br> Ends emphasized printing started by ESC E. <br> Example: <br> LPRINT CHR\$(27);CHR\$(70); |
| ESC G | Double-Strike Printing <br> Sets the printer to double-strike printing. Characters are struck twice with no horizontal offset between strikes. <br> Example: <br> LPRINT CHR\$(27);CHR\$(71); |
| ESC H | Cancel Double-Strike Printing <br> Ends double-strike printing started by ESC G. <br> Example: <br> LPRINT CHR\$(27);CHR\$(72); |
| ESC I | Change Printing Quality <br> Format ESC I;n; <br> Selects the printing quality. When n is 1 , data processing quality is selected; when n is 2 , text quality is selected; when $n$ is 3 , letter quality is selected. Each printing quality selection produces a different spacing of the dots that make up a character. Each character box is: with data-processing quality selected, 8 by 9 dots; with text quality selected, 24 by 9 dots; and with near-letter quality selected, 36 by 18 dots. Example: <br> LPRINT CHR\$(27);CHR\$(73);CHR\$(n); |
| ESC J | Variable Line Space <br> Format: ESC J;n; <br> Advances the paper in increments of $n / 144$ inch. The value of n must be between 1 and 255 . Line spacing of $14 / 144$ is recommended for bit-image graphics using eight bits. ESC J is canceled after the line space takes place. The value of $n$ is not stored. <br> Example: <br> LPRINT CHR\$(27);CHR\$(74);CHR\$(n); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC K | 1108 Bit-Image Graphics <br> Format: ESC K; $n_{1} ; n_{2} ; v_{1} ; v_{2} ; \ldots v_{1108}$; <br> Sets dot spacing to 84 by 84 dots per inch in 1:1 aspect ratio, to 70 by 84 dots per inch in 5:6 aspect ratio (see "ESC $n$ (Set Aspect Ratio)"). All bit-image graphics is printed from left to right. If the graphics data exceeds the space remaining on the line, the data to be printed beyond the end of the line is printed at the left margin on the next line. <br> $\mathrm{n}_{1}$ and $\mathrm{n}_{2}$ are binary numbers that specify the number of bit-image data bytes to be transferred. $n_{1}$ represents values from 0 to 255 , and $n_{2}$ represents values from 0 to 4 times 256. The total number of bit-image data bytes is equal to $n_{1}+n_{2} \times 256$ and cannot exceed 1108 (the total number of dot positions in a 13.2 inch line). <br> Bit-image graphics is printed using eight of the nine print-head wires (the bottom wire is not used). $v_{1}$ through $v_{1108}$ are bit-image data bytes, each of which represents a set of 8 dots in a vertical line. The horizontal position of these 8 dots is determined by the position of the bit-image data byte within the $\mathrm{v}_{1}$ through $v_{1108}$ series. $v_{1}$ is printed at the starting position followed in order from left to right by $\mathrm{v}_{2}$ through $\mathrm{v}_{1108}$. Each bit of a bit-image data byte represents a vertical dot position at the horizontal position represented by that bit-image data byte. The lowest value, or least significant bit (Bit 0), represents the bottom dot position, and the highest value, or most significant bit (Bit 7), represents the top dot position. |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC K Cont. | In the following table the left-hand column of (•)s represents dot positions within a vertical line. The right-hand column shows the corresponding bit number within a bit-image data byte. (The bits are numbered 7 through 0 , from left to right.) <br> For example: if $\mathrm{v}_{1}$ is binary 10000000 (decimal 128), only the top dot prints in that horizontal position; if $v_{1}$ is binary 00000001 (decimal 01), only the bottom dot prints; and if $\mathrm{v}_{1}$ is binary 11111111 (decimal 255), all eight dots print. <br> Example: <br> LPRINT CHR\$(27);CHR\$(75);CHR\$( $\mathrm{n}_{1}$ ); <br> CHR $\$\left(\mathrm{n}_{2}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{2}\right) ; \ldots$ CHR $\$\left(\mathrm{v}_{1108}\right)$; |
| ESC L | 2216 Bit-Image Graphics (half-speed) <br> Format: ESC $L ; n_{1} ; n_{2} ; V_{1} ; v_{2} ; \ldots \mathrm{v}_{2216}$; <br> Sets dot spacing to 168 by 84 dots per inch in 1:1 aspect ratio, to 140 by 84 dots per inch in 5:6 aspect ratio (see "ESC $n$ (Set Aspect Ratio)"). 2216 bit-image graphics (half-speed) prints at one-half the speed of 2216 bit-image graphics (ESC Y) for improved print quality and the ability to print consecutive dot positions. $n_{1}, n_{2}, v_{1}$, <br> and $v_{2}$ through $v_{2216}$ represent the same values as in 1108 bit-image graphics (ESC K). Refer to the description of ESC K for a complete description of these values. The total number of bit-image data bytes cannot exceed 2216 (the total number of dot positions in a 13.2 -inch line). <br> Example: <br> LPRINT CHR\$(27);CHR\$(76);CHR\$( $n_{1}$ ); <br> CHR $\$\left(\mathrm{n}_{2}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{v}_{2216}\right)$; |
| ESC M | Automatic Line Justification <br> Format: ESC M;n; <br> Justifies the right margin. Automatic justification is started when n is 1 , and stopped when n is 0 . The printer adjusts the spaces between words in the text so that the last character of the words at the end of the lines all print in the last position of the line. Thus both the left and right margins appear as straight lines. This gives a block appearance to the printed text. Automatic line justification can be used with any of the character spacings. |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC M Cont. | Notes: <br> 1. Lines are not right justified if the text is less than $75 \%$ of the specified line length. If a line fails the greater than $75 \%$ rule, the remaining portion of the text is tested. <br> 2. If the justification results in a word wrap condition, the remaining text is treated as separate lines and follows the above rule. <br> 3. Control codes in the datastream cause the text before the control code to be printed based on the justification rules. The remainder of the text is justified between the current print position and the right margin. <br> 4. If the last line of a paragraph, or any line of data, is not to be justified, use the control code sequence, backspace (BS) and carriage return (CR). <br> 5. The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(77);CHR\$(n); |
| ESC m | Select Band 2 <br> Selects ribbon band 2. The actual color printed depends on the ribbon being used. The printer will continue to print with band 2 until a command to change the ribbon band is received by the printer. <br> Example: <br> LPRINT CHR\$(27);CHR\$(109); |
| ESC N | Set Automatic Perforation-Skip <br> Format: ESC N;n; <br> Specifies the number of lines to be skipped at the end of each page. This causes the printer to automatically skip over the perforation between pages of continuous forms. The number of lines $n$, is converted to inches using the line-spacing in effect. The value of $n$ must be between 1 and 127. ESC $N$ must be reset anytime the page length is changed by ESC C (Set Page Length in Lines) or by ESC C 0 (Set Page Length in Inches). <br> Example: <br> LPRINT CHR\$(27);CHR\$(78);CHR\$(n); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC n | Set Aspect Ratio <br> Format: ESC $n$;x; <br> Sets the printer to a $5: 6$ or $1: 1$ aspect ratio. When $x$ is 1 , the aspect ratio is set to $1: 1$; when x is 0 , the aspect ratio is set to $5: 6$. With the $5: 6$ aspect ratio selected, graphics are printed to match the shape that appears on the display. The 1:1 aspect ratio is recommended for bit-image graphics to improve quality and simplify bit-position calculations. The power-on default is the 5:6 aspect ratio. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(110);CHR\$(x); |
| ESC 0 | Cancel Automatic Perforation-Skip <br> Cancels the automatic perforation-skip function. <br> Example: <br> LPRINT CHR\$(27);CHR\$(79); |
| ESC P | Proportional Spacing <br> Format: ESC P;n; <br> Starts proportional spacing when n is 1 . Stops proportional spacing when n is 0 . Proportional spacing gives each different character a different amount of space on the line. That is, narrow characters, such as $i$, are given a small amount of space on the line relative to a broader character, such as M. This is similar to the way people write characters and gives a more balanced look to the text. Many books are printed in proportional spacing, as is this one. <br> The distance of a forward space is 10 units; the distance of a backspace is determined by the last printed character or space, if the printing of the character or the space was the last carriage movement. <br> Normal processing of all control codes continues during proportional spacing. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR $\$(27) ; C H R \$(80) ; C H R \$(n)$; |



| Printer Code | Printer Function |
| :---: | :---: |
| ESC T | Cancel Subscript or Superscript <br> Ends subscript or superscript printing started by ESC S. <br> Note: If ESC T is issued when not printing in subscript or superscript, it is acknowledged and ignored. <br> Example: <br> LPRINT CHR\$(27);CHR\$(84); |
| ESC U | Unidirectional Printing <br> Format: ESC U;n; <br> When n is 1 , sets the printer to print from left to right only. ESC $\cup O$ returns the printer to normal two-direction printing. Unidirectional printing ensures a more accurate printing start position for better print quality. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(85);CHR\$(n); |
| ESC W | Continuous Double-Width Printing <br> Format: ESC W;n; <br> ESC W 1 changes the printer to double-width printing. ESC W 0 ends the double-width printing started by ESC W 1. ESC W 1 is not canceled by a line ending code and must be canceled by ESC W 0. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(87);CHR\$(n); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC $X$ | Set Left and Right Margins <br> Format: ESC $X ; n_{1} ; n_{2}$; <br> The numbers, $n_{1}$ and $n_{2}$, are selected in relation to the left side of the printer, with $\mathrm{n}_{1}$ representing the left margin and $n_{2}$ the right margin. The value of $n_{1}$ or $n_{2}$ is the column of the page you wish to set as the left or right margin. <br> $n_{2}$ must be greater than $n_{1}$ by $1.27 \mathrm{~cm}(1 / 2 \mathrm{inch})$ or more, and cannot be greater than 13.2 times the character-spacing (in characters per inch) in effect. If $\mathrm{n}_{2}$ is greater than this limit, the right margin will be set at the maximum allowable length. Data is printed beginning in column $n_{1}$. Column $n_{2}$ is considered the last printable position of the line. If a word to be printed exceeds the right margin, a carriage-return and line-feed are inserted before the word, and the word is printed on the next line. The margins are converted to inches based on the current character-spacing setting. The power-on default is set with DIP Switch 5. <br> Note: Both $\mathrm{n}_{1}$ and $\mathrm{n}_{2}$ must be included in the command or the results will be unpredictable. <br> Example: <br> LPRINT CHR\$(27);CHR\$(88);CHR\$( $\left.n_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{n}_{2}\right)$; |
| ESC Y | 2216 Bit-Image Graphics <br> Format: ESC $Y ; n_{1} ; n_{2} ; v_{1} ; v_{2} ; \ldots v_{2216}$; <br> Sets dot spacing to 168 by 84 dots per inch in 1:1 aspect ratio, to 140 by 84 dots per inch in 5:6 aspect ratio (see "ESC $n$ (Set Aspect Ratio)") and prints at normal printing speed. ESC Y graphics cannot print dots in consecutive horizontal dot positions. If consecutive dot positions are specified, the printer will not print the second dot. <br> $n_{1}, n_{2}, v_{1}$, and $v_{2}$, through $v_{2216}$ represent the same values as in 1108 Bit-Image Graphics (ESC K). Refer to the description of ESC K for a complete description of these values. The number of bit-image databytes cannot exceed 2216 (the total number of dot positions in a 13.2-inch line). <br> Example: <br> LPRINT CHR\$(27);CHR\$(89);CHR\$( $\left.n_{1}\right) ;$ CHR $\$\left(n_{2}\right)$; <br> CHR $\left(\mathrm{v}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{v}_{2216}\right)$; |
| ESC y | Select Band 1 <br> Selects ribbon band 1. The actual color printed depends on the ribbon being used. The printer will continue to print with band 1 until a command to change the ribbon band is received by the printer. <br> Example: <br> LPRINT CHR\$(27);CHR\$(121); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC Z | 4432 Bit-Image Graphics <br> Format: ESC $Z ; n_{1} ; n_{2} ; v_{1} ; v_{2} ; \ldots v_{4432}$; <br> Sets dot spacing to 336 by 84 dots per inch in 1:1 aspect ratio, to 280 by 84 dots per inch in 5:6 aspect ratio (see <br> 'ESC $n$ (Set Aspect Ratio)"). 4432 bit-image graphics prints at one-half the speed of 1108 bit-image graphics (ESC K) for improved print quality. ESC $Z$ graphics can print only every third consecutive horizontal dot position. If consecutive dot positions are specified, the printer will ignore the second and third dots. <br> $n_{2}, v_{1}, v_{2}$, and $v_{4432}$ represent the same values as in 1108 bit-image graphics (ESC K). Refer to the description of ESC K for a complete description of these values. The number of bit-image databytes cannot exceed 4432 (the total number of dot positions in a 13.2-inch line). Example: <br> LPRINT CHR $\$(27) ; \mathrm{CHR} \$(90) ; \mathrm{CHR} \$\left(\mathrm{n}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{n}_{2}\right)$; CHR $\$\left(\mathrm{v}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{v}_{443}\right)$; |
| ESC 0 | 1/8 Inch Line Spacing <br> Sets line spacing to 8 lines per inch. <br> Example: <br> LPRINT CHR\$(27);CHR\$(48); |
| ESC 1 | 6/72 Inch Line Spacing <br> Sets line spacing to $6 / 72$ inch. <br> Example: <br> LPRINT CHR\$(27);CHR\$(49); |
| ESC 2 | Start Text Line Spacing <br> ESC 2 is an execution command for ESC A (Set Text Line Spacing). If no ESC A command has been given, line spacing returns to 6 lines per inch. <br> Example: <br> LPRINT CHR\$(27);CHR\$(50); |
| ESC 3 | Graphics Line Spacing <br> Format: ESC 3;n; <br> Sets line spacing to $n / 144$ inch. Line spacing of $14 / 144$ is recommended for bit-image graphics using eight bits. The value of n must be between 1 and 255. <br> Example: <br> LPRINT CHR\$(27);CHR\$(51);CHR\$(n); |
| ESC 4 | Set Top of Page <br> Sets the current vertical position as the top-of-page. <br> Example: <br> LPRINT CHR\$(27);CHR\$(52); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC 5 | Automatic Line Feed <br> Format: ESC 5;n; <br> When $n$ is 1 , automatic line feeding starts; the printer will line-feed each time a code that indicates the end of a line, such as $C R$, is received. When $n$ is 0 , automatic line feeding stops. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(53);CHR\$(n); |
| ESC 6 | Select Character Set 2 <br> Selects character set 2. (See "Character Set 2.") <br> Character Set 2 contains most characters and symbols used in non-English languages. The power-on default for Character Set is set with DIP Switch 1. <br> Note: Some programs use the control codes in Character Set 1 that have ASCII decimal values above 128. These control codes are not in Character Set 2. The use of Character Set 2, therefore, may not give the desired results with some programs. <br> Example: <br> LPRINT CHR\$(27);CHR\$(54); |
| ESC 7 | Select Character Set 1 <br> Selects character set 1. (See "Character Set 1".) <br> Character Set 1 contains characters and symbols commonly used in the English language, along with some common, non-English, characters and symbols. The power-on default for Character Set is set with DIP Switch 1. <br> Example: <br> LPRINT CHR\$(27);CHR\$(55); |
| ESC - | Continuous Underline <br> Format: ESC -;n; <br> When n is 1 -all of the following data is underlined. ESC followed by 0 cancels underlining. <br> Note: The Color Printer operates only on the least significant bit of $n$. Therefore, any odd-numbered ASCII decimal value gives the same result as $n=1$, and any even-numbered ASCII decimal value gives the same result as $\mathrm{n}=0$. <br> Example: <br> LPRINT CHR\$(27);CHR\$(45);CHR\$(n); |


| Printer <br> Code | Printer Function |
| :--- | :--- |
| ESC: | 12 Characters per Inch Printing <br> Sets character spacing to 12 characters per inch. <br> Example: <br> LPRINT CHR $\$(27) ; C H R \$(58) ;$ <br> ESC $<$ <br> Move Carriage to Home Position <br> Returns the print head to the left side of the printer to <br> print the line following the command. No line feed occurs. <br> Example: <br> LPRINT CHR\$(27);CHR\$(60); <br> Set Initialize Signal Function <br> Format: ESC ?;n; <br> Defines what the printer does when an initialize signal is <br> received. The initialize signal is a hardware signal sent to <br> the printer by the system unit when called for by the program <br> being used. This signal is commonly called for when a <br> program is first loaded. When n is 1, the initialize function <br> is set On; when n is 0, the initialize function is set Off. <br> When the initialize function is On, the initialize signal <br> causes the printer to clear all data from the printer memory <br> and set all printer functions to the power-on defaults. Some <br> of the data may not have been printed and will be lost. <br> When the initialize function is Off, the initialize signal <br> causes the printer to insert CAN (Clear Data) into the data <br> in the printer memory. The CAN, when processed by the <br> printer, clears the printer memory of all data waiting to be <br> printed following the-last received line-ending code. All <br> control codes are cleared and the printer is set to the values <br> set by the DIP switches. This allows a printing job to be <br> completed before the printer is reset for the next application. <br> The power-on default is the initialize function set Off. <br> Note: The Color Printer operates only on the least <br> significant bit of n. Therefore, any odd-numbered <br> ASCII decimal value gives the same result as n=1, and <br> any even-numbered ASCII decimal value gives the same <br> result as n=0. <br> Example: <br> LPRINT CHR\$(27);CHR\$(63);CHR\$(n); |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC @ | Select Control-Value Data Type <br> Format: ESC @; n; <br> Allows the printer to accept certain parameters for the ESC commands in either of two forms: binary or ASCII character. When " $n$ " is 1 (odd) ASCII is selected. <br> When " $n$ " is 0 (even) Binary is selected. <br> Note: See "Programming Considerations at the Beginning of this section for a detailed explanation of this command. <br> Example: <br> LPRINT CHR\$(27);CHR\$(64);CHR\$(n); |
| ESC | Print All Characters <br> Format: ESC $\backslash ; \mathrm{n}_{1} ; \mathrm{n}_{2}$; <br> Allows the printing of all characters. This includes characters that are normally recognized by the printer as control codes. This code (ESC <br> ) allows the printer to print the special symbols assigned to these ASCII values. If no character is assigned to a decimal value received by the printer, a space character is printed. No control code functions are performed when this command is in effect. $n_{1}$ and $n_{2}$ are binary numbers that specify the number of characters to be printed. $\mathrm{n}_{1}$ represents values from 0 to 255 , and $\mathrm{n}_{2}$ represents values from 0 to 255 times 256 . Example: <br> LPRINT CHR\$(27);CHR\$(92); CHR\$( $\left.n_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{n}_{2}\right)$; |
| ESC ] | Reverse Line Feed <br> Causes the printer to move the paper down one line space as defined by DIP Switch 2 or by printer control codes, ESC A and ESC 2, ESC 0, ESC 1, or ESC 3. <br> Example: <br> LPRINT CHR\$(27);CHR\$(93); |
| ESC $\wedge$ | Print Any Character <br> Allows the printer to print any character each time the command is received. This includes characters normally recognized by the printer as control codes. This code (ESC $\wedge$ ) allows the printer to print the special symbols assigned to these ASCII values. If no character is assigned to a decimal value received by the printer, a space character is printed. <br> Example: <br> LPRINT CHR\$(27);CHR\$(94); |


| Printer Code | Printer Function |
| :---: | :---: |
| FF | Form Feed <br> Advances the paper to the next top-of-form position. The top-of-form position is set by the position of the paper when power is switched On, or by ESC 4, ESC C, or the control-panel buttons. The next top-of-form is determined by the form length defined by DIP Switch 6, ESC C, or ESC C 0. Example: <br> LPRINT CHR\$(12); |
| HT | Horizontal Tab <br> Moves the print head to the next horizontal tab stop. If the next horizontal tab stop is beyond the right margin, the character following HT is printed at the left margin. Tab stops are set with ESC D. A tab stop every 8 columns is the power-on default. <br> Example: <br> LPRINT CHR\$(9); |
| LF | Line Feed <br> Advances the paper one linespace, as defined by DIP Switch 2 or by printer control codes; ESC A and ESC 2, ESC 0, ESC 1 , or ESC 3. <br> Example: <br> LPRINT CHR\$(10); |
| NUL | Command End <br> Used with control commands as a command list terminator. NUL is also used with other printer control codes to select options. <br> Example: <br> LPRINT CHR\$(0); |
| SI | Compressed Printing <br> Causes the printer to begin compressed printing. Character spacing in compressed printing is 17.1 characters per inch. Example: <br> LPRINT CHR\$(15); |
| SO | Double-Width Printing by Line <br> Causes the printer to start double-width printing. Double-width printing prints the characters twice as wide as the current character spacing. This results in half as many characters per inch. A Carriage Return, Line Feed or DC4 (End Double-Width Printing by Line) cancels the SO command. Example: <br> LPRINT CHR\$(14); |


| Printer <br> Code | Printer Function |
| :--- | :--- |
| VT | Vertical Tab <br> Advances the paper to the next vertical tab-stop position. <br> If the next vertical tabstop is beyond the bottom of the <br> page, the paper is placed at the first line of the next <br> page. If no vertical tab stops are set, the VT command is <br> treated as a line-feed (LF) command. <br> Example: <br> LPRINT CHR\$(11); |

## Printer Control Code Quick Reference

This is an alphabetic listing of the descriptions of the printer control codes. You will find it helpful in locating the code you need to perform a certain job, or to determine the ASCII decimal value quickly, once you are familiar with the control codes.

Note: ASCII values greater than 27 must be preceded by the ESC code (ASCII value 27).

| Description | Code | ASCII <br> Value |
| :--- | :--- | ---: |
| 10 characters-per-inch print |  |  |
| 12 characters-per-inch print | DC2 | 18 |
| 17.1 characters-per-inch print | ESC : | 58 |
| Alarm | SI | 15 |
| All-characters print | BEL | 7 |
| Aspect ratio set | ESC |  |
| Audible alarm | ESC n | 110 |
| Auto justification On/Off | BEL | 7 |
| Auto line feed On/Off | ESC M | 77 |
| Auto perforation skip Off | ESC 5 | 53 |
| Auto perforation skip On | ESC O | 79 |
| Auto ribbon-band shift | ESC N | 78 |
| Auto ribbon shift | ESC a | 97 |
| Backspace | ESC a | 97 |
| Backspace n increments | BS | 8 |
| Backspace variable | ESC e | 101 |
| Band 1 | ESC e | 101 |
| Band 2 | ESC y | 121 |
| Band 3 | ESC m | 109 |
| Band 4 | ESC c | 99 |
| Bell | ESC b | 98 |
| Black ribbon band | BEL | 7 |
| Buzzer | ESC b | 98 |


| Description | Code | ASCII <br> Value |
| :---: | :---: | :---: |
| Cancel | CAN | 24 |
| Cancel auto line feed | ESC 5 | 53 |
| Cancel data | CAN | 24 |
| Cancel double-strike printing | ESC H | 72 |
| Cancel double-width by line | DC4 | 20 |
| Cancel double-width printing (lines) | ESC W | 87 |
| Cancel emphasized printing | ESC F | 70 |
| Cancel perforation skip | ESC O | 79 |
| Cancel proportional spacing | ESC P | 80 |
| Cancel subscript | ESC T | 84 |
| Cancel superscript | ESC T | 84 |
| Carriage return | CR | 13 |
| Change color (see ribbon band desired) |  |  |
| Change printing quality | ESC I | 73 |
| Character quality set | ESC I | 73 |
| Character set 1 select | ESC 7 | 55 |
| Character set 2 select | ESC 6 | 54 |
| Character spacing, 12 per inch | ESC : | 58 |
| Character spacing, 10 per inch | DC2 | 18 |
| Character spacing, 17.1 per inch | SI | 15 |
| Character under decimal 32, print | ESC $\wedge$ | 94 |
| Characters under decimal 32, print | ESC | 92 |
| Clear data | CAN | 24 |
| Clear horizontal tabs | ESC R | 82 |
| Clear tabs | ESC R | 82 |
| Clear vertical tabs | ESC R | 82 |
| Color band 1 | ESC y | 121 |
| Color band 2 | ESC m | 109 |
| Color band 3 | ESC c | 99 |
| Color band 4 | ESC b | 98 |


| Description | Code | ASCII <br> Value |
| :---: | :---: | :---: |
| Command designator | ESC | 27 |
| Command end | NUL | 0 |
| Command prefix | ESC | 27 |
| Command start | ESC | 27 |
| Command terminator | NUL | 0 |
| Compressed On | SI | 15 |
| Compressed print | SI | 15 |
| Condensed print | SI | 15 |
| Control-data value-type set | ESC @ | 64 |
| Data clear | CAN | 24 |
| Data-processing quality set | ESC I | 73 |
| Data-value type set | ESC @ | 64 |
| Deselect printer | DC3 | 19 |
| Deselect specific printer | ESC Q | 81 |
| Double-strike printing | ESC G | 71 |
| Double-strike printing Off | ESC H | 72 |
| Double-width-by-line Off | DC4 | 20 |
| Double-width-by-line On | SO | 14 |
| Double-width On/Off (lines) | ESC W | 87 |
| Eject form | FF | 12 |
| Eject paper | FF | 12 |
| Emphasized printing | ESC E | 69 |
| Emphasized printing Off | ESC F | 70 |
| Escape | ESC | 27 |
| Feed line | LF | 10 |
| Form feed | FF | 12 |
| Form, set top of | ESC 4 | 52 |
| Forward space variable | ESC d | 100 |
| Graphics, 1108 bit-image | ESC K | 75 |
| Graphics, 2216 bit-image, 1/2 speed | ESC L | 76 |
| Graphics, 2216 bit-image, full speed | ESC Y | 89 |


| Description | Code | ASCII |
| :--- | :--- | :---: |
| Value |  |  |
|  |  |  |
| Graphics, 4432 bit-image, 1/2 speed | ESC Z | 90 |
| Graphics, line-feed set | ESC 3 | 51 |
| Head, home | ESC < | 60 |
| Home head | ESC < | 60 |
| Horizontal tab | HT | 9 |
| Horizontal tab stops set | ESC D | 68 |
| Incremental backspace | ESC e | 101 |
| Initialize function set | ESC ? | 63 |
| Justification On/Off | ESC M | 77 |
| Length-of-page set in lines | ESC C | 67 |
| Length-of-page set in inches | ESC C 0 | 670 |
| Line-feed | LF | 10 |
| Line-feed, auto On/Off | ESC 5 | 53 |
| Line-feed, reverse | ESC ] | 93 |
| Line-feed, set 1/8 inch | ESC 0 | 48 |
| Line-feed, set 6/72 inch | ESC 1 | 49 |
| Line-feed, set graphics | ESC 3 | 51 |
| Line-feed, store text | ESC A | 65 |
| Line-feed, start text | ESC 2 | 50 |
| Line-feed, variable | ESC J | 74 |
| Margins set | ESC X | 88 |
| Near-letter quality, set | ESC I | 73 |
| Null | NUL | 0 |
| Page eject | FF | 12 |
| Page length, set in inches | ESC C 0 | 670 |
| Page length, set in lines | ESC C | 67 |
| Paper eject | FF | 12 |
| Perforation skip Off | ESC N | 79 |
| Perforation skip set | ESC | 98 |
| Print all characters | ESC | 92 |
| Print character under decimal 32 |  | 94 |
|  |  |  |


| Description | Code | ASCII <br> Value |
| :--- | :--- | ---: |
|  |  |  |
| Print double-width one line | SO | 14 |
| Print double-width multiple lines | ESC W | 87 |
| Print emphasized | ESC E | 69 |
| Print emphasized Off | ESC F | 70 |
| Print quality set | ESC I | 73 |
| Print 10 characters per inch | DC2 | 18 |
| Print 12 characters per inch | ESC : | 58 |
| Print unidirectional On/Off | ESC U | 85 |
| Printer deselect | DC3 | 19 |
| Printer deselect specific | ESC Q | 81 |
| Printer select | DC1 | 17 |
| Proportional spacing On/Off | ESC P | 80 |
| Quality set | ESC I | 73 |
| Return carriage | CR | 13 |
| Reverse line feed | ESC ] | 93 |
| Ribbon band 1 | ESC y | 121 |
| Ribbon band 2 | ESC m | 109 |
| Ribbon band 3 | ESC c | 99 |
| Ribbon band 4 | ESC b | 98 |
| Ribbon band auto shift | ESC a | 97 |
| Select character set 1 | ESC 7 | 55 |
| Select character set 2 | ESC 6 | 54 |
| Select color |  |  |
| (see ribbon band desired) |  |  |
| Select printer | DC1 | 17 |
| Set 1 (character set 1) | ESC 7 | 55 |
| Set 1/8-inch line feed | ESC 0 | 48 |
| Set 2 (character set 2) | ESC 6 | 54 |
| Set 6/72-inch line feed | ESC 1 | 49 |
| Set aspect ratio | ESC n | 110 |
| Set data-processing quality | ESC I | 73 |


| Description | Code | ASCII <br> Value |
| :--- | :--- | :---: |
|  |  |  |
| Set data-value type | ESC @ | 64 |
| Set graphics line feed | ESC 3 | 51 |
| Set horizontal tab stops | ESC D | 68 |
| Set initialize function | ESC ? | 63 |
| Set left margin | ESC X | 88 |
| Set margins | ESC I | 88 |
| Set near-letter quality | ESC C | 73 |
| Set page length in lines | ESC C 0 | 67 |
| Set page length in inches | ESC N | 78 |
| Set perforation skip | ESC X | 88 |
| Set right margin | ESC I | 73 |
| Set text quality | ESC 4 | 52 |
| Set top-of-form | ESC B | 66 |
| Set vertical tabs | ESC d | 100 |
| Space forward variable | ESC Q | 81 |
| Specific printer deselect | ESC 1 | 49 |
| Start 6/72 inch line feed | ESC 5 | 53 |
| Start auto line feed | ESC G | 71 |
| Start double-strike print | SO | 14 |
| Start double-width print by line | ESC W | 87 |
| Start double-width print (lines) | ESC E | 69 |
| Start emphasized print | ESC 3 | 51 |
| Start graphics line feed | ESC N | 78 |
| Start perforation skip | ESC P | 80 |
| Start proportional spacing | ESC S | 83 |
| Start subscript | ESC S | 83 |
| Start superscript | ESC 2 | 50 |
| Start text line feed | ESC - | 45 |
| Start underline | ESC 5 | 53 |
| Stop auto line feed | ESC H | 72 |
| Stop double-strike print |  |  |
|  |  |  |


| Stop double-width by line | DC4 | 20 |
| :--- | :--- | ---: |
| Stop double-width print (lines) | ESC W | 87 |
| Stop emphasized print | ESC F | 70 |
| Stop perforation skip | ESC O | 79 |
| Stop proportional spacing | ESC P | 80 |
| Stop subscript | ESC T | 84 |
| Stop superscript | ESC T | 84 |
| Stop underline | ESC - | 45 |
| Stops, horizontal tabs, set | ESC D | 68 |
| Stops, vertical tabs, set | ESC B | 66 |
| Store text line feed | ESC A | 65 |
| Subscript Off | ESC T | 84 |
| Subscript On | ESC S | 83 |
| Superscript Off | ESC T | 84 |
| Superscript On | ESC S | 83 |
| Tab horizontal | HT | 9 |
| Tab stops, horizontal, set | ESC D | 68 |
| Tab stops, vertical, set | ESC B | 66 |
| Tab vertical | VT | 11 |
| Tabs clear | ESC R | 82 |
| Tabs horizontal set | ESC D | 68 |
| Tabs vertical set | ESC B | 66 |
| Text line-feed store | ESC A | 65 |
| Text line-feed start | ESC 2 | 50 |
| Text quality set | ESC I | 73 |
| Top-of-form set | ESC 4 | 52 |
| Underline On/Off | ESC - | 45 |
| Unidirectional printing On/Off | ESC U | 85 |
| Variable backspace | ESC e | 101 |
| Variable forward space | ESC d | 100 |
| Variable line feed | ESC J | 74 |
| Vertical tabs set | ESC B | 66 |
| Vertical tab | VT | 11 |

## Printing in Color

The IBM Personal Computer Color Printer is capable of printing in 8 colors when the process color ribbon is used. The 4 colors of the ribbon are selected by: ESC b (Select Band 4) for black, ESC c (Select Band 3) for cyan, ESC m (Select Band 2) for magenta, and ESC y (Select Band 1) for yellow. You can print four additional colors, orange, green, violet, and brown, by printing the data twice. Print the data in one color and then print over the data in a second color according to the table below. When printing data twice to mix colors, always print the lighter color first to avoid contaminating the ribbon.

## Color Desired Ribbon Bands to Mix

| Orange | Bands 1 (ESC y) and 2 (ESC m) |
| :--- | :--- |
| Green | Bands 1 (ESC y) and 3 (ESC c) |
| Violet | Bands 2 (ESC m) and 3 (ESC c) |
| Brown | Bands 2 (ESC m) and 4 (ESC b) |

To mix colors, data must be sent to the printer in the following order: printer control code to select the first color, data to be printed, carriage return with no line feed, printer control code to select the second color, repeat the data to be printed. For example, to print "IBM Personal Computer" in green, you must; select band 1 (yellow) with ESC y, print "IBM Personal Computer", return the carriage with no line feed with ASCII decimal value 141 from "Character Set 1," select band 3 (cyan) with ESC c, and print "IBM Personal Computer." To do this, type the following:

LPRINT CHR \$(27);CHR\$(121);'IBM Personal Computer"; CHR \$(141);CHR\$(27);CHR\$(99;)'IBM Personal Computer"

Note: The above example is for use with "Character Set 1."

## Color Printer Character Set 1



## Color Printer Character Set 1 (Continued)



Color Printer Character Set 2


Color Printer Character Set 2 (Continued)


## All Printable Characters



All Printable Characters (Continued)


## DIP-Switch Settings

Many of the printer functions can be manually set with a 10 -position dual in-line package (DIP) switch. Although these same functions are programmable, the printer defaults to the values set by the DIP switch.

The DIP switches must be set prior to switching the printer's power to On. The printer logic reads the DIP-switch settings only at power-on or printer initialization.

Note: Some programs use the control codes in Character Set 1 that have ASCII decimal values above 128. These control codes are not in Character Set 2. The use of Character Set 2, therefore, may not give the desired results with some programs.

The charts on the following page describe the functions available through the DIP-switch settings.


| Switch | Setting | Function |
| :--- | :--- | :--- |
| 1 | On | Selects Character Set 2 (see "Character Set <br> $\left.2^{\prime \prime}\right)($ see "Note" below) |
| 1 | Off | Selects Character Set 1 (see "Character Set 1") |
| 2 | On | Sets line spacing to 8 lines per inch |
| 2 | Off | Sets line spacing to 6 lines per inch |
| 3 | On | Sets automatic 1-inch perforation skip |
| 3 | Off | No automatic perforation skip |
| 4 | On | Sets automatic line feed on carriage return |
| 4 | Off | No automatic line feed on carriage return |
| 5 | On | Sets printer to a 13.2-inch print line |
| 5 | Off | Sets printer to an 8-inch print line. |
| 6 | On | Selects 12-inch page length |
| 6 | Off | Selects 11-inch page length |
| 7 | On | Sets automatic ribbon-band shift (use with <br> all-black ribbon) |
| 7 | Off | No automatic ribbon-band shift (use with color) |
| 8 | On | Does not allow audible alarm to sound |
| 8 | Off | Allows audible alarm to sound |

## DIP-Switch Settings - 1 Through 8

| Switch 9 | Switch 10 | Quality and Spacing Set |
| :--- | :--- | :--- |
| Off | Off | Data processing quality, 12 characters per <br> inch, (see "Note" below) |
| Off | On | Data processing quality, 10 characters per <br> inch |
| On | Off | Text quality, 10 characters per inch |
| On | On | Near letter quality, 10 characters per inch |

DIP-Switch Settings - 9 and 10

Switches 9 and 10 select the printing quality and character spacing. See "ESC I" in "Printer Control Codes" for a description of the printing qualities.

Note: When switches 9 and 10 are Off, the printer prints with a 1 -inch page length with no perforation skip. Switches 3 and 6 are overridden. This is the self-test setup.

## Interface

Specifications:

- Data transfer rate: 1000 CPS (max.)
- Synchronization: By externally supplied STROBE pulses.
- Handshaking: -ACKNLG or +BUSY signals.
- Logic level: Input data and all interface control signals are TTL-compatible.
- Connector type: 57-30360 (AMPHENOL), or equivalent, 36-pin connector on printer end of cable.


## Data Transfer Sequence:



## Parallel Interface Timing Diagram

## Specifications

| Size |  |
| :--- | :--- |
| Height | $24.4 \mathrm{~cm}(10 \mathrm{in})$. |
| Width | $57.8 \mathrm{~cm}(22.75 \mathrm{in})$. |
| Depth | $35.43 \mathrm{~cm}(14 \mathrm{in})$. |
| Weight | $18.4 \mathrm{~kg}(40 \mathrm{lb})$ |
|  |  |
| Power Cable | $1.98 \mathrm{~m}(6.5 \mathrm{ft})$ |
| Length | 28 AWG |
| Size |  |
| Signal Cable | $1.89 \mathrm{~m} \mathrm{(6} \mathrm{ft)}$ |
| Length | 3 by 18 AWG |
| Size |  |

## Physical Specifications

| Voltage (Vac) |  | Frequency <br> $(\mathrm{Hz})$ | Current <br> (Amps) | Power <br> (Watts) |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Nominal | Minimum | Maximum | $\pm 3 \mathrm{~Hz}$ | Maximum | Maximum |
| 100 | 90 | 118 | $50 / 60$ | 1.5 | 135 |
| 120 | 102 | 139 | 60 | 1.5 | 135 |
| 200 | 180 | 236 | $50 / 60$ | 1.0 | 135 |
| 220 | 190 | 264 | $50 / 60$ | 1.0 | 135 |

## Electrical Specifications

| Print Method | Wire matrix |
| :---: | :---: |
| Print Speed |  |
| Data Processing Quality | 200 cps |
| Text Quality | 110 to 150 cps |
| Near Letter Quality | 30 to 40 cps |
| Print Direction | Bidirectional with logic seeking |
| Number of Pins in Head | 9 (4- and 5-column arrangement) |
| Size of Pins in Head | . $356-\mathrm{mm}$ (0.014-in.) wire diameters |
| Line Spacing | 4.23 mm (1/6 in.) or programmable |
| Printing Characteristics |  |
| Matrices | Data processing: $9 \times 9$ |
|  | Near-letter: $36 \times 18$ |
|  | Block graphic: $24 \times 14$ |
| Character Sets | See "Color Printer Character Sets" 1 and 2. |
| Printing Sizes |  |
|  | Characters Maximum <br> characters <br> per inch per line |
| Normal | 10132 |
| Double Width | 566 |
| Compressed | 17.1 225.7 |
| Double Width-Compressed | 13.3 ) 175.5 |
| Proportional | 12 (average) 158.4 (average) |
| Subscript | 10132 |
| Superscript | 10132 |
| Media Handling |  |
| Paper Feed | Forms tractor feed and friction feed |
| Speed | 127 mm ( 5.0 in.$)$ per second |
| Paper Width Range |  |
| Forms tractor feed | 76.2 to 406.4 mm ( 3 to 16 in .) |
| Friction feed | 177.8 to 304.8 mm ( 7 to 12 in .) |
|  | ( 216 to 432 mm ( 8.5 to 17 in .) |
| Paper Weight |  |
| Continuous forms | Single part: 15 to 20 lb bond <br> Multipart: 12 to $15 \mathrm{lb}, 6$ to 8 lb carbon |
| Single sheet | 15 to 20 lb bond |

## Printer Specifications (Part 1 of 2)

| Media Handling (continued) |  |  |
| :---: | :---: | :---: |
| Copies |  |  |
| Continuous forms | 1 to 4 parts |  |
| Single sheet | 1 part only |  |
| Paper Path |  |  |
| Continuous forms | Front, bottom, and rear |  |
| Single sheet | Front |  |
| Interfaces | Standard <br> Data and |  |
| Inked Ribbon |  |  |
| Type | Cartridge (all ribbons) |  |
| Color |  |  |
| Process Ribbon | COLOR | BAND |
|  | Yellow | 1 |
|  | Magenta | 2 |
|  | Cyan | 3 |
|  | Black | 4 |
| Primary Ribbon | COLOR | BAND |
|  | Red | 1 |
|  | Green | 2 |
|  | Blue | 3 |
|  | Black | 4 |
| Environmental Conditions |  |  |
| Operating Temperature | 10 to $40^{\circ} \mathrm{C}\left(50\right.$ to $\left.104^{\circ} \mathrm{F}\right)$ 10 to $80 \%$ non-condensing |  |
| Operating Humidity |  |  |
| Heat Output | $140 \mathrm{BTU} / \mathrm{hr}$ (maximum) |  |
| Memory Allocation |  |  |
| Internal | 2K bytes |  |
| Data | 6K bytes |  |
| Reserved | 8 K bytes |  |
| Total | 16 K bytes |  |

## Printer Specifications (Part 2 of 2)

## Connector Pin Assignments

Printer connector-pin assignments and descriptions of signals are provided in the following chart.

| Connector Pin Assignment |  |  |
| :---: | :---: | :---: |
| Signal Pin No. | Signal | Description |
| 1 | -STROBE | -STROBE pulse to read data in. Pulse width must be more than $0.5 \mu \mathrm{~s}$ at receiving terminal. The signal level is normally high (logical 1); data is read at the low (logical 0) level. |
| 2 | DATA 1 | These signals represent information of the 1st to 8th bits of parallel data respectively. |
| 3 | DATA 2 |  |
| 4 | DATA 3 |  |
| 5 | DATA 4 |  |
| 6 | DATA 5 |  |
| 7 | DATA 6 |  |
| 8 | DATA 7 |  |
| 9 | DATA 8 |  |
| 10 | -ACKNLG | Approx. $0.5 \mu \mathrm{~s}$ pulse. A low signal indicates that the printer is ready to accept other data. |
| 11 | + BUSY | A high signal indicates that the printer cannot receive data. The signal becomes high in the following cases: <br> 1. During data entry <br> 2. During printing operation <br> 3. In offline state <br> 4. During printer error status |
| 12 | + PE | A high signal indicates that the printer is out of paper. |
| 13 | $\begin{aligned} & \hline+ \text { SLCT } \\ & \text { (ENABLE) } \end{aligned}$ | A high signal indicates that the remote control select feature has not deselected the printer. The signal level goes high upon going ready or receiving a DC 1 (SELECT). If currently ready but deselected, it goes low upon receiving a DC 3 (DESELECT). |
| 14 | -AUTO FEED | Not used |
| 15 |  | Not used |
| 16 | Ov | Logic GND level. |

Connector Pin Assignment (Part 1 of 2)

| Connector Pin Assignment |  |  |
| :---: | :--- | :--- |
| Signal Pin <br> No. | Signal | Description |
| 17 | CHASSIS <br> GND | Printer chassis ground (GND). In the <br> printer, the chassis GND and the logic <br> GND are isolated from each other. |
| 18 |  | Not used |
| $19-30$ | GND | TWISTED-PAIR RETURN logic GND <br> level. |
| 31 | -INIT | When the level of this signal becomes <br> low, the printer controller is reset to <br> its initial state, and the print buffer is <br> cleared. This signal is normally at high <br> level, and its pulse width must be more <br> than 50 $\mu$ at the receiving terminal. |
| 32 | -ERROR | The level of this signal becomes low <br> when the printer is in: <br> 1. Paper Out state <br> 2. Offline state <br> 3. Error state |
| 33 | GND | TWISTED-PAIR return logic GND level. |
| 34 |  | Not used |
| 35 |  | Not used |
| 36 |  | Not used |

## Connector Pin Assignment (Part 2 of 2)

## Notes:

1. All interface conditions are based on TTL-level signals. The rise and fall time of each signal must be less than 0.2 microseconds.
2. Data must not be transmitted until the -ACKNLG signal and +BUSY signal go low.

52 Color Printer



Color Printer - Color Shift (Sheet 1 of 1)



Color Printer - Controller Board (Sheet 1 of 3)


Color Printer - Controller Board (Sheet 2 of 3)


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Personal Computer Hardware Reference Library

## IBM PC Compact Printer

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## Description

The IBM PC Compact Printer is a stand-alone, tabletop unit that plugs into a standard, $120-$ Vac wall outlet. Using a print head with eight print elements and thermal-sensitive paper, the printer can print characters from the standard ASCII, 96-character, uppercase and lowercase character set, and prints the characters in a 5-by- 8 dot matrix at 50 characters per second (cps). The printer prints in one direction (left-to-right) and has four print modes. In the standard mode, the printer prints 80 characters per line; in the compressed mode, 136 characters per line; in the double-width mode, 40 characters per line, and in the compressed double-width mode, 66 characters per line. The IBM PC Compact Printer can also underline characters, has an extended character set for international languages, and can accept special characters in all-points-addressable mode to do graphics or draw special characters under program control.

The printer has a 1.89 meter ( 6 -foot), 16 -lead, printer cable. This cable connects to the $25-\mathrm{pin}$ D-shell connector of an Asynchronous Communications Adapter (primary or alternate) through the use of the IBM PC Compact Printer Connector Adapter.

The following is a block diagram of the IBM PC Compact Printer.


Compact Printer Block Diagram

## Programming Considerations

## Printer Control Codes

The following pages list, in alphabetic order, the printer control codes with a description of each. Some knowledge of BASIC programming is necessary to insert printer control codes in your program. An example of each code in BASIC is given at the end of each description. The "Format" information is given where more information is needed for programming considerations.

| Printer <br> Code | Printer Function |
| :--- | :--- |
| CAN | Cancel <br> Clears the printer memory of all data waiting to be printed <br> following the last-received line-ending code. Resets the <br> printer to the power-on defaults. <br> Example: <br> LPRINT CHR\$(24); <br> Carriage Return <br> Causes the printer to print the data that follows CR <br> beginning at the left margin. No line-feed operation takes <br> place unless ESC 5;1 (Automatic Line-Feed) has been sent. <br> Notes: |
| $\quad$1. IBM Personal Computer BASIC (and many other <br> programs) automatically sends LF (line feed) with CR. <br> 2. If no data precedes the CR, or if all <br> preceding data is spaces, the printer does not <br> carriage return. If automatic line feed is On, <br> the paper is advanced one line space. |  |
| Example: |  |
| LPRINT CHR\$(13); |  |
| Device Control 2 (Compressed Off) |  |
| Ends printing in the Compressed mode. |  |
| Example: |  |
| LPRINT CHR\$(18); |  |
| Device Control 4 (Double Width Off) |  |
| Devds printing in the Double Width mode. |  |
| Example: |  |
| LPRINT CHR\$(20); |  |
| Escape |  |
| Sets the printer to accept the next data sent as a printer |  |
| command. (See the following list.) |  |
| Example: |  |
| LPRINT CHR\$(27); |  |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC B | Escape B (Set Vertical Tabs) <br> Format: ESC B; $n_{1} ; \mathrm{n}_{2} ; \ldots \mathrm{n}_{64} ; \mathrm{NUL}$; <br> Sets the vertical tab-stop positions. The power-on default is no vertical tab stops set. $n_{1}$ through $n_{64}$ represent tab-stop positions by line number. The topmost line of the page is line 0 . Tab-stop positions must be received in ascending numeric order and cannot exceed the set page length. Up to 64 positions are recognized by the Compact Printer. The positions do not take effect until NUL is received. Once vertical tab stops are set, they remain in effect until new ones are specified or all tab stops are set to the power-on defaults by ESC R (Clear Tabs). (If the printer is reset or switched Off, set tab stops are cleared.) If no vertical tab stops are set, the Vertical Tab (VT) command behaves as a Line Feed (LF) command. ESC B followed only by NUL clears all vertical tab stops. The form length must be set by the ESC C command (Set Lines per Page) prior to setting vertical tab stops. <br> Example: <br> LPRINT CHR\$(27);CHR\$(66);CHR\$( $n_{1}$ ); <br> CHR $\$\left(n_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{n}_{64}\right) ; \mathrm{CHR} \$(0)$; |
| ESC C | Escape C (Set Lines per Page) <br> Format: ESC C;n; <br> Sets the page length in number of lines ( n ). The ESC C command must be followed by a value to specify the length of page desired. (Maximum form length for the printer is 127 lines.) The printer default is 66 lines per page when switched On or reset. <br> Example: <br> LPRINT CHR $\$(27) ; \mathrm{CHR} \$(67) ; \mathrm{CHR} \$(\mathrm{n})$; |
| ESC D | Escape D (Set Horizontal Tab Stops) <br> Format: ESC D; $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \ldots \mathrm{n}_{28} ; \mathrm{NUL}$; <br> Sets the horizontal tab-stop positions represented by $n_{1}$ through $n_{28}$. The power-on default is a tab stop set at column 8 and every eighth column thereafter. The printer recognizes up to 28 horizontal tab stops. They must be in ascending numeric order and followed by NUL. Tab stops can be set between 1 and 80 in standard print mode; between 1 and 136 in compressed print mode. ESC D immediately followed by NUL will clear all horizontal tabs. ESC R (Clear Tabs) may be used to set horizontal tabs to the power-on default. <br> Example: <br> LPRINT CHR\$(27);CHR\$(68);CHR\$( $n_{1}$ ); <br> CHR $\$\left(\mathrm{n}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{n}_{28}\right) ; \mathrm{CHR} \$(0)$; |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC K | Escape K ( 560 Bit-Image Graphics Mode) <br> Format: ESC K; $\mathrm{n}_{1} ; \mathrm{n}_{2} ; \mathrm{v}_{1} ; \mathrm{v}_{2} ; \ldots \mathrm{v}_{560}$; <br> Changes the printer to the Bit-Image Graphics mode. Dot density is 70 by 70 dots per inch. If the graphics data exceeds the space remaining on the line, the printer ignores the excess data. 7 bytes of bit-image data equal 1 standard-width character. <br> $n_{1}$ and $n_{2}$ are binary numbers that specify the number of bit-image data bytes to be transferred. $n_{1}$ represents values from 0 to 255, and $n_{2}$ represents values from 0 to 2 times 256. The total number of bit-image data bytes is equal to $n_{1}+\left(n_{2} \times 256\right)$ and cannot exceed 560 . <br> All eight of the print-head thermal dots are used to print bit-image graphics. $\mathrm{v}_{1}$ through $\mathrm{v}_{560}$ are bit-image data bytes, each of which represents a set of 8 printable dots in a vertical line. The horizontal position of these 8 dots is determined by the position of the bit-image data byte within the $v_{1}$ through $v_{560}$ series. $v_{1}$ is printed at the starting position followed in order from left to right by $\mathrm{v}_{2}$ through $\mathrm{v}_{560}$. <br> Each bit of a bit-image data byte represents a vertical dot position at the horizontal position represented by that bit-image data byte. The lowest value, or least significant bit (bit 0), represents the bottom dot position, and the highest value, or most significant bit (bit 7), represents the top dot position. <br> In the following table the left-hand column of ( $\cdot$ )'s represents dot positions within a vertical line. The right-hand column shows the corresponding bit number within a bit-image data byte. (The bits are numbered 7 through 0 , from left to right.) <br> For example, if $v_{1}$ is binary 10000000 (decimal 128), only the top dot prints in that horizontal position; if $\mathrm{v}_{1}$ is binary 00000001 (decimal 01), only the bottom dot prints; and if $\mathrm{v}_{1}$ is binary 11111111 (decimal 255), all eight dots print. <br> Example: <br> LPRINT CHR\$(27);CHR\$(75);CHR\$( $\mathrm{n}_{1}$ ); <br> CHR\$ $\left(\mathrm{n}_{2}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{1}\right) ; \mathrm{CHR} \$\left(\mathrm{v}_{2}\right) ; \ldots \mathrm{CHR} \$\left(\mathrm{v}_{560}\right)$; |


| Printer Code | Printer Function |
| :---: | :---: |
| ESC N | Escape N (Set Skip Perforation) <br> Format: ESC N;n; <br> Specifies the number of lines to be skipped at the end of each page. This causes the printer to automatically skip over the perforation between pages of continuous forms. The number of lines $n$, is converted to inches using the line-spacing in effect. The value of $n$ must be between 1 and 127. ESC $N$ must be reset anytime the page length (ESC C) is changed. The default for skip perforation is 25.4 mm ( 1 in .). Example: <br> LPRINT CHR\$(27);CHR\$(78);CHR\$(n); |
| ESC 0 | Escape 0 (Cancel Skip Perforation) Cancels the Skip Perforation function. Example: <br> LPRINT CHR\$(27);CHR\$(79); |
| ESC R | Escape R (Clear Tabs) <br> Resets all tab stops, both horizontal and vertical, to the power-on defaults. <br> Example: <br> LPRINT CHR\$(27);CHR\$(82); |
| ESC W | Escape W (Continuous Double-Width Print) <br> Format: ESC W;n; <br> Changes the printer to double-width printing when ESC W is followed by 1 . This mode is not canceled by a line feed or DC4. It is canceled when ESC $W$ is followed by 0 (zero). <br> Example: <br> LPRINT CHR\$(27);CHR\$(87);CHR\$(n); |
| ESC 0 | Escape Zero (1/9-Inch Line Feed) <br> Changes the line feed to 2.82 mm ( $1 / 9 \mathrm{in}$.). This produces 9 lines per inch. <br> Example: <br> LPRINT CHR\$(27);CHR\$(48); |
| ESC 1 | Escape One (1/9-Inch Line Feed) <br> Changes the line feed to 2.82 mm ( $1 / 9 \mathrm{in}$.). This produces 9 lines per inch. ESC 1 functions the same as ESC 0. <br> Example: <br> LPRINT CHR\$(27);CHR\$(49); |
| ESC 2 | Escape Two (1/6-Inch Line Feed) <br> Resets line spacing to 4.23 mm ( $1 / 6 \mathrm{in}$.). This produces 6 lines per inch and is the power-on default for vertical line spacing. <br> Example: <br> LPRINT CHR\$(27);CHR\$(50); |


| Printer <br> Code | Printer Function |
| :---: | :---: |
| ESC 5 | Automatic Line Feed <br> Format: ESC 5;n; <br> When $n$ is 1 , automatic line feeding starts; the printer will line-feed each time a code that indicates the end of a line, such as CR, is received. When n is 0 , automatic line feeding stops. <br> Example: <br> LPRINT CHR\$(27);CHR\$(53); |
| ESC - | Escape Minus (Underline) <br> Format: ESC -;n; <br> ESC - followed by 1 , causes all of the following data to be printed with an underline. ESC - followed by 0 (zero), cancels the underlining. <br> Example: <br> LPRINT CHR\$(27);CHR(45);CHR\$(n); |
| ESC < | Escape Less Than (Home Head) <br> Returns the print head to the left margin to print the line following ESC < . This occurs for one line only. <br> Example: <br> LPRINT CHR\$(27);CHR\$(60); |
| FF | Form Feed <br> Advances the paper to the top of the next page. The location of the paper, when the printer Power switch is set to On, is the top-of-page position. The next top-of-page is determined by the form length as defined by the power-on default, 279 mm ( 11 in. ), or as set by ESC C. Always separate multiple Form Feed commands with spaces. Example: <br> LPRINT CHR\$(12); |
| HT | Horizontal Tab <br> Causes the carriage to move to the next horizontal tab stop. Tab stops are set with ESC D. A horizontal tab stop every 8 columns is the power-on default. <br> Example: <br> LPRINT CHR\$(9); |
| LF | Line Feed <br> Advances the paper one line space. Line spacing is 4.23 mm ( $1 / 6$ in.) unless reset by ESC 0, ESC 1 , or ESC 2. <br> Example: <br> LPRINT CHR\$(10); |
| NUL | Null <br> Used with control commands as a command list terminator. <br> NUL is also used with some printer control codes to select options. <br> Example: <br> LPRINT CHR\$(0); |


| Printer <br> Code | Printer Function |
| :--- | :--- |
| SI | Shift In (Compressed On) <br> Causes the printer to begin compressed printing. This <br> command is canceled by DC2 (Compressed Off). <br> Example: <br> LPRINT CHR\$(15); <br> SO <br> Shift Out (Double Width) <br> Causes the printer to start double-width printing. <br> Double-width printing prints the characters twice as wide as <br> the current character spacing. This results in half as many <br> characters per inch. A Carriage Return, Line Feed or DC4 <br> (Double Width Off) cancels the SO command. <br> Example: <br> LPRINT CHR\$(14); <br> Vertical Tab <br> Advances the paper to the next vertical tab-stop position. If <br> no vertical tab stops are set, the VT command is treated as a <br> line-feed (LF) command. Vertical tab stops are set with <br> ESC B. <br> Example: <br> LPRINT CHR\$(11); |

## Printer Control Code Quick Reference

Note: ASCII values greater than 27 must be preceded by the ESC code (ASCII value 27).

| Description | Code | ASCII <br> Value |
| :--- | :--- | ---: |
|  |  |  |
| Cancel | DC2 | 24 |
| Carriage return | CR | 13 |
| Compressed character off | DC2 | 18 |
| Double width off | DC4 | 20 |
| Escape | ESC | 27 |
| Vertical tab set | ESC B | 66 |
| Lines per page set | ESC C | 67 |
| Horizontal tab stops set | ESC D | 68 |
| Graphics mode (bit-image) | ESC K | 75 |
| Skip perforation | ESC N | 78 |
| Cancel skip perforation | ESC O | 79 |
| Tabs clear | ESC R | 82 |
| Double width (multiple lines) | ESC W | 87 |
| Line feed (2.82 mm (1/9 in.)) | ESC 0 | 48 |
| Line feed (2.82 mm (1/9 in.)) | ESC 1 | 49 |
| Line feed (4.23 mm (1/6 in.)) | ESC 2 | 50 |
| Line feed (automatic) | ESC 5 | 53 |
| Underline | ESC - | 45 |
| Home head | ESC < | 60 |
| Form feed | FF | 12 |
| Tab (horizontal) | HT | 9 |
| Line feed | LF | 10 |
| Null | NUL | 0 |
| Compressed character | SI | 15 |
| Double width | SO | 14 |
| Tab (vertical) | VT | 11 |
|  |  |  |

## Print Mode Combinations

The following figure shows the print-mode combinations possible with the IBM PC Compact Printer. Modes shown with XXX in the same column can be combined.

A print mode can be changed at any time within a line; however, the double-width mode affects the entire line.

| Allowable Mode Combinations |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: |
| Standard | XXX |  |  |  |  |  |  |
| Compressed |  | XXX |  | XXX | XXX |  |  |
| Double-Width |  |  | XXX | XXX | XXX |  |  |
| Underline | XXX | XXX | XXX |  | XXX |  |  |

## Allowable Mode Combinations

Compact Printer Character Set


## Compact Printer Character Set (continued)



Compact Printer 13

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## Interface

Specifications:

- Data transfer rate: 1200 bps (maximum)
- Synchronization: Internal clocking
- Handshaking: CTS (Clear to Send) Pacing
- Logic level: Input data and all interface control signals are EIA levels


## Serial Interface Timing Diagram



## Specifications

| Size |  |
| :--- | :--- |
| Height | $88.9 \mathrm{~mm}(3.5 \mathrm{in})$ |
| Width | $312.4 \mathrm{~mm}(12.3 \mathrm{in})$ |
| Depth | $221 \mathrm{~mm}(8.7 \mathrm{in})$ |
| Weight | $3.0 \mathrm{~kg}(6.6 \mathrm{lb})$ |
| Power Cable |  |
| Length | $1.98 \mathrm{~m}(6.5 \mathrm{ft})$ |
| Size | 28 AWG |
| Signal Cable |  |
| Length <br> Size | $1.89 \mathrm{~m}(6 \mathrm{ft})$ |

## Physical Specifications

| Voltage (Vac) |  | Frequency <br> $(\mathrm{Hz})$ | Current <br> (Amps) | Power <br> (Watts) |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Nominal | Minimum | Maximum | $\pm 3 \mathrm{~Hz}$ | Maximum | Maximum |
| 120 | 108 | 132 | 60 | 0.25 | 36 |

## Electrical Specifications

| Print Method | Thermal, non-impact, dot-matrix |  |
| :---: | :---: | :---: |
| Print Speed | 50 cps |  |
| Print Direction | Left to right only |  |
| Print Elements in Head | 8 |  |
| Line Spacing | 4.23 mm (1/6 in.) or 2.82 mm (1/9 in.) |  |
| Printing Characteristics |  |  |
| Matrix | $5 \times 8$ |  |
| Character Set | See "Compact Printer Character Set" tables. |  |
| Graphics | APA (All Points Addressable) |  |
| Printing Sizes |  |  |
|  | Characters per inch | Maximum characters per line |
| Normal | 10 | 80 |
| Double Width | 5 | 40 |
| Compressed | 17.5 | 136 |
| Double Width-Compressed | 8.75 | 66 |
| Media Handling |  |  |
| Paper Feed | Friction feed |  |
| Paper Width | $216 \mathrm{~mm}(8-1 / 2 \mathrm{in} .)$ |  |
| Copies | Single sheet only |  |
| Paper Path | Top |  |
| Interface | Serial data and control lines |  |
| Print Color | Black |  |
| Environmental Conditions |  |  |
| Operating Temperature Operating Humidity | 5 to $40^{\circ} \mathrm{C}$ ( 41 to $104^{\circ} \mathrm{F}$ ) 10 to $80 \%$ non-condensing |  |
| Heat Output | 54.6 BTU/hr (maximum) |  |

## Printer Specifications

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Note: An IBM PC Compact Printer Connector (as shown in the diagram above) is required to connect the Compact Printer to an IBM Asynchronous Communications Adapter (primary or alternate).


Notes:

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Personal Computer Hardware Reference Library

## IBM 5-1/4" Diskette Drive

## Contents

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## Description

The system unit has space and power for one or two 5-1/4 inch diskette drives. A drive can be single-sided or double-sided with 40 tracks for each side. The diskette drive is a self-contained unit consisting of a spindle drive system, a read positioning system, and a read/write/erase system.

The diskette drive uses modified frequency modulation (MFM) to read and write digital data, with a track-to-track access time of 6 milliseconds.

The IBM 5-1/4" Diskette Drive uses a standard 133.4 millimeter ( 5.25 inch) diskette. Single-sided, double-density, soft-sectored diskettes are used for single-sided drives. Double-sided drives use double-sided, double-density, soft-sectored diskettes.

This recording medium is a flexible magnetic disk enclosed in a protective jacket. The protected disk, free to rotate within the jacket, is continuously cleaned by the soft fabric lining of the jacket during normal operation. Read/write/erase head access is made through an opening in the jacket. Openings for the drive hub and diskette index hole are also provided. The following figure is a simplified drawing of the diskette used with the IBM 5-1/4" Diskette Drive.


Recording Medium

To insert a diskette, the operator raises the latch at the front of the diskette drive and inserts the diskette in the slot. Plastic guides in the slot ensure the diskette is in the correct position. Closing the latch centers the diskette and clamps it to the drive hub. After 250 milliseconds, the servo-controlled de motor starts and drives the hub at a constant speed of 300 rpm . The head positioning system, which consists of a 4-phase stepper-motor and band assembly with its associated electronics, moves the magnetic head so it comes in contact with the desired track of the diskette. The stepper-motor and band assembly uses one-step rotation to cause a one-track linear movement of the magnetic head. No operator intervention is required during normal operation. During a write operation, a 0.33 -millimeter ( 0.013 -inch) data track is recorded, then tunnel-erased to 0.30 millimeter ( 0.012 inch). If the diskette is write-protected, a Write Protect sensor disables the drive's circuitry, and an appropriate signal is sent to the interface.

Data is read from the diskette by the data-recovery circuitry, which consists of a low-level read amplifier, differentiator, zero-crossing detector, and digitizing circuits. All data decoding is done by the adapter card.

The diskette drive also has the following sensor systems:

1. The Track 00 switch, which senses when the head/carriage assembly is at track 00.
2. The Index sensor, which consists of an LED light source and phototransistor. This sensor is positioned to generate a digital signal when an index hole is detected.
3. The Write Protect sensor disables the diskette drive's electronic circuits whenever a write-protect tab is applied to the diskette.

For interface information and programming considerations, refer to "IBM 5-1/4" Diskette Drive Adapter" in this manual.

## Specifications

| Size (maximum) |  |
| :---: | :---: |
| Height | 86 mm (3.4 in.) |
| Width | 149 mm ( 5.9 in.$)$ |
| Depth | 203 mm (8.0 in.) |
| Weight | 2.04 kg ( 4.5 lb ) |
| Power | $+12 \mathrm{Vdc} \pm 5 \%$, ( 900 mA average) <br> $+5 \mathrm{Vdc} \pm 5 \%$, ( 600 mA average) |
| Media | Industry-compatible 5-1/4 inch diskette |
| Tracks per Inch | 48 |
| Number of Tracks | 40 |
| Temperature (exclusive of media) |  |
| Operating | 10 to $44^{\circ} \mathrm{C}$ ( 50 to $112^{\circ} \mathrm{F}$ ) |
| Non-operating | -40 to $60^{\circ} \mathrm{C}\left(-40\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Relative humidity (exclusive of media) |  |
| Operating | 20 to 80\% (non-condensing) |
| Non-operating | 5 to 95\% (non-condensing) |
| Seek Time | 6 ms track-to-track |
| Head Settling Time | 15 ms (last track addressed) |
| Error Rate |  |
| Recoverable | 1 per $10^{9}$ bits read |
| Irrecoverable | 1 per $10^{12}$ bits read |
| Seek Errors | 1 per $10^{6}$ seeks |
| Heaci Life | 20,000 hours (normal use) |
| Media Life | $3.0 \times 10^{6}$ passes per track |
| Disk Speed |  |
| Long term | $300 \mathrm{rpm} \pm 1.5 \%$ |
| Instantaneous | $300 \mathrm{rpm} \pm 3.0 \%$ |
| Start Time | 500 ms (maximum) |
| Transfer Rate | 250K bps |
| Recording Mode | MFM |

Mechanical and Electrical Specifications


5-1/4 Inch Diskette Drive - Type 1 (Sheet 1 of 3)

## Logic Diagrams



5-1/4 Inch Diskette Drive - Type 1 (Sheet 2 of 3)


NOTES: UNLESS OTHEFWISE SPECIIIED
RESISTORS ARE IN OHMS. $5^{\circ}{ }^{\circ}, 1 / 4 \mathrm{~W}$
2. $1^{\circ}$ O RESISTORS ARE $1 / 8 \mathrm{WW}$. $5^{\circ}$, $/ 4 \mathrm{~W}$

5-1/4 Inch Diskette Drive - Type 1 (Sheet 3 of 3)


5-1/4 Inch Diskette Drive - Type 2 (Sheet 1 of 2)


5-1/4 Inch Diskette Drive - Type 2 (Sheet 2 of 2)




5-1/4 Inch Diskette Drive - Type 3 (Sheet 3 of 3)

## IBM Slimline Diskette Drive

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## Description

The IBM Portable Personal Computer has space and power for one or two 5-1/4 inch slimline diskette drives. Each drive can use single-sided or double-sided diskettes with 40 tracks on each side. The drive is completely self contained, and consists of a spindle drive system, a head positioning system, and a read/write/erase system.

The recording medium is a flexible magnetic disk enclosed in a protective jacket. The protected disk, free to rotate within the jacket, is continuously cleaned by the soft fabric lining of the jacket during normal operation. Read/write/erase head access is made through an opening in the jacket. Openings for the drive hub and diskette index hole are also provided. The following figure is a simplified drawing of the diskette used with the IBM 5-1/4 Diskette Drive.


Recording Medium

To load a diskette, the operator twists the latch at the front of the diskette drive counter-clockwise and inserts the diskette into the slot. Plastic guides in the slot ensure the diskette is in the correct position. Twisting the latch clockwise centers the diskette and clamps it to the drive hub. After 250 milliseconds, the servo-controlled dc motor starts and drives the hub at a constant speed of 300 rpm .

The diskette drive uses modified frequency modulation (MFM) to read and write digital data with a track to track access time of 6 milliseconds. It reaches operating speed in 0.5 seconds and drives the hub at a constant 300 rpm .

The head positioning system, which consists of a 4-phase stepper-motor and band assembly with its associated electronics, moves the magnetic head so it comes in contact with the desired track of the diskette. The stepper-motor and band assembly uses one-step rotation to cause a one-track linear movement of the magnetic head. No operator intervention is required during normal operation. During a write operation, a 0.33 millimeter ( 0.013 -inch) data track is recorded, then tunnel-erased to 0.30 millimeter ( 0.012 inch). If the diskette is write-protected, a write-protect sensor disables the drives circuitry, and an appropriate signal is sent to the interface.

Data is read from the diskette by the data-recovery circuitry, which consists of a low-level read amplifier, differentiator, zero-crossing detector, and digitizing circuits. All data decoding is done by the adapter card.

## 2 Slimline Diskette Drive

The diskette drive also has the following sensor systems:

- The track 00 switch, which senses when the head/carriage assembly is at track 00.
- The index sensor, which consists of a light emitting diode (LED) light source and phototransistor. This sensor is positioned so that a digital signal is generated when the index hole is detected.
- The write-protect sensor disables the diskette-drive write circuits whenever the diskette has a write-protect tab.

For interface information and programming considerations, refer to "IBM 5-1/4" Diskette Drive Adapter" in this manual.

## Specifications

| Size (maximum) |  |
| :---: | :---: |
| Height | 42 mm (1.6 in.) |
| Width | 146 mm ( 5.8 in .) |
| Depth | 203 mm (8.0 in.) |
| Weight | 1.1 kg ( 2.4 lb ) |
| Power | $\begin{aligned} & +12 \mathrm{Vdc} \pm 5 \% \\ & +5 \mathrm{Vdc} \pm 5 \% \end{aligned}$ |
| Media | Industry-compatible 5-1/4 inch diskette |
| Tracks per Inch | 48 |
| Number of Tracks | 40 |
| Temperature (exclusive of media) |  |
| Operating Non-operating | 10 to $50^{\circ} \mathrm{C}$ (41 to $122^{\circ} \mathrm{F}$ ) <br> -40 to $60^{\circ} \mathrm{C}\left(-40\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Relative humidity (exclusive of media) |  |
| Operating Non-operating | 20 to 80\% (non-condensing) 5 to 95\% (non-condensing) |
| Seek Time | 6 ms track-to-track |
| Head Settling Time | 21 ms (from last step pulse) |
| Error Rate |  |
| Recoverable | 1 per $10^{9}$ bits read |
| Irrecoverable | 1 per $10^{12}$ bits read |
| Seek Errors | 1 per $10^{6}$ seeks |
| Head Life | 20,000 hours (normal use) |
| Media Life | $3.0 \times 10^{6}$ passes per track |
| Disk speed |  |
| Long Term | $300 \mathrm{rpm} \pm 1.5 \%$ |
| Instantaneous | $300 \mathrm{rpm} \pm 3.0 \%$ |
| Start Time | 500 ms (maximum) |
| Transfer Rate | 250K bits/sec |
| Recording Mode | MFM |

## Mechanical and Electrical Specifications

## Logic Diagrams

The following pages contain the logic diagrams for the IBM Slimline Diskette Drive.


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# Double Sided Diskette Drive 

for

## IBM Personal Computer AT ${ }^{\circledR}$ and IBM Personal Computer XT

Notes:

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Notes:

## Description

The IBM Personal Computer Double Sided Diskette Drive is a direct-access device that can store $320 / 360 \mathrm{~Kb}$ of data on a dual-sided 5-1/4 inch diskette. All data format and access control is in the system. The following figure describes the type of diskette required by this drive.

| Characteristic | Requirement |
| :--- | :--- |
| Certification | Double sided |
|  | 48 TPI |
|  | 40 tracks per surface |
|  | Soft Sector |
| Recording density | 5,876 bits per inch |
| Media coercivity | 300 to 350 0ersteds |
| Jacket | Standard 5-1/4 inch |

Diskette Requirements
The signals for operating the diskette drive are generated through the IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter or the IBM Personal Computer Diskette Adapter.

## Interfaces

The diskette drive has two types of interface: control and dc power. The following figure shows the signals and pin assignments for the control interface.

| Signal Name | I/0 | Signal Pin | Ground Pin |
| :--- | :---: | :---: | :---: |
| Reserved | - | 2 | 1 |
| Reserved | - | 4 | 3 |
| -Drive Select 3 | 1 | 6 | 5 |
| -Index | 0 | 7 |  |
| -Drive select 0 | 0 | 1 | 10 |
| -Drive select 1 | 1 | 12 | 11 |
| -Drive select 2 | 1 | 14 | 13 |
| -Motor On | 1 | 16 | 15 |
| -Direction Select | 1 | 18 | 17 |
| -Step | 1 | 20 | 19 |
| -Write Data | 1 | 22 | 21 |
| -Write Gate | 1 | 24 | 23 |
| -Track 00 | 0 | 26 | 25 |
| -Write Protect | 0 | 28 | 27 |
| -Read Data | 0 | 30 | 29 |
| -Side 1 Select | 1 | 32 | 31 |
| Reserved | - | 34 | 33 |

Control Interface (P1/J1)
Following are the signals and pin assignments for the dc power interface.

| Signal Name | Pin |
| :--- | :---: |
| $+12 V d c$ | 1 |
| $+12 V d c$ Return | 2 |
| $+5 V d c$ Return | 3 |
| $+5 V d c$ | 4 |

Power Interface (P2/J2)
All signals operate between +5 Vdc and ground with the following definitions:

Inactive Level: +2.5 to +5.25 Vdc
Active Level: 0.0 to +0.4 Vdc
All outputs from the drive can sink 40 mA at the active level. The system provides pull-up registers.

## Input Signals

All input signals are active when low.

## Drive Select 0 through 3

These '-drive select' signals enable or disable all other drive interface signals, except '-motor on'. When '-drive select' is at the active level, the drive is enabled. When it is at the inactive level, all controlled inputs are ignored, and all drive outputs are disabled. The enabled or disabled condition of the drive is established within 500 nanoseconds after a change to the select input, excluding head-load time and settling times.

## -Motor On

An active level of this signal starts the drive motor. There must be a 750 millisecond delay after '-motor on' becomes active before any read or write operation starts.

## -Direction Select

This signal determines the direction the read/write head moves when the step signal is pulsed. An active level indicates away from the center of the diskette (out); an inactive level indicates toward the center of the diskette (in). Any change in the '-direction select' signal must be made at least 1 microsecond before the leading edge of the step pulse, and at least 1 microsecond after the trailing edge of the step pulse.

## -Step

This signal causes the read/write heads to move in the direction determined by the '-direction select' signal. Motion is started each time the signal changes from an active to inactive level (at the trailing edge of the pulse).

## -Write Data

Each time this signal changes from the inactive to active level, the current through the read/write heads reverses, and writes a data bit. This signal is enabled when '-write gate' is at the active level. A 250 -nanosecond active pulse of this signal causes a bit to be written on the diskette. These pulses may occur with either a 4,6 , or 8 -microsecond spacing ( $\pm 0.5 \%$ ).

## -Write Gate

An active level of this input enables the write current circuits, and the '-write data' input controls the writing of information. Transitions of '-write gate' occur 4 to 8 microseconds before the first significant data bit, and 4 to 8 microseconds after the last significant data bit. After deactivating '-write gate', deactivation of '-drive select' and '-motor on', and changing '-side 1 select' must be delayed 1 millisecond, because the erase head is active for this period.

## -Side 1 Select

This signal determines which side of the two-sided diskette will be used for reading or writing. An inactive level of this signal selects the read/write head on the 0 side of the diskette; an active level selects the 1 side. A 100-microsecond delay must be allowed after switching from one head to the other before starting to read or write.

## Output Signals

## -Index

When the drive senses the index hole in the diskette, it generates a 1 - to 8 -microsecond active pulse on this line.

## -Track 00

An active level of this signal means that the read/write heads are at Track 00 (the outermost track).

## -Write Protect

An active level of this signal means that a diskette without a write-protect notch is in the drive. The drive will not write when a protected diskette is loaded.

## -Read Data

A 250-nanosecond active pulse is provided on this line for each bit detected on the diskette. These pulses may occur with either 4,6 , or 8 -microsecond spacing.

## Drive-In-Use Indicator

The Drive-In-Use indicator lights when the drive is selected.

## Specifications

The following figures show the physical, and performance specifications for this drive.

| Power Dissipation | 11 W (Typical) |
| :---: | :---: |
| Operating Limits |  |
| Ambient Temperature | 10 to 50 Degrees C ( 41 to 114.8 Degress F) 8 to $80 \%$ |
| Relative Humidity | 86.7 to $80 \%$ Cegrees C (84 Degrees F) |
| Non-Operating Limits |  |
| Ambient Temperature | -40 to 60 Degrees C ( -40 to 140 Degrees F) |
| Humidity | No Condensation |
| Mechanical Dimensions Width | 146.0 mm ( 5.8 in.$)$ |
| Height | 41.0 mm ( $1.6 \mathrm{in}$. ) |
| Depth | 203.2 mm ( $8.0 \mathrm{in}$. ) |
| Weight | 1.6 kg ( 3.52 pounds) |

## Physical Specifications

| Capacity Unformatted | 500 Kb |
| :--- | :--- |
| Capacity Formatted |  |
| 9 Sectors Per Track | 368.6 Kb |
| 8 Sectors Per Track | 320.0 Kb |
| Recording density | 5,876 bits per inch |
| Track Density | 48 TPI (tracks per inch) |
| Cylinders | 40 |
| Tracks | 80 |
| Encoding Method | MFM |
| Rotational Speed | $300 \mathrm{RPM} \pm 1.5 \%$ |
| Transfer Rate | 250 K bits per second |
| Latency Average) | 100 ms |
| Access Time: | 81 ms |
| Average | 6 ms |
| Track to Track | 15 ms |
| Settling Time | 0 ms |
| Head Load Time |  |
| Motor Start Time | 500 ms |

## Performance Specifications



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## High Capacity Diskette Drive

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## Description

The IBM Personal Computer AT High Capacity Diskette Drive is a direct-access device that can store 1.2 Mb of data on a dual-sided 5-1/4 inch diskette. All data format and access control is in the system. The following figure describes the type of high-density diskette required by this drive. Diskettes, which meet these specifications may not be used in either a $160 / 180 \mathrm{~Kb}$ or a $320 / 360 \mathrm{~Kb}$ diskette drive.

| Characteristic | Requirement |
| :--- | :--- |
| Certification | Double Sided |
|  | 96 TPI |
|  | 80 Tracks/Surface |
|  | Soft Sector |
| Recording Density | 9,646 Bits Per Inch |
| Media Coercivity | 600 to 650 Oersteds |
| Jacket | Standard 5-1/4 Inch |

## Diskette Requirements

The signals for operating the diskette drive are generated through the IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter.

Note: This drive also can read diskettes formatted for a $320 / 360 \mathrm{~Kb}$ dual-sided drive or a $160 / 180 \mathrm{~Kb}$ single-sided drive.

## Interfaces

The diskette drive has two types of interface: control and dc power. The following show the signals and pin assignments for the control interface.

| Signal Name | I/O | Signal Pin | Ground Pin |
| :--- | :--- | :--- | :--- |
| -Reduced Write | I | 2 | 1 |
| Reserved | - | 4 | 3 |
| -Drive Select 3 | 1 | 6 | 5 |
| -Index | 0 | 8 | 7 |
| -Drive Select 0 | 1 | 10 | 9 |
| -Drive Select 1 | I | 12 | 11 |
| -Drive Select 2 | 1 | 14 | 13 |
| -Motor On | 1 | 16 | 15 |
| -Direction Select | I | 18 | 17 |
| -Step | I | 20 | 19 |
| -Write Data | 1 | 22 | 21 |
| -Write Gate | 1 | 24 | 23 |
| -Track 00 | 0 | 26 | 25 |
| -Write Protect | 0 | 28 | 27 |
| -Read Data | 0 | 30 | 29 |
| -Side 1 Select | 1 | 32 | 31 |
| -Diskette Change | 0 | 34 | 33 |

## Control Interface (P1/J1)

The signals and pin assignments for the dc power interface are as follows:

| Signal Name | Pin |
| :--- | :--- |
| +12 Vdc | 1 |
| +12 Vdc Return | 2 |
| +5 Vdc Return | 3 |
| +5 Vdc | 4 |

DC Power Interface (P2/J2)
All signals operate between +5 Vdc and ground with the following definitions:

Inactive Level: +2.5 to +5.25 Vdc
Active Level: 0.0 to +0.4 Vdc

All outputs from the drive can sink 40 mA at the active level. The system provides pull-up registers.

## Input Signals

Following are descriptions of the input signals.

## -Reduced Write

The inactive state of this signal indicates that high-density media is present requiring normal write currents, and the active state indicates low-density media is present, requiring a reduced write current.

## -Drive Select 0, 1, 2, and 3

The Drive Select signals enable or disable all other drive interface signals, except '-motor on'. When '-drive select' is at the active level, the drive is enabled. When it is at the inactive level, all controlled inputs are ignored, and all drive outputs are disabled. The enabled or disabled condition of the drive is established within 500 nanoseconds after a change to the '-drive select ' input, excluding head-load time and settling time.

## -Motor On

The spindle motor runs when this input is active. The drive requires a 750 millisecond delay after '-motor on' becomes active before a read or write operation.

## -Direction Select

If this input is at a inactive level the '-step' input signal moves the heads away from the drive spindle. An active level causes the opposite. This input is stable for a minimum of 1 microsecond before and after the trailing edge of the step pulse.

A 1-microsecond active pulse on this input causes the read/write heads to move one track. The state of '-Direction Select' at the trailing edge of the Step pulse determines the direction of motion.

## -Write Data

A 150-nanosecond pulse on this input causes a bit to be written on the disk if '-Write Gate' is active. These pulses may occur with either a $2,3,3.3,4,5$, or 6.67 -microsecond spacing $\pm 0.5 \%$. When Write Gate is inactive, pulses do not appear on this input.

## -Write Gate

An active level of this input enables the write current circuits, and the '-Write Data' input controls the writing of information. Transitions of this line occur 4 to 8 microseconds before the first significant data bit, and 4 to 8 microseconds after the last significant data bit. Making this input inactive removes all current from the read/write heads and allows the read circuits to operate within 590 microseconds. All motor-start, head-settle, and head-load times are complied with before the line becomes active.

## -Side 1 Select

This signal determines which side of the two-sided diskette will be used for reading or writing. An inactive level of this signal selects the read/write head on the 0 side of the diskette; an active level selects the 1 side. A 100-microsecond delay must be allowed after switching from one head to the other before starting to read or write.

## Output Signals

Following are descriptions of the output signals.
-Index
When a diskette's index hole aligns with the hole in the diskette jacket, a 1- to 8-millisecond active pulse is generated on this line.

## -Track 00

This signal is active when the upper head is on Track 00.

## -Write Protect

An active level of this signal means that a diskette without a write-protect notch is in the drive. The drive will not write when a protected diskette is loaded.

## -Read Data

Each bit detected provides a 150-nanosecond active pulse on this line. These pulses may occur with either a $2,3,3.33,4,5$, or 6.67 -microsecond spacing $\pm 0.5 \%$.

## -Diskette Change

This output is active unless a diskette is present and a step pulse is received when the drive is selected.

## Drive-in-Use Indicator

The Drive-in-Use indicator lights when the drive is selected.

## Specifications

The following figures show the physical and performance specifications for this drive.

| Power Dissipation | 11 W (TYP) |
| :--- | :--- |
| Operating Limits | Ambient Temperature 5 to 46 Degrees |
|  | Celsius (41 to 114.8 Degrees Fahrenheit) |
|  | Relative Humidity 20 to 80 \% |
|  | Maximum Wet Bulb 29 Degrees Celsius (84 |
|  | Degrees Fahrenheit) |
| Ambient Temperature -40 to 60 Degrees |  |
|  | Cen-operating Limits (-40 to 140 Degrees Fahrenheit) |
|  | Cumidity no Condensation |
|  | Hechanical Dimensions |
|  | Width $146.0 \mathrm{~mm}(5.8 \mathrm{in})$ |
|  | Height $41.0 \mathrm{~mm}(1.6 \mathrm{in})$ |
|  | Depth $203.2 \mathrm{~mm}(8 \mathrm{in})$ |
|  | 1.6 kg |

## Physical Specifications

| Capacity Unformatted | 1604 Kb |
| :--- | :--- |
| Capacity Formatted |  |
| 15 Sectors Per Track | 1.2 Mb |
| Recording Density | 9646 Bits Per Inch |
| Track Density | 96 TPI |
| Cylinders | 80 |
| Tracks | 160 |
| Encoding Method | MFM |
| Rotational Speed | 360 RPM |
| Transfer Rate | 500 K Bits /Second |
| Latency (Average) | 83 ms |
| Access Time | 91 ms |
| Average | 3 ms |
| Track to Track | 18 ms |
| Settling Time | 50 ms |
| Head Load Time | 750 ms |
| Motor Start Time |  |

## Performance Specifications

## Logic Diagrams



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## Double Sided Diskette Drive

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Notes:

## Description

The IBM Personal Computer AT Double Sided Diskette Drive is a direct-access device that can store $320 / 360 \mathrm{~Kb}$ of data on a dual-sided $5-1 / 4$ inch diskette. All data format and access control is in the system. The following figure describes the type of diskette required by this drive.

| Characteristic | Requirement |
| :--- | :--- |
| Certification | Double-Sided |
|  | 48 TPI |
|  | 40 Tracks/Surface |
|  | Soft Sector |
| Recording Density | 5876 Bits Per Inch |
| Media Coercivity | 300 to 350 Oersteds |
| Jacket | Standard 5-1/4 Inch |

## Diskette Requirements

The signals for operating the diskette drive are generated through the IBM Personal Computer AT Fixed Disk and Diskette Drive Adapter.

## Interfaces

The diskette drive has two types of interface: control and dc power. The following figure shows the signals and pin assignments for the control interface.

| Signal Name | I/O | Signal Pin | Ground Pin |
| :--- | :--- | :--- | :--- |
| Reserved | - | 2 | 1 |
| Reserved | - | 4 | 3 |
| -Drive Select 3 | 1 | 6 | 5 |
| -Index | 0 | 8 | 7 |
| -Drive Select 0 | 1 | 10 | 9 |
| -Drive Select 1 | 1 | 12 | 11 |
| -Drive Select 2 | 1 | 14 | 13 |
| -Motor On | 1 | 16 | 15 |
| -Direction Select | 1 | 18 | 17 |
| -Step | 1 | 20 | 19 |
| -Write Data | 1 | 22 | 21 |
| -Write Gate | 1 | 24 | 23 |
| -Track 00 | 0 | 26 | 25 |
| -Write Protect | 0 | 28 | 27 |
| -Read Data | 0 | 30 | 29 |
| -Side 1 Select | 1 | 32 | 31 |
| Reserved | - | 34 | 33 |

Control Interface (P1/J1)

Following are the signals and pin assignments for the dc power interface.

| Signal Name | Pin |
| :--- | :--- |
| +12 Vdc | 1 |
| +12 Vdc Return | 2 |
| +5 Vdc Return | 3 |
| +5 Vdc | 4 |

Power Interface (P2/J2)
All signals operate between +5 Vdc and ground with the following definitions:

Inactive Level: +2.5 to +5.25 Vdc
Active Level: 0.0 to +0.4 Vdc

All outputs from the drive can sink 40 mA at the active level. The system provides pull-up registers.

## Input Signals

All input signals are active when low.

## Drive Select 0 through 3

These '-drive select ' signals enable or disable all other drive interface signals, except '-motor on'. When '-drive select' is at the active level, the drive is enabled. When it is at the inactive level, all controlled inputs are ignored, and all drive outputs are disabled. The enabled or disabled condition of the drive is established within 500 nanoseconds after a change to the select input, excluding head-load time and settling times.

## -Motor On

An active level of this signal starts the drive motor. There must be a 750 millisecond delay after '-motor on' becomes active before any read or write operation starts.

## -Direction Select

This signal determines the direction the read/write head moves when the step signal is pulsed. An active level indicates away from the center of the diskette (out); an inactive level indicates toward the center of the diskette (in). Any change in the '-direction select' signal must be made at least 1 microsecond before the leading edge of the step pulse, and at least 1 microsecond after the trailing edge of the step pulse.

## -Step

This signal causes the read/write heads to move in the direction determined by the '-direction select' signal. Motion is started
each time the signal changes from an active to inactive level (at the trailing edge of the pulse).

## -Write Data

Each time this signal changes from the inactive to active level, the current through the read/write heads reverses, and writes a data bit. This signal is enabled when '-write gate' is at the active level. A 250 -nanosecond active pulse of this signal causes a bit to be written on the diskette. These pulses may occur with either a 4,6 , or 8 -microsecond spacing ( $\pm 0.5 \%$ ).

## -Write Gate

An active level of this input enables the write current circuits, and the '-Write Data' input controls the writing of information.
Transitions of this line occur 4 to 8 microseconds before the first significant data bit, and 4 to 8 microseconds after the last significant data bit. After deactivating '-write gate', deactivation of '-drive select' and '-motor on', and changing '-side 1 select' must be delayed 1 millisecond, because the erase head is active for this period.

## -Side 1 Select

This signal determines which side of the two-sided diskette will be used for reading or writing. An inactive level of this signal selects the read/write head on the 0 side of the diskette; an active level selects the 1 side. A 100-microsecond delay must be allowed after switching from one head to the other before starting to read or write.

## Output Signals

-Index
When the drive senses the index hole in the diskette, it generates a 1 - to 8 -microsecond active pulse on this line.

## -Track 00

An active level of this signal means that the read/write heads are at Track 00 (the outermost track).

## -Write Protect

An active level of this signal means that a diskette without a write-protect notch is in the drive. The drive will not write when a protected diskette is loaded.

## -Read Data

A 250-nanosecond active pulse is provided on this line for each bit detected on the diskette. These pulses may occur with either 4,6 , or 8 -microsecond spacing.

## Drive-in-Use Indicator

The Drive-in-Use indicator lights when the drive is selected.

## Specifications

The following figures show the physical, and performance specifications for this drive.

| Power Dissipation | 11 W (Typical) |
| :--- | :--- |
| Operating Limits | Ambient Temperature 5 to 46 Degrees C (41 |
|  | to 114.8 Degrees Fahrenheit) |
|  | Relative Humidity 20 to 80 \% |
|  | Maximum Wet Bulb 29 Degrees Celsius (84 |
|  | Degrees Fahrenheit) |
| Non-Operating Limits | Ambient Temperature -40 to 60 Degrees C |
|  | (-40 to 140 Degrees Fahrenheit) |
|  | Humidity no Condensation |
| Mechanical Dimensions | Width $146.0 \mathrm{~mm} \mathrm{(5.8} \mathrm{in)}$ |
|  | Height 41.0 mm (1.6 in) |
|  | Depth $203.2 \mathrm{~mm} \mathrm{(8} \mathrm{in)}$ |
|  | 1.6 kg |

## Physical Specifications

| Capacity Unformatted | 500 Kb |
| :--- | :--- |
| Capacity Formatted: |  |
| $\quad$ 9 Sectors Per Track | 368.6 Kb |
| 8 Sectors Per Track | 320.0 Kb |
| Recording Density | 5876 Bits Per Inch |
| Track Density | 48 TPI |
| Cylinders | 40 |
| Tracks | 80 |
| Encoding Method | MFM |
| Rotational Speed | 300 RPM |
| Transfer Rate | 250 K Bits/Second |
| Latency (Average) | 100 ms |
| Access Time: |  |
| Average | 81 ms |
| Track to Track | 5 ms |
| Settling Time | 20 ms |
| Head Load Time | 50 ms |
| Motor Start Time | 750 ms |

## Performance Specifications

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Double Sided Diskette Drive (Sheet 2 of 2)

Personal Computer Hardware Reference Library

# IBM Personal Computer 3.5"-720KB Diskette Drive 

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Notes:

## Description

The IBM Personal Computer $3.5^{\prime \prime}-720 \mathrm{~KB}$ Diskette Drive is a direct-access device containing a spindle drive system, a head positioning system, and a read/write/erase system. The drive uses double-sided diskettes with 80 tracks on each side. Each diskette has a formatted capacity of 720 K .

## 3.5" Diskette

This diskette is a flexible magnetic disk with a metal hub enclosed in a protective hard plastic cover. The disk is free to rotate within the cover and is continuously cleaned by the cover's soft fabric lining. The diskette's write-protect feature is enabled by sliding the plastic window in the corner of the diskette cover to the open position. A sliding metal cover is provided to protect the diskette when it is out of the drive. The following figure is a simplified drawing of the diskette used with the 3.5"-720KB Diskette Drive.


## Operation

When a diskette is being inserted, metal guides ensure it is in the correct position. The diskette then drops down onto the spindle motor. The spindle motor engages the metal hub of the diskette through a pin-to-hole arrangement called the chucking mechanism. The chucking mechanism provides precise positioning of the diskette. The upper read/write head is then lowered onto the diskette. (The lower head is fixed and does not move vertically.) The spindle system spins the diskette at a constant speed of 300 revolutions per minute (rpm). A sensor generates an index signal once per rotation of the spindle motor. The two read/write heads are positioned over the desired track of the diskette by a stepper motor. One step of the stepper motor results in a one-track linear movement of the read/write heads. An optical sensor generates a signal when the heads are over track 00.

During a write operation, data is provided to the drive in modified frequency modulation (MFM) coded form by a diskette drive adapter.

> Note: Refer to the "System-to-Adapter Compatibility Chart" and "Option-to-Adapter Compatibility Chart" in the front of the Technical Reference Options and Adapters manual for systems and types of diskette drive adapters compatible with this drive.

The read/write heads record a track of 0.115 mm ( 0.0045 in .) nominal width, within a 0.1875 mm ( 0.00738 in .) track pitch. The area between the tracks is erased by an erase head. If the diskette is write-protected, the drive's write-protect sensor inhibits the write operation.

During a read operation, the signal from the head is amplified and filtered by read-recovery circuitry, which consists of a low-level read amplifier, differentiator, zero-crossing detector, and digitizing circuits. The data is then transferred as MFM data to the diskette drive adapter.

To remove a diskette, push the diskette eject button to the rear. This raises the upper head from the diskette, lifts the diskette off the spindle motor, and ejects the diskette approximately 11 mm
(7/16 in.). A signal is sent from the drive to the diskette adapter indicating that the diskette has been ejected. The signal is reset when a diskette is inserted and the diskette drive adapter selects and steps the drive.

## Interface

The diskette drive connects to a diskette drive adapter through an internal, daisy-chained, flat cable (data/control cable). An interface adapter is used to connect the drive's 40-pin edge connector to the 34 -pin data/control cable and the 4 -pin power connector. The following figure shows the signals and pin assignments for the drive's 40-pin edge connector.

Note: Assignments for pins 1 through 34 are the same on both sides of the interface adapter. Pins 37 through 40 go to the 4 -pin power connector.

| Signal Name | 1/0 | Signal Pin | Ground Pin |
| :---: | :---: | :---: | :---: |
| Reserved | - | 2 | 1 |
| Reserved | - | 4 | 3 |
| -Drive Select 3 | 0 | 6 | 5 |
| - Index | 0 | 8 | 7 |
| -Drive Select 0 | I | 10 | 9 |
| -Drive Select 1 | I | 12 | 11 |
| - Drive Select 2 | 1 | 14 | 13 |
| - Motor On | 1 | 16 | 15 |
| - Direction Select | 1 | 18 | 17 |
| -Step | I | 20 | 19 |
| -Write Data | I | 22 | 21 |
| -Write Gate | 1 | 24 | 23 |
| -Track 00 | 0 | 26 | 25 |
| -Write Protect | 0 | 28 | 27 |
| -Read Data | 0 | 30 | 29 |
| -Side 1 Select | 0 | 32 | 31 |
| -Diskette Change | 0 | 34 | 33 |
| Reserved | - | 36 | 35 |
| +5 Vdc +12 Vdc | - | 38 40 | 37 39 |

3.5"- Diskette Interface

A key slot is located between pins 34 and 36 . Pins 35 and 36 are grounded on the drive.


Diskette Drive Interface Adapter

## Input Signals

All input signals are active when low.

## --Drive Select 0 through 3

These '-drive select' signals enable or disable all other drive interface signals, except '-motor on'. When '-drive select' is active, the drive is enabled. When it is inactive, all controlled inputs are ignored, and all drive outputs are disabled. If, at this time, the '-motor on' signal is also inactive, the drive is in low power standby mode. When the drive is not in standby mode, the maximum '-drive select' delay time is 500 nanoseconds. When the drive is in standby mode, all signals except '-track 00 ' and '-write protect' have a maximum delay of 500 nanoseconds.

## -Motor On

An active level of this signal starts the spindle motor. There must be a 750 -millisecond delay after '-motor on' becomes active before a read or write operation starts. When inactive, this signal causes the spindle motor to decelerate and stop.

When this signal is inactive, the '-step' signal moves the heads away from the drive spindle; when active, toward the drive spindle. Any change in the '-direction select' signal must be made at least 1 microsecond before the leading edge of the '-step' pulse, and at least 1 microsecond after the trailing edge of the '-step' pulse.
-Step
A 1-microsecond active pulse of this signal causes the read/write heads to move one track. The state of '-direction select' at the trailing edge of the '-step' pulse determines the direction of motion.

## -Write Data

A 250-nanosecond pulse of this signal causes a bit to be written if '-write gate' is active. These pulses may occur with either a 2,3 , $3.3,4,5$, or 6.67 -microsecond spacing $\pm 0.5 \%$. When '-write gate' is inactive, pulses do not appear on this input.

## -Write Gate

When active, this signal enables the write current circuits, and the '-write data' signal controls the writing of information.
Transitions of this line occur 4 to 8 microseconds before the first significant data bit, and 4 to 8 microseconds after the last significant data bit. Making this signal inactive removes all current from the read/write heads and allows the read circuits to operate within 590 microseconds. All motor-start, head-settle, and head-load times are met before the line becomes active.

## -Side 1 Select

Making this signal active selects the upper head; otherwise the lower head is selected.

## Output Signals

## -Index

When the drive senses an '-Index', it generates a 1- to 8 -microsecond active pulse on this line.

## -Track 00

When active, this signal indicates that the read/write heads are at Track 0 (the outermost track).

## -Write Protect

When active, this signal indicates that a diskette with an open write-protect window (write-protected diskette) is in the drive, and the drive will not write.

## -Read Data

A 250-nanosecond active pulse is provided on this line for each bit detected on the diskette. These pulses may occur with either 4,6 , or 8 -microsecond spacing.

## -Diskette Change

This signal is active unless a diskette is present and a step pulse is received by the diskette adapter when the drive is selected. The presence of a diskette is determined by a media sensor.

## Drive-In-Use Indicator

The Drive-In-Use indicator lights when the drive is selected.

## Specifications

```
Size (maximum)
    Height
    Width
    Depth
Weight
Power
Media
    Capacity Unformatted
    Capacity Formatted
Track Density
Tracks
Number of Heads 2
Transfer Rate 250K bits per second (MFM)
Access Time
    Track-to-Track
    Head Settle Time
    Head Load Time
    Motor Start Time
Temperature
(exclusive of media)
    Operating
    Non-operating
Relative Humidity
(exclusive of media)
    Operating
    Non-operating
Disk Speed
    Long Term
    Instantaneous
Error Rate
    Recoverable
    Irrecoverable
    Seek Errors
Head Life
Media Life
1 per 109 bits read
1 per 1012 bits read
1 per }106\mathrm{ seeks
Approximately 360,000,000 wear
revolutions with less than
10% signal loss
4.0 X 1016 passes per track
```


## Specifications







## Adapter Card

The following is a logic diagram for the Adapter Card.


Adapter Card Logic Diagram

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## IBM 10MB Fixed Disk Drive

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## Description

The IBM 10MB Fixed Disk Drive is a random-access storage device that uses two non-removable 5-1/4 inch disks for storage. Each disk surface employs one movable head to service 306 cylinders. The total formatted capacity of the four heads and surfaces is 10 M bytes ( 17 sectors per track with 512 bytes per sector and a total of 1224 tracks).

An impact-resistant enclosure provides mechanical and contamination protection for the heads, actuator, and disks. A self-contained air recirculating system, which consists of an internal filter and a breather filter, maintains a clean-air environment. Thermal isolation of the stepper and spindle motor assemblies from the disk enclosure results in a very low temperature rise within the enclosure. This isolation provides a greater off-track margin and the ability to perform read and write operations immediately after power-up with no thermal stabilization delay.


Fixed Disk Drive 1

## Specifications

| Size (maximum) |  |
| :---: | :---: |
| Height | 82.55 mm ( 3.25 in .) |
| Width | 146.05 mm ( 5.75 in .) |
| Depth | 203 mm ( 8.0 in .) |
| Weight | 2.08 kg (4.6 lb) |
| Power | $+12 \mathrm{Vdc} \pm 5 \%, 1.8 \mathrm{~A}$ (4.5 A maximum) <br> $+5 \mathrm{Vdc} \pm 5 \%, 0.7 \mathrm{~A}(1.0$ A maximum) |
| Maximum Ripple | 1\% with equivalent resistive load |
| Media | Rigid media disk |
| Track Density | 345 tracks per inch |
| Number of Tracks | 1224 |
| Temperature |  |
| Operating | 4 to $50^{\circ} \mathrm{C}\left(40\right.$ to $122^{\circ} \mathrm{F}$ ) |
| Non-operating | -40 to $60^{\circ} \mathrm{C}\left(-40\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Relative humidity |  |
| Operating | 8 to 80\% (non-condensing) |
| Maximum Wet Bulb | $26^{\circ} \mathrm{C}\left(78^{\circ} \mathrm{F}\right)$ |
| Shock |  |
| Operating | 10 Gs |
| Non-operating | 20 Gs |
| Access Time | $3 \mathrm{~ms} \mathrm{track-to-track}$ |
| Average Latency | 8.33 ms |
| Error Rates |  |
| Recoverable | 1 per $10^{10}$ bits read |
| Irrecoverable | 1 per $10{ }^{12}$ bits read |
| Seek Errors | 1 per $10^{6}$ seeks |
| Design Life | 5 -years (8,000 hours MTF) |
| Disk speed | $3600 \mathrm{rpm} \pm 1 \%$ |
| Transfer Rate | 5.0 M bps |
| Recording Mode | MFM |

## Mechanical and Electrical Specifications


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# IBM Personal Computer 20MB Fixed Disk Drive 

Notes:

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## Description

The IBM Personal Computer 20MB Fixed Disk Drive is a direct-access device that can store up to $20 \mathrm{M}(1 \mathrm{M}=1,048,576$ bytes) of formatted data. The average access time is 85 milliseconds using a servo positioner.

An impact-resistant enclosure provides mechanical and contamination protection for the heads, actuators, and disks. A self-contained air recirculating system, which consists of an internal filter and a breather filter, maintains a clean-air environment. Thermal isolation of the stepper and spindle motor assemblies from the disk enclosure results in a very low temperature rise within the enclosure. This isolation provides a greater off-track margin and the ability to perform read and write operations immediately after power-up with no thermal stabilization delay.


## Interfaces

The interfaces of this drive are divided into three categories: control, data transfer, and dc power.

The control interface is a 34 -pin printed circuit board (PCB) edge connector. The signals and pin assignments are as follows.

| Signal Name | Signal Pin | Ground Pin |
| :---: | :---: | :---: |
| Reserved | 2 | 1 |
| -Head select 2 | 4 | 3 |
| -Write gate | 6 | 5 |
| -Seek complete | 8 | 7 |
| -Track 000 | 10 | 9 |
| -Write fault | 12 | 11 |
| -Head select 0 Reserved | 14 | 13 |
| -Head select 1 | 16 | 15 |
| -Index | 18 | 17 |
| -Ready | 20 | 19 |
| -Step | 22 | 21 |
| -Drive select 1 | 24 | 23 |
| -Drive select 2 | 26 | 25 |
| -Drive select 3 | 28 | 27 |
| -Drive select 4 | 30 | 29 |
| -Direction in | 32 | 31 |

Control Interface

The data transfer interface is a 20 -pin PCB connector. The signals and pin assignments are as follows.

| Signal Name | Signal Pin |
| :--- | :--- |
| -Drive Selected | 1 |
| +MFM Write Data | 13 |
| -MFM Write Data | 14 |
| +MFM Read Data | 17 |
| -MFM Read Data | 18 |
| Grounds | $2,4,6,8,10,11$, |
| Reserved | $3,5,7,9$ |

Data-Transfer Interface
The dc power interface is a 4-pin PCB connector. The signals and pin assignments are as follows.

| Signal Name | Pin |
| :---: | :---: |
| +12 Vdc | 1 |
| +12 Vdc Return | 2 |
| +5 Vdc Return | 3 |
| +5 Vdc | 4 |

DC Power Interface

## Control Input Signals

The control input signals are of two types: those that are multiplexed in a multiple drive system, and those intended to do the multiplexing. These input signals have the following specifications.

- Active=Low=True: 0.0 to 0.4 Vdc at 40 mA
- Inactive $=$ High $=$ False: 2.5 to 5.25 Vdc at 0 mA

The following are descriptions of the control input signals.

## -Write Gate

The active level of this signal allows data to be written on the disk and prohibits any step pulses from moving the heads. The inactive level allows data to be read from the disk, and allows the step pulse to move the heads.

## -Head Select 0, 1, and 2

These three signals enable the selection of each read/write head in a binary-coded sequence. The '-head select 0 ' signal is the least significant. Heads are numbered 0 through 8 . When all head-select signals are inactive, head 0 is selected.

## -Direction In

This signal defines the direction the read/write heads move when '-step' is pulsed. An inactive level defines the direction as out, and if a pulse is applied to '-step', the read/write heads move away from the center of the disk. An active level defines the direction as in, and the read/write heads move toward the center of the disk.

## -Step

This signal causes the read/write heads to move in the direction defined by the '-direction in' signal. The motion starts when the '-step' signal changes from active to inactive (the trailing edge of this signal pulse). Any change in '-direction in' is made at least 100 nanoseconds before the leading edge of the step pulse. This drive supports two methods of stepping or seeking:

| Slow Seek | The read/write heads move at the rate of <br> incoming step pulses. The minimum time <br> between successive steps is 3 milliseconds and the <br> minimum pulse width is 2 microseconds. |
| :--- | :--- |
| Buffered Seek | The adapter's controller may burst step pulses to <br> the drive until the time after the last pulse <br> exceeds 200 microseconds or the maximum |

number of step pulses is received ( 1 for each track). The drive starts motion of the heads after receiving the first step pulse. Step pulses are sent to the drive every 70 to 200 microseconds.

## -Drive Select Signals 1, 2, 3, and 4

When one of these signals is active, it connects that drive to the control lines. The drive select lines are daisy-chained and all drives are jumpered to respond to drive 1.

The fixed disk drive provides a $220 / 230$ ohm termination for a single '-drive select' signal.

## Output Control Signals

The drive control signals are open collector outputs that can sink a maximum of 40 mA in the active state, with a maximum output voltage of 0.4 Vdc . When the output is in the inactive state, the collector's cutoff current is a maximum of 250 microamperes.

## -Seek Complete

This signal goes active when the read/write heads settle on the final track at the end of a seek. Reading or writing is not attempted when '-seek complete' is inactive. The following situations force '-seek complete' inactive:

- When power-on starts a recalibration sequence because the read/write heads are not over track 0
- When less than 2 microseconds have elapsed after the leading edge of a step pulse or a series of step pulses
- If the +5 or +12 Vdc fluctuates or is lost momentarily but restored.

The '-seek complete' signal returns to the active level no later than 100 milliseconds after the trailing edge of the last step pulse.

## -Track 000

This signal is at an active level when the drive's read/write heads are at the outermost track.

## -Write Fault

This signal means that a condition at the drive is causing improper operation of the disk. An active level of this signal prevents further writing and stepping at the drive until drive power is switched off.

This signal goes active when any of the following conditions occur:

- Write current exists in the head without '-write gate' active, or no write current exists in the head with '-write gate' active and '-drive select' active.
- A step pulse is received while '-write gate' is active.
- Multiple heads are selected when '-write gate' is active.
- DC voltages are out of tolerance.
- An off track condition is detected while '-write gate' is active.
- The '-write gate' signal is active when write is disabled by the drive electronics.


## -Index

The drive provides this output signal once each revolution to indicate the beginning of a track. This signal normally is inactive and goes active to indicate an index. Only the change from inactive to active is valid (leading edge of the pulse).

## -Ready

When this signal and '-seek complete' are active, the drive is ready to read, write, or seek, and the I/O signals are valid. An inactive level of this signal prevents all writing and seeking.

The '-ready' signal is inactive four times during drive operation:

- At power-up time, '-ready' remains inactive until:
- Access recalibration to track 0 is complete.
- Spindle speed is stable within $\pm 1.0 \%$ of nominal (10 revolution average).
- Spindle speed deviates $\pm 1.0 \%$ of nominal ( 10 revolution average).
- The '-write fault' signal is active.


## Data-Transfer Signals

All signals associated with the transfer of data between the drive and the system are differential (pairs of balanced signals) and are not multiplexed.

Two pairs of balanced signals are used for the transfer of data: 'write data' and 'read data'. The following describes the data-transfer signals.

## MFM Write Data

This is a differential pair that defines signal shifts written on the track. When ' + MFM write data' goes more positive than '-MFM write data', flux reverses on the track, provided that '-write gate' is active. The system drives '-MFM write data' to an active level when in the read mode.

## MFM Read Data

Read data is sent to the system through the differential pair of 'MFM read data' lines. When '+MFM read data' goes more positive than '-MFM read data', flux reverses on the track of the selected head.

## Specifications - Type 13

| Size (maximum) |  |
| :---: | :---: |
| . Height | 82.5 mm ( 3.25 in.$)$ |
| Width | 146 mm ( $5.75 \mathrm{in}$. ) |
| Depth | 203.2 mm (8.0 in.) |
| Weight | 2.8 kg ( 6.16 lb.$)$ |
| Power | $\begin{aligned} & +12 \mathrm{Vdc} \pm 5 \%, 1.0 \mathrm{~A}(2.0 \mathrm{~A} \text { maximum) } \\ & +5 \mathrm{Vdc} \pm 5 \%, 0.75 \mathrm{~A}(0.8 \mathrm{~A} \text { maximum }) \end{aligned}$ |
| Maximum Ripple (0 to 15 MHz ) | 100 mV , peak-to-peak |
| Media | Rigid media disk |
| Track Density | 350 tracks per inch |
| Number of Tracks | 2448 |
| Formatted Capacity | 21.3 M bytes |
| Bytes/Sector | 512 |
| Sectors/Track | 17 |
| Number of Cylinders | 306 |
| Number of Heads | 8 |
| Temperature |  |
| Operating | 10 to $45^{\circ} \mathrm{C}$ ( 50 to $113^{\circ} \mathrm{F}$ ) |
| Non-Operating | -40 to $65^{\circ} \mathrm{C}\left(-40\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Relative Humidity |  |
| Operating | 8 to 80\% (non-condensing) |
| Non-Operating | 5 to 80\% (non-condensing) |
| Maximum Wet Bulb | $26^{\circ} \mathrm{C}$ ( $78.8{ }^{\circ} \mathrm{F}$ ) (non-condensing) |
| Shock |  |
| Operating | 10 Gs |
| Non-Operating | 25 Gs |
| Access Time |  |
| Track-to-Track | 20 ms (average) |
| Average | 85 ms (traverse 1/3 Tracks) |
| Maximum | 200 ms |
| Average Latency | 8.33 ms |
| Error Rates |  |
| Recoverable <br> (16 retries-soft) | 1 per $10^{10}$ bits read |
| Non-recoverable | 1 per $10^{12}$ bits read |
| Seek Errors | 1 per $5 \times 10^{6}$ seeks |
| Design Life | 5 years ( 20,000 hours MTBF) |
| Disk Speed | $3600 \mathrm{rpm} \pm 0.5 \%$ |
| Transfer Rate | 5.0 M bps |
| Recording Mode | MFM |

## Specifications - Type 13

## Specifications - Type 2

| Size (maximum) |  |
| :---: | :---: |
| Height | 82.5 mm ( $3.25 \mathrm{in}$. ) |
| Width | 146 mm ( $5.75 \mathrm{in}$. ) |
| Depth | 203.2 mm (8.0 in.) |
| Weight | 0.59 kg ( 1.3 lb.$)$ |
| Power | $\begin{aligned} & +12 \mathrm{Vdc} \pm 5 \%, 1.0 \mathrm{~A}(2.0 \mathrm{~A} \text { maximum }) \\ & +5 \mathrm{Vdc} \pm 5 \%, 0.75 \mathrm{~A}(0.8 \mathrm{~A} \text { maximum }) \end{aligned}$ |
| Maximum Ripple (0 to 15 MHz ) | 100 mV , peak-to-peak |
| Media | Rigid media disk |
| Track Density | 580 tracks per inch |
| Number of Tracks | 2460 |
| Formatted Capacity | 20.1 M bytes |
| Bytes/Sector | 512 |
| Sectors/Track | 17 |
| Number of Cylinders | 615 |
| Number of Heads | 4 |
| Temperature |  |
| Operating | 10 to $45^{\circ} \mathrm{C}$ ( 50 to $113^{\circ} \mathrm{F}$ ) |
| Non-Operating | -40 to $65^{\circ} \mathrm{C}\left(-40\right.$ to $\left.140^{\circ} \mathrm{F}\right)$ |
| Relative Humidity |  |
| Operating | 8 to 80\% (non-condensing) |
| Non-Operating | 5 to 80\% (non-condensing) |
| Maximum Wet Bulb | $26^{\circ} \mathrm{C}$ ( $75.8{ }^{\circ} \mathrm{F}$ ) (non-condensing) |
| Shock |  |
| Operating | 10 Gs |
| Non-Operating | 25 Gs |
| Access Time |  |
| Track-to-Track | $20 \mathrm{~ms} \mathrm{(average)}$ |
| Average | 85 ms (traverse 1/3 Tracks) |
| Maximum | 200 ms |
| Average Latency | 8.33 ms |
| Error Rates |  |
| (16 retries-soft) | 1 per $10^{10}$ bits read |
| Non-recoverable | 1 per $10^{12}$ bits read |
| Seek Errors | 1 per $5 \times 10^{6}$ seeks |
| Design Life | 5 years ( 20,000 hours MTBF) |
| Disk Speed | $3600 \mathrm{rpm} \pm 0.5 \%$ |
| Transfer Rate | 5.0 M bps |
| Recording Mode | MFM |

## Specifications - Type 2

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Note J1 CONNECTOR ALL ODD NUMBER POSTITONS J2 CONNECTOR 2. 4
6.8. $11,12,15,16,19,20$ ARE GROUNDED
(SH. 2) WRITE ERROR
(SH. 3) POWER ERROR



## $\not{ }^{\ddagger}$ <br> 



20MB Fixed Disk Drive - Type 13 (Sheet 4 of 4)

Personal Computer Hardware Reference Library

## 20MB Fixed Disk Drive

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Notes:

## Description

The IBM Personal Computer AT 20MB Fixed Disk Drive is a direct-access device that can store up to 20 Mb of formatted data. The average access time is 40 milliseconds using a quasi closed-loop servo positioner.

## Interfaces

The interfaces of this drive are divided into three categories: control, data transfer, and dc power.

The control interface is a 34 pin printed circuit board (PCB) edge connector. The following shows the signals and pin assignments.

| Signal Name | Signal Pin | Ground Pin |
| :--- | :--- | :--- |
| -Head Select 3 | 2 | 1 |
| -Head Select 2 | 4 | 3 |
| -Write Gate | 6 | 5 |
| -Seek Complete | 8 | 7 |
| -Track O00 | 10 | 9 |
| -Write Fault | 12 | 11 |
| -Head Select 0 | 14 | 13 |
| Reserved | 16 | 15 |
| -Head Select 1 | 18 | 17 |
| -Index | 20 | 19 |
| -Ready | 22 | 21 |
| -Step | 24 | 23 |
| -Drive Select 1 | 26 | 25 |
| -Drive Select 2 | 28 | 27 |
| -Drive Select 3 | 30 | 29 |
| -Drive Select 4 | 32 | 31 |
| -Direction In | 34 | 33 |

Control Interface

The data transfer interface is a 20 Pin PCB connector. The signals and pin assignments are as follows:

| Signal Name | Signal Pin |
| :--- | :--- |
| -Drive Selected | 1 |
| +MFM Write Data | 13 |
| -MFM Write Data | 14 |
| +MFM Read Data | 17 |
| -MFM Read Data | 18 |
| Ground | $2,4,6,8,11,12,15,16,19$ |

Data-Transfer Interface

The dc power interface is a 4-pin PCB connector. The signals and pin assignments follow.

| Signal Name | Pin |
| :--- | :--- |
| +12 Vdc | 1 |
| +12 Vdc Return | 2 |
| +5 Vdc | 4 |
| +5 Vdc Return | 3 |

DC Power Interface

## Control Input Signals

The control input signals are of two types: those that are multiplexed in a multiple drive system, and those intended to do the multiplexing. These input signals have the following specifications.

- Active: 0.0 to 0.4 Vdc at 40 mA
- Inactive: 2.5 to 5.25 Vdc at 0 mA

The following are descriptions of the control input signals.

## -Write Gate

The active level of this signal allows data to be written on the disk. The inactive level allows data to be read from the disk, and allows the step pulse to move the heads.

These four signals enable the selection of each read/write head in a binary-coded sequence. '-Head Select 0' is the least significant. Heads are numbered 0 through 15. When all Head Select signals are inactive, head 0 is selected.

## -Direction In

This signal defines the direction the read/write heads move when '-Step' is pulsed. An inactive level defines the direction as out, and if a pulse is applied to '-Step', the read/write heads move away from the center of the disk. An active level defines the direction as in, and the read/write heads move toward the center of the disk.

## -Step

This signal causes the read/write heads to move in the direction defined by the '-Direction In' signal. The motion starts when the '-Step' signal changes from active to inactive (the trailing edge of this signal pulse). Any change in '-Direction In' is made at least 100 nanoseconds before the leading edge of the step pulse. This drive supports two methods of stepping or seeking:

Slow Seek The read/write heads move at the rate of incoming step pulses. The minimum time between successive steps is 3 milliseconds and the minimum pulse width is 2 microseconds.

Buffered Seek The adapter's controller may burst step pulses to the drive until the time after the last pulse exceeds 200 microseconds or the maximum number of step pulses is received ( 1 for each track). The drive starts motion of the heads after receiving the first step pulse. Step pulses are sent to the drive every 35 microseconds.

## -Drive Select Signals 1 through 4

When one of these signals is active, it connects that drive to the control lines. Making the appropriate jumper connections at the drive determines which select line of the interface activates that drive.

The fixed disk drive provides a $220 / 230$ ohm termination for a single 'drive select' signal. The signal lead that is terminated is the one that selects the drive based on the position of the drive select jumpers.

## Output Control Signals

The drive control signals are open collector outputs that can sink a maximum of 40 mA in the active state, with a maximum output voltage of 0.4 Vdc . When the output is inactive, the collector's cutoff current is a maximum of 250 microamperes.

## -Seek Complete

This signal goes active when the read/write heads settle on the final track at the end of a seek. Reading or writing is not attempted when '-Seek Complete' is inactive. The following situations force '-Seek Complete' inactive:

- When power-on starts a recalibration sequence because the read/write heads are not over track 0 .
- When less than 5 microseconds have elapsed after the trailing edge of a step pulse or a series of step pulses.
- If the +5 or +12 Vdc fluctuates or is lost momentarily but restored.
- If the drive attempts to retry a seek after settling on a track.
-Seek Complete returns to the active level no later than 100 milliseconds ( 1 second if a seek retry occurs) after the trailing edge of the last -Step pulse.


## -Track 000

This signal is at an active level when the drive's read/write heads are at the outermost track.

## -Write Fault

This signal means that a condition at the drive is causing improper operation of the disk. An active level of this signal prevents further writing and stepping at the drive until drive power is switched off.

This signal goes active when any of the following conditions occur:

- Write current exists in the head without '-Write Gate' active, or no write current exists in the head with '-Write Gate' active and '-Drive Selected' active
- More than one seek retry between Seek commands from the controller
- A step pulse is received while '-Write Gate' is active.


## -Index

The drive provides this output signal once each revolution to indicate the beginning of a track. This signal normally is inactive and goes active to indicate '-Index'. Only the change from inactive to active is valid (leading edge of the pulse).

## -Ready

When this signal and '-Seek Complete' are active, the drive is ready to read, write, or seek, and the I/O signals are valid. An
inactive level of this signal prevents all writing and seeking.
'-Ready ' is inactive four times during drive operation:

- At power-up time ' -Ready ' remains inactive until:
- Access recalibration to track 0 is complete.
- $\quad$ Spindle speed is stable within $\pm 0.5 \%$ of nominal (10 revolution average).
- Drive self-check is complete.
- Spindle speed deviates $\pm 0.5 \%$ of nominal ( 10 revolution average).
- '-Write Fault $'$ is active.
- DC voltages are out of tolerance.


## Data-Transfer Signals

All signals associated with the transfer of data between the drive and the system are differential (pairs of balanced signals) and are not multiplexed.

Two pairs of balanced signals are used for the transfer of data: '-Write Data' and '-Read Data'. The following describes the data-transfer signals.

## MFM Write Data

This is a differential pair that defines signal shifts written on the track. When ' + MFM Write Data' goes more positive than '-MFM Write Data', flux reverses on the track, provided that '-Write Gate' is active. The system drives '-MFM Write Data' to an active level ( '-MFM Write Data' more negative than ' + MFM Write Data') when in the read mode.

To ensure data integrity, the controller applies a write-precompensation of $\pm 12$ nanoseconds to all write data on cylinders 300 and greater.

## MFM Read Data

Read data is sent to the system through the differential pair of MFM Read Data lines. When ' + MFM Read Data' goes more positive than '-MFM Read Data', flux reverses on the track of the selected head.

## Overlapped Seek

The drive supports overlapped-seek operations. An overlapped seek occurs when the drive is deselected 20 microseconds after the last step pulse is sent. Another drive is then selected, and the '-Step' and '-Direction In' signals are set by the operation desired. The controller provides at least 100 nanoseconds of hold time on '-Step' and '-Direction In' after '-Drive Select' is deactivated.

## Specifications

The following figures list the internal and performance specifications of this drive.

| Rotational speed | 3573 rpm $\pm 0.5 \%$ |
| :--- | :--- |
| Cylinders | 615 + Landing Zone |
| R/W Heads | 4 |
| Index | 1 |

## Internal Specifications

| Formatted Capacity | 20 Mb |
| :--- | :--- |
| Bytes/Sector | 512 |
| Sectors/Track | 17 |
| Transfer Rate | 5 M Bits/Second |
| Access Time |  |
| Track-to-Track | 2 ms |
| Average | 40 ms |
| Maximum | 85 ms |
| Settling | 12 ms |
| Average Latency | 8.4 ms |
| Track Density | 750 TPI |

## Performance Specifications

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# IBM Personal Computer AT 30MB Fixed Disk Drive 

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Notes:

August 15, 1985

## Description

The IBM Personal Computer AT 30MB Fixed Disk Drive is a direct-access device that can store up to 30 M of formatted data. The average access time is 40 milliseconds using a servo positioner.

## Interfaces

The interfaces of this drive are divided into three categories: control, data transfer, and dc power.

The control interface is a 34 -pin printed circuit board (PCB) edge connector. The signals and pin assignments are as follows.

| Signal Name | Signal Pin | Ground Pin |
| :---: | :---: | :---: |
| -Head select 3 | 2 | 1 |
| -Head select 2 | 4 | 3 |
| -Write gate | 6 | 5 |
| -Seek complete | 8 | 7 |
| -Track 000 | 10 | 9 |
| -Write fault | 12 | 11 |
| -Head select 0 Reserved | 14 | 13 |
| -Head select 1 | 16 | 15 |
| -Index | 18 | 17 |
| -Ready | 20 | 19 |
| -Step | 22 | 21 |
| -Drive select 0 | 24 | 23 |
| -Drive select 1 | 26 | 25 |
| -Drive select 2 | 28 | 27 |
| -Drive select 3 | 30 | 29 |
| -Direction in | 32 | 31 |

Control Interface

The data transfer interface is a 20 -pin PCB connector. The signals and pin assignments are as follows.

| Signal Name | Signal Pin |
| :--- | :--- |
| -Drive Selected | 1 |
| +MFM Write Data | 13 |
| -MFM Write Data | 14 |
| +MFM Read Data | 17 |
| -MFM Read Data | 18 |
| Grounds | $2,4,6,8,10,11$, |
| Reserved | $3,5,7,9$ |

## Data-Transfer Interface

The dc power interface is a 4-pin PCB connector. The signals and pin assignments are as follows.

| Signal Name | Pin |
| :---: | :---: |
| +12 Vdc | 1 |
| +12 Vdc Return | 2 |
| +5 Vdc Return | 3 |
| +5 Vdc | 4 |

DC Power Interface

## Control Input Signals

The control input signals are of two types: those that are multiplexed in a multiple drive system, and those intended to do the multiplexing. These input signals have the following specifications.

- Active: 0.0 to 0.4 Vdc at 40 mA
- Inactive: 2.5 to 5.25 Vdc at 0 mA

The following are descriptions of the control input signals.

## -Write Gate

The active level of this signal allows data to be written on the disk. The inactive level allows data to be read from the disk, and allows the step pulse to move the heads.

## -Head Select 0, 1, 2, and 3

These four signals enable the selection of each read/write head in a binary-coded sequence. The '-head select 0 ' signal is the least significant. Heads are numbered 0 through 15 . When all head-select signals are inactive, head 0 is selected.

## -Direction In

This signal defines the direction the read/write heads move when '-step' is pulsed. An inactive level defines the direction as out, and if a pulse is applied to '-step,' the read/write heads move away from the center of the disk. An active level defines the direction as in, and the read/write heads move toward the center of the disk.

## -Step

This signal causes the read/write heads to move in the direction defined by the '-direction in' signal. The motion starts when the '-step' signal changes from active to inactive (the trailing edge of this signal pulse). Any change in '-direction in' is made at least 100 nanoseconds before the leading edge of the step pulse. This drive supports two methods of stepping or seeking:

| Slow Seek | The read/write heads move at the rate of <br> incoming step pulses. The minimum time <br> between successive steps is 3 milliseconds and |
| :--- | :--- |
| the minimum pulse width is 2 microseconds. |  |

The adapter's controller may burst step pulses to the drive until the time after the last pulse exceeds 200 microseconds or the maximum number of step pulses is received ( 1 for each track). The drive starts motion of the heads after receiving the first step pulse. Step pulses are sent to the drive every 35 microseconds.

## -Drive Select Signals 0, 1, 2, and 3

When one of these signals is active, it connects that drive to the control lines. Making the appropriate jumper connections at the drive determines which select line of the interface activates that drive.

The fixed disk drive provides a 220/230 ohm termination for a single '-drive select' signal. The signal lead that is terminated selects the drive based on the position of the drive select jumpers.

## Output Control Signals

The drive control signals are open collector outputs which can sink a maximum of 40 mA in the active state, with a maximum output voltage of 0.4 Vdc . When the output is in the inactive state, the collector's cutoff current is a maximum of 250 microamperes.

## -Seek Complete

This signal goes active when the read/write heads settle on the final track at the end of a seek. Reading or writing is not attempted when '-seek complete' is inactive. The following situations force '-seek complete ' inactive:

- When power-on starts a recalibration sequence because the read/write heads are not over track 0
- When less than 2 microseconds have elapsed after the leading edge of a step pulse or a series of step pulses
- If the +5 or +12 Vdc fluctuates or is lost momentarily but restored
- If the drive attempts to retry a seek after settling on a track

The '-seek complete' signal returns to the active level no later than 100 milliseconds ( 1 second if a seek retry occurs) after the trailing edge of the last step pulse.

## -Track 000

This signal is at an active level when the drive's read/write heads are at the outermost track.

## -Write Fault

This signal means that a condition at the drive is causing improper operation of the disk. An active level of this signal prevents further writing and stepping at the drive until drive power is switched off.

This signal goes active when any of the following conditions occur:

- Write current exists in the head without '-write gate ' active, or no write current exists in the head with '-write gate ' active and '-drive select' active
- More than one seek retry between Seek commands from the controller
- A step pulse is received while '-write gate' is active
- An off track condition is detected while '-write gate' is active
- The '-write gate ' signal is active when write is disabled by the drive electronics

The drive provides this output signal once each revolution to indicate the beginning of a track. This signal normally is inactive and goes active to indicate an index. Only the change from inactive to active is valid (leading edge of the pulse).

## -Ready

When this signal and '-seek complete' are active, the drive is ready to read, write, or seek, and the I/O signals are valid. An inactive level of this signal prevents all writing and seeking.

The '-ready' signal is inactive four times during drive operation:

- At power-up time, '-ready ' remains inactive until:
- Access recalibration to track 0 is complete.
- Spindle speed is stable within $\pm 0.25 \%$ of nominal ( 10 revolution average).
- Drive self-check is complete.
- Spindle speed deviates $\pm 0.5 \%$ of nominal ( 10 revolution average).
- The '-write fault' signal is active.
- DC voltages are out of tolerance.


## Data-Transfer Signals

All signals associated with the transfer of data between the drive and the system are differential (pairs of balanced signals) and are not multiplexed.

Two pairs of balanced signals are used for the transfer of data: 'write data' and 'read data.' The following describes the data-transfer signals.

## MFM Write Data

This is a differential pair that defines signal shifts written on the track. When ' + MFM write data' goes more positive than
'-MFM write data,' flux reverses on the track, provided that '-write gate' is active. The system drives '-MFM write data' to an active level ('-MFM write data' more negative than ' + MFM write data') when in the read mode.

## MFM Read Data

Read data is sent to the system through the differential pair of 'MFM read data' lines. When '+MFM read data' goes more positive than '-MFM read data,' flux reverses on the track of the selected head.

## Overlapped Seek

The drive supports overlapped-seek operations. An overlapped seek occurs when the drive is deselected 20 microseconds after the last step pulse is sent. Another drive is then selected, and the '-step' and '-direction in' signals are set by the operation desired. The controller provides at least 100 nanoseconds of hold time on '-step' and '-direction in' after '-drive select' is deactivated.

## Notes:

## Specifications

The internal specifications of this drive are listed in the BIOS Fixed Disk Parameter Table, under "Real-Time Clock/CMOS RAM Information" in Section 1 of the IBM Personal Computer AT Technical Reference manual. The fixed disk type is on the defect label on the drive.



30MB Fixed Disk (Sheet 2 of 18)






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30MB Fixed Disk (Sheet 11 of 18)



30MB Fixed Disk (Sheet 12 of 18)







30MB Fixed Disk (Sheet 17 of 18)


## Notes:

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## Description

The 64 KB Memory Module Kit and the $64 / 256 \mathrm{~KB}$ Memory Expansion Option are available for the IBM Personal Computer family of products. Depending upon the amount of memory currently installed on the system board, memory module kits can be added to provide a maximum of 256 KB of RAM without using any of the system unit expansion slots for a memory expansion option. The system board must be populated to the maximum 256 KB of RAM before a 64/256KB Memory Expansion Option can be installed.

The IBM 64/256KB Memory Expansion Option has four banks of nine pluggable sockets. Each bank will accept a 64 KB Memory Module Kit, consisting of 9 ( 64 K by 1) modules with 16 -pin industry-standard parts. The base $64 / 256 \mathrm{~K}$ expansion option comes with modules installed in bank 0 , providing 64 K of memory. The kits must be installed sequentially into banks 1,2 , and 3. The following chart shows how the 64 KB Memory Module Kit can be installed on the system board and the 64/256KB Memory Expansion Option.

|  | Minimum <br> Memory | Maximum <br> Memory | Number of <br> 64K Memory <br> Module Kits | Memory <br> Module <br> Type |
| :--- | :---: | :---: | :---: | :---: |
| $64 / 256 \mathrm{~K}$ <br> System Board | 64 K | 256 K | 1,2, or 3 | 64 K by 1 Bit, <br> 16 pin |
| 64/256K <br> Memory Option | 64 K | 256 K | 1,2, or 3 | 64 K by 1 Bit, <br> 16 pin |

In addition to the memory modules, the memory expansion option contains the following circuits: bus buffering, dynamic memory timing generation, address multiplexing, and card-select decode logic.

Dynamic-memory refresh timing and address generation are functions that are performed by the system board and made available in the I/O channel for all devices.

The $64 / 256 \mathrm{~KB}$ Memory Expansion Option is parity checked. If a parity error is detected, a latch is set and an I/O 'channel check' line is activated, indicating an error to the microprocessor.

To allow the system unit to address the expanded memory provided by the 64 KB Memory Module Kit or the $64 / 256 \mathrm{~K}$ Memory Expansion Option, refer to the Guide to Operations manual for the proper memory-expansion-option switch settings.

## Switch-Configurable Start Address

The 64/256KB Memory Expansion Option must be configured to reside at a sequential 64 K memory address boundary within the system address space. This is done by setting dual-in-line package (DIP) switches on the option. The $64 / 256 \mathrm{~KB}$ expansion option has a small DIP module containing eight switches. The switches are used to set the card start address as follows:

| Number | 64/256K Options |
| :---: | :--- |
| 1 | ON: A19 = O; OFF: A19 = 1 |
| 2 | ON: A18=0; OFF: A18=1 |
| 3 | ON: A17 =0; OFF: A17 = 1 |
| 4 | ON: A16=0; OFF: A16=1 |
| 5 | ON: Select 64K |
| 6 | ON: Select 128 K |
| 7 | ON: Select 192 K |
| 8 | ON: Select 256 K |

## DIP Module Start Address



## Operating Characteristics

The system board operates at a frequency of 4.77 MHz , which results in a clock cycle of 210 ns .

Normally four clock cycles are required for a bus cycle so that an 840 -ns memory cycle time is achieved. Memory-write and memory-read cycles both take four clock cycles, or 840 ns .

Access and cycle times for memory used on the 64/256 Memory Expansion Option are:

|  | 64K by 1 Bit |
| :--- | :---: |
| Access | 200 ns |
| Cycle | 345 ns |

The 64 K by 1 modules require only one voltage level of +5 Vdc , and require 128 refresh cycles every 2 ms . Absolute maximum access times are:

|  | 64K by 1 Bit |
| :---: | :---: |
| From $\overline{\text { RAS }}$ | 200 ns |
| From $\overline{\mathrm{CAS}}$ | 115 ns |

## Specifications

| Pin | 64K by 1 Bit Module <br> (used on 64/256K option <br> and 64/256K <br> system board) |
| :---: | :---: |
| 1 | N/C |
| 2 | Data In** |
| 3 | - Write |
| 4 | - RAS |
| 5 | AO |
| 6 | A2 |
| 7 | A1 |
| 8 | -5 Vdc |
| 9 | A7 |
| 10 | A5 |
| 11 | A4 |
| 12 | A3 |
| 13 | A6 |
| 14 | Data Out ** |
| 15 | - CAS |
| 16 | GND |
| 17 | $*$ |
| 18 | $*$ |

## Memory Module Pin Configuration




64/256KB Memory Expansion Option (Sheet 2 of 4)



64/256KB Memory Expansion Option (Sheet 4 of 4)

# IBM 256KB Memory Expansion Option 



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Notes:

## Description

The IBM 256 KB Memory Expansion Option is available for the IBM Personal Computer family of products. The system board must be populated to the maximum 256 KB of RAM before the IBM 256KB Memory Expansion Option can be installed.

The IBM 256KB Memory Expansion Option has four pluggable sockets. Each socket will accept a 64KB Memory Module, consisting of one ( 64 K by 9) 32-pin D RAM Module. The 256 KB expansion option comes with all four modules installed providing 256 KB of memory.

In addition to the memory modules, the memory expansion option contains the following circuits: bus buffering, dynamic memory timing generation, address repowering, and card-select decode logic.

Dynamic-memory refresh timing and address generation are functions that are performed by the system board and made available in the I/O channel for all devices.

The 256KB Memory Expansion Option is parity checked. If a parity error is detected, a latch is set and an I/O 'channel check' line is activated, indicating an error to the microprocessor.

To allow the system unit to address the expanded memory provided by the IBM 256KB Memory Expansion Option, refer to the Guide to Operations manual for the proper memory-expansion-option switch settings.

## Switch-Configurable Start Address

The 256KB Memory Expansion Option must be configured to reside at a sequential 64 KB memory address boundary within the system address space. This is done by setting dual-in-line package (DIP) switches on the option. The IBM 256KB Memory Expansion Option has a small DIP module containing eight switches. The switches are used to set the card start address as follows:

| Number | 256KB Options |
| :---: | :--- |
| 1 | ON: A19=0; OFF:A19=1 |
| 2 | ON: A18=0; OFF:A18=1 |
| 3 | ON: A17=0; OFF:A17=1 |
| 4 | ON: A16=0; OFF:A16=1 |
| 5 | ON: Select 64KB |
| 6 | ON: Select 128KB |
| 7 | ON: Select 192KB |
| 8 | ON: Select 256KB |

## DIP Module Start Address

The following method can be used to determine the switch settings for the 256KB memory expansion option.

Starting Address $=x \times x K B$
$64 \mathrm{~KB} \quad \mathrm{xxxKB}=$ Decimal value

Convert decimal value to binary
Bit.......... 3210
Bit value.... 8421
Switch


## Operating Characteristics

The system board operates at a frequency of 4.77 MHz , which results in a clock cycle of 210 ns .

Normally four clock cycles are required for a bus cycle so that an 840 -ns memory cycle time is achieved. Memory-write and memory-read cycles both take four clock cycles, or 840 ns .

Access and cycle times for memory used on the IBM 256KB Memory Expansion Option are:

| Time. | 256KB Card |
| :--- | ---: |
| Access <br> Cycle | 290 ns |

Access/Cycle Times

## Voltage Requirements

The IBM 256KB Memory Expansion card requires 3 voltage levels: $+12 \mathrm{Vdc},+5 \mathrm{Vdc}$, and -5 Vdc .

## Specifications



IBM 64KB Memory Module Pin Configuration

Notes:



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256KB Memory Expansion Option (Sheet 3 of 3)

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# 128KB Memory Expansion Option 

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Notes:

## Description

The IBM Personal Computer AT 128 Kb Memory Expansion Option has 18 RAM modules ( $64 \mathrm{~Kb} \times 1$ ) for a total capacity of 128 Kb .

## Memory Cycles

Memory read and write commands require a 1-wait-state, 3-clock memory cycle. Data moves as a byte ( 8 data bits and 1 parity bit) or as a word ( 16 data bits and 2 parity bits) and is parity-checked on the adapter. A parity error causes an I/O channel check (non-maskable interrupt) to the system.

## I/O Channel Check

When the I/O channel check occurs, a non-maskable interrupt (NMI) results. Bits 6 and 7 of hex address 0061 are the status bits used to determine the source of the NMI (bit 6 is I/O channel check, and bit 7 is system board parity check). Writing to the failing card will clear the status bit.

## Addressing

This adapter responds to addresses from hex 080000 to hex 09FFFF.

## Specifications

## Voltage Tolerances

The maximum variation of the +5 Vdc is $\pm 5 \%$ at the adapter pins.

## Power Dissipation

The +5 Vdc power used by the adapter is a maximum of 5.25 watts, and the maximum current used is 1 ampere.

## Temperature Variation

The adapter will operate between 10 and 50 degrees Celsius (50 and 122 degrees Fahrenheit).
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128KB Memory Expansion Option (Sheet 2 of 7)




128KB Memory Expansion Option (Sheet 4 of 7)





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## 512KB Memory Expansion Option

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Temperature Variation ..... 3
Logic Diagrams ..... 5

Notes:

## Description

The IBM Personal Computer AT 512 Kb Memory Expansion option has 36 RAM modules ( $128 \mathrm{~Kb} \times 1$ ) for a total capacity of 512 Kb .

## Memory Cycles

Memory read and write commands require a 1 -wait-state, 3-clock memory cycle. Data moves as a byte ( 8 data bits and 1 parity bit) or as a word ( 16 data bits and 2 parity bits) and is parity-checked on the adapter. A parity error causes an I/O channel check (non-maskable interrupt) to the system.

## Memory Address Switches

There are two banks of memory address switches on each memory adapter. These switches are set to values for the first, second, third, etc. memory adapter in the system.

The first memory expansion adapter must start at address space hex 100000. If more than one adapter is installed, no gaps between memory are allowed. All expansion memory must be one contiguous block starting at address hex 100000.

The figure on the following page shows the switch settings for each adapter.


Switch Bank 0
Switch Bank 1

1st 512KB Memory Expansion Adapter

2nd 512KB Memory Expansion Adapter

3rd 512KB Memory Expansion Adapter

4th 512 KB Memory Expansion Adapter

5th 512KB Memory Expansion Adapter


## I/O Channel Check

When the I/O channel check occurs, a non-maskable interrupt (NMI) results. Bits 6 and 7 of hex address 0061 are the status bits used to determine the source of the NMI (bit 6 is I/O channel check, and bit 7 is system board parity check). Writing to the failing card will clear the status bit.

## Specifications

## Voltage Tolerances

The maximum variation of the +5 Vdc is $\pm 5 \%$ at the adapter pins.

## Power Dissipation

The +5 Vdc power used by the adapter is a maximum of 5.25 watts, and the maximum current used is 1 ampere.

## Temperature Variation

The adapter will operate between 10 and 50 degrees Celsius (50 and 122 degrees Fahrenheit).

Notes:

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512 KB Memory Expansion Option (Sheet 1 of 8)


512 KB Memory Expansion Option (Sheet 2 of 8)



512 KB Memory Expansion Option (Sheet 3 of 8)


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## IBM Personal Computer AT ${ }^{\circledR}$ 128KB/640KB Memory Expansion Option

## Contents

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Notes:

## Description

The IBM PERSONAL COMPUTER AT ${ }^{\circledR} 128 \mathrm{~KB} / 640 \mathrm{~KB}$ Memory Expansion Option is a variable-size memory adapter designed to:

- Increase the size of base memory by 128 K to allow full 640 K real mode memory addressing
- Increase the size of expansion memory by 512 K without using an additional I/O slot.

The option has two banks of pluggable sockets, Bank 0 and Bank 1.

Module


## Memory Module Location

Bank 1 is the 128 K bank. It contains eighteen 64 K by 1 dynamic random access memory (DRAM) modules. The 128 K is base memory residing at address hex 80000 through hex 9FFFF. Bank 0 is the 512 K bank. This bank may be populated by an IBM Personal Computer AT 512KB Memory Module Kit, consisting of eighteen 256 K by 1 DRAM modules. The 512 K is expansion memory residing at an address determined by the option's dual-inline-package (DIP) switch settings.

## Operating Characteristics

Memory-read (MEMR) and memory-write (MEMW) operations require a 1 -wait-state, 3 -clock memory cycle. Data moves as a byte ( 8 data bits and 1 parity bit) or as a word ( 16 data bits and 2 parity bits) and is parity-checked on the adapter.

## I/O Channel Check

If a parity error is detected, a latch is set and an I/O 'channel check' line is activated; the result being a non-maskable interrupt (NMI) indicating an error to the system unit's microprocessor. The status bits (I/O channel check and system-board parity check) determine the source. Writing to the failing option clears the status bit.

## Memory Address Switches

An eight-position DIP module is mounted on the option. Its switch assignments are as follows:

| Switch Number | Switch Assignments |  |
| :---: | :---: | :---: |
| 1 | ON:LA23 $=0$ | OFF:LA23 $=1$ |
| 2 | ON:LA22 $=0$ | OFF:LA22 = 1 |
| 3 | ON:LA21 $=0$ | OFF:LA21 $=1$ |
| 4 | ON:LA20 $=0$ | OFF:LA20 $=1$ |
| 5 | ON:LA19 = 0 | OFF:LA19 = 1 |
| 6 | ON: Bank 0 populated | OFF:Bank 0 not populated |
| 7 | ON: Bank 1 populated | OFF:Bank 1 not populated |
| 8 | ON:Reserved | OFF: Bank 1 memory is 128 K |

## DIP Module Switch Assignments

The first 512 K of expansion memory must start at address space hex 100000. If additional memory expansion options are installed, no gaps between memory are allowed. All expansion memory must be one contiguous block starting at address hex 100000.

## Specifications



| Pin | 256 K by 1 bit Module | 64 K by 1 Bit Module |
| :---: | :---: | :---: |
| $\begin{array}{r} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \\ 7 \\ 8 \\ 9 \\ 10 \\ 11 \\ 12 \\ 13 \\ 14 \\ 15 \\ 16 \end{array}$ | A8 Data In * -Write -RAS A0 A2 A1 +5 Vdc A7 A5 A4 A3 A6 Data Out * -CAS GND | $\begin{gathered} \text { N/C } \\ \text { Data In } \\ \text {-Write } \\ \text {-RAS } \\ \text { A0 } \\ \text { A2 } \\ \text { A1 } \\ +5 \text { Vdc } \\ \text { A7 } \\ \text { A5 } \\ \text { A4 } \\ \text { A3 } \\ \text { A6 } \\ \text { Data Out } \\ \text {-CAS } \\ \text { GND } \end{gathered}$ |
| * Data In and Data Out are tied together on Data Bits 0-7 (three state bus) |  |  |

Memory Module Pin Configuration


128/640 Memory Card (Sheet 1 of 8)



128/640 Memory Card (Sheet 2 of 8)



128/640 Memory Card (Sheet 4 of 8)

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# IBM Personal Computer AT ${ }^{\circledR}$ 512KB/2MB Memory Expansion Option 

## Contents

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Notes:

## Description

The IBM PERSONAL COMPUTER AT ${ }^{\text {© }} 512 \mathrm{~KB} / 2 \mathrm{MB}$ Memory Expansion provides 512 K of additional random access memory (RAM) and can be expanded to provide a total of 2 M of additional RAM.

Four 18-socket banks accept 256K-by-1 dynamic RAM (DRAM) modules. Bank 0 is fully populated. Banks 1,2 , and 3 may be populated by using three IBM Personal Computer AT 512KB Memory Module Kits, consisting of eighteen 256K-by-1 DRAM modules each.


Memory Module Location

## Operating Characteristics

Memory-read (MEMR) and memory-write (MEMW) operations require a 1 -wait-state, 3 -clock memory cycle. Data moves as a byte ( 8 data bits and 1 parity bit) or as a word ( 16 data bits and 2 parity bits) and is parity-checked on the adapter.

## I/O Channel Check

If a parity error is detected, a latch is set and an '-I/O channel check' line is activated; the result is a non-maskable interrupt (NMI) indicating an error to the system unit's microprocessor. The status bits (I/O channel check and system-board parity check) determine the source. Writing to the failing option clears the status bit.

## Memory Address Switches

An eight-switch DIP module is mounted on the memory expansion option. These switches set the starting address for each option above the 1 M system board RAM. The switch assignments for the starting address for Bank 0 are as follows:

| Switch <br> Number | Switch Assignments |
| :--- | :--- |
| 1 | ON:LA23 $=0$ |
| 2 | ON:LA22 $=0$ |
| 3 | ON:LA21 $=0$ |
| 4 | ON:LA20 $=0$ |
| 5 | ON:LA19 = |
| 6 | Not Used. |
| 7 | Not Used. |
| 8 | NFF:LA23 $=1$ |
| Not Used. | OFF:LA21 $=1$ |

## Switch Assignments

The address of the first expansion memory option must start at address space hex 100000 . If additional memory expansion options or IBM Personal Computer AT 512KB Memory Module Kits are installed, no gaps between memory are allowed. All expansion memory must be one contiguous block starting at address hex 100000 .

## Notes:

1. An expansion option must be fully populated before another can be installed.
2. In order to determine the total expansion memory installed check bytes hex ( $30 \& 31$ ) in CMOS RAM.

## Programming

Programs that test for memory by writing and reading until a data error is detected, must write back to the failing card to clear possible parity checks. This is required for a partially populated 512KB/2MB Memory Expansion.

## Specifications



| Pin | 256 by 1 Bit <br> Module |
| :---: | :---: |
| 1 | A8 |
| 2 | Data In $*$ |
| 3 | -Write |
| 4 | -RAS |
| 6 | AO |
| 7 | A2 |
| 8 | A1 |
| 9 | Vdc |
| 10 | A7 |
| 11 | A4 |
| 12 | A3 |
| 13 | A6 |
| 14 | Data Out $*$ |
| 15 | - CAS |
| 16 | Ground |
| * Data In and Data Out are tied |  |
| together on Data Bits 0-7 |  |
| (three state bus). |  |

Memory Module Pin Configuration


512KB/2MB Memory Card (Sheet 1 of 10)



512KB/2MB Memory Card (Sheet 3 of 10)



512KB/2MB Memory Card (Sheet 5 of 10)



$512 \mathrm{~KB} / 2 \mathrm{MB}$ Memory Card (Sheet 8 of 10)


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[^0]:    Receiver Card Block Diagram

[^1]:    Parallel Interface Timing Diagram

