





(2)	63	DECLARATIONS
(3)	118	UDA50 Bootstrap device initialization
(4)	276	UDA50 Bootstrap driver QIO
(5)	357	UDA50 Bootstrap device disconnect

```

0000 1      .TITLE PUBTDRIVR - UDA50 BOOT DRIVER
0000 2      .IDENT 'V04-000'
0000 3
0000 4
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0000 24 :*
0000 25 :*
0000 26 :*****
0000 27 :
0000 28 :
0000 29 :++
0000 30 : FACILITY:      BOOTS
0000 31 :
0000 32 : ABSTRACT:
0000 33 :   This module contains the bootstrap device driver for the
0000 34 :   UDA 50 disks.
0000 35 :
0000 36 : ENVIRONMENT:  IPL 31, kernel mode, code must be PIC
0000 37 :
0000 38 : AUTHOR:      Kerbey T. Altmann,   CREATION DATE: 20-Nov-1981
0000 39 :
0000 40 : MODIFIED BY:
0000 41 :
0000 42 :   V03-006 KTA3110      Kerbey T. Altmann      12-Mar-1984
0000 43 :   Set controller timeout to max for GEN booting.
0000 44 :
0000 45 :   V03-005 KDM0073      Kathleen D. Morse      23-Aug-1983
0000 46 :   Added $BQODEF for use by new version of TIMEDWAIT macro.
0000 47 :
0000 48 :   V03-004 KDM0059      Kathleen D. Morse      13-Jul-1983
0000 49 :   Replace time-wait loops that use IPR TODR with the
0000 50 :   new TIMEDWAIT macro.
0000 51 :
0000 52 :   V03-003 KTA3064      Kerbey T. Altmann      03-Jul-1983
0000 53 :   Fix page boundary problem.
0000 54 :
0000 55 :   V03-002 KTA3059      Kerbey T. Altmann      23-Jun-1983
0000 56 :   Add support for the boot device name.
0000 57 :

```

PUBTDRIVR  
V04-000

- UDA50 BOOT DRIVER

C 5

15-SEP-1984 23:57:44 VAX/VMS Macro V04-00  
4-SEP-1984 23:05:04 [BOOTS.SRC]PUBTDRIVR.MAR;1

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(1)

0000 58 :  
0000 59 :  
0000 60 :  
0000 1 :--

V03-001 KTA3007 Kerbey T. Altmann  
Fix problem with setting VMB\$V\_SCS.

09-Oct-1982

```

0000 63      .SBTTL  DECLARATIONS
0000 64      :
0000 65      : INCLUDE FILES:
0000 66      :
0000 67      :
0000 68      $BQODEF      ; Boot qio offset definitions
0000 69      $BTDDDEF     ; Boot device types
0000 70      $IODEF      ; I/O function codes
0000 71      $MSCPDEF    ; MSCP definitions
0000 72      $PRDEF      ; Processor registers
0000 73      $PTEDEF     ; Page table entries
0000 74      $RPBDEF     ; RPB offsets
0000 75      $SSDEF      ; Status codes
0000 76      $UBADEF     ; UBA definitions
0000 77      $SUBIDEF    ; 11/750 UBA definitions
0000 78      $VADEF      ; Virtual addresses
0000 79      $VMBARGDEF  ; VMB argument list offsets
0000 80      :
0000 81      :
0000 82      : EQUATED SYMBOLS:
0000 83      :
0000 84      :

```

```

00000000 0000 85      UDAIP   = 0
00000002 0000 86      UDASA   = 2
00000001 0000 87      GO      = 1
00008000 0000 88      OWN     = 1@15
0000000B 0000 89      S1      = 11
0000000E 0000 90      S4      = 14
000001EE 0000 91      UMR     = 494      ; Last-1 UNIBUS Mapping Register
0000 92      :
0000 93      :
0000 94      : OWN STORAGE:
0000 95      :
0000 96      :
0000 97      :
0000 98      : Boot driver table entry
0000 99      :

```

```

0000 100     $BOOT_DRIVER  DEVTYPE = BTDSK_UDA,- ; Device type (UDA50)
0000 101     SIZE = UD_DRVSIZ,- ; Driver size
0000 102     ADDR = START,- ; Driver starting address
0000 103     ENTRY = UD_DRIVER,- ; Driver entry point
0000 104     UNIT_INIT = UD_INIT,- ; Driver unit init entry
0000 105     UNIT_DISC = UD_DISC,- ; Driver disconnect entry
0000 106     DRVRNAME = DSKDRVNAME,- ; Driver disk name
0000 107     AUXDRNAME = PRTDRVNAME,- ; Driver port name
0000 108     DEVNAME = DEVNAME ; Boot device name
0000 109
0000 110

```

```

0000 111 START:
0000 112 DSKDRVNAME:
58 45 2E 52 45 56 49 52 44 55 44 00' 0000 113      .ASCIC /DUDRIVER.EXE/ ; Disk class driver filename
45 000C
0C 0000
0000 114 PRTDRVNAME:
58 45 2E 52 45 56 49 52 44 55 50 00' 000D 115      .ASCIC /PUDRIVER.EXE/ ; Port driver filename
45 0019
0C 000D

```

PUBTDRIVR  
V04-000

- UDASO BOOT DRIVER  
DECLARATIONS

E 5

15-SEP-1984 23:57:44 VAX/VMS Macro V04-00  
4-SEP-1984 23:05:04 [BOOTS.SRC]PUBTDRIVR.MAR;1

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(2)

55 44 001A 116 DEVNAME:.ASCII /DU/

; Boot device name

```

001C 118      .SBTTL  UDA50 Bootstrap device initialization
001C 119
001C 120      :++
001C 121      :
001C 122      : Inputs:
001C 123      :
001C 124      :         R9 --> RPB
001C 125      :         AP --> VMB argument list
001C 126      :
001C 127      : Outputs:
001C 128      :
001C 129      :         R0 - status code
001C 130      :
001C 131      :--
001C 132
001C 133      UD_INIT:
001C 134      .ENABLE LSB
01FC 001C 135      .WORD  ^M<R2,R3,R4,R5,R6,R7,R8>
001E 136
50 38 DB 001E 137      MFPR  #PRS MAPEN, R0          ; Get the mapping status
1A 50 EB 0021 138      BLBS  RC,10$          ; If virtual, skip some set up
0024 139      :
0024 140      : Set up the SYSTEMID for the local UDA.
0024 141      :
51 34 A9 D0 0024 142      MOVL  RPBSL IOVEC(R9),R1      ; Point to iovec
00'A1 94 0028 143      ^LRB  B^<BOO$GB UMR DP-BOO$AL_VECTOR>(R1) ; Set for Direct Data Path
2C AC 01 D0 002B 144      ASSUME VMB$V_LOAD_SCS EQ 0
24 A9 D0 002B 145      MOVL  #1,VMB$L_F[AGS(AP)      ; Set a flag to load SCS code
24 AC D0 002F 146      MOVL  RPBSL_BOOTR2(R9),-
20 A9 B0 0032 147      VMB$B_SYSTEMID(AP)      ; Low 32 bits is CSR of UDA
28 AC B0 0034 148      MOVW  RPBSL_BOOTR1(R9),-
00 24 AC 2F E2 0037 149      VMB$B_SYSTEMID+4(AP)      ; Hi 16 bits is TR of UBA
0039 150      BBSS  #47,VMB$B_SYSTEMID(AP),10$ ; Set bit 47
003E 151      :
003E 152      : Set up an interrupt vector.
003E 153      :
1E A9 01FC 8F B0 003E 154 10$: MOVW  #<127*4>,RPB$W_ROUBVEC(R9) ; Use the highest possible
0044 155      :
0044 156      : Set up a UNIBUS mapping register(s) to cover the ring and buffers.
0044 157      : To make things easy, we will grab the last two register (494 & 495).
0044 158      : These registers are necessary since the ring area will be accessed by
0044 159      : the controller which is a UNIBUS device that does not do any mapping.
0044 160      :
0044 161      MOVAB  W^INTTBL,R2          ; Get the address of the ring
51 52 014A'CF 9E 0044 162      BICL3  #^C<^X1ff>,R2,R1          ; Get the byte offset in page
02 A2 51 0003DC00 8F C9 0051 163      BISL3  #<UMR@9>,R1,2(R2)          ; Set in the UNIBUS addr
02 A2 10' C0 005A 164      ADDL  S^#<RING-INTTBL>,2(R2)      ; Make it the ring address
52 52 15 09 EF 005E 165      EXTZV  #VASV_VPN,#VASS_VPN,R2,R2 ; Get the page frame
0063 166      ASSUME  RPBSL_ADPVIR EQ RPBSL ADPPHY+4
53 5C A940 D0 0063 167      MOVL  RPBSL_ADPPHY(R9)[R0],R3 ; Get correct pointer to UBA reg
0068 168      ASSUME  RPBSL_CSRVIR EQ RPBSL CSRPHY+4
57 54 A940 D0 0068 169      MOVL  RPBSL_CSRPHY(R9)[R0],R7 ; Get correct address of device CSR
0C 50 E9 006D 170      BLBC  R0,20$          ; If clr, then physical
52 52 50 B942 D0 0070 171      MOVL  @RPBSL SVASPT(R9)[R2],R2 ; Virtual, get physical
52 FF00000 8F CA 0075 172      BICL  #^C<PTE$M PFN>,R2          ; Now a physical PFN
84 52 54 0FB8 C3 DE 007C 173 20$: MOVAL  UBASL_MAPT<UMR*4>(R3),R4 ; Get the last two UMR's
0081 174      BISL3  VALID,R2,(R4)+      ; Set as valid w/PFN

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64 52 000000DF'EF 52 D6 0089 175 INCL R2 ; Set next page just in case
C9 008B 176 BISL3 VALID,R2,(R4) ; Set as valid w/PFN
0093 177
0093 178 : Now go thru the ridiculously complicated startup sequence. This is a
0093 179 : fugue in four parts.
0093 180
53 58 02 D0 0093 181 MOVL #2,R8 ; Make two tries at this
014A'CF 9E 0096 182 RETRY: MOVAB W^INTTBL, R3
52 0B D0 009B 183 MOVL #S1, R2 ; Step flag
67 B4 009E 184 CLRW UDAIP(R7) ; Poke the controller's CSR
00A0 185
00A0 186 : Wait 100 microseconds.
00A0 187
00A0 188 TIME: TIMEDWAIT TIME=#1000*1000,- ; Wait for 10 seconds
00A0 189 INS1=<MOVW UDASA(R7),R4>,- ; Check the status register
00A0 190 INS2=<BLSS 25$>,- ; Bit 15 set is the error indicator
00A0 191 INS3=<BBS R2,R4,25$>,- ; Done with this step?
00A0 192 DONELBL=25$ ; Label for exiting wait loop
OD 50 E8 00D3 193 BLBS R0,26$ ; Br if not timed out
00D6 194
50 BD 58 F5 00D6 195 ERROR: SOBGTR R8,RETRY ; Try once again
0054 8F 3C 00D9 196 MOVZWL #SS$_CTRLERR,R0 ; Set failure status
04 00DE 197 RET
00DF 198
80000000 00DF 199 VALID: .LONG ^X80000000 ; Sign bit set
00E3 200
54 B5 00E3 201 26$: TSTW R4 ; Check status register for error
EF 19 00E5 202 BLSS ERROR ; Br if error
00E7 203
02 A7 83 B0 00E7 204 30$: MOVW (R3)+,UDASA(R7) ; Send the controller the next step
B1 52 0E F3 00EB 205 AOBLEQ #S4,R2,TIME ; Set for next step
00EF 206
00EF 207 : Initialization complete. Write the packet address in the ring.
00EF 208 : Writing the addresses must be deferred until this point because the
00EF 209 : hardware zeroes the entire ring as a memory write check.
00EF 210
00000040'8+ C1 00EF 211 ADDL3 #<RSPPKT-RING>,-
5A'AF 4C'AF 00F5 212 B^INTTBL+2,B^RD ; Response packet
OC' C1 00F9 213 ADDL3 S^#<CMDPKT-RING>,-
5E'AF 4C'AF 00FB 214 B^INTTBL+2,B^CD ; Command packet
00FF 215
00FF 216 : Set the controller timeout to be the maximum
00FF 217
55 66'AF 9E 00FF 218 MOVAB B^CMDPKT,r5 ; Get the address of command packet
85 01 D0 0103 219 MOVL #1,(R5)+ ; Set command ref number
85 85 D4 0106 220 CLRL (R5)+ ; Reserved field
85 04 9A 0108 221 MOVZBL #MSCPSK_OP_STCON,(R5)+ ; Set opcode to SET CTRL CHAR
85 85 D4 0108 222 CLRL (R5)+ ; Version and flags
85 FF 8F 9A 010D 223 MOVZBL #255,(R5)+ ; Set timeout to 255 seconds
85 85 7C 0111 224 CLRQ (R5)+ ; Clear time & date
65 D4 0113 225 CLRL (R5) ; Clear controller depend parameters
00CC 30 0115 226 BSBW IO ; Send it out
0118 227
0118 228 : Now bring the device on-line
0118 229
55 66'AF 9E 0118 230 MOVAB B^CMDPKT,r5 ; Get the address of command packet
85 01 D0 011C 231 MOVL #1,(R5)+ ; Set command ref number

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85 64 A9 9A 011F 232 MOVZBL RPBSW UNIT(R9),(R5)+ ; Put unit number in cmd packet field
85 85 09 9A 0123 233 MOVZBL #MSCPSK_OP_ONLN,(R5)+ ; Set opcode to bring drive online
85 85 7C 0126 234 CLRQ (R5)+ ; Clear byte count, buff desc
65 7C 0128 235 CLRQ (R5) ; buff desc and LBN
00B7 30 012A 236 BSBW IO ; Send it out
16 EF 012D 237 EXTZV #MSCPSV MTYP D1,-
05 012F 238 #MSCPS5 MTYP D1,-
01B6'CF 0130 239 W^RSPPKT+ -
51 51 08 78 0133 240 MSCPSL MEDIA_ID,R1 ; Pull out 2nd device character
51 51 1B EF 0134 241 ASHL #8,R1,RT ; Stick it in high byte
05 0138 242 EXTZV #MSCPSV MTYP D0,-
B6'AF 013A 243 #MSCPS5 MTYP D0,-
52 013B 244 B^RSPPKT+ -
51 4040 8F A8 013D 245 MSCPSL MEDIA_ID,R2 ; Pull out 1st device character
FED1 CF 52 51 A9 013E 246 BISW #^X4040,R1 ; Make ASCII characters
04 0143 247 BISW3 R1,R2,DEVNAME ; Set into driver name
0149 248 RET
014A 249
014A 250
014A 251 .DISABLE LSB
0000014A 014A 252 .=<. +1>8-2
014A 253 :
014A 254 : RINGS
014A 255 :
014A 256 :
8000 014A 257 INTTBL: .WORD OWN ; Step 1 pattern
00000000 014C 258 .LONG 0 ; Step 2 & 3 pattern
0001 0150 259 .WORD GO
0152 260
0000 0000 0152 261 .WORD 0,0 ; Reserved
0000 0156 262 CMDINT: .WORD 0 ; Command status word
0000 0158 263 RSPINT: .WORD 0 ; Response status word
015A 264 RING:
00000000 015A 265 RD: .LONG 0 ; UNIBUS address of response ring
00000000 015E 266 CD: .LONG 0 ; UNIBUS address of command ring
0162 267 :
0030 0162 268 .WORD 48 ; Length of message
0001 0164 269 .WORD 1 ; ID
0001 0166 270 CMDPKT: .WORD 1
00000196 0168 271 .BLKW 23 ; Full envelope
0196 272 :
0000019A 0196 273 .BLKW 2
000001CA 019A 274 RSPPKT: .BLKW 24

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01CA 276      .SPITL UDA50 Bootstrap driver Q10
01CA 277
01CA 278 :++
01CA 279 :
01CA 280 : Inputs:
01CA 281 :
01CA 282 : R3      - base address of adapter's register space
01CA 283 : R5      - lbn for current piece of transfer
01CA 284 : R6      - contains 0
01CA 285 : R7      - address of the device's CSR
01CA 286 : R8      - size of transfer in bytes
01CA 287 : R9      - address of the RPB
01CA 288 : R10     - starting address of transfer (byte offset in first
01CA 289 :          page ORed with starting map register number)
01CA 290 : R11     - LBN at start of transfer
01CA 291 :
01CA 292 : FUNC(AP)- I/O operation (IOS_READBLK or IOS_WRITEBLK only)
01CA 293 : SIZE(AP)- Size of transfer in bytes
01CA 294 : MODE(AP)- Address interpretation mode (0 = physical, 1 = virtual)
01CA 295 :
01CA 296 : Implicit inputs:
01CA 297 :
01CA 298 : RPB$W_UNIT - RPB field containing boot device unit number
01CA 299 :
01CA 300 : Outputs:
01CA 301 :
01CA 302 : R0 - status code
01CA 303 :
01CA 304 :          SSS_NORMAL - successful transfer
01CA 305 :          SSS_NOSUCHDEV - unsupported device
01CA 306 :          SSS_CTRLERR - fatal controller error
01CA 307 :
01CA 308 : R3 - must be preserved
01CA 309 :
01CA 310 :
01CA 311 : --
01CA 312 :
00000010 01CA 313 FUNC = 16
00000014 01CA 314 MODE = 20
01CA 315 :
01CA 316 UD_DRIVER: ; UDA50 device driver.
01CA 317 :
01CA 318 :
01CA 319 : Translate the I/O function code into a device-dependent function
01CA 320 : code for this disk.
01CA 321 :
01CA 322 :
A0 AF 21 90 01CA 323      MOVB #MSCPSK_OP_READ, - ; Assume read
01CE 324      CMDPKT+MSCPSB_OPCODE
20 10 AC D1 01CE 325      CMPL FUNC(AP),#IOS_WRITEBLK ; Check for write function
01D2 326      BNEQ 20$ ; No, do read
96 AF 22 90 01D4 327      MOVB #MSCPSK_OP_WRITE, - ; Set write function code
01D8 328      CMDPKT+MSCPSB_OPCODE
A6 AF 55 D0 01D8 329 20$: MOVL R5,CMDPKT+MSCPSL_LBN ; Set the logical block number
92 AF 58 D0 01DC 330      MOVL R8,CMDPKT+MSCPSL_BYTE_CNT ; Set the byte count
92 AF 5A D0 01E0 331      MOVL R10,CMDPKT+MSCPSB_BUFFER; Set the UNIBUS map register
54 02 A7 B0 01E4 332 10: MOVW UDA5A(R7),R4 ; Controller offline?

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FF6F CF 8000 8D 12 01E8 333 BNEQ ERROR1 ; Yep, error out
FF64 CF 8000 8F AB 01EA 334 BLSW #OWN, CD+2 ; Set controller ownership
54 54 67 B0 01F1 335 BLSW #OWN, RD+2 ; Ditto
02 A7 B0 01F8 336 MOVW UDAIP(R7),R4 ; Tell controller to read
16 12 01FB 337 MOVW UDASA(R7),R4 ; Any problems?
FF57 CF B5 0201 338 BNEQ ERROR1 ; Yes
FA 19 0205 339 30$: TSTW RD+2 ; Any response back?
9A AF B5 0207 340 BLSS 30$ ; No, spin until there is
OB 12 020A 341 TSTW RSPPKT+MSCPSW_STATUS ; Any drive errors?
FF49 CF 8000 8F AB 020C 342 BNEQ ERROR1 ; Yes
0213 343 BLSW #OWN, RD+2 ; No, set controller ownship
0213 344 :
0213 345 : Transfer is complete. Return with success status code.
0213 346 :
50 01 3C 0213 347 MOVZWL #SS$_NORMAL,R0 ; SET COMPLETION CODE
05 0216 348 RSB ; AND RETURN
0217 349 :
0217 350 : Error occured during transfer. Return and retry.
0217 351 :
0217 352 :
50 0054 8F 3C 0217 353 ERROR1:
05 021C 354 MOVZWL #SS$_CTRLERR,R0 ; Set failure status
355 RSB ; Return to BOOTDRIVR

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```

021D 357          .SBTTL  UDA50 Bootstrap device disconnect
021D 358
021D 359 :++
021D 360 : This routine disconnect the boot device after a bugcheck dump.
021D 361 : It sends an AVAIL packet to the controller, in effect doing a
021D 362 : dismount of the system device. It is designed to be called
021D 363 : only from BUGCHECK immediately after the dump has finished.
021D 364 : It assumes virtual mapping turned on.
021D 365
021D 366 : Inputs:
021D 367
021D 368 :       R9 --> RPB
021D 369
021D 370 : Outputs:
021D 371
021D 372 :       R0 - status code
021D 373
021D 374 :--
021D 375
021D 376 UD_DISC:
021D 377   .ENABLE LSB
0090 021D 378   .WORD  ^M<R4,R7>
021F 379
021F 380   MOVZBL #MSCPSK_OP_AVAIL,-      ; Make drive AVAILable
57  FF4A CF 0221 381   CMDPKT+MSCPSB_OPCODE
0224 382   MOVL  RPB$L_CSRVIR(R9),R7  ; Get correct address of device CSR
0228 383   BSBB  IO                      ; Send it out
022A 384   RET
022B 385
0000022B 022B 386 UD_DRVSIZ=-.START
022B 387
022B 388   .END

```

PUBTDRIVR  
Symbol table

- UDA50 BOOT DRIVER

L 5

15-SEP-1984 23:57:44 VAX/VMS Macro V04-00  
4-SEP-1984 23:05:04 [BOOTS.SRC]PUBTDRIVR.MAR;1

```

$TABLE = 00000000 R 02
BOOSAL_VECTOR ***** X 03
BOOSGB_UMR_DP ***** X 03
BOOSL_TENUSEC = 0000003E
BOOSL_UBDELAY = 00000042
BTDSK_UDA = 00000011
CD = 0000015E R 03
CMDINT = 00000156 R 03
CMDPKT = 00000166 R 03
DEVNAME = 0000001A R 03
DSKDRVNAME = 00000000 R 03
ERROR = 000000D6 R 03
ERROR1 = 00000217 R 03
FUNC = 00000010
GO = 00000001
INTTBL = 0000014A R 03
IO = 000001E4 R 03
IOS_WRITEBLK = 00000020
MODE = 00000014
MSCPSB_BUFFER = 00000010
MSCPSB_OPCODE = 00000008
MSCPSK_OP_AVAIL = 00000008
MSCPSK_OP_ONLIN = 00000009
MSCPSK_OP_READ = 00000021
MSCPSK_OP_STCON = 00000004
MSCPSK_OP_WRITE = 00000022
MSCPSL_BYTE_CNT = 0000000C
MSCPSL_LBN = 0000001C
MSCPSL_MEDIA_ID = 0000001C
MSCPSS_MTYP_D0 = 00000005
MSCPSS_MTYP_D1 = 00000005
MSCPSV_MTYP_D0 = 0000001B
MSCPSV_MTYP_D1 = 00000016
MSCPSW_STATUS = 0000000A
OWN = 00008000
PR$ MAPEN = 00000038
PRTDRVNAME = 0000000D R 03
PTESM_PFN = 001FFFFFF
RD = 0000015A R 03
RETRY = 00000096 R 03
RING = 0000015A R 03
RPBSL_ADPPHY = 0000005C
RPBSL_ADPVIR = 00000060
RPBSL_BOOTR1 = 00000020
RPBSL_BOOTR2 = 00000024
RPBSL_CSRPHY = 00000054
RPBSL_CSRVIR = 00000058
RPBSL_IOVEC = 00000034
RPBSL_SVASPT = 00000050
RPBSW_ROUBVEC = 0000001E
RPBSW_UNIT = 00000064
RSPINT = 00000158 R 03
RSPPKT = 0000019A R 03
S1 = 0000000B
S4 = 0000000E
SS$_CTRLERR = 00000054
SS$_NORMAL = 00000001

```

```

START = 00000000 R 03
TIME = 000000A0 R 03
UBASL_MAP = 00000800
UDAIP = 00000000
UDASA = 00000002
UD_DISC = 0000021D R 03
UD_DRIVER = 000001CA R 03
UD_DRVSIZ = 0000022B
UD_INIT = 0000001C R 03
UMR = 000001EE
VASS_VPN = 00000015
VASV_VPN = 00000009
VALID = 000000DF R 03
VMBSB_SYSTEMID = 00000024
VMBSB_ARGBYTCNT = 0000003C
VMBSL_CI_HIPFN = 00000030
VMBSL_FLAGS = 0000002C
VMBSL_HI_PFN = 00000010
VMBSL_LO_PFN = 0000000C
VMBSQ_FILECACHE = 00000004
VMBSQ_NODENAME = 00000034
VMBSQ_PFNMAP = 00000014
VMBSQ_UCODE = 0000001C
VMBSV_LOAD_SCS = 00000000

```

-----  
! Psect synopsis !  
-----

PSECT name	Allocation	PSECT No.	Attributes
. ABS .	00000000 ( 0.)	00 ( 0.)	NOPIC USR CON ABS LCL NOSHR NOEXE NORD NOWRT NOVEC BYTE
\$AB\$\$	0000003C ( 60.)	01 ( 1.)	NOPIC USR CON ABS LCL NOSHR EXE RD WRT NOVEC BYTE
BOOTDRIVR_4	00000028 ( 40.)	02 ( 2.)	NOPIC USR CON REL LCL NOSHR EXE RD WRT NOVEC BYTE
BOOTDRIVR_2	0000022B ( 555.)	03 ( 3.)	NOPIC USR CON REL LCL NOSHR EXE RD WRT NOVEC BYTE

-----  
! Performance indicators !  
-----

Phase	Page faults	CPU Time	Elapsed Time
Initialization	32	00:00:00.09	00:00:00.31
Command processing	121	00:00:00.75	00:00:03.97
Pass 1	409	00:00:14.82	00:00:26.80
Symbol table sort	0	00:00:02.58	00:00:04.16
Pass 2	83	00:00:02.52	00:00:04.75
Symbol table output	11	00:00:00.10	00:00:00.10
Psect synopsis output	2	00:00:00.03	00:00:00.03
Cross-reference output	0	00:00:00.00	00:00:00.00
Assembler run totals	660	00:00:20.89	00:00:40.12

The working set limit was 1500 pages.  
83195 bytes (163 pages) of virtual memory were used to buffer the intermediate code.  
There were 90 pages of symbol table space allocated to hold 1651 non-local and 9 local symbols.  
388 source lines were read in Pass 1, producing 16 object records in Pass 2.  
24 pages of virtual memory were used to define 21 macros.

-----  
! Macro library statistics !  
-----

Macro library name	Macros defined
_\$255\$DUA28:[BOOTS.OBJ]BOOTS.MLB;1	3
-\$255\$DUA28:[SYS.OBJ]LIB.MLB;1	8
-\$255\$DUA28:[SYSLIB]STARLET.MLB;2	7
TOTALS (all libraries)	18

1804 GETS were required to define 18 macros.

There were no errors, warnings or information messages.

MACRO/LIS=LIS\$:PUBTDRIVR/OBJ=OBJ\$:PUBTDRIVR MSRC\$:PUBTDRIVR/UPDATE=(ENH\$:PUBTDRIVR)+EXECMLS/LIB+LIB\$:BOOTS.MLB/LIB



