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ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS WORLDWIDE


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MARCH 30, 1992


On the cover: The first and second generation of RISC microprocessors laid the groundwork for the increased performance of the current collection. (Photo courtesy Intel, Chandler Div; concept, design, sets, and photography by Imagination)

# Third-generation RISC processors 

# Time-domain techniques DESIGN FEATURES enhance testing of high-speed ADCs 

Add a sine-wave curve-fitting algorithm or beatfrequency test to commonly used DSP techniques to characterize the performance of ADCs.
-Michael J Demler, Micro Networks

## Use the analytic approach to avoid errors when probing CMOS circuits

Probe resistance and probe capacitance can affect voltage measurements as well as the accuracy of delay-

## Micropower voltage <br> T:CHNOOOGY UPDATES references: Microamps sustain stable sources

The selection, handling, and application of micropower voltage references remain decisive issues in set-

## Battery-powered DSOs:

Versatile units find more use than you'd expect

These instruments offer surprisingly good performance that often is just what design engineers need.
-Dan Strassberg, Technical Editor
Continued on page 7

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## INSIDE EDN

A summary and analysis of articles in this issue

Third-generation RISC processors are just starting to appear. Some of these $\mu$ Ps represent the latest evolutionary step for an existing processor family, whereas others skipped the first and second generations entirely. Technical Editor Ray Weiss rounds up both the available and soon-to-be available RISC devices and architectures in this issue's Special Report. If you're not yet comfortable with the brave new world of superlative adjectives ("superscalar" and "superpipelined") used to describe these high-powered computing engines, this article will bring you up to speed.
Although a few of these processors are already available in sample quantities, many have not yet been realized in working silicon. Generally, EDN's articles present products with both price and availability data because our reader surveys tell us that you want it that way. The price and date of availability serve as reality checks; if a vendor can tell you when a product will be available and how much it will cost, the product is probably real. However, for critical products with long evaluation or design-in times, such as 32 -bit $\mu$ Ps, we make an exception to this policy. Even when the products are not yet available, we will still supply the best availability information we can get. Such is the case with this issue's Special Report on RISC $\mu$ Ps.
Technical Editor Brian Kerridge's Technology Update on micropower voltage references jumps from high-power $\mu \mathrm{P}$ systems into the world of low-power analog design. Micropower voltage references are all based on bandgap de-
vices instead of zeners. Kerridge's story tells you why and also gives you several application pointers to help you avoid noise and stability problems.

You'll most likely find one or more of these micropower voltage references in the battery-powered digital sampling oscilloscopes (DSOs) covered in Technical Editor
 Dan Strassberg's Technology Update. You might think of these instruments as field-service tools, but Strassberg shows that they pack enough punch for general design use. Some even have enough extra functions to replace a rack of equipment with one handheld instrument. The article's sidebar discussing batteries for DSOs should interest designers of any battery-powered equipment.

> Steven H Leibson
> Executive Editor

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## FPGA delivers $10,000+$ gate densities

With its XC4010, Xilinx increased its FPGA (field programmable gate array) densities to 10,000 usable gates. The FPGA is the next step in the XC4000 FPGA chip family. The RAM-based-array usable-gate density increases with the availability of a programmable RAM, which you can use as a RAM block. XCA4010 register clock rates can hit 45 MHz , according to Xilinx.
Register-intensive designs can use the programmable RAM look-up table instead of the block logic it controls. You can address the RAM as a $2 \times 16$ - or $1 \times 32$-register array with a 4.5 -nsec access time. You can configure multiple logic blocks to build wide, deep register sets. The FPGA is made up of a $20 \times 20$ matrix of 400 of these configurable logic blocks (CLBs). Each CIB has two 4 -input functional logic units and two D flip-flops. Fast-carry logic supplements the CLBs for adder and addressing functions. The FPGA suits 32 -bit processing. The chip provides $40-$ chip-wide, 3 -state bit buses, which can handle a 32 -bit word with additional control or parity byte. You can route the CLBs to pick up or put data values on any bit bus. The FPGA family includes 1611 -nsec, 60 -input decoders.
Designers can change the FPGA designs on the board as well as FPGA functionality, depending on board or system conditions. However, the company's FPGAs require programming on power up, requiring special logic and system memory or an EPROM to hold FPGA programming data. The chip costs $\$ 737$ (1000). Xilinx Inc, San Jose, CA, (408) 559-7778, FAX (408) 559-7114.-Ray Weiss

## VHDL package integrates multiple tools

Vantage Analysis Systems Vantage Spreadsheet version 4.0 lets engineers compile, debug, and analyze their VHDL (VHSIC Hardware Description Language) designs. The software's compilation and simulation speeds are an order of magnitude faster than previous versions. The software also speeds testing with a tool that grades test stimulus by counting up the num-
ber of times a VHDL sourcecode line executes, as well as tracking the number of events for each signal. The Concurrent Compiler, a parallel version of the VHDL compiler that automatically partitions and distributes compilation tasks across a Sun or HP processor network, speeds compilation. Finally, a generic loader lets you load as many as 100,000 parameters per minute, without stopping the compiler. The software pricing starts at $\$ 44,000$. Vantage Analysis Systems Inc, Fremont, CA, (510) 659.
0901.-Ray Weiss

# Ethernet and Token Ring on one chip 

Texas Instruments' TMS380C26 chip handles both Ethernet and TokenRing communications protocols. With this chip on a mother board, users can connect their system to either network-they do not have to choose a desktop protocol when buying the system. The chip supports Ethernet standards and remains pin and software compatible with TT's TMS380C16, an IBMverified 4 - or 16 -Mbit/sec Token-Ring coprocessor.

To make reconfiguration (shifting from one to the other on site) easier, the company is also releasing the C26 Selectable Physical Layer Interface Transceivers to ease reconfiguration. These transceivers let you interface a mother board to either Token-Ring or Ethernet wiring media. Configuration is at the cable level. The TMS380C26 will be available in a 132-pin plastic quad flatpack. $\$ 58.80(10,000)$. Texas Instruments Inc, Dallas, TX, (800) 3365236, ext 3990.
-Ray Weiss

## Cache-tag RAM offers 12 -nsec validated match

## The CY7B180 and

 CY7B181 are $4 \mathrm{k} \times 18$-bit cache-tag RAMs with extra logic to simplify your cachedesigns. Both devices offer a 16 -bit tag field with a 2 bit status field at each location. You can read and write the two fields independently. The 180 lets you use the status bits to code the tag data for multiprocessing systems. The 181 uses these status bits to denote valid and "dirty" data. It automatically sets the "dirty" bit on a write hit and uses the valid bit to gate the match signal so that only valid matches are signaled to the cache. The validated match takes 12 nsec.
To further simplify designs, the devices automatically generate a write output signal to the cache RAM when they detect a write hit. The devices also offer an additional data port, letting you read tag data immediately when you find a match. The instant availability of the tag data helps speed copy-back cache schemes. The devices come in a 68 -pin plastic leaded chip carrier and cost $\$ 72.05$ (100). Cypress Semiconductor, San Jose, CA, (408) 943-2600, FAX (408) 943-2741.
-Richard A Quinnell

## Scope offers record lengths to 8 Mbytes

The Systemware digital oscilloscope is available with as much as 8 Mbytes of memory words, letting the instrument record exceptionally long waveforms. The PC-based oscilloscope runs under Microsoft Windows 3.0 with
a software control panel. The instrument has a 40 MHz bandwidth and digitizes 8 bits at 100 Msamples/sec. Prices range from $\$ 10,000$ for an instrument with 256 kbytes of
memory, to $\$ 18,825$ for a system with 8 Mbytes of memory. Systemware, Westlake Village, CA, (805) 497-9603, FAX (805) 494-9719.
—Doug Conner

## Conditions relax as Europe's EMC Law comes into force

Although Europe's EMC law theoretically came into force on January 1 of this year, clarifications of its implementation continue to appear. Since EDN first reported details of this law (September 16, 1991, pg 57), later statements from the Commission of European Communities have defined more clearly what products the law applies to and over what time scale the law will be introduced.

Generally, there is an overall relaxation in the scope of products that must comply with the law. Broadly, the law classifies products into one of four categories: components, apparatus, systems, and installations. Components and installations do not have to comply with the law, but apparatus and systems must. The terms are thus defined:

- Components: Any element likely to be part of an apparatus, and not intended for use by an end user. This category includes passive components, ICs, and pcboard subassemblies.
- Apparatus: A finished product with an intrinsic function intended for an end user that will be placed on the market as a single commercial unit. The law squarely applies to products in this category.
- Systems: Several pieces of apparatus designed and intended to work together. A typical example is a PC, and such products must comply.
- Installations: Several pieces of apparatus put into service in a given place for a specific task but not intended to be placed on the market as a single commercial unit. On the understanding that an installation consists of already-compliant apparatus and systems, the overall installation needs no further approval.
The Commission of European Communities has also made clear that the end-date of the transition period is December 31, 1995. During the transition period you can opt to comply with the EMC law or continue to observe prevailing national EMC regulations. At present, only Denmark has incorporated the EMC law into its national legislation. Other countries will follow suit later this year.

The arrangement for competent bodies and notified bodies to perform approval work in the EC stands. In the UK, the Department of Trade and Industry has issued a provisional list of companies to perform this service.
-Brian Kerridge

## Mixed-signal IC tester gets smaller and faster

As mixed-signal ICs grow in digital complexity, the distinction between testers for mixed analog/digital chips and those for high-pin-count digital devices is becoming less clear. Teradyne Inc's mixed-signal-IC tester, the A580, has many of the attributes of testers for purely digital ICs. The system has 280 chan-nels-of which 192 are digital-and a $200-\mathrm{MHz}$ maximum clock rate for digital testing. The mixed-signal-chip tester can handle the majority of testing performed on high-pin-count digital ICs, so many companies that make both digital and mixed-signal parts should be able to use a single type of tester.

In addition to offering $2.5 \times$ as many channels and $4 \times$ the digital-test speed of its most nearly equivalent predecessor, the tester is considerably smaller (about one-half the floor space), and at $\$ 1$ to $\$ 2$ million, slightly less expensive. The unit also uses so much less power that it has no need for a separate power-conditioning "vault." The lower power dissipation means users won't have to install as much air conditioning. For analog applications, the highest signal frequency is 4 GHz vs 10 MHz for the earlier system; the highest voltage
is 1 kV vs 60 V ; and the largest source current is 100 A vs 1 A . Teradyne Inc, Boston, MA, (617) 422-2567.

## -Dan Strassberg

## VGA chips attack PC-video performance problems

Now that PC processor speeds have jumped into the $33-$ to $50-\mathrm{MHz}$ range, IC vendors are attacking the next major performance bottleneck-video display speeds-with chips that off-load graphics operations from the main CPU. AT\&T's ATT20C101 superVGA controller incorporates several features that boost display performance, including a 16 -bit bus interface that can keep pace with 80386 and 80486 $\mu$ Ps, a write buffer that reduces wait times (at least during write operations), and a 32-bit interface to page-mode dynamic RAMs for the bit-map memory. The \$14(1000) chip has nine display modes that range from $640 \times 480$ to $1024 \times 768$ pixels and display 256 - to 16.8 -million colors.

The company is also offering three companion color-palette DACs: the $110-\mathrm{MHz}$, triple 8 -bit ATT20C491; the $110-\mathrm{MHz}$, triple 6-bit ATT20C492; and the $200-\mathrm{MHz}$, triple 8bit ATT20C458. These DACs cost \$13, \$11, and $\$ 45$, respectively, (1000).

ATI Technologies' 68800 super-VGA coprocessor

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SV430 outperforms every other SBC on the market by as much as $150 \%$. urprisingly, this kind of quality won't cost you any extra, because Synergy products lead in another important area - value. At Synergy, you don't have to pay a premium price for premium performance.
Let us show you just how far ahead your system can be with a Synergy processor board. Call us today, and get the whole '040 story.

## Compare our specs. Synergy is superior across the board!



VME Transfers VME64 doubles bus performance to $66 \mathrm{MB} / \mathrm{s}$ - and the SV430 is the only '040 board that has it. But we don't need VME64 to win this comparison. Even normal 32-bit transfers race at $33 \mathrm{MB} / \mathrm{s}$. That's 200\% faster than Force or Motorola.


I/O Modules
Synergy's EZ-Bus modules are compatible with our entire line of SBCs. This means Synergy's current line of 12 intelligent I/O modules are immediately available for the SV430 - today. No other vendor comes close for selection, functionality or availability.

Data from Motorola MVME1 65 data sheet dated 2/90, and Force CPU-40 data sheet AI Rev. I. DRAM measurements shown are with parity. VMEbus transfers are to a 60 ns slave

VME64 is a trademark of Performance Technologies. Inc

| Write: 80 <br> Read: 67 |  | Mbytes/sec | DRAM |
| :---: | :---: | :---: | :---: |
|  |  |  | Burst |
| 50 |  |  | Rates |
|  |  |  | A 25 MHz ' 040 is capable of accessing mem ory at $80 \mathrm{MB} / \mathrm{s}$ |
|  | F |  | The closer you are to this maximum, the more |

ance you're gaining. SV430 bursts are $26 \%$ faster than Force and Motorola.


DRAM Random Accesses Non-burst '040 performance is measured in wait states. Fewer wait states mean higher performance. The SV430 is not only $66 \%$
faster than Force or Motorola, it supports twice the on-board memory - 32 MB .


## Product

 Warranty Synergy backs the reliability of its SBCs with a two year standard warranty. Force and Motorola only offer you one.'030 SBCs. Force offers compatibility only from the ' 030 level, and Motorola offers "upward migration"-a polite phrase that means rewriting your code.
uses many of the same graphics-acceleration techniques and adds a few of its own. The $\$ 79$ (1000) IC has a configurable bus interface with a FIFO buffer that will transfer 8-, 16-, or 32 -bit words and is fast enough to operate on the host CPU's local bus at clock speeds to 40 MHz . The controller chip communicates with video memory over a 64-bit bus and can accommodate 4 M bytes of video RAM, producing a maximum display resolution of $1280 \times 102424$-bit pixels. An on-chip drawing coprocessor can perform bitblts, point-to-point line
drawing, pattern filling, and clipping with little or no host CPU intervention. The chip also provides hardwarebased assistance for antialiased character fonts. A less-expensive version of the device, the $\$ 49$ (1000) 68800SX, will be available later this year. It will only accommodate 2 M bytes of video memory and $1024 \times 768$-pixel displays. AT\&T Microelectronics, Allentown, PA, (800) 372 2446, FAX (215) 7784106. ATI Technologies, Inc, Scarborough, ON, Canada, (416) 756-0718, FAX (416) 756-0720.
-Steven H Leibson

## High-density PLD allows in-system programming

Lattice Semiconductor's PLSI 1032 and ISPLSI 1032 are the first members of a high-density PLD family that are based on EEPROM technology. Both devices have 64 I/O pins, 8 dedicated input pins, and 196 registers. The devices' basic logic block lets you create 20 AND-product terms from a selection of 18 complementary signal pairs, 2 of which come from the dedicated input pins and 16 from any of the logic blocks. Propagation delay through the device is 15 nsec ; delay for internal feedback is as low as 3 nsec.

Both the PLSI and ISPLSI devices are pin- and parameter compatible, but the ISPLSI device has an additional feature: You can program the device in-system. The ISPLSI device multiplexes four I/O pins and uses one dedicated pin (noconnect on the PLSI parts) to provide a serial access port for programming. The device has an on-chip programming voltage, so you don't need any additional voltages in your system.

Lattice supports the family with development software and engineering kits. The software runs under Windows, offers a library of macro functions, and lets you design with Boolean equations. The software costs $\$ 995$; the engineering kit costs $\$ 395$. The parts' cost varies with speed grade. The PLSI 1032 costs from $\$ 49$ to $\$ 81$ (1000). The ISPLSI 1032 costs $\$ 142$ (100) in sample qty. Lattice Semiconductor, Hillsboro, OR, (503) 681-0118, FAX (503) 681-0347. -Richard A Quinnell

## Voltage regulator models thin package

The TL-SCSI 285 fixed-voltage regulator from Texas Instruments implements a new method for terminating SCSI lines, called active termination, which reduces power consumption by as much as $30 \times$, thereby increasing the possibilities for SCSI portable systems. The regulator lets input voltages drop as low as 3.45 V and still maintain an output voltage of 2.85 V . With this dropout voltage of 0.6 V , the regulator meets demands of both desktop computer systems and laptop and portable systems. Total tolerance in the 2.85 V output is $\pm 2 \%$ overtemperature, including variations caused by line voltage and load changes. The device's $110 \Omega, \pm 2 \%$ series resistors match the typical trans-mission-line characteristic impedance.

The device comes in a thin-scaled small-outline package (TSSOP). The 20pin package has lead spacings of 0.025 in . and is 0.040 in. thick, which is half the height of the standard small-outline package. At $25^{\circ} \mathrm{C}$, the package's power-dissipation rating is 0.775 W compared with IW for a standard DIP. The TSSOP-packaged regulator costs \$1.70; DIP and TO200 versions are also available. A second regulator with a IV dropout voltage, the TL2217-285, costs from $\$ 1.39$. These regulators are the first devices available in the thin package,
but the company will also offer the package for existing and new standard linear devices. Texas Instruments Inc, Dallas, TX, (800) 3365236, ext 3990, (214) 995-6611, ext 3990.
-Anne Watson Swager

## Microsoft introduces $\mathbf{C}++$

Microsoft Corp has introduced C/C + + v 7.0 Development System for Windows. The system is an ANSI $C$ and $C++v 3.1$ development environment. The system's compilers use precompiled header and C ++ files for increased speed.

The package includes the Microsoft Foundation Classes and an Application Framework. These classes are available in source form for use as program examples. The framework is a platform for multiple tools, including third-party development packages. Among the debug tools are a new version of Codeview for $\mathrm{C}++$ and a $\mathrm{C}++$ Object Browser. Other optimizations include "Packed P code" object format (interpreted P-code for 40 to 60\% size reductions), pro-grammer-directed function in-lining (saving call overhead by expanding function calls with the actual code), automatic function in-lining (compiler directed), and a virtual overlay manager. Also provided is a set of Windows documentation and basic $\mathrm{C}++$ class libraries. The software costs \$499. Microsoft Corp, Redmond, WA, (206) 8828080. -Ray Weiss

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$\begin{array}{ll}\text { T16-1 } & 5950-01-094-7439 \\ \text { TMO1-1 } & 5950-01-178-2612\end{array}$

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To find out more about the Z8 Microcontroller family, or any of Zilog's rapidly growing Superintegration product families, contact your local Zilog sales office or your authorized distributor today. Zilog, Inc., 210 East Hacienda Ave., Campbell, CA 95008-6600, (408) 370-8000.


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## Criteria for <br> manufacturable IC

Concerning Charles Small's editorial, "Make FPGA design easier" (EDN, October 10, 1991, pg 49), I'd like to add my perspective. I'm an engineer at a manufacturing plant where I'm the process owner for IC programming.

FPGA manufacturers, in addition to lacking the vision that they are in the IC manufacturing business, not the software business, haven't even made their devices fully manufacturable. Instead of using the JEDEC format for programming files, some use binary or POF formats. (For those who use Data I/O equipment, these formats correspond to Translation Formats 10 and 14 , respectively.) These formats wreaked havoc with my programming system because of their non-ASCII nature. FPGA manufacturers also seem to prefer that I use their development systems rather than my industry-standard equipment to do my production programming.
A fully programmable IC must meet these criteria:

1. The programming file must be ASCII readable. Not only does this allow easy, reliable transmission from my design group in New Jersey, but it also allows me to write software to check its integrity.
2. All manufacturing functions must be supported by industrystandard, production-grade equipment. These include, but may not be limited to

- Reading a master device into the programmer's RAM.
- Uploading the programmer's RAM to a host computer.
- Verifying the device from RAM. This presupposes that test vectors can be generated and added to the (ASCII) programming file.
- IC handling machines connected to the programmer can be used. (The interface I have between programmer and handler
doesn't support certain FPGAs.)
- Gang programming should be supported for those limited to manual operations.
- Downloading of programming files from a host computer into the programmer's RAM.
- Blank-device check.

I'm currently stuck programming FPGAs one at a time, taking 5 or 10 minutes for each.

Not only have FPGA vendors locked up the design of these wondrous devices, but they have also locked up the mass programming, too. These vendors would stand to gain a fortune if these two areas were freed up so that their devices could be put into widespread use.
Bill Fox
AT\&T, Network Systems
The Columbus Works
Columbus, OH

## Need of harmonizing European partners in trade

I've just read the article, "The economic challenge of a united Europe" by Jay Fraser, on the consequences of the Single European Market (EDN, November 7, 1991, pg 355), and I felt compelled to put pen to paper. Then I remembered that, despite living in "low-tech" Europe, I do have access to word-processing and fax facilities so I threw away the quill pen and shot the carrier pigeon-this is the result.

Europe is not quite as weak on high-tech as the article implies. We may not have put a man on the moon, but we are more than capable of producing high-tech products. A major problem facing Europe as a single market is the harmonization of standards that have followed separate evolutionary paths for hundreds of years.
[The differences] obviously cannot change overnight, if at all. Neither will I be running out to change all the main sockets in my house so. I can buy a CD player in Dusseldorf. What Europe means is that
there will be no difference between the cost of that CD player and the one on sale down the road due to some artificial tariff.
Eventually, when our politicians finish their posturings about national identities and other primitive tribalism, we may end up with a single currency. Perhaps it should be called the "Youess dollar," which would make it difficult for those who gamble on foreign exchanges at the expense of real wealth crea-tion-but that's another issue!
Peter J Osborn
Product Manager
Newport Components Ltd
Blakelands North
Milton Keynes, UK

## Changed phone number

The phone number listed for inquiries about Intel's iRMX for Windows in EDN's November 21, 1991, issue (pg 47) should be changed to ( 800 ) 438-4769.

## Calling all pizzas

If you want information about Motorola's MC-145191 frequency synthesizer, don't call the number we listed on pg 118 in the February 3 issue-you'll get information about Domino's pizza instead. Try the correct number: (800) 521-6274.

## HAVE YOUR SAY

EDN's Signals \& Noise column provides a forum for readers to express their opinions on issues raised in the magazine's articles or on any topic that affects the engineering industry. Send your letters to Signals \& Noise Editor, EDN Magazine, 275 Washington St, Newton, MA 02158. You can also send a note via MCI mail at EDNBOS or use EDN's bulletin-board system at (617) 558-4241: From the Main System Menu, enter SS/SOAPBOX, then $W$ to write us a letter. You'll need a $2400-\mathrm{bps}$ (or less) modem and a communications program set for $8, \mathrm{~N}, 1$.

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# Getting small quantities is tough all over 

After printing Peter Gottlieb's letter about the difficulties he experiences getting small quantities of state-of-the-art parts for making prototypes, Ask EDN has received dozens of replies. All of the replies reinforced Mr Gottlieb's complaint. Here's a sampling of the letters:

## Industry ignores the independent engineer

I believe Peter Gottlieb has understated the problem. I am an electrical engineer running my own business with two part-time engineers and one part-time secretary. I work on the design and prototyping of computer/ microcontroller-based process controllers and custom computer bus interfaces. I generally do three or four complete designs a year. Not only do I have a difficult time obtaining small quantities of parts, but I have difficulty getting manufacturers' data books or even return phone calls from distributors of manufacturers' sales offices. I have even been turned down as a qualified subscriber to EDN. It is nearly impossible to be an independent engineer and stay afloat with the industry ignoring me.
Joe Heck
Owner
Joe Heck Enterprises
Wrentham, MA

## Lack of custom parts for repair results in landfill

The letter from Mr Gottlieb hit a nerve with me. At least he has the option of ordering "production quantities" of some items-in my case, five may be a year's supply. If I had to order 1000, I'd have to find a way to resell them.

A related problem: Our company is primarily in the repair business, although we do build one-offs and short runs. Question: What happens when some of these wonderful new de-
signs made with gate arrays, PLDs, and other such custom parts go wrong? (Notice I said "when," not "if.") Chances are the manufacturer won't have any of the gate arrays left, and of course the design will be proprietary, so telling anyone else about it is out of the question. Result: landfill. And that's regardless of whether the product is otherwise any good or not. In a way, this is a "green" issue. What happens when all this wonderful stuff starts being tossed out because one flip-flop in a 3000-gate array went out, rendering half a ton of equipment useless? Ric Locke
E Coyote Enterprises Inc Mineral Wells, TX

## Seed small companies with state-of-the-art parts

In reference to the problem expressed by Peter Gottlieb in the December 5, 1991, issue of EDN, I too have experienced continuing frustration with the difficulty of obtaining small numbers of state-of-the-art components for constructing prototypes.

Manufacturers of ICs and other components fail to realize the importance of seeding small corporations with components that they can use to design new products. Like Mr Gottlieb, I too would be all too happy to pay full price for the privilege of getting a small quantity of state-of-theart components. This would be preferable to jumping through manufacturers' hoops trying to get "freebie" samples.

Please listen, you big IC guys. Sell some of your best stuff to distributors like Allied Electronics or Newark Electronics, charge full price, and let us buy a few to make prototypes. You'll be doubly rewarded. Not only will you get paid for your samples, but some of those samples will turn into products that result in big orders. The most innovative companies are the small ones; that's where the least amount of seed will yield the most product.
Mark Wilson, MD
President
Enkef Instruments Inc
Boulder, CO

## Turn problem into business opportunity

Regarding Peter Gottlieb's complaint in the December 5, 1991, issue: If it's not too late, I'd like to add my name to the amen column. Not only is finding prototype quantities of parts time consuming for a lot of people-with the commensurate lack of productiv-ity-you sometimes settle for a little less than your best in a design just to get it moving. The problem is serious enough that I don't know why someone hasn't turned it into a business opportunity, something like a specialized Digi-Key, if you will. There should be a way to have some kind of shared service. Jim Pierce
JN Designs Inc
Kansas City, MO

## Try Dallas Semiconductor

Amen to Peter Gottlieb's observations about obtaining prototype quantities of electronic parts. Yes, Mr Gottlieb's experiences are typical.

Dallas Semiconductor (Dallas, TX) has a simple method of making very small volumes of their products readily available: You call (800) 336 6933 and use a personal or corporate credit-card number, just as if you were ordering from a consumer catalog. If the company has stock, you will get what you want with little fuss or bother.

Too bad most companies don't do this.
Walt Henry
Fort Worth, TX

[^4]

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## Get real



My son Chris has a problem with most of the auto manufacturers that feature futuristic vehicles at the auto shows. He thinks that unless car manufacturers are really going to offer those cars for sale, they shouldn't show them. I've explained that the futuristic cars at the shows are only testbeds for new technologies and are proof-of-concept vehicles. In fact, many of the tested technologies and designs never make it to market. Either they turn out to be too expensive, no one wants them, or they just don't work. Chris makes a good point, though: Why whet the consumers' appetites when you don't expect to offer the product? I imagine there are others who feel the same way.

Unfortunately, the electronics industry does much the same thing. Companies often announce or demonstrate products that won't reach the market for a year or more-if ever. For example, some people in our industry take the International Solid State Circuits Conference (ISSCC) as a watershed event at which people announce new products. It isn't. The ISSCC gathering is worth attending if you're a chip designer. You'll hear what other companies are doing, and you'll have an opportunity to talk about your own develop-
ment work. However, don't depend on the meeting's papers as plans for newproduct introductions.
We found only a few developments at this year's ISSCC that were set for use in new products within the next quarter. Many of the developments are like the jazzy cars at the auto show. They're one-off models built to test concepts and processes. Testing new ideas is important, as is sharing ideas, and for IC designers, the ISSCC is a good forum. However, there's a big gap in time and cost between talking about ideas and demonstrating test devices, and actually delivering useful products. Some developments never make it out of the lab.

When new processes and technologies begin to show up in real products, we'll let you know. Sure, there will be times when you need to know about complex new products before they become available, but overall, readers tell us that when a product is more than six months from being available for purchase, hold off on telling them about it. After all, what's the use of knowing about a "product" that doesn't exist when you need a real product or design to solve a real problem?
 Editor

Jesse H. Neal
Editorial Achievement Awards 1990 Certificate, Best Editorial 1990 Certificate, Best Series 1987, 1981 (2), 1978 (2), 1977, 1976, 1975

American Society of Business Press Editors Award 1991, 1990, 1988, 1983, 1981

Send me your comments via FAX at (617) 558-4470, or on the EDN Bulletin Board System at (617) 558-4241 300/1200/2400, 8,N,1; on 9600-bps modems try (617) 558-4580, 4582 , or 4398.

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Breaking the Barriers...

## EDN-TECHNOLOGY UPDATE

## MICROPOWER VOLTAGE REFERENCES

# Microamps sustain stable sources 

BRIAN KERRIDGE, Technical Editor



Micropower bandgap references provide an attractive alternative to powerhungry zener diodes. But selection, handling, and application of these components remain decisive issues in setfing overall performance.

Achieving a stable voltage is possible using a micropower reference component that consumes as little as $10-\mu \mathrm{A}$ operating current. With other key specifications, like voltage TC (temperature coefficient) of $20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, slope-resistance of $<1 \Omega$, and a one-dollar price tag, suddenly a $7.5-\mathrm{mA}$ reference zener looks like a luxury that powerconscious designers can no longer afford.

All semiconductor references rely upon either zener diode or bandgap operation for generating a stable output voltage. All micropower examples use the bandgap reference principle, which is explained in more detail in the box "Generating a bandgap voltage reference."

A great attraction of bandgap devices is that the primary reference level is inherently a minimum of approximately 1.2 V . (Zeners with comparable performance to bandgap devices don't exist for levels much below 6 V .) In addition, vendors offer bandgap references with output levels of $2.5,4.1,5$, and 10 V , or with the facility to trim output externally to any point within this range.

By far the greatest appeal of bandgap devices is the ability to function with operating currents from milli- down to microamps. Table 1 overviews the specifications of bandgap devices that have minimum operating currents below 100
$\mu \mathrm{A}$, and therefore includes examples that truly qualify as micropower.
The major application for micropower references is to provide a reference source for ADCs and DACs, and increasingly in these applications manufacturers combine converters and references on-chip. Other important applica-


The curved TC-response of Linear Technology's LM 185-2.5 is typical of most micropower references. Quoted TC figures assume a straight-line average from room ambient to temperature extremes.
tions include the primary reference circuit for any battery-powered measuring instrument, battery-condition detectors, and level detecting circuits for initiating protection and control of other circuitry during power-up and powerdown, or power-supply transient situations.

Table 1 clearly illustrates the voltagenoise drawback associated with all bandgap devices. For example, $60-\mu \mathrm{V}$ rms

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## MICROPOWER VOLTAGE REFERENCES

for a $10-\mathrm{Hz}$ to $10-\mathrm{kHz}$ bandwidth is typical. This figure represents at least ten times the voltage noise exhibited by reference zeners, particularly buried types.

Take care when comparing noise performance in vendor's data, as it's
common to find figures expressed as $\mu \mathrm{V} / \sqrt{\mathrm{Hz}}, \mathrm{p}-\mathrm{p}$, or rms, and over different bandwidths-even by the same vendor. What is more useful to know is the p-p noise in ppm over the bandwidth of interest. You can then easily translate $p$-p noise to
digits of error on an ADC, DAC, or digital readout. For a 1.2 V micropower reference, the typical figure of $60-\mu \mathrm{V} \mathrm{rms}$ is equivalent to $300-\mathrm{ppm} \mathrm{p}-\mathrm{p}$ noise error. If you use such a device as the internal reference for a meter or data converter,

## Generating a bandgap voltage reference

All micropower references rely upon the "bandgap" principle for operation. At the heart of each reference are two similar transistors operating at roughly a $10: 1$ current-density ratio. Fig A shows the essential circuit elements. If the collector current in $Q_{1}$ is approximately ten-times that in $Q_{2}$, then the $\mathrm{V}_{\mathrm{BE}}$ difference for the two transistors at $25^{\circ} \mathrm{C}$ is around 60 mV , with a negative TC of approximately $-0.2 \mathrm{mV} /{ }^{\circ} \mathrm{C}$. These numbers result from a simple analysis using Ebers-Moll equations for a p-n junction (for more on Ebers-Moll equations, see Ref 1). The key factor that determines these figures is the operating current-density ratio in the two transistors. In practice, chip geometry maintains the currentdensity ratio, since designers can accurately lay down transistors with emitter areas of a fixed ratio. Often, an 8:1 ratio is chosen.

The negative TC $V_{B E}$ difference across $R_{3}$ translates to a positive TC collector current in $Q_{2}$, which tends to lower $Q_{2}$ 's collector voltage with rising temperature. If


Fig A-Bandgap reference circuits produce a temperature-stable output voltage by combining the + TC voltage across $R_{2}$ in series with -TC $\mathrm{V}_{\mathrm{BE}}$ of $\mathbf{Q}_{3}$.
you choose the ratio $R_{2}: R_{3}$ appropriately, then you can make the positive TC voltage across $R_{2}$ balance the negative TC $V_{B E}$ of another similar transistor, in this case $Q_{3}$. Adding the two voltages produces a reference output voltage that is stable with temperature, and in practice a 1.2 V output exhibits zero TC.

More often, you need reference levels greater than 1.2 V , and it's common to find the circuit shown in Fig B. The circuit still uses the same bandgap difference to produce a stable 1.2 V level, but additional levelshifting and amplifier circuits produce a range of other reference levels depending upon the value of $R_{8}$ and $R_{9}$.

Both circuits shown in Figs A and B are simplified versions of what you will find in the latest micropower references. Reference designers install a multiplicity of additional circuitry for compensating secondary effects on TC and to produce low slope resistance. Laser trimming resistors to produce close-tolerance output voltages adds further complexity.


Fig B-Transistors $Q_{1}$ and $Q_{2}$ operate at the same $I_{C}$, but have different emitter area. Consequent current-density difference produces $\mathrm{V}_{\mathrm{BE}}$ bandgap difference across $\mathrm{R}_{6}$. Internal bandgap reference voltage ( $\approx 1.2 \mathrm{~V}$ ) appears across $\mathrm{R}_{9}$. Reference output voltage is set by ratio $\mathrm{R}_{8}: \mathrm{R}_{9}$.

## EDN-TECHNOLOGY UPDATE

## MICROPOWER VOLTAGE REFERENCES

then this error would contribute directly to approximately 1 digit of run-around on a 12 -bit ADC or DAC or 2 to 3 digits of run-around on a 4.5 -digit display.
In practice, applying a simple low-pass filter across the reference's output reduces noise for most applications. But to obtain appreciable noise reduction, you need to restrict bandwidth to roughly 10 Hz , and this requires large components that take up valuable pe-board space and increase component cost. You need to take care with this ad-
dition, as a reference's output is active and adding only a capacitor directly across the terminals is likely to induce oscillation.

The relatively poor characteristic noise performance of bandgap devices derives from their low operat-ing-current design. Micropower examples suffer proportionately more, since operating currents down to 10 $\mu \mathrm{A}$ are permissible. The problem is one fundamental to any lowcurrent IC design. By virtue of the design, internal IC resistor values need to be high, as are intrinsic
transistor resistances when operating at such low currents ( $I_{C}$ may be $<1 \mu \mathrm{~A}$ ). Consequently, you cannot avoid Johnson noise in these high resistances. In fact, Johnson noise forms the dominant noise source in a micropower reference. Types with outputs boosted above 1.2 V have higher noise levels still, since additional internal components make their noise contribution to the amplified inherent noise.

Selecting a micropower reference with a voltage TC anywhere from 100 down to $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ simply de-

| Manufacturer | Type | Voltage | Operatingcurrent (min) ( $\mu \mathrm{A}$ ) | sentative$\begin{gathered} \text { TC max } \\ \left(-40 \text { to }+85^{\circ} \mathrm{C}\right) \\ \left(\mathrm{ppm} /{ }^{\circ} \mathrm{C}\right) \end{gathered}$ | Noise (typical) | Output slope resistance (max) ( 1 ) | Package | Comments | Price ${ }^{3}$ <br> (100) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |
| Analog Devices | REF-195 | $\begin{gathered} 5.0 \mathrm{~V} \\ \pm 0.02 \% \end{gathered}$ | 30 | $\begin{gathered} 4 \mathrm{ppm} /{ }^{\circ} \mathrm{C} \\ \pm 1 \mathrm{mV} \end{gathered}$ | $\begin{gathered} 50 \mu \vee p-p, \\ 0.1 \text { to } 10 \mathrm{~Hz} \end{gathered}$ | 0.01 | Plastic and ceramic 8 -pin DIP, SO-8 | 2-stage output adjust-laser trim on wafer and fuse links after packaging; output sources to 30 mA . | \$1.95 |
| GEC Plessey Semiconductors | SR12D | $\begin{aligned} & 1.23 \mathrm{~V} \\ & \pm 3 \% \end{aligned}$ | 90 | 120 | $10 \mu \mathrm{~V}$ rms, 1 Hz to 25 kHz | 2.5 | SOT-23 | Other voltages 2.5 and 5 V , maximum operating current 2.5 mA . | \$1.10 |
|  | REF12 | $\begin{aligned} & 1.26 \mathrm{~V} \\ & \pm 1 \% \end{aligned}$ | 60 | 56 | $\begin{gathered} 1 \mu \mathrm{~V} / \sqrt{\mathrm{Hz}} \\ 0.1 \mathrm{~Hz} \text { to } 25 \mathrm{kHz} \end{gathered}$ | 4 | T0-92, MP-8 | Other voltages 2.5 and 5 V , maximum operating current 2.5 mA , TC in MP-8 package is $80 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$. | \$1.10 |
| Linear Technology | LT1004C-1.2 | $\begin{aligned} & 1.20 \mathrm{~V} \\ & \pm 0.3 \% \end{aligned}$ | 10 | 20 typ ${ }^{2}$ | $\begin{gathered} 60 \mu \mathrm{rms} \\ 10 \mathrm{~Hz} \text { to } 10 \mathrm{kHz} \end{gathered}$ | 0.6 | TO-46, TO-92 | Other voltage 2.5 V , maximum operating current 20 mA , longterm stability $20 \mathrm{ppm} / 1000$ hours. | \$1.35 |
|  | LT1034C-1.2 | $\begin{aligned} & 1.20 \mathrm{~V} \\ & \pm 1 \% \end{aligned}$ | 20 | $40^{2}$ | $\begin{gathered} 4 \mu \mathrm{~V} \text { p-p } \\ 0.1 \text { to } 10 \mathrm{~Hz} \end{gathered}$ | 1 | TO-46, TO-92 | Other voltage 2.5 V , maximum operating current 20 mA , package includes 7 V zener reference. | \$2.85 |
|  | LM385-2.5 | $\begin{aligned} & 2.50 \mathrm{~V} \\ & \pm 1 \% \end{aligned}$ | 20 | 20 typ ${ }^{2}$ | $\begin{array}{\|c\|} \hline 120 \mu \mathrm{~V} \mathrm{~ms} \\ 10 \mathrm{~Hz} \text { to } 10 \mathrm{kHz} \end{array}$ | 1 | TO-46, TO-92 | Maximum operating current 20 mA , long-term stability 20 ppm/1000 hours. | \$0.80 |
| Maxim | MAX872 | $\begin{aligned} & 2.50 \mathrm{~V} \\ & \pm 0.1 \% \end{aligned}$ | 10 | $40^{2}$ | $\begin{aligned} & 60 \mu \mathrm{Vp-p} \\ & 0.1 \text { to } 10 \mathrm{~Hz} \end{aligned}$ | 0.3 | Plastic 8-pin DIP | Minimum supply voltage 2.6 V , trim-pin for +100 mV to $\mathbf{- 2 5 ~ m V}$ adjustment. | \$2.25 |
|  | MAX874 | $\begin{aligned} & 4.10 \mathrm{~V} \\ & \pm 0.1 \% \end{aligned}$ | 15 | $40^{2}$ | $\begin{aligned} & 90 \mu \vee \mathrm{p}-\mathrm{p} \\ & 0.1 \text { to } 10 \mathrm{~Hz} \end{aligned}$ | 0.3 | Plastic 8-pin DIP | Minimum supply voltage 4.2 V , trim-pin for $\pm 0.2 \mathrm{~V}$ adjustment. | \$2.25 |
|  | ICL8069 | $\begin{gathered} 1.23 \mathrm{~V} \\ \pm 1.6 \% \\ \hline \end{gathered}$ | 50 | $100^{2}$ | $\begin{array}{\|c\|} \hline 5 \mu \mathrm{~V} \mathrm{~ms} \\ 10 \mathrm{~Hz} \text { to } 10 \mathrm{kHz} \\ \hline \end{array}$ | 2 | TO-52, TO-92 | Maximum operating current 5 $\mathrm{mA}, \mathrm{TC}$ selection to $10 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$. | \$1.13 |
| Micro Power Systems | MP5010 | $\begin{gathered} 1.22 \mathrm{~V} \\ \pm 2.5 \% \\ \hline \end{gathered}$ | 50 | 100 | $5 \mu \mathrm{~V}$ rms 10 Hz to 10 kHz | 2 | $\begin{gathered} \text { TO-52, TO-92, } \\ \text { or SO-8 } \end{gathered}$ | Maximum operating current 5 mA , TC selection to $5 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ | \$0.86 |
| National Semiconductor | LM385-1.2 | $\begin{aligned} & 1.2 \mathrm{~V} \\ & \pm 3 \% \end{aligned}$ | 10 | $150^{2}$ | $\begin{gathered} 60 \mu \mathrm{Vms} \\ 10 \mathrm{~Hz} \text { to } 10 \mathrm{kHz} \end{gathered}$ | 1.5 | $\begin{aligned} & \text { TO-46, TO-92, } \\ & \text { or SO- } 8 \end{aligned}$ | Maximum operating current 20 mA , other voltages 2.5 V and adjustable, voltage selection to $\pm 0.3 \%$, long-term stability 20 ppm/1000 hours. | \$0.94 |
|  | LM4040 | $\begin{aligned} & 2.5 \mathrm{~V} \\ & \pm 2 \% \end{aligned}$ | $65$ | 100 | $\begin{gathered} 35 \mu \mathrm{Vms} \\ 10 \mathrm{~Hz} \text { to } 10 \mathrm{kHz} \end{gathered}$ | 0.8 | $\begin{aligned} & \text { TO-92, SO-8, } \\ & \text { or SO-23 } \end{aligned}$ | Maximum operating current 20 mA , other voltages 4.1, 5, 8.2, and 10 V , voltage selection to $\pm 0.1 \%$. | \$0.85 |
| Notes: <br> 1. Specifications at $25^{\circ} \mathrm{C}$ unless otherwise stated. <br> 2. TC for ambient temperature range 0 to $70^{\circ} \mathrm{C}$. <br> 3. Prices shown for TO-92 where available, or plastic 8 -pin DIP. |  |  |  |  |  |  |  |  |  |



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## MICROPOWER VOLTAGE REFERENCES

pends upon how much you are prepared to pay. For approximately $\$ 1$ you get a typical $20 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ device. For a guaranteed maximum of 5 $\mathrm{ppm} /{ }^{\circ} \mathrm{C}$, you'll pay more than $\$ 10$. At this level, micropower reference TC performance equates to the best specification reference zeners, such as 1 N 829 A .

In all cases, the TC figure quoted in specifications is a straight-line average of a curved response taken from the midpoint to the extremes of the operating temperature range. The reference designers arrange that the TC approaches zero somewhere around room-ambient temperature. As the operating temperature moves off to either the maximum or minimum limit, the reference's output voltage falls more and more rapidly. Manufacturers apply various forms of compensation to iron out this basic curved response, but the TC result is never linear over the full operating temperature range.

## Stress influences stability

Long-term performance of micropower references is something most vendors are reluctant to specify, since this specification is very much stress related, and therefore dependent upon application. Linear Technology quotes a figure of 20 $\mathrm{ppm} / 1000$ hours for all its micropower references. This figure is worst case over the first 1000 hours, because as the component ages, the voltage increasingly stabilizes. As a rule of thumb for designing-in micropower references, you can safely assume a long-term stability specification of $20 \mathrm{ppm} / \sqrt{1000 \text { hours }}$ when you operate the component at room ambient.

However, if you operate references at extremes of temperature, then expect other effects to appear. For example, if you temperature cycle a reference from room ambient to its maximum or minimum operating temperature and back, you may see a hysteresis jump in output
voltage as high as 100 ppm . Stress in the die and package forces changes' into the reference circuit to cause this jump. The reference output voltage will eventually recover close to its original value over several days of operation.

If long-term stability is a major concern, then oven baking all your reference parts at $150^{\circ} \mathrm{C}$ for a couple of days before you use them generally proves beneficial. This process tends to relieve initial stress left in the die and package following component manufacture, which in turn influences stability.

This effect raises the issue of choice of packaging in general. Although most vendors don't differentiate performance relative to package style, it's well known that choice of packaging does influence reference output voltage. In a plastic package for example, the moulding presses down on the top of the die, and therefore exerts a slight force. IC legs running through plas-
tic are not hermetically sealed, and therefore atmospheric changes can access the die. Plastic surfacemount packages introduce the additional possibility of a flexing pc-board's transmitting vibration through to the die. The net result is that your reference voltage performance is more likely to be further inside its published specification if you use a package that stands off from the pc-board, or even better has hermetically sealed legs (as in the case of ceramic or metal-can packages).

GEC Plessey Semiconductors is the only company to declare stability figures for different packages. Its REF12 1.2 V references in TO92 and 8-pin surface-mount packages have TC maximum values of 56 and $80 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$, respectively.

With a favorable mix of specifications, micropower references, in general, can supplant zeners in many applications. Future references will offer tight voltage and

## For more information . . .

For more information on the micropower reference products discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you read about their products in EDN.

| Analog Devices Inc | Maxim Integrated Products | National Semiconductor <br> 1500 Space Park Dr |
| :--- | :--- | :--- |
| Santa Clara, CA 95052 120 Gabriel Dr | 2900 Semiconductor Dr |  | A/D \& D/A CONVERSION POWER HYBRIDS SOLID-STATE POWER CONTROLLERS



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[^6]

CIRCLE NO. 36

EDN-TECHNOLOGY UPDATE

## MICROPOWER VOLTAGE REFERENCFS

TC specifications by design, rather than by the expensive component selection route. Analog Devices' REF-195 exemplifies this trend with its $0.02 \%$ tolerance and $4 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ as standard. However, $10 \mu \mathrm{~A}$ as a minimum operating current is likely to remain simply because of fundamental noise problems.

EDD

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1. Knapp, Ron. "Selection criteria assist in choice of optimum reference." EDN, February 18, 1988, pg 183.
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3. Williams, Jim. "Micropower Circuits for Signal Conditioning." Linear Technology App Note 23, April 1987.

Article Interest Quotient (Circle One)
High 479 Medium 480 Low 481


Designed for use with the Intel 80486DX and 80486SX microprocessors and the Intel i860XR RISC processor, packaged in 168-pin ceramic PGAs, the EG\&G Wakefield 669 Series Heat Sink/Clip Assembly offers a cost-effective heat dissipation solution for today's high-speed microprocessors. This assembly provides the highest clamping force available with a nylon-coated stainless steel clip, for the most efficient interface heat transfer and to meet system shock and drop test requirements. Our omnidirectional heat sink offers optimized heat dissipation and ease of application; the symmetrical clip is suitable for high volume installation with the EG\&G Wakefield 162 -IT installation tool.
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| MC 79MXX | 500 mA | Negative Fixed | $-5,-12,-15$ |
| LM 317M | 500 mA | Psositive <br> Adjustable | $1.2-37$ |
| LM 2931 | 100 mA | Positive Fixed, <br> low V diff. | 5 |

Planned for introduction in mid-1992:

| Device | Output <br> Current | Type | Output <br> Voltage |
| :---: | :---: | :---: | :---: |
| MC 34268 | 800 mA | SCSI-2 Active <br> Regulator | 2.85 |

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## BATIERY-POWERED DSOs

# Versatile units find more use than you might expect 

DAN STRASSBERG, Technical Editor

> Though widely thought of as tools for field service and, at times, for fest, these rugged versatile instruments offer surprisingly good performance that often is iust what
design engineers often is just what
design engineers need. tools for field


A product designed to meet the needs of a well-defined audience can appeal to a significantly larger group. Although the designers of three and possibly four of the five battery-powered DSOs in Table 1 clearly had field-service engineers in mind, the scopes will also be useful to many design engineers.

Four of these five battery-powered DSOs (from Fluke/Philips, Gould, Leader, and Tektronix) feature small size and light weight. Three of the units (Fluke, Leader, Tektronix) weigh less than 5 lbs and fit easily into an attache case. These three units also provide input-to-chassis ohmic isolation unavailable in acpowered DSOs-although, in one instance (Leader), the isolation applies not to the scope but to the DMM that resides in the same enclosure. The two larger units (Hewlett-Packard (HP) and Gould) are full-featured designs that make few compromises. One of these, the HP unit, is a generalpurpose DSO teamed with a package that contains a sealed lead-acid battery and an inverter.

The smallest units (Fluke, Leader) have LCDs that display both numeric information and waveforms (see box, "Some notable features"). The Fluke 97 's LCD offers electroluminescent backlighting. (Fluke's lower-priced 95 and 93 and Leader's 300 lack backlighting; you can use their displays only where there is adequate ambient light.) The
other scopes use CRTs. The Tektronix units' CRTs are small but quite readable; the HP's screen is standard scope size ( 7 in . diagonal); the Gould's screen size falls in between the other two.
To digitize repetitive waveforms at very high effective rates ( 2 to 10 GHz ), all of the DSOs, except the Leader 300, use random equivalent-time sampling, which lets you view pretrigger information. The Leader unit uses sequential equivalent-time sampling to multiply its acquisition rate by 5 to $10 \times$ at the highest sweep speeds. To take full advan-


Drawing some of its design concepts from handheld DMMs, Fluke's 97, which is about $3 \times$ the size of such meters, provides $\mathbf{5 0 - M H z}$ bandwidth, a 2.5 -Gsample/sec equivalent acquisition rate for repetitive signals, and a long list of features, including a built-in sine/square-wave generator.

Table 1-Representative battery-powered DSOs

| Vendor and model | Fluke 973 | Gould 465 | HP 54600A/601A scopes; 85901A inverter | Leader 300 | Tektronix 222A, 224, 222PS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Base US list price | \$1795 | \$4485 | Scopes: \$2495, \$2895; Inverter: \$1290 | \$1995 | \$2450, \$2750, \$2750 |
| Size $-H \times W \times D$ (in.) | $10.8 \times 5.5 \times 2.5$ | $7.6 \times 10.7 \times 15.7$ | $\begin{aligned} & 6.8 \times 12.7 \times 12.5 ; \\ & 4.9 \times 13.3 \times 18.1 \end{aligned}$ | $6.5 \times 9.4 \times 1.8$ | $3.4 \times 6.3 \times 9.9$ |
| Weight (lbs) | 4 | 14 | Scopes: 14; Inverter: 31.3 | 2.69 | 4.4 |
| Battery type; size | $4 \mathrm{NiCd} ; \mathrm{C}^{4}$ | NiCd | Sealed lead-acid | 4 Alkaline; AA | Sealed lead-acid |
| Operating time (hours) | 4 | 2 | 2 minimum, 2.5 typical | 2.25 | 3 minimum; 4 typical |
| Low-battery indication | Symbol flashes | None | Flashing LED and buzzer | Display | Warning on CRT |
| Warning before shutoff | 1 hour | NA ${ }^{7}$ | 10 minutes | 10 minutes | 2 to 3 minutes |
| Fastest recharge time | 10 hours | 2 x discharge time | 3 hours typical, 6 hours maximum | See "Battery" box | 3 hours |
| Charge within scope? | Yes | Yes, ONLY in scope | Battery recharges within inverter | No | Yes |
| Use while charging? | Yes | Yes | Can use scope by disconnecting inverter | NA | Yes |
| Charge time (scope on) | 18.5 hours | 2 x discharge time | NA | NA | About 6 hours |
| Supply needed for ac? | Yes | No | No; without inverter, scopes run on ac | Yes | Yes |
| Supply price | Included | NA | $N A$ | $\$ 39$ | Included |
| External charger price Battery price |  | NA $\$ 250$ (repair) | Included in inverter \$72.50 | See box in story Depends on type | $\begin{aligned} & \$ 200 \text { See "Battery" box } \\ & \$ 70 \end{aligned}$ |
| Channels, max traces ${ }^{1}$ | 2, 4 | 2, 2 | $\begin{aligned} & \text { 54600A: } 2,4 ; \\ & 54601 A: 4,4 \end{aligned}$ | 2, 4 | 2, 2 |
| Bandwidth ( MHz ) | $50$ | $100$ |  | $10$ | 222A, 222PS: 10; 224: 60 |
| Max samples/sec/ channel | See note 6 | $200 \mathrm{M}$ | 20M | $\begin{aligned} & \text { 30M-1 shared } \\ & \text { ADC } \end{aligned}$ | $10 \mathrm{M}$ |
| Samples/trace (stored) | 512 | 512 | 4000 | $180 ; 1800$ <br> switchable | 512 |
| Bits/sample | 12 | 8 | 8 |  |  |
| Equivalent-time mode | Random 2.5G | Random | Random | Sequential | Random |
| Effective samples/sec | $2.5 \mathrm{G}$ | $2 G$ | 10G (100-psec resolution) | $150 \mathrm{M}$ | 1G |
| Captured-glitch width | 40 nsec | See note 8 | 50 nsec at all sweep speeds | No glitch capture | 100 nsec at slowest sweep |
| Time/div (min, max) Volts/div (min, max) | $10 \mathrm{nsec}, 60 \mathrm{sec}$ <br> $1 \mathrm{~m}, 1 \mathrm{k}$ (probe) | $\begin{aligned} & 25 \mathrm{nsec}, 50 \mathrm{sec} \\ & 2 \mathrm{~m}, 5 \end{aligned}$ | $2 \mathrm{nsec}, 5 \mathrm{sec}$ $2 \mathrm{~m}, 5$ ( 50 with probe) | 0.1 usec, 200 sec $5 \mathrm{~m}, 20$ (2-kV probe) | 5 nsec (magnified), 200 sec 222A: $5 \mathrm{~m}, 50$; Others: $50 \mathrm{~m}, 200$ |
| Display type <br> Display size <br> Display resolution | $\begin{aligned} & \text { EL back-lit LCD } \\ & 84 \times 84 \mathrm{~mm} \\ & 240 \times 240 \text { pixels } \end{aligned}$ | $\begin{aligned} & \text { CRT } \\ & \text { NS } \\ & \text { NA } \end{aligned}$ | CRT <br> 7 in. diagonal $255 \times 500$ points | $\begin{aligned} & \text { LCD } \\ & 60 \times 113 \mathrm{~mm} \\ & 128 \times 180 \text { pixels } \end{aligned}$ | CRT with stroke vectors NS NA |
| Isolation voltage ${ }^{2}$ | 600 V rms; 4 kV peak | Not isolated | Floating ground NOT recommended | See note 10 | 222 PS: 600 V rms; Others: 400 V peak |
| Hard-copy provisions | Isolated RS-232C | Integral plotter | RS-232C, IEEE-488, parallel modules | Accessory printer | Yes, see note 11 |
| Affects isolation? | No | NA | NA | No | No |
| Extended data storage | Months | About 1 month | With optional module; duration NS | 1 month | Several months |
| Retains panel setups? | Yes, 10 | No | Yes, 16 | No (has autosetup) | Yes, 4 |

## Notes:

1. The first figure is the number of signals the unit can acquire and simultaneously display. The second figure is the largest number of traces displayed at one time. Some units can display signals acquired and stored earlier, in addition to those being acquired.
2. The highest common-mode voltage you can safely apply between the scope's chassis and its $Y$-axis input terminals.
3. The 90 series also includes the 93 and 95 , which offer fewer features at lower prices.
4. Unit can also run from nonrechargeable Alkaline cells.
5. $N S=$ Not specified.
6. Because of the need to sample a signal several times per cycle to reconstruct it with reasonable accuracy, the usable bandwidth for single-shot events is approximately 6 MHz .
7. $N A=$ Not applicable.
8. $1 \mu \mathrm{sec}$ at $100-\mu \mathrm{sec} / \mathrm{div}$ sweep speed.
9. Weight shown is without batteries.
10. Withstands 1.1 kV between either DMM input and scope ground and also between DMM voltage and common inputs. Withstands 250 V between DMM ohms and common inputs. DMM mA input is fused. Scope Y -axis inputs withstand 400 V to ground without a probe and 600 V with a probe. Trigger inputs withstand 100 V to ground. All withstanding voltages are $\mathrm{dc}+\mathrm{p}-\mathrm{p}$ ac for 1 minute.
11. The $\$ 295$ WP200 provides a parallel interface to Epson FX-compatible printers. The $\$ 395$ CAT200 allows an MS-DOS PC to control the scope. With this package, you can obtain waveform printouts on a graphics-capable printer connected to the PC.
tage of any of these scopes' vertical bandwidth, you must use their equivalent-time modes.
The Gould 465 has a real-time sampling rate of $200 \mathrm{Msample} / \mathrm{sec}$ high enough, in theory, to let you view single-shot events whose frequencies extend over its full $100-$ MHz bandwidth. However, you're well advised to limit your viewing of single-shot signals to those whose frequencies don't exceed 50 MHz . Observing this precaution will provide 4 samples/cycle, the minimum most scopes need to reconstruct waveforms well enough for you to make sense of what you see. (Although 4 samples/cycle is a usable rate, several scope vendors recommend rates of at least 10 samples/ cycle. Using that figure, you should limit the bandwidth of single-shot events you view with the Gould 465 to 20 MHz .)
Similarly, the Leader 300's maximum 30-Msample/sec rate (when digitizing one channel) is theoretically adequate to capture signals having components at 10 MHz (the full bandwidth). But at 3 samples/ cycle, signal reconstruction would not be adequate, so the scope switches to the sequential equiva-lent-time mode at sweep speeds that let you observe the details of $10-\mathrm{MHz}$ signals.
These units represent some of the best examples of how today's DSOs exhibit both higher performance and lower prices than were obtainable in instruments introduced only a few years ago. Still, these scopes are somewhat more expensive than analog scopes whose key electrical specifications are similar. Therefore, you have good reason to ask why you shouldn't choose a less-expensive battery-powered analog scope in place of a batterypowered DSO.
In the case of the Fluke/Philips and Leader units, no analog scopes offer equivalent performance and features in similar packages (see


Although it resembles a pint-size version of a conventional scope, the Tektronix 224 is not conventional. It offers $60-\mathrm{MHz}$ bandwidth, and its two inputs are ohmically isolated not just from the chassis but from each other.
box, "Some notable features"). Moreover, the Tektronix scopes, in addition to their small size and high performance, offer inputs that are ohmically isolated not just from the chassis but from each other. Not only is such isolation unique among the scopes in Table 1, if it is available at all in analog scopes, it isn't easy to find.

Isolation is particularly important when you work with high voltages. When you connect a source of high common-mode voltage to an isolated scope input, you can touch the instrument's controls without fear of receiving a shock, provided the voltage doesn't exceed the scope's breakdown rating. The only currents that flow across the isolation barrier are small leakage currents, due mostly to the barrier's nonzero isolation capacitance.

With nonisolated inputs, including differential ones, the usual way to measure signals at high commonmode voltages is to disconnect the scope's chassis from ground (for example by connecting the scope to the ac line with a "cheater" 3 -prong to 2-prong adapter). With such a connection, you risk a possibly le-
thal shock if you touch any of the scope's metal parts. Obviously, scope manufacturers don't sanction such operation.

In some applications that require isolation, the classic reasons for choosing a DSO rather than an analog scope are particularly important. When displaying phenomena that occur infrequently, most ana$\log$ scopes present dim, flickering images; observing these dim traces at best requires a viewing hood. Sometimes, the only way to see such displays is by photographing them with very fast film. Low repe-tition-rate signals are common in power-supply and motor-control work where high voltages often necessitate isolation. Among analog scopes, only storage scopes provide bright displays of low repetitionrate phenomena. But most storage scopes are large and costly, and few operate from batteries or offer isolation.

## Isolation and battery power

One reason that isolation and battery power seem to go together is that, although you can certainly design a power supply with no resis-

## EDN-TECHNOLOGY UPDATE

## BATTERY-POWERED DSOs

tive path to its output from the ac line, designing a supply with line-to-output capacitance (isolation capacitance) of only a few pF is a challenging task that usually increases its cost. By eliminating the line connection, battery operation lowers isolation capacitance and allows higher common-mode voltages than economical ac-powered instruments
can withstand. Stated another way, even if your battery-powered scope works when connected to ac, when you take advantage of its isolation capability, you'll get the best results if you run it from its batteries.

If you don't need isolation but need portability and want to save captured waveforms indefinitelysay, on a floppy disk-the idea of
plugging an ISA-bus DSO card into a laptop PC, thus turning the PC into a battery-powered DSO, seems an obvious solution. As far as EDN could find out, though, no such configuration operates completely from batteries. We know that notebook PCs (which are even smaller than laptops) are out of the question; they lack bus slots. On the other

## Some notable features

Fluke 97 -Simultaneously acts as DMM (3000 counts full-scale) and scope through same leads. Adds, subtracts, multiplies, inverts, filters, and integrates waveforms. Also functions as sine/square-wave generator.

Numeric display capabilities: Voltage differences; time differences; frequency; maximum, minimum, $p-p, r m s$, $\mathrm{rms}+\mathrm{dc}$, and mean voltage; phase; rise time; fall time; time from trigger to cursor; ratio; $\mathrm{dBm}^{2}$; dBV ; dBW; resistance.
Gould 465-Any two traces can be added, subtracted, or multiplied. In persistence mode, simultaneously displays all acquisitions over a period of time. Auto-setup mode evaluates inputs, chooses appropriate ranges, and displays settings on screen. A plotter option $(\$ 600$ if purchased with the scope; $\$ 695$ if you add it after purchase-you can install it yourself) provides hard-copy output capability within scope. The identical scope, without battery power, costs $\$ 3490$. You can later add battery power for \$1275.

Numeric display capabilities: Cursor measurements of rise time, frequency, duty cycle, overshoot, p-p voltage, period, pulse width, area, and rms voltage.
Hewlett-Packard 54600A/601A, 85901AFast ( $250 \times$ per sec) updates and familiar control layout produce a DSO with "analog feel" but, when displaying low repetition-rate signals, without the faint, flickering traces of analog scopes. Autostore mode displays the average of many waveforms at full brightness and the envelope of all measurements at half brightness. Optional modules allow expanding the scopes' capabilities, for example to add an RS-232C, parallel, or IEEE488 interface; long-term waveform storage; or limittesting.

Numeric display capabilities: Automatic and cursorbased measurements of average, rms, peak, $\mathrm{p}-\mathrm{p}$, and minimum voltage; frequency; period; duty cycle; rise time; fall time; time a signal is positive; and time a signal is negative.

Leader 300-Incorporates 3200-count DMM whose input is separate from the scope channels, making it, in a sense, a 3 -channel unit. With optional logic probe, functions as 8 -channel $15-\mathrm{MHz}$ logic-timing analyzer. Logic-analyzer memory depth is 180 words when sweep speed is $5 \mu \mathrm{sec} / \mathrm{div}$ or faster and 1.8 k words at slower sweep speeds. Optional credit-card size bat-tery-backed memory card stores 80 normal-length ( 180 -word) DSO traces, eight 1.8 k -word traces, 10 screens of 8 -channel $\times 180$-word (or one screen of 8 channel $\times 1.8 \mathrm{k}$-word) logic-analyzer data. Uses sequential equivalent-time sampling to achieve a 5 to $10 \times$ improvement in sampling rate at the highest sweep speeds. Also offers a "strip-chart" or "roll" mode for low-speed signals.

Numeric display capabilities: Range and mode information appears continuously at left side of screen and on screen printouts produced by accessory printer.
Tektronix 222A, 224, 222PS - The 222PS has a motor-control trigger feature that provides a stable display of variable-frequency waveforms that normally cause triggering problems. Because of the stroke-vector display and $1 / 30$-sec update speed, the display resembles that of an analog scope. Channels are separately isolated from chassis and have separate ADCs. (Some competitive scopes provide isolation between the chassis and all inputs as a group. Such scopes tolerate only limited common-mode voltages between their inputs and the floating ground.) The 220 -series scopes are listed by Underwriters' Laboratories (UL) and Canadian Standards Association (CSA). The 222PS withstands 6 -kV common-mode transients.
Numeric display capabilities: These scopes do not provide numeric displays of measured quantities. They do display range settings on their CRTs.

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## BATTERY-POWERED DSOs

hand, some laptops do have slots (usually a single slot). We inquired of two vendors of PC-based scope hardware-Rapid Systems (Seattle, WA) and Gage Applied Sciences (Montreal, PQ, Canada)-to see if they knew of a laptop PC and a scope card or scope accessory that would work together under battery power.

The few laptops that have slots seem not to have the full-length slots needed to accommodate DSO cards. Moreover, the bus connectors of some of these laptops don't deliver the normal supply voltages that DSO cards need. The laptops that allow you to use a full-length ISA-bus board require you to bolt an accessory unit to their lower surfaces. Such combinations are still quite small and light and provide large high-resolution screens. Unfortunately, although the PCs operate from internal batteries, the accessory units' supplies require ac. So, although you may be able to configure a DSO around a laptop PC, your PC-based scope won't operate without ac power.

If you could construct a PC-based


A different approach to battery-powered DSOs is embodied in Gould's 465. You can purchase this small scope with or without the battery pack. The vendor intends the scope primarily for operation where ac is available, but with the batteries, it will run for two hours or more away from the power line.
battery-powered digital scope, with appropriate software, its disk drives would provide a feature not available in any of Table 1's DSOs: truly nonvolatile waveform storage. Although none of the scopes has a disk drive, most of the units offer fairly long-term storage, even when you have drained their batteries so much that you need fresh batteries or an ac source to continue scope operation. (See the row "Extended

## For more information

For more information on the battery-powered DSOs discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you read about their products in EDN.

John Fluke Mfg Co Inc Box 9090
Everett, WA 98206
(800) 443-5853;
(206) 347-6100

Circle No. 700
In Europe:
Philips Test \&
Measurement
Bldg TQIII
5600 MD , Eindhoven
The Netherlands
Phone local office
Circle No. 701

## Gould Inc

Test \& Measurement Group
8333 Rockside Rd Valley View, OH 44125 (216) 328-7000 FAX (216) 328-7400 Doug Maclennan Circle No. 702

Hewlett-Packard Co
19043 Pruneridge Ave Cupertino, CA 95014 (800) 752-0900 Circle No. 703

## Leader Instruments Corp

 380 Oser AveHauppauge, NY 11788
(800) 645-5104;
(516) 231-6900

FAX (516) 231-5295
Joe Fisher
Circle No. 704
Tektronix Inc
Box 1520
Pittsfield, MA 01202
(800) 426-2200

Circle No. 705

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data storage" in Table 1.) In some cases though, if you retain a critical waveform, you limit the scope's ability to acquire additional signals.

Of the listed scopes, only the Leader 300 can transfer waveforms to a credit-card-size, batterybacked RAM card. Such cards store data for years. Although RAM cards sometimes can function as media for exchanging data with other units-for example, suitably equipped PCs-you shouldn't assume that all such cards are interchangeable. Leader's Joe Fisher says that the main purpose of the 300's RAM cards is to extend the scope's storage. Your PC most likely will not be able to read waveforms from the 300's RAM cards.

With the other scopes, if you want to save a waveform indefinitely, you must transfer it elsewhere, say to a desktop PC's hard disk. Several of the scopes provide ports through which you can transfer the data. In some cases, you have a choice of the type of port-RS-232C, parallel, or IEEE-488. The Fluke and Tektronix scopes allow you to use the serial port without affecting the scope's input-tooutput isolation.

However, using an RS-232C port to save a waveform is not an ideal

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solution. Usually, this approach requires you to be near the computer to which you will transfer the data. Connecting a small modem to the scope's serial port might save the day when the computer is some distance away, but remember, the scope is not a PC. The scope won't run your favorite telecommunications software package. On the PC, a package designed to download waveforms from your scope may not work with a modem.

If you can't save waveforms as files on a disk, perhaps the best alternative is printing them out. Your computer may not be able to read the printouts, but you will be able to, and the printouts will last a while. Mostly, if you want a printout, you must rely on communicating via a serial, parallel, or IEEE488 port. The Leader 300 offers a


Extended data storage in credit-card-size, battery-backed RAM cards and the ability to print out waveforms on a dedicated accessory printer are just two of the Leader 300's features. The unit also includes a 3000 -count DMM and, with an accessory probe, converts to an 8-channel logic-timing analyzer.

## A battery of batteries for battery-powered DSOs

Among manufacturers of battery-powered equipment, there is no unanimity on which battery chemistry system is "the best." The reason, not surprisingly, is that "best" means different things to different people. Even when the products perform similar functions and are used by people in similar jobs under similar conditions, product designers can have radically different views of the relative importance of various aspects of performance and cost. As a result, the scopes in Table 1 use NiCd, Nickel-metal-hydride, and sealed lead-acid rechargeable batteries as well as nonrechargeable Alkaline cells. (Technically, a battery consists of several cells. Despite what people commonly call them, most cylindrical "batteries"-for example, the C and AA sizesreally are individual cells. On the other hand, a 9 V "transistor-radio" battery really is a battery because it contains several cells.)

The designers of Fluke's 90 series had flexibility in mind. They chose C -size NiCd cells as the units' usual power source, but designed the scopes (or "Scopemeters," as Fluke calls them) to work from C-size Alkaline cells too. That way, if you don't spend the money for an extra set of NiCds and you exceed the four hours of operation you can expect from the rechargeable cells, you can remove the NiCds and substitute a set
of Alkaline cells. C-size Alkaline cells are quite inexpensive and are available in supermarkets and variety stores. Moreover, Alkaline cells have a shelf life measured in years and will run the Scopemeters longer than the NiCd cells will-perhaps twice as long.

Fluke has not yet stated that you can substitute Nickel-metal-hydride cells for the NiCds. Nickel-metal-hydride cells are only just now starting to appear commercially. They are still quite expensive, but in applications that draw moderate discharge currents (and that includes the majority of battery-powered electronic equipment), they will usually run the equipment for a period significantly longer than NiCd cells will (that is, for nearly as long as Alkaline cells will run it). On the other hand, Nickel-metal-hydride cells discharge themselves more rapidly than NiCd cells do, and NiCds exhibit faster self-discharge than Alkaline cells. In other words, if you use rechargeable batteries, to maximize their operating time, you should, if possible, keep them "float charged" (so they don't self discharge) until just before you use them.

The designers of Leader's 300 did not give top priority to using rechargeable batteries. They built the scope to run first of all from Alkaline cells (AA size), but you can substitute NiCd or Nickel-metal-hydride cells for
separate accessory printer designed for use with the scope. Its printouts show the measurement ranges in use. The larger Gould 465 provides the most convenient solution: It accommodates a color plotter, and installing the plotter doesn't increase the scope's size. You can order the scope with the plotter or easily add the plotter yourself after purchase.

## No time left

If you are in the middle of taking important data when your scope's batteries are about to run down, you'd probably like some warning and maybe you'd like to replace the batteries with a freshly charged set. Most of the units provide a lowbattery indication on their displays. Usually, the warning occurs when enough operating time remains for you to print out the contents of the
waveform memories-if a printer is handy.
Some of the scopes use separate batteries to retain data after shutdown, so you can replace the main batteries and resume operating pretty much as if there had been no power interruption. In some cases, if you don't have more rechargeable batteries ready, you can substitute nonrechargeable ones. (See box, "A battery of batteries for battery-powered DSOs.")

Stacked up against larger and more expensive DSOs, these units set no performance records, but the availability of very respectable performance in small, rugged, relatively inexpensive packages is definitely noteworthy. When you consider that these instruments operate without ac power (and in some cases, provide isolated inputs)
and that some of them offer useful features rarely found in scopes (fullfeatured DMMs in the Fluke and Leader units, a logic-timing analyzer in the Leader 300, a sine/ square-wave generator in the Fluke 97), you're justified in calling them quite remarkable.

EDT
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the Alkaline cells. Unlike the Fluke units, which let you recharge the NiCd cells inside the scope, with the Leader unit you must remove the cells to recharge them. Although having to use an external charger may seem like a disadvantage, it does let you match the charger to the type of cells you are using. In the case of Leader, though, this flexibility means that the scope vendor doesn't supply chargers, nor did it indicate charger prices. Leader did emphasize, however, that chargers are readily available and multiply sourced. Because charging times depend on both the batteries and the charger, leader did not provide information on charging times.

Obviously, external chargers vary in price. The $\$ 200$ price of the charger for the Tektronix 220 series scopes includes-besides a charger that can charge two batteries at once-a spare battery, a viewing hood, an extra ac adapter, and an automobile cigarette-lighter adapter.

## A battery of battery prices, too

The price of the batteries varies from $\$ 40$ to $\$ 250$, although the cost of nonrechargeable batteries-if your scope can use them-is considerably less. The Gould 465 's battery is a special case. Its $\$ 250$ price
includes the factory's labor. The battery, which is sealed within a unit that includes the charger, is not replaceable in the field. You must return the entire unit, and perhaps the scope, to the factory for a replacement. Gould says that an EE with a soldering iron and a screwdriver should have no trouble installing the battery unit on a scope not originally equipped with it. The unit, which attaches to the bottom of the scope case, is no harder to remove than to install. Hence if the battery fails, you probably won't have to go without the scope while the factory replaces the battery.
All of the scopes operate from ac as well as from batteries. In some cases, ac operation requires an external unit, such as a transformer that plugs into a wall outlet. In Table 1, the row "Supply needed for ac?" tells whether an external unit is needed. The next row, "Supply price" shows the cost of the supply.

The row marked "fastest recharge time" presents the times required to recharge the units' batteries to full charge from a state of discharge that causes the unit to shut down. These times apply with the scope not in use. With the scope in use, recharging times sunder otherwise similar conditions are generally longer and appear on the row labeled "Charging time (scope on)."

## LIS TEN.

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# Coupling DRAM and bus technology yields $500-\mathrm{MHz}$ burst transfers 

The dynamic RAM (DRAM) bottleneck in high-performance computer systems may become a thing of the past if Rambus Inc's RAMbus interface and DRAM design gains acceptance. The interface uses a 9-bit synchronous-data link between processor and DRAM memory, achieving burst data-transfer rates as great as $500 \mathrm{Mbytes} / \mathrm{sec}$.

Physically, the interface is straightforward. It has 28 wires, of which 15 are active, 8 are ground, and 5 are power. The 15 active lines include 9 data bits, bus control and enable signals, $250-\mathrm{MHz}$ transmit and receive clocks, and a voltage reference. Data transfers occur at both edges of the clock signals.

Data transfer along the interface begins with the generation of a request packet by the CPU or bus master. The packet is 6 characters long and contains a transaction code, a 36 -bit memory address, and an 8 -bit block length. The buscontrol line serves as a start bit, signaling the other devices on the bus that a request has begun.

All memory devices on the bus monitor the bus control and data lines, but respond only if the request falls within their address space. The addressed device must respond within 36 nsec either with an acknowledge code, indicating that it can handle the request, or with a negative-acknowledge code, if it cannot handle the request. If the response is negative, the bus master will re-issue the request until it receives an acknowledge.

The timing differs for read and write data transfers. When reading, the bus master will begin receiving data 36 nsec after the request packet ends. When writing, the bus master can begin supplying data 4
nsec after the request packet ends. During a write transfer, therefore, the memory's response arrives after data transfer has begun. If the response is negative, the bus master simply aborts the transfer and reissues the request.
To be able to transfer data on both edges of the $250-\mathrm{MHz}$ clocks, the interface must have carefully controlled electrical characteristics. The interface uses a variety of techniques so that you don't have to work too hard to use RAMbusbased devices.
To begin with, the interface's mechanical details are completely defined, including specifications for circuit-board trace widths and lengths and component layout. The interface's capacity is limited to 32 memory devices. RAMbus-based devices must connect in a straight line, with the bus master at one end of the circuit.
To minimize clock-to-data skew,
the $250-\mathrm{MHz}$ receive clock enters the circuit at the end away from the bus master so that
 it propagates toward the bus master alongside the data that it clocks. The transmit clock is simply the receive clock looped back at the bus master, so that the master's data and the transmit clock propagate together to the memory devices.

To achieve the $500-\mathrm{MHz}$ data clocking rate with currently available DRAM technology, the interface's output signal swing is restricted. Signals on the interface swing $\pm 300 \mathrm{mV}$ about a nominal 2 V reference voltage. That reference voltage is included in the interface's 15 active signals so that all devices on the bus work from the same standard.

A memory subsystem built on the RAMbus interface possesses a num-


By utilizing small signal swings and by having the clocks and data signals propagate together, the RAMbus interface achieves burst transfer rates of 500 MHz . The RAMbus DRAMs use their sense amplifiers to provide two $\mathbf{l k} \times 9$-bit internal caches.

## New IEEE 488.2 Control for Microsoft Windows



IOtech's Personal488/WIN includes a DLL driver with C and Visual Basic support

IOtech's new Personal488/WIN includes a DLL (dynamic link library) that enables IEEE 488.2 control from Microsoft Windows applications. Personal488/WIN includes either IOtech's 8 - or 16-bit IEEE 488.2 interface boards for PC, AT, and EISA bus computers. It features easy-touse HP style commands for IEEE 488 control and is compatible with an array of Windows development languages, from Visual Basic to MicrosoftC, QuickC,Turbo C , and Borland $\mathrm{C}++$.

## Multitasking Bus Arbitration

Microsoft Windows allows multiple test applications toconcurrently access the same IEEE 488 instrument network. Unlike other Windows drivers, Personal488/WIN automatically arbitrates among applications, letting users run multiple applications concurrently without fear of data loss.

## SRQ and Error Handling in C

Personal488/WIN conforms to Windows standard event-handling system, passing IEEE 488 events such as bus errors and instrument interrupts to Windows as standard messages, thus ensuring consistent handling of IEEE 488 and user-interface events.

## Interactive C Code Generation

 Personal488/WIN includes a Windows application for interactive IEEE 488 instrument control and $C$ code generation. Users can employ this application's menus and dialog boxes to select, configure, and execute IEEE 488 applications interactively, and then directly paste the generated code into their source code.
## Visual Basic Custom Control

Personal488/WIN adds an IEEE 488 event tool to Visual Basic's GUI (graphical user interface) development tool palette. Use of this tool to insert an IEEE 488 event object into an application allows Visual Basic to automatically create procedures for servicing IEEE 488 events such as bus errors and instrument interrupts.

## Pricing

Personal488/WIN, which includes an 8-bit IEEE 488.2 interface, is $\$ 395$; Personal488AT/WIN, which includes a 16-bit, 1 Mbyte/s IEEE 488.2 interface, is $\$ 495$. For more information, call IOtech at (216) 439-4091 or fax your request to (216) 439-4093.
ber of unique characteristics. For one, the DRAMs have the same pinout and behavior regardless of their size, so you don't need to change your circuit board in order to upgrade to higher-density devices as they become available.

Another characteristic of the subsystem is the caching nature of the RAMbus DRAMs. When accessed, the RAMbus DRAM uses part of the address to activate one 1-kword . row of its internal array and caches the data in its sense amplifiers. You can cache two rows simultaneously. The remainder of the address selects which words get transferred over the serial data link. The first access to a row takes between 160 and 210 nsec. If the new access uses the same row, a read hit, the RAMbus DRAM can begin sending data within 36 nsec of the request.

When not being accessed, the RAMbus DRAM retains its cached data. A memory subsystem composed of several devices, then, has multiple independent caches active. The larger your memory array becomes, the more cache lines you have active and the greater the chance for a read hit.

The company does not produce ICs itself. Instead, it licenses its technology and provides design support to semiconductor vendors and ASIC foundries. The company already has several licensees, including Fujitsu, Toshiba, and NEC. Initial products from these companies, to be released this year, will include $512 \mathrm{k} \times 9$-bit RAMbus DRAMs and an ASIC that connects the RAMbus to a conventional $\mu \mathrm{P}$.-Richard A Quinnell

Rambus Inc, 2465 Latham St, Mountain View, CA 94040. Phone (415) 903-3800. FAX (415) 9651528.

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[^7]
# Modular unit combines functions of pulse and word generators 

When selecting signal sources to stimulate digital systems or ICs-to verify system design or to perform production tests-EEs have had to choose between word and pulse generators. Word generators (data generators) provide wide data from many channels, each backed with pattern memory. However, most such generators allow little, if any, control over parameters such as edge placement, transition times, and pulse width. For precise control of signal characteristics, EEs have preferred pulse generators. But most pulse generators have few channels and, at best, offer limited pattern memory. Not only do Tektronix's HFS 9000 -series modular Data Time Generators eliminate the need to choose, but they also cost less and are easier to use than a set of separate word and pulse generators.

A $\$ 28,4958$-channel configuration of the Data Time Generator replaces a collection of word and pulse generators that cost three times as much and occupy many times the 7 in. of rack space used by the small Data Time Generator setup. According to the generator's manufacturer, this comparison doesn't involve choosing a particularly costly group of older instruments, and it doesn't reveal the dramatic reduction in setup time the new generators make possible (minutes vs days).

The user interface, based on a touch-sensitive monochrome CRT that displays timing diagrams and menus, is only part of the reason for the rapid setup. The major reason is a new architecture: The generators are not merely an amalgamation of classical word and pulse generators. Tektronix has replaced
nearly all of the analog functions of a pulse generator with the digital equivalents. Eliminating the analog circuits reduces interactions among controls. For example, there is no baseline shift when a pulse approaches $100 \%$ duty cycle. Among the benefits of the new architecture is the generator's ability to precisely and repeatedly simulate metastable states, which is a difficult feat for most pulse generators.
The Data Time Generators produce signals at rates to $630 \mathrm{Mbits} /$ sec/channel. Behind each channel is 64 kbits of pattern memory. You specify the data format, for example NRZ (non-return-to-zero), on a perchannel basis. Similarly, you specify the placement of pulse edges within a clock period on a per-channel basis, and you can specify pulses wider than one clock period. The edge-position resolution, a minus-
cule 5 psec, allows precise deskewing of the multiple-channel outputs without resorting to techniques such as precise matching of cables' electrical lengths.
The modular system includes two generator units. An $\$ 11,0004$ channel plug-in offers fixed rise and fall times of less than 250 psec. A $\$ 7900$ 4-channel plug-in provides transition times that you can vary from 800 psec to 6 nsec. Tektronix offers two mainframes: a 3 -slot (12channel) unit that costs $\$ 12,695$, and a 9 -slot (36-channel) unit priced at $\$ 19,995$. By using several mainframes, you can put together larger configurations having 640 or more channels. Delivery is 8 to 12 weeks, ARO.-Dan Strassberg
Tektronix Inc, Box 1520, Pittsfield, MA 01202. Phone (800) 426-2200.

Circle No. 733


You can contigure a combination word and pulse-generator from HFS 9000 -series modules. Unlike systems built from classic word and pulse generators, which often provide full pulse-parameter control on only a few channels, these new instruments provide full parametric control-including 5 -psec-resolution edge placement-on all channels.

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Master／slave D－flip／flop prevents oscillation and resolves signals as low as 3 mV

Incomparable ECL Comparators For Your Application！

| $\begin{aligned} & \text { NEW } \\ & \text { NEW } \end{aligned}$ | Device | Description | Comparators per Pkg． | Prop Delay （ns） | No Dispersion＊ | 3 mV Resolution | Input Range Includes Neg．Rail |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | MAX905 | Edge－triggered master／slave architecture | 1 | 2.0 | $\checkmark$ | $\checkmark$ | $\checkmark$ |
|  | MAX906 | Dual MAX905 | 2 | 2.0 | $\checkmark$ | $\checkmark$ | $\checkmark$ |
|  | MAX9685 | Higher－speed Industry Standard ${ }^{\dagger}$ | 1 | 1.3 |  |  |  |
|  | MAX9687 | Dual Higher－speed Industry Standard ${ }^{\dagger}$ | 2 | 1.4 |  |  |  |
|  | MAX9690 | Available in 8 －pin DIP／SO | 1 | 1.3 |  |  |  |



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## ノルスNI

[^8]
## \$20,980 DSO takes 2 Gsamples/sec on four channels simultaneously

With recent introductions from several vendors, digital storage oscilloscopes (DSOs) that sample transient phenomena in real time have gotten faster than ever. Now they have also become more affordable. Tektronix's TDS 640 has four channels, takes 2 Gsamples/sec/channel, and costs $\$ 20,980$ with four active probes. Although another recently announced scope, the HP 54720A ( $E D N$, March 2, 1992, pg 114), takes 4 Gsamples/sec/channel, it does so only when you configure it with two channels. When configured with four channels-like the TDS 460-it also takes 2 Gsamples/ sec/channel. With four probes, the HP unit's price exceeds $\$ 50,000$.

The TDS 640's display is high-resolution monochrome; the 54720 A's is color. The 54720A has a plug-in architecture, a waveform memory exceeding 30 ksamples, and a built-in disk drive; the TDS 640 doesn't include a disk drive, stores 2 ksamples/channel, and comes in a fixed 4-channel configuration. (A 2-channel version, the TDS 620, costs $\$ 13,540$ with two probes.) Both the TDS 620 and TDS 640 have a $0.5-\mathrm{GHz}$ bandwidth for transient and repetitive phenomena. They do not use techniques to enhance their effective sampling rate when they acquire high-speed repetitive waveforms; the HP scope does use such techniques, and its repetitive-signal bandwidth is 1.5 GHz .

Only you can decide whether, for your application, the difference in features justifies the 54720A's higher price. Of course, if you require single-shot bandwidth of "only" $250-\mathrm{MHz}$ (with simultaneous 1 Gsåmple/sec real-time acquisition


A clever user interface and advanced triggering features characterize two new series within Tektronix's TDS family. The TDS 620 and 640 (left) take 2 Gsamples/sec in real time on each of two or four channels, respectively. The TDS 820 (right) is a 2-channel sequential-sampling digital scope with $6-\mathrm{GHz}$ bandwidth and the ability to display pretrigger data ( $8-\mathrm{GHz}$ bandwidth optional).
on four channels), you can find at least one other DSO at a price somewhat lower than that of the TDS 640. (Both the TDS 620 and 640 offer the option of deleting the active probes to reduce their prices by $\$ 495$ per channel in applications that don't require probes.)

Tektronix has also introduced the TDS 820, a 2 -channel sequentialsampling digital scope that has 6GHz repetitive-signal bandwidth (8 GHz optional) and 14 -bit resolution. Sampling scopes, several of which offer bandwidths in the tens of gigahertz, have acquired a reputation as finicky beasts-ones you use only if you really need their exceptional bandwidth. The vendor's intent with the TDS 820 is to provide very high bandwidth and very high sensitivity ( $2 \mathrm{mV} / \mathrm{div} \mathrm{max} ; 1 \mathrm{mV} / \mathrm{div}$ in the $8-\mathrm{GHz}$ version) in an attractively priced, easy-to-use scope. Like all members of the TDS series,
the 820 offers a menu-driven interface based on both words and icons and extremely flexible triggering.

A TDS 820 feature that is unusual in sequential-sampling scopes is a delay line (not available in the 8 GHz -bandwidth version) that lets you view pretrigger information. Most sequential-sampling scopes can't display pretrigger information. In scopes that offer equiva-lent-time sampling, pretrigger displays are normally found only in units that use random repetitive sampling, a technique that doesn't provide the bandwidth of sequential sampling.

The TDS 820 's price is $\$ 19,100$; delivery is eight weeks ARO. Delivery for the TDS 620 and TDS 640 is six weeks ARO.-Dan Strassberg

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## MAXIノU

[^9]
# Streaming-data protocol extends IEEE-488 standard to 5 Mbytes/sec 

Over the past 15 years, the IEEE488 communications protocol has become a true standard in instrumentation. Except for handheld, battery-powered units, a majority of modern instruments offer an IEEE-488 port-at least as an option. But the protocol has become a bit long in the tooth; it isn't very efficient for instruments that send or receive large blocks of data. Without obsoleting existing instruments, Capital Equipment Corp (CEC) has developed an extension to the standard, called 488 SD , where SD stands for "streaming data." (Note that the IEEE has not yet made this extended protocol a standard.)

Hardware support for 488SD exists only in CEC's $\$ 495$ 488EX IEEE-488 interface board and in a similar board from Keithley Metrabyte (Taunton, MA). These boards, designed for the 16 -bit ISA bus, also work in half-length and 8 -bit slots. CEC is betting that vendors of instruments that require or produce large blocks of data, such as arbitrary-waveform generators and digitizers, will want to speed up their products' operation by implementing this protocol.

The 488 SD standard actually transcends IEEE-488. One of the goals of the VXIbus modular-instrumentation standard is to achieve much faster data transfer than is possible using IEEE-488. So far, though, most users of VXI have not been able to realize that goal. Using VXI's register-based and shared-memory protocols requires tackling software issues that few users have dealt with. The alterna-tive-treating VXI as if it were IEEE-488, that is, using VXI's message-based (word-serial) proto-
col-is the approach most VXI users take. Because it's compatible with VXI, 488SD could enable VXI systems to achieve their speed potential without incurring major software hassles.
Moreover, the popular method of building systems that combine VXI and IEEE-488 instruments is to make a VXI mainframe an IEEE488 device. In such mixed systems, the streaming protocol promises faster communication with cages full of VXI modules.
Equally important is the protocol's potential to head off "destandardization" in rack-and-stack instrumentation. Because of IEEE488's throughput limitations, some vendors of instruments that require
high transfer rates offer alternative interfaces such as SCSI ports. Clearly, though, staying with a single interface for communication between computers and instruments contains system-hardware costs and simplifies software.

When an interface that supports the SD protocol tries to initiate a streaming interchange with an instrument that lacks SD support, an instrument that conforms to IEEE488.2 will tell the interface that it doesn't support the transaction. This function even occurs with older instruments designed before this protocol existed.

You can expect that instruments offering 488 SD support will continue to allow word-at-a-time trans-


Under the existing standard, (a), when a listener makes NRFD (not ready for data) false, a talker can send one byte. The listener then makes NDAC (not data accepted) false. Each time NRFD or NDAC becomes false, you must wait for the driver circuit to charge the bus capacitance. Under the streaming-data protocol, (b), after NRFD becomes false, a talker can send an unlimited number of bytes. In some circumstances, the result is a 5 -fold speed increase over the best IEEE-488 data-transfer rates currently possible. (Note: DAV = data valid.)

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fers. Thus there won't be compatibility problems between newer instruments and older interfaces, although achieving streaming speeds requires support by both instruments and interfaces.

The protocol's simplicity ensures freedom from constraints on the depth of a device's memory. At any time during a streaming transfer, a device can stop the transfer by asserting the NRFD (not ready for data) signal. If your test system contains a device whose output needs checking at some minimum rate, you need not worry about streaming transfers that cause you to miss critical data. You can set up the system's software to limit the duration of the streaming transfers, allowing you to check the critical device.

The best throughput will occur if you don't interrupt streaming transfers. CEC claims that with a 1m-long cable, you can achieve transfer rates of 5 Mbytes/sec, which is $5 \times$ greater than the best performance claimed by other vendors for standard IEEE-488. With a cable 10 m long, the transfer rate is 2.5 Mbytes/sec.

An indexed manual describing 488 SD-with state and timing diagrams and signal definitions-is free of charge. CEC will update this manual as the protocol evolves. The 488 EX board includes a universal software driver for languages that support file I/O, a software analyzer that detects and suggests corrections to programming errors, a library of sample programs, and a programming and applications manual.-Dan Strassberg

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## EDN-PROCESSOR UPDATE

## 24-bit DSP processor runs at 40 MHz

DSP processor clock rates are climbing. Motorola's 56002 is the second generation of the 24 -bit, fixed-point 56001 . The 56002 runs to 40 MHz , whereas the 56001 topped out at 33 MHz ; this speed increase yields an improved performance of more than $20 \%$. The 56002 peaks at 20 MIPS and 120 million operations/sec: it performs a MAC (24-bit add and multiply, result to 56 -bit accumulator) with X and Y data transfers.

The $56001 / 2$ is the only 24 -bit, fixed-point DSP processor currently available. It provides higher accuracy and performance than basic 16 -bit DSPs, without the larger memory of a 32-bit fixed- or float-ing-point DSP.

The 56002 incorporates the 56001 's core and peripherals. However, the 56002 uses Motorola's uni-versal-design-rule technology, which enables designs to move from process to process easily. The current implementation is on $1.0-\mu \mathrm{m}$ CMOS but eventually will be moved to $0.8-\mu \mathrm{m}$ CMOS. The design is

fully static with clocks to dc frequencies. The PLL is programmable with a clock multiple to 4096 .
Motorola added on-chip-emulation features of the 32 -bit 96002 to the 24 -bit DSP. Using on-chip emulation, designers can debug their application code, controlling the DSP processor via a 6 -wire serial interface. Thus, engineers can opt to start and stop the processor, set breakpoints, and monitor and change memory and register values. Breakpoints trigger on program or data access, either ad-
dresses or address ranges. On-chipemulation features include a breakpoint or pass counter to trigger a breakpoint on the $n$th compare iteration; the features also furnish a trace counter, specifying the number of instructions to be executed for each trace step.-Ray Weiss

Motorola Inc, Microprocessor and Memory Technologies Group, 6501 William Cannon Dr W, Austin, TX 78735. Phone (512) 891 2000. FAX (512) 891-2652.

Circle No. 713

## Chip links DAT devices and DSP $\mu$ Ps

Digital audio brings the ease and interchangeability of today's plug-in audio jacks. Motorola's single-chip digital audio chip, the DSP56401, links DAT (digital audio tape) devices to DSP processors. The chip acts as a transceiver to multiple digital-audio devices, linking them directly to DSP56001/2 DSP processors.
The device meets the AES/EBU and EIAJ CP-340 digital-audio standards. It takes in unidirec-
tional, self-clocked, stereo digitalaudio formats in a single serial channel. It acts as a DAT transmitter and receiver and contains a transmit serial interface, transmit demodulator, receive demodulator and a receive serial interface with a common clock generator. The transmit and receive serial interfaces can be clocked independently if needed. The hardware implements preamble detection and synchronization, parity and CRC checks, and block and frame synchronization.

A phase-locked loop (PLL) detects and recovers the bit clock from the modulated serial input. For


With this single-chip digital-audio transmitter/receiver, you can link DAT devices to DSP processors, ADCs, and DACs.

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| $\begin{aligned} & 2 \times 4.5 \times 9^{\prime \prime} \\ & 2 \times 4.5 \times 9^{\prime \prime} \end{aligned}$ | $\begin{aligned} & 250 \mathrm{~W} \\ & 250 \mathrm{~W} \end{aligned}$ | $5 \mathrm{~V} / 30 \mathrm{~A}$ <br> $5 \mathrm{~V} / 30 \mathrm{~A}$ | $\begin{aligned} & 12-15 \mathrm{~V} / 10 \mathrm{~A} \\ & 12-15 \mathrm{~V} / 10 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 12-24 \mathrm{~V} / 2 \mathrm{~A} \\ & 12-15 \mathrm{~V} / 3 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 2-6 \mathrm{~V} / 3 \mathrm{~A} \\ & 5-15 \mathrm{~V} / 3 \mathrm{~A} \end{aligned}$ |  |
| $\begin{aligned} & 2.5 \times 5 \times 10^{\prime \prime} \\ & 2.5 \times 5 \times 10^{\prime \prime} \\ & 2.5 \times 5 \times 11^{\prime \prime} \\ & 2.5 \times 5 \times 11^{\prime \prime} \end{aligned}$ | 400W <br> 400W <br> 400W <br> 400W | $5 \mathrm{~V} / 50 \mathrm{~A}$ <br> 5V/50A <br> 2-6V/60A <br> $5-15 \mathrm{~V} / 24 \mathrm{~A}$ | $\begin{gathered} 12-15 \mathrm{~V} / 15 \mathrm{~A} \\ 12-15 \mathrm{~V} / 15 \mathrm{~A} \\ 5-15 \mathrm{~V} / 12 \mathrm{~A} \\ 5-15 \mathrm{~V} / 12 \mathrm{~A} \end{gathered}$ | $\begin{gathered} 12-24 \mathrm{~V} / 3.5 \mathrm{~A} \\ 12-24 \mathrm{~V} / 3.5 \mathrm{~A} \\ 5-15 \mathrm{~V} / 12 \mathrm{~A} \\ 5-15 \mathrm{~V} / 12 \mathrm{~A} \end{gathered}$ | $\begin{aligned} & 5-15 \mathrm{~V} / 6 \mathrm{~A} \\ & 2-6 \mathrm{~V} / 6 \mathrm{~A} \\ & 2-6 \mathrm{~V} / 12 \mathrm{~A} \\ & 2-6 \mathrm{~V} / 12 \mathrm{~A} \end{aligned}$ |  |
| $\begin{aligned} & 2.5 \times 5 \times 11.5^{\prime \prime} \\ & 2.5 \times 5 \times 11.5^{\prime \prime} \end{aligned}$ | 500W <br> 500W | 5V/70A 5V/70A | $\begin{aligned} & 12-15 V / 15 A \\ & 12-15 V / 15 A \end{aligned}$ | $\begin{aligned} & 12-24 \mathrm{~V} / 3.5 \mathrm{~A} \\ & 12-24 \mathrm{~V} / 3.5 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 5-15 \mathrm{~V} / 6 \mathrm{~A} \\ & 2-6 \mathrm{~V} / 6 \mathrm{~A} \end{aligned}$ |  |
| $\begin{aligned} & 3 \times 5 \times 14.25^{\prime \prime} \\ & 3 \times 5 \times 14.25^{\prime \prime} \end{aligned}$ | $\begin{aligned} & 600 \mathrm{~W} \\ & 600 \mathrm{~W} \end{aligned}$ | 5V/80A <br> 5V/100A | $5-24 \mathrm{~V} / 10 \mathrm{~A}$ $5-24 \mathrm{~V} / 10 \mathrm{~A}$ | $\begin{aligned} & 5-24 V / 10 A \\ & 5-24 V / 5 A \end{aligned}$ | $\begin{aligned} & 5-24 V / 5 A \\ & 5-24 V / 5 A \end{aligned}$ | 5-24V/5A |
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transmission, a modulator state machine generates the preambles, parity, and CRC data incorporated in the transmitted frame with audio and nonaudio data. DAT transmission uses the LSB-first, biphasemark Manchester decoding for transmission and receive. Multiple DAT devices interface to a single DSP56401. Combined with the DSP56001/2, it provides two chips for processing DAT applications.

In addition, the chip interfaces directly to Motorola D/A and A/D converters. The chip includes four oscillators and a jitter clock recovery system.
The DSP56401 comes in a 64 -pin
plastic quad flatpack and costs $\$ 25$ (sample qty). An evaluation board is available from Spectrum Signal Processing Inc (Burnaby, BC, Canada). This $5 \times 5.75$-in., 4-layer board includes DAT input/output ports as well as ports to the DSP56001/2 and to audio converters such as those made by Burr-Brown. Audio connectors for AES/EBU optical lines, balanced-line XLR connectors, and unbalanced RCA connectors are also available.-Ray Weiss

Motorola Inc, Microprocessor and Memory Technologies Group, 6501 William Cannon Dr W, Austin, TX 78735. Phone (512) 8912000.

Circle No. 714

## 80C51 family hits 33-MHz clock rates

Memory costs-especially for high speed parts-are a major limiting factor for embedded systems. Signetics has raised 8051 clock rates to an unprecedented 33 MHz and held down memory access time, keeping memory costs down as well. Other 8051 vendors such as Matra MHS and Siemens are supplying $30-\mathrm{MHz}$ parts.
Two 80C51 family members, the 80 C 51 and 80 C 52 , run at rates to 33 MHz but require only a $90-\mathrm{nsec}$ memory access time for external memory. As designers moved clock rates out, they recharacterized the parts, reducing interface requirements and gradually improving process upgrades.
The 8051 architecture is designed for both single-chip and externalmemory applications. An 8051 supports a single 64 -kbyte external address space or two 64 -kbyte address spaces: one for instructions and one for data. External references are slower than referencing internal RAM; they must go through the accumulator and take extra cycles. The 80C51 and 80C52 differ in their amounts of scratchpad RAM and on-chip ROM: The 80C52 doubles

80C51 RAM and ROM to 256 bytes of RAM and 8 kbytes of ROM.

An 8051 takes 12 external clocks ( 6 internal clocks) for an instruction cycle, which includes an instruction and a potential data fetch. At 33 MHz , a base instruction takes 360 nsec. The instruction access time for external memory is specified at 90 nsec , which under previous specs would have been 60 nsec .

Recharacterized 80C51 timing results in memory access times that are lower across the entire line: a $24-\mathrm{MHz} 8 \mathrm{xC} 51$ now uses a $120-\mathrm{nsec}$ memory, compared with 90 nsec previously required.-Ray Weiss

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[^11]1757 Dhrystones/s is 1 MIPS (VAX ${ }^{\text {w }} 11 / 780$ ). MIPS performance is based on the Diab 2.36E compiler.


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# Third-generation R•I•S•C processors 

Ray Weiss, Technical Editor

Third-generation RISC processors are moving into the technical world spurred by rising chip densities and higher clock rates. RISC (reduced-instruction-set computer) microprocessors delivering 50 to 100 VAX MIPS are here now; others will be available within the next six months.

First-generation RISC processors-the IBM 801, the Berkeley SPARC, and the Stanford MIPSwere research projects that laid the groundwork for the second generation. Second-generation RISC processors operate at 25 to 60 VAX MIPS. They have a single instruction pipeline, which lets them execute multiple instruction in sequence at one time. These processors issue one instruction per cycle but complete one instruction every 1.2 to 1.6 clock cycles. The problems that prevent these chips from completing the ideal of one instruction every cycle include data dependencies, register conflicts, instruc-tion- and data-cache misses, and the occurrence of branch instructions.

Two design techniques are enabling thirdgeneration RISC chips to crash through the performance barriers of the second generation. Superpipelining is the treating of pipeline stages as miniature pipelines. Thus, the stages can

> Mainframe and supercomputer design techniques are pushing the performance of third-generation RISC processors to 70 VAX MIPS and beyond. These processors issue as many as three instructions per clock cycle and have clock rates ranging from 50 to 200 MHz .
start executing a second instruction before finishing the first, which speeds the performance of the processor as a whole. Superscalar RISC processors have two or more instruction pipelines running in parallel, which quickly increases instruction throughput.

However, superpipelined and superscalar architectures have their own set of problems. For example, the branch-related problem of secondgeneration chips are even worse for the third generation. And, third-generation chips require more-complex control logic and wider instruction bandwidths. The superpipelined and superscalar architectures came from the world of mainframe and supercomputer designers, as do two techniques for easing third-generation chip problems: register scoreboarding and register renaming.
Every major RISC chip design is moving to either superpipelining or superscalar implementations to break out of the performance limitations of second-generation RISC processors. The Mips Computer Systems R4000, Sun SPARC, Motorola 88110, Intergraph Clipper, IBM RS/6000, Intel i960 and i860, National Semiconductor 32SF641, SGS-Thomson T9000


## THIRD-GENERATION RISC PROCESSORS

Transputer, and Digital Equipment Corp Alpha are all part of this nextgeneration of processing power.
RISC processors are pipelined so multiple instructions can execute in sequence at one time. A pipeline is a series of stages; each stage performs one of the micro-operations that make up an instruction. These micro-operations include instruction fetch, instruction decode, operand fetch, operation execution, and result writeback. The ideal is to have a balanced pipeline in which all stages take the same number of clock cycles to execute. Pipelining isn't new; IBM introduced the technique in its 7030 Stretch computer in 1960.

With careful hardware design, a pipeline that has $n$ stages can concurrently execute $n$ sequential instructions: fetching the next instruction in the first stage, decoding the current instruction in the second stage, fetching the operands for the previous instruction in the third stage. . . A new instruction starts at each pipeline cycle, but the instruction latency (the time for an instruction to finish) would be $n$ cycles.

The maximum instruction throughput of an ideal pipelined RISC chip would be 1 CPI (cycles per instruction). At each clock cycle, the CPU would issue a new instruction and finish a previous instruction. In practice, second-generation RISC processors deliver throughputs of 1.2 to 1.6 CPI .

## Hang-ups and hurdles

Rocks and shoals limit RISCprocessor performance. Data dependencies and resource conflicts can cause processing to stall or hang up. For example, a load instruction whose value is used by the following instruction can trigger an interlock. The second operation stalls until the data is available in the pipeline. Similarly, data dependencies-the result of one instruction being used by a following one-can cause a delay until the result is passed to the pipeline stage where it's needed.
Branches can cause worse problems, and most code has a lot of branches. In fact, branches often average as many as one every four to six instructions. The problem with pipelines and branches is selfevident: On each cycle the pipeline

Intel i960CA

- 16-, 25-, 33-, 40-MHz clock
instruction/fetch, integer, and address generation; no FPU
- 575,000 transistors
- 30 SPECmarks
- Superscalar, issues as many as 3 instructions per clock cycle
- 6 -port $32 \times 32$-bit register file, $128 / 64$ bit paths
- 1-kbyte 2 -way set-associative instruction cache with 128 -bit line size; 1.5 kbyte data/register-set cache
- 32-bit pipelined external memory interface; multiple memory regions, burst mode
- 3 -stage pipeline, 2 stages for branches
- Four functional units: multiply/divide,
- Branch-prediction bit; out-of-order branch execution; speculative postbranch execution
- Pipelined store, 3 -entry buffer
- Register scoreboard in scheduler
- $16-\mathrm{MHz}$ version, $\$ 69.90 ; 33-\mathrm{MHz}$ version, \$107.65 (25000)

Comments: First commercial embedded RISC $\mu P$. Family targets embedded systems and data-handling chores. Military part has FPU, MMU, and 2 -kbyte instruction and data caches.

PIPELINE

fetches a new instruction, but which instruction should it pick following a conditional branch? The logic executing a branch instruction may not know which is the next instruction address for one or more stages. And if the logic chooses the wrong path, it will have to flush the pipeline to remove intermediate results.

Another hurdle for RISC chips to overcome is load and store delays. RISC architectures tend to limit memory accesses to load and store instructions. The CPU manipulates data in loaded registers. Some RISC processors, however, do have complex instructions: IBM's RS/ 6000 features multiple loads or stores.

Loads cause delays of as many as three cycles in second-generation RISC processors. If an instruction following a load uses the loaded value, it stalls until that value is available to the pipeline. In some third-generation RISC chips, such as the Mips R4000, an instruction can't use a loaded value until the third or fourth pipeline stage. DEC's Alpha chip, for example, has a 3-cycle delay for loads.

Store instructions can also cause significant delays, especially if they need a new cache entry or write to memory. Many third-generation RISC chips buffer stores to decouple memory accesses from the CPU pipeline, thus minimizing stalls. Another way to lessen store delays is to forward the buffered store data to downstream loads so the loads won't stall while waiting for the data.

## Pushing the clock

Probably the most obvious way to increase performance is to increase the base CPU clock rate, which is what RISC chip vendors have been doing. Second-generation RISC processor clock rates have peaked at 40 to 50 MHz .

Simply pushing up the clock rates has the advantage of minimizing mi-
cro-architectural changes you'd otherwise have to make to get higher speeds. However, as internal clock rates go up, the nicely balanced, fixed-stage RISC pipeline
often starts to crumble. Designers can easily speed up and even double the rate of some stages; the rates of others, such as caches, can't be increased.

One way around the speed-up difficulty is to pipeline the individual pipeline stages. Thus, a pipelined stage, such as a cache or a multiplier, could accept a new instruction

Mips Computer Systems R4000SC

- $100-\mathrm{MHz}$ internal clock ( $50-\mathrm{MHz}$ external) 1.1 M transistors 70 SPECmarks Superpipelined architecture 64-bit architecture; 36-bit physical address space
- $32 \times 64$-bit integer registers, $16 \times 64$-bit floating-point registers
- Two direct-mapped 8 -kbyte caches, 64 -bit fetch, 16 - or 32 -byte line size
- PC version has 64-bit multiplexed, address/data bus; SC version has 128 -bit data bus.

S Supports 128 -kbyte to 4 -Mbyte directmapped secondary cache

- Eight pipeline stages
- 3-cycle branch delay
- 2-cycle load delay
- 2-entry ( 64 bits each) store buffer
- Chip vendors are sampling (see manufacturers' box); prices vary from \$615 to $\$ 1300$, depending on version, quantity, and vendor.

Comments: Three chip versions: the low-end PC (179 pins); the SC, which supports secondary cache; and the MC, an SC that can do multiprocessing. The ISA architecture was designed by Mips; six chip vendors have signed up to produce the R4000, which is one of the ACE (Advanced Computing Environment) consortium CPUs.

| $\begin{aligned} & \text { INSTRUCTION } \\ & \text { FETCH } \end{aligned}$ | $\begin{aligned} & \hline \text { INSTRUCTION } \\ & \text { ISSUE } \\ & \hline \end{aligned}$ | $\begin{gathered} \hline \text { REGISTER } \\ \text { FETCH } \end{gathered}$ | EXECUTE | DATA FETCH* | DATA STORE* | TAG CHECK | RESULT WRITEBACK |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | INSTRUCTION FETCH | INSTRUCTION ISSUE | REGISTER FETCH | EXECUTE | DATA FETCH* | DATA STORE* | TAG CHECK | RESULT WRITEBACK |

'ONLY FOR LOAD UR STORE INSTRUCTIONS

## RISC references

Here are five technical references to help you get up to speed on third-generation RISC microprocessor architectures:

- Microprocessor Report (triweekly newsletter, \$445/ year), 874 Gravenstein Hwy S, Suite 14, Sebastopol, CA 95472. (707) 823-4004. FAX (707) 8230504.

Edited by Michael Slater, this periodical is an excellent source for evaluating $\mu \mathrm{P}$ and $\mu \mathrm{C}$ chips. The newsletter provides in-depth analysis for new chips and architectures. The same organization also holds the annual Microprocessor Forum, which is where most companies present their major chip designs.

- Superscalar Microprocessor Design, by Mike Johnson, Prentice-Hall Inc, Englewood Cliffs, NJ, 1991, \$48. ISBN 0-13-875634-1.
This resource is the only technical book that completely addresses superscalar processor design. It provides a good, clear set of definitions and in-depth analysis of superscalar design techniques.
- Computer Architectures: A Quantative Approach, by John L Hennessy and David A Patterson, Morgan Kaufmann Publishers Inc, Palo Alto, CA, 1990, \$64.95. ISBN 1-55880-069-8.

This book is rapidly becoming the computer designer's bible. Written by RISC pioneers Hennessy and Patterson, it is a textbook, a collection of design lore, and a RISC-based design example to study. This massive book contains some 700 pages of tutorial and design techniques and is an easy read as well.

- Cache and Memory Hierarchy Design: A Performance Directed Approach, by Steven A Przybylski, Morgan Kaufmann Publishers Inc, Palo Alto, CA, 1990, \$43.95. ISBN 1-55860-136-8.
If you need the numbers to evaluate cache designs, this book is for you. It provides detailed models of cache designs that are based on actual simulation and trace data. The book breaks down memory-level design and includes models for varying cache and lines sizes, memory speed, and set size.
- IBM Journal of Research and Development, Vol 34, Number 1, January, 1990. IBM Corp, Armonk, NY.
This volume is a complete set of papers defining the IBM RS/6000 superscalar architecture. It provides a comprehensive system, hardware, and software view of superscalar design and implementations.


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each clock cycle, even if the stage had not finished executing the current instruction. This technique is called superpipelining.
Superpipelining enables RISC designers to take advantage of higher clock speeds and still keep their basic pipeline stages. However, the technique only makes sense if the designer can raise clock rates dramatically, which is not possible every year.
Mips Computer Systems used superpipelining for its R4000. The R4000's base clock is 50 MHz , but the chip actually uses a $100-\mathrm{MHz}$ internal clock. The Mips R3000's 5stage pipeline grew to eight stages for the superpipelined R4000.
Superpipelining has its own costs. Each superpipelined pipeline stage must be latched. Functional units-logic that does one or more specific function-must be partitioned to match the basic clock rate, perhaps complicating the logic. In addition, the functional units' pipelined stages need their own level of control. Most new and emerging RISC processors include pipelined functional units. Intel's i860, introduced in 1989, has pipelined float-ing-point add, multiply, and graphics units, as does the IBM RS/6000's FPU (floating-point unit).
Another way to increase processor performance is to do more than one operation at a time. Superscalar RISC processors can issue, and ideally execute, more than one scalar instruction per clock cycle. In effect, such processors run multiple pipelines in parallel.
One of the benefits of using superscalar techniques is that designers can increase performance without necessarily raising clock rates. Typically, higher clock rates open up new difficulties in interfacing the CPU to the lower memory levels, such as main memory and disk storage. These memory media do not move as rapidly up the speed curve as processor silicon. So the faster


One way to get superscalar performance-a processor's issuing more than one instruction per cycle-is to have multiple functional units executing in parallel. You can even cascade functional units, as shown by the two parallel adders feeding a third adder their results.
a CPU goes, the larger the speed gap between the CPU and the various memory levels.

Thus, increased delays in memory and store accesses for cache misses and page faults can nibble away performance increases realized from faster clocks. One reason for the increasing use of secondary caches is that these caches provide a buffer layer between the highspeed on-chip caches and the slower system memories.

Superscalar techniques let you have your cake and eat it, too: You get more instruction throughput without a need for faster caches. These gains aren't free. Processor control logic must, by necessity, become more complex, although this logic will still be a small portion of the total chip transistor count.

Also, superscalar processors need wider memory accesses than sec-ond-generation, single-pipeline RISC chips so they can pump through groups of multiple instruc-
tions for execution. A superscalar processor of degree $n$-one that issues an average of $n$ instructions per clock cycle-requires an instruction bandwidth approaching $n$ times the scalar instruction bandwidth. Superscalar operation does not as heavily affect the data bandwidth because loads and stores are $10 \%$ or less of a typical RISC instruction mix. Memory interfaces are moving to 64 bits in most processors; some superscalar RISC processors have a 256 -bit-wide memory bus.

## Evaluating the third generation

However, designing a high-performance third-generation RISC processor is more complex than just choosing between superpipelining and superscalar techniques. Implementation technology has changed the playing field. Yesteryear's world of fixed-length pipelines and stages is gone. Secondgeneration RISC ALUs and caches
were major performance bottlenecks. But third-generation fast adders and multipliers and pipelined caches are changing that state of affairs. Today, RISC adders can do a full addition in what used to be half a stage clock. For example, the Mips R4000 does a 64 -bit addition in one $50-\mathrm{MHz}$ clock cycle.
Fast adders and pipelined caches have led to a confusing state of affairs. The previous way of evaluating RISC implementations by taking the functional-unit clock rate as a base won't work anymore. Many emerging RISC chips, such as the Motorola 88110 and the TI SuperSparc, no longer have functional units that all take the same number of clock cycles. Some stages take three cycles; others complete in one. The SuperSpare, for example, has three adders, two of which can feed into the third. All adds complete in one $50-\mathrm{MHz}$ clock cycle; the individual adders operate in half a clock cycle. The IBM RS/6000, a multichip RISC implementation, has different-length pipelines to compensate for delays between

## National Semiconductor 32SF641

33-, 40-, $50-\mathrm{MHz}$ internal clock; exter nal bus half internal rate

- 1.1 M transistors
v 100 native MIPS peak, 1024 -item FFT in $1.5 \mu \mathrm{sec}$, single-cycle integer multiply takes 20 nsec; 2-cycle floatingpoint multiply
- Superscalar architecture, dual instruction fetch, dual pipelines
6-port register file; $32 \times 32$-bit general purpose registers, $16 \times 64$-bit floatingpoint registers
4-kbyte, 2-way set-associative instruction cache, 64 -bit line size; 1 -kbyte, 2 way set-associative data cache, 128 bit line size; both are locking caches
- 64-bit external-memory interface
- Two pipelines with buses: 4-stage integer pipeline, 5 -stage integer/floatingpoint pipeline

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- Four functional units: two ALUs, DSP multiplier, FPU
- Branch-destination offset stored in cache with branch address; 2-cycle delay if wrong
- 1-cycle penalty for load that needs a store value
- Bypass register passes values between pipelines.
- Loads can bypass data cache.
- In-order execution, 1 or 2 instructions per clock cycle
- 16-bit timer, two DMA channels
$\$ 970$ with FPU, $\$ 300(1000)$ without
Comments: Chip suits embedded systems and math-intensive, DSP-type processing. 64-bit memory bus is dynamically sizable and designed for interleaved memory. C-like assembly language. Dual-processor mode for fault-tolerant operation.

| INSTRUCTION <br> FETCH | INSTRUCTION <br> DECODE | EXECUTE | MEMORY <br> ACCESS <br> FOR <br> LOAD | , STORE |
| :---: | :---: | :---: | :---: | :---: |
|  |  | RESULT |  |  |

functional units on different chips.
Thus, there's no clear dividing line between superpipelined and superscalar architectures. Super-
pipelining-the pipelining of functional units-is becoming universal. You can't evaluate the emerging third-generation RISC processors by looking at the basic clock frequency and calculating a CPI rating. The superscalar Mips R4000 delivers 70 Specmarks. In the old view, that performance would be considered good for a $50-\mathrm{MHz}$ clock but mediocre for a $100-\mathrm{MHz}$ clock. Many RISC chips always had internal clocks faster than their system clocks, but now the internal clocks are viewed as the instruction-cycle clock.

## Parallel functional units

Superscalar RISC processors are following the track pioneered by mainframe and supercomputer designers. Chip designers are dividing processor operations into separate, parallel functional units. These units can execute in parallel if there are no data dependencies or resource conflicts. CDC (Minneapolis, MN) introduced this technique in its

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6600 mainframe, which had 16 functional units including four FPUs and seven integer units.

Most RISC superscalar processors issue two to three instructions per clock cycle. Thus, they can make do with as few as two or three parallel functional units. The i960, 32SF641, T9000, and DEC Alpha chips have four functional units each. IBM's multichip RS/6000 and single-chip RCS each have three functional units.

All functional units, however, are not alike. IBM's RS/6000 and Intel's i960 have a few, sophisticated functional units, which include multistage control logic. An example of such a unit is the RS/6000's instruc-tion-cache unit, which handles branches and condition-code operations internally. It dispatches instructions to the fixed-point or floating-point functional units.

The alternative approach is to have more, less-sophisticated functional units. These units are more like the execution units that run the execute stage in a second-generation CPU pipeline. The 32SF641,

88110, and SuperSparc take this more egalitarian tack.
The 88110 has 10 functional units, including two ALUs, two graphics units, a bit-field unit, a floatingpoint add unit, a multiply unit, and a divide unit. The two remaining units-the load/store and supersca-lar-instruction units-are more control oriented. The load/store functional unit helps coordinate loads and stores. Its logic can easily check for loads that are dependent on pending stores. For example, the 88110 has a separate load/store execution unit. The 88110 also has seven spare functional-unit addresses for future expansion.

Integer ALU instructions make up the largest percentage of instructions executed by RISC processors. In some studies of the Mips architecture, ALU operations were 40 to $50 \%$ of all instructions executed. Thus, multiple ALUs provide a way to speed execution. Many third-generation RISC processors have implemented multiple ALUs, including the National Semiconductor 32SF641, which has two

## Intergraph C400

| $50-\mathrm{MHz}$ internal clock | - Compare and branch instruction takes |
| :---: | :---: |
| C411 integer unit, 160,000 transistors; C421 FPU, 140,000 transistors | 2 delay-slot cycles and has no condition codes; branch-prediction bit |
| - 42 SPECmarks | - Pipelined loads and stores |
| Superscalar architecture, issues as many as 2 instructions per clock cycle; superpipelined functional units; C411 integer unit | Register scoreboard stalls instructions until resources are available. <br> In-order execution <br> $\checkmark$ 7W chip has off-chip drivers/receivers; |
| 5-port $32 \times 32$-bit register file | multilayer PGA |
| Separate FPU chip, C421, has $16 \times 64$ bit floating-point registers | - \$1000 (1000) for C411 and C421 chip |
| External, direct-mapped unified cache as large as 128 kbytes | Comments: The C400 is the latest version of the Clipper RISC chip. Separate FPU on- |
| Separate input and output buses: 64 -bit output bus, 32 -bit address/input bus | suits mutich implementa |
| V Variable-stage pipeline: 3 to 5 stages |  |
| Four functional units: ALU, multiplier, divider, shifter | a multichip module. |

PIPELINE

| INSTRUCTION FETCH | INSTRUCTION FETCH | INSTRUCTION DECODE | INSTRUCTION DECODE | EXECUTE | RESULT WRITEBACK |
| :---: | :---: | :---: | :---: | :---: | :---: |
| INSTRUCTION-CACHE $\qquad$ ACCESS |  | REGISTER FETCH | DATA-CACHE $\qquad$ ACCESS |  | $\begin{aligned} & \text { REGISTER } \\ & \text { FETCH } \end{aligned}$ |

separate pipelines each of which has an integer ALU, and Motorola's 88110, which also has two ALUs.

Problems, however, start with data dependencies between sequential instructions; for example, an add that is followed by another add that uses the results of the first add instruction. Multiple ALUs won't help in this case: The second instruction will stall until it can use the result of the first as an input. Software scheduling can make the best use of multiple parallel ALUs by sorting instructions to minimize data dependencies. The compiler can intermix instruction sequences with partial results held in registers or cache.

The Sun/TI SuperSparc design team went even further than hanging three ALU functional units on a general bus. It created an ALU hierarchy: The first two ALUs operate independently, and the resulting outputs can feed into the third ALU. Thus, the third ALU can add the results of two adds. Moreover, all three adds can be done in a single group of simultaneously issued instructions.

## One, two, many

Legend has it that one Pacific Aborigine tribe has a limited counting system of 1,2 , and many. That system is perfect for describing superscalar CPI rates. One for the second-generation RISC limit, two for the third-generation superscalar limit, and many for future RISC processors.

It's just not that easy for a superscalar RISC chip to consistently issue multiple instructions. Dependency problems become worse than those of chips with a single pipeline because you've got more instructions to worry about at any given time. Issuing more instructions means having more-complex control logic. Techniques like register scoreboarding and register renaming help to detect and minimize data
dependencies and register conflicts.
In register scoreboarding, which was pioneered by the CDC 6600 mainframe, a table or scoreboard tracks register use. A register scoreboard has a bit for each processor register. If the bit is set, the register has a pending update (a result coming). When the register is updated, the bit is cleared, opening the register up for use. Intel's i960, Motorola's 88110, and DEC's Alpha all use register scoreboarding. The Alpha also uses scoreboarding to check for resource and load/store dependencies.
Current superscalar chips issue multiple instructions, but in objectcode order. The instructions issue in order, although they can finish out of order. The CPU checks for data dependencies before issuing the instructions. In-order execution minimizes control logic but limits instruction throughput. The hard-

## Digital Alpha

$200-\mathrm{MHz}$ internal clock 1.68 M transistors 100 SPECmarks (estimated)$\checkmark$ Superscalar architecture, issues as many as 2 instructions per clock cycle; pipelined functional units
64-bit processor

- $32 \times 64$-bit register file, $32 \times 64$-bit FPU register file
$\checkmark$ 8 -kbyte, 2-way set-associative instruction cache; 8 -kbyte data cache; 32 byte line size
$\checkmark$ Supports secondary cache
7 -stage pipeline, 10 cycles for floatingpoint operations
- Four functional units: load/store, integer, FPU, branch
- Branch/data replacement operation: can load one of two values without taking a branch



## Manufacturers of RISC processors

For more information on RISC processors such as those described in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

## Digital Equipment Corp

146 Main St
Maynard, MA 01754
(508) 493-5111

Circle No. 650

## IBM Corp

Old Orchard Rd
Armonk, NY 10504
(800) 426-3333

Circle No. 651
Intel Corp
Embedded Processor Group
5000 W Chandler Ave
Chandler, AZ 85226
(602) $554-2388$

Circle No. 652
Intergraph Corp
Advanced Processor Div 2400 Geng Rd
Palo Alto, CA 94303
(415) 494-8800

FAX (415) 856-9224
Circle No. 653

Mips Computer Systems Inc 950 DeGuigne Dr
Sunnyvale, CA 94086
(408) 720-1700

FAX (408) 991-7777

## Circle No. 654

## Motorola Inc

Microprocessor and Memory Technologies Group
6501 William Cannon Dr W
Austin, TX 78735
(512) 891-2000

FAX.(512) 891-2652
Circle No. 655

## National

Semiconductor Corp
Box 58090
Santa Clara, CA 95052
(408) $721-6816$

FAX (408) 730-6241
Circle No. 656

## SGS-Thomson

Microelectronics
1000 E Bell Rd
Phoenix, AZ 85022
(602) 867-6100

FAX (602) 867-6102
Circle No. 657

Texas Instruments Inc
Box 809066
Dallas, TX 75380
(713) 274-2379

Circle No. 658
Mips vendors:
Integrated Device
Technology
Box 58015
Santa Clara, CA 95052
(408) 727-6166

FAX (408) 988-3029
Circle No. 659

## LSI Logic Inc

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ware is stuck with the instruction parallelism inherent to the instruction stream. It cannot reorder the stream for better parallelism.

Issuing instructions out of order is certainly possible, but the technique imposes a heavy hardware complexity cost because of the number of different possible instruction combinations that could occur ( $n$ fetched instructions $\times m$ issued instructions $\times p$ pipeline stages).

Register renaming is a hardware technique to minimize conflicts for register resources. The concept was introduced in the IBM 360/91 mainframe in 1967. Compilers convert high-level languages to assembly code, and in the process assign registers to hold values. In a superscalar processor, an operation may request a register before a prior instruction is finished using that register. This condition is not a data conflict. The downstream operation doesn't need the register value, just a register, and the operation

## Motorola 88110

## - $50-\mathrm{MHz}$ clock

- 1.3 M transistors
63.7 SPECmarks ( 80 with secondary cache, both figures estimated)
- Superscalar architecture, issues as many as 2 instructions per clock cycle
- 8 -port $32 \times 64$-bit register file, $32 \times 64$ bit or $32 \times 80$-bit FPU register file
- 80 -bit internal data paths
- 8 -kbyte, 2 -way set-associative instruction cache; 8 -kbyte data cache with 64 bit fetch; 32 -byte line size
- 32-bit address, 64 -bit external interfaces; split transaction (can start new cycle while waiting for access); 8 -word burst bus, bus snooping
$\checkmark$ 88410 chip is 256 -kbyte to 1 -Mbyte secondary-cache controller
- 4 -stage pipeline, different-length stages
$\checkmark$ Ten functional units: 2 AlUs, bit field,
PIPELINE

| INSTRUCTION <br> FETCH | INSTRUCTION <br> DECODE | EXECUTE | RESULT |
| :---: | :---: | :---: | :---: |

will stall until a register is free.
The idea is to pick a free register, rename it to match the instruction

## Texas Instruments SuperSPARC

50-MHz base clock, $100-\mathrm{MHz}$ clock cycle

- 3.1 M transistors
- 75 SPECmarks (estimated)
- Issues 3 instructions per clock cycle
- 8 -port $32 \times 32$-bit register file

20-kbyte, 5 -way set-associative instruction cache; 128 -bit instruction fetch; 16 kbyte, 4 -way set-associative data cache; single 64-entry TLB (translation look-aside buffer) for both caches.

- 64-bit memory interface designed to Mbus-level II interface
- Cache-controller chip (2.2M transistors) handles as much as 2 Mbytes of directmapped secondary cache.
- 4-stage pipeline; different-length stages (2/3/2/1 clock cycles)
- Eight functional units: 3 integer AlUs, shifter, load/store, branch, floatingpoint multiply, floating-point divide

PIPELINE

INSTRUCTION INSTRUCTION 2 INSTRUCTION 3

- Branch-prediction bit, taken branches optimized; loads branch target address on instruction fetch
- Fast load from cache, can use data in same group; 8-entry store buffer; load bypass
- Speculative execution; 2 instruction buffers: 8 -word instruction prefetch, 4 word branch target prefetch; can stop and squash target instructions before writing values
- Sampling to SPARC International members

Comments: Most sophisticated, largest superscalar RISC processor to date. Joint development by Sun and TI. First superscalar SPARC chip. Both uniprocessing and multiprocessing configurations.
parameter, and let the instruction use it. A fast look-up table, usually an associative memory, translates the map or renames the register.

Register renaming is not yet in general use by most third-generation RISC processors. One reason is that third-generation processors are issuing small numbers of instructions concurrently. The SGSThomson T9000 can issue a group of as many as eight instructions, but it is a stack-oriented machine and doesn't need register renaming. IBM's RS/6000 uses register renaming in its FPU.

## Beating branches

Conventional branch-delay slots won't work well for superscalar RISC chips. A branch delay can be two cycles, but a superscalar chip that issues $n$ instructions per clock cycle must find $2 n$ instructions to plug into the empty pipeline execution slots. Using branch delays has been relatively successful for a single branch in a single-pipeline RISC chip, but the technique's effectiveness falls off rapidly as more in-

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## THIRD-GENERATION RISC PROCESSORS

structions are needed to fill empty slots.

The second-generation HewlettPackard PA chip limits branch delays by using built-in branch prediction. The CPU predicts that forward branches (tests) will not be taken and that backward branches (loops) will be taken. A 1-cycle stall results when the prediction is incorrect. SGS-Thomson takes a simpler approach for its T9000 Transputer. The processor predicts that all branches will not be taken and incurs a 5 -cycle penalty for taken branches.

Other RISC processors use branch-prediction bits the compiler sets into the branch instruction word to predict taken or nontaken branches. The i960, C400, RCS, and 88110 all use branch-prediction bits.

Speculative execution takes branch prediction one step further. Not only does the processor pick a path to succeed the branch instruction, but it then begins filling the pipeline with the path's instructions and executing them. If the wrong branch path was taken, pipeline

## SGS Thomson T9000 Transputer

- $50-\mathrm{MHz}$ clock (external $5-\mathrm{MHz}$ clock)
- 3.2 M transistors
- 70 SPECmarks (estimated)
- Superscalar architecture; issues as many as 8 instructions per clock cycle (prefix bytes count as instructions)
- 8 -bit instructions
$\checkmark$ Register file: Three integer stack registers, three floating-point registers, three ports (two read, one write)
- Local cache for local variables (256 bytes or 32 words)
$\checkmark$ S-kbyte cache RAM in 4 banks, fully associative; 4 -word ( 16 -byte) line size
Memory interface: 32 -bit address, 64 bit data buses; four 32 -bit crossbar buses (1 for each cache bank); glueless 8-Mbyte max SIMM connection


## PIPELINE

| INSTRUCTION <br> FETCH | INSTRUCTION <br> DECODE | OPERAND <br> REAP | EXECUTE | RESULT <br> WRITEBACK |
| :---: | :---: | :---: | :---: | :---: |

execution for the post branch instructions halts, and the processor state rolls back to the branch point.
Another way to cope with branch indeterminacy is to use branchtarget caches to hold branch-target

## Intel i860XP



- 25-, 40-, 50-MHz clock
- 2.55 M transistors
- 42 SPECmarks
- VLIW (very-long-instruction-word) architecture: issues 2 instructions- 1 scalar and 1 floating point-per clock cycle; FPU instruction can schedule 2 FPUs.
- $32 \times 32$-bit register file, $16 \times 64$-bit FPU register file
- 4 -way set-associative 16 -kbyte instruction and 16 -kbyte data caches; 32 byte line size
- 64-bit memory interface, 2 clock cycles per transfer, burst mode; uses MESI (modified, exclusive, shared, or invalid) cache-coherency protocol
- 4-stage pipeline
- RISC core and three functional units-
multiply, add, and graphics (all pipelined) - in FPU
- Compiler-filed branch-delay slots
- Pipelined floating-point load instruction bypasses cache with 128 -bit load.
- Single- or dual-instruction mode
$\checkmark$ Built-in support for PAX (parallel architecture extension) for medium grain parallelism.
- Built-in graphics functional unit for pixel and $Z$ buffer manipulation
- \$132, \$327, \$551 (1000) for 25-, 40and $50-\mathrm{MHz}$ versions, respectively.

Comments: New XP version has faster clock, write-through caches, bus snooping, and built-in hooks for medium grain multiprocessing.
addresses. Typically, on the first pass the CPU takes the branchdelay penalty. On subsequent executions, the CPU takes the previously calculated branch address, thus eliminating any pipeline delays. This tactic is effective for loops; AMD pioneered this technique in RISC $\mu \mathrm{Ps}$ with its secondgeneration 29000 . The 88110 has an on-chip, 32-entry branch-target cache for holding target addresses. The cache holds instruction pairs for both taken and nontaken branch paths.

National Semiconductor's designers store the target address in a different place. The 32SF641 caches the branch-target address with the branch instruction in the instruction cache. Accessing the branch instruction brings up the target address. TI's SuperSparc uses branch prediction to select which branch path to execute. The CPU places branch-target instructions into a branch-target cache and then executes them. If the branch is wrong, the alternate path's set of instructions is also ready for execution,

PIPELINE

| INSTRUCTION <br> FETCH | INSTRUCTION <br> DECODE | EXECUTE | RESULT <br> WRITEBACK |
| :---: | :---: | :---: | :---: |

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## RISC PROCESSORS

which minimizes the cost of the CPU's predicting wrong.
The DEC Alpha architecture has combined instructions: The processor can do a value selection-setting one value or another depending on a test-without needing to use a branch. The first instruction sets the first value. The second instruction tests another value and will load a second value if specified by the test results. This instruction sequence eliminates the need to use a branch to set alternative values, which in turn avoids pipeline interruptions.
Conventional condition codes can become a real problem with superscalar execution. Multiple instructions, such as two adds, could set conflicting condition codes. Designers needed a way to handle multiple conditions without conflict. IBM took the tack of creating separate condition-code registers in its in-struction-cache unit. Multiple conditions can be tested using a single branch.
Some RISC processors take a different approach to condition codes by eliminating them entirely and placing ALU and test results into an addressed register. The Mips RISC chips and the 88110 use this approach.
[DD

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# Time-domain techniques enhance testing of high-speed ADCs 

Michael J Demler, Micro Networks

Designers commonly use DSP techniques to characterize the dynamic performance of bighspeed A/D converters, but these tests often yield an incomplete picture. Adding a sinewave curve-fitting algorithm or beat-frequency test provides the missing description of sampling accuracy in the time domain.

The increasing availability and applications of highspeed A/D converters has led most manufacturers to include specifications for dynamic performance in their data sheets. Limiting dynamic testing to DSP techniques such as FFTs or statistical modeling such as sine-wave histograms does not portray the complete picture of a device's performance. Designers can employ a sine-wave curve-fitting algorithm or beatfrequency test techniques to add measurements in the time domain for a more comprehensive analysis. Timedomain analysis allows an engineer to evaluate test results without the limitations inherent in transforming sampled signals into other forms.
The most common DSP test uses a fast Fourier transform (FFT) to do a spectral analysis of an ADC's digital output. Fig 1 shows the FFT obtained by testing the Micro Networks MN5902, an 8-bit CMOS flash ADC. The ADC was sampling a full-scale $828.75-\mathrm{kHz}$ sine wave at 15 MHz . The test was a 4 k -point FFT. The ratio of signal amplitude to noise plus distortion was 44.1 dB .

Spurious-free dynamic range (SFDR) is a measure of the usable dynamic range of an ADC. SFDR is
defined as the difference, in decibels, between the amplitude of the fundamental and that of the largest spurious component in the FFT spectrum. In the example, the SFDR measured 49.6 dB between the fundamental and the second harmonic at 1.66 MHz .

An equation that expresses the signal-to-noise ratio ( $\mathrm{S} / \mathrm{N}$ ratio) of an ideal ADC with a resolution of n bits is $\mathrm{S} / \mathrm{N}$ ratio $=6 \mathrm{n}+1.8 \mathrm{~dB}$ (Ref 1). Because the $\mathrm{S} / \mathrm{N}$ ratio of an ideal 8-bit ADC is 49.8 dB , the spurious-free range of 49.6 dB illustrated in Fig 1 depicts an ADC that exhibits a usable dynamic range of 8 bits. A parameter called the effective number of bits (ENOB),


Fig 1-This plot shows the result of a 4k-point fast Fourier transform (FFT) performed on the MN5902 8 -bit flash A/D converter. The ADC was sampling a full-scale $828.75-\mathrm{kHz}$ sine wave at 15 MHz. FFT plots graphically illustrate parameters such as $\mathrm{S} / \mathrm{N}$ ratio and spurious-free dynamic range (SFDR).

## testing high-speed a/d converters

which is commonly derived from an FFT, provides a measure of dynamic resolution. To find the ENOB of an equivalent real ADC , the equation for $\mathrm{S} / \mathrm{N}$ ratio is rearranged so that $\mathrm{ENOB}=(\mathrm{S} / \mathrm{N}$ ratio-1.8)/6.

Using the data from the example FFT, with an $\mathrm{S} / \mathrm{N}$ ratio of 44.1 dB , the effective number of bits would be approximately 7 . One problem with this calculation is that all manufacturers do not use the same technique for measuring $\mathrm{S} / \mathrm{N}$ ratio. Many measure the $\mathrm{S} / \mathrm{N}$ ratio by first eliminating all harmonics and intermodulation products from the FFT. In such cases, the manufacturer should also report these distortion products separately.

In the Fig 1 example, the $\mathrm{S} / \mathrm{N}$ ratio without harmonics was 47 dB , which results in an effective bit calculation of 7.5. The problem exemplified by this erroneous 0.5 -bit improvement is that the $\mathrm{S} / \mathrm{N}$ ratio measurement doesn't reflect the actual resolution and accuracy of the individual samples taken by the ADC . If your interest is only in frequency-domain processing, the error may not matter; but if the accuracy of dynamic measurements is important, you'll want to include the harmonics and other spurious components in the ENOB calculation.

To show how severe the ENOB error can be when relying solely on the frequency domain, the data used to calculate the FFT in Fig 1 was edited to create a spurious code at one of the zero crossings in the data record. Fig 2 depicts a portion of the edited sine wave. Instead of producing the code 128, the data was changed to produce code 0 . Such spurious codes often occur and are called sparkle codes. The high slew rate


Fig 2-The data used to calculate the FFT in Fig 1 was edited to create a spurious code (code 0 instead of code 128) at one of the zero crossings in the data record. This plot depicts a portion of the edited sine wave, which exhibits corrupted data in the form of a sparkle code.
of the input signal near the mid-scale point of the waveform can cause problems in the encoding circuitry of some flash ADCs. These problems result in glitches in the digital output. Fig 3 shows the result of reproducing the 4 k -point FFT with the corrupted data. The spectra differ very little. The signal-to-noise measurement of the Fig 3 spectrum indicates less than 2 dB of loss, which shows up as a slightly elevated noise floor. The SFDR did not change significantly, and the ENOB was reduced by only 0.3 bits.

Using a long data record, such as the 4 k points in the example, is a common way to accurately measure an ADC's $\mathrm{S} / \mathrm{N}$ ratio. An undesirable result of this method is that small numbers of large errors, such as the mid-scale glitch, are averaged out with no indication of the severity of the error in the frequency domain. Shorter FFTs can have other problems because the higher noise floor that results from taking fewer samples can mask many small coding errors. For this reason, multiple FFTs are often performed so that the spectra can be averaged together to remove random noise and clearly discriminate harmonics. Of course, this averaging further conceals information about sampling errors unless you examine the actual acquired data.

An alternative method of calculating effective bits is to use an algorithm that will find the sine wave that achieves the "best fit" to the data from the ADC (Ref 1). A sine-wave-fitting algorithm recursively calculates the amplitude, offset, and phase of an ideal sine wave that results in the minimum rms error when compared with the actual quantized waveform. Using the same


Fig 3-The result of reproducing the $4 \mathbf{k}$-point FFT of Fig 1 using the corrupted data of Fig 2 shows very little difference when compared with the original. The main difference is the corrupteddata plot's slightly elevated noise floor.


Fig 4-This quantization-error plot of the flash ADC first tested in Fig 1 provides a graphical measurement of the time-domain errors under dynamic conditions. As is evident, the samples are generally within $\pm 1$ bit of the ideal.
flash ADC tested in Fig 1, 512 data points were collected to produce an FFT and a best-fit sine wave. Subtracting the best-fit waveform from the original quantized data produced the dynamic-quantizationerror plot of Fig 4. The plot provides a graphical measurement of time-domain errors under dynamic conditions.

As you can see, the samples were generally within $\pm 1$ bit of the ideal, with worst-case errors of $\pm 1.5$ bits. By including all of the nonlinearity and noise effects of the ADC , this method gives a true indication of the device's dynamic resolution. You should not confuse the dynamic-error plot with "dynamic linearity," which some manufacturers specify in their data sheets. Dynamic linearity is usually based on histogram techniques, which can hide time-domain errors. In contrast, looking directly at the quantization error plot, both large and small errors, which could be lost in an FFT or sine-wave histogram, are immediately evident.

The rms quantization error ( $\mathrm{V}_{\mathrm{e}}(\mathrm{rms})$ ) in Fig 4 is 0.55 bits. In an ideal ADC with a uniform distribution of all codes, the rms quantization error would be $q / \sqrt{12}$, where $q$ is one quantization step, or LSB. This relationship leads to an alternative equation for effective bits:

$$
\begin{gathered}
\mathrm{V}_{\mathrm{e}}=\frac{\mathrm{V}_{\mathrm{REFF}}}{2^{\text {ENOII }} \cdot \sqrt{12}} \\
\text { ENOB }=\log _{2}\left(\frac{\mathrm{~V}_{\mathrm{REFF}}}{\sqrt{12} \cdot \mathrm{~V}_{\mathrm{e}}(\mathrm{rms})}\right),
\end{gathered}
$$

where $V_{\text {REF }}$ is the full-scale range of the ADC.

Because this method includes all harmonics and spurious components, it is better for calculating the effective number of bits than the FFT-based technique. When you analyze data digitally, as in the quantization error plot of Fig 4, you can convert the equation for ENOB to units of bits rather than volts:

$$
\mathrm{ENOB}=\log _{2}\left(\frac{\mathrm{MAX} \text { CODE }-\mathrm{MIN} \mathrm{CODE}}{\sqrt{12} \cdot \mathrm{rms} \mathrm{BIT} \text { ERROR }}\right) .
$$

Converting to the more convenient base-10 logarithm yields

$$
\mathrm{ENOB}=3.32 \cdot \log _{11}\left(\frac{\mathrm{MAX} \mathrm{CODE}-\mathrm{MIN} \mathrm{CODE}}{\sqrt{12} \cdot \mathrm{rms} \text { BIT ERROR }}\right) .
$$

A disadvantage of sine-wave curve-fitting algorithms is that they may have long execution times and sometimes have difficulty converging to a solution. An alternative that is fast and can provide a quick graphical interpretation of performance, as well as supply data for more quantitative measurements, is the beatfrequency test. This test is the ultimate stress test of a flash $\mathrm{A} / \mathrm{D}$ converter in the time domain. The beatfrequency test directly measures input signal bandwidth, reveals sampling errors that result in spurious or out-of-place codes, and provides a measure of aperture errors.
Designers familiar with sampling theory know that the Nyquist criterion requires that you sample a signal


Fig 5-This single-tone beat frequency is the result of using an input sine wave slightly higher in frequency than the sampling clock, and connecting the sampled data points in a continuous time record. To guarantee that you exercise all the codes, calculate the input frequency to produce a change of less than 1 bit in the beat tone at the maximum slewing point. This point is set at the mid-scale point of unipolar ADCs.

## TESTING HIGH-SPEED A/D CONVERTERS



Fig 6-You can use this test circuit to demonstrate the ADC beat-frequency measurements Figs 7 through 10 show.
at a rate greater than twice the signal's highest frequency component. Signals that do not adhere to this limitation result in "aliases." Aliases are the result of high-frequency signals at an ADC's input that are transferred to lower-frequency signals within the output bandwidth of one half the sampling rate. Beatfrequency testing exploits this phenomenon by deliberately producing low-frequency representations of highfrequency signals.
You should note that many flash A/D converters are


Fig 7-This plot shows the $10-\mathrm{kHz}$ beat-frequency results of digitizing a full-scale input at 17.01 MHz with the ADC sampling at 17.00 MHz . The peak-to-peak amplitude of the output code is -0.275 dB relative to full scale, and the beat waveform shows no evidence of spurious codes.
specified for a "full-power bandwidth" that is less than the Nyquist rate. Often this specification describes the point where gross errors occur on the ADC's output.
During a beat-frequency test, the ADC digitizes input signals that are multiples of the sampling rate. If you use an input sine wave just slightly higher in frequency than the sampling clock, the sampling point will change in relative phase at a rate equal to the difference in frequency between the two signals. By connecting the sampled data points in a continuous time record, the single-tone beat frequency is traced out as Fig 5 shows. To guarantee that you exercise all the codes, calculate the input frequency to produce a change of less than one bit in the beat tone at the maximum slewing point. This point is set to the midscale point of unipolar ADCs. The calculation is

$$
\frac{d V_{\mathrm{IN}}}{\mathrm{dt}}(\mathrm{MAX})=2 \pi \cdot \mathrm{~A} \cdot \mathrm{f}_{\mathrm{IEAT}} .
$$

Set A to half the full-scale range of the ADC, which is $\mathrm{V}_{\text {refer }} / 2$ for a unipolar converter. For a change of one bit per sample at the maximum slewing point:

$$
\frac{\mathrm{d} \mathrm{~V}_{\mathrm{IN}}}{\mathrm{dt}}=\frac{2 \pi \cdot \mathrm{~V}_{\mathrm{REF}} \cdot \mathrm{f}_{\mathrm{BEAT}}}{2},
$$

and $f_{I N}=\frac{f_{C L K K}}{2^{\mathrm{N}} \cdot \pi}+x \cdot f_{C L K,}$,
where x is an integer.
To demonstrate the technique, a series of beat-


Fig 8-In this test, the input frequency was doubled to 34.01 MHz while the sampling rate was kept at 17.00 MHz . Again, the plot shows a $10-\mathrm{kHz}$ beat, but with a peak-to-peak attenuation of 1.24 dB .
frequency tests were performed using the MN5902 CMOS flash ADC in the test circuit of Fig 6. The beat tests started by digitizing a full-scale input ( $\mathrm{f}_{\mathrm{IN}}$ ) of 17.01 MHz with the ADC sampling at a $17.00-\mathrm{MHz}$ clock rate ( $\mathrm{f}_{\mathrm{CLK}}$ ). This test produced the $10-\mathrm{kHz}$ beat frequency evident in the Fig 7 plot of digital output codes. In this plot, the horizontal axis represents the number of data points, and the vertical axis represents the 8 -bit code. The peak-to-peak output-code amplitude was -0.275 dB relative to full scale. An examination of the beat waveform shows no evidence of spurious codes.


Fig 9-In this third test, the input frequency of 51.01 MHz is three times the clock rate. Under these conditions, there were still no spurious codes present, and the peak-to-peak output was attenuated by 3.4 dB . The attenuation of the beat frequency gives an accurate indication of the overall $-3-\mathrm{dB}$ bandwidth of the composite sampling system.


Fig 10 -In this final test, the input frequency of 68.01 MHz is four times the sampling rate. The frequency increase attenuated the output amplitude by 9.28 dB but generated no sparkle codes.

You can also derive the beat waveform from signals that are offset in frequency from harmonics of the sampling rate. In the second test, which Fig 8 shows, the input frequency was doubled to 34.01 MHz while the sampling rate was kept the same. Once again the $10-$ kHz beat was obtained, with a peak-to-peak attenuation of 1.24 dB . In the third test, which Fig 9 shows, the input frequency is increased to three times the clock rate for an input of 51.01 MHz . Under these conditions, no spurious codes were present, and the peak-to-peak output was attenuated -3.4 dB . Although these results include effects caused by the large-signal-bandwidth roll-off from the input-signal amplifier, attenuation in the beat frequency gives an accurate indication of the overall $-3-\mathrm{dB}$ bandwidth of the composite sampling system.

Finally, in Fig 10, the input frequency was increased to 68.01 MHz , or four times the sampling rate. This increase reduced the output amplitude by 9.20 dB but did not result in any sparkle codes. Although you may observe increased distortion as you approach an ADC's performance limits, it is more important to users that a device degrades gracefully and has no abrupt onset of gross sampling errors. If more accurate measurements are required under extreme undersampling conditions, you can lock the two signal sources to a common reference to reduce phase jitter, which can corrupt the low-frequency beat. No attempt to do so was made for the tests described here.

You can use the extremes of input frequency to measure the margin of aperture uncertainty a flash ADC is capable of providing. If there is a small variation in the sampling point of the ADC's adjacent comparators, high-frequency signals will slew through mul-


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tiple quantization levels while the circuit makes a decision. The resulting ambiguity can cause large errors in the encoding of the digital output. To determine the amount of sampling aperture uncertainty that would produce coding errors greater than 1 bit, use the following equation:

$$
\frac{\mathrm{dV}}{\mathrm{dt}}=2 \pi \cdot \mathrm{~A} \cdot \mathrm{f}_{\mathrm{IN}} .
$$

To scale in fractions of an LSB, use

$$
\mathrm{dt}=\frac{\mathrm{dV}}{\pi \cdot 2^{\mathrm{N}} \cdot \mathrm{f}_{\mathrm{IN}}}
$$

For a full-scale signal and an error in the sampling voltage of 1 bit:

$$
\mathrm{dt}(\mathrm{MAX})=\frac{1}{\pi \cdot 2^{\mathrm{N}} \cdot \mathrm{f}_{\mathrm{IN}}}
$$

As an example, for the Fig 9 input signal of 51.01 MHz with an effective attenuation of -3 dB , the aperture uncertainty is less than 35 psec .

In addition to providing an immediate indication of large-signal bandwidth and sparkle immunity, sinewave beat signals can be used to perform the other dynamic tests previously described. For example, you can use sine-wave-fitting algorithms to measure the quantization error of the beat waveforms. You can perform FFTs if you take aliasing into account and provide any required bandpass filtering at the input.

EDJ

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## Author's biography

Mike Demler has been with Micro Networks (Worcester, MA) for three years and is the manager of monolithic design engineering. Mike, who has been instrumental in the design of 6 - and 8 -bit flash A/D converters, also develops test systems for dynamic analysis. He holds a BSEE from the State University of New York at Buffalo and an MSEE from
 Southern Methodist University (Dallas, TX). In his leisure time, Mike enjoys home remodeling, photography, and sports.

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## EDN-DESIGN FEATURE

# Use the analytic approach to avoid errors when probing CMOS circuits 

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#### Abstract

Heisenberg's uncertainty principle states that you can't measure a physical event without somehow affecting that event. This principle bolds true for CMOS circuits, but armed with the right analytical techniques you can render those effects immaterial.


When you're making measurements on CMOS circuitry, you must take probe characteristics into consideration. Probe resistance and probe capacitance can affect voltage measurements as well as the accuracy of delay-time measurements. However, using the right techniques can help you overcome these problems.

To understand how a probe's characteristics can affect measurements, you must look inside the device you're measuring. The output circuitry of any CMOS device consists of one or more FETs tied to the positive supply rail and one or more FETs tied to ground (Fig 1a.) In the high output state, the FETs connecting the gate's output pin to the power supply are turned on hard; in the low state, the FETs between the output and ground are turned on hard.

When you consider the addition of a pull-up resistor and add the resistance of the probe, the output circuit looks like Fig 1b. The first thing you'll want to know is how the dc voltage levels at the output node will change due to probe resistance.

In the low output state, no current will flow through the probe resistance because there is no voltage across it. Thus, you need only consider the high state. To
analyze the high-output voltage level, you need to understand the characteristics of a CMOS output. Fig 2 reproduces published high-level voltage vs current (E/I) characteristics for various CMOS devices.

The plot in Fig 2a depicts the output characteristics for a family of CMOS logic from Integrated Device Technology (IDT). The output E/I slope corresponds to an equivalent resistance of approximately $25 \Omega$ as long as the current does not exceed 100 mA . This impedance is the equivalent on-resistance of the onchip FET between the gate's output pin and the positive power-supply rail. This output impedance is much smaller than any reasonable pull-up resistor you might design into a circuit using this FET, so you only need


Fig 1 -You can understand the effects of probe resistance on measurement accuracy best when you look at the output circuitry of CMOS devices (a). Addition of the probe resistance (b) creates a resistive divider and introduces error into level measurements.

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to consider the circuit, which consists of the FET's on-channel resistance and the probe resistance.
Fig 2b illustrates how the IDT FET's output voltage will vary as a function of the probe resistance when the supply voltage equals 5 V . A $1-\mathrm{k} \Omega$ probe represents a $5-\mathrm{mA}$ load on the output.
The same concepts apply to devices with steeper E/I output curves. For example, Cypress' CY7C909/ CY7C911 microprogram sequencers have an output E/I slope (Fig 2c) that is very nearly linear and has an equivalent resistance of approximately $100 \Omega$. For these devices, Fig 2d illustrates how the high output level will react as a function of probe resistance.
These examples make one significant point-when the gate is in the active-high state, the effect of a probe's resistive loading depends on the on-channel resistance of the output-stage FET rather than on the value of the external pull-up resistor. These examples illustrate that an understanding of an IC's high-outputstate $\mathrm{E} / \mathrm{I}$ characteristics can be useful when deciding what measurement probe to use. In general, a probe resistance of $100 \mathrm{k} \Omega$ is adequate for virtually all types of CMOS circuitry, and some circuits can tolerate $1-\mathrm{k} \Omega$ resistive loads.
A probe's capacitance affects the accuracy of timing measurements. To change the output level from low to high or high to low, an IC's output stage must
source or sink current to charge or discharge the capacitive load. This load includes the capacitance of the probe, the input capacitance of any gates connected to the IC's output, and any parasitic capacitance associated with the pe board or other fixtures. Altering the charge on this capacitance takes a finite amount of time-it is not instantaneous.

Some CMOS-device data sheets provide information on how propagation delays change with load capacitance. For example, Fig 3 shows delay curves for the Cypress CY7C150 static RAM. For this device, a probe with a load capacitance of 8 pF will change the outputedge timing by about 0.4 nsec.
For vital timing measurements on very-high-speed CMOS circuitry (transition times of approximately 1 nsec), the probe capacitance can become critical. In these cases, choose the probe type with the lowest capacitance. A passive resistive-divider probe, designed to be terminated into $50 \Omega$, has the lowest capacitance (see box, "A probing primer"). A 20:1 resis-tive-divider probe designed for a $50 \Omega$ termination will present an input resistance of $1 \mathrm{k} \Omega$ to the circuit under test. High-speed CMOS circuits are typically designed to have a relatively low on-channel resistance and can provide relatively high currents, so a $1-\mathrm{k} \Omega$ probe will introduce minimal voltage errors.
Probe resistance is not a significant factor in making


| Probe resistance | Output "high" level | Error |
| :--- | :---: | :---: |
| Infinite (no probe) | 5 Vdc | $0 \%$ |
| $1 \mathrm{M} \Omega$ | 5 Vdc | $0 \%$ |
| $100 \mathrm{k} \Omega$ | 5 Vdc | $0 \%$ |
| $10 \mathrm{k} \Omega$ | 4.99 Vdc | $0.25 \%$ |
| $1 \mathrm{k} \Omega$ | 4.88 Vdc | $2.5 \%$ |

(a)
(b)

(c)

| Probe resistance | Output "high" level | Error |
| :--- | :---: | :---: |
| Infinite (no probe) | 4 Vdc | $0 \%$ |
| $1 \mathrm{M} \Omega$ | 4 Vdc | $0 \%$ |
| $100 \mathrm{k} \Omega$ | 4 Vdc | $0 \%$ |
| $10 \mathrm{k} \Omega$ | 3.96 Vdc | $1 \%$ |
| $1 \mathrm{k} \Omega$ | 3.64 Vdc | $9.1 \%$ |

(d)

Fig 2-To analyze high-output voltage levels, you must look to the output characteristics of CMOS logic (a). The FET's output voltage will vary as a function of probe resistance (b). For CMOS devices with steeper I/O characteristics (c), the effects of probe loading are more pronounced (d).


Fig 3-Propagation delay and access time both increase as the load capacitance increases. To minimize problems, always choose the probe with the lowest capacitance.
accurate voltage-level measurements on CMOS circuits as long as the outputs are in an active-high or an activelow state. However, high-Z measurements can be problematic. Measuring the time it takes for a device's output to go into the high-Z state after its outputenable pin is negated can be difficult. It's even tougher to make a measurement when you suspect that some device's output is trying to drive a bus high or low when the bus should be in the high-Z state. Having several drivers connected to a bus makes it very tough to find the culprit.

The output impedance of a device should be infinite when it is in the high-Z state, so you might guess that you need a very-high-resistance scope probe to detect this state. You might at least assume that the resistance of the scope probe should be many times larger than that of the node's pull-up resistor. Neither of these assumptions is correct.
To approach this measurement, think about what it means for an output to be in the high-Z state and how the circuit behaves. When a logic output is in the highZ state, no current should be flowing. Other components connected to the output node will therefore determine the voltage at the device's output pin. These components include the pull-up resistor, other device inputs or active outputs connected to the same node, and the capacitances of the pc-board trace and the components attached to the circuit node.

When all outputs on a circuit node are in the high-Z state, the voltage at that node will change only if the charge on the node's load capacitance changes. With all outputs in a high-Z state, the only current source available to alter the charge on the node's load capacitance is the pull-up resistor, if one is connected. The rate of voltage change will therefore be set by the
node's time constant, which equals the load capacitance value times the pull-up resistor's value. Typical CMOS devices have an input capacitance of 4 to 10 pF . Circuitboard traces can add several pF. For a bus with several devices connected to it, the total capacitive load might be on the order of 100 pF . For a $10-\mathrm{k} \Omega$ pull-up resistor and a $100-\mathrm{pF}$ load capacitance, the time constant is $1 \mu \mathrm{sec}$.
Thus, when a device's output enters the high-Z state, we would not expect to see the output voltage level change significantly for tens or hundreds of nanoseconds. Of course, if the output were at a "high" level before going to the high-Z state, we would not expect the output level to change at all because the voltage is already as high as it can go. Therefore, voltage measurements will not tell you whether a device is really in the high-Z state or how long it takes to reach that state, regardless of the probe's resistance.
The best way to determine whether a particular device is trying to drive the bus either high or low is to measure the current in the device's output pin using a current probe and an oscilloscope. No current should flow through the device's output pin in either direction when the device is in the high-Z state. Make sure you select a current probe and oscilloscope with adequate bandwidth for this task ( 5 to $10 \times$ wider than the circuit's bandwidth).

Because the current probe introduces an unknown time delay, you should first de-skew the current probe and the voltage probe. Connect the equipment as shown in Fig 4a. Some digital oscilloscopes have internal de-skewing capabilities. If the scope you are using doesn't have the capability to automatically de-skew channels, record the amount of delay between the two

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## A probing primer

Any time you connect a scope or logic-analyzer probe to a circuit, the probe becomes a part of the circuit under test and the probe's transfer function affects the overall measurement system's response. These probe effects will degrade measurement accuracy because the new circuit including the probe will behave differently from the circuit without the probe. But you cannot eliminate the probe's effect.
The probe contributes resistive and capacitive loading effects. Inductance in the probe's ground lead can also affect measurements. The probe's resistance to ground forms a divider network in conjunction with the source resistance of the circuit under test (Fig A), decreasing the signal amplitude and also reducing the dc offset. If the probe's resistance is nine times greater than the Thevenin-equivalent output resistance of the circuit under test, attaching the probe will reduce the output-signal amplitude by approximately 10\%. In general, the frequency-independent amplitude errors and dc offset errors introduced by a probe's resistive loading are approximately proportional to the ratio of the probe's resistance to ground and the equivalent output resistance of the circuit under test.

The probe's tip capacitance (in parallel with the probe resistance) forms an RC circuit with the output resistance of the circuit under test. The RC circuit's time constant will slow the rise time of any signal transitions, increase the slew rate, and introduce delay in the actual time the transitions occur. As a rule of thumb, the rise time of a simple RC circuit is approximately 2.2 RC. Thus, for an output resistance of $100 \Omega$ and an $8-\mathrm{pF}$ probe tip capacitance, the real rise time at the node under test cannot be faster than about 1.8 nsec .

If the output of the circuit under
test is current limited (as is often the case for CMOS), the slew rate will be limited by the relationship

$$
d V / d t=I / C
$$

The inductance of the probe ground lead forms an LC circuit with the probe's capacitance and the output capacitance of the circuit under test, (including any parasitic capacitance of pc-board traces and other stray capacitances). As a handy rule of thumb, a probe's ground wire has an inductance of about 25 nH per inch. Neglecting circuit capacitance, a probe with a tip capacitance of 8 pF and a 4 -in. ground wire will have a ringing frequency of approximately 178 MHz . Therefore, a signal with a rise time of less than 1.9 nsec may stimulate ringing.

## A look at system bandwidth

To obtain error-free time-interval measurements, the bandwidth of the combined oscilloscope-andprobe system must be wide enough to accurately reproduce the circuit's signal. If you use a scope-probe combination that has a combined rise time of 1 nsec to measure a signal with a 1 -nsec rise time, the approximate measured rise time will be 1.41 nsec . This answer is in error by $41 \%$. If you use a scope-probe combination with a system rise time of 330 psec to measure the same


[^12]1-nsec actual rise time, the indicated rise time will be approximately 1.05 nsec -an error of only $5 \%$.

You may find it useful to memorize three rules of thumb. First, the combined system rise time (oscilloscope and probe) should be less than $1 / 3$ of the rise time of the signal you're measuring to keep errors below $5 \%$ and less than $1 / 7$ of the rise time of the signal you're measuring to keep errors below 1\%. Second, rise time and bandwidth are related by the following approximations:

Rise time $\approx 0.35 /$ Bandwidth
and
Bandwidth $\approx 0.35 /$ Rise time.
Finally, rise times add approximately as the square root of the sum of the squares.

For example, if the oscilloscope and the probe each have a $1-\mathrm{GHz}$ bandwidth, the combined bandwidth is approximately 707 MHz and the combined rise time is roughly 495 psec. Therefore this combination could be used confidently to measure actual signal rise times of 1.5 nsec with a less than $5 \%$ error or 3.5 nsec with a less than 1\% error.

Oscilloscope probes are available in three common types: lowimpedance resistive-divider probes; compensated, high-resistance pas-sive-divider probes; and active probes. Resistive-divider probes are designed for scopes with a $50 \Omega$ input impedance. The probe tip consists of a $450 \Omega$ or $950 \Omega$ series resistor. The probe's cable is a $50 \Omega$ transmission line. Because the cable is terminated by $50 \Omega$ at the scope input, it appears as a purely resistive $50 \Omega$ load at the probe's tip. Therefore the resistive divider is flat over a wide range of frequencies, limited primarily by the
parasitic capacitance and inductance of the $450 \Omega$ or $950 \Omega$ resistor and the fixture that holds it. The resistive-divider probe has the lowest capacitive loading. Its low capacitance and inherent wide bandwidth of several GHz make the resistive-divider probe the best choice for wide-bandwidth measurements or measurements where timing is the most critical parameter.
Relatively heavy resistive loading is a drawback of the resistivedivider probe. Not all circuits can drive $500 \Omega$ or $1 \mathrm{k} \Omega$. Even for measurements in a relatively low-impedance circuit, the amplitude errors caused by a resistive-divider probe may be significant. When using this type of probe, keep in mind that the probe may cause changes in bias levels or operating currents that can cause the circuit's behavior to change.

Compensated passive-divider probes are the most common type of scope probe. Most logic ana-
lyzer probes also use this same general design. The $900-\mathrm{k} \Omega$ resistor in the probe tip forms a 10:1 voltage divider with a $100-k \Omega$ resistor located at the other end of the probe cable. Some probe designs put a $9-M \Omega$ resistor at the probe's tip, and the scope's 1-M $\Omega$ input resistance forms the other part of the voltage divider. To achieve a flat frequency response, the voltage divider must include compensation for the capacitance of the cable and for the scope (or analyzer) input capacitance. Because the input capacitance of the scope is unknown, one of the compensating capacitors should be adjustable so you can optimize the step-response flatness.

The compensated passive-divider probe has the highest input resistance of any probe type. However, it also has the highest capacitive loading and the lowest bandwidth. At 2 MHz , an $8-\mathrm{pF}$ capacitance has a $10-k \Omega$ impedance and at 100 MHz it is only $200 \Omega$. Com-

Table A-Probe characteristics

| Manufacturer | Model number | Resistance | Capacitance | Bandwidth |
| :---: | :---: | :---: | :---: | :---: |
| Resistive-divider probes |  |  |  |  |
| Hewlett-Packard | 54006A | $\begin{aligned} & 1 \mathrm{k} \Omega, \\ & 500 \Omega \end{aligned}$ | 0.25 pF | 6 GHz |
| Tektronix | P6150 | $500 \Omega$ | 0.15 pF | 9 GHz |
| Compensated passive-divider probes |  |  |  |  |
| Hewlett-Packard | $\begin{gathered} 1043 A \\ 10432 A \end{gathered}$ | $\begin{gathered} 1 \mathrm{M} \Omega \\ 10 \mathrm{M} \Omega \end{gathered}$ | $\begin{aligned} & 6.5 \mathrm{pF} \\ & 7.5 \mathrm{pF} \end{aligned}$ | 500 MHz 300 MHz |
| Tektronix | $\begin{aligned} & \hline \text { P6137 } \\ & \text { P6562 } \end{aligned}$ | $\begin{aligned} & 10 \mathrm{M} \Omega \\ & 10 \mathrm{M} \Omega \end{aligned}$ | $\begin{aligned} & 10.8 \mathrm{pF} \\ & 10.3 \mathrm{pF} \end{aligned}$ | $\begin{aligned} & 400 \mathrm{MHz} \\ & 350 \mathrm{MHz} \end{aligned}$ |
| Fluke/Philips | PM8929/391 | $10 \mathrm{M} \Omega$ | 12 pF | 325 MHz |
| Active probes |  |  |  |  |
| Hewlett-Packard | $\begin{aligned} & 54001 \mathrm{~A} \\ & 54701 \mathrm{~A} \end{aligned}$ | $\begin{aligned} & 100 \mathrm{k} \Omega \\ & 100 \mathrm{k} \Omega \end{aligned}$ | $\begin{gathered} 2 \mathrm{pF} \\ 0.6 \mathrm{pF} \end{gathered}$ | $\begin{gathered} 1 \mathrm{GHz} \\ 2.5 \mathrm{GHz} \end{gathered}$ |
| Tektronix | $\begin{aligned} & \hline \text { P6203 } \\ & \text { P6204 } \\ & \text { P6205 } \end{aligned}$ | $\begin{aligned} & 10 \mathrm{M} \Omega \\ & 10 \mathrm{M} \Omega \\ & 1 \mathrm{M} \Omega \end{aligned}$ | $\begin{gathered} 2 \mathrm{pF} \\ 1.9 \mathrm{pF} \\ 2 \mathrm{pF} \end{gathered}$ | $\begin{gathered} 1 \mathrm{GHz} \\ 1 \mathrm{GHz} \\ 750 \mathrm{MHz} \end{gathered}$ |
| Fluke/Philips | PM8943Q | $1 \mathrm{M} \Omega$ | 3.5 pF | 650 MHz |
| Logic-analyzer probes |  |  |  |  |
| Hewlett-Packard | $\begin{gathered} \hline 1650 \mathrm{~B}, 16510 \mathrm{~B} \\ 16515 \mathrm{~A}, 16516 \mathrm{~A} \\ \hline \end{gathered}$ | $\begin{aligned} & 100 \mathrm{k} \Omega \\ & 10 \mathrm{k} \Omega \end{aligned}$ | $\begin{aligned} & 8 \mathrm{pF} \\ & 3 \mathrm{pF} \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { NA } \\ & N A \end{aligned}$ |
| Tektronix | $\begin{gathered} 1230 \\ \text { Prism 30HSM } \end{gathered}$ | $\begin{gathered} 1 \mathrm{M} \Omega \\ 165 \mathrm{k} \Omega \end{gathered}$ | $\begin{gathered} 8 \mathrm{pF} \\ 11 \mathrm{pF} \end{gathered}$ | $\begin{aligned} & \text { NA } \\ & \text { NA } \end{aligned}$ |
| Fluke/Philips | PM3580 | $200 \mathrm{k} \Omega$ | 7 pF | NA |

[^13]pensated passive-divider probes are often referred to as highimpedance probes. This is a misnomer because these probes exhibit high input impedances only at relatively low frequencies.
An active probe has a buffer amplifier at its tip. This buffer amplifier drives a $50 \Omega$ cable terminated by $50 \Omega$ at the scope's input. Active probes offer the best overall combination of resistive loading, capacitive loading, and bandwidth, even though they don't have the highest resistance, the highest bandwidth, or the lowest capacitance available. The disadvantages of active probes are relatively high cost, relatively large tip size, a somewhat limited dynamic input range, and greater susceptibility to damage. You should handle them with care.
The perfect probe doesn't exist, so you must exercise some discretion when choosing the best type for each measurement. To make this choice, you must know the equivalent circuit for the circuit you're going to test, the approximate bandwidth or spectral content of the signal you'll be measuring, and the characteristic (voltage or time) you want to measure most accurately. Logic analyzers generally don't give you a choice of probes. Logicanalyzer probes are usually designed to be used with a particular analyzer. The table lists some characteristics of representative oscilloscope and logic-analyzer. probes.

However, you still need to understand the effect of the probes on the measurement. The examples above used a simple resistance as the equivalent circuit for the circuit under test. For actual cases, you need a more complete model to understand the probe's effects. For truly demanding measurements you may find it worthwhile to simulate the effect of the probe using SPICE.

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channels and subtract that amount from subsequent measurements.

If you don't have a current probe, you can use an alternate method to measure the time required by a device to achieve the high-Z state after its outputenable pin is negated. Construct a relatively smallvalue resistive divider connected to the output as shown in Fig 4b. The combined parallel value of the divider resistors should be less than $1 / 10$ of the probe's resistance. For example, for a $100-\mathrm{k} \Omega$ probe, the equivalent resistance of the divider should be less than $10 \mathrm{k} \Omega$, so each divider resistor should be $20 \mathrm{k} \Omega$ or smaller. If you plan to use a $1-\mathrm{k} \Omega$ resistive divider probe, use the probe as one of the divider resistors ( $\mathrm{R}_{2}$ in Fig: 4b), and a $1-k \Omega$ resistor for the other half of the divider.

Using this resistive-divider probe, you will measure an output level of $\mathrm{V}_{\mathrm{Cc}} / 2$ when the device's output is in the high-Z state. When the output is not in the high-Z state, you will measure the normal high- or low-output levels. Using a normal probe, you can then connect another oscilloscope channel to the device's output-enable input to measure the delay between ne-

| RTXC ${ }^{T M}$ \& RTXC/MP |  |
| :---: | :---: |
| Written in C , portable by design | Intel 80x86, 80x96, 8051 Motorola 68HC11/16, 68xxx TI TMS320C30/C40 Zilog Z80, Z×80 Aralog Devices 2101 Inmos T2xx, T4xx, T8xx |
| Dynamic priorities Task Management Timer Management Memory Management Semaphores <br> Message mailboxes FIFO queues Resource Management | From 8-bit microcontrollers to multiple 32 -bit processors : same API! |
| Virtual single processor with RTXC/MP | (distributed) Debugger System generation tool Workload monitor |
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Fig 4-To account for probe time-delay characteristics when making high-Z-state measurements, you should de-skew the scope's current and voltage probes by adjusting the scope controls until the edges on channels 1 and 2 are coincident (a). When you don't have a current probe, you can use a resistive divider (b) to verify high-Z output-state conditions.
gation of the output-enable pin and the transition to the high-Z state. This technique will not identify the offending device in cases of bus contention. Any device driving the node will force the bus line to either the high or low state. You can only use the resistivedivider technique for verifying the delay between the negation of the output-enable pin and the onset of the high-Z state. You still need a current probe to trace bus-contention problems.

5DD

## Author's biography

Art Porter is a product marketing engineer at Hewlett-Packard Co (Colorado Springs, CO). He is currently involved with research and development activities in the planning of new products. During his 29 years at HewlettPackard, Art has worked on the development of several oscilloscope product lines. In his spare time, Art enjoys pho-
 tography, rock climbing, and cross- country skiing.

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| OUTPUT VOLTAGE | 5VDC | 12 VDC | 15 VDC | 24 VDC | 28VDC |
| OVERVOLTAGE SETTING (TYP) | 7.2 VDC | 16 VDC | 19VDC | 26VDC | 30 VDC |
| OUTPUT CURRENT (MAX) | 15A | 8.3 A | 6.7 A | 4.2 A | 3.6A |
| INITIAL SETTING (MAX) | $\pm 1 \%$ | $\pm 1 \%$ | $\pm 1 \%$ | $\pm 1 \%$ | $\pm 1 \%$ |
| TRIM RANGE | $\pm 10 \%$ | $\pm 10 \%$ | $\pm 10 \%$ | $\pm 10 \%$ | $\pm 10 \%$ |
| LINE REGULTATION (MAX) | 0.3\% | 0.3\% | 0.3\% | 0.3\% | 0.3\% |
| LOAD REGULATION (MAX) | 0.3\% | 0.3\% | 0.3\% | 0.3\% | 0.3\% |
| TEMP. STABILITY (MAX) | $0.015 \% /{ }^{\circ} \mathrm{C}$ | $0.015 \% /{ }^{\circ} \mathrm{C}$ | $0.015 \% /{ }^{\circ} \mathrm{C}$ | $0.015 \% /{ }^{\circ} \mathrm{C}$ | $0.015 \% /{ }^{\circ} \mathrm{C}$ |
| EFFICIENCY (28VDC IN, FL TYP) | 65\% | 70\% | 72\% | 72\% | 72\% |
| RIPPLE \& NOISE (MAX) <br> ( 20 MHz Bw 10\% TO FL) | 200 mV p-p | 175 mV p-p | 175 mV p-p | 175 mV p-p | 175 mV p-p |

## Mechanical




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| LTC PART NUMBER | DESCRIPTION | LTC POWER | Icc MAX | STD PINOUT |
| :---: | :---: | :---: | :---: | :---: |
| LTC485 | Half Duplex Transceiver | 60X Lower | $500 \mu \mathrm{~A}$ | 75ALS176B |
| LTC486 | $\begin{gathered} \text { 10Mbs } \\ \text { Quad Driver } \end{gathered}$ | 400XLower | $150 \mu \mathrm{~A}$ | 75172 |
| LTC487 | 10Mbs Quad Driver | 400XLower | $150 \mu \mathrm{~A}$ | 75174 |
| LTC488 | 10Mbs Quad Receiver | 7XLower | 10mA | 75173 |
| LTC489 | 10Mbs Quad Receiver | 7XLower | 10mA | 75175 |
| LTC490 | Full Duplex Transceiver | 140XLower | $500 \mu \mathrm{~A}$ | 75179B |
| LTC491 | Full Duplex Transceiver | 60X Lower | $500 \mu \mathrm{~A}$ | 75ALS180 |
| LTC1485 | 10 Mbs Half <br> Duplex <br> Transceiver | 8XLower | 3.5 mA | 75ALS176B |

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## EDN-DESIGN IDEAS

## CMOS logic creates precision waveforms

Michael A Wyatt, Honeywell SSO, Clearwater, FL

The circuit in Fig 1 generates three different waveforms having frequencies less than 1 Hz : triangle waves, positive ramps, and negative ramps. At very low output frequencies, the stability of the circuit's input frequencies almost completely determines the output waveform's linearity.

XOR gate $\mathrm{IC}_{: ;}$beats input frequency $\mathrm{f}_{\mathrm{IN}}$ against reference frequency $f_{\text {li:F }}$, thus producing a train of pulses whose periods increase gradually until the frequency sources are completely out of phase. Then, the pulses' periods decrease until the sources are again in phase. Flip-flops $\mathrm{IC}_{1 \lambda}$ and $\mathrm{IC}_{11}$ produce $50 \%$ duty-cycle inputs for XOR gate $\mathrm{IC}_{\text {; }}$.
$\mathrm{IC}_{\overline{5}}$ and its surrounding components form a thirdorder, lowpass filter ( $f_{1}=1 \mathrm{kHz}$ ). The filter averages the output of pulse buffer $\mathrm{IC}_{4}$ to produce a triangle waveform having a peak amplitude of $\mathrm{V}_{1 c}$ and a frequency of $\left|f_{L_{N}}-f_{\text {R: }}\right| \div 2$. Be sure to select low-dielectric-absorption capacitors for the filter circuit.

The circuit generates ramp waveforms in a similar manner except that the SR flip-flop phase comparator formed by $\mathrm{IC}_{2 \mathrm{~A}}$ and $\mathrm{IC}_{2,}$, replaces the XOR gate. The phase comparator sets on every other negative transition of $\mathrm{f}_{\mathrm{IN}}$ and subsequently resets on every other negative transition of $f_{\text {LEFF }}$. If $f_{\text {IS }}$ 's frequency is greater than $\mathrm{f}_{\mathrm{RLPF}}$ 's, then the width of $\mathrm{IC}_{21}$ 's S output pulse will gradually increase. This increase produces a positivegoing ramp at the circuit's output. If $f_{1 \times}$ 's frequency is less than $f_{\text {li: }}$ 's, the output will be a negative-going ramp. Note that the filter's step response controls the ramp's reset time. Selecting a frequency greater than 100 kHz for $\mathrm{f}_{\mathrm{lN}}$ and $\mathrm{f}_{\mathrm{liPF}}$ attenuates the pulse's ripple, which relaxes the reset-time restrictions.
EDN BBS /DI_SIG \#1101
EDJ

To Vote For This Design, Circle No. 746


Fig 1-By beating two high-frequency input-pulse frequencies against each other and then integrating the resulting beat-frequency pulse train, this circuit produces low-frequency analog waveforms having good linearity.

# Voltage-reference circuit boasts low noise 

Adolfo Garcia, Analog Devices Inc, Santa Clara, CA

Noise is of critical importance in high-resolution, 16-to 20 -bit, data-acquisition systems. The voltage reference can contribute the dominant share of the system's noise floor, thereby degrading system dynamic range and S/N ratio. To maximize these parameters, all external noise contributions should be much less than $1 / 2$ LSB. Thus, the wideband noise contribution of a voltage reference and all other sources to 5 V full-scale 16 - and 18 -bit systems should be less than $38 \mu \mathrm{~V}$ rms and 9.5 V rms, respectively. Very few commercially available references exhibit low enough wideband noise without noise shaping or filters.

Fig 1 shows a single-supply 5V reference design whose performance is summarized in the accompanying table. This design's noise is more than a factor of 2 lower than any 5 V monolithic reference. In addition, the circuit's wideband noise in a $100-\mathrm{kHz}$ bandwidth is $20 \mu \mathrm{~V} \mathrm{rms}$, and therefore is suitable for 16 -bit systems. The circuit uses very-low-noise matched transistors operating at high collector currents to keep their noise contribution low. The design also ensures that $Q_{1}$ and $Q_{2}$ operate at the same temperature. Any temperature differences between these two transistors
causes $\mathrm{V}_{\text {le }}$ differences that will unbalance the bandgap reference's core. The MAT-04, a quad monolithic transistor, prevents $V_{\text {IBE }}$ temperature differences because all the transistors share a common substrate. Another dominant noise source is $\mathrm{R}_{3}$, and by operating high currents in the bandgap core, its value is kept to a minimum. In this circuit topology, the lower the value of $R_{:}$the lower the noise. To ensure repeatable lowfrequency noise measurements, take care to shield the circuit from air currents. Any air movement around the circuit can create noise because of the thermoelectric differences between the IC's package leads and the copper traces on a pc board. A Styrofoam cooler works well to keep air turbulence from polluting noise measurements.

An important parameter in any voltage reference is drift over temperature. Careful layout and selection of components account for this reference's low drift. Much in the same way air currents can generate noise in the circuit, they can be a source of drift. Junctions formed by the IC's pins and the copper traces on a pc board can generate parasitic thermoelectric differences, which can be as large as $15 \mu \mathrm{~V} /{ }^{\circ} \mathrm{C}$. Packing the


Fig 1-Minimizing noise in high-resolution data-acquisition systems-no simple design task-starts with minimizing the reference's noise contribution. This circuit uses matched transistors and carefully selected resistors to implement a bandgap reference with noise of $1.6 \mu \mathrm{~V}_{\mathrm{p}-\mathrm{p}}$ in the 0.1 - to $10-\mathrm{Hz}$ band.

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|  | RANGE <br> (MHz) | GAIN$\mathrm{dB}$ |  | MAX PWR ${ }^{+}$ | $\begin{aligned} & \mathrm{NF} \\ & \mathrm{~dB} \end{aligned}$ | $\begin{gathered} \text { ISOL. } \\ \mathrm{dB} \end{gathered}$ | $\begin{gathered} \text { DC } \\ \text { PWR } \end{gathered}$ | PRICE \$ ea. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | $\mathrm{f}_{\mathrm{L}}$ to $\mathrm{f}_{\mathrm{U}}$ | $\min$ | flat ${ }^{+\dagger}$ | dBm | (typ) | (typ) | $\mathrm{V} / \mathrm{ma}$ | (10-24) |
| MAN-1 | 0.5-500 | 28 | 1.0 | +8 | 4.5 | 40 | 12/60 | 13.95 |
| MAN-2 | 0.5-1000 | 18 | 1.5 | +7 | 6.0 | 34 | 12/85 | 15.95 |
| MAN-1LN | 0.5-500 | 28 | 1.0 | +8 | 2.8 | 39 | 12/60 | 15.95 |
| $\triangle$ MAN-1HLN | 10-500 | 10 | 0.8 | +15 | 3.7 | 14 | 12/70 | 15.95 |
| MAN-1AD | 5-500 | 16 | . 05 | +6 | 7.2 | 41 | 12/85 | 24.95 |
| MAN-2AD | 2-1000 | 9 | 0.4 | -2 | 6.5 | 28 | 15/22 | 22.50 |
| MAN-11AD | 2-2000 | 8 | 0.5 | -3.5 | 6.5 | 22 | 15/22 | 29.95 |

$\dagger \dagger$ Midband $10 \mathrm{f}_{\mathrm{L}}$ to $\mathrm{f}_{\mathrm{U} / 2}, \pm 0.5 \mathrm{~dB}+1 \mathrm{~dB}$ Gain Compression $\diamond$ Case Height 0.3 in . Max input power (no damage) +15 dBm ; VSWR in/out 1.8:1 max.

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components tightly on the pe board minimizes this error by making sure that all the components operate at the same temperature. Enclosing the circuit in a box is a good way to shield the circuit from air currents.
Since the circuit's output voltage and drift are sensitive to resistor tolerance and temperature coefficient, all fixed resistors are type RN55C ( $1 \%, \pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ ). Since $R_{1}$ and $R_{2}$ set the current ratio in the core, any mismatch in these components changes the current ratio, which affects $\Delta \mathrm{V}$ and introduces drift. Second, the ratio of $R_{4}$ to $R_{;}$amplifies $\Delta V$ with the current ratio. The result is voltage $V_{1}$, which adds to $Q$ 's $V_{\mathrm{IF}}$, thus producing a temperature-invariant bandgap voltage of 1.23 V at the bases of $\mathrm{Q}_{1}$ and $\mathrm{Q}_{2}$. Any mismatch in tolerance or temperature coefficient in $\mathrm{R}_{;}$and $\mathrm{R}_{4}$ introduces drift by affecting $V_{1}$ and Q's $^{2} \mathrm{~s} \mathrm{~V}_{\text {IE }}$. Last, $\mathrm{R}_{6}$ and $\mathrm{R}_{\stackrel{*}{ }}$ amplify the bandgap voltage of 1.23 V to an output of +5.0000 V . Any mismatch in these resistors changes the gain of the circuit and therefore changes the output voltage.

Another heavy contributor to the circuit's overall drift comes from the op amp's input-offset-voltage drift over temperature, which affects the bandgap core and introduces drift by changing the current ratio set by $R_{1}$ and $R_{2}$. Therefore, choose an op amp first for its low input-offset voltage drift and second for its high open-loop gain. $\mathrm{C}_{1}$ provides compensation and stabili-
zes the core by rolling off the op amp's high loop gain.
Although you can use low-cost cermet trimmers for $\mathrm{R}_{5}$ and $\mathrm{R}_{7}$, keep in mind that these components typically have $\pm 100 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ temperature coefficients. Therefore, use low-valued trimmers to keep the trim range narrow. Even mechanical changes that result from thermal expansion in the trimpot materials can be a large source of error. To trim the circuit, first adjust $R_{\text {; }}$ so that the bandgap voltage equals 1.23 V at $25^{\circ} \mathrm{C}$. Second, use $\mathrm{R}_{7}$ to adjust the gain of the reference for +5.0000 V at the output.

Bandgap references have a tendency not to start up when the power supply is turned on. You can avoid this condition by using a pair of resistors and an inexpensive npn transistor. $\mathrm{R}_{\mathrm{s}}, \mathrm{R}_{11}$, and $\mathrm{Q}_{\text {: }}$ form the startup circuit. When the supply is turned on, there is no current in the bandgap core and the op amp's output is at 0 V . Q: then turns on, and its emitter current flows through $R_{6}, R_{7}$, and $R_{4}$. When the output voltage reaches 3.2 V , the op amp kicks in and stabilizes the operating point around 5 V . This action shuts off $Q$; because its base is set to 3.9 V . For a wider range of supply voltages, you can replace $R_{10}$ with a 3.9 V zener diode to improve the start-up circuit's supply rejection. EDN BBS /DI_SIG \#1100

इD]
To Vote For This Design, Circle No. 749

# Buffer goes solo in fast active filter 

Michael Sedayao, Elantec Inc, Milpitas, CA

Active filters that drive low-impedance loads generally require a buffer with high output current at the filter output. If the filter doesn't require any gain, as in


$$
\begin{aligned}
& Q=\frac{\sqrt{m n}}{m+1} \\
& K \approx \frac{1}{26} F O R \text { EL2002 for desired } f_{O}>100 \mathrm{kHz}
\end{aligned}
$$

unity-gain operation, you can synthesize the filter using only the buffer. Although you give up gain adjustment, you still retain the buffer's $100-\mathrm{mA}$ output driver and $180-\mathrm{MHz}$ bandwidth. And, you've saved the cost of an op amp.

Fig 1 illustrates a basic Sallen-Key low-pass filter using only one buffer. Resistor and capacitor ratios m and n and values R and C (see equations in Fig 1) determine the $-3-\mathrm{dB}$ frequency and Q of the filter. In this design, the $-3-\mathrm{dB}$ frequency is 12.2 MHz and the $Q$ is 0.5 . To change the low-pass filter to a high-pass filter, simply switch the resistor and capacitor locations. The resultant high-pass filter has a $-3-\mathrm{dB}$ frequency of 36 kHz and a Q of 0.5 . This circuit will drive $\pm 4.5 \mathrm{~V}$ into 50 ohms and draws 5 mA of quiescent current. To achieve a Butterworth response, set Q $=0.707$. EDN BBS /DI_SIG \#1096

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Fig 1-A single buffer implements this unity-gain Sallen-Key lowpass filter with a $12.2-\mathrm{MHz}$ cutoff frequency.

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nels; and 14 channels for time processing, auxiliary asynchronous serial I/O or digital I/O. The board works with hard disks to 500 Mbytes. From $\$ 1995$. Onset Computer Corp, Box 1030, North Falmouth, MA 02556. Phone (508) 563-9000. FAX (508) 563-9477.

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Circle No. 359


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[^14]16-bit-wide SCSI 2/3 bus tester. The IPC-6020 development system uses a board that plugs into the 16 -bit ISA bus and that interfaces to the SCSI bus via a 68 -pin P-cable connector. The board transfers data synchronously at $20 \mathrm{Mbytes} / \mathrm{sec}$. The system includes Borland's $\mathrm{C}++$ compiler. Libraries for MS C V6.0 are available at no extra cost. $\$ 6800$; IPC-4020 interactive version, $\$ 5300$. I-Tech Corp, 6975 Washington Ave S, Suite 220, Edina, MN 55439. Phone (612) 941-5905. FAX (612) 941-2386

Circle No. $\mathbf{3 6 0}$

Open-architecture programmable controller. The combination of Wizdom's PLC (programmable logic controller) with the Workhorse A/D I/O systém lets you control machinery and industrial processes. As higher-performance processors become available, you can upgrade the CPU without obsoleting the rest of the system. I/O system board providing interface to PLC, $\$ 700$. Keithley Metrabyte, 440 Myles Standish Blvd, Taunton, MA 02780. Phone (508) 880-3000. FAX (508) 8800179.

Circle No. 361

Gang programmer for MC68HC11xx $\mu$ Cs. The Gangpro-SM Series II programs from 8 to 32 devices simultaneously, taking from 7 to 34 sec , depending on the memory size. The vendor can supply the stand-alone unit to program a mixture of EPROMs or EEPROMs and microcontrollers. $\$ 9995$. Delivery, 8 to 12 weeks ARO. Logical Devices Inc, 1201 NW 65th Pl, Fort Lauderdale, FL 33309. Phone (800) 331-7766; (305) 974-0967.

Circle No. 362

Development system for $\mu$ COM87AD $\mu$ Ps. The CT-NEC87 system nonintrusively emulates all processors in the family including single-chip and ROMless units, whether in 68-pin plastic leaded chip carriers, 64 -pin quad inline packages, or shrink DIPs. The system offers a configurable, windowed interface; C and assembly-language debugging; automatic synchronization of software displays with hardware activity; real-time monitoring of variables without halting emulation; real-time tracing of address, data, and external signals; and unlimited breakpoints. \$8750. Ashling Microsystems Ltd, Plassey Technological Park, Limerick, Ireland. Phone (61) 334466. FAX (61) 334477.

Circle No. 363

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## EDN-NEW PRODUCTS

Integrated Circuits

## 4-Channel, Simultaneous Sample/Hold Circuit <br> - Includes output multiplexer <br> - Features fast acquisition

The MSH-840 4-channel S/H circuit can arquire a 10 V step to $0.01 \%$ accuracy in 775 nsec (including the settling time of the output multiplexer). The hybrid IC operates in two modes: single-channel or simultaneous sampling. In either mode, the use of the reset pin will set all the $\mathrm{S} / \mathrm{H}$ circuits to the sample mode. Internal decoder circuitry allows channel selection to be digitized or the channel to be put into hold mode. The MSH-840 operates over $\mathrm{a} \pm 10 \mathrm{~V}$ input range and has a maximum nonlinearity of $\pm 0.01 \%$. Other specifications include $-70-\mathrm{dB}$ harmonic distortion, a $45 \mathrm{~V} /$ usec slew rate, and a $13-\mathrm{MHz}$ small-signal bandwidth. The MSH-840 requires 5 and $\pm 15 \mathrm{~V}$ supplies and comes in a 32 -pin package. From $\$ 224$ (OEM qty).

Datel Inc, 11 Cabot Blvd, Mansfield, MA 02048. Phone (508) 3393000. FAX (508) 339-6356.

Circle No. 364


## 5V Regulator For $\boldsymbol{\mu}$ P Functions

- Low dropout voltage
- Low quiescent current

Combining a $5 \mathrm{~V} \pm 4 \%$ regulator with watchdog, enable, and reset functions, the CS-8140 gives the system's $\mu \mathrm{P}$ control over its own power. The low-dropout regulator $(1.25 \mathrm{~V}$ at 500 mA$)$ has a quiescent current of 7 mA . A sleep mode reduces current drain to $250 \mu \mathrm{~A}$. A watchdog signal from the $\mu \mathrm{P}$ to the IC's enable input controls the $\mu$ P's supply voltage. When the enable pin is high, the regulator's output stage is active. When the enable pin is low, and the watchdog signal falls outside user-programmable frequency limits, the IC's output turns off, setting the IC and the $\mu \mathrm{P}$ in sleep mode. The IC generates a re-
set signal when the watchdog signal falls outside its frequency limits while enable is high; when the IC's output voltage drops more than $4.5 \%$; or when the IC power is on. CS-8140, in 7 -pin TO-220 or 24 -pin SOIC packages, from $\$ 2.03$ (1000).

Cherry Semiconductor Corp, 2000 South County Trail, East Greenwich, RI 02818. Phone (401) 885-3600.

Circle №. 365

## High-Speed MOSFET Driver

- Sources 6A and sinks 3A
- Drives high-capacitive loads

The HV400 MOSFET driver can drive capacitive loads ranging from 5000 to $100,000 \mathrm{pF}$. With a $20,000-$ pF load, the monolithic IC achieves rise and fall times of 70 - and 30 -
nsec, respectively. The driver, which does not draw any quiescent current, can source peak currents to 6 A via its high-side npn switch and can sink peak currents to 30A via its low-side SCR switch. This capability lets the IC switch four parallel-connected IR452 MOSFETs in 20 nsec . In floating applications, the HV400 can operate from a small pulse transformer driven by the system's PWM circuit. Using this pulse transformer and a few low-cost components, the driver provides its own power supply, isolation, level shifting, timing, and buffering. HV400, in 8-pin DIP and SOIC packages, from $\$ 1.40$ (100).

Harris Semiconductor, Box 883, Melbourne, FL 32901. Phone (800) 442-7747, ext 1047. Circle No. 366

# EDN-NEW PRODUCTS 

Integrated Circuits



Self-timed SRAM. Optimized for SPARC processors, the CXK77910J self-timed static RAM (SRAM) integrates 1 Mbit of memory with input and output registers. Organized as $128 \mathrm{k}-$ words $\times 9$ bits, the SRAM comes in 16.6 - and $20-$ nsec versions. Power consumption of the TTL-compatible device is 715 mW . In 32-pin SOJ package, from $\$ 75$ (1000). Sony Corp of America, Component Products Co, Box 6016, Cypress, CA 90630. Phone (714) 229-4197. FAX (714) 229-4333.

Circle No. 367

Power-factor preregulator. The UC3852 allows 50 to 100 W power supplies to operate at a 0.99 power factor. The IC regulates the output dc voltage by controlling switch on-time, and the
boost inductor controls the off-time. A zero-current sensing circuit activates the switching cycle. Other features include undervoltage lockout, current limiting, and output clamping. In 8-pin DIP and SO packages, from $\$ 1.77$ (100). Unitrode Integrated Circuits Corp, 7 Continental Blvd, Merrimack, NH 03054. Phone (603) 424-2410. FAX (603) 4243460.

Circle No. 368

60-MHz op amp. The EL2044 op amp features a $325 \mathrm{~V} / \mu \mathrm{sec}$ slew rate and a $60-\mathrm{MHz}$ bandwidth. Operating from a $\pm 15 \mathrm{~V}$ supply, the IC has an output swing of $\pm 13.6 \mathrm{~V}$. Output-current capability is 75 mA . The IC operates from a dual supply of $\pm 2$ to $\pm 18 \mathrm{~V}$ or a single supply of 2.5 to 36 V . In 8 -pin DIP and SO packages, from $\$ 1.80$ (100). Elantec Inc, 1996 Tarob Ct, Milpitas, CA 95035. Phone (408) 945-1323. FAX (408) 9459305. TWX 910-997-0649. Circle No. 369

Bus transceiver. Designed for balanced transmission lines, the SN75LBC176 bus transceiver meets EIA RS-485 and ISO 8482:1987(E) stan-
dards. The IC has a 3 -state differential line driver and a differential line receiver, both of which operate from a single 5 V supply. The bus lines, which are connected internally, can send or receive data over a common-mode voltage range of -7 to +12 V . In an 8 -pin DIP, $\$ 1.57$ (1000). Texas Instruments Inc, Semiconductor Group (SC-92008), Box 809066, Dallas, TX 75380. Phone (800) 336-5236, ext 3990. Outside US and Canada, (214) 995-6611, ext 3990.

Circle No. 370

Analog filters. The MAX274 eighthorder filter has four cascadable sections, and the MAX275 fourth-order filter has two. Each second-order, state-variable section can implement bandpass or lowpass filter responses. The MAX274 programmable center frequency ranges from 100 Hz to 150 kHz ; the MAX275's range is from 100 Hz to 300 kHz . Available in 24 - and 20 -pin packages, respectively, MAX274 and MAX275, from $\$ 4.95$ and $\$ 3.75$ (1000). Maxim Integrated Products, 120 San Gabriel Dr, Sunnyvale, CA 94086. Phone (408) 7377600 .

Circle No. 371

# Breakthrough multichip modules 



## Integrated Circuits

Low drop-out regulators. Designed for automotive applications, the MIC2950/51/54 regulators combine low dropout voltages with load-dump and re-verse-battery protection. The 2950 provides a fixed $5 \mathrm{~V} / 150-\mathrm{mA}$ output and has a $380-\mathrm{mV}$ dropout. The 2951 has the same dropout voltage and current rating but provides an adjustable 1.24 to 29 V output. The 2954 provides a fixed $5 \mathrm{~V} / 250-\mathrm{mA}$ output and has a $500-\mathrm{mV}$ dropout. Depending on type and package options, from $\$ 1.07$ to $\$ 2.53$ (100). Micrel Semiconductor, 560 Oakmead Pkwy, Sunnyvale, CA 94086. Phone (408) 245-2500.

Circle No. 372

10-bit A/D converter. The AD773 10-bit ADC includes an onboard T/H amplifier, a high-impedance reference input, and CMOS/TTL-compatible outputs. Optimized for video application, the ADC features a full-power bandwidth of 100 MHz , a speed of $18 \mathrm{Msam}-$ ples/sec, and differential gain and phase specifications of $0.4 \%$ and $0.2^{\circ}$, respectively. The ADC can acquire full-scale voltage swings in less than 55 nsec and offers common-mode noise rejection of

75 dB . In 28-pin ceramic DIP, from $\$ 55$ (100). Analog Devices Inc, Applications Engineering, 181 Ballardvale St, Wilmington, MA 01887. Phone (617) 937-1428. FAX (617) 821-4273.

Circle No. 373

Dual comparator and pin receiver. The $100-\mathrm{MHz}$ EL2254 replaces the buffer, attenuator, and ECL comparators used in test equipment and data-communications line receivers. The IC provides a 4 -nsec propagation delay with low dispersion of 100 psec (typ). The inhibit and latch-enable inputs are ECL-, TTL-, and CMOScompatible differential inputs. In a 20 pin SO package, $\$ 6.40$ (100). Elantec Inc, 1996 Tarob Ct, Milpitas, CA 95035. Phone (408) 945-1323. Circle No. 374

RF power amplifier. Designed for handheld cellular-phone applications, the S-AU55 RF power amplifier operates over the frequency range of 824 to 849 MHz . Input power to the GaAs FET amplifier is 4 mW , and output power is 1.12 W . The $17 \times 12 \times 4-\mathrm{mm}$

module operates from a 5.8 V supply, has an efficiency of $55 \%$, and a gain of 24.4 dB. $\$ 36.50$ ( 1 to 3000 qty). Delivery, 14 weeks ARO. Toshiba America Electronic Components Inc, 9775 Toledo Way, Irvine, CA 92718. Phone (714) 455-2000.

Circle No. 375

64-channel push-pull driver. The HV3225X integrates low-voltage logic with 64 push-pull output drivers rated at 250 V . The logic section, which operates at 5 or 12 V , comprises a 64 -bit shift register and 64 latches. The programmable output stages can source or sink currents from 25 to $250 \mu \mathrm{~A}$. In die form waffle packs, $\$ 13.24$ (1000). Supertex Inc, 1350 Bordeaux Dr, Sunnyvale, CA 94089. Phone (408) 744-0100. Circle No. 376

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Deutsch Engineered Connecting Devices, Municipal Airport, Banning, CA 92220. Phone (714) 849-7822.

Circle No. 377


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- Comply with MIL-C-83513

Requiring only one-third the space of conventional D subminiature connectors, the MDSM family pc-board-to-cable connectors feature a
0.05 -in. contact pitch. The units are fully compatible with MIL-C-83513 and feature a contact design that makes three points of contact. A shielding system integral to the backshell provides $70-\mathrm{dB}$ attenuation. The line features right-angle and cable-type connectors in 9-, 15-, and 25 -position versions, as well as double-stack 9 - and 15 -position versions. Crimp contacts for the cable versions are available for \#26 and \#28 AWG wire. $\$ 7$ per mated pair (1000).

ITT Cannon, 1851 E Deere Ave, Santa Ana, CA 92705. Phone (714) 261-5300.

Circle №. 378

## Rocker Switches

- Rated for 10A loads
- Have a 10,000-cycle life

D Series miniature power-rocker
switches feature a right-angle terminal style that snaps into a pc board to secure switches for soldering. The switches snap into a standard panel cutout and require no tools for mounting. The line features five spst switch functions. Contacts are rated for 10 A at 125 V ac and 5 A at 250 V ac. Electrical life is specified at 10,000 cycles at full load. Dielectric strength measures 1000 V rms min at sea level. Actuators and housing are available in nine colors with custom actuator markings available. The $6 / 6$ nylon material carries a UL $94 \mathrm{~V}-2$ rating. Most models are UL recognized and CSA certified. From $\$ 1.11$ (1000).

C\&K Components Inc, 15 Riverdale Ave, Newton, MA 02158. Phone (617) 964-6400. FAX (617) 527-3062. TLX 922544.

Circle No. 379

Simulator Multi-degree Analog-Structural Hierarchical on your personal workstation


Main features:

- Mixed electrical, structural, analog behavioral and digital behavioral simulation.
- Data base: SPICE-like and HILO-like (pending VHDL) netlists from various schematics editors with hierarchy. - Libraries: compatibility with most common libraries of ASICs and PCBs, capability given to the user to write his own modules in a C-like language at behavioral degree, or available from Dolphin Integration upon request. - Interactive set up and simulation display for all analyses: DC transfer function (including operating point and temperature analysis), $A C$ transfer function, transient analysis.
- Delays at structural level.
- Processing capability in background mode.
- Device visibility through analog behavioral modeling. - Modularly designed to enable separation of three modules initializer, engine and vizualizer (ICD). — Results: EXCEL files, ICD format files. - Available on your personal computer (Mac, PC) and UNIX workstation (SUN...).

SMASH ${ }^{\text {TH }}$ processes simultaneously 12000 gates, 250 transistors and 12000 steps or events.


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## Components \& Power Supplies

Fan trays. Designed for VME systems, these fan trays feature a 5 -fan design that offers direct cooling of slots 1 through 3-the most critical in a VME system. The trays are designed for use with 160 -, $220-$, 280 -, or $400-\mathrm{mm}$-deep chassis. Each tray includes a filter, a power-on LED, and a quick-disconnect power connector. From $\$ 300$. ACT Inc, 1 Ivybrook Blvd, Suite 180, Ivyland, PA 18974. Phone (215) 957-9071.

Circle No. 380

Circuit breaker. The IML family of circuit breakers includes $1-, 2$-, and 3 pole versions. The units are available with ratings of 0.5 to 70 A at 80 V de and 0.5 to 50 A at 240 V ac. The breakers are UL recognized, CSA certified, and meet international spacing requirements of IEC-157-1 and VDE 0660. Models are available in screw panelmount or snap-in styles. $\$ 14$ to $\$ 16$ (OEM qty). Airpax, Corporate Advertising, 7 McKee Pl, Cheshire, CT 06410. Phone (410) 228-4600. FAX (410) 2288910.

Circle No. 381

Memory-card connector. The FCN560 H series of DRAM-memory-card connectors consists of a right-angle board-mount plug and a surface-mountable card socket. The plug features 88 pins arranged in two rows with $0.05-\mathrm{in}$. contact spacing. Contact resistance equals $40 \mathrm{~m} \Omega$ and operating range spans -55 to $+105^{\circ} \mathrm{C}$. $\$ 5.42$ and $\$ 6.25$ for plug and socket, respectively, (1000). Delivery, stock to six weeks ARO. Fujitsu Microelectronics Inc, 3545 N First St, San Jose, CA 95134. Phone (800) 642-7616; (408) 922-9000. FAX (408) 428-0640.

Circle No. 382

Crystal oscillator. The HSM531/536 surface-mount oscillators are available with frequencies of 1.8432 to 70 MHz . The units are available with stabilities of $\pm 50$ or $\pm 100 \mathrm{ppm}$ over a temperature range of 0 to $70^{\circ} \mathrm{C}$. The oscillators are housed in a ceramic package that has a grounded metal cover to suppress RFI. \$11.25. Connor-Winfield Corp, 1865 Selmarten Rd, Aurora, IL 60505. Phone (708) 851-4722. FAX (708) 8515040.

Circle No. 383

Rotary switch. Series 94 rotary switches are available in surface-mount and through-hole versions. The units operate logic level loads, are rated for 25,000 operations, and feature octal,


BCD, hexadecimal-or their complements' coded-output choices. Octal unit, $\$ 1.69$ (1000). Grayhill Inc, Box 10373, La Grange, IL 60525. Phone (708) 3541040. FAX (708) 354-2820. TLX 190254.

Circle No. 384

DIN connectors. These DIN 41612 connectors come with snap-in clips that secure the units during soldering. The connectors fit into boards that are 1.6 mm thick and are available in angled male and female versions. $\$ 2.37$ (1000). Harting Elektronik Inc, 2155 Stonington Ave, Suite 212, Hoffman Estates, IL 60195. Phone (708) 519-7700. FAX (708) 519-9771.

Circle No. 385

Card cage. The rack-mountable Power Cage III includes a 12 -slot VME ( $6 \mathrm{U} \times 160 \mathrm{~mm}$ ) card cage, a high efficiency 400 W power supply with integral cooling, and a rugged Eurocard subrack that features a 10 -layer J1-J2 VME backplane. The unit features frontpanel LED voltage indicators; the hinged rear panel provides access to the fans and power supply and the rear of the backplane. $\$ 2495$. Delivery, four to six weeks ARO. Electronic Solutions, 6790 Flanders Dr, San Diego, CA 92121. Phone (800) 854-7086; (619) 452-9333. TWX 910-335-1169.

Circle No. 386

Power supplies. The SWA series of supplies includes 15,20 , and 30 W wall plug-in units and 40 and 60 W cord-tocord units. The cord-to-cord models have an input range of 90 to 264 V ac; plug-in versions accept 90 to 132 V and 198 to 264 V . The units output from 5 to 17.5 V at currents ranging to 4 A . All models feature overload protection and feature 65 to $70 \%$ efficiencies. Wall plug-ins, from \$39; cord-to-cord models, from $\$ 78$ (100). Tamura Corp of America, 1150 Dominguez St, Carson, CA 90746. Phone (213) 638-1790. FAX (213) 638-9956.

Circle No. 387

## Computers \& Peripherals

## Portable Computer

- Has a $50-\mathrm{MHz} 80486 \mu \mathrm{P}$ and 4Mbytes of RAM
- Optional TFT screen displays 24,389 colors
The P.A.C. $486-50 \mathrm{E}$ portable computer contains a $50-\mathrm{MHz} \mu \mathrm{P}$. Standard features include 4 Mbytes of RAM expandable to 32 Mbytes; an 8 - to 128 -kbyte cache RAM; a 1.44 Mbyte floppy-disk drive; a 120 - to 420-Mbyte hard-disk drive; a 64kbyte disk buffer; and support for a WE4167 coprocessor. The unit has four internal EISA expansion slots and three external ISA expansion slots. A Gas-Plasma VGA display is standard, and you can opt for an active-matrix TFT screen that displays 24,389 colors. The unit has two serial ports, a parallel port, and a VGA port for simultaneous

display on an external monitor. The computer measures $16 \times 9.5 \times 7.8 \mathrm{in}$. and weighs 18 lbs. 120-Mbyte hard-disk-drive version, less than $\$ 9000$.

Dolch Computer Systems, 372 Turquoise St, Milpitas, CA 95035. Phone (408) 957-6575. FAX (408) 263-6305.

Circle No. 388

## VMEbus Single-Board Computer

- Has a 25 - or $40-\mathrm{MHz}$ 68EC030 $\mu P$
- Three memory banks accept SRAM, EPROM, and dual-port RAM
The XVME-630 VMEbus singleboard computer (SBC) contains a $25-$ or $40-\mathrm{MHz} 68 \mathrm{EC} 030 \mu \mathrm{P}$. The


6 U board contains three memory banks having four 32 -pin sockets each. Bank 1 accepts static RAMs (SRAMs); bank 2 accepts EPROM; and bank 3 , which has dual-port access to the VMEbus, accommodates SRAM, EPROM, or flash memory. The board has a socket for a 68882 coprocessor; two serial ports; a sin-gle-level VMEbus arbiter; and ACfail and SYSfail monitoring func-
tions. It also has an interrupt handler and a programmable VME interrupter. The operating temperature ranges from 0 to $65^{\circ} \mathrm{C}$, and board humidities are 0 to $95 \%$ noncondensing relative humidity. The board survives 30 g and a vibration rate of 5 to 2000 Hz . From $\$ 1950$.

Xycom Inc, 750 N Maple Rd, Saline, MI 48176. Phone (800) 3677300 ; (313) 429-4971. Circle No. 389

## Single-Board Computer

- Has a $16-\mathrm{MHz}$ 80C196KC $\mu \mathrm{C}$
- Has 28 kbytes of static RAM

The MP-196 single-board computer has a $16-\mathrm{MHz} 80 \mathrm{C} 196 \mathrm{KC}$ microcontroller. It measures $4.5 \times 5.5 \mathrm{in}$. and supports 32 kbytes of EPROM and 28 kbytes of static RAM (SRAM). An optional page-mode feature supports 64 kbytes of EPROM and 56 kbytes of SRAM. The board has as many as three 8-bit parallel ports, two buffered serial ports, and one unbuffered serial port. An optional analog daughter board provides a 4-channel ADC and a 2 -channel DACboth have 12 -bit resolution. Two

27 C 128 EPROMs contain a system monitor and a Basic interpreter. The monitor can trace the execution of a user program and set as many as eight breakpoints. Using the board's serial link, you can save and load programs on a $5^{1 / 4}$-in. disk. Board, with user's manual, $\$ 125$; assembled and

tested board having 32 kbytes of EPROM and 28 kbytes of RAM, $\$ 500$.

Allen Systems, 2346 Brandon Rd, Columbus, OH 43221. Phone (614) 488-7122.

Circle No. 390

# EDN-NEW PRODUCTS 

Computers \& Peripherals



Color display station. The model TX600C features a $25-\mathrm{MHz} 68030 \mu \mathrm{P}$ for an X-Window CPU, a $40-\mathrm{MHz} 34020$ for a graphics CPU, and 6 Mbytes of RAM. Memory is upgradable to 37 Mbytes. A plug-and-play version comes with a $1280 \times 1024$-pixel, $19-\mathrm{in}$. monitor, keyboard, and mouse. A hot-key feature lets you switch between two screen presentations. Local client software connects to any host on the system. $\$ 5865$. Visual Technology Inc, 120 Flanders Rd, Westboro, MA 01581. Phone (508) 836-4400. FAX (508) 3664337.

Circle No. 391

GPIO adapter board. The Model 600 GPIO adapter board for the ISA bus connects to HP's Model 98622 GPIO bus. It provides 16 TTL input-data lines, 16 open-collector output-data lines, six handshake and control lines, and four general-purpose lines. The board operates with High Tech Basic software that lets you transfer data between workstations running HP Basic and DOS software. \$375. TransEra Corp, 3707 N Canyon Rd, Provo, UT 84604. Phone (801) 224-6550. FAX (801) 224-0355. TLX 296438. Circle No. 392

SCSI converter. The Parallel-SD10 converts single-ended SCSI-2 signals to differential SCSI-2 signals and vice versa. It handles $10-\mathrm{Mbyte} / \mathrm{sec}$ rates and is transparent to devices on the bus. The unit meets ANSI X3T9.2 standards for ports separated by as much as 102 ft . The stand-alone box has a wallmount power supply. Model SD10, $\$ 475$; Model SD11, \$285. Paralan Corp, 7171 Ronson Rd, San Diego, CA 92111. Phone (619) 560-7266. FAX (619) 5608929.

Circle No. 393

Dual-channel SCSI-2 adapters. The RF3590 and RF3870 are 9 U and 6 U , respectively, VMEbus SCSI-2 adapters. Two independent Fast SCSI-2
channels handle asynchronous and 10 Mbyte/sec synchronous data-transfer rates. The boards support both singleended and differential SCSI connections. Both models handle 8-, 16 -, and 32-bit data transfers on the VMEbus as fast as $30 \mathrm{Mbytes} / \mathrm{sec}$. From $\$ 3050$ (OEM qty). Ciprico Inc, 2955 Xenium Lane, Plymouth, MN 55441. Phone (612) 559-2034.

Circle No. 394

SPARCserver memory package. The CPSM-09A/S16-80 is a 16 -Mbyte memory package for Sun's SPARCserver $630 \mathrm{MP}, 670 \mathrm{MP}$, and 690 MP computers. The double-sided surface-mount package employs SOJ 16-bit dynamic RAMs. The package installs in Sun's 64 SIMM-slot (single-inline-memorymodule) memory-expansion board to provide as much as 1024 Mbytes of system memory. $\$ 6000$. Clearpoint Research Corp, 35 Parkwood Dr, Hopkinton, MA 01748. Phone (508) 435-2000. FAX (508) 435-7504. Circle No. 395


80386SX notebook computer. The NB913 Notebook PC contains a $20-\mathrm{MHz}$ 80386SX $\mu$ P, 2 Mbytes of RAM, and a $60-\mathrm{Mbyte}$ hard-disk drive. The RAM is expandable to 4 , 6 , or 8 Mbytes. The computer runs on DOS 4.01 and Windows 3.0 operating systems. A $10-\mathrm{in}$. black-on-white LCD screen has $640 \times$ 480 pixels and displays 64 levels of gray. Battery life is approximately 5 hours, and the unit weighs $7.7 \mathrm{lbs} . \$ 1999$. Micro Express, 1801 Carnegie Ave, Santa Ana, CA 92705. Phone (800) 9899900; (714) 852-1400. FAX (714) 8521225.

Circle No. 396

Laser printer. The QMS-PS 1700 intelligent laser printer serves as many as 20 users. It connects directly to either Ethernet or Token-Ring networks and supports DECnet, TCP/IP, Netware, or Ethertalk protocols. The printer has either $600 \times 600$ - or $300 \times 300$-dpi resolution and prints at 17 pages/minute. It comes with a 1000 -
sheet input tray and has a duty cycle of 50,000 pages/month. $\$ 7995$. QMS Inc, Box 81250, Mobile, AL 36689. Phone (205) 633-4300. FAX (205) 6330013.

Circle No. 397

GPS receiver. The GPStar device provides time and frequency with atomic accuracy by receiving the Universal Time Code (UTC) transmitted by Global Positioning System (GPS) satellites. It tracks as many as five satellites at a time and provides an accuracy of 100 nsec for UTC. The stand-alone unit accommodates long cable lengths by placing the down-converter near the antenna. It has an RS-232C port to download time data to a computer. $\$ 3995$. Odetics, 1515 S Manchester Ave, Anaheim, CA 92802. Phone (714) 7745000. FAX (714) 774-9432. Circle No. 398

Color Postscript printer. The G5241PS/4 prints Adobe Postscript images in Pantone licensed colors on A-size paper or overhead transparencies. The ther-mal-transfer printer has 300 -dpi resolution and 4 Mbytes of RAM. Standard interfaces include Appletalk, Centronics parallel, and RS-232C ports. $\$ 6990$. Océ Graphics Inc, Box 7169, Mountain View, CA 94039. Phone (415) 964-7900. FAX (415) 961-6152.

Circle No. 399


Plasma display. The model FPF20000 S is a stand-alone ac-memory plasma flat-panel display. The screen has 100 -dpi resolution on a 16 -in. diagonal viewing area. The $1280 \times 1024$-pixel display interfaces to Sun's SPARCstations. The monitor includes interface circuitry and an ac/dc converter in a chassis measuring $16.85 \times 12.56 \times 3.5$ in. The unit weighs approximately 14 lbs and has an operational life of 50,000 hours. $\$ 5000$. Fujitsu Microelectronics Inc, 3545 N First St, San Jose, CA 95134. Phone (800) 642-7616; (408) 9929000. FAX (408) 428-0640. Circle №. 400

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date, country of origin, subject, or key word or phrase. To use the product, you need a PC XT, MSDOS 3.0, and a CD-ROM drive. $\$ 2195$.
Document Engineering Co Inc, 15210 Stagg St, Van Nuys, CA 91405. Phone (800) 363-3647; (818) 782-1010. FAX (818) 782-2374.

Circle No. 407

Interactive math for VAX. Maple V for VAX/VMS is an interactive computer algebra system. A user interface for the X-Window system edits input expressions and maintains session logs. It also produces interactive 3-D color graphics. US $\$ 1395$. Waterloo Maple Software, 160 Columbia St W, Waterloo, ON, N2L 3L3, Canada. Phone (519) 747-2373. Girde No. 408

Real-time operating system. An optimized version of the OS-9 real-time operating system is now available for the Motorola MVME167 single-board computer. This latest version allows development of real-time software that uses all of the board's features, including onboard serial, SCSI, and Ethernet hardware. The software is available in two versions. The OS-9/167 Development Pak includes the OS-9/167 operating system and a full suite of development tools. A corresponding Run-Time Pak provides
only OS modules. The development version includes a Kernighan \& Ritchie C compiler, a macro assembler and linker, a user-state debugger, a screen editor, a shell-command interpreter, and utility programs. It also includes device drivers for next-generation I/O peripherals. These include SCSI drivers for the NCR 53C710 controller; the controller supports floppy and hard disks and tape units that use the Common Command Set. Microware Systems Corp, 1900 NW 114th St, Des Moines, IA 50322. Phone (515) 224-1929. Circle No. 409

Fuzzy-logic design tool. RT/Fuzzy aids the development and implementation of real-time software using rulebased logic. An extension of the supplier's family of tools for graphical modeling, system design, simulation, and code generation, it simulates and generates code for fuzzy-logic designs. Fuzzy
logic attempts to mimic imprecise human thinking by operating on IF-THEN statements that describe conditions and actions; it differs from conventional algorithms since all rules are based on qualitative information rather than a set of procedural equations. Software is available for Sun-4, SPARCstations, VAX, and HP workstations. From $\$ 5000$. Integrated Systems Inc, 3260 Jay St, Santa Clara, CA 95054 . Phone (408) 980-1500. Circle No. 410

VHDL tool set. Silicon 1076 offers a complete concept-to-silicon VHSIC hardware-description language, according to its developer. It lets you start at the architectural level, registertransfer level, or gate level and complete the design of an ASIC. It supports all of its developer's libraries. From $\$ 55,000$. LSI Logic, M/S D-102, 1551 McCarthy Blvd, Milpitas, CA 95035. Phone (408) 433-7161.

Circle No. 411

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## Reference guide for open systems.

 The World of Standards covers more than 75 standards from 19 organizations worldwide, such as CCITT, IEEE, and ANSI. The first section describes the standards individually and lists the organization that developed each one. The second section discusses the various organizations in detail. 88open Consortium Ltd, 100 Homeland Ct, Suite 800, San Jose, CA 95112. Phone (408) 436-6600. Circle No. 401VXIbus product catalog. This publication introduces more than 30 VXI modules, including analog and digital I/O, monitors and controllers, signal conditioners, and ARINC-429 and MIL-STD1553 interfaces. It discusses VXIbus data-acquisition systems that you configure using the National Instruments' VXIpc-386 PC/AT and VXIpc-030 68030 embedded computers. KineticSystems 11 Maryknoll Dr, Lockport, IL 60441. Phone (815) 838-0005.

Circle No. 402

Test equipment cataloged. The $40-\mathrm{pg}$ catalog describes and illustrates recording systems, oscilloscopes, analog and digital snap-arounds, digital multimeters,
data-logging digital multimeters, and many related devices. The alphanumeric table of contents lists products by model number. AW Sperry Instruments Inc, Box 9300, Smithtown, NY 11787. Phone (516) 231-7050.

Circle No. 403

Data sheet for $10 \times$ coplanar microprobe. This data sheet presents the $10 \times$ coplanar microprobe that's designed to allow internal node probing of multichip modules, mixed-signal hybrids, microwave hybrids, and high-density SMT assemblies. It provides a listing of features and specifications, as well as graphs and diagrams, illustrating performance and verification. Cascade Microtech Inc, Box 1589, Beaverton, OR 97075. Phone (503) 626-8245.

Circle No. 404

Brochure on microcontroller family. This 6-pg foldout deals with the H8/500 family of 8 - and 16 -bit microcontrollers. In addition to describing and illustrating the products and their features, the brochure presents a listing of specifications. Hitachi America Ltd, Semiconductor \& IC Div, 2000 Sierra Point Pkwy, Brisbane, CA 94005. Phone (415) 589-8300. Circle No. 405

Test-and-measurement-product catalog. The Tek Direct Catalog emphasizes that the test-and-measurement equipment listed in this publication is "affordable." It lists meters, handheld and low-end portable oscilloscopes, probes, plotters, accessories, and training aids. The "Tek Tips" section provides helpful hints and suggestions for solving common test-and-measurement problems. Tektronix Inc, Tek Direct, Box 1520, Pittsfield, MA 01202.

Circle No. 406

## Brochure of electrostatic plotters.

This 8-pg publication discusses largeformat electrostatic plotters: the monochrome Model 67436 and the color 68000 Series. It describes the plotters' accuracy and line quality, area and color-fill capabilities, connectivity, and memory options. The brochure provides drawings for applications, such as architecture, mechanics, and IC design; solids modeling; mapping; and graphic arts. Calcomp Inc, 2411 W La Palma Ave, MS 52, Anaheim, CA 92801. Phone (800) 932-1212; (714) 821-2000. FAX (714) 821-2714.

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## EDN-ACRONYMS \& ABBREVIATIONS

AA-a size of nonrechargeable and rechargeable cell
ACE-Advanced Computing Environment, an industry consortium
ADC-analog-to-digital converter
ALU-arithmetic and logic unit
C-a size of nonrechargeable and rechargeable cell
CMOS-complementary metal-oxide semiconductor
CPI-cycles per instruction
CPU-central processing unit
CRT-cathode-ray tube
CSA-Canadian Standards Association
DAC-digital-to-analog converter
DMA-direct memory access
DMM-digital multimeter
DSO-digital storage oscilloscope
DSP-digital signal processing
ENOB-effective number of bits
FFT-fast Fourier transform
FPU-floating-point unit
I/O-input-output
IC-integrated circuit
IEEE-488-The Institute of Electrical and Electronics Engineers' standard for communication with test instruments
ISA-the Industry Standard Architecture I/O bus of IBM PCs and compatible computers
ISSCC-International Solid-State Circuits Conference
LCD-liquid-crystal display
LSB-least significant bit
MESI-modified, exclusive, shared, or invalid, a cachecoherency protocol
MIPS-million instructions per second


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MMU-memory-management unit
NiCd—nickel cadmium, a type of rechargeable cell and rechargeable battery
p-n junction-the region of transition between p-type and n-type material in a single semiconductor crystal
p-p-peak-to-peak
PAX—parallel architecture extension
PC-personal computer
pc board-printed-circuit board
PGA—pin-grid array
ppm-part per million
RAM—random-access memory
RISC—reduced-instruction-set computer
rms-root-mean-square
RS-232C-an Electronic Industry Association standard for serial data communication, popular in PCs
S/H-sample and hold
S/N ratio-signal-to-noise ratio
SFDR-spurious-free dynamic range
SIMM-single in-line memory module
SINAD-signal to noise and distortion
TC-temperature coefficient
T/H-track and hold
THD-total harmonic distortion
3-D-three-dimensional
TLB-translation look-aside buffer
UL-Underwriters' Laboratories Inc

This list includes acronyms and abbreviations found in EDN's Special Report, Technology Updates, and feature articles.

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| IF-2-16 | 2VA | 16Vct. @ 125mA | 8 V @ 250 mA |  |
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| IF-2-40 | 2VA | 40Vct. @ 50mA | 20V@100mA |  |
| IF-2-56 | 2VA | 56Vct. @ 40mA | 28 V @ 80 mA |  |
| IF-2-230 | 2VA | 230Vct. @ 9mA | 115 V @ 18mA |  |
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| IF-10-16 | 10VA | 16Vct. @ 625mA | 8V @ 1.25A |  |
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| IF-30-16 | 30VA | 16Vct.@ 1.90A | 8V@3.80A |  |
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| IF-30-34 | 30VA | 34 Vct @ 900 mA | 17V@1.80A |  |
| IF-30-40 | 30VA | 40 Vct @ 750 mA | 20V@ 1.50A |  |
| IF-30-56 | 30VA | 56 Vct @ 550 mA | 28V@ 1.10A |  |
| IF-30-230 | 30VA | 230Vct. @ 130mA | 115 V @ 260mA |  |




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|  | 67.6 mm | 57.0 mm | 22.2 mm | 62.5 mm | 50.0 mm | 0.29 kg |
| 30 | $2.68^{\prime \prime}$ | $2.26^{\prime \prime}$ | $1.39^{\prime \prime}$ | $2.46^{\prime \prime}$ | $1.97^{\prime \prime}$ | 19.7 oz |
|  | 68.0 mm | 57.5 mm | 35.3 mm | 62.5 mm | 50.0 mm | 0.58 kg |

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[^12]:    The amplitude of the output signal and the value of dc offset will both decrease because the probe resistance forms a divider network with the source resistance of the device under test.

[^13]:    $N A=$ Not applicable.

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[^16]:    NORTH AMERICA: P.O. Box 7643, Mt. Prospect, IL 60056-7643 (Tel: 1800628 7364, ext. 143; Fax: 1800888 5113); EUROPE: Industriestraße 10, D-8080 Fürstenfeldbruck, Germany (Tel: 498141103 0; Fax: 498141103 515); HONG KONG: 15th Floor, Straight Block, Ocean Centre, 5 Canton Rd., Tsimshatsui, Hong Kong (Tel: 8527371654 ; Fax: 8527369921 ); JAPAN: Sanseido Building 5F, 4-15-3, Nishi-shinjuku, Shinjuku-ku, Tokyo, Japan 160 (Tel: 81332997001 ; Fax: 81332997000 ).

[^17]:    INSTRUMENTS

