HP 64770

TLCS-9000 Emulator Softkey Interface

User's Guide



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Printing History

New editions are complete revisions of the manual. The date on the title page changes only when a new edition is published.

A software code may be printed before the date; this indicates the version level of the software product at the time the manual was issued. Many product updates and fixes do not require manual changes and, manual corrections may be done without accompanying product changes. Therefore, do not expect a one-to-one correspondence between product updates and manual revisions.

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Using this Manual

This manual shows you how to use the following emulators with the Softkey Interface.

■ HP 64770A/B TLCS-9000 emulator

This manual:

- Shows you how to use emulation commands by executing them on a sample program and describing their results.
- Shows you how to use the emulator in-circuit (connected to a target system).
- Shows you how to configure the emulator for your development needs. Topics include: restricting the emulator to real-time execution.

This manual does not:

Show you how to use every Softkey Interface command and option; the Softkey Interface is described in the Softkey Interface Reference manual.

For the most part, the HP 64770A and HP 64770B emulators all operate the same way. Differences of between the emulators are described where they exist. Both the HP 64770A and HP 64770B emulators will be referred to as the "HP 64770A/B TLCS-9000 emulator" or "TLCS-9000 emulator". In the specific instances where HP 64770B emulator differs from HP 64770A emulator, it will be described as "HP 64770A emulator".

Organization

- **Chapter 1** Introduction to the TLCS-9000 Emulator. This chapter briefly introduces you to the concept of emulation and lists the basic features of the TLCS-9000 emulator.
- **Chapter 2** Getting Started. This chapter shows you how to use emulation commands by executing them on a sample program. This chapter describes the sample program and how to: load programs into the emulator, map memory,display and modify memory, display registers, step through program, run programs, set software breakpoints, search memory for data, and use the analyzer.
- **Chapter 3** "In-Circuit" Emulation. This chapter shows you how to install the emulator probe into a demo board and target system and how to use "in-circuit" emulation features.
- **Chapter 4 Configuring the Emulator.** This chapter shows you how to: restrict the emulator to real-time execution, allow the target system to insert wait states, and select foreground or background monitor.
- **Chapter 5** Using the Emulator. This chapter describes emulation topics which are not covered in the "Getting Started" chapter.

Conventions	Example commands throughout the manual use the following conventions:					
	bold	Commands, options, and parts of command syntax.				
	bold italic	Commands, options, and parts of command syntax which may be entered by pressing softkey.				
	normal	User specified parts of a command.				
	\$	Represents the HP-UX prompt. Commands which follow the "\$" are entered at the HP-UX prompt.				
	<return></return>	The carriage return key.				

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Introduction to the TLCS-9000 Emulator

Introduction	 The topics in this chapter include: Purpose of the emulator Features of the emulator Limitations and Restrictions of the emulator
Purpose of the Emulator	The TLCS-9000 emulator is designed to replace the TLCS-9000 microprocessor series in your target system to help you debug/integrate target system software and hardware. The emulator performs just like the processor which it replaces, but at the same time, it gives you information about the bus cycle operation of the processor. The emulator gives you control over target system execution and allows you to view or modify the contents of processor registers, target system memory, and I/O resources. Refer to "Memory Mapping" section in the "Using the Emulator" chapter.

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Figure 1-1 HP 64770A/B Emulator for TLCS-9000

1-2 Introduction

Features of the TLCS-9000 Emulator

This section introduces you to the features of the emulator. The chapters which follow show you how to use these features.

Supported Microprocessors

The HP 64770A emulator supports the microprocessors listed in Table 1-1. The HP 64770B emulator supports the microprocessors listed in Table 1-2.

Supported Microprocessors	Internal ROM size	Internal RAM size					
TMP97C241F	0	2K byte					
TMP97PS40F	64K byte	2K byte					
TMP97CS40F	64K byte	2K byte					
TMP97CM40F	32K byte	1K byte					
TMP97PW40F	128K byte	4K byte					
TMP97CW40F	128K byte	4K byte					

Table 1-1 Supported Microprocessors (HP 64770A)

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Supported Microprocessors	Internal ROM size	Internal RAM size
TMP97CS42	64K byte	3.5K byte
TMP97PU42	64K byte	3.5K byte
	96K byte	5.25K byte
TMP97CU42	96K byte	5.25K byte
TMP97PW42	128K byte	5.25K byte
TMP97CW42	128K byte	5.25K byte

Table 1-2 Supported Microprocessors (HP 64770B)

Clock Speeds	The HP 64770A emulator runs with a target system clock from 4 to 20 MHz. The HP 64770B emulator runs with a target system clock from 4 to 16 MHz.
Emulation memory	The HP TLCS-9000 emulator can be used with one of the following Emulation Memory Modules.
	 HP 64171A 256K byte Emulation Memory Module(35 ns) HP 64171B 1M byte Emulation Memory Module(35 ns) HP 64172A 256K byte Emulation Memory Module(20 ns) HP 64172B 1M byte Emulation Memory Module(20 ns) HP 64173A 4M byte Emulation Memory Module(25 ns)
	You can define up to 7 memory ranges. You can characterize memory ranges as emulation RAM, emulation ROM, target system RAM, target system ROM, or guarded memory. The emulator generates an error message when accesses are made to guarded memory locations. You can also configure the emulator so that writes to memory defined as ROM cause emulator execution to break out of target program execution. Refer to the "Memory Mapping" section in the "Using the emulator" chapter.
Analysis	The HP 64770A emulator is used with one of the following analyzers which allows you to trace code execution and processor activity.

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	 HP64704A 80-channel Emulation Bus Analyzer HP64794A/C/D Deep Emulation Bus Analyzer 	
	The Emulation Bus Analyzer monitors the emulation processor using an internal analysis bus.	
Registers	You can display or modify the TLCS-9000 internal register contents.	
Emulation Monitor	The emulation monitor is a program that is executed by the emulation processor. It allows the emulation controller to access target system resources, and emulation memory. For example, when you display target system memory, it is monitor program that executes TLCS-9000 instructions which read the target memory locations and send their contents to the emulation controller.	
	The emulation monitor takes up 64K bytes of processor's address space.	
Single-Step	You can direct the emulation processor to execute a single instruction or a specified number of instructions.	
Breakpoints	You can set up the emulator/analyzer interaction so that when the analyzer finds a specific state, emulator execution will break to the emulation monitor.	
	You can also define software breakpoints in your program. The emulator uses the undefined instruction(7F9Fh) to provide software breakpoint. When you define a software breakpoint, the emulator places a this undefined instruction at the specified address; after the undefined instruction causes emulator execution to break out of your program, the emulator replaces undefined instruction with the original opcode.	
Reset Support	The emulator can be reset from the emulation system under your control, or your target system can reset the emulation processor.	
Real-Time Operation	Real-time operation signifies continuous execution of your program without interference from the emulator. (Such interference occurs when the emulator temporarily breaks to the monitor so that it can access register contents or memory.)	

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	You can restrict the emulator to real-time execution. When the emulator is executing your program under the real-time restriction, commands which display/modify registers, display/modify memory are not allowed.
Coverage	The TLCS-9000 emulator does not support coverage test.
Easy Products Upgrades	Because the HP 64700 Series development tools (emulator, analyzer, LAN board) contain programmable parts, it is possible to reprogram the firmware and some of the hardware without disassembling the HP 64700B Card Cage. This means that you'll be able to update product firmware, if desired, without having to call an HP field representative to your site

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Limitations, Restrictions

Reset While in Monitor	If monitor program is running, $\overline{\text{RESET}}$ signal from target system is ignored while in monitor.		
User Interrupts While in Monitor			
While Executing Step Command	While stepping user program, interrupts are ignored. While single stepping, BUSRQ from target system is always ignored even if BUSRQ from target system is enabled.		
Note	You should not use step command in case the interrupt handler's punctuality is critical.		
Watch Dog Timer (HP 64770A Only)	When the HP 64770A emulator breaks into the monitor, the watched dog timer is resets, and disabled until the emulator goes into user program operation.		
	You must display/modify MDMOD register by "reg" command instead of "m" command.		
Vector Area	 You need to configure vector entry for the emulator to realize the following features. Break Single-Step Software Break Point 		
	Refer to the "Vector Area Setting" section in the "Using the Emulator" Chapter in this manual.		

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Register Bank	When the emulator breaks into the monitor, the PC and PSW are stored at register bank of "CBP-1" in the same way as the emulator accepts interrupts.	
Unbreaking into the Monitor	The emulator can not break into the monitor when the emulation processor is the following states.	
	 Standby Mode by HALT instruction Power Save state(Hardware standby mode) by PS signal Hold Mode by BUSRQ signal Reset state by RESET signal from target 	
Emulation Memory	When you use the emulator in single chip mode, you need the emulation memory because the emulator maps internal ROM/RAM area as emulation memory.	
	If you use the emulator in single chip mode or the emulation processor does burst fetch, the emulation memory module is restricted by clock speed as following.	
	HP 64770A	
	If clock speed is equal to 18MHz or greater 18MHz, you need HP64712A/B emulation memory module. If clock speed is less than 18MHz, you can use HP64712A/B and HP64713A emulation memory modules. If clock speed is less than 15MHz, you can use HP64171A/B, HP64172A/B and HP64713A emulation memory module.	
	HP 64770B	
	If clock speed is equal to 16MHz or less than 16MHz, you can use HP64712A/B and HP64713A emulation memory modules. If clock speed is less than 15MHz, you can use HP64171A/B, HP64172A/B and HP64713A emulation memory module.	
Evaluation Chip	Hewlett-Packard makes no warranty of the problem caused by the TLCS-9000 Evaluation chip in the emulator.	

1-8 Introduction

Getting Started

Introduction

This chapter will lead you through a basic, step by step tutorial that shows how to use the HP 64770A/B emulator (for the TLCS-9000 microprocessor) with the Softkey Interface.

This chapter will:

 Tell you what must be done before you can use the emulator as shown in the tutorial examples.

• Describe the demo program used for this chapter's examples. This chapter will show you how to:

- Start up the Softkey Interface.
- Load programs into emulation and target system memory.
- Enter emulation commands to view execution of the demo program.

2

Getting Started 2-1

Before You Begin

Prerequisites	Before beginning the tutorial presented in this chapter, you must have completed the following tasks:		
	1. Connected the emulator to your computer. The <i>HP</i> 64700 Series Installation/Service manual show you how to do this.		
	2. Installed the Softkey Interface software on your computer. Refer to the <i>HP 64700 Series Installation/Service</i> manual for instructions on installing software.		
	3. In addition, you should read and understand the concepts of emulation presented in the <i>Concepts of Emulation and Analysis</i> manual. The <i>Installation/Service</i> manual also covers HP 64700 system architecture. A brief understanding of these concepts may help avoid questions later.		
	You should read the <i>Softkey Interface Reference</i> manual to learn how to use the Softkey Interface in general. For the most part, this manual contains information specific to the TLCS-9000 emulator.		
A Look at the Demo Program	The demo program is <i>spmt_demo</i> consisting of source program <i>spmt_demo.c</i> and <i>init.s</i> .		

Where is the spmt_demo Software?

The demo program is shipped with the Softkey Interface and may be copied from the following directory.

/usr/hp64000/demo/emul/hp64770

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Assembling/Compiling the Demo Program	The demo program is written for and compiled/linked with the MICROTEC RESEARCH Inc. MCCT9K C Compiler Package. The demo program was assembled/compiled with the following commands. \$ mcct9k -c -g spmt_demo.c <return> \$ asmt9k -f debug,casemcct9k -1 init.s > init.lis <return></return></return>
Linking the Demo Program	The following command was used to generate the absolute file. The "spmt_demo.cmd" linker command file is shown in figure 2-1.
DEBUG_SYMBOLS SECT stack=\$400 SECT zerovars=\$800 SECT code=\$a00 LOAD init.o LOAD spmt_demo.o END	<pre>\$ lnkt9k -c spmt_demo.cmd -M<return></return></pre>
	Figure 2-1 Linker Command File
Entering the Softkey Interface	If you have installed your emulator and Softkey Interface software as directed in the <i>HP 64700 Series Emulators Softkey Interface</i> <i>Installation Notice</i> , you are ready to enter the interface. The Softkey

From the HP-UX Shell If /usr/hp64000/bin is specified in your PATH environment variable,

Interface can be entered from the HP-UX shell.

you can also enter the Softkey Interface with the following command.

\$ emul700 <emul_name> <RETURN>

The "emul_name" in the command above is the logical emulator name given in the HP 64700 emulator device table (/usr/hp64000/etc/64700tab.net).

#-				+
#	Channel	Logical	Processor	Remainder of Information for the Channel
#	Type	Name	Туре	(IP address for LAN connections)
#-		+	+	+
	lan:	tlcs	t9k40	21.17.9.143

If this command is successful, you will see a display similar to figure 2-2. The status message shows that the default configuration file has

Getting Started 2-3

been loaded. If the command is not successful, you will be given an error message and returned to the HP-UX prompt. Error messages are described in the *Softkey Interface Reference* manual.

HPB3075-11001 A.05.20 10Jan95 TLCS-9000/40 SOFTKEY USER INTERFACE A Hewlett-Packard Software Product Copyright Hewlett-Packard Co. 1993 All Rights Reserved. Reproduction, adaptation, or translation without prior written permission is prohibited, except as allowed under copyright laws. RESTRICTED RIGHTS LEGEND Use , duplication , or disclosure by the Government is subject to restrictions as set forth in subparagraph (c) (1) (II) of the Rights in Technical Data and Computer Software clause at DFARS 52.227-7013. HEWLETT-PACKARD Company , 3000 Hanover St. , Palo Alto, CA 94304-1181 STATUS: Starting new session_ _...R.... ---ETC-run trace step display modify break end

Figure 2-2 Softkey Interface Display

Configure the Emulator for Examples	To do operations described in this chapter (loading absolute program into emulation memory, displaying memory contents, etc), you need to configure the emulator as below. For detailed description of each configuration option (question), refer to the " <i>Configuring the Emulator</i> " chapter.
	To get into the configuration session of the emulator, enter the following command.
	modify configuration <return></return>
Restrict to real-time runs?	Answer to the series of questions as below. <i>no</i> <return></return>
Processor type? 97CM40 <ret< th=""><th>When you use HP 64770A emulator, answer this question as shown.</th></ret<>	When you use HP 64770A emulator, answer this question as shown.
	When you use HP 64770B emulator, answer this question as shown.
Processor type? 97CU42 <ret< td=""><td>URN></td></ret<>	URN>

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Processor operation mode? **external_bus** <RETURN> Monitor base address? **0F0000H** <RETURN> Enable emulation VBP? **yes** <RETURN>

When you use HP 64770A emulator, answer this question as shown.

Vector base address (97PS/CM40)? **OFF0000H** <RETURN>

When you use HP 64770B emulator, answer this question as shown.

Vector base address (97CU42)? OFE7800H <RETURN>
Initial CBP value? 01H <RETURN>
Modify memory configuration? yes <RETURN>

Now you should be facing memory mapping screen. If you use HP 64770A emulator, two mapper terms must be specified for the demo program. Enter the following lines to map the program code area as emulation ROM, data area as emulation RAM. If you use HP 64770B emulator, you do not need to map because mapper terms for the demo program are specified automatically.

400h thru 9ffh emulation ram <RETURN>
0a00h thru 0fffh emulation rom <RETURN>
end <RETURN>
Modify emulator pod configuration? no <RETURN>
Modify debug/trace options? no <RETURN>
Modify simulated I/O configuration? no <RETURN>
Modify interactive measurement specification? no <RETURN>

If you wish to save the configuration specified above, answer this question as shown.

Configuration file name? **spmt_demo** <RETURN>

Now you are ready to go ahead. Above configuration is used through out this chapter.

On-Line Help	There are two ways to access on-line help in the Softkey Interface. The first is by using the Softkey Interface help facility. The second method allows you to access the firmware resident Terminal Interface on-line help information.
Softkey Driven Help	To access the Softkey Interface on-line help information, type either "help" or "?" on the command line; you will notice a new set of softkeys. By pressing one of these softkeys and <return>, you can cause information on that topic to be displayed on your screen. For example, you can enter the following command to access "system command" help information.</return>
	? system_commands <return></return>

SYSTEM COMMANDS & COMMAND FILES		
? help	displays the possible help files displays the possible help files	
! ! <shell command=""></shell>	fork a shell (specified by shell variable SH) fork a shell and execute a shell command	
pwd cd <directory></directory>	print the working directory change the working directory	
pws cws <symb></symb>	print the default symbol scope change the working symbol - the working symbol also gets updated when displaying local symbols and displaying memory mnemonic	
forward <ui> "command"</ui>	send the command in the quoted string from this user interface to another one. Replace <ui> with the name of the other user interface as shown on the softkeys:</ui>	
More(15%)		

The help information is scrolled on to the screen. If there is more than a screenful of information, you will have to press the space bar to see the next screenful, or the <RETURN> key to see the next line, just as you do with the HP-UX **more** command. After all the information on the particular topic has been displayed (or after you press "q" to quit scrolling through information), you are prompted to press <RETURN> to return to the Softkey Interface.

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Pod Command Help

To access the emulator's firmware resident Terminal Interface help information, you can use the following commands.

display pod_command <RETURN>
pod_command 'help cf' <RETURN>

Pod Commands Time Command cf <item> <item> <item> - set and display can be combined help cf <item> - display long help for specified <item></item></item></item></item></item>	
VALID CONFIGURATION <item> NAMES breq - en/dis /BUSRQ input from target system cbp - CBP value on break from reset state emvbp - en/dis emulation VBP int - en/dis interrupts loc - specify monitor location mode - select operation mode proc - select processor type rrt - en/dis restriction to real time runs trst - en/dis /RESET input from target system vector - specify vector address wdt - en/dis watch dog timer on break from reset state</item>	
STATUS: T9K40Emulation resetR pod_command 'help cf'	
run trace step display modify break endETC	

The command enclosed in string delimiters (", ', or ^) is any Terminal Interface command, and the output of that command is seen in the pod_command display. The Terminal Interface help (or ?) command may be used to provide information on any Terminal Interface command or any of the emulator configuration options (as the example command above shows).

Note



Getting Started 2-7

Loading Absolute Files

The "load" command allows you to load absolute files into emulation or target system memory. You can load absolute files in the following formats:

- IEEE-695
- HP absolute(No symbols)

The "load" command has no special options for loading different absolute file formats; instead, the contents of the file are examined to determine the format being used. If you wish to load only that portion of the absolute file that resides in memory mapped as emulation RAM or ROM, use the "load emul_mem" syntax. If you wish to load only the portion of the absolute file that resides in memory mapped as target RAM, use the "load user_mem" syntax. If you want both emulation and target memory to be loaded, do not specify "emul_mem" or "user_mem". For example:

load spmt_demo <RETURN>

Note



When you use HP 64770B emulator, you must enter "break" command before you load a program. Enter the following command. break <RETURN> Note

When loading a program if the status line shows

```
"ERROR: No absolute file, No database: spmt_demo
```

, you may NOT be in the directory that your program is in. To find out what directory you are in, enter:

! pwd <RETURN> The "!" allows you to use an HP-UX shell command. To move into the correct directory, enter:

cd <directory path> <RETURN>

You can also specify the pathname where your program resides. For example, you could enter:

load

/usr/hp64000/demo/emul/hp64770/spmt_demo <RETURN>

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Displaying Symbols

When you load an absolute file into memory (unless you use the "nosymbols" syntax), symbol information is also loaded. Both global symbols and symbols that are local to a source file can be displayed.

Global To display global symbols, enter the following command.

display global_symbols <RETURN>

Listed are address ranges associated with a symbol, the segment that the symbol is associated with, and the offset of that symbol within the segment.

Global symbols in spmt_demo.x Procedure symbols Procedure name apply_controller apply_productions	Address range 000DBC - 000E0B 000CC0 - 000D13	code	_ Offset 0396 029A		
calculate_answer	000E0C - 000E53		03E6		
clear_buffer	000BEC - 000C1B		01C6		
endcommand	000EFA - 000F05		04D4		
format_result	000D14 - 000D43		02EE		
get_next_token initialze	000D80 - 000DBB 000D44 - 000D7F	code code	035A 031E		
input line	000D44 = 000D7F 000A26 = 000A57		0000		
lookup token	0000000 = 0000000000000000000000000000		0000 01F6		
main	000F06 - 000F6B		04E0		
math library	000B38 - 000BAD		0112		
move byte	000A58 - 000A83		0032		
outputline	000BAE - 000BEB	code	0188		
parse_command	000E84 - 000EBD	code	045E		
STATUS: T9K40Emulation resetR display global_symbols					
run trace step dis	play modi	fy break end	ETC		

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Local When displaying local symbols, you must include the name of the source file in which the symbols are defined. For example,

display local_symbols_in spmt_demo.c:
<RETURN>

As you can see, the procedure symbols and static symbols in "spmt_demo.c" are displayed.

To list the next symbols, press the <PGDN> or <Next> key. the source reference symbols in "spmt_demo.c" will be displayed.

Listed are: address ranges associated with a symbol, the segment that the symbol is associated with, and the offset of that symbol within the segment.

Symbols in spmt_demo(module)				
Procedure symbols		a	0.5.5	
Procedure name				
apply_controller	000DBC - 000E0B		0396	
apply_productions	000CC0 - 000D13		029A	
calculate_answer	000E0C - 000E53	code	03E6	
clear_buffer	000BEC - 000C1B	code	01C6	
endcommand	000EFA - 000F05	code	04D4	
format_result	000D14 - 000D43	code	02EE	
get_next_token	000D80 - 000DBB	code	035A	
initialze	000D44 - 000D7F	code	031E	
input_line	000A26 - 000A57	code	0000	
lookup token	000C1C - 000C55	code	01F6	
main	000F06 - 000F6B	code	04E0	
math_library	000B38 - 000BAD	code	0112	
move byte	000A58 - 000A83	code	0032	
outputline	000BAE - 000BEB	code	0188	
parse_command	000E84 - 000EBD	code	045E	
STATUS: cws: spmt_demoR display local_symbols_in spmt_demo.c:				
run trace step dis	play modi	fy break end	ETC	

Source Lines To display the address ranges associated with the program's source file, you must display the local symbols in the file. For example:

display local_symbols_in spmt_demo.c:
<RETURN>

And scroll the information down on the display with up arrow, or <Next> key.

Line range	Address range	_ Segment	Offset		
#1-#35	000A26 - 000A27	code	0000		
#36-#37	000A28 - 000A29	code	0002		
#37-#37	000A50 - 000A53	code	002A		
#37-#37	000A4E - 000A4F	code	0028		
#38-#39	000A2A - 000A2F	code	0004		
#40-#40	000A30 - 000A35	code	A000		
#41-#41	000A36 - 000A3B	code	0010		
#42-#42	000A3C - 000A41	code	0016		
#43-#43	000A42 - 000A47	code	001C		
#44-#44	000A48 - 000A4D	code	0022		
#45-#46	000A54 - 000A57	code	002E		
#47-#49	000A58 - 000A59	code	0032		
#50-#51	000A5A - 000A5B	code	0034		
#51-#51	000A70 - 000A73	code	004A		
#51-#51	000A6E - 000A6F	code	0048		
STATUS: cws: spmt_demo."spmt_demo.c":R					
display local symbols in spmt demo.c:					

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Displaying Memory in Mnemonic Format

You can display, in mnemonic format, the absolute code in memory. For example to display the memory of the demo program,

display memory main mnemonic <RETURN>

		e = spmt_demo(module)	."spmt_de	emo.c":		
address	data					
000F06	04A1					
000F08	518E	LD.W:S RW4,1				
000F0A	00D060AB00	CLR.W (000800)				
000F10	00D05420	JR 000F64				
000F14	413F	CALR 000E54				
000F16	6F3F	CALR 000E84				
000F18	00D08AB900	LD.W:A RW10,(000800)				
000F1E	0AF3	EXTS.D RD10				
000F20	05870AAF	DIVS.W:G RW10,05				
000F24	BB88	LD.W:S RW10,RW11				
000F26	A186	ADD.W:S RW10,1				
000F28	00D80AB992	LD.W:A (000992),RW10				
000F2E	00D802BF92	CP.W:A (000992),2				
000F34	00D00A18	JRC LE,000F3E				
000F38	00D803BF92	LD.W:A (000992),3				
000F3E	00D060A192	PUSH.W (000992)				
STATUS: C	ws: spmt_dem	o."spmt_demo.c":				R
display mem	ory main mne	monic				
run t	race ste	p display	modify	break	end	ETC

Notice that you can use symbols when specifying expressions. The global symbol **main** is used in the command above to specify the starting address of the memory to be displayed.

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Display Memory with Symbols

If you want to see symbol information with displaying memory in mnemonic format, the emulator Softkey Interface provides "set symbols" command. To see symbol information, enter the following command.

set	symbols	on	<return></return>
-----	---------	----	-------------------

Memory :n address		= spmt_demo(data	<pre>module)."spmt_demo.c":</pre>	
	spmt_de.main		PUSH.W RW4	
000F08			LD.W:S RW4,1	
000F0A		00D060AB00	CLR.W (zerova stack_end)	
000F10		00D05420	JR code main+00005E	
000F14		413F		
000F16		6F3F	CALR sp.parse_command	
000F18			LD.W:A RW10,(zerova stack_end)	
000F1E			EXTS.D RD10	
000F20			DIVS.W:G RW10,05	
000F24			LD.W:S RW10,RW11	
000F26			ADD.W:S RW10,1	
000F28			LD.W:A (zerovars _count),RW10	
000F2E			CP.W:A (zerovarscount),2	
000F34			JRC LE, code main+000038	
000F38			LD.W:A (zerovars _count),3	
000F3E		00D060A192	PUSH.W (zerovars _count)	
STATUS: 7 set symbols		on reset		R
SCC SYNDOIS	, 011			
run t	trace step	display	modify break end	ETC

As you can see, the memory display shows symbol information.

2-14 Getting Started
Display Memory with Source Code

If you want to reference the source line information with displaying memory in mnemonic format, the emulator Softkey Interface provides "set source" command. To reference the source line information in inverse video, enter the following command:

set source on inverse_video on <RETURN>

```
Memory :mnemonic :file = spmt_demo(module)."spmt_demo.c":
   address
            label
                            data
     371
            /************************* main program *****************/
     372
     373
     374
            main()
     375
    000F06
            spmt_de.main 04A1
                                       PUSH.W RW4
     376
                    int dummyv;
     377
                    dummyv = 1;
    000F08
                          518E
                                       LD.W:S RW4,1
     378
                    tasknumber = 0;
    000F0A
                           00D060AB00 CLR.W (zerova|stack_end)
    000F10
                           00D05420
                                      JR code main+00005E
     380
                    {
     381
                            request_command();
    000F14
                           413F
                                      CALR .request_command
                            parse_command();
     382
          T9K40--Emulation reset
STATUS:
                                                                          ...R....
set source on inverse_video on
  run
                           display
                                              modify
                                                       break
                                                                  end
                                                                         ---ETC--
          trace
                    step
```

To see the memory without source line referencing, enter the following command:

set source off <RETURN>

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Running the Program	The "run" command lets you execute a program in memory. Entering the "run" command by itself causes the emulator to begin executing at the current program counter address. The "run from" command allows you to specify an address at which execution is to start.
From Transfer Address	The "run from transfer_address" command specifies that the emulator start executing at a previously defined "start address". Transfer addresses are defined in assembly language source files with the END assembler directive (i.e., pseudo instruction). Enter: <i>run from transfer_address</i> <return></return>
From Reset	The "run from reset" command specifies that the emulator begin executing from reset vector as actual microprocessor does.
	(See "Running From Reset" section in the "In-Circuit Emulation" chapter).
Displaying Memory	The demo program "spmt_demo.c" alters memory.
Using Symbolic Addresses	In the following display, the memory range is displayed using symbolic addresses data .
	The memory display window is periodically updated. For example, enter the following command:
	display memory data thru +7fh blocked bytes <return></return>
	This command string is used to specify the range of memory from data to data+7fh .

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Memory :bytes	:access=b	ytes :bloc	ked :ı	update	5								
address	data	:hex							:as	sci	i		
000990-97	07 00	03 00	FF	49	03	00					Ι		
000998-9F	BF 55	FB 86	FF	E1	FF	FE	. τ	J.					
0009A0-A7	BF 7E	FD 7C	FF	C0	FF	8B	•	~ .					
0009A8-AF	FF F4	FF EF	FF	D7	FB	CD							
0009B0-B7	F7 79	FF AB	FF	66	FF	OF	• 3	γ.			f		
0009B8-BF	FF 75	F7 4F	FF	ЕG	FF	FF	. 1	ı.	0				
0009C0-C7	FF 6C	FF 7F	FF	7F	FF	ED		ι.					
0009C8-CF	FF F4	BF F7	DF	E8	FF	CF							
0009D0-D7	FF ED	FF 7F	FF	7E	FD	D9					~		
0009D8-DF	FF EC	FF 65	FF	FC	FF	29			е)
0009E0-E7	FF FE	F7 A7	FF	FF	FF	1F							
0009E8-EF	FF C6	F7 FF	FF	CE	FF	BF							
0009F0-F7	FF DO	FF CF	FF	EC	FF	FF							
0009F8-FF	FF E1	FF 3F	FF	EA	FF	EF			?				
000A00-07	31 OB	00 08	00	00	39	0B						9	
000A08-0F	00 08	00 00	FF	DF	00	7F					•		
STATUS: T9K40-	Running	user progr	am										R
display memory of				tes								•••	
			1										
run trace	step	display		r	nodify	breal	c	e	nd			E	TC

Modifying Memory

You can use the modify memory command to send commands to the sample program. Memory locations **stackarea** and **stackarea+10h** correspond to memory address 804 hex and 814 hex respectively. For example, to enter the '10h' at address 804 and enter 'A' at address 814 : use the following commands.

```
display memory stackarea <RETURN>
modify memory stackarea to 10h <RETURN>
modify memory stackarea+10h string to 'A'
<RETURN>
```

After the memory location are modified, the memory display shows the following

Memory :bytes	:access=b	ytes :bloc	ked :	update	3									
address	data	:hex		_					:	as	cii			
000804-0B	10 AE	FF 67	FE	97	FF	5F				g				_
00080C-13	FF AA	FF E7	FF	ЕG	FF	OF								
000814-1B	41 5E	FF 5B	FF	FA	FF	DF	А	^		[
00081C-23	F7 E3	FF BF	F7	31	FD	FF						1		
000824-2B	FE AB	FF 5B	FD	5F	FF	E9	•	•	•	[_	•	
00082C-33	FF F1	FB 1F	FF	79	FF	ED						У		
000834-3B	FF 7E	FD 5F	FF	72	FF	6D	•	~	•	_		r	•	m
00083C-43	FF F2	FF CE	FF	Еб	F7	EF	•	•	•	•		•	•	
000844-4B	FF AB	FF BC	FF	A3	FF	AF	•			•		•	•	•
00084C-53	FF F8	FF 62	FF	FA	FF	FF	•	•	•	b		•	•	;
000854-5B	FF FA	FF ED	FF	F5	FE	7B	•	•	•	•		•	•	{
00085C-63	FF F6	F5 BC	FF	FO	FF	E3	•	•	•	•		•	·	•
000864-6B	FF FA	fe 7b	FF	B8	7B	07	•	•	•	{		•	{	
00086C-73	FF 7F	FF 7E	FF	FF	FF	FE	•	•	•	~		•	•	
000874-7B	FF Bl	FE FE	FF	F9	FF	в9	•	•	•	•		•	•	•
00087C-83	FF AB	FF FF	FF	F8	BF	7E	•	•	•	•		•	•	~
STATUS: T9K40	Running	user progr	am											.R
modify memory s				,								_		
run trace	step	display		r	nodify	break			er	nd			F	STC

Breaking into the Monitor

The "break" command allows you to divert emulator execution from the user program to the monitor. You can continue user program execution with the "run" command. To break emulator execution from the demo program to the monitor, enter the following command.

break <RETURN>

Notice that the current address is pointed out with inverse video in displaying memory when the execution breaks to the monitor.

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Using Software Breakpoints	Software breakpoints are handled by the TLCS-9000 undefined instruction (breakpoint interrupt instruction:7F9Fh). When you define or enable a software breakpoint, the emulator will replace the opcode at the software breakpoint address with a breakpoint interrupt instruction.
Caution	Software breakpoints should not be set, cleared, enabled, or disabled while the emulator is running user code. If any of these commands are entered while the emulator is running user code and the emulator is executing code in the area where the breakpoint is being modified, program execution may be unreliable.
Note 🥵	You must only set software breakpoints at memory locations which contain instruction opcodes (not operands or data). If a software breakpoint is set at a memory location which is not an instruction opcode, the software breakpoint instruction will never be executed. Further, your program won't work correctly.
Note	NMI will be ignored, when software breakpoint and NMI occur at the same time.
Note	Because software breakpoints are implemented by replacing opcodes with the breakpoint interrupt instruction, you cannot define software breakpoints in target ROM. Them you can use software breakpoints.

	When software breakpoints are enabled and the emulator detects the breakpoint interrupt instruction, it generates a break into the monitor. Since the system controller knows the locations of defined software breakpoints, it can determine whether the breakpoint instruction in your target program.
	If the breakpoint interrupt was generated by a software breakpoint, execution breaks to the monitor, and the breakpoint interrupt instruction is replaced by original opcode. A subsequent run or step command will execute from this address.
	If the breakpoint interrupt was generated by a undefined instruction(7F9Fh) in the target program, execution still breaks to the monitor, and an "undefined breakpoint" status message is displayed. To continue program execution, you must run or step from the target program's breakpoint interrupt vector address.
Enabling/Disabling Software Breakpoints	When you initially enter the Softkey Interface, software breakpoints are disabled. To enable the software breakpoints feature, enter the following command.
	<pre>modify software_breakpoints enable <return></return></pre>
	When software breakpoints are enabled and you set a software breakpoint, the TLCS-9000 breakpoint interrupt instruction (7F9Fh) will be placed at the address specified. When the breakpoint interrupt instruction is executed, program execution will break into the monitor.
Setting a Software Breakpoint	To set a software breakpoint at line 80 of "spmt_demo.c", enter the following command.
	<pre>modify software_breakpoints set line 80 <return></return></pre>
	To see the address where the software breakpoint has been set, enter the following command:
	display memory line 80 mnemonic <return> set source on inverse_video on <return></return></return>

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М					module)."spmt_de	emo.c":		
		s label		data				
	80			data = 1;				
*	000ABC				illegal opcode			
	000ABB	1			LD.W:A (zerova:	rs _data),	,1	
	81			stack = 0				
	000AC2	2		00D060AB96	CLR.W (zerovars	s _stack)		
	77.2	26	for (:	i = 0; i 8;	i++)			
	000AC8	3			ADD.W:S RW4,1			
	77.1	.9	for (:	i = 0; i 8;	i++)			
	000AC#	A		04020800	CP.W:I RW4,0008	3		
	000ACE]		E81B	JRC LT, cod scar	n_number+0	00004	
	82		}					
	83		pre_fe	etch = 0;				
	000AD0)		00D060AB8E	CLR.W (zerov	pre_fetch))	
	84		pre_fe	etch = 1;				
	000AD6	5		00D801BF8E	LD.W:A (zerov]_	_pre_fetch	ı),1	
	85	}						
ST.	ATUS:	T9K40Ri	unning :	in monitor				R
di	splay me	emory line	e 80 mne	emonic				
		-						
	run	trace	step	display	modify	break	end	ETC

The asterisk (*) in left side of the address lists points out that the software breakpoint has been set. The opcode at the software breakpoint address was replaced to the software breakpoint instruction.

Displaying Software Breakpoints

To display software breakpoints, enter the following command.

display software_breakpoints <RETURN>

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addres	breakpoin s C	label	bled mo(module)	."spmt_d	emo.c":	line	80	status pending	
	T9K40R oftware_b		n monitor ts						R
run	trace	step	display		modify	break	e	nd	-ETC

The software breakpoints display shows that the breakpoint is pending. When breakpoints are hit they become inactivated. To reactivate the breakpoint so that is "pending", you must re-enter the "modify software breakpoints set" command.

After the software breakpoint has been set, enter the following command to cause the emulator to continue executing the demo program.

run <RETURN>

A message on the status line shows that the software breakpoint has been hit. The status line also shows that the emulator is now executing in the monitor.

The software breakpoint address is pointed out with inverse video in displaying memory in mnemonic format. To see the software breakpoint with memory, enter the following command.

display memory line 80 mnemonic <RETURN>

Notice that the original opcode was replaced at the address that the software breakpoint has been set.

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Clearing a Software
BreakpointTo remove software breakpoint defined above, enter the following
command.

modify software_breakpoints clear line 80
<RETURN>

The breakpoint is removed from the list, and the original opcode is restored if the breakpoint was pending.

To clear all software breakpoints, you can enter the following command.

modify software_breakpoints clear <RETURN>

Displaying Registers

Enter the following command to display registers. You can display the basic registers, or an individual register. Refer to "REGISTER CLASS and NAME" section in "Using the Emulator" chapter .

display registers <RETURN>

Registers
Next_PC 000ABC PC 000ABC CBP 01 PBP 00 PSW 00000808 [<bost (2000)="" 2="" column="" line="" line<="" rm="" th=""></bost>
STATUS: T9K40Running in monitor Software break: 0000abcR display registers
run trace step display modify break endETC

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Stepping Through the Program

The step command allows you to step through program execution an instruction or a number of instructions at a time. Also, you can step from the current program counter or from a specific address. To step through the example program from the address of the software breakpoint set earlier, enter the following command.

step <RETURN>, <RETURN>, <RETURN>, ...

You will see the inverse-video moves according to the step execution. You can continue to step through the program just by pressing the <<u>RETURN</u>> key.

Registers Next_PC 000ABC PC 000ABC CBP 01 PBP 00 PSW 00000808 [<b0>P <m0>z RW1 0000 RW2 RW7 0000 RW8 0000 RW3 0000 RW4 0000 RW5 0000 0000 RW9 0000 RW10 0002 RW11 0001 RW0 0000 RW6 0000 RW8 RW12 0003 RW13 0000 RW14 0000 RW15 0000 ISP 000007E8 USP 0000000 FP 0000000 Step_PC 000ABC LD.W:A (zerovars |_data),1 Next_PC 000AC2 PC 000AC2 CBP 01 PBP 00 PSW 00000808 [<b0>P < m0 > z0000 RW3 0000 RW0 0000 RW1 0000 RW2 RW4 0000 RW5 0000 0000 0000 RW8 0000 RW9 0000 RW10 0002 RW11 0001 RW6 RW7 RW12 0003 RW13 0000 RW14 0000 RW15 0000 FP 0000000 ISP 000007E8 USP 00000000 STATUS: T9K40--Stepping complete .R... step step display modify break end ---ETC-trace run

You can step program execution by source lines, enter:

step source <RETURN>

Source line stepping is implemented by single stepping assembly instructions until the next PC is outside of the address range of the current source line. When source line stepping is attempted on assembly code, stepping will complete when a source line is found. To terminate stepping type <Ctrl>-C.

2-24 Getting Started

Using the Analyzer	HP 64700 emulators contain an emulation analyzer. The emulation analyzer monitors the internal emulation lines (address, data, and status).
Source Line Referencing	A trace may be taken and displayed using source line referencing. Also, lines of the source program can be displayed with the trace list where the trace occurred.
	To display the trace with source code in inverse video, enter the following command:
	set source on inverse_video on <return></return>
Specifying a Simple Trigger	Suppose you want you trace program execution after the point at address semantic_check . The following command make this trace specification.
	<pre>trace after semantic_check <return></return></pre>
	The STATUS message shows "Emulation trace started.".
	Enter the following command to cause sample program execution to continue from the current program counter.
	run <return></return>
	The STATUS message shows "Emulation trace complete.".

Display the Trace The trace listings which following are of program execution on the TLCS-9000 emulator. To see the trace list, enter the following command:

Trace List Dep	th=8192 Of	fset=0				
Label: Addre	ss Data	Opcode	or Status w/ S	Source Lines	time cou	nt
Base: symbo	ls hex	-		mbols		
			############			###
}	pino_deinere	11110 200				
after =syntax ch+	00002C A1	04 INSTRU	CTIONopcode 1	unavailable		
+001 s.semantic	check Al	.04 A104			220	nS
+002 st init.s+		00 0000	read mem wor	rd	240	nS
+003 =syntax ch+			CTIONopcode	unavailable	40.	nS
+004 semantic +		04 AB04			220	nS
+005 st init.s+		D6 0DD6	read mem wo	rd	240	nS
+006 st init.s+				rd	260	nS
+007 apply con+				- 4	240	nS
	pmt_demo.c -		#######################################	*****		
	(i = 0; i]					
+008 =apply con+	•	43 ADD.W:	S DWA 1		40.	nS
+009 apply con+		43 8E43			200	nS
	pmt demo.c -		#######################################			
##########	plic_dello.c -	TTHE 792	***	*****	*****	###
STATUS: T9K40	Dunning ugon	2200000	Emulation tw	aga gammalata	П	
	Running user	program	Emulation tra	ace complete	ĸ.	• • •
display trace						
run trace	step dis	play	modify 1	break end	ETC	

display trace <RETURN>

The trace list shows the trace after line (semantic_check()).

To list the next lines of the trace, press the <PGDN> or <NEXT> key.

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Displaying Trace with No Symbol

The trace listing shown above has symbol information because of the "**set symbols on**" setting before in this chapter. To see the trace listing with no symbol information, enter the following command.

set	symbols	off	<return></return>
DCC	Dynaotb	011	AIGHT OIGHAN

Base: hex hex	Dffset=0 Opcode or Status w/ Source Lines mnemonic line 200 ##################################	relative	
after = 000C82 A104 INS	TRUCTIONopcode unavailable		
+001 000C86 A104 A		220	nS
	1000 read mem word		nS
			nS
	B04 fetch		nS
	DD6 read mem word		nS
	000 read mem word		nS
+007 000DD6 8641 8			nS
······································	line 292 ##################################	#########	##
for $(i = 0; i$			
+008 = 000DD6 8E43 ADD	.W:S RW4,1	40.	nS
+009 000DD8 8E43 8	E43 fetch	200 1	nS
#########spmt demo.c -	line 292 ##################################	#########	##
STATUS: T9K40Running user	program Emulation trace complete	R	
set symbols off	1		
run trace step di	splay modify break end	ETC-	-

As you can see, the analysis trace display shows the trace list without symbol information.

Displaying Trace with Compress Mode

If you want to see more executed instructions on a display, the TLCS-9000 emulator Softkey Interface provides **compress mode** for analysis display. To see trace display with compress mode, enter the following command:

display trace compress on <RETURN>

Trace List Depth=8192 Offset=0 Label: Address Data Opcode or Status w/ Source Line Base: hex hex mnemonic #########spmt_demo.c - line 200 ##################################	relat	ive
<pre>after = 000C82 A104 INSTRUCTIONopcode unavailable</pre>		
	460	nS
+003 = 000C84 AB04 INSTRUCTIONopcode unavailable	40.	
+005 0007EA 0DD6 0DD6 read mem word	460	nS
+006 0007EC 0000 0000 read mem word	260	nS
###########spmt_demo.c - line 292 ##################################	#############	#####
for $(i = 0; i = 1 * 3; i++)$		
+008 = 000DD6 8E43 ADD.W:S RW4,1	280	nS
###########spmt_demo.c - line 292 ##################################	#############	#####
for (i = 0; i 1 * 3; i++)		
+010 = 000DD8 1BFA CP.W:S RW4,3	260	
+012 = 000DDA AB04 JRC LT,000DD4	240	nS
##########spmt_demo.c - line 293 ###################################	#############	#####
STATUS: T9K40Running user program Emulation trace com	plete?	R
display trace compress on		
	_	
run trace step display modify break	endE	TC

As you can see, the analysis trace display shows the analysis trace lists without fetch cycles. With this command you can examine program execution easily.

If you want to see all of cycles including fetch cycles, enter following command:

display trace compress off <RETURN>

The trace display shows you all of the cycles the emulation analyzer have captured.

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Trigger the Analyzer at an Instruction Execution State

The emulator analyzer can capture states of instruction execution. If you want to trigger the analyzer when an instruction at a desired address is executed, you should not set up the analyzer trigger condition to detect the address. If you do so, the analyzer will be also triggered in case that the address is accessed to fetch the instruction, or read the data from address. You should use the execution address(eaddr) qualifier.Suppose that you want to trace the states of the execution after the instruction at *clear_buffer* of the *spmt_demo.c* file, enter the following command.

trace after eaddr clear_buffer <RETURN>

The message "Emulation trace started" will appear on the status line, and the status line now shows "Emulation trace complete".

Depth=8192 Offset=0 Trace List Label: Address Opcode or Status w/ Source Lines time count Data hex relative Base: hex mnemonic #########spmt_demo.c - line 153 thru clear_buffer() D000 INSTRUCTION--opcode unavailable 000BEC after = 460 0007E8 0000 +0020000 write mem word nS ##########spmt_demo.c - line 158 thru int i; for (i = 0; i)3; i++) 000BEE INSTRUCTION--opcode unavailable = #########spmt_demo.c - line 160 thru { data = 0;STATUS: T9K40--Running user program Emulation trace complete_ ...R.... trace after eaddr clear_buffer trace step display modify break end ---ETC-run

The emulator has disassemble capability in trace listing. When the emulator disassembles instructions in stored trace information, the fetch cycles of each instruction are required. When you displayed the results of analyzer trace, some lines which include "INSTRUCTION--opcode unavailable" message may be displayed. Each line is instruction execution cycle at the address in the left side of the displayed because the fetch states for the instructions were not stored by the analyzer.

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To display complete disassembles in the trace listing, you should modify location of trigger state in trace list, referred to as the "trigger position", to "**about**" instead of "**after**".

Displaying trace option

You can specify whether the emulator display only bus cycles, or only execution cycles, or both cycles. To specify, the TLCS-9000 emulator Softkey Interface provides display trace option. To display only bus cycles, enter the following command:

display trace mnemonic option bus_cycles_only <RETURN>

If you want to display only execution cycles, enter the following command:

display trace mnemonic option
exec_cycles_only <RETURN>

If you want to display bus cycles and execution cycles, enter the following command:

display trace mnemonic option both_cycles
<RETURN>

Emulator Analysis Status Qualifiers

The following analysis status qualifiers may also be used with the TLCS-9000 emulator.

<u>Qualifier</u>	<u>Status bits</u>
bus	0x0xxxxxxxxxxx
byte	0x010xxxxx1xxy
exec	00xxx1xxxxxxxxy
fetch	0x010x1xxxxx1xy
halt	0x011xxxxxxxxxy
intack	0x000xxxxxxxxxy
monitor	0x0xxxxxxxx0y
read	0x010xxxxxx1xy
user	0x0xxxxxxxx1y
word	0x010xxxxx0xxy
write	0x010x0xxxxx0xy

Description bus cycle byte memory cycle execute instruction program fetch halt interrupt acknowledge monitor cycle read user program cycle word memory cycle write

For a Complete Description

For a complete description of using the HP 64700 Series analyzer with the Softkey Interface, refer to the *Analyzer Softkey Interface User's Guide*.

Resetting the Emulator	To reset the emulator, enter the following command.
	reset <return></return>
Exiting the Softkey Interface	There are several options available when exiting the Softkey Interface: exiting and releasing the emulation system, exiting with the intent of re-entering (continuing), exiting locked from multiple emulation windows, and exiting (locked) and selecting the measurement system display or another module.
End Release System	To exit the Softkey Interface, releasing the emulator so that other users may use the emulator, enter the following command. end release_system <return></return>
Ending to Continue Later	You may also exit the Softkey Interface without specifying any options; this causes the emulator to be locked. When the emulator is locked, other users are prevented from using it and the emulator configuration is saved so that it can be restored the next time you enter (continue) the Softkey Interface.
Ending Locked from All Windows	When using the Softkey Interface from within window systems, the "end" command with no options causes an exit only in that window. To end locked from all windows, enter the following command. <i>end locked</i> <return> This option only appears when you enter the Softkey Interface via the</return>
	emul700 command. Refer to the <i>Softkey Interface Reference</i> manual for more information on using the Softkey Interface with window systems.

Notes



2-32 Getting Started

In-Circuit Emulation Topics

Introduction

Many of the topics described in this chapter involve the installation, and the commands which relate to using the emulator in-circuit, that is, connected to a target system or demo target board.

This chapter will:

- Show you how to install the emulation probe cable
- Show you how to install the emulation memory module.
- Show you how to install the emulation probe to demo target board.
- Describe the issues concerning the installation of the emulation probe into target systems.
- Describe how to execute program from target reset. This topics is related to program execution in general.
- Describe how to use software breakpoints with ROMed code, and how to test patches to ROMed code. These topics relate to the debugging of target system ROM.

Prerequisites

Before performing the tasks described in this chapter, you should be familiar with how the emulator operates in general. Refer to the *Concepts of Emulation and Analysis* manual and the "Getting Started" chapter of this manual.

Installing the Emulation Probe Cable

The probe cables consist of three ribbon cables. The longest cable connects to J3 of the emulation control card, and to J3 of the probe. The shortest cable connects to J1 of the emulation control card and J1 of the probe. The ribbon cables are held in place on the emulation control card by a cable clamp attached with two screws. No clamp holds the ribbon cables in the probe.

1. Secure the cable on the emulation control card with cable clamp and two screws.



Figure 3-1 Installing cables to the control board

3-2 In-Circuit Emulation Topics

2. When insert the ribbon cables into the appropriate sockets, press inward on the connector clops so that they into the sockets as shown.



Figure 3-2 Installing cables into cable sockets

3. Connect the other ends of the cable s to the emulation probe.



Figure 3-3 Installing cables to the emulation probe

3-4 In-Circuit Emulation Topics

Installing the Emulation Memory Module

There are four types of emulation memory modules that can be inserted into sockets on the probe.

1. Remove plastic rivets that secure the plastic cover on the top of the emulation probe, and remove the cover. The bottom cover is only removed when you need to replace a defective active probe on the exchange program.



Figure 3-4 Opening the emulation probe cover

2. Insert emulation memory module on the emulation probe. There is a cutout on one side of the memory modules so that they can only be installed one way.

To install memory modules, place the memory module into the socket groove at an angle. Firmly press the memory module into the socket to make sure it is completely seated. Once the memory module is seated in the connector groove, pull the memory module forward so that the notches on the socket fit into the holes on the memory module. There are two latches on the sides of the socket that hold the memory module in place.





3. Replace the plastic cover, and insert new plastic rivets to secure the cover.

3-6 In-Circuit Emulation Topics

Installing into the Demo Target Board

To connect the microprocessor connector to the demo target board, proceeded with the following instructions.

- 1. Remove front bezel and connect the power cable to the connector of the HP 64700A front panel. Refer to the *HP* 64700 Series Installation/Service manual.
- 2. With HP 64700A power OFF, connect the emulation probe to the demo target board. When you install the emulation probe into the demo target board, be careful not to bend any of the pins.

After connection the probe to the demo target board, set the TEST/TARGET MODE and SINGLE CHIP/EXTERNAL BUS MODE switches. Use TEST MODE position when you run performance verification test, and use TARGET MODE position when you run the emulator in "out-of-circuit" mode. You must set SINGLE CHIP/EXTERNAL BUS switch according to 'Processor operation mode?' configuration.





3. Connect the power cable supply wires from the emulator to demo target board. When attaching the wire cable to the demo target board, make sure the connector is aligned properly so that all three pins are connected.



Figure 3-7 Installing the power cable

3-8 In-Circuit Emulation Topics

Installing into a Target System	The TLCS-9000 emulation probe has a 135-pin PGA connector; The emulation probe is also provided with a conductive pin protector to protect the delicate gold-plated pins of the probe connector from damage due to impact.
Caution	Protect against electrostatic discharge. The emulator probe contains devices that are susceptible to damage by electrostatic discharge. Therefore, precautionary measures should be taken before handling the microprocessor connector attached to the end of the probe cable to avoid damaging the internal components of the probe by electrostatic electricity.
Caution	Make sure target system power is OFF. Do not install the emulation probe into the target system microprocessor socket with power applied to the target system. The emulator may be damaged if target system power is not removed before probe installation.
Caution	Make sure pin 1 of probe connector is aligned with pin 1 of the socket. When installing the emulation probe, be sure that probe is inserted into the processor socket so that pin 1 of the connector aligns with pin 1 of the socket. Damage to the emulator probe will result if the probe is incorrectly installed.
Caution	DO NOT use the microprocessor connector without using a pin protector. The pin protector prevents damage to the prove when inserting and removing the probe from the flexible adapter.

Caution	4	Compatibility of VOLTAGE/CURRENCY. Please be sure to check that the voltage/currency of the emulator and target system being connected are compatible. If there is a discrepancy, damage may result.
Caution	÷	Do not apply strong force to PGA-QFP probe, as that might damage the probe.
Caution	4	Turn ON power. When you start to use the 64770A/B emulator which is plugged into a target system, you must turn HP 64770A/B power ON at first, then turn target system power ON.
Caution	¢	Turn OFF power Do not turn HP 64770A/B power OFF while the emulator is plugged into a target system whose power is ON.

3-10 In-Circuit Emulation Topics

Installing into a QFP-PGA Adaptor

To connect the microprocessor connector to the target system, proceeded with the following instructions.

- 1. Attach the QFP socket/adapter(YAMAICHI IC149-120K13207-0B) on your target system.
- 2. Connect the PGA-QFP probe(64770-61602) to the emulation probe through PGA connector(1200-1840).
- 3. Install the PGA-QFP probe to the QFP socket/adaptor on your target system.



Figure 3-8 Installing into a taget system board

In-Circuit configuration Options

The TLCS-9000 emulation provides configuration options for the following in-circuit emulation issues. Refer to the "Configuring the Emulator" chapter for more information on these configuration option.

Enabling BUSRQ, NMI, RESET and INT0-7(for HP 64770A), IREQ(for HP 64770B) Input from the Target System

You can configure whether the emulator should accept or ignore the BUSRQ, NMI, RESET and INT0-7(for HP 64770A), IREQ(for HP 64770B) signals from the target system.

Running the Emulation from Target Reset

You can specify that the emulator begins execution from target system reset. When the target system **RESET** line becomes active and then inactive, the emulator will start reset sequence (option) as actual microprocessor.

At first, you must specify the emulator responds to **RESET** signal by the target system (see the "Enable **RESET** inputs from target system?" configuration in "Configuring the Emulator" chapter on this manual).

To Specify a run from target system reset, enter the following command:

run from reset <RETURN>

The status now shows that the emulator is "Awaiting target reset". After the target system is reset, the status line message will change to show the appropriate emulator status.

3-12 In-Circuit Emulation Topics

ote I	In the "Awaiting target reset" status, you can not break into the monitor. If you enter "run from reset" in the configuration that emulator ignores target system reset, you must reset the emulator.
ote	After you turn on the emulator, you must enter "reset" command and then "break" command to set the emulation stack pointer.
	The TLCS-9000 emulator supports power on reset. If you want program to be executed by power on reset, execute the following process.
	1) Enter "reset"
	2) Enter "break"
	3) Enter "run from reset"
	4) Turn OFF your target system
	4-1) If you see the p> system prompt, enter "run from reset" again.

5) Turn On your target system

Pin State in Background

While the emulator is running in the monitor, the probe pins of the emulator are in the following state.

Address Bus	Same as running user's program.
Data Bus	Same as running user's program.
$\overline{\text{BS}} \text{ R/W}$	Same as running user's program.
UB/WEH LB/WEL CAS/OE RAS0/CE0 RAS1/CE1 RAS2/CE2 RAS3/CE3	Same as running user's program except accessing monitor area. When accessing monitor area, High level.
RFSH/CE	Same as running user's program except accessing monitor area. When accessing monitor area, Low level.

3-14 In-Circuit Emulation Topics

Target System Interface



Other signals

These signals are connected to TLCS-9000 emulation processor.



Notes

3-16 In-Circuit Emulation Topics

Configuring the Emulator

Introduction

Your TLCS-9000 emulator can be used in all stages of target system development. For instance, you can run the emulator out-of-circuit when developing target system software, or you can use the emulator in-circuit when integrating software with target system hardware. Emulation memory can be used in place of, or along with, target system memory. You can use the emulator's internal clock or the target system clock. You can execute target programs in real-time or allow emulator execution to be diverted into the monitor when commands request access of target system resources (target system memory, register contents, etc.)

The emulator is a flexible instrument and it may be configured to suit your needs at any stage of the development process. This chapter describes the options available when configuring the TLCS-9000 emulator.

The configuration options are accessed with the following command.

modify configuration <RETURN>

After entering the command above, you will be asked questions regarding the emulator configuration. The configuration questions are listed below and grouped into the following classes.

Configuring the Emualtor 4-1

Δ

General Emulator Configuration:

- Restricting to real-time execution.
- Selecting processor type.
- Specifying processor operation mode.
- Specifying value of the monitor base address.
- Enabling emulation Vector Base Pointer.
- Specifying value of Vector base address.
- Specifying initial Current Bank Pointer value.

Memory Configuration:

- Mapping memory.

Emulator Pod Configuration:

- Enabling watch dog timer.
- Enabling BUSRQ input from target system.
- Enabling RESET input from target system.
- Enabling interrupt requests.
- Selecting target memory access size.

Debug/Trace Configuration:

- Enabling breaks on writes to ROM.
- Specifying tracing of user program/emulation monitor cycles.
- Selecting emulation analyzer speed.
Simulated I/O Configuration: Simulated I/O is described in the *Simulated I/O* reference manual.

Interactive Measurement Configuration: See the chapter on coordinated measurements in the *Softkey Interface Reference* manual.

Configuring the Emualtor 4-3

General Emulator Configuration	The configuration emulator operatio	questions described in this section involve general n.
Restrict to Real-Time Runs?	should take place	n allows to you specify whether program execution in real-time or whether commands should be allowed the monitor during program execution.
	no	All commands, regardless of whether or not they require a break to the emulation monitor, are accepted by the emulator.
	yes	When runs are restricted to real-time and the emulator is running the user program, all commands that cause a break (except "reset", "break", "run", and "step") are refused. For example, the following commands are not allowed when runs are restricted to real-time:
	■ I	Display/modify registers.
	∎ I	Display/modify memory.
aile.		

Caution



If your target system circuitry is dependent on constant execution of program code, you should restrict the emulator to real-time runs. This will help insure that target system damage does not occur. However, remember that you can still execute the "run", "reset", "break", and "step" commands; you should use caution in executing these commands.

4-4 Configuring the Emulator

Processor type? (HP 64770A)	This question allows you to select which microprocessor to be emulated.	
	97PS40	The TMP97PS40F, TMP97CS40F, and TMP97C241F microprocessors are emulated. When you emulate TMP97C241F microprocessor, you must specify "Processor operation mode? external_bus".
	97CM40	The TMP97CM40F microprocessor is emulated.
	97PW40	The TMP97PW40F, TMP97CW40F microprocessors are emulated.
	NONE	no valid processor is selected. This is a power up default and can not break into monitor from reset until valid processor is selected.
Processor type? (HP 64770B)	This question allows you to select which microprocessor to be emulated.	
	97CS42	The TMP97CS42, TMP97PU42(64K mode) microprocessors is emulated.
	97CU42	The TMP97CU42, TMP97PU42(96K mode) microprocessor are emulated.
	97CW42	The TMP97PW42, TMP97CW42 microprocessors are emulated.
	NONE	no valid processor is selected. This is a power up default and can not break into monitor from reset until valid processor is selected.

Configuring the Emualtor 4-5

Note	-	y processor type before operation the emulator, can not operate the emulator correctly.
Note	state and will res	onfiguration setting will drive the emulator into a reset set the memory mapping. Monitor address and vector ations will be set to their default.
Processor operation mode?	-	on allows to you specify whether operation mode is e or external bus mode.
	single	The emulator will operate in single chip mode.
	external_bus	The emulator will operate in external bus mode.
Note		lator operates in accordance with this configuration gnal from target system.
		nulator breaks into the monitor from reset state, \overline{EA} rd with this configuration.
Note	state and will res	onfiguration setting will drive the emulator into a reset set the memory mapping. Monitor address and vector ations will be set to their default.

4-6 Configuring the Emulator

Monitor base address?	monitor use and the add	aration allows you to specify the range of addresses that the s. The emulation monitor occupies 64K byte address space ress of the monitor must be located on a 64K boundary. ss range is from 10000H through 0EF0000H.	
Note	Changing this configuration setting will drive the emulator into a reset state and will reset the memory mapping. The vector address configuration will set to its default.		
Enable emulation VBP?	This configu VBP is used	aration allows you to specify whether or not the emulation	
	yes	The emulator supplies VBP value which determines the base address of the vector address. The emulator automatically initializes necessary vector entry to perform emulation tasks, emulation break, single stepping, and software breakpoint breaks.	
	no	VBP value is read from target system. The emulator does not do initializations for the vector entries to perform emulation tasks.	
Note Contraction	Changing th state.	is configuration setting will drive the emulator into a reset	
Vector base address?	Base Pointer whenever th emulation V	aration allows you to specify the value for the VBP (Vector r) to be calculated. Because this configuration is used e emulator breaks into the monitor regardless "Enable 'BP?" configuration, you must specify address which vector address.	

Configuring the Emualtor 4-7

Note



Changing this configuration setting will drive the emulator into a reset state and will reset the memory mapping.

Initial CBP value?

This configuration allows you to specify the value of CBP (Current Bank Pointer) when the emulator breaks into the monitor from reset state. When emulation VBP is enabled and first 256 byte of vector area is mapped as emulation ROM/RAM, this configuration is ignored and CBP is initialized along with the vector entry.



4-8 Configuring the Emulator

Memory Configuration	The memory configuration questions allows you to select the monitor type, to select the location of the monitor, and to map memory. To access the memory configuration questions, you must answer "yes" to the following question. Modify memory configuration?	
	Mouny memory comparation:	
Mapping Memory	The emulation memory consists of 256k, 1M, or 4Mbytes. You can define up to 7 memory range.	
	The memory mapper allows you to characterize memory locations. It allows you specify whether a certain range of memory is present in the target system or whether you will be using emulation memory for that address range. You can also specify whether the target system memory is ROM or RAM, and you can specify that emulation memory be treated as ROM or RAM.	
	The internal RAM area(if you select the single chip mode, also internal ROM area) and emulation monitor area are mapped automatically. And you can not delete these map terms. External I/O area can not be mapped as emulation memory. When you characterize memory ranges as emulation memory, note the following.	
	 When you characterize memory range which does not override 64K byte boundary as emulation memory, 64K byte is used. 	
	For example, when you characterize memory rang(1000h thru 010ffh), 64K byte of emulation memory is used.	
	■ When you characterize memory range which override N block of 64K byte as emulation memory, 64K x 2 ^M (2 ^{M-1} < N =< 2 ^M) byte is used.	
	For example, when you characterize memory range(0ff00h thru 200ffh) which overrides 3 block of 64K byte as emulation RAM, the 64K x 2^2 ($2^1 < 3 = < 2^2$:M=2) byte of emulation memory is used.	
	For examle, when 192K byte emulation memroy is remained you can not characterize memory range(80000h thru 0affffh), which is 192K byte and override 3 block of 64K byte, as	

Configuring the Emualtor 4-9

emulatoin RAM by one mapper term because the emulator needs 256K byte to map memory range(80000h thru 0affffh). In this case, you can characterize that memeoy range by two mapper term, the one is 128K byte(80000h thru 9ffffh) mapper term, the another is 64K byte(0a0000h thru 0affffh) mapper term.

Note



Target system accesses to emulation memory are not allowed. Target system devices that take control of the bus (for example, DMA controllers) cannot access emulation memory.

Blocks of memory can also be characterized as guarded memory. Guarded memory accesses will generate "break to monitor" requests. Writes to ROM will generate "break to monitor" requests if the "Enable breaks on writes to ROM?" configuration item is enabled (see the "Debug/Trace Configuration" section which follows).

Determining the Locations to be Mapped

Typically, assemblers generate relocatable files and linkers combine relocatable files to form the absolute file. The linker load map listing will show what locations your program will occupy in memory.

4-10 Configuring the Emulator

Emulator Pod Configuration	To access the emulator pod configuration questions, you must answer "yes" to the following question.		
	Modify emulator	Modify emulator pod configuration?	
Enable watch dog timer? (HP 64770A Only)	This question allows you to specify whether the watch dog timer is enabled or disabled when usr's program running.		
	yes	The emulator enables watch dog timer.	
	no	The emulator disables watch dog timer.	
Respond to BUSRQ from target system?	This configuration allows you to specify whether or not the emulator accepts BUSRQ(Bus Request) signal generated by the target system.		
	yes	The emulator accepts BUSRQ signal. When the BUSRQ is accepted, the emulator will respond as actual microprocessor.	
	no	The emulator ignore $\overline{\text{BUSRQ}}$ signal from target system completely.	
Respond to RESET from target system?	The TLCS-9000 emulator can respond or ignore target system reset while running in user program or waiting for target system reset (refer to "run from reset" command in the <i>Softkey Interface Reference</i> manual). While running in monitor, the TLCS-9000 emulator ignores target system reset completely independent on this setting.		
	yes	Specify that, this is a default configuration, make the emulator to respond to reset from target system. In this configuration, emulator will accept reset and execute from reset vector as same manner as actual microprocessor after reset is inactivated.	

Configuring the Emualtor 4-11

	no	The emulator ignores reset signal from target system completely, even while in foreground (executing user program).
Note	Changing this costate.	onfiguration option will drive the emulator into a reset
Respond to interrupts ?	This question al processor accep	lows you to specify whether or not the emulation ts interrupts.
	yes	The emulator will respond to interrupt requests from target system(NMI and INT0-3 for HP 64770A, NMI and IREQ for 64770B) and an internal peripheral during user program execution.
	no	The emulator will always ignore interrupt requests.
Note	emulator <u>is ru</u> nr monitor, NMI, I	errupts signal is enabled, it is in effect while the ning the target program. While the emulator is running INT0-7(edge sense) for HP 64770A, IREQ for HP suspended until the emulator goes into user's program.
Target memory access size	used by the mor When a comma memory or I/O,	ion specifies the type of microprocessor cycles that are nitor program to access target memory or I/O locations. nd requests the monitor to read or write to target system the monitor program will look at the access mode nine whether byte or word instructions should be used.
	bytes	Selecting the byte access mode specifies that the emulator will access target memory using byte cycles (one byte at a time).

4-12 Configuring the Emulator

words	Selecting the word access mode specifies that the emulator will access target memory using word cycles (one word at a time).
any	Selecting the any access mode specifies that the emulator will access target memory using a display/modify target memory command option. If option "words" is specified, access size will be set to "words". Other target memory commands such as "load" and "store" will use an access size of "bytes".

Debug/Trace Configuration	The debug/trace configuration questions allows you to specify breaks on writes to ROM, enable/disable the software breakpoints feature, and specify that the analyzer trace foreground/background execution. To access the debug/trace configuration questions, you must answer "yes to the following question.	
	Modify debug/tr	ace options?
Break Processor on Write to ROM?	This question allows you to specify that the emulator break to the monitor upon attempts to write to memory space mapped as ROM. The emulator will prevent the processor from actually writing to memory mapped as emulation ROM; however, they cannot prevent writes to target system RAM locations which are mapped as ROM, even though the write to ROM break is enabled.	
	yes	Causes the emulator to break into the emulation monitor whenever the user program attempts to write to a memory region mapped as ROM.
	no	The emulator will not break to the monitor upon a write to ROM. The emulator will not modify the memory location if it is in emulation ROM.

Configuring the Emualtor 4-13

N	ote
---	-----

The **wrrom** trace command status option allows you to use "write to ROM" cycles as trigger and storage qualifiers. For example, you could use the following command to trace about a write to ROM:

trace about status wrrom <RETURN>

Trace monitor or user program operation?

This question allows you to specify whether the analyzer trace only user program emulation processor cycles, only monitor cycles, or both monitor or user program cycles.

user Specifies that the analyzer trace only user program cycles. This option is specified by the default emulator configuration.
 monitor Specifies that the analyzer trace only emulation monitor cycles. (This is rarely a useful setting.)
 both Specifies that the analyzer trace both user program

Specifies that the analyzer trace both user program and emulation monitor cycles. You may wish to specify this option so that all emulation processor cycles may be viewed in the trace display.

Emulation analyzer speed? (HP 64770A Only)

This question allows you specify the emulation processor clock speed. The analyzer capabilities of time and state count are affected by the processor clock speed. If you use 64794A/C/D Deep emulation analyzer, the trace state and time counter qualifiers can be used regardless of clock speed. You must answer this question, when you use HP 64770A emulator with HP 64704A emulation bus analyzer.

slow Specifies the processor clock speed is less than or equal to 16MHz. Both state and time counting are available.

fast

Specifies the processor clock speed is greater than 16MHz. Only state counting are available.

4-14 Configuring the Emulator

Simulated I/O Configuration	The simulated I/O feature and configuration options are described in the <i>Simulated I/O</i> reference manual.	
Interactive Measurement Configuration	The interactive measurement configuration questions are described in the chapter on coordinated measurements in the <i>Softkey Interface</i> <i>Reference</i> manual. Examples of coordinated measurements that can be performed between the emulator and the emulation analyzer are found in the "Using the Emulator" chapter.	
Saving a Configuration	The last configuration question allows you to save the previous configuration specifications in a file which can be loaded back into the emulator at a later time. Configuration file name? <file></file>	
	The name of the last configuration file is shown, or no filename is shown if you are modifying the default emulator configuration. If you press <return> without specifying a filename, the configuration is saved to a temporary file. This file is deleted when</return>	
	 When you specify a filename, the configuration will be saved to two files; the filename specified with extensions of ".EA" and ".EB". The file with the ".EA" extension is the "source" copy of the file, and the file with the ".EB" extension is the "binary" or loadable copy of the file. Ending out of emulation (with the "end" command) saves the current configuration, including the name of the most recently loaded configuration file, into a "continue" file. The continue file is not normally accessed. 	

Loading a Configuration

Configuration files which have been previously saved may be loaded with the following Softkey Interface command.

load configuration <FILE> <RETURN>

This feature is especially useful after you have exited the Softkey Interface with the "end release_system" command; it saves you from having to modify the default configuration and answer all the questions again. To reload the current configuration, you can enter the following command.

load configuration <RETURN>



4-16 Configuring the Emulator

Using the Emulator

Introduction

The "Getting Started" chapter shows you how to use the basic This chapter discuss:

- Register names and classes
- Hardware breakpoint
- Vector area setting
- Analyzer topics
 - Specifying address and status for trigger or store condition
 - Specifying data for trigger or store condition
 - Specifying execute address for trigger or store condition
- Features available via "pod_command"

This chapter shows you how to:

- Store the contents of memory into absolute files
- Make coordinated measurements

REGISTER CLASS and NAME

Summary 70732 register designator. All available register class names and register names are listed below. <REG_CLASS> <REG_NAME> Description *(All basic registers) PC BASIC registers. RW0 RW1 RW2 RW3 RW4 RW5 RW6 RW7 RW8 RW9 **RW10 RW11 RW12 RW13 RW14 RW15** ISP USP FP CBP PBP PSW

5-2 Using the Emulator

PBANK (Previous bank registers)

PPC	Saved PC
PPSW	Saved PSW
PPBP	Saved PBP
1121	
PR0	pw0 on previous bank
PR1	pw1 on previous bank
PR2	pw2 on previous bank
PR3	pw3 on previous bank
PR4	pw4 on previous bank
PR5	pw5 on previous bank
PR6	pw6 on previous bank
PR7	pw7 on previous bank
PR8	pw8 on previous bank
PR9	pw9 on previous bank
PR10	pw10 on previous bank
PR11	pw11 on previous bank
PR12	pw12 on previous bank
PR13	pw13 on previous bank
PR14	pw14 on previous bank
PR15	pw15 on previous bank

SYS (System control registers) (HP 64770A Only)

WDMOD	Watch dog timer mode	
WDCR	Watch dog timer control	(Write Only)
CH0CR	Memory controller channel 0	
CH1CR	Memory controller channel 1	
CH2CR	Memory controller channel 2	
CH3CR	Memory controller channel 3	
REFHREG	Refresh control	

SYS (System control registers) (HP64770B Only)

OMR	Operation mode
PDMR	Power down mode
STBYMD	Stand-by mode
CH0CR	Memory controller channel 0
CH1CR	Memory controller channel 1
CH2CR	Memory controller channel 2
CH3CR	Memory controller channel 3
REFHREG	Refresh control

Using the Emulator 5-3

TMR (Timer registers) (HP 64770A Only)

TRUN0	Timer control (TRUN0123)	
TRUN4	Timer control (TRUN4567)	
TRDC0	Double buffer control (TRDC0123)	
TRDC4	Double buffer control (TRDC4567)	
TFFCR0	Timer flip-flop control (TFFCR0123)
TFFCR4	Timer flip-flop control (TFFCR4567	
T01MOD	Timer source clk and mode	(Write Only)
T23MOD	Timer source clk and mode	(Write Only)
T45MOD	Timer source clk and mode	(Write Only)
T67MOD	Timer source clk and mode	(Write Only)
TREG0	Timer register 0	(Write Only)
TREG1	Timer register 1	(Write Only)
TREG2	Timer register 2	(Write Only)
TREG3	Timer register 3	(Write Only)
TREG4	Timer register 4	(Write Only)
TREG5	Timer register 5	(Write Only)
TREG6	Timer register 6	(Write Only)
TREG7	Timer register 7	(Write Only)
TTORUN	Timer control 0	
TT1RUN	Timer control 1	
TT0MOD	Timer source clk and mode	
TT1MOD	Timer source clk and mode	
TT0FFCR	Timer flip-flop control	
TT1FFCR	Timer flip-flop control	
TTREG0	Timer register 0	(Write Only)
TTREG1	Timer register 1	(Write Only)
TTREG2	Timer register 2	(Write Only)
TTREG3	Timer register 3	(Write Only)
CAP1	Capture register 1	(Read Only)
CAP2	Capture register 2	(Read Only)
CAP3	Capture register 3	(Read Only)
CAP4	Capture register 4	(Read Only)

5-4 Using the Emulator

GTO (General output timer registers)(HP 64770B Only)

GTR CPRS0 CPRS1 CPRS2 CPRS3	General timer Compare reg for "Set ch0" Compare reg for "Set ch1" Compare reg for "Set ch2" Compare reg for "Set ch3"
CPRS4	Compare reg for "Set ch4"
CPRS5	Compare reg for "Set ch5"
CPRS6	Compare reg for "Set ch6"
CPRS7	Compare reg for "Set ch7"
CPRR0	Compare reg for "Reset ch0"
CPRR1	Compare reg for "Reset ch1"
CPRR2	Compare reg for "Reset ch2"
CPRR3	Compare reg for "Reset ch3"
CPRR4	Compare reg for "Reset ch4"
CPRR5	Compare reg for "Reset ch5"
CPRR6	Compare reg for "Reset ch6"
CPRR7	Compare reg for "Reset ch7"
DOMR1	Digital output mode
DOCR	Digital output control
DOR1	Digital out
LGTO	Output level of GTO
GTOEN	GTO enable

(Read Only)

Using the Emulator 5-5

GTI (General input timer registers)(HP 64770B Only)

CPCL0	Pulse conter latch 0	(Read Only)
CPCL1	Pulse conter latch 1	(Read Only)
CPCL2	Pulse conter latch 2	(Read Only)
CPCL3	Pulse conter latch 3	(Read Only)
GTA0P	GTIA positive edge 0	(Read Only)
GTA1P	GTIA positive edge 1	(Read Only)
GTA2P	GTIA positive edge 2	(Read Only)
GTA3P	GTIA positive edge 3	(Read Only)
GTA0N	GTIA negative edge 0	(Read Only)
GTA1N	GTIA negative edge 1	(Read Only)
GTA2N	GTIA negative edge 2	(Read Only)
GTA3N	GTIA nagative edge 3	(Read Only)
GTB0	GTIB edge 0	(Read Only)
GTB1	GTIB edge 1	(Read Only)
GTB2	GTIB edge 2	(Read Only)
GTB3	GTIB edge 3	(Read Only)

POUT (Pulse timer output registers)(HP 64770B Only)

TIOC	TIO control	
LPOUT	Output level of POUT	(Read Only)
DOMR2	Digital output mode	
DOR2	Digital out	
CPRD0	Compare register for Pout 0	
CPRD1	Compare register for Pout 1	
CPRD2	Compare register for Pout 2	
CPRD3	Compare register for Pout 3	
CPRD4	Compare register for Pout 4	
CPRD5	Compare register for Pout 5	
CPRD6	Compare register for Pout 6	
CPRD7	Compare register for Pout 7	



5-6 Using the Emulator

POC (Pulse output down-counter registers)(HP 64770B Only)

CPOC0	Pulse output counter of ch0
CPOC1	Pulse output counter of ch1
CPOC2	Pulse output counter of ch2
CPOC3	Pulse output counter of ch3
CPOC4	Pulse output counter of ch4
CPOC5	Pulse output counter of ch5
CPOC6	Pulse output counter of ch6
CPOC7	Pulse output counter of ch7

SC (Serial communication registers) (HP 64770A Only)

SCOCR	Serial channel 0 control
SCOMOD	Serial channel 0 mode
BR0CR	Serial channel 0 baud rate control
SCOBUF	Serial channel 0 buffer
SC1CR	Serial channel 1 control
SC1MOD	Serial channel 1 mode
BR1CR	Serial channel 1 baud rate control
SC1BUF	Serial channel 1 buffer
SC2CR	Serial channel 2 control
SC2MOD	Serial channel 2 mode
BR2CR	Serial channel 2 baud rate control
SC2BUF	Serial channel 2 buffer
ODE	Port 8 open-drain enable

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SCI (Serial interface registers) (HP 64770B Only)

SCATB	SCIA transmit buffer	(Write Only)
SCARB	SCIA receive buffer	(Read Only)
SCAMR	SCIA mode	
SCASR	SCIA status	(Read Only)
SCACR	SCIA control	
SC2TB	SCI2 transmit buffer	(Write Only)
SC2RB	SCI2 receive buffer	(Read Only)
SC2MR	SCI2 mode	
SC2SR	SCI2 status	(Read Only)
SC2CR	SCI2 control	
SCBTB	SCIB transmit buffer	(Write Only)
SCBRB	SCIB receive buffer	(Read Only)
SCBMR	SCIB mode	
SCBSR	SCIB status	(Read Only)
SCBCR	SCIB control	

SEI (Expansion serial interface registers) (HP 64770B Only)

ASCR	Asynchronous mode command	(Write Only)
ASBF	Asynchronous mode buffer	(Read Only)
AKCR	Synchronous mode command	(Write Only)
SKBF	Synchronous mode buffer	(Read Only)
SE2CR	SEI2 control & status	
SE3BO	SEI3 buffer register out	(Write Only)
SE3BI	SEI3 buffer register in	(Read Only)
SE3SFO	SEI3 shift register out	(Write Only)
SE3SFI	SEI3 shift register in	(Read Only)
SE3CR	SEI3 control	
SESR	SEI shif register	
SECR	SEI control & status	

SMP (Serial monitor port registers) (HP 64770B Only)

SMISR	SMP input shift register	(Read Only)
SMOSR	SMP output shift register	(Write Only)
SMFULL	SMP input full register	

5-8 Using the Emulator

AD (A/D converter registers) (HP 64770A Only)

ADMOD	A/D converter mode	
ADCCS	ADC channel selector	
ADREG04	AD result 04	(Read Only)
ADREG15	AD result 15	(Read Only)
ADREG26	AD result 26	(Read Only)
ADREG37	AD result 37	(Read Only)

DMA (DMA controler registers) (HP 64770B Only)

MAR0 DTCR0 MAR1 DTCR1 MAR2 DTCR2 MAR3 DTCR3 MAR4 DTCR4 MAR5 DTCR5	Memory address 0 Data transfer count 0 Memory address 1 Data transfer count 1 Memory address 2 Data transfer count 2 Memory address 3 Data transfer count 3 Memory address 4 Data transfer count 4 Memory address 5 Data transfer count 5	
	2	
		(Decid Order)
CHSR0	Channel status 0	(Read Only)
CHSR1	Channel status 1	(Read Only)
CHSR2	Channel status 2	(Read Only)

Using the Emulator 5-9

INT (Interrupt control registers) (HP 64770A Only)

INTE0	Interrupt enable 0
INTE1	Interrupt enable 1
INTE2	Interrupt enable 2
INTE3	Interrupt enable 3
INTE4	Interrupt enable 4
INTE5	Interrupt enable 5
INTE6	Interrupt enable 6
INTE7	Interrupt enable 7
INTET0	Interrupt enable 8 bit timer 0
INTET1	Interrupt enable 8 bit timer 1
INTET2	Interrupt enable 8 bit timer 2
INTET3	Interrupt enable 8 bit timer 3
INTET4	Interrupt enable 8 bit timer 4
INTET5	Interrupt enable 8 bit timer 5
INTET6	Interrupt enable 8 bit timer 6
INTET7	Interrupt enable 8 bit timer 7
INTETT0	Interrupt enable 16 bit timer TTREG0
INTETT1	Interrupt enable 16 bit timer TTREG1
INTETT2	Interrupt enable 16 bit timer TTREG2
INTETT3	Interrupt enable 16 bit timer TTREG3
INTESOR	Interrupt enable serial 0 receive
INTESOT	Interrupt enable serial 0 transmit
INTES1R	Interrupt enable serial 1 receive
INTES1T	Interrupt enable serial 1 transmit
INTES2R	Interrupt enable serial 2 receive
INTES2T	Interrupt enable serial 2 transmit
INTEAD	Interrupt enable A/D
INTETASK	Interrupt enable TASK
INMIMC	Interrupt NMI input mode control

5-10 Using the Emulator

PIC (Interrupt control registers) (HP 64770B Only)

GTICR	General timer interrupt control
TIICR0	GTI interrupt control 0
TIICR1	GTI interrupt control 1
TIICR2	GTI interuput control 2
TOICR0	GTO interrupt control 0
TOICR1	GTO interrupt control 1
TOICR2	GTO interrupt control 2
TOICR3	GTO interrupt control 3
POICR0	POUT interrupt control 0
POICR1	POUT interrupt control 1
SIOICR0	SCI interupt control
DMAICR0	SCI2 interupt control
DMAICR1	SCI3 interupt control
SWICR0	SOFTWARE interrupt control 0
SWICR1	SOFTWARE interrupt control 1
SWICR2	SOFTWARE interrupt control 2
NMIRQ	NMI interrupt request flag
GTIRQ	GT interrupt request flag
TIIRQ	Timer input interrupt request flag
TOISRQ	Timer output set interrupt request
TOIRRQ	Timer output reset interrupt request
POIRQ	Pout interrupt flag
DMAIRQ	DMA interrupt flag
SWIRQ	SWI interrupt flag

Using the Emulator 5-11

PRT (Port registers) (HP 64770A Only)

PT0	Port 0	
PT1	Port 1	
PT2	Port 2	
PT3	Port 3	
PT4	Port 4	
PT5	Port 5	
PT6	Port 6	
PT7	Port 7	
PT8	Port 8	
РТ9	Port 9	
PTA	Port A	
РТВ	Port B	
PTC	Port C	(Read Only)
POCR	Port 0 control	(Write Only)
POFC	Port 0 function	(Write Only)
P1CR	Port 1 control	(Write Only)
P1FC	Port 1 function	(Write Only)
P2CR	Port 2 control	(Write Only)
P2FC	Port 2 function	(Write Only)
P3CR	Port 3 control	(Write Only)
P3FC	Port 3 function	(Write Only)
P4CR	Port 4 control	(Write Only)
P4FC	Port 4 function	(Write Only)
P5CR	Port 5 control	(Write Only)
P5FC	Port 5 function	(Write Only)
P6CR	Port 6 control	(Write Only)
P6FC	Port 6 function	(Write Only)
P7CR	Port 7 control	(Write Only)
P7FC	Port 7 function	(Write Only)
P8CR	Port 8 control	(Write Only)
P8FC	Port 8 function	(Write Only)
P9CR	Port 9 control	(Write Only)
P9FC	Port 9 function	(Write Only)
PACR	Port A control	(Write Only)
PAFC	Port A function	(Write Only)
PBCR	Port B control	(Write Only)
PBFC	Port B function	(Write Only)



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PRT (Port registers) (HP 64770B Only)

P0	Port 0 data
P1	Port 1 data
P2	Port 2 data
P3	Port 3 data
P4	Port 4 data
P5	Port 5 data
P6	Port 6 data
P9	Port 9 data
PJ	Port J data
PF	Port F data
PG	Port G data
PM	Port M data
PH	Port H data
PS	Port S data
POCR	Port 0 control
POFC	Port 0 function
P1CR	Port 1 control
P1FC	Port 1 function
P2CR	Port 2 control
P2FC	Port 2 function
P3CR	Port 3 control
P3FC	Port 3 function
P4CR	Port 4 control
P4FC	Port 4 function
P5CR	Port 5 control
P5FC	Port 5 function
P6CR	Port 6 control
P6FC	Port 6 function
P9CR	Port 9 control
PJCR	Port J control
PFCR	Port F control
PGCR	Port G control
PMCR	Port M control
PHCR	Port H control
PSCR	Port S control

(Write Only)



PFSR0	Port function select 0	
PFSR1	Port function select 1	
PFSR2	Port function select 2	
PFSR3	Port function select 3	
PFSR4	Port function select 4	(Write Only)
PFSR5	Port function select 5	
PFSR6	Port function select 6	

OTHER (Other registers)

RB0	RB0
RB1	RB1
RB2	RB2
RB3	RB3
RB4	RB4
RB5	RB5
RB6	RB6
RB7	RB7
RB8	RB8
RB9	RB9
RB10	RB10
RB11	RB11
RB12	RB12
RB13	RB13
RB14	RB14
RB15	RB15
RD0	RD0
RD2	RD2
RD4	RD4
RD6	RD6
RD8	RD8
RD10	RD10
RD12	RD12
RD14	RD14
USPL	lower 16 bits of USP
USPH	upper 16 bits of USP
FPL	lower 16 bits of FP
FPH	upper 16 bits of FP

5-14 Using the Emulator

Hardware Breakpoints	The analyzer may generate a break request to the emulation processor. To break when the analyzer trigger condition is satisfied, use the "break_on_trigger" trace option. Additionally, you can see the program states before the breakpoint in trace listing. Specify the trigger position at the end of trace listing by using "before" option.
	When the trigger condition is found. the emulator execution will break into the emulation monitor. Then you can also see the trace listing mentioned above, enter the following commands. trace before <qualifier> break_on_trigger<return></return></qualifier>
	Without the trigger condition, the trigger will never occur and will never break.
Vector Area Setting	TLCS-9000 microprocessor has vector area(2k bytes). TLCS-9000 emulator uses three vector entry in vector area to realize the following emulator features.
	 Break Single-Step Software Break Point
Single Chip Mode	If you use the TLCS-9000 emulator in single chip mode, you do not need to set the vector entry since the emulator set automatically. The values of PC, PSW, and CBP are set by vector entry when the emulator breaks into the monitor from reset state.
External Bus Mode	IF you use the TLCS-9000 emulator in external bus mode, the way of the emulator's operations differ according to "Enable emulation VBP?" configuration and memory mapping.

"Enable emulation VBP? yes"

The emulator read Vector Base Pointer(VBP) from emulation VBP. When the emulator breaks into the monitor from reset state, the value of emulation VBP is specified by "Vector base address?" configuration.

If vector area are mapped as emulation memory, the emulator sets the vector entry when the emulator breaks into the monitor from reset state. When the emulator breaks into the monitor from reset state, the values of PC, PSW, and CBP are set by vector entry.

If vector area are mapped as target memory, the emulator uses copy of vector area. The emulator copies data of vector ares when the emulator breaks into the monitor from reset state, and then sets the vector entry. When the emulator breaks into the monitor from reset, the value of PC, and PSW are set by vector entry and the value of CBP is specified by "Initial CBP value?" configuration.

"Enable emulation VBP? no"

In this case, the emulator does not set the vector entry. So you must set up the vector entry to realize the emulator features. If you do not set the vector entry, the emulator can not operate correctly.

Even if you specify that "Enable emulation VBP? no", the value of PC, PSW, and CBP are specified in the same way as you specify that "Enable emulation VBP? yes" when the emulator breaks into the monitor from reset state.

Vector number	Offset	value	Purpose
12	60H	0000H	Break
	62H	0202H	
	64H	00xxH	
	66H	0000H	
Vector number	Offset	value	Purpose

Set the vector area as following.

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14	70H	0000H	Step
	72H	0204H	
	74H	00xxH	
	76H	0000H	
31	F8H	0000H	Software break
	FAH	0200H	point
	FCH	00xxH	
	FEH	0000H	

xx: Upper 8 bits of monitor area

Analyzer Topics

Specifying Address and Status for Trigger or Store Condition

The analyzer captures the actual bus states and execute states by exclusive bus. In some case, bus state and execute state are captured simultaneously. To specify actual bus states for trigger or store condition by "address", "status", and "data", you should add "status bus" condition to trigger/store condition as following.

trace after address 1000h status bus<RETURN>
trace after status write and bus

Specifying Data for
Trigger or Store
ConditionThe analyzer captures the actual bus states of the TLCS-9000
microprocessor. When you specify a data in the analyzer trigger or
store condition, the ways of analyzer data specification differ according
to the address and the data size.

To trigger analyzer when the TLCS-9000 microprocessor accesses the byte data 12h at address 1000h(even address), enter the following,

trace after address 1000h data $0 \mathrm{xx12h}$ status bus and byte

To trigger analyzer when the TLCS-9000 microprocessor accesses the byte data 12h at address 1001h(odd address), enter the following,

trace after address 1001h data 012xxh status bus and byte

To trigger analyzer when the TLCS-9000 microprocessor accesses the word data 1234h at address 1001h(odd address), the data bus activity of cycles will be as follows.

Sequencer level Address bus Data bus 1 1001 34xx2 1002 xx12 In this case, you need to use the analyzer sequential trigger capabilities. We do not describe the detail about the sequential trigger feature. Only how to trigger the analyzer at this example is described. To specify the condition, enter; trace find_sequence 1001h data 34xxh status bus trigger after 1002h data 0xx12h status **bus** <RETURN> **Specifying Execute** To specify "eaddr" for trigger or store condition, you must specify even **Address for Trigger** addresses as execute address. To trigger analyzer when TLCS-9000 microprocessor executes instruction at address 2000h, enter the or Store Condition following,

trace after eaddr 2000h <RETURN>

5-18 Using the Emulator

Features Available via Pod Commands

Several emulation features available in the Terminal Interface but not in the Softkey Interface may be accessed via the following emulation commands.

```
display pod_command <RETURN>
pod_command '<Terminal Interface command>'
<RETURN>
```

Some of the most notable Terminal Interface features not available in the Softkey Interface are:

- Searching memory for strings or numeric expressions.
- Sequencing in the analyzer.

Refer to your Terminal Interface documentation for information on how to perform these tasks.

Note

Be careful when using the "pod_command". The Softkey Interface, and the configuration files in particular, assume that the configuration of the HP 64700 pod is NOT changed except by the Softkey Interface. Be aware that what you see in "modify configuration" will NOT reflect the HP 64700 pod's configuration if you change the pod's configuration with this command. Also, commands which affect the communications channel should NOT be used at all. Other commands may confuse the protocol depending upon how they are used. The following commands are not recommended for use with "pod_command":

stty, po, xp - Do not use, will change channel operation and hang.
echo, mac - Usage may confuse the protocol in use on the channel.
wait - Do not use, will tie up the pod, blocking access.
init, pv - Will reset pod and force end release_system.
t - Do not use, will confuse trace status polling and unload.0h)0



Storing Memory Contents to an Absolute File	The "Getting Started" chapter shows you how to load absolute files into emulation or target system memory. You can also store emulation or target system memory to an absolute file with the following command.	
	<pre>store memory 800h thru 84fh to absfile <return></return></pre>	
	The command above causes the contents of memory locations 800H-84FH to be stored in the absolute file "absfile.X". Notice that the ".X" extension is appended to the specified filename.	
Coordinated Measurements	For information on coordinated measurements and how to use them, refer to the "Coordinated Measurements" chapter in the <i>Softkey Interface Reference</i> manual.	



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