CONTROL DATA 9461 DISK STORAGE DRIVE

A12 AND ABOVE B12 AND ABOVE

MAINTENANCE

CONTROL DATA CUSTOMER ENGINEERING MANUAL

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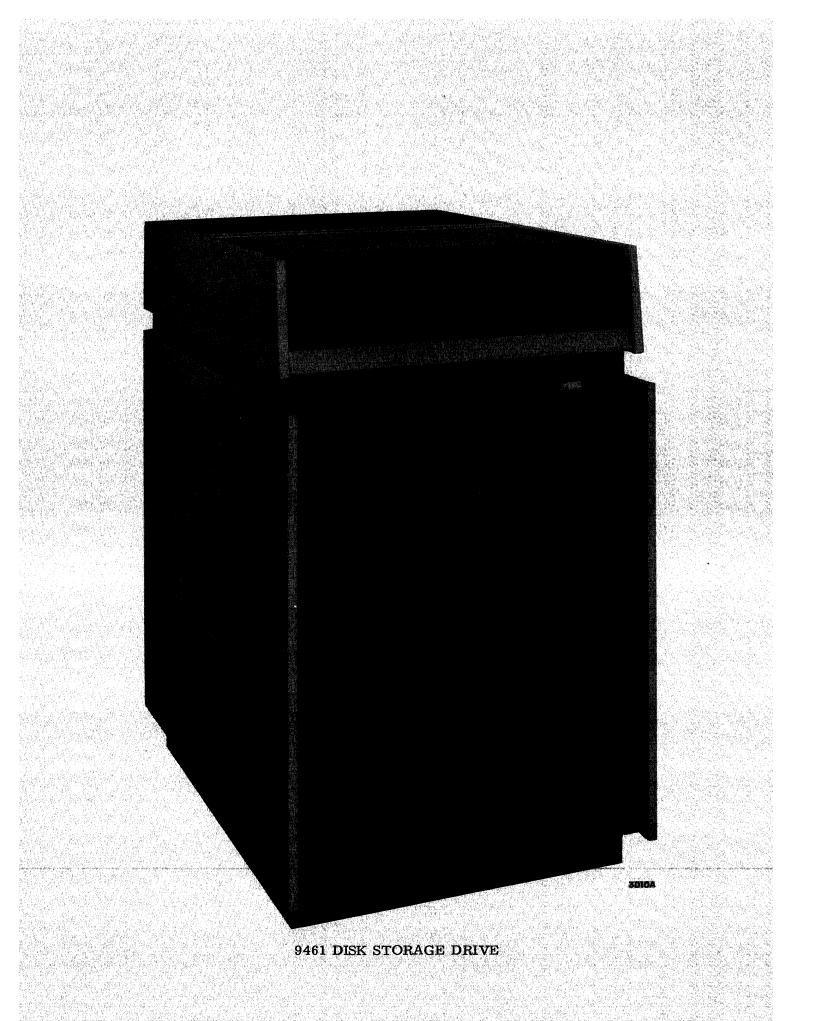
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SECTION 1

INTRODUCTION



INTRODUCTION

The CONTROL DATA® 9461 Disk Storage Drive is a high-speed, random-access, input/output device to be used with a central processor. The performance characteristics of the unit make it suitable for use with all Control Data computers and most other data processing systems.

SCOPE

This manual is a technical guide for customer engineers and other technical personnel who are directly involved with maintaining the disk storage drive. The manual is divided into seven sections: Introduction, Operation, Functional Description, Interface, Preventive Maintenance, Maintenance Procedures, and Special Maintenance Information.

DESCRIPTION

The 9461 stores information on a disk pack in the form of magnetized bits or spots. Disk packs may be freely and quickly interchanged between disk storage drives of the same type using the same addressing scheme. Disk packs also allow unlimited shelf storage of files of input data as well as random access to the data. The data on a disk pack, although permanent, may be erased and replaced by new information if desired.

The 9461 may be used with computers in an on-line capacity or with external equipment in an off-line processing system. Transfer of data and exchange of control information from computers or off-line equipment to the disk storage drive is via a separate external control unit. The control unit provides the timing information necessary to buffer and control the flow of information into and out of the disk storage drive.

ASSOCIATED PUBLICATIONS

Manuals of the customer engineering series which are to be used in conjunction with this maintenance manual are:

• 9461 Diagrams and Wire List, Pub. No. 41248400

The diagrams section contains the logic and electrical schematics of the major assemblies of the disk storage drive. The wire list section contains information such as conductor origin and destination, color coding, length, and size. The circuit description contains explanations of logic and electrical schematics and is located in the diagrams section.

- 9461 Illustrated Parts List, Pub. No. 41245200
 The parts list contains part numbers, part identification views, and part identification information.
- Disk Storage Drive (OEM), 1604 Series Logic Modules, Pub. No. 40826700. The electrical schematics, component layout diagrams, and the operational description of the logic cards used in Control Data peripheral equipment are found in this manual.

Refer to the Control Data Literature Catalog for the latest publication numbers and revision levels of the associated publications.

CONFIGURATION OF EQUIPMENT BY MOD LEVEL

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Mod A - The 9461 Mod A is designed to operate with a 60-Hz power source.

Mod B - The 9461 Mod B is designed to operate with a 50-Hz power source.

SPECIAL TOOLS

TOOL	PART NO.	
CE Disk Pack	84357500	
Disk Pack Runout Gage	84357600	
Plastic Feeler Gage (0.001 in.)	12205637	
Plastic Feeler Gage (0.002 in.)	1220 5636	
Plastic Feeler Gage (0.003 in.)	12205635	
Plastic Feeler Gage (0.005 in.)	12205633	
Tachometer	84362900	
Lock Wedge Removal Tool	84371800	
Extraction Tool	12210915	
Push-Pull Gage	12210797	
Head Plug Adapter	46812200	
Compression Tool	84356100	
Oscilloscope, dual trace, Tektronix 545 with type CA preamplifier (or equivalent)		

EQUIPMENT SPECIFICATIONS

CHARACTERISTIC	SPECIFICATION
Capacity/Data Format	
Total Capacity	7,250,000 characters
Bits per Byte	8
Bytes per Disk Surface	725,000
Bytes per Track	3625
Processing Speed	
Access Time (max)	135 ms
One-Track Access Time	24 ms (max)
Average Access Time	85 m s

CHARACTERISTIC (Cont'd)

SPECIFICATION

Recording

Mode	Double frequency
Density	765 bpi (outer track) and 1105 bpi (inner track)
Bit Rate	1.25 MHz
Data Transfer Rate	156,250 characters/sec

Disks

Number of Disks	6
Usable Disk Surfaces	10
Tracks per Disk Surface	200 tracks +3 spares
Speed	2400 ±48 rpm
Diameter	1 4 in.
Coating material	Magnetic oxide

Heads

Total	10
Read/Write Width	0.008 in.
Total Erase Width	0.012 in.
Erase Tunnel Width	0.005 in.
Track Spacing	0.010 in.

Addressing

Optional

Operator Controls

START switch/indicator Access Ready indicator (green) SELECT LOCK switch/indicator

Physical

41 in. (104 cm)
24 in. (61 cm)
36 in. (91.4 cm)
480 lb. (217.7 kg)

CHARACTERISTIC (Cont'd)

 ${\tt Environment}$

Operating

Nonoperating

Heat Dissipation

Electrical

Power Source

Maximum Run Current

SPECIFICATION

 60° to 90° F (20° F/hr-max gradient) 10% to 80% relative humidity - 30° to 150° F 5% to 98% relative humidity 3000 BTU/hr

208 volts, 60 Hz, 3-phase Mod A (or 208 volts, 50-Hz, 3-phase Mod B) delta

4.3 amperes/phase

SECTION 2

OPERATION

OPERATION

This section provides the operator with general operating instructions for the disk storage drive and a functional description of the controls and indicators of the unit.

GENERAL OPERATING INSTRUCTIONS

APPLICATION OF POWER

The power distribution circuit contains three interlock switches. The front and top rear covers must be closed and a disk pack must be installed before power can be applied to the spindle drive motor.

- 1. Make certain that the disk storage drive power cord is connected to the correct external ac power source (check unit identification plate for required voltage and frequency).
- 2. To gain access to the power supply control panel, grasp the top edge of the cabinet rear panel and pull outward.

CAUTION

If the disk storage drive is connected to the controller in series with other units, do not turn the power supply MAIN POWER circuit breaker on or off while one of the other units is reading or writing. This may cause the disk storage drive or the controller to make errors. Refer to the Diagrams and Wire List Manual (see Section 1) for additional information on the Power-Up sequence.

- 3. Set the power supply MAIN POWER circuit breaker to ON. The adjacent neon phase and +20Y indicators light to verify the application of external ac power.
- 4. Set the remaining power supply circuit breakers to ON. The related indicators light to verify the presence of each voltage.
- 5. Install the cabinet rear panel. Install a disk pack.

NOTE

Maximum operational stability is achieved after the unit has reached thermal stability. The warmup time (spindle rotating) is approximately 45 minutes if the ac power has been removed for longer than 4 hours. It is recommended that the power supply remain energized (MAIN POWER circuit breaker ON) or that the warmup period be allowed prior to a Read/Write operation.

6. Press the START switch to apply power to the spindle drive motor and start the First Seek operation. The Access Ready indicator lights when the read/ write heads are loaded. When the carriage stops at Track 00, the unit is ready to receive a Read, a Write, or a Seek command from the controller.

DISK PACK INSTALLATION AND REMOVAL

Installation

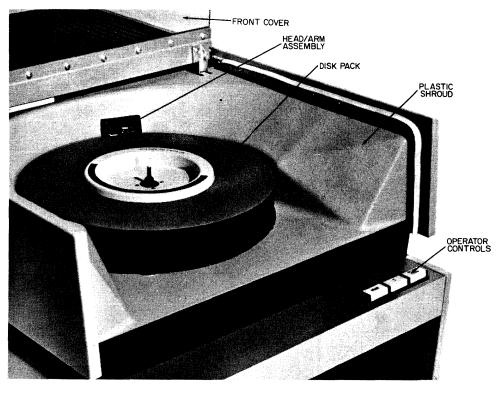
Prior to installing a disk pack, set the power supply MAIN POWER circuit breaker to ON (applies spindle brake). Do not press the START switch/indicator. Make certain that the disk pack to be installed has been cleaned according to the preventive maintenance schedule, Section 5.

- 1. Lift the disk pack by the plastic cannister handle.
- 2. Unscrew the bottom dust cover from the disk pack using the knob in the center of the cover. Set the cover aside.
- 3. Raise the front cover on the disk storage drive, Figure 2-1.

CAUTION

Avoid abusive contact between the disk pack and the spindle assembly. Avoid touching either the spindle assembly or the mating surface of the disk pack. Corrosion may result.

- 4. Place the disk pack onto the spindle.
- 5. Twist the plastic cannister clockwise to lock the disk pack in place. Make certain the cover has been rotated clockwise to a positive stop.



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Figure 2-1. Disk Pack Load and Unload Mechanics

- 6. Lift the cannister clear of the disk pack.
- 7. Close the front cover immediately to prevent the entry of dust and the contamination of the disk surfaces.

Removal

Before removing the disk pack, make certain it has stopped rotating. The power supply MAIN POWER circuit breaker should remain ON to apply the spindle brake.

- 1. Raise the front cover on the disk storage drive.
- 2. Place the plastic cannister over the mounted disk pack so that the post protruding from the center of the disk pack is received into the cannister handle.
- 3. Twist the cannister handle counterclockwise until the disk pack is free of the spindle.

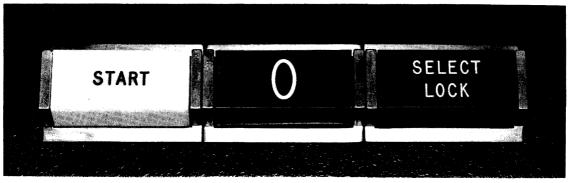
CAUTION

Avoid abusive contact between the disk pack and the spindle.

- 4. Lift the cannister and the disk pack clear of the spindle.
- 5. Close the front cover over the shrouded area.
- 6. Place the bottom dust cover in position on the disk pack and tighten it.
- 7. If operations requiring further use of the disk storage drive are complete, set the power supply MAIN POWER circuit breaker to OFF.

CONTROLS AND INDICATORS

Manual controls and indicators (Figure 2-2) used in operating the disk storage drive are mounted in front of the front cover. Additional controls and indicators (used by authorized maintenance personnel only are located on the logic chassis maintenance panel (Figure 2-3) and the power supply control panel (Figure 2-4). A brief functional description of these controls and indicators follows Figure 2-4.



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Figure 2-2. Operator Panel



Figure 2-3. Logic Chassis Maintenance Panel

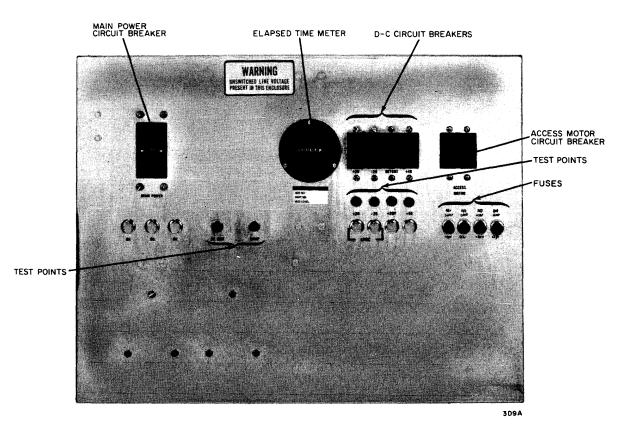


Figure 2-4. Power Supply Control Panel

CONTROL AND INDICATOR FUNCTIONS

CONTROL OR INDICATOR

FUNCTION

Operator Panel

START switch/indicator

Energizes (when pressed to light) the spindle drive motor to begin a First Seek sequence if the disk pack is in place and all unit interlocks are closed.

Access Ready indicator De-energizes (when pressed to extinguish) the spindle drive motor causing heads to unload and carriage to retract. The number etched on the Access Ready indicator is the unit number assigned to the disk storage drive when several units are used in the same system. The indicator lamp lights at the end of the First Seek operation (heads loaded and positioned at Track 00). The indicator lamp extinguishes if the START switch is pressed (to extinguish), main power to the unit is removed, or the detent pawl is out of the detent gear for more than 600 ms. All disk storage drives leave the factory as unit 0. Wiring (at the controller) and changing the indicator lens are necessary to change the unit number.

> Lights when one or more of the following unwanted conditions exist:

- 1. More than one head is selected.
- 2. Read and write selects exist simultaneously.
- 3. Read and erase selects exist simultaneously.
- 4. Erase current is applied without write current (if the condition exists for more than 200 usec).

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SELECT LOCK switch/ indicator

CONTROL AND INDICATOR FUNCTIONS (Cont'd)

CONTROL OR INDICATOR

FUNCTION

- 5. Erase is selected in combination with both write drivers.
- 6. One or both write drivers are on with no erase driver.
- 7. Write or Erase is selected without the Selected Drive Ready signal.
- 8. Write Gate is present without ac write current.
- 9. Low dc voltages in the disk storage drive.
- 10. Loss of ac power.

The Select Lock flip-flop in the logic section can be cleared by setting the ON LINE/OFF LINE switch to OFF LINE and depressing the SELECT LOCK switch. The Select Lock FF will remain cleared until the source of the problem reappears.

Switch is located directly below the operator panel controls. The switch disables the brake for purposes of disk pack inspection. and maintenance. When in the OFF position the brake is disabled. The switch must be in the ON position for all other operations.

Spindle Lock Disable

Power Supply Control Panel

MAIN POWER circuit breaker

 ± 20 vdc circuit breakers

+40 vdc circuit breaker

Controls the ac voltage to the disk storage drive unit.

Control the application of these voltages to the logic section.

Controls the application of this voltage to the write supply.

CONTROL AND INDICATOR FUNCTIONS (Cont'd)

CONTROL OR INDICATOR

FUNCTION

NOTE

An indicator is provided with each of the preceding circuit breakers. Each indicator is lighted when the corresponding potential is present. Test points are also provided as service aids to test the various voltage levels.

Controls the +20X vdc to the detent magnet.

Controls the +20X vdc to the access motor.

Indicates the spindle drive motor operating

Protects the +20Y vdc line to the head and

Protects the +20X vdc line to the sector

DETENT circuit breaker

ACCESS MOTOR circuit breaker

Elapsed Time Meter

- F01/5 amp/+20v Fuse
- F02/1 amp/+20 v Fuse

F04/1 amp/+20v Fuse

F03/1 amp/+36v Fuse Protects the +36 vdc sequence voltage line.

solenoid.

time (pack rotating).

cam latch solenoids.

Protects the +20 vdc to the START and Access Ready indicators.

NOTE

F05 and F06 are located behind the Power Supply Control Panel on the right side of the chassis assembly.

F05/1 amp/24 vac Fuse	Protects the 24 vac line to the brush motor.
F06/5 amp/+40v Fuse	Protects the +40 vdc line to the spindle
	drive motor.

CONTROL AND INDICATOR FUNCTIONS (Cont'd)

CONTROL OR INDICATOR

FUNCTION

Logic Chassis Maintenance

Panel

OFF LINE/ON LINE switch

Transfers the control of the disk storage drive unit from the controller to the unit itself, and vice versa. When the switch is in one of the two OFF LINE positions, a Read operation may be performed from either head 0 or head 1 as selected.

Actuator Assembly

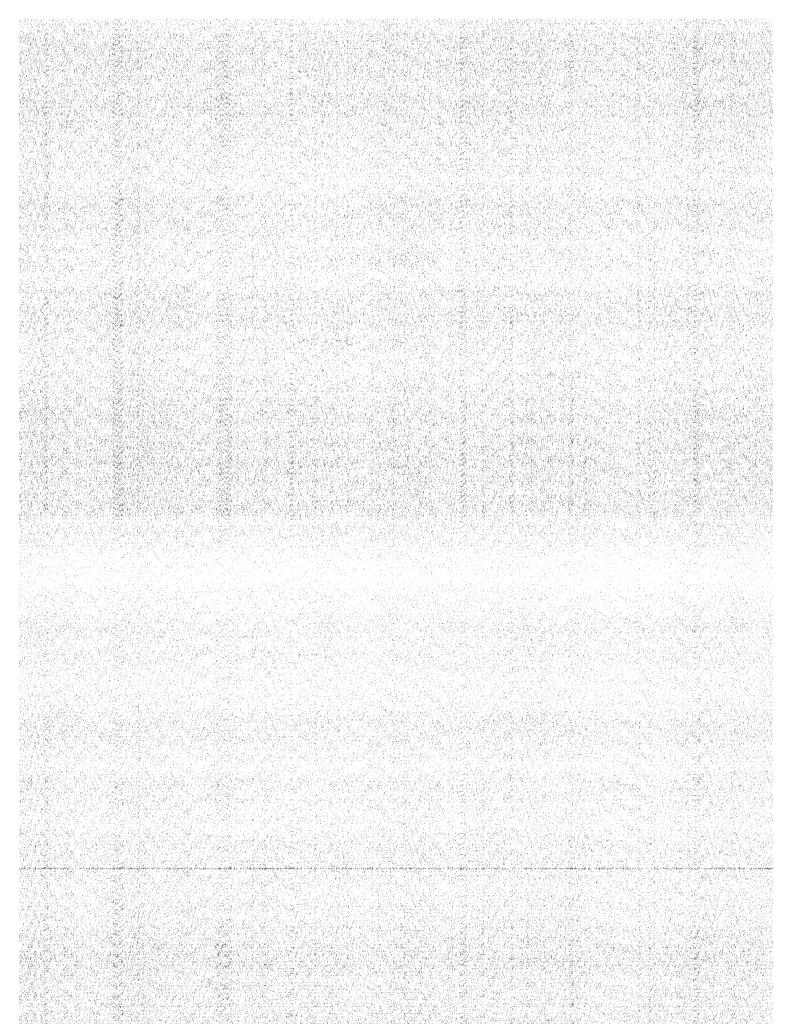
Track indicator dial

The dial is etched on the timing disk (Figure 3-14) and indicates the track number at which the carriage is detented. The dial is read at the track indicator index (overhangs timing disk).

FUNCTION DESCRIPTION

SECTION 3

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FUNCTION DESCRIPTION

INTRODUCTION

The functions performed by the disk storage drive and the signals (Figure 3-1 and Table 3-1) exchanged with the controller are described in the first part of Section 3. (For a detailed description of the logical functions of the unit, refer to the Diagrams and Wire List manual.) The second part of Section 3 relates the major assemblies of the unit to the previously discussed functions. Unit cooling, the disk pack, and data recording sections are included last as an aid in understanding the overall operation.

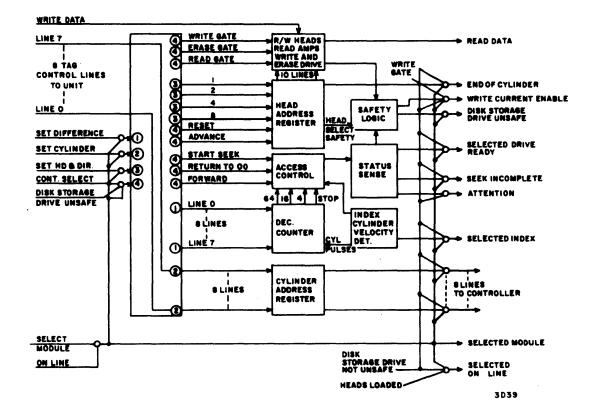


Figure 3-1. General Block Diagram

FUNCTIONS

FIRST SEEK AND UNIT SELECT

The First Seek function includes the preliminary operations the disk storage drive must perform before it can effectively respond to a Read, a Write, or a Seek command from the controller.

In preparation for the First Seek, the controller provides a sequence voltage to the disk storage drive power supply. This signal causes the power supply to perform a Power-On sequence. After the disk pack is up to speed, the carriage (mounting point of the read/write heads) is driven forward into the disk pack until the read/write heads are loaded (latched in the read/write position over the disk surfaces). When the heads are loaded, carriage motion is reversed, the read/write heads are positioned over cylinder zero of the disk pack and the spring-loaded detent pawl engages the detent gear. Ten ms later, a Selected Drive Ready signal is sent to the controller. The disk storage drive is now ready to perform a Read, a Write or a Seek (Direct or Return to Zero) operation.

SIGNAL*	FUNCTION
Tag Control Lines	Information carried by the tag control lines is coupled by four tag control signals. The influencing tag control must be known before information on a tag control line can be interpreted. The four tag controls are defined under Input Lines (below). The information coupled by each tag control is as follows:
*Throughout Table 3-1 signal levels are within the following voltage ranges: +Q = +3.5 to +0.65 vdc +L = +6.28 to +2.0 vdc -Q = -0.5 to -3.5 vdc -L = +0.3 to 0.0 vdc	

TABLE 3-1. INPUT/OUTPUT LINES

·			
Drive Bus	Set Cylinder/ Difference	Set Head and Direction	Control Select
Bit 7	1	1	Advance: A -Q pulse increments the Head Address register so that the next head in order can be selected.
Bit 6	2	2	Return to 00: A $-Q$ pulse initiates motion of the carriage to cylinder 00.
Bit 5	4	4	Head Select: A -Q pulse enables the head indicated by the Head Address register to read/write/erase.
Bit 4	8	8	Erase Gate: A -Q level enables the erase drive to pass current through the head erase coil.
Bit 3	16	Not Used	Reset: A -Q pulse sets the Head Address register to zero. This function must pre- cede a Set Head and Direction function.
Bit 2	32	Not Used	Start Seek: A -Q pulse initiates carriage positioning according to that previously specified by the Set Head and Direction tag.
Bit 1	64	Not Used	Read Gate: A -Q level enables the digital read data line.
Bit 0	128	Forward Access: absence indicates Reverse Access	Write Gate: A -Q level enables the write drivers.

SIGNAL	FUNCTION
Input Lines	
Set Difference .	A -Q pulse on this line indicates that the tag control lines contain the complement of the difference address from the controller. This address is the difference between the controller's current cylinder request and the disk storage drive's present cylinder location.
Set Cylinder	A -Q pulse on this line indicates that the tag control lines contain the controller's current cylinder request.
Set Head and Direction	A -Q pulse on this line indicates that the tag control lines contain the head select information and the cylinder access direction.
Control Select	A -Q level on this line indicates that the tag control lines contain control information.
Write Data	Carries information to be written from the controller to the disk storage drive. Information pulses are at a -L level.
Select Module	Determines which disk storage drive is to communi- cate with the controller. A -Q level causes selection.
Output Lines	
Read Data	Carriage digital information read from the disks to the controller. Information pulses are at a +L level.
Selected Drive Ready	A -Q level indicates that the positioning mechanism has stopped and the read/write heads have reached the addressed cylinder.
End of Cylinder	A -Q level is provided when the Head Address register goes from 9 to 10 as it is incremented in a multi- track operation requiring the use of sequential head addressing.

SIGNAL	FUNCTION
Seek Incomplete	A -Q level indicates that the selected disk storage drive was unable to complete a Seek operation to the point of returning a Selected Drive Ready signal to the controller within 600 ms of receiving the Seek command. A Return to Zero Seek command sent to the unit indicat- ing a seek error or a spindle drive motor Power-On/ Off sequence clears the Seek Incomplete condition, and returns the heads to cylinder 00.
Selected Module	A -Q level indicates that the respective disk storage drive unit has been selected.
Selected On Line	 A -Q level indicates that the selected disk storage drive is available. Unavailable conditions occur when: 1. Heads not loaded. 2. Disk Storage Drive Unsafe signal present. 3. The OFF LINE/ON LINE switch is in the OFF LINE position.
Selected Index	Provides a track-beginning reference mark (-Q level, 20 usec minimum) from the selected disk storage drive to the controller.
Disk Storage Drive Unsafe	A -Q level indicates that the selected disk storage drive has one or more fault conditions. These con- ditions include:
	1. More than one head selected.
	2. Write current OR non-complement write current AND no erase current.
	3. Erase current AND no write current OR no non- complement write current (if condition exists for more than 200 usec).

SKGNAL	FUNCTION		
	4. Write OR Erase Gate AND no Selected Drive Ready.		
	5. Write Gate OR Erase Gate AND Read Gate.		
	6. Write Gate AND no ac write current.		
	 Low voltage condition on disk storage ±20 vdc or +36 vdc outputs. 		
	8. Loss of ac line voltage (from controller) to disk storage drive.		
	One or more of the above conditions will:		
	1. Generate a Disk Storage Drive Unsafe signal.		
	2. Remove all write and erase current from the heads.		
	3. Disable the Set Head and Direction tag.		
	 Set all Q-type level output cards (except Disk Stor- age Drive Unsafe and Selected Module) to the +Q level. 		
	5. Light the SELECT LOCK switch/indicator.		
	The Disk Storage Drive Unsafe status can be cleared by removing power (START switch to the spindle motor and then applying power. If the OFF LINE/ON LINE switch is set to OFF LINE, the unsafe status can be cleared by pressing the SELECT LOCK switch/indicator.		
Attention	A -Q level indicates that the disk storage drive has com- pleted a seek or that a Seek Incomplete has occurred.		
Cylinder Address register	Eight lines that provide the disk storage drive's cur- rent cylinder to the controller. The register is set by a Set Cylinder function or cleared by a Return to 00 function. See Tag Control Lines for bit assignments.		
Write Current Enabled	A - Q level indicates that write current is enabled.		

DIRECT (FORWARD/REVERSE) SEEK

The Direct Seek function involves the operations that must be performed to move the read/write heads from their current cylinder to the cylinder specified by the controller.

In order to start a Direct Seek, the controller samples the Cylinder Address register to determine the present location of the read/write heads. The controller then clears the Head Address register and applies a Set Cylinder signal. The controller Set Cylinder signal sets all stages of the Decrement counter to "1". This signal enables the tag control lines containing the actual number (00 through 199) of the desired cylinder into the Cylinder Address register. Next the Set Head and Direction tag is applied which enables head select data into the Head Address register and specifies the direction of the up-coming Seek operation.

The disk storage drive must now be informed of the difference address (number of cylinders between the present and the desired cylinder). The complement of the difference address is then transferred into the Decrement counter leaving the actual number of cylinders to go in the counter. The Seek is initiated by the controller Start Seek pulse. At this point the controller may (assuming it has the capability) elect to proceed to the next unit and command a Read, a Write, or a Seek operation while the previous unit performs the assigned seek, or it may wait for the completion of the Seek by this unit. In either case the Seek continues in the same manner.

Assume that the number of cylinders (or tracks, refer to Cylinder Concept paragraph) to go is greater than 64. The access motor driving the carriage accelerates toward maximum velocity. As the carriage is moved to reposition the heads, track pulses

are supplied to the Decrement counter from a track photocell (part of Index Cylinder Velocity Detector). Each track pulse decreases the Decrement counter count by one. A speed photocell (also part of Index Cylinder Velocity Detector) provides pulses representative of the rate (in ips) at which the read/write heads are approaching the desired cylinder.

When the Decrement counter content is less than 64, the carriage is dynamically braked to a speed of 15 ips. The motor now drives at 15 ips until the number of tracks to go is less than 16. The carriage is then dynamically braked to a speed of 6 ips and continues at this speed until three tracks remain. At this point, the carriage is braked to approximately 2 ips. This speed is maintained until the desired cylinder is reached. When the selected track is reached, the spring-loaded detent pawl engages the detent gear, positioning the heads precisely over the selected track. Ten ms after the carriage stops, a Selected Drive Ready signal is supplied to the controller. This signal indicates that the disk storage drive is ready to perform a Read or Write operation.

RETURN TO ZERO SEEK

The Return to Zero Seek function allows a controller to re-establish the location of the read/write heads if for some reason the location is in doubt or if an illegal seek length caused a Seek Error signal to occur.

When a Return to Zero Seek is selected, the Decrement counter and the Head Address and Cylinder Address registers are set to zero, the Selected Drive Ready signal is dropped, and the carriage is driven toward Track 0 at 6 ips. When light is sensed by the home cell (photocell that senses when heads are outside of recordable area of disk surfaces), the access motor drive current is reversed and the carriage is driven forward until Track 0 is reached. The detent pawl is dropped and 10 ms later the Selected Drive Ready signal is supplied to the controller. The disk storage drive is now ready to perform a Seek, a Read, or a Write operation.

READ/WRITE/ERASE

The Selected Drive Ready signal indicates to the controller that the disk storage drive has completed the Seek operation and is waiting for further instruction. If the next operation to be performed is a Read or Write, the sequence of events depends on the optional addressing format (address code or sector mark) used on the disk pack.

If the address code format is used, a Write operation starts when the Control Select signal enables the Head Select signal. At this point, the Head Select signal enables the contents of the Head Address register (which has stored the desired head address during Head Set and Start Seek time). The Read Gate signal is enabled 60 usec (minimum) after Head Select.

As each record is reached, the address is read and compared, by the controller, with the address of the desired record. When comparison indicates that the address just read was the address of the desired record, the Read Gate signal is dropped and Control Select enables the Write Gate (enabling the Write Drive circuit). Data from the controller is then written on the selected record. Erase current is applied to the erase head during the Write operation to ensure proper narrowing of the recorded data track.

If the sector mark format is used, a Write operation starts with the Head Select signal. The controller then waits for a Selected Index signal after which it begins counting selected Sector signals (both signals derived from sector photocell, part of Index Cylinder Velocity Detector). When the desired number of sector signals has been counted, the Control Select enables the Write Gate and data is written in the same manner as for the address code format.

A Read operation is performed in much the same manner as a Write operation. The difference in the address code format is that the Write Gate signal is never enabled (Read Gate stays on constantly). In the sector mark format the difference is that Control Select enables the Read Gate (instead of the Write Gate) when the desired number of Selected Sector pulses has been counted.

ASSEMBLIES

POWER SUPPLY

The disk storage drive has a self-contained power supply (Figure 3-2) located behind the rear panel of the machine. The power supply is a drawer-type unit that mounts on self-lubricating, slide-borne rollers. The front panel of the unit is hinged and latched to allow access to the interior wiring and components.

The power supply is supplemented by an auxiliary power unit which is located below the main power supply on the disk storage drive chassis. Both the main power supply and the auxiliary power unit are completely solid state to provide low heat dissipation and high reliability to the operating system.

Primary input power is applied through the closed contacts of the MAIN POWER circuit breaker to the blower motors in the logic chassis and the two fan motors in the power supply, and through a power sequence relay to the spindle motor. Primary power is also applied through the MAIN POWER circuit breaker to the primary windings of ferroresonant transformer T01.

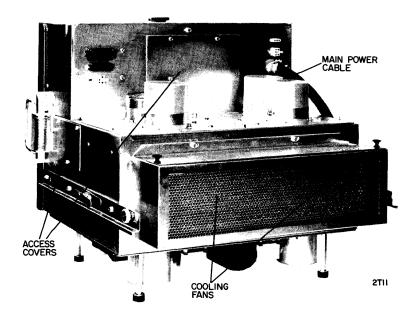


Figure 3-2. Power Supply

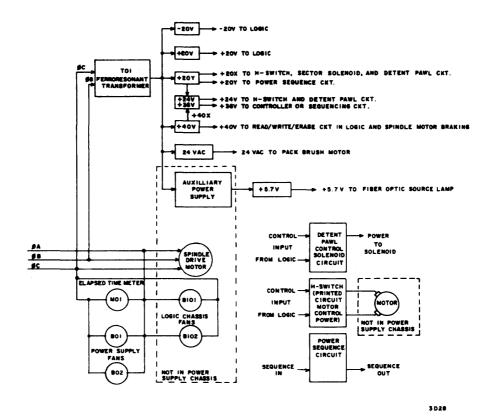


Figure 3-3. Power Supply General Block Diagram

Power applied to the primary of transformer T01 is coupled to the secondary. Since T01 is a ferroresonant transformer, the secondary voltage tends to remain constant, regardless of the voltage variation of the applied signal or the load applied to the secondary. The voltage developed across the secondary of T01 is coupled to the power supply rectifier diodes, the primary windings of transformer T02, and to the auxiliary power supply for further voltage development. Also coupled from the secondary of T01 is 24 vac to the pack brush motor.

The various dc voltages developed by the power supply are used by all major assemblies of the disk storage drive. The voltages developed (Figure 3-3) are an adjustable ± 20 vdc which is supplied to the logic chassis, ± 24 vdc and ± 20 vdc for the access motor and detent solenoid, ± 36 vdc and ± 20 vdc for the power sequencing circuit, and ± 40 vdc which is supplied to the logic write circuit and the dynamic braking circuit. These voltages are sequenced and coupled to the related circuits by a series of relays.

The auxiliary power supply develops +5.7 vdc which is provided for the fiber optics source lamp.

Refer to the related Diagrams and Wire List Manual (see Section 1) for a detailed description of the power sequence and distribution functions performed by the power supply.

LOGIC CHASSIS

All logic cards for the disk storage drive, except the read/write logic cards, are mounted on a single forced-air-cooled chassis (Figure 3-4). This assembly is located behind the front panel of the machine. The chassis is hinged, latched and equipped with a removable plate to allow access to the wiring.

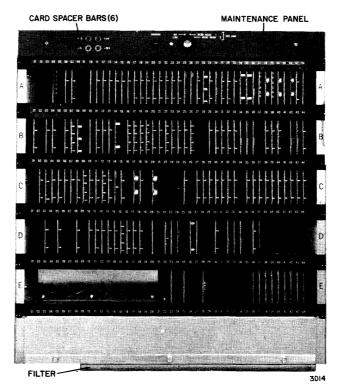


Figure 3-4. Logic Chassis

The logic chassis contains circuit cards to control printed circuit motor velocity, head positioning, head loading, head selecting, seek overlap, and data channeling. The logic chassis maintenance panel (located along top edge of chassis) contains the switch that controls the on-line/off-line status of the unit. The off-line positions of this switch are used only during maintenance situations.

Refer to the related Diagrams and Wire List Manual (see Section 1 of this manual) for a detailed description of the functions performed by the logic.

READ/WRITE LOGIC CHASSIS

The read/write logic chassis is mounted on the main deck adjacent to the actuator. The logic cards of this chassis are involved in all Read and Write operations. Access to the cards is gained by raising the top rear cover of the disk storage drive. Refer to the related Diagrams and Wire List Manual (see Section 1) for a detailed description of the functions performed by this logic.

SPINDLE AND BRAKE

The spindle and brake assembly is the physical interface between the disk storage drive and the disk pack. The conical surface of the spindle cone (Figure 3-5) mates directly with the cone-shaped opening in the center of the disk pack.

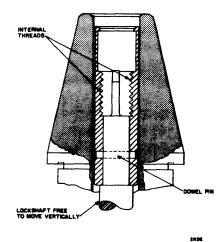


Figure 3-5. Spindle Cone

Starting in the spindle cone and running through the center of the spindle and brake assembly is the vertically free-floating lockshaft (Figure 3-6). The upper end of the lockshaft contains internal threads (Figure 3-5) that engage the external threads of a stud projecting from the disk pack. When the disk pack cannister cover handle is rotated clockwise, the spring-loaded lockshaft is pulled upward and the disk pack is pulled down. As a result, the conical surfaces of the disk pack and the spindle cone are engaged by a force of approximately 200 pounds. When the disk pack is fully engaged, a release mechanism in the cannister handle frees the cannister from the disk pack. The spindle drive pulley secures to the lockshaft. A flat belt links the spindle drive motor and the pulley. The brake assembly, consisting of the spindle lock assembly and the spindle lock disk, mounts at the lower end of the spindle (Figure 3-6). The brake holds the spindle stationary to facilitate loading and unloading a disk pack. The spindle lock assembly, consisting of a pawl, a spring, a solenoid, and a switch, is the mechanism that engages the lock disk. The spring-loaded pawl engages the disk whenever the power supply MAIN POWER circuit breaker is ON and the disk pack rotation is below pre-determined rpm (except during Power-On sequence). When the solenoid de-energizes, the springloaded plunger (on solenoid) pivots the pawl tip clear of the lock disk. The switch monitors the position of the pawl

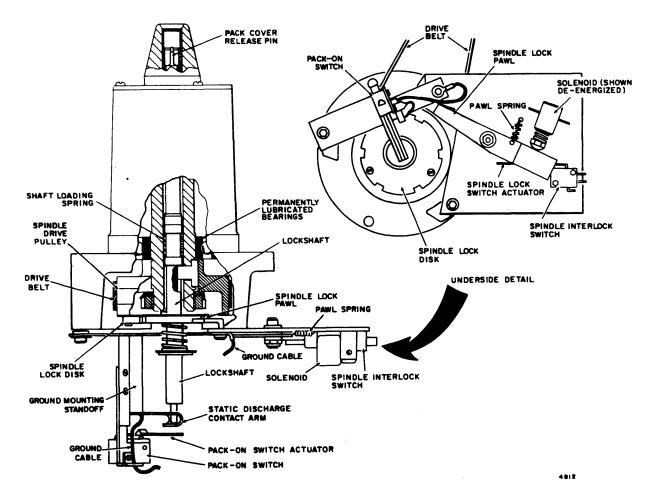


Figure 3-6. Spindle and Brake Assembly

The Pack-On switch and a static discharge contact are also mounted on the spindle base. The static discharge contact mounts on a spring arm so that it is always in contact with the tip of the lockshaft. The Pack-On switch contacts are closed only when a disk pack is installed. The contacts are opened or closed by the vertical position of the lockshaft.

SPINDLE DRIVE MOTOR

The spindle drive motor that drives the disk pack is an induction-type, 1/3-hp unit which is mounted on the lower surface of the main deck. Thermal and electrical isolators are used when mounting the motor. These isolators allow separation of the signal ground from the ac motor ground, preventing ground loops, and reducing heat transfer to the main deck. The motor drives the pulley on the spindle and brake assembly by a flat, smooth-surfaced belt. The motor brings the disk pack up to normal operating speed in approximately 4 seconds.

The temperature of the motor is monitored by a thermal protection switch. To restore operation after an over-temperature condition, the red button on the lower end of the motor must be manually reset (pressed).

SECTOR SENSOR

The sector sensor originates pulses (in combination with the disk pack) used by the power supply to sequence power application and by the controller when reading or writing data on the disk pack.

The sensor consists of a photocell containing a fiber optic and a phototransistor, the sector solenoid, and a base block. The base block mounts on the main deck and the photocell is pivot mounted on the base block. The pivoting of the photocell is controlled by the sector solenoid and a spring. When power is applied, the solenoid is energized and pivots the sector sensor so that the notched edge of the sector disk (part of the disk pack, Figure 3-7) comes between the fiber optic and the phototransistor of the photocell. When the solenoid is de-energized, the spring pulls the photocell from the edge of the disk pack. With the sensor retracted, a disk pack may be installed or removed from the spindle without danger of damage.

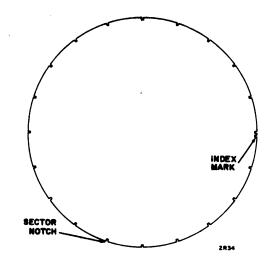


Figure 3-7. Sector Disk

The sector photocell generates output pulses each time a notch on the sector disk passes. The repetition rate of these pulses is logically decoded to determine the speed of the disk pack. Further, the output pulses of the photocell indicate the starting point of various organizational segments of the disk pack. The sector pulse indicates the start of a cylinder of data. The starting point for a cylinder is called index.

The Pack Cover-On switch is also mounted on the sector sensor base block. The switch contacts are closed only when the sector arm is fully extended into the disk pack sector disk. Closing the contacts allows the spindle drive motor to be energized and the pack to rotate.

FIBER OPTIC LAMP

The fiber optic lamp (Figure 3-8) generates light used to excite the sector, track, speed, and home photocells.

The lamp assembly consists of four fiber optics, the lamp, and the lamp housing. The fiber optics (fiber bundles of glass) transmit the light from the source lamp to the four photocells.

BRUSH ASSEMBLY

The brush assembly (Figure 3-8) is used to clean the disk pack of loose particles prior to actual loading of the disk storage drive heads.

The brush assembly consists of a motor, mechanical linkage, brushes and brush holders, reset switch, and base block. The base block mounts on the main deck and the brushes are pivot mounted on the base block. The pivoting of the brushes is controlled by the brush motor and linkage. Initiation of the brush cycle occurs when disk pack speed reaches 1900 rpm. A brush cycle consists of driving the brushes toward the center of the pack, reversing direction, and returning to the reset position. The cycle lasts approximately 52 seconds. Heads will not be loaded until brush cycle is completed.

A detent mechanism in the brush assembly allows the operator to manually retract the brushes. The next power up sequence after the brushes have been manually retracted will not contain a complete brush sweep cycle but rather an automatic reset cycle to properly reset the brush assembly. The brush cycle will be normal in subsequent power-up sequences.

ACTUATOR

The actuator assembly (Figure 3-8) loads (to the read/write position) and unloads (to prevent impact with the disk surfaces) the read/write heads, drives the heads to the correct data track at speeds proportional to the distance to be traveled, and accurately positions and holds the head over the track as data is read or written. The actuator consists of three subassemblies: the carriage, the carriage mount, and the carriage drive and positioning mechanism.

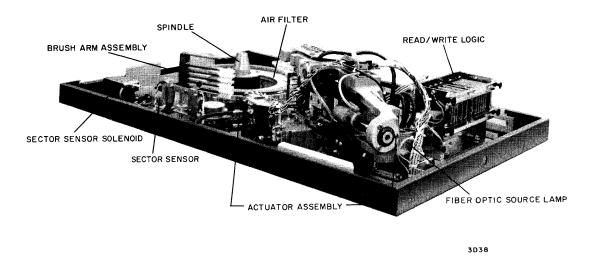


Figure 3-8. Actuator Assembly

Carriage Subassembly

The carriage subassembly (Figure 3-9) is the mounting point and the accessing mechanism for the read/write heads.

The carriage consists of a casting on which are mounted 10 head/arm assemblies, two guide plates, two clamp strips, five torsion arms, five torsion arm loading gears, the heads-loaded latch assembly, torsion rod, cam mechanism, and the carriage rack gear.

Carriage motion is derived via the carriage rack gear which is driven by the carriage drive and positioning subassembly. Total travel of the carriage is 3.3 inches, of which 1.3 inches are required to bring the carriage from the fully retracted position outward until the heads are over Track 00 of the disk pack.

Each read/write head is mounted on a supporting arm to form a head/arm assembly, Figure 3-10. The 10 head/arm assemblies are secured to the carriage (using the guide plates and the clamping strips) in two equal, adjacent, and vertical stacks.

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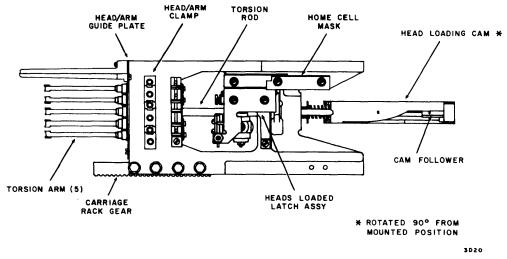


Figure 3-9. Carriage Subassembly

The torsion arms, torsion arm loading gears, and the heads-loaded latch assembly are used during head loading and unloading operations. A torsion arm is secured to the center of each torsion arm loading gear. The five gears are mounted in-line vertically (between the two rows of heads) and are driven by the center gear. When the gears turn, the attached torsion arms rotate and each tip of the T-shaped torsion arms applies a vertical (either up or down) force to the back side of one head/arm assembly. This vertical force drives the head face toward the related disk surface. The spinning disk surface creates a cushion of air between itself and the adjacent head face. An equilibrium is established between the two forces so the head flies at approximately 120 microinches from the disk surface. The heads-loaded latch assembly holds the heads in the loaded position until power is removed from the spindle drive motor or the speed of the disk pack drops below a predetermined rpm. The cam mechanism and torsion rod are also used during read/write head loading and unloading operations. These operations involve additional components that are not part of the carriage subassembly. For a detailed description of the operation, refer to the Head Loading paragraph.

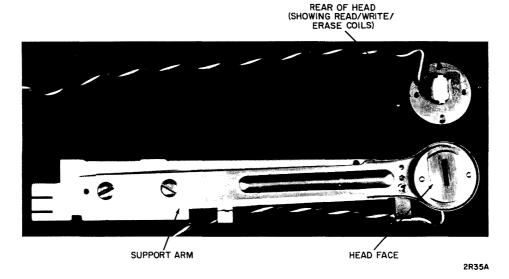


Figure 3-10. Head/Arm Assembly

Carriage Mount Subassembly

The carriage mount (Figure 3-11) is the mounting point for the carriage subassembly and the carriage drive and positioning mechanism. It consists of a casting, cantilevered and fixed bearings, shock mount, cam latch solenoid, and the home photocell assembly (home cell).

The cam latch solenoid is used during read/write head loading and unloading operations. These operations involve additional components that are not part of the carriage mount. For a detailed description of the operation, refer to the Head Loading paragraph.

The home cell consists of a fiber optic and a phototransistor mounted on a bracket which is secured to the carriage mount. When light from the fiber optic excites the phototransistor, the latter produces a signal. Mounted on the moveable carriage subassembly is the home cell mask. The mask separates the fiber optic from the phototransistor when the read/write heads are positioned anywhere within the data track area. Whenever the heads are positioned outside of the data track area, the light from the fiber optic activates the phototransistor which sends a signal to the logic chassis. The logical response to the occurence of a home cell signal depends on the operation being performed at the time.

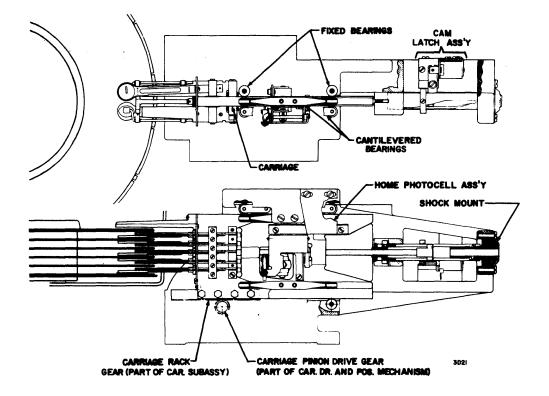


Figure 3-11. Elements of Carriage Mount Subassembly

The carriage mount casting is accurately positioned on the main deck by a dowel pin and is secured to the deck by four machine bolts. The carriage mount casting, in effect, surrounds the carriage subassembly with bearing surfaces. The carriage subassembly is supported from below by a fixed bearing (and the carriage pinion drive gear which engages the carriage rack gear). The carriage is held down on the bearing (and the gear) by cantilevered bearings at the top of the carriage. The carriage subassembly is also supported horizontally by three cantilevered bearings which are opposed by fixed bearings. The carriage may only be extended toward the disk pack or retracted from it.

Carriage Drive and Positioning Mechanism

The carriage drive and positioning mechanism (Figure 3-12) provides the mobility required by the carriage. The mechanism also keeps itself in check by providing velocity and position signals to the logic chassis. The logic decodes these signals and returns signals which cause the carriage to be driven to the desired track or cylinder at speeds that are proportional to the distance that must be traveled. When the read/write heads are positioned over the desired track, the carriage drive and positioning mechanism locks itself in place while the Read or Write operation takes place.

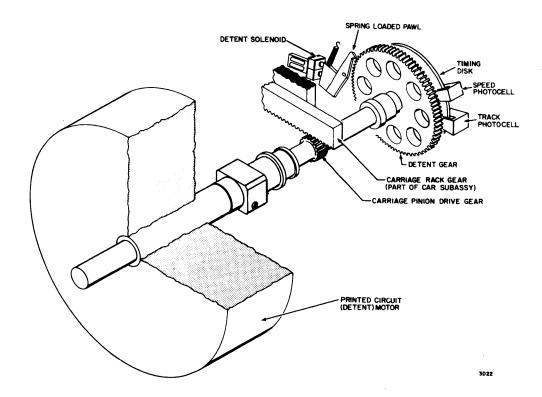


Figure 3-12. Carriage Drive and Positioning Mechanism

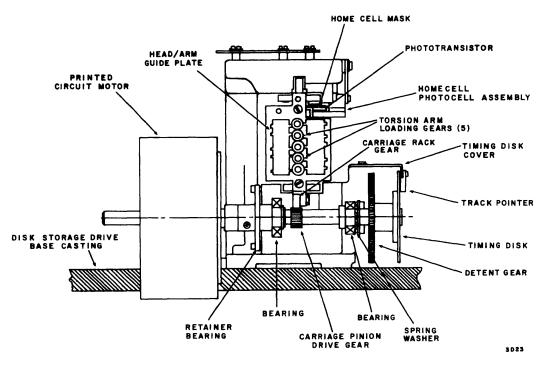


Figure 3-13. Front View Actuator Cutaway

A move command comes from the controller. The command specifies the number of tracks to be moved (entered into the Decrement counter on logic chassis) and the direction of the move (relative to the disk storage drive's current position). When a move command is received from the controller, current is supplied to the detent solenoid. Activating the solenoid causes the spring-loaded pawl to be pulled out of the detent gear. The drive and positioning mechanism is now free to move.

The move command is applied to the printed circuit motor in the form of current. The polarity of the current determines the motor's direction of rotation. The amplitude and drive time of the applied current depends on the number of cylinders of data over which the carriage must be moved. When the number of cylinders to go is greater than 64, maximum drive current is applied to the motor and no velocity limits are imposed.

As the motor is driven, the carriage pinion rotates giving forward or reverse movement to the carriage rack gear (Figure 3-13). As the carriage assembly moves, a corresponding rotational movement is imparted to the detent gear and the glass timing disk. A pair of photocells sense the slots etched on the timing disk as they pass. This glass disk is photoetched with three concentric rings of transparent slots (Figure 3-14). The outer ring contains 1020 slots, the middle ring contains 203 slots, and the inner ring contains 100 slots. Only the outer and middle ring of slots are used by the disk storage drive. The middle ring (203 slots) represents the data cylinder (200 plus 3 spares) locations on the disk pack. Each slot corresponds to a gear tooth on the detent gear. The blank position provides an area used for reversing carriage motion. As the space between each slot (track) is crossed, the fiber optic light contacts the phototransistor and produces an output pulse to the logic chassis. Each output pulse decreases the content of the Decrement counter by one.

The outer ring (1020 slots) provides pulses that are used for speed control of the printed circuit motor. The output pulses of this ring are supplied to the logic where the time between the pulses is measured to determine the speed of the motor and hence the carriage. The greater number of slots is required for speed sensing to maintain stability at lower speeds.

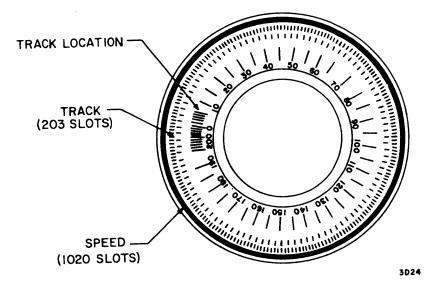


Figure 3-14. Timing Disk

The fourth ring of markings (numbered) on the disk indicates the track number at which the carriage is located. The track location is read at the indicator index that overhangs the disk.

When a maximum carriage movement of 200 cylinders is required, full current is applied to the motor, accelerating the carriage at a maximum rate. The carriage continues to accelerate until the Decrement counter indicates less than 64 cylinders to go. At this time the carriage velocity is approximately 35 ips.

When the carriage has less than 64 cylinders to go, the current applied to the motor is reversed, dynamically braking the motion of the carriage to 15 ips. When the speed is reduced to 15 ips, the motor is servoed (current is applied to the motor in pulses so that the average current sustains the carriage at the selected speed). The servoing of the printed circuit motor continues until the Decrement counter indicates less than 16 cylinders remaining to the selected cylinder. At this point, the carriage is again dynamically braked. When the carriage has been slowed to 6 ips, the printed circuit motor is servoed until the Decrement counter indicates remaining to the desired cylinder. The carriage is again dynamically braked, reducing the forward speed of the carriage to 2 ips. The carriage continues to be moved forward at 2 ips until the selected cylinder is reached.

When the trailing edge of the next to last track pulse is sensed, the Stop command is initiated within the logic. This command is not completed until the leading edge of the last track pulse is detected. The trailing edge of the last track pulse causes the logic to produce a Detent command. The Detent command drops the current to the detent solenoid. The detent pawl is spring-loaded so that when the solenoid is de-energized, the spring pulls the pawl to the detent gear. When the pawl engages the gear, it holds the carriage securely on the selected cylinder.

When the Detent command occurs and the pawl begins to drop, a delay is initiated. During this delay time, the gear continues to rotate so that the falling pawl is approximately one-third of the way over the selected gear tooth when the delay is timed out. The end of the delay causes a 2 ms high-current Dynamic Braking pulse to be applied to the motor. This pulse completely stops the motor (and the carriage) so that the pawl tip engages the gear very near to the center of the selected slot. A settling time of 10 ms (beginning at the Detent command) is allowed for all vibration to be damped before a Selected Drive Ready signal is sent to the controller. This signal indicates that the disk storage drive is ready for a Read or Write operation.

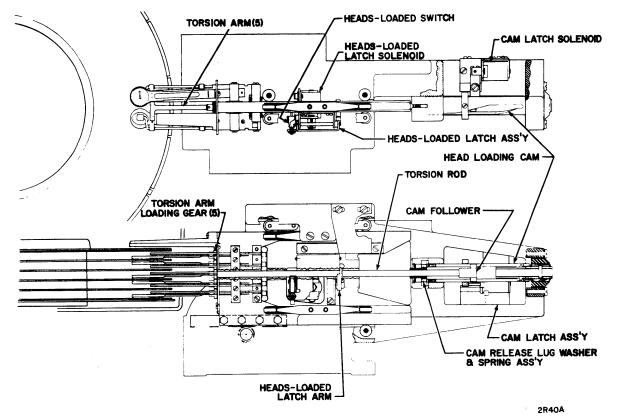


Figure 3-15. Head Loading Components

Head Loading

Head loading amounts to applying spring pressure to the back of the read/write head so the aerodynamically shaped head face approaches the related disk surface. When the cushion of air that exists on the surface of the spinning disk is encountered, it resists the further approach by the head. Spring pressure is designed to just equal the opposing cushion pressure (function of disk pack rpm) at a height of approximately 120 microinches; as a result the head flies. However, if the spring pressure exceeds the cushion pressure (as would happen if the disk pack lost enough speed), the heads will stop flying and contact the disk surface. This could cause damage to the head as well as the disk surface.

The read/write heads must be loaded to the disk surfaces before exchanging data with the controller. The heads must be released from this position (unloaded) and driven clear of the disk pack when power is removed to the unit or the disk pack velocity

falls below a predetermined rpm. The actuator components involved in these operations are identified on Figure 3-15.

When the unit is initially energized, the carriage subassembly is in the retracted position (heads clear of the disk pack edge) and the heads are unloaded. However, as the power to the unit is sequenced up, the disk pack speed is brought up to 2400 rpm. When the pack is up to 1900 rpm, a 52-second delay is allowed for the pack to purge the air in the shroud area and for the brush assembly to complete a clean cycle of the disk pack. This action assists in maintaining clean disk surfaces and reduces the possibility of disk scoring.

Once the 2400-rpm speed is reached and the pack has purged the surrounding air, the machine automatically proceeds to load the heads by performing a First Seek operation. First the spring-loaded pawl is pulled out of the detent gear by energizing the detent solenoid. When the pawl tip is out of the gear, the printed circuit motor starts driving the carriage toward the spindle at 6 ips.

With the heads unloaded, the torsion rod holds the cam follower at such an angle that the head loading cam is aligned with two notches in the carriage shock mount. The head loading cam is forced into these notches by the cam latch solenoid when the carriage starts moving forward.

With the head loading cam held (to stop rotation) by the notches, the cam follower is forced to ride the cam sides and rotates the torsion rod 60 degrees. Rotation occurs as the carriage is moved forward.

The 60-degree rotation imparted to the torsion rod by the cam follower turns the middle torsion arm loading gear. The five gears are meshed and mounted vertically so that as the middle gear rotates all the gears rotate (Figure 3-16).

A torsion arm mounted in the center of each gear is connected between each pair of heads. By rotating each arm, one head is forced down toward a disk surface while the other head is forced upward toward a disk surface. Rotating the five gears and torsion arms (each accommodating two heads) results in the loading of all ten heads. At the end of the 60-degree rotation, the heads are loaded and the heads-loaded latch arm engages a catch in the heads-loaded latch assembly. The catch is enabled by the latch solenoid when the pack is up to speed.

When the heads have been loaded, the heads-loaded switch closes and the head loading cam is disengaged by de-energizing the cam latch solenoid. The heads remain loaded as long as the heads-loaded latch solenoid is energized. If power to the machine is lost or the disk pack speed is not properly maintained, the solenoid is de-energized.

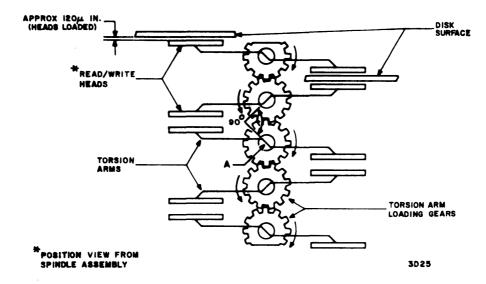


Figure 3-16. Head Loading Mechanism

This releases the latch arm and removes torsion arm pressure to the back side of the heads causing the heads to move (vertically) away from the disk surfaces. An air damper device cushions the release of the heads.

When the heads are loaded, the First Seek operation generates a Reverse Motion command. This causes the carriage to be driven in the reverse direction at 6 ips. The carriage is retracted until a home cell signal is sensed at which time a Forward Motion command occurs, causing the carriage to be driven forward at 2 ips to cylinder 00 where the spring-loaded pawl is dropped.

CABINET COOLING

Filtered air is distributed throughout the disk storage drive to clean and cool the various components (Figure 3-17).

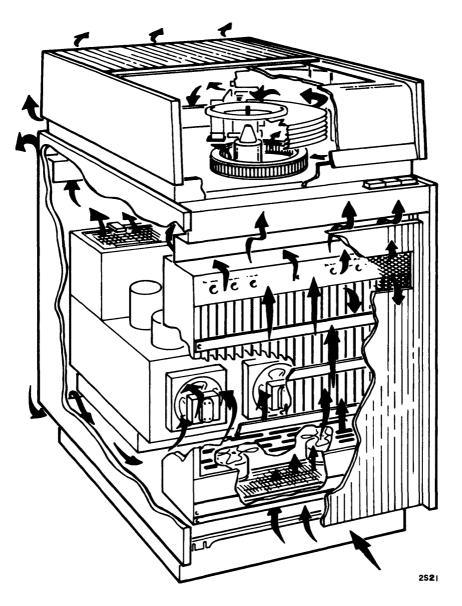


Figure 3-17. Cabinet Cooling

The logic chassis is cooled by filtered air from two fans. The front panel of the unit allows air to enter between the lower position of the panel and the main frame. Mounted over this opening is the logic chassis air intake through which air is drawn, filtered, and then forced upward between the cards of the logic chassis. The warm air is exhausted through openings in the top of the logic chassis and channeled out of the disk storage drive between the top of the front panel and the main frame and the grill in the front panel. The power supply is also cooled by filtered air from two fans. Air enters between the lower portion of the rear panel and the main frame. This air is drawn along the bottom of and to the rear of the power supply by the fans. The air is then forced through the power supply, exhausted through a grill in the top of the power supply, and channeled out (via a metal deflector) through the openings between the top of the rear panel and the main casting and the rear panel grill.

The spinning disk pack acts as an air pump, drawing air through the filter at the base of the disk pack on the main deck and through the nylon mesh filter in the base of the disk pack. This air is channeled up through the hub of the disk pack and dispersed outward between the disks. Consequently, all air in and around the disk pack surfaces is filtered air. This prevents head and disk surface damage due to foreign particle accumulation. Whenever the disk pack is set in motion, a 52-second purge time (starting when disk pack is up to 80 percent of maximum speed) is allowed to clean the disk surfaces before the heads are loaded. The filtered air blown across the disk surfaces is forced through the shroud opening for the head/arm assembly. The air is exhausted through an opening between the lower edge of the top rear cover and the main frame and through slotted holes at the back of the top rear cover.

DISK PACK ASSEMBLY

The disk pack is the recording medium for the disk storage drive. The disk pack consists of six 14-inch, magnetic-oxide coated disks that are center-mounted on a vertical shaft. Eight recording surfaces are gained by using both surfaces of the four interior disks. Only the inner (relative to original four) surfaces of the top and bottom disk are used, yielding a total of 10 recording surfaces. The outer surface of the top recording disk is covered by a seventh disk which provides stability and protection only. A larger disk at the bottom of the assembly with notches around the circumference, divides the disk pack into organizational pieces called sectors. The disk pack mounts on and is driven by the spindle of the disk storage drive. Each disk pack has a two-piece dust cover (plastic cannister with bottom). The handle of the plastic cannister contains a mechanism to release or lock (depending on direction of rotation) the disk pack on the spindle during removal or installation.

When the disk pack is not installed, both dust covers should be in place. After the disk pack is installed, the front cover of the disk storage drive should be kept closed.

DATA RECORDING

CYLINDER CONCEPT

The 10 recording surfaces of a disk pack are numbered 00 through 09 from top to bottom. Ten read/write heads are mounted on the carriage assembly in two equal, adjacent, vertical stacks. Each head is oriented so as to service one disk surface. Each head is identified by the number assigned to the disk surface it services. By moving the carriage assembly, the actuator can position the 10 heads (as a group) at 200 discrete positions (tracks) on the disk surfaces. These 200 tracks are numbered 00 through 199 from the outer edge of the disk pack toward the spindle. Assume now that the disk pack is rotating and that the actuator is detented so that the heads are positioned over track 50 of the disk surfaces. Then a cylinder (Figure 3-18) is defined as the total data available to all heads during one revolution of the disk pack. In this example there would be 149 additional cylinders of data available if the heads were moved one track at a time toward the spindle (forward), and 50 additional cylinders if the heads were moved in the reverse direction from their present position.

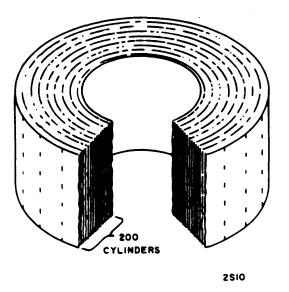


Figure 3-18. Cylinder Concept

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SECTION 4

INTER FACE

INTERFACE

SYSTEM CABLING

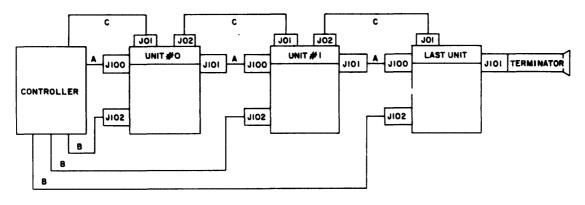
The disk storage drive units are designed so that eight units may be connected to each controller. The cabling required to accomplish the intercabling is shown in Figure 4-1.

The cabling arrangement shown for cables A and C is called "daisy chaining". Voltages and signals of these two cables are coupled through intervening units during exchanges between the controller and the active disk storage drive. Voltages and signals of cable B are exchanged directly between the controller and the active unit and hence are not termed "daisy chaining".

To effect system operation, each machine must be connected to the controller and the MAIN POWER circuit breaker at each unit must be set to ON. If any one of the machines is not plugged in or the MAIN POWER circuit breaker is OFF, subsequent machines cannot be cycled up or used (Figure 4-2).

CAUTION

Do not turn the power supply MAIN POWER circuit breaker of an inactive disk storage drive on or off while another disk storage drive is reading or writing. This may cause the controller or the disk storage drive recording surface to make errors.



NOTES:

A - SIGNAL CABLE - CONTROL FUNCTIONS

B - DC CABLE- ±3 VDC, +6 VDC, -36 VDC, READ AND WRITE DATA, ATTENTION, SELECTED MODULE, AND MODULE SELECTED

C - AC CABLE-AC VOLTAGES

Figure 4-1. System Intercabling Diagram (Daisy Chain)

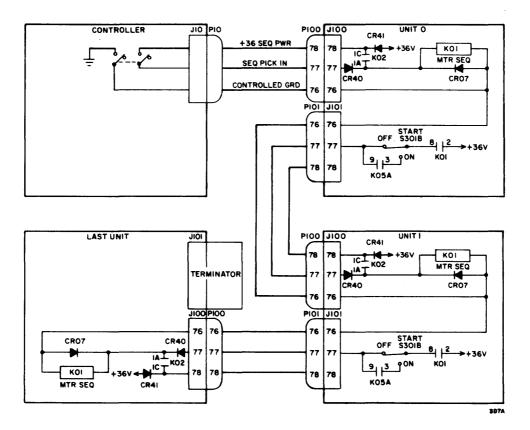


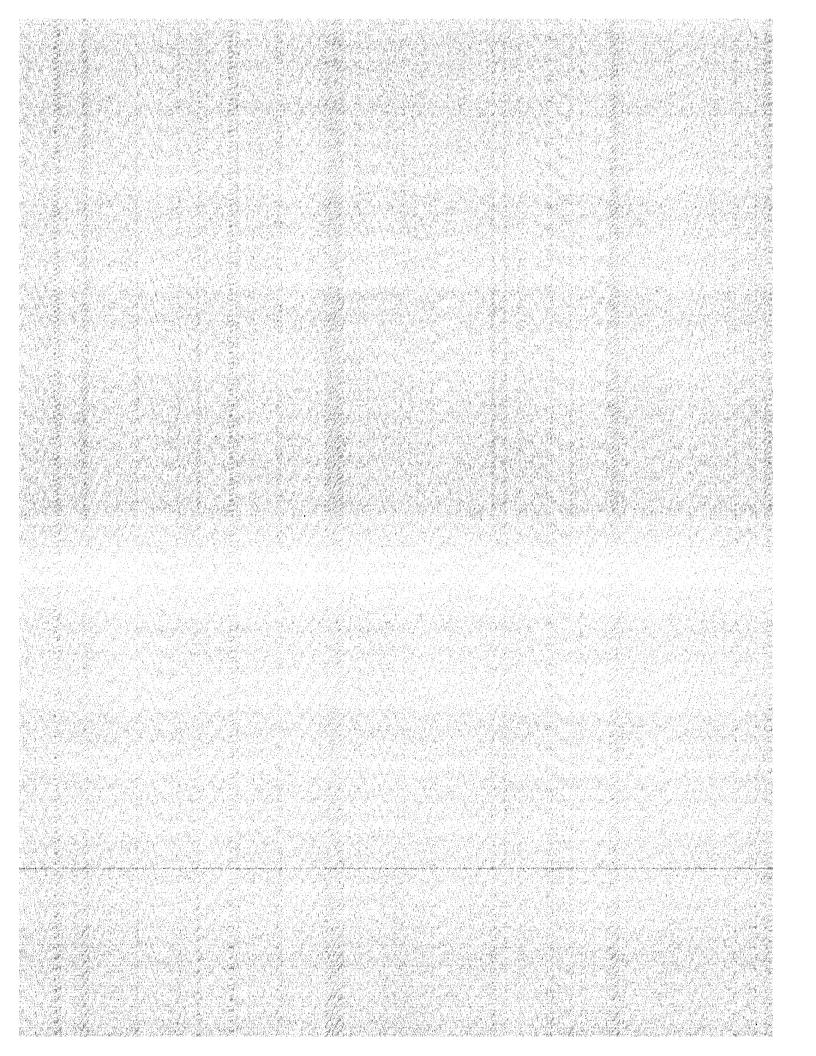
Figure 4-2. System Power-On Sequencing Circuit

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SECTION 5

PREVENTIVE MAINTENANCE



PREVENTIVE MAINTENANCE

INTRODUCTION

The performance of the disk storage drive (Figure 5-1) depends upon a carefully planned and executed program of preventive maintenance, proper corrective maintenance when required, and recording of all information pertinent to the maintenance and operation of the unit. This program, if followed, will ensure optimum performance and maximum equipment up-time.

This Section contains the procedures for scheduled preventive maintenance on an hoursused basis except for the read/write heads and the disk pack (see Caution). It is essential that scheduled preventive maintenance be performed at the specified intervals even though the unit is operating satisfactorily. Scheduled preventive maintenance procedures should not be performed other than at the intervals indicated. The elapsed time meter (Figure 5-2) should be used to check these intervals. Keep an accurate log of all pertinent maintenance and operation information.

CAUTION

Be especially attentive to the following paragraphs relating to contamination of the heads and disk surfaces. Failure to observe the cleaning procedures outlined could cause serious scoring of the heads and recording surfaces through build-up of foreign particles on these areas.

HEADS

Heads must be cleaned once a month. Dust and dirt present on the disks or the read/ write heads can damage both the heads and the disks. The air is kept clean and any loose dust is evacuated when pressurization of the pack and actuator is positive. Dust does not accumulate under these conditions. However, when the disk storage drive is off or a disk pack is in storage, dust and dirt can accumulate on the heads and the recording surfaces and possibly cause scoring of the heads.

DISK PACKS

Clean disk packs once a month and at any time the heads show an oxide buildup or a specific disk pack causes read errors. The disk pack should not remain on unpowered units and should have the bottom cover secured immediately upon removal from the disk storage drive. This cover should remain secured until the disk pack is again mounted on the spindle. Both top and bottom covers should be cleaned periodically and care should be taken so that they do not become a source of contamination.

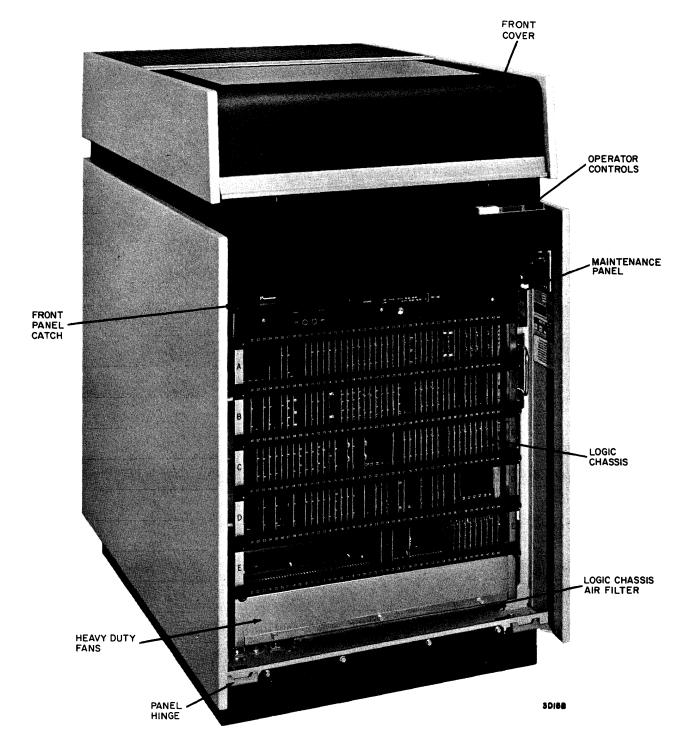


Figure 5-1. Disk Storage Drive, Front View

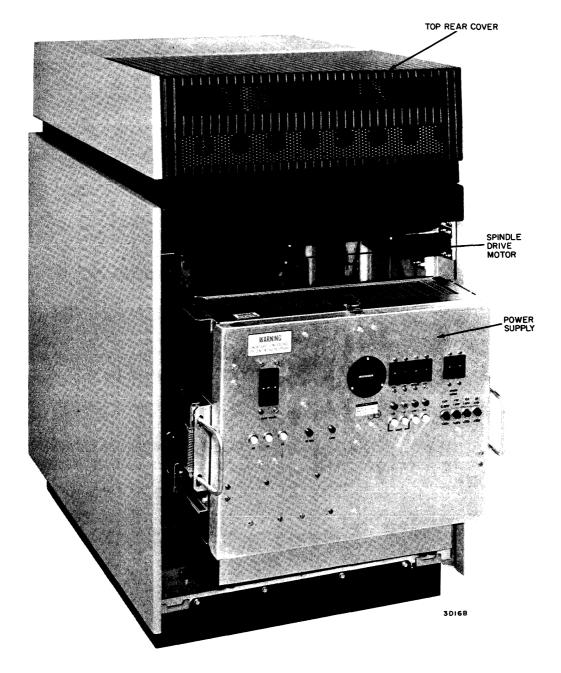


Figure 5-2. Disk Storage Drive, Rear View

PREVENTIVE MAINTENANCE PROCEDURES

500 HOUR MAINTENANCE

Inspect Heads for Scratches

CAUTION

Use extreme care not to damage the heads with the dental mirror.

- 1. Using a dental mirror, inspect the head for scratches.
- 2. If the head has a series of grooves across the shoe face, the head has been flown across a disk surface which contains an imbedded particle. Clean the suspected disk pack.

NOTE

The presence of the grooves does not necessarily mean an unusable head. When the surface of a head contacts a particle, it is possible for a burr to be found on the head or for a particle to be partially imbedded in the ferrite. If this protrusion is greater than the flight height, it scratches the disk. Refer to head replacement criteria.

- 3. Carefully check a scratched head for protrusions by drawing a dry, lint-free gauze on a plastic spatula across the head.
- 4. Check the functioning of the head with trial Read and Write operations.

Inspect Heads for Oxide Buildup

CAUTION

Use extreme care not to damage the heads with the dental mirror.

- 1. Using a dental mirror, inspect the heads for oxide. The reddish brown oxide buildup is readily discernible on the head.
- 2. Proceed with the head cleaning if required.

Clean Read/Write Heads

- 1. Wrap clean, lint-free gauze around a plastic spatula and dampen with 91 percent isopropyl alcohol.
- 2. Support the back of the read/write head with a second spatula.

CAUTION

Do not touch or breathe on heads; skin acids etch head surfaces and moisture causes dust to accumulate and rust to form. Wipe heads carefully; residue or dirt scores heads and disks when unit is returned to operation. Data is lost in scored areas.

3. Thoroughly wipe the face of each read/write head with the isopropyl alcoholdampened gauze.

CAUTION

Use extreme care not to damage the heads with the dental mirror.

4. Inspect the head surface with a dental mirror to be sure that the surface is free of dirt and scratches. Repeat cleaning if necessary.

Head Replacement Criteria

Heads of the disk storage drive have been designed so that they should not require replacement if given proper preventive maintenance and care. If a head requires replacement, refer to Section 6 of this manual. Heads are defective and need replacing if any of the following conditions exist:

- 1. Consistent oxide buildup on the head, indicating repeated head/disk impact.
- 2. Concentric scratches on the disk surface. Inspect the head for imbedded particles.
- 3. An audible ping indicating that the head is hitting the disk surface.

Clean Disk Pack

NOTE

If the disk pack to be cleaned is on an energized disk storage drive, position the Spindle Lock Disable switch located directly below the operator panel to OFF and proceed to step 2.

- 1. Mount the disk pack to be cleaned on a de-energized disk storage drive.
- 2. Wrap clean lint-free gauze around a plastic spatula and dampen (do not soak) with 91 percent isopropyl alcohol.
- 3. Insert the gauze wrapped spatula between the disks and manually rotate the disk pack. Apply downward pressure to clean the lower disk surfaces then apply upward pressure to clean the upper disk surfaces.
- 4. Withdraw the gauze wrapped spatula while the disk pack is still rotating.
- 5. Wrap dry lint-free gauze around another spatula and repeat step 3.
- 6. Dampen the gauze with 91 percent isopropyl alcohol and wipe the exposed outer surface of the disk pack.
- 7. Switch the Spindle Lock Disable to ON. Remove the disk pack from the spindle.
- 8. Clean the disk pack spindle mounting area and disk pack bottom cover throughly with 91 percent isopropyl alcohol-dampened gauze.
- Inspect the nylon gauze filter in the bottom of the disk pack for dirt or discoloration. Remove the O-ring securing the filter and install a new filter (Control Data 45546500), securing it with the original O-ring.
- 10. Replace the disk pack in the container and store until required for use.

Disk Pack Visual Inspection

- 1. Position the Spindle Lock Disable switch located directly below the operator panel to OFF.
- 2. Open the front cover and inspect the disk pack.
- 3. Inspect each disk surface for scratches.
- 4. Comet-like scratches indicate that a particle has been caught and dragged between the head and the disk surface. The particle is usually embedded in the disk. Proceed with disk pack cleaning. If the particle cannot be dislodged, the disk pack must be replaced.
- 5. Scratches that are concentric and have spirals connecting them indicate that the head contains an embedded particle, a burr on the shoe face, or an improperly mounted head. Check the head related to that disk surface.
- 6. Switch the Spindle Lock Disable to ON.

Criteria for Disk Pack Replacement

This disk pack is designed to last the lifetime of the equipment. Replacement of the disk pack is required only if excessive runout (see Disk Pack Runout Check, Section 7) is encountered or physical damage to the pack results in the loss of recording ability. This physical damage includes:

- 1. Damage to the disk pack resulting in broken disk. If a disk is bent, refer to Disk Pack Runout Check, Section 7.
- 2. Gouged or scored disk surface causing the loss of stored data.
- 3. Imbedded particles in a disk surface that cannot be removed by cleaning and are causing damage to the heads.

Inspect Brushes

- 1. Open and latch the disk storage drive top rear cover.
- 2. Inspect the brush assembly for brush wear (Figure 5-3). If a brush is worn so that it is not compressed when it enters the disk pack, it should be replaced.

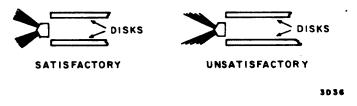


Figure 5-3. Brush Condition

- 3. Remove the worn brushes by gently snapping the brush out of the brush holder.
- 4. Align the flat of the replacement brush with the key of the brush holder and insert into place.

Clean Shroud

- 1. Open the front cover and remove disk pack.
- 2. Dampen a piece of gauze with 91 percent isopropyl alcohol.
- 3. Wipe the shroud and the spindle carefully. Remove all dirt and smudges.

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- 4. Inspect for any metal or dust particles remaining on, around, or near shroud.
- 5. Remove these loose particles using the sticky surface of adhesive or masking tape.

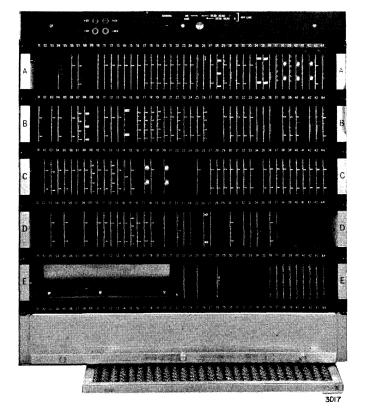


Figure 5-4. Air Filter at Bottom of Logic Chassis

Clean Air Intake Filters

- 1. Remove the air filters from the bottom of the logic chassis (Figure 5-4) and at the rear of the power supply (Figure 5-5).
- 2. Agitate the filter in mild detergent solution. Rinse the filter in the reverse direction using a low-pressure nozzle.
- 3. Shake any excess water from the filter and allow a reasonable drying time before proceeding.

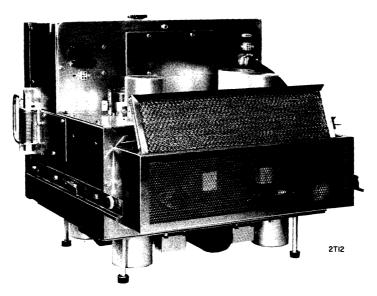


Figure 5-5. Air Filter at Rear of Power Supply

4. Spray the filter thoroughly with Filter Coat (Research Products Corp) to restore filtration ability.

Lubricate Rack, Pinion Gear, and Cam

Saturate the oil wick assembly on the carriage rack gear with oil (Texaco All-Purpose EP Lubricant, Control Data 95020400). Do not add oil to the extent that it runs out of the wick assembly. Add one drop of oil to the pinion. Add one drop of oil to the upper and lower forward sloping surfaces of the cam. Refer to Figure 3-11.

Lubricate Detent Gear

Carefully clean the detent gear (Figure 3-12) using a lint-free cloth. Apply a thin coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400).

Lubricate Cam Release Lug Washer

Using the customer engineering syringe (or equivalent), carefully lubricate the two cams on the cam follower side of the cam release lug washer (Figure 3-15) with 1 drop of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400).

1000 HOUR MAINTENANCE

Lubricate Carriage Rollerways

Carefully clean the carriage rollerways using a lint-free cloth. Apply a thin coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400), wiping off any excess.

Lubricate Torsion Arm Loading Gears

Clean the gears carefully using a lint-free cloth. Apply 1 drop of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400) to each gear.

2000 HOUR MAINTENANCE

Lubricate Disk Pack Locking Screw and Spindle Lockshaft

Wipe the disk pack locking screw (in disk pack) and the spindle lockshaft (in the spindle) using a lint-free cloth to remove contaminated lubricant. Repeat procedure with clean cloth until the surfaces are clean. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400) to the clean surfaces.

Clean Base of Machine and Covers

- 1. Dampen a lint-free cloth with 91 percent isopropyl alcohol.
- 2. Carefully wipe the sides and base to remove dirt and dust accumulation. Use a new cloth as often as necessary.
- 3. Stains or heavy dirt accumulation may be removed using soap and water.

Replace Disk Pack Air Filter

- 1. Remove the disk pack.
- 2. Raise and latch the top rear cover.
- 3. Remove the four phillips screws holding the inner shroud to the main casting standoffs. Carefully remove the shroud.

- 4. Remove the disk pack filter and replace.
- 5. Visually center the replacement filter (Control Data 45467300).
- 6. Install the shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.
- 7. Lower the top rear cover.

Check Disk Storage Drive Leveling

Check the inclination of the disk storage drive unit by placing a level on the top of each of the supporting sides. If the inclination is more than 3 degrees, the symmetry of the forward and reverse carriage move times may be lost. Level the machine as required by adjusting the four screw-type feet.

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SECTION 6

MAINTENANCE PROCEDURES

MAINTENANCE PROCEDURES

GENERAL

The maintenance procedures for the disk storage drive are provided in the form of replacement and adjustment procedures. It is recommended that maintenance personnel read the entire procedure prior to performing the replacement or adjustment.

Refer to Section 1, Special Tools, for a list of special tools required during the performance of maintenance procedures.

CAUTION

During some of the procedures of this section, it is necessary to operate the disk storage drive (disk pack installed) with the top covers open. Operating in this configuration for a period in excess of 2 hours may damage the read/write heads and disk pack. Operating in this configuration for a period of 1 hour necessitates cleaning the heads and disk pack according to Section 5.

REPLACEMENT

SPINDLE LOCK OR DRIVE BELT REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover and remove the front panel. Swing the logic chassis out.
- 3. Proceed to step 4 for spindle lock replacement or to step 5 for drive belt replacement.

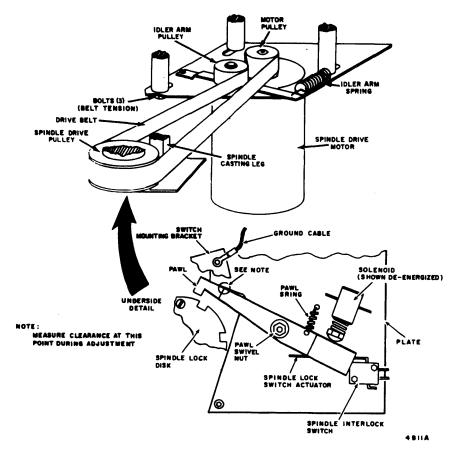


Figure 6-1. Lock and Belt Adjustment

- 4. Replace the spindle lock disk according to step a. Replace any other spindle lock part according to steps b, c, and d.
 - a. To replace the spindle lock disk, remove the two socket head screws securing the switch mounting bracket to the base of ths spindle assembly. Carefully lower the assembly clear of the spindle. Remove the three screws and washers securing the spindle lock disk to the bottom of the pulley. Install the replacement disk with the original three screws and washers. Install the switch mounting bracket with two socket head screws. Use two washers between the bracket and the spindle casting

leg at the right hand end of bracket (use one washer between the left-hand screw and the bracket). Secure the loose end of the ground cable with the screw in the right-hand end of the bracket. Proceed to step 6.

- b. To replace the spindle lock solenoid, the pawl, or the spindle lock switch, tag and then disconnect the four electrical connections to the spindle lock assembly. Remove the two socket head screws that secure the assembly to the base of the spindle. Slide the assembly clear of the spindle. Replace the faulty component according to the original installation.
- c. Tighten the screw/nut pivot through the pawl until all play is removed, but make certain that the pawl is free to pivot. Check that the acorn nut is completely threaded on to the armature of the solenoid, and that the armature spring is in place. Hook the extension spring between the pawl and the grooved pin. Loosen the screws securing the solenoid. Using a 6-inch scale, check the $14/64 \pm 1/64$ inch gap between the pawl and the mounting plate (Figure 6-1). With the solenoid armature retracted and the acorn nut against the pawl, tighten the solenoid mounting screws. Remove the shim or feeler gage and check that the pawl/plate gap is correct.
- d. Install the spindle lock assembly on the base of the spindle. At the mounting point used in common by the spindle lock assembly and the switch mounting bracket, the spindle lock assembly faces against the spindle casting. Restore the four electrical connections to the lock assembly. Proceed to step 6.
- 5. Replace the drive belt as follows:
 - a. Disconnect the spring to the drive belt idler arm. Lift the belt clear of the motor pulley.
 - b. Remove the two socket head screws securing the switch mounting bracket to the base of the spindle assembly. Carefully lower the assembly clear of the spindle.
 - c. Thread the belt between the pawl tip and the spindle lock disk. Allow the belt to fall free of the spindle assembly.

- d. Place a loop of the replacement drive belt around the spindle drive pulley so that when the belt is extended toward the motor pulley, it passes on both sides of the spindle casting leg between the spindle drive pulley and the motor pulley. Place the drive belt over the motor drive pulley. Make certain that the belt is not twisted and that the smooth surface of the belt faces against the pulleys.
- e. Note the free length of the idler arm spring. Connect the spring to the idler arm. The spring must extend $1-1/4 \pm 1/4$ inch from its free length when connected to the idler arm. Loosen the three bolts securing the drive motor assembly to the bottom of the main deck and reposition the drive motor assembly to meet the requirement.
- f. Assemble the switch mounting bracket to the base of the spindle with two socket head screws. Use two washers between the bracket and the casting leg at the right-hand end of the bracket (use one washer between the lefthand screw and the bracket). Secure the loose end of the ground cable with the screw in the right-hand end of the bracket.
- 6. Connect the unit power cord. Set the power supply MAIN POWER circuit breaker to ON. Place a disk pack on the spindle and tighten it in place. Set the MAIN POWER circuit breaker to OFF and disconnect the power cord.
- 7. Using a feeler gage, check that the gap between the static discharge contact arm and the Pack-On switch actuator meets the requirement of Figure 6-2. Loosen the two screws securing the microswitch bracket to the switch mounting bracket and slide the bracket vertically to attain the correct dimension. Tighten the screws. Make certain that the static discharge contact is aligned to the lockshaft according to Figure 6-2. The contacts will be damaged during operation if not properly aligned.

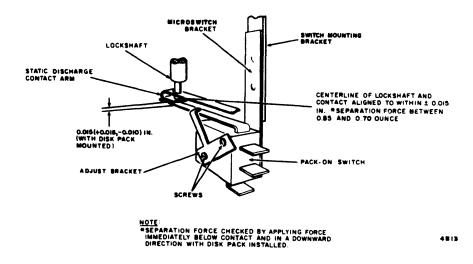


Figure 6-2. Pack-On Switch Adjustment

PACK-ON SWITCH OR STATIC DISCHARGE CONTACT REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Remove the disk drive front panel and swing the logic chassis out.
- 3. Note or tag all electrical connections to the Pack-On switch and the static discharge terminals. Disconnect each connection.
- 4. Remove the two screws and four washers holding the microswitch bracket to the switch mounting bracket.
- 5. Proceed to step 6 for Pack-On Switch Replacement or step 7 for Statis Discharge Contact Replacement (Figure 6-2).
- 6. Replace the Pack-On switch as follows:
 - a. Remove the two screws, three washers, and the nut securing the adjust bracket, the ground cable, and the faulty switch to the microswitch bracket.

- b. Apply 2 drops of Loctite, Grade C, to the screw threads. Loosely assemble the adjust bracket, the ground cable, and the replacement switch to the microswitch bracket.
- c. Position the adjust bracket to keep the switch actuation arm downwardtravel (before switching) to an absolute minimum. Make certain, however, that this position allows switching to occur again when the switch actuation arm moves upward. Tighten the screws.
- d. Proceed to step 8.
- 7. Replace the static discharge contact as follows:
 - a. Remove the screw and shims (if used) securing the static discharge contact arm to the bottom of the ground mounting standoff.
 - b. Install the replacement static discharge contact arm (use all shims present on the faulty contact arm). Make certain that the contact and the lockshaft center lines are aligned and that the contact arm and the lockshaft are not in contact. Tighten the screw to secure the contact arm.
- 8. Loosely assemble the microswitch bracket to the switch mounting bracket with two screws and four washers.
- 9. Restore the electrical connections at the Pack-On switch and the static discharge contact terminals.
- 10. Connect the unit power cord. Set the power supply MAIN POWER circuit breaker to ON. Place a disk pack on the spindle and tighten it in place. Set the MAIN POWER circuit breaker to OFF and disconnect the power cord.
- 11. Using a feeler gage, check that the gap between the static discharge contact arm and the Pack-On switch actuator meets the requirement of Figure 6-2. Slide the microswitch bracket vertically to attain the correct dimension. Tighten the screws.
- 12. Use a push-pull gage (12210797) to check that the force required to separate the contacts is as shown on Figure 6-2. If the separation force exceeds the maximum allowable, add shims as required between the ground mounting standoff and the contact arm. Shim part numbers are available in Illustrated Parts List.

BRUSH MOTOR REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk storage drive top rear cover.
- 4. Remove the four screws and washers holding the plastic shroud. Set the shroud aside.
- 5. Disconnect the J11-P11 connection.
- 6. Remove the two screws and washers securing the brush assembly to the main deck. Remove the assembly from the disk storage drive.
- 7. Note the motor leadwire connections and disconnect them.
- 8. Loosen the two setscrews in the brush motor link. Disconnect the link from the motor shaft.
- 9. Remove the two screws securing the motor to the brush assembly base. Remove the motor.
- 10. Using two screws and 2 drops Loctite, Grade C, mount the replacement motor on the brush assembly base.
- 11. Restore the leadwire connections according to step 7.
- 12. Position the brush holder against the rubber stop (Figure 6-3).
- 13. Connect the brush motor link to the motor shaft. Align the linkage as it appears in Figure 6-4. Tighten the two setscrews.
- 14. Mount the brush assembly on the disk storage drive with two screws and washers. Do not tighten.
- 15. Connect J11 to P11.
- 16. Connect the disk drive power cord. Set the MAIN POWER circuit breaker to ON.
- 17. Install a disk pack.
- 18. Align the curved edge of the brush holder parallel to the disk pack. Make certain the brush holder is against the rubber stop.
- 19. Manually swing the sweeper arms to the extreme position to ensure that the ends of the brushes do not hit the hub of the disk pack.

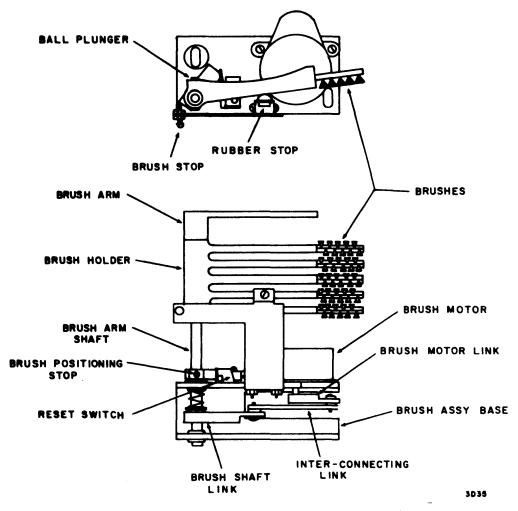


Figure 6-3. Brush Assembly

- 20. Tighten the two brush assembly mounting screws.
- 21. Pull upward on the rear cover interlock switch.
- 22. Press (to light) the START switch. The brushes should make one 52-second pass into the disk pack and return to the retract position.
- 23. Press (to extinguish) the START switch.
- 24. Remove the disk pack.
- 25. Install the shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

BRUSH RESET SWITCH REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Remove the four screws and washers securing the plastic shroud. Set the shroud aside.
- 5. Note the switch leadwire connections and disconnect them.
- 6. Remove the two screws and washers securing the reset switch to the brush assembly.
- 7. Install the replacement switch with two screws and washers.
- 8. Restore the leadwire connections to the reset switch according to step 5.
- 9. Move the brush holder against the rubber stop so that the linkage appears as it is in Figure 6-4.

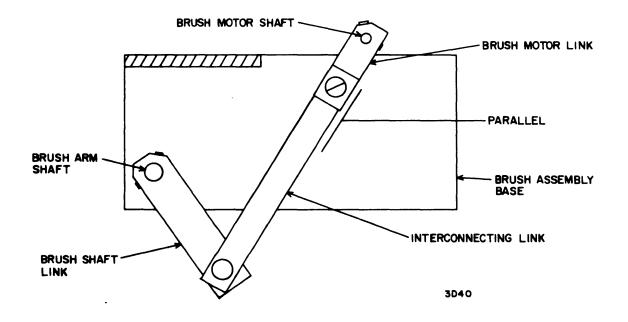


Figure 6-4. Brush Linkage Adjustment

- 10. Loosen the two setscrews in the brush positioning stop (Figure 6-3).
- 11. Adjust the stop so that the switch lever is moved approximately 1/32 inch beyond where the switch makes an audible click.
- 12. Tighten the two setscrews in the brush positioning stop.
- 13. Install the shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

FIBER OPTIC SOURCE LAMP REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Remove the four lamp housing screws.
- 5. Disconnect the P36-J36 connection.

CAUTION

The fiber optics may be damaged if they are pinched or bent at a radius of less than 1 inch.

- Invert the lamp housing assembly and remove the three nylon mounting screws. Be careful not to lose the three insulating washers.
- 7. Remove the lamp assembly.
- 8. Remove the lamp connector. Loosen the two mounting screws and remove the lamp.
- 9. Install the new lamp. Tighten the two mounting screws. The strap and plate should be flush with the top of the metallic lamp base.
- 10. Install the lamp connector.

- Using the three nylon screws and washers, remount the lamp assembly in the lamp housing. Do not overtighten the screws. Make sure the lamp is insulated from the housing assembly.
- 12. Remount the lamp housing assembly on the main deck with the four housing screws.
- 13. Connect P36 to J36.
- 14. Perform the Fiber Optic Adjustment procedure.

FIBER OPTIC REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.

CAUTION

The fiber optics may be damaged if they are pinched or bent at a radius of less than 1 inch.

- 4. Disconnect the defective fiber optic from the clip end.
- 5. Remove the fiber optic from the cable clamps up to the lamp housing assembly.
- 6. Note the orientation of the fiber optics and ball joint retaining plate at the housing assembly (Figure 6-5). Mark the retaining plate.
- 7. Remove the five screws from the ball joint retaining plate.
- 8. Gently lift the fiber optics vertically and remove the center screw from the plate. Do not lose the small spacer under the center screw.
- 9. Slide the damaged fiber optics through the ball joint retaining plate.
- 10. Install the new fiber optic.
- 11. Place the small spacer over the center tapped hole on the lamp housing assembly.
- 12. Insert the center screw through the ball joint retaining plate.

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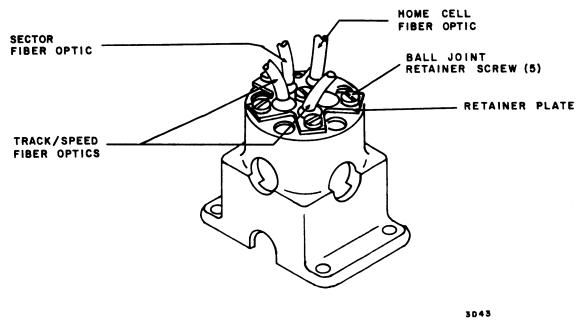


Figure 6-5. Fiber Optic Source Lamp

- 13. Note the marked orientation of the plate and fiber optics from step 6. Lower the fiber optics and retaining plate on the lamp housing assembly by gently pushing down on the center screw with a screwdriver. Lift up on the fiber optics to seat the ball joint ends in the plate. Tighten the center screw.
- 14. Insert the five retainer plate screws. Do not tighten.
- 15. Reroute the new fiber optic through the cable clamps.
- 16. Perform the Fiber Optic Adjustment procedure.

HOME CELL PHOTOTRANSISTOR REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Note or tag the two leadwires connected to the phototransistor plate and disconnect them.
- 5. Disconnect the fiber optic from the end clip.

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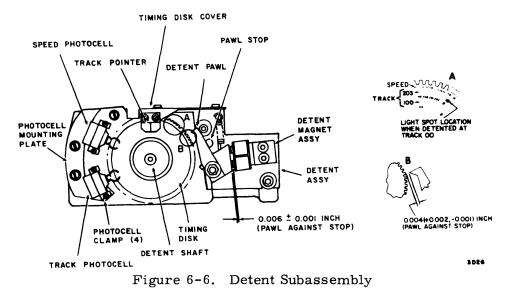
- 6. Remove the two screws securing the photocell block to the mounting bracket.
- 7. Remove the two screws holding the phototransistor plate to the photocell block.
- 8. Install the replacement phototransistor plate using two screws and 2 drops Loctite, Grade C.
- 9. Secure the photocell block to the mounting bracket with two screws and 2 drops Loctite, Grade C. Keep the dimension between the phototransistor plate and the mask to a minimum.
- 10. Restore the leadwire connections to the phototransistor plate according to step 4.
- 11. Insert the fiber optic into the photocell clip. Adjust the fiber optic at the clip end until the clip contacts the shoulder of the end ferrule.
- 12. Perform the Home Cell Mechanical Adjustment procedure.

SECTOR PHOTOTRANSISTOR REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Note or tag the three leadwires connected to the phototransistor plate and disconnect them.
- 5. Remove the two screws securing the phototransistor plate to the photocell block.
- 6. Apply 2 drops of Loctite, Grade C, to the screw threads and install the replacement phototransistor plate.
- 7. Restore the leadwire connections to the phototransistor plate according to step 4.
- 8. Perform the Sector Block Tangential and Radial Adjustment procedure.

TRACK/SPEED PHOTOTRANSISTOR REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Note or tag the two leadwires connected to the applicable phototransistor plate (Figure 6-6) and disconnect them.
- 5. Disconnect the fiber optic from the photocell clip.
- 6. Loosen the two photocell clamp screws. Remove the photocell block.



- 7. Remove the two screws securing the phototransistor plate to the photocell block.
- 8. Apply 2 drops of Loctite, Grade C, to the threads of the two screws and install the replacement phototransistor plate.
- 9. Insert the photocell block in the photocell clamp. Tighten the clamp screws.
- 10. Restore the leadwire connections to the phototransistor plate according to step 4.
- 11. Insert the fiber optic into the mounting clip until it is within $2/16 \pm 1/16$ inch of the timing disk.

- 12. Perform the Track/Speed Photocell Mechanical Adjustment procedure.
- 13. Perform the Track Photocell Rotational Adjustment procedure.
- 14. Perform the Actuator Dynamic Tests and Adjustments procedure.

CARRIAGE ASSEMBLY OR DETENT SHAFT REPLACEMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Remove the four screws and washers holding the plastic shroud. Remove the shroud and set it aside.
- 4. Disconnect the J230-P230 connection at the top rear of the carriage.
- 5. Disconnect the read/write cable from the head diode board. Remove the screw securing the cable clamp to the side of the carriage mount.
- 6. Remove the track/speed fiber optics from the photocell mounting clips.
- 7. Remove the screw securing the home cell fiber optic clamp to the head diode board. Remove the fiber optic from the photocell mounting clip.
- 8. Remove the four bolts securing the actuator assembly to the main deck. Lift the actuator assembly from the disk storage drive.

NOTE

Further disassembly and reassembly will be greatly aided by referring to the exploded view for the carriage assembly in the Illustrated Parts List. See Section 1 of this manual for the Publication number.

- 9. Note the connection scheme and disconnect the 10 read/write head connector plugs from the head diode board.
- 10. Remove the two screws securing the carriage stop bracket to the carriage assembly.
- 11. Remove the screw securing the ground strap to the carriage.
- 12. Remove the three screws securing the shock mount to the carriage mount.

- 13. Disengage the detent pawl and move the carriage forward so that the torsion arm shaft clears the shock mount.
- 14. Twist the shock mount counterclockwise to disengage it from the cam and remove it from the carriage mount.
- 15. Remove the two screws securing the cam latch collar to the head loading cam.
- Locate the part of the carriage mount that surrounds the forward end of the head loading cam. Remove the retaining ring (0.831-inch OD) from the forward face.
- 17. For carriage assembly replacement proceed to step 18. For detent shaft replacement proceed to step 19.
- 18. Replace the carriage assembly as follows:

Do not touch the face of the heads. Skin acids can etch and damage faces. Avoid any contact between head/arm assembly being removed and any adjacent head/arm assembly.

- a. Note the orientation of the head arms and mark the arms. Refer to Figure 6-7 for head identification.
- b. Loosen the wrenching nuts in the head/arm clamp.
- c. Push the head/arm assembly toward the spindle assembly. Grasp the support arm and carefully pull it clear of the head/arm guide plate.
 Guide the head connector plug until it is clear of the carriage.
- d. Referring to Figure 6-7 and step a, carefully thread the connector plug of the head/arm through the head/arm guide plate and clamp of the new carriage assembly. Align the leading end of the head/arm with the slot in the guide plate. Slide the head/arm through the slot and back to the head/ arm locating block.
- e. Repeat steps c and d for the nine remaining head/arm assemblies. Tighten the 12 wrenching nuts in the head/arm clamp.
- f. Note or tag the five leadwire connections to the head latch assembly and disconnect them. Note the orientation of the diode on the head latch solenoid and transfer it to the new actuator assembly.

- g. Remove the screw securing the head latch cable clamp to the home photocell mounting bracket.
- h. Disengage the detent pawl and move the carriage forward, separating the carriage assembly from the carriage mount.
- i. Proceed to step 20 for assembly of the new carriage.
- 19. Replace the detent shaft as follows:
 - a. Loosen the head latch cable clamp on the home photocell mounting bracket.
 - b. Disengage the detent pawl and slide the carriage forward, separating the carriage assembly from the carriage mount.
 - c. Remove the two screws and washers securing the timing disk cover to the carriage mount.

The timing disk markings are a photoemulsion. Use extreme care in removing the photocells to prevent scraping or scratching the disk.

- d. Separate the photocell mounting plate from the carriage mount by removing the three screws and washers. Carefully slide the photocells away from the center of the timing disk.
- e. Rotate the detent shaft until the setscrew in the detent gear hub is visible through the opening above the speed photocell. Remove the setscrew with a long-shaft Allen wrench.
- f. Turn the detent shaft until the detent gear hub is positioned 180 degrees from step e. Using a lock wedge removal tool (84371800), carefully push the locking wedge out of the detent gear hub. Remove the timing disk and detent gear from the detent shaft.
- g. Remove the lock washer and screw securing the torque arm to the carriage mount.
- h. Rotate the detent shaft until the setscrew securing the motor to the shaft is visible through the opening in the actuator casting. Remove the setscrew.

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- Rotate the detent shaft until it is positioned 180 degrees from step h.
 Using a lock wedge removal tool (84371800), carefully push the locking wedge out of the detent shaft. Remove the motor from the detent shaft.
- j. Remove the three screws and washers securing the bearing retainer plate to the carriage mount.
- k. Slide the detent shaft assembly out of the carriage mount. Do not lose the spring washer and flatwasher at the end of the shaft.
- Install the spring washer and flatwasher in the bottom of the bore. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400) on the detent shaft bearings and slide the new detent shaft assembly into the carriage mount.
- m. Remount the bearing retainer plate on the carriage mount with three screws and washers. Apply 2 drops of Loctite, Grade C, to the screw threads. Rotate the tightening of the screws so that the retainer plate lip will fit uniformaly around the detent shaft bearing.
- n. Mate the motor shaft and the detent shaft. Do not make contact between the detent shaft and the motor. Maintain a gap of 0.06 ± 0.02 inch between the motor and the end of the detent shaft.
- o. Insert the locking wedge into the detent shaft (via the threaded end of the hole). Install the setscrew.
- p. Attach the torque arm to the carriage mount with a screw and lockwasher.

The timing disk markings are a photoemulsion. Use extreme care when installing the timing disk and the photocell mounting plate. Use plastic feeler gages when setting the gap.

- q. Install the timing disk and detent gear on the detent shaft.
- r. Position the photocell mounting plate so that the speed and track photocells are approximately over their respective segments of the timing disk and secure the plate with three screws and washers.

- s. Using a plastic feeler gage, establish a gap of 0.004 ± 0.002 inch between the phototransistor plate and the emulsion side of the timing disk. Maintain this gap while installing the locking wedge in the detent shaft. Install the setscrew.
- t. Install the timing disk cover and cable clamp with two screws and washers. Make certain the track indicator index does not contact the timing disk.
- 20. Lubricate the detent and pinion gears and the carriage assembly according to the procedures outlined under 500 and 1000 hour maintenance in Section 5 of this manual.
- 21. Disengage the detent pawl and carefully slide the carriage assembly into the carriage mount. As the head loading cam exits the front hole in the carriage mount, place the spring and then the cam latch collar over the head loading cam. Make certain the cam latch collar stays forward of the cam latch arm. Slide the carriage to the rear of the carriage mount. Using Loctite, Grade C, on the screw threads, secure the cam latch collar to the head loading cam with two screws.
- 22. Seat the cam lug washer, the spring, and the spring retainer washer in the carriage mount. Using the compression tool (84356100), force the spring retainer washer into the carriage mount. Insert the retaining ring (0.831-inch OD) into the groove of the carriage mount to hold the washer and spring in place.
- 23. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400) to the rear grooves of the shock mount. Using three screws and 2 drops Loctite, Grade C, install the carriage shock mount.
- 24. Connect the ground cable to the carriage assembly with a screw and washer.
- 25. Install the carriage stop bracket with two screws and 2 drops of Loctite, Grade C.
- 26. If the carriage assembly was replaced, connect the leadwires to the head latch assembly according to step 18 (f). If the detent shaft was replaced, tighten the head latch cable clamp on the home photocell mounting bracket.
- 27. Thread the head/arm cables through the cable retainer connected to the head latch assembly. Connect the cable plugs to the head diode board according to step 9.

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- 28. Perform the Carriage Limit Stop Adjustment procedure.
- 29. Using the four bolts, remount the actuator assembly on the main deck of the disk storage drive.
- 30. Insert the home cell fiber optic into the photocell clip so that the shoulder of the fiber optic end ferrule contacts the clip. Secure the fiber optic clamp to the head diode board with a screw and washer.
- 31. Insert the track/speed fiber optics into the photocell mounting clips until they are within $2/16 \pm 1/16$ inch of the timing disk.
- 32. Connect the read/write cable to the head diode board. Using a screw and washer, secure the cable clamp to the side of the carriage mount.
- 33. Restore the P230-J230 connection.
- 34. Perform steps 8 through 13 of the Head/Arm Replacement procedure.
- 35. Perform the Detent Adjustment procedure.
- 36. Perform the Track/Speed Photocell Mechanical Adjustment procedure.
- 37. Perform the Track Photocell Rotational Adjustment procedure.
- 38. Perform the Actuator Dynamic Tests and Adjustments procedure.
- 39. Install the plastic shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

TIMING DISK/DETENT GEAR ASSEMBLY REPLACEMENT

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Separate the timing disk cover from the carriage mount by removing the two screws and washers (Figure 6-6).

The timing disk markings are a photoemulsion. Use extreme care in removing the photocells to prevent scraping or scratching the disk.

- 5. Remove the three screws securing the photocell mounting plate and carefully slide the photocells away from the center of the timing disk until they are clear of the detent gear teeth (Figure 6-6).
- 6. Manually disengage the detent pawl and move the carriage forward until the screw in the detent gear hub is visible through the opening above the speed photocell. Remove the screw with a long-shaft Allen wrench.
- Disengage the detent pawl and move the carriage until the detent gear hub is positioned 180 degrees from step 6. Using a lock wedge removal tool (84371800), carefully push the locking wedge out of the detent gear hub. Remove the timing disk and detent gear from the detent shaft.

CAUTION

The timing disk markings are a photoemulsion. Use extreme care and plastic feeler gages when setting the gap.

- 8. Install the replacement timing disk and detent gear on the detent shaft. Insert the locking wedge into the detent hub (via the threaded end of the hole).
- 9. Using a plastic feeler gage, establish a gap of 0.004 ± 0.002 inch between the phototransistor plate and the emulsion side of the timing disk. Maintain this gap while installing the locking wedge in the detent shaft. Install the setscrew in the detent gear hub.
- Install the timing disk cover and cable clamp with two screws and washers. Make certain the track indicator index does not contact the timing disk.
- 11. Perform the Detent Adjustment procedure.
- 12. Perform the Track/Speed Photocell Mechanical Adjustment procedure.
- 13. Perform the Track Photocell Rotational Adjustment procedure.
- 14. Perform the Actuator Dynamic Tests and Adjustments procedure.

ACCESS MOTOR REPLACEMENT

NOTE

Field repair of the access motor is not recommended. Return faulty motor to the factory for repair.

- 1. Press (to extinguish) the START switch.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Open and latch the disk drive top rear cover.
- 4. Remove the four screws and washers holding the plastic shroud. Set the shroud aside.
- 5. Remove the lockwasher and screw securing the torque arm to the carriage mount.
- 6. Manually disengage the detent pawl and move the carriage forward until the screw in the detent shaft is visible through the opening in the actuator casting. Remove the screw with a long-shaft Allen wrench.
- Manually disengage the detent pawl and position the carriage until the detent shaft is positioned 180 degrees from step 6. Using a lock wedge removal tool (84371800), carefully push the locking wedge out of the detent shaft.
- 8. Disconnect the J230-P230 connection at the top rear of the carriage mount.
- Note the motor leadwire pin positions in J230. Using an extraction tool (12210915), remove the motor leadwires from J230. Remove the leadwires from the spiral cable wrap.

CAUTION

Pulling on the detent shaft may result in a scored or broken timing disk. If the motor cannot be easily removed, it may be necessary to remove the gear and timing disk to prevent damage before proceeding with motor removal.

- 10. Carefully separate the motor and torque arm assembly from the detent shaft.
- 11. Remove the screw and conical shakeproof lockwasher attaching the torque arm and washer to the faulty motor and remount the arm on the new motor.

- 12. Mate the motor shaft and the detent shaft. Do not make contact between the detent shaft and the motor. Maintain a gap of 0.06 ± 0.02 inch between the motor and the end of the detent shaft.
- 13. Insert the locking wedge into the detent shaft (via the threaded end of the hole). Install the setscrew.
- 14. Attach the torque arm to the carriage mount with a screw and lockwasher.
- Dress the leadwires of the replacement motor into the spiral cable wrap.
 Press the contact pins into J230. Connect P230 to J230.
- 16. Manually disengage the detent pawl. Using a push-pull gage (12210797), check that the force encountered when moving the carriage from Track 00 to Track 202 plus one and back does not exceed 32 ounces.
- 17. Perform step 10 of the Track Photocell Rotational Adjustment procedure (align track indicator dial).
- 18. Perform the Actuator Dynamic Tests and Adjustments procedure.
- 19. If the four bolts securing the carriage mount to the main deck were loosened, perform the Head/Arm Adjustment procedure.
- 20. If the four bolts securing the carriage mount to the main deck were loosened, perform the Head/Arm Adjustment procedure.
- 21. Install the plastic shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

DETENT PAWL REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover.
- 3. Referring to the applicable part of Figure 6-6, remove the self-locking nut, the spring, and the washers securing the detent pawl. Disconnect the pawl spring.

- 4. Mount the replacement pawl on the shaft. Place a washer at each end of the spring. Assemble the spring and washers to the shaft and secure with the self-locking nut. Tighten the nut until the spring length is 0.50 ± 0.03 inch.
- 5. Connect the pawl spring.
- 6. Perform the Detent Adjustment procedure.
- 7. Perform the Head/Arm Adjustment procedure.
- 8. Perform the Actuator Dynamic Tests and Adjustments procedure.

DETENT MAGNET REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover.
- 3. Referring to the applicable part of Figure 6-6, remove the two socket head screws and washers securing the detent magnet.
- Disconnect the J230-P230 connection at the top rear of the carriage. Note the detent magnet leadwire pin positions in J230. Using an extraction tool (12210915), remove the magnet contact pins from J230.
- 5. Press the contact pins of the replacement magnet into J230.
- 6. Install the new assembly with two screws and washers and 2 drops of Loctite, Grade C.
- 7. Perform the Detent Adjustment procedure.

HEAD LATCH SOLENOID OR MICROSWITCH REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover.
- 3. Remove the nut securing the head cable retainer to the carriage. Remove the three screws holding the solenoid mounting bracket to the carriage and care-fully pull the assembly clear of the carriage.

- 4. Proceed to step 5 for head latch solenoid replacement or step 6 for Microswitch replacement.
- 5. Replace the head latch solenoid as follows:
 - a. Remove the two screws and washers that hold the solenoid to the bracket.
 - b. Note or tag the two leadwire connections to the solenoid and the diode orientation. Disconnect each.
 - c. Connect the leadwires and the diode to the replacement solenoid according to step b.
 - d. Apply 2 drops of Loctite, Grade C to the screws and using the washers, secure the solenoid to the bracket.
 - e. Proceed to step 7.
- 6. Replace the Microswitch as follows:
 - a. Rotate the assembly so that the Microswitch is up and level.
 - b. Carefully remove the two screws and washers that secure the Microswitch and actuating mechanism to the bracket.
 - c. Carefully lift the Microswitch off the bracket and immediately install the replacement unit. Apply 2 drops of Loctite, Grade C, to the threads and secure the switch to the bracket with two screws and washers.
 - d. Transfer the leadwire connections from the faulty Microswitch to the new unit.
- 7. Apply 2 drops of Loctite, Grade C, to the threads and install the mounting bracket on the carriage with three screws. Secure the cable clamp with the lower screw. Using a nut, secure the head cable retainer to the carriage assembly.
- 8. Perform the Head Latch Solenoid and Switch Adjustment procedure.

CAM LATCH SOLENOID REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover.

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- 3. Remove the three screws and washers securing the cam latch solenoid bracket to the carriage.
- 4. Note or tag the two leadwire connections to the solenoid and the diode orientation and disconnect each.
- 5. Remove the two screws securing the solenoid to the bracket.
- 6. Apply 2 drops of Loctite, Grade C, to the screws and install the replacement solenoid on the bracket.
- 7. Connect the leadwires and the diode to the replacement solenoid according to step 4.
- 8. Apply 2 drops of Loctite, Grade C, to the screws and using the washers, secure the bracket to the carriage.
- 9. Perform the Cam Latch Solenoid Adjustment procedure.

HEADS RETRACTED SWITCH REPLACEMENT

- 1. Open and latch the top rear cover.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.

NOTE

The lower two screws securing the heads retracted switch mounting bracket also hold the cam latch solenoid bracket in place. Perform the following procedures so as to preserve, as nearly as possible, the cam latch solenoid adjustment.

- 3. Remove the screws securing the heads retracted switch bracket to the actuator casting.
- 4. Note the orientation of the switch on the bracket and remove the screws holding the switch. Disconnect the leadwires to the faulty switch and make the same connections to the replacement switch.
- 5. Secure the new switch to the bracket. Mount the bracket on the actuator casting so that the switch is actuated (actuation can be felt while holding the switch) during the last 1/4 inch of carriage motion prior to contacting the heads retracted stop.

6. Perfrom the Cam Latch Solenoid Adjustment.

HEAD/ARM REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Open and latch the disk drive top rear cover.
- 3. Determine the faulty head. Refer to Figure 6-7 for the physical location of the head.
- 4. Disconnect the connector plug for the faulty head at the head diode board.
- 5. Loosen the wrenching nuts immediately above and below the faulty head/arm (Figure 6-7).

CAUTION

Do not touch the face of the heads. Skin acids can etch and damage the faces. Avoid any contact between the head/arm assembly being removed and any adjacent head/arm assembly.

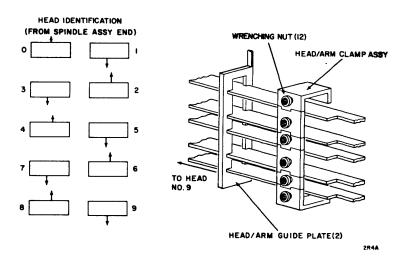


Figure 6-7. Head/Arm Assembly Adjustment

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- 6. Push the head/arm assembly toward the spindle assembly. Grasp the support arm and carefully pull it clear of the head/arm guide plate. Guide the head connector plug until it is clear of the carriage.
- 7. Carefully thread the connector plug for the replacement head/arm through the head/arm guide plate and clamp. Align the leading end of the head/arm with the slot in the guide plate. Slide the assembly toward the rear of the carriage until alignment is approximately the same as the adjacent head/arm assemblies. Connect the head connector plug. Tighten the wrenching nuts in the head/arm clamp.
- 8. Set the MAIN POWER circuit breaker to ON. Install a disk pack.
- 9. Manually pull the detent and move the heads slowly into the pack. Make certain that no part of the carriage (cable, cable clamp, torsion arm, or head) contacts the disk. Prior to latching, the replacement head should approach the disk with the outside and rear edges leading. Return the carriage to the retracted stop.
- Set the power supply ACCESS MOTOR circuit breaker to OFF. Pull upward on the top rear cover interlock switch (behind carriage). Press (to light) START switch.
- 11. Repeat the checks of step 9.
- 12. Perform the Head/Arm Adjustment procedure.
- 13. Perform the Actuator Adjustment procedure.

TORSION ARM/SHAFT REPLACEMENT

- 1. Open and latch the top rear cover.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Remove the four screws and washers holding the plastic shroud. Remove the shroud and set it aside.
- 4. Note the connection scheme, and disconnect the 10 read/write head connector plugs from the head diode board.
- 5. Loosen the 12 wrenching nuts (Figure 6-7) through the head/arm clamp.

Do not touch the face of the heads. Skin acids can etch and damage the faces. Avoid any contact between head/ arm assembly being removed and any adjacent head/arm assembly.

- 6. Note the orientation of the head arms and mark the arms. Refer to Figure 6-7 for head identification.
- 7. Push the head/arm assembly toward the spindle assembly. Grasp the support arm and carefully pull it clear of the head/arm guide plate. Guide the head connector plug until it is clear of the carriage. Repeat this step for the nine remaining heads.
- 8. If the center torsion arm is to be replaced, go to step 9. If one of the other four torsion arms is to be replaced, go to step 10.
- 9. Replace the center torsion arm assembly as follows:
 - a. Disengage the detent pawl and move the carriage to the fully retracted position. Note the carriage track location for later use.

NOTE

Further disassembly and reassembly will be greatly aided by referring to the exploded view for the carriage assembly in the Illustrated Parts List. See Section 1 of this manual for the Publication Number.

- b. Remove the two screws securing the carriage stop bracket to the carriage assembly. Remove the screw securing the ground strap to the carriage.
- c. Remove the three screws securing the shock mount to the carriage mount. Disengage the detent pawl and move the carriage forward so that the torsion arm shaft clears the shock mount. Twist the shock mount counterclockwise and remove it from the carriage mount.
- d. Remove the two screws securing the cam latch collar to the head loading cam. Locate the part of the carriage mount that surrounds the forward end of the head loading cam. Remove the retaining ring (0.831-inch OD) from the forward face.

- e. Locate the nut securing the head cable retainer. Remove the nut and the retainer. Remove the three screws securing the heads loaded latch assembly to the carriage.
- f. Disengage the detent pawl and move the carriage forward, separating the the carriage assembly from the carriage mount.
- g. Remove the torsion arm assemblies (except the center torsion arm) from the carriage by releasing the retaining ring at the end of the torsion arm shaft.
- h. Note the orientation of the cam follower (pinned on end of torsion shaft) for use during reassembly. Use a punch to remove the 3/32-inch diameter roll pin that secures the cam follower to the torsion shaft.
- i. Note the orientation of the heads loaded latch arm (pinned to approximate center of torsion shaft) for use during reassembly. Use a punch to remove the 3/32-inch diameter roll pin that secures the latch arm to the torsion shaft. Slide the center torsion arm (and torsion shaft) out of the carriage.
- j. Slide the replacement center torsion arm (and torsion shaft) into the carriage. Stop sliding the torsion shaft when the end of the shaft is just visible in the opening of the carriage casting.

The damping cylinder is fragile glass. Use care when handling.

- k. Seat the unloading damper piston in the damping cylinder (mounted on side of carriage). Place the heads loaded latch arm (oriented according to step i) and the thrust bearing over the end of the shaft and slide the torsion shaft through the remainder of the carriage. Pin the heads loaded latch arm to the torsion shaft with the roll pin $(3/32 \times 1/2 \text{ inch})$.
- 1. In the following order, slide the retaining ring (0.831-inch OD), the spring retaining washer (small OD first), the spring (smaller of the two available), and the cam lug washer (lug end first) on the end of the torsion shaft.

- m. Slide the head loading cam (notched end first) on the end of the torsion shaft until the shaft end is just visible in the opening cut in the side of the cam. Place the cam follower (lug end to the rear) in the cam opening and slide the torsion shaft through the center of the cam follower. Pin the cam follower to the end of the torsion shaft with the roll pin $(3/32 \times 3/8 \text{ inch}).$
- n. Lubricate the detent and pinion gears, carriage mount bearings, and the carriage assembly according to the procedure outline under 500 and 1000 hour maintenance in Section 5 of this manual.
- o. Disengage the detent pawl and carefully slide the carriage assembly into the carriage mount. As the head loading cam exits the front hole in the carriage mount, place the spring and then the cam latch collar over the head loading cam. Make certain the cam latch collar stays forward of the cam latch arm. Slide the carriage to the rear of the carriage mount. Using Loctite, Grade C, on the screw threads, secure the cam latch collar to the head loading cam with two screws.
- p. Seat the cam lug washer, the spring, and the spring retainer washer in the carriage mount. Using the compression tool (84356100), force the spring retainer washer into the carriage mount. Insert the retaining ring (0.831-inch OD) into the groove of the carriage mount to hold the washer and spring in place.
- q. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 94020400) to the rear grooves of the shock mount. Using three screws and 2 drops of Loctite, Grade C, install the carriage shock mount.
- r. Connect the ground cable to the carriage assembly with a screw and washer. Install the carriage stop bracket with two screws and 2 drops of Loctite, Grade C.
- s. Disengage the detent pawl and move the carriage to the fully retracted position. Make certain that the lugs on the cam follower are pointing up and down and are located at the extreme rear of the slotted opening in the head loading cam. The center torsion spring (see point A on Figure 3-16) should be aligned to 45-degrees from vertical, running from upper right to lower left.

The 90-degree relationship in the next step (shown on Figure 3-16) must be closely adhered to. The disk pack and/or the read/write heads may be damaged by incorrect assembly.

- t. Place a washer over the shaft end of each torsion arm assembly and carefully install the assemblies on the carriage. The assemblies with the full set of gear teeth go immediately above and below the center torsion arm. The assemblies with the partial set of gear teeth are the top and bottom assemblies in the stack, and the flat spot on the gear should be up on the top assembly and down on the bottom assembly. As the torsion arms are installed, mesh the gears so that a 90-degree angle is formed between adjacent faces of the torsion springs, Figure 3-16. Secure the torsion arm assemblies to the carriage with retaining rings (0.145-inch ID).
- u. Apply 2 drops of Loctite, Grade C, to the screw threads and install the heads loaded latch assembly with three screws. Install the two top screws first and then install the lower screw and the head latch cable clamp. Install the head cable retainer with a nut.
- v. Disengage the detent pawl and move the carriage to the fully retracted position. Note the carriage track location from step a and the location now. If an adjustment must be made, remove three screws and washers securing the head diode board. Free the Delrin block by removing the screw immediately behind the Delrin block setscrew, Figure 6-13. Slide the Delrin block clear of the top of the carriage. Separate the carriage rack gear from the pinion gear by pressing downward on the rear of the carriage. Rotate the pinion gear until the carriage track location is the same as it was in step a. Allow the gears to mesh and check that the track location did not change.
- w. Install the Delrin block with one screw. Perform the Carriage Limit Stop Adjustment procedure.
- x. Adjust the home cell according to the Home Cell Mechanical Adjustment procedure.
- y. Proceed to step 11.

- 10. Replace a torsion arm assembly (other than the center assembly) as follows:
 - a. Disengage the detent pawl and move the carriage to the fully extended position.
 - b. Remove the retaining ring that secures the faulty torsion arm to the carriage. Pull the assembly clear of the carriage.
 - c. Slide the washer (from old assembly) onto the shaft end of the replacement torsion arm assembly.

The 90-degree relationship in the next step (shown on Figure 3-16) must be closely adhered to. The disk pack and/or the read/write heads may be damaged by incorrect assembly.

d. As the replacement assembly is installed, mesh the gears so that a 90-degree angle (see Figure 3-16) is formed between the adjacent faces of the torsion springs. Secure the new assembly to the carriage with the original retaining ring.

CAUTION

Do not touch the face of the heads. Skin acids can etch and damage the faces. Avoid any contact between head/ arm assembly being installed and any adjacent head/arm assembly.

- 11. Referring to Figure 6-7 and step 6, carefully thread the connector plug for a head/arm assembly through the head/arm guide plate and clamp. Slide the head/arm into the slots in the guide plate and back to the head/arm locating block. Thread the head/arm cables through the cable retainer connected to the head latch assembly. Repeat this procedure for each of the nine remaining head/arm assemblies. Tighten the 12 wrenching nuts in the head/arm clamp.
- 12. Restore the head connector plug connections according to step 4.
- 13. Perform steps 8 through 13 of the Head/Arm Replacement procedure.
- 14. Install the shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

ADJUSTMENT

NOTE

Machine adjustments should be made only if the unit is not operating properly. Adjustments may drift outside of the tolerances provided. Such drift should not in itself be cause for adjustment.

SPINDLE LOCK ADJUSTMENT

- 1. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Remove the front panel and swing out the logic chassis.
- 3. Referring to Figure 6-1, use a 6-inch scale to check the $14/64 \pm 1/64$ -inch gap between the pawl and the plate (circled on figure). If this requirement is not met, remove the spindle lock assembly from the base of the spindle and adjust it according to step 4c of the Spindle Lock or Drive Belt Replacement procedure.
- 4. Press the armature of the spindle lock solenoid into the body of the solenoid and hold it there. Grasp the pawl and check to ensure that it rotates freely. The ends of the pawl should not be free to move vertically. Carefully allow the solenoid armature to extend.
- 5. Close the logic chassis and install the front panel.

PACK-ON SWITCH ADJUSTMENT

- 1. Set the power supply MAIN POWER circuit breaker to ON. Open the disk drive front cover, mount a disk pack on the spindle assembly, and tighten it in place.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Open the front panel and swing out the logic chassis.
- Using a feeler gage, check to see that the gap between the static discharge contact arm and the Pack-On switch actuator meets the requirements of Figure 6-2. Loosen the two screws securing the Microswitch bracket to the switch

mounting bracket and slide the lower bracket vertically until the dimension is correct. Tighten the screws. Make certain that the static discharge contact is aligned to the lockshaft according to Figure 6-2. The contacts will be damaged during operation if not properly aligned.

- 5. Refer to Figure 6-2 and use a push-pull gage (12210797) to check that the force required to separate the contacts is as shown.
- 6. Close the logic chassis and install the front panel.

DRIVE BELT TENSION ADJUSTMENT

- 1. Press (to extinguish) the START switch.
- 2. Remove the front panel and swing out the logic chassis.
- 3. Disconnect the spring to the drive belt idler arm. Note the free length of the spring and reconnect it to the idler arm. The spring must extend $1-1/4 \pm 1/4$ inch from its free length when connected to the idler arm.
- 4. If the requirement is not met, loosen the three bolts securing the drive motor assembly to the disk drive and reposition the drive motor assembly to meet the requirement. Apply 2 drops of Loctite, Grade C, to the bolt threads and tighten.

BRUSH ARM AND LINKAGE ADJUSTMENT

- 1. Open and latch the top rear cover of the disk storage drive.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Remove the four screws and washers holding the plastic shroud. Set the shroud aside.
- 4. Loosen the two screws locking the brush shaft link to the brush arm shaft.
- 5. For brush arm adjustment proceed to step 6. To adjust the linkage proceed to step 9.

- 6. Note the ball plunger (having the appearance of a setscrew) in the brush holder (Figure 6-3). This ball detents into a slot on the brush arm shaft. Rotate the brush holder so that the ball is not over the slot of the shaft.
- Bottom the ball plunger on the daimeter of the shaft and back off approximately 1/8 turn.
- 8. Rotate the brush holder and the brush arm so that the plunger is detented in the shaft slot.
- 9. Position the brush arm against the rubber stop.
- 10. Align the linkage as it appears in Figure 6-4. Tighten the two setscrews in the brush shaft link.
- 11. Loosen the two setscrews in the brush positioning stop (Figure 6-3).
- 12. Adjust the stop so that the switch lever is actuated approximately 1/32-inch beyond where the switch makes an audible click. Make certain the brush holder is against the rubber stop.
- 13. Tighten the two setscrews in the brush positioning stop.
- 14. Install the plastic shroud with four screws and washers. Make certain the carriage, sector block, and the brush assembly fit properly through the openings in the shroud. Pull the shroud toward the front of the unit to ensure that it protects the heads when the carriage is in the retracted position.

FIBER OPTIC ADJUSTMENT

- 1. Open and latch the disk storage drive top rear cover.
- 2. Set the power supply MAIN POWER and ± 20 vdc circuit breakers to ON.
- 3. Using a multimeter, measure $+5.7 \pm 0.2$ vdc at the power supply panel LAMP and DC GRD jacks. Refer to the Power Level Adjustment procedure if the correct voltage is not read.
- 4. Remove the front panel and connect the ground of an oscilloscope to the maintenance panel GROUND jack. Press (to light) the START switch.
- 5. Proceed to step 6 for the track, speed, and sector fiber optic adjustment or step 7 for the home cell fiber optic adjustment.

- 6. Adjust the track, speed, and sector fiber optics as follows:
 - a. Connect the oscilloscope probe to the yellow leadwire terminal of the speed phototransistor plate.

The fiber optics may be damaged if they are pinched or bent at a bend radius of less than 1 inch.

- b. Mount the appropriate fiber optic in the speed cell mounting clip.
- c. Disconnect the spring from the detent pawl and move the carriage so that the speed cell output is Class A (between +1.0 and +5.5 vdc). The speed cell must not be saturated at this time.
- d. Loosen the appropriate ball joint retaining screw on the source lamp housing assembly (Figure 6-5) until the ball joint can be moved with some resistance. If the plate is deformed so that the ball is not free, lift the plate with a screwdriver while making adjustment.
- e. Move the fiber optic ball joint until the photocell output is maximum.
- f. If the phototransistor saturates, reposition the carriage so that the phototransistor output is again Class A. Readjust the fiber optic ball joint until the phototransistor output is maximum.
- g. Tighten the ball joint retaining screw.
- h. Connect the fiber optic to its original position. Insert the sector fiber optic until the clip contacts the shoulder of the end ferrule. Insert the track/speed fiber optics into the mounting clip until they are within $2/16 \pm 1/16$ -inch of the timing disk.
- i. Proceed to step 8.
- 7. Adjust the home cell fiber optic as follows:
 - a. Adjust the fiber optic at the clip end until the clip contacts the shoulder of the end ferrule.
 - b. Connect the oscilloscope probe to the left leadwire terminal of the home cell phototransistor plate.

- c. Disconnect the spring from the detent pawl and move the carriage so that the home cell output is Class A (between +1.0 and +5.5 vdc). The home cell must not be saturated at this time.
- d. Loosen the home cell fiber optic ball joint retaining screw on the source lamp housing assembly (Figure 6-5) until the ball joint can be moved with some resistance. If the plate is deformed so that the ball joint is not free, lift the plate with a screwdriver while making adjustment.
- e. Move the fiber optic ball joint until the photocell output is maximum.
- f. If the phototransistor saturates, reposition the carriage so that the output is again Class A. Readjust the fiber optic ball joint until the phototransistor output is maximum.
- g. Tighten the ball joint retaining screw.
- 8. Disconnect the oscilloscope.
- 9. Hook the spring over the detent pawl.

DETENT ADJUSTMENT

For the following procedures refer to Figure 6-6.

- 1. Press (to extinguish) the START switch.
- 2. Open and latch the top rear cover.
- Manually disengage the detent pawl. Use a feeler gage to measure the gap between the tip of the pawl and the adjacent tops of the detent gear teeth. The gap should be 0.004 (+0.002, -0.001) inch.
- 4. With the pawl disengaged, use a feeler gage to measure the gap between the detent pawl armature and the pole faces of the detent magnet. The gap should be 0.006 ± 0.001 inch.
- 5. If the requirements of step 3 and 4 are met, go to step 8.

The gaps checked in step 3 and 4 are independent of each other and can be adjusted separately.

- 6. To adjust the gap between the detent pawl armature and the magnet pole faces, loosen the two screws securing the detent magnet assembly until the assembly can be moved by hand. Place a 0.006-inch shim between the magnetic pole armature. With the pawl against the stop, the pivot pin at the end of the slot in the pawl, and the magnet pole facing parallel to the pawl armature face, tighten the two screws securing the detent magnet assembly. Remove the shim. Check the gap (0.006 ± 0.001 inch) and readjust if required.
- 7. To adjust the gap between the tip of the pawl and the tops of the adjacent detent gear teeth, loosen the two screws securing the detent assembly. Place a 0.004-inch shim between the pawl tip and the tops of the adjacent detent gear teeth. Position the detent assembly until the gap is held with the pawl against the stop and the pivot pin at the end of the slot in the pawl, then tighten the two screws securing the detent assembly. Remove the shim. Check the gap for a dimension of 0.004 (+0.002, -0.001) inch and readjust if required.
- 8. Check the adjustment of delay Y312 according to step 5 of the Delay Tests and Adjustments procedure.
- 9. Attach a push-pull gage (12210797) to the neck of the detent pawl. Apply a pull force perpendicular to the pawl. The gage should indicate that a mini-mum force of 4 ounces is required to disengage the pawl.

HEAD/ARM ADJUSTMENT

The head/arm assemblies must be adjusted to place each of the read/write heads on the same radial position with reference to the center of the disk pack. Radial positioning is accomplished by physically moving the heads into or out of the disk pack.

NOTE

The room temperature should be maintained at $72^{\circ} + 6^{\circ}F$ during the entire adjustment procedure.

1. Open and latch the top rear cover of the disk drive.

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- 2. Remove the diode card at X10 (read/write logic chassis).
- 3. Remove the disk drive front panel. Connect the oscilloscope external trigger to test point C of I028 Index pulse (C27) and set the External Sync switch to negative. Ground the oscilloscope at the maintenance panel GROUND jack.

To read any head other than head 0 or head 1, the selected head cable plug connection must be exchanged with either head 0 or head 1 at the head diode card. Connect heads 3, 4, 7, and 8 (Figure 6-7) at head 0 head diode card connector. All other heads are exchanged with head 1.

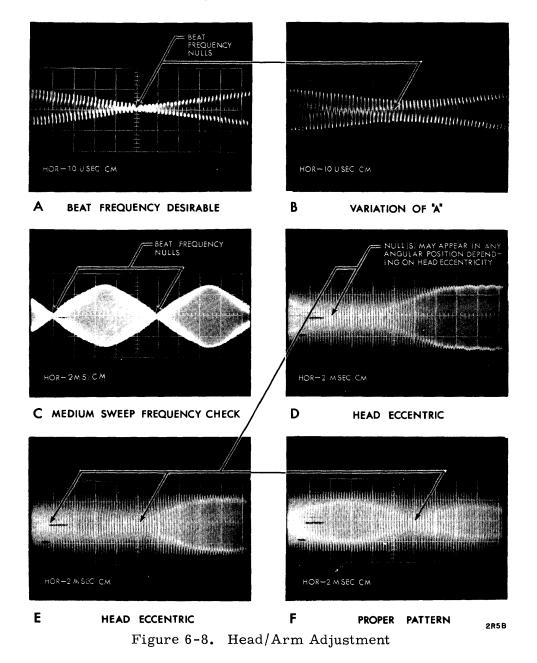
- Exchange the head plug connection of the desired head with either head 0 or head 1. Install a head plug adapter (46812200) between the head diode and connector and the head plug of the head to be adjusted.
- Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ
 0 or READ 1 position (as required by the exchange in step 4).
- 6. Connect 1X oscilloscope probes (to read differentially) to test points A and B of the EUC card at X09 (on read/write logic chassis).
- 7. Set the oscilloscope sweep frequency to 2 ms/cm.
- 8. Set the power supply circuit breakers to ON.
- 9. Mount the CE disk pack (84357500) on the spindle and tighten in place. Pull upward on the rear cover interlock switch.
- 10. Press (to light) the START switch. Record the time of power application.
- 11. After the heads load and the carriage stops, set the power supply ACCESS MOTOR and DETENT circuit breakers to OFF.
- 12. Manually pull the detent pawl, move the carriage to Track 73, and allow the detent pawl to engage the detent gear.
- 13. A 45 minute warm-up period with the top rear cover down and the heads loaded, followed by a 15 minute period with the top cover raised, must precede the following adjustment procedures.
- 14. Adjust the oscilloscope for a stable pattern. The pattern should be similar to Figure 6-8, part C.

- 15. If beat fequency envelopes are not observed, pull the detent pawl and manually move the carriage back and forth across the tracks adjacent to Track 73. As the heads are moving, the following linear progression should be observed on the oscilloscope.
 - a. An erased area with no signal.
 - b. An all "1's" pattern.
 - c. A pattern of beat frequency envelopes (Track 73).
 - d. An all "1's" pattern.
 - e. An erased area with no signal.
- Determine which way the head/arm must be moved to appear as shown on Figure 6-8, part C. Detent the carriage at Track 73.

Do not contact or otherwise disturb an adjacent head/ arm during the following adjustments.

- 17. Loosen the two wrenching nuts above and below the affected head/arm, Figure 6-7. If the head/arm is located before Track 73, proceed to step 18. If the head/arm is located beyond Track 73, carefully slide the head/arm away from the spindle.
- 18. Slowly move the head/arm assembly toward the spindle assembly. Stop when the beat frequency envelopes begin to form.
- 19. Set the oscilloscope to display one complete revolution of the disk (2 ms/cm). The beat frequency display will now be seen as a bright pattern or envelope of nulls within the all "1's" frequency pattern, Figure 6-8, part D or E.
- 20. Slowly adjust the head/arm assembly toward the spindle. The envelopes of nulls will come to an absolute null at one point and then will develop into a pair of absolute nulls with lobes of greater amplitude between them. The head/arm is properly aligned over Track 73 when the maximum amplitude of the two envelopes is equal to within 20 percent, Figure 6-8, part F. Tighten the two adjacent wrenching nuts in the head/arm clamp.

- 21. Set the ACCESS MOTOR and DETENT circuit breakers to ON. Perform three First Seek operations (by pressing the START switch six times at 75-second intervals).
- 22. Recheck the Track 73 beat frequency envelope trace on the oscilloscope. If the difference between the maximum amplitude of the two envelopes exceeds 50 percent, repeat the adjust procedure from step 16.



- 23. Press (to extinguish) the START switch. Remove the CE disk pack from the spindle.
- 24. Install the diode card at location X10 on the read/write logic chassis.
- 25. Remove the head plug adapter.
- 26. Restore the head plug connections to the original configuration.

ACTUATOR ADJUSTMENT

- 1. Open and latch the top rear cover of the disk drive.
- 2. Remove the diode card at X10 (read/write logic chassis).
- 3. Remove the disk drive front panel. Connect the oscilloscope external trigger to test point C of I028 Index pulse (C27) and set the External Sync switch to negative. Ground the oscilloscope at the maintenance panel GROUND jack.
- 4. Connect 1X oscilloscope probes (to read differentially) to test points A and B of the EUC card at X09 (on read/write logic chassis).
- 5. Set the oscilloscope sweep frequency to 5 usec/cm.
- 6. Set the power supply circuit breakers to ON.
- 7. Mount the CE disk pack (84357500) on the spindle and tighten in place. Pull upward on the rear cover interlock switch.
- 8. Press (to light) the START switch. After the heads load and the carriage stops, set the power supply ACCESS MOTOR and DETENT circuit breakers to OFF.
- 9. Manually pull the detent pawl, move the carriage to Track 03, and allow the detent pawl to engage the detent gear.
- Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ
 0 position.

- 11. Record the oscilloscope period (as well as head and track) between Index pulse and the peak of the first data pulse, Figure 6-9.
- 12. Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ 1 position. Repeat step 11.

To read any head other than head 0 or head 1, the selected head cable plug must be exchanged with either head 0 or head 1 at the head diode card. Connect heads 3, 4, 7, and 8 (Figure 6-7) at the head 0 head diode connector. All other heads are exchanged with head 1. In either case, the maintenance panel OFF LINE/ON LINE switch must be positioned to reflect the exchange.

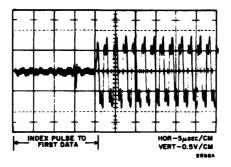


Figure 6-9. Index to Data Period

- 13. Repeat the observation of step 11 for each of the eight remaining heads.
- 14. The total spread for the 10 recorded periods should not exceed 8 usec. If this requirement is not met, replace the applicable head arm assembly. The 10 recorded periods should be within 20 ± 4 usec. If this requirement is not met, perform steps 31 and 32 of the Sector Block Tangential and Radial Adjustment procedure.

NOTE

When performing step 15, a head plug adapter (46812200) must be installed between the cable plug of the selected head and head 0 or 1 (as required) head diode card connector.

- 15. Install the head plug adapter (46812200) between the head 0 cable plug and the head diode card connector. Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ 0. Record the oscillscope period between the Index pulse and the peak of the first data pulse (Figure 6-9). The period should be approximately 48 usec.
- 16. Repeat step 15 for the other nine heads.
- 17. Manually pull the detent pawl, move the carriage to Track 201, and allow the detent pawl to engage the detent gear.
- 18. Repeat steps 15 and 16.
- 19. The difference in timing at Track 03 and Track 201 for any one head must not exceed 4 used. If this requirement is met, proceed to step 22.
- 20. If the requirement of step 19 is not met, loosen the four bolts holding the actuator assembly to the main deck. Pivot the actuator assembly to bring the Track 03 and 201 periods to within 4 usec of each other. Tighten the bolts. Remove the head plug adapter and repeat steps 9 through 14.
- 21. Recheck the alignment of each head to Track 73 according to the Head/Arm Adjustment procedure. Make adjustments as required.
- 22. Press (to extinguish) the START switch. Remove the CE disk pack from the spindle.
- 23. Remove the head plug adapter.
- 24. Restore the head plug connections to the original configuration.
- 25. Install the diode card at location X10 on the read/write logic chassis.

SECTOR BLOCK TANGENTIAL AND RADIAL ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Remove the disk storage drive front panel.
- 3. Remove the diode card at X10 on the read/write logic chassis.
- 4. Set the power supply circuit breakers to ON.
- 5. Mount the CE disk pack (84357500) on the spindle and tighten in place.

- 6. Move the sector arm toward the disk pack until the stop post is encountered.
- 7. Using a plastic feeler gage, check the 0.070 ± 0.030 inch clearance (Figure 6-10).
- If the requirement is not met, remove the shoulder screw (Figure 6-10) and add shims (p/n according to Illustrated Parts List) between the top of the mounting block and the washer.
- 9. Secure the sector arm with the shoulder screw.
- 10. Move the sector arm toward the disk pack until the stop post is encountered.
- 11. Using a 6-inch scale, check the $10/64 \pm 1/64$ -inch clearance (Figure 6-10).
- 12. If the requirement is not met, loosen the stop screw locking nut.
- Adjust the stop screw against the stop post until the clearance is correct. Tighten the locking nut.
- 14. Move the sector photocell toward the disk pack until the stop post is encountered (Figure 6-10). At this position the solenoid armature should be bottomed out. If this requirement is not met, loosen the screws in the solenoid mounting bracket and reposition the solenoid.

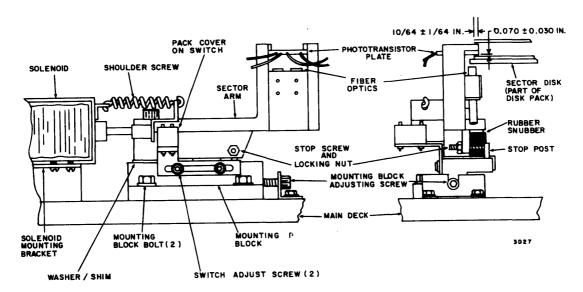


Figure 6-10. Sector Radial Adjustment

- 15. Position the sector arm against the stop post. At this position the pack cover on switch should be actuated by the sector arm (Figure 6-10). The sector arm must not touch the body of the switch. If this condition is not met, loosen the two screws securing the switch mounting bracket and reposition the switch.
- 16. Pull the post of the rear cover interlock switch upward.
- 17. Press (to light) the START switch.
- 18. Ground the oscilloscope at the maintenance panel GROUND jack.
- 19. Connect the oscilloscope probe to the yellow leadwire terminal of the sector phototransistor plate.
- 20. The photocell analog output trace should switch between a low voltage of -0.6 ± 0.4 vdc and a high voltage of $+5.0 \pm 0.5$ vdc. The photocell must saturate at the high voltage level. The photocell is saturated if the photocell output voltage (yellow leadwire) is within 0.6 vdc of the supply voltage (black leadwire). If the photocell does not saturate, correct the situation according to one of the following:
 - * Perform the Fiber Optic Adjustment procedure.
 - * Recheck steps 10 through 13 to make sure that the sector block has not moved too far into the disk pack.
 - * Refer to the Power Level Adjustment procedure. Adjust R03 until the cell saturates (do not exceed +6.0 vdc).
 - * Replace the fiber optic and/or phototransistor.
- Connect the oscilloscope external trigger to test point D of I035 Index Pulse (C19) and set the External Sync switch to negative.
- 22. Connect the oscilloscope probe to test point C of Y005 (C22). The oscilloscope traces should meet the requirements of Figure 6-11.
- 23. If the requirements of Figure 6-11 are not met, adjust the potentiometer on Y005 (C22).
- 24. Connect 1X oscilloscope probes (to read differentially) to test points A and B of EUC card at X09 on the read/write logic chassis.
- 25. Set the oscilloscope sweep frequency to 5 usec/cm.

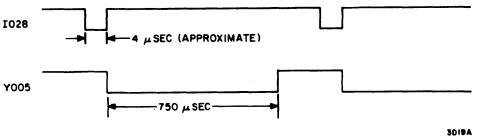


Figure 6-11. Sector Pulse Timing

- 26. Set the power supply ACCESS MOTOR and DETENT circuit breakers to OFF.
- 27. Manually pull the detent pawl, move the carriage to Track 03, and allow the detent pawl to engage the detent gear.
- 28. Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ0 position.
- 29. Record the oscilloscope period between the Index pulse and the peak of the first data pulse (Figure 6-9).

NOTE

To read any head other than head 0 or 1, the selected head cable plug must be exchanged with either head 0 or head 1 at the head diode card. Connect heads 3, 4, 7, and 8 (Figure 6-7) at the head 0 head diode card connector. All other heads are exchanged with head 1. In either case, the maintenance panel OFF LINE/ON LINE switch must be positioned to reflect the exchange.

- 30. Repeat step 29 for the remaining heads.
- 31. The midpoint in the spread of the 10 recorded periods at track 03 must be approximately 20 usec. If this requirement is met, proceed to step 34.
- 32. If the requirement is not met, determine the difference between the actual midpoint and 20 and whether the actual midpoint must be increased or decreased.
- 33. Select one of the heads. Loosen the two bolts securing the sector/presector photocell mounting block to the disk drive main deck (Figure 6-10). Turn the mounting block adjusting screw under the solenoid arm clockwise to decrease or counterclockwise to increase the period. Stop adjusting when the period of the selected head has been changed by the amount and in the direction determined in step 32.

- 34. Press (to extinguish) the START switch. Remove the CE disk pack from the spindle.
- 35. Install the diode card at X10 on the read/write logic chassis.
- 36. Return the plug connections to the original configuration.

HOME CELL MECHANICAL ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Remove the disk storage drive front panel.
- 3. Set the power supply circuit breakers to ON.
- 4. Connect the ground of an oscilloscope to the maintenance panel GROUND jack.
- 5. Connect the oscilloscope probe to the left leadwire terminal of the home cell phototransistor plate.

NOTE

The home cell may be considered saturated if the voltage drop across the photocell is less than 0.6 vdc.

- 6. Disengage the detent pawl and move the carriage to a position that results in maximum light on the home cell phototransistor. The oscilloscope should indicate a minimum of +4.5 vdc. Check the photocell supply voltage (black leadwire) and the output voltage. The photocell must be saturated.
- 7. Manually pull the detent pawl and position the carriage at track 00. The oscilloscope should indicate an output of -0.7 ± 0.2 vdc. Position the carriage at track -01. The output should be a minimum of +3 vdc. If these requirements are met, proceed to step 10.

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8. If the requirements were not met, check the track indicator adjustment according to steps 10 and 11 of the Track Photocell Rotational Adjustment procedure. If this does not solve the problem, position the carriage at Track 00 and loosen the two screws securing the notched mask (nearest to spindle) to the carriage. Position the mask, holding a clearance of approximately 1/16-inch between the mask and the mask of the phototransistor plate, until an output of -0.7 ± 0.2 vdc is attained. Tighten the screws securing the mask. Position

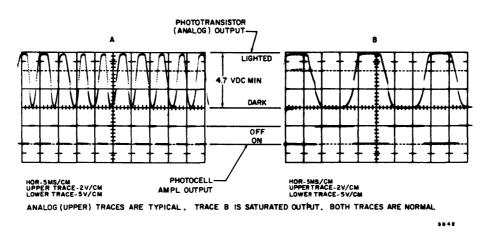
the carriage at Track -01. The output should be a minimum of +3 vdc. If this requirement is not met, replace the fiber optic and/or phototransistor.

- 9. Position the carriage at Track 202. The oscilloscope should indicate an output of -0.7 ± 0.2 vdc. Position the carriage at Track 203. The output should be a minimum of +3 vdc. If these requirements are met, proceed to step 11.
- 10. If the requirements were not met, position the carriage at track 202. Loosen the two screws securing the unnotched mask (farthest from the spindle) to the carriage. Position the mask, holding a clearance of approximately 1/16-inch between the mask and the mask of the phototransistor plate until an output of -0.7 ± 0.2 vdc is attained. Tighten the screws securing the mask. Position the carriage at Track 203. The output should be a minimum of +3 vdc. If this requirement is not met, replace the fiber optic and/or phototransistor.
- 11. Disconnect the oscilloscope.

TRACK/SPEED PHOTOCELL MECHANICAL ADJUSTMENT

- 1. Open and latch the disk storage drive top rear cover.
- 2. Remove the disk drive front panel.
- 3. Set the power supply MAIN POWER and ± 20 vdc circuit breakers to ON.
- 4. Connect the ground of an oscilloscope to the maintenance panel GROUND jack.
- 5. Connect the oscilloscope probe to the yellow leadwire terminal of the track phototransistor plate.
- 6. Manually pull the detent pawl and move the carriage back and forth. The photocell output trace should be an excursion between a low voltage of -0.6 ± 0.4 vdc and a high voltage of $+5.0 \pm 0.5$ vdc (Figure 6-12). The photocell must saturate (flat top) at the high voltage level as the carriage is moved back and forth. If the requirement is not met, unhook the pawl spring from the grooved pin. Slowly rotate the detent gear until the oscilloscope trace amplitude is maximum. If the photocell does not saturate, correct the situation according to one of the following:
 - Perform the Fiber Optic Adjustment procedure.

- Loosen the two screws through the photocell clamps. Reposition the photocell radially for a maximum amplitude. Make certain that the photocell is sensing the correct row of slots on the timing disk. Tighten the clamp screws.
- Refer to the Power Level Adjustment procedure. Adjust R03 until the cell saturates (do not exceed +6.0 vdc).



• Replace the fiber optic and/or phototransistor.

Figure 6-12. Photocell/Amplifier Outputs

- 7. If the screws in the photocell clamp were loosened in step 6, hook the pawl spring over the grooved pin and perform the Track Phototcell Rotational Adjustment and the Actuator Dynamic Tests and Adjustments procedures.
- 8. Connect the oscilloscope probe to the yellow leadwire terminal of the speed phototransistor plate. Repeat step 6.
- 9. Hook the pawl spring over the grooved pin.
- 10. Disconnect the oscilloscope.

TRACK PHOTOCELL ROTATIONAL ADJUSTMENT

- 1. Open and latch the disk storage drive top rear cover.
- 2. Remove the disk storage drive front panel.

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- 3. Set the power supply MAIN POWER and ± 20 vdc circuit breakers to ON.
- 4. Connect the ground of an oscilloscope to the maintenance panel GROUND jack.
- 5. Connect the oscilloscope probe to the yellow leadwire terminal of the track phototransistor plate.
- 6. Disengage the detent pawl and move the carriage forward to approximately Track 100. Allow the pawl tip to engage the detent gear between the teeth.
- 7. Loosen the three screws securing the photocell mounting plate (Figure 6-6).
- 8. Slowly rotate the photocell mounting plate counterclockwise.
- 9. Tighten the three screws securing the photocell mounting plate. Make certain that the oscilloscope trace amplitude is still 0 vdc.
- 10. Disengage the detent pawl and position the carriage until the fiber optic light spot is located between the first two track slots clockwise from the blank area (interruption in slots), Figure 6-6. Release the detent pawl. The track indicator pointer should be pointing at 00 on the timing disk. Reposition the pointer as required.
- 11. Disengage the detent pawl and move the carriage out to the forward stop. The track indicator index should be between the Track 01 and 05 marks. If this requirement is not met, perform the Carriage Limit Stop Adjustment procedure.
- 12. If any adjustment was performed in step 8, perform the Actuator Dynamic Tests and Adjustments procedure.

CARRIAGE LIMIT STOP ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Disengage the detent pawl and move the carriage out to the forward stop. The track indicator index should be between the Track 01 and 05 marks on the timing disk. If this requirement is met, proceed to step 7.
- 4. If the requirement of step 3 is not met, remove the screws securing the head diode board. Under the diode board (and above the Delrin block, Figure 6-13)

is a setscrew. Free the Delrin block by removing the screw immediately to the rear of this setscrew. Pull the Delrin block clear of the top edge of the carriage.

- 5. With the carriage against the forward stop, disengage the detent pawl and lift the front of the carriage slightly. Manually turn the detent gear until the track indication is between the Track 01 and 05 marks on the timing disk.
- 6. Lower the front end of the carriage, slide the Delrin block in place, and secure the rear screw.
- Disengage the detent pawl and position the carriage at approximately Track 100. Using a feeler gage, check that the gap dimension between the bottom of the Delrin block and the top of the carriage (Figure 6-13) is between 0.001 and 0.004 inch.
- 8. If the requirement is not met, remove the head diode board (if not already removed). Adjust the setscrew (located above Delrin block) to attain the correct dimension.
- 9. Disengage the detent pawl and check that the established dimension is maintained as the carriage is positioned at various tracks. Secure the head diode board to the top of the actuator.
- 10. Disengage the dentent pawl and extend the carriage until the cam follower just contacts the cam lug washer. The carriage stop bumper should be horizontal and just contacting the carriage mount below the home photocell assembly.

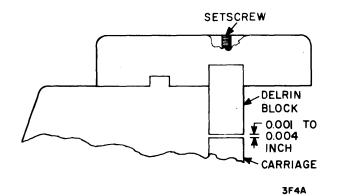


Figure 6-13. Carriage Limit Stop Adjustment

11. If the requirement of step 10 is not met, loosen the locking nut and adjust the stop. Tighten the locking nut.

HEAD LATCH SOLENOID AND SWITCH ADJUSTMENT

- 1. Open and latch the top rear cover.
- 2. Set all power supply circuit breakers except ACCESS MOTOR and DETENT to ON.
- 3. Install a disk pack. Pull upward on the rear cover interlock switch. Turn the Microswitch Actuation Adjust (Figure 6-14) counterclockwise until is is completely clear of the microswitch actuating arm.
- 4. Press (to light) the START switch. The Access Ready indicator should not be lighted.
- 5. With the detent pawl disengaged from the detent gear, manually push the carriage forward while observing the head latch cam and arm. Stop moving the carriage as soon as the cam and arm become latched.
- 6. Remove the disk storage drive front panel. Ground an oscilloscope at the maintenance panel GROUND jack. Connect the oscilloscope probe to logic chassis test point A28C. The oscilloscope should indicate a voltage level of -3.0 vdc. Adjust the Microswitch Actuation Adjustment until the voltage level changes to -0.5 vdc, then turn the actuation adjustment an additional three-quarter turn. Tighten the adjustment setscrew locking nut. Disconnect the oscilloscope.
- 7. When the heads are latched, surface A (Figure 6-14) of the head latch must be vertical and the solenoid armature should be fully retracted. If this requirement is not met, loosen the two screws securing the solenoid to the bracket, and reposition.

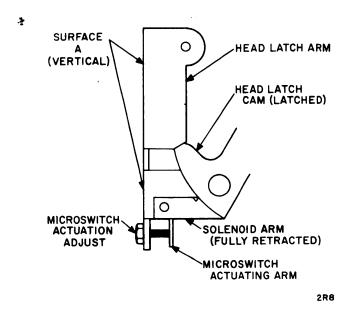


Figure 6-14. Head Latch Solenoid Adjustment

CAM LATCH SOLENOID ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Set the power supply circuit breaker to ON.
- 3. Mount a disk pack on the spindle and tighten in place.
- 4. Set the ACCESS MOTOR and DETENT circuit breakers to OFF.
- 5. Pull upward on the rear cover interlock switch.
- 6. Press (to light) the START switch.
- 7. Manually disengage the detent pawl and move the carriage seven tracks forward.
- 8. Push the head loading cam forward until it locks in the upturned position.
- 9. Loosen the two screws securing the cam latch solenoid to the mounting bracket.
- 10. To prevent binding of the actuator arm, adjust the solenoid so that the actuator arm is parallel with the mounting bracket (Figure 6-15).

- 11. Tighten the two solenoid mounting screws.
- 12. Loosen the three screws securing the mounting bracket to the carriage mount assembly.

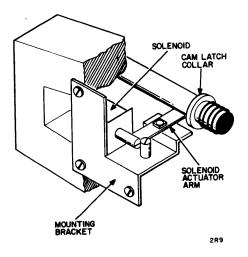


Figure 6-15. Cam Latch Solenoid Adjustment

The solenoid actuator arm must contact the cam latch collar with just enough tension so that the head loading cam (when energized) can be manually pulled back and when released will snap forward into the locked position.

- Move the cam latch assembly until the solenoid actuator arm contacts the cam latch collar (Figure 6-15). Move the assembly forward so that the solenoid is slightly preloaded.
- 14. Tighten the mounting bracket top screw.
- 15. Tighten the two lower screws. Make certain the heads retracted switch is actuated within the last 1/4-inch of carriage motion before encountering the fully retracted stop.

COVER INTERLOCK SWITCHES ADJUSTMENT

- 1. Set the power supply MAIN POWER circuit breaker to OFF. Open and latch the top rear cover.
- 2. Adjust the top rear cover interlock switch as follows:
 - a. Connect an ohmmeter across the leadwire terminals of the rear cover interlock switch, S306 (located below and at rear of actuator).
 - b. Push the switch post down (to simulate top rear cover closed). The ohmmeter should indicate 0 ohm.
 - c. Allow the switch post to spring upward. The ohmmeter should indicate infinity. Disconnect the ohmmeter.
 - d. Lower the top rear cover while listening for the switch to close.
 - e. If the switch does not actuate when the cover is closed, loosen the screws in the switch mounting bracket and move the assembly upward. Repeat step d.
- 3. Adjust the front cover interlock switch as follows:
 - a. Connect an ohmmeter across the leadwire terminals of the front cover interlock switch, S304 (located on interior surface on actuator side of top rear cover).
 - b. Open and close the front cover while observing the ohmmeter indication.
 - c. The ohmmeter should indicate 0 ohm when the cover is closed and infinity when the cover is open. The switch should operate when a gap of 1.0 ± 0.5 -inch exists between the front edge of the cover and the frame.
 - d. If the switch does not operate as required, loosen the two screws securing the switch and reposition it vertically.

ACTUATOR DYNAMIC TESTS AND ADJUSTMENTS

NOTE

In the following procedures, it is necessary to command the disk drive to perform various seek lengths. These commands may be derived from a disk storage drive exerciser or by using suitable software and the computer. Unit must meet requirements of Detent Adjustment and Delay Tests and Adjustments procedures before performing this procedure.

- 1. Open and latch the top rear cover of the disk drive.
- 2. Set the power supply circuit breakers ON.
- 3. Remove the front panel and connect the ground of an oscilloscope to the maintenance panel GROUND jack.
- 4. Install a disk pack. Pull upward on the rear cover interlock switch (behind carriage). Press (to light) the START switch.

CAUTION

A tachometer must be used when performing the following adjustments.

- 5. Attach a tachometer (84362900) to the access motor shaft.
- 6. Connect the oscilloscope external trigger to test point A of I218 Any Seek(C25). Connect the tachometer leadwires to the oscilloscope preamplifier input and preamplifier ground. Connect the tachometer leadwires so that a Forward Seek shows a positive envelope on the oscilloscope.
- 7. Command the disk storage drive to perform a 3-track repeat seek (three tracks forward and three tracks reverse, continuously) centering on Track 100.

NOTE

The bottom traces shown on Figure 6-16 through 6-18 are provided for information only. They need not be displayed during the related procedure.

 Set the oscilloscope vertical to 0.2 v/cm and the horizontal to 5 ms/cm. Compare the oscilloscope trace to Figure 6-16, part A.

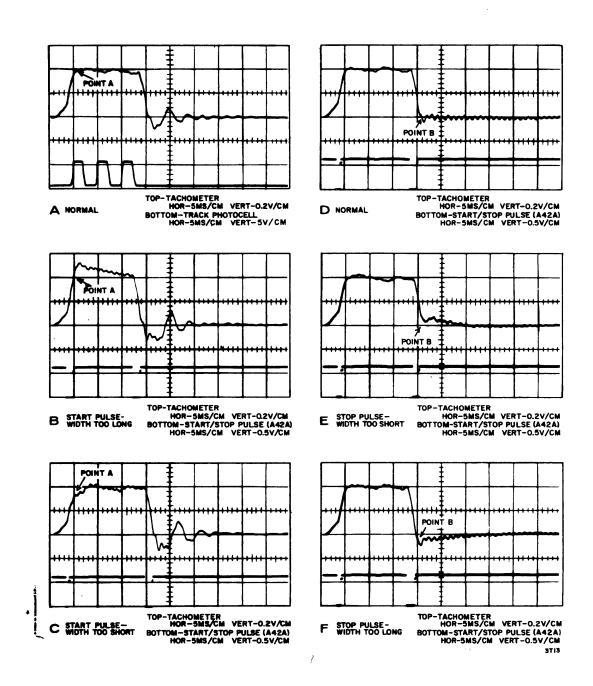


Figure 6-16. Tachometer Output (3-Track Forward Seek)

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- 9. The average amplitude (Figure 6-16, part A) should be 0.040 vdc. Adjust the amplitude with the potentiometer on Y307 at logic chassis location B36 (counter-clockwise adjustment increases the amplitude).
- 10. The start pulse applies high current to the access motor that causes acceleration from stop to 2 ips (Figure 6-16, part A, point A) in approximately 2 ms. The width of the start pulse is controlled by the potentiometer on Y315 at logic chassis location D37. Turn the potentiometer shaft clockwise until the oscilloscope trace overshoots Figure 6-16, part B, point A. Turn the potentiometer shaft counterclockwise until the overshoot disappears (Figure 6-16, part A). Figure 6-16, part C depicts an undershoot condition.
- 11. The stop pulse applies high (reverse) current to the access motor that causes deceleration from 2 ips to 0 ips (Figure 6-16, part D, point B) in approximately 2 ms. The width of the stop pulse is controlled by the potentiometer on Y332 at logic chassis location D32. Adjust the pulse width as follows:
 - a. While the actuator performs the 3-track repeat seek, disengage and hold the detent pawl clear of the detent gear. Observe point B on the oscillo-scope.
 - b. If point B is located above 0 vdc (Figure 6-16, part E) the stop pulse is too narrow. Turn the potentiometer shaft clockwise.
 - c. If point B is located below 0 vdc (Figure 6-16, part F), the stop pulse is too wide. Turn the potentiometer shaft counterclockwise.
- 12. The forward stop pulse delay is the time between the trailing edge of the last track pulse and the leading edge of the stop pulse during a Forward seek. This delay times the dropping of the detent pawl with respect to the detent gear position. Figure 6-17 shows the tachometer output trace for a properly adjusted delay (point A is where the pawl should engage the gear and area A is the resulting carriage rebound caused by engagement). The pawl should not engage the gear before zero velocity is reached. The amplitude and duration of TA is primarily a function of the accuracy of the detent gear and the timing disk assembly. It is therefore necessary to inspect the operation at a minimum of three positions (approximately Tracks 09, 100, and 189).

Make certain that the oscilloscope displays the tachometer output resulting from the forward portion of the repeat seek.

- a. While the actuator performs a 3-track repeat seek centering on Track 100, observe the resulting trace.
- b. Adjust Y331 (D33) to make the trace approximate Figure 6-17, if required.
- c. The width of TA should be 5 ± 3 ms.
- d. Position the carriage to Track 09 and 189. At each position command a 3-track repeat seek and repeat step c.
- e. If the optimum (Figure 6-17) tachometer output cannot be achieved, perform the procedures of step 14.

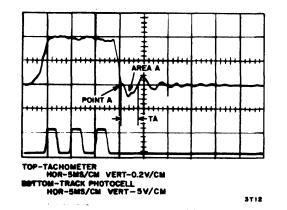


Figure 6-17. Tachometer Output (Forward Seek)

13. The reverse stop pulse delay is the time between the trailing edge of the last track pulse and the leading edge of the stop pulse during a Reverse Seek. This delay times the dropping of the detent pawl with respect to the detent gear position. Figure 6-18 shows the tachometer output trace for a properly adjusted delay (area B is the rebound caused by the pawl/gear engagement). The pawl should not engage the gear before zero velocity is reached. The amplitude and duration of TB is primarily a function of the accuracy of the detent gear and timing disk assembly. It is therefore necessary to inspect the operation at a minimum of three positions (approximately Tracks 09, 100, and 189).

Make certain that the oscilloscope displays the tachometer output resulting from the reverse portion of the repeat seek.

- a. Connect the oscilloscope external trigger to test point C of K214 Reverse FF (C28). While the actuator performs a 3-track seek centering on Track 100, compare the trace to Figure 6-18.
- b. Adjust Y330 (D34) to make the trace approximate Figure 6-18, if required.
- c. The width of TB should be 2(+3, -2) ms.
- d. Position the carriage to Track 09 and 189. At each position command a 3-track repeat seek and repeat step c.
- e. Recheck step 12 and then proceed to step 14.

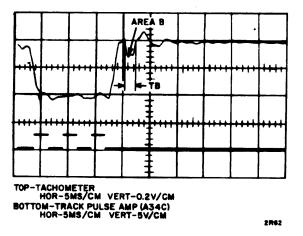


Figure 6-18. Tachometer Output (Reverse Seek)

- 14. Perform the dynamic test and adjustment of the track photocell as follows:
 - a. Command the disk storage drive to perform a 3-track repeat seek centering on Track 100.
 - b. Monitor the tachometer output on one channel of the oscilloscope.
 Connect the other channel to the yellow leadwire terminal of the track phototransistor plate.

- c. Refer to Figure 6-19, part A, for oscilloscope settings. Each of the Track pulses should swing between a low voltage of -0.6 ± 0.4 vdc and a high voltage of $+5.0 \pm 0.5$ vdc. There should be no track pulses of less amplitude during the settle time (as shown by FAULT on Figure 6-19, part A). If the extra pulses do exist, they will be corrected during the following steps.
- d. If the amplitude of the track pulses is less than +4.7 vdc, adjust the track photocell according to the Track/Speed Photocell Mechanical Adjustment procedure.
- e. Disconnect the oscilloscope probe at the track photocell and connect it to the track pulse amplifier, test point C at logic chassis location A34.
- f. Connect the oscilloscope external trigger to test point A of I218 Any Seek (C25). Command the disk storage drive to perform a 1-track repeat seek (one track forward and one track reverse, continuously) at Track 100.
- g. Refer to Figure 6-19, part B, for oscilloscope settings and compare waveforms. The track pulses should be approximately coincidental (leading and trailing edges of pulse vertically aligned).
- h. Slightly loosen the three screws securing the photocell mounting plate, Figure 6-6.
- As the unit performs the 1-track repeat seek, observe the pair of track pulses on the oscilloscope. If the forward pulse is to the left of the reverse pulse, very lightly tap the photocell mounting plate downward. If the forward pulse is to the right of the reverse pulse, place a screw-driver between the main deck and the bottom of the photocell mounting plate and force the plate upward.
- j. When the oscilloscope trace is similar to Figure 6-19, part B, tighten the three locking screws in the photocell mounting plate. Make certain that the trace does not change.
- k. Disconnect the oscilloscope (except the ground connection).
- 1. Moving the photocell mounting plate changed the reference of the forward and reverse stop pulse delays. Repeat steps 12 and 13. If the forward or reverse delay cannot be made short enough (pawl engages gear before zero velocity is reached) in steps 12 or 13, the photocell mounting block may be repositioned to favor the direction in which the difficulty occurs.

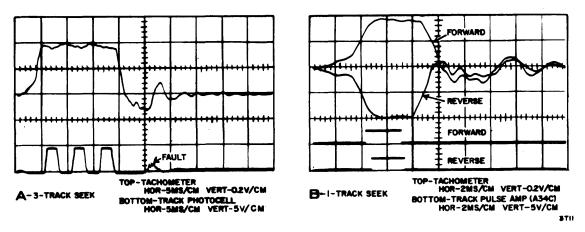


Figure 6-19. Dynamic Track Photocell Adjustment

- 15. Perform the seek profile tests and adjustment as follows:
 - a. Connect the oscilloscope external trigger to test point A of I218 Any Seek (C25). Monitor the tachometer output on one channel of the oscilloscope. Connect the other channel to the track pulse amplifier at test point C of logic chassis location A34.
 - b. Command the disk storage drive to perform a 4-track repeat seek (four tracks forward and four tracks reverse continuously) centering at Track 100. Refer to Figure 6-20, part A for oscilloscope settings and the required trace. If required, adjust the potentiometer shaft at B43 (Y313) until there is a sharp drop from the higher velocity to the 2 ips plateau without any overshoot at point A.
 - c. Command the disk storage drive to perform a 16-track repeat seek centering at Track 100. Refer to Figure 6-20, part B for oscilloscope settings and the required trace. If required, adjust the potentiometer shaft at B35 (Y306) so that the 6 ips plateau amplitude is approximately 1.2 volts and the 2 ips plateau occurs before the next to last track pulse.

If the 6 ips plateau is not flat, repeat step 13. If the track pulse timing is difficut to read due to signal instability, lower the 6 ips speed slightly and it will settle down.

- d. Command the disk storage drive to perform a 64-track repeat seek centering at Track 100. Refer to Figure 6-20, part C for oscilloscope settings and the required trace. If required, adjust the potentiometer shaft at B34 (Y305) so that the 15 ips plateau amplitude is approximately 3 volts and the period of the 6 ips plateau is 6 ± 2 ms.
- e. Command the disk storage drive to perform a 128-track repeat seek centering at Track 100. Refer to Figure 6-20, part D for oscilloscope settings and the required trace. If required, perform the following adjustments.
 - Adjust the 6 ips plateau (shaft at B35) to a position that ensures the start of the 2 ips plateau by the end of the next to last track pulse.
 - Adjust the 15 ips plateau (shaft at B34) to a position that causes the
 6 ips plateau to have a period of 6 ± 2 ms.
- f. Command the disk storage drive to perform a 202-track repeat seek. Refer to Figure 6-20, part E for oscilloscope settings and the required trace. The duration of the 15 ips plateau should be 5 ms minimum. The duration of the 15 ips plateau is controlled by changing its amplitude Raising the amplitude lengthens the duration. If the 5 ms minimum duration is not met, readjust the 6 ips and 15 ips plateaus as described in step 3 (with the actuator performing a 202-track repeat seek).

READ OPERATION TEST AND ADJUSTMENT

1. Open and latch the top rear cover of the disk storage drive.

NOTE

The following procedure requires that data be written on a disk pack via a disk storage drive exerciser or the central processor. Timing measurements of the recorded data require that the oscilloscope be triggered from an external source that is synchronous with the data being displayed. Oscilloscope synchronizing with the Index pulse or internally on the signal results in signal instability that may make measurements unreliable. If a disk storage drive exerciser is used, a suitable sync point is available at exerciser test point D, location A04. Amplitude measurements can be made with the oscilloscope triggered by Index test point C, logic chassis location C27.

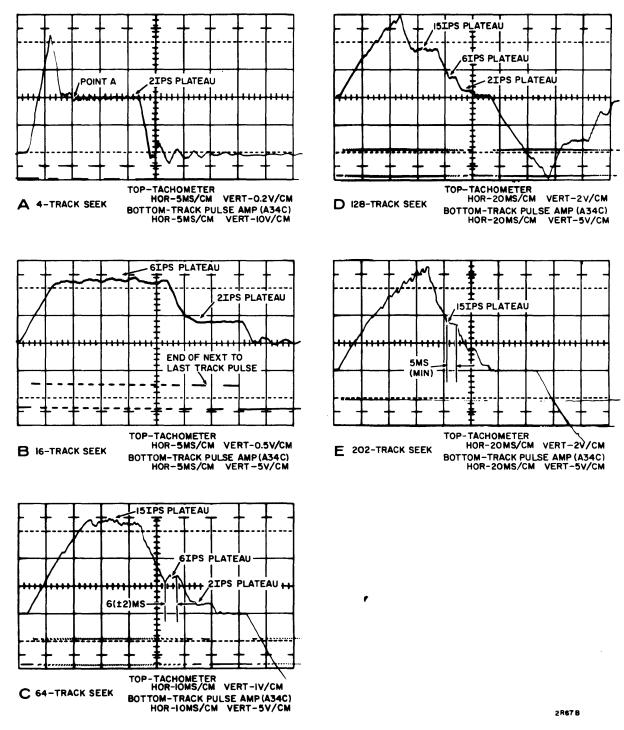


Figure 6-20. Tachometer Output (Various Seek Lengths)

- 2. Remove the disk storage drive rear panel. Set the power supply circuit breakers to ON. Mount a disk pack (not a CE disk pack) on the spindle and tighten in place.
- 3. Pull the post of the interlock switch (behind carriage) upward. Press (to light) the START switch.
- 4. Test and adjust the ATB/ATC card adjustment as follows:
 - a. Write a pattern of all "1's" with each head at Track 202.
 - b. Ground an oscilloscope at the maintenance panel GROUND jack. Connect the external trigger according to the above note. Connect the oscillo-scope differentially to test points A and B of the EUC card at X09 (read/write logic chassis).
 - c. Select any head and read Track 202. Make oscilloscope settings according to Figure 6-24, part C.
 - d. Turn the potentiometer shaft on the ATB/ATC card at X13 (read/write logic chassis) clockwise until the amplitude of the trace is maximum, then turn the shaft three turns counterclockwise. The amplitude of the signal (Figure 6-24, part C) will be a minimum of 0.6 volt.
- 5. Test and adjust the EWC card adjustment as follows:
 - a. Write a pattern of all "1's" with each head at Track 202.
 - b. Ground an oscilloscope at the maintenance panel GROUND jack. Connect the external trigger according to the above note. Connect the oscillo-scope probe to test point C of L402 (D23).
 - c. Select any head and read Track 202. Make oscilloscope settings and a trace comparison according to Figure 6-21.
 - d. The pulses should be 150 ± 50 nsec wide and should occur every 400 nsec. Adjust the pulse symmetry with the potentiometer shaft at D22, if required.
 - e. Select several heads. There should be no measurable difference in the symmetry of the traces for any of the heads.

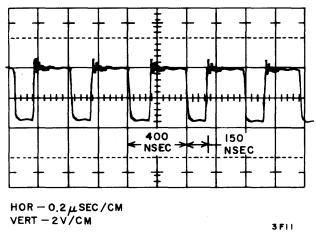


Figure 6-21. Pulse Shaper Trace

- 6. Test the read/write head peak shift as follows:
 - a. Write a pattern of alternate "1's" and "0's" with each head at Track 202.
 - b. Ground an oscilloscope at the maintenance panel GROUND jack. Connect the external trigger according to the above note. Connect the oscilloscope probe to test point C of L402 (D23).
 - c. Select any head and read Track 202. Make oscilloscope settings and a trace comparison according to Figure 6-22, parts A and B. The trace should meet the requirements of Figure 6-22, part B.
 - d. Repeat step c for the remaining read/write heads.
 - e. If the requirements of Figure 6-22 are not met, replace the applicable head/arm assembly and/or the related torsion arm assembly.
- 7. Test and read/write head amplitude as follows:
 - a. Ground an oscilloscope at the maintenance panel GROUND jack. Connect the external trigger according to the above note. Connect the oscilloscope differentially to test points A and B of the EUC card at X09 (read/write logic chassis).

b. Refer to Figure 6-23 and 6-24. Write the pattern of "1's" or "0's" on the specified track with all heads. Read the data from each head and compare it with the applicable figure. The figures depict typical amplitudes that will be encountered. A pattern of all "1's" at Track 202 (Figure 6-24, parts A and C) should result in a minimum amplitude of approximately 1 volt, although amplitudes of slightly less are acceptable if no readback problems have been encountered.

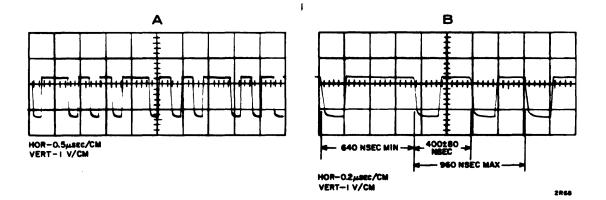


Figure 6-22. Read/Write Peak Shift

DELAY TESTS AND ADJUSTMENTS

The procedures of this paragraph cover the following delays: Y203 and Y221 (Selected Drive Ready) and Y312.

NOTE

In the following procedures, it is necessary to command the disk storage drive to perform seek operations. These commands may be derived from a disk storage drive exerciser or by using the central processor.

- 1. Remove the disk storage drive rear panel and set the power supply circuit breakers to ON.
- 2. Install a disk pack. Press (to light) the START switch.

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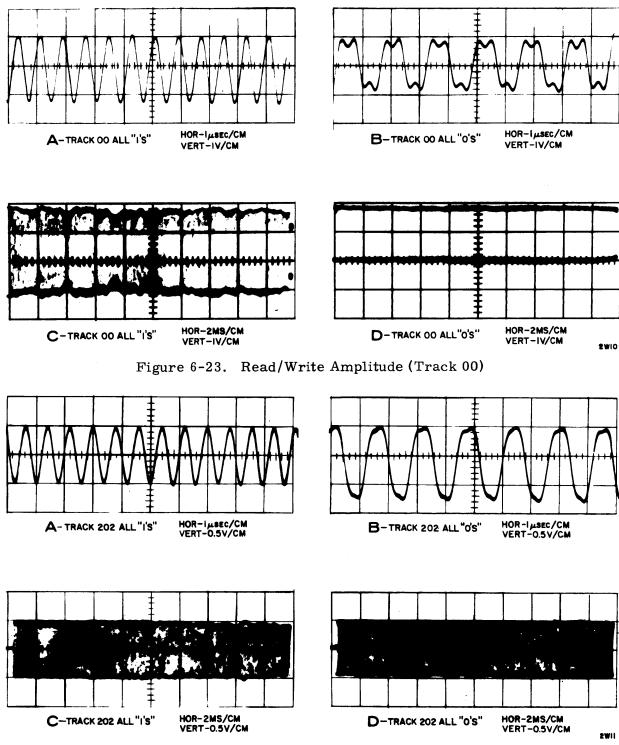


Figure 6-24. Read/Write Amplitude (Track 202)

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- 3. Remove the disk storage drive front panel. Ground an oscilloscope at the maintenance panel GROUND jack.
- 4. Adjust delays Y203 and Y221 as follows:
 - a. Connect the oscilloscope external trigger and channel A probe to test point C of I220 (B28). Set the External Sync switch to positive.
 - b. Connect the channel B probe to test point A of Y203 (A30).
 - c. Command the disk storage drive to perform a 1-track repeat seek operation.
 - Make oscilloscope settings and track comparisons according to
 Figure 6-25, part A. Adjust the potentiometer shaft on Y203 until its output pulse is delayed by 10 ms with respect to the "0" output of I220.
 - e. Connect the oscilloscope external trigger and channel A probe to test point A of Y203 (A30).
 - f. Connect the channel B probe to test point A of Y221 (A36).
 - g. Make oscilloscope settings and trace comparisons according to
 Figure 6-25, part B. Adjust the potentiometer shaft on Y221 until its
 output pulse is delayed by 200 usec with respect to the "0" output of Y203.
 - h. Stop the Seek operation.
- 5. Adjust delay Y312 as follows:

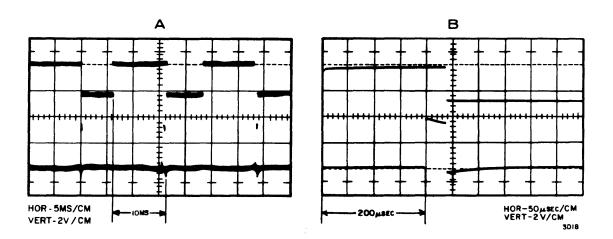


Figure 6-25. Selected Drive Ready Delay Timing

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- a. Connect the oscilloscope external trigger and channel A probe to test point C of K213 Detent FF (C38). Set the External Sync switch to positive.
- b. Connect the channel B probe to test point C of Y312 (B42).
- c. Set the oscilloscope horizontal sensitivity of 0.5 ms/cm. Command the disk storage drive to perform a 1-track repeat seek.
- d. Observe the delay time of Y312. Slowly turn the potentiometer shaft counterclockwise. Note the duration of the delay when the detent fails to pick.
- e. Turn the shaft a few turns clockwise and restart the disk storage drive. Continue to turn the shaft clockwise until the delay time is 0.5 ms greater than the delay noted in step d, or equals 2 ms.
- f. If the final delay time (step e) is not the same as the initial delay time (step d), perform the Actuator Dynamic Tests and Adjustments procedure.
- 6. Disconnect the oscilloscope.

POWER LEVEL ADJUSTMENT

- 1. Remove the disk storage drive rear panel.
- 2. Set the power supply MAIN POWER, +20 and -20 circuit breakers to ON.

WARNING

Dangerous voltages are present in the power supply. When making power supply adjustments, do not contact interior components other than those to be adjusted.

3. Using a multimeter, make voltage checks and adjustments as follows:

NOTE

Voltage measurements made at the read/write logic chassis necessitate opening the disk drive top rear cover. When this is done, power is removed unless the cover Interlock switch behind the carriage is pulled upward.

- a. Measure +20 (+1, -0) vdc at read/write logic chassis locations X22-15 and -14 (ground). Unlatch power supply panel and adjust rheostat R03 if required.
- b. Measure -20 (-1, +0) vdc at read/write logic chassis locations X22-13 and -14 (ground). Unlatch power supply panel and adjust rheostat R04 as required.

In the following step R03 is a part of the auxiliary power supply located on the disk storage drive directly below the main power supply chassis.

c. Measure $+5.7 \pm 0.2$ vdc at the power supply LAMP and DC GRD jacks. Adjust R03 in the auxiliary power supply if required.

POWER SUPPLY TROUBLESHOOTING PROCEDURE

External test equipment connections to the power supply are made to test points on the front panel of the unit (located behind the lower rear panel). The terminals are labeled for easy reference.

Troubleshooting of the individual portions of the power supply requires that the front panel be lowered. If the power supply must be opened, observe the following warning.

WARNING

Make certain that the power supply is not connected to any power source, and that all capacitors have been discharged before making any external connections.

Initially troubleshoot the power supply by checking the following:

- 1. Using a multimeter, note the output voltage and ripple at the front panel test points.
- 2. Check the line voltage applied to the power supply.

3. Visually inspect the power supply for burned or damaged parts, foreign matter, and loose leads.

WARNING

The power supply is capable of producing voltages that are dangerous. Whenever measurements are being made on internal components, be sure that the measuring equipment case has a common ground with the power supply. Whenever test equipment leads are attached or removed, the power supply should be turned off.

The troubleshooting chart (Table 6-1) lists the symptom, probable cause, and remedy. To properly check the power supply and associated circuits, match the observed symptom with the symptom on the chart, then complete the analysis and correction.

CAUTION

Before making any continuity measurement, remove all input power.

SYMPTOM	PROBABLE CAUSE	REMEDY
1. Phase indicators do not illuminate	a. No input power	Check to assure that the main power cable is connected.
	b. MAIN POWER circuit breaker defective	With the main power cable disconnected, check the con- tinuity of the circuit breaker.
	c. Defective wiring	Check the continuity of the phase wiring from input con- nector J01 to output connector J04.
	d. Lamp defective	Check, by replacement, the continuity of the lamp.
2. Phase lamps illuminate, but fans do not operate	Defective wiring	Check continuity of fans (the wiring between the phase A input and TB05-1, and the wiring between the phase C input and TB05-2).

TABLE 6-1. TROUBLESHOOTING CHART

SYMPTOM	PROBABLE CAUSE	REMEDY
3. Phase lamps illuminate, power supply fans operate, but logic chassis fans do not operate	Defective wiring	Check the continuity between the phase A wiring input and pin 1 of J05. Check the wir- ing between the phase C input wiring and pin 3 of J05. Make the necessary corrections.
4. No voltage at +20 test point	a. Loss of input voltage	Check voltage at pins 8 and 9 of ferroresonant transformer T01.
	b. Rectifier diode defective	Check continuity of rectifier diodes CR04A and CR04B.
	c. Capacitor C03 shorted	Check the continuity of the component using a multimeter set to the Rx1 meg scale.
	d. Resistor R03 defective	Check resistance of the resistor.
	e. Choke L02 open	Check continuity of the choke
	f. Contacts 3C and 3A of K02 are pitted	Check continuity of the relay contacts. Replace K02 if necessary.
	g. Capacitor C04 shorted	Check C04 using a multimeter set to the Rx1 meg scale.
5. Improper voltage at +20 test point	a. R03 needs adjustment	Adjust R03 for the proper output.
	b. Leaky or open output filter	Check C04 using a multimeter set to the Rx1 meg scale.
	c. Capacitor C03 open or leaky	Check C03 using a multimeter set to the Rx1 meg scale.
	d. CR13 shorted	Check reverse resistance of CR13 on the Rx100 scale.
	e. Improper front- to-back ratio on rectifier diodes CR04A and CR04B	Check and replace if defective.
	f. Bleeder resistor R02 open	Check resistance and replace if necessary.
6. Excessive ripple at +20 test point	a. Leaky or open output filter	Check C04 using a multimeter set to the Rx1 meg scale.
	b. Shorted turns of choke	Check and replace L02 if defective.

SYMPTOM	PROBABLE CAUSE	REMEDY
	c. Improper front- to-back ratio on rectifier diodes CR04A and CR04B	Check and replace if defective.
7. No voltage at -20 test point	a. Loss of input voltage	Check voltage at pins 8 and 9 of ferroresonant transformer T01.
	b. Rectifier diode defective	Check continuity of rectifier diodes CR01A and CR02A.
	c. Capacitor C01 shorted	Check C01 using a multimeter set to the Rx1 meg scale.
	d. Resistor R04 defective	Check resistance of resistor.
	e. Choke L01 open	Check continuity of choke.
	f. Contacts 4C and 4A of K02 are pitted	Check continuity of the relay contacts and replace K02 if necessary.
	g. Capacitor C02 is shorted	Check C02 using a multimeter set to the Rx1 meg scale.
8. Improper voltage at -20 test point	a. R04 needs adjustment	Adjust R04 for the proper output.
	b. Leaky or open output filter	Check C02 using a multimeter set to the Rx1 meg scale.
	c. Capacitor C01 open or leaky	Check C01 using a multimeter set to the Rx1 meg scale.
	d. Diode CR14 is shorted	Check reverse resistance of CR14 on the Rx100 scale.
	e. Improper front- to-back ratio on rectifier diodes CR01A and CR02A	Check and replace if defective.
	f. Bleeder resistor R01 open	Check the resistance and replace if necessary.
9. Excessive ripple at -20 test point	a. Leaky or open output filter	Check C02 using a multimeter set to the Rx1 meg scale.
	b. Shorted turns of filter choke	Check and replace L01 if defective.
	c. Improper front- to-back ratio on rectifier diodes CR01A and CR02A	Check and replace if defective.

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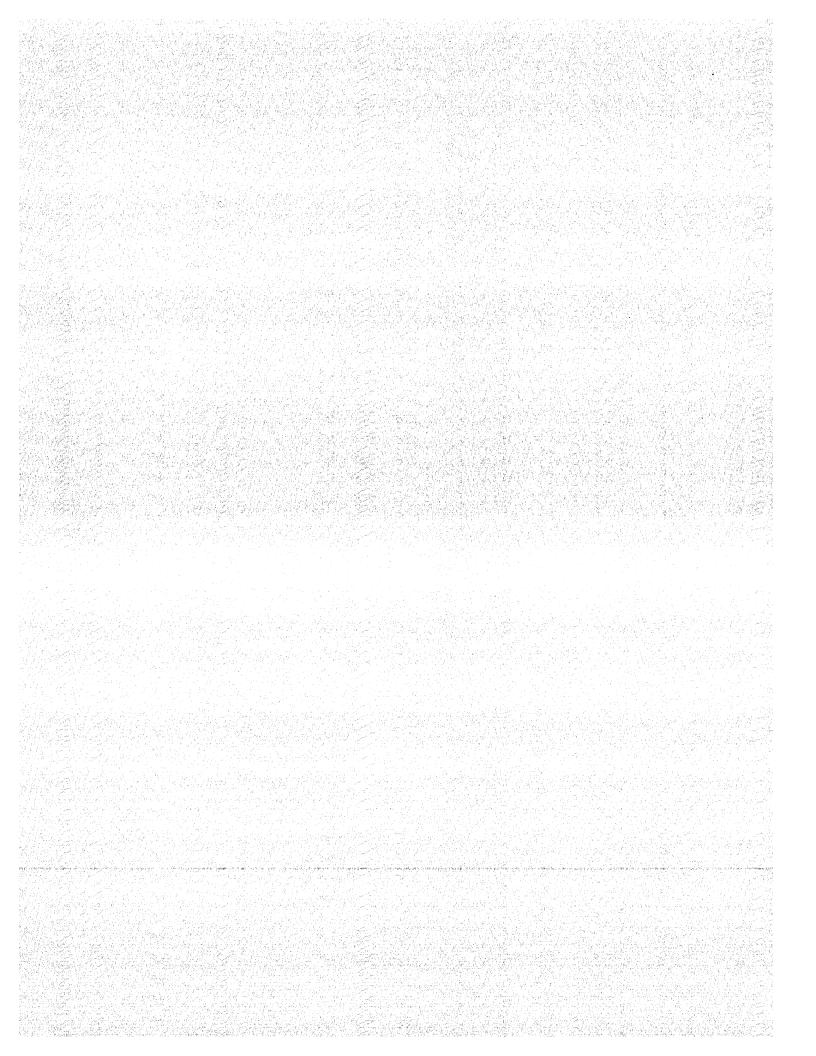
SYMPTOM	PF	OBABLE CAUSE	REMEDY
10. No voltage at +20Y test point	a.	Capactior C09 C10, or C11 shorted	Check the capacitors using a multimeter set to the Rx1 meg scale.
	b.	Bad lead or broken solder connection.	Check continuity, isolate, and repair the defective lead.
11. Improper voltage at +20 Y test point	a.	Leaky or open capacitor	Check the capacitors using a multimeter set to the Rx1 meg scale.
	b.	Resistor R06 is open	Check and replace if defective.
12. Excessive ripple at +20Y test point.	a.	Leaky or open capacitor	Check the capacitors using a multimeter set to the Rx1 meg scale.
	b.	Improper front- to-back ratio on rectifier diodes CR01B and CR02B	Check and replace if defective.
13. No voltage at +40 test point	a.	No input power	Check the continuity from pins 8 and 9 of T01 to pins 1 and 2 of T02 respectively.
	b.	Transformer T02 is defective	Check the voltage developed across pins 3 and 5 of T02. Replace the transformer if defective.
	c.	Capacitor C07 is shorted	Check the capacitor using a multimeter set to the Rx1 meg scale.
	d.	Contacts of CB05 are not making contact	Check continuity and replace if necessary.
	e.	Contacts 1 and 7 of K05A are not making electri- cal contact	Check and replace K05 if defective.
	f.	Rectifier CR03A or B is shorted	Check the reverse resistance of the diodes using a multi- meter set to the Rx1 meg scale.

	SYMPTOM	P	ROBABLE CAUSE	REMEDY
14.	Improper voltage at +40 test point	a.	One half of the transformer is shorted or open	Check continuity and replace if necessary.
		b.	Rectifier CR03A or B is defective	Check the forward and reverse resistance using a multimeter set to the Rx1 meg scale.
		c.	Capacitor C07 is leaky	Check and replace if necessary.
		d.	Resistor R09 is defective	Check continuity and resis- tance of the resistor.
		e.	Bad lead or broken solder connection	Check continuity, isolate, and repair the defective lead.
15.	Excessive ripple at +40 test point	a.	Leaky or open capacitor	Check C07 and replace if defective.
		b.	Rectifier CR03A or B is defective	Check the forward and reverse resistance using a multimeter set to the Rx1 meg scale.
16.	No automatic First Seek	а.	H switch failure circuit	With the disk drive in the on condition and the START switch ON, check the base bias of the forward transistors and check the applied supply voltages. Repair the defect.
		b.	Bad lead or solder connection	Check continuity, isolate, and repair the defective lead.
		c.	Detent pawl not pulled	Check Q07 and associated circuit. Replace if defective.
		d.		Check transistor Q01 and associated circuit. Replace defective part.
17.	Heads are loaded but no reverse drive	a.	Reverse drive transistors Q05 or Q04 are defective.	Check transistors and replace if defective.
		b.	Bad lead or solder connec- tion	Check continuity of H switch reverse drive section, isolate, and repair the defect.
18.	Brake solenoid not operating		Shunt diode is shorted	Check reverse resistance of CR05 using a multimeter set to Rx100 scale.

SYMPTOM	PROBABLE CAUSE	REMEDY	
	b. Relay contacts not completing circuit or defective lead or solder con- nection	Check continuity, isolate, and repair defect.	
	c. Pawl binding	Check adjustment according to Section 6.	
19. Sequence power is not completed to successive units	a. Bad lead or broken solder connection or defective relay	Check continutiy of circuit, isolate, and repair defective lead or replace defective relay.	

SECTION 7

SPECIAL MAINTENANCE INFORMATION



SPECIAL MAINTENANCE INFORMATION

This section contains information required at the time of initial installation and setup.

INSTALLATION REQUIREMENTS AND PROCEDURES

The installation of the disk storage drive equipment requires only that allowance be made for the physical space requirements of the machine. These requirements are the height, width, depth, and weight of the machine plus 3 additional feet in front of and to the rear of the machine. This additional space is needed to allow for proper maintenance of the machine.

Figure 7-1 illustrates the outline dimensions of the equipment.

For an initial installation, the packing material should be removed and the disk storage drive carefully taken from the container. Inspection for shipping damage should then be made. All claims for damage should be filed promptly with the transportation company involved. If claims are filed for shipping damage, save the original packing case and materials.

INITIAL CHECKOUT PROCEDURE

NOTE

Machine adjustments should be made only if the unit is not operating properly. Adjustments may drift outside of the tolerances provided. Such drift should not in itself be cause for adjustment.

The following procedures and visual inspections should be performed at the site immediately following installation and before the disk storage drive is placed in operation. If the equipment does not respond as outlined, corrective procedures must be performed.

- 1. Open and latch the disk storage drive top rear cover. Inspect the actuator assembly and read/write heads for shipping damage.
- 2. Remove the tape from the top rear cover interlock switch.

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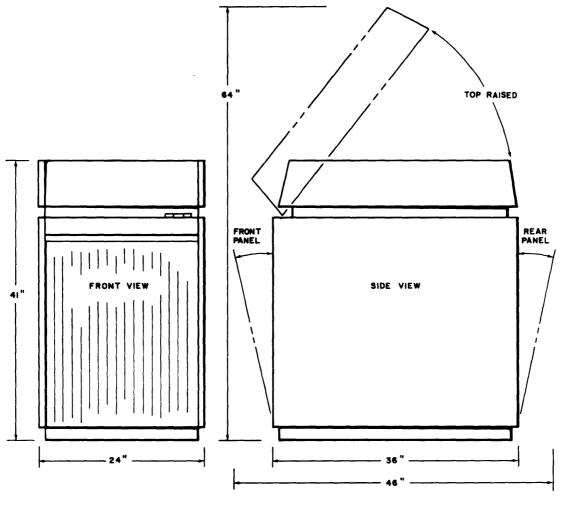


Figure 7-1. Outline Dimensions

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- 3. Remove the four rubber shipping blocks located at the corners between the main deck and frame.
- 4. Remove the tape holding the sector sensor assembly against its opening in the shroud. The sector sensor arm should pivot freely.

CAUTION

Any disturbance to the read/write heads in the following step could require a replacement or readjustment of one or more heads.

- 5. Remove the tape covering the shroud opening for the read/write heads. Inspect for any apparent head damage.
- Remove the carriage tie-down cord and the attached red identification tag.
 Do not attempt to move the carriage at this time.
- 7. Remove the disk storage drive front panel. Remove the two air filters which are taped to the inside of the panel.
- 8. Open and close the logic chassis assembly. If binding or drag occurs, adjust the upper and lower pivot brackets.
- 9. Check that all logic cards are firmly seated in their connectors.
- 10. Install the air filter in its slot at the bottom of the logic chassis (Figure 5-4).
- 11. Remove the disk storage drive rear panel.
- 12. Slide the power supply in and out of the unit. Replace any nylon rollers which do not move freely.
- 13. Install the air filter in its slot at the rear of the power supply (Figure 5-5).
- 14. Inspect the intracabling connections of the unit (Figure 7-2).
- Inspect the ground lead running from the home cell assembly to the carriage. Make certain that it is clear of all components and will not interfere with carriage movement.

CAUTION

The timing disk markings are a photo emulsion. In the following step, use extreme care to prevent scraping or scratching the disk.

- 16. Carefully inspect the glass timing disk and photocell mount assemblies. The timing disk should rotate freely as the carriage is moved and should not contact either the speed or track phototransistor plates. Check that there are no scratches in the middle and outer rings of slots. If the disk requires cleaning, use only a dry lint-free piece of gauze to clean the emulsion. Do not use alcohol and do not rub the emulsion side of the disk. If the timing disk is scratched, perform the Timing Disk/Detent Gear Assembly Replacement procedure.
- 17. Connect the input/output cables (System Cabling paragraph, Section 4). Check for proper intercabling between all disk storage drives and the controller.

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FITLE: 9461 DISK STORAGE DRIVE MAINTENANCE MANUAL

{EASON FOR CHANGE:

Engineering Change Order PE12542 incorporating the following:

- 1. Engineering Change Order PE12219. Eliminates Read errors caused by improper and inconsistent grounding of spludle.
- 2. Technical Changes.

Adds new or revised technical information.

1

INSTRUCTIONS: Replace the following pages with the attached revised pages:

PAGE NO.	REASON FOR CHANGE	DESCRIPTION/AREA OF CHANGE
111	2	CONTENTS
v	2	FIGURES
vi	2	TABLES
3-15	1	Figure 3-6
3-18	2	Para 3
Section 5	2	Section revised and rewritten
6-5	1	Figure 6-2
6-6	1	Steps 7a,7b, deleted step 12
6-19	2	Step 20
6-31 -	2	Step 9n
6-35	1	Deleted step 5 of PACK-ON SWITCH ADJUSTMENT, renumbered step 6
6-40	2	Added NOTE before step 2
6-43	2	Added NOTE
6-45	2	Added NOTE
6-52	2	Added step 13
6-63	2	Added step 14m
6-73	2	Step 3c
7-3	2	Steps 10,13

ORIGINATED BY M. A. Krantz APPROVED DATE 1-25-70

RECORD of REVISIONS		
REVISION	NOTES	_ _
	Manual released. This edition incorporates all change orders released prior to 4-1-69.]
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(1, 25, 70)	Engineering Change Order PE12542 incorporating the following: Engineering Change Order PE12219 affecting pages 3-15, 6-5, 6-6, 6-35,	+
(1-2)-(0)	Technical Changes affecting pages iii. v. vi. 3-18. 5-1 thru 5-47.	1
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Address comments concerning this manual to:

Control Data Corporation Technical Publications Department 4201 North Lexington Avenue St. Paul, Minnesota 55112)

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or use Comment Sheet in the back of this manual.

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The brake assembly, consisting of the spindle lock assembly and the spindle lock disk, mounts at the lower end of the spindle (Figure 3-6). The brake holds the spindle stationary to facilitate loading and unloading a disk pack. The spindle lock assembly, consisting of a pawl, a spring, a solenoid, and a switch, is the mechanism that engages the lock disk. The spring-loaded pawl engages the disk whenever the power supply MAIN POWER circuit breaker is ON and the disk pack rotation is below pre-determined rpm (except during Power-On sequence). When the solenoid de-energizes, the springloaded plunger (on solenoid) pivots the pawl tip clear of the lock disk. The switch monitors the position of the pawl

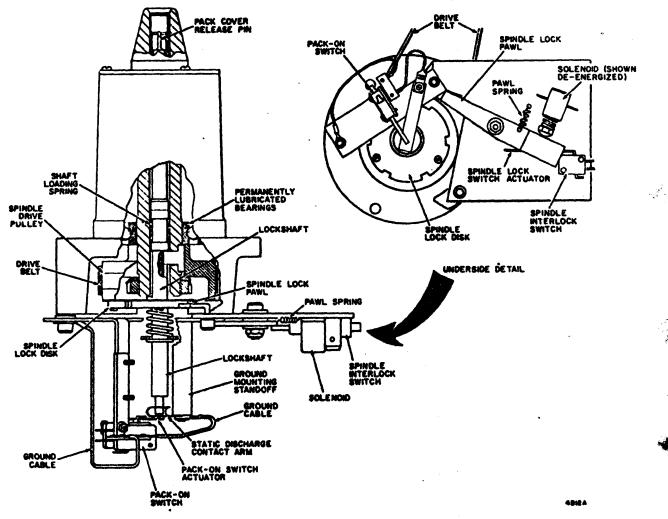


Figure 3-6. Spindle and Brake Assembly

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The lamp assembly consists of four fiber optics, the lamp, and the lamp housing. The fiber optics (fiber bundles of glass) transmit the light from the source lamp to the four photocells.

BRUSH ASSEMBLY

The brush assembly (Figure 3-8) is used to clean the disk pack of loose particles prior to actual loading of the disk storage drive heads.

The brush assembly consists of a motor, mechanical linkage, brushes and brush holders, reset switch, and base block. The base block mounts on the main deck and the brushes are pivot mounted on the base block. The pivoting of the brushes is controlled by the brush motor and linkage. Initiation of the brush cycle occurs when disk pack speed reaches 1900 rpm. A brush cycle consists of driving the brushes toward the center of the pack, reversing direction, and returning to the reset position. The cycle lasts approximately 52 seconds. Heads will not be loaded until brush cycle is completed.

A detent mechanism in the brush assembly allows the operator to manually retract the brushes. The next power up sequence after the brushes have been manually retracted will not contain a complete brush sweep cycle but rather an automatic reset cycle to properly reset the brush assembly. The brush cycle will be normal in subsequent power-up sequences.

ACTUATOR

The actuator assembly (Figure 3-8) loads (to the read/write position) and unloads (to prevent impact with the disk surfaces) the read/write heads, drives the heads to the correct data track at speeds proportional to the distance to be traveled, and accurately positions and holds the head over the track as data is read or written. The actuator consists of three subassemblies: the carriage, the carriage mount, and the carriage drive and positioning mechanism.

PREVENTIVE MAINTENANCE

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GEDERAL

The performance of the disk storage drive depends on a carefully planned and executed program of preventive maintenance and proper corrective maintenance when required. This program, if followed, will ensure optimum performance and maximum up-time.

MAINTENANCE PRECAUTIONS

The air is kept clean and any loose dust is evacuated when pressurization of the pack and actuator area is positive. Dust does not accumulate under these conditions. However, when the disk storage drive is off or a disk pack is in storage, dust and dirt accumulates on the heads and the recording surfaces. This can cause scoring of the heads and recording surfaces when the heads are loaded.

Therefore, do not leave a disk pack on an unpowered unit and secure the bottom cover immediately upon removal from the disk storage drive. Leave the cover secured until the disk pack is again mounted on the spindle. Clean both the top and bottom cover periodically so that they do not become a source of contamination.

HEAD REPLACEMENT CRITERIA

The read/write heads have been designed so that they should not need to be replaced if given proper preventive maintenance and care. If a head requires replacement, refer to Section 6 of this manual. Heads are defective and need replacing if any of the following conditions exist:

- 1. Consistent oxide buildup on the head, indicating repeated head/disk impact.
- 2. Concentric scratches on the disk surface. Inspect the head for imbedded particles.
- 3. An audible ping indicating that the head is hitting the disk surface.

DISK PACK REPLACEMENT CRITERIA

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The disk pack has been designed to last the lifetime of the equipment. Replacement of the disk pack is required only if excessive runout (see Disk Pack Runout Check, Section 7) is encountered or physical damage to the pack results in the loss of recording shility. This physical damage includes:

- 1. Damage to the disk pack resulting in a broken disk. If a disk is bent, refer to Disk Pack Runout Check, Section 7.
- 2. Gouged or scored disk surface causing the loss of data.
- 3. Imbedded particles in a disk surface that cannot be removed by cleaning and are causing damage to the heads.

PREVENTIVE MAINTENANCE INDEX

There are three levels of maintenance in the preventive maintenance schedule. These are based on a calander period or hours used (whichever comes first). An elapsed time meter, located on the power supply, keeps a cumulative record of operating time.

The preventive maintenance procedures, referenced in the Preventive Maintenance Index (Table 5-1), follow the index and are in numerical order. The three levels of maintenance listed in the index are as follows:

- Level 1 Weekly or 150 hours
- Level 2 Monthly or 500 hours
- Level 3 Quarterly or 1500 hours

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*As required			

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PM-1005

CLEAN READ/WRITE HEADS

- 1. Place MAIN POWER circuit breaker in OFF position.
- 2. Remove disk pack from spindle.
- 3. Raise top cover and manually move carriage to forward limit. Close top cover.
- 4. Raise front cover.
- 5. Wrap head cleaning tool (84323000) or wooden paddle with lint-free cloth.

6. Using alcohol dispenser (12211578), dampen loaded cleaning tool with isopropyl alcohol (12210956).

CAUTION

Do not touch or breathe on heads; skin acids etch head surfaces and moisture causes dust to accumulate and rust to form. Wipe heads carefully; residue or dirt scores heads and disks when unit is returned to operation.

- 7. Support back of head being cleaned with a second paddle.
- 8. Thoroughly wipe face of each head with dampened cleaning tool.
- 9. Inspect head surface with a dental mirror.

Is head surface free of no Repeat steps 7 through 9.

10. Manually move carriage to retract position.

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PN-1012

CLEAN FRONT COVER

1. Remove disk pack from spindle.

2. Clean glass in front cover with Windex (or equivalent).

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PM-1015

CLEAN	SHROUD AND SPINDLE		
1.	Raise and latch top cover.		
2.	Remove disk pack from spindle.		
3.	Dampen a lint-free cloth or Kimwipe with isopropyl alcohol (12210956).		
4.	Wipe shroud and spindle carefully. Remove all	dirt and smudges.	
5.	Inspect shroud area.		
	Are there any metal or dust yes particles on or around shroud?	Using sticky surfaces of adhesive or masking tape,	
	no	remove all loose particles from shroud area.	
	Procedure completed		

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PM-1020

CHECK FOR HEAD CRASHING

- 1. Mount a disk pack on spindle.
- 2. Raise and latch top cover and bypass interlock.
- 3. Press (to light) START switch and allow heads to load.
- 4. Manually disengage detent pawl.
- 5. Move carriage assembly slowly back and forth across disk surfaces. Listen for audible ping or scratching noise caused by heads contacting disk surface.

Was crashing detected?	yes 1.	Determine which head is
no		 crashing as follows: a. Check for consistent oxide buildup on head indicating repeated head/disk impact. b. Check for concentric scratches on disk surface spaced approximately 0.010 inches apart. Inspect head for imbedded particles.
	2.	Replace defective head (refer to Head/Arm Replacement procedure).
\checkmark	3.	Repeat steps 3 through 5.
Press (to extinguish) ST.	ART switch and allo	w heads to unload.

PM-1025

RUN DI	AGNOSTIC TEST		
1.	Mount a scratch disk destroyed).	: pack on spin	dle (information on pack will be
2.	Press START switch	and allow he	eads to load.
3.	Run applicable diagn	ostic test.	
	Were any errors detected?	yes >	1. Troubleshoot and correct problem.
	no		2. Repeat step 3.
	Procedure completed	i	

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PM-1030

CLEAN CABINET

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- 1. Raise and latch top cover.
- 2. Open front panel and swing out logic chassis.
- 3. Using a vacuum cleaner, thoroughly clean entire main deck area and inside of cabinet.

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PM-1031

INSPEC	T BRUSHES
1.	Raise and latch top cover.
2.	Inspect brush assembly and inner shroud area for accumulation of
	loose particles.
	<pre>was any evidence of oxide yes or foreign material found? no no line line line line line line line line</pre>
	3. Perform procedure PM-1015.

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PM-1035

REPLACE AIR INTAKE FILTERS

- 1. Open front panel and swing out logic chassis.
- 2. Remove air filter from bottom of logic chassis and replace with new filter.
- 3. Open rear panel and slide out power supply.
- 4. Remove air filter from rear of power supply and replace with new filter.

PM-1040

LUBRICATE RACK, PINION GEARS, AND CAM

- 1. Raise and latch top cover.
- 2. Manually disengage detent pawl and move carriage to forward limit.
- 3. Add 2 drops of oil (12208888) to each of four oil wick assembly holes on carriage drive rack.
- 4. Add 1 drop of oil to pinion.
- 5. Add 1 drop of oil to upper and lower forward sloping surface of head loading cam.
- 6. Manually move carriage to retract position.

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PM-1045

LUBRICATE DETENT GEAR

- 1. Remove detent pawl spring and disengage pawl.
- 2. Carefully clean detent gear with a lint-free cloth or Kimwipe.

3. Apply a thin coat of oil (12208888) to detent gear.

4. Replace detent pawl spring.

PM-1046

LUBRICATE DETENT PALL

1. Disconnect detent pawl spring.

- 2. Remove self-locking nut, spring, and washers securing detent pawl.
- 3. Carefully clean detent pawl with a lint free cloth.
- 4. Fill grease well of detent pawl and coat bearing hole and adjacent sides on detent pawl with Molykote, type G (95016101).

5. Install detent pawl.

6. Connect detent pawl spring.

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PM-1050

LUBRICATE CAM RELEASE LUG WASHER

1. Disengage detent pawl.

2. Manually move carriage to forward limit.

- 3. Using a hypodermic syringe (or equivalent), carefully lubricate two cams on cam follower side of cam release lug washer with 1 drop of oil (12208888).
- 4. Move carriage to retract position.

PM-1055

LUBRICATE CARRIAGE ROLLERWAYS

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1. Raise and latch top cover.

2. Carefully clean carriage rollerways with a lint-free cloth or Kimwipe.

3. Apply a thin coat of oil (12208888) to carriage rollerways.

4. Wipe off excess oil.

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LUBRICATE TORSION ARM LOADING GEARS

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1. Raise and latch top cover.

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2. Apply 1 drop of oil (12208888) to each torsion arm loading gear.

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PM-1065

LUBRICATE DISK PACK LOCKING SCREW AND SPINDLE LOCKSHAFT

- 1. Remove disk pack from spindle.
- 2. Using a lint-free cloth, wipe disk pack locking screw (in disk pack) and spindle lockshaft (in spindle) to remove contaminated lubricant. Repeat until surfaces are clean.
- 3. Apply a light coat of oil (12208888) to clean surfaces.

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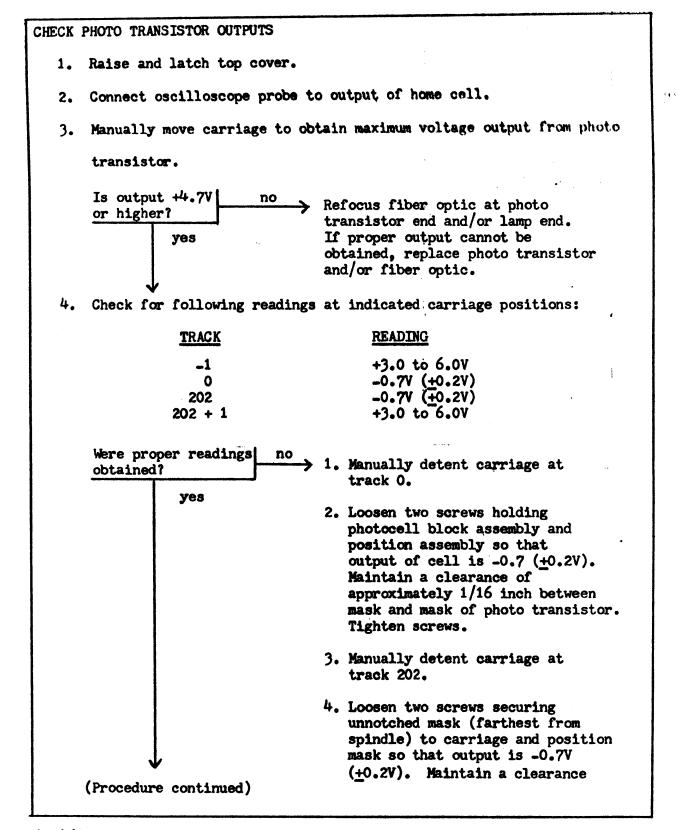
CHECK POWER SUPPLY VOLTAGES
1. Raise and latch top cover.
NOTE
Record all readings obtained during this procedure.
2. Measure +20V levels at pins 13 and 15 of buggie at location X16.
Do levels read 20V (+1V)? yes No Adjust R03 (+) and R04 (-) in power supply to obtain proper readings.
Procedure completed

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PM_1076



PM_1076 (Cont'd)

2	of approximately 1/16 inch between mask and mask of photo transistor. Tighten screwa.
	5. Repeat step 4 of procedure.
5. Connect oscilloscope probe to out	put of speed cell.
6. Disengage detent pawl and observe	output signal while slowly
moving carriage back and forth.	
Is maximum amplitude no above +4.7?	1. Loosen two screws securing photocell assembly to photo- cell mounting plate.
	2. Reposition photocell radially to obtain maximum amplitude. Make sure photocell is sensing outer row of slots on timing disk. Tighten screws.
	3. Adjust photo transistor end of fiber optic and/or lamp end to obtain maximum amplitude. Maintain 6/32 (±1/32) inch clearance between fiber optic and timing disk.
	4. If proper amplitude is not obtained, replace fiber optic and/or photo transistor.
	5. Repeat step 6 of procedure.
7. Connect oscilloscope probe to out	put of track cell.
8. Disengage detent pawl and observe	output signal while slowly
moving carriage back and forth.	
(Procedure continued)	

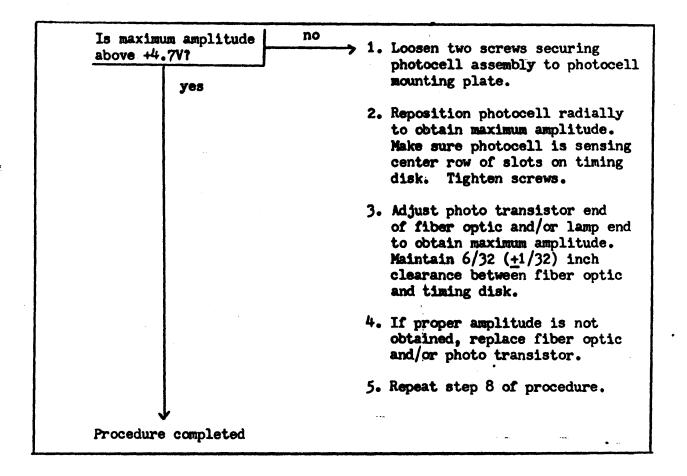
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PM-1076 (Cont'd)



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REPLACE SHROUD FILTER

- 1. Remove disk pack from spindle.
- 2. Raise and latch top cover.
- 3. Remove four screws securing shroud to top deck assembly.
- 4. Replace filter cartridge.
- 5. Reinstall shroud.

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CHECK	CARRIAGE LIMIT STOP					
1.	Remove disk pack from spindle.					
2.	Remove and latch top cover.					
3.	Manually position carriage to track 10	0.				
4.	Using a feeler gauge, check that gap between bottom of delrin block					
	and top of carriage is between 0.001 a	nd 0.004 inch.				
	Was gap dimension correct? no Adjust setscrew located above delrin block to					
	yes	obtain correct gap dimension.				
		, ,				
5.	Move carriage to retract position.					

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	PM -1090		
CHECK	COMPATABILITY		
	NOTE		
	This procedure is only applicable or more disk storage drives. On perform the Head/Arm Alignment time. Make sure that the diagnost has been run on all units before pe procedure.	a one-u proced ic test	nit system, ure at this (PM-1025)
1.	Mount a scratch disk pack on unit 0.		1
2.	Write headers on disk pack.		
3.	Run applicable diagnostic random positio	oning te	st.
•	CAUTION	:	- , 1
	If adjustments are made during thi previously written on disk packs m		
	Were any address and/or yes checkword errors detected in step 3?	-> 1	Determine cause and correct.
	no	2.	Repeat steps 2 and 3 o procedure.
4.	Move disk pack to next unit.		
			ostic random positioning

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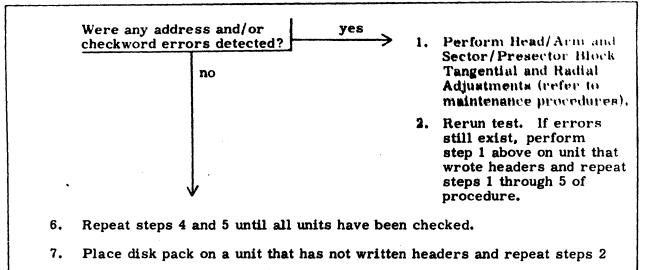
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PM-1090 (Cont'd)



through 6. Repeat until all units have written headers.

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INSPECT	DISK PACK
1. Po	osition Spindle Lock Disable switch to OFF.
2. R	aise front cover.
	spect disk surfaces for scratches by rotating disk pack and shining flash- ght between disks.
	NOTE
	Comet-like scratches indicate that a particle has been caught and dragged between the head and the disk surface. The particle is usually imbedded in the disk. Scratches that are concentric and have spirals connecting them indicate that the head contains an imbedded particle, has a burr on the shoe face, or is improperly mounted. Check the head related to that disk surface.
	vere any scratches yes Perform procedure PM-2011.
Р	rocedure completed

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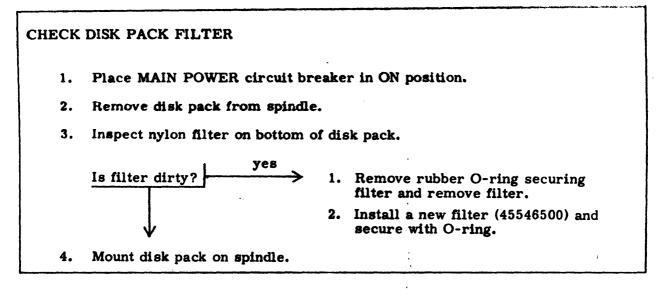
CLEAN DISK PACK

NOTE

The following guidelines should be used to determine the frequency of cleaning a disk pack:

- New disk pack; clean before using.
- Disk pack used less than once a week; clean before each use.
- Disk pack used more than once a week; clean once a week.
- Disk pack operating in other than clean computer room environment or involved in frequent start/stop operation; clean daily.
- Disk pack causing read errors; clean immediately.
- 1. Position Spindle Lock Disable switch to OFF.
- 2. Mount disk pack to be cleaned on spindle.
- 3. Wrap fiberglass spatula (84323000) or wooden tongue depressor with lintfree cloth.
- 4. Using alcohol dispenser (12211578), dampen cloth with isopropyl alcohol (12210956).
- 5. Insert spatula between disks and manually rotate disk pack. Apply downward pressure to clean lower disk surfaces and upward pressure to clean upper disk surfaces. Withdraw spatula while disk pack is still rotating.
- 6. Wrap spatula with dry cloth and repeat step 5.
- 7. Dampen another spatula wrapped in lint-free cloth with isopropyl alcohol and wipe external surface of disk pack.

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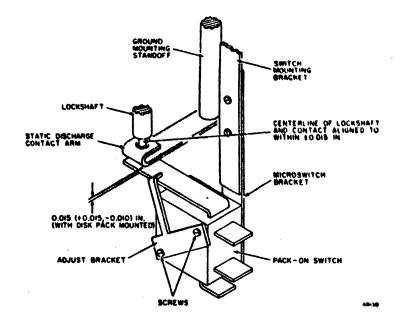


Figure 6-2. Pack-On Switch Adjustment

PACK-ON SWITCH OR STATIC DISCHARGE CONTACT REPLACEMENT

- 1. Press (to extinguish) the START switch. Set the power supply MAIN POWER circuit breaker to OFF.
- 2. Remove the disk drive front panel and swing the logic chassis out.
- 3. Note or tag all electrical connections to the Pack-On switch and the static discharge terminals. Disconnect each connection.
- 4. Remove the two screws and four washers holding the microswitch bracket to the switch mounting bracket.
- 5. Proceed to step 6 for Pack-On Switch Replacement or step 7 for Statis Discharge Contact Replacement (Figure 6-2).
- 6. Replace the Pack-On switch as follows:
 - a. Remove the two screws, three washers, and the nut securing the adjust bracket, the ground cable, and the faulty switch to the microswitch bracket.

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- b. Apply 2 drops of Loctite, Grade C, to the screw threads. Loosely assemble the adjust bracket, the ground cable, and the replacement switch to the microswitch bracket.
- c. Position the adjust bracket to keep the switch actuation arm downwardtravel (before switching) to an absolute minimum. Make certain, however, that this position allows switching to occur again when the switch actuation arm moves upward. Tighten the screws.
- d. Proceed to step 8.
- 7. Replace the static discharge contact as follows:
 - a. Remove the screw and shime (if used) securing the static discharge contact arm to the bottom of the ground mounting standoff.
 - b. Install the replacement static discharge contact arm (use all shims prethe contact arm is mounted between the terminal and the standoff). sont on the faulty contact arm. Make certain that the contact and the lockshaft center lines are aligned and that the contact arm and the lockshaft are not in contact. Tighten the screw to secure the contact arm.
- 8. Loosely assemble the microswitch bracket to the switch mounting bracket with two screws and four washers.
- 9. Restore the electrical connections at the Pack-On switch and the static discharge contact terminals.
- 10. Connect the unit power cord. Set the power supply MAIN POWER circuit breaker to ON. Place a disk pack on the spindle and tighten it in place. Set the MAIN POWER circuit breaker to OFF and disconnect the power cord.
- 11. Using a feeler gage, check that the gap between the static discharge contact arm and the Pack-On switch actuator meets the requirement of Figure 6-2. Slide the microswitch bracket vertically to attain the correct dimension. Tighten the screws.

12. Use a push-pull gage (12210797) to check that the force required to apparate the contacts is as shown on Figure 6-2. If the separation force exceeds the maximum allowable, add shims as required between the ground mounting standoff and the contact arm. Shim part numbers are available in Illustrated Parts List.

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s. Using a plastic feeler gage, establish a gap of 0.004 ± 0.002 inch between the phototransistor plate and the emulsion side of the timing disk. Maintain this gap while installing the locking wedge in the detent shaft. Install the setscrew.

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- t. Install the timing disk cover and cable clamp with two screws and washers. Make certain the track indicator index does not contact the timing disk.
- 20. Lubricate the detent and pinion gears and the carriage assembly according to the procedures outlined under 500 and 1000 hour maintenance in Section 5 of this manual.
- 21. Disengage the detent pawl and carefully slide the carriage assembly into the carriage mount. As the head loading cam exits the front hole in the carriage mount, place the spring and then the cam latch collar over the head loading cam. Make certain the cam latch collar stays forward of the cam latch arm. Slide the carriage to the rear of the carriage mount. Using Loctite, Grade C, on the screw threads, secure the cam latch collar to the head loading cam with two screws.
- 22. Seat the cam lug washer, the spring, and the spring retainer washer in the carriage mount. Using the compression tool (84356100), force the spring retainer washer into the carriage mount. Insert the retaining ring (0.831-inch OD) into the groove of the carriage mount to hold the washer and spring in place.
- 23. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 95020400) to the rear grooves of the shock mount. Using three screws and 2 drops Loctite, Grade C, install the carriage shock mount.
- 24. Connect the ground cable to the carriage assembly with a screw and washer.
- 25. Install the carriage stop bracket with two screws and 2 drops of Loctite, Grade C.
- 26. If the carriage assembly was replaced, connect the leadwires to the head latch assembly according to step 18 (f). If the detent shaft was replaced, tighten the head latch cable clamp on the home photocell mounting bracket.
- 27. Thread the head/arm cables through the cable retainer connected to the head latch assembly. Connect the cable plugs to the head diode board according to step 9.

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- m. Slide the head loading cam (notched end first) on the end of the torsion shaft until the shaft end is just visible in the opening cut in the side of the cam. Place the cam follower (lug end to the rear) in the cam opening and slide the torsion shaft through the center of the cam follower. Pin the cam follower to the end of the torsion shaft with the roll pin $(3/32 \times 3/8 \text{ inch}).$
- n. Lubricate the detent and pinion gears, carriage mount bearings, and the carriage assembly according to the procedure outline under 500 and 1000 hour maintenance in Section 5 of this manual.
- o. Disengage the detent pawl and carefully slide the carriage assembly into the carriage mount. As the head loading cam exits the front hole in the carriage mount, place the spring and then the cam latch collar over the head loading cam. Make certain the cam latch collar stays forward of the cam latch arm. Slide the carriage to the rear of the carriage mount. Using Loctite, Grade C, on the screw threads, secure the cam latch collar to the head loading cam with two screws.
- p. Seat the cam lug washer, the spring, and the spring retainer washer in the carriage mount. Using the compression tool (84356100), force the spring retainer washer into the carriage mount. Insert the retaining ring (0.831-inch OD) into the groove of the carriage mount to hold the washer and spring in place.
- q. Apply a light coat of oil (Texaco All-Purpose EP Lubricant, Control Data 94020400) to the rear grooves of the shock mount. Using three screws and 2 drops of Loctite, Grade C, install the carriage shock mount.
- r. Connect the ground cable to the carriage assembly with a screw and washer. Install the carriage stop bracket with two screws and 2 drops of Loctite, Grade C.
- s. Disengage the detent pawl and move the carriage to the fully retracted position. Make certain that the lugs on the cam follower are pointing up and down and are located at the extreme rear of the slotted opening in the head loading cam. The center torsion spring (see point A on Figure 3-16) should be aligned to 45-degrees from vertical, running from upper right to lower left.

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mounting bracket and slide the lower bracket vertically until the dimension is correct. Tighten the screws. Make certain that the static discharge contact is aligned to the lockshaft according to Figure 6-2. The contacts will be damaged during operation if not properly aligned.

-force-required-to-separate-the-contacts-is-as-shown.

5. β . Close the logic chassis and install the front panel.

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DRIVE BELT TENSION ADJUSTMENT

- 1. Press (to extinguish) the START switch.
- 2. Remove the front panel and swing out the logic chassis.
- 3. Disconnect the spring to the drive belt idler arm. Note the free length of the spring and reconnect it to the idler arm. The spring must extend $1-1/4 \pm 1/4$ inch from its free length when connected to the idler arm.
- 4. If the requirement is not met, loosen the three bolts securing the drive motor assembly to the disk drive and reposition the drive motor assembly to meet the requirement. Apply 2 drops of Loctite, Grade C, to the bolt threads and tighten.

BRUSH ARM AND LINKAGE ADJUSTMENT

- 1. Open and latch the top rear cover of the disk storage drive.
- 2. Set the MAIN POWER circuit breaker to OFF.
- 3. Remove the four screws and washers holding the plastic shroud. Set the shroud aside.
- 4. Loosen the two screws locking the brush shaft link to the brush arm shaft.
- 5. For brush arm adjustment proceed to step 6. To adjust the linkage proceed to step 9.

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NOTE

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A fault will occur when the diode card at X10 is removed.

- 2. Remove the diode card at X10 (read/write logic chassis).
- Remove the disk drive front panel. Connect the oscilloscope external trigger to test point C of 1028 Index pulse (C27) and set the External Sync switch to negative. Ground the oscilloscope at the maintenance panel GROUND jack.

NOTE

To read any head other than head 0 or head 1, the selected head cable plug connection must be exchanged with either head 0 or head 1 at the head diode card. Connect heads 3, 4, 7, and 8 (Figure 6-7) at head 0 head diode card connector. All other heads are exchanged with head 1.

- Exchange the head plug connection of the desired head with either head 0 or head 1. Install a head plug adapter (46812200) between the head diode and connector and the head plug of the head to be adjusted.
- Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ
 0 or READ 1 position (as required by the exchange in step 4).
- 6. Connect 1X oscilloscope probes (to read differentially) to test points A and B of the EUC card at X09 (on read/write logic chassis).
- 7. Set the oscilloscope sweep frequency to 2 ms/cm.
- 8. Set the power supply circuit breakers to ON.
- 9. Mount the CE disk pack (84357500) on the spindle and tighten in place. Pull upward on the rear cover interlock switch.
- 10. Press (to light) the START switch. Record the time of power application.
- 11. After the heads load and the carriage stops, set the power supply ACCESS MOTOR and DETENT circuit breakers to OFF.
- 12. Manually pull the detent pawl, move the carriage to Track 73, and allow the detent pawl to engage the detent gear.
- 13. A 45 minute warm-up period with the top rear cover down and the heads loaded, followed by a 15 minute period with the top cover raised, must precede the following adjustment procedures.
- 14. Adjust the oscilloscope for a stable pattern. The pattern should be similar to Figure 6-8, part C.

- 23. Press (to extinguish) the START switch. Remove the CE disk pack from the spindle.
- 24. Install the diode card at location X10 on the read/write logic chassis.
- 25. Remove the head plug adapter.
- 26. Restore the head plug connections to the original configuration.

ACTUATOR ADJUSTMENT

1. Open and latch the top rear cover of the disk drive.

NOTE

A fault will occur when the diode card at X10 is removed.

- 2. Remove the diode card at X10 (read/write logic chassis).
- 3. Remove the disk drive front panel. Connect the oscilloscope external trigger to test point C of IO28 Index pulse (C27) and set the External Sync switch to negative. Ground the oscilloscope at the maintenance panel GROUND jack.
- 4. Connect 1X oscilloscope probes (to read differentially) to test points A and B of the EUC card at X09 (on read/write logic chassis).
- 5. Set the oscilloscope sweep frequency to 5 usec/cm.
- 6. Set the power supply circuit breakers to ON.
- 7. Mount the CE disk pack (84357500) on the spindle and tighten in place. Pull upward on the rear cover interlock switch.
- 8. Press (to light) the START switch. After the heads load and the carriage stops, set the power supply ACCESS MOTOR and DETENT circuit breakers to OFF.
- 9. Manually pull the detent pawl, move the carriage to Track 03, and allow the detent pawl to engage the detent gear.
- 10. Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ 0 position.

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- 15. Install the head plug adapter (46812200) between the head 0 cable plug and the head diode card connector. Set the maintenance panel OFF LINE/ON LINE switch to the OFF LINE READ 0. Record the oscillscope period between the Index pulse and the peak of the first data pulse (Figure 6-9). The period should be approximately 48 usec.
- 16. Repeat step 15 for the other nine heads.
- 17. Manually pull the detent pawl, move the carriage to Track 201, and allow the # detent pawl to engage the detent gear.
- 18. Repeat steps 15 and 16.
- 19. The difference in timing at Track 03 and Track 201 for any one head must not exceed 4 used. If this requirement is met, proceed to step 22.
- 20. If the requirement of step 19 is not met, loosen the four bolts holding the actuator assembly to the main deck. Pivot the actuator assembly to bring the Track 03 and 201 periods to within 4 usec of each other. Tighten the bolts. Remove the head plug adapter and repeat steps 9 through 14.
- 21. Recheck the alignment of each head to Track 73 according to the Head/Arm Adjustment procedure. Make adjustments as required.
- 22. Press (to extinguish) the START switch. Remove the CE disk pack from the spindle.
- 23. Remove the head plug adapter.
- 24. Restore the head plug connections to the original configuration.
- 25. Install the diode card at location X10 on the read/write logic chassis.

SECTOR BLOCK TANGENTIAL AND RADIAL ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Remove the disk storage drive front panel.

NOTE

A fault will occur when the diode card at X10 is removed.

- 3. Remove the diode card at X10 on the read/write logic chassis.
- 4. Set the power supply circuit breakers to ON.
- 5. Mount the CE disk pack (84357500) on the spindle and tighten in place.

- 3. Set the power supply MAIN POWER and ± 20 vdc circuit breakers to ON.
- 4. Connect the ground of an oscilloscope to the maintenance panel GROUND jack.
- 5. Connect the oscilloscope probe to the yellow leadwire terminal of the track phototransistor plate.
- 6. Disengage the detent pawl and move the carriage forward to approximately Track 100. Allow the pawl tip to engage the detent gear between the teeth.
- 7. Loosen the three screws securing the photocell mounting plate (Figure 6-6).
- 8. Slowly rotate the photocell mounting plate counterclockwise.
- 9. Tighten the three screws securing the photocell mounting plate. Make certain that the oscilloscope trace amplitude is still 0 vdc.
- 10. Disengage the detent pawl and position the carriage until the fiber optic light spot is located between the first two track slots clockwise from the blank area (interruption in slots), Figure 6-6. Release the detent pawl. The track indicator pointer should be pointing at 00 on the timing disk. Reposition the pointer as required.
- 11. Disengage the detent pawl and move the carriage out to the forward stop. The track indicator index should be between the Track 01 and 05 marks. If this requirement is not met, perform the Carriage Limit Stop Adjustment procedure.
- 12. If any adjustment was performed in step 8, perform the Actuator Dynamic Tests and Adjustments procedure.
- 13. Perform the Home Cell Mechanical Adjustment procedure.

CARRIAGE LIMIT STOP ADJUSTMENT

- 1. Open and latch the disk drive top rear cover.
- 2. Set the power supply MAIN POWER circuit breaker to OFF.
- 3. Disengage the detent pawl and move the carriage out to the forward stop. The track indicator index should be between the Track 01 and 05 marks on the timing disk. If this requirement is met, proceed to step 7.
- 4. If the requirement of step 3 is not met, remove the screws securing the head diode board. Under the diode board (and above the Delrin block, Figure 6-13)

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c. Refer to Figure 6-19, part A, for oscilloscope settings. Each of the Track pulses should swing between a low voltage of -0.6 ± 0.4 vdc and a high voltage of $+5.0 \pm 0.5$ vdc. There should be no track pulses of leas amplitude during the settle time (as shown by FAULT on Figure 6-19, part A). If the extra pulses do exist, they will be corrected during the following steps.

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- d. If the amplitude of the track pulses is less than +4.7 vdc, adjust the track photocell according to the Track/Speed Photocell Mechanical Adjustment procedure.
- e. Disconnect the oscilloscope probe at the track photocell and connect it to the track pulse amplifier, test point C at logic chassis location A34.
- f. Connect the oscilloscope external trigger to test point A of I218 Any Seek (C25). Command the disk storage drive to perform a 1-track repeat seek (one track forward and one track reverse, continuously) at Track 100.
- g. Refer to Figure 6-19, part B, for oscilloscope settings and compare waveforms. The track pulses should be approximately coincidental (leading and trailing edges of pulse vertically aligned).
- h. Slightly loosen the three screws securing the photocell mounting plate, Figure 6-6.
- i. As the unit performs the 1-track repeat seek, observe the pair of track pulses on the oscilloscope. If the forward pulse is to the left of the reverse pulse, very lightly tap the photocell mounting plate downward. If the forward pulse is to the right of the reverse pulse, place a screwdriver between the main deck and the bottom of the photocell mounting plate and force the plate upward.
- j. When the oscilloscope trace is similar to Figure 6-19, part B, tighten the three locking screws in the photocell mounting plate. Make certain that the trace does not change.
- k. Disconnect the oscilloscope (except the ground connection).
- Moving the photocell mounting plate changed the reference of the forward and reverse stop pulse delays. Repeat steps 12 and 13. If the forward or reverse delay cannot be made short enough (pawl engages gear before zero velocity is reached) in steps 12 or 13, the photocell mounting block may be repositioned to favor the direction in which the difficulty occurs.
 m. Perform the Home Cell Mechanical Adjustment procedure.

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- a. Measure +20 (+1, -0) vdc at read/write logic chassis locations N29-10 and -14 (ground). Unlatch power supply panel and adjust rheostat R03 if required.
- b. Measure -20 (-1, +0) vdc at read/write logic chassis locations N22-13 and -14 (ground). Unlatch power supply panel and adjust rheostat R04 as required.

NOTE

In the following step R03 is a part of the auxiliary power supply located on the disk storage drive directly below the main power supply chassis.

c. Measure $+5.7 \pm 0.2$ vdc at the power supply LAMP and DC GRD jacks. Adjust R03 in the auxiliary power supply if required.

POWER SUPPLY TROUBLESHOOTING PROCEDURE

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External test equipment connections to the power supply are made to test points on the front panel of the unit (located behind the lower rear panel). The terminals are labeled for easy reference.

Troubleshooting of the individual portions of the power supply requires that the front panel be lowered. If the power supply must be opened, observe the following warning.

WARNING

Make certain that the power supply is not connected to any power source, and that all capacitors have been discharged before making any external connections.

Initially troubleshoot the power supply by checking the following:

- 1. Using a multimeter, note the output voltage and ripple at the front panel test points.
- 2. Check the line voltage applied to the power supply.

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5. Remove the tape covering the shroud opening for the read/write heads. Inspect for any apparent head damage.

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- 6. Remove the carriage tie-down cord and the attached red identification tag. Do not attempt to move the carriage at this time.
- 7. Remove the disk storage drive front panel. Remove the two air filters which are taped to the inside of the panel.
- 8. Open and close the logic chassis assembly. If binding or drag occurs, adjust the upper and lower pivot brackets.
- 9. Check that all logic cards are firmly seated in their connectors.
- 10. Install the air filter in its slot at the bottom of the logic chassis. (Figure 5-4).
- 11. Remove the disk storage drive rear panel.
- 12. Slide the power supply in and out of the unit. Replace any nylon rollers which do not move freely.
- 13. Install the air filter in its slot at the rear of the power supply. (Figure 5-5).
- 14. Inspect the intracabling connections of the unit (Figure 7-2).
- Inspect the ground lead running from the home cell assembly to the carriage.
 Make certain that it is clear of all components and will not interfere with carriage movement.

CAUTION

The timing disk markings are a photo emulsion. In the following step, use extreme care to prevent scraping or scratching the disk.

- 16. Carefully inspect the glass timing disk and photocell mount assemblies. The timing disk should rotate freely as the carriage is moved and should not contact either the speed or track phototransistor plates. Check that there are no scratches in the middle and outer rings of slots. If the disk requires cleaning, use only a dry lint-free piece of gauze to clean the emulsion. Do not use alcohol and do not rub the emulsion side of the disk. If the timing disk is scratched, perform the Timing Disk/Detent Gear Assembly Replacement procedure.
- 17. Connect the input/output cables (System Cabling paragraph, Section 4). Check for proper intercabling between all disk storage drives and the controller.

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