

[illegible]

3

Sy

MT

MT
MT

MT

MT

MT
MTMT
MTMT
MTMT
MT

MT
MT

MT
MT

MT

MT

MT
MT

MI
MT

MT
MT

MT
MT

MT
MT

MT
MT

MT

111
227

MT

MT
MT

MT

MT

M1
M1MT
MT

M1

M1

10

1

10

100

10

1

★★

```

LL               IIIIII               SSSSSSSS
LL               IIIIII               SSSSSSSS
LL               II                  SS
LL               II                  SS
LL               II                  SS
LL               II                  SS
LL               II                  SSSSSS
LL               II                  SSSSSS
LL               II                  SS
LL               II                  SS
LL               II                  SS
LL               II                  SS
LLLLLLLLLLLLLL  IIIIII               SSSSSSSS
LLLLLLLLLLLLLL  IIIIII               SSSSSSSS

```


MTH\$DTAN
Table of contents

G 1
; Double Precision Floating Point Tangen 16-SEP-1984 01:22:34 VAX/VMS Macro V04-00

Page 0

(2)	54	HISTORY ; Detailed Current Edit History
(3)	91	DECLARATIONS ; Declarative Part of Module
(4)	132	MTH\$DTAN - Standard Double Precision Floating DTAN
(5)	175	MTH\$DTAN_R7 - JSB entry point
(6)	221	MTH\$DTAND - Standard Double Precision Floating DTAND
(7)	264	MTH\$DTAND_R7 - JSB entry point

```
0000 1      .TITLE  MTH$DTAN      ; Double Precision Floating Point Tangent routine
0000 2      ; (DTAN, DTAND)
0000 3      .IDENT  /1-013/      ; File: MTHDTAN.MAR  EDIT:SBL1013
0000 4      ;
0000 5      ;*****
0000 6      ;
0000 7      ;*  COPYRIGHT (c) 1978, 1980, 1982, 1984 BY
0000 8      ;*  DIGITAL EQUIPMENT CORPORATION, MAYNARD, MASSACHUSETTS.
0000 9      ;*  ALL RIGHTS RESERVED.
0000 10     ;*
0000 11     ;*  THIS SOFTWARE IS FURNISHED UNDER A LICENSE AND MAY BE USED AND COPIED
0000 12     ;*  ONLY IN ACCORDANCE WITH THE TERMS OF SUCH LICENSE AND WITH THE
0000 13     ;*  INCLUSION OF THE ABOVE COPYRIGHT NOTICE. THIS SOFTWARE OR ANY OTHER
0000 14     ;*  COPIES THEREOF MAY NOT BE PROVIDED OR OTHERWISE MADE AVAILABLE TO ANY
0000 15     ;*  OTHER PERSON. NO TITLE TO AND OWNERSHIP OF THE SOFTWARE IS HEREBY
0000 16     ;*  TRANSFERRED.
0000 17     ;*
0000 18     ;*  THE INFORMATION IN THIS SOFTWARE IS SUBJECT TO CHANGE WITHOUT NOTICE
0000 19     ;*  AND SHOULD NOT BE CONSTRUED AS A COMMITMENT BY DIGITAL EQUIPMENT
0000 20     ;*  CORPORATION.
0000 21     ;*
0000 22     ;*  DIGITAL ASSUMES NO RESPONSIBILITY FOR THE USE OR RELIABILITY OF ITS
0000 23     ;*  SOFTWARE ON EQUIPMENT WHICH IS NOT SUPPLIED BY DIGITAL.
0000 24     ;*
0000 25     ;*
0000 26     ;*****
0000 27     ;
0000 28     ;
0000 29     ; FACILITY: MATH LIBRARY
0000 30     ;++
0000 31     ; ABSTRACT:
0000 32     ;
0000 33     ; MTH$DTAN is a function which returns the double precision floating point
0000 34     ; tangent of its double precision floating point radian argument. The call is
0000 35     ; standard call-by-reference. It JSB to MTH$DTAN_R7.
0000 36     ;
0000 37     ; MTH$DTAND is a function which returns the double precision floating point
0000 38     ; tangent of its double precision floating point degree argument. The call is
0000 39     ; standard call-by-reference. It JSB to MTH$DTAND_R7.
0000 40     ;
0000 41     ;--
0000 42     ;
0000 43     ; VERSION: 01
0000 44     ;
0000 45     ; HISTORY:
0000 46     ; AUTHOR:
0000 47     ; Peter Yuo, 29-Jun-77: Version 01
0000 48     ;
0000 49     ; MODIFIED BY:
0000 50     ;
0000 51     ;
0000 52     ;
```



```
0000 54      .SBTTL HISTORY ; Detailed Current Edit History
0000 55
0000 56
0000 57 : ALGORITHMIC DIFFERENCES FROM FP-11/C ROUTINE: none
0000 58 :
0000 59 :     The result is reserved operand when DCOS(X) = 0, instead
0000 60 :     of largest or smallest representable floating number.
0000 61 :
0000 62 : Edit History for Version 01 of MTH$DTAN
0000 63 :
0000 64 : 01-2 Error handling mechanism changed. Instead of having
0000 65 :     MTH$FLG JACKET at the entrance, MTH$$ERROR_CONT is stored on the
0000 66 :     top of the stack frame so when error happened in MTH$DSIN or MTH$DCOS
0000 67 :     the message will be hid away, but will get signalled in MTH$DTAN.
0000 68 : 0-3 MTH$$ERROR changed to MTH$$SIGNAL.
0000 69 :     MTH$$ERROR_CONT changed to MTH$$SIGNAL_CON
0000 70 :     MTH$... changed to MTH
0000 71 :     Changed error handling mechanism. Put error result in R0:R1 before
0000 72 :     calling MTH$$SIGNAL in order to allow user modify error result.
0000 73 : 1-001 - Update version number and copyright notice. JBS 16-NOV-78
0000 74 : 1-002 - Changed MTH_FLOOVEMAT to MTH$K_FLOOVEMAT. JBS 06-DEC-78
0000 75 : 1-003 - Removed $SRMDEF macro - not needed. JBS 16-DEC-78
0000 76 : 1-004 - Add "" to the PSECT directive. JBS 22-DEC-78
0000 77 : 1-005 - Declare externals. SBL 17-May-1979
0000 78 : 1-006 - Rearrange code to handle exceptions correctly. SBL 17-May-1979
0000 79 : 1-007 - Add JSB entry point. JBS 16-AUG-1979
0000 80 : 1-008 - Signal exceptions correctly. JBS 16-AUG-1979
0000 81 : 1-009 - Correct a typo in edit 007. JBS 17-AUG-1979
0000 82 : 1-010 - Make CALL entry use JSB routine. Correct error handling.
0000 83 :     Do COS before SIN. SBL 31-Oct-1979
0000 84 : 1-011 - Added degree entry points. RNH 8-MAR-1981
0000 85 : 1-012 - Modify MTH$DTAN_R7 and MTH$DTAND_R7 to JSB to MTH$DSINCOS_R7 and
0000 86 :     MTH$DSINCOSD_R7 instead of MTH$DSIN_R7, MTH$DCOS_R7, and
0000 87 :     MTH$DSIND_R7, MTH$DCOSD_R7. RNH 27-AUG-81.
0000 88 : 1-013 - Use general mode addressing. SBL 30-Nov-1981
0000 89 :
```

```
0000 91      .SBTTL  DECLARATIONS      ; Declarative Part of Module
0000 92
0000 93      ;
0000 94      ; INCLUDE FILES:
0000 95      ;
0000 96      ;
0000 97      ;
0000 98      ; EXTERNAL SYMBOLS:
0000 99      ;
0000 100     .DSABL  GBL
0000 101     .EXTRN  MTH$DSINCOS_R7
0000 102     .EXTRN  MTH$DSINCOSD_R7
0000 103     .EXTRN  MTH$K_FLOOVEMAT
0000 104     .EXTRN  MTH$$SIGNAL
0000 105     .EXTRN  MTH$K_FLOUNDMAT
0000 106     .EXTRN  MTH$$JACKET_TST
0000 107
0000 108      ;
0000 109     ; EQUATED SYMBOLS:      none
0000 110      ;
0000 111     ; MACROS:
0000 112
0000 113     $SFDEF                      ; Define SF (Stack Frame) symbols
0000 114
0000 115      ;
0000 116     ; PSECT DECLARATIONS:
0000 117
00000000 118     .PSECT  _MTH$CODE      PIC,SHR,LONG,EXE,NOWRT
0000 119                                     ; program section for math routines
0000 120      ;
0000 121     ; OWN STORAGE:  none
0000 122      ;
0000 123     ; CONSTANTS:
0000 124
00000004 125     X = 4                      ;Position of argument from AP.
0000 126
0000 127     D_SMALLEST_DEG:
2EE04365 128     .LONG  ^X2EE04365
0FBED31E 129     .LONG  ^X0FBED31E
0008 130
```



```
0008 132      .SBTTL MTH$DTAN - Standard Double Precision Floating DTAN
0008 133
0008 134
0008 135 :++
0008 136 : FUNCTIONAL DESCRIPTION:
0008 137 :
0008 138 : DTAN - double precision floating point function
0008 139 :
0008 140 :     For algorithm, see MTH$DTAN_R7.
0008 141 :
0008 142 : CALLING SEQUENCE:
0008 143 :
0008 144 :     DTAN.wd.v = MTH$DTAN(x.rd.r)
0008 145 :
0008 146 : INPUT PARAMETERS:
0008 147 :
0008 148 :     X.rd.r                      Address of value of angle in radians.
0008 149 :
0008 150 : IMPLICIT INPUTS:      none
0008 151 :
0008 152 : OUTPUT PARAMETERS:
0008 153 :
0008 154 :     VALUE: double precision floating tangent of the argument
0008 155 :
0008 156 : IMPLICIT OUTPUTS:    none
0008 157 :
0008 158 : COMPLETION CODES:    none
0008 159 :
0008 160 : SIDE EFFECTS:
0008 161 :
0008 162 :     See MTH$DTAN_R7
0008 163 :
0008 164 : ---
0008 165
40FC 0008 166      .ENTRY MTH$DTAN, ^M<IV, R2, R3, R4, R5, R6, R7>
000A 167                      ; standard call-by-reference entry
000A 168                      ; disable DV (and FU), enable IV
000A 169
000A 170      MTH$FLAG_JACKET
6D 00000000'GF 9E 000A      MOVAB G^MTH$$JACKET_HND, (FP)
0011                      ; set handler address to jacket
0011                      ; handler
0011
50 04 BC 70 0011 171      MOVD @X(AP), R0          ; R0/R1 = argument
01 10 0015 172      BSBB MTH$DTAN_R7          ; Get the tangent
04 0017 173      RET                          ; With result in R0-R1
```

```
0018 175 .SBTTL MTH$DTAN_R7 - JSB entry point
0018 176 :
0018 177 :++
0018 178 : FUNCTIONAL DESCRIPTION:
0018 179 :
0018 180 : DTAN - JSB entry point
0018 181 :
0018 182 : Algorithmic steps:
0018 183 : 1. Compute DSIN and DCOS.
0018 184 : 2. If DCOS is zero, we have an error.
0018 185 : 3. Return DSIN / DCOS.
0018 186 :
0018 187 : CALLING SEQUENCE:
0018 188 :
0018 189 :     MOVD    argument, R0
0018 190 :     JSB     MTH$DTAN_R7
0018 191 :
0018 192 : INPUT PARAMETERS:
0018 193 :
0018 194 :     R0 / R1 contains X
0018 195 :
0018 196 : IMPLICIT INPUTS:
0018 197 :
0018 198 :     NONE
0018 199 :
0018 200 : OUTPUT PARAMETERS:
0018 201 :
0018 202 :     The result is the tangent of X, in double precision.
0018 203 :
0018 204 : IMPLICIT OUTPUTS:
0018 205 :
0018 206 :     NONE
0018 207 :
0018 208 : SIDE EFFECTS:
0018 209 :
0018 210 :
0018 211 : --
0018 212 MTH$DTAN_R7::
0018 213 JSB     G^MTH$DSINCOS_R7      ; Compute DSIN(X) and DCOS(X)
001E 214 TSTD    R2                  ; Is DCOS(X) zero ?
0020 215 BEQL    COSZER                ; If yes, then go to common error path
0022 216 DIVD2   R2, R0                ; Compute DSIN / DCOS
0025 217 RSB
0026 218
0026 219
```

00000000'GF 16
52 73
62 13
50 52 66
05 0022 216
0025 217
0026 218
0026 219


```
0026 221 .SBTTL MTH$DTAND - Standard Double Precision Floating DTAND
0026 222
0026 223
0026 224 :++
0026 225 : FUNCTIONAL DESCRIPTION:
0026 226 :
0026 227 : DTAND - double precision floating point function
0026 228 :
0026 229 : For algorithm, see MTH$DTAND_R7.
0026 230 :
0026 231 : CALLING SEQUENCE:
0026 232 :
0026 233 : DTAND.wd.v = MTH$DTAND(X.rd.r)
0026 234 :
0026 235 : INPUT PARAMETERS:
0026 236 :
0026 237 : X.rd.r ;Address of value of angle in degrees.
0026 238 :
0026 239 : IMPLICIT INPUTS: none
0026 240 :
0026 241 : OUTPUT PARAMETERS:
0026 242 :
0026 243 : VALUE: double precision floating tangent of the argument
0026 244 :
0026 245 : IMPLICIT OUTPUTS: none
0026 246 :
0026 247 : COMPLETION CODES: none
0026 248 :
0026 249 : SIDE EFFECTS:
0026 250 :
0026 251 : See MTH$DTAND_R7
0026 252 :
0026 253 :---
0026 254 :
0026 255 :
40FC 0026 256 .ENTRY MTH$DTAND, ^M<IV, R2, R3, R4, R5, R6, R7>
0028 257 ; standard call-by-reference entry
0028 258 ; disable DV (and FU), enable IV
0028 259 MTH$FLAG_JACKET
0028
6D 00000000'GF 9E 0028 MOVAB G^MTH$$JACKET_HND, (FP)
002F ; set handler address to jacket
002F ; handler
002F
50 04 BC 70 002F 260 MOVD @X(AP), R0 ; R0/R1 = argument
01 10 0033 261 BSBB MTH$DTAND_R7 ; Get the tangent
04 0035 262 RET ; With result in R0-R1
```

```
0036 264 .SBTTL MTH$DTAND_R7 - JSB entry point
0036 265 :
0036 266 :++
0036 267 : FUNCTIONAL DESCRIPTION:
0036 268 :
0036 269 : DTAND - JSB entry point
0036 270 :
0036 271 : Algorithmic steps:
0036 272 : 1. Make sure that the absolute value of the argument is greater
0036 273 :    than 180/pi*2*128
0036 274 : 2. Compute DSIND and DCOSD.
0036 275 : 3. If DCOSD is zero, we have an error.
0036 276 : 4. Return DSIND / DCOSD.
0036 277 :
0036 278 : CALLING SEQUENCE:
0036 279 :
0036 280 :     MOVD    argument, R0
0036 281 :     JSB     MTH$DTAND_R7
0036 282 :
0036 283 : INPUT PARAMETERS:
0036 284 :
0036 285 :     R0 / R1 contains x
0036 286 :
0036 287 : IMPLICIT INPUTS:
0036 288 :
0036 289 :     NONE
0036 290 :
0036 291 : OUTPUT PARAMETERS:
0036 292 :
0036 293 :     The result is the tangent of x, in double precision.
0036 294 :
0036 295 : IMPLICIT OUTPUTS:
0036 296 :
0036 297 :     NONE
0036 298 :
0036 299 : SIDE EFFECTS:
0036 300 :
0036 301 :     NONE
0036 302 : --
0036 303 MTH$DTAND_R7::
0036 304     MOVD    R0, R2
0036 305     BICW    #^X8000, R2
0036 306     CMPW    #^X0300, R2
0036 307     BLEQ    20$
0036 308     CMPD    D_SMALLEST_DEG, R2
0036 309     BLSS    20$
0036 310     TSTD    R2
0036 311     BNEQ    UNFL
0036 312     CLRD    R0
0036 313     RSB
0036 314 20$:
0036 315     JSB     G^MTH$DSINCOSD_R7
0036 316     TSTD    R2
0036 317     BEQL    COSZER
0036 318     DIVD2   R2, R0
0036 319     RSB
0036 320

52      52      50      70      0036 304     MOVD    R0, R2
52      8000 8F      AA      0039 305     BICW    #^X8000, R2
52      0300 8F      B1      003E 306     CMPW    #^X0300, R2
52      B8 AF      71      0043 307     BLEQ    20$
52      07      19      0045 308     CMPD    D_SMALLEST_DEG, R2
52      73      07      0049 309     BLSS    20$
52      11      12      004B 310     TSTD    R2
52      7C      05      004D 311     BNEQ    UNFL
52      05      05      004F 312     CLRD    R0
52      05      05      0051 313     RSB
52      05      05      0052 314 20$:
00000000 GF      16      0052 315     JSB     G^MTH$DSINCOSD_R7
52      73      05      0058 316     TSTD    R2
52      13      05      005A 317     BEQL    COSZER
52      66      05      005C 318     DIVD2   R2, R0
52      05      05      005F 319     RSB
52      05      05      0060 320
```

```
: Save argument
: R2/R3 = |argument|
: Compare |arg| with 2**-121
: No possible underflow, compute DCOSD
: Possible underflow, use better check
: No possible underflow, compute DCOSD
: Check for argument = 0
: If arg not 0, go to underflow logic
: Load R0/R1 with zero
: Return with value = 0
```

```
: Compute DSIND(X), and DCOSD(X)
: Is DCOSD(X) zero?
: If yes, then go to common error path
: Compute DSIND / DCOSD
: Return.
```


MTH\$DTAN
1-013

: Double Precision Floating Point ^{B 2} Tangen 16-SEP-1984 01:22:34 VAX/VMS Macro V04-00
MTH\$DTAND_R7 - JSB entry point 6-SEP-1984 11:22:54 [MTHRTL.SRC]MTHDTAN.MAR;1

Page 8
(7)

0060 321

MT
VA
MA

```
0060 323 :  
0060 324 :  
0060 325 :  
0060 326 :  
0060 327 :  
0060 328 : Underflow; if user has FU set, signal error. Always return 0.0  
0060 329 :  
0060 330 UNFL:  
00000000'GF 52 DC 0060 331 MOVPSL R2 ; R2 = user's or jacket routine's PSL  
04 00 FB 0062 332 CALLS #0, G^MTH$$JACKET_TST ; R0 = TRUE if JSB from jacket routine  
52 04 50 E9 0069 333 BLBC R0, 10$ ; branch if user did JSB  
04 AD 3C 006C 334 MOVZWL SF$W_SAVE_PSW(FP), R2 ; get user PSL saved by CALL  
50 D4 0070 335 10$: CLRL R0 ; R0 = result. LIB$SIGNAL will save in  
0D 52 06 E1 0072 336 ; CHF$L_MCH_R0/R1 so any handler can fixup  
6E DD 0076 337 BBC #6, R2, 20$ ; has user enabled floating underflow?  
7E 00'8F 9A 0078 338 PUSHL (SP) ; yes, return PC from special routine  
007C 339 MOVZBL #MTH$K_FLOUNDMAT, -(SP) ; trap code for hardware floating underflow  
007C 340 ; convert to MTH$FLOUNDMAT (32-bit VAX-11  
007C 341 ; exception code)  
00000000'GF 02 FB 007C 342 CALLS #2, G^MTH$$SIGNAL ; signal (condition, PC)  
05 0083 343 20$: RSB ; return  
0084 344 :  
0084 345 :+  
0084 346 : Come here if COS value is zero.  
0084 347 :-  
0084 348 COSZER:  
7E 00'8F 6E DD 0084 349 PUSHL (SP) ; Push 'caller' PC  
50 01 0F 9A 0086 350 MOVZBL #MTH$K_FLOOVEMAT, -(SP) ; Condition value  
00000000'GF 02 FB 008A 351 ASHQ #15, #T, R0 ; R0/R1 = reserved operand  
05 008E 352 CALLS #2, G^MTH$$SIGNAL ; Signal an error  
0095 353 RSB ; Return to caller  
0096 354  
0096 355 .END
```


MTH\$DTAN
Symbol table

D 2
; Double Precision Floating Point Tangen 16-SEP-1984 01:22:34 VAX/VMS Macro V04-00
6-SEP-1984 11:22:54 [MTHRTL.SRC]MTHDTAN.MAR;1

Page 10
(8)

```
COSZER      00000084 R    02
D_SMALLEST_DEG 00000000 R    02
MTH$$JACKET_HND ***** X    02
MTH$$JACKET_TST ***** X    00
MTH$$SIGNAL     ***** X    00
MTH$DSINCOSD_R7 ***** X    00
MTH$DSINCOS_R7  ***** X    00
MTH$DTAN       00000008 RG   02
MTH$DTAND      00000026 RG   02
MTH$DTAND_R7   00000036 RG   02
MTH$DTAN_R7    00000018 RG   02
MTH$K_FLOOVEMAT ***** X    00
MTH$K_FLOUNDMAT ***** X    00
SFSW_SAVE_PSW  = 00000004
UNFL          00000060 R    02
X              = 00000004
```

+-----+
! Psect synopsis !
+-----+

PSECT name	Allocation	PSECT No.	Attributes
. ABS .	00000000 (0.)	00 (0.)	NOPIC USR CON ABS LCL NOSHR NOEXE NORD NOWRT NOVEC BYTE
\$AB\$\$	00000000 (0.)	01 (1.)	NOPIC USR CON ABS LCL NOSHR EXE RD WRT NOVEC BYTE
_MTH\$CODE	00000096 (150.)	02 (2.)	PIC USR CON REL LCL SHR EXE RD NOWRT NOVEC LONG

+-----+
! Performance indicators !
+-----+

Phase	Page faults	CPU Time	Elapsed Time
Initialization	33	00:00:00.09	00:00:00.84
Command processing	112	00:00:00.70	00:00:06.99
Pass 1	121	00:00:01.46	00:00:06.06
Symbol table sort	0	00:00:00.03	00:00:00.13
Pass 2	74	00:00:00.90	00:00:03.69
Symbol table output	3	00:00:00.02	00:00:00.25
Psect synopsis output	2	00:00:00.03	00:00:00.33
Cross-reference output	0	00:00:00.00	00:00:00.00
Assembler run totals	347	00:00:03.23	00:00:18.30

The working set limit was 900 pages.
6631 bytes (13 pages) of virtual memory were used to buffer the intermediate code.
There were 10 pages of symbol table space allocated to hold 44 non-local and 3 local symbols.
415 source lines were read in Pass 1, producing 16 object records in Pass 2.
9 pages of virtual memory were used to define 8 macros.

+-----+
! Macro library statistics !
+-----+

Macro library name	Macros defined
_\$255\$DU 78:[SYSLIB]STARLET.MLB;2	4

88 GETS were required to define 4 macros.

There were no errors, warnings or information messages.

MACRO/ENABLE=SUPPRESSION/DISABLE=(GLOBAL,TRACEBACK)/LIS=LIS\$:MTHDTAN/OBJ=OBJ\$:MTHDTAN MSRC\$:MTHJACKET/UPDATE=(ENH\$:MTHJACKET)+MSRC\$:

0260 AH-BT13A-SE
VAX/VMS V4.0

DIGITAL EQUIPMENT CORPORATION
CONFIDENTIAL AND PROPRIETARY

