

```

EEEEEEEEEE XX XX AAAAAA MM MM PPPPPPPP LL EEEEEEEEEE SSSSSSSS
EEEEEEEEEE XX XX AAAAAA MM MM PPPPPPPP LL EEEEEEEEEE SSSSSSSS
EEEEEEEEEE XX XX AAAAAA MM MM PPPPPPPP LL EEEEEEEEEE SSSSSSSS
EE XX XX AA AA MMMM MMMM PP PP LL EE SS
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EEEEEEEEE XX XX AA AA MM MM PPPPPPPP LL EEEEEEEEE SSSSSSS
EE XX XX AAAAAAAAAA MM MM PP LL EE SS
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EEEEEEEEEE XX XX AA AA MM MM PP LLLLLLLLLL EEEEEEEEE SSSSSSSS
EEEEEEEEEE XX XX AA AA MM MM PP LLLLLLLLLL EEEEEEEEE SSSSSSSS
EEEEEEEEEE XX XX AA AA MM MM PP LLLLLLLLLL EEEEEEEEE SSSSSSSS

```

```

TTTTTTTTT1 DDDDDDD DD RRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRR
TTTTTTTTT1 DDDDDDD DD RRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRR
TT DD DD RR RR
TT DD DD RR RR
TT DD DD RR RR
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TT DD DD RRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRR
TT DD DD RRRRRRR IIIIII VV VV EEEEEEEEE RRRRRRR
TT DD DD RR RR IIIIII VV VV EEEEEEEEE RRRRRRR
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TT DD DD RR RR IIIIII VV VV EEEEEEEEE RRRRRRR
TT DDDDDDD RR RR IIIIII VV VV EEEEEEEEE RRRRRRR
TT DDDDDDD RR RR IIIIII VV VV EEEEEEEEE RRRRRRR

```

```

MM MM AAAAAA RRRRRRR
MM MM AAAAAA RRRRRRR
MMMM MMM AA AA RR RR
MMMM MMM AA AA RR RR
MM MM AA AA RR RR
MM MM AA AA RR RR
MM MM AA AA RRRRRRR
MM MM AA AA RRRRRRR
MM MM AAAAAAAAAA RR RR
MM MM AAAAAAAAAA RR RR
MM MM AA AA RR RR
MM MM AA AA RR RR
MM MM AA AA RR RR

```

: R  
: RES1  
: D  
: UNSC

.TITLE TDRIVER - VAX/VMS TEMPLATE DRIVER  
.IDENT 'V04-000'

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FACILITY:

VAX/VMS Template driver

ABSTRACT:

This module contains the outline of a driver:

- Models of driver tables
- Controller and unit initialization routines
- An FDT routine
- The start I/O routine
- The interrupt service routine
- The cancel I/O routine
- The device register dump routine

AUTHOR:

S. Programmer 11-NOV-1979

REVISION HISTORY:

- V02 JHP001 J. Programmer 2-Aug-1979 11:27  
Remove BLBC instruction from CANCEL routine.
- V02-001 ROW0067 Ralph O. Weber 11-FEB-1981 13:10

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Add description of reason argument to CANCEL routine.  
Correct references to channel index number.

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.SBTTL External and local symbol definitions

:: External symbols

```

$CANDEF      : Cancel reason codes
$CRBDEF      : Channel request block
$DCDEF       : Device classes and types
$DDBDEF      : Device data block
$DEVDEF      : Device characteristics
$IDBDEF      : Interrupt data block
$IODEF       : I/O function codes
$IPLDEF      : Hardware IPL definitions
$IRPDEF      : I/O request packet
$SSDEF       : System status codes
$UCBDEF      : Unit control block
$VECDEF      : Interrupt vector block

```

:: Local symbols

:: Argument list (AP) offsets for device-dependent QIO parameters

```

P1      = 0      : First QIO parameter
P2      = 4      : Second QIO parameter
P3      = 8      : Third QIO parameter
P4      = 12     : Fourth QIO parameter
P5      = 16     : Fifth QIO parameter
P6      = 20     : Sixth QIO parameter

```

:: Other constants

```

TD_DEF_BUFSIZ = 1024 : Default buffer size
TD_TIMEOUT_SEC = 10  : 10 second device timeout
TD_NUM_REGS   = 4    : Device has 4 registers

```

:: Definitions that follow the standard UCB fields

```

$DEFINI UCB      : Start of UCB definitions
.=UCBSK_LENGTH  : Position at end of UCB
$DEF UCBSW_TD_WORD .BLKW 1 : A sample word
$DEF UCBSW_TD_STATUS .BLKW 1 : Device's CSR register
$DEF UCBSW_TD_WRCNT .BLKW 1 : Device's word count register

```

```

$DEF UCBSW_TD_BUFADR      ; Device's offer address
      .BLKW 1             ; register
$DEF UCBSW_TD_DATBUF      ; Device's data buffer register
      .BLKW 1
$DEF UCBSK_TD_UCBLEN      ; Length of extended UCB

```

```

; Bit positions for device-dependent status field in UCB
;

```

```

$VIELD UCB,0,<-          ; Device status
        <BIT_ZERO,,M>,-  ; First bit
        <BIT_ONE,,M>,-   ; Second bit
>

```

```

$DEFEND UCB              ; End of UCB definitions

```

```

; Device register offsets from CSR address
;

```

```

$DEFINI TD              ; Start of status definitions
$DEF TD_STATUS          ; Control/status
      .BLKW 1

```

```

; Bit positions for device control/status register
;

```

```

_VIELD TD_STS,0,<-      ; Control/status register
        <GO,,M>,-        ; Start device
        <EIF1,,M>,-      ; Bit one
        <BIT2,,M>,-      ; Bit two
        <BIT3,,M>,-      ; Bit three
        <XBA,2,M>,-      ; Extended address bits
        <INTEN,,M>,-     ; Enable interrupts
        <READY,,M>,-     ; Device ready for command
        <BIT8,,M>,-      ; Bit eight
        <BIT9,,M>,-      ; Bit nine
        <BIT10,,M>,-     ; Bit ten
        <BIT11,,M>,-     ; Bit eleven
        <.1>,-           ; Disregarded bit
        <ATTN,,M>,-      ; Attention bit
        <NEX,,M>,-       ; Nonexistent memory flag
        <ERROR,,M>,-    ; Error or external interrupt
>

```

```

$DEF TD_WRCNT          ; Word count
      .BLKW 1
$DEF TD_BUFADR         ; Buffer address
      .BLKW 1
$DEF TD_DATBUF         ; Data buffer
      .BLKW 1
$DEFEND TD            ; End of device register

```



.SBTTL Standard tables

Driver prologue table

```

DPTAB - ; DPT-creation macro
      END=TD END,- ; End of driver label
      ADAPTER=UBA,- ; Adapter type
      UCBSIZE=<UCBSK_TD_UCBLEN>,- ; Length of UCB
      NAME=TDDRIVER ; Driver name
DPT_STORE INIT ; Start of load
              ; initialization table
DPT_STORE UCB,UCBSB_FIPL,B,8 ; Device fork IPL
DPT_STORE UCB,UCBSB_DIPL,B,22 ; Device interrupt IPL
DPT_STORE UCB,UCBSL_DEVCHAR,L,<- ; Device characteristics
      DEVSM_IDV!- ; input device
      DEVSM_ODV> ; output device
DPT_STORE UCB,UCBSB_DEVCLASS,B,DC$_SCOM ; Sample device class
DPT_STORE UCB,UCBSW_DEVBUFSIZ,W,- ; Default buffer size
      TD_DEF_BUFSIZ

DPT_STORE REINIT ; Start of reload
              ; initialization table
DPT_STORE DDB,DBSL_DDT,D,TD$DDT ; Address of DDT
DPT_STORE CRB,CRBSL_INTD+4,D,- ; Address of interrupt
      TD_INTERRUPT ; service routine
DPT_STORE CRB,- ; Address of controller
      CRBSL_INTD+VECSL_INITIAL,- ; initialization routine
      D,TD_CONTROL_INIT

DPT_STORE CRB,- ; Address of device
      CRBSL_INTD+VECSL_UNITINIT,- ; unit initialization
      D,TD_ONIT_INIT ; routine

DPT_STORE END ; End of initialization
              ; tables

```

Driver dispatch table

```

DDTAB - ; DDT-creation macro
      DEVNAM=TD,- ; Name of device
      START=TD_START,- ; Start I/O routine
      FUNCTB=TD_FUNC$TABLE,- ; FDT address
      CANCEL=TD_CANCEL,- ; Cancel I/O routine
      REGDMP=TD_REG_DUMP ; Register dump routine

```

Function decision table

```

TD_FUNC$TABLE: ; FDT for driver
  FUNCTAB - ; Valid I/O functions
      <READVBLK,- ; Read virtual
      READLBLK,- ; Read logical

```





.SBTTL TD\_UNIT\_INIT, Unit initialization routine

TD\_UNIT\_INIT, Readies unit for I/O operations

Functional description:

The operating system calls this routine after calling the controller initialization routine:

- at system startup
- during driver loading
- during recovery from a power failure

Inputs:

- R4 - address of the CSR (controller status register)
- R5 - address of the UCB (unit control block)

Outputs:

The routine must preserve all registers except R0-R3.

```

--
TD_UNIT_INIT:
  BISW    #UCBSM_ONLINE, -      ; Initialize unit
  RSB     UCBSW_STS(R5)         ; Set unit online
  RSB                                     ; Return

```

```
.SBTTL TD_FDT_ROUTINE, Sample FDT routine
```

```
TD_FDT_ROUTINE, Sample FDT routine
```

```
Functional description:
```

```
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```

```
Inputs:
```

```
R0-R2 - scratch registers
R3    - address of the IRP (I/O request packet)
R4    - address of the PCB (process control block)
R5    - address of the UCB (unit control block)
R6    - address of the CCB (channel control block)
R7    - bit number of the I/O function code
R8    - address of the FDT table entry for this routine
R9-R11 - scratch registers
AP    - address of the 1st function dependent QIO parameter
```

```
Outputs:
```

```
The routine must preserve all registers except R0-R2, and
R9-R11.
```

```
TD_FDT_ROUTINE:      ; Sample FDT routine
RSB                  ; Return
```

.SBTTL TD\_START, Start I/O routine

TD\_START - Start a transmit, receive, or set mode operation

Functional description:

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Inputs:

R3 - address of the IRP (I/O request packet)  
R5 - address of the UCB (unit control block)

Outputs:

R0 - 1st longword of I/O status: contains status code and  
number of bytes transferred  
R1 - 2nd longword of I/O status: device-dependent

The routine must preserve all registers except R0-R2 and R4.

TD\_START: ; Process an I/O packet

WFIK PCH TD\_TIMEOUT, #TD\_TIMEOUT\_SEC

After a transfer completes successfully, return the number of bytes transferred and a success status code.

IOFORK  
INSV UCBSW\_BCNT(R5), #16, - ; Load number of bytes trans-  
#16, R0 ; ferred into high word of R0.  
MOVW #SS\$\_NORMAL, R0 ; Load a success code into R0.

Call I/O postprocessing.

COMPLETE\_IO: ; Driver processing is finished.  
REQCOM ; Complete I/O.

Device timeout handling. Return an error status code.

TD\_TIMEOUT: ; Timeout handling  
SETIPL UCBSB\_FIPL(R5) ; Lower to driver fork IPL  
MOVZWL #SS\$\_TIMEOUT, R0 ; Return error status.  
BRB COMPLETE\_IO ; Call I/O postprocessing.

.SBTTL TD\_INTERRUPT, Interrupt service routine

++  
: TD\_INTERRUPT, Analyzes interrupts, processes solicited interrupts

: Functional description:

The sample code assumes either

that the driver is for a single-unit controller, and  
that the unit initialization code has stored the  
address of the UCB in the IDB; or

that the driver's start I/O routine acquired the  
controller's channel with a REQPCANL macro call, and  
then invoked the WFIKPC macro to keep the channel  
while waiting for an interrupt.

: Inputs:

0(SP) - pointer to the address of the IDB (interrupt data  
block)  
4(SP) - saved R0  
8(SP) - saved R1  
12(SP) - saved R2  
16(SP) - saved R3  
20(SP) - saved R4  
24(SP) - saved R5  
28(SP) - saved PSL (program status longword)  
32(SP) - saved PC

The IDB contains the CSR address and the UCB address.

: Outputs:

The routine must preserve all registers except R0-R5.

```

:--
: TD_INTERRUPT:           ; Service device interrupt
: MOVL   @ (SP)+, R4      ; Get address of IDB and remove
:                   ; pointer from stack.
: MOVL   IDB$$_OWNER(R4), R5 ; Get address of device owner's
:                   ; UCB.
: MOVL   IDB$$_CSR(R4), R4  ; Get address of device's CSR.
: BBCC   #UCB$$_INT, -      ; If device does not expect
:                   ; UCSW_STS(R5), -
:                   ; UNSOL_INTERRUPT

```

: This is a solicited interrupt. Save  
: the contents of the device registers in the UCB.

```

: MOVW   TD_STATUS(R4), -   ; Otherwise, save all device
:                   ; UCSW_TD_STATUS(R5) ; registers. First the CSR.

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```
MOVW TD WRDCNT(R4),-      ; Save the word count register.
UCBSW TD WRDCNT(R5)
MOVW TD BUFADR(R4),-     ; Save the buffer address
UCBSW TD BUFADR(R5)     ; register.
MOVW TD DATBUF(R4),-    ; Save the data buffer register.
UCBSW TD DATBUF(R5)

; Restore control to the main driver.
;
RESTORE_DRIVER:
MOVW UCBSL_FR3(R5),R3    ; Jump to main driver code.
                          ; Restore driver's R3 (use a
                          ; MOVQ to restore R3-R4).
JSB @UCBSL_FPC(R5)      ; Call driver at interrupt
                          ; wait address.

; Dismiss the interrupt.
;
UNSOL_INTERRUPT:
POPR #*M<R0,R1,R2,R3,R4,R5> ; Dismiss unsolicited interrupt.
REI                               ; Restore R0-R5
                                ; Return from interrupt.
```

```
.SBTTL TD_CANCEL, Cancel I/O routine
```

```
TD_CANCEL, Cancels an I/O operation in progress
```

```
Functional description:
```

```
This routine calls IOC$CANCELIO to set the cancel bit in the
UCB status word if:
```

```
the device is busy,
the IRP's process ID matches the cancel process ID,
the IRP channel matches the cancel channel.
```

```
If IOC$CANCELIO sets the cancel bit, then this driver routine
does device-dependent cancel I/O fixups.
```

```
Inputs:
```

```
R2 - channel index number
R3 - address of the current IRP (I/O request packet)
R4 - address of the PCB (process control block) for the
    process canceling I/O
R5 - address of the UCB (unit control block)
R8 - cancel reason code, one of:
    CAN$C_CANCEL if called through $CANCEL or
    $DALLOC system service
    CAN$C_DASSGN if called through $DASSGN system
    service
    These reason codes are defined by the $CANDEF macro.
```

```
Outputs:
```

```
The routine must preserve all registers except R0-R3.
The routine may set the UCBSM_CANCEL bit in UCBSW_STS.
```

```
TD_CANCEL:
    JSB G^IOC$CANCELIO ; Cancel an I/O operation
    BBC #UCBSV_CANCEL,- ; Set cancel bit if appropriate.
    UCBSW_STS(R5),10$ ; If the cancel bit is not set,
    ; just return.
```

```
Device-dependent cancel operations go next.
```

```
Finally, the return.
```

```
10$:
    RSB ; Return
```

.SBTTL TD\_REG\_DUMP, Device register dump routine

TD\_REG\_DUMP, Dumps the contents of device registers to a buffer

Functional description:

Writes the number of device registers, and their current contents into a diagnostic or error buffer.

Inputs:

R0 - address of the output buffer  
 R4 - address of the CSR (controller status register)  
 R5 - address of the UCB (unit control block)

Outputs:

The routine must preserve all registers except R1-R3.

The output buffer contains the current contents of the device registers. R0 contains the address of the next empty longword in the output buffer.

```

--
TD_REG_DUMP:
MOVZBL #TD_NUM_REGS,(R0)+ ; Dump device registers
MOVZWL UCBSW_TD_STATUS(R5),- ; Store device register count.
      (R0)+ ; Store device status register.
MOVZWL UCBSW_TD_WRDCNT(R5),- ; Store word count register.
      (R0)+
MOVZWL UCBSW_TD_BUFADR(R5),- ; Store buffer address register.
      (R0)+
MOVZWL UCBSW_TD_DATBUF(R5),- ; Store data buffer register.
      (R0)+
RSB ; Return
  
```



This image displays a grid of 100 small terminal window screenshots, arranged in 10 rows and 10 columns. Each window shows a different set of system commands and their outputs, demonstrating the capabilities of the VAX/VMS operating system. The windows are labeled with various system utilities and commands, including:

- LPMULT B32
- DRMAST MAR
- ADDRIVER MAR
- TDRIVER MAR
- USSTEST MAR
- GBLSECURF MAR
- USSDISP MAR
- XADDRIVER MAR
- LABLOCIN MAR
- DRSLV MAR
- DTE\_DF03 MAR
- SECRET MAR
- WORKO LIS
- EXAMPLES

The screenshots show a variety of system messages, command prompts, and data outputs, illustrating the system's configuration and operation. The text is rendered in a monospaced font, typical of early computer terminals.