

ELECTRONIC TECHNOLOGY FOR ENGINEERS AND ENGINEERING MANAGERS

Special Report:
Achieve blazing data transit with FDDI ${ }_{\text {pg } 88}$

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On the cover: Light traveling along fiber-optic highways lets FDDI (Fiber Distributed Data Interface) LANs transmit data at 100 Mbps . See our Special Report on pg 88. (Photo courtesy Interphase Corp)

## SPECIAL REPORT

## FDDI stations

Increasing network demands are straining the throughput of first-generation LANs. To meet high-performance requirements, network designers are starting to adopt the $100-\mathrm{Mbps}$ Fiber Distributed Data Interface (FDDI). Unfortunately, FDDI stations don't come cheap.-John Gallant, Associate Editor

## DESIGN FEATURE

## EDN's DSP-chip directory

The tools needed to develop applications that use digital signal processing (DSP) continue to improve. Now, a choice of operating systems and interfaces to host operating systems is making DSP available to more applications.-David Shear, Contributing Editor

## TECHNOLOGY UPDATES

## SCPI instruments will ease ATE development

Engineers who want to minimize test-system development time and maximize system flexibility should use SCPI instruments whenever possible.-Maury Wright, Regional Editor

## Serial EEPROMs: Serial memory offers cheap frills

 57You don't need a byte-wide interface or large devices to add a little nonvolatile memory to your system. Serial EEPROMs are an inexpensive option that offer a few extras.
-Richard A Quinnell, Regional Editor
Continued on page 7

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It's all a part of our innovative sell-design-build business philosophy. To identify our customer's needs sooner. Then
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## VME BOARD TOPS 1.1 BOPS PERFORMANGE

A single V-C40 VME board from Ariel Corp sets a VME peak-performance mark-as much as 1.1 billion operations per second (BOPS). Additionally, it can move data at rates as high as 1.3 Gbytes $/ \mathrm{sec}$. The 6U VME board holds as many as four TI TMS320C40 32-bit floating-point DSP processors along with as much as 64 Mbytes of local dynamic RAM, and 8 Mbytes of static RAM ( 2 Mbytes per CPU). You can hook up processors and multiple boards in a number of multiprocessing configurations. Each board has six special byte-wide DMA communications ports, three of which are brought off board for 12 communications links, each capable of moving $20 \mathrm{Mbytes} / \mathrm{sec}$. The board has a proprietary 24 -bit bus for linking to analog converter cards. The board functions as both a VME bus master and slave and costs $\$ 20$ per million operations. Ariel Corp, Highland Park, NJ, (908) 249-2900, FAX (908) 249-2123.-Ray Weiss

## PALM-SIZE INDUSTRIAL PC OPERATES FROM - 40 TO $\mathbf{+ 8 5}^{\circ} \mathbf{C}$

Suitable for use in rugged environments that present extreme temperatures, the 5012 Micro PC needs no keyboard, monitor, or disk drives to operate. With DOS embedded in its ROM, this computer includes two 512-kbyte solid-state data-storage locations that you can populate with RAM and EPROM. Housed on a pc-board, the computer comes with a built-in EPROM programmer, 1 Mbyte of dynamic RAM that you can expand to 2 Mbytes, a watchdog timer, battery backup for RAM, and a battery-backed calendar/clock. This board also contains ports for a printer, a keyboard, a speaker, and two serial ports. The basic board costs $\$ 495$, and you can order enclosures starting at \$45. Octagon Systems Corp, Westminster, CO, (303) 430-1500, FAX (303) 426-8126.-J D Mosley

## MULTIPLY-ACCUMULATE UNIT ENHANCES SERVO CONTROLLER

An embedded multiply-and-accumulate unit (MAU) highlights a range of features of the HPC46100 16-bit microcontroller from National Semiconductor. Running off a $40-\mathrm{MHz}$ system clock, the MAU provides 32 -bit results from 16 -bit, signed-integer multiply-and-accumulate operations in 400 nsec . Peripheral functions such as an 8 -bit ADC with $5-\mu \mathrm{sec}$ conversion, three independent timers with separate frequencyand duty-cycle control registers, a programmable UART, and 1 kbyte of onboard RAM tailor the microcontroller to such embedded servo applications as found in automo-tive-chassis and hard-disk drive control. The ADCs convert as many as eight singleended channels or four differential-channel pairs. You can trigger the converters for single readings, or you can perform these operations continuously. Eight dedicated registers let you store single-channel data for average reading calculations. The onboard UART can operate in synchronous or asynchronous modes and offers multiple character widths and stop bits, status reporting, error detection, an addressing mode, and diagnostic testing. The $\mu \mathrm{C}$ is upward-source-code-compatible with the HPC family of controllers and includes such other features as watchdog logic, vectored interrupts, and HALT and IDLE power-down modes. Available development tools for the $\$ 23$ ( 1000 ), $14 \times 14-\mathrm{mm}, 80$-pin device include a development system, serial hook hardware, logic-analyzer interface board, HP logic-analyzer disassembler, and cross-development system. The device comes in a plastic quad flatpack. National Semiconductor, Santa Clara, CA, (408) 721-5185.-Michael C Markowitz

## NEWS BREAKS

## COLOR PANFL-MOUNT DISPLAY INCLUDFS 80386SX PC

Computer Dynamics's Color Displaypac includes an IBM PC-compatible 80386SX single-board computer and a color LCD with infrared touch screen in a panel-mount package. The integrated package measures $11.5 \times 8.5 \times 2 \mathrm{in}$., and the display screen is 10.4 in . wide. The display provides VGA color graphics and includes a fluorescent backlight. The single-board computer includes as much as 4 Mbytes of dynamic RAM, two RS-232C serial ports, keyboard and printer ports, and hard- and floppy-disk interfaces. The computer can boot MS-DOS from an onboard RAM/ROM disk. A configuration with 1 Mbyte of memory and a $16-\mathrm{MHz} \mu \mathrm{P}$ costs $\$ 6174$. Computer Dynamics, Greer, SC, (803) 877-8700, FAX (803) 879-2030.-Maury Wright

## MPLD COMBINES AS MANY AS 40 ALTERA FPLDS

Altera's Mask-Programmable Logic Device (MPLD) can replace as many as 40 of the company's erasable programmable logic devices (EPLDs) or up to 700 of its macro cells. Offered as a synthesis service, the company will take EPLD designs at the netlist level and synthesize them into a single mask-programmed device. The company guarantees results from working designs using EPLD circuits, letting engineers prototype, and even put out as initial products, EPLD-based designs. For size reduction, they can then have the design reduced to a single, foundry-programmed maskbased chip. The conversion process is automated and the company will guarantee layout timing as well as $95 \%$-or better-fault coverage for supplied test vectors. Prototypes will be delivered within 6 weeks of receipt of the design. The cost is $\$ 0.06$ per macro cell for production units; $\$ 20,000$ to $\$ 60,000$ for design conversions (NRE). Production units are delivered within 10 to 12 weeks. Initially, Classic and MAX 5000 EPLDs are covered, with MAX 700 devices added by the fourth quarter of 1991. Altera Corp, San Jose, CA, (408) 984-2800, FAX (408) 435-1394.-Ray Weiss

## SOLID-STATE RELAYS SUIT LOW-CURRENT APPLICATIONS

The LH1500 family of <1A solid-state relays from AT\&T Microelectronics each comprise a photodiode array, various switch control circuits, and DMOS switches. The relays use an LED for actuation control and an IC for the switch output. The family consists of 21 products, ranging in price from $\$ 1.25$ to $\$ 4.75$ (1000) and includes all the common switch forms: normally open, normally closed, and combinations of each. Each relay features 3750 V of isolation, thereby meeting European standards and exceeding US standards. The relays are constructed on a dielectrically isolated process, which provides for breakdown voltages between 140 and 440 V . Typical on-resistance varies from 2 to $23 \Omega$. Special features of some of the relays include current limiting, make-before-break switching, and dual packaging. The relays come in either 6- or 8 -pin DIPs or surface-mount gull-wing packages. Sample quantities are available now; production quantities will be available by the fourth quarter of 1991. AT\&T Microelectronics, Allentown, PA, (800) 372-2447.-Anne Watson Swager

## CMOS PLDS ACHIEVE 7.5-NSEC SPRED

Intel Corp's faster versions of its $\$ 10$ 85C244 24-pin and $\$ 6.10$ (1000) 85C220 20-pin PLDs have programmable I/O structures, letting them emulate a variety of 20- and 24-pin PLD architectures. They have a $7.5-\mathrm{nsec}$ input-to-output propagation delay and support clock frequencies as great as 74 MHz using external feedback. The parts consume 105 mA at maximum operating frequency and come in plastic leaded chip carriers. Intel Corp, Santa Clara, CA, contact local sales office.-Richard A Quinnell

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Of course, we provide comprehensive support with the industry's best-rated documentation,*", complete systems integration support and technical assistance.
CPU-40 PERFORMANCE CHARACTERISTICS

| Data from | CPU | CPU | CPU | CPU | VMEbus | SCSI* | Floppy Disk* | Ethernet* | Shared <br> RAM ${ }^{*}$ | VMEbus. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Transter to | Shared RAM | EPROM | Serial I/O <br> Timers | SCSI. <br> Ethernet Controller. Floppy Disk | Shared <br> RAM | Shared <br> RAM | Buffer RAM | Dual-port RAM | VmEbus | VMEbus |
| Transter Speed | 53.7 <br> MB/sec | 16 <br> MB/sec | $\begin{aligned} & 2 \\ & \mathrm{MB} / \mathrm{sec} \end{aligned}$ | $\begin{aligned} & 2 \\ & \mathrm{MB} / \mathrm{sec} \end{aligned}$ | 5 MB/sec | 4 $\mathrm{MB} / \mathrm{sec}$ | 500 <br> KBit/sec | 10 <br> MBit/sec | 15 $\mathrm{MB} / \mathrm{sec}$ | 15 $\mathrm{MB} / \mathrm{sec}$ |
| Local 68040 <br> CPU <br> Operation | 100\% | 100\% | 100\% | 100\% | 70\% | 80\% | 100\% | 100\% | $75 \%$ | 100\% |

So be the first in your company to turn 040. Call 1-800-BEST-VME, ext. 40, for more information or fax a request to (408) 374-1146 for an immediate response.

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CIRCLE NO. 11


## People say boundary inlow cost,highquality Now you can test that



Increasing device complexity. Rising pattern development costs. High density packaging. Disappearing nodal access. These are the board test problems boundary scan was created to solve. Which is fine in theory. Only problem is there hasn't been any way to put boundary scan to the test. Until now.

VICTORY- the first software to automate boundary-scan testing.

Introducing VICTORY ${ }^{\text {th }}$ from Teradyne: the only software toolset ready to help you turn boundary-scan theory into a practical advantage. From the moment your first boundary-scan device is designed in, VICTORY starts
to simplify the testing of complex digital boards. And the more bound-ary-scan parts you have, the more time and money you save.


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Whether you're testing one boundary-scan part or boundary-scan networks, VICTORY software automatically gives you $100 \%$ pin-level fault coverage. Using the IEEE 1149.1 and BSDL standards, it takes VICTORY only a minute or two to generate test patterns. It would take a programmer days, even weeks to deliver the same fault coverage for conventional designs.

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# scanisabreakthrough board testing. <br> <br> theory. 

 <br> <br> theory.}
feedback you need to eliminate defects where it's most cost-effective-at the source.

Helps solve the test access problem.
With boundary-scan design and VICTORY software, you won't need bed-of-nails access on nodes where boundary-scan parts
are interconnected. That means fewer test pads. Fewer test probes.


That's
a compelling advantage to board designers. Which is why VICTORY's Access Analyzer was developed. With this concurrent engineering tool, designers get testability information early in the design process. They can easily see where test points are required for visibility and where they can be dropped, for opti-
mized board layout without lowering fault coverage.

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Boundary-Scan Intelligent Diagnostics identify faults by type and location without physical probing - even on high-density SMT assemblies

Shorter test programming time. Higher fault coverage. Lower PC board and test fixture costs. The bottom line on VICTORY is how positively it will affect your bottom line. And because VICTORY works with all Teradyne board testers, you're free to tailor a test process that's cost-effective for both your boundaryscan and non-scan boards. No matter what your test objectives. For example, with our new Z1800VPseries testers, a complete solution for in-circuit and boundary-scan testing starts at well under $\$ 100,000$.

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## SIGNALS \& NOISE

## Juggling equation for better solution

Just as my subscription to EDN is reinstated, Peter Anderson shocks me with the equation on pg 31 of EDN (May 23, 1991), [which uses N to characterize a triode]. For example, the dual triodes 12AU7, 12BH7, and 5687 all have values of a $\mu$ of 20 , but only one may work properly in a circuit.
The value of $\mu$ is the ratio of $\mathrm{g}_{\mathrm{m}} \cdot \mathrm{MDSU} / \cdot \mathrm{MDNM} /$ to $\mathrm{g}_{\mathrm{p}}$ or the product $g_{m} \mathrm{r}_{\mathrm{p}}$. You can double $\mathrm{g}_{\mathrm{m}}$ and $\mathrm{g}_{\mathrm{p}}$ or halve $\mathrm{r}_{\mathrm{p}}$ by doubling the plate current, and the $\mu$ is unchanged. The point is that using the smallsignal equation

$$
\mathrm{I}_{\mathrm{p}}=\mathrm{g}_{\mathrm{m}} \mathrm{~V}_{\mathrm{g}}+\mathrm{g}_{\mathrm{p}} \mathrm{~V}_{\mathrm{p}}
$$

where $I_{p}$ is plate-current change and $V_{g}$ and $V_{p}$ are voltage changes, [would make a better basis for a Spice model.] The equation is related to the equation noted by Peter Anderson, but expresses the operating characteristics of a tube, a bipolar, or a FET device in a much more useful form. The above equation expresses the way we have to operate a [tube,] anyway. We set the plate current, then adjust the bias voltage with degeneration as needed to give that plate current.
Keats A Pullen Jr, PE
Kingsville, MD

## Engineer should look for higher paying job

The author of the letter "Engineers' salaries should be professional" (EDN, March 14, 1991, pg 26) suggests that, as a member of the engineering profession, he ought, by that very fact, to be paid a commensurate salary.
The thought is very lofty, but the fact of the matter is that salaries, like most economic matters, are ultimately a question of supply and demand. I really can't imagine a doctor or a lawyer saying, "Gee, guys, I'm a professional. You ought to pay me more."

If you feel you are worth more, then put it on the line and look for a higher paying job. Finally, your salary is a measure of your own capabilities combined with your marketing ability. The professionalism of the engineering profession has nothing to do with it.
Ted Ruel
Controls Inc
Logansport, IN

## Battery of tests showed his true learning skills

I appreciated Charles Small's editorial, "Intelligences theory reshapes thought" (EDN's Software Engineering Special Supplement, June 20, 1991, pg 9). His article proves to be profoundly true in my case. I thought I was stupid until I received the results of a battery of tests in the Navy that showed I was not stupid-I just couldn't spell!

Engineers are a unique bunch who, if they cannot spell, will conceptualize, innovate, and design a software program to do it for them.
Charles Cutler
Bear Medical Systems Inc
Riverside, CA

## Phone number changed

The phone number for Information Storage Devices Inc (EDN, July 4, 1991, pg 93) has been changed. The new number is (408) 428-1400.

## NEXT IN EDN October 3

Look to EDN News Edition's October 3 issue for a Product Watch on ICs for automatic test equipment and a Career Opportunities article on multimedia.

## More answers. Every week in EDN.

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| The 90 <br> An Exhaustive Look At High Tech <br> Training Equipment | Virtual Reality <br> Close But No Cigar |




How Fast Is A Flash?
A Direct Comparison

| Density | AMD | Fastest Competitor |
| :---: | :---: | :---: |
| 256 K | 90 ns | 120 ns |
| 512 K | 90 ns | 120 ns |
| 1 Mbit | 90 ns | 120 ns |
| 2 Mbit | 90 ns | 150 ns |

SUNNYVALE - The computer industry takes a giant leap forward in performance with the help of the new Flash memory family from Advanced Micro Devices, Inc.

Flash memory is a high-density, reprogrammable, non-volatile technology that has a bright future in computation, laserprinters, network and telecommunications hardware. Many military systems use Flash tectmology in radar and navigational applications.

Flashmemoryalsohas the potential to eliminate mechanical hard disks and the need for cumbersome batteries. These are twoof the biggest and heaviest obstacles in laptop and notebook computer applications.

Today, Flash memory is the most cost effective replacement technology for UV EPROMs and EEPROMs in applications that require in-system applications that require in-system
programming. Flash memories can programming. Flash memones can
literally be reprogrammed in a flash -
hence the name.
Standard, But With A Little More Flast
AMD's Flash memory famil effectively etches in silicon the de-fact standard for this burgeoning technolog that is compatible with Intel's initic Flash architecture.

Because AMDFlash memories an pin-for-pin compatible with the nov standard architecture, AMD i positioned as an altemate source fo design engineers and purchasing agent: alike.
"Alternate source may be ar inadequate term," said Jerry Sanders chairman and CEO of Advanced Micro Devices. "Given our speed and feature set, ourcustomersthink of us as a superior resource,"

Indeed, AMD's Flash memory amily offers designers significant performance advantages (see chart), with speeds almost twice as fast as the nearest competitor.

## Engineer Spontaneously Comburcta At Mantina



FOOD

## Chips And Salsa <br> A Business Person's Guide To Silicon Valley PAGE 7F

## MORNING EDITION

## ASHES! Megabit,90ns, Memories


#### Abstract

The AMD Flash family offers denghers and purchasers many packaging options. Particularly popular AMD s advanced 2 Megabit PLCC par, Other packaging options include PDIP, CDIP and LCC in $256 \mathrm{~K}, 512 \mathrm{~K} .1$ Mbit and 2 Mbit capacities. TSOP packages will be available in the second half of this year. (LCC not currently

AMD 2 Mbit.) anem memories and eomplee withembedded program drase algorithms on board. These procestatgorithms speedupthedesign process and considerably shorten time required to Previously, engineers were consuming algorithms toimple time system reparamailislement inatomate AMD's Flash mengorimms a soallow several -ine monies to be written or erased解基, without tying-up the CPU. The ystem is now free to perform other asks while these operations are progress. AMD plans to include embedded algorithms in a future release The Ultro Flash suited to particularly reprogramming in place, because the devicescanbereprogrammed inseconds and within the system.

To update the c EPROM, the par must firs ber from the system. Oncerembe removed can take up to a full 20 moved,erasure reprogramming ull 20 minutes. After back into thg, the part is then plugged result io the systern. The process can costly damage to other components. Hervice calls, and headaches Fash memories, on the other hand, can be buik erased in about one to two seconds, without system disassembly. accomplishedving can then be lines, or even ISDN (continued)


Stop the presses!
Advanced Micro Devices makes big news again-this time with an enhanced family of Flash memory devices.

That's good news for veteran and new Flash users alike.

Because our Flash devices are pin-for-pin compatible with Intel's existing Flash memory architecture, they establish the de facto industry standard.

Our standards, however, are a bit higher. And so are yours.
That's why our Flash Memory family offers densities, speeds and packaging options that improve performance and save board space. For instance, our advanced 2 Mbit PLCC part with a scant 90 nanosecond delay.

You can also choose from Flash devices in $256 \mathrm{~K}, 512 \mathrm{~K}$ and 1 Mbit densities. As well as packaging options that fit your design best, including CDIP, PDIP, LCC, TSOP, and PLCC.

And you'll find implementation faster and easier than ever, because we've included automatic programming algorithms on all our 2 Mbit devices, and soon on our 1 Mbit parts, too. So you'll spend less time writing code, and take less time getting products to market.

To keep up to date with all the latest and greatest in Flash memory, call AMD today at $\mathbf{1 - 8 0 0 - 2 2 2 - 9 3 2 3}$. And start making some headlines of your own.

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## National's Linear Circuit

## Sept. 25 Palo Alto, CA

Sept. 26 Newark, CA Sept. 30 Montreal, QC Oct. 1 Boxborough, MA Oct. 2 Rochester, NY Oct. 3 Edison, NJ Oct. 4 Ft. Washington, PA Oct. 7 Schaumburg, IL Oct. 8 Ft. Wayne, IN Oct. 9 Dearborn, MI Oct. 10 Toronto, ON Oct. 11 Minneapolis, MN Oct. 14 Orlando, FL
Oct. 15 Reston, VA Oct. 16 Linthicum, MD Oct. 17 Newton, MA
Oct. 21 Longmont, CO Oct. 22 Houston, TX

## Oct. 23 Austin, TX

Oct. 24 Richardson, TX
Oct. 25 La Jolla, CA Oct. 28 Cleveland, OH Oct. 29 Indianapolis, IN Oct. 30 Dayton, OH Oct. 31 Dearborn, MI Nov. 1 Schaumburg, IL Nov. 4 Englewood, CO Nov. 5 Scottsdale, AZ Nov. 6 Woodland Hills, CA Nov. 7 Los Angeles, CA Nov. 8 Costa Mesa, CA Nov. 12 Burnaby, BC Nov. 13 Bellevue, WA Nov. 14 Beaverton, OR Nov. 15 San Jose, CA

| National's Linear |  |  |  |
| :--- | :--- | :--- | :--- |
| Sept. 25 | Palo Alto, CA | Oct. 23 | Austin, TX |
| Sept. 26 | Newark, CA | Oct. 24 | Richardson, TX |
| Sept. 30 | Montreal, QC | Oct. 25 | La Jolla, CA |
| Oct. 1 | Boxborough, MA | Oct. 28 | Cleveland, OH |
| Oct. 2 | Rochester, NY | Oct. 29 | Indianapolis, IN |
| Oct. 3 | Edison, NJ | Oct. 30 | Dayton, OH |
| Oct. 4 | Ft. Washington, PA | Oct. 31 | Dearborn, MI |
| Oct. 7 | Schaumburg, IL. | Nov. 1 | Schaumburg, IL. |
| Oct. 8 | Ft. Wayne, IN | Nov. 4 | Englewood, CO |
| Oct. 9 | Dearborn, MI | Nov. 5 | Scottsdale, AZ |
| Oct. 10 | Toronto, ON | Nov. 6 | Woodland Hills, CA |
| Oct. 11 | Minneapolis, MN | Nov. 7 | Los Angeles, CA |
| Oct. 14 | Orlando, FL | Nov. 8 | Costa Mesa, CA |
| Oct. 15 | Reston, VA | Nov. 12 | Burnaby, BC |
| Oct. 16 | Linthicum, MD | Nov. 13 | Bellevue, WA |
| Oct. 17 | Newton, MA | Nov. 14 | Beaverton, OR |
| Oct. 21 | Longmont, CO | Nov. 15 | San Jose, CA |
| Oct. 22 | Houston, TX |  |  |
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[^3]
## More diagrammatic programming tools for engineers



Little known or appreciated outside the world of tool and die makers, machine tools were nevertheless crucial to industrial development. Now, engineering software assumes the crucial role of the machine tool of the next industrial revolution.
Engineering software is too important and too different from ordinary software to be left solely to programmers. Give a carpenter a problem, and he thinks of solving it with hammers and nails. Give a programmer a problem, and he thinks of solving it with written-out lines of code. Unfortunately, engineers do not think or express themselves in terms of language. Instead, they use visual symbols.

Although we associate programming with text files, that association is not a fundamental given. In reality, programmers' fixation on text is an artifact of the teletypewriter output of early computers. Today, textual programming is no longer mandatory; even inexpensive computers can handle complex graphics and symbols. Few good software tools take advantage of these capabilities to let engineers construct programs visually.
Proponents of textual ASIC and FPGA software tools say that the increasing complexity of today's devices is forcing engineers to abandon diagrammatic systems for textual ones. This false imperative rests on an unproven foundation. Text is not inherently more comprehensible, lucid, compact, and rigorous than diagrams are. Few developers seem to consider the possibility that more complex devices may lead to more powerful diagrammatic design systems.

Good engineers are in the 99th percentile for spatial ability, and good programmers are in the 99th percentile for linguistic ability. Thus, we often find software kluges masquerading as tools that let users mix textual and diagrammatic design. Such tools best suit designers who are exceptional in both spatial and linguistic areas, and not enough such people are available to do all the engineering that needs to be done.
Therefore, everyone who has a hand in developing software tools for engineers should become familiar with Harvard researcher Howard Gardner's Theory of Multiple Intelligences. Gardner has written several popular books on the subject, and his theories provide the scientific underpinning for the notion that engineers need visual-not textualdesign tools. Engineering-tool companies need to research the mental activity of creative engineers and then develop new visual metaphors that support the ways engineers think.


Charles H Small Senior Editor

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2. Gardner, Howard, "The Mind's New Science: A History of Cognitive Revolution," Basic Books, New York, NY, 1987. ISBN 0-465-0435-5.

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Engineers who want to minimize test-system development time and maximize system flexibility should use SCPI instruments whenever possible.

Maury Wright, Regional Editor

# SCPI instruments will ease ATE development 

The SCPI (Standard Commands for Programmable Instruments, pronounced "skippy") standard promises to simplify the programming of automatic test systems. Companies complying with the standard will ensure that similar instruments from different manufacturers have similar command languages. Thus, a programmer would need to learn how to program a voltmeter, frequency counter, or other instrument only once.
Most major instrument makers plan to use SCPI in all their new products. SCPI-compatible GPIB (General-Purpose Instrument Bus) and VXIbus test instruments have started to ship, but most types of SCPI instruments are still scarce. If you can find a SCPI version of a test instrument that you need now, buy it. SCPI compliance should be a determining factor when you choose instruments for a test system, and SCPI products cost the same as their non-SCPI counterparts.
The SCPI standard defines an extensible command language for the remote control of instruments. The language was developed independently of the front-panel terminology specific to individual instruments. The language uses a consistent style and English-like mnemonics, both of which make the language readable and easy to use. For example, the following command will read the de voltage from any SCPI instrument that can measure voltage:

MEASure:VOLTage:DC?

The language's keywords can be written out in full or abbreviated to the 3- or 4 -character strings indicated by the capital letters. Strings of keywords make up SCPI commands.

The creators of the SCPI standard sought to develop a language that offered what they termed vertical, horizontal, and functional compatibility. Vertical compatibility means that two instruments of the same generic instrument type, such as two digital oscilloscopes from different manufacturers, will have compatible command sets. A


The SCPI VXIbus arbitrary waveform generator from Hewlett-
Packard, the $\$ 8000$ E1445A, is one of a variety of HP instruments
The SCPI VXIbus arbitrary waveform generator from Hewlett-
Packard, the $\$ 8000$ E1445A, is one of a variety of HP instruments that comply with the SCPI standard.
single software driver could control either instrument.

Horizontal compatibility refers to a situation in which two different types of instruments can perform the same measurement. For example, both frequency counters and digital oscilloscopes can measure the frequency of a signal. The horizontal-compatibility goal mandates that the same frequencymeasurement command will properly instigate a frequency measurement in either type of instrument.

Functional compatibility refers to the

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## TECHNOLOGY UPDATE

## The SCPI standard

compatibility of specific features in different types of instruments. For example, the same frequency and sweep commands can control a spectrum analyzer and a RF source because both types of instruments can sweep in frequency.

## SCPI allows instrument updates

Designers who use SCPI-compatible instruments exclusively will realize several benefits. First, updating an ATE (automatic-testequipment) system with the best voltmeter available will require minimal changes in system and test software. Second, the time required to develop software for new ATE systems should drop because SCPI leads to reusable code. Third, programmers will be more efficient when using SCPI instruments because of the three types of compatibility and the fact that the language is easy to read and consistent in style.

SCPI poses no larger challenge to the first-time user than do the one-of-a-kind command sets currently common in instruments. Senior Electronics Engineer Mike Hanus of Sundstrand Power Systems

Table 1-INPut subsystem commands

| Keyword | Parameter form |
| :---: | :---: |
| INPut |  |
| :ATTenuation | <numeric value> |
| :AUTO | < Boolean > ONCE |
| COUPling | AC\|DC |
| :FILTer |  |
| [:LPASs] |  |
| [:STATe] | <Boolean> |
| :FREQuency | <numeric_value> |
| :HPASs |  |
| [:STATe] | <Boolean> |
| :FREQuency | <numeric_value> |
| GAIN | <numeric_value> |
| :AUTO | <Boolean > ONCE $^{\text {a }}$ |
| :GUARd | LOW\|FLOat |
| IMPedance | <numeric value> |
| :LOW | FLOat\|GROund |
| [:STATe] | <Boolean> |

(San Diego, CA) recently worked with a SCPI instrument for the first time. Hanus replaced a test set's programmable power source with a SCPI version. He reports that the software driver for the new source took no longer to write than did the original driver and that he wouldn't have had to write a new driver had the first source been SCPI compatible. Hanus says the experience has prompted him to write more modular code with the goal of reusing portions of his code for SCPIcompatible instruments.

The SCPI standard is independent of any physical interconnection specification. You will most often hear the term SCPI associated with VXIbus-based instruments and instruments that use the GPIB defined by the IEEE-488.1 specification. But SCPI works equally well on instruments connected to a controller via an RS-232C serial interface or any other interface.

Although the SCPI standard doesn't specify a physical interface, it does mandate the use of features defined in the IEEE-488.2 specification. The IEEE-488.2 standard defines controller functions, data formats, and status reportingbasically a common set of housekeeping commands for instruments. (See Ref 1 for more information on the IEEE-488.2 specification.)

Alan Hoffman, director of engineering at IOtech, points out that SCPI offers a way for manufacturers to standardize the commands used for board-level PC instruments. IOtech offers a line of GPIB controller cards for IBM PCs. The Power488 and Power488CT cards also feature SCPI-compatible test-and-measurement capabilities. The


Fig 1-The generic instrument model depicted here guided the development of the tree-structured SCPI standard.

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Power488 costs $\$ 495$ and includes 40 digital I/O lines in addition to the GPIB controller and driver software. The $\$ 595$ Power488CT adds counter/timer features.

SCPI's creators based the language on the generic instrument model in Fig 1 (see box, "SCPI Consortium controls standard," for a history of SCPI's creation). The SCPI standard defines a tree-like structure that has more than 20 ma-
jor subsystems as the main branches. The squares in Fig 1 correspond to major subsystems of the SCPI language. Additional major subsystems handle special instrument capabilities such as calibration and diagnostics. The box, "Major SCPI subsystems," lists the major command subsystems.

Look at Table 1 for a sample of a SCPI command subsystem taken directly from the specification. The

INPut command lets you program the conditioning an instrument applies to an incoming signal. Keywords in square brackets indicate default paths through the SCPI tree structure. A program can use one or more of the command options for the instrument in use.

Instruments don't need to implement commands from every SCPI subsystem. Instrument designers can choose the subsystems they

## SCPI Consortium controls standard

A consortium of leading test-and-measurement instrument vendors defined SCPI and still controls the evolution of the standard. The consortium considers the standard to be "free and open"-any test equipment manufacturer can use SCPI commands in an instrument free of charge. The consortium continues to add to the SCPI standard to account for additional types of programmable instruments.

Customer demand led to the creation of SCPI. Sophisticated customers recognized that the time test programmers spent writing drivers for each new incompatible instrument was wasted. HewlettPackard reacted to the need for standardization among its varied instruments by creating its Test and Measurement Systems Language (TMSL), which the company introduced in August 1989. Simultaneously, a group of instrument vendors was contemplating a similar project. And for once in this intensively competitive electronics industry, the best possible thing happened. Hewlett-Packard contributed its TMSL work and joined the group of companies that went on to form the SCPI Consortium.

The consortium refined Hewlett-Packard's work and added capabilities. Tektronix contributed its Analog Data Interchange Format (ADIF) standard. ADIF provides a standard way to store analog data such as waveforms. In addition, ADIF includes environmental data such as scaling information, instrument settings, and time and date stamps.

The consortium moved quickly and published the first version of the SCPI standard in April 1990. The second version was published in June of this year, and the consortium plans to publish an updated spec annually. The consortium meets every two
months to discuss proposed additions to the SCPI standard. A private forum on the Compuserve dialup service includes up-to-date information on proposals, meeting schedules, and newly approved commands.

The founding members of the consortium are Bruel \& Kjaer (Naerum, Denmark), John Fluke Mfg Co (Everett, WA), Hewlett-Packard Co (Loveland, CO ), Keithley Instruments Inc (Cleveland, OH), National Instruments Corp (Austin, TX), Philips (Almelo, The Netherlands), Racal-Dana (Irvine, CA), Tektronix Inc (Beaverton, OR), and Wavetek Inc (San Diego, CA). The consortium now has more than 20 members.

Any company can join the SCPI Consortium. Sponsor memberships cost $\$ 20,000$ annually and include one seat on the consortium's board of directors. A contributing membership costs $\$ 5000$ annulally and includes the right to vote on proposed additions to the standard. Five contributing members are elected to the board of directors each year. The $\$ 750$ associate membership grants access to the private SCPI Compuserve forum only. SCPI Consortium meetings are open to the public, and anyone can propose additions to the standard.

For more information on SCPI and to buy copies of the standard ( $\$ 50$ ), contact

## Fred Bode

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## TECHNOLOGY UPDATE

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need to control an instrument's features. The SCPI standard requires only that an instrument implement the SYSTem command subsystem.

Joe Mueller, a project manager at Hewlett-Packard and the com-
pany's representative to the SCPI Consortium, points out that SCPI allows for $100 \%$ control of an instrument's features. A typical instrument might implement 100 to 200 total SCPI commands, according to

Mueller. The average user may need no more than a dozen commands to develop a specific test program.

The most frequently used commands are those in the MEASure

## Major SCPI subsystems

The following list describes the major subsystems that make up the main branches of the SCPI tree. The beginning capital letters indicate the subsystem's abbreviated form.

CALCulate-The CALCulate subsystem includes commands that control data-processing functions performed on data typically acquired by a SENSe command. For example, a CALCulate command can control the conversion of data from the frequency domain to the time domain.
CALibration-Commands in the CALibration subsystem control system-calibration functions.
DIAGnostic-The DIAGnostic subsystem includes
all the service and diagnostic commands for routine maintenance and repair.
DISPlay-Commands in the DISPlay subsystem control the selection and presentation of textual, graphical, and TRACe information.
FORMat-The FORMat subsystem commands set the data format for transferring numeric and array information.
INPut-INPut subsystem commands control the characteristics, such as the attenuation, of a sensor's input ports.
INSTrument-INSTrument subsystem commands are used for instruments, such as a dual-channel power supply, that support multiple logical instruments.
MEASure-The MEASure subsystem defines a set of high-level instructions that are used to acquire data. This subsystem includes the most commonly used SCPI commands. The concept of horizontal compatibility defined in the SCPI standard is implemented in the MEASure subsystem.
MEMory-The MEMory subsystem commands manage the semiconductor memory instruments use to store various types of data.
MMEMory-MMEMory commands manage massstorage devices, such as disk drives, that are inside instruments or directly connected to instruments.
OUTPut-Commands in the OUTPut subsystem control the characteristics of a source's output port. For example, an OUTPut command can set the output source impedance of a signal.

PROGram-The PROGram subsystem commands provide control of one or more user-programmed tasks resident in an instrument.
ROUTe-ROUTe subsystem commands control instruments primarily designed to route signals. These commands also control signal routing on instruments that offer routing capability as a front end to input and output ports.
SENSe-The SENSe subsystem includes commands that directly set device-specific features before taking a measurement. An example of such a feature is an instrument's filter bandwidth.
SOURce-SOURce subsystem commands set de-vice-specific features, such as modulation controls, on a signal source.
STATus-The STATus subsystem commands add status-reporting structures to those defined in IEEE-488.2.
SYSTem-The SYSTem subsystem includes the functions not related to instrument performance, such as the characteristics of an instrument's communications interface. This subsystem forms the command base required in all instruments.
TEST-The TEST subsystem extends standard instrument self-test procedures beyond those defined in IEEE-488.2.
TRACe-Commands in the TRACe subsystem control the definition and manipulation of trace data. TRIGger-The TRIGger subsystem commands serve to synchronize instrument actions with other events.
UNIT-The UNIT subsystem provides a way to change the units of measure associated with an instrument feature.
VXI-Commands in the VXI subsystem include the administration functions associated with VXIbusbased systems.

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## The SCPI standard

subsystem. The MEASure subsystem enjoys special status although it is a major branch on the SCPI tree with the more than 20 other subsystems. The MEASure subsystem implements the horizontal compatibility the SCPI specification defines.

Hewlett-Packard's Mueller offers an example that illustrates the horizontal compatibility SCPI makes possible and the philosophy behind it. He describes the compatibility of an integrating digital voltmeter with a sampling digital voltmeter. A test programmer could use SCPI's capabilities to program the sampling meter to take 4012 samples to measure dc voltage.

A program that commanded the integrating meter to take 4012 samples, however, might receive an error as an answer because the integrating meter doesn't take samples. The instrument designer could be clever and use SCPI to design the integrating meter so that it would take a meaningful measurement after such a request. The SCPI standard doesn't require instrument manufacturers to take such precautions, however.

Mueller suggests a way to write the test program that ensures an accurate measurement from SCPIcompliant instruments. The reason the programmer set the number of samples was to limit the amount and frequency of the ac voltage rejection present in the dc voltage measurement. You could use a higher-level SCPI command to instruct either meter to account for $60-\mathrm{dB}$ rejection at 52 Hz , for example. The instrument would then take the measurement in the best possible way.

The thousands of possible SCPI command combinations will always make exact compatibility of instruments impossible. No two instru-ments-not even two voltmeters-


The synthesized sweep/function generator, Model 1378, from Wavetek demonstrates that SCPI's concept of vertical compatibility works. The command set of the VXIbus instrument on the left is compatible with that of the Hewlett-Packard E1440A sweeplfunction generator on the right.
have the exact same measurement capabilities. But SCPI does provide the means to achieve the vertical, horizontal, and functional compatibility of the specification.

Unfortunately, little evidence now exists that indicates how well SCPI will work in practice. Hewl-ett-Packard offers a line of VXIbus instruments and a few GPIB instruments that use SCPI. But HP had a head start on the industry because much of SCPI was derived from the company's Test and Measurement System Language (TMSL).

Other companies that now offer SCPI products include the Fluke
(Everett, WA) and Phillips (Almelo, The Netherlands) conglomerate. Between these two companies you can buy SCPI-compatible frequency counters, programmable power sources, and signalswitching systems. Finally, Wavetek, San Diego offers a line of VXIbus instruments for signal generation.
Thus far, the best example of SCPI success can be found in the compatibility between the Wavetek 1378 Synthesized Sweep/Function Generator (\$3295) and HewlettPackard's E1440A generator ( $\$ 5750$ ). The products have a similar

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- set of signal-generation capabilities and clearly demonstrate vertical compatibility. Bill Lee, Wavetek design engineer and the company's SCPI Consortium representative, points out that the SCPI standard includes explicit commands that let the companies implement all the desired functions. Thus, the instruments were compatible.

Both Hewlett-Packard and Wavetek also offer VXIbus arbi-trary-function generators based on SCPI. The function generators were not compatible at the time of introduction. Both companies found the SCPI standard lacking in a few key areas required to exploit all the capabilities of the instruments. So each company added to the spec in different places and planned to pro-
pose the new commands to the SCPI Consortium as formal SCPI changes. Both companies worked on the new commands in secret because neither wanted to disclose features of an unannounced product.

Wavetek engineers added com-
mands to the TRACe subsystem to perform additional waveform functions. Hewlett-Packard engineers added similar capability in the SOURce subsystem. The resulting products were not vertically compatible. Both companies presented their propos-

## For more information . . .

For more information on the SCPI-based products discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

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## TECHNOLOGY UPDATE

als to the committee, and a compromise ensued. Soon you will see revision B instruments from both companies that support the SCPI

## Acronyms used in this article

ac-alternating current
ADIF-Analog Data Interchange
Format
ATE-automatic test equipment dc-direct current
GPIB-General-Purpose Instrument Bus
PC-personal computer
SCPI-Standard Commands for Programmable Instruments
TMSL—Test Measurement System Language
VXIbus-VMEbus extension for instrumentation

Consortium-approved compromise. The revision B function generators will be vertically compatible.

You can expect other conflicts to arise because of the competitive nature of the electronics industry and the constant influx of new products with new features. Also, the SCPI standard is admittedly short of commands that can control certain types of instruments, such as logic analyzers.

The SCPI Consortium, however, adds to the standard every two months. The consortium features an unprecedented level of cooperation in such a competitive industry. SCPI seems to be an idea with no drawbacks. Most major instrument vendors plan to use SCPI in all their new products, many of which will
be introduced over the next year. Shortly, designers who don't buy SCPI instruments exclusively will find the price, development time, and extensibility of their test systems lacking compared with SCPIbased systems.

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## Reference

1. Leibson, Steven H, "IEEE-488.2 products are just now appearing," EDN, April 25, 1991, pg 91.

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| ROM/RAM/EEPROM | 10K/256/8K | 8K/256/0 | $16 \mathrm{~K} / 512 / 0$ | $24 \mathrm{~K} / 1 \mathrm{~K} / 0$ | $32 \mathrm{~K} / 1 \mathrm{~K} / 0$ | 16K/512/0 | $32 \mathrm{~K} / 512 / 0$ |
| Timers |  | 3 |  |  |  | 5 | 10 |
| Serial Channel |  | 2 |  |  |  | 1 | 2 |
| A/D Converter |  |  |  |  |  | 8 -Bit, 8 Channel | 8 -Bit, 16 Channel |
| Interrupts |  | 4 External 16 Internal |  |  |  | 9 External 19 Internal | 9 External 47 Internal |
| I/O Ports | $1-\mathrm{Bit} \mathrm{I} / \mathrm{O}$ Common | $\begin{gathered} 47 \mathrm{I} / \mathrm{O} \\ 4 \text { Input Only } \end{gathered}$ |  |  |  | $\begin{gathered} 58 \mathrm{I} / \mathrm{O} \\ 8 \text { Input Only } \end{gathered}$ | $\begin{gathered} 50 \mathrm{I} / \mathrm{O} \\ 16 \text { Input Only } \\ \hline \end{gathered}$ |
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2 The maximum number of columns depends on the font and size selected. The higher number is for $5 \times 7$ characters, approximately 16 characters $/$ in. tures like thick-film printheads, high-torque stepper motors and heavy-gauge construction provide long life. While permanently lubricated gear trains and gold-plated connectors ensure reliable operation. And special touches such as automatic paper loading simplify operation.

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INSTRUMENTS

## TECHNOLOGY UPDATE

## SERIAL EEPROMs

## Serial memory offers cheap frills

You don't need a byte-wide interface or large devices to add a little nonvolatile memory to your system. Serial EEPROMs are an inexpensive option that offer a few extras.

Richard A Quinnell, Regional Editor

Serial EEPROMs provide an opportunity to add nonvolatile memory to your system at very low cost, both in terms of price and system resources. Newer devices also have the ability to protect your data, speed the data-transfer rate, and operate at lower voltages.

As the name implies, you interact with a serial EEPROM by clocking addresses, data, and commands into a single data line. A complete interface requires from two to five wires, depending on the type of device you use. The most common interface type, Microwire (developed by National Semiconductor), uses four lines. Some devices add a status pin to bring the total to five. Alternatively, you can reduce the number of lines needed by tying together the data input and output lines (see box, "Interfacing alternatives"). The Philips interintegrated circuit ( $I^{2} \mathrm{C}$ ) bus, running a close second to Microwire in availability, uses only two lines. Other available interfaces include UART-compatibles and those that work with Motorola's serialpipeline interface (SPI).

The compact nature of the serial interface is vital if you're trying to produce a minimal system and still provide nonvolatile memory. For many microcontrollers, the CPU's address and data buses are not available outside of the IC, in order to conserve I/O pins.


Compact and nonvolatile, serial EEPROMs let you add memory without using up your system's I/O resources. These 2-kbit devices from Xicor need only two wires for complete access.

Most microcontrollers offer parallel ports, however, and designers needing off-chip memory use those ports to generate the needed address and data bits. Interfacing to a conventional memory device would consume at least 8 bits of the parallel port, versus the 2 to 5 bits for serial memory. Using a microcontroller with on-chip EEPROM is a possibility, but CPU vendors such as Zilog admit that a 2-chip design is less expensive than a CPU with onboard EEPROM.
In addition to offering a compact interface, the serial EEPROMs themselves are compact. Almost all of them, regardless of their bit density, are available in 8 -pin DIPs, and many come in small-outline (SO) packages. The variety of bit densities having a common physical interface gives you the option of changing the amount of memory in


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## TECHNOLOGY UPDATE

## Serial EEPROMs

your design to increase capacity or decrease cost without affecting board layout or wiring. If you use devices having the $I^{2} \mathrm{C}$ interface, you may not need to change software, either, because the $I^{2} \mathrm{C}$ command protocol uses a fixed-length address field.

Nothing in life is free, however, including the serial EEPROM's advantages. There are a number of design considerations you must confront before deciding to incorporate serial EEPROM in your design. For example, using a serial interface extends the time required for memory access. In addition to the time needed to shift the data in and out, you must include the time to clock in a command code and an address for each transaction. Further, the serial protocols aren't always amenable to the use of byte-oriented serial peripherals. Therefore, you'll have software overhead for converting the serial data to parallel, and vice versa. Finally, storing data in an EEPROM requires a considerable amount of time, on the order of $10 \mathrm{msec}($ Ref $\mathbf{1})$.

## Page mode speeds data storage

Manufacturers of serial EEPROMs have implemented a number of improvements addressing the first of these considerations: access time. Some offer clock rates as fast as 1 MHz , for example, reducing the time required for shifting data out. Manufacturers have also reduced the command and address overhead by giving some of the serial EEPROM the ability to perform both page-oriented write transactions and sequential reads. Devices


Packaging options abound for serial EEPROMs. Microchip Technology, for example, offers DIP, small-outline (SO), chip-on-board (COB), and bare die for its products.
with the sequential-read capability let you specify a single address, then read all the data between that address and the end of memory without further addressing.
Access time is not the only consideration, however. Serial EEPROMs, like all EEPROMs, have a limited service life. EEPROMs store their data on a floating gate in each memory location. During erasing and writing, charge moves to or from the gate using quantum mechanical tunneling through the surrounding insulators. Each time an EEPROM cell is erased or written to, some electrons may become permanently trapped in the insulator. Over time, these trapped electrons build up enough charge to prevent the cell's proper operation. Using an EEPROM, therefore, requires careful attention to system design in order to
minimize the number of erase/write cycles needed at a given memory location.
Manufacturers specify the lifetime of an EEPROM in terms of endurance: the minimum number of erase/write cycles a cell is guaranteed to provide. Read cycles do not affect a cell's endurance. As shown in Table 1 (see pg 64), the endurance ratings of available serial EEPROMs range from 10,000 to 1 million cycles. Realize, however, that these are minimums; you may get a much greater lifetime in your application.

## Endurance ratings vary

Ratings expressed by different manufacturers aren't always directly comparable, though, because their test methods differ. The differing conditions result in differing test results. Operation at elevated

## Acronyms used in this article

CPU-central processing unit
DIP-dual in-line package
EEPROM-electrically erasable read-only memory
EIAJ-Electronic Industries Association of Japan
$\mathbf{I}^{2} \mathbf{C}$-interintegrated circuit
JEDEC—Joint Electron Device Engineering Council
SO-small-outline package
UART—universal asynchronous receiver/transmitter

## Serial EEPROMs

temperatures greatly speeds the cell's failure rate and decreases the endurance rating. Allowing a cell to rest between erase/write cycles, on the other hand, enables it to release some of the trapped electrons and extends its effective life. Therefore, when examining endurance ratings, be sure you know the conditions under which devices were rated.

If the EEPROM's endurance is
a limiting factor in your designs, there are several steps you can take to extend your circuit's service lifetime. One possibility is to use a device with more capacity than you need. If you check for cell failure following each write operation, or use a counter to keep track of the erase/write cycles you've used, you can move your data into another section of memory if one section
starts failing, then resume operation.
Alternatively, you may wish to use a nonvolatile RAM that offers a serial interface, such as the Cata-lyst CAT24C44 (\$1.50) and the Xicor X24C4 (\$1.11). These devices operate like a serial RAM, but have an EEPROM array backing the RAM array. If you need a nonvolatile copy of the data in RAM, you simply signal the device to copy the

## Interfacing alternatives

Although there are a variety of interface methods for serial EEPROMs, only two are widely distributed: Microwire from National Semicondutor and the interintegrated circuit $\left(\mathrm{I}^{2} \mathrm{C}\right)$ from Philips. Each method has its own strengths and weaknesses.

Several fundamental differences exist between the two interfaces, the most obvious being the number of signals required. The Microwire interface uses four signals: data in, data out, chip select, and a shift clock. You activate the device by asserting chip select and clocking in an opcode and data address (if applicable). You then clock data in or out as applicable. The $\mathrm{I}^{2} \mathrm{C}$ bus uses only two wires, a clock and a data line. The $\mathrm{I}^{2} \mathrm{C}$ protocol calls for the bus master to send a slave address to activate the device desired, then the opcode and data. The slave device acknowledges reception of the address and each byte of opcode and data, then supplies any data requested. The $I^{2} \mathrm{C}$ protocol prevents any contention on the shared data line.

You can reduce by one the number of I/O lines needed to connect to a Microwire device by tying the data-in and data-out lines together. This reduction is possible because the data-out line remains in a high-impedance state unless supplying read data. The danger in this approach is that the dataout line begins by supplying a dummy-zero bit as soon as the last address bit of the read command has entered the data-in line. If that address bit is high, the resulting bus contention may prevent the device from reading the address properly, or may result in excessive current being drawn into the device. Placing a current-limiting resistor in the connection between the data-in and data-out lines can help prevent damage, but may slow the data bus.

The two interfaces also differ in the way they indicate device status. Because EEPROMs require a relatively long time to complete erase or write
operations (worst case can be as long as 10 msec ), most serial EEPROMs offer a method of indicating when the operation is complete. Using this status indication can speed your overall access to the memory; you don't have to wait for the worst-case time period to elapse before using the EEPROM again.

The Microwire interface requires you to poll the data output line following an erase or write instruction. The line changes state to indicate the device's readiness. Some older devices use the interface developed by General Instruments. They communicate with a Microwire-like serial protocol, but have separate busy/status lines. They are handy if you wish to use an interrupt to signal the processor to the memory's readiness, rather than poll a status line. $I^{2} \mathrm{C}$-compatible devices don't offer any specific sig-nal-they simply fail to acknowledge a command string if they are still busy.

The speed of the interface and depth of memory are other differences. The $\mathrm{I}^{2} \mathrm{C}$ specification limits the serial clock rate to 100 kHz . Further, its fixed addressing protocol limits the total amount of memory that can reside on a single bus to 16 kbytes. The fixed protocol is not entirely a disadvantage, however. It enables you to make your interface software independent of the EEPROM's bit density, letting you increase or reduce memory without changing software. Microwire devices have a vari-able-length address, dependent upon their bit density.

The Microwire interface has no clock and addressing limits. Clock rates as high as 3 MHz are available, and the number of devices on a bus is limited only by your bus driver's capability. Recall, though, that each Microwire device needs a chip-select signal, so you'll need additional I/O ports to handle the additional memory.

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## TECHNOLOGY UPDATE

## Serial EEPROMs

RAM into EEPROM. Similarly, you can load the RAM from the EEPROM array. This dual-array structure lets you make many changes to the contents of memory, using the EEPROM only when needed.

Another system consideration when choosing to use serial EEPROMs is the relative lack of standards for them. For example, the devices use a variety of interface protocols. Even with devices using the same protocol, there may be timing differences between manufacturers. Packaging is also nonstandard. The DIP versions of the EEPROMs are uniform, but surface-mount packages are diverse. There are two sizes of SO packages available, based on either the JEDEC or EIAJ standards. Although, by sizing the solder pads properly, you can accommodate either size device, the problem
doesn't end there. The pinout of the SO packages is not standardized. Two pinout patterns are available, corresponding to the direction the manufacturers' die fit within the SO package. If you are looking at alternate sources for your design, therefore, be sure to check the package size and pinouts.
If you can get past the design considerations, you'll find that serial EEPROMs offer a range of special features. During the last two years, manufacturers have added features to increase the versatility of serial EEPROMs. One such feature is selectable word size. Many serial EEPROMs are organized as a series of 16 -bit-wide registers, with some available in 8 -bit widths. To give you more flexibility in choice, manufacturers now offer devices with a selectable organization, controlled by the logic level at an I/O pin.

Another frill is the ability to write-protect a section of memory. Most serial EEPROMs will protect memory from inadvertent write access when the supply voltage is low. Further, they have a software command to disable write access to a part. Both of these features are designed to prevent inadvertent writes to the memory when power is unstable and logic behavior is unpredictable. The newer write-protection feature is the ability to lock out a portion of memory during normal operation. Parts from International CMOS Technology, for example, have a pin-controlled write protect that prevents writing to the entire memory, letting you use it as a ROM. Some parts from Microchip, on the other hand, protect only the top half of memory, allowing you free access to the lower half. This type of write-protect scheme lets you create calibration tables or con-

## For more information . . .

For more information on the serial EEPROMs discussed in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

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| FAX (408) 436-4300 | (800) 642-7616; | (408) 721-5000 | FAX (602) 867-6101 |
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|  | FAX (408) 432-9044 | Contact Bryan Liddiard | Circle No. 709 |
|  | Circle No. 703 | Circle No. 706 |  |
| 2231 Calle de Luna |  |  | Signetics |
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|  | Contact Ed Nieda |  |  |
| Exel Microelectronics 2150 Commerce Dr | Circle No. 704 | Samsung Semiconductor |  |
| San Jose, CA 95161 |  | S725 N 1st St | 851 Buckeye Ct |
| (408) 432-0500 | Microchip Technology Inc | San Jose, CA 95134 | Milpitas, CA 95035 |
| FAX (408) 432-8710 | 2355 W Chandler Blvd | (408) 954-7229 | (408) 432-8888 |
| Contact Reggie Huff, x4658 | Chandler, AZ 85224 | FAX (408) 954-7873 | FAX (408) 432-0640 |
| Circle No. 702 | (602) 345-3400 | Circle No. 708 | Contact Rick Orlando |
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## TECHNOLOGY UPDATE

## Serial EEPROMs

figuration data, then lock them into the EEPROM.
A more flexible version of the write-protect scheme comes in the form of a programmable writeprotect. This scheme, offered by several companies including Exel, National Semiconductor, Samsung, and SGS-Thomson, lets you select the beginning address of protected memory, thus protecting only the amount of memory you desire. This protection can be temporary or, by programming a special register, made permanent.
A unique data-protection scheme is available from Catalyst Semiconductor in its CAT33C704/804 series.

These devices offer programmable write protection. Then, by programming the device with a password, you can convert the writeprotected area of memory to readprotected memory, accessible only with the proper password. The remaining section of memory becomes write-protected. This secure-access feature is particularly useful if your EEPROM is to contain proprietary information, serial numbers, or access codes that you want to deny to the user.

Another relatively new feature of serial EEPROMs is low-voltage operation. Manufacturers have extended the operating voltage range
of some serial EEPROMs to include typical battery voltages. Many now come in 3 V versions, with some tolerating as low as 2.5 V . Others, like the Exel parts, offer full operation to 3 V and allow read-only operation as low as 2 V .

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## Reference

1. Leibson, Steven H, "Nonvolatile, in-circuit-reprogrammable memories," EDN, January 3, 1991, pg 88.

## Article Interest Quotient <br> (Circle One)

High 518 Medium 519 Low 520

Table 1-Representative serial EEPROMs

| Company | Part | $\begin{array}{\|l\|l} \text { Size } \\ \text { (bits) } \end{array}$ | Organization (bits) | Interface compatibility | Serial clock rate | Supply current |  |  | Data retention (years) | Operating voltage range ${ }^{1}$ (volts) | Package styles ${ }^{2}$ | Special features | $\begin{gathered} \text { Price } \\ (10,000) \\ \text { (DIP) } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | Active (mA) | Standby ( $\mu \mathrm{A}$ ) |  |  |  |  |  |  |
| Atmel | AT93C46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$0.77 |
|  | AT93C46-3 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 100 | 10k | 10 | 3 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$0.96 |
|  | AT24C02 | 2 k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1.5 | 150 | 10k | 10 | 5 | DIP, SO | 100k/100 year endurance option | \$0.99 |
|  | AT24C02-3 | 2 k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 150 | 10k | 10 | 3 to 6 | DIP, SO | 100k/100 year endurance option | \$1.51 |
|  | AT24C04 | 4 k | $512 \times 8$ | $1^{2} \mathrm{C}$ | 100 kHz | 1.5 | 150 | 10k | 10 | 5 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$1.70 |
|  | AT24C04-3 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 150 | 10k | 10 | 3 to 6 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$2.46 |
| Catalyst Semiconductor | CAT32C101 | 1k | $64 \times 16$ <br> or $128 \times 8$ | Microwire | 700 kHz | 1 | 2 | 10k | 10 | 2 to 4 | DIP, SO | 100k/100 year endurance option | \$1.69 |
|  | CAT33C101 | 1k | $64 \times 16$ or $128 \times 8$ | Microwire | 700 kHz | 2 | 50 | 10k | 10 | 3 | DIP, SO | 100k/100 year endurance option | \$0.85 |
|  | CAT33C201 | 1k | $64 \times 16$ <br> or $128 \times 8$ | General Instruments | 700 kHz | 2 | 50 | 10k | 10 | 3 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$0.79 |
|  | CAT59C11 | 1k | $64 \times 16$ <br> or $128 \times 8$ | General Instruments | 250 kHz | 5 | 100 | 10k | 10 | 5 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$0.63 |
|  | CAT93C46 | 1k | $64 \times 16$ <br> or $128 \times 8$ | Microwire | 700 kHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | 100k/100 year endurance option | \$0.77 |
|  | CAT93C46A | 1k | $64 \times 16$ | Microwire | 700 kHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$0.77 |
|  | CAT24C02 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 40 | 100k | 100 | 5 | DIP, SO | Page mode | \$1.13 |
|  | CAT24C02Z | 2 k | $256 \times 8$ | $1^{12} \mathrm{C}$ | 100 kHz | 3 | 0 | 100k | 100 | 5 | DIP, SO |  | \$1.40 |
|  | CAT24LC02 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 50 | 100k | 100 | 3 to 6 | DIP, SO |  | \$1.40 |
|  | CAT35C102 | 2k | $128 \times 16$ <br> or $256 \times 8$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | 100k/100 year endurance option | \$1.13 |
|  | CAT35C202 | 2k | $\left\|\begin{array}{c} 128 \times 16 \\ \text { or } 256 \times 8 \end{array}\right\|$ | General Instruments | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | 100k/100 year endurance option | \$1.44 |

## Notes:

1. Operating voltages have $\pm 10 \%$ tolerance unless a range is shown.
2. DIPs listed are 8 -pin, dual in-line packages unless noted, SOs are 8 -pin, small-outline packages unless noted, and COB means chip on board.

## The FS700 LORAN-C frequency standard

## 10 MHz cesium stability

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The FS700 LORAN-C frequency standard provides the optimum, cost-effective solution for frequency management and calibration applications. Four 10 MHz outputs from built-in distribution amplifiers provide cesium standard long-term stability of $10^{-12}$, with short-term stability of $10^{-10}$ ( $10^{-11}$ optional). Reception is guaranteed in North America, Europe and Asia.

Since the FS700 receives the ground wave from the LORAN transmitter, reception is unaffected by atmospheric changes, with no possibility of missing cycles, a common occurrence with WWV due to discontinuous changes in the position of the ionosphere layer. Cesium and rubidium standards, in addition to being expensive initially, require periodic refurbishment, another costly item.

The FS700 system includes a remote active 8 -foot whip antenna, capable of driving up to 1000 feet of cable. The receiver contains six adjustable notch filters and a frequency output which may be set from 0.01 Hz to 10 MHz in a 1-2-5 sequence. A Phase detector is used to measure the phase shift between this output and another front panel input, allowing quick calibration of other timebases. An analog output with a range of $\pm 360$ degrees, provides a voltage proportional to this phase difference for driving strip chart recorders, thus permitting continuous monitoring of long-term frequency stability or phase locking of other sources.


Table 1-Representative serial EEPROMs (continued)

|  |  |  |  |  |  | Supply | y current |  | Data reten- |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Company | Part | $\begin{aligned} & \text { Size } \\ & \text { (bits) } \end{aligned}$ | ization <br> (bits) | compatibility | clock rate | Active (mA) | Standby ( $\mu \mathrm{A}$ ) | $\begin{gathered} \text { ance } \\ \text { (cycles) } \end{gathered}$ | tion (years) | range ${ }^{1}$ (volts) | Package styles ${ }^{2}$ | Special features | $\begin{gathered} (10,000) \\ \text { (DIP) } \end{gathered}$ |
| Catalyst Semiconductor (continued) | CAT93C56 | 2k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \end{array}$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | 100k/100 year endurance option | \$1.13 |
|  | CAT93LC56 | 2 k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \\ \hline \end{array}$ | Mlcrowire | 250 kHz | 2 | 50 | 10k | 10 | 3 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$1.25 |
|  | CAT24C04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 40 | 100k | 100 | 5 | DIP, SO | Page mode | \$2.25 |
|  | CAT24C04Z | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 0 | 100k | 100 | 5 | DIP, SO |  | \$2.50 |
|  | CAT24LC04 | 4 k | $512 \times 8$ | $1^{12} \mathrm{C}$ | 100 kHz | 3 | 50 | 100k | 100 | 3 to 6 | DIP, SO |  | \$2.50 |
|  | CAT33C104 | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \\ \hline \end{array}$ | Microwire | 250 kHz | 2 | 50 | 10k | 10 | 3 | DIP, SO | 100k/100 year endurance option | \$2.50 |
|  | CAT33C704 | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \end{array}$ | Synchronous | 1 MHz | 3 | 200 | 10k | 10 | 3 | $\begin{gathered} \text { DIP, SO, } \\ \text { COB } \end{gathered}$ | $100 \mathrm{k} / 100$ year endurance option, password protection | \$4.50 |
|  | CAT33C804A/B | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \end{array}$ | UART | 9600 Baud | 3 | 200 | 10k | 10 | 3 | $\begin{array}{\|c} \hline \text { DIP, SO, } \\ \text { COB } \end{array}$ | $100 \mathrm{k} / 100$ year endurance option, password protection | \$5.63 |
|  | CAT35C104 | 4k | $\begin{array}{\|l\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | $100 \mathrm{k} / 100$ year endurance option | \$2.25 |
|  | CAT35C704 | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \\ \hline \end{array}$ | Synchronous | 3 MHz | 3 | 200 | 10k | 10 | 5 | $\begin{array}{\|c} \hline \text { DIP, SO, } \\ \text { COB } \end{array}$ | $100 \mathrm{k} / 100$ year endurance option, password protection | \$3.60 |
|  | CAT35C804A/B | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \end{array}$ | UART | 9600 Baud | 3 | 200 | 10k | 10 | 5 | $\begin{gathered} \mathrm{DIP}, \mathrm{SO}, \\ \mathrm{COB} \end{gathered}$ | $100 \mathrm{k} / 100$ year endurance option, password protection | \$4.05 |
|  | CAT24C08 | 8k | $1024 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 40 | 100k | 100 | 5 | DIP, SO | Page mode | \$2.95 |
|  | CAT24C08Z | 8k | $1024 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 0 | 100k | 100 | 5 | DIP, SO |  | \$3.25 |
|  | CAT24LC08 | 8 k | $1024 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 50 | 100k | 100 | 3 to 6 | DIP, SO |  | \$3.25 |
|  | CAT24C16 | 16k | $2048 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 40 | 100k | 100 | 5 | DIP, SO | Page mode | \$3.50 |
|  | CAT24C16Z | 16k | $2048 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 0 | 100k | 100 | 5 | DIP, SO |  | \$3.75 |
|  | CAT24LC16 | 16k | $2048 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3 | 50 | 100k | 100 | 3 to 6 | DIP, SO |  | \$3.75 |
| Exel Microelectronics | XL93LC06 | 256 | $16 \times 16$ | Microwire | 1 MHz | 2 | 2 | 100k | 10 | 5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.47 |
|  | XL93LC06-3 | 256 | $16 \times 16$ | Microwire | 250 kHz | 2 | 2 | 100k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.52 |
|  | XL93C46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 2 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V | \$0.50 |
|  | XL93C46-3 | 1k | $64 \times 16$ | Microwire | 250 kHz | 2 | 2 | 10k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V | \$0.55 |
|  | XL93CS46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 2 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V , programmable data protection | \$0.70 |
|  | XL93CS46-3 | 1k | $64 \times 16$ | Microwire | 250 kHz | 2 | 2 | 10k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , programmable data protection | \$0.75 |
|  | XL93LC46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 2 | 100k | 10 | 5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.50 |
|  | XL93LC46-3 | 1k | $64 \times 16$ | Microwire | 250 kHz | 2 | 2 | 100k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.55 |
|  | XL35LC102 | 2k | $128 \times 16$ | Microwire | 1 MHz | 2 | 2 | 100k | 10 | 5 | DIP, SO | Read operation to 2 V , auto-increment | \$1.15 |
|  | XL35LC102-3 | 2k | $128 \times 16$ | Microwire | 250 kHz | 2 | 2 | 100k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , auto-increment | \$1.23 |
|  | XL90C21 | 2k | $128 \times 16$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V | \$0.90 |
|  | XL93C56 | 2k | $128 \times 16$ | Microwire | 1 MHz | 2 | 4 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V | \$0.90 |
|  | XL93C56-3 | 2k | $128 \times 16$ | Microwire | 250 kHz | 2 | 4 | 10k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V | \$1.35 |
|  | XL93LC56 | 2k | $128 \times 16$ | Microwire | 1 MHz | 2 | 2 | 100k | 10 | 5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.90 |
|  | XL93LC56-3 | 2k | $128 \times 16$ | Microwire | 250 kHz | 2 | 2 | 100k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , auto-increment | \$0.98 |
|  | XL90C41 | 4k | $256 \times 16$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V | \$1.25 |
|  | XL93C66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 2 | 4 | 10k | 10 | 5 | DIP, SO | Read operation to 2 V | \$1.25 |
|  | XL93C66-3 | 4k | $256 \times 16$ | Microwire | 250 kHz | 2 | 4 | 10k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V | \$1.88 |
|  | XL93LC66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 2 | 2 | 100k | 10 | 5 | DIP, SO | Read operation to 2 V , auto-increment | \$1.25 |
|  | XL93LC66-3 | 4k | $256 \times 16$ | Microwire | 250 kHz | 2 | 2 | 100k | 10 | 2.7 to 5.5 | DIP, SO | Read operation to 2 V , auto-increment | \$1.35 |

Notes:

1. Operating voltages have $\pm 10 \%$ tolerance unless a range is shown.
2. DIPs listed are 8 -pin, dual in-line packages unless noted, SOs are 8 -pin, small-outline packages unless noted, and COB means chip on board.

| Company | Part | $\begin{array}{\|l} \text { Size } \\ \text { (bits) } \end{array}$ | Organization (bits) | Interface compatibility | Serial clock rate | Supply current |  | $\begin{array}{\|l} \text { Endur- } \\ \text { ance } \\ \text { (cycles) } \end{array}$ | $\left\|\begin{array}{c} \text { Data } \\ \text { reten- } \\ \text { tion } \\ \text { (years) } \end{array}\right\|$ | Operating voltage range ${ }^{1}$ (volts) | Package styles ${ }^{2}$ | Special features | $\begin{array}{\|c} \hline \text { Price } \\ (10,000) \\ \text { (DIP) } \\ \hline \end{array}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | Active (mA) | Standby ( $\mu \mathrm{A}$ ) |  |  |  |  |  |  |
| International CMOS Technology | 93C46A | 1k | $64 \times 16$ | Microwire | 2 MHz | 3 | 50 | 10k | 40 | 5 | DIP, SO | $3 V$ version available, hardware write protect | \$0.60 |
|  | $93 C 56 \mathrm{~A}$ | 2k | $128 \times 16$ | Microwire | 2 MHz | 3 | 50 | 10k | 40 | 5 | DIP, SO | Hardware write protect | \$1.65 |
|  | $93 \mathrm{CX56}$ | 2k | $128 \times 16$ | Microwire | 1 MHz | 4 | 50 | 10k | 40 | 2.5 to 6 | DIP, SO | Hardware write protect | \$2.25 |
|  | 93C66A | 4k | $256 \times 16$ | Microwire | 2 MHz | 3 | 50 | 10k | 40 | 5 | DIP, SO | Hardware write protect | \$2.30 |
|  | $93 \mathrm{CX66}$ | 4k | $256 \times 16$ | Microwire | 1 MHz | 4 | 50 | 10k | 40 | 2.5 to 6 | DIP, SO | Hardware write protect | \$2.90 |
| Microchip Technology | 93C06 | 256 | $16 \times 16$ | Microwire | 1 MHz | 4 | 100 | 100k | 10 | 5 | DIP, SO |  | \$0.53 |
|  | 24C01A | 1k | $128 \times 8$ | $1^{2} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode | \$0.98 |
|  | 24LC01 | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 100k | 10 | 2 to 5.5 | DIP, SO | Sequential read, page mode, hardware write protect | \$1.05 |
|  | 59 C 11 | 1k | $64 \times 16$ or $128 \times 8$ | General Instruments | 1 MHz | 4 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode, hardware write protect | \$0.55 |
|  | 85 C 72 | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode | \$1.03 |
|  | 93C46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 4 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode, hardware write protect | \$0.55 |
|  | 24C02A | 2 k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode, hardware write protect | \$1.02 |
|  | 24LC02 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 100k | 10 | 2 to 5.5 | DIP, SO | Sequential read, page mode, hardware write protect | \$1.10 |
|  | 85C82 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode | \$1.07 |
|  | 93C56 | 2k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \end{array}$ | Microwire | 2 MHz | 4 | 100 | 100k | 10 | 4 to 5.5 | DIP, SO | Sequential read | \$1.05 |
|  | 24C04A | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode, hardware write protect | \$1.44 |
|  | 24LC04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 100k | 10 | 2 to 5.5 | DIP, SO | Sequential read, page mode, hardware write protect | \$1.52 |
|  | 85C92 | 4k | $512 \times 8$ | $1^{2} \mathrm{C}$ | 100 kHz | 3.5 | 100 | 100k | 10 | 5 | DIP, SO | Sequential read, page mode | \$1.52 |
|  | 93C66 | 4k | $\begin{array}{\|c\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \\ \hline \end{array}$ | Microwire | 2 MHz | 4 | 100 | 100k | 10 | 4 to 5.5 | DIP, SO | Sequential read | \$1.28 |
|  | 24LC16 | 16k | $2048 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 100k | 10 | 2 to 5.5 | DIP, SO | Sequential read, page mode, hardware write protect | \$3.56 |
| National Semiconductor | NM93C06 | 256 | $16 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | 5 V -only version available | \$0.63 |
|  | NM93CS06 | 256 | $16 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | Sequential read, programmable write protect, 5 V -only version | \$1.57 |
|  | NM59C11 | 1k | $64 \times 16$ <br> or $128 \times 8$ | General Instrument | 1 MHz | 0.4 | 25 | 500k | 40 | 5 | DIP, SO |  | \$0.82 |
|  | NM93C46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | 5 V -only version available | \$0.75 |
|  | NM93C46A | 1k | $64 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 5 | DIP, SO |  | \$0.82 |
|  | NM93CS46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | Sequential read, programmable write protect, 5 V -only version | \$1.82 |
|  | NM95C12 | 1k | $64 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 40k | 10 | 5 | 14-pin DIP, 14-pin SO | 8 onboard DIP switches | \$3.13 |
|  | NM24C02 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 0.4 | 25 | 500k | 40 | 5 | DIP, 14 pin SO | Page mode | \$0.90 |

## Notes:

1. Operating voltages have $\pm 10 \%$ tolerance unless a range is shown.
2. DIPs listed are 8 -pin, dual in-line packages unless noted, SOs are 8 -pin, small-outline packages unless noted, and COB means chip on board.

Table 1-Representative serial EEPROMs (continued)

| Company | Part | $\begin{aligned} & \text { Size } \\ & \text { (bits) } \end{aligned}$ | Organization (bits) | Interface compatibility | Serial <br> clock <br> rate | Supply current |  | Endur-ance(cycles) | $\left\lvert\, \begin{gathered} \text { Data } \\ \text { reten- } \\ \text { tion } \\ \text { (years) } \end{gathered}\right.$ | Operating voltage range ${ }^{1}$ (volts) | Package styles ${ }^{2}$ | Special features | $\begin{gathered} \text { Price } \\ (10,000) \\ (\mathrm{DIP}) \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | $\begin{gathered} \text { Active } \\ (\mathrm{mA}) \end{gathered}$ | Standby <br> ( $\mu \mathrm{A}$ ) |  |  |  |  |  |  |
| National Semiconductor (continued) | NM24C03 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 60 | 500k | 40 | 5 | $\begin{array}{\|l\|} \hline \text { DIP, } 14 \\ \text { pin SO } \end{array}$ | Page mode, hardware write protect | \$1.05 |
|  | NM93C56 | 2 k | $128 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | 5 V -only version available | \$1.19 |
|  | NM93CS56 | 2 k | $128 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | Sequential read, programmable write protect, 5V-only version | \$3.07 |
|  | NM24C04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 60 | 500k | 40 | 5 | $\begin{aligned} & \mathrm{DIP}, 14- \\ & \text { pin SO } \end{aligned}$ | Page mode | \$1.45 |
|  | NM24C05 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 60 | 500k | 40 | 5 | $\begin{aligned} & \mathrm{DIP}, 14 \\ & \text { pin SO } \end{aligned}$ | Page mode, hardware write protect | \$1.60 |
|  | NM93C66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | DIP, SO | 5 V -only version available | \$2.25 |
|  | NM93CS66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 0.4 | 25 | 500k | 40 | 2 to 5.5 | $\begin{aligned} & \text { DIP, } 14- \\ & \text { pin SO } \end{aligned}$ | Sequential read, programmable write protect, 5 V -only version | \$5.00 |
|  | NM24C08 | 8k | 1024×8 | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 60 | 500k | 40 | 5 | $\begin{array}{\|l\|} \hline \text { DIP, } 14- \\ \text { pin SO } \end{array}$ | Page mode | \$2.85 |
|  | NM24C09 | 8k | 1024×8 | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 60 | 500k | 40 | 5 | $\begin{array}{\|l\|} \hline \text { DIP, } 14 \\ \text { pin SO } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Page mode, hardware } \\ \text { write protect } \end{array} \\ \hline \end{array}$ | \$3.05 |
| Oki Semiconductor | MSM16881 | 1k | $\begin{array}{\|c\|} \hline 64 \times 16 \\ \text { or } 128 \times 8 \\ \hline \end{array}$ | Microwire | 250 kHz | 3 | 100 | 10k | 10 | 5 | DIP, SO |  | \$0.80 |
|  | MSM16911 | 1k | $\begin{array}{\|c\|} \hline 64 \times 16 \\ \text { or } 128 \times 8 \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \text { General } \\ \text { Instruments } \end{array}$ | 250 kHz | 3 | 100 | 10k | 10 | 5 | DIP, SO |  | \$0.80 |
|  | MSM16812 | 2k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP |  | \$1.50 |
|  | MSM16912 | 2k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \\ \hline \end{array}$ | General Instruments | 1 MHz | 3 | 100 | 10k | 10 | 5 | DIP |  | \$1.50 |
| Samsung Semiconductor | KM93C06 | 256 | 16x16 | Microwire | 250 kHz | 5 | 100 | 100k | 10 | 5 | DIP, SO |  | \$0.42 |
|  | KM93C07 | 256 | $16 \times 16$ | Microwire | 250 kHz | 5 | 100 | 100k | 10 | 5 | DIP, SO |  | \$0.43 |
|  | KM93C46 | 1k | $64 \times 16$ | Microwire | 250 kHz | 5 | 100 | 100k | 10 | 5 | DIP, SO |  | \$0.45 |
|  | KM93C46V | 1k | $64 \times 16$ | Microwire | 250 kHz | 5 | 100 | 100k | 10 | 2.7 to 5.5 | DIP, SO |  | \$0.47 |
|  | KM93C56 | 2 k | $128 \times 16$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7105 .5 | DIP, SO |  | \$0.80 |
|  | KM93CS56 | 2 k | $128 \times 16$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7 to 5.5 | DIP, SO | $\begin{array}{\|c} \text { Programmable write } \\ \text { protect } \end{array}$ | \$1.00 |
|  | KM93C57 | 2k | $\begin{array}{\|c\|} \hline 128 \times 16 \\ \text { or } 256 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7 to 5.5 | DIP, SO |  | \$0.82 |
|  | KM93C66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7 to 5.5 | DIP, SO |  | \$1.30 |
|  | KM93CS66 | 4k | $256 \times 16$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7 to 5.5 | DIP, SO | $\begin{array}{\|c} \hline \text { Programmable write } \\ \text { protect } \end{array}$ | \$1.50 |
|  | км93С67 | 4k | $\begin{array}{\|l\|} \hline 256 \times 16 \\ \text { or } 512 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 1 | 50 | 100k | 10 | 2.7 to 5.5 | DIP, SO |  | \$1.32 |
| SGS- <br> Thompson Microelectronics | ST93C06 | 256 | $\begin{array}{\|c\|} \hline 16 \times 16 \\ \text { or } 32 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 2 | 50 | 1M | 10 | 5 | DIP, SO |  | \$0.50 |
|  | ST24C01 | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 1 M | 10 | 5 | DIP, SO | Page mode, sequential <br> read | \$0.62 |
|  | ST93C46A | 1k | $\begin{array}{\|c\|} \hline 64 \times 16 \\ \text { or } 128 \times 8 \\ \hline \end{array}$ | Microwire | 1 MHz | 5 | 50 | 1 M | 10 | 5 | DIP, SO |  | \$0.62 |
|  | ST93CS46 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 50 | 1M | 10 | 5 | $\begin{gathered} \text { DIP, SO, } \\ \text { 14-pin } \\ \text { SO } \end{gathered}$ | Page mode, programmable write protect | \$0.84 |
|  | ST93CS47 | 1k | $64 \times 16$ | Microwire | 1 MHz | 2 | 50 | 1M | 10 | 2.5 to 5.5 | $\begin{gathered} \text { DIP, SO, } \\ \text { 14-pin } \\ \text { SO } \end{gathered}$ | Page mode, programmable write protect | \$1.10 |
|  | ST24C02A | 2k | 256x8 | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 1 M | 10 | 5 | DIP, SO | Page mode, sequential read, programmable write protect | \$0.84 |
|  | ST25C02A | 2k | 256x8 | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 1M | 10 | 2.5 to 5.5 | DIP, SO | Page mode, sequential read, programmable write protect | \$1.10 |
|  | ST93CS56 | 2k | $128 \times 16$ | Microwire | 1 MHz | 2 | 50 | 19 | 10 | 5 | $\begin{gathered} \text { DIP, SO } \\ 14 \text {, pin } \\ \text { SO } \end{gathered}$ | Page mode, programmable write protect | \$0.94 |

## Notes:

1. Operating voltages have $\pm 10 \%$ tolerance unless a range is shown.
2. DIPs listed are 8 -pin, dual in-line packages unless noted, SOs are 8 -pin, small-outline packages unless noted, and COB means chip on board.

| Company | Part | $\begin{array}{\|l\|} \hline \text { Size } \\ \text { (bits) } \\ \hline \end{array}$ | Organization (bits) | Interface compatibility | Serial clock rate | \|Supply current |  | Endurance (cycles) | $\left\|\begin{array}{c} \text { Data } \\ \text { reten- } \\ \text { tion } \\ \text { (years) } \end{array}\right\|$ | Operating voltage range ${ }^{1}$ (volts) | Package styles ${ }^{2}$ | Special features | $\begin{array}{\|c} \text { Price } \\ (10,000) \\ \text { (DIP) } \end{array}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | Active (mA) | Standby ( $\mu \mathrm{A}$ ) |  |  |  |  |  |  |
| SGS- <br> Thompson Microelectronics (continued) | ST93CS57 | 2 k | $128 \times 16$ | Microwire | 1 MHz | 2 | 50 | 1 M | 10 | 2.5 to 5.5 | $\begin{gathered} \text { DIP, SO, } \\ \text { 14-pin } \\ \text { SO } \end{gathered}$ | Page mode, programmable write protect | \$1.40 |
|  | ST24C04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 1M | 10 | 5 | $\begin{aligned} & \text { DIP, 14- } \\ & \text { pin SO } \end{aligned}$ | Page mode, sequential read, programmable write protect | \$1.85 |
|  | ST25C04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 2 | 100 | 1M | 10 | 2.5 to 5.5 | $\begin{aligned} & \text { DIP, } 14- \\ & \text { pin SO } \end{aligned}$ | Page mode, sequential read, programmable write protect | \$2.40 |
| Signetics | PCF8581 | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1.6 | 10 | 10k | 10 | 5 | DIP, SO | Page mode, sequential read | \$0.94 |
|  | PCF8581C | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1.6 | 10 | 10k | 10 | 2.5 to 6 | DIP, SO | Page mode, sequential read | \$0.94 |
|  | PCF8582B | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1.6 | 10 | 500k | 10 | 5 | $\begin{gathered} \hline \text { DIP, SO, } \\ \text { 16-pin } \\ \text { SO } \end{gathered}$ | Page mode, sequential read | \$0.99 |
|  | PCF8582C | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1.6 | 10 | 500k | 10 | 2.5 to 6 | DIP, SO, 16-pin SO | Page mode, sequential read | \$0.99 |
| Xicor | X24C01 | 1k | $128 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | DIP, SO | 3.3 V and 3.5 to 5.5 V versions available | \$0.65 |
|  | X24C01A | 1k | 128×8 | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | DIP, SO | 3.3 V and 3.5 to 5.5 V versions available | \$0.77 |
|  | X24C02 | 2k | $256 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | DIP, SO | 3.3 V and 3.5 to 5.5 V versions available | \$0.94 |
|  | X24C04 | 4k | $512 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | DIP, SO, <br> 14-pin SO | 3.3 V and 3.5 to 5.5 V versions available | \$1.55 |
|  | X24C08 | 8k | $1024 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | DIP, SO, 14-pin SO | 3.3 V and 3.5 to 5.5 V versions available | \$2.40 |
|  | X24C16 | 16k | $2048 \times 8$ | ${ }^{12} \mathrm{C}$ | 100 kHz | 1 | 50 | 100k | 100 | 5 | $\left\|\begin{array}{c} \text { DIP, SO, } \\ \text { 14-pin } \\ \text { SO } \end{array}\right\|$ | 3.3 V and 3.5 to 5.5 V versions available | \$3.36 |

Notes:

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2. DIPs listed are 8 -pin, dual in-line packages unless noted, SOs are 8 -pin, small-outline packages unless noted, and COB means chip on board.

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# $3^{1 / 2}$-in. optical drive offers MO and read-only modes 

The OD-3000 optical disk drive lets designers buy optical technology in the increasingly popular $3^{1 / 2-i n}$. form factor. The multifunction drive uses read/write MO (magneto-optical) technology and reads O-ROM (optical read-only memory) disks, whose features are similar to those of $5 \frac{1 / 4-}{}$ in. CD-ROM disks. The drive stores 128 Mbytes on a removable optical disk that looks much like a $3^{1 / 2}$-in. floppy disk.

MO technology gives the OD3000 several advantages compared with $5^{1 / 4}-\mathrm{in}$. products that use other types of rewritable optical media. MO technology uses magnetic-flux transitions to store data on the physical medium. The optical system writes to the disk using a laser beam to change the magnetic polarity of data bits on the disk. Likewise, the optical system reads data by sensing the reflection of the laser beam from the surface of the disk. Disks that use MO technology can withstand 10 million write cycles and still record data reliably. Other rewritable optical technologies typically limit media to 10,000 write cycles.

The drive can also read 0-ROM disks that store prerecorded information, much like CD-ROM drives do. Mass duplication of O-ROM disks uses a stamping production technology. This technology is similar to the process used to make CD-ROM disks and audio record albums. Therefore, manufacturing costs of prerecorded O-ROM disks should soon drop to less than $\$ 2$ each.

Both CD-ROM and O-ROM disks store data via pits in the physical


A 42-msec seek time and 10-msec latency spec make the OD-3000 multifunction optical drive useful in some primary-storage applications.
medium's surface. O-ROM offers some advantages compared with CD-ROM technology, however. CD-ROMs employ a long spiral track; O-ROM disks feature a format with tracks and sectors, like magnetic disks. The track-andsector configuration results in superior seek times for computer applications. O-ROM technology also leads to a third type of medium that you can use with the OD-3000. Par-tial-ROM disks have O-ROM and rewritable technology mixed on a single surface. Users can add their own information such as graphics to the rewritable sections of a par-tial-ROM disk.
The OD-3000 features a $3000-\mathrm{rpm}$ rotational speed, which minimizes latency during seek operation. The drive's average rotational latency is 10 msec . The drive's optic components are in two different physical
locations to minimize seek time. The semiconductor laser, photodiode detector, lens, and prism are fixed in place away from the actuator arm. Only minimal optical components that provide focus and tracking functions reside on the actuator, resulting in a lower-mass actuator. The drive has a $42-\mathrm{msec}$ seek time compared with specs greater than 60 msec for some optical drives.

Other key specs include 11 W power dissipation during read/write operations and 2.6 W when the drive is inactive. A Reed-Solomon errorcorrection scheme results in less than 1 error bit per $10^{12}$ bits. The drive can read data continuously from disk at 640 kbytes/sec and write data continuously at 203 kbytes/sec. Write operations require the erase, write, and verify passes common to all rewritable optical drives and

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The drive features a 128 -kbyte buffer on the SCSI-2 controller. The controller can transfer buffered data to the host at $2 \mathrm{Mbytes} / \mathrm{sec}$ in asynchronous mode and at 5.3 Mbytes/sec in synchronous mode. The drive's MTBF spec is 30,000 poweron hours.

The key to the acceptance of $3^{1 / 2-}$ in. optical drives will eventually be price. The OD-3000 costs $\$ 1050$ ( 1000 ) and the rewritable disks cost $\$ 60$ each. The company hopes to drop the prices by $50 \%$ or more within the next 18 months.
-Maury Wright
Teac America Inc, 7733 Telegraph Rd, Montebello, CA 90640, (213) 726-0303, FAX (213) 7277621.

Circle No. 733

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## Who's Behind The Simulation Acceleration Movement?



And Who's Leading It?

# Generator owes accuracy and versatility to DSP and arbitrary-waveform technology 

Analogic Corp's 2030 harnesses technology not yet widely used in function generators to make daunting wave-form-generation tasks seem rather straightforward. You can set it up to produce complicated waveforms with no more difficulty than you can get classical generators to output sine, square, and triangular waves. Moreover, the waveforms that the unit produces exhibit unusually low distortion and few artifacts. The firm accomplishes this feat by using digital technology-DSP technol-ogy-and playing tricks such as predistorting the samples fed to the unit's D/A converter to compensate for sampling effects and for the inherently nonideal transient response of the anti-imaging filter that follows the DAC.

Hidden within the half-rackwidth enclosure is a Motorola 56001 DSP $\mu \mathrm{P}$. The $\mu \mathrm{P}$ earns its keep; it executes algorithmic routines stored in ROM and fills the generator's dual-ported memory with samples that represent the output waveforms. The algorithms are much more compact than are point-by-point signal representations; therefore the generator can store an extensive waveform repertoire. If the individual waveforms stored this way don't meet your needs, you can add the waveforms to each other and multiply them by one another. Moreover, to remove artifacts that would otherwise appear, before routing the calculated waveforms to the DAC, the $\mu \mathrm{P}$ convolves them with the reciprocal of the output filter's impulse response.
This technique and other numeric


Adding and multiplying waveforms to produce even more complex waves is a snap with the block diagrams that appear on the bit-mapped, backlit LCD screen of the 20.30 function generator. You make your selections using soft keys next to the screen.
sleights-of-hand let the generator produce a long list of modulated and swept-frequency waves-in addition to dc and the familiar sine, square, ramp, triangular, pulse, and pseudo-random-noise waveforms. The modulated waveforms include double-sideband AM (amplitude modulation) with full and suppressed carriers; single-sideband AM, also with full and suppressed carriers; FM (frequency modulation); phase modulation; exponentially decaying waves; the $\sin (\mathrm{x}) / \mathrm{x}$ function; and both linear and logarithmic sweeps.
The sine-wave distortion level, although dependent on amplitude
and frequency, is 80 dB below the output level at or below 100 kHz , regardless of amplitude. There are four amplitude ranges, from 10 mV to 10 V full scale into an opencircuit. You can set the amplitude with 4-digit resolution, and you can select either $50 \Omega$ or $600 \Omega$ output resistance.

The generator's frequency range starts at 0.001 Hz and extends to 20 MHz for sine waves and to 5 MHz for pulses and for square, triangular, and ramp waves. Pulse rise time is approximately 15 nsec at and below $100 \mathrm{~Hz} ; 10.0$ to $10.4 \mu \mathrm{sec}$ from 100 Hz to 1 kHz ; 1 to 1.04 $\mu$ sec from 1 kHz to 10 kHz ; and 46

## Why make users do this?



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The vendor's earlier waveform generators relied heavily on algebraic definition of signals. If you could represent a signal as an equation and key it in, the generator would synthesize it. With the new instrument, which has a backlit, bitmapped LCD screen, instead of fumbling with formulas, you make selections from menus of stored functions and from block diagrams of multiplication and addition operations. The unit has soft keys with functions designated by legends that appear on the screen, fixedfunction keys, a numeric keypad, and, for those who prefer it to the keypad, a rotary control.

Because it incorporates the technology of a 12 -bit-resolution arbi-trary-waveform generator, the instrument can synthesize signals that are not in its library and that are not producible by manipulating the library functions. The vendor doesn't emphasize this arbitrary-function-generation capability, however. To use it, you must load wave-form-definition files from an external source, such as a PC, via the unit's IEEE-488 or RS-232C ports. The generator includes both ports as standard equipment. The ports let you use terse commands to recall any of 15 complete setups from nonvolatile memory. You can retrieve the setups manually by pressing a few keys. The unit costs $\$ 3995$.
-Dan Strassberg
Analogic Corp, 8 Centennial Dr, Peabody, MA 01960. Phone (508) 977-3000. FAX (508) 531-1266. TLX 6817021. Doug Estrich.

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## Panther SCSI

Stalking system performance is your goal. That's why Maxtor's 1.2GB SCSI Panther was designed to perform a data seek in just 13 ms . No other drive in its class features such lightning speed.
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Experience counts. Panther uses the reliable head disk assembly used in the Maxtor XT-8000, which boasts more than 300,000 units in the field. Panther shreds the competition with the widest range of available controllers, an MTBF of $\mathbf{1 5 0 , 0 0 0}$ hours, Novell certification and a highly competitive price.
Call about the full line of Panther drives that range from 1.2 GB to more than 1.7 GB capacity. If you're stalking performance, check out Panther's killer specs.
Call your nearest Authorized Maxtor Distributor.

| 1GB-plus Disk Drive Comparison Criteria | Maxtor Panther P0-12S | Seagate Wren 7 |
| :---: | :---: | :---: |
| Capacity (unformatted) | 1.2GB | 1.2 GB |
| Seek Time | 13 ms | 15 ms |
| Track-to-Track | 2 ms | 2.5 ms |
| Internal Transfer | 17.4 to $29.7 \mathrm{Mb} / \mathrm{s}$ | $15-23 \mathrm{Mb} / \mathrm{s}$ |
| Maximum Seek | 26 ms | 34 ms |

[^5]A.D.P.I.

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## PRODUCT UPDATE

## Raster image-accelerator IC renders fonts in real time

The D7001 IC renders outline fonts in real time for graphics display and printer applications. The device is the first IC in the company's RIDA (raster image device accelerator) family of ICs that accelerate the rendering of graphic objects. It can produce outline fonts scaled to any size fast enough for laser printers to print at speeds of 17 pages/ minute and slower. The IC can also be used in mother board graphics applications to directly drive WYSIWYG display and printer engines.

The IC accepts Bezier curves, Bspline curves, and vectors. You can use the chip in Truetype, Postscript, and Intellifont page-descrip-tion-language applications. Multiple filling algorithms handle both Roman characters and Kanji glyphs, and on-chip hardware compensates for pixel dropouts-a key feature for Kanji applications in which slight changes affect the meaning of glyphs. Scaling capabilities enable the chip to produce fonts ranging in size from 0.25 to 999.99 points.

Currently, most display and printer controllers use software or
firmware to render fonts. The D7001 provides 1000 -to- 1 fontrendering acceleration compared with firmware- and software-based designs. The IC treats outline fonts as objects rather than using graphics primitives.

The IC uses on-chip parallel processors with pipelined hard-wired instruction sets (Fig 1). When producing 300 -dpi-resolution fonts at 12 points, the IC can render more than 7500 cps . Such a speed lets you implement a printer controller without the traditional 1- or multi-ple-line font cache. In fact, the IC can essentially render fonts in real time and requires only an 8 -kbyte single-character font cache.
The D7001 comes in a 144 -pin quad flatpack. Samples cost $\$ 35$. Expect production quantities to be available by year's end for $\$ 25$ (1000). The company hopes to offer a companion IC next year that can accelerate the drawing of graphic images.-Maury Wright

Destiny Technology Corp, 300 Montague Expressway, Suite 150, Milpitas, CA 95035, (408) 2629400, FAX (408) 262-0221.

Circle No. 730


Fig 1-A parallel-processor architecture lets the D7001 render outline fonts in sizes ranging from 0.25 to 999.99 points. The IC can keep up with 17-page/minute printers and requires only a single-character font cache.

Multiple-stage centrifugal fan system

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handling applications.
Just $5.7^{\prime \prime}$ in diameter, the blowers have 1 -, 2-, or 3 -stage fans for performance from $75^{\prime \prime} \mathrm{H}_{2} \mathrm{O}$ vacuum at 0 CFM to 125 CFM at $0^{\prime \prime} \mathrm{H}_{2} \mathrm{O}$. With one version, a 0 to 10 VDC signal
from a sensor or other device will control motor speed and adjust air performance from 0 to $100 \%$. Or, a second model provides manual speed control by means of a potentiometer located in the blower housing.

These blowers also feature low noise performance and are UL/ CSA component recognized. Get complete details by contacting AMETEK, Lamb Electric Division, 627 Lake Street, Kent, OH 44240. (216) 673-3451. Fax: 216-673-8994. Telex: 433-2140. Cable: LAMETEK.

## IC tester offers $200-\mathrm{MHz}$ testing for analytical applications

The Logic Master ATS test station provides characterization of new chips, failure analysis, quality assurance, and low-volume production tests for devices requiring clock rates as high as 200 MHz . Proper device characterization requires clock rates and accuracy comparable to a production tester.

Although production testers can perform characterization and other applications, they often have two drawbacks. First, they are expen-sive-the demand for high clock rates, high accuracy, and high throughput place requirements on production test systems that are difficult to achieve at any price. Because the high throughput capability of a production tester is not used during characterization, the cost of a production tester is difficult to justify. Second, because production test-system software is designed for test engineers, it's not always easy for a design engineer to use when evaluating a new chip design.

This test station is priced at $\$ 2600$ to $\$ 3200$ per pin. It offers 200-

MHz clock rates without multiplexing channels and data rates as high as $400 \mathrm{Mbits} / \mathrm{sec}$. Standard system accuracy is $\pm 500 \mathrm{psec}$. The system has 50 -psec edge-placement resolution and $\pm 100$-psec stability and linearity, allowing you to fine-tune the calibration for special applications.

The test system uses the highest performance for the pin drivers and uses custom GaAs drivers and receivers. Other parts of the tester use ECL standard-cell devices, CMOS gate arrays, and FPGAs.

The GaAs drivers let you program driver rise and fall times between 1 and 3 nsec for 5 V swings. For $600-\mathrm{mV}$ signal swings, the rise and fall times are programmable from 500 psec to 1 nsec. Each driver and comparator is independent and can have its own drive and compare levels set with $10-\mathrm{mV}$ resolution between -1.5 and +6.5 V for drive high and -2.5 and +4.5 V for drive low. Dual threshold comparators let you perform timing-window comparisons.

The tester also provides dynamic
current loads for testing output pins under real-world load conditions and for testing the time required for 3 -state outputs to switch to their high-impedance state. Two optional parametric measurement units (PMUs) are available for the tester. One is a "per-pin" PMU that uses comparators to test voltage or current levels to programmed limits. The other PMU analyzes and measures absolute current or voltage levels.

The tester operates with dual formats for channels running at twice the clock or data rate of other channels. This feature is useful when you need to test microprocessors and other devices with multiple phase clocks.

The system is hosted by a Sun workstation and has an Ethernet port for network operation. A 502Mbyte hard disk is standard.

Software included with the tester provides simulator pattern conversion, system setup, pattern generation, and graphical waveform editing. The system has built-in soft-


As many as 448 channels of $\mathbf{2 0 0}-\mathrm{MHz}$ testing is possible with the Logic Master ATS. The drivers have programmable slew rates so you can use the optimum value for your test setup.


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- Frequency Stability: $\pm 3 \mathrm{ppm}\left(-10^{\circ} \mathrm{C}\right.$ to $\left.+60^{\circ} \mathrm{C}\right)$ to $\pm 100 \mathrm{ppm}\left(-10^{\circ} \mathrm{C}\right.$ to $\left.+70^{\circ} \mathrm{C}\right)$

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## CIRCLE NO. 51

## UPDATE

ware for measuring standard device parameters such as setup, hold, and propagation-delay times. Software is also available for translating test programs written for mainframe testers.
The test station is available in two versions. The ATS 1 supports 16 to 224 I/O channels and has 12 timing generators providing 24 timing edges. The ATS 2 supports 16 to 448 I/O channels and has 24 timing generators. Each channel in either system can select timing edges from 12 timing generators. A 128-I/O-channel system with 128k-deep pattern memory costs $\$ 360,000$-Doug Conner

Integrated Measurement Systems Inc, 9525 SW Gemini Dr, Beaverton, OR 97005. Phone (503) 6267117. FAX (503) 644-6969.

Circle No. 732


## JUST ASK

Have you been stumped by a design problem? Can't interpret a spec sheet? Ask EDN. Our editors are ready to help.
The Ask EDN column serves as a forum to solve nagging problems and answer difficult questions. EDN's editors will provide the solutions. If we can't solve a problem, we'll find an expert who can, or we'll print your letter and ask your peers for help.
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Notes: 1. A series resistor is required to limit continuous input current to 50 mA (peak current can be higher).
2. Rated input current is 25 mA for all tests.
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4.ON resistance shown is for the bidirectional configuration. The DC ON resistance is $1 / 4$ of these values.
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## FDDI.

## From deskwork to network.

Good news for networks!
The X3T9.5 Task Group, under the procedures of ANSI Accredited

Standards Committee X3, has reaffirmed approval of the Media Interface Connector (MIC) for the proposed FDDI (Fiber Distributed
Data Interface) Physical Layer Medium Dependent (PMD) document.

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Local-area networks (LANs) are becoming as congested as our nation's highways. Packet data traveling on Ethernet LANs must share a single $10-\mathrm{Mbps}$ pathway. Packet data on a Token Ring LAN migrate at 4 or 16 Mbps . These posted speed limits can cause severe data-traffic jams during peak activity periods. The slowdowns are not only frustrating, but in some cases they can bring network activity to a virtual halt. The most expedient option to alleviate congestion is to move data faster-an option that, if employed in highway management, would have disastrous consequences.

In 1982, the X3T9.5 committee of the American National Standards Institute (ANSI) recognized these impending logjams and set about defining a set of protocols that lets packet data whiz over a LAN at 100 Mbps. This super highway is the Fiber Distributed Data Interface (FDDI). The ANSI X3T9.5 standard for FDDI defines a dual counter-rotating ring LAN that uses a fiber-optic medium and a token-passing protocol. (For definitions of FDDI terms, see box, "Glossary of FDDI terms.")

An FDDI LAN can stretch 100 km and connect more than 500 nodes spaced by as much as 2 km . In contrast, first-generation LANs such as Ethernet, defined by IEEE standard 802.3, and Token Ring, defined by IEEE standard 802.5, operate over a more limited distance. Ethernet can stretch only 2.5 km and connect as many as 1024 nodes spaced by as much as 0.5 km . Token Ring can stretch only 1.2 km and connect as many as 96 nodes spaced by as much as 0.46 km . FDDI's long distance specification coupled with its $100-$ Mbps data transmission rate make it suitable as a fast-
requirements, network designers are starting to adopt the $100-\mathrm{Mbps}$ Fiber Distributed Data Interface (FDDI). Unfortunately, FDDI stations don't come cheap.
throughput backbone that can transport data between existing LANs via gateways, bridges, and routers (Fig 1). Any network manager who is experiencing or projecting network traffic overloads should consider the pros and cons of FDDI.
The FDDI specification conforms to a general, 7-layer hierarchical model for network communications called the Open Systems Interconnection (OSI) model (Fig 2). The FDDI spec describes both a physical layer that corresponds to the OSI model's physical layer and a media-accesscontrol (MAC) sublayer that corresponds to the lower half of the OSI model's data-link layer. The spec also describes a Station Management (SMT) network supervisory function, which falls outside of the OSI model. The SMT function is implemented in software. This software resides on each station of the ring and creates logical paths between the physical layer and the MAC sublayer to permit SMT-to-SMT communications between stations. SMT software connects and disconnects the station to the ring, monitors network operations for reporting status to the host computer, isolates network faults, and detects conditions such as duplicate addresses that would inhibit ring operation.

Realizing that there would be considerable discussion about the types of fiber, connectors, and other interconnect hardware, the ANSI X3T9.5 committee decided to break the specification for the OSI physical layer into two sublayers-the Physical Medium Dependent (PMD) sublayer and the Physical (PHY) sublayer. The lower of the two sublayers, PMD, specifies the transmission wavelength to be 1300 nm . Both LEDs and lasers can emit light of this wavelength.

The PMD sublayer spec recommends $62.5 / 125-\mu \mathrm{m}$


The FDDI standard defines a dual counter-rotating ring LAN that uses fiber-optic cable and lets packet data rocket to 100 Mbps . (Photo courtesy SBE Inc, concept and photography by Imagination)

# The ANSI X3T9.5 FDDI standard defines a dual counter-rotating ring LAN that uses a fiber-optic medium and a token-passing protocol. 

(core diameter/cladding diameter) multimode cable and has advice on using 50/125-, 85/125-, and $100 / 140-\mu \mathrm{m}$ cable. The dispersion in multimode $62.5 / 125$ micron cable is small enough to ensure FDDI's $10^{-9}$ bit error rate. Debate continues over cable size. The PMD document is written so that any size cable capable of 1300 nm transmission conforms to the FDDI standard as long as the cable also meets the optical power, channel bandwidth, and distance requirements.

## Trying to reduce cable costs

However, fiber-optic cable isn't cheap, and the cost of the cable, as well as the light-emitting source, increases as the wavelength increases. In fact, the highcost associated with implementing FDDI is the major drawback to its proliferation. Codenoll Technology Corp, an FDDI-node-controller vendor, has proposed using an $830-\mathrm{nm}$ LED emitter and $830-\mathrm{nm}$ multimode cable to reduce the high materials cost of an FDDI network. The wavelength does not meet the FDDI standard, but the company claims that the only effect
of the wavelength change is the shortening of the maximum allowable distance between nodes from 2 to 0.5 km .

A working group of the ANSI X3T9.5 committee is trying to lower FDDI costs by developing a PMD spec that uses less-expensive shielded twisted-pair (STP) copper wire as the medium while maintaining FDDI speeds. The specification would specify a much shorter distance between nodes-probably less than 100 m and replace optical transceivers and connectors with lower-cost STP connectors. STP is also attractive because many facilities already have STP copper wire installed for Ethernet LANs.

Because an ANSI standard for STP communication is not expected until late 1992, five companiesAdvanced Micro Devices, Chipcom Corp, Digital Equipment Corp, Motorola Inc, and Synoptics Communications Inc-recently defined and published an STP standard for $100-\mathrm{Mbps}$ data. Products conforming to this standard, which is open for public use, will be able to communicate with each other.

Copper wire costs much less than fiber cable, but


Fig 1-A 100-Mbps FDDI backbone can interconnect multiple disparate LANs using gateways, bridges, and routers.
metal-based networks are susceptible to electromagnetic interference and are less secure than fiber-optic communications-two of FDDI's big pluses. In addition, because FDDI's ring topology demands that each station operate as a repeater, nonstandard PMD implementations can't be used on the FDDI backbone.

## Group encoding limits bandwidth

PHY, the upper sublayer of FDDI's physical-layer specification, defines a 4B/5B group-encoding scheme for representing 4 -bit data and control symbols. The scheme doesn't use Manchester encoding, which is typical of other LAN protocols. Manchester encoding would require a $200-\mathrm{MHz}$ clock to transmit $100-\mathrm{Mbps}$ data. The $4 \mathrm{~B} / 5 \mathrm{~B}$ group-encoding scheme requires the transmission of a 5-bit code word for each 4-bit symbol, thereby achieving a $125-\mathrm{Mbps}$ rate. The code word is converted to a nonreturn-to-zero-inverted (NRZI) signal for network transmission. The PHY sublayer also defines how to decode the $4 \mathrm{~B} / 5 \mathrm{~B}$ NRZI signal from the network into symbols that the station can recognize.


Fig 2-The FDDI specification defines three sublayers that correspond to the data-link and physical layers of the 7 -layer OSI model. FDDI also specifies an SMT function, which supervises sublayer and ringmanagement operations.


FDDI specifies a media interface connector (MIC) to attach a station to the dual ring. Formation Inc's Fibernet fv1000 node controller for the VMEbus has two MIC connectors. The controller can operate as a dual- or single-attachment station.

Because an NRZI signal has no transitions when all zeros are present in the data, the $4 \mathrm{~B} / 5 \mathrm{~B}$ encoding scheme guarantees that data have no more than three consecutive zeros. Although the encoding scheme uses less bandwidth than Manchester encoding, clock recovery is more difficult. Therefore, instead of using one master clock to generate data as the IEEE 802 standards specify, PHY sublayer specifies that each station in the FDDI ring regenerate the data with a frequencystable reference to prevent frequency-jitter from accumulating around the ring. Each station has a phaselocked loop, which clocks the received data into an accordion buffer, and a crystal-controlled frequency source, which clocks the data out of the buffer.

## MAC sublayer delivers frames

The FDDI media-access-control (MAC) sublayer defines the token-passing protocol for data transmission over the ring. The MAC spec defines packet-frame fields such as headers, trailers, addresses, and cyclic redundancy checking (CRC). An FDDI informationpacket frame comprises a preamble having 16 or more IDLE (5-bit group code of all 1s) symbols, a 2 -symbol
start-of-frame field, a 2-symbol frame-control field that identifies the packet type, a 16- or 48-bit destination address, a 16- or 48-bit source address, the information field, a 32-bit CRC field, a 1-symbol end-of-frame field, and a frame-status field. The maximum packet size is 4500 octets. (Ethernet has 1514 octets max, and Token Ring has 8191 octets max.)

Stations wanting to transmit data over the ring must first obtain a unique 6 -symbol token. The Timed Token Rotation (TTR) protocol requires each station to measure the time elapsed since it last received this token. An initialization procedure guarantees fairness by establishing a target token-rotation time (TTRT) that each station must observe. When a station has the token, it can transmit synchronous data during the TTRT. If the next station receives the token before the previous station's TTRT expires, the station can transmit frames asynchronously during the leftover time.

The MAC sublayer is responsible for controlling the flow of data. Each station's MAC sublayer monitors a
packet's destination address, copies the packet into the station's memory if the packet is addressed to the station, and then relays the packet to the next station on the ring. The sending station's MAC sublayer deletes the packet once it comes full circle.

## Chip set implements FDDI sublayers

Three vendors currently offer chip sets that implement the FDDI MAC and PHY sublayers-Advanced Micro Devices, National Semiconductor, and Motorola. These chip sets interface directly to the logical-linkcontrol (LLC) sublayer of the OSI model's data-link layer. All vendors offering stations that connect to an FDDI network employ one of these chip sets. The stations implement the SMT functions in software or firmware. Most stations employ the media interface connector (MIC) defined in the FDDI PMD specification. The MIC is a shrouded fiber-optic coupling in which a male plug terminates the cable and a female receptacle resides on the FDDI module. Some stations employ an ST connector to reduce cost. The ST connec-

## Glossary of FDDI terms

ANSI: American National Standards Institute.
Backbone network: A primary network that interconnects two or more secondary networks via gateways, bridges, and concentrators.
BNC: Baby n connector.
bps: Bits per second.
Concentrator: A node on the FDDI ring that provides connections for multiple FDDI stations to communicate with other stations on the dual ring.
Connection management (CMT): That portion of the SMT software that controls station insertion and removal as well as the connection of a station's PHY and MAC sublayers.
CRC: Cyclic redundancy checking.
Data-link layer: The OSI layer that implements data transfer between two stations on an FDDI network.
Dual-attachment station (DAS): A station that provides two physical attachments to accommodate the dual counter-rotating FDDI ring.
Fiber Distributed Data Interface (FDDI): A standard for a $100-\mathrm{Mbps}$ token-ring LAN based on a fiber-optic medium. The ANSI X3T9.5 standard employs a dual counter-rotating ring, which provides fault tolerance. FDDI conforms to the OSI model.

IEEE: Institute of Electrical and Electronics Engineers.
LAN: Local-area network.
LED: Light-emitting diode.
Logical link control (LLC) sublayer: The upper sublayer of OSI's data-link layer. The LLC sublayer controls the flow of data.
Media access control (MAC) sublayer: The lower sublayer of OSI's data-link layer. The MAC sublayer is responsible for scheduling frames for data transmission over the FDDI ring.
Media interface connector (MIC): The specified FDDI fiber-optic connector. The connector has two $2.5-\mathrm{mm}$ ceramic ferrules within a shrouded assembly. An MIC plug terminates the cable, and an MIC receptacle resides on the FDDI attachment.
Network layer: The OSI layer responsible for routing, switching, and internetworking access.
Nonreturn to zero inverted (NRZI): A signal code that represents a logical 1 by a polarity transition and a logical 0 by no transition.
Octet: A data unit comprising eight bits. An octet represents a pair of data symbols.
Open Systems Interconnection (OSI) model: A general, 7-layer model that defines a hierarchy of services necessary to exchange information between


You can configure some FDDI node controllers, such as the V/FDDI 4211 Peregrine board for the VMEbus, as single- or dual-attachment stations. The Interphase Corp board uses the Advanced Micro Devices FDDI chip set.
tor is a spring-loaded twist-and-lock coupling similar to a BNC connector.

FDDI permits two types of stations: Class A and Class B. Class A stations are dual-attachment stations (DAS), which have dual physical layers that connect to the primary and secondary rings in FDDI's dual counter-rotating ring topology. All the stations attached to the FDDI's dual-ring backbone must be Class A stations. A Class A station on the dual-ring backbone
can function in one of three ways: as a node controller that adapts a computer or peripheral to the ring, as a concentrator that acts as the hub of a star topology when connecting multiple FDDI stations to the ring, or as an internetworking module, such as a gateway, bridge, or router. Class B stations are single-attachment stations (SAS) and have a single physical layer. They attach to a concentrator's SAS port (Fig 3) and can be node controllers or internetworking modules.

Although the FDDI specification doesn't prohibit Class A stations from transmitting data on both the primary and the secondary ring, this mode of operation isn't wise. Theoretically, you could double the datatransmission rate to 200 Mbps by using both rings, but you would defeat one of FDDI's most attractive features. FDDI's secondary ring is meant to provide fault tolerance, which is a critical need in highperformance applications. If a fault occurs in the primary ring, the SMT ring-management protocol recognizes that the TTRT is violated and notifies the network manager. The SMT software isolates the fault
computers. The International Organization for Standardization (ISO) defined the model in 1979 as a framework for defining network protocols.
PC: Personal computer.
Physical (PHY) sublayer: FDDI's upper sublayer that corresponds to the OSI model's physical layer. This sublayer is responsible for delivering symbols from the MAC sublayer to the FDDI network.
Physical layer: The OSI layer that permits the physical connection of a station to a LAN.
Physical Medium Dependent (PMD) layer: FDDI's lower sublayer that corresponds to OSI's physical layer. The PMD sublayer specifies optical power, cable specifications, the MIC connector, and optical bypassing.
RAM: Random-access memory.
Ring management (RMT): That portion of the SMT software that manages a station's MAC sublayer. RMT software detects faults, such as duplicate addresses, at the MAC layer.
Shielded twisted pair (STP): Describes copper wire commonly used in LANs.
Simple Network Management Protocol (SNMP): Software for managing a TCP/IP network.
Single-attachment station (SAS): A station that
offers one attachment to an FDDI network. Station: An addressable node on an FDDI network that is capable of transmitting, repeating, and receiving information.
Station management (SMT): Describes the supervisory software that monitors an FDDI station and controls station activity.
ST connector: A fiber-optic connector employed in many fiber-optic LANs. The AT\&T connector contains a ceramic ferrule encased in a twist-and-lock assembly similar to a BNC connector.
Target token-rotation time (TTRT): The maximum time an FDDI station has to transmit data on the ring. The TTRT is established by the lowest bidding station during an initialization process.
TCP/IP: The US Department of Defense's Arpanet suite of protocols for implementing the transport and network layers of the OSI model.
Token: A unique 6 -symbol frame that circulates around the FDDI ring. A station must have the token to transmit data.
$4 B / 5 B$ : The symbol encoding method specified by the FDDI standard in which each set of four bits is encoded as five bits.
and wraps the upstream primary ring into the downstream secondary ring to reconstruct a ring network.

Multiple failures on the ring can segment the network. In these rare cases, the network manager may have another ring-reconstruction option at his or her disposal. The PMD specification provides for an optional optical bypass switch that can be activated to bypass a Class A station completely. Activating the optical bypass switch would let the network manager service the faulty station off line.

FDDI stations can be node controllers, concentrators, or internetworking modules. Node controllers are adapter boards for popular computer buses, such as the ISA bus, VMEbus, and Multibus (Table 1). One of the three commercially available FDDI chip sets provides the PHY and MAC sublayers for the station. The board's PMD hardware determines whether the node controller is an SAS or a DAS. A node controller generally has a microprocessor unit and enough RAM to run the LLC sublayer and offload communications tasks from the host computer.

Some node controllers contain EPROM for SMT
firmware; others download the SMT software into the onboard RAM. All of these boards communicate with the host at the network layer of the OSI model. Although the ANSI committee has not yet drafted protocols for the network layer, the TCP/IP suite of protocols is the most popular method for transferring files. FDDI node controllers support other network-layer protocols as well.

Concentrators play a crucial role in an FDDI network by letting you connect multiple stations to an FDDI backbone via one DAS port (Table 2). FDDI defines four types of concentrator ports: A, B, S, and M ports. The A and B ports provide the DAS connection to the dual ring. The M (master) and S (slave) ports let you cascade concentrators and SAS stations in tree topologies. A concentrator can have as many as 255 M ports. These ports can connect to the primary or secondary FDDI ring or to an S port on another concentrator.

Concentrators are either computer bus boards or stand-alone chassis containing expansion boards. Because a concentrator is a critical link for connecting


NOTE: DAS=DUAL-ATTACHMENT STATION: SAS=SINGLE-ATTACHMENT STATION.

Fig 3-You can attach multiple Class B stations to an FDDI dual ring by using a concentrator. Class A stations have dual-attachment-station (DAS) ports, which connect directly to the dual ring.

Table 1-Representative FDDI node controllers

| Company | Model | Computer Bus | Protocol support | Microprocessor unit | FDDI chip set | Connector type | Power | RAM buffer | Interoperability tests ${ }^{1}$ | Price | Features |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CMC | $\begin{array}{\|l\|} \hline 1150 \\ \text { Series } \end{array}$ | VMEbus (6U) | TCP/IP (onboard SMT firmware) | Am29000 | AT\&T (PHY), AMD (MAC), CMC (LLC) | ST (SAS or DAS) | 32.5W | 2 Mbytes | ANTC | $\left.\begin{array}{\|c\|} \$ 11,245 \\ \text { to } \\ \$ 11,955 \end{array} \right\rvert\,$ | Link-level firmware interfaces to hostbased TCP/IP. Microprocessor unit can implement networkand transport-layer protocols on board. Integrated SMT and SNMP software. |
|  | $\begin{array}{\|l\|} \hline 1050 \\ \text { Series } \end{array}$ | VMEbus (9U) | TCP/IP (onboard SMT firmware) | Am29000 | AMD | ST (SAS or DAS) | 140W | 1 Mbyte | ANTC, UNH | $\begin{gathered} \$ 8950 \\ \text { to } \\ \$ 9950 \end{gathered}$ | Integrated SMT and SNMP software. Link-level firmware interfaces to hostbased TCP/IP. |
| Codenoll Technology Corp | Code-net9540 | EISA or ISA bus | TCP/IP | None | AMD | MIC (SAS) | 10W | 128 kbytes | None | \$4995 | Optional support for $830-\mathrm{nm}$ fiber. Optical bypass switch support. |
|  | Code-net9543 | EISA or ISA bus | TCP/IP | None | AMD | MIC (DAS) | 15W | 128 kbytes | None | \$7495 | Optional support for 830-nm fiber. Optical bypass switch support. |
| Concurrent Technologies | $\begin{gathered} \hline \mathrm{CL} \\ 386 / \\ \mathrm{DAS} \end{gathered}$ | Multibus II (6U) | TCP/IP (end of 1991) (onboard SMT firmware) | 80386 | AMD | MIC (DAS) | 45W | 4 Mbytes | None | $\begin{aligned} & \$ 7140 \\ & (100) \end{aligned}$ | Optical bypass control. Two RS232C serial ports. |
| CXi | CXMBII | Multibus II (6U) | GOSIP, TCP/IP (onboard SMT firmware) | 80386 | AMD | MIC (DAS) | NA ${ }^{2}$ | 4 Mbytes | NA | $\begin{array}{\|c\|} \hline \$ 11,280 \\ \text { to } \\ \$ 12,280 \end{array}$ | Optical bypass control. Implements Intel's iNA 960 Networking software. |
| Digital Equipment Corp | FDDI Controller 400 | XMI bus | XTP, <br> TCP/IP <br> (onboard <br> SMT <br> firmware) <br> TCPIP | 68020 | Digital (licensed to AMD and Motorola) | MIC (SAS) | 65W | 1 Mbyte | ANTC UNH | \$19,900 | Operates in VAX 6000 and VAX 9000 computers. |
|  | FDDI Controller 700 | Turbo Channel bus | TCP/IP (onboard SMT firmware) | 68000 | Digital (licensed to AMD and Motorola) | $\begin{aligned} & \text { ST, BNC } \\ & \text { (SAS) } \end{aligned}$ | 20W | 1 Mbyte | ANTC UNH | $\begin{gathered} \$ 4500 \\ \text { to } \\ \$ 6000 \end{gathered}$ | Operates in VAX 6000 and VAX 9000 computers. Board supports shielded twisted-pair connections. |
| Formation Inc | $\begin{array}{\|l\|} \hline \text { Fiber- } \\ \text { net } \\ \text { fv1000 } \end{array}$ | VME bus (6U) | TCP/IP (onboard SMT firmware) | Am29000 | AMD | MIC (SAS or DAS) | 35W | 2 Mbytes | ANTC | $\begin{aligned} & \$ 8500 \\ & \text { (SAS) } \\ & \$ 9500 \\ & \text { (DAS) } \end{aligned}$ | Optical bypass control. VRTX operating system. Optional Sun OS drivers. |
| Interphase Corp | $\begin{aligned} & \text { M/ } \\ & \text { FDDI } \\ & 2211 \end{aligned}$ | Multibus I | SNMP, TCP/IP, XTP (onboard SMT firmware) | Am29000 | AMD | ST BNC (SAS or DAS) | 42.5W | 1.0 Mbytes | ANTC, UNH | \$8995 (SAS) $\$ 10,995$ (DAS) | Connection for dual PHY and dual MAC operation using two boards. Board supports shielded twisted-pair copper wire. |
|  | VI FDDI 4211 Peregrine | VMEbus ( 6 U or 9 U ) | SNMP, TCP/IP, XTP (onboard SMT firmware) | Am29000 | AMD | ST BNC (SAS or DAS) | NA | 1.0 Mbytes | ANTC, UNH | $\$ 8995$ (SAS) $\$ 10,995$ (DAS) | Connection for dual PHY and dual MAC operation using two boards. Board supports shielded twisted-pair copper wire. |
| SBE Inc | $\begin{gathered} \hline \text { VCOM } \\ 100 \end{gathered}$ | VMEbus (6U) | ```TCP/IP, XTP (onboard SMT firmware)``` | 68030 | National Semiconductor | ST (SAS) | 32.5W | 4 Mbytes | ANTC | $\begin{aligned} & \$ 4500 \\ & (100) \end{aligned}$ | Runs Synernetics's implementation of SMT. Two RS-232C serial ports. An optional mezzanine board provides DAS operation. |
| Summit Microsystems Corp | $\begin{aligned} & \text { smFd- } \\ & \text { AT201 } \end{aligned}$ | ISA bus | Onboard SMT firmware | None | AMD | ST (DAS) | 10W | 128 kbytes | ANTC | \$5950 | Host-to-RAM block transfer rate is 3.0 Mbytes/sec (sustained). |

Notes: 1. ANTC=Advanced Networking Test Center; UNH=University of New Hampshire.
2. $N A=n o t$ applicable.
3. See box, "Glossary of FDDI terms," for definitions of other abbreviations.
multiple stations to the ring, some concentrators have fault-tolerant power supplies and let you insert and remove boards on the backplane while the power is on-a process called live insertion. In addition to the FDDI PMD, PHY, and MAC sublayers and the SMT function, concentrators also provide the Simple Network Management Protocol (SNMP) software for managing a TCP/IP network.
Internetworking modules let you integrate multiple disparate LANs onto an FDDI backbone-in effect creating a hybrid network (Table 3). A bridge is the
oldest method for transparently interconnecting two networks. Bridges communicate at the data-link layer of the OSI model. An FDDI bridge reads each destination field in an FDDI frame to infer a destination address for the frame. By comparing this information with an address table, the bridge determines whether to ignore the frame or forward it to a station on an interconnected network.

Routers operate at the network layer of the OSI model. Routers forward data packets not based on the destination address but according to a network identi-

Table 2-Representative FDDI concentrators

| Company | Model | Housing | Faulttolerant power supply | Live insertion | Protocol support | Number of ports (max) | Power | Connector type | Interoperability tests | Price | Features |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Codenoll Technology Corp | $\begin{array}{\|l} \hline \text { Codenet- } \\ 9041 \end{array}$ | EISA or ISA bus boards | No | No | $\begin{aligned} & \text { SNMP, } \\ & \text { TCP/IP } \end{aligned}$ | 12 | 10W | MIC (SAS or DAS); ST optional | No | \$1995 <br> (soft- <br> ware); <br> \$2795 <br> (1-port <br> card); <br> \$4995 <br> (2-port <br> card) | Optional support for $830-\mathrm{nm}$ fiber. Runs on VRTX software. |
| Digital Equipment Corp | DEC concen- trator 500 | Standalone chassis | Yes | No | Protocol independent | 18 | $\begin{array}{\|c\|} \hline 120 \mathrm{~W} \\ \text { (AC } \\ \text { power) } \end{array}$ | MIC FC/PC, ST, BNC (DAS) | ANTC, UNH | $\$ 9000$ to $\$ 52,500$ | Supports shielded twisted pair and thinwire. |
| Interphase Corp | Fiber hub 800 | Standalone chassis | Yes | Yes | SNMP | 8 | NA | $\begin{aligned} & \text { MIC (SAS } \\ & \text { or DAS) } \end{aligned}$ | No | $\begin{gathered} \text { From } \\ \$ 12,000 \end{gathered}$ | Supports shielded twisted-pair and $830-\mathrm{nm}$ fiber. |
| Network Systems Corp | FDDI concen- trator | Standalone chassis | No | No | SNMP | 16 | 150W | MIC or ST | ANTC | $\$ 3000$ <br> (chassis <br> and <br> mother- <br> board) <br> $\$ 2200$ <br> (2-port <br> board) | Optional opticalbypass switch. |
| Summit Microsystems Corp | $\begin{aligned} & \text { smFD- } \\ & \text { AT301 } \end{aligned}$ | ISA bus boards | No | NA | Onboard SMT firmware | 12M ports, 2 DAS ports | 10W | ST | ANTC | $\$ 12,900$ (DAS plus four M ports); $\$ 6950$ (4-M-port card) ( | Mapped to the ISA bus I/O space. |
| Synoptics Communications Inc | 3000-05 | Standalone chassis | Optional | Yes | SNMP (onboard SMT firmware) | 40 SAS ports; 1 A/B port | $\begin{array}{\|l\|} \hline 460 \mathrm{~W} \\ \text { supply } \end{array}$ | MIC | No | $\$ 4495$ (hous- ing); $\$ 14,995$ (network- manage- ment module); $\$ 7495$ (4-M-port FDDI card); $\$ 4995$ (4-M-port STP card) | Backplane accepts cards for connection to FDDI, Ethernet, and Token Ring modules. Optical bypass support. Three MAC sublayers permit dual homing to identify redundant links. |

Notes: 1. NA=not applicable; ANTC=Advanced Networking Test Center; UNH=University of New Hampshire.
2. See box, "Glossary of FDDI terms," for definitions of other abbreviations.

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fier. Routers are more versatile than bridges: They also perform packet fragmentation and reassembly, packet control, and priority routing. In some cases, both bridge and router functions are appropriate for
internetworking. In these cases, a hybrid bridge-router can provide routing services for two or more networklayer protocols or can implement a transparent datalink connection.

Table 3-Representative FDDI internetworking products

| Company | Model | Product description | Network Support | Power | Interoperability tests ${ }^{1}$ | Price | Features |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Cisco Systems Inc | AGS + | Router | Appletalk, DEC net, Novell, IPX, Token Ring, Ethernet, Cheapernet, DDN X.25, Apollo Domain, Ultranet | 500W | ANTC, UNH | \$12,300 | Routes 16 protocols over an FDDI network. Supports 9600 -bps, 48 -kbps, 56 -kpbs, 64 -kbps, T1, E1, and fractional T1 wide-area networks. Maximum aggregate forwarding rate is 75,000 packets/sec. |
| Digital <br> Equipment Corp | DEC bridge | Bridge | Ethernet, Appletalk | 390W | ANTC, UNH | $\begin{gathered} \$ 25,000 \\ \text { to } \\ \$ 45,000 \end{gathered}$ | Supports dual-homing to identify redundant links. Supports Internet protocol fragmentation. Singlemode fiber option permits $40-\mathrm{km}$ distance between stations. |
| Fibercom Inc | Ring Master 7200 | Bridge | Token Ring, Ethernet, DECnet, Novell | NA ${ }^{2}$ | NA | \$15,000 | Maximum forwarding rate is 20,000 packets/sec. Filtering rate is 500,000 packets $/ \mathrm{sec}$. Supports Internet Protocol fragmentation. Self learning for as many as 4000 addresses. Supports spanning tree algorithm. |
| Fibronics International Inc | FX8210 | Bridge | Token Ring, Appletalk, DECnet, Novell, Ethernet | 250W | ATNC, UNH | \$14,990 | Down-line loadable across networks. Performs protocol-translation bridging. Comes with Interview Network Management System software. |
|  | $\begin{aligned} & \text { FX8210B } \\ & \text { Brouter } \end{aligned}$ | Bridgerouter | Token Ring, Appletalk, DECnet, Novell, Ethernet | 250W | ANTC, UNH | \$27,000 | Down-line loadable across networks. Protocoltranslation bridging interview Network Management System. |
| In-net Corp | Fiber Talk 5000 | Bridge | Token Ring, Ethernet, DECnet | 360W | ANTC | \$17,500 | Down-line loadable across networks. Filtering rate is 100,000 packets $/ \mathrm{sec}$. Forwarding rate is 6000 packets/sec. |
|  | Fiber Talk 3000 <br> Channel Bridging Unit | Gateway | Ethernet | 360W | ANTC | \$35,000 | Down-line loadable across networks. Connects an IBM 360/370 mainframe computer to an FDDI ring. Software provides Telnet Virtual Terminal, File Transfer Protocol, and Electronic Mail services. |
| Network Systems Corp | $\begin{gathered} 6400 \\ \text { Family } \end{gathered}$ | Bridgerouter | Ethernet, DECnet, Appletalk, Novell, T1, T3 | 500W | ANTC | \$30,000 | 400-Mbps, 6-card backplane. Ethernet forwarding rate is 15,000 packets/sec/port. Supports the Spanning Tree Algorithm. Dynamically learns packet addresses. |
|  | $\begin{gathered} 6600 \\ \text { Family } \end{gathered}$ | Bridgerouter | Ethernet, DECnet, Appletalk, Novell, T1, T3 | 500W | ANTC | \$23,000 | FDDI-to-FDDI bridge. Single-board chassis. Ethernet forwarding rate is 15,000 packets $/ \mathrm{sec} /$ port. Supports the Spanning Tree algorithm. Dynamically learns packet addresses. |
|  | $\begin{gathered} 6800 \\ \text { Family } \end{gathered}$ | Bridgerouter | Ethernet, DECnet, Appletalk, Novell, T1, T3 | 500W | ANTC | \$46,000 | Supports the Spanning Tree algorithm. Deletes undeliverable packets on the network after a preset period. Dynamically learns packet addresses. 800 Mbps, 16 -card backplane. |
| Synernetics Inc | $\begin{aligned} & \text { LANplex } \\ & 5004 \end{aligned}$ | Bridgeconcentrator | Ethernet, Token Ring | NA | ANTC, UNH | \$25,500 | Backplane has three FDDI paths, three Token Ring paths, three Ethernet paths, and a VMEbus that operate in paraliel. Backplane accepts four plug-in modules. Connects as many as 24 Ethernet segments to an FDDI network. Modules support line insertion. |
|  | $\begin{aligned} & \text { LANplex } \\ & 5012 \end{aligned}$ | Bridgeconcentrator | Ethernet, Token Ring | NA | ANTC, UNH | \$32,900 | Backplane has three FDDI paths, three Token Ring paths, three Ethernet paths, and a VMEbus path that operate in parallel. Backplane accepts 12 plug-in modules. Connects as many as 24 Ethernet segments to an FDDI network. Modules support line insertion. |

Notes: 1. ANTC=Advanced Networking Test Center; UNH=University of New Hampshire.
2. $N A=n o t$ applicable.


Because FDDI is a fairly new LAN standard and multiple versions of the SMT function exist, the issue of interoperability is a concern. To ensure that FDDI stations from various vendors operate together properly, two groups are testing these FDDI products. Both the Advanced Networking Test Center, which Advanced Micro Devices sponsors, and the University of New Hampshire (Durham, NH) have test centers that run a suite of tests on vendor products they connect to an FDDI cable installation. The test centers try to ensure that there is one worldwide FDDI rather than multiple versions that don't interoperate.

If you already have an FDDI LAN installed and need an analyzer to troubleshoot the network in real
time, Digital Technology Inc offers the Lanhawk-5700 Network Analyzer family. The portable 5733 and 5732 analyzers cost $\$ 28,300$ to $\$ 50,000$ and passively couple into the ring. The analyzers monitor, analyze, and collect data on FDDI networks. They also let you collect traffic statistics to evaluate ring performance and maximize ring utilization.

## Nice-but expensive

The high cost of FDDI networks necessitates a wait-and-see attitude, but if projected trends for the 1990s pan out, network administrators may soon be upgrading existing LANs to the $100-\mathrm{Mbps}$ standard. For example, PCs are emerging that exceed the power of

## Manufacturers of FDDI products

For more information on FDDI products such as those described in this article, circle the appropriate numbers on the Information Retrieval Service card or use EDN's Express Request service. When you contact any of the following manufacturers directly, please let them know you saw their products in EDN.

| Advanced Micro Device Inc | CXi | In-net Corp | SBE Inc |
| :---: | :---: | :---: | :---: |
| Box 3453 | 10260 Old Columbia Rd | 15150 Avenue of Science | 2400 Bisso Lane |
| Sunnyvale, CA 94088 | Columbia, Maryland 21046 | San Diego, CA 92128 | Concord, CA 94520 |
| (800) 538-8450 | (301) 290-9500 | (800) 283-3334 | (800) 347-2666 |
| (408) 732-2400 | (301) 621-8588 | (619) 487-3693 | (415) 680-7722 |
| TLX 34-6306 | FAX (301) 290-7012 | FAX (619) 487-3697 | FAX (415) 680-1427 |
| Circle No. 650 | Circle No. 656 | Circle No. 662 | Circle No. 667 |
| Cisco Systems Inc | Digital Equipment Corp | Interphase Corp | Summit Microsystems Corp |
| 1525 O'Brien Dr | 550 King St | 13800 Senlac | 710 Lakeway, Suite 150 |
| Menlo Park, CA 94025 | Littleton, MA 01460 | Dallas, TX 74234 | Sunnyvale, CA 94086 |
| (415) 326-1941 | (508) 493-7161 | (214) 919-9000 | (408) 730-4900 |
| FAX (415) 326-1989 | Circle No. 657 | FAX (214) 919-9200 | FAX (408) $730-1675$ |
| Circle No. 651 |  | Circle No. 663 | Circle No. 668 |
|  | Digital Technology Inc |  |  |
| Chipeom Corp | 2300 Edwin C Moses Blvd | Motorola Inc | Synernetics Inc |
| 118 Turnpike Rd | Dayton, OH 45408 | Technical Information Center | 85 Rangeway Rd |
| Southborough, MA 01772 | (513) 443-0412 | Box 52073 | North Billerica, MA 01862 |
| (508) 460-8900 | Circle No. 658 | Phoenix, AZ 85072 | (508) 670-9009 |
| Circle No. 652 |  | (512) 928-7726 | FAX (508) 670-9015 |
|  | Fibercom Inc | Circle No. 664 | Circle No. 669 |
| CMC | Box 11966 |  |  |
| 125 Cremona Dr | Roanoke, VA 24022 | National Semiconductor Corp | Synoptics Communications Inc |
| Santa Barbara, CA 93117 | (703) 342-6700 | Box 58090 | Box 58185 |
| (805) 562-3104 | FAX (703) 342-5961 | Santa Clara, CA 95052 | Santa Clara, CA 95052 |
| FAX (805) 968-6478 | Circle No. 659 | (800) 272-9959 | (408) 764-1046 |
| Circle No. 653 |  | (408) 721-5000 | FAX (408) 988-5525 |
|  |  | FAX (408) 730-0764 | Circle No. 670 |
|  | Fibronics International Inc | Circle No. 665 |  |
| Codenoll Technology Corp 1086 N Broadway | 1 Communications Way Hyannis, MA 02601 |  |  |
| Yonkers, NY 10701 | (508) 778-0700 | Network Systems Corp |  |
| (914) 965-6300 | FAX (508) 778-0821 | 7600 Boone Ave N |  |
| FAX (914) 965-9811 | Circle No. 660 | Minneapolis, MN 55428 |  |
| Circle No. 654 |  | (612) 424-4888 |  |
|  |  | FAX (612) 424-2853 |  |
|  | Formation Inc | Circle No. 666 |  |
| Concurrent Technologies | 121 Whittendale Dr |  |  |
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## FDDI stations



The FDDI chip set from National Semiconductor implements the VCOM100 VMEbus node controller. The SBE Inc board has a microprocessor unit and enough dynamic RAM to execute SMT software as well as the network- and transport-layer protocols.

80386-based computers. These PCs can manage a sea of documents and images that were traditionally the province of mainframes and minicomputers. Many applications must send the images and data to multiple locations on a LAN that has insufficient bandwidth to handle such bit-heavy traffic. In addition, multimedia applications, which integrate voice, data, and video, require a bandwidth way beyond what Ethernet and Token Ring networks can offer.

Many analysts say FDDI deployment will occur in multiple stages. In the early stages, FDDI backbones will interconnect smaller token-ring LANs that employ existing STP copper wiring for horizontal distribution. In the later stages, companies having intensive graphics and CAD communications needs will invest in a full fiber-optic LAN. The attendant drop in FDDIproduct prices will encourage the widespread use of FDDI networks.

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# EDN'S DSP-Chip Directory 

# The tools needed to develop applications that use digital signal processing (DSP) continue to improve. Now, a choice of operating systems and interfaces to host operating systems is making DSP available to more applications. 

## David Shear, Contributing Editor

This year there are many new DSP parts that add to the array of optional word formats, peripherals, and memory sizes. Naturally these family members are created to fit an existing or perceived market. In the past, if your application didn't fit easily within an existing device, you were out of luck. Now, almost all DSP manufacturers have programs that will let you configure your own DSP $\mu$ P. You can select from the available peripherals and memory options, or you can use an ASIC approach and put a gate array on the DSP chip.

Before DSP $\mu \mathrm{Ps}$ can move into general use, however, it is essential that the functions of the algorithm developer and the end-user-application developer are separated. It is hard enough for algorithm developers to keep up with DSP algorithm development. It is rare for them to have the luxury of maintaining expertise in the creation of end-user applications that use the latest whiz-bang graphical user interface.

Likewise, the end-user-application developer must be able to concentrate on his applications. He must not be distracted with new algorithms and DSP $\mu$ Ps. That is the algorithm-developer's domain.

Ideally, a DSP operates as if it is just another peripheral. When the end-user-application developer uses a hard disk, he doesn't have to know how the data is
stored on the disk. He just wants to use the hard-disk function: store data and retrieve it later.

Using a DSP must be the same. The algorithms must be available via a well-defined and standard method. If the end-user application needs a modem or a fax, speech or an image compressed, or whatever, the developer must be able to call the DSP as if he were sending data to a disk.

Right now, if an engineer creating an end-user application wants the application to use a DSP $\mu \mathrm{P}$, he must devote a significant amount of effort (and time) to create the DSP portion of the project. At the same time, he has less time to develop his product. It doesn't make sense-in terms of time and effort-for him to spend months, or more, getting up to speed in DSP.

## New software interfaces

Soon, software interfaces between your DSP $\mu \mathrm{P}$ and the end-user application will let you develop DSP code that the end-user-application developer can use off the shelf. A separate group, or even a separate company, can use the DSP functions that you create. OSPA (Open-Signal Processing Architecture) from Spectron Microsystems (Santa Barbara, CA) and VCOS from AT\&T are two current interfaces.

OSPA is a set of interfaces and protocols that lets
your DSP $\mu \mathrm{P}$ communicate with an end-user application. You must use the Spox real-time, multitasking operating system on the DSP $\mu \mathrm{P}$.

Spox was introduced by Spectron Microsystems three years ago. It was first introduced to run on TI's TMS320C30. Spox has grown in acceptance to include Motorola's DSP96002, Analog Devices' ADSP-21020, and TI's TMS320C40.

Spox runs on the DSP $\mu \mathrm{P}$ while the Spox Server runs on the host. The DSP functions that you write interface to the end-user application via the Spox Server. Host- and DSP- $\mu$ P independence is achieved if you create OSPA-compatible DSP programs and use the Spox server. Your DSP $\mu \mathrm{P}$ can be transported to any computer that has a Spox Server for the host operating system.

## Separate the experts

David Wong, president of Spectron Microsystems, says that Spox and OSPA separate the functions of the end-user-application developer and the algorithm developer (Fig 1). By using high-level commands and data-stream conventions described by OSPA, you can develop the application software and the real-time DSP functions independently.

Even if the end-user application moves to another host computer, the Spox server for the new host operating system lets you transport your DSP $\mu \mathrm{P}$. You can also use more powerful DSP $\mu$ Ps as they become available to create more capable DSP solutions. The end-user-application developer will then be able to use the more capable DSP solution without modifying his code.

The near industry-wide acceptance of OSPA and Spox places them in a great place to become the standard. The host independence of OSPA and the DSP- $\mu \mathrm{P}$ independence of Spox further strengthens their positions.

VCOS is another approach to separate your efforts from the end-user application. Frank Ferro, DSP Mar-
keting Manager at AT\&T, says that VCOS is not intended to be an operating system that is all things to all people. It is an approach to implement AT\&T's 32 -bit floating-point DSP3210 on the mother board of a PC or workstation.

The major emphasis of VCOS is to make the hardware implementation of the DSP3210 inexpensive and the software easy to create. The DSP3210 interfaces directly to Motorola and Intel $\mu \mathrm{P}$ buses and shares the host memory. This approach does away with the cost of high-speed static RAM (SRAM).

The VCOS kernel is a small program (fewer than 40032 -bit words) that runs on the DSP $\mu \mathrm{P}$. It handles execution control, caching, and buffer I/O. The VCOS Application Server runs on the host, loads and links the DSP tasks, and performs all memory-management functions. A debugger and library are also included to ease development.

The DSP program is loaded into the internal RAM of the DSP $\mu \mathrm{P}$. The internal RAM is used to run the program, usually in sections. The DSP $\mu$ P has access to the host memory where it can store data. Taking over the slower host bus reduces the performance of both the DSP $\mu \mathrm{P}$ and the host $\mu \mathrm{P}$. But AT\&T claims that the performance of both is not reduced significantly.

Two workstations already have DSP $\mu \mathrm{Ps}$ on the mother board: Next Inc's Next and Silicon Graphics' Iris Indigo computers both have Motorola's DSP56001.
Many chip vendors feel that it is too early to place the DSP $\mu \mathrm{P}$ on the mother board, and that add-in boards should be used for some time. The workstation market will see DSP chips on the mother board first. The workstation market traditionally has proprietary systems and can make its own decisions about how to implement a DSP $\mu$ P. Apple also has considerable control over what will end up on the mother board of its Macs. The PC market is different-with so many different manufacturers, it will take some time before a consensus is reached.

Acronyms used in this article and in the chip directory
ADC-analog-to-digital converter
ALU-arithmetic and logic unit
ASIC-application-specific inte-
grated circuit
CMOS-complementary metal-oxide
semiconductor
CPU-central processing unit
CQFP-ceramic quad flat pack
DAC-digital-to-analog converter
DIP-dual in-line package
DMA-direct memory access
DSP-digital-signal processing
EPROM-erasable PROM

ADC-analog-to-digital converter ALU-arithmetic and logic unit ASIC-application-specific integrated circuit CMOS-complementary metal-oxide semiconductor CPU-central processing unit CQFP-ceramic quad flat pack DAC-digital-to-analog converter -dual in-line package DSP-digital-signal processing EPROM - erasable PROM

FFT-fast Fourier transform
FIFO-first in, first out
FIR-finite-impulse response
IC-integrated circuit
IIR-infinite-impulse response
I/O-input-output
JTAG-Joint Test Action Group
$\mu \mathrm{P}$-microprocessor
NMOS-n-type metal-oxide semiconductor
OSPA-Open-Signal Processing Architecture
PC-personal computer

PGA-pin-grid array
PLCC-plastic leaded chip carrier
PLL_phase-locked loop
PQFP-plastic quad flat pack
PROM-programmable read-only memory
QFP-quad flat pack
RAM-random-access memory
ROM-read-only memory
SOP-small-outline package
Spox-real-time multitasking operating system

It is doubtful that the next year will bring a DSP $\mu \mathrm{P}$ to the mother board of a majority of computers. But watch for a number of announcements along these lines. Within a few years, applications will require these high speed devices.

## DSP in real time

If you need a real-time operating system that can run directly on the DSP $\mu \mathrm{P}$ in embedded applications, you have the choice of Spox for floating-point chips and VRTX32 for Motorola's fixed-point DSP56001. Bryant Wilder, Motorola's DSP operations manager, says that VRTX32/DSP56000 from Ready Systems (Sunnyvale, CA) is the only real-time operating system available for fixed point DSP $\mu$ Ps. It is basically the same as the other versions of VRTX32, which have been available on a number of $\mu \mathrm{Ps}$ for many years. Users of VRTX32 can use their existing tools and experience and just add the DSP56000 version.

## High-level-language options grow

Whichever operating system you choose, you will still be able to take advantage of the productivity gains from using a high-level language. By far, the most common high-level language for DSP $\mu$ Ps is C. Nearly all of the floating-point DSP $\mu$ Ps have an ANSI C compiler. You can also use an Ada compiler. Eric West, C40 Marketing Manager at TI, says that the company plans to develop a Fortran compiler for the C30 and C40.

C is not standing still. ANSI C (more appropriately called Standard C) allows program transportability. But there are an ever growing array of C variations,

Numerical C, Concurrent C, C,$++ \mathrm{C}^{*}$, and GNU C, to name a few.

Numerical C is intended to make C more applicable to calculation-intensive applications, like DSP. Tim Counihan, strategic marketing manager for DSP at Analog Devices, says that Analog Devices is actively supporting Numerical C. He feels that the standard is well enough defined to produce a product. He does admit that Analog Devices will probably have to make some changes by the time a standard is available. The Numerical C Extensions Group (NCEG) is working within ANSI (X3J11.1) on a technical report, not a standard, so an actual standard is still in the future.

Other DSP- $\mu \mathrm{P}$ manufacturers are not supporting Numerical C yet. They are waiting for either their customers to request it or a standard to be available. TI says the company will definitely support Numerical C when it becomes a standard.

All of the C compilers for DSP $\mu \mathrm{Ps}$ claim to be optimizing compilers. It is difficult to determine how well the optimizing compilers will work in your application. You will often have to optimize some sections of your high-level code by hand. On one recent project, a DSP consulting group was able to prototype the system with C code in a matter of hours. This C version proved the concept, but would only run at 12 frames/ sec . The customer needed 15 frames $/ \mathrm{sec}$. The group spent three months optimizing the code to meet the 15 frames/sec requirement.
The Comdisco (Foster City, CA) DSP Procoder is an option to the company's Signal Processing Worksystem (SPW). The SPW is a block-diagram-based devel-


Fig 1-Separating the DSP function developer from the end-user application developer lets each expert concentrate on his speciality.

## EDN's DSP-chip directory

opment system. The DSP Procoder will take a block diagram of a DSP algorithm and create assembly code. Comdisco claims the resulting code is productionquality. The DSP Procoder presently uses Motorola's DSP56001. Other fixed-point DSP $\mu$ Ps will be used in the future.

Multiprox is another option for SPWs used to partition a block diagram to run on multiple processors. When used with the Code Generation System, you can automatically produce C code for multiple floatingpoint DSP $\mu$ Ps. The generated code includes the inter-processor-communication code to pass data between the processors. The TMS320C30, TMS320C40, and DSP96002 are supported.

## Need quadruples performance every 18 months

As soon as you finish designing a product, you will often be called upon to start the next generation. Rick Rinehart, floating-point DSP marketing manager at Texas Instruments, points out that the market window today averages about 18 months. The market window is the length of time from when a company introduces a product until they begin ramping down production. Each new generation of a product needs about a four times increase in performance to remain competitive. The improvements in design and processes used to build ICs will double performance every three years. Rinehart feels the only way to meet the quadrupling performance needs of their customers is with parallel processing.

Making products that can see, talk, and listen is difficult. Much of that type of development is possible

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| Zoran | 34325 | 32-bit floating-point | 133 |  |  |

today, but it requires expensive parallel processing systems. Prices will continue to drop until today's expensive systems become tomorrow's low cost peripherals. For example, the TMS32010 started sampling at $\$ 500$. Now you can buy them in single quantities for $\$ 4.90$.

EDN

Article Interest Quotient (Circle One)
High 494 Medium 495 Low 496

## Key to abbreviations used in block diagrams

AB-combined program and data
address bus
ACC-accumulator
ADC/DAC-analog-to-digital and
digital-to-analog converter
ADDR GEN-address generator
ALU-arithmetic logic unit
BIT MANIP-bit manipulation
BS-barrel shifter
CDB-control data bus
CM-cache memory
CPUB-CPU bus
DAB-data address bus
DB-combined program and data bus
DDB-data data bus
DM-memory for data only
DMAAB-DMA address bus
address bus
ACC-accumulator
ADC/DAC-analog-to-digital and digital-to-analog converter
ADDR GEN-address generator
ALU-arithmetic logic unit
BIT MANIP - bit manipulation
BS-barrel shifter
CDB-control data bus
CM-cache memory
CPUB-CPU bus
DAB-data address bus
DB-combined program and data bus
DDB-data data bus

DMAAB-DMA address bus

DMADB-DMA data bus DMAC-direct-memory-access controller
FX-fixed-point
FP-floating-point
GDB - global data bus
HOST INTER-host interface
IDB-instruction data bus
INT-external interrupt
MAC-multiplier accumulator
MULT-multiplier
PAB-program address bus
PDB-program data bus
P/DM-memory for program and data
PIO-parallel I/O
$\mathbf{P M}$-memory for program only

PPCP-parallel processor communication port
PRAB-peripheral address bus
PRDB-peripheral data bus
REG-register
REGB-register bus
SIO-serial I/O
TIM-timer
XAB-external address bus
XDB - external data bus
XDAB-external data address bus
XDDB - external data data bus
XIOAB - external I/O address bus
XIODB - external I/O data bus
XPAB - external program address
bus
XPDB-external program data bus

## ADSP2100 FAMILY

## 16-BIT FIXED-POINT CMOS DSP $\mu \mathrm{P}$

AVAILABILITY: The ADSP2100/A, 2101, 2102, 2106, 2111, 2112 are in production now. The 21 msp 50 and the 21 msp 51 are now sampling.

COST: ADSP2100, $\$ 45$ (1000); 2101, $\$ 36$ (1000); 2102, \$34 (5000); 2105, \$9.90; 2106, \$11.39 (25,000); 2111, \$48 (1000); 2112, \$46 (5000); 21msp50, \$57 (1000); 21msp51, \$40 (25,000).
SECOND SOURCE: None.

DESCRIPTION: The ADSP2100 family ranges from the 2100 with no on-chip memory and an off-chip Harvard architecture to the 21 msp 51 with program and data ROM, data RAM, and peripherals, including an analog-to-digital and digital-to-analog

Analog Devices Inc
1 Technology Way
Norwood, MA 02062
(617) 461-3074

Circle No. 671


FEATURES: 60-, 77-, 80-, 100-, 125-, and 167-nsec cycle-time versions.
Separate on-chip program and data buses. On-chip memory: The 2100/A has no on-chip memory. The 2101 has a $2 k \times 24$ bit program RAM and a $1 \mathrm{k} \times 16$-bit data RAM. The 2102 has a $2 k \times 24$-bit program ROM or RAM and a $1 \mathrm{k} \times 16$-bit data RAM. The 2105 has a $1 \mathrm{k} \times 24$-bit program RAM and a $512 \times 16$-bit data RAM. The 2016 has a $1 \mathrm{k} \times 24$-bit program ROM or RAM and a $512 \times 16$-bit data RAM. The 2111 and 21 msp 50 have a $2 \mathrm{k} \times 24$-bit program RAM and a $1 \mathrm{k} \times 16$-bit data RAM. The 2112 has a $2 \mathrm{k} \times 24$-bit program ROM or RAM and a $1 \mathrm{k} \times 16$-bit data RAM. The 21 msp 51 has a $2 \mathrm{k} \times 24$-bit program RAM, $2 \mathrm{k} \times 24$-bit program ROM, and a $1 \mathrm{k} \times 16$-bit data RAM.
Separate program and data buses brought off the chip only on the 2100/A. All other parts combine program and data buses off the chip.
Off-chip memory capacity: The 2100/A has $32 \mathrm{k} \times 24$-bit program and $16 \mathrm{k} \times 16$-bit data memory capacities. All others have $16 \mathrm{k} \times 24$-bit program and $16 \mathrm{k} \times 16$-bit data memory capacities.
Boot memory controller loads program from external byte-wide EPROM (except 2100/A).
On-chip peripherals: The 2100/A has no on-chip peripherals. The 2101 and 2102 have two serial I/O ports and a timer; the 2105 has one serial I/O port and a timer. The 2111/2 have two serial $1 / O$ ports, a timer, and a host interface port.
The 21 msp 50 has two serial $1 / 0$ ports, a parallel $1 / O$
port, a timer, and a 16 -bit ADC/DAC (linear codec).
Multiplier/accumulator accepts 16-bit fixed-point input and creates 32 -bit fixed-point results within a 40 -bit accumulator. 16 -bit ALU. 32 -bit bidirectional barrel shifter. 40-bit accumulator.
Multiplier/accumulator, ALU, and shifter are separate blocks connected by the 16 -bit R-bus and the data bus.
Zero-overhead looping.
Only the $2100 /$ A has a $16 \times 24$-bit on-chip cache.
Direct, indirect, immediate, circular, and bit-reversal addressing modes.
Two address generators.
No on-chip DMA. Serial port and codecs have auto buffer, which transparently transfers data to and from memory.
16-level hardware stack. Status stack limits interrupts to four levels of nesting on the 2100/A, seven levels on the others.
Four external interrupts on the 2100/A; three external interrupts on others.
The 2100/A has only hardware wait states. Others have only software-programmable wait states.
No on-chip emulation port.
Only the 21 msp 50 has power-down mode to CMOS standby levels. The 2101, 2105, 2106, 2111, and 2112 have an idle mode, which lowers power until an interrupt is detected.
Packaging: 2100/A, 100-pin PQFP and 100-pin PGA. 2101/2, 68 -pin PGA and 68 -pin PLCC. 2105/6, 68-pin PLCC. 2111, $100-$ pin PQFP and $100-$ pin PGA. $21 \mathrm{msp} 50 / 1,100-$ and $132-$ pin PQFPs, 144-pin PGA.

## HARDWARE

## SUPPORT

Full-featured in-circuit emulator.
Low-cost in-circuit emulator board.
Demo board.
Evaluation packages.
Third-party support: Contact Analog Devices for a list of thirdparty vendors.

C compiler.
Simulator.
Macroassembler/linker.
Application libraries.
Upcoming Numerical C.

## 16-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: The DSP16, 16A, and 16C are in production. The DSP1610 and 1616 are sampling with production starting in 1992.
COST: DSP16, \$9.60; DSP16A, \$16.70; DSP1610, \$125; DSP1616, \$35 $(10,000)$.
SECOND SOURCE: None.

AT\&T Microelectronics
Dept 52AL040420
555 Union Blvd
Allentown, PA 18103
(800) 372-2447, ext 802;
in Canada, (800) 553-2448, ext 802
Circle No. 672

DESCRIPTION: The members of the DSP16 family have long been the fastest fixed-point DSP chips. The DSP16A has a 25 -nsec cycle time. The DSP16A and DSP16C also have the largest on-chip program memory at $12 \mathrm{k} \times 16$ bits. Many applications that would require external ROMs with other DSP chips can fit within the DSP16 family's on-chip memory. The DSP16C
has an A/D and a D/A converter on chip. The DSP16C also has a 4 -pin JTAG interface, which assists in testing tightly packed boards. A 3.3 V version of the DSP16A is available. The DSP1610 and 1616 are enhanced versions intended for digital cellular telephones.


FEATURES: $25-, 33-$, $55-$, and $75-\mathrm{nsec}$ cycle-time versions. The DSP16C has 38.5 - and 76.9 -nsec cycle-time versions.
Separate on-chip program and data buses.
On-chip memory: The DSP16 has a $2 \mathrm{k} \times 16$-bit program ROM and a $512 \times 16$-bit data RAM. The DSP16A and -16 C have a $12 \mathrm{k} \times 16$-bit program ROM and a $2 \mathrm{k} \times 16$-bit data RAM. The DSP1610 has a $512 \times 16$-bit boot ROM and an $8 \mathrm{k} \times 16$-bit dual-port RAM. The DSP1616 has a $12 \mathrm{k} \times 16$-bit ROM and a $2 \mathrm{k} \times 16$-bit dual-port RAM.
The program ROM on the DSP16 can be replaced with as many as 64 k words of external memory.
The program ROM on the DSP16A and 16C can be replaced or augmented with as many as 64 k words of external memory.
The DSP1610/1616 can access two external 64k address spaces.
Parallel and serial I/O port.
The DSP16C has an on-chip codec.
The DSP1610 and 1616 have an on-chip timer.
The multiplier accepts 16 -bit fixed-point data and creates 32 -bit
fixed-point results within a 36 -bit accumulator.
32-bit ALU.
Only the DSP1610 and 1616 have a 36 -bit barrel shifter and bit-manipulation instructions.
Two 36 -bit accumulators.
Zero-overhead cache looping as many as 127 times.
15 -word instruction cache.
Immediate, register-indirect, and circular addressing modes.
No on-chip DMA.
Single-level hardware stack is software expandable into main memory.
One external interrupt.
DSP1610 has hardware and software wait states. DSP1616 has software wait states.
DSP1610 and 1616 have on-chip emulation ports.
The DSP16A, 16G, 1610, and 1616 have power-down mode.
The DSP1616 will run from 3.3 to 5 V .
Packaging: DSP16 and 16A, 84-pin PLCC or 133-pin PGA. DSP16C, 100-pin PQFP. DSP1610, 132-pin PQFP. DSP1616, $100-$ pin PQFP or PLCC.

Development system with in-circuit emulation.
Evaluation board that plugs into a PC.

Assembler/linker.
Simulator.
Application library.
Third-party support includes filter-design packages. Contact AT\&T for a list of third-party vendors.

## 16-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: Now.
COST: 40 MHz , $\$ 104.50$ (180); 60 MHz , $\$ 135.85$ (180). SECOND SOURCE: None.

Motorola Inc
Microprocessor Products Group
6501 William Cannon Dr
Austin, TX 78735
(512) 891-2030

FAX (512) 891-3874
Circle No. 673

DESCRIPTION: The 56156 is a 16 -bit subset version of the 56001. It is intended for cellular telephone and other communication applications. It has a built-in codec and phases-locked
loop. Development tools are similar to the 56001 and the 96002 . The 56156 has been available to select customers and is now moving into general availability.


FEATURES: 33 - and $50-$ nsec cycle-time versions
Three address buses and three data buses.
On-chip memory includes a $2 \mathrm{k} \times 16$-bit program RAM and a $2 \mathrm{k} \times 16$-bit data RAM.
ROM-based version (DSP56156ROM) contains a $12 \mathrm{k} \times 16$-bit program ROM.
Separate external program and data memory spaces. Each can address $64 \mathrm{k} \times 16$-bit locations.
Can load program from external EPROM.
Asynchronous and synchronous serial I/O ports.
Parallel port can interface with a host $\mu \mathrm{P}$.
Has on-chip PLL.
On-chip, sigma-delta voice-band codec.
Multiplier accepts 16 -bit data and returns 40 -bit results to 40 -bit accumulator.

ALU performs arithmetic operations on 40 -bit data and logical operations on 16-bit data.
No barrel shifter.
Two 40-bit accumulators.
Zero-overhead looping.
Immediate, direct, indirect, circular, and bit-reversed addressing modes.
No DMA support.
Two external vectored interrupts.
Has on-chip emulation.
Low-power mode.
Packaged in a 112-pin CQFP

Application-development system includes in-circuit emulator Contact Motorola for a list of third-party vendors.

Macro cross-assembler.
Linker.
Application-development board.

## 24-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: Now.
COST: DSP56001: $27 \mathrm{MHz}, \$ 52.00(180)$ and 33 MHz , $\$ 62.40$ (180); DSP56002: in PGA, \$166 (180) and in CQFP, \$91 (180).

SECOND SOURCE: None.

Motorola Inc<br>Microprocessor Products Group<br>6501 William Cannon Dr<br>Austin, TX 78735<br>(512) 891-2030<br>FAX (512) 891-3874<br>Circle No. 674

DESCRIPTION: The 56001 provides one 24-bit data word and two 56 -bit accumulators. This extended precision lets the chip process 16 -bit data more easily than the 16 -bit machines can. The 24 -bit word width eases scaling, and the 56 -bit accumu-
lators prevent overflow. The 24-bit data width suits digital audio applications. The 56002 is a high-speed, low-power, low-voltage version of the 56001, which is $100 \%$ software compatible, and includes a PLL and on-chip emulation.


FEATURES: 60- and 74-nsec cycle-time versions.
Three address buses and four data buses.
Separate address buses for program ROM and the two data RAMs.
Separate data buses for program ROM, the two data RAMs, and global data.
On-chip memory includes a $512 \times 24$-bit program RAM, a $32 \times 24$-bit boot ROM, dual $256 \times 24$-bit data RAMs, and dual $256 \times 24$-bit data ROMs.
ROM-based version (56000) available.
Three separate memory spaces ( $\mathrm{X}, \mathrm{Y}$, and P). Each can address $64 \mathrm{k} \times 24$-bit locations.
Can load program from external EPROM.
Asynchronous 8 -bit serial I/O port.
Synchronous 8 - to 24 -bit serial interface.
Parallel port can interface with a host $\mu \mathrm{P}$
56002 has on-chip PLL.
Multiplier accepts 24 -bit data and returns 48 -bit results to 56 -bit accumulator.

ALU performs arithmetic operations on 56 -bit data and logical operations on 24 -bit data.
No barrel shifter.
Two 56 -bit accumulators.
Zero-overhead looping.
Immediate, direct, indirect, circular, and bit-reversed addressing modes.
Two address generators.

## No DMA support.

System stack is 15 -levels deep, but can be read by program to extend stack into main memory.
Two external vectored interrupts on 56001 , three on 56002.
Hardware and software-programmable wait states.
Only the 56002 has on-chip emulation.
Low-power mode.
56002 operates on 2.0 to 5.5 V power supplies.
Packaging: 56001, 132-pin CQFP or 88 -pin PGA. 56002, 132-pin
PGA, CQFP, or PQFP.

## HARDWARE

Application-development system includes in-circuit emulator. Contact Motorola for a list of third-party vendors.

C compiler
GNU C compiler and source-level debugger.
Macro cross-assembler.
Linker/librarian.
Simulator.
Code translator from TMS320C10 to 56001.
Third-party support includes filter-design software, and VRTX32/DSP56001 real-time operating system.

## 16-BIT FIXED-POINT DSP $\mu$ P

AVAILABILITY: The 77C25 is available now. A 3 V operation version is planned for 1992.
COST: 77C25, \$9 (5000); 77P25, \$45 (1000); 77P25C, \$20 (1000).

SECOND SOURCE: Oki Semiconductor (Sunnyvale, CA) also makes the 7720 .

NEC Electronics
401 Ellis St
Mountain View, CA 94039
(800) 632-3531;
(415) 965-6158

FAX (800) 729-9288
Circle No. 675

DESCRIPTION: The 77 C 25 is an upgrade of the 7720 , which was one of the first successful DSP chips. The basic architecture is out of date and its memory can't be expanded off chip. The
manufacturer says there is still interest in new 77 C 25 designs because of the chip's low cost. The 77P25 is an EPROM version of the 77C25. The 77P25C is a one-time-programmable version.


FEATURES: 100- and 122-nsec cycle time.
Single address bus only for program memory.
Pointers address data memory.
Single data bus for both program and data.
On-chip memory: The 77 C 25 has a $2 \mathrm{k} \times 24$-bit program ROM, a $256 \times 16$-bit data RAM, and a $1 \mathrm{k} \times 16$-bit data ROM. The 77 P 25 has the same memory as the 77 C 25 , but replaces ROM with EPROM.
No external memory expansion.
One 8-bit serial I/O port.
Parallel I/O port.
Multiplier accepts 16 -bit fixed-point data and produces 31 -bit fixed-point results within two 16 -bit accumulators.
16-bit ALU.

No barrel shifter.
Two 16 -bit accumulators.
No zero-overhead looping.
No address generators.
No on-chip DMA controller.
4-level stack stores the program counter during subroutines and interrupts and is not expandable.
Single external interrupt.
No wait states.
No on-chip emulation port.
No low-power mode.
Packaged in 28-pin DIP, 28-pin PLCC, 44-pin PLCC, and 32 -pin SOP.

Evaluation kit for application development also functions as incircuit emulator.

Assembler/linker.
Third-party simulator available.

## 24-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: 100- and 122-nsec versions available now. COST: \$27 (1000).
SECOND SOURCE: None.

NEC Electronics
401 Ellis St
Mountain View, CA 94039
(800) 632-3531; (415) 965-6158

FAX (800) 729-9288; (415) 965-6130
Circle No. 676

DESCRIPTION: The 77220 is a scaled-down version of the 32-bit floating-point 77230 . The chip size and pin count are reduced by using 24 -bit data and removing the floating-point exponent hardware. The 24 -bit word width suits the digital audio market. The instruction set is a subset of the 77230 and is
source-code compatible with the floating-point device. The vendor says the 77220's architecture is optimized for adaptive filter applications. The 77P220R EPROM version and the 77P220L one-time-programmable version are for prototyping and lowvolume applications.


FEATURES: 100- and 122-nsec cycle-time versions.
Separate on-chip program and data buses.
On-chip memory includes a $2 k \times 32$-bit program ROM, dual $256 \times 24$-bit data RAMs, and a $1 \mathrm{k} \times 24$-bit data ROM.
Off-chip memory can be expanded to $8 \mathbf{k} \times 32$-bit program memory and $8 \mathrm{k} \times 24$-bit data memory.
One serial I/O port.
Parallel I/O port can be used as host $\mu \mathrm{P}$ interface.
Multiplier accepts 24 -bit fixed-point data and creates 47 -bit fixed-point results within a 47-bit accumulator.
47-bit ALU.
47-bit bidirectional barrel shifter.

Eight 47-bit accumulators.
Direct, indirect, immediate, circular, and bit-reversal addressing modes.
Three address generators.
No on-chip DMA.
Hardware stack is eight levels deep and is not expandable.
Two external interrupts.
No supported wait states.
No on-chip emulation port.
No low-power mode.
Packaged in a 68 -pin PGA or 68 -pin PLCC.

## HARDWARE

SUPPORT
SOFTWARE
Evaluation kit and PC evaluation board
Assembler/linker.
Simulator.
C compiler available by mid 1992.

## ST18930/31/32/42

## 16-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: Now.
COST: ST18930, \$15 (10,000); ST18931, \$75 (100); ST18942, $\$ 35(10,000)$; ST18R942, $\$ 80$ (100). The ST18932 is only available for ASIC designs.
SECOND SOURCE: None.

SGS-Thomson Microelectronics
1000 E Bell Rd
Phoenix, AZ 85022
(602) 867-6340

Circle No. 677

DESCRIPTION: The ST18 family consists of four devices. The ST18930 and 31 are CMOS versions of the NMOS original with a few enhancements and twice the speed. The ST18932 is a core for custom DSP $\mu \mathrm{Ps}$. The CMOS ST18942 offers
further enhancements in its arithmetic capabilities, addressing modes, and I/O functions. All family members can operate on complex and double-precision data. The ST18932 and 42 have a 32 -bit ALU and 16-bit data buses.


FEATURES: The ST18930 and 31 have $80-n s e c ~ c y c l e ~ t i m e s . ~$ The ST18932 has a $50-\mathrm{nsec}$ cycle time. The ST18942 has a $100-$ nsec cycle time.
Two address buses and four data buses on chip.
On-chip memory: The ST1 8930 has a $3 \mathrm{k} \times 32$-bit program ROM, a $192 \times 16$-bit data RAM, a $128 \times 16$-bit data RAM, and a $512 \times 16$-bit data ROM. The ST18931 has the same memory as the ST18930, but without ROM. The ST18942 has a $4 \mathrm{k} \times 32$-bit program ROM, two $256 \times 16$-bit data RAMs, and a $512 \times 16$-bit data ROM. The ST18R942 is a ROMless version of the ST18942 and has two $256 \times 16$-bit and one $128 \times 16$-bit data RAMs.
$64 \mathrm{k} \times 32$-bit external program memory (except ST18930).
The ST18930 and 31 have $4 \mathrm{k} \times 16$-bit external data memory space. The ST18932 has $8 \mathrm{k} \times 16$-bit external data memory. The ST18942 and ST18R942 have $64 \mathrm{k} \times 16$-bit external memory.
Only the ST18942 has both a serial I/O port and a parallel I/O port.
ST18932 and 42 multipliers accept 16-bit fixed-point data and return 32 -bit fixed-point results to 32 -bit accumulator. The ST18930 and 31 return 16-bit results.
In complex mode, the multiplier multiplies two complex numbers in two cycles.

16-bit ALU in ST18930 and 31. 32-bit ALU in ST18932 and 42.
16 -bit bidirectional barrel shifter in ST18930 and 31. 32-bit bidirectional barrel shifter in the ST18932 and 42.
ST18930 and 31 have two 16-bit accumulators. ST18932 and 42 have four 32 -bit accumulators.
Zero-overhead looping.
Immediate, direct, indirect, and circular addressing modes.
ST18942 has on-chip DMA.
ST18930 and 31 have a 1-level, ST18932 has a 2-level, and ST18942 has an 8 -level hardware stack for interrupts and subroutines. All can be expanded into main memory with software.
Three external interrupts on the ST18930 and 31 and eight on the ST18932 and 42.
Hardware and software-programmable wait states.
Only the ST18932 has on-chip emulation port.
Low-power mode.
Packaging: ST18930, 48-pin DIP and 52-pin PLCC. ST18931, 124-pin PGA. ST18942, 160 PQFP. ST18R942, 160 PQFP and 144-pin PGA.

[^6]Macroassembler/linker.
Simulator.


Your deadline is looming. The budget stopwatch is ticking. The scope and the complexity of your project are mounting. To weed out your design problems, you need sophisticated system analysis and integration tools which run on your Sun workstation.
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## NHRODUGE YOURSFAF TOTHE ALLNヨMEONNGVILE

If you've always believed the only way to get an agile, aero-styled, high-performance sedan was to buy small, you're in for a big surprise. It's time to forget the past, and get to know the all-new 1992 Pontiac Bonneville. ${ }^{\circledR}$

Under its beautifully redesigned shape lurks a potent 170 horsepower 3.8L 3800 with tuned port sequential fuel injection locked onto an advanced 4-speed automatic. Available amt-lock brakes and a precisionengineered, road-gripping sport suspension for outstanding control, stopping or steering. Available advanced traction comtroll for superb power application on slippery surfaces. Bonneville even
features a standard driverss airbag, for additional safety assurance.

That's the technical side. But to really get the feel of the new Bonneville, you've got to get behind the wheel. Notice how the solid-feeling controls react smoothly to the touch. How the analog gauges are well-defined for quick, decisive reads. How the whole cockpit is driver-oriented, and designed for performance. Then remind yourself this is a
furl/-sizzed four-door sedan that can easily and comfortably carry six adults.

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## 16-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: The C10, C15, C16, C17, E14, E15, E17, P15, P17, P14, LC15 (3.3V), and LC17 (3.3V) are available now. The C14 will be available in the fourth quarter of 1991.
COST: C10 (20 MHz), \$4.90; C10 (25 MHz), \$6; C14, \$9; E14, \$45; P14, \$22; C15 (20 MHz), \$7; C15 (25 MHz), \$6; E15 (20 MHz), \$35; E15 (25 MHz), \$45; P15, \$20; C16, \$9; E17, \$38; P17, \$20 (1000).
SECOND SOURCE: Microchip Technology (Chandler, AZ) for the C10, C14, and E14. No second source for other parts.

Texas Instruments Inc
Semiconductor Group, SC-001
Box 809066
Dallas, TX 75380
(800) 336-5236, ext 700

Circle No. 678

DESCRIPTION: This first generation of the vendor's DSP family was introduced in 1982. Although this family is difficult to use and slower than similar devices, the chips' cost-which has dropped to $\$ 3$ in high volumes-and the large body of associated software and expertise will keep this family going.

Newer family members have additional memory and peripheral options. EPROM (TMS320E1X) and one-time-programmable (TMS320P1X) versions are also available. 3.3 V versions of the C1X family are now available.


FEATURES: 114-, 160-, 200-, and 280-nsec cycle-time versions. Separate on-chip program and data buses.
On-chip memory: The C10 has a $1.5 \mathrm{k} \times 16$-bit program ROM and a $144 \times 16$-bit data RAM. The C14, C15, and C17 have a $4 \mathrm{k} \times 16$-bit program ROM and a $256 \times 16$-bit data RAM. The E14, E15, and E17 have a $4 \mathrm{k} \times 16$-bit program EPROM and a $256 \times 16$-bit data RAM. The C16 has an $8 \mathrm{k} \times 16$-bit program ROM and a $256 \times 16$-bit data RAM. P1X versions are one-time programmable.
Program and data buses are combined off chip.
$4 \mathrm{k} \times 16$-bit total external memory, except the C16, which has $64 \mathrm{k} \times 16$-bit external memory, and the C17, which has no external memory.
On-chip peripherals: The $\mathrm{C} 10, \mathrm{C} 15$, and C 16 have parallel $\mathrm{I} / \mathrm{O}$. The C14 has serial and parallel I/O. The C17 has two serial $\mathrm{I} / \mathrm{O}$ ports, parallel I/O, and a compander.

Multiplier accepts 16 -bit fixed-point data and creates 32 -bit fixed-point results within a 32 -bit accumulator.
32-bit ALU.
16-bit left barrel shifter.
Single 32-bit accumulator.
No zero-overhead looping.

## No DMA

4-level hardware stack except the C16, which has an 8 -level hardware stack.
Single external interrupt.
No wait states.
No on-chip emulation.
LC1X devices operate at 3.3 V .
Packaging: C10, 40-pin DIP or 44-pin PLCC. C14, 40-pin DIP or 44 -pin PLCC. C15, 40 -pin DIP or 44 -pin PLCC. C16, 64 -pin QFP. C17, 40-pin DIP or 44-pin PLCC.

## In-circuit emulator.

Evaluation module.
Software-development system.
Many third-party support tools. Contact Texas Instruments for a list of third-party vendors.

Assembler/linker.
Simulator.
Application library.
Many third-party support tools.

## 16-BIT FIXED-POINT CMOS DSP $\mu$ P

AVAILABILITY: The C25, C26, and E25 are available now. The C50 and C51 are sampling now and will be in production in the fourth quarter of 1991.
COST: C25 (33 MHz), \$14; C25 (40 MHz), \$15; C25 ( 50 MHz ), \$17; E25, \$55; C26, \$16; C50, \$130; C51, \$40 (1000).
SECOND SOURCE: None.

Texas Instruments Inc
Semiconductor Group, SC-9053
Box 809066
Dallas, TX 75380
(800) 336-5236, ext 700

Circle No. 679

DESCRIPTION: These chips make up the second generation of the vendor's DSP family. They offer higher performance than the first-generation chips and are easier to use. For many applications, the C25's price has dropped to a point where the chip is replacing the C1X. The C5X parts are enhancements to the

C 25 . They use the same basic core architecture as the C25, but have double the performance level, additional on-chip peripherals, and expanded memory. An EPROM version of the C25, the E25, is also available.


FEATURES: The C2X chips come in 78 -, 98 -, and $125-\mathrm{nsec}$ cycle-time versions. The C5X chips come in 35 - and 50 -nsec cycle-time versions.
On-chip memory: The C25 has a $4 \mathrm{k} \times 16$-bit program ROM and a $544 \times 16$-bit data RAM. The C26 has a $1.5 \mathrm{k} \times 16$-bit program RAM with boot ROM to load programs from external memory and a $544 \times 16$-bit data RAM. The C50 has a $9 \mathrm{k} \times 16$-bit program/data RAM and a $1056 \times 16$-bit dual-access RAM. The C51 has an $8 \mathrm{k} \times 16$-bit program ROM, a $1 \mathrm{k} \times 16$-bit program/ data RAM, and a $1056 \times 16$-bit dual-access RAM.
Program and data memory are combined off chip.
The C2X and C5X can address $64 \mathrm{k} \times 16$-bit programs and $64 \mathrm{k} \times 16$-bit data memories.
The C25 and C26 have one serial port each. The C5X has two serial ports.
Multiplier accepts 16 -bit fixed-point data and creates 32 -bit fixed-point results within a 32 -bit accumulator.
32-bit ALU.
The C5X has a separate 16-bit parallel logic unit for manipulating bits without affecting the contents of the accumulator.

16-bit left barrel shifter.
Single 32-bit accumulator.
Next-instruction-repeat looping. Only the C5X has zerooverhead block looping.
Immediate, direct, indirect, and bit-reversal addressing modes. C5X also has circular addressing.

## No DMA.

8-level expandable hardware stack.
C5X has a 1-level-deep shadow RAM, which stores some registers.
C2X has three external interrupts; C5X has five.
Hardware wait states. C5X also has software-programmable wait states.
The C5X has an on-chip emulation port.
The C2X is source-code compatible with the C5X.
The C5X has a JTAG interface.
The C25 and C26 have an idle mode. The C5X has a power-down mode.
Packaging: C25 and C26, 68-pin PGA or PLCC. C50, 132pin QFP.

## HARDWARE

Both the C2X and C5X have an in-circuit emulator. Both also have a software-development board for PCs.
Many third-party support tools. Contact manufacturer for a list of third-party vendors.

C compiler for both C25 and C5X.
Source-level debugger for C5X.
Assembler/linker.
Simulator.
Application library.
Many third-party support tools.


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## 32-BIT FLOATING-POINT CMOS DSP $\mu \mathrm{P}$

AVAILABILITY: The ADSP21020 is available now.
COST: \$147 (1000).
SECOND SOURCE: None.

Analog Devices Inc 1 Technology Way Norwood, MA 02062
(617) 461-3074

Circle No. 680

DESCRIPTION: This device is the vendor's first floating-point DSP $\mu$ P. It has an off-chip Harvard architecture and is similar to the fixed-point 2100 family. On-chip emulation supported via
a JTAG port. The device conforms to the IEEE-754 floating-point standard.


FEATURES: 40-, 50-, and 66-nsec cycle-time versions.
One 32 -bit and one 24 -bit address bus.
One 40 -bit and one 48 -bit data bus.
Seven 40-bit additional buses in the CPU.
Separate program, and data buses (off-chip Harvard Architecture).
$4 \mathrm{G} \times 40$-bit external data memory and $16 \mathrm{M} \times 48$-bit external program memory.
One 32-bit timer.
IEEE-754 32-bit and 40-bit floating-point format.
Multiplier accepts 32 -bit and 40 -bit floating-point data and returns 32 -bit or 40 -bit results. 32 -bit fixed-point operands produce 64 -bit fixed-point products. The multiplier also incorporates dual 80 -bit fixed-point accumulators.
ALU accepts 32 -bit and 40 -bit floating-point data and returns 32 -bit or 40 -bit results. 32 -bit fixed-point operands produce 32-bit results.
Parallel multiplier and ALU operate in single cycle.

32-bit bidirectional barrel shifter
32 40-bit register-based accumulators.
Zero-overhead looping.
$32 \times 48$-bit instruction cache.
Cache optimizes performance by selecting only 3-bus-operation instructions for storage in cache. Cache can be frozen to keep often-used instructions in cache.
Register, direct, indirect, immediate, relative, circular buffer, and bit-reversed addressing modes. Two independent address generators.
The hardware stack is 20 deep and can be expanded into main memory.
Four external vectored interrupts.
Four bidirectional I/O flags.
Hardware and software programmable wait states.
JTAG support of in-circuit emulation.
Idle state for low-power mode.
Packaging: 223-pin PGA, plastic and ceramic. PQFP available in 1992.

## SOFTWARE

Full-speed in-circuit emulator.
Demo board for PCs.
Evaluation package.
Third-party support: Contact Analog Devices for a list of thirdparty vendors.

Optimizing ANSI C and Numerical C compilers.
Source-level debugger for ANSI C and Numerical C.
Simulator, assembler, linker, PROM splitter.
Application libraries.
Third-party support includes Spox, filter-design packages with code generation, and block-level algorithm development packages.

## DSP32C/3210

## 32-BIT FLOATING-POINT CMOS DSP $\mu$ P

AVAILABILITY: The DSP32C is available now. The DSP3210 is sampling now with production by the fourth quarter of 1991. COST: DSP32C, $\$ 70(1000)$. DSP3210, $\$ 50(100,000)$. SECOND SOURCE: None.

AT\&T Microelectronics
Dept 52AL300240
555 Union Blvd
Allentown, PA 18103
(800) 372-2447;
in Canada, (800) 553-2448
Circle No. 681

DESCRIPTION: The DSP32C has one of the simplest architectures of the 32 -bit floating-point DSP chips. It uses a single 4 M -word linear-memory space instead of the separate program and data memory common in other DSP chips. The single address bus and single data bus can be accessed as many as
four times per cycle. Each internal memory can be accessed as many as two times per cycle. The DSP3210, along with the VCOS operating system, is intended for use on the mother board of PCS and workstations, where it shares memory with the host.


FEATURES: $80-$ and 100 -nsec cycle-time versions.
Single address and data buses. Each can be accessed as many as four times per cycle to imitate separate buses.
DSP32C has three on-chip $512 \times 32$-bit RAMs. Optional ROMbased DSP32C replaces one RAM with a $4 \mathrm{k} \times 32$-bit ROM. DSP3210 has two $1 \mathrm{k} \times 32$-bit RAMs and a $256 \times 32$-bit boot ROM.
The DSP32C can address as much as $4 \mathrm{M} \times 32$-bits of external memory. The DSP3210 can address 4 Gbytes of external memory.
All memory is a general resource; both program and data can exist anywhere.
Data addressable as 8 -, 16 -, or 32 -bit words.
DSP3210 can load program from external EPROM.
The DSP32C has on-chip serial and parallel I/O. The DSP3210 has serial I/O, timer, DMA controller, and a 32 -bit bus interface that is compatible with Motorola and Intel $\mu$ Ps.
The serial $I / O$ is a double-buffered port that allows concurrent input and output of 8 -, 16-, 24-, or 32-bit data widths.
The DSP32C has an 8 - or 16 -bit parallel I/O port that an external $\mu \mathrm{P}$ can control.
Proprietary 32-bit floating-point format.
Single-cycle conversion to/from nonstandard DSP32 floatingpoint format from/to IEEE-754 floating-point format.
Multiplier accepts 32 -bit floating-point data and creates 45 -bit floating-point results.
Separate floating-point adder accepts 40 -bit floating-point data and creates 40 -bit floating-point results.
Fixed-point ALU accepts 16 - or 24 -bit data.
Does not have a barrel shifter.
Four 40-bit accumulators.
Zero-overhead looping. As many as 2048 repeats of a block with a maximum size of 32 words.
Immediate, memory-direct, register-direct, register-indirect, and bit-reversal addressing modes.
DMA can be used with both the serial I/O and the parallel I/O.
No hardware stack.
1-level-deep shadow RAM of some registers.
Two external interrupts.
Hardware wait states. DSP3210 has software-programmable wait states.
No on-chip emulation port.
Only the DSP3210 has a low-power mode.
DSP32C packaged in a 164 -pin PQFP, 133-pin PGA, or 68 -pin PLCC (microcontroller version, no external memory).

In-circuit emulator.
IBM PC-based development board.
VME bus-based development board.
Many third-party support tools, including the HP64773 in-circuit emulator from Hewlett-Packard. Contact AT\&T for a list of thirdparty vendors.

Optimizing C compiler.
Assembler/linker.
State simulator.
VCOS operating system.
Many third-party support tools.

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## Raytheon

## 32-BIT FLOATING-POINT CMOS DSP $\mu$

AVAILABILITY: Available now. Enhanced revision available the first quarter of 1992.
COST: 96002 ( 33 MHz ), $\$ 368$; 96002 ( 40 MHz ), $\$ 441$.
SECOND SOURCE: None.

Motorola Inc
Microprocessor Products Group
6501 William Cannon Dr
Austin, TX 78735
(512) 891-2030

FAX (512) 891-0400
Circle No. 682

DESCRIPTION: The 96002 is an architectural superset of the fixed-point 56001. The 96002 continues Motorola's emphasis on precision. The 96 -bit accumulators will support future double-precision parts. The 32-bit floating-point device conforms to the IEEE-754 floating-point standard. The dual 32 -bit external buses support glueless multi-96002 systems. The ex-
ternal buses can access external memory and peripherals or communicate with a host $\mu$ P. A revision of the 96002 provides some enhancements, including increased speed and letting the internal RAM act as an instruction cache. It will remain software compatible with the existing 96002.


FEATURES: $50-$, $60-$, and $74-\mathrm{nsec}$ cycle-time versions. $50-$ nsec cycle-time version scheduled for the fourth quarter of 1991.

Three 32-bit address buses and five 32-bit data buses on chip.
Separate address buses for program and the two on-chip RAMs.
Separate data buses for program, the two on-chip RAMs, global data, and DMA.
On-chip memory includes a $1 \mathrm{k} \times 32$-bit program RAM, a $64 \times 32$ bit boot ROM, dual $512 \times 32$-bit data RAMs, and dual $512 \times 32$-bit data ROMs.
On-chip boot ROM loads program from external byte-wide EPROM.
Revised version will let the internal $1 \mathrm{k} \times 32$-bit program RAM function like an instruction cache.
Two complete 32-bit external expansion ports for memory and $\mathrm{I} / \mathrm{O}$.
Three separate memory spaces (X, Y, and P). Each can address 4G words.
Each memory space is divided into eight 0.5 G -word areas. Each can be programmed to either the A or B expansion ports.
Two host interfaces allow interface to $\mu \mathrm{P}$ or other 96002s. No other on-chip peripherals.

IEEE-754 32-bit floating-point format.
Multiplier accepts 32 -bit floating-point data and returns 44 -bit results. Multiplier accepts 32 -bit integer data and returns 64-bit results.
32-bit bidirectional barrel shifter.
Ten 96 -bit or thirty 32 -bit register-based accumulators.
Zero-overhead looping.
Immediate, direct, indirect, circular, and bit-reversal addressing modes.
Two address ALUs.
Supports DMA. Uses its own internal bus and doesn't cyclesteal. Can use all of the addressing modes, including bitreversal, with the DMA controller.
The stack is 15 levels deep and can be expanded into main memory.
Three external vectored interrupts.
Hardware and software-programmable wait states.
Serial debug port for in-circuit debugging.
Low-power mode.
Packaged in a 223-pin PGA. 256-pin CQFP available in 1991.

## HARDWARE - SUPPORT

## SOFTWARE

Hardware-evaluation system includes in-circuit emulator.
Some third-party hardware products are available. Contact Motorola for a list of third-party vendors.

Optimizing C compiler.
Assembler/linker.
Simulator.
Application library.
GNU C compiler and source-level debugger.
Third-party support includes optimizing C compiler, block-level diagraming language, filter-design software, and Spox.

## 32-BIT FLOATING-POINT CMOS DSP $\mu \mathrm{P}$

AVAILABILITY: The 132-pin PGA package is available now. NEC Electronics The PQFP will be available in 1992.
COST: $\$ 75$ (1000).
SECOND SOURCE: None.

401 Ellis St
Mountain View, CA 94039
(415) 965-6158;
(800) 632-3531

Circle No. 683

DESCRIPTION: The $\mu$ PD77240 is a 32 -bit CMOS floatingpoint DSP chip. The internal instruction and data ROM are preprogrammed with math matrix routines. It has two external
buses: one for data addressing up to $16 \mathrm{M} \times 32$-bit, and the other for instruction addressing up to $64 \mathrm{k} \times 32$-bit. The vendor says the architecture suits adaptive filter applications.


FEATURES: 90 -nsec cycle time.
Separate on-chip program and data buses.
On-chip memory: $2 k \times 32$-bit program ROM (preprogrammed), dual $512 \times 32$-bit data RAMs, and a $1 \mathrm{k} \times 32$-bit data ROM (preprogrammed).
External memory expansion: $64 \mathrm{k} \times 32$-bit program memory and $16 \mathrm{M} \times 32$-bit data memory.
Separate external program and data buses.
The 77240 has no on-chip peripherals.
Proprietary 32 -bit floating-point format.
Multiplier accepts 32 -bit floating-point data and creates 55 -bit floating-point results.
Multiplier accepts 24 -bit fixed-point data and creates 47 -bit fixed-point results.

47-bit ALU.
47-bit bidirectional barrel shifter.
Eight 55 -bit register-based accumulators.
Direct, indirect, immediate, circular, and bit-reversal addressing modes.
Three address ALUs.
No on-chip DMA.
The stack is eight levels deep and is not expandable.
Two external interrupts.
No wait states.
No on-chip emulation port.
No low-power mode.
Packaged in a 132-pin PGA.


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## 32-BIT FLOATING-POINT CMOS DSP $\mu$ P

AVAILABILITY: The C30 and C30-27 are available now. The C30-40, C31, and C31-27 are sampling now.
COST: C30, \$160; C30-27, \$125; C30-40, \$210; C31, \$70; C3127, \$55 (1000).
SECOND SOURCE: None.

Texas Instruments Inc
Semiconductor Group, SC-91011
Box 809066
Dallas, TX 75380
(800) 336-5236, ext 700

Circle No. 684

DESCRIPTION: This device is the floating-point member of the vendor's TMS320 family. It was the first sub-100-nsec 32-bit floating-point CMOS DSP. It is not code compatible with the fixed-point chips. The C30 is available in a slower, lower-cost version called the C30-27. The C31 is object-code compatible
with the C30 and C30-27, but has only one serial port, one parallel port, and one timer. This feature reduction decreases the chip size and pin count, which allows TI to offer a floatingpoint DSP for $\$ 35$ in high volume.


FEATURES: 50 -, 60-, and 74 -nsec cycle-time versions.
Four 24-bit address buses and three 32-bit data buses.
Two 32 -bit and two 40 -bit additional buses in the CPU.
Separate program, data, and DMA buses.
Each internal RAM and ROM allows two accesses per cycle.
Any of the separate memories can be used for program or data.
Two on-chip $1 \mathrm{k} \times 32$-bit RAMs and an on-chip $4 \mathrm{k} \times 32$-bit ROM.
24 -bit external memory-address bus provides $16 \mathrm{M} \times 32$-bit total address space.
13 -bit external-I/O address bus provides $8 \mathrm{k} \times 32$-bit I/O ports, which are mapped into the 16-Mbyte address space.
Two 8-, 16-, 24-, and 32 -bit serial I/O ports. Two 32 -bit timers.
Proprietary 2's-complement 32 -bit floating-point format.
Multiplier accepts 32 -bit floating-point data and returns 40 -bit floating-point result. 24-bit integers result in 32-bit fixed-point results.
ALU operates on 40-bit floating-point and 32-bit fixed-point data.

Parallel multiplier and ALU operations in a single cycle. 32-bit bidirectional barrel shifter.
Eight 40-bit register-based accumulators.
Single-instruction and zero-overhead block looping.
$64 \times 32$-bit instruction cache.
Cache can be disabled when not needed and frozen to keep an often-used portion of code available in the cache.
Register, direct, indirect, immediate, relative, circular, and bitreversed addressing modes. Two address ALUs.
DMA controller allows concurrent I/O and CPU operation.
Hardware pointer to software stack.
Four external vectored interrupts.
Hardware and software-programmable wait states.
Serial debug port can provide in-circuit emulation.
Packaging: C30, 180-pin PGA. C30-27, 180-pin PGA. C31, 132pin QFP.

## HARDWARE

Full-speed in-circuit emulator for PCs and Sun workstations. Evaluation module plugs into a PC.
Significant third-party support. Contact Texas Instruments for a list of third-party vendors. Hewlett-Packard has a version of the HP64700 in-circuit emulator for the C30.

Optimizing ANSI C compiler. Source-level debugger and code profiler. (PC or Sun).
Assembler/linker. Simulator. (PC or Sun).
Application library.
Third-party support includes Spox, Ada compiler, filter-design packages, and block-level diagraming language.

## TMS320C40

## 32-BIT FLOATING-POINT CMOS DSP $\mu$ P

AVAILABILITY: Samples available now. Production quantities in 1992.
COST: Samples cost approximately $\$ 500 . \$ 250(5000)$.
SECOND SOURCE: None.

Texas Instruments Inc
Semiconductor Group, SC-9026
Box 809066
Dallas, TX 75380
(800) 336-5236, ext 700

Circle No. 685

DESCRIPTION: This device was designed for applications that require the performance of parallel processing. It is upward compatible with the C30, but adds six 32-bit FIFO dual-buffered communication ports, two complete 32 -bit external buses, an analysis module that supports multiprocessor debugging via a

JTAG interface, and a 4G-word address space. The chip also features single-cycle conversion to and from the IEEE floatingpoint standard and a cycle time of 40 nsec . Each communication port can transfer data to and from another C40 at $20 \mathrm{Mbyte} / \mathrm{sec}$ without any external logic.


FEATURES: 40- and 50-nsec cycle time
Four 32-bit address buses and three 32-bit data buses.
Two 32-bit and two 40-bit additional buses in the CPU.
Separate program, data, and DMA buses.
Each internal RAM and ROM allow two accesses per cycle.
Any of the separate memories can be used for program or data.
Two on-chip $1 \mathrm{k} \times 32$-bit RAMs and a $4 \mathrm{k} \times 32$-bit ROM.
Dual 32 -bit e^ternal buses. Each has a 31 -bit address, so the 4G-word memory is equally divided between the two buses.
Six independent 32 -bit communication ports for glueless communications between C40s. Separate $8 \times 32$-bit FIFOs for input and output buffering.
No on-chip serial ports. Two 32-bit timers.
Proprietary 2's-complement 32-bit floating-point format.
Single-cycle conversion from and to the IEEE-754 32-bit format.
Multiplier accepts 32 -bit floating-point data and returns 40-bit floating-point data. 24-bit integers result in 32-bit fixed-point results.
ALU operates on 40-bit floating-point and 32-bit fixed-point data

Parallel multiplier and ALU operations in a single cycle.
32-bit bidirectional barrel shifter
Twelve 40-bit register-based accumulators.
Single-instruction and zero-overhead block looping.
$128 \times 32$-bit instruction cache.
Cache can be disabled when not needed and frozen to keep an often-used portion of code available in the cache.
Register, direct, indirect, immediate, relative, circular, and bitreversed addressing modes. Two address ALUs.
6 -channel DMA controller for concurrent I/O and CPU operation. Transmitting DMA can control the operation of the receiving DMA, so setup for DMA transfer will not affect CPU
Hardware pointer to software stack.
Four external vectored interrupts.
Hardware and software-programmable wait states.
JTAG-based debug port controls the analysis module, which functions as an in-circuit emulator. Multiple C40s can be debugged via JTAG interface.
Packaged in a 325 -pin ceramic PGA.

## HARDWARE

Development system includes in-circuit emulation via JTAG interface.
4 -processor host-independent evaluation board.

Optimizing ANSI C compiler with parallel-processing runtime support.
Source-level debugger. Assembler/linker
Simulator.
Application library.
Third-party support includes Spox with drivers for parallel processing


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LT1228 is a high speed gain controlled amp with guaranteed operation down to $\pm 2 \mathrm{~V}$ or 4 V single supply and output swing to within 1 V of the rails.

LT1122 is a JFET input op amp which slews $80 \mathrm{~V} / \mu$ s. LT1193 and 1194 are video differential input amplifiers with programmable or fixed gain powered from single 5 V or $\pm 5 \mathrm{~V}$ supplies with $\pm 50 \mathrm{~mA}$ output drive.

Singles and duals are available in 8 -pin DIP and 8 -pin SOIC package, quads in 14 -pin. For data sheets and a comprehensive 132 page application note contact Linear Technology Corporation, 1630 McCarthy Blvd., Milpitas, CA 95035. Or call 800-637-5545.

| Parameter | $\mathbf{1 2 2 0}$ | $\mathbf{1 2 2 4}$ | $\mathbf{1 1 9 1}$ | $\mathbf{1 2 2 3}$ | $\mathbf{1 1 2 2}$ | Units |  |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| S.R. | Slew Rate (Typ) | 250 | 400 | 450 | 1000 | 80 | $\mathrm{~V} / \mu \mathrm{sec}$ |
| G.B.W. | Gain Bandwidth (Typ) | 45 | 45 | 90 | 100 | 14 | MHz |
| $\mathrm{t}_{\mathrm{s}}$ | Settling Time (to 0.1\%) (Typ) | 90 | 90 | 100 | 75 | $340^{*}$ | nsec |
| AvoL | Open Loop Gain (Typ) | 50 | 7 | 45 | 28 | 450 | $\mathrm{~V} / \mathrm{mV}$ |
| VOS | Offset Voltage (Max) | 1 | 2 | 6 | 3 | 0.9 | mV |
| IOS | Offset Current (Max) | 0.3 | 0.4 | 1 | - | .00005 | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{\mathrm{B}}$ | Bias Current (Max) | 0.3 | 8 | 1.7 | 3 | .0001 | $\mu \mathrm{~A}$ |
| $\mathrm{e}_{\mathrm{n}}$ | Voltage Noise (f=10KHz) | 17 | 22 | 25 | 3.3 | 15 | $\mathrm{nV} / \sqrt{\mathrm{Hz}}$ |
| $\mathrm{i}_{\mathrm{n}}$ | Current Noise (f=10KHz) | 3 | 1.5 | 4 | 2.1 | .002 | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ |
|  | Min Gain Stable | 1 | 1 | 1 | 1 | 1 |  |
| $\mathrm{I}_{\mathrm{H}}$ | Supply Current (Max) | 10.5 | 9 | 40 | 10 | 11 | mA |
|  | Price (100's) S (PDIP) | 3.85 | 2.85 | 2.40 | 2.85 | 2.50 |  |

[^7]
## 32-BIT FLOATING-POINT CMOS DSP $\mu$ P

AVAILABILITY: Now.
COST: 34325 ( 25 MHz ), \$137; 34325 (20 MHz), \$124 ( 10,000 ). SECOND SOURCE: None.

Zoran Corp
1705 Wyatt Dr
Santa Clara, CA 95054
(408) 986-1314

FAX (408) 986-1240
Circle No. 686

DESCRIPTION: The ZR34325 is a vector-signal processor, which is a DSP chip that operates on complex data and large blocks of data with single high-level instructions. The instruction set includes a single instruction to calculate an FFT, FIR filter, IIR filter, and other complex functions. The highly specialized
architecture is optimized to perform these functions quickly. The architecture also eases programming because the programmer doesn't have to write code for complex DSP functions. The 32-bit floating-point data conforms to the IEEE-754 standard.


FEATURES: $80-$ and $100-\mathrm{nsec}$ cycle-time versions.
Single address and data bus.
Vector instructions generally take longer to execute than to fetch, so little speed penalty is incurred with this simple bus architecture.
High-level instructions, such as those to calculate FFTs and FIR and IIR filters, simplify programming:
$256 \times 32$-bit coefficient dual-port ROM and $128 \times 32$-bit dual-port RAM on chip.
No on-chip program memory.
Internal memory can be directly accessed by external device.
$16 \mathrm{M} \times 32$-bit memory space.
No on-chip peripherals.
IEEE-754 32-bit floating-point format.
Multiplier accepts 32 -bit floating-point data and creates 44 -bit results.

Three ALUs: two floating point and one integer. 32-bit floatingpoint data can be added to 32 bits with one ALU and to 44 bits with the other.
24-bit bidirectional barrel shifter.
Two 32-bit accumulators.
No zero-overhead looping.
Direct, indirect, register, immediate, circular, and bit-reversed addressing modes.
Address generators for internal RAM and ROM.
On-chip DMA.
Slave mode opens chip to external access.
Hardware stack maintained in main memory.
Single external interrupt.
Hardware wait states.
No on-chip emulation port.
No low-power mode.
Packaged in an 84-pin PGA or 84-pin QFP.

## HARDWARE

Hardware-development-system board.
VME bus-based product for development.
Third-party hardware available.

Assembler/linker/simulator (MS-DOS and VAX/VMS).
Application library (MS-DOS and VAX/VMS).
Ada Compiler for VAX/VMS.


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## DESIGN IDEAS

## High-frequency VCOs top 100 MHz

Di Paolo Franco<br>Ericsson Fatme, Rome, Italy

VCOs that use surface-acoustic-wave (SAW) filters have higher operating frequencies and higher pull ranges than do circuits that use crystal oscillators. Figs 1 and 2 present two practical realizations of SAW-filter-
based VCOs. The circuits' operating frequencies are 140 and 181 MHz , respectively. The differences between the two figures stem from that fact that two types of SAW filters are available. Fig 1's circuit uses a SAW filter that has $180^{\circ}$ of phase shift. The filter in Fig 2 has a phase shift of $0^{\circ}$. Both circuits draw about 20 mA and operate from a 5 V supply.


Fig 1-This oscillator is based on a $\mathbf{1 8 0 ^ { \circ }}$ phase-shift SAW filter and has a free-running frequency of 140 MHz .


Fig 2-This oscillator is based on a $0^{\circ}$ phase-shift SAW filter and has a free-running frequency of 181 MHz .

## DESIGN IDEAS

Each circuit's operating frequency is solely dependent on the SAW filter's passband center frequency, which can be higher than 1000 MHz . The SAW filters have a pull range near 500 ppm when the BBY31 varactor diode's control voltage, $\mathrm{V}_{\text {Control }}$, varies by 4 V .

These circuits' typical p-to-p voltage when driving a $50 \Omega$ load is 600 mV . The spectrum of the output signals is such that all the harmonics are below 25 dB with respect to the carrier. The variation with temperature when the circuits run in the free-running mode is 100 ppm , which is typical for SAW filters.

Crystal oscillators tend to be more stable over their operational frequency range than are SAW-based oscillators. However, that range is limited compared with the range of SAW-based oscillators. SAW filters are available with center frequencies starting at 120 MHz. The components cost of Fig 1 and Fig 2, without the SAW filter, is about $\$ 1$ each. SAW filters cost about $\$ 25$. EDN BBS DI \#1030

EDN

To Vote For This Design, Circle No. 746

## Three transistors convert ac to dc

## Stephen Theobald <br> Bang \& Olufsen, Harboфre, Denmark

The 3-transistor ac-to-dc converter in Fig 1 features a better frequency response and higher accuracy than most op-amp-based designs. The circuit runs from a 5 V supply. $\mathrm{Q}_{1}$ and $\mathrm{Q}_{2}$ form a standard amplifier to buffer the input from the output. $Q_{3}$ bootstraps the collector load of $Q_{2}$ to provide current drive for the rectifier diodes. Current drive is essential for high accuracy. $Q_{2}$ also provides a low-impedance take-off point for the dc feedback to $Q_{1}$. Using an RF transistor for $\mathrm{Q}_{2}$ ensures a wide bandwidth. The transistor's critical parameter is $\mathrm{C}_{\mathrm{OB}}$, which is less than 2 pF at a $\mathrm{V}_{\mathrm{CE}}$ of 2 V .

The Fig 1 circuit was tested at frequencies as high as 300 kHz . The circuit's low-frequency response is limited to 1 kHz . By multiplying the capacitor values by a constant, you can convert frequencies lower than 1 kHz provided that the time constants of the rectifier stage prove acceptable. The maximum output voltage is approximately 800 mV before limiting occurs. $\mathrm{R}_{1}$ ensures stability for the circuit. The resistor isn't necessary if the driving circuit's impedance is greater than $300 \Omega$. EDN BBS DI \#1033

EDN

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Fig 1-To ensure accuracy, $Q_{3}$ of this ac-to-dc converter bootstraps the collector load of $Q_{2}$ to provide current drive to the rectifier diodes.

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## NEW PRODUCTS

## SOFTWARE DEVELOPMENT TOOLS

## Data-Transfer Program

- Converts Macintosh to DOS
- Requires no hardware or software modifications
The PC version of Common-Link, Mac-In-DOS, lets you format Macintosh disks in your IBM PC or compatible disk drive. The software runs under Microsoft Windows 3.0. No special hardware is needed to perform conversions. The software shows listings of two directories of files side by side on the screen. On one side are the Mac files resident on a Mac disk in the drive; on the other side are the DOS files in a selected directory on the hard drive or on a disk in another drive. Files are copied from one side to the other; conversions take place automatically. Because Mac files have three parts and DOS files have one, during Mac to DOS transfers, tutorial notes pop up with prompts to let the user select the appropriate conversion level. In DOS-to-Mac transfers, the DOS files are placed in a dummy Mac file. The software comes on a DOS disk and is loaded on the DOS computer. No hardware modification is needed for either machine, but both machines must have 1.44 -Mbyte disk drives. $\$ 199$.
Pacific Micro, 201 San Antonio Circle C250, Mountain View, CA 94040. Phone (415) 948-6200. FAX (415) 948-6296. Circle No. 351


## C Compiler And Source-Level Debugger

- Connect DOS or Unix computer to target hardware
- Software provides source-level debugging on target system
The Crosscode C compiler and Freeform source-level debugger are tailored specifically for Motorola MVME-165 VME CPU and 6800series evaluation boards. The tools provide source-level debugging directly on the target system. The de-
bugger includes a transparentmonitor program for the evaluation boards. The monitor can retrieve the target system's register contents and other information for the debugger, thereby eliminating the need for a hardware emulator. You can use the debugger to connect any MS-DOS or Unix computer directly to the target hardware through an RS-232C cable. The tool can debug fully optimized code in real time and can run on a laptop. It is integrated with the compiler; the compiler includes an ANSI-standard C compiler, a macro relocating assembler, linker, librarian, download, symbol listing routines, and startup routine. The tools come bundled together. $\$ 3490$.

Software Development Systems Inc, 4248 Belle Aire Lane, Downers Grove, IL 60515. Phone (708) 9718170.

Circle No. 352

## Visual Programming Tool

- Object-oriented, visual system - Imports C, Pascal, Fortran code This version of Prograph 2.5 can graph code, including interfaces. It allows you to import existing C, Pascal, or Fortran code and build interactive front ends to existing applications. It incorporates a database engine for multiuser access to tables, indices, and data types. The software is compatible with the Macintosh System. The system lets you define program classes and modules graphically. Modules are defined as data-flow diagrams, using processing nodes. Prograph has an interface builder for the automatic generation of interface objects from a set of supplied System Classes. Prograph 2.5, \$495; C and Pascal interfaces, $\$ 75$ each; Fortran interface, $\$ 149$.

TGS Systems, 2745 Dutch Village Rd, Suite 200, Halifax, Nova Scotia, Canada B3L 4G7. Phone (902) 455-4446. Circle No. 353

## Memory-Management Software

- Manages multiple memory resources
- Compatible with MS- and PCDOS
386Max and Bluemax memorymanagement tools are compatible with MS-DOS and PC-DOS. The tools enhance DOS's abilities by providing advanced automatic memory configuration and optimization. The software provides expanded and extended memory compatibility with LIM EMS 4.0, XMS 2.0 , VCPI, and VDS. The software recovers available memory resources and automatically relocates resident software into previously unused memory regions. Automatic ROM caching improves system performance. Video RAM and ROM, other adapter RAM and ROM, and the system ROM BIOS are located within the reserved-memory region. Both tools automatically recover the monochrome area of DOS memory. The 386Max identifies and recovers unused filler patterns within the ROM BIOS; Bluemax automatically compresses the PS/ 2 BIOS and provides an additional 80 kbytes of contiguous reserved-memory RAM. Both tools configure Micro Channel Architecture adapters. The tools also perform ROM caching and resident software instancing and can swap the fastest system memory into the first megabyte of memory. The tools require 1 kbyte of memory. The tools come bundled with the ASQ system analyzer and memory-management tutorial and the 386 Cache disk-cache program. The cache program loads its executable DOS into high DOS while leaving track buffers in conventional memory. 386Max, $\$ 130$; Bluemax, $\$ 155$.

Qualita Inc, 7101 Wisconsin Ave, Suite 1386, Bethesda, MD 20814. Phone (301) 907-6700. FAX (301) 907-0905. Circle No. 354

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## NEW PRODUCTS

## COMPUTERS \& PERIPHERALS

## Industrial 80486 Single-Board Computer

- Has eight SIMM sockets for as much as 32 Mbytes of DRAM
- Operates at 25 or 33 MHz

The QPC-5160 single-board computer (SBC) for a passive ISA bus
backplane contains an Intel 25- or $33-\mathrm{MHz} 80486 \mu \mathrm{P}$. It also has eight SIMM (single-inline-memory-module) sockets for as much as 32 Mbytes of dynamic RAM (DRAM). Memory options are $1,2,4,8,16$, or 32 Mbytes. In addition, the hard-

ware supports the LIM 4.0 specification. You can expand the memory to 64 Mbytes, using a piggy-back daughter board. The SBC's DRAM features page-mode and 2 -way interleaved access modes, and the daughter-board's memory has a 4 way interleaved access mode. The company designed the SBC to withstand harsh industrial conditions. The board also features a shadow RAM. Board with 4 Mbytes of DRAM ( 25 MHz ), $\$ 3795$; ( 33 MHz ), $\$ 4195$.

Qualogy Inc, 109 Bonaventure Dr, San Jose, CA 95134. Phone (408) 434-5200. Circle No. 355


## QIC Tape Drives

- Connect to SCSI port on Macintosh computers
- Have capacities ranging from 150 to 525 Mbytes
The latest models of the Panther Tape Backup System are compatible with Apple's Macintosh Macplus, SE, SE 30, MAC II, IICX, IICI, and portable computers. Because the $5^{1 / 4}-\mathrm{in}$. drives employ the SCSI bus, you can attach them directly to the computer's SCSI port without using a host adapter board. The drives have capacities ranging from 150 to 525 Mbytes. The 525 -Mbyte model can back up the entire tape in less than 45 minutes. Backup and restore rates range from 5 Mbytes/minute to $12 \mathrm{Mbytes} /$ minute. The drives perform file-by-file and image backups, and they are compatible with the A/UX operating system. The
units use DC 6000 or equivalent tape medium, and the MTBF is 80,000 hours. Bit error rate is less than $10^{-15} .150$-Mbyte drive, $\$ 2145$; 525-Mbyte drive, $\$ 2695$.

Tandberg Data Inc, 2649 Townsgate Rd, Suite 600, Westlake Village, CA 91361. Phone (805) 4958384.

Circle No. 356
that's expandable to 128 kbytes. You can install as much as 32 Mbytes of dynamic RAM, using single inline memory modules. The board has eight 16-bit ISA bus expansion slots and a socket for an 80387 coprocessor. A shadow RAM for the system BIOS and video BIOS increases the execution speed as much as three times. The
mother board runs Windows, OS/2, MS-DOS, Unix, Xenix, and Novell software. Performance figures include a 63.6 Landmark Speed (1.14), 8.55 Power Meter MIPS (1.5), and a Norton SI rating (4.5) of 48. $\$ 855$.
Pioneer Computer Inc, 49066 Milmont Dr, Fremont, CA 94538. Phone (415) 623-0808. Circle No. 358


386 Personal Computer

- Employs AMD's $40-\mathrm{MHz} 80386 \mu P$
- Has 4 Mbytes of DRAM and one 64-kbyte cache RAM
The 386WB-40SL ISA bus personal computer employs AMD's $40-\mathrm{MHz}$ $80386 \mu \mathrm{P}$. The computer comes with 4 Mbytes of dynamic RAM, a 200Mbyte hard-disk drive, a 14 -in. super VGA monitor, a 1-Mbyte VGA Freedom Card, and 64 kbytes of cache RAM. The RAM is expandable to 64 Mbytes. In addition, the computer has FCC Class B approval, a parallel port, and two serial ports. Other features include a mouse, and DOS 4.01 and Windows 3.0 software. A 6month GE on-site service contract, which is optionally expandable to five years, is also available. $\$ 2999$.

Bell Computer Systems, 6615 Valjean Ave, Van Nuys, CA 91406. Phone (818) 909-3501. Circle No. 357

## 80386 Mother Board

- Employs AMD's $40-\mathrm{MHz} 80386 \mu \mathrm{P}$
- Has 64-kbyte cache RAM expandable to 128 kbytes
The 386 Cache 40 Mini-AT mother board uses AMD's $40-\mathrm{MHz} 80386$ $\mu$ P. It has 64 kbytes of cache RAM

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gain. The maximum per-channel supply current is $625 \mu \mathrm{~A}$. The low offset voltage and high gain eliminate offset trims and additional gain stages in many designs. The superbeta input stage includes biascurrent cancellation circuitry that maintains low ( pA ) bias current over the full operating temperature range. This action contrasts with traditional FET-input amplifiers whose bias current is initially low but typically doubles for every $10^{\circ} \mathrm{C}$ rise in temperature. Other features include a supply-voltage operating range of $\pm 2$ to $\pm 20 \mathrm{~V}$, and a $120-\mathrm{dB}$ PSRR and CMRR. The commonmode range extends to within 1 V of the operating supply. The quad op amp is available in industrial and military temperature ranges. Package options include 14-pin plastic

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- Frank Lucas

Test Engineering Manager
Welch Allyn
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Analog Devices, PMI Div, 1500 Space Park Dr, Santa Clara, CA 95052. Phone (408) 727-9222.

Circle No. 359

## SONET Chip Set

- For STS-3 and STS-12 applications
- Satisfies both SONET and SDH requirements
This 3-piece chip set, consisting of the VP15301, VP15311, and VP15323, satisfies both SONET (Synchronous Optical Network) and SDH (Synchronous Digital Hierarchy) standards. Optimized primarily for STS-3 and STS-12 applications at 155 Mbps and 622 Mbps , respectively, the chip set is usable
at other standardized rates and has been tested to comply with ANSI, CCITT, and Bellcore standards. The VP15301 is used for terminating the section overhead of SONET data streams. The VP15311 is used for terminating line overhead, and

the VP15323 is used for processing and aligning SONET payloads to system timing. The VP15323 can also process concatenated data streams for handling asynchronous transfers and for SDH compatibil-


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ity. Package options, which vary by chip and application, include an 84 pin plastic leaded chip carrier, a 144-pin plastic pin-grid array, and a 160 -pin plastic quad flatpack. VP15301, VP15311 and VP15323, from $\$ 56, \$ 90$, and $\$ 69$, respectively (2000).

VLSI Technology, 1109 McKay Dr, San Jose, CA 95131. Phone (408) 434-3000. FAX (408) 2632511.

Circle No. 360

## Power Switching Regulator

- Output switch handles 5A
- Duty cycle is adjustable

Featuring an output-switch rating of 5A, the MC34167 switching regulator comes in a 5-lead TO-220 power package, which simplifies heat sinking. The regulator operates at a fixed frequency of 72 kHz . Because the timing components are on the chip, you don't need an external resistor and capacitor to set the oscillator frequency. In addition to the oscillator and on-chip timing, the regulator contains a latching pulse-width modulator, a high-gain ( 80 dB ) error amplifier, and a highcurrent ( 5 A ) output transistor. The duty cycle is adjustable from 0 to $95 \%$. Protective features include cy-cle-by-cycle current limiting, undervoltage lockout, and thermal shutdown. A low-power standby mode reduces current drain to $36 \mu \mathrm{~A}$. In addition, the regulator has an internal resistor divider, which sets the output at a nominal 5.05 V , eliminating the need for an external divider and providing an extra 50 mV to compensate for a $1 \%$ voltage drop in external wiring. The regulator is available in two temperature ranges; the MC34167T for 0 to $70^{\circ} \mathrm{C}$ operation, and the MC33167T for -40 to $+85^{\circ} \mathrm{C}$ operation. MC34167T, \$2.03; MC33167T, $\$ 2.19(10,000)$. Delivery, stock to six weeks ARO.

Motorola Inc, EL340, 2100 E Elliot Rd, Tempe, AZ 85284. Phone (602) 897-3615. FAX (602) 897-4193.

Circle No. 361

## NEW PRODUCTS

## TEST \& MEASUREMENT INSTRUMENTS

## Enhancement For JitterSpectrum Analyzer

- Unit computes spectra of jitter in time measurements
- Instrument requires no external computer
When equipped with Option 040, the HP 5372A modulation-domain analyzer uses FFT techniques to determine the frequency spectrum

of the jitter in a series of time measurements. The unit requires no external computer and works with jitter that has a bandwidth as high as 2 MHz . When the data stream is nonrepetitive, the analyzer does not require a clock. HP 5372 A , $\$ 30,000$. Option $040, \$ 2000$ (if installed by factory in new analyzer). Option 040 field upgrade for existing analyzers, $\$ 3000$.
Hewlett-Packard Co, 19310 Pruneridge Ave, Cupertino, CA 95014. Phone (800) 752-0900. Circle No. 365


## 68HC11 Emulators

- Interface to MS-DOS PCs via 115.2-kbps RS-232C link
- Work with $\mu$ Ps that generate a 3.3-MHz E-clock

There are two versions of the Icemaster 68 HC 11 in-circuit emulator: The Model 200 is a basic emulator; the Model 400 contains all of the basic unit's features and a 4 k frame trace buffer, two real-time performance analyzers, and watchdog-timer support. Both emulators work with 68 HC 11 s that generate a $3.3-\mathrm{MHz}$ clock. You connect the instruments to an MS-DOS PC via an RS-232C link that supports host communica-

tion at speeds to 115.2 kbps . Both models have trace-on and trace-off triggers, 64 kbytes of emulation memory, 64 k hardware breakpoints, and 64 k write-access triggers. The emulators include symbolic and source-level debuggers that display dynamically annotated code in a source window. Model 200, $\$ 1999$; Model 400, $\$ 4199$; probe cards, from $\$ 599$.

Metalink Corp, Box 1329, Chandler, AZ 85244 . Phone (602) 926 0797.

Circle No. 366

## Pocket-Size <br> $3.5-\mathrm{GHz}$ Counter

- Operates as long as five hours from NiCd battery
- Measures $3.4 \times 3.8 \times 1 \mathrm{in}$. and weighs 9 oz
The Model 35008 -digit, $3.5-\mathrm{GHz}$ frequency counter operates as long as five hours from a rechargeable NiCd battery. The unit, which offers a display-hold function, will operate while connected to its battery charger. Input resistance is $1 \mathrm{M} \Omega$ to 12 MHz ; a second $50 \Omega$ input works from 10 MHz to 3.5 GHz . You can choose among three gate times, the longest of which gives $0.1-\mathrm{Hz}$ resolution at $12 \mathrm{MHz} . \$ 3500$.

Startek International Inc, 398 NE 38th St, Fort Lauderdale, FL 33334. Phone (305) 561-2211. FAX (305) 561-9133. Circle No. 367



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## NEW PRODUCTS

## COMPONENTS \& POWER SUPPLIES



## Expansion Chassis

- Designed for EISA systems
- Includes a backplane

The PX1591 expansion chassis is designed for EISA/ISA systems. It includes a 13 -slot, rack-mountable
passive backplane and a 200 W modular power supply. It also includes an expansion card module and one expansion card with the cables necessary to extend from the PCXI chassis to EISA/ISA desktop or rackmount PCs. The chassis provides EMI/RFI shielding, vibration protection, and industrial cooling with filtered fans. The unit accommodates as many as 10 function cards. $\$ 2395$.

Rapid Systems Inc, 433 N 34th St, Seattle, WA 98103. Phone (206) 547-8311.

Circle No. 362

## Voltage Suppressors

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- Respond in 1 nsec max

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## Announcing a night to recognize greatness



## EDN's Innovation and Innovator of the Year Awards Ceremony

0n the night of November 19 during Wescon, EDN will present the 1991 Innovation and Innovator of the Year awards at the Mark Hopkins Hotel in San Francisco. You are invited to show the finalists that you support greatness in innovation by attending the awards ceremony that is the culmination of their hard work. Through its Innovation Crusade, EDN hopes to inspire EDN October 1, 1991
engineering professionals within the electronics field to reach for higher plateaus of inspiration and creativity.

The dedication and involvement of EDN readers, like yourself, have made the Innovation Crusade and awards ceremony a reality. By taking the time to nominate your peers and, in
fact, select the winners, you show commitment to quality and creativity in electronics and are driving this crusade. But don't stop there ... order your ticket to the industry event of the year and show these innovators that greatness does not go unrecognized. All proceeds of the dinner will be donated to the EDN Scholarship Fund.

To receive a reservation order form to the EDN 1991 Innovation Dinner and Awards Ceremony, fax Pam Winch at (617) 558-4470.


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- All units exceed the requirements of MIL-T-27 ( $+130^{\circ} \mathrm{C}$ )
- Transformers have input voltages of $5 \mathrm{~V}, 12 \mathrm{~V}, 24 \mathrm{~V}$ and 48 V . Output voltages to 300 V .
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- Inductors have split windings
 Electronics, Inc. 453 N. MacQuesten Pkwy. Mt. Vernon, N.Y. 10552 Call Toll Free 800-431-1064 IN NEW YORK CALL 914-699-5514

COMPONENTS \& POWER SUPPLIES
a current capability of 150 to 300A. These surface-mount varistors have a response time of 1 nsec max and are available in a variety of package sizes. These low-voltage devices have a circuit-operation capability ranging to 60 working volts. Clamp-ing-voltage figures range from 15.5 to 30 V . Transient-energy figures span a 0.3 to 1.2 J range. $\$ 0.45$ to $\$ 0.55$ (1000). Delivery, six to eight weeks ARO.
AVX Corp, 3900 Electronics Dr, Raleigh, NC 27604. Phone (919) 878-6200.

Circle No. 363


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- Have a 0.1\% tolerance

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Dale Electronics Inc, 2300 Riverside Blvd, Norfolk, NE 68701. Phone (402) 644-4247.

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sow PSA-5031 $5 \mathrm{FV} / 5 \mathrm{~A}, \quad 12 \mathrm{~V} / 25 \mathrm{~A}-12 \mathrm{~V} / 05 \mathrm{~A} \quad 160 \times 100 \times 45$ (3 MODELS)


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WATTS MODEL O/P1 O/P2 O/P3 O/P4 DIMENSION 150W PSA-1500U $\quad 5 \mathrm{~V} / 15 \mathrm{~A} \quad-5 \mathrm{~V} / 1 \mathrm{~A} \quad 12 \mathrm{~V} / 1 \mathrm{~A} \quad 12 \mathrm{~V} / 5 \mathrm{~A} 198 \times 97 \times 38$ PSA-1503U 5V/30A $\begin{array}{lllllllllll}\text { PSA }-1509 \mathrm{U} & 5 \mathrm{~V} / 15 \mathrm{~A} & -5 \mathrm{~V} / 1 \mathrm{~A} & -12 \mathrm{~V} / 1 \mathrm{~A} & 12 \mathrm{~V} / 5 \mathrm{~A}\end{array}$ (10 MODELS) 200W PSA-2041U $5 \mathrm{~V} / 25 \mathrm{~A} \quad-5 \mathrm{~V} / 25 \mathrm{~A}-12 \mathrm{~V} / 2.5 \mathrm{~A} 12 \mathrm{~V} / 5 \mathrm{~A} 203 \times 114 \times 51$ (3 MODELS

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## IC DESIGN ENGINEER

Responsible for circuit design and technology development for low power implantable custom ICs, including microcomputers, switched capacitor filters, A/D and DC/DC energy converters. Requires BS/MSEE or PhD and 3+ years experience in design/development of analog/digital CMOS ICs. Respond to Dept. EDNMAG/ICDE.

## PROCESS ENGINEER

Will handle machine design projects utilizing electropneumatic mechanisms/processes involving YAG laser welding. Requires BSME/EE with 5 years experience in CNC machine control, diagnostics, mechanical fixture design and repair of digital/analog circuits. Respond to Dept. EDNMAG/PE.

## SR. ANALOG POWER ENGINEER

Engineering duties involve switching power supplies/hybrid power circuits for implantable medical devices. Background

must include BS/MSEE or PhD and $5+$ years experience in analog circuit design, prototype, test and debug. Respond to Dept. EDNMAG/APE.
SR. COMPONENT RELIABILITY ENGINEER
Selected candidate will have BSEE with 5 years experience in reliability engineering, failure analysis techniques and rate predictions. Knowledge of IC and hybrid design/evaluation/qualification techniques and CMOS is essential, as well as ability to establish test requirements and evaluate results. Respond to Dept. EDNMAG/CRE.
SR. ELECTRONIC DESIGN ENGINEER
Requires proven expertise in design, prototype, test, debug and documentation of analog, digital, CMOS and microprocessor-based circuitry for implantable medical products. BS/MSEE and 5+ years experience also necessary. Respond to Dept. EDNMAG/EDE.

## SR. ELECTRONIC PRODUCT ENGINEER

BSEE and 3-5 years experience in analog/digital design, CMOS/TTL devices and microprocessor-based systems essential. Ideal candidate will have knowledge of hybrid microelectronics involved in the manufacture of high-reliability electronic devices. Electronic test procedure experience would be a plus. Respond to Dept. EDNMAG/EPE.

## SOFTWARE ENGINEER

 Utilizing Assembly and C languages, will design/develop system and application SW for real-time embedded microprocessor-based pacemaker support products. Requires BSEE/CE or equivalent and 3+ years experience in embedded microprocessor and system-level SW design/ development. Respond to Dept. EDNMAG/SE.In addition to our desirable Southern California location, we offer competitive compensation, paid relocation and an excellent benefits package, including employer-contributed pension plan, $401(\mathrm{k})$, tuition reimbursement, vision care and a choice of dental/health plans. Send resume (NO PHONE CALLS, PLEASE!) to the appropriate department: Greer A. Brooks, Employment Representative, Pacesetter Systems, Inc., 12884 Bradley Avenue, Sylmar, CA 91342. AA/EOE

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Senior Hardware Design Engineer - Dallas, Tx.
Candidate will design and simulate ASIC devices and interface to ASIC vendors. Minimum of 3-5 years experience in board-level design and high speed CMOS design using ASIC technologies (gate array or standard cell). Knowledge and use of schematic capture, logic simulation and fault simulation tools (Verilog and/or Synopsys) desired. Working knowledge of $\mu \mathrm{P}$ and related architecture required. Disk, communication, VMEbus, Sbus and EISA bus experience are pluses. Prefer BSEE or equivalent experience.

Product Marketing Manager - Dallas, Tx.
Senior level candidate who can: formulate strategic plans, develop markets and size markets for INTERPHASE's EISA products, technologies, and protocols. Represent INTERPHASE at various national and international forums, committees and working groups. Act as Product Line Champion within the corporation. 8-10 years applicable engineering and/or marketing experience with VAR, VAD, and dealer channels desired. Prefer BSEE, BSCS or equivalent experience. M.B.A. is a plus.

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#### Abstract

Applications Engineer - Dallas, Tx. Individual will provide second level technical assistance for customers and liaison between Customer Service and Engineering. Will maintain an in-depth product and system knowledge in order to identify and solve software and hardware problems. Assemble hardware, generate test scripts or programs (C, assembler, or shell language), and modify software drivers. Minimum of 3 years experience with C in an UNIX environment required. Systems administration experience a plus. Prefer BSCS or equivalent experience.


## Systems Administrator - Dallas, Tx.

Candidate will be responsible for the administration of Engineering Service's UNIX based workstation network. Primary duties will involve VALID systems administration, training engineers, developing and maintaining on-line help, writing behávior models in C, supporting schematic entry, component packaging and simulation. Minimum of 2 years experience with UNIX, O/S administration, C programming, shell programming and networking required. Experience with PC-NFS, modeling and simulation desired. Prefer BSEE, BSCS or equivalent experience.

## Software Engineer - Dallas, Tx.

Candidate will develop device drivers for various INTERPHASE products. Experience with UNIX, Kernal I/O, TCP/IP or other protocol experience on super-minicomputer or mini-computer required. Minimum five years writing UNIX device drivers required. BSCS required. MSCS preferred.

## Networking Programmer - Mountain View, Ca.

 Individual will participate in the development of networking coprocessor products in a real-time environment. 3 years experience developing networking software in a real-time UNIX environment required. Working knowledge of TCP/IP, UDP and NFS/RPC desirable. Prefer BSCS, BSEE or equivalent experience. MSCS or MSEE a plus.
## Software Performance Engineer - Mountain View, Ca.

 Candidate will benchmark and test networking products as well as interface with all OEMs/customers regarding performance issues. Minimum of 5 years experience with UNIX and C programming and 2 years of performance evaluation and benchmarking. Prefer BSCS, BSEE or equivalent experience. MSCS or MSEE a plus.
## Software Engineer - Mountain View, Ca.

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## dc to 2000 MHz amplifier series

| SPECIFICATIONS |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | FREQ. <br> MHz | $\begin{aligned} & 100 \\ & \mathrm{MHz} \end{aligned}$ | $\begin{aligned} & \text { AIN, d } \\ & 1000 \\ & \mathrm{MHz} \end{aligned}$ | $\begin{aligned} & 2000 \\ & \mathrm{MHz} \end{aligned}$ | Min. (note) | - MAX PWR. dBm | $\begin{aligned} & \mathrm{NF} \\ & \mathrm{~dB} \end{aligned}$ | $\begin{aligned} & \text { PRICE } \\ & \text { Ea. } \end{aligned}$ | \$ty. |
| MAR-1 | DC-1000 | 18.5 | 15.5 | - | 13.0 | 0 | 5.0 | 0.99 | (100) |
| MAR-2 | DC-2000 | 13 | 12.5 | 11 | 8.5 | +3 | 6.5 | 1.50 | (25) |
| MAR-3 | DC-2000 | 13 | 12.5 | 10.5 | 8.0 | +8口 | 6.0 | 1.70 | (25) |
| MAR-4 | DC-1000 | 8.2 | 8.0 | - | 7.0 | +11 | 7.0 | 1.90 | (25) |
| MAR-6 | DC-2000 | 20 | 16 | 11 | 9 | 0 | 2.8 | 1.29 | (25) |
| MAR-7 | DC-2000 | 13.5 | 12.5 | 10.5 | 8.5 | +3 | 50 | 1.90 | (25) |
| MAR-8 | DC-1000 | 33 | 23 | - | 19 | +10 | 3.5 | 2.20 | (25) |

NOTE: Minimum gain at highest frequency point and over full temperature range.

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$\square+4 \mathrm{dBm} 1$ to 2 GHz


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Also, for your design convenience, Mini-Circuits offers chip coupling capacitors at 12 cents each. $\dagger$

| Size <br> (mils) | Tolerance | Temperature <br> Characteristic |
| :---: | :---: | :---: |
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| $80 \times 50$ | $10 \%$ | X7R |
| $120 \times 60$ | $10 \%$ | X7R |
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