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.TITLE TSXPRO -- TSX-Plus PROxxx Routines
.ENABL LC
.ENABL AMA
.DSABL GBL

; Starting at V6.40, this module includes relevant TSTIO routines, to
; reduce the size of PRO/TSX-Plus. Actual TSXPRO code starts at TSXPRO:
;
; Copyright (c) 1984, 1985, 1986, 1987, 1988.
; S&H Computer Systems, Inc.
; Nashville, Tennessee 37212
; U. S. A.
;
; Assembly parameters
;
; Set QPASM to 1 to include support for quad serial line unit.
; Set QPASM to 0 to exclude quad line unit code.
;
QPASM = 1 ;Select quad port code
MAXPOC = 15 ;Max consecutive output chars to PI
;
;

000001
000017

```

1          .SBTTL  TSTIO  -- PRO/TSX-Plus terminal interrupt driver
2          ;-----
3 000000   .PSECT  TSTIO
4          .ENABL  LC
5          ;
6          ; TSTIO contain the interrupt processing code for sending and receiving
7          ; characters to DL11, DZ11, and DH11 lines.
8          ;
9          ; Global definitions
10         ;
11         .GLOBL  TSTIO, DLINT, DZ0INT, CDSTRT, CDSTOP, NEDSOT
12         .GLOBL  CDIRTN, CDIFLG, CDORTN, CDOFLG, NEDCDI, NEDCDO
13         .GLOBL  ININT, CDSSPD, LINRTS, TTRSAV, TTINPT
14         .GLOBL  CDCLOK, CDGDSS, CDSOSS, CDSBRK, SETSPD
15         .GLOBL  CDSTR2, CDSXON, CDSXOF, DLSTRT, DZSTRT
16         .GLOBL  SILFET, TRNSTR, NEDCLO, TIOVEC, GETDSS, SETDSS
17         ;
18         ; Global references
19         ;
20         .GLOBL  $OITIM, $XCHAR
21         .GLOBL  KPAR6, LMXLN
22         .GLOBL  DHSSPD, VHSSPD, DHSBRK, VHSBRK
23         .GLOBL  LMXNUM
24         .GLOBL  LSW3, LSW5
25         .GLOBL  MXCSR, MXLNT
26         .GLOBL  MXTBUF, MXTCR, NEDCHR, PR7, PSW
27         .GLOBL  RLINE
28         .GLOBL  TBR, TRINT, TRRDY, TSR
29         .GLOBL  DHSTRT, DHSTOP, DLSBRK, DZSBRK, DZSSPD
30         .GLOBL  VHSTRT, DLCLOK, DLSSPD, $DHCDO
31         .GLOBL  DHXON, DHXOFF, VHXON, VHXOFF
32         .GLOBL  DZCLOK, DLGDSS, DZGDSS, DHGDSS, VHGDSS
33         .GLOBL  DLSOSS, DZSDSS, DHSOSS, VHSOSS
34         .GLOBL  LOUTIR, KPAR5
35         .GLOBL  LSW10
36         .GLOBL  $HISTP
37         .GLOBL  $SXOFF, LCDTYP
38         .GLOBL  $SXON
39         .GLOBL  VHSTOP, INTPRI
40         .GLOBL  DHCLOK, VHCLOK

```

```

1      ; -----
2      ; Macro definitions:
3      ;
4      ; Disable interrupts
5      ;
6      .MACRO  DISABL          ;Disable interrupts
7      BIS    #340, @PSW
8      .ENDM  DISABL
9      ;
10     ; Enable interrupts
11     ;
12     .MACRO  ENABL          ;Enable interrupts
13     BIC    INTPRI, @PSW
14     .ENDM  ENABL
15     ;
16     ; Call a routine in a system overlay
17     ;
18     .MACRO  OCALL  ENTADD
19     .IF    B, ENTADD
20     .ERROR ;OCALL without entry address
21     .ENDC
22     CALL  OVRHC
23     .WORD ENTADD
24     .ENDM  OCALL
25     ;
26     ; The TTMAP and TTMAPX macros are used to map kernel-mode par6 to the
27     ; terminal character buffer area. The previous contents of par6 map
28     ; register are pushed on the stack and may be restored by using the
29     ; UNMAP or UNMAPX macros.
30     ; R1 must contain the line index number of the line whose buffers
31     ; are being accessed.
32     ; The difference between the TTMAP-UNMAP macros and the TTMAPX-UNMAPX
33     ; macros is that the X-versions are more efficient but may only be
34     ; used from within interrupt service routines where we are guaranteed
35     ; to be running on the system stack.
36     ; The TTMAP and UNMAP versions of the macros must only be
37     ; used in sections of code where the interrupts are disabled.
38     ;
39     .MACRO  TTMAPX
40     MOV    LTPAR(R1), @KPAR6
41     .ENDM  TTMAPX
42     ;
43     ;
44     ;
45     .MACRO  UNMAPX
46     .ENDM  UNMAPX
47     ;
48     .MACRO  TTMAP
49     MOV    @KPAR6, MAPHLD
50     MOV    LTPAR(R1), @KPAR6
51     .ENDM  TTMAP
52     ;
53     .MACRO  UNMAP
54     MOV    MAPHLD, @KPAR6
55     .ENDM  UNMAP

```

```

1 ;-----
2 ; Address vectors used to transfer control to device specific routines
3 ; based on the device type code (CDX$xxx).
4 ; Note: the entries in these vectors must be arranged in the same order
5 ; as the CDX$xxx values defined in TSGEN.
6 ;
7 ; Table of routines to call to initiate transmission to a line
8 ;
9 ; Inputs:
10 ; R1 = Physical line index number.
11 ;
12 000000 TSTIO:
13 177770' CDSTRT = .-10 ; Offset for absent DL,DZ,DH,DHV entries
14 000000 000120' .WORD DORTS ; Professional console
15 000002 000120' .WORD DORTS ; Professional communications port
16 000004 000120' .WORD DORTS ; Professional printer port
17 000006 000120' .WORD DORTS ; Professional quad serial line unit
18 ;
19 ; Table of routines used to perform actual hardware startup
20 ; of output transmission.
21 ;
22 000000' CDSTR2 = .-10 ; Offset for absent DL,DZ,DH,DHV entries
23 000010 000120' .WORD DORTS ; Professional console
24 000012 000120' .WORD DORTS ; Professional communications port
25 000014 000120' .WORD DORTS ; Professional printer port
26 000016 000120' .WORD DORTS ; Professional quad serial line unit
27 ;
28 ; Table of routines to call to stop transmission to a line.
29 ; (These routines are used if a ctrl-S is received)
30 ;
31 ; Inputs:
32 ; R1 = Physical line index number.
33 ;
34 000010' CDSTOP = .-10 ; Offset for absent DL,DZ,DH,DHV entries
35 000020 000120' .WORD DORTS ; Professional console
36 000022 000120' .WORD DORTS ; Professional communications port
37 000024 000120' .WORD DORTS ; Professional printer port
38 000026 000120' .WORD DORTS ; Professional quad serial line unit
39 ;
40 ; Table of routines called to stuff an XOFF (ctrl-S) into the output
41 ; stream for a line.
42 ;
43 ; Inputs:
44 ; R1 = Line index number
45 ;
46 000020' CDSXOF = .-10 ; Offset for absent DL,DZ,DH,DHV entries
47 000030 000174' .WORD DLXOFF ; Professional console
48 000032 000120' .WORD DORTS ; Professional communications port
49 000034 000174' .WORD DLXOFF ; Professional printer port
50 000036 000174' .WORD DLXOFF ; Professional quad serial line unit
51 ;
52 ; Table of routine called to stuff an XON (ctrl-Q) into the output
53 ; stream for a line.
54 ;
55 ; Inputs:
56 ; R1 = Line index number.
57 ;

```

```

58          000030'          CDSXON = .-10          ;Offset for absent DL,DZ,DH,DHV entries
59 000040 000222'          .WORD DLXON          ;Professional console
60 000042 000120'          .WORD DORTS          ;Professional communications port
61 000044 000222'          .WORD DLXON          ;Professional printer port
62 000046 000222'          .WORD DLXON          ;Professional quad serial line unit
63          ;
64          ; Table of routines to be called on a 0.5 second basis to do line checking.
65          ;
66          ; Inputs:
67          ; R1 = Physical line index number.
68          ;
69          000040'          CDCLOK = .-10          ;Offset for absent DL,DZ,DH,DHV entries
70 000050 000120'          .WORD DORTS          ;Professional console
71 000052 000120'          .WORD DORTS          ;Professional communications port
72 000054 000120'          .WORD DORTS          ;Professional printer port
73 000056 000120'          .WORD DORTS          ;Professional quad serial line unit
74          ;
75          ; Table of routines to be called to get the data set status
76          ;
77          ; Inputs:
78          ; R1 = Physical line index number.
79          ;
80          ; Outputs:
81          ; RO = Generic data set status flags (MS$xxx)
82          ;
83          000050'          CDGDSS = .-10          ;Offset for absent DL,DZ,DH,DHV entries
84 000060 000120'          .WORD DORTS          ;Professional console
85 000062 000120'          .WORD DORTS          ;Professional communications port
86 000064 000120'          .WORD DORTS          ;Professional printer port
87 000066 000120'          .WORD DORTS          ;Professional quad serial line unit
88          ;
89          ; Table of routines to be called to set data set status
90          ;
91          ; Inputs:
92          ; RO = Data set control flags (MS$xxx)
93          ; R1 = Physical line index number.
94          ;
95          000060'          CDSDSS = .-10          ;Offset for absent DL,DZ,DH,DHV entries
96 000070 000120'          .WORD DORTS          ;Professional console
97 000072 000120'          .WORD DORTS          ;Professional communications port
98 000074 000120'          .WORD DORTS          ;Professional printer port
99 000076 000120'          .WORD DORTS          ;Professional quad serial line unit
100         ;
101         ; Table of routines to be called to control break transmission
102         ;
103         ; Inputs:
104         ; RO = Break control flag (MS$BRK)
105         ; R1 = Physical line index number.
106         ;
107         000070'          CDSBRK = .-10          ;Offset for absent DL,DZ,DH,DHV entries
108 000100 000120'          .WORD DORTS          ;Professional console
109 000102 000120'          .WORD DORTS          ;Professional communications port
110 000104 000120'          .WORD DORTS          ;Professional printer port
111 000106 000120'          .WORD DORTS          ;Professional quad serial line unit
112         ;
113         ; Table of routines to be called to control transmission speed
114         ;

```

TSTIO -- PRO/TSX-Plus terminal interrupt driver

```

115      ; Inputs:
116      ;   R0 = Line speed code.
117      ;   R1 = Line index number.
118      ;
119      000100' CDSSPD = .-10      ; Offset for absent DL,DZ,DH,DHV entries
120 000110 000120'      .WORD DORTS      ; Professional console
121 000112 000120'      .WORD DORTS      ; Professional communications port
122 000114 000120'      .WORD DORTS      ; Professional printer port
123 000116 000120'      .WORD DORTS      ; Professional quad serial line unit
124      ;
125      ; Dummy routine to do a simple return
126      ;
127 000120 000207 DORTS: RETURN
128      ;
129      ; -----
130      ; Pointer vector to routines in TSTIOX module that is relocated over TSINIT.
131      ;
132 000122 TIOVEC:
133 000122 000000 ININTP: .WORD 0
134 000124 000000 TTINPT: .WORD 0
135 000126 000000 SILFET: .WORD 0
136 000130 000000 TTRSAV: .WORD 0
137 000132 000000 TRNSTR: .WORD 0
138 000134 000000 NEDCP: .WORD 0
139 000136 000000 CDORTN: .WORD 0
140 000140 000000 CDIRTN: .WORD 0
141 000142 000000 SNDFRE: .WORD 0
142 000144 177777      .WORD -1      ; Signal end of vector
143      ;
144      ; -----
145      ; Data areas
146      ;
147 000146 000000 MAPHLD: .WORD 0      ; TEMP CELL USED BY TTMAP MACRO
148 000150 000000 NEDCDI: .WORD 0      ; Non-zero ==> Need clock driven input proc
149 000152 000000 NEDCDO: .WORD 0      ; Non-zero ==> Need clock driven output proc
150 000154 000000 NEDCLO: .WORD 0      ; Non-zero ==> Need CL output processing
151 000156 000000 NEDSOT: .WORD 0      ; Non-zero ==> Need output-low job scheduling
152      ;
153      ; Byte data
154      ;
155 000160 000 CDIFLG: .BYTE 0      ; Non-zero ==> Input char fork routine running
156 000161 000 CDOFLG: .BYTE 0      ; Non-zero ==> Output char fork routine running
157      ; Table used to select bit-within-word corresponding to a line
158 000162 001 002 004 MXLBIT: .BYTE 1,2,4,10,20,40,100,200
      000165 010 020 040
      000170 100 200
159      .EVEN
160      ;
161      ; Ignore an interrupt
162      ;
163 000172 000207 LINRTS: RETURN      ; Ignore interrupt

```


DLXOFF -- Transmit XOFF character

```

1          .SBTTL  DLXOFF -- Transmit XOFF character
2          ;-----
3          ; DLXOFF is called to transmit an XOFF (ctrl-S) character to stop
4          ; transmission to us.
5          ;
6          ; Inputs:
7          ; R1 = Line index number.
8          ;
9 000174   DLXOFF:
10         ;
11         ; Set flag saying we have stopped the sender
12         ;
13 000174 052761 000000G 000000G      BIS    #$HISTP,LSW10(R1);Set flag saying we have stopped sender
14         ;
15         ; Set flag to cause an XOFF character to be sent by the transmitter
16         ; interrupt routine.
17         ;
18 000202 052761 000000G 000000G      BIS    #$SXOFF,LSW10(R1);Set flag saying to send XOFF
19         ;
20         ; Start the transmitter
21         ;
22 000210 016100 000000G      MOV     LCDTYP(R1),R0    ;Get device type code index
23 000214 004770 177770'      CALL   @CDSTRT(R0)     ;Call routine to start the transmitter
24         ;
25         ; Finished
26         ;
27 000220 000207      RETURN

```

DLXON -- Transmit XON character

```

1          .SBTTL  DLXON  -- Transmit XON character
2          ;-----
3          ; DLXON is called to transmit an XON (ctrl-Q) character.
4          ;
5          ; Inputs:
6          ;   R1 = Line index number.
7          ;
8 000222   DLXON:
9          ;
10         ; Clear flag that says XOFF has been sent
11         ;
12 000222  042761  000000G 000000G      BIC    ##HISTP,LSW10(R1);Clear flag that says XOFF has been sent
13         ;
14         ; Set flag to cause an XON character to be sent by the transmitter
15         ; interrupt routine.
16         ;
17 000230  052761  000000G 000000G      BIS    ##SXON,LSW10(R1);Force transmission of XON
18         ;
19         ; Start the transmitter
20         ;
21 000236  016100  000000G      MOV     LCDTYP(R1),R0    ;Get device type index number
22 000242  004770  177770'      CALL   @CDSTRT(R0)     ;Call routine to start the transmitter
23         ;
24         ; Finished
25         ;
26 000246  000207      RETURN

```

DLINT -- DL terminal output interrupt entry point

```

1          .SBTTL DLINT -- DL terminal output interrupt entry point
2          ;-----
3          ; DLINT contains the DL device specific output interrupt service routine.
4          ; The interrupt is vectored directly to an instruction sequence of the
5          ; form
6          ;
7          ;     JSR     R4,@#DLINT
8          ;     .WORD  line_number
9          ;
10         ; Thus on entry to DLINT R4 has been saved on the stack and currently
11         ; points to a word containing the line index number.
12         ;
13         ;
14 000250 010046 DLINT:  MOV     RO,-(SP)          ;Save registers (R4 already on stack)
15         ;
16         ; Obtain the interrupting physical line number.
17         ;
18 000252 011404         MOV     (R4),R4          ;Get physical line index number
19         ;
20         ; Get next character to transmit
21         ;
22 000254 004774 000000G CALL    @LOUTIR(R4)      ;Get next character for line
23 000260 103417         BCS    DLCLR          ;Br if no character available
24         ;
25         ; Transmit the character contained in RO.
26         ;
27 000262 052764 000000G 000000G BIS     #$XCHAR,LSW3(R4) ;Set transmitter busy flag
28 000270 042764 000000G 000000G BIC     #$OITIM,LSW5(R4) ;Start timer to catch lost interrupts
29 000276 032774 000000G 000000G 1$: BIT     #TRRDY,@TSR(R4) ;Make sure transmitter is ready
30 000304 001774         BEQ     1$          ;Should never loop here
31 000306 110074 000000G         MOVB   RO,@TBR(R4)      ;Transmit the character
32         ;
33         ; Finished. Return from interrupt.
34         ;
35 000312 012600 DLRTN:  MOV     (SP)+,RO
36 000314 012604         MOV     (SP)+,R4          ;R4 was pushed by JSR instruction
37 000316 000002         RTI
38         ;
39         ; Disable transmit interrupts.
40         ;
41 000320 042764 000000G 000000G DLCLR:  BIC     #$XCHAR,LSW3(R4) ;Set not busy transmit flag
42 000326 042774 000000G 000000G         BIC     #TRINT,@TSR(R4) ;Disable transmit interrupt enable
43 000334 000766         BR     DLRTN          ;Return from interrupt
44         ;
45         .SBTTL DLSTRT -- Start output to a DL11 line
46         ;-----
47         ; Start output to a DL11 line.
48         ; Enable transmit interrupts.
49         ; R1 = Physical line number
50         ;
51 000336 052771 000000G 000000G DLSTRT: BIS     #TRINT,@TSR(R1) ;Enable transmit interrupt enable
52 000344 000207         RETURN
53

```

NEDCHR -- Get next character for output

```
1           .SBTTL  NEDCHR -- Get next character for output
2           ;-----
3           ; This is a dummy resident routine which calls the relocated
4           ; NEDCHR routine in the TSTIOX module.
5           ;
6 000346 000177 177562  NEDCHR: JMP      @NEDCP           ;Call routine in TSTIOX
7           ;
8           ;-----
9           ; This is a dummy resident routine which calls the relocated
10          ; ININT routine in the TSTIOX module.
11          ;
12 000352 000177 177544  ININT:  JMP      @ININTP          ;Call routine in TSTIOX
13          ;
```

SETSPD -- Set transmit/receive speed for a line

```

1                                     .SBTTL  SETSPD -- Set transmit/receive speed for a line
2                                     ;-----
3                                     ; SETSPD is called to set the transmit/receive speed for a line.
4                                     ;
5                                     ; Inputs:
6                                     ;   R0 = Speed code.
7                                     ;   R1 = Line index number of line being set.
8                                     ;
9 000356 010246 SETSPD: MOV      R2, -(SP)
10 000360 013746 000000G      MOV      @#KPAR5, -(SP) ; Save kpar 5 in case an overlay is calling us
11                                     ;
12                                     ; Call hardware dependent routine to set the speed
13                                     ;
14 000364 016102 000000G      MOV      LCDTYP(R1), R2 ; Get hardware device type code
15 000370 004772 000100'      CALL     @CDSSPD(R2) ; Call routine to set the speed
16                                     ;
17                                     ; Finished
18                                     ;
19 000374 012637 000000G      MOV      (SP)+, @#KPAR5
20 000400 012602      MOV      (SP)+, R2
21 000402 000207      RETURN

```

GETDSS/SETDSS -- Get/set data set status

```

1          .SBTTL  GETDSS/SETDSS -- Get/set data set status
2          ;-----
3          ; Inputs: R1 contains line index
4          ;           For set, options are in R0 (for @CSDSS routine)
5          ; Outputs: For get, options are returned in R0 (by @CDGSS routine)
6          ;
7 000404  005046  GETDSS: CLR      -(SP)          ; Say we are getting status
8 000406  000402          BR      DSSCOM        ; Br to common routine
9 000410  012746  000001  SETDSS: MOV      #1, -(SP)        ; Say we are setting data set status
10         ;
11 000414  010246  DSSCOM: MOV      R2, -(SP)
12 000416  013746  000000G  MOV      @#KPAR5, -(SP) ; Save KPAR 5 in case overlay is calling us
13         ;
14         ; Call hardware dependent routine to get current data set status
15         ;
16 000422  016102  000000G  MOV      LCDTYP(R1), R2 ; Get hardware device type code
17 000426  005766  000004    TST      4(SP)          ; Get or set data set status?
18 000432  001003          BNE      1$            ; Br if set
19 000434  004772  000050'   CALL     @CDGSS(R2)     ; Get data set status (into R0)
20 000440  000402          BR      2$            ; Br to exit
21 000442  004772  000060'   1$:     CALL     @CSDSS(R2) ; Set data set status (from R0)
22         ;
23         ; Clean up and return
24         ;
25 000446  012637  000000G  2$:     MOV      (SP)+, @#KPAR5 ; Restore KPAR 5 mapping
26 000452  012602          MOV      (SP)+, R2
27 000454  005726          TST      (SP)+        ; Remove GET/SET flag from stack
28 000456  000207          RETURN

```

```
1          .SBTTL  DZOINT,DZSTRT (Dummies)
2          ;-----
3          ; TSINIT requires an entry for DZOINT for initializing mux line
4          ; (including the Qual-SLU), so create a dummy DZ output interrupt
5          ; routine to just throw DZ output interrupts (which will never
6          ; happen anyway on the Pro) away.
7          ;
8 000460 012605 DZOINT: MOV      (SP)+,R5      ;Was pushed by JSR R5,@#DZOINT
9 000462 000002          RTI                  ;Discard interrupt
10         ;
11         ; TSEXC2 requires an entry point for DZSTRT.
12         ;
13 000464 000207 DZSTRT: RETURN                ;Dummy routine
14         ;
15         ; End of modified and truncated TSTIO section.
16         ;
```

```

1          .SBTTL  TSXPRO -- Digital PRO-3xx specific routines
2          ;-----
3 000000   .CSECT  TSXPRO
4 000000   TSXPRO:
5 000000   PROBAS:
6          ;
7          ;   TSX-Plus interface routines for Digital PRO-3xx series
8          ;   personal computers.
9          ;
10         ;   Global definitions
11         ;
12         .GLOBL  TSXPRO
13         .GLOBL  PROSIZ,PROLIN,PROINI,PROHAN,PIHAN,PRONOP
14         .GLOBL  PIDRIV
15         ;
16         ;   Global references
17         ;
18         .GLOBL  FRKCQE,DOSCHD,CORUSR,LXCL
19         .GLOBL  LMXPRM,$XCHAR,LSW3,$OITIM,LSW5,PROSLT
20         .GLOBL  FORK,INTEN,TTINPT,RBERR,OVRRUN,FRMERR,RCVPAR
21         .GLOBL  RSR,PSW,INTPRI,CDSTRT,CDGDSS,CSDSS,$PHONE,ILSW2
22         .GLOBL  LCDTYP,CDX$PC,CDX$PP,MS$DTR,MS$CAR,MS$RNG
23         .GLOBL  PROBRK,$DEAD,PPTERM,LSTHL,CDX$PI,$HISTP
24         .GLOBL  INVEC,LOUTIR,S9600,CDSXOF,CDSXON
25         .GLOBL  KPAR5,KPAR6,VPAR5,VPAR6,PISRT,CDCLOK,VSWPSL
26         .GLOBL  RT$BAS,IOFIN,FP$PIO,LSW10,$SXON,$SXOFF
27         .GLOBL  MS$BRK,CDSBRK,CDSSPD,VT100,ITRMTTP,TTRSAV
28         .GLOBL  LP$SPD,LP$PAR,LP$ODD,LP$7BT,S4800
29         .GLOBL  RPRCSR,RPRVEC,DWTYPE,VIDCSR,CDX$QP
30         .GLOBL  SRMMR,SR3MMR,MMENBL,EMMAP,LMXNUM,LMXLN
31         .GLOBL  MXVEC,MXCSR,PROBUF

```


Macros

```
1           .SBTTL  Macros
2           ;-----
3           ; Macro to disable interrupts
4           ;
5           .MACRO  DISABL
6           BIS    #340, @PSW
7           .ENDM  DISABL
8           ;
9           ; Macro to enable interrupts
10          ;
11          .MACRO  ENABL
12          BIC    INTPRI, @PSW
13          .ENDM  ENABL
```

Data areas

```

1          .SBTTL  Data areas
2          ;-----
3          ; Vector of addresses used to move information between TSXPRO and PI handler.
4          ;
5          PROVEC:
6          ;
7          ; Addresses passed from the PI handler to TSXPRO
8          ;
9          000000 000000  PIINAD: .WORD 0 ;Address of initialization code
10         000002 000000  PIINWD: .WORD 0 ;Number of words of initialization code
11         000004 000000  PIXOCH: .WORD 0 ;Routine called to send a char to the video
12         000006 000000  PIXEOF: .WORD 0 ;Routine called for end-of-frame interrupts
13         000010 000000  PIXICH: .WORD 0 ;Routine to process keyboard input interrupts
14         000012 000000  PIXIOI: .WORD 0 ;Routine to process keyboard output interrupts
15         000014 000000  PIXIOQ: .WORD 0 ;Routine to process an I/O queue request
16         000016 000000  $VDCSR: .WORD 0 ;Address of video CSR address
17         000020 000000  REENAB: .WORD 0 ;Pointer to REENAB cell
18         000022 000000  PRIOO: .WORD 0 ;Pointer to PRIOO cell
19         000024 000000  VDFLAG: .WORD 0 ;Pointer to VDFLAG cell
20         000026 000000  PIGOFL: .WORD 0 ;Pointer to PIGOFL cell (1==>PI run, 0==>stop)
21         ;
22         ; Addresses passed from TSXPRO to the PI handler
23         ;
24         000030 002156' .WORD KBDCHR ;Routine to process an input character
25         000032 000000G .WORD FORK ;Address of system .FORK routine
26         000034 001740' .WORD PINDCH ;Routine to get next char to send
27         000036 001172' .WORD GPRCSR ;Routine to get CSR address for device
28         000040 001254' .WORD GETSLT ;Routine to get option slot # for device
29         ;
30         ; End of address vector
31         ;
32         000042 000000 .WORD 0 ;End of PROVEC vector
33         ;
34         ;-----
35         ; Data areas:
36         ;
37         000044 000000  PILINE: .WORD 0 ;# of line connected to Pro console
38         000046 000000  PPLINE: .WORD 0 ;# of line connected to printer port
39         000050 000000  CPLINE: .WORD 0 ;# of line connected to communications port
40         000052 000000  PIBASE: .WORD 0 ;Base 64-byte block # of PI handler
41         000054 000000  PIOIFL: .WORD 0 ;Non-zero ==> Doing PI output interrupt
42         000056 177777  PISCNT: .WORD -1 ;Counts output starts per clock period
43         000060 062550  R5OPI: .RAD50 /PI / ;Name of PI handler
44         000062 000000  VIDSLT: .WORD 0 ;Option slot # where video controller is
45         000064 000000  VIDVEC: .WORD 0 ;Address of video vector A
46         000066 000000  QPCSR: .WORD 0 ;Address of base of registers for quad port
47         000070 000000  QPVEC: .WORD 0 ;Address of vector for quad port
48         000072 000017  PIMOC: .WORD MAXPOC ;Limit consecutive output chars to PI
49         ;
50         ; Table of possible video device ID values
51         ;
52         000074 001002  VIDTBL: .WORD 1002 ;350 video
53         000076 000050 .WORD 50 ;380 video
54         000100 010050 .WORD 10050 ;380 video with EBO
55         000102 002002 .WORD 2002 ;IVIS video
56         ;
57         ; Byte data

```

Data areas

```
58  
59 000104      000      000      000      ;  
      000107      000      QPLX:  .BYTE  0,0,0,0      ;Line #'s connected to each quad port line  
60 000110      000      QPMODM: .BYTE  0      ;0==>4/0 configuration, 1==>2/2 configuration  
61 000111      000      QPSLOT: .BYTE  0      ;Slot # where quad port controller installed  
62      .EVEN
```

System control register

1		.SBTTL System control register
2		;
3		-----
4		; Control values in system status register
5	173700	; PSSREG = 173700 ; Address of status register
6		;
7		; Flags in status register
8		;
9	000007	SS\$BNK = 7 ; Mask for memory bank information
10	000020	SS\$MON = 20 ; Monitor-present flag
11	000200	SS\$BRK = 200 ; Break enable flag for diagnostic port

```

1          .SBTTL  Interrupt control values
2          ;-----
3          ; The following values relate to the interrupt control system on the
4          ; Professional computer.
5          ;
6          ; Addresses of control registers
7          ;
8          173200 ICODR  =      173200 ; Interrupt controller 0 data register
9          173202 ICOCRS =      173202 ; Interrupt controller 0 control register
10         173204 IC1DR  =      173204 ; Interrupt controller 1 data register
11         173206 IC1CSR =      173206 ; Interrupt controller 1 control register
12         173210 IC2DR  =      173210 ; Interrupt controller 2 data register
13         173212 IC2CSR =      173212 ; Interrupt controller 2 control register
14         ;
15         ; Interrupt Mode Register
16         ;
17         000001 IM$PM  =      1 ; Priority mode (0=fixed, 1=rotating)
18         000002 IM$VS  =      2 ; Vector selection
19         000004 IM$IM  =      4 ; Interrupt mode (1==>Do not interrupt)
20         000010 IM$GIP =     10 ; Group interrupt polarity
21         000020 IM$IRP =     20 ; Interrupt request polarity
22         000140 IM$RP  =    140 ; Mask for register preselect values
23         000200 IM$MM  =     200 ; Master mask (1==>Enable group interrupts)
24         000200 IM$STV =     200 ; Standard value for TSX-Plus
25         ;
26         ; Command values that can be stored into CSR register
27         ;
28         000000 IM$RST =     000 ; Reset
29         000020 IM$ZRM =     020 ; Clear bits in IRR and IMR registers
30         000030 IM$CRM =     030 ; Clear single bit in IRR and IMR registers
31         000040 IM$ZM  =     040 ; Clear all bits in IMR register
32         000050 IM$CM  =     050 ; Clear single bit in IMR register
33         000060 IM$OM  =     060 ; Set all bits in IMR register to one
34         000070 IM$SM  =     070 ; Set single bit in IMR register
35         000100 IM$ZR  =    100 ; Clear all bits in IRR register
36         000110 IM$CR  =    110 ; Clear single bit in IRR register
37         000120 IM$OR  =    120 ; Set all bits in IRR register to ones
38         000130 IM$SR  =    130 ; Set single bit in IRR register
39         000140 IM$CHP =    140 ; Clear highest priority ISR bit
40         000160 IM$ZS  =    160 ; Clear ISR register to zero
41         000170 IM$CS  =    170 ; Clear single bit in ISR register
42         000200 IM$LMB =    200 ; Load mode bits
43         000240 IM$CMB =    240 ; Control mode bits
44         000260 IM$PR  =    260 ; Preselect IMR register
45         000300 IM$PA  =    300 ; Preselect ACR register
46         000340 IM$PRM =    340 ; Preselect response memory
47         ;
48         ; Values used with command codes to select specific interrupts
49         ;
50         000001 IM$KBR =      1 ; ICO - Keyboard receiver interrupt
51         000002 IM$KBT =      2 ; ICO - Keyboard transmitter interrupt
52         000003 IM$CPD =      3 ; ICO - Communications port data transfer
53         000004 IM$CPM =      4 ; ICO - Communications port modem change
54         000005 IM$PPR =      5 ; ICO - Printer port receiver interrupt
55         000006 IM$PPT =      6 ; ICO - Printer port transmitter interrupt
56         000007 IM$CLK =      7 ; ICO - Clock interrupt

```

Video display control values

```

1          .SBTTL  Video display control values
2          ;-----
3          ; The following values relate to the video display.
4          ;
5          ; Control flags in Constrol/status register
6          ;
7          000001 VP$LMD = 1          ;Line mode definition
8          000002 VP$IMD = 2          ;Interlace mode definition
9          000040 VP$OEF = 40         ;Odd/Even frame flag
10         000100 VP$EFI = 100        ;End of frame interrupt enable
11         000200 VP$EOF = 200        ;End of frame flag
12         001400 VP$COO = 1400       ;Mask for class of operation
13         002000 VP$CME = 2000       ;Color map enable
14         010000 VP$OMP = 10000      ;Option module presence flag
15         040000 VP$DOI = 40000     ;Done interrupt enable
16         100000 VP$TRD = 100000    ;Transfer done flag

```

```

1          .SBTTL Printer port control values
2          ;-----
3          ; The following values relate to the "printer port" which can optionally
4          ; be used as a time-sharing terminal under TSX-Plus.
5          ;
6          ; Register addresses and vectors
7          ;
8          173400 PP$DBR = 173400 ;Data buffer register
9          173402 PP$STR = 173402 ;Status register
10         173404 PP$MDR = 173404 ;Mode registers
11         173406 PP$CMR = 173406 ;Command register
12         177560 PP$RCS = 177560 ;Receiver CSR for maintenance mode
13         177564 PP$TCS = 177564 ;Transmitter CSR for maintenance mode
14         ;
15         000220 PP$RCV = 220 ;Receiver vector
16         000224 PP$TRV = 224 ;Transmitter vector
17         ;
18         ; Flags in the status register
19         ;
20         000001 PP$TR = 1 ;Transmitter ready
21         000002 PP$RD = 2 ;Receive done
22         000010 PP$PE = 10 ;Parity error detected
23         000020 PP$OE = 20 ;Overrun error
24         000040 PP$FE = 40 ;Framing error
25         000200 PP$DSR = 200 ;Data set ready
26         ;
27         ; Flags in mode register 1
28         ;
29         000014 PP$LEN = 14 ;Mask for character length
30         000010 PP$7BT = 10 ;7 bit characters
31         000014 PP$8BT = 14 ;8 bit characters
32         000020 PP$PAR = 20 ;Enable parity control
33         000040 PP$EVN = 40 ;1==>even parity, 0==>odd parity
34         000300 PP$SBL = 300 ;Mask for stop bit length
35         000102 PP$M1F = 102 ;Standard mode register 1 value for TSX-Plus
36         ;
37         ; Flags in mode register 2
38         ;
39         000017 PP$BRS = 17 ;Mask for baud rate select field
40         000260 PP$M2F = 260 ;Standard mode register 2 value for TSX-Plus
41         ;
42         ; Command register
43         ;
44         000001 PP$TEN = 1 ;Transmitter enable
45         000002 PP$DTR = 2 ;Data terminal ready
46         000004 PP$REN = 4 ;Receiver enable
47         000010 PP$FB = 10 ;Force break transmission
48         000020 PP$RE = 20 ;Reset error
49         000040 PP$RTS = 40 ;Request to send
50         000300 PP$OM = 300 ;Operating mode mask
51         000047 PP$CMF = 47 ;Standard command register value for TSX-Plus

```

```

1          .SBTTL Communications port control values
2          ;-----
3          ; Control values for the communications port which may be used as
4          ; a TSX-Plus time-sharing line.
5          ;
6          ; Control registers and vectors
7          ;
8          173300 CP$DBR = 173300 ;Data buffer register
9          173302 CP$CAR = 173302 ;Control/status register A
10         173306 CP$CBR = 173306 ;Control/status register B
11         173310 CP$MOR = 173310 ;Modem control register 0
12         173312 CP$M1R = 173312 ;Modem control register 1
13         173314 CP$BRR = 173314 ;Baud rate register
14         ;
15         000210 CP$RTV = 210 ;Receive/transmit vector
16         000214 CP$MCV = 214 ;Modem change vector
17         ;
18         ; Control/status Register A
19         ;
20         000007 CP$ARP = 7 ;Mask to select read/write sub-register
21         000070 CP$ACM = 70 ;Mask for command bits
22         000300 CP$CRC = 300 ;Mask for CRC control bits
23         ;
24         ; Read/Write sub-register select values
25         ; (These values are stored into CP$ARP and CP$BRP to select sub registers)
26         ;
27         000000 CP$WRO = 0 ;Write register 0
28         000001 CP$WR1 = 1 ;Write register 1
29         000002 CP$WR2 = 2 ;Write register 2
30         000003 CP$WR3 = 3 ;Write register 3
31         000004 CP$WR4 = 4 ;Write register 4
32         000005 CP$WR5 = 5 ;Write register 5
33         000006 CP$WR6 = 6 ;Write register 6
34         000007 CP$WR7 = 7 ;Write register 7
35         000000 CP$RRO = 0 ;Read register 0
36         000001 CP$RR1 = 1 ;Read register 1
37         000002 CP$RR2 = 2 ;Read register 2
38         ;
39         ; Command values for WRO under control/status register A
40         ;
41         000010 CP$SA = 10 ;Send abort
42         000020 CP$RES = 20 ;Reset external interrupt
43         000030 CP$CR = 30 ;Channel reset
44         000040 CP$EIR = 40 ;Enable interrupt on next char received
45         000050 CP$RTI = 50 ;Reset transmitter interrupt pending
46         000060 CP$ER = 60 ;Error reset
47         000070 CP$EI = 70 ;End of interrupt
48         ;
49         ; Sub-register WR1 under control/status register A
50         ;
51         000001 CP$EIE = 1 ;External interrupt enable
52         000002 CP$TIE = 2 ;Transmitter interrupt enable
53         000030 CP$RIE = 30 ;Mask for receiver interrupt enable flags
54         ;
55         ; Sub-register WR3 under control/status register A
56         ;
57         000001 CP$REN = 1 ;Receiver enable

```


Communications port control values

```

58      000002      CP$SCL =      2      ; Sync character load inhibit
59      000004      CP$ASM =      4      ; Address search mode
60      000010      CP$RCE =     10      ; Receiver CRC enable
61      000020      CP$EHP =     20      ; Enter hunt phase
62      000300      CP$RCL =    300      ; Receiver character length
63      000100      CP$7BR =    100      ; 7 bit characters
64      000300      CP$8BR =    300      ; 8 bit characters
65      000001      CP$AW3 =     001      ; Standard value for TSX-Plus
66      ;
67      ; Sub-register WR4 under control/status register A
68      ;
69      000001      CP$PAR =      1      ; Parity enable
70      000002      CP$EVN =      2      ; 1==>even parity, 0==>odd parity
71      000014      CP$SBS =     14      ; Mask for stop bits select value
72      000060      CP$SMS =     60      ; Mask for synchronous mode control flags
73      000300      CP$CMM =    300      ; Mask for clock mode value
74      000104      CP$AW4 =    104      ; Standard value for TSX-Plus
75      ;
76      ; Sub-register WR5 under control/status register A
77      ;
78      000001      CP$TCE =      1      ; Transmitter CRC enable
79      000004      CP$CCS =      4      ; CRC polynomial select
80      000010      CP$TEN =     10      ; Transmitter enable
81      000020      CP$SB  =     20      ; Send break
82      000014      CP$LEN =     14      ; Transmitter character length
83      000040      CP$7BT =     40      ; 7 bit characters
84      000140      CP$8BT =    140      ; 8 bit characters
85      000010      CP$AW5 =     010      ; Standard value for TSX-Plus
86      ;
87      ; Sub-register RRO under control/status register A
88      ;
89      000001      CP$RCA =      1      ; Receive character available
90      000002      CP$INP =      2      ; Interrupt pending
91      000004      CP$TBM =      4      ; Transmit buffer empty
92      000020      CP$SH  =     20      ; Sync/hunt
93      000100      CP$TEM =    100      ; Transmitter underrun/end of message
94      000200      CP$BR  =    200      ; Break received
95      ;
96      ; Sub-register RR1 under control/status register A
97      ;
98      000001      CP$AS  =      1      ; All sent -- Transmitter ready for next char
99      000016      CP$RC  =     16      ; Mask for residue codes
100     000020      CP$RPE =     20      ; Received parity error
101     000040      CP$ROE =     40      ; Receiver overrun error
102     000100      CP$RFE =    100      ; Framing error
103     000200      CP$EOF =    200      ; End of frame
104     ;
105     ; Control/status Register B
106     ;
107     000007      CP$BRP =      7      ; Mask to select sub-register
108     ;
109     ; Sub-register WR1 under control/status register B
110     ;
111     000004      CP$BW1 =      4      ; Standard value for TSX-Plus
112     ;
113     ; Sub-register WR2 under control/status register B
114     ;

```

115	077777	CP\$BW2 =	77777	; Standard value for TSX-Plus
116		;		
117		;	Sub-register RR2 under control/status register B	
118		;		
119	000000	CP\$ITE =	0	; Transmitter buffer empty
120	000024	CP\$IES =	24	; External status change
121	000030	CP\$IRC =	30	; Receiver character available
122	000034	CP\$ISR =	34	; Special receiver condition
123		;		
124		;	Modem Control Register 0	
125		;		
126	000001	CP\$LL =	1	; Local loopback
127	000002	CP\$RL =	2	; Remote loopback
128	000004	CP\$SRS =	4	; Signaling rate select
129	000010	CP\$RTS =	10	; Request to send
130	000020	CP\$DTR =	20	; Data terminal ready
131	000140	CP\$CS =	140	; Mask for clock source values
132	000200	CP\$MM =	200	; Maintenance mode
133	000030	CP\$MCO =	30	; Standard value for TSX-Plus
134		;		
135		;	Modem Control Register 1	
136		;		
137	000004	CP\$SMI =	4	; Speed mode indicator
138	000010	CP\$TI =	10	; Test indicator
139	000020	CP\$CD =	20	; Carrier detect
140	000040	CP\$CTS =	40	; Clear to send
141	000100	CP\$RI =	100	; Ring indicator
142	000200	CP\$DSR =	200	; Data set ready

Quad Serial Line Unit control values

```

1          .SBTTL  Quad Serial Line Unit control values
2          ;-----
3          ;
4          ; Device ID for quad serial line unit
5          ;
6          000064 QP$ID = 64 ;Device ID for quad serial line unit
7          ;
8          ; Addresses of registers relative to base address for module
9          ;
10         ; Read registers
11         ;
12         000004 QPRMSR = 004 ;Module status register
13         000100 QPRMRA = 100 ;Mode register A
14         000102 QPRSRA = 102 ;Status register A
15         000106 QPRRRA = 106 ;Receiver register A
16         000112 QPRISR = 112 ;Interrupt status register
17         000120 QPRMRB = 120 ;Mode register B
18         000122 QPRSRB = 122 ;Status register B
19         000126 QPRRRB = 126 ;Receiver register B
20         000132 QPRIP = 132 ;Input port
21         ;
22         ; Write registers
23         ;
24         000102 QPRCSA = 102 ;Clock select A
25         000104 QPRCRA = 104 ;Command register A
26         000106 QPRTRA = 106 ;Transmitter register A
27         000110 QPRACR = 110 ;Auxiliary control register
28         000112 QPRIMR = 112 ;Interrupt mask register
29         000122 QPRCSB = 122 ;Clock select B
30         000126 QPRTRB = 126 ;Transmitter register B
31         000132 QPROPC = 132 ;Output port configuration register
32         000134 QPRSOP = 134 ;Set output port bits register
33         000136 QPRROP = 136 ;Reset output port bits register
34         ;
35         ; Offsets to register addresses by channel and DUART
36         ;
37         000020 QPRCOF = 020 ;Diff between channel A and B registers
38         000040 QPRUOF = 040 ;Diff between DUART 0 and DUART 1 registers
39         ;
40         ; Control flags for the quad serial line unit.
41         ;
42         ; Module status register
43         ;
44         000004 QP$22C = 4 ;2/2 configuration
45         000010 QP$40C = 10 ;4/0 configuration
46         000100 QP$IEN = 100 ;Interrupt enable
47         ;
48         ; Mode register 1
49         ;
50         000002 QP$7BR = 2 ;7 bit characters
51         000003 QP$8BR = 3 ;8 bit characters
52         000004 QP$ODD = 4 ;On ==> Odd parity
53         000020 QP$NPR = 20 ;No parity (off==>Want parity)
54         000040 QP$BEM = 40 ;Block error mode
55         000100 QP$SFL = 100 ;Interrupt when silo full
56         000200 QP$RXR = 200 ;Receiver RTS control
57         ;

```

Quad Serial Line Unit control values

```

58      ; Mode register 2
59      ;
60      000007      QP$1SB =      7      ; One stop bit
61      000017      QP$2SB =     17      ; Two stop bits
62      000020      QP$TCS =     20      ; Transmitter CTS enable
63      000040      QP$TRS =     40      ; Transmitter RTS enable
64      ;
65      ; Command register
66      ;
67      000001      QP$ERX =      1      ; Enable receiver
68      000002      QP$DRX =      2      ; Disable receiver
69      000004      QP$ETX =      4      ; Enable transmitter
70      000010      QP$DTX =     10      ; Disable transmitter
71      ;
72      ; Command values for command register
73      ;
74      000020      QP$RPR =     20      ; Reset MR pointer
75      000040      QP$RRX =     40      ; Reset receiver
76      000060      QP$RTX =     60      ; Reset transmitter
77      000100      QP$RES =    100      ; Reset error status
78      000120      QP$RBC =    120      ; Reset break change interrupt
79      000140      QP$SBT =    140      ; Start break transmission
80      000160      QP$EBT =    160      ; End break transmission
81      ;
82      ; Status register
83      ;
84      000001      QP$RDN =      1      ; Receiver ready (character received)
85      000002      QP$FFL =      2      ; FIFO silo full
86      000004      QP$TDN =      4      ; Transmitter ready (finished sending char)
87      000010      QP$TEM =     10      ; Transmitter buffer empty
88      000020      QP$ROE =     20      ; Receiver overrun error
89      000040      QP$RPE =     40      ; Received parity error
90      000100      QP$RFE =    100      ; Received framing error
91      000200      QP$BRK =    200      ; Received break
92      ;
93      ; Auxiliary control register
94      ;
95      000360      QP$AWA =    360      ; Standard value for TSX-Plus
96      ;
97      ; Interrupt status register
98      ;
99      000001      QP$TAR =      1      ; Transmitter A finished transmission
100     000002      QP$RAR =      2      ; Receiver A has a character
101     000004      QP$BCA =      4      ; Receiver A break status change
102     000010      QP$CNR =     10      ; Counter/timer ready
103     000020      QP$TBR =     20      ; Transmitter B finished transmission
104     000040      QP$RBR =     40      ; Receiver B has a character
105     000100      QP$BCB =    100      ; Receiver B break status change
106     000200      QP$IPC =    200      ; Input port status change
107     ;
108     ; Interrupt mask register
109     ;
110     000063      QP$AWI =     63      ; Standard value for TSX-Plus

```

```

1          .SBTTL  PROINI -- General initialization for Pro
2          ;-----
3          ; Perform general system initialization for PRO.
4          ;
5 000112  010146  PROINI: MOV      R1,-(SP)
6          ;
7          ; Set up information about which device is installed in each option slot
8          ;
9 000114  004737  000270'          CALL      INISLT
10         ;
11        ; Set up address of video interrupt vector and CSR
12        ;
13 000120  012701  000074'          MOV      #VIDTBL,R1          ;Point to table with video ID's
14 000124  012100          1$:  MOV      (R1)+,RO          ;Get next possible video device ID
15 000126  004737  001254'          CALL     GETSLT          ;See if we can find this ID
16 000132  103774          BCS     1$          ;Loop if not
17 000134  010037  000062'          MOV      RO,VIDSLT          ;Save video option slot number
18 000140  072027  000003          ASH     #3,RO          ;Convert slot # to interrupt address
19 000144  062700  000300          ADD     #300,RO
20 000150  010037  000064'          MOV      RO,VIDVEC          ;Save address of video int vector
21 000154  013700  000062'          MOV      VIDSLT,RO          ;Get video slot #
22 000160  072027  000007          ASH     #7,RO          ;CSR addresses are 200 apart per slot
23 000164  062700  174000          ADD     #174000,RO          ;Add address of CSR for slot 0
24 000170  010037  000000G          MOV      RO,VIDCSR          ;Set CSR address for video
25        ;
26        ; Store pointers to the routines that get CSR and Vector addresses
27        ; for PRO devices.
28        ;
29 000174  012737  001126' 000000G          MOV      #GPVVEC,RPRVEC          ;Routine to get PRO vector addresses
30 000202  012737  001130' 000000G          MOV      #GPVCSR,RPRCSR          ;Routine to get PRO CSR addresses
31        ;
32        ; Determine if a terminal is connected to the printer port.
33        ;
34 000210  113700  177560          MOVB   @PP$RCS,RO          ;Get receiver control register
35 000214  153700  177564          BISB   @PP$TCS,RO          ;Combine flags from transmitter
36 000220  001405          BEQ    4$          ;Br if terminal not connected
37 000222  105237  000000G          INCB   PPTERM          ;Remember terminal on printer port
38        ;
39        ; A terminal is connected to the printer port.
40        ; Enable BREAK key on diagnostic terminal to enter ODT
41        ;
42 000226  005727  000000G          TST    #PROBRK          ;Is break control wanted?
43 000232  001004          BNE    2$          ;Br if yes
44 000234  042737  000200  173700  4$:  BIC    #SS$BRK,@PSSREG          ;Disable break control
45 000242  000406          BR     5$
46 000244  052737  000200  173700  2$:  BIS    #SS$BRK,@PSSREG          ;Enable break ODT entry
47 000252  012737  000067  173406          MOV    #PP$CMF!PP$RE,@PP$CMR ;Enable printer port
48        ;
49        ; Perform initialization for quad serial line unit
50        ;
51 000260          5$:
52        .IF      NE,QPASM          ;Do if quad line support wanted
53 000260  004737  004660'          CALL   QPINIT          ;Init quad line unit
54        .ENDC      ;NE,QPASM
55        ;
56        ; Finished
57        ;

```

58 000264 012601
59 000266 000207

9#: MOV (SP)+,R1
RETURN

INISLT -- Set up information about option slots

```

1                                     .SBTTL  INISLT -- Set up information about option slots
2                                     ;-----
3                                     ; This routine initializes a table that contains the device ID's of
4                                     ; devices installed in each of the PRO option slots.
5                                     ;
6 000270 010146  INISLT: MOV      R1,-(SP)
7 000272 010246      MOV      R2,-(SP)
8                                     ;
9                                     ; Map KPAR5 to system configuration table
10                                    ;
11 000274 005001      CLR      R1          ;Get byte value without sign extension
12 000276 153701 173050  BISH    @#173050,R1      ;Get 32Kb top of memory block #
13 000302 072127 000011  ASH     #9,R1          ;Convert to 64 byte block number
14 000306 162701 000200  SUB     #200,R1         ;Get # of last 8Kb block of memory
15 000312          DISABL          ;** Disable interrupts **
16 000320 013746 000000G  MOV     @#KPAR5,-(SP)    ;Save current par 5 mapping
17 000324 010137 000000G  MOV     R1,@#KPAR5     ;Map par5 to configuration table
18 000330 052737 000000G 000000G  BIS     #MMENBL,@#SROMMR ;Turn on memory management
19 000336 052737 000000G 000000G  BIS     #EMMAP,@#SR3MMR ;Enable 22 bit addressing
20                                    ;
21                                    ; Get number of option slots
22                                    ;
23 000344 012702 017764G  MOV     #VPAR5+17764,R2 ;Point to cell with # option slots
24 000350 011200          MOV     (R2),R0        ;Get # of option slots
25                                    ;
26                                    ; Set up table in TSX that has device ID number of each option slot
27                                    ;
28 000352 012701 000000G  MOV     #PROSLT,R1     ;Point to table that will store option ID's
29 000356 005742 1$: TST     -(R2)          ;Skip word with option status value
30 000360 014221          MOV     -(R2),(R1)+    ;Store option ID code
31 000362 077003          SOB     R0,1$         ;Loop to get all option slot device ID's
32 000364 012711 177777  MOV     #-1,(R1)      ;Store -1 at end of table
33                                    ;
34                                    ; Restore KPAR5 mapping
35                                    ;
36 000370 012637 000000G  MOV     (SP)+,@#KPAR5 ;Restore par 5 mapping
37 000374 042737 000000G 000000G  BIC     #MMENBL,@#SROMMR ;Turn off memory mapping
38 000402          ENABL          ;** Enable interrupts **
39                                    ;
40                                    ; Finished
41                                    ;
42 000410 012602          MOV     (SP)+,R2
43 000412 012601          MOV     (SP)+,R1
44 000414 000207          RETURN

```

PRONOP -- Disable PRO interrupts

```

1          .SBTTL PRONOP -- Disable PRO interrupts
2          ;-----
3          ; PRONOP is called during system startup to direct PRO interrupts to
4          ; an RTI instruction so they will not enter RT-11.
5          ;
6 000416 010146 PRONOP: MOV R1, -(SP)
7 000420 012700 000466' MOV #DORTI, R0 ;Get address of RTI instruction
8 000424 010037 000060 MOV R0, @#60 ;Catch keyboard input interrupt
9 000430 010037 000200 MOV R0, @#200 ;380 keyboard input interrupt
10 000434 010037 000064 MOV R0, @#64 ;End-of-transfer video interrupt
11 000440 010037 000204 MOV R0, @#204 ;Keyboard output interrupt
12 000444 010037 000230 MOV R0, @#230 ;380 clock interrupt
13 000450 013701 000064' MOV VIDVEC, R1 ;Point to video interrupt vectors
14 000454 010011 MOV R0, (R1) ;End-of-frame video interrupt
15 000456 010061 000004 MOV R0, 4(R1) ;end-of-transfer video interrupt
16          ;
17          ; Finished
18          ;
19 000462 012601 MOV (SP)+, R1
20 000464 000207 RETURN
21          ;
22          ; RTI instruction used to render interrupts harmless
23          ;
24 000466 000002 DORTI: RTI ;Return from interrupt immediately

```


PROHAN -- Initialize the PI handler

```

1          .SBTTL  PROHAN -- Initialize the PI handler
2          ;-----
3          ; PROHAN is called to initialize the PI handler.
4          ;
5 000470   010146   PROHAN: MOV     R1,-(SP)
6 000472   010246           MOV     R2,-(SP)
7 000474   010346           MOV     R3,-(SP)
8 000476   013746   000000G   MOV     @#KPAR5,-(SP) ;Save current kernel PAR5 mapping
9 000502   013746   000000G   MOV     @#KPAR6,-(SP) ;Save current kernel PAR6 mapping
10         ;
11         ; Set up information about where the PI handler is in memory.
12         ;
13 000506   012703   000000G   MOV     #PISRT,R3      ;Point to shared run-time descriptor for PI
14 000512   016337   000000G   000052'   MOV     RT$BAS(R3),PIBASE;This is base 64-byte block # of run-time
15 000520   013737   000052'   000000G   MOV     PIBASE,@#KPAR5 ;Map to base of PI handler through PAR 5
16         ;
17         ; Transfer information between TSXPRO and the PI handler.
18         ;
19 000526   012701   001000G   MOV     #VPAR5+1000,R1 ;Point to HOKVEC vector in PI handler
20 000532   012702   000000'   MOV     #PROVEC,R2     ;Point to TSXPRO vector
21 000536   011100           5#:     MOV     (R1),R0    ;Get address of a cell in PI handler
22 000540   001404           BEQ     6$             ;Br if PI wants an address
23 000542   062700   000000G   ADD     #VPAR5,R0      ;Bias the address to be in PAR 5 region
24 000546   010012           MOV     R0,(R2)        ;Store address pointer in TSXPRO cell
25 000550   000402           BR      7$             ;
26 000552   011211           6#:     MOV     (R2),(R1) ;Pass an address to PI handler
27 000554   001402           BEQ     8$             ;Br if just hit end of lists
28 000556   022122           7#:     CMP     (R1)+,(R2)+ ;Increment both list pointers
29 000560   000766           BR      5$             ;Continue processing lists
30         ;
31         ; Move the PI initialization overlay into the TSINIT work buffer.
32         ;
33 000562   013701   000000'   8#:     MOV     PIINAD,R1 ;Get address of init overlay
34 000566   162701   000000G   SUB     #VPAR5,R1      ;Subtract bias we added
35 000572   072127   177772   ASH     #-6,R1         ;Convert to 64-byte block #
36 000576   063701   000052'   ADD     PIBASE,R1      ;Get mapping base for init overlay
37 000602   010137   000000G   MOV     R1,@#KPAR6     ;Map to overlay through PAR 6
38 000606   013700   000002'   MOV     PIINWD,R0      ;Get # words in init overlay
39 000612   162700   000000G   SUB     #VPAR5,R0      ;Subtract bias we added
40 000616   012701   000000G   MOV     #VPAR6,R1      ;Get virtual address of init overlay
41 000622   013702   000000G   MOV     PROBUF,R2      ;Get address of TSINIT work buffer
42 000626   012122           4#:     MOV     (R1)+,(R2)+ ;Move init code to work buffer
43 000630   077002           SOB     R0,4$          ;
44         ;
45         ; Now execute the PI initialization code that we have moved to
46         ; the TSINIT work buffer.
47         ; Note: PAR5 is now mapped to the resident portion of the PI handler.
48         ; On entry,
49         ; R3 = Virtual address of base of PI handler.
50         ; R1 = 64-byte block number of base of PI handler.
51         ;
52 000632   013701   000052'   MOV     PIBASE,R1      ;Get 64-byte block # of PI base
53 000636   012703   000000G   MOV     #VPAR5,R3      ;Get virtual address of PI base
54 000642   004777   000000G   CALL    @PROBUF        ;Call PI initialization code
55         ;
56         ; Now get some actual addresses from PI handler
57         ;

```

```

58 000646 017737 177144 000016'      MOV      @%VDCSR,%VDCSR ;Get video CSR address
59                                     ;
60                                     ; Connect to interrupt vectors
61                                     ;
62 000654 012700 000340      MOV      #340,R0        ;Get priority 7 code
63 000660 012701 000060      MOV      #60,R1        ;Get address of start of vector area
64 000664 012721 002114'      MOV      #PIKIIR,(R1)+ ;Set keyboard input interrupt routine
65 000670 010021              MOV      R0,(R1)+      ;Set interrupt service priority to 7
66 000672 012721 001560'      MOV      #PIVTIR,(R1)+ ;Set end of transfer video interrupt
67 000676 010021              MOV      R0,(R1)+      ;Set priority = 7
68 000700 012737 002214' 000204      MOV      #PIKOIR,@#204 ;Set keyboard output interrupt routine
69 000706 010037 000206      MOV      R0,@#206      ;Set priority
70                                     ;
71                                     ; Connect to 380 interrupt vectors
72                                     ;
73 000712 013737 000060 000200      MOV      @#60,@#200     ;380 keyboard input interrupt
74 000720 013737 000062 000202      MOV      @#62,@#202
75 000726 013701 000064'      MOV      VIDVEC,R1     ;Point to video interrupt vector A
76 000732 012721 002052'      MOV      #PIVFIR,(R1)+ ;Set end-of-frame video interrupt
77 000736 010021              MOV      R0,(R1)+      ;Set priority
78 000740 012721 001560'      MOV      #PIVTIR,(R1)+ ;Set end-of-transfer video interrupt
79 000744 010021              MOV      R0,(R1)+      ;Set priority
80 000746 013737 000100 000230      MOV      @#100,@#230   ;380 clock interrupt
81 000754 013737 000102 000232      MOV      @#102,@#232
82                                     ;
83                                     ; Connect to interrupt for quad serial line unit
84                                     ;
85                                     ; IF NE,QPASM ;Assemble if quad line unit support wanted
86 000762 013703 000070'      MOV      QPVEC,R3     ;Get address of interrupt vector
87 000766 001410              BEQ      10$          ;Br if quad serial unit not installed
88 000770 012723 005354'      MOV      #QPCINT,(R3)+ ;Set PC for interrupt
89 000774 010013              MOV      R0,(R3)      ;Set PS for interrupt
90 000776 013703 000066'      MOV      QPCSR,R3     ;Get address of CSR register
91 001002 152763 000100 000004      BISB    #QP$IEN,QPRMSR(R3) ;Enable interrupts
92                                     ; ENDC ; NE,QPASM
93                                     ;
94                                     ; Finished
95                                     ;
96 001010 012637 000000G      10$:    MOV      (SP)+,@#KPAR6 ;Restore kernel mapping
97 001014 012637 000000G      MOV      (SP)+,@#KPAR5
98 001020 012603              MOV      (SP)+,R3
99 001022 012602              MOV      (SP)+,R2
100 001024 012601              MOV      (SP)+,R1
101 001026 000207              RETURN
    
```

```

1          .SBTTL  PROLIN -- See if line is a special PRO terminal
2          ;-----
3          ; PROLIN is called once for each DL11 type line defined in the system.
4          ; It determines if the line is a printer port or communications port
5          ; line and if so performs the initialization for the line.
6          ;
7          ; Inputs:
8          ;   R1 = Line index number.
9          ;
10         ; Outputs:
11         ;   C-flag cleared ==> This is a printer port or comm port line.
12         ;   C-flag set      ==> This is not a printer port or comm port line.
13         ;
14 001030  PROLIN:
15         ;
16         ; See if this is a line connected to the quad serial line unit
17         ;
18         .IF      NE, QPASM          ; Assemble for quad line support
19 001030 005761 000000G              TST      LMXNUM(R1)          ; Is this line on a mux?
20 001034 001403                      BEQ      3$                    ; Br if not
21 001036 004737 005136'              CALL    QPLINE           ; Initialize line on quad unit
22 001042 000427                      BR      9$
23         .ENDC      ; NE, QPASM
24         ;
25         ; See if this is the Professional video console
26         ;
27 001044 026127 000000G 000060 3$:   CMP      INVEC(R1), #60      ; Is this the console line?
28 001052 001003                      BNE      2$                    ; Br if not console line
29 001054 004737 001316'              CALL    PIINIT           ; Initialize PI line
30 001060 000420                      BR      9$
31         ;
32         ; Get address of receiver status register for the line
33         ;
34 001062 016100 000000G              2$:   MOV      RSR(R1), RO        ; Get address of receiver status register
35         ;
36         ; See if this is the printer port
37         ;
38 001066 020027 173400                CMP      RO, #PP$DBR      ; Printer port?
39 001072 001003                      BNE      1$                    ; Br if not
40 001074 004737 002324'              CALL    PPINIT           ; Initialize the printer port
41 001100 000410                      BR      9$
42         ;
43         ; See if this is the communications port
44         ;
45 001102 020027 173300                1$:   CMP      RO, #CP$DBR      ; Communications port?
46 001106 001003                      BNE      8$                    ; Br if not
47 001110 004737 003146'              CALL    CPINIT           ; Initialize the comm port
48 001114 000402                      BR      9$
49         ;
50         ; This line is not the printer port or the comm port
51         ;
52 001116 000261                      8$:   SEC                      ; Signal failure on return
53 001120 000401                      BR      10$
54         ;
55         ; This line was the printer port or the comm port
56         ;
57 001122 000241                      9$:   CLC                      ; Signal success on return

```

```
58 ;  
59 ; Finished  
60 ;  
61 001124 000207 10%: RETURN
```

PROLIN -- See if line is a special PRO terminal

```

1          ;
2          ; Branch vector to entry points of PRO CSR/Vector/Slot routines
3          ;
4 001126 000402 GPVVEC: BR      GPRVEC      ;Get vector address
5 001130 000420 GPVCSR: BR      GPRCSR      ;Get CSR address
6 001132 000436 GPVSLT: BR      GPRSLT     ;Get Slot value
7
8          .SBTTL  GPRVEC -- Get address of vector for PRO device
9          ;-----
10         ; This routine is called to determine the address of the interrupt vector
11         ; for a PRO device based on the device ID.
12         ;
13         ; Inputs:
14         ; Device ID is pushed on stack before calling GPRVEC.
15         ;
16         ; Outputs:
17         ; C-flag cleared ==> Found device in tables; C-flag set ==> No such device.
18         ; Top of stack contains vector for device.
19         ;
20 001134 010046 GPRVEC: MOV      RO,-(SP)
21 001136 016600      MOV      4(SP),RO      ;Get the device ID code
22 001142 004737 000004      CALL     GETSLT      ;Determine which option slot has the dev
23 001146 103407      BCS      9#          ;Br if device not recognized
24 001150 072027 000003      ASH      #3,RO      ;Vectors are 8 bytes apart per slot
25 001154 062700 000300      ADD      #300,RO     ;Vectors for slot 0 start at 300
26 001160 000241      CLC          ;Signal success on return
27 001162 010066 000004      MOV      RO,4(SP)    ;Place vector address on stack
28 001166 012600 9#:      MOV      (SP)+,RO
29 001170 000207      RETURN

```

GPRCSR -- Get address of CSR for PRO device

```

1          .SBTTL  GPRCSR -- Get address of CSR for PRO device
2          ;-----
3          ; This routine is called to determine the address of the CSR
4          ; for a PRO device based on the device ID.
5          ;
6          ; Inputs:
7          ; Device ID is pushed on stack before calling GPRCSR.
8          ;
9          ; Outputs:
10         ; C-flag cleared ==> Found device in tables; C-flag set ==> No such device.
11         ; Top of stack contains address of CSR for device.
12         ;
13 001172 010046 GPRCSR: MOV     RO, -(SP)
14 001174 016600      MOV     4(SP), RO      ;Get the device ID code
15 001200 004737 001254' CALL   GETSLT      ;Determine which option slot has the dev
16 001204 103407      BCS     9$          ;Br if device not recognized
17 001206 072027 000007 ASH    #7., RO     ;CSR address are 200 apart per slot
18 001212 062700 174000 ADD    #174000, RO ;CSR for slot 0 starts at 174000
19 001216 000241      CLC                    ;Signal success on return
20 001220 010066 000004      MOV     RO, 4(SP) ;Place CSR address on stack
21 001224 012600 9$:      MOV     (SP)+, RO
22 001226 000207      RETURN

```

GPRSLT -- Get Slot number for PRO device

```

1          .SBTTL  GPRSLT -- Get Slot number for PRO device
2          ;-----
3          ; This routine is called to determine the slot number
4          ; for a PRO device based on the device ID.
5          ;
6          ; Inputs:
7          ; Device ID is pushed on stack before calling GPRSLT.
8          ;
9          ; Outputs:
10         ; C-flag cleared ==> Found device in tables; C-flag set ==> No such device.
11         ; Top of stack contains slot number for device.
12         ;
13 001230 010046 GPRSLT: MOV     RO, -(SP)
14 001232 016600      MOV     4(SP),RO      ;Get the device ID code
15 001236 004737 000004 CALL    GETSLT      ;Determine which option slot has the dev
16 001242 103402      BCS     9$          ;Br if device not recognized
17 001244 010066 000004      MOV     RO, 4(SP)      ;Put slot number back onto stack
18 001250 012600 9$:      MOV     (SP)+,RO
19 001252 000207      RETURN

```

GETSLT -- Determine which option slot has device controller

```

1          .SBTTL  GETSLT -- Determine which option slot has device controller
2          ;-----
3          ; This routine is called to determine which PRO option slot contains the
4          ; controller for a specified device.
5          ;
6          ; Inputs:
7          ;   RO = Device ID code.
8          ;
9          ; Outputs:
10         ;   C-flag cleared ==> Found the device; C-flag set ==> No such device
11         ;   RO = Slot number.
12         ;
13 001254 010146
14 001256 010001
15 001260 012700 000000G
16 001264 021027 177777
17 001270 001407
18 001272 020120
19 001274 001373
20 001276 162700 000002G
21 001302 006200
22 001304 000241
23 001306 000401
24 001310 000261
25 001312 012601
26 001314 000207

GETSLT: MOV    R1, -(SP)
        MOV    RO, R1          ;Get device ID code
        MOV    #PROSLT, RO    ;Point to table with device ID codes
1$:     CMP    (RO), #-1      ;Reached end of table entries?
        BEQ    2$            ;Br if yes
        CMP    R1, (RO)+     ;Search for device ID in table
        BNE    1$            ;Loop if not found
        SUB    #PROSLT+2, RO  ;Compute table offset of entry
        ASR    RO            ;Convert to word index
        CLC                    ;Signal success on return
        BR     9$
2$:     SEC                    ;Signal failure on return
9$:     MOV    (SP)+, R1
        RETURN

```


*** Console Control Routines ***

```

1          .SBTTL *** Console Control Routines ***
2          .SBTTL PIINIT -- Initialize the console
3          ;-----
4          ; PIINIT is called during system initialization to initialize the
5          ; console.
6          ;
7          ; Inputs:
8          ;   R1 = Line index number.
9          ;
10         PIINIT:
11         ;
12         ; Remember index number of line connected to console
13         ;
14         001316 010137 000044'      MOV     R1,PILINE      ;Save line index # of console line
15         001322 012761 000000G 000000G  MOV     #CDX$PI,LCDTYP(R1);Set type of communications controller
16         ;
17         ; Set addresses of communication port device-dependent routines
18         ;
19         001330 012737 001354' 000000C  MOV     #PISTRT,CDSTRT+CDX$PI ;Set address of start routine
20         ;
21         ; Default terminal type to VT100
22         ;
23         001336 005761 000000G      TST     ITRMTP(R1)      ;Is a terminal type specified?
24         001342 001003                BNE     1$              ;Br if yes
25         001344 012761 000000G 000000G  MOV     #VT100,ITRMTP(R1);Set default terminal type to VT100
26         ;
27         ; Finished
28         ;
29         001352 000207                1$:   RETURN

```

PISTRT -- Start output to video screen

```

1          .SBTTL  PISTRT -- Start output to video screen
2          ;-----
3          ; PISTRT is called after a character is placed in the output ring
4          ; buffer to initiate transmission to the video screen
5          ;
6          ; Inputs:
7          ; R1 = Line index number of line being started.
8          ;
9 001354   PISTRT:
10         ;
11         ; See if we have already started transmitter during this clock period
12         ;
13 001354   005237   000056'   INC      PISCNT      ;Have we already started during clk interval?
14 001360   003005           BGT      9$           ;Br if yes
15         ;
16         ; Do not allow output to the console to consume the entire system.
17         ;
18 001362   004737   002000'   CALL     PIQUIT      ;Is it time to suspend output?
19 001366   103402           BCS      9$           ;Br if yes
20         ;
21         ; Start output
22         ;
23 001370   004737   001420'   CALL     PIGO        ;Start transmitter
24         ;
25         ; Finished
26         ;
27 001374   000207   9$:      RETURN
28
29         .SBTTL  PIDRIV -- Clock driven PI transmitter routine
30         ;-----
31         ; PIDRIV is called periodically from the clock interrupt routine
32         ; to force output to the PI console.
33         ;
34 001376   PIDRIV:
35         ;
36         ; Reset output character suspend count
37         ;
38 001376   012737   000017   000072'   MOV      #MAXPOC,PIMOC ;Reset output character count
39         ;
40         ; Start output to PI
41         ;
42 001404   004737   001420'   CALL     PIGO        ;Start the transmitter
43         ;
44         ; Reset flag saying if transmitter has been started during clock interval
45         ;
46 001410   012737   177777   000056'   MOV      #-1,PISCNT   ;Reset counter
47         ;
48         ; Finished
49         ;
50 001416   000207   RETURN

```

PIGO -- Start PI transmitter

```

1          .SBTTL  PIGO  -- Start PI transmitter
2          ;-----
3          ; PIGO is called to enable a transfer-done interrupt which will start
4          ; transmission to the PI console.
5          ;
6 001420 013746 000000G PIGO:  MOV    @#KPAR5,-(SP)  ;Save current PAR5 mapping
7 001424 013737 000052' 000000G      MOV    PIBASE,@#KPAR5 ;Set up PAR5 to map to PI
8          ;
9          ; See if output to the PI handler has been suspended
10         ;
11 001432 005777 176370          TST    @PIGOFL          ;Has PI output been suspended?
12 001436 001013          BNE    1$              ;Br if not
13         ;
14         ; Output to the PI handler has been suspended.
15         ; Consume all pending output characters and then return.
16         ;
17 001440 010446          MOV    R4,-(SP)
18 001442 013704 000044'        MOV    PILINE,R4          ;Get line index number
19 001446          DISABL          ;;;** Disable interrupts **
20 001454 004774 000000G      4$:   CALL  @LOUTIR(R4)      ;;;Get next char for PI
21 001460 103375          BCC   4$              ;;;Loop till all characters consumed
22 001462 012604          MOV    (SP)+,R4          ;;;
23 001464 000427          BR    9$              ;;;
24         ;
25         ; Output to PI handler is not suspended
26         ;
27 001466          1$:   DISABL          ;;;** Disable interrupts **
28         ;
29         ; See if we have already triggered a PI interrupt
30         ;
31 001474 005737 000054'        TST    PIDIIFL          ;;;Have we already triggered an output int?
32 001500 001021          BNE    9$              ;;;Br if output interrupt active now
33 001502 005237 000054'        INC    PIDIIFL          ;;;Set flag saying output int active
34 001506 010677 176312        MOV    SP,@VDFLAG        ;;;Tell VDCURS that buffer is not empty
35 001512 032777 040000 176276  BIT    #VP$DOI,@$VDCSR  ;;;Is end-of-transfer interrupt enabled?
36 001520 001011          BNE    9$              ;;;Br if yes
37 001522 005777 176274        TST    @PRID0          ;;;Has video said to leave it alone?
38 001526 001003          BNE    2$              ;;;Br if yes
39 001530 052777 040000 176260  BIS    #VP$DOI,@$VDCSR  ;;;Generate end-of-transfer interrupt
40 001536 012777 100000 176254  2$:   MOV    #100000,@REENAB ;;;Tell video to turn on interrupts when ready
41         ;
42         ; Finished
43         ;
44 001544 012637 000000G      9$:   MOV    (SP)+,@#KPAR5  ;;;Restore PAR5 mapping
45 001550          ENABL          ;;;** Enable interrupts **
46 001556 000207          RETURN

```

PIVTIR -- Video end of transfer interrupt

```

1          .SBTTL  PIVTIR -- Video end of transfer interrupt
2          ;-----
3          ; PIVTIR is jumped to from the video end-of-transfer interrupt.
4          ;
5          PIVTIR:
6          ;
7          ; Do .INTEN to drop priority to 4
8          ;
9          001560 004537 000000G      JSR      R5,INTEN      ;Do standard interrupt entry
10         001564 000140                .WORD    140           ;Priority = 4
11         001566 010046                MOV      RO,-(SP)     ;Save R0
12         ;
13         ; Set flag saying output interrupt is in progress
14         ;
15         001570 005237 000054'      INC      PIOIFL      ;Doing output interrupt processing
16         ;
17         ; Disable transfer done interrupt
18         ;
19         001574 013737 000052' 000000G  MOV      PIBASE,@#KPAR5 ;Map kernel PAR 5 to the PI handler
20         001602 012777 100000 176210  MOV      #100000,@REENAB ;Set flag to reenale transfer-done int
21         001610 042777 040000 176200  BIC      #VP$DOI,@$VDCSR ;Disable transfer-done interrupt
22         ;
23         ; Limit the number of consecutive characters sent to the console
24         ; to prevent the PI output processing (which is compute bound) from
25         ; consuming 100% of the machine.
26         ;
27         001616 013704 000044'      MOV      PILINE,R4   ;Get line index number of console line
28         001622 004737 002000'      CALL     PIQUIT      ;Time to suspend output?
29         001626 103431                BCS     2$           ;Br if yes
30         ;
31         ; Get the next character to transmit.
32         ;
33         001630 004774 000000G      CALL     @LOUTIR(R4) ;Get next char for line
34         001634 103423                BCS     1$           ;Br if no character available
35         001636 010005                MOV      RO,R5       ;Get char to transmit to R5
36         001640 012600                MOV      (SP)+,RO    ;Restore RO before we fork
37         ;
38         ; There is another character to transmit. Now fork
39         ;
40         001642 004537 000000G      JSR      R5,FORK     ;Fork to get to priority 0
41         001646 000000G                .WORD    FP$PIO      ;Fork priority
42         001650 010046                MOV      RO,-(SP)   ;Save R0
43         ;
44         ; Map PAR5 to the PI handler
45         ;
46         001652 013737 000052' 000000G  MOV      PIBASE,@#KPAR5 ;Map kernel PAR 5 to the PI handler
47         ;
48         ; Enter PI handler to transmit the character
49         ;
50         001660 010500                MOV      R5,RO       ;Get char to transmit
51         001662 052764 000000G 000000G  BIS      #$XCHAR,LSW3(R4);Set transmitter busy flag
52         001670 042764 000000G 000000G  BIC      #$OITIM,LSW5(R4);Start output interrupt timer
53         001676 004777 176102                CALL     @PIXQCH     ;Call routine to transmit the character
54         001702 000412                BR       9$          ;Finished
55         ;
56         ; No character is available for transmission
57         ;

```

PIVTIR -- Video end of transfer interrupt

```

58 001704 012737 000017 000072' 1#:   MOV    #MAXPOC,PIMDC    ;Reset output char limit count
59 001712 042764 000000G 000000G 2#:   BIC    #$XCHAR,LSW3(R4);Say transmitter is not busy
60 001720 005077 176100                CLR    @VDFLAG         ;Tell VDCURS that buffer is empty
61 001724 005077 176070                CLR    @REENAB        ;Tell video not to turn on interrupts
62                                     ;
63                                     ; Finished
64                                     ;
65 001730 005037 000054' 9#:   CLR    PIDIFL         ;Say output interrupt not in progress
66 001734 012600                MOV    (SP)+,R0
67 001736 000207                RETURN

```

PINDCH -- Get next output character for console

```

1          .SBTTL  PINDCH -- Get next output character for console
2          ;-----
3          ; PINDCH is called from within the VIDE0 handler to try to get another
4          ; character to send to the console terminal.
5          ;
6          ; Outputs:
7          ;   C-flag cleared ==> a character is available.
8          ;   C-flag set      ==> No more characters available.
9          ;   RO = Character to send if C-flag is cleared.
10         ;
11 001740 010446 PINDCH: MOV      R4,-(SP)
12 001742 013704 000044'  MOV      PILINE,R4          ;Get line index number of console
13         ;
14         ; Limit the number of consecutive output characters to prevent the
15         ; PI output processing (which is compute bound) from completely
16         ; dominating the system.
17         ;
18 001746 004737 002000'  CALL     PIQUIT          ;Time to suspend output?
19 001752 103410          BCS     9$              ;Br if yes
20         ;
21         ; Call line-dependent routine to try to get another output character
22         ;
23 001754 1$:  DISABL          ;;; ** Disable interrupts for LOUTIR **
24 001762 004774 000000G  CALL     @LOUTIR(R4)    ;;; Get next character for line
25 001766          ENABL          ;;; ** Enable interrupts **
26         ;
27         ; Finished
28         ;
29 001774 012604 9$:  MOV      (SP)+,R4
30 001776 000207          RETURN

```

PIQUIT -- Check output character limit

```

1          .SBTTL  PIQUIT -- Check output character limit
2          ;-----
3          ; This routine causes output to the console terminal to be suspended
4          ; after a certain number of characters have been transmitted.
5          ; The output is resumed after a timed interval.
6          ; This is done to prevent the console terminal output processing (which
7          ; is compute bound) from consuming 100% of the machine.
8          ;
9          ; Outputs:
10         ; C-flag set      ==> Suspend output.
11         ; C-flag cleared ==> Continue output.
12         ;
13 002000  PIQUIT:
14         ;
15         ; See if there is any other pending system activity
16         ;
17 002000  105737  000000G      TSTB   DOSCHD      ; Scheduler cycle needed?
18 002004  001013      BNE     2$          ; Br if yes
19 002006  005737  000000G      TST   FRKCQE      ; Fork requests pending?
20 002012  001010      BNE     2$          ; Br if yes
21 002014  105737  000000G      TSTB  CORUSR      ; Is there another executing job?
22 002020  001412      BEQ     1$          ; Br if not
23 002022  013700  000044'      MOV   PILINE,RO   ; Get # of job using console terminal
24 002026  005760  000000G      TST   LXCL(RO)    ; Is that job cross-connected to CL line?
25 002032  002405      BLT     1$          ; Br if not
26         ;
27         ; There is some pending system activity.
28         ; See if it is time to suspend PI output.
29         ;
30 002034  005337  000072'      2$:   DEC   PIMDC      ; Time to suspend output?
31 002040  003002      BGT   1$          ; Br if not
32 002042  000261      SEC          ; Signal to suspend
33 002044  000401      BR    9$          ;
34 002046  000241      1$:   CLC          ; Signal to continue output
35         ;
36         ; Finished
37         ;
38 002050  000207      9$:   RETURN

```

```
1                                     .SBTTL PIVFIR -- Video end of frame interrupt
2                                     ;-----
3                                     ; PIVFIR is jumped to from the interrupt vector whenever a video
4                                     ; end-of-frame interrupt occurs.
5                                     ;
6 002052 PIVFIR:
7                                     ;
8                                     ; Do .INTEN to drop priority to 4
9                                     ;
10 002052 004537 000000G JSR R5,INTEN ;Do standard interrupt entry
11 002056 000140 .WORD 140 ;Priority = 4
12 002060 010046 MOV RO,-(SP)
13 002062 010146 MOV R1,-(SP)
14 002064 010246 MOV R2,-(SP)
15 002066 010346 MOV R3,-(SP)
16                                     ;
17                                     ; Enter overlay to do the actual processing
18                                     ;
19 002070 013737 000052' 000000G MOV PIBASE,@#KPAR5 ;Map kernel PAR 5 to the PI handler
20 002076 004777 175704 CALL @PIXEOF ;Do end of frame processing
21                                     ;
22                                     ; Finished
23                                     ;
24 002102 012603 MOV (SP)+,R3
25 002104 012602 MOV (SP)+,R2
26 002106 012601 MOV (SP)+,R1
27 002110 012600 MOV (SP)+,R0
28 002112 000207 RETURN
```


PIKOIR -- Output interrupt for keyboard

```

1                                     .SBTTL  PIKOIR -- Output interrupt for keyboard
2                                     ;-----
3                                     ; PIKOIR is vectored to when we receive an interrupt on completion of
4                                     ; transmitting a character to the keyboard.
5                                     ;
6 002214                               PIKOIR:
7                                     ;
8                                     ; Do .INTEN to drop priority to 4
9                                     ;
10 002214 004537 000000G                JSR     R5,INTEN          ;Do standard interrupt entry
11 002220 000140                        .WORD  140             ;Priority = 4
12 002222 010046                        MOV     R0,-(SP)
13 002224 010146                        MOV     R1,-(SP)
14 002226 010246                        MOV     R2,-(SP)
15 002230 010346                        MOV     R3,-(SP)
16                                     ;
17                                     ; Call overlay routine to do the processing
18                                     ;
19 002232 013737 000052' 000000G        MOV     PIBASE,@#KPAR5 ;Map kernel PAR 5 to the PI handler
20 002240 004777 175546                  CALL    @PIXIOI        ;Call overlay processing routine
21                                     ;
22                                     ; Finished
23                                     ;
24 002244 012603                        MOV     (SP)+,R3
25 002246 012602                        MOV     (SP)+,R2
26 002250 012601                        MOV     (SP)+,R1
27 002252 012600                        MOV     (SP)+,R0
28 002254 000207                        RETURN

```

PIHAN -- Simulated PI handler

```

1          .SBTTL  PIHAN  -- Simulated PI handler
2          ;-----
3          ; The following routine is a simulated handler for the PI device.
4          ; It is used to allow SETUP to perform .SPFUN operations on
5          ; the PI device.
6          ;
7          ; Simulated handler header
8          ;
9          002256 000000  PIHAN: .WORD 0          ;Device vector
10         002260 000014          .WORD PIINT-      ;Offset to interrupt service entry point
11         002262 000000          .WORD 0          ;Interrupt priority
12         002264 000000  PILQE: .WORD 0          ;Last queue element
13         002266 000000  PICQE: .WORD 0          ;Current queue element
14         002270 000402          BR      PIENTR    ;Enter here from system I/O queueing
15         ;
16         ; Simulated interrupt point and abort entry point
17         ;
18         002272 000207          RETURN          ;Abort entry point
19         002274 000002  PIINT: RTI          ;Fake interrupt entry point
20         ;
21         ; Process an I/O queue request directed to the PI device
22         ;
23         002276  PIENTR:
24         ;
25         ; Map PAR 5 to the real PI handler
26         ;
27         002276 013737 000052' 000000G  MOV     PIBASE,@#KPAR5 ;Map PAR 5 to PI handler
28         ;
29         ; Call real PI handler to process the .SPFUN
30         ;
31         002304 013700 002266'  MOV     PICQE,R0      ;Pass address of I/O queue element in R0
32         002310 004777 175500  CALL    @PIXIOQ      ;Enter handler to process the .SPFUN
33         ;
34         ; Finished processing the I/O queue request
35         ;
36         002314 012704 002266'  MOV     #PICQE,R4     ;Set up R4 for IOFIN
37         002320 000137 000000G  JMP     IOFIN        ;I/O operation is completed

```

*** Printer Port Control Routines ***

```

1          .SBTTL *** Printer Port Control Routines ***
2          .SBTTL PPINIT -- Initialize the printer port
3          ;-----
4          ; PPINIT is called during system initialization to initialize the
5          ; printer port.
6          ;
7          ; Inputs:
8          ; R1 = Line index number.
9          ;
10         002324 010246 PPINIT: MOV      R2, -(SP)
11         ;
12         ; Remember the line index number of the line connected to the printer port
13         ;
14         002326 010137 000046'      MOV      R1, PPLINE      ;Remember which line connected to printer port
15         002332 012761 000000G 000000G      MOV      #CDX$PP, LCDTYP(R1) ;Set type of communications controller
16         ;
17         ; Set addresses of printer port routines in vector of device-dependent
18         ; routines.
19         ;
20         002340 012737 002620' 000000C      MOV      #PPSTRT, CDSTRT+CDX$PP ;Set address of start routine
21         002346 012737 002772' 000000C      MOV      #PPGDSS, CDGDSS+CDX$PP ;Address of rtn to get data set status
22         002354 012737 002776' 000000C      MOV      #PPSBRK, CDSBRK+CDX$PP ;Address of rtn to control break
23         002362 012737 003024' 000000C      MOV      #PPSSPD, CDSSPD+CDX$PP ;Address of rtn to set speed
24         ;
25         ; Connect the printer port interrupts to the service routine
26         ;
27         002370 012737 002654' 000220      MOV      #PPRINT, @PP$RCV; Connect receiver interrupt
28         002376 012737 000340 000222      MOV      #340, @PP$RCV+2 ;Set prio = 7 on interrupt entry
29         002404 012737 002516' 000224      MOV      #PPTINT, @PP$TRV; Connect transmitter interrupt
30         002412 012737 000340 000226      MOV      #340, @PP$TRV+2 ;Set prio 7
31         ;
32         ; Set up mode register 1
33         ;
34         002420 005737 173406      3$:    TST      @PP$CMR      ;Access command reg to reset mode reg ptr
35         002424 112737 000102 173404      MOV      #PP$M1F, @PP$MDR; Initialize values in mode register 1
36         ;
37         ; Set speed in mode register 2
38         ;
39         002432 116100 000001G      MOV      LMXPRM+1(R1), R0 ;Get line parameter values
40         002436 001007      BNE      1$      ;Br if parameter values were specified
41         002440 012700 000000G      MOV      #S9600, R0      ;Default to 9600 baud
42         002444 105737 000000G      TST      PPTERM      ;Is a terminal connected to printer port?
43         002450 001002      BNE      1$      ;Br if yes
44         002452 012700 000000G      MOV      #S4800, R0      ;Default to 4800 baud
45         002456 004737 003024'      1$:    CALL      PPSSPD      ;Set the speed in mode register 2
46         ;
47         ; Initialize the command register
48         ;
49         002462 012737 000067 173406      MOV      #PP$CMF!PP$RE, @PP$CMR ; Initialize command register
50         ;
51         ; Enable receiver interrupts
52         ;
53         002470 112737 000035 173202      MOV      #IM$CRM!IM$PPR, @ICOC$SR ; Clear IRR&IMR flags for receiver
54         ;
55         ; Disable transmitter (set mask bit in IMR), but raise a transmitter
56         ; request so we will get an interrupt by clearing the mask flag later.
57         ;

```

PPINIT -- Initialize the printer port

```
58 002476 112737 000076 173202          MOVB  #IM$SM!IM$PPT,@#ICOCSSR ;Set interrupt mask flag in IMR
59 002504 112737 000136 173202          MOVB  #IM$SR!IM$PPT,@#ICOCSSR ;Raise interrupt request flag in IRR
60                                     ;
61                                     ; Finished
62                                     ;
63 002512 012602          9*:      MOV   (SP)+,R2
64 002514 000207          RETURN
```

PPTINT -- Transmitter interrupt

```

1          .SBTTL PPTINT -- Transmitter interrupt
2          ;-----
3          ; Interrupt service routine for printer port transmitter interrupts.
4          ;
5 002516 010046 PPTINT: MOV     RO,-(SP)
6 002520 010446      MOV     R4,-(SP)
7 002522 013746 000000G      MOV     INTPRI,-(SP) ;Save current interrupt priority
8 002526 005037 000000G      CLR     INTPRI      ;Say running priority = 7
9          ;
10         ; Disable interrupts from transmitter
11         ;
12 002532 112737 000076 173202      MOVB   #IM$SM!IM$PPT,@#ICOCSSR ;Set interrupt mask for transmitter
13         ;
14         ; Get number of line connected to printer port
15         ;
16 002540 013704 000046'      MOV     PPLINE,R4      ;Get index # of line connected to printer
17         ;
18         ; Say line is no longer transmitting a character
19         ;
20 002544 042764 000000G 000000G      BIC     #$XCHAR,LSW3(R4);Say line no longer transmitting a character
21         ;
22         ; Get next character to transmit
23         ;
24 002552 004774 000000G      CALL   @LOUTIR(R4)    ;Get next character to transmit
25 002556 103413      BCS    1$             ;Br if no character available
26         ;
27         ; Transmit the character contained in R0
28         ;
29 002560 052764 000000G 000000G      BIS     #$XCHAR,LSW3(R4);Set transmitter busy flag
30 002566 042764 000000G 000000G      BIC     #$OITIM,LSW5(R4);Start timer to catch lost interrupts
31 002574 110037 173400      MOVB   RO,@#PP$DBR    ;Transmit the character
32         ;
33         ; Enable transmitter interrupts
34         ;
35 002600 112737 000056 173202      MOVB   #IM$CM!IM$PPT,@#ICOCSSR ;Clear interrupt mask flag
36         ;
37         ; Finished. Return from interrupt
38         ;
39 002606 012637 000000G 1$:      MOV     (SP)+,INTPRI    ;Restore interrupt priority
40 002612 012604      MOV     (SP)+,R4
41 002614 012600      MOV     (SP)+,R0
42 002616 000002      RTI

```

```
1          .SBTTL  PPSTRT -- Start output to printer port
2
3          ; Subroutine called to attempt to start output for the printer port.
4          ; Enable transmitter interrupt.
5          ; R1 = Physical line number.
6          ;
7 002620  032761  000000G 000000G PPSTRT: BIT    #$XCHAR,LSW3(R1)    ; Is the transmitter busy now?
8 002626  001011                BNE     1$                    ; Br if yes
9 002630  112737  000076  173202    MOVB   #IM$SM!IM$PPT,@#ICOCSR ; Set interrupt mask bit
10 002636  112737  000136  173202    MOVB   #IM$SR!IM$PPT,@#ICOCSR ; Set interrupt request flag
11 002644  112737  000056  173202    MOVB   #IM$CM!IM$PPT,@#ICOCSR ; Clear interrupt mask flag for xmitter
12 002652  000207                1$:   RETURN
```

```

1          .SBTTL  PPRINT -- Receiver interrupt
2          ;-----
3          ; Interrupt service routine for printer port receiver interrupt.
4          ;
5 002654   PPRINT:
6          ;
7          ; Call routine to save R0, R1, R4, and R5.
8          ;
9 002654   004577   000130'   JSR      R5,@TTRSAV      ;Save some registers
10         ;
11         ; R0, R1, R4 and R5 are now available.
12         ; Get number of line connected to printer port.
13         ;
14 002660   013704   000046'   MOV      PPLINE,R4      ;Get line index number
15         ;
16         ; Get the character from the receiver
17         ;
18 002664   113705   173400   MOVVB   @#PP$DBR,R5     ;Get the received character
19 002670   042705   177400   BIC     #^C<377>,R5    ;Kill sign extension
20         ;
21         ; Set flags in R5 to simulate status flags returned by DL11 receiver
22         ;
23 002674   032737   000010   173402   BIT     #PP$PE,@#PP$STR ;Was a parity error detected?
24 002702   001402                   BEQ     1$              ;Br if not
25 002704   052705   000000C   BIS     #RBERR!RCVPAR,R5;Set parity error flag
26 002710   032737   000040   173402   1$:    BIT     #PP$FE,@#PP$STR ;Was a framing error detected?
27 002716   001402                   BEQ     2$              ;Br if not
28 002720   052705   000000C   BIS     #RBERR!FRMERR,R5;Set framing error flag
29 002724   032737   000020   173402   2$:    BIT     #PP$OE,@#PP$STR ;Did an overrun error occur?
30 002732   001402                   BEQ     3$              ;Br if not
31 002734   052705   000000C   BIS     #RBERR!OVRRUN,R5;Set overrun error flag
32         ;
33         ; Clear error flags in receiver
34         ;
35 002740   032705   000000G   3$:    BIT     #RBERR,R5     ;Were any errors detected?
36 002744   001403                   BEQ     4$              ;Br if not
37 002746   052737   000020   173406   BIS     #PP$RE,@#PP$CMR ;Clear error flags
38         ;
39         ; Call TTINPT to process the character we received
40         ;
41 002754   004777   000124'   4$:    CALL   @TTINPT        ;Enter character input routine
42 002760   000403                   BR      9$              ;Return from interrupt
43         ;
44         ; We got an interrupt but no character was available
45         ;
46 002762   112737   000115   173202   6$:    MOVVB   #IM$CR!IM$PPR,@#ICOC$R ;Clear interrupt request flag
47         ;
48         ; Return from interrupt
49         ;
50 002770   000207   9$:    RETURN                ;Return from interrupt

```


PPGDSS -- Get data set status for printer port

```
1          .SBTTL  PPGDSS -- Get data set status for printer port
2          ;-----
3          ; This is the device-dependent routine for the printer port which
4          ; returns generic flags indicating the status of the data set for
5          ; this line.
6          ;
7          ; Inputs:
8          ;   R1 = Physical line index number
9          ;
10         ; Outputs:
11         ;   R0 = Generic status flags
12         ;
13 002772 005000 PPGDSS: CLR      R0          ; Say no ring, carrier, or DTR
14         ;
15         ; Finished
16         ;
17 002774 000207          RETURN
```

PPSBRK -- Control break transmission

```

1          .SBTTL  PPSBRK -- Control break transmission
2          ;-----
3          ; PPSBRK is called to start or stop transmitting a break character
4          ; to the printer port.
5          ;
6          ; Inputs:
7          ;   R1 = Physical line index number.
8          ;   R0 = Break control flag (MS$BRK)
9          ;
10         PPSBRK:
11         ;
12         ; See if we are to start or stop sending a break
13         ;
14         002776 032700 000000G      BIT      #MS$BRK,R0      ; Start or stop sending break?
15         003002 001404              BEQ      1$              ; Br to stop
16         ;
17         ; Start sending a break character
18         ;
19         003004 152737 000010 173406  BISB     #PP$FB,@#PP$CMR ; Start sending a break
20         003012 000403              BR      9$
21         ;
22         ; Stop sending a break character
23         ;
24         003014 142737 000010 173406 1$:     BICB     #PP$FB,@#PP$CMR ; Stop sending a break
25         ;
26         ; Finished
27         ;
28         003022 000207 9$:     RETURN

```

```

1          .SBTTL  PPSSPD -- Set transmission speed for printer port
2          ;-----
3          ; PPSSPD is called to set the transmission speed for the printer port.
4          ;
5          ; Inputs:
6          ;   R0 = Speed code.
7          ;   R1 = Physical line index number.
8          ;
9 003024 010346 PPSSPD: MOV      R3, -(SP)
10         ;
11         ; Save new parameter flags for line
12         ;
13 003026 110061 0000010 MOVB   R0, LMXPRM+1(R1) ; Save new flags for line
14         ;
15         ; Build value to store in mode register 1 (char length and parity)
16         ;
17 003032 012703 000102      MOV    #PP$M1F, R3      ; Get standard mode register 1 flags
18 003036 032700 0000000      BIT    #LP$7BT, R0      ; 7 bit characters wanted?
19 003042 001003              BNE    2$                ; Br if yes
20 003044 052703 000014      BIS    #PP$8BT, R3      ; Select 8 bit characters
21 003050 000402              BR     3$                ;
22 003052 052703 000010 2$:  BIS    #PP$7BT, R3      ; Select 7 bit characters
23 003056 032700 0000000 3$:  BIT    #LP$PAR, R0      ; Parity wanted?
24 003062 001407              BEQ    1$                ; Br if not
25 003064 052703 000020      BIS    #PP$PAR, R3      ; Enable parity
26 003070 032700 0000000      BIT    #LP$ODD, R0     ; Odd parity wanted?
27 003074 001002              BNE    1$                ; Br if yes
28 003076 052703 000040      BIS    #PP$EVN, R3     ; Select even parity
29 003102              1$:  DISABL                ; ** Disable interrupts **
30 003110 105737 173406      TSTB  @PP$CMR          ; Access command reg to reset mode reg ptr
31 003114 110337 173404      MOVB  R3, @PP$MDR      ; Store value into mode register 1
32         ;
33         ; Store baud rate code into mode register 2
34         ;
35 003120 042700 000000C      BIC    #^C<LP$SPD>, R0 ; Clear all but baud rate code
36 003124 052700 000260      BIS    #PP$M2F, R0      ; Set standard flags for mode register 2
37 003130 110037 173404      MOVB  R0, @PP$MDR      ; Store value into mode register 2
38 003134              ENABL                ; ** Enable interrupts **
39         ;
40         ; Finished
41         ;
42 003142 012603              MOV    (SP)+, R3
43 003144 000207              RETURN

```

*** Communications Port Control Routines ***

```

1          .SBTTL *** Communications Port Control Routines ***
2          .SBTTL CPINIT -- Communications port initialization
3          ;-----
4          ; Perform initialization for the communications port.
5          ;
6          ; Inputs:
7          ;   R1 = Index number of time-sharing line connected to comm port
8          ;
9          003146 CPINIT:
10         ;
11         ; Remember which line is connected to comm port
12         ;
13         003146 010137 000050'      MOV     R1,CPLINE      ;Remember line index number
14         003152 012761 000000G 000000G  MOV     #CDX$PC,LCDTYP(R1) ;Set type of communications controller
15         ;
16         ; Set addresses of communication port device-dependent routines
17         ;
18         003160 012737 003772' 000000C  MOV     #CPSTRT,CDSTRT+CDX$PC ;Set address of start routine
19         003166 012737 004060' 000000C  MOV     #CPCLOK,CDCLOK+CDX$PC ;Set address of timer-driven routine
20         003174 012737 004122' 000000C  MOV     #CPXOFF,CDSXOF+CDX$PC ;Routine to send XOFF
21         003202 012737 004210' 000000C  MOV     #CPXON,CDSXON+CDX$PC  ;Routine to send XON
22         003210 012737 004276' 000000C  MOV     #CPGDSS,CDGDSS+CDX$PC ;Routine to get data set status flags
23         003216 012737 004346' 000000C  MOV     #CPSDSS,CDSDSS+CDX$PC ;Routine to do data set control
24         003224 012737 004374' 000000C  MOV     #CPSBRK,CDSBRK+CDX$PC ;Routine to control break transmission
25         003232 012737 004462' 000000C  MOV     #CPSSPD,CDSSPD+CDX$PC ;Routine to set transmission speed
26         ;
27         ; Connect to interrupt vectors
28         ;
29         003240 012737 003504' 000210  MOV     #CPCINT,@#CP$RTV;Receiver/transmitter interrupt
30         003246 012737 000340 000212  MOV     #340,@#CP$RTV+2 ;Set prio = 7
31         003254 012737 003504' 000214  MOV     #CPCINT,@#CP$MCV;Modem change interrupt
32         003262 012737 000340 000216  MOV     #340,@#CP$MCV+2 ;Set prio = 7
33         ;
34         ; Initialize values in CSR A
35         ;
36         003270 012700 173302      MOV     #CP$CAR,R0      ;Get pointer to CSR A
37         003274 112710 000030      MOV     #CP$CR,(R0)    ;Reset the channel
38         003300 000240              NOP                    ;Delay time for channel clear operation
39         003302 000240              NOP
40         003304 000240              NOP
41         003306 000240              NOP
42         003310 112710 000300      MOV     #300,(R0)      ;Reset transmitter underrun condition
43         003314 112710 000004      MOV     #CP$WR4,(R0)   ;Select write register 4
44         003320 112710 000104      MOV     #CP$AW4,(R0)   ;16x clock rate, 1 stop bit, asynch
45         003324 112710 000003      MOV     #CP$WR3,(R0)   ;Select write register 3
46         003330 112710 000001      MOV     #CP$AW3,(R0)   ;Enable receiver and set 8-bit char len
47         003334 112710 000005      MOV     #CP$WR5,(R0)   ;Select write register 5
48         003340 112710 000010      MOV     #CP$AW5,(R0)   ;8-bit char, enable transmitter
49         003344 112710 000002      MOV     #CP$WR2,(R0)   ;Select write register 2
50         003350 112710 000000      MOV     #0,(R0)        ;Store all zero in WR2
51         003354 112710 000020      MOV     #CP$RES,(R0)   ;Reset external interrupts
52         003360 116100 000001G      MOV     LMXPRM+1(R1),R0 ;Get flags for line
53         003364 001002              BNE     1$             ;Br if speed specified
54         003366 012700 000000G      MOV     #S9600,R0      ;Default to 9600 baud
55         003372 004737 004462'      1$:    CALL    CPSSPD      ;Set speed, parity, character length
56         ;
57         ; Initialize values in CSR B

```

```
58 ;
59 003376 012700 173306      MOV      #CP$CBR,RO      ;Get pointer to CSR B
60 003402 112710 000030      MOV      #CP$CR,(RO)    ;Reset the channel
61 003406 112710 000002      MOV      #CP$WR2,(RO)  ;Select write register 2
62 003412 112710 000000      MOV      #0,(RO)       ;Set 0 as vector base
63 003416 112710 000001      MOV      #CP$WR1,(RO)  ;Select write register 1
64 003422 112710 000004      MOV      #4,(RO)       ;Store value specified in ref manual
65 ;
66 ; Enable interrupts
67 ;
68 003426 112737 000033 173202 MOV      #IM$CRM!IM$CPD,@#ICOC$CSR ;Clear interrupt mask
69 003434 112737 000000 173310 MOV      #0,@#CP$MOR     ;Initialize modem control register 0
70 003442 112737 000001 173302 MOV      #CP$WR1,@#CP$CAR ;Select CSR A write register 1
71 003450 112737 000032 173302 MOV      #CP$RIE!CP$TIE,@#CP$CAR ;Enable receiver and transmitter ints
72 003456 152737 000010 173310 BISB     #CP$RTS,@#CP$MOR ;Set RTS
73 003464 032761 000000G 000000G BIT      #$PHONE,ILSW2(R1); Is this a dial-up line?
74 003472 001003          BNE      2$           ;Br if yes -- don't set DTR yet, wait for ring
75 003474 152737 000020 173310 BISB     #CP$DTR,@#CP$MOR ;Set DTR
76 ;
77 ; Finished
78 ;
79 003502 000207          2$:      RETURN
```

```

1                                     .SBTTL  CPCINT -- Receiver/Transmitter interrupt routine
2                                     ;-----
3                                     ; CPCINT is the interrupt entry point for both receiver and transmitter
4                                     ; interrupts.
5                                     ;
6 003504 010046 CPCINT: MOV      RO, -(SP)      ;Get a work register
7 003506 112737 000002 173306 MOVB   #CP$RR2, @CP$CBR; Select CSR B read register 2
8 003514 113700 173306 MOVB   @CP$CBR, RO    ;Get the interrupt flags from RR2
9 003520 006200 ASR     RO          ;Get value as word table index
10 003522 042700 177761 BIC    ^C<16>, RO    ;Clear all but interrupt code flags
11 003526 000170 003532' JMP     @CPIVEC(RO)  ;Jump to appropriate interrupt service rtn
12                                     ;
13                                     ; Jump vector based on interrupt type
14                                     ;
15 003532 003572' CPIVEC: .WORD   CPIERR      ;0 - Invalid
16 003534 003572'      .WORD   CPIERR      ;1 - Invalid
17 003536 003572'      .WORD   CPIERR      ;2 - Invalid
18 003540 003572'      .WORD   CPIERR      ;3 - Invalid
19 003542 003672'      .WORD   CPITR      ;4 - Transmitter buffer empty
20 003544 003564'      .WORD   CPIESC     ;5 - External status change
21 003546 003604'      .WORD   CPIREC     ;6 - Received character
22 003550 003552'      .WORD   CPISRC     ;7 - Special receiver condition
23                                     ;
24                                     ; Special receiver condition interrupt
25                                     ;
26 003552 112737 000060 173302 CPISRC: MOVB   #CP$ER, @CP$CAR ;Reset error status flags
27 003560 000137 003604'      JMP     CPIREC      ;Process any character we got with errors
28                                     ;
29                                     ; External status change interrupt processing
30                                     ;
31 003564 112737 000020 173302 CPIESC: MOVB   #CP$RES, @CP$CAR; Reset external status
32                                     ;
33                                     ; Invalid interrupt code.
34                                     ; Reset interrupt status and return.
35                                     ;
36 003572 112737 000070 173302 CPIERR: MOVB   #CP$EI, @CP$CAR ;Declare end of interrupt
37 003600 012600      MOV     (SP)+, RO
38 003602 000002      RTI          ;Return from interrupt

```

```

1          .SBTTL  CPIREC -- Received character from comm port
2          ;-----
3          ; CPIREC is the interrupt service routine called when we get an
4          ; interrupt from the comm port saying that it has received a character.
5          ;
6          ; On entry, R0 is on the stack.
7          ;
8 003604 012600 CPIREC: MOV      (SP)+,R0      ;Restore R0
9          ;
10         ; Call routine to save R0, R1, R4, and R5
11         ;
12 003606 004577 000130' JSR      R5,@TTRSAV      ;Save registers
13         ;
14         ; R0, R1, R4 and R5 are available.
15         ; See if a framing error was detected
16         ;
17 003612 005005 CLR      R5          ;Build character and flags in R5
18 003614 112737 000000 173302 MOVVB   #CP$RRO,@#CP$CAR;Select read register 0
19 003622 113704 173302 MOVVB   @#CP$CAR,R4      ;Get contents of read register 0
20 003626 132704 000200 BITB    #CP$BR,R4      ;Was a break detected?
21 003632 001402 BEQ     3$          ;Br if not
22 003634 052705 000000G BIS     #FRMERR,R5     ;Set framing error flag
23 003640 112737 000020 173302 3$: MOVVB  #CP$RES,@#CP$CAR;Reset register 0 flags
24         ;
25         ; Get the character from the receiver
26         ;
27 003646 153705 173300 BISB   @#CP$DBR,R5     ;Get the received character
28         ;
29         ; Reenable interrupts from receiver
30         ;
31 003652 112737 000070 173302 MOVVB  #CP$EI,@#CP$CAR ;Declare end of interrupt
32         ;
33         ; Get number of line connected to communications port
34         ;
35 003660 013704 000050' MOV     CPLINE,R4      ;Get line index number
36         ;
37         ; Call TTINPT to process the character
38         ;
39 003664 004777 000124' CALL   @TTINPT        ;Enter routine to process the character
40         ;
41         ; Return from interrupt
42         ;
43 003670 000207 RETURN          ;Return from interrupt through TTRSAV

```

CPITR -- Transmitter interrupt

```

1          .SBTTL  CPITR  -- Transmitter interrupt
2          ;-----
3          ; CPITR is the interrupt service routine for the communications port
4          ; transmitter.
5          ;
6          ; On entry, R0 is on the stack.
7          ;
8 003672 010416 CPITR:  MOV    R4,-(SP)      ;Stack R4 also
9 003674 013746 000000G  MOV    INTPRI,-(SP)  ;Save current interrupt priority
10 003700 005037 000000G  CLR    INTPRI       ;Say running interrupt priority is 7
11          ;
12          ; Say that line is no longer transmitting a character
13          ;
14 003704 013704 000050'  MOV    CPLINE,R4    ;Get # of line connected to comm port
15 003710 042764 000000G 000000G  BIC    #$XCHAR,LSW3(R4);Clear transmitting-character flag for line
16 003716 112737 000050 173302  MOVB  #CP$RTI,@#CP$CAR;Reset transmitter interrupt flag
17 003724 112737 000070 173302  MOVB  #CP$EI,@#CP$CAR ;Declare end of interrupt
18          ;
19          ; Get next character to transmit
20          ;
21 003732 004774 000000G  CALL  @LOUTIR(R4)   ;Get next char to transmit
22 003736 103410  BCS   9$           ;Br if no more chars to send
23          ;
24          ; Transmit the character
25          ;
26 003740 052764 000000G 000000G  BIS    #$XCHAR,LSW3(R4);Say a character is being transmitted
27 003746 042764 000000G 000000G  BIC    #$OITIM,LSW5(R4);Start timer to catch lost interrupts
28 003754 110037 173300  MOVB  RO,@#CP$DBR    ;Transmit the character
29          ;
30          ; Finished
31          ;
32 003760 012637 000000G  9$:   MOV    (SP)+,INTPRI ;Restore interrupt priority level
33 003764 012604  MOV    (SP)+,R4
34 003766 012600  MOV    (SP)+,R0
35 003770 000002  RTI          ;Return from interrupt

```


CPSTRT -- Start output to communications port

```

1          .SBTTL  CPSTRT -- Start output to communications port
2          ;-----
3          ; CPSTRT is called to initiate output to the communications port.
4          ;
5          ; R1 = Line index number of line being started.
6          ;
7 003772   010046   CPSTRT: MOV     RO,-(SP)
8 003774   010446           MOV     R4,-(SP)
9          ;
10         ; Disable communications port interrupts
11         ;
12 003776           DISABL           ;;;Disable interrupts
13         ;
14         ; See if the communications port transmitter is already busy
15         ;
16 004004   032761   000000G 000000G   BIT     $$XCHAR,LSW3(R1)           ;;;Is the transmitter busy now?
17 004012   001014           BNE     1$           ;;;Br if yes
18         ;
19         ; Transmitter is idle.
20         ; Get next character to transmit
21         ;
22 004014   010104           MOV     R1,R4           ;;;Get line # to R4 for NEDCHR
23 004016   004774   000000G           CALL    @LOUTIR(R4)           ;;;Get a character to transmit
24 004022   103410           BCS    1$           ;;;Br if nothing to transmit
25         ;
26         ; Start transmission
27         ;
28 004024   052761   000000G 000000G   BIS     $$XCHAR,LSW3(R1)           ;;;Say a character being transmitted
29 004032   042761   000000G 000000G   BIC     $$OITIM,LSW5(R1)           ;;;Start timer to catch lost interrupt
30 004040   110037   173300           MOVB   RO,@#CP#DBR           ;;;Transmit the character
31         ;
32         ; Enable the transmitter interrupt
33         ;
34 004044           1$: ENABL           ;Enable interrupts
35         ;
36         ; Finished
37         ;
38 004052   012604           MOV     (SP)+,R4
39 004054   012600           MOV     (SP)+,RO
40 004056   000207           RETURN

```

CPCLOK -- Timer driven routine for communications port

```

1          .SBTTL  CPCLOK -- Timer driven routine for communications port
2          ;-----
3          ; CPCLOK is a timer driven routine called periodically to check on
4          ; the status of the communications port.
5          ;
6          ; Inputs:
7          ; R1 = Line index number.
8          ;
9          004060 CPCLOK:
10         ;
11         ; Check for lost output interrupts
12         ;
13 004060 032761 000000G 000000G          BIT    #$DITIM,LSW5(R1);Have we started timer interval?
14 004066 001411          BEQ    1$          ;Br if not
15 004070 032761 000000G 000000G          BIT    #$XCHAR,LSW3(R1);Are we still waiting for an interrupt?
16 004076 001410          BEQ    9$          ;Br if not
17 004100 042761 000000G 000000G          BIC    #$XCHAR,LSW3(R1);Say wait is over
18 004106 004737 003772'          CALL   CPSTRT          ;Try to restart transmitter
19 004112 052761 000000G 000000G 1$:    BIS    #$DITIM,LSW5(R1);Start timed interval
20         ;
21         ; Finished
22         ;
23 004120 000207          9$:    RETURN

```

CPXOFF -- Transmit XOFF to communications port

```

1          .SBTTL  CPXOFF -- Transmit XOFF to communications port
2          ;-----
3          ; CPXOFF is called to stuff an XOFF character into the output stream
4          ; for the communications port.
5          ;
6          ; Inputs:
7          ; R1 = Line index number.
8          ;
9 004122   CPXOFF: DISABL          ;;; ** Disable interrupts **
10         ;
11         ; Set flag that says XOFF has been sent
12         ;
13 004130   052761  000000G 000000G      BIS    ##HISTP,LSW10(R1);; Remember that XOFF has been sent
14         ;
15         ; See if the transmitter is busy now
16         ;
17 004136   032761  000000G 000000G      BIT    ##XCHAR,LSW3(R1);; Is the transmitter busy now?
18 004144   001404          BEQ    1$          ;;; Br if not busy now
19         ;
20         ; The transmitter is busy now.
21         ; Set flag which will cause output character generator to send XOFF
22         ;
23 004146   052761  000000G 000000G      BIS    ##SXOFF,LSW10(R1);; Set flag to cause XOFF to be sent
24 004154   000411          BR     9$          ;;;
25         ;
26         ; Transmitter is not busy.
27         ; Transmit an XOFF character.
28         ;
29 004156   052761  000000G 000000G 1$:   BIS    ##XCHAR,LSW3(R1);; Say transmitter busy
30 004164   042761  000000G 000000G      BIC    ##OITIM,LSW5(R1);; Start output interrupt timer
31 004172   112737  000023  173300      MOVB   #23,@#CP#DBR    ;;; Transmit XOFF
32         ;
33         ; Finished
34         ;
35 004200   9$:      ENABL          ;;; ** Enable interrupts **
36 004206   000207      RETURN

```

CPXON -- Transmit XON to communications port

```

1          .SBTTL  CPXON  -- Transmit XON to communications port
2          ;-----
3          ; CPXON is called to stuff an XON character into the output stream
4          ; for the communications port.
5          ;
6          ; Inputs:
7          ; R1 = Line index number.
8          ;
9 004210   CPXON:  DISABL          ; ** Disable interrupts **
10         ;
11         ; Clear flag that says XOFF has been sent
12         ;
13 004216   042761   000000G 000000G      BIC    #$HISTP,LSW10(R1);; Clear flag that says XOFF sent
14         ;
15         ; See if the transmitter is busy now
16         ;
17 004224   032761   000000G 000000G      BIT    #$XCHAR,LSW3(R1);; Is the transmitter busy now?
18 004232   001404          BEQ    1$          ;; Br if not busy now
19         ;
20         ; The transmitter is busy now.
21         ; Set flag which will cause output character generator to send XON
22         ;
23 004234   052761   000000G 000000G      BIS    #$SXON,LSW10(R1);; Set flag to cause XON to be sent
24 004242   000411          BR     9$          ;;
25         ;
26         ; Transmitter is not busy.
27         ; Transmit an XON character.
28         ;
29 004244   052761   000000G 000000G 1$:   BIS    #$XCHAR,LSW3(R1);; Say transmitter busy
30 004252   042761   000000G 000000G      BIC    #$OITIM,LSW5(R1);; Start output interrupt timer
31 004260   112737   000021   173300      MOVB   #21,@#CP$DBR    ;; Transmit XON
32         ;
33         ; Finished
34         ;
35 004266          9$:   ENABL          ; ** Enable interrupts **
36 004274   000207          RETURN
37
38

```

```
1          .SBTTL  CPGDSS -- Get communications port data set status
2          ;-----
3          ; CPGDSS is called to get the data set (modem) status for the
4          ; communications port.
5          ;
6          ; Inputs:
7          ;   R1 = Physical line index number
8          ;
9          ; Outputs:
10         ;   R0 = Generic data set status flags (MS$xxx)
11         ;
12 004276 005000 CPGDSS: CLR      R0          ;Develop result in R0
13         ;
14         ; See if the phone is ringing
15         ;
16 004300 132737 000100 173312      BITB   #CP$RI,@#CP$M1R ;Is the phone ringing?
17 004306 001402      BEQ     1$          ;Br if not
18 004310 052700 000000G      BIS     #MS$RNG,R0      ;Set ringing flag
19         ;
20         ; See if carrier is detected
21         ;
22 004314 132737 000020 173312 1$:   BITB   #CP$CD,@#CP$M1R ;Do we have carrier detect?
23 004322 001402      BEQ     2$          ;Br if not
24 004324 052700 000000G      BIS     #MS$CAR,R0      ;Set carrier-detect flag
25         ;
26         ; See if Data Terminal Ready is asserted
27         ;
28 004330 132737 000020 173310 2$:   BITB   #CP$DTR,@#CP$MOR;Are we asserting DTR?
29 004336 001402      BEQ     3$          ;Br if not
30 004340 052700 000000G      BIS     #MS$DTR,R0      ;Remember DTR is asserted
31         ;
32         ; Finished
33         ;
34 004344 000207 3$:   RETURN
```

CPSDSS -- Set data set status for communications port

```

1          .SBTTL  CPSDSS -- Set data set status for communications port
2          ;-----
3          ; CPSDSS is called to control the data set (modem) status for the
4          ; communications port.
5          ;
6          ; Inputs:
7          ;   R1 = Physical line index number
8          ;   R0 = Data set control flags (MS$xxx)
9          ;
10         CPSDSS:
11         ;
12         ; See if we should raise or drop Data Terminal Ready
13         ;
14         004346 032700 000000G      BIT      #MS$DTR,R0      ;Raise or drop DTR?
15         004352 001404              BEQ      1$              ;Br to drop DTR
16         ;
17         ; Raise DTR
18         ;
19         004354 152737 000020 173310  BISB     #CP$DTR,@#CP$MOR;Raise DTR
20         004362 000403              BR      9$
21         ;
22         ; Drop DTR
23         ;
24         004364 142737 000020 173310 1$:     BICB     #CP$DTR,@#CP$MOR;Drop DTR
25         ;
26         ; Finished
27         ;
28         004372 000207              9$:     RETURN

```

```

1          .SBTTL CPSBRK -- Control break transmission on communications port
2          ;-----
3          ; CPSBRK is called to start or stop transmitting a break character to
4          ; the communications port.
5          ;
6          ; Inputs:
7          ;   RO = Break control flag (MS$BRK)
8          ;   R1 = Physical line index number.
9          ;
10         004374 010246 CPSBRK: MOV      R2,-(SP)
11         ;
12         ; Set standard flags for write-register 5
13         ;
14         004376 012702 000050          MOV      #CP$AW5!CP$7BT,R2 ;Standard flags and 7-bit char length
15         004402 132761 000000G 000001G BITB    #LP$7BT,LMXPRM+1(R1);7-bit characters wanted?
16         004410 001002          BNE     2$ ;Br if yes
17         004412 052702 000140          BIS     #CP$8BT,R2 ;Select 8-bit characters
18         ;
19         ; See if we want to start or stop sending a break
20         ;
21         004416 032700 000000G 2$:    BIT     #MS$BRK,RO ;Start or stop sending break?
22         004422 001402          BEQ     1$ ;Br if stop
23         004424 052702 000020          BIS     #CP$SB,R2 ;Set send-break flag
24         ;
25         ; Store parameters into control register
26         ;
27         004430 1$:    DISABL          ;;;** Disable interrupts **
28         004436 112737 000005 173302 MOVB   #CP$WR5,@#CP$CAR;;Select write register 5
29         004444 110237 173302 MOVB   R2,@#CP$CAR ;;;Start or stop sending break
30         004450          ENABL          ;;; Enable interrupts **
31         ;
32         ; Finished
33         ;
34         004456 012602 9$:    MOV     (SP)+,R2
35         004460 000207          RETURN
  
```

```

1
2
3
4
5
6
7
8
9
10 004462 010346
11 004464 010446
12 004466 010546
13
14
15
16 004470 110061 0000010
17
18
19
20 004474 010003
21 004476 042703 000000C
22 004502 010346
23 004504 072327 000004
24 004510 052603
25 004512 110337 173314
26
27
28
29 004516 012704 173302
30 004522 012703 000104
31 004526 032700 000000G
32 004532 001407
33 004534 052703 000001
34 004540 032700 000000G
35 004544 001002
36 004546 052703 000002
37 004552 112714 000004
38 004556 110314
39
40
41
42 004560 012703 000001
43 004564 012705 000010
44 004570 032700 000000G
45 004574 001005
46 004576 052705 000140
47 004602 052703 000300
48 004606 000404
49 004610 052705 000040
50 004614 052703 000100
51 004620
52 004626 112714 000003
53 004632 110314
54 004634 112714 000005
55 004640 110514
56 004642
57

          .SBTTL  CPSSPD -- Set speed for communications port
          -----
          ; CPSSPD is called to set the transmit/receive speed for
          ; the communications port.
          ;
          ; Inputs:
          ;   R0 = Speed code.
          ;   R1 = Physical line index number.
          ;
          CPSSPD:  MOV     R3, -(SP)
                  MOV     R4, -(SP)
                  MOV     R5, -(SP)
          ;
          ; Set baud rate in line parameter word for this line
          ;
                  MOVVB   R0, LMXPRM+1(R1) ; Save new flags for line
          ;
          ; Store speed value into hardware control register
          ;
                  MOV     R0, R3           ; Get all flags
                  BIC     #^C<LP$SPD>, R3 ; Clear all but speed code
                  MOV     R3, -(SP)       ; Save speed code
                  ASH     #4, R3          ; Shift speed value left 4 bits
                  BIS     (SP)+, R3       ; Combine with unshifted value
                  MOVVB   R3, @#CP$BRR    ; Set baud rate in hardware register
          ;
          ; Set parity control
          ;
                  MOV     #CP$CAR, R4     ; Get pointer to CSR A
                  MOV     #CP$AW4, R3     ; Get standard bits for WR4
                  BIT     #LP$PAR, R0     ; Is parity wanted?
                  BEQ     1$              ; Br if not
                  BIS     #CP$PAR, R3     ; Set parity-enable flag
                  BIT     #LP$ODD, R0     ; Is odd parity wanted?
                  BNE     1$              ; Br if yes
                  BIS     #CP$EVN, R3     ; Select even parity
1$:          MOVVB   #CP$WR4, (R4)        ; Select write register 4
                  MOVVB   R3, (R4)       ; Set parity control flags
          ;
          ; Set character length
          ;
                  MOV     #CP$AW3, R3     ; Get standard flags for WR3
                  MOV     #CP$AW5, R5     ; Get standard flags for WR5
                  BIT     #LP$7BT, R0     ; 7 bit characters wanted?
                  BNE     2$              ; Br if yes
                  BIS     #CP$8BT, R5     ; Select 8 bit characters
                  BIS     #CP$8BR, R3
                  BR     3$
2$:          BIS     #CP$7BT, R5         ; Select 7 bit characters
                  BIS     #CP$7BR, R3
3$:          DISABL ; ** Disable interrupts **
                  MOVVB   #CP$WR3, (R4)  ; Select write register 3
                  MOVVB   R3, (R4)       ; Set length for received characters
                  MOVVB   #CP$WR5, (R4)  ; Select write register 5
                  MOVVB   R5, (R4)       ; Set length for transmitted characters
                  ENABL  ; ** Enable interrupts **

```



```
58 ; Finished  
59 ;  
60 004650 012605 MOV (SP)+,R5  
61 004652 012604 MOV (SP)+,R4  
62 004654 012603 MOV (SP)+,R3  
63 004656 000207 RETURN
```

```

1          . IF      NE, QPASM          ; Assemble if quad line unit code wanted
2          . SBTTL   *** Quad Serial Line Unit Routines ***
3          . SBTTL   QPINIT -- Initialize quad serial line unit
4          ; -----
5          ; QPINIT is called to initialize the quad serial line unit
6          ;
7 004660   010546   QPINIT: MOV      R5, -(SP)
8          ;
9          ; Determine if a quad line unit is installed
10         ;
11 004662   012746   000064           MOV      #QP$ID, -(SP)      ; Stack device ID for quad line unit
12 004666   004737   001172'         CALL     GPRCSR          ; Get CSR for quad line unit
13 004672   012605           MOV      (SP)+, R5        ; Get returned CSR address
14 004674   103014           BCC     2$              ; Br if it is installed
15         ;
16         ; There is no quad line unit installed.
17         ; Mark all lines associated with quad line unit as dead.
18         ;
19 004676   012705   000000G         MOV      #LSTHL, R5      ; Get index to last line
20 004702   005765   000000G         3$:     TST     LMXNUM(R5) ; Is this a quad unit line?
21 004706   001403           BEQ     4$              ; Br if not
22 004710   052765   000000G 000000G  BIS     #$DEAD, LSW3(R5) ; Mark line as dead
23 004716   162705   000002         4$:     SUB     #2, R5      ; Get next line index
24 004722   003367           BGT     3$              ; Br if more lines to do
25 004724   000502           BR      9$              ; Finished
26         ;
27         ; There is a quad line unit installed
28         ;
29 004726   010537   000066'         2$:     MOV      R5, QPCSR      ; Save CSR address
30 004732   132765   000004 000004     BITB   #QP$22C, QPRMSR(R5) ; Do we have modem control on lines 0 and 2?
31 004740   001402           BEQ     1$              ; Br if not
32 004742   105237   000110'         INCB   QPMODM          ; Remember we have modem control on two lines
33 004746   142765   000100 000004     1$:     BICB   #QP$IEN, QPRMSR(R5) ; Clear interrupt-enable bit
34 004754   012746   000064           MOV      #QP$ID, -(SP)      ; Stack device ID
35 004760   004737   001134'         CALL     QPRVEC          ; Get vector address
36 004764   012637   000070'         MOV      (SP)+, QPVEC       ; Save vector address
37 004770   012700   000064           MOV      #QP$ID, R0        ; Get device ID
38 004774   004737   001254'         CALL     GETSLT          ; Get slot # where device is installed
39 005000   110037   000111'         MOV     RO, QPSLOT        ; Save the slot number
40         ;
41         ; Set addresses of quad line unit device-dependent routines
42         ;
43 005004   012737   005310' 000000C     MOV      #QP$STRT, CDSTRT+CDX$QP ; Start-output routine
44 005012   012737   006054' 000000C     MOV      #QP$DSS, CDGDSS+CDX$QP ; Get data set status
45 005020   012737   006160' 000000C     MOV      #QP$SDSS, CDSDDSS+CDX$QP ; Set data set status
46 005026   012737   006016' 000000C     MOV      #QP$BRK, CDSBRK+CDX$QP ; Control break transmission
47 005034   012737   005632' 000000C     MOV      #QP$SSPD, CDSSPD+CDX$QP ; Set line speed
48         ;
49         ; Initialize Output Port Configuration Register
50         ;
51 005042   105065   000132           CLRB   QPROPC(R5)        ; All bits are off in OPCR
52 005046   105065   000172           CLRB   QPROPC+QPRUOF(R5) ; DUART 1
53         ;
54         ; Initialize Auxiliary Control Register
55         ;
56 005052   112765   000360 000110     MOV     #QP$AWA, QPRACR(R5) ; Initialize ACR
57 005060   112765   000360 000150     MOV     #QP$AWA, QPRACR+QPRUOF(R5) ; DUART 1

```

```
58 ;  
59 ; Initialize Interrupt Mask Register  
60 ;  
61 005066 112765 000063 000112      MOVB    #QP$AWI,QPRIMR(R5) ;Intialize IMR  
62 005074 112765 000063 000152      MOVB    #QP$AWI,QPRIMR+QPRUOF(R5) ;DUART 1  
63 ;  
64 ; Initialize output port  
65 ;  
66 005102 112765 000377 000136      MOVB    #377,QPRROP(R5) ;Reset all output port bits  
67 005110 112765 000377 000176      MOVB    #377,QPRROP+QPRUOF(R5) ;DUART 1  
68 ;  
69 ; Initialize interrupt controller  
70 ;  
71 005116 012700 000030              MOV     #IM$CRM,RO        ;Get command to clear IRR and IMR int flags  
72 005122 153700 000111'            BISB   QPSLOT,RO         ;Or in slot number where QP controller is  
73 005126 110037 173206            MOVB   RO,@#IC1CSR      ;Clear IRR and IMR flags for quad port  
74 ;  
75 ; Finished  
76 ;  
77 005132 012605                    9#:    MOV     (SP)+,R5  
78 005134 000207                    RETURN
```

QPLINE -- Initialize a line connected to quad line unit

```

1          .SBTTL  QPLINE -- Initialize a line connected to quad line unit
2          ;-----
3          ; QPLINE is called to initialize a specific line that is connected to
4          ; the quad serial line unit.
5          ;
6          ; Inputs:
7          ;   R1 = Line index number.
8          ;
9 005136 010546 QPLINE: MOV      R5, -(SP)
10         ;
11         ; Say this line is controlled by quad serial line unit
12         ;
13 005140 012761 000000G 000000G      MOV      #CDX$QP, LCDTYP(R1)
14         ;
15         ; See if quad line unit is installed
16         ;
17 005146 005737 000066'      TST      QPCSR          ; Is quad line unit installed?
18 005152 001454      BEQ      9$          ; Br if not
19         ;
20         ; Remember the TSX-Plus line index number associated with this unit line
21         ;
22 005154 016105 000000G      MOV      LMXLN(R1), R5      ; Get # of line within quad unit
23 005160 110165 000104'      MOVB    R1, QPLX(R5)      ; Store TSX-Plus line index #
24 005164 016100 000000G      MOV      LMXNUM(R1), R0      ; Get mux index number
25 005170 013760 000066' 000000G      MOV      QPCSR, MXCSR(R0) ; Remember CSR address for unit
26 005176 013760 000070' 000000G      MOV      QPVEC, MXVEC(R0) ; Remember vector address of unit
27         ;
28         ; See if this line should have modem control
29         ;
30 005204 105737 000110'      TSTB    QPMODM          ; Are we configured for modem control?
31 005210 001403      BEQ      3$          ; Br if not -- No lines have modem control
32 005212 032705 000001      BIT      #1, R5          ; Is this line 0 or 2?
33 005216 001403      BEQ      4$          ; Br if yes -- Has modem control
34 005220 042761 000000G 000000G 3$:  BIC      #$PHONE, ILSW2(R1) ; Say line does not have modem control
35         ;
36         ; Convert line number into quad unit address
37         ;
38 005226 004737 006236' 4$:  CALL    QPCVLA          ; Convert line # to address
39         ;
40         ; At this point,
41         ;   R5 = Base address of registers for quad unit and channel.
42         ;
43         ; Initialize mode registers 1 and 2
44         ;
45 005232 112765 000020 000104      MOVB    #QP$RPR, QPRCRA(R5) ; Select mode register 1
46 005240 112765 000023 000100      MOVB    #023, QPRMRA(R5) ; Initialize mode register 1
47 005246 112765 000007 000100      MOVB    #007, QPRMRA(R5) ; Initialize mode register 2
48         ;
49         ; Initialize clock select register
50         ;
51 005254 112765 000273 000102      MOVB    #273, QPRCSA(R5) ; Initialize to 9600 baud
52         ;
53         ; Initialize receiver and transmitter
54         ;
55 005262 112765 000052 000104      MOVB    #QP$RRX!QP$DRX!QP$DTX, QPRCRA(R5) ; Reset receiver + disable
56 005270 112765 000100 000104      MOVB    #QP$RES, QPRCRA(R5) ; Reset error status
57 005276 112765 000065 000104      MOVB    #QP$RTX!QP$ERX!QP$ETX, QPRCRA(R5) ; Reset transmitter + enable

```

```
58 ;  
59 ; Finished  
60 ;  
61 005304 012605 9*: MOV (SP)+,R5  
62 005306 000207 RETURN
```

```

1          .SBTTL  QPSTRT -- Start output
2          ;-----
3          ; QPSTRT is called to initiate output to a line connected to the
4          ; quad line unit.
5          ;
6          ; Inputs:
7          ;   R1 = Line index number.
8          ;
9 005310  010546  QPSTRT: MOV      R5, -(SP)
10         ;
11         ; Convert line number into quad unit address
12         ;
13 005312  004737  006236'  CALL     QPCVLA      ;Convert line # to address
14         ;
15         ; At this point,
16         ;   R5 = Base address of registers for quad unit and channel.
17         ;
18         ; See if the transmitter is already busy
19         ;
20 005316         DISABL      ;;;Disable interrupts
21 005324  032761  000000G 000000G  BIT     #$XCHAR,LSW3(R1);;Is the transmitter busy now?
22 005332  001003         BNE     1$      ;;;Br if yes
23         ;
24         ; Transmitter is idle.
25         ; Enable the transmitter which will cause an interrupt.
26         ;
27 005334  112765  000004  000104  MOVB   #QP$ETX,QPRCRA(R5);;Enable transmitter (will cause interrupt)
28         ;
29         ; Finished
30         ;
31 005342  1$:  ENABL      ;Enable interrupts
32 005350  012605  MOV     (SP)+,R5
33 005352  000207  RETURN

```

QPCINT -- Interrupt from quad line unit

```

1
2
3
4
5
6 005354
7
8
9
10
11
12
13
14 005354 004577 000130'
15 005360 010246
16 005362 010346
17
18
19
20 005364 013703 000066'
21 005370 142763 000100 000004
22 005376 010301
23
24
25
26 005400 005002
27
28
29
30 005402 116204 000104'
31 005406 001461
32
33
34
35 005410 136263 005622' 000112
36 005416 001422
37
38
39
40
41 005420 004774 000000G
42 005424 103411
43
44
45
46 005426 052764 000000G 000000G
47 005434 042764 000000G 000000G
48 005442 110061 000106
49 005446 000406
50
51
52
53
54 005450 042764 000000G 000000G
55 005456 112761 000010 000104
56
57

```

.SBTTL QPCINT -- Interrupt from quad line unit

```

; QPCINT is the interrupt entry point for all interrupts from the
; quad line unit.
;
QPCINT:
;
; Save registers R0, R1, R4, and R5.
; TTRSAV is the standard interrupt entry routine called when processing
; received character interrupts. We always call it in the case of an
; interrupt from a quad unit line since we don't know whether the interrupt
; is from a transmitter or receiver.
;
; JSR R5,@TTRSAV ;Save registers
; MOV R2,-(SP)
; MOV R3,-(SP)
;
; Disable further interrupts from the quad line unit
;
; MOV QPCSR,R3 ;Get address of base of registers for DUART 0
; BICB #QP$IEN,QPRMSR(R3) ;Clear interrupt-enable bit
; MOV R3,R1 ;Get addr of base of registers for DUART
;
; Begin loop to determine which of the four lines needs service
;
; CLR R2 ;Start with line # 0 (DUART 0, channel A)
;
; Get TSX-Plus line index number of this line
;
1$: MOVB QPLX(R2),R4 ;Get TSX-Plus line index number
; BEQ 3$ ;Br if no line connected
;
; See if an output interrupt occurred
;
; BITB QPFTXR(R2),QPRISR(R3);Is transmitter ready for another char?
; BEQ 2$ ;Br if not
;
; The transmitter is ready for another character.
; See if there is another character to transmit.
;
; CALL @LOUTIR(R4) ;Get next character to transmit
; BCS 8$ ;Br if no more chars to transmit
;
; Transmit the character contained in R0
;
; BIS #XCHAR,LSW3(R4);Set transmitter-busy flag
; BIC #OITIM,LSW5(R4);Start timer to catch lost interrupts
; MOVB R0,QPRTRA(R1) ;Start transmitting the character
; BR 2$
;
; There are no more characters to transmit.
; Disable the transmitter
;
8$: BIC #XCHAR,LSW3(R4);Say transmission finished
; MOVB #QP$DTX,QPRCRA(R1) ;Disable the transmitter
;
; See if this line has received a character

```

QPCINT -- Interrupt from quad line unit

```

58 ;
59 005464 136263 005626' 000112 2$: BITB QPFRXR(R2),QPRISR(R3);Is a received character ready?
60 005472 001427 ; BEQ 3$ ;Br if not
61 ;
62 ; Get received character
63 ;
64 005474 116100 000102 ; MOVB QPRSRA(R1),R0 ;Get status flags for character
65 005500 116105 000106 ; MOVB QPRRRA(R1),R5 ;Get the received character
66 005504 042705 177400 ; BIC #^C<377>,R5 ;Mask character to 8 bits
67 ;
68 ; Set status flags in R5 to simulate status flags returned by DL11
69 ;
70 005510 032700 000040 ; BIT #QP$RPE,R0 ;Did we have a parity error?
71 005514 001402 ; BEQ 4$ ;Br if not
72 005516 052705 000000C ; BIS #RBERR!RCVPAR,R5;Set parity-error flags
73 005522 032700 000300 4$: BIT #QP$RFE!QP$BRK,R0 ;Framing error or break?
74 005526 001402 ; BEQ 5$ ;Br if not
75 005530 052705 000000C ; BIS #RBERR!FRMERR,R5;Set framing-error flags
76 005534 032700 000020 5$: BIT #QP$ROE,R0 ;Did an overrun occur?
77 005540 001402 ; BEQ 6$ ;Br if not
78 005542 052705 000000C ; BIS #RBERR!OVRRUN,R5;Set overrun flags
79 ;
80 ; Call TTINPT to process the received character
81 ;
82 005546 004777 000124' 6$: CALL @TTINPT ;Enter character input routine
83 ;
84 ; Check for other lines connect to the quad unit that may need service
85 ;
86 005552 005202 3$: INC R2 ;Advance line # within quad unit (0-3)
87 005554 020227 000003 ; CMP R2,#3 ;Have we serviced all lines?
88 005560 101010 ; BHI 7$ ;Br if yes
89 005562 062701 000020 ; ADD #QPRCOF,R1 ;Point to registers for next channel
90 005566 020227 000002 ; CMP R2,#2 ;Time to advance register base to DUART 1?
91 005572 001303 ; BNE 1$ ;Br if not
92 005574 062703 000040 ; ADD #QPRUOF,R3 ;Point to registers for DUART 1
93 005600 000700 ; BR 1$ ;Go service next line
94 ;
95 ; We have serviced all four lines.
96 ; Reenable interrupt for quad line unit.
97 ;
98 005602 013703 000066' 7$: MOV QPCSR,R3 ;Get address of base of registers for DUART 0
99 005606 152763 000100 000004 ; BISB #QP$IEN,QPRMSR(R3) ;Set interrupt-enable bit
100 ;
101 ; Finished
102 ;
103 005614 012603 ; MOV (SP)+,R3
104 005616 012602 ; MOV (SP)+,R2
105 005620 000207 ; RETURN ;Return through TTRSAV which restores regs
106 ;
107 ; Vector containing the proper bit mask to test for transmitter-ready
108 ; in the Interrupt Status Register for each line.
109 ;
110 005622 001 020 001 QPFTXR: .BYTE 1,20,1,20
111 005625 020
112 ;
113 ; Vector containing the proper bit mask to test for receiver-done
; in the Interrupt Status Register for each line.

```


114
115 005626 002 040 002 QPFRXR: .BYTE 2,40,2,40
005631 040
116 .EVEN

QPSSPD -- Set speed for quad line port

```

1          .SBTTL  QPSSPD -- Set speed for quad line port
2          ;-----
3          ; QPSSPD is called to set the transmit/receive speed for a line
4          ; connected to the quad serial line unit.
5          ;
6          ; Inputs:
7          ;   R0 = Speed code
8          ;   R1 = Physical line index number.
9          ;
10         005632  010346  QPSSPD: MOV      R3, -(SP)
11         005634  010546         MOV      R5, -(SP)
12         ;
13         ; Save info about baud rate for this line
14         ;
15         005636  110061  000001G     MOVVB   R0, LMXPRM+1(R1) ; Save info in line table
16         ;
17         ; Convert line number into quad unit address
18         ;
19         005642  004737  006236'     CALL    QPCVLA          ; Convert line # to address
20         ;
21         ; At this point,
22         ;   R5 = Base address of registers for quad unit and channel.
23         ;
24         ; Set transmit/receive speed
25         ;
26         005646  010003         MOV      R0, R3          ; Get control flags
27         005650  042703  000000C     BIC     #^C<LP$SPD>, R3 ; Clear all but speed value
28         005654  116303  005776'     MOVVB   QSPD(R3), R3    ; Get speed code for quad unit
29         005660  010346         MOV      R3, -(SP)
30         005662  072327  000004     ASH     #4, R3          ; Position speed code for receive
31         005666  052603         BIS     (SP)+, R3       ; Or in transmit speed
32         005670  110365  000102     MOVVB   R3, QPRCSA(R5) ; Set speed for line
33         ;
34         ; Set character length and parity
35         ;
36         005674  032700  000000G     BIT     #LP$7BT, R0     ; 7 bit characters wanted?
37         005700  001403         BEQ     1$,             ; Br if not
38         005702  012703  000002     MOV     #QP$7BR, R3     ; Get 7 bit char flags
39         005706  000402         BR      2$,             ;
40         005710  012703  000003     1$:   MOV     #QP$8BR, R3 ; Get 8 bit char flags
41         005714  032700  000000G     2$:   BIT     #LP$PAR, R0 ; Is parity wanted?
42         005720  001003         BNE     3$,             ; Br if yes
43         005722  052703  000020     BIS     #QP$NPR, R3     ; Set no-parity flag
44         005726  000405         BR      4$,             ;
45         005730  032700  000000G     3$:   BIT     #LP$ODD, R0 ; Odd parity wanted?
46         005734  001402         BEQ     4$,             ; Br if not
47         005736  052703  000004     BIS     #QP$ODD, R3     ; Select odd parity
48         005742         4$:   DISABL          ; ; ** Disable interrupts **
49         005750  112765  000020  000104  MOVVB   #QP$RPR, QPRCRA(R5) ; ; Select mode register 1
50         005756  110365  000100     MOVVB   R3, QPRMRA(R5) ; ; Set char length and parity
51         005762         ENABL          ; ; ** Enable interrupts **
52         ;
53         ; Finished
54         ;
55         005770  012605         MOV     (SP)+, R5
56         005772  012603         MOV     (SP)+, R3
57         005774  000207         RETURN

```

```
58 ;  
59 ; Vector of values to convert TSX-Plus standard transmit/receive  
60 ; speed codes into codes for the quad serial line unit.  
61 ;  
62 005776 000 000 001 QPSPD: .BYTE 0,0,1,2,3,4,5,6,10,7,8,0,9,0,11,12.  
006001 002 003 004  
006004 005 006 012  
006007 007 010 000  
006012 011 000 013  
006015 014  
63 . EVEN
```

QPSBRK -- Control break transmission to quad line unit

```

1          .SBTTL  QPSBRK -- Control break transmission to quad line unit
2          ;-----
3          ; QPSBRK is called to start or stop transmitting a break character to
4          ; a line connected to the quad serial line unit.
5          ;
6          ; Inputs
7          ; R0 = Break control flag (MS$BRK)
8          ; R1 = Physical line index number.
9          ;
10         006016  010546  QPSBRK: MOV      R5, -(SP)
11         ;
12         ; Convert line number to address of control register
13         ;
14         006020  004737  006236'      CALL      QPCVLA      ;Convert line # to address
15         ;
16         ; At this point,
17         ; R5 = Base address of registers for quad unit and channel.
18         ;
19         ; See if we are to start or stop sending a break
20         ;
21         006024  032700  000000G      BIT       #MS$BRK,R0      ;Start or stop sending a break?
22         006030  001404                      BEQ      1$              ;Br if stop
23         ;
24         ; Start sending a break
25         ;
26         006032  112765  000140  000104      MOVVB    #QP$SBT,QPRCRA(R5) ;Start break transmission
27         006040  000403                      BR       9$
28         ;
29         ; Stop sending a break
30         ;
31         006042  112765  000160  000104  1$:  MOVVB    #QP$EBT,QPRCRA(R5) ;Stop break transmission
32         ;
33         ; Finished
34         ;
35         006050  012605  9$:  MOV      (SP)+,R5
36         006052  000207                      RETURN

```

```

1          .SBTTL  QPGDSS -- Get data set status for line
2          ;-----
3          ; QPGDSS is called to get the data set (modem) status for a line
4          ; connected to the quad serial line unit.
5          ;
6          ; Inputs:
7          ; R1 = Physical line index number.
8          ;
9          ; Outputs:
10         ; RO = Generic data set status flags (MS$xxx)
11         ;
12 006054 010346 QPGDSS: MOV     R3,-(SP)
13 006056 010546      MOV     R5,-(SP)
14         ;
15         ; Convert line number to address of control register
16         ;
17 006060 004737 006260'      CALL    QPCVLX      ;Convert line # to address
18         ;
19         ; At this point,
20         ; R5 = Base address of registers for quad unit.
21         ; R3 = Table index whose value depends on whether we are accessing
22         ; lines 0 or 1 (DUART 0) or lines 2 and 3 (DUART 1)
23         ; and the configuration 4/0 or 2/2.
24         ;
25         ;
26         ;
27         ;
28         ;
29         ;
30         ;
31         ;
32         ;
33         ; See if the phone is ringing
34         ;
35 006064 005000      CLR     RO      ;Develop flags in RO
36 006066 136365 006144' 000132 BITB   QPFRI(R3),QPRIP(R5) ;Is the RI flag set for line?
37 006074 001402      BEQ    1$      ;Br if not
38 006076 052700 000000G    BIS    #MS$RNG,RO      ;Set ring status flag for return
39         ;
40         ; See if carrier is detected
41         ;
42 006102 136365 006140' 000132 1$: BITB   QPFCD(R3),QPRIP(R5) ;Is carrier detected?
43 006110 001402      BEQ    2$      ;Br if not
44 006112 052700 000000G    BIS    #MS$CAR,RO      ;Set carrier-detected flag for return
45         ;
46         ; See if Data Terminal Ready is asserted
47         ;
48 006116 136363 006150' 006154' 2$: BITB   QPFDTR(R3),QPOP(R3) ;Is DTR asserted?
49 006124 001402      BEQ    3$      ;Br if not
50 006126 052700 000000G    BIS    #MS$DTR,RO      ;Set DTR return flag
51         ;
52         ; Finished
53 006132 012605      3$:  MOV    (SP)+,R5
54 006134 012603      MOV    (SP)+,R3
55 006136 000207      RETURN
56         ;
57         ; Flag values to check Carrier Detect flag based on channel and config

```

```
58 ;  
59 006140 004 010 004 QPFCD: .BYTE 4,10,4,0  
   006143 000  
60 ;  
61 ; Flag values to check for line ringing  
62 ;  
63 006144 000 000 010 QPFRI: .BYTE 0,0,10,0  
   006147 000  
64 ;  
65 ; Flag values to check for (or assert) Data Terminal Ready  
66 ;  
67 006150 004 010 004 QPFDTR: .BYTE 4,10,4,0  
   006153 000  
68 ;  
69 ; Shadow cells to hold value of output port settings  
70 ;  
71 006154 000 000 000 QPOP: .BYTE 0,0,0,0  
   006157 000
```



```

1          .SBTTL  QPCVLA -- Convert line index into register addresses
2          ;-----
3          ; QPCVLA is called to convert a TSX-Plus line index number of a line
4          ; connected to the quad serial line unit into an address that corresponds
5          ; to the base of the registers for the corresponding DUART and channel.
6          ;
7          ; Inputs:
8          ;   R1 = TSX-Plus line index number
9          ;
10         ; Outputs:
11         ;   R5 = Address of base of registers for DUART and channel
12         ;   (R0 is preserved)
13         ;
14 006236  QPCVLA:
15         ;
16         ; Determine which quad line this line is connected to
17         ;
18 006236  016105  000000G      MOV      LMXLN(R1),R5      ;Get line # within quad line unit (0-3)
19         ;
20         ; Compute address of registers for this line
21         ;
22 006242  116505  006254'    2#:  MOVB   QPFADR(R5),R5      ;Get offset based on DUART and channel
23 006246  063705  000066'    ADD    QPCSR,R5      ;Add base CSR address for module
24         ;
25         ; Finished
26         ;
27 006252  000207      RETURN
28         ;
29         ; Table of register address offsets based on line number
30         ;
31 006254      000      020      040  QPFADR: .BYTE  0,20,40,60
32 006257      060
          .EVEN

```



```

1          .SBTTL  QPCVLX -- Get address and configuration info
2          ;-----
3          ; QPCVLX is called to convert a TSX-Plus line number for a line connected
4          ; to the quad serial line unit into two items of information:
5          ; (1) the address of the base of the registers for the DUART to which
6          ; the line is connected; (2) an index value in the range 0 to 3 which
7          ; indicates which channel of the DUART the line is connected to and
8          ; which configuration (2/2 or 4/0) the serial line unit is in.
9          ;
10         ; Inputs:
11         ; R1 = TSX-Plus line index number.
12         ;
13         ; Outputs:
14         ; R5 = Base address of registers for DUART.
15         ; R3 = Channel and configuration index value as follows:
16         ;
17         ;           Line  Config  Value
18         ;           ----  -
19         ;           0/2    4/0     0
20         ;           1/3    4/0     1
21         ;           0/2    2/2     2
22         ;           1/3    2/2     3
23         ;
24         ; (R0 is preserved)
25         ;
26 006260  QPCVLX:
27         ;
28         ; Determine which quad line this line is connected to
29         ;
30 006260  016103  000000G      MOV      LMXLN(R1),R3      ;Get line # within quad line unit (0-3)
31         ;
32         ; Get the DUART base register address
33         ;
34 006264  116305  006314'     2$:      MOVB     QPFDAD(R3),R5      ;Get offset based on DUART 0 or 1
35 006270  063705  000066'     ADD      QPCSR,R5        ;Add CSR address of base of module
36         ;
37         ; Get index value based on line # and configuration
38         ;
39 006274  042703  177776      BIC      #^C<1>,R3       ;Get 0 for lines 0&2, 1 for lines 1&3
40 006300  105737  000110'     TSTB     QPMODM          ;Is this a 2/2 configuration?
41 006304  001402      BEQ      9$              ;Br if not
42 006306  062703  000002      ADD      #2,R3           ;Set index based on config
43         ;
44         ; Finished
45         ;
46 006312  000207     9$:      RETURN
47         ;
48         ; Table of address offsets to base registers for DUARTs based on line #
49         ;
50 006314      000      000      040  QPFDAD: .BYTE  0,0,40,40
51         ;
52         ;           .EVEN
53         ;           .ENDC      ;NE,QPASM      ;End of quad line unit code
54         ;
55         ; Size of TSXPRO
56         ;
56         ; PROSIZ =      .-PROBAS      ;Size of TSXPRO

```

57 000001 .END
Errors detected: 0

*** Assembler statistics

Work file reads: 0
Work file writes: 0
Size of work file: 8488 Words (34 Pages)
Size of core pool: 18176 Words (71 Pages)
Operating system: RT-11

Elapsed time: 00:00:49.46
.LP:TSXPRO=DK:TSXPRO/C/N:SYM

\$DEAD	12-23	59-22											
\$DHCDO	2-30												
\$HISTP	2-36	5-13	6-12	12-23	53-13	54-13							
\$OITIM	2-20	7-28	12-19	33-52	41-30	50-27	51-29	52-13	52-19	53-30	54-30	62-47	
\$PHONE	12-21	47-73	60-34										
\$SXOFF	2-37	5-18	12-26	53-23									
\$SXON	2-38	6-17	12-26	54-23									
\$VDCSR	14-16#	24-58	24-58*	32-35	32-39*	33-21*							
\$XCHAR	2-20	7-27	7-41	12-19	33-51	33-59	41-20	41-29	42-7	50-15	50-26	51-16	
	51-28	52-15	52-17	53-17	53-29	54-17	54-29	61-21	62-46	62-54			
CDCLOK	2-14	4-69#	12-25	47-19*									
CDGDSS	2-14	4-83#	10-19	12-21	40-21*	47-22*	59-44*						
CDIFLG	2-12	4-155#											
CDIRTN	2-12	4-140#											
CDQFLG	2-12	4-156#											
CDORTN	2-12	4-139#											
CDSBRK	2-14	4-107#	12-27	40-22*	47-24*	59-46*							
CSDSDS	2-14	4-95#	10-21	12-21	47-23*	59-45*							
CDSSPD	2-13	4-119#	9-15	12-27	40-23*	47-25*	59-47*						
CDSTOP	2-11	4-34#											
CDSTR2	2-15	4-22#											
CDSTRT	2-11	4-13#	5-23	6-22	12-21	30-19*	40-20*	47-18*	59-43*				
CDSXOF	2-15	4-46#	12-24	47-20*									
CDSXON	2-15	4-58#	12-24	47-21*									
CDX\$PC	12-22	47-14	47-18*	47-19*	47-20*	47-21*	47-22*	47-23*	47-24*	47-25*			
CDX\$PI	12-23	30-15	30-19*										
CDX\$PP	12-22	40-15	40-20*	40-21*	40-22*	40-23*							
CDX\$QP	12-29	59-43*	59-44*	59-45*	59-46*	59-47*	60-13						
CORUSR	12-18	35-21											
CP\$7BR	19-63#	58-50											
CP\$7BT	19-83#	57-14	58-49										
CP\$8BR	19-64#	58-47											
CP\$8BT	19-84#	57-17	58-46										
CP\$ACM	19-21#												
CP\$ARP	19-20#												
CP\$AS	19-98#												
CP\$ASM	19-59#												
CP\$AW3	19-65#	47-46	58-42										
CP\$AW4	19-74#	47-44	58-30										
CP\$AW5	19-85#	47-48	57-14	58-43									
CP\$BR	19-94#	49-20											
CP\$BRP	19-107#												
CP\$BRR	19-13#	58-25*											
CP\$BW1	19-111#												
CP\$BW2	19-115#												
CP\$CAR	19-9#	47-36	47-70*	47-71*	48-26*	48-31*	48-36*	49-18*	49-19	49-23*	49-31*	50-16*	
	50-17*	57-28*	57-29*	58-29									
CP\$CBR	19-10#	47-59	48-7*	48-8									
CP\$CCS	19-79#												
CP\$CD	19-139#	55-22											
CP\$CMM	19-73#												
CP\$CR	19-43#	47-37	47-60										
CP\$CRC	19-22#												
CP\$CS	19-131#												
CP\$CTS	19-140#												
CP\$DBR	19-8#	25-45	49-27	50-28*	51-30*	53-31*	54-31*						

CP\$DSR	19-142#						
CP\$DTR	19-130#	47-75	55-28	56-19	56-24		
CP\$EHP	19-61#						
CP\$EI	19-47#	48-36	49-31	50-17			
CP\$EIE	19-51#						
CP\$EIR	19-44#						
CP\$EOF	19-103#						
CP\$ER	19-46#	48-26					
CP\$EVN	19-70#	58-36					
CP\$IES	19-120#						
CP\$INP	19-90#						
CP\$IRC	19-121#						
CP\$ISR	19-122#						
CP\$ITE	19-119#						
CP\$LEN	19-82#						
CP\$LL	19-126#						
CP\$MOR	19-11#	47-69*	47-72*	47-75*	55-28	56-19*	56-24*
CP\$M1R	19-12#	55-16	55-22				
CP\$MCO	19-133#						
CP\$MCV	19-16#	47-31*	47-32*				
CP\$MM	19-132#						
CP\$PAR	19-69#	58-33					
CP\$RC	19-99#						
CP\$RCA	19-89#						
CP\$RCE	19-60#						
CP\$RCL	19-62#						
CP\$REN	19-57#						
CP\$RES	19-42#	47-51	48-31	49-23			
CP\$RFE	19-102#						
CP\$RI	19-141#	55-16					
CP\$RIE	19-53#	47-71					
CP\$RL	19-127#						
CP\$ROE	19-101#						
CP\$RPE	19-100#						
CP\$RRO	19-35#	49-18					
CP\$RR1	19-36#						
CP\$RR2	19-37#	48-7					
CP\$RTI	19-45#	50-16					
CP\$RTS	19-129#	47-72					
CP\$RTV	19-15#	47-29*	47-30*				
CP\$SA	19-41#						
CP\$SB	19-81#	57-23					
CP\$SBS	19-71#						
CP\$SCL	19-58#						
CP\$SH	19-92#						
CP\$SMI	19-137#						
CP\$SMS	19-72#						
CP\$SRS	19-128#						
CP\$TBM	19-91#						
CP\$TCE	19-78#						
CP\$TEM	19-93#						
CP\$TEN	19-80#						
CP\$TI	19-138#						
CP\$TIE	19-52#	47-71					
CP\$WRO	19-27#						
CP\$WR1	19-28#	47-63	47-70				

PIINIT	25-29	30-10#						
PIINT	39-10	39-19#						
PIINWD	14-10#	24-38						
PIKIIR	24-64	37-5#						
PIKDIR	24-68	38-6#						
PILINE	14-37#	30-14*	32-18	33-27	34-12	35-23	37-45	
PILQE	39-12#							
PIMOC	14-48#	31-38*	33-58*	35-30*				
PINDCH	14-26	34-11#						
PIOIFL	14-41#	32-31	32-33*	33-15*	33-65*			
PIQUIT	31-18	33-28	34-18	35-13#				
PISCNT	14-42#	31-13*	31-46*					
PISRT	12-25	24-13						
PISTRT	30-19	31-9#						
PIVFIR	24-76	36-6#						
PIVTIR	24-66	24-78	33-5#					
PIXEOF	14-12#	36-20						
PIXICH	14-13#	37-19						
PIXIOI	14-14#	38-20						
PIXIOQ	14-15#	39-32						
PIXOCH	14-11#	33-53						
PP\$7BT	18-30#	46-22						
PP\$8BT	18-31#	46-20						
PP\$BRS	18-39#							
PP\$CMF	18-51#	21-47	40-49					
PP\$CMR	18-11#	21-47*	40-34	40-49*	43-37*	45-19*	45-24*	46-30
PP\$DBR	18-8#	25-38	41-31*	43-18				
PP\$DSR	18-25#							
PP\$DTR	18-45#							
PP\$EVN	18-33#	46-28						
PP\$FB	18-47#	45-19	45-24					
PP\$FE	18-24#	43-26						
PP\$LEN	18-29#							
PP\$M1F	18-35#	40-35	46-17					
PP\$M2F	18-40#	46-36						
PP\$MDR	18-10#	40-35*	46-31*	46-37*				
PP\$OE	18-23#	43-29						
PP\$OM	18-50#							
PP\$PAR	18-32#	46-25						
PP\$PE	18-22#	43-23						
PP\$RCS	18-12#	21-34						
PP\$RCV	18-15#	40-27*	40-28*					
PP\$RD	18-21#							
PP\$RE	18-48#	21-47	40-49	43-37				
PP\$REN	18-46#							
PP\$RTS	18-49#							
PP\$SBL	18-34#							
PP\$STR	18-9#	43-23	43-26	43-29				
PP\$TCS	18-13#	21-35						
PP\$TEN	18-44#							
PP\$TR	18-20#							
PP\$TRV	18-16#	40-29*	40-30*					
PPGDSS	40-21	44-13#						
PPINIT	25-40	40-10#						
PPLINE	14-38#	40-14*	41-16	43-14				
PPRINT	40-27	43-5#						

RBERR	12-20	43-25	43-28	43-31	43-35	62-72	62-75	62-78
RCVPAR	12-20	43-25	62-72					
REENAB	14-17#	32-40*	33-20*	33-61*				
RLINE	2-27							
RPRCSR	12-29	21-30*						
RPRVEC	12-29	21-29*						
RSR	12-21	25-34						
RT\$BAS	12-26	24-14						
S4800	12-28	40-44						
S9600	12-24	40-41	47-54					
SETDSS	2-16	10-9#						
SETSPD	2-14	9-9#						
SILFET	2-16	4-135#						
SNDFRE	4-141#							
SR0MMR	12-30	22-18*	22-37*					
SR3MMR	12-30	22-19*						
SS\$BNK	15-9#							
SS\$BRK	15-11#	21-44	21-46					
SS\$MON	15-10#							
TBR	2-28	7-31*						
TIOVEC	2-16	4-132#						
TRINT	2-28	7-42	7-51					
TRNSTR	2-16	4-137#						
TRRDY	2-28	7-29						
TSR	2-28	7-29	7-42*	7-51*				
TSTIO	2-11	4-12#						
TSXPRO	12-4#	12-12						
TTINPT	2-13	4-134#	12-20	37-46	43-41	49-39	62-82	
TTRSAV	2-13	4-136#	12-27	43-9	49-12	62-14		
VDFLAG	14-19#	32-34*	33-60*					
VHCLOK	2-40							
VHQDSS	2-32							
VHSBRK	2-22							
VHSDSS	2-33							
VHSSPD	2-22							
VHSTOP	2-39							
VHSTRT	2-30							
VHXOFF	2-31							
VHXON	2-31							
VIDCSR	12-29	21-24*						
VIDSLT	14-44#	21-17*	21-21					
VIDTBL	14-52#	21-13						
VIDVEC	14-45#	21-20*	23-13	24-75				
VP\$CME	17-13#							
VP\$COO	17-12#							
VP\$DOI	17-15#	32-35	32-39	33-21				
VP\$EFI	17-10#							
VP\$EOF	17-11#							
VP\$IMD	17-8#							
VP\$LMD	17-7#							
VP\$DEF	17-9#							
VP\$OMP	17-14#							
VP\$TRD	17-16#							
VPAR5	12-25	22-23	24-19	24-23	24-34	24-39	24-53	
VPAR6	12-25	24-40						
VSWPSL	12-25							
VT100	12-27	30-25						

