

EEEEEEEEEE	XX	XX	AAAAAA	MM	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AAAAAA	MM	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AAAAAA	MM	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AA	AAAA	MM	PP	LL	EE	SS
EEEEEEEEEE	XX	XX	AA	AAAA	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AA	AAAA	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AA	AAAA	MM	PPPPPPPP	LL	EEEEEEEEEE	SSSSSSSS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EE	XX	XX	AAAA	AAAA	MM	PP	LL	EE	SS
EEEEEEEEEE	XX	XX	AAAA	AAAA	MM	PP	LLLLLLLLLL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AAAA	AAAA	MM	PP	LLLLLLLLLL	EEEEEEEEEE	SSSSSSSS
EEEEEEEEEE	XX	XX	AAAA	AAAA	MM	PP	LLLLLLLLLL	EEEEEEEEEE	SSSSSSSS

```
TTTTTTTTT! DDDDDDDD RRRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRRR
TTTTTTTTT! DDDDDDDD RRRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRRR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DD      DD  RRRRRRRR
TT          DD      DD  RRRRRRRR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DD      DD  RR      RR
TT          DDDDDDDD RR      RR
TT          DDDDDDDD RR      RR
```

```
MM      MM      AAAAAA RRRRRRRR
MM      MM      AAAAAA RRRRRRRR
MMMM    MMMM    AA      AA  RR      RR
MMMM    MMMM    AA      AA  RR      RR
MM      MM      AA      AA  RR      RR
MM      MM      AA      AA  RRRRRRRR
MM      MM      AA      AA  RRRRRRRR
MM      MM      AAAAAAAAAA RR      RR
MM      MM      AAAAAAAAAA RR      RR
MM      MM      AA      AA  RR      RR
MM      MM      AA      AA  RR      RR
MM      MM      AA      AA  RR      RR
MM      MM      AA      AA  RR      RR
```


.TITLE TDRIVER - VAX/VMS TEMPLATE DRIVER
.IDENT 'V04-000'

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FACILITY:

VAX/VMS Template driver

ABSTRACT:

This module contains the outline of a driver:

- Models of driver tables
- Controller and unit initialization routines
- An FDT routine
- The start I/O routine
- The interrupt service routine
- The cancel I/O routine
- The device register dump routine

AUTHOR:

S. Programmer 11-NOV-1979

REVISION HISTORY:

V02 JHP001 J. Programmer 2-Aug-1979 11:27
Remove BLBC instruction from CANCEL routine.

V02-001 ROW0067 Ralph O. Weber 11-FEB-1981 13:10

Add description of reason argument to CANCEL routine.
Correct references to channel index number.

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:
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:--

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TD_

.SBTTL External and local symbol definitions

: External symbols

\$CANDEF	:	Cancel reason codes
\$CRBDEF	:	Channel request block
\$DCDEF	:	Device classes and types
\$DDBDEF	:	Device data block
\$DEVDEF	:	Device characteristics
\$IDBDEF	:	Interrupt data block
\$IODEF	:	I/O function codes
\$IPLDEF	:	Hardware IPL definitions
\$IRPDEF	:	I/O request packet
\$SSDEF	:	System status codes
\$UCBDEF	:	Unit control block
\$VECDEF	:	Interrupt vector block

: Local symbols

: Argument list (AP) offsets for device-dependent QIO parameters

P1	= 0	:	First QIO parameter
P2	= 4	:	Second QIO parameter
P3	= 8	:	Third QIO parameter
P4	= 12	:	Fourth QIO parameter
P5	= 16	:	Fifth QIO parameter
P6	= 20	:	Sixth QIO parameter

: Other constants

TD_DEF_BUFSIZ	= 1024	:	Default buffer size
TD_TIMEOUT_SEC	= 10	:	10 second device timeout
TD_NUM_REGS	= 4	:	Device has 4 registers

: Definitions that follow the standard UCB fields

\$DEFINI	UCB	:	Start of UCB definitions
.	=UCB\$K_LENGTH	:	Position at end of UCB
\$DEF	UCB\$W_TD_WORD	:	A sample word
\$DEF	UCB\$W_TD_STATUS	.BLKW 1	: Device's CSR register
\$DEF	UCB\$W_TD_WRCNT	.BLKW 1	: Device's word count register


```

$DEF   UCBSW_TD_BUFADR      ; Device's buffer address
      .BLKW 1               ; register
$DEF   UCBSW_TD_DATBUF      ; Device's data buffer register
      .BLKW 1
$DEF   UCBSK_TD_UCBLEN      ; Length of extended UCB

```

```

; Bit positions for device-dependent status field in UCB
;

```

```

$VIELD UCB,0,<-             ; Device status
      <BIT_ZERO,,M>,-       ; First bit
      <BIT_ONE,,M>,-        ; Second bit
      >

```

```

$DEFEND UCB                 ; End of UCB definitions

```

```

; Device register offsets from CSR address
;

```

```

      $DEFINI TD            ; Start of status definitions
$DEF   TD_STATUS            ; Control/status
      .BLKW 1

```

```

; Bit positions for device control/status register
;

```

```

_VIELD TD_STS,0,<-          ; Control/status register
      <GO,,M>,-             ; Start device
      <BIT1,,M>,-           ; Bit one
      <BIT2,,M>,-           ; Bit two
      <BIT3,,M>,-           ; Bit three
      <XBA,2,M>,-           ; Extended address bits
      <INTEN,,M>,-          ; Enable interrupts
      <READY,,M>,-          ; Device ready for command
      <BIT8,,M>,-           ; Bit eight
      <BIT9,,M>,-           ; Bit nine
      <BIT10,,M>,-          ; Bit ten
      <BIT11,,M>,-          ; Bit eleven
      <.1>,-                ; Disregarded bit
      <ATTN,,M>,-           ; Attention bit
      <NEX,,M>,-            ; Nonexistent memory flag
      <ERROR,,M>,-         ; Error or external interrupt
      >

```

```

$DEF   TD_WRCNT             ; Word count
      .BLKW 1
$DEF   TD_BUFADR            ; Buffer address
      .BLKW 1
$DEF   TD_DATBUF            ; Data buffer
      .BLKW 1
$DEFEND TD                 ; End of device register

```

; definitions.

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++
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.SBTTL Standard tables

; Driver prologue table

```

DPTAB      -      ; DPT-creation macro
            END=TD END,-      ; End of driver label
            ADAPTER=UBA,-      ; Adapter type
            UCBSIZE=<UCB$K_TD_UCBLEN>,-      ; Length of UCB
            NAME=TDDRIVER      ; Driver name
DPT_STORE INIT      ; Start of load
            ; initialization table
DPT_STORE UCB,UCB$B_FIPL,B,8      ; Device fork IPL
DPT_STORE UCB,UCB$B_DIPL,B,22      ; Device interrupt IPL
DPT_STORE UCB,UCB$L_DEVCHAR,L,<-      ; Device characteristics
            DEV$I_IDV!-      ; input device
            DEV$I_ODV>      ; output device
DPT_STORE UCB,UCB$B_DEVCLASS,B,DC$_SCOM      ; Sample device class
DPT_STORE UCB,UCB$W_DEVBUFSIZ,W,-      ; Default buffer size
            TD_DEF_BUFSIZ

DPT_STORE REINIT      ; Start of reload
            ; initialization table
DPT_STORE DDB,DDB$L_DDT,D,TD$DDT      ; Address of DDT
DPT_STORE CRB,CRB$L_INTD+4,D,-      ; Address of interrupt
            TD_INTERRUPT      ; service routine
DPT_STORE CRB,-      ; Address of controller
            CRB$L_INTD+VEC$L_INITIAL,-      ; initialization routine
            D,TD_CONTROL_INIT

DPT_STORE CRB,-      ; Address of device
            CRB$L_INTD+VEC$L_UNITINIT,-      ; unit initialization
            D,TD_UNIT_INIT      ; routine

DPT_STORE END      ; End of initialization
            ; tables

```

; Driver dispatch table

```

DDTAB      -      ; DDT-creation macro
            DEVNAM=TD,-      ; Name of device
            START=TD_START,-      ; Start I/O routine
            FUNCTB=TD_FUNC$TABLE,-      ; FDT address
            CANCEL=TD_CANCEL,-      ; Cancel I/O routine
            REGDMP=TD_REG_DUMP      ; Register dump routine

```

; Function decision table

```

TD_FUNC$TABLE:      ; FDT for driver
FUNCTAB      -      ; Valid I/O functions
            <READVBLK,-      ; Read virtual
            READLBLK,-      ; Read logical

```



```

      READPBLK,-      : Read physical
      WRITEVBLK,-     : Write virtual
      WRITELBLK,-     : Write logical
      WRITEPBLK,-     : Write physical
      SETMODE,-       : Set device mode
      SETCHAR>        : Set device chars.
FUNCTAB :             : No buffered functions
FUNCTAB +EXESREAD,-   : FDT read routine for
      <READVBLK,-     : read virtual,
      READLBLK,-      : read logical,
      READPBLK>       : and read physical.
FUNCTAB +EXESWRITE,-  : FDT write routine for
      <WRITEVBLK,-    : write virtual,
      WRITELBLK,-     : write logical,
      WRITEPBLK>      : and write physical.
FUNCTAB +EXESSETMODE,- : FDT set mode routine
      <SETCHAR,-      : for set chars. and
      SETMODE>        : set mode.
```

.SBTTL TD_CONTROL_INIT, Controller initialization routine

++
TD_CONTROL_INIT, Readies controller for I/O operations

Functional description:

The operating system calls this routine in 3 places:

at system startup
during driver loading and reloading
during recovery from a power failure

Inputs:

R4 - address of the CSR (controller status register)
R5 - address of the IDB (interrupt data block)
R6 - address of the DDB (device data block)
R8 - address of the CRB (channel request block)

Outputs:

The routine must preserve all registers except R0-R3.

--

TD_CONTROL_INIT: ; Initialize controller
RSB ; Return

.SBTTL TD_UNIT_INIT, Unit initialization routine

++
: TD_UNIT_INIT, Readies unit for I/O operations

: Functional description:

: The operating system calls this routine after calling the
: controller initialization routine:

: at system startup
: during driver loading
: during recovery from a power failure

: Inputs:

: R4 - address of the CSR (controller status register)
: R5 - address of the UCB (unit control block)

: Outputs:

: The routine must preserve all registers except R0-R3.

:--

TD_UNIT_INIT: ; Initialize unit
BISW #UCB\$M_ONLINE, - ; Set unit online
RSB UCB\$W_STS(R5) ; Return

.SBTTL TD_FDT_ROUTINE, Sample FDT routine

++
TD_FDT_ROUTINE, Sample FDT routine

Functional description:

T.B.S.

Inputs:

R0-R2 - scratch registers
R3 - address of the IRP (I/O request packet)
R4 - address of the PCB (process control block)
R5 - address of the UCB (unit control block)
R6 - address of the CCB (channel control block)
R7 - bit number of the I/O function code
R8 - address of the FDT table entry for this routine
R9-R11 - scratch registers
AP - address of the 1st function dependent QIO parameter

Outputs:

The routine must preserve all registers except R0-R2, and R9-R11.

--
TD_FDT_ROUTINE:
RSB

; Sample FDT routine
; Return

.SBTTL TD_START, Start I/O routine

++ TD_START - Start a transmit, receive, or set mode operation

Functional description:

T.B..

Inputs:

R3 - address of the IRP (I/O request packet)
R5 - address of the UCB (unit control block)

Outputs:

R0 - 1st longword of I/O status: contains status code and
number of bytes transferred
R1 - 2nd longword of I/O status: device-dependent

The routine must preserve all registers except R0-R2 and R4.

--
TD_START: ; Process an I/O packet

WFIKPB TD_TIMEOUT, #TD_TIMEOUT_SEC

After a transfer completes successfully, return the number of bytes transferred and a success status code.

```
IOFORK
INSV   UCB$W_BCNT(R5), #16, - ; Load number of bytes trans-
      #16, R0                ; ferred into high word of R0.
MOVW   #SS$_NORMAL, R0       ; Load a success code into R0.
```

Call I/O postprocessing.

COMPLETE_IO: ; Driver processing is finished.
REQCOM ; Complete I/O.

Device timeout handling. Return an error status code.

```
TD_TIMEOUT: ; Timeout handling
SETIPL  UCB$B_FIPL(R5) ; Lower to driver fork IPL
MOVZWL #SS$_TIMEOUT, R0 ; Return error status.
BRB     COMPLETE_IO    ; Call I/O postprocessing.
```


.SBTTL TD_INTERRUPT, Interrupt service routine

++ TD_INTERRUPT, Analyzes interrupts, processes solicited interrupts

Functional description:

The sample code assumes either

that the driver is for a single-unit controller, and
that the unit initialization code has stored the
address of the UCB in the IDB; or

that the driver's start I/O routine acquired the
controller's channel with a REQPCANL macro call, and
then invoked the WFIKPC macro to keep the channel
while waiting for an interrupt.

Inputs:

0(SP) - pointer to the address of the IDB (interrupt data
block)
4(SP) - saved R0
8(SP) - saved R1
12(SP) - saved R2
16(SP) - saved R3
20(SP) - saved R4
24(SP) - saved R5
28(SP) - saved PSL (program status longword)
32(SP) - saved PC

The IDB contains the CSR address and the UCB address.

Outputs:

The routine must preserve all registers except R0-R5.

```

TD_INTERRUPT:
    MOVL    @ (SP)+, R4          ; Service device interrupt
                                ; Get address of IDB and remove
                                ; pointer from stack.
    MOVL    IDB$L_OWNER(R4), R5  ; Get address of device owner's
                                ; UCB.
    MOVL    IDB$L_CSR(R4), R4    ; Get address of device's CSR.
    BBCC    #UCB$V_INT, -       ; If device does not expect
    UCB$W_STS(R5), -            ; interrupt, dismiss it.
    UNSOL_INTERRUPT

```

;; This is a solicited interrupt. Save
;; the contents of the device registers in the UCB.

```

    MOVW    TD_STATUS(R4), -    ; Otherwise, save all device
    UCB$W_TD_STATUS(R5)        ; registers. First the CSR.

```



```
MOVW    TD WRDCNT(R4),-      ; Save the word count register.
UCBSW TD WRDCNT(R5)
MOVW    TD BUFADR(R4),-      ; Save the buffer address
UCBSW TD BUFADR(R5)         ; register.
MOVW    TD DATBUF(R4),-      ; Save the data buffer register.
UCBSW TD DATBUF(R5)
```

```
; Restore control to the main driver.
;
```

```
RESTORE_DRIVER:
MOVW    UCB$L_FR3(R5),R3     ; Jump to main driver code.
JSB     @UCB$L_FPC(R5)       ; Restore driver's R3 (use a
                             ; MOVQ to restore R3-R4).
                             ; Call driver at interrupt
                             ; wait address.
```

```
; Dismiss the interrupt.
;
```

```
UNSOL_INTERRUPT:
POPR    #^M<R0,R1,R2,R3,R4,R5> ; Dismiss unsolicited interrupt.
REI     ; Restore R0-R5
        ; Return from interrupt.
```

.SBTTL TD_CANCEL, Cancel I/O routine

++ TD_CANCEL, Cancels an I/O operation in progress

Functional description:

This routine calls IOC\$CANCELIO to set the cancel bit in the UCB status word if:

the device is busy,
the IRP's process ID matches the cancel process ID,
the IRP channel matches the cancel channel.

If IOC\$CANCELIO sets the cancel bit, then this driver routine does device-dependent cancel I/O fixups.

Inputs:

R2 - channel index number
R3 - address of the current IRP (I/O request packet)
R4 - address of the PCB (process control block) for the process canceling I/O
R5 - address of the UCB (unit control block)
R8 - cancel reason code, one of:
 CAN\$C_CANCEL if called through \$CANCEL or \$DALLOC system service
 CAN\$C_DASSGN if called through \$DASSGN system service
These reason codes are defined by the \$CANDEF macro.

Outputs:

The routine must preserve all registers except R0-R3.
The routine may set the UCB\$M_CANCEL bit in UCB\$W_STS.

```
TD_CANCEL:      ; Cancel an I/O operation
    JSB        G^IOC$CANCELIO      ; Set cancel bit if appropriate.
    BBC        #UCB$V_CANCEL,-     ; If the cancel bit is not set,
    UCB$W_STS(R5),10$             ; just return.
```

; Device-dependent cancel operations go next.

; Finally, the return.

```
10$:          RSB                  ; Return
```


.SBTTL TD_REG_DUMP, Device register dump routine

++ TD_REG_DUMP, Dumps the contents of device registers to a buffer

Functional description:

Writes the number of device registers, and their current contents into a diagnostic or error buffer.

Inputs:

R0 - address of the output buffer
 R4 - address of the CSR (controller status register)
 R5 - address of the UCB (unit control block)

Outputs:

The routine must preserve all registers except R1-R3.

The output buffer contains the current contents of the device registers. R0 contains the address of the next empty longword in the output buffer.

--

```
TD_REG_DUMP:
MOVZBL #TD_NUM_REGS,(R0)+ ; Dump device registers
MOVZWL UCBSW_TD_STATUS(R5),- ; Store device register count.
(R0)+ ; Store device status register.
MOVZWL UCBSW_TD_WRDCNT(R5),- ; Store word count register.
(R0)+
MOVZWL UCBSW_TD_BUFADR(R5),- ; Store buffer address register.
(R0)+
MOVZWL UCBSW_TD_DATBUF(R5),- ; Store data buffer register.
(R0)+
RSB ; Return
```

```

; ++
; Label that marks the end of the driver
; --

```

[illegible][illegible]

