INSTRUCTION MANUAL

KXO9A MEMORY PROTECTION OPTION



DEC-09-I1BA-D

KXO9A Memory protection Option

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DIGITAL EQUIPMENT CORPORATION . MAYNARD, MASSACHUSETTS

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CHAPTER 1 INTRODUCTION

The KX09A Memory Protection Option is a PDP-9 computer option manufactured by Digital Equipment Corporation. It is used to trap certain instructions, references to protected areas of the core memory and references to nonexistent memory banks. This document and the referenced documents provide information necessary for installation, operation and maintenance of the KX09A Memory Protection Option. The level of discussion assumes that the reader is familiar with the core memory system of the PDP-9 central processor.

1.1 RELATED DOCUMENTATION

The documents listed in Table 1-1 contain material which supplements information in this document.

Title	Document Number	Contents
Digital Logic Handbook	C-105	Specifications and descriptions of most FLIP CHIP * modules, plus simplified explanation of the selection and use of these modules in numerous applications.
PDP-9 User Handbook	F-95	Operation and programming information for the PDP-9.
PDP-9 Maintenance Manual Volumes I and II	F-97	Operation and maintenance information for the PDP-9, including engineering drawings.
DM09A Instruction Manual	DEC-09-19AB-D	Operation and maintenance information for the PDP-9 DMA Multiplexer option.
KX09A Memory Protect Test	MAINDEC-9A- D1EB-D	Operating instructions and program listing for the KX09A diagnostic program.

Table 1–1 Reference Documents

^{*}FLIP CHIP is a trademark of Digital Equipment Corporation

1.2 SYSTEM DESCRIPTION

The KX09A Memory Protection Option is connected to the PDP-9 central processor and control memory system (Figure 1-1). It establishes a foreground/background environment for PDP-9 time-sharing processing activity by specifying the boundary between the protected (lower) and un-protected (upper) regions of core memory. Memory locations are assigned to the protected region in increments of 2000₈ locations and the protected region is variable by a programmed instruction.

All instructions are monitored before they are executed. The logic within this equipment traps instructions that reference locations below the boundary or instructions that are in the illegal category. This trapping causes the execution of an effective JMS instruction after the machine cycle in which the attempted violation occurred. The address referenced by the effective JMS instruction will be location absolute 20 if the program interrupt facility is disabled, or location absolute 0 if the program interrupt facility is enabled.

If a nonexistent memory bank is referenced by an instruction, a trap occurs to prevent a hang-up condition in the central processor.



Figure 1-1 Memory Protection System

CHAPTER 2 INSTALLATION

The KX09A Memory Protection Option consists of 47 FLIP CHIP modules of the B-, R-, Sand W-series mounted in two Type 1943D module mounting panels. Wiring for the KG09A, MP09A and MP09B options is also installed on the two module mounting panels. The complete assembly, Type ME09B, is mounted in two spaces immediately above the paper tape reader/punch unit in the PDP-9 central processor cabinet. There are no special installation requirements other than those required for the PDP-9 central processor if the equipment is installed in the plant. If a field installation is performed, insert the module complement per drawing D-MU-KX09-A-1. Remove jumpers and install external components using drawing A-CP-ME09-B-3 as a reference.

2.1 INTERCONNECTIONS

Standard PDP-9 I/O bus cables and three flexiprint cables connect the KX09A to the PDP-9 central processor, and three flexiprint cables complete the connections to the control memory system. The I/O bus cables are shown on drawing D-IC-KX09-A-4 and the six flexiprint cables are shown on drawing D-IC-KX09-A-5, sheet 1. Drawing D-IC-KX09-A-5, sheet 2, shows a schematic view of the installed cables and identifies the cable lengths and the terminating module types.

2.2 POWER REQUIREMENTS

The KX09A draws the necessary dc power from the PDP-9 central processor power buses. It requires 10V at 0.2A and -15V at 3.2A.

2.3 ENVIRONMENT

The environmental specifications for the KX09A are identical to the PDP-9 central processor environmental specifications.

2.4 ON-SITE CHECKOUT

Check wiring for shorts and correct any shorts that are found. Check that the jumpers for the KX09A are removed from W18-D25 and that all unused pins on W18-D25 are jumpered per drawing A-CP-ME09-B-3. Check that the external components are installed. Check all cables using drawing D-KX09-A-5 (sheet 2) as a reference. Check that the jumper between H35C and H35F (USER MODE (1)B to ground) in the PDP-9 central processor is removed.

Turn on power and run a few small programs to check the operation of the boundary register and the PRTCT switch. A sample program is shown below:

The boundary register should follow the state of the appropriate bits in the data switches. If the results are incorrect, check the IOT's and the logic for missing signals, etc.

Run a JMP. program. Press the START key with the PRTCT switch in the UP position and observe that both the USMD indicator and the indicator above the PRTCT switch illuminate. Check that the PRTCT switch has no further effect once the program is running. Check that the IO RESET key clears the boundary register and the USMD lights.

Run the diagnostic program MAINDEC-9A-D1EB-D and run margins on racks A, B, C, and D of the ME09B using margins of $10 \pm 4V$ and $-15 \pm 3V$.

CHAPTER 3 OPERATION AND PROGRAMMING

3.1 OPERATION

The user mode (memory protect) of the KX09A is enabled by either a MPEU instruction, or by placing the PRTCT switch on the PDP-9 operator console in the UP position and pressing the START key. Once the program has started, the KX09A is in user mode and the PRTCT switch has no further effect. The indicator above the PRTCT switch lights when the user mode is enabled.

3.1.1 KX09A Indicators

The indicators shown in Figure 3-1 are mounted above the PDP-9 marginal check panel. Indicator functions are listed in Table 3-1.



Figure 3–1 KX09A Indicator Panel

Table 3–1 KX09A Indicators

Name	Function
PRVN	Lights when protect violation flag is raised.
NEXM	Lights when nonexistent memory flag is raised.
USMD	Lights to indicate that the user mode is enabled.
BR3 through BR7	Indicate the upper limit (in 2000 ₈ increments) of the protected region of core memory.

3.2 PROGRAMMING

The KX09A memory protection option adds the IOT instructions listed in Table 3-2.

Mnemonic	Octal Code	Function
MPSNE	701741	Skip on nonexistent memory flag. The nonexistent memory flag is set whenever the processor attempts to reference a nonexistent area of core. For a 32K machine, the flag would never get set.
MPSK	701701	Skip on violation flag. The memory protect viola- tion flag will be set whenever the execution of an instruction has violated the provision of memory protection.
MPEU	701742	Enter user (protect) mode. Memory protect mode will be entered at the end of the next instruction that is not an IOT.
MPCV	701702	Clear violation flag.
MPCNE	701744	Clear nonexistent memory flag.
MPLD	701704	Load the memory protection boundary register with the contents of AC3 through 7. The boundary register will store the number of 2000 ₈ word blocks to be pro- tected.

Table 3–2 KX09A IOT Instructions

3.2.1 Stored Data Word Format

Figure 3–2 shows the data format of the word deposited in location 20 or 0 when a violation is trapped.



Figure 3-2 Stored Data Word Format

CHAPTER 4 THEORY OF OPERATION

4.1 BLOCK DIAGRAM DISCUSSION

The KX09A Memory Protection Option (Figure 4-1) establishes a foreground/background environment for PDP-9 time-sharing processing activity by specifying the boundary between protected (lower) and unprotected (upper) regions of the core memory. Memory locations are allocated to the protected region in word blocks of 2000₈ locations. A number that represents the upper limit of the protected region is transferred from the PDP-9 AC register and to the boundary register via the IO BUS 03 through 07 lines. This number is jammed into the boundary register by an MPLD instruction.

The KX09A can be placed in the user (protect) mode by an MPEU instruction or by placing the PRTCT switch in the UP position and pressing the START key on the PDP-9 operator console. With the user mode enabled, the KX09A monitors the instruction to be performed for illegal instructions (instructions that should not be used by time-sharing users; e.g., IOT, OAS, HLT, a chain of XCT), references to memory locations within the protected region, and reference to nonexistent memory banks. If one of these conditions is detected, control is transferred to a monitor program before the instruction is executed.

These functions are performed in the following manner. A comparator circuit compares the number stored in the boundary register with bits 3 through 7 of the instruction address. The KMA < BR signal is generated and the monitor circuit is enabled if the number in bits 3 through 7 is less than the number in the boundary register. The operation code of the instruction is decoded in the monitor circuit and the monitor circuit is enabled if the instruction is decoded in the monitor circuit and the monitor circuit is enabled if the instruction is in the illegal category. To check for references to nonexistent memory banks, the MEM START pulse sets the MEM OK flip-flops and the MEM STROBE pulse clears the flip-flop. If a nonexistent memory bank is referenced, the MEM STROBE pulse is not generated and the MEM OK flip-flop remains set. Then, the next CLKD pulse sets the NON-EX MEM flip-flop. Outputs from the MEM OK and NON-EX MEM flip-flops are ANDed enabling the monitor circuit.

When the monitor circuit is enabled, the $1 \rightarrow FOUND 1$ signal is sent to the trap circuit causing the $13 \rightarrow CMA$ and FOUND 1 SAVE (B) signals to be generated. The FOUND 1 SAVE (B) signal from the trap circuit is sent to the central processor and causes the execution of an effective JMS instruction after the machine cycle that attempts to violate. The address referenced by the effective JMS instruction is location absolute 20, if the PI facility is disabled, or location absolute 0, if the PI facility is enabled. The 13 \rightarrow CMA signal sets the PROTECT VIOLATION flip-flop, disables the user mode enable circuit, and sets the CMA register to 33.

The state of the KX09A (a 1 for the user mode) is stored in bit 2 of the storage word by those operations that save the state of the machine (CAL, JMS, PI). The stored program count (PC) will contain one more than the location of the violating instruction, except for JMP to a protected area. In this case, the stored PC will contain the protected address.



Figure 4-1 Block Diagram

If the user mode is enabled when an API break starts and the API channel address contains a HLT, OAS, or IOT instruction rather than the normal JMS instruction, the instruction is inhibited, the user mode is disabled and no violation is detected. A debreak and restore (DBR) instruction (703344_o) is performed to return the KX09A to the user mode.

A CAL instruction disables the user mode and never causes a violation.

If the user mode is disabled when reference to a nonexistent memory bank is made, the NON-EX MEM flip-flop is set but no trap occurs. Since the MEM STROBE pulse is not generated, the program will hang-up. To prevent this, the output from the MEM OK flip-flop is inverted and sent to the PDP-9 as a RESTART signal (drawing KC-16). The input to B104-F31T is conditioned and the next CM CLK pulse enables the strobe logic. The program continues after a 1 µs pause.

There are six IOT instructions added for the KX09A. The functions of the MPLD and MPEU instructions have been briefly explained in this discussion. Refer to Section 4.3 for complete details on all KX09A IOT instructions.

4.2 DEVICE SELECTION

Signals on the device selection lines (DS0 through DS5) and one subdevice select line (SD0) of the PDP-9 I/O bus are used to select the KX09A Memory Protection Option and generate the required control signals. A description of device selection using drawing D-BS-KX09-A-2 (sheet 1) as a reference follows.

Device select lines DS0 and DS1 are inverted generating buffered signals. These signals and the signals on DS2 through DS5 are sent to a W103 module that has been coded for a 17_8 code. The signal on the SD0 line is inverted generating complementary SD0 signals. When an KX09A IOT instruction is placed on the I/O bus, the 17_8 code is decoded by the W103 module and enables the IOP pulse. The resultant IOT pulse is ANDed with the appropriate SD0 signal to generate the control signal.

4.3 INSTRUCTION DESCRIPTIONS

There are six IOT instructions which initiate action in the KX09A Memory Protection Option. The functions performed by these IOT instructions are described below using drawing D-BS-KX09-A-2 (sheets 1 and 2) as a reference.

4.3.1 Skip on Nonexistent Memory Flag (MPSNE): 701741

This instruction checks the condition of the NON-EX MEM flip-flop. A -3V level is applied to R111-A27E if a nonexistent memory bank has been referenced. The signal on the SD0 line (-3V during this instruction) is inverted twice and applied to R111-C28E. The signals on the device selection lines and the IOP1 line are decoded by the W103 decoder module and the resultant pulse is applied to R111-C28D. The AND gate is enabled and its output signal is applied to W640-C29D generating the MPSNE pulse. The MPSNE pulse is applied to R111-A27D generating a skip request (SKIP RQ) that is sent to the PDP-9 via the I/O bus.

4.3.2 Skip on Violation Flag (MPSK): 7017018

The condition of the PROTECT VIOLATION flag flip-flop is checked with this instruction. A -3V level is applied to R111-A28E if a violation is detected (i.e., a reference to locations below the boundary, an illegal instruction, etc.) and the PROTECT VIOLATION flip-flop is set. The signal on the SD0 line (0V during this instruction) is inverted and applied to R111-D28E. Signals on the device select lines and the IOP1 pulse are decoded by the W103 module and the resultant pulse is applied to R111-D28D. The AND gate is enabled and its output pulse is applied to W640-C29K generating the MPSK pulse which is applied to R111-A28D generating a SKIP RQ.

4.3.3 Enter User Mode (MPEU): 701742,

This instruction is performed to place the KX09A in the protect (user) mode. The signal on the SD0 line (-3V during this instruction) is inverted and applied to S202-C32V conditioning the DCD gate at the set side of the PRE-USER MODE flip-flop. The signals on the device select lines and the IOP2 pulse are decoded by the W103 module generating the IOT 1702 pulse.

The IOT 1702 pulse is applied to S202-C32U setting the PRE-USER MODE flip-flop and applying -3V to R111-D32E. During this instruction and all IOT instructions, the IOT flip-flop in the PDP-9 (drawing KC12) is set. Therefore, 0V is applied to R111-D32D, disabling the DCD gate at the set side of the USER MODE flip-flop. The DCD gate remains disabled until an instruction other than an IOT instruction is performed. Then, the IOT flip-flop is cleared, R111-D32D goes to -3V, the DCD gate is enabled and the USER MODE flip-flop is set by the DONE (1) pulse at the end of the instruction. A 0V level from the USER MODE flip-flop is inverted generating the USER MODE (1)B signal that is sent to the central processor as UM (1) via the memory extension/parity interface (drawing KC-28).

4.3.4 <u>Clear Violation Flag (MPCV)</u>: 701702₈

The PROTECT VIOLATION flip-flop (violation flag) is cleared by this instruction. The signal on the SD0 line (0V during this instruction) is inverted twice and the resulting signal is applied to S202-B29L conditioning the DCD gate at the clear side of the flip-flop. Signal IOT 1702 is generated by the W103 decoder module and applied to S202-B29K clearing the flip-flop.

4.3.5 Clear Nonexistent Memory Flag (MPCNE): 7017448

This instruction is performed to clear the NON-EX MEM (nonexistent memory flag) flip-flop. The signal on the SD0 line (-3V during this instruction) is inverted and applied to the DCD gate at the clear side of the NON-EX MEM flip-flop. The W103 decoder module generates the IOT 1704 pulse that is also applied to the DCD gate. The DCD gate is enabled and the flip-flop is cleared.

4.3.6 Load the Boundary Register (MPLD): 701704,

The protected area of core memory is established during the performance of this instruction. A number that represents the number of 2000₈ word blocks to be protected is sent from the AC to the jam inputs of the boundary register flip-flops via I/O bus 03 through 07. The signal on the SDO line (0V during this instruction) is inverted and applied to R111-D28S. The signals on the device selection lines and IOP4 are decoded by the W103 decoder module and the resultant signal is applied to R111-D28R. The AND gate is enabled and its output signal is applied to a pulse amplifier generating the MPLD (IOT 1704) pulse which enables the jam inputs of the boundary register jamming the number into the register.

The output signals from the boundary register are sent to a comparator circuit at the top of drawing D-BS-KX09-A-2 (sheet 1). Bits 3 through 7 of the referenced address (bits 3 and 4 specify the memory bank number) are also sent to the comparator circuit and compared with the contents of the boundary register. Any reference to a memory location with an address lower than the number contained in the boundary register causes the KMA < BR signal to be generated. Any reference to a location which is equal to or greater than the contents of the boundary register has no effect.

4.4 DETAILED DESCRIPTIONS

The logic contained in the four circuit blocks (Figure 4–1) is described using drawing D-BS-KX09-A-2 (sheet 1 and 2) as a reference. The PDP-9 Maintenance Manual drawing reference conventions are used in this manual to reference PDP-9 engineering drawings.

4.4.1 Comparator Circuit

The comparator circuit consists of nine AND gates which compare bits 3 through 7 of the referenced memory address with the number stored in the boundary register. The number in the boundary register represents the upper limit of the core memory protected region. If BR7 and BR6 equal 1 the first 6000₈ locations are protected, etc. Complementary signals (BR3 (0) through BR6 (1) and BR7 (1)) are sent to the comparator and connected to the AND gates. Bits 5 through 7 of the referenced address are jammed into KMA5 through KMA7 during the fetch cycle as the instruction is being read into the MB and the complementary outputs from the flip-flops are connected to the AND gates. Complementary signals of EMA3 and EMA4 (bits 3 and 4) of the address are also sent to the AND gates if the memory extension control is in use. This ANDing of signals causes the KMA < BR signal to be generated if the referenced address is within the protected region of core memory.

4.4.2 User Mode Enable Circuit

The user mode enable circuit (sheet 2) consists of the PRE-USER MODE flip-flop, the USER MODE flip-flop, and a number of control gates which enable and disable the KX09A user mode. The USER MODE flip-flop is set or cleared by the DONE (1) signal from the central processor depending on the condition of the PRE-USER MODE flip-flop. The IOT (0) signal from the IOT flip-flop in the PDP-9 central processor prevents the generation of the USER MODE (1)B signal until the IOT flip-flop is cleared. Therefore, an IOT instruction that set the PRE-USER MODE flip-flop does not cause a violation.

The PRE-USER MODE flip-flop can be set in any of the following ways: the DCD gate at the set side of the flip-flop is enabled by an MPEU instruction; the direct set input (S202-C32M) is enabled when the START key is pressed, if the PRTCT switch is in the UP position; or the direct set input is enabled by a DBR instruction, if MB02 (1) is 1 (bit 2 of the word deposited in location 20 or 0 when a violation is trapped).

The PRE-USER MODE flip-flop can be cleared in any of the following ways: the EXT (1) and PROG SYNC (1)B signals are ANDed together during a JMS 0; the EXT (1) and API BK RQ (1)B signals are ANDed together during a JMS X; CAL (1) and IRI (0) signals are ANDed together during a JMS 20; the 0 \rightarrow EPC signal generated during an I/O RESET: or the 13 \rightarrow CMA signal generated when a violation is detected.

When the USER MODE flip-flop is set, the USER MODE (1)B signal goes to -3V. It is sent to the PDP-9 I/O control (drawing KD-3 (3)) where it is applied to S107-H18S as UM (1). The UM (0)B signal at the output of the inverter goes to 0V and performs the following functions: disables the output from R111- J12H (drawing KD-3 (3)) preventing the IOP pulses from being generated and inhibiting the IOT instruction; prevents data from being loaded into the AC during an input transfer by inhibiting the generation of the OR ACI signal (drawing KC-12); prevents an output transfer from the AR by inhibiting the generation of the IOT OR ARO signal (drawing KC-12); during operate instruction, disables the output from R111-J28H (drawing KC-10 (1)) preventing the RUN (0) signal from going to 0V (the HLT instruction is disabled); and inhibits the generation of the LIO and DASO signals (drawing KC-13) required for an OAS instruction by disabling the output from R111-D07U.

4.4.3 Monitor Circuit

The monitor circuit decodes conditions that cause violations and generates the $1 \rightarrow FOUND1$ signal. The conditions that cause a violation are the second XCT instructions in a chain of XCT instructions (the first XCT instruction is allowed), a HLT instruction, an OAS instruction, an IOT instruction, a reference to a nonexistent memory bank, or a reference to a memory location within the protected

region. The HLT, OAS, and IOT instructions are totally inhibited when the user mode is enabled. If a HLT or OAS instruction is combined with any other operate group instructions (microprogramming), the other parts of the operate group instruction are performed.

An instruction in the illegal category is detected by decoding the operation code (MB00 through MB04) of the instructions. Then, the EXT (0) conditions a DCD gate at the set side of the JAM VIOLATION flip-flop during a fetch entry and the IRI (0) B pulse sets the flip-flop. The JAM VIOLATION pulse is sent to the instruction decoders and generates the 1 + FOUND 1 signal if an operation code for an illegal instruction is present.

A reference to a nonexistent memory bank is detected by ANDing the MEM OK (1) and NON-EX MEM (1) signals. If both flip-flops are set, the $1 \rightarrow FOUND1$ signal is generated.

If a memory location within the protected region is addressed, the KMA < BR signal is generated and inverted conditioning a pair of AND gates. One of the AND gates generates the 1 +FOUND1 signal, if the instruction is a JMP to an address within the protected region (the PCI (1)B signal is -3V), and if the program was not just started by depressing the START key (ADSO (0) signal is -3V). This logic allows a reference to an address within the protected region when the program is started with the START key. The second AND gate generates the 1 + FOUND1 signal if an address within the protected region is addressed directly (IR4 (0) signal OV) and if the instruction is not a CAL instruction (CAL (0) signal is 0V). This logic allows an indirect reference within the protected region and the execution of a CAL instruction.

4.4.4 Trap Circuit

The trap circuit consists of the FOUND 1 and FOUND 1 SAVE flip-flops and their associated gates. It is enabled and the $13 \rightarrow CMA$ and FOUND 1 SAVE (B) signals are generated if a violation is detected and the user mode is enabled.

The USER MODE (1) and PRE-USER MODE (1) signals are ANDed together; the resulting signal conditions a DCD gate at the set side of the FOUND 1 flip-flop. Then the $1 \rightarrow$ FOUND 1 pulse sets the FOUND 1 flip-flop when a violation is detected. The leading edge of the FOUND 1 (1) signal sets the FOUND 1 SAVE flip-flop generating the FOUND 1 SAVE signal that is applied to the level input of the PV flip-flop (drawing KC-12).

The SM flip-flop is set (CMA 24) and the SM1 signal is ANDed with a -3V signal from the FOUND1 flip-flop generating the $13 \rightarrow CMA$ pulse. The $13 \rightarrow CMA$ pulse is sent to the direct set input of the CMA 2, 4 and 5 flip-flop (drawing KC-19 (1)) setting the CMA register to 33. The PRE-USER MODE flip-flop is cleared and the PROTECT VIOLATION flip-flop is set by the $13 \rightarrow CMA$ pulse. To prevent a second $13 \rightarrow CMA$ pulse from being generated, the SM (1) signal is delayed and ANDed with the CLKD pulse generating the MEM START pulse that clears the FOUND1 flip-flop.

When location 33 is addressed, the IRI flip-flop is set and the IRI (1) signal is applied to the jam input of the PV, CAL and IR flip-flops. With FOUND 1 SAVE present, the PV flip-flop is set and the PV (1) signal disables the SA inputs to the IR clearing the IR. The PV (1) signal is also ANDed with the PIE (1) signal. If the PIE (1) signal is -3V (PI enabled), the level input of the CAL flip-flop is disabled and an effective JMS 0 is performed. If the PIE (1) signal is a OV (PI disabled), the contents of the IR are decoded (all 0 at this time) and an effective JMS 20 is performed.

Since the FOUND1 flip-flop was cleared by a MEM START pulse generated during a preceding cycle, the DCD gate at the clear side of the FOUND1 SAVE flip-flop is conditioned by the FOUND 1 (0) signal. The MEM START pulse generated during this cycle enables the DCD gate and clears the FOUND1 SAVE flip-flop. With both flip-flops cleared, the trap circuit is ready to check the next instruction.

CHAPTER 5

MAINTENANCE

The maintenance procedures contained in the PDP-9 Maintenance Manual apply to the KX09A Memory Protection Option.

5.1 DIAGNOSTIC PROGRAM

The diagnostic program MAINDEC-9A-D1EB-D checks the KX09A Memory Protection Option for normal operation. All IOT instructions associated with the option are tested and the logic's ability to trap instructions, which can interface with the protected area of memory, is checked. The instructions tested include HLT, OAS, any IOT, and an XCT followed by an XCT. Operation of the boundary register is then checked by allocating protected areas of core memory in segments of 2000₈ locations. During the boundary register tests, the program checks that a protect violation does not occur when the referenced address is equal to the contents of the boundary register. Additional tests are provided in the diagnostic program to check KX09A operation when the PDP-9 is equipped with the KG09A Memory Extension Control option and/or the KF09A Automatic Priority Interrupt option.

5.2 RECOMMENDED SPARES

Table 5-1 lists the modules used in the KX09A. All of these modules with the exception of the W640 module, are used elsewhere in the PDP-9 system. Since it is unnecessary to carry duplicate spare modules, one W640 module is the only recommended spare.

Quantity	Туре	Function
1	B104	Inverter
1	B105	Inverter
4	B213	Jam Flip–Flop
1	B310	Delay
5	R002	Diode Network
22	R111	NAND/NOR Gate
5	S202	Dual Flip-Flop

Tabl	e 5-1
KX09A	Modules

Table 5–1 (Cont) KX09A Modules

Quantity	Туре	Function
3	W005	Clamped Load
1	W103	Device Selector
3	W612	Pulse Amplifier
1	W640	Pulse Output Converter

CHAPTER 6 ENGINEERING DRAWINGS

This chapter contains the standard block schematics, circuit schematics, and engineering drawings necessary for understanding and maintaining the KX09A Memory Protection Option. The drawings are listed in the same order as they appear in this manual.

Engineering Drawings

Drawing Number	Title	Revision	Page
D-MU-KX09-A-1	Module Utilization List	А	6-3
D-BS-KX09-A-2	Control (Sheet 1)	А	6-5
D-BS-KX09-A-2	Control (Sheet 2)	Α	6-7
D-TD-KX09-A-3	Memory Protect (Sheet 1)	-	6-9
D-TD-KX09-A-3	Memory Protect (Sheet 2)	-	6-11
D-TD-KX09-A-3	Memory Protect (Sheet 3)	-	6-13
D-IC-KX09-A-4	I/O Interface	-	6-15
D-IC-KX09-A-5	Cable Connection Type	В	6-17
	Module Schematics		
B-CS-B104-0-1	Inverter	С	6-19
B-CS-B105-0-1	Inverter	E	6-19
B-CS-B213-0-1	Jam Flip-Flop	F	6-20
B-CS-B310-0-1	Delay	В	6-20
B-CS-R002-0-1	Diode Network	A	6-21
B-CS-R111-0-1	NAND/NOR Gate	F	6-21
B-CS-S202-0-1	Dual Flip-Flop	D	6-22
B-CS-W005-0-1	Clamped Load	В	6-22
C-CS-W103-0-1	Device Selector	D	6-23
B-CS-W612-0-1	Pulse Amplifier	С	6-24
B-CS-W640-0-1	Pulse Output Converter	L	6-24

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		, ! ,	, 2	, 3	4	, 5	, 6	, 7	18	, 9	10		12	13	14	15	16	17	18	1 19	, 20	1 21	1 22	, 23	, 24	, 25	26	1 27	1 28	1 29	30	31
				G795¥		-	G795															B213	<u>R111</u>	R882 A24F	R111	R802 A26F	<u>R111</u>	R111	<u>R111</u>	S2#2	R111 1→	RE82 A27T
D																						KMA5	B27D	A24W	A24K	A26F	B2/D	RQ	RQ RQ	хст	FOUND 1	A30W
	А			₩8 Bits 0-→9																			A22R	A26W	B27D	A26M	A26R	1→ Found 1	1 → Found 1		хст	AJON
																						KMAG		A24T		A26T		A295	NR	XCT OF XCT		A3OT
																							B27D	A22T	A26D	A26T	B27D	FOUND 1	328(1)B		FOUND 1	A3DT
				6795*	<u>6796*</u>	6796	K <u>8</u> 34*	<u>KØ33*</u>						16,8,85							B213	B213	B213	R111	M2885 A22R A24K	R111 $1 \rightarrow$ FOUND 1	R882 A27N	\$2,92	IRI(19)	\$2,92	SZØ2	C32R
				NHB Bits	#1 CP	#2 CP	#3 CP	NEN Signals						MEM STR							BR3	BR5	BR7	MB 02(1)B	A26R B27D	 	A27W	FCUND 1	(B)	PROTECT VIO- LATION	SAVE	SPARE
	В			9-17	SIGNAL	SIGNALS	SIGNALS							MB 02 (1) B										₩B Ø1(1)B	WB1(B) WB1(B)	MBI(B)	A27T		MB ;03(1)B			C32R
с																					BR4	BR6	KMA7		D24L IRI(#) MB#3(B)		A27T	JAM VIO-		NON-EX New	MENOK	SPARE
																								SD49(18)	MB15(B) MB(2)0(1)9 MB12(1)8	SYNC _	C29R		MB 12(1)B			SPARE
		¥950*	2	3	4	5	6	7	8	9	10		12	13 R111	14	15	16	17	18	19 B213	20	21	22	23	24	25 8892	26 R111	27	28 8111	29 18649	30 	31 B1:85
\rightarrow		15.40	80.50																	* * Eha						* *	NSØ(B)		C29D	MPSNF	(R.4(B)	CLK (B)
	С																			; ø3									D32H			USER Mode (1)B
			- 10	BUS -										ЕХТ (B)													DS(1)B		15(I)B	MPSK	CAL(B)	C32R
Р																				ENA 184						 			D29F	D24M	RESTART	B25E
													B 1:84	R111				R111	R111				8885	R111		PV;0EMA	R111			¥612		XCT (B) W612
													FOUND 1 SAVE (B)										ADSO (B) ADSO (B)	ADSO (1)B	SM	INDI-	P V¢JEMA		C29K	13→		JAM
	ח												SM Delay FD											SPARE	DELAYE	CATOR			SPARE	CMA		LATION
	0		BI	LOCK										PCI (1)B				SDØ(B) 											CLR(B)		ø→ BP3	Ø→ BR5
																			WB (Ø1(B)				D13N		A29W		PRE USER WODE(1))	D29R	MPLD	BR4	BR6 BR7
																							DI3N				NODE(1)					
A																										N	0TE: ¥ USI ¥ ¥	DENOTE: ED ON C DENOT	S NODULE Able Ass es mod	S ENBLIES ULES	•	
																											ON KG	LY ТО Ø9 ОР	BE FI	INSTAL	NHEN LED	
l			8	<u>.</u>					7						6						5		-	1			4					3



D-MU-KX09-A-1 Module Utilization List



D-BS-KX09-A-2 Control (Sheet 1)



D-BS-KX09-A-2 Control (Sheet 2)

	8	7	6	5	Ļ	4		:
			NORMAL LAG ENTRY		TOU THIEV			
	CAL Z	21 12 CLR 24	32 23 6Ø 15	2 21 12	CLR			
D	USER MODE							
	PRE USER MODE	CAL·IRI						
	CAL							
	IRI	l					MODE (8)	
	FE	TCH ENTRY BELOW BOUNDARY	FORCED XCT ENTRY CAL	IAØ ENTR	Y FOR NORMAL C	AL NORMAL FE	TCH ENT	र४
	VIOLATION, CASE() 2	I 12 CLR 24 MACHINE IS STARTED B	33 CLR 2 ELOW THE BOUNDARY WI	4 32 23 TH USER MODE O	6Ø 1Ø N.	21 12]	
	USER MODE 3		R	RE USER MODE . DON	<u>E</u>]			
	PRE USER MODE	I3→CMA						
		MAY CONTINUE, L	DEPENDS ON ADDRESS	REFERENCED,				
	FOUND I SAYE FO		MEM START . FOU					
С	PV	FOUNDISAVE·IRI			FOUND	I SAVE IRI		
	PROTECT VIOLATION	I3→ CMA			CLEAR	ED BY PROGRAM	3	
	DACIN (ASE(2) 12	TCH ENTRY "TAD"	DEFER ENTRY "Y"	FORCED X	CT ENTRY CAL	IAO ENTR	Y "CAL"	10
	ICEP MODE ST	WHERE "Y" IS IN THE	PROTECTED AREA.					10
	PRE USER MODE		I3→CMA					
	KMA < BR				_ MAY GO AWAY,	DEPENDS ON W	HAT WAS R	EAD OUT
	PV			IRI · FOUND	1 SAVE			IRI · FC
	FOUND I		KMACBR-TI	MEM START				
	FOUND I SAVE		FOUND	1	MEM START . FOU	ND T		
в	PROTECT VIOLATION		[13→	CMA				CLEA
	JMP "Y; CASE(3)	21 12 CLR 74 10	33 CLR Z	4 32 23	60 10	21 12]	
	KMA < BR	WHERE T IS IN TH	MAY GO AWAY, DE	PENDS ON CONTE	NTS OF "Y"			
	FOUND I	KMAC BR-PCI MEM STA	RT					
	FOUND I SAVE	FOUND	MEM START	· FOUND I			MODE PE	E NCEP
	PV		IRI-FOUND SAVE		IRI ·	FOUND I SAVE USER	ATION ETC	; SAME
A								
L	8	7	6	5	1	4		3

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D-TD-KX09-A-3 Memory Protect (Sheet 1)

	8	7	6	5	↓	4	3
	-						
	+	NORMAL IOT FETCH ENTRY	÷ ÷	XCT ENTRY FOR CAL	AS IN DWG (1) 1AD	ENTRY FOR CAL A	S IN DWG()
	101	21 12 CLR 76	20 10	33 CLR	24 32	23 60	10
U	USER MODE &	s			DONE . PRE US	ER MODE	
	FOUND 1	I-> FOUND I	MEM START				
	FOUND I SAVE	FOUND		MEM	START . FOUND		
	IØ RESTART _		__	IRI FOUND I SAVE		IRI · FO	UND I SAVE 4
	PROTECT VIOLATION		I3→CMA			CLEARED BY	PROGRAM
	I3→CMA	FETCH ENTRY OF NORMAL	XCT ENTRY FINDS SECON	D XCT ENTRY	FORCED BY		
	XCT OF XCT [21 12 CLR 7Ø	33 CLR 7	Ø 33 CL	R 24	32 23 G	Ø IØ
	JAM VIOLATION _						
c	PRE USER MODE	·	13 → CMA			EP MODE - DONE	
						SER MODE DONE	
	XCT OF XCT						
	FOUNDI		XCT C	DF XCT	MEM START		
	FOUND SAYE _		FOUN	DI		FO	UND T . MEM STAR
\rightarrow	PV -			IRI · FOUND I S	AVE		IRI · FOUNI
		NORMAL FETCH NORMAL INDIRE	T EXECUTE CYCLE RESTAR	G FORCED XCT	IAØ ENTRY (CAL) + CLK	PULSES
	NUN EX MENIL	NON EXISTENT MEMORY	REF. (ASSUME TAD I NON	EX MEM)		121112 • MEM	STROBES
	NON EX MEM		CLK·MEM	ок	CLEARED BY P	ROGRAM Z	
В	FOUND 1		MEM OK-NEXM	MEMSTART			
	FOUND I SAVE _		FOUND I	FOUND I . MEM STAT	RT]		
	PROTECT VIOLATION]13→ CM	A	CLEARED BY P	TRI	
	USER MODE 2			PRE USER M	ODE · DONE		
	PRE USER MODE 2		$13 \rightarrow CMA$				
^							
	•			E	*		
	ō	/	0) S		4	3



D-TD-KX09-A-3 Memory Protect (Sheet 2)





D-TD-KX09-A-3 Memory Protect (Sheet 3)



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D-IC-KX09-A-4 I/O Interface



D-IC-KX09-A-5 Cable Connection Type



B-CS-B104-0-1 Inverter



UNLESS OTHERWISE INDICATED: RESISTORS ARE 1/4W; 5% CAPACITORS ARE MMFD TRANSISTORS ARE DEC 2894-18





B-CS-B213-0-1 Jam Flip-Flop



UNLESS OTHERWISE INDICATED: RESISTORS ARE 1/4W; 10% DIODES ARE D-664 DEI - DE4 ARE TECHNITROL, .05usec, 330 A TAPS AT .0125usec, DD-330-5-1, 6012

B-CS-B310-0-1 Delay



B-CS-R002-0-1 Diode Network



UNLESS OTHERWISE INDICATED: RESISTORS ARE 1/4W; 5% PRINTED CIRCUIT REV. FOR DGL BOARD IS SIB

B-CS-R111-0-1 NAND/NOR Gate



B-CS-S202-0-1 Dual Flip-Flop



B-CS-W005-0-1 Clamped Load



UNLESS OTHERWISE INDICATED: TRANSISTORS ARE DEC 3639 RESISTORS ARE 1/4 W, 5 % CAPACITORS ARE MMFD DIODES ARE D-664

C-CS-W103-0-1 Device Selector



UNLESS OTHERWISE INDICATED: RESISTORS ARE 1/4W; 5% DIODES ARE D664







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