SEPTEMBER 16, 1981

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CIRCLE NO 2



SEPTEMBER 16, 1981 . VOLUME 26, NUMBER 18 . EXCLUSIVELY FOR DESIGNERS AND DESIGN MANAGERS IN ELECTRONICS



Frequency counters span a wide spectrum of parameter choices (pg 33).



٦

Intelligent terminals *develop along two paths to provide for varying needs (pg 45).*



On the cover: Hardware and software innovations in hand-held computers provide problem-solving power in a host of unusual applications. Turn to pg 70. (Photo by Alexander Kruper, courtesy Panasonic Inc)



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	Implementing the fast Fourier transform and its inverse on your personal μ C can increase your productivity.
	Noise-property analysis enhances PLL designs
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	Operating systems cost more —but they also do more 101 Updated operating systems reflect their suppliers' efforts to maintain performance parity with advances in 8- and 16-bit μ C hardware.
	16-bit- uP benchmarks—an update with explanations
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CIRCLE NO 3



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TEXAS INSTRUMENTS INCORPORATED CIRCLE NO 4

News Breaks

US SEMICONDUCTOR FIRM RECEIVES DOLBY LABS'S APPROVAL

Interdesign Inc (Sunnyvale, CA) has won the hotly contested race to be the first US semiconductor company to obtain Dolby Laboratories's approval for a single IC that meets the specs of the new Dolby C noise-reduction system. The company joins Hitachi as the only two IC suppliers currently approved by Dolby Labs.

The Dolby C noise-reduction system is based on a new dual-level processing scheme with two sliding-band processors operating in tandem at different levels to solve the problems of achieving 20 dB of compression and expansion without introducing side effects. Interdesign will use one of its Monochip bipolar linear component arrays to integrate the system. The device will be offered in a 24-pin DIP to Dolby licensees only. Full volume production is scheduled for November.—JM

68000 FAST FLOATING-POINT SOFTWARE AVAILABLE ON 8-IN. DISK

Offering single-precision (32-bit) software floating-point operations optimized for the MC68000 μ P, the 68343 Fast Floating Point program comes on an 8-in. floppy disk in VersaDOS format. Simple to use and customize (the source code is included on the disk), it allows subroutine calls. While it's not based on IEEE floating-point format, conversion routines are available to output that format. Other conversion routines go back and forth from fixed to floating point, ASCII to floating point and BCD to floating point.

In addition to the standard arithmetic operations, the package performs Test, Compare, Absolute Value and Negate plus most of the transcendental functions. Execution time for an Add or Subtract is 22 μ sec; Multiply, 44 μ sec; Divide, 76 μ sec; and Sinh, 623 μ sec. These times are for the 8-MHz 68000; using the 10-MHz part drops them by 20%. Order the 86343 as M68KFFP from Motorola's Microsystems Group in Phoenix, AZ for less than \$1000 with no limitation on use or redistribution (no royalties).—WT

OPERATING SYSTEM SUPPORTS PRINTERS, DISKS, 16 CONSOLES

The MP/M II operating system from Digital Research (Pacific Grove, CA) operates in systems employing an 8080, 8085 or Z80 μ P. It requires 48k bytes of RAM, a clock/timer interrupt and at least one disk. The multiuser/multitasking software supports as many as 16 user consoles, printers and disk drives with storage capacity of 512M bytes each for a total on-line storage capacity of 8G bytes. It can also manage 400k bytes of system RAM, with banks being selected in blocks of 48k among eight users. Utilities include a relocatable macro assembler and a linking loader. MP/M II is compatible with CP/M files and supports the company's CP/Net networking operating system. Distributed on 8-in. single-density IBM-format diskettes, it costs \$450.—CW

DESKTOP BUSINESS COMPUTER JUGGLES WORDS, NUMBERS, GRAPHS

Running under the CP/M operating system and offering a choice of five business application-software packages, the HP 125 single-user desktop computer system combines the features of a personal computer, word processor, visual display terminal, financial calculator and graphics workstation. From Hewlett Packard (Palo Alto, CA), Models 10 and 20 employ a CRT with a separate keyboard; a choice of a thermal, letter-quality or dot-matrix printers; a 1or 8-pen plotter; and either 5¼- or 8-in. floppy-disk drives for storing 500k or 2.4M bytes of information, respectively. In addition to working as a stand-alone local processor, the HP 125 can also function as a remote station to an HP 3000-based network or a mainframe via dual RS-232C datacomm ports at speeds to 9600 baud. Prices start at \$7460.—GK

News Breaks

INTERFACE PUTS STREAMER ON THE S-100 BUS

A nonintelligent interface from Scientific Enterprises Inc (Wilsonville, OR) gives your S-100 system tape-cartridge-backup protection. The S-100 Architape interfaces any S-100 system to Archive Corp's 20M-byte streaming-tape cartridge drive, transferring data at either 2M bytes/min (the A version working with the 30-ips drive) or 6M bytes/min (the B version working with the 90-ips drive). Both versions provide read-while-write data verification and 16-bit CRC generation and checking. The A version costs approximately \$500; the B version, \$600 (less than 100 units).—ET

COLOR-GRAPHICS TERMINAL TO COST LESS THAN \$1600

In the first quarter of next year, look for a color terminal costing approximately \$1500. The Intelligent Systems Corp (Norcross, GA) terminal will support a 480×380 graphics matrix and several communication protocols and terminal emulations. The company says the terminal is being developed for high-volume OEMs.—CW

NONVOLATILE-MEMORY LINE EXPANDS UP AND DOWN IN SIZE

General Instrument Microelectronics (Hicksville, NY) is putting a variety of processes to work on various EAROM (EEPROM) products. The ER5816, a word-alterable, 2816-compatible, n-channel metal-gate MNOS part, has been sampling since March; the ER4201 (EDN, January 21, pg 40) is scheduled to start sampling this month. The 4201 is also fabricated in metal-gate n-channel MNOS, but the 128×8 -bit unit also provides latches for both address and data and features a Reprogram command that combines an erase and write cycle. The word-alterable part also provides a Busy signal for μ P compatibility; it accesses in 450 nsec. Production is scheduled for December, with pricing at \$7 (1000).

The company's latest efforts deal with n-channel Si-gate MNOS. The first product announced using that technology is the ER5716—a 16k alternative to the 2716 EPROM. The $2k \times 8$ bulkerasable part accesses in 300 nsec and serves as a second source to the HN48016.

Other things to look for: the AR5304, a 4k shadow RAM similar to parts made by Xicor, which will be available in the first quarter of 1982; and the ER1450, a 50×14 -bit EAROM aimed at the TV-tuner industry. A spinoff from the ER1400, the new part will cost considerably less.—WT

SPEAKING OF VOICE I/O ...

Now you can digitize your own vocabulary and make your computer system say what you want it to. A voice-development system from Centigram Corp (Sunnyvale, CA) provides this capability in a stand-alone unit. Intended for use by nonprogrammers, the real-time system is easy to use: Just speak the words into the microphone and the system digitizes them for instant use, storing the vocabulary on 500k-byte diskettes. The first version of the \$25,000 system will work with Multibus systems and run under CP/M with deliveries beginning in October. The firm will also announce versions to provide a similar capability for other computer systems.—ET

ENHANCEMENTS EXTEND BUBBLE-MEMORY TESTER'S USEFULNESS

With programmable drivers that feature wider current ranges, Model Q-1012 bubble-memory test system tests a larger variety of bubble devices than earlier systems. From Megatest Corp (Santa Clara, CA), it offers parallel test capability to increase throughput: It can test two Intel 1M-bit devices or three ¹/₄M- or 1M-bit Motorola devices at one time, using four output sense channels. Stimulus signals are applied simultaneously to the devices under test, but output error maps and bad-loop masking information are maintained individually.—AS

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16 bits of information



1. Self-contained and upward compatible. The 8550 Microcomputer Development Lab is the single-user member of the new 8500 Modular MDL Series, which also includes the 8560 multi-user system and the 8540 Advanced Integration Unit for the host computer environment. The 8550 is a complete microcomputer design tool, covering both software development and integration into the prototype. The 8550 can also be used as a station on Tek's forthcoming 8560 multi-user system.

2. Real-Time Emulation. Takes the concept of emulation to a new performance level. Advanced circuitry eliminates the need for wait states during program execution and debugging. The emulator processor now functions in real-time, with its operation totally transparent to the user.



3. Multi-Vendor Chip Support. The 8550 MDL supports 26 chips in all. The broadest support available anywhere, covering a wide range of vendors. With microcomputers as well as microprocessors. The ultimate in design flexibility.

on the new 8550 MDL.

4. 16-bit Support. You'll be able to choose from an entire new generation of 16-bit processors. Tektronix has the high performance tools to make it possible. Assembler support is available now for the 16-bit chips listed below. The TMS 9900 and SBP 9900 are fully supported with emulation today. Real-Time Emulation and Pascal support will be available in stages for the 68000, Z8000 and 8086.

68000 **TMS 9900** Z8000 **SBP 9900** 8086

5. 16-bit Trigger Trace Analysis. Gives you highly sophisticated triggering ability for selective snapshots of fullspeed code execution on the prototype bus. Up to four data acquisition triggers can be combined in a wide variety of ways. Bus cycle resolution to 8 MHz.

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6800	8048	3870
6802	8039	3872
6808	8039-6	3874
Z80A	8035	3876
8080A	8021	F8
8085A	8022	1802
8049	8041A	6500/1

7. 8-bit Real-Time Analysis. An optional Real-Time Prototype Analyzer lets you extract both bus and hardware logic at full operating speeds. You capture 48-bit words for storage in a 128-word memory. Two triggers for precise data acquisition.

8. Split-Bus Architecture. The 8550 uses one processor and bus for system operation, and another for real-time emulation. This architecture assures that the emulator processor is denied access to system memory, preventing the possibility of a system crash during prototype program execution.

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CIRCLE NO 8

Signals & Noise

Does engineering benefit from competition?

Dear Editor:

ELECTRONICS

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AUTOMOTIVE EQUIPMENT

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AVIONICS

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ENERG

EDN's June 24 editorial has three disagreements with Mr Feerst's objections to the publicly funded advertising of the University of Massachusetts. They don't survive scrutiny.

One, the "low unemployment rate" argument, merely reflects an artificially depressed and unrewarding salary structure for engineering compared with other less contributory (and less expensive to enter) professions. Attempts to dilute the profession with promises of cheap engineering by "starving graduate students" both depress salaries further and increase the cost of entry into the profession. It's difficult to find an advantage to the nation in such an approach. More encouragement is needed; not "starvation."

Your second disagreement might be only slightly less unsupportable. Interplay between academia and industry is certainly desirable, but not the undercutting kind that is the obvious aim of U Mass.

To use the limited resources of our poorly equipped grad schools as a "cure" for the "outrageously wasteful" practice of industrial training and learning is really farcical. Virtually every other segment of the industrial world uses training in the work area, where problems can be recognized and resolved with far better focus and speed than in the classroom or isolated laboratory. The experience of US industries today shows that more training is needed in the work area, not less.

Your third objection seems irrelevant. Mr Feerst's comments relate to engineering work normally performed by

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industrial staffs (who recommend and authorize the purchase of products advertised by your publication) and consultants (some of whom are from academia)-the very work solicited by the U Mass brochure. That is not the kind of research, contributed by Bardeen, Shockley and others, that affects the eventual mainstream of the industrial world. Those and many other contributions also deserve great reward. Their sources should not have to rely on "starving graduate students" as a resource.

On this matter, I think Mr Feerst is right. The public trough is a poor place from which to launch a competitive drive. Congratulations on your otherwise fine publication. Loren L Krueger, PE Minnetonka, MN

Amend those bus specs

EDN's recent Designer's Guide to μ C buses (May 24, June 10 and June 24) mistakenly listed the Multibus (P796) as a 32-bit-wide bus. The Multibus can accommodate 32-bit-wide transfers via multiplexing, however, and incorporates refinements that make it an obvious step toward more powerful and wider word μ Ps.

Further, buses such as Fastbus and P896 represent a new category of bus design. Both are designed for maximum implementation ease and thus don't restrict designers by imposing stringent specifications that must be followed in all cases.

Note that some of the specifications for these two buses presented in the Designer's Guide were also in error (table). To clarify the table entries, note that the P896 bus only specifies an interconnection

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BUS FEATURES	FASTBUS	P896
NUMBER OF LINES SPECIFIED/AVAILABLE	130/58(1)	64/643
DATA-FIELD WIDTH	32M	32
TRANSMISSION MECHANISM (PM = PARTIALLY MULTIPLEXED, FP = FULLY PARALLE	L) PM	FP
SYSTEM GEOMETRY (PC = ONE PCB, OC = ONE CRATE, SC = SEVERAL CRATES)	SC	OC
UNIFIED ACCESS TO MEMORY AND I/O?	Y	Y
MULTIPROCESSOR CAPABILITY?	Y	Y
REDUNDANT TRANSMISSION PATHS SPECIFIED?	Ŷ	Y(4)
ADDRESS LINES WIDTH (M = MULTIPLEXED)	32, M	32, M
DATA LINES WIDTH (M = MULTIPLEXED)	M	32, M
CONTROL LINES	-	4
TIMING LINES		6
LINES OTHERWISE SPECIFIED	_	85
RESERVED LINES	19	N
FREE-USE LINES	0	N
POWER LINES (M = MULTIPLE)	м	4 + 5
	-	
DATA-LINE USE (U = UNIDIRECTIONAL, B = BIDIRECTIONAL)	В	В
	1	20
	<22	32
	231	32
MAXIMUM NUMBER OF DEVICES BY DEVICE ADDRESSING CAPABILITY	2312	232
BUS-ACCESS MANAGEMENT—CENTRALIZED?	-	N
-DAISY CHAIN?		N
-PARALLEL POLLING?	_	Y
-SERIAL POLLING?	_	N
-DIRECT LINES?	_	N
-OTHER?		-
PROGRAM-INTERRUPT MANAGEMENT-CENTRALIZED?	_	N
-DAISY CHAIN?	_	N
-PARALLEL POLLING?	_	Ŷ
		Y
-OTHER METHODS?	_	N
MAXIMUM TIMES FOR SINGLE REQUEST—BUS-ACCESS DETECTION (AS = ASYNC)	-	AS
-PROGRAM INTERRUPT DETECTION	-	VAR
-PROGRAM INTERRUPT LATENCY	_	VAR
- PROGRAM INTERRUPT PROCESSING	-	VAR
DATA TRANSFER TYPE SYNCHRONOUS (EIVED TIMING)2	V	N
ASVNCHPONOUS?	×	N V
-SYNCHBONOUS (HANDSHAKE)?	Ý	_
SINGLE OPERATIONS ONLY?	N	N
MULTIPLE UNINTERRUPTIBLE OPERATIONS?	Y	Y
MULTIPLE INTERRUPTIBLE OPERATIONS?	Y	Y
MULTIPLE-SOURCE READ?	Y	N
MULTIPLE-DESTINATION WRITE?	N	Y
DISTINCTION BETWEEN BYTE/WORD TRANSFER?	N	Y
SPECIAL LINES-HOLD?	Y	N
-WAIT?	Ŷ	N
-INITIALIZE-BESET?	Ŷ	N
POWER FAIL/WARNING?	Y	N
-INTERRUPT REQUEST?	Y	N
-INTERRUPT ACKNOWLEDGE?	Y	N
-OTHERS?	_	N
LINES FOR HANDLING ERRORS—TRANSMISSION ERRORS?	Y	4
-OPERATIONAL (USER ERRORS)?	-	4
NOTES:		
THAS 130 LINES ON BACKPLANE AND 58 ON CABLE BUS.		
(2) ≤32 DEVICES PER SEGMENT.		
3 HAS TWO LEVELS. LEVEL-1 LINES (CURRENTLY BEING DEVELOPED) ARE 64 SPECI	FIED/64 AV	AILABLE
AND LEVEL-2 LINES (STILL NEEDING REFINEMENT) ARE 96 SPECIFIED/96 AVAILA	BLE.	
(4) NO PROVISION EXISTS WITH THE 64-PIN ARRANGEMENT FOR REDUNDANT PATCH	HS WITHOU	JI AN
EXTRA CONNECTOR. THIS IMPLEMENTATION PHOBLEM IS LEFT TO DESIGNERS.		
GINDIVISIBLE - CUBRENT BUS OPERATION WILL BUN TO COMPLETION		

medium and protocol with minimal emphasis on implementation. Most of the attributes listed in the **table** are left up to the system designer's choice. Items such as timing requests are implementation dependent, and special line functions are part of the interrupt structure.

Additionally, the Fastbus high-speed data bus (less than 100-nsec word transfer on a short segment), suits multicrate, multiprocessor applications that require a system-wide (over several crates) addressing

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capability. Consequently, the bus definitions don't lend themselves to comparison with less capable buses (hence the lack of specs in the **table** for bus-access management and detection and program-interrupt management). You can obtain additional information on the Fastbus from R S Larsen, chairman, Fast System Design Group, Stanford Linear Accelerator Center, Box 4349, Stanford, CA 94305.

Benchmark update updated

Dear Editor:

In the box in EDN's Benchmark Update (see pg 169 in this issue), the execution times shown for the MC68000L12 are correct for a clock frequency of 12.0 MHz. However, the specified minimum clock-cycle period for the MC68000L12 is 80 nsec, which yields a maximum clock frequency of 12.5 MHz.

This clock frequency produces an approximately 4.0% execution-time reduction on the benchmarks as shown below:

Benchmark	Execution time
	(μsec)
Α	25.6
В	257.3
E	180
F	55.7
Н	96.8
Ι	13,878
K	293

Motorola's branding procedures do not allow fractions (½ would be too small to be read) or decimal points (also too small) in the branded part number. Sincerely, James J Farrell III Manager, Technical

Communications Motorola MOS Integrated Circuits Group Austin, TX



Stand-alone ICE is a new class of instrument, created by Millennium, for use in development labs to debug μ P-based systems. Traditionally, microprocessor development systems were used for all development functions: code entry and edit, assembly, compilation, linkage of relocatable modules, and debug. And, the same system was used to debug hardware.

By distributing both the hardware and software debug functions into a separate instrument, development becomes "unbundled." The software development system can perform its classic functions (code entry, edit, assemble/compile), and the separate stand-alone ICE station debugs hardware or software simultaneously. The result is two users employing one "singleuser" development system for two separate tasks at the same time.

This approach of unbundling debug and software development stations provides modules that may be configured to support the development task at hand. The ratio of software development stations to software/hardware debug stations may be varied to properly support the number of engineers and programmers on a project.

Development labs which use minicomputers for software development can also benefit from the unbundled approach. Stand-alone ICE debug stations can work with minicomputers as readily as with microprocessor development systems. Software can be generated using editors and cross-assemblers on the minicomputer, and downloaded to the ICE station via an RS232 port. The ICE station can be used as either a code execution vehicle, or as a hardware/software debug station. The minicomputer thus becomes a multi-user development system.



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Easy to work with. Start with a straightforward command set. Just 25 commands, all of which are functionally relevant. With the command set,

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Is there no limit to IEEE's arrogance?

Because of IEEE's apparent unwillingness over the years to represent the best interests of the bulk of its membership—working engineers—many of its members have dropped their affiliation. Additionally, many other engineers have refused to join at all. However, "unwillingness" (translate to "unresponsiveness") might be too kind in describing the Board of Directors's latest move. "Arrogant" is closer to the mark.

Once again, without consulting IEEE's membership, the Board has taken an action that appears to be self serving and ill advised. In the name of IEEE, it has filed a brief with the US Supreme Court supporting the contention of ASME (the American Society of Mechanical Engineers) that engineering societies should be exempt from the Sherman Anti-Trust Act.

ASME's appeal to the Supreme Court stems from a lower court's ruling that ASME members conspired with a manufacturer of boiler safety equipment when they met with that manufacturer and then issued a statement on

ASME letterhead implying that another manufacturer's safety device did not meet ASME's boiler-code regulations. In reality, the device did meet the regulations. The second company claimed that this letter affected sales, forcing it to go out of business. The court agreed and awarded the firm \$9.9 million in the resulting suit against ASME.

The basis for ASME's appeal and IEEE's brief is that the society's committees consist of volunteers who should not be held accountable for their actions in the name of ASME. IEEE contends, "Indeed, a rule of strict liability may herald the curtailment of beneficial professional society programs in any case where organizational procedures theoretically may be abused by volunteer members for individual commercial advantage. In a large society such as IEEE, a significant number of such programs may be jeopardized, in spite of the existence of reasonable, workable procedural controls, because of the impossibility of policing all society members' conduct."

EDN believes that this position is a foul-smelling smokescreen. The fact that committee members are volunteers should have no bearing on their accountability. They can do the same amount of harm (or good) whether they're paid or not. And if a society accepts the responsibility of setting industry standards and/or regulations, it must be willing to be held accountable for its actions and the actions of the members it appoints to key committees.

IEEE's Board consists of company executives and academics. It has rarely been accused of taking stands that benefit the membership when such stands conflict with its members' interests. The Board's actions have remained true to form in this case.

EDN urges IEEE to withdraw its brief. The engineering profession will never attain the respect and stature it strives for if it refuses to be held responsible and accountable for its actions.

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Technology Update

Frequency counters offer wide selection in form, function and price

Andy Santoni, Western Editor

Instrument vendors now supply a wide variety of frequency counters to meet virtually any frequencymeasurement need. Monolithic counters range from low-cost instruments-some with IEEE-488 interfaces-to microwave units that reach 110 GHz. Plug-in counters provide flexibility, either as counter mainframes with plug-ins for different functions or frequencies or as general-purpose instrument mainframes that accept a variety of counter modules. And you'll also find counters in multifunction instruments or logic analyzer/counters.

When shopping for any of these instrument types, you'll encounter a multitude of suppliers offering many counter variations, notes Michael Nelson, marketing product analyst at instrument renter Leasametric Inc. There's probably one to meet virtually any need. And a handful of general-purpose models would probably cover almost every requirement. For instance, three counters-a 1-GHz battery-operated portable, a 1-GHz universal counter/timer and a microwave counter-could probably satisfy 95% of all user needs.

When renting a unit for a few days, you can afford to pay for such extra capability. But when buying in OEM quantities, the price differential between a generalpurpose instrument and one more closely matching your requirements becomes significant. Then, you'll do best by reviewing the wide variety of models available and selecting the one best matched to your needs.

Counters cover more

Today you can select one versatile United States Instrument Rentals. unit that handles a wide range of Thus, to provide performance applications. Hewlett-Packard's roughly equivalent to that of the EDN SEPTEMBER 16, 1981



Counters and universal counter/timers offer a wide range of performance and features. At the high end, Hewlett-Packard's \$5200 Model 5345A covers dc to 500 MHz; plug-ins widen its coverage to 40 GHz. Single-shot time-interval measurements to 2 nsec and an optional IEEE-488 interface are also available.

Model 5335A (\$2950), for example, covers dc to 200 MHz and with the optional C channel (\$450) reaches 1.3 GHz. Yet its standard features, such as a GPIB interface, make it cost competitive with the older HP Model 5328A (\$1450), notes Susan Davis, purchasing manager at United States Instrument Rentals. Thus, to provide performance roughly equivalent to that of the 1.3-GHz 5335A, the plug-in Model 5328A needs a bus-interface module (\$350), 1.3-GHz C channel (\$650) and programmable input-control module (\$950)—and the 5335A still provides better single-shot timeinterval averaging performance (2 vs 10 nsec) as well as built-in math and statistics capabilities.

With its improved performance, Model 5335A illustrates the evolu-

Technology Update

tionary refinement of today's frequency-counter designs, says Leasametric's Nelson, as opposed to quantum leaps in performance. Suppliers have been "chipping away at problems," agrees Richard Watts, product marketing manager at Hewlett-Packard's Santa Clara, CA Instrument Div. Math functions, for instance, make it easier for users to get the data they want, not just a raw readout of frequency or time interval.

The latest counters also implement the devices and features becoming standard in all types of instruments—usually an IEEE-488 interface and μ P control.

Bus control at any price

The IEEE-488 bus is not restricted to the more expensive models, either. It's also available in low-cost counters. For instance, HP's Model 5316A (\$1500) furnishes bus-programmable measurement functions,



Modular frequency counters in Tektronix's TM 500 Series can plug into a mainframe. Units range from the 5-digit, 80-MHz DC 504 (\$525) to the 9-digit, 1-GHz DC 508 (\$1250). All are compatible with the firm's TM 5000 programmable instrument system.



Among the various programmable plug-in instruments in Tektronix's TM 5000 Series, you'll find two counters: Models DC 5009 (135 MHz, \$2200) and DC 5010 (350 MHz, \$3600).

dc trigger level and slope. And like the manually controlled Model 5315B (\$1050) and the portable Model 5315A (\$875), it measures frequency to 100 MHz. It also provides an optional C channel (\$250) that increases capability to 1.0 GHz for both continuous-wave and pulsed RF signals as narrow as 60 msec.

All these units measure time intervals from 100 nsec to 100,000 sec. Additionally, their time-interval-averaging function provides greater resolution for repetitive events, and the time-interval-delay feature avoids spurious-signal measurements by holding off the counter's trigger point for a precise, selectable time.

You'll also find IEEE-488 interfaces at the high end of the frequency spectrum. EIP Microwave's Model 575 (\$7600) covers 10 Hz to 18 GHz, and Model 578 (\$8800), extends this range to 26.5 GHz; optional accessories for 110-GHz capability add another \$7000 (see pg 215 in this issue).

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Both instruments offer source locking, which affords broadband control of swept sources to provide synthesizer stability at relatively low cost. This feature also allows you to control a swept source via the IEEE-488 bus even if the source lacks a bus interface; you program the counters over the bus to set the source at any desired frequency.

µPs enhance features

EIP's instruments exemplify how μ Ps have found their way into frequency counters, as they have into almost every other instrument.

In early applications, they controlled interfaces to the keyboard, front-panel readouts and rear-panel programming inputs and outputs. Later, they added features such as arithmetic processing. More recent designs, though, use the processor in the measurement process itself, yielding a wider frequency range, shorter measurement time and simpler operation along with lower complexity and cost. Such products are therefore μP based, not merely μP controlled.

Improvements in frequencycounter designs, however, go beyond those implemented in other instrument types, notes Norbert Laengrich, international marketing manager at Racal-Dana Instruments. These developments have changed the nature of both frequency counters and the more capable universal counter/timers.

In frequency counters, the most obvious trend is to higher frequencies. Along with the record-holding 110-GHz models from EIP Microwave, units such as HP's 5345A and Systron-Donner's 6000 Series reach far into the microwave region.

EIP's instruments also typify the trend away from plug-in units to monolithic instruments. Such instruments, with internal modular designs, offer more value than mainframe/plug-in units because they are less expensive to build, explains Howard Lurie, marketing VP at EIP.



A low-cost counter featuring IEEE-488-bus compatibility, Hewlett-Packard's Model 5316A (bottom) costs \$1500. The \$1050 nonprogrammable Model 5315B (center) and the \$875 portable Model 5315A also provide 488 compatibility.

To widen frequency range, Lurie's firm's instruments incorporate a second internal down converter, which is mechanically simpler than using front-panel plug-ins. Thus, you don't have to pay for an expensive mainframe more powerful than you require.

Another trend that has surfaced in the last few years is direct counting at higher frequencies, points out Racal-Dana's Laengrich. Compared to prescaler designs, direct-count instruments provide lower conversion times. For example, they can cut conversion times from 10 to 1 sec compared to a divide-by-10 prescaler.

A counter is more than a chip

Laengrich also notes that specialpurpose LSI chips for frequency counting have become more widely used. These counter-on-a-chip designs, available from most major instrument vendors, reduce system chip count to achieve lower cost and better reliability.

LSI counter chips also facilitate the design of basic frequency counters, and this fact has led to many vendors offering this type of instrument. A question arises, however, about the staying power of some of these firms because their low-cost products are difficult to distribute and support.

The companies best able to design and market low-cost counters are those with in-house counter-IC capabilities, believes Gail Dishong, product director for frequency and communication products at Systron-Donner. His firm does not claim such in-house capabilities; instead, for continued success it relies on its



The highest frequency you can measure today with a frequency counter is 110 GHz, and you can measure it with EIP Microwave's Model 578. Models 575 and 578 feature source locking; they can control a swept source to achieve synthesizer-like performance at low cost.

software and microwave expertise —including its thin-film hybrid technology—to design complex front-end circuits such as those for microwave measurements. Dishong expects Systron-Donner to continue leaving the low end to other suppliers and aim at the midrange to high-performance markets.

One instrument vendor with chip capacity is Hewlett-Packard, a firm that also develops custom circuits. Its multiple-register counter IC handles all counter functions and is in Models 5315A/B and 5316A.

Standard frequency-counter chips have also made it easier for designers to incorporate such functions into other instruments. Thus,


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Technology Update



Wide-range frequency counters from Systron-Donner include Models 6241A (100 MHz, \$800) through 6244A (4.5 GHz, \$3300), shown at left; thin-line, rack-mounting Models 6041A (100 MHz, \$1400) through 6043A (1.25 GHz, \$1900), in the center; and Models 6245 (18 GHz, \$4700) and 6446A (26 GHz, \$5200), on the right.



Universal counter/timers and basic frequency counters in Fluke's line include Models 7250A (\$675), 7260A (\$850) and 7261A (\$995) universal counter/timers and Model 7220A counter (\$1050).

For more information...

For more information on the frequency-counter products and services described in this article, circle the appropriate numbers on the Information Retrieval Service card or contact the following manufacturers directly.

EIP Microwave Inc 2731 N First St San Jose, CA 95134 (408) 946-5700 Circle No 636

John Fluke Mfg Co Inc Box C9090 Everett, WA 98206 (206) 342-6300 Circle No 637

Hewlett-Packard Co 1507 Page Mill Rd Palo Alto, CA 94304 Phone local office Circle No 638

Leasametric Inc 1164 Triton Dr Foster City, CA 94404 (415) 574-4441 Circle No 639

Nicolet Paratronics Inc 2140 Bering Dr San Jose, CA 95131 (408) 263-2252 Circle No 640 Racal-Dana instruments Inc 18912 Von Karman Ave Irvine, CA 92713 (714) 833-1234 Circle No 641

Systron-Donner Instrument Div 2727 Systron Dr Concord, CA 94518 (415) 676-5000 Circle No 642

Tektronix Inc Box 1700 Beaverton, OR 97077 (800) 547-6711; in OR, (800) 452-6773 Circle No 643

US Instrument Rentals Inc 2988 Campus Dr San Mateo, CA 94403 (415) 572-6600 Circle No 644

Vu-Data Corp 7170 Convoy Ct San Diego, CA 92111 (714) 279-6572 Circle No 645 you'll find counter capability in logic analyzers such as Paratronics's Model NPC-764 or System 5000. HP's Model 1611A and Model 64000 development system also provide counter-like capabilities such as time-interval measurements.

Frequency counters are also available as options in oscilloscopes; Tektronix's Model 465B has a frequency counter/DMM option costing \$445, and Vu-Data's PS900 Series scopes offer the same capability for approximately \$400.

Universal counter/timers have added new features, too. For example, these instruments can now usually make high-level measurements for rise time, fall time and slew rate. They also feature more selective measuring characteristics, with sophisticated arming and triggering functions. These capabilities allow you to trigger exactly where you want to, not just on voltage crossings, and synchronize the counter to any desired pulse, not just the first or largest in amplitude. And they simplify measurements, especially in applications such as radar burst measurements.

CRTs could aid counter usage

Simplifying measurements will be one goal of future counter designs. A simple CRT screen built into a counter, for instance, could help users to visualize trigger levels and frequencies and provide greater confidence in measurements.

In this regard, HP's Watts feels that too many engineers, lacking this visual aid, turn to oscilloscopes for such measurements. Scopes, however, permit relatively accurate frequency measurements at best. Watts thus foresees a monolithic counter with a CRT tailored to frequency-counter needs as a more inexpensive alternative to a modular CRT/instrument design with frequency-counter functions.

This speculation shows how valuable a counter with a built-in CRT would be in bench applications. In system applications, designers

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Technology



Measuring frequencies from 30 MHz to 3 GHz, frequency counters and universal counter/timers in the 99Hundred Series from Racal-Dana (\$625 to \$2195) cover HF, VHF, UHF and microwave ranges and feature timebase, battery-pack and IEEE-488 options. A bipolar collector-diffusion-isolation LSI chip operating at frequencies greater than 60 MHz handles most counter functions.

would perhaps use a counter and oscilloscope to set up the system, then use a counter tailored to the application—perhaps without panel controls—in the operating system.

A CRT, however, would probably not prove too useful in microwave applications, says EIP Microwave's Lurie: At these frequencies, the user generally deals with a welldefined signal confined to a narrow frequency range.

CRTs could also help overcome another counter problem: control complexity. To provide access to all functions, front panels have become large, complex and even intimidating to many users. A solution might be to take a lesson from logic analyzers and employ CRTs and pushbuttons to facilitate function selection via menus.

HP's Watts points out one final area of counter design that will improve—input characteristics. Today's counters have dynamic ranges too narrow to handle applications such as measuring the rise time of a TTL pulse. Tomorrow's counters, however, should overcome this limitation. EDN

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Technology Update

Intelligent-terminal hardware, software evolves to meet dual designer needs

Patrick Kenealy and David H Freedman, GML Corp

With some intelligent terminals virtually indistinguishable from stand-alone systems, manufacturers are still looking for that novel combination of mass storage, μP and communications capability that will give them a niche in an as-yet-undefined market. But now two areas of competition—both with implications for OEM designers are emerging for first-generation intelligent-terminal manufacturers who seek a market edge:

- Development of the hardware and software features to support special functions
- Improvement of the price/ performance characteristics of nonspecialized, µC-like intelligent terminals.

Defining a typical terminal

The intelligent-terminal market spans distributed-processing, officeautomation, word - processing, graphics and stand-alone applications. Although this diversity of functions denies manufacturers a coherent market against which to define product features and prices, companies have nevertheless characterized first-generation intelligent terminals themselves.

Such a full-function unit typically incorporates 64k bytes of RAM, an 8-bit μ P and one or more floppydisk drives. It supports at least one programming language and offers a standard or optional serial printer.

Patrick Kenealy and **David H Freedman** are editors of *Terminals Review* and The Display Pricing Strategy Service, published by GML Corp, Lexington, MA.



An RS-232C-interfaced ASCII terminal, the CTM-300 from Matrox Electronic Systems also features an 8-color CRT display. You can customize its functions from the host computer via a downloaded program.

Many intelligent units display sophisticated graphics, and more than a dozen current models feature multicolored displays. The userprogrammable CTM-300 from Matrox Electronic Systems, for example, incorporates an 8-color CRT display and sells for less than \$3000.

Average intelligent-terminal prices (figure) now range from \$4000 to \$8000 for basic units and from \$6000 to \$10,000 for units with bundled software and printers; prices, however, continue to drop. The wide price distribution results from the diversity of terminal applications; similar hardware configurations can command different prices depending on customers' applications and price tolerances.

You can program virtually all intelligent terminals in assembly language, and more than half support BASIC. COBOL, FOR- TRAN and PASCAL are also widely supported, and many intelligent terminals feature CP/M or similar operating systems with extensive multilanguage capability.

Move to specialization

As distributed processing, office automation, word processing and other intelligent-terminal applications become more standardized, intelligent-terminal manufacturers will be forced to dedicate their machines to fewer and fewer applications. Datapoint Corp and Texas Instruments, both specializing in distributed data processing, exemplify this trend. Wang Laboratories has notably stressed office automation, and still other manufacturers, such as Chromatics, have branched into the business colorgraphics market.

Intelligent Systems, Televideo

Technology Update

and Zentec, on the other hand, continue to offer general-purpose intelligent terminals that provide users with the equivalent of a stand-alone μ C. For example, Zentec's latest offering in this product area, its ZMS-35, employs a 8085 μ P and sells for \$1350.

Although such terminals usually

cannot support extensive wordprocessing or shared-database capabilities, they allow users to develop and run programs off line, reducing demands on their hosts.

What's to come

The intelligent-terminal product area continues to develop. First-







provides 16k bytes of user RAM, a fully configurable keyboard and a 12-in. nonglare CRT with a 128-character set.

generation intelligent terminals, whether specialized or general purpose, are now being joined by second-generation hardware—128kbyte, 16-bit systems based on Winchester disk drives and backed by streaming cartridge-tape drives.

This second-generation hardware suits users designing systems for distributed-processing/office-automation applications. Additionally, prices for 8-bit μ Ps and memory continue to fall for firms offering basic stand-alone units. Thus, such a system should eventually sell for less than \$3000, including a low-cost matrix printer. Distributed-processing units, on the other hand, should sell for \$5000 to \$10,000.

Memory-, μ P- and diskettesystem prices are stabilizing just as display-tube, keyboard and powersupply costs have, and prices for basic intelligent units should become more defined and competitive in the next 8 months.

Developments further in the future promise to be just as interesting. The intelligent-terminal industry combines high profits and high risk. Prices and profit margin both remain high and flexible, along with off-line-storage,



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Technology

printer and software-development costs. Thus, manufacturers of stand-alone, general-purpose intelligent terminals will compete with one another as well as with μC vendors. (Commercial μC systems, however, usually communicate with larger computer systems and sell for less than intelligent terminals with similar software, memory and off-line storage.)

Manufacturers of intelligent terminals for distributed-processing applications will find themselves competing as system vendors rather than terminal vendors. Datapoint, Four-Phase, Northern Telecom and others will face minicomputer manufacturers such as DEC, Honeywell and Hewlett-Packard rather than mainstream terminal firms. And as 16-bit μ Cs are used more frequently in intelligent terminals, those terminals will become even less distinguishable from minis and small business systems.

Proprietary operating systems, communication interfaces and other software will keep prices for such intelligent terminals high, and their manufacturers will have to offer field service, extensive peripheralsoftware support and flexible leasing arrangements to remain competitive with minicomputer firms. A solid intelligent-terminal-firm commitment to distributed processing will thus amount to that firm's leaving the terminal industry and entering the minicomputer industry. EDN

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Leadtime Index

ACTIVE COMPONENTS

PRODUCT	LEAD Min.	DTIME IN Max.	WEEKS Trend	PRODUCT	LEAD Min.	DTIME IN Max.	WEEKS Trend
DISCRETE SEMICONDUCT	ORS			MEMORY CIRCUITS			
Diode. switching	2	4	=	EPROM	3	5	=
Diode, zener	1	5	=	PROM. bipolar	3	4	+
Rectifier, low-power	1	5	-	BAM, bipolar	3	14	+
Rectifier, power	1	4	-	BAM, CMOS	2	10	=
Thyristor, low-power	1	4	=	RAM, 4k MOS dynamic	4	16	=
Thyristor, power	2	7	-	RAM, 16k MOS dynamic	4	16	=
Transistor, bipolar power	6	13	=	RAM, 1k MOS static	4	16	=
Transistor, bipolar signal	6	20	=	BAM, 4k MOS static	4	14	=
FET. power	5	12	-	BOM masked MOS	5	15	+
FET, signal	4	10	-			VOTE	10
Transistor, RF power	5	12	=	MICROCOMPUTER/MEMOI	AY S	YSTE	MS
				Core memory board	5	9	=
DISPLAYS			-	IC memory board	5	9	=
Fluorescent	2	12	=	Interface board	4	8	4
Gas-discharge	1	12	=	Microcomputer board	3	9	=
Incandescent	4	8	=	MICROPROCESSOR IC'S			
LED	2	8	=	CPU, bipolar bit slice	3	14	
Liquid crystal	2	10		CPU, 4-bit MOS	4	12	0
Plasma panel	5	12	=	CPU, 8-bit MOS	3	12	=
ELECTRON TUBES				CPU, 16-bit MOS	4	14	=
CRT, black and white TV	6	14		Peripheral chip	5	14	=
CRT, color TV	8	12	=		-0		
CRT, industrial	8	16	0	OPTOELECTRONIC DEVICE			Part of the second
Industrial power	4	10	=	Coupler and isolator	1	14	+
Light and image sensing	4	10	=	Discrete light-emitting diode	9	19	=
Microwave power	9	13	=	PACKAGED FUNCTIONS			
		A 1		Amplifier, instrumentation	3	11	+
CMOS				Amplifier, operational	2	9	+
CMUS Diada transistar lagis (DTL)	4	10		Amplifier, sample/hold	5	12	=
Emitter equaled logic (ECL)	0	12	-	Converter, analog/digital	5	9	
Low power Schottler TT	4	10	4	Converter, digital/analog	5	9	0
Standard Schottky TT	5	17		PANEL METERS			11.0
Standard Schollky TTL	6	10		Analog	10	10	•
Standard TTL	0	18	=	Digital	5	10	4
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Communications circuit	6	14	=	POWER SUPPLIES	-	-	-
Data converter	8	12	0	Custom	15	18	=
Interface circuit	6	15	=	Enclosed modular	7	16	=
Operational amplifier	1	3	=	Open-frame module	11	18	
Voltage regulator	1	4	=	Printed circuit	10	16	=

Leadtimes are based on recent figures supplied to *Electronic Business* magazine by a composite group of major manufacturers and OEMs. They represent the typical times necessary to allocate manufacturing capacity to build and ship a medium-sized order for a moderately popular item. Trends represent changes expected for next month.

Will the FCC put you in a cost-delivery crunch October 1? Not with Sierracin power systems.

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We'll gladly show you a CRT for sore eyes.



A MITSUBISHI ELECTRIC COLOR CATHODE RAY TUBES

Editor's Choice: New Products

Speech module generates 120 words

Model M410 Speech Generator board uses a single-chip voice synthesizer to provide low-cost voice output for virtually any computer system. Measuring $3.75 \times 4 \times 0.5$ in., it includes the linear-predictive-coding (LPC) speech chip, a μ P, a clock, control logic and memory.

You add the board to your system via a 20-pin flat-cable connector. Designing a parallel interface for it is easy: It looks like an 8212 parallel latch and buffer to the μ C and runs on a 5V power supply (225 mA typ).

For S-100-bus systems, you can even choose a larger version (Model VR/S100) that plugs directly into any bus slot.

The word's the thing

In four 32k EPROMs, the speech generator stores approximately 120 words and phrases. (Typical word packing puts 12 to 20 words in a 16k memory or 25 to 40 words in a 32k unit.)

The manufacturer supplies a basic vocabulary in one 32k EPROM and includes the digits one through nine and the words *plus, minus, times, point, is, enter, repeat, error, what?, oh, thank you* and *goodbye*. You also get pauses of 50, 100, 200 and 400 msec, which allow you to pace the speech output and make it more intelligible.

If none of these words suits your needs, you can choose (for an extra charge) from the manufacturer's rapidly growing library of pre-encoded utterances. And if the library doesn't fill your needs, the firm will create the exact custom vocabulary you require for \$200 per second



Speaking for nearly any \muC system, the M410 speech generator provides all the flexibility you need in a voice-response peripheral.

of speech (\$1000 minimum).

If you choose to develop such a custom vocabulary, you can select among data rates ranging from 1200 to 1600 bps for low-quality speech and from 2000 to 2200 bps for high-quality output. (The lowest data rates provide the largest vocabulary.)

Getting the words out

You connect the M410's audio output directly to an 8Ω speaker. The board outputs 0.2W and requires no additional circuitry for speech generation. You can even make the system speak on the telephone by connecting it directly over an acoustic coupler.

You address vocabulary words

with an 8-bit parallel code. The on-board μ P accepts 54 bytes of selector codes, storing them in its internal RAM and thus acting as a FIFO buffer.

If the buffer gets full, the board's Ready line goes LOW, inhibiting the selection of new words until the buffer has room for them. Further, if you choose an invalid selector code, the μP ignores it and looks for the next.

\$95 (OEM qty); \$185 (1-19) with basic vocabulary. S-100 VR/S100A version, \$190 (OEM qty) with no vocabulary; \$325 (1-19) with the basic vocabulary.

Speech Technology Corp, 631 Wilshire Blvd, Santa Monica, CA 90401. Phone (213) 393-0101. Circle No 456

A LITTLE BASIC TRAINING FOR SMART MILITARY DESIGNERS.

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impedance control. Good news if you're dealing with advanced IC logic families. The KS1025 Series features Dynamic Retention*press-fit compliant contacts for unsurpassed reliability and performance. *Pat. No. RE29513

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So if you're working with MIL-C-28859, MIL-C-28754 or WS6157, or if you simply want the highest quality backplane systems in the world, contact Teradyne.

All the facts and a complete Teradyne system design kit are yours for the asking. Write Teradyne Connection Systems, Inc., 44 Simon St., Nashua, N.H. 03060. Or call (603) 889-5156.



CIRCLE NO 33

Editor's Choice: New Products

Dual-redundant microcomputer system delivers fail-safe bumpless transfers

A fail-safe processor for realtime process-control applications, Model DRS2102 dualredundant μ C system executes a bumpless transfer between its primary and secondary computer boards in the event of a primary-unit fault. The dual redundancy improves computer availability (eg, percentage of total time a system is up and operating properly) in applications where loss of the computer can lead to costly or dangerous operating conditions.

Cutover from a primary to a secondary control unit usually results in a temporary loss of control, shutdown or manual operation until secondary-unit initialization and on-line placement. But the DRS2102's hardware/software design eliminates these problems by effecting a cutover in 5 to 10 μ sec—fast enough to keep up with highspeed processes.

Dual boards do the job

The DRS2102 comprises two identical μ C boards linked by buffers that don't corrupt the receiving μ P should either one fail. The linkage allows each μ C board (A and B) to communicate continuously; thus, each board is always in the same state.

Each board contains an 8085 μ P and 8k bytes of memory, consisting of static RAM for a real-time database and PROM or EEPROM for control firmware. Upon power shutdown, variable data goes to EEPROM or a separate 4k-byte core module.

Also on each board are six addressable bidirectional I/O ports, three programmable tim-



Two 8085-based μ **C boards** combine to produce a dual-redundant controller that ensures proper operation of real-time process-control systems. When a fault occurs in one board, the Redundancy Manager operating system pulls it off line and switches in the second board, performing a fail-safe bumpless transfer.

ers, interrupt inputs and an RS-232C port. An expansion bus allows use of a 16k-byte static-RAM board and a 4k-byte core board.

An external interface and display module contains status lights, numerical readouts and a hexadecimal keypad for manual access to the μ C system. It operates via a control port on the μ C system.

Both μ C boards function under control of the Redundancy Manager operating system. This OS checks critical variables in the application-program flow for proper response and validity. If it detects a fault, it can retry on a nonfatal fault or activate the output selector to push the primary μ C (board A) off line and switch the backup μ C (board B) on line. Because of the communication requirements between the A and B boards, the μ C system does not employ an industry-standard bus (eg, STD, S-100 or Multibus). Instead, the manufacturer has opted for a no-bus or direct handshaking version, simplifying system expansion and circuit operation.

Packaged on two stackable 6×8 -in. pc boards, the μ C system utilizes flat cable for interconnections. Accepting raw +8 and $\pm16V$ dc power, each board contains regulators for reduced common-mode noise.

Operating over 0 to 70°C, the system costs \$3250 (OEM qty) without software.

Del Rey Systems Inc, 8929 Sepulveda Blvd, Los Angeles, CA 90045. Phone (213) 641-4955. Circle No 457



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MOTOROLA Display Systems

CIRCLE NO 35

1299 E. Algonquin Road Schaumburg, IL 60196 312/397-8000

Editor's Choice: New Products

General-purpose computer joins three processors in small package

Combining three coprocessors a 16-bit 68000 CPU, a second 68000 for virtual-memory management and a 6809 I/O processor—the 68K Miniframe general-purpose computer runs the Bell Labs UNIX operating system and operates at 12 MHz with no Wait states.

The 6809 interfaces to all I/O devices on an interrupt-driven basis and interacts with the CPU through a sophisticated high-speed DMA channel using cycle stealing. The 68000's DMA is daisy chained, with the 6809 having the highest priority.

The memory processor addresses as much as 4G bytes of RAM through a virtual-memory management unit (VMMU). This processor, which connects the CPU's address bus to a dynamic-RAM-array address bus, receives its control signals from the data bus. A modified least-recently-used page-replacement algorithm provides demand-paged virtual memory in 16M-byte increments.

Memory comes on dynamic-RAM boards that work with or without the VMMU. The boards connect to the CPU via a flat ribbon cable that terminates in dual-row 50-pin insulation-displacement connectors. You can configure the boards for as little as 128k bytes of RAM (using 16k×1 RAMs) or as much as 2M bytes (using 64k×1 RAMs).

Each byte of RAM has an associated parity bit that you can disable at the board level. An intelligent statistical-refresh method ensures refresh with maximum transparency.

A 4k×16 high-speed associa-



A powerful 16-bit general-purpose computer in a small package, the 68K Miniframe supports multiple users with the Bell Labs UNIX operating system.

tive memory furnishes the page map, and it is accessible within the last 1M bytes of supervisor data-address space.

Many things to many users

In multiuser and multitasking applications, the system maintains both relocation and limit registers for each user. Each version of the system works with either floppy or hard disks and provides six RS-232 ports (through six ACIAs) capable of 500k-baud transmission, plus four parallel ports (PIAs) consisting of eight bidirectional lines and two handshaking lines.

A single-user UNIX-based Miniframe starts at less than

\$12,000 and comes with 256k of RAM, 2M bytes of 8-in. floppydisk storage and the complete UNIX v.7 package including FORTRAN-77, the C language, BASIC, and text-processor and file-processing utilities.

For multiuser systems, a typical configuration accommodates six or more users and comes with 512k bytes of RAM in a 16M-byte virtual space, 40M bytes of Winchester-disk storage and the UNIX package; it sells for less than \$20,000.

MicroDaSys Inc, 2811 Wilshire Blvd, Santa Monica, CA 90403. Phone (213) 829-6781. Circle No 458

YOU CAN USUALLY TELL WHEN THERE'S A NOISY POT IN THE CONTROL PANEL.



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• Molded Carbon	11/2%	Not guaranteed after 100K cycles.

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Terminals are in-line PC style on .100 inch centers. You can position them forward, back or down for vertical or horizontal board mounting. Choose from two bushing sizes, six tapers and three standard shaft lengths to %". Resistance values from 250 ohms to 5 megohms.

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THERE IS NO EQUIVALENT.

EDN SEPTEMBER 16, 1981

Editor's Choice: New Products

Mini-floppy-disk formatter/controller family offers full features at lower cost

Exhibiting all the features of their more expensive 179X relatives, 176X-family disk controllers are designed exclusively for mini-floppy use. All run at 1 MHz and are compatible with the 179X units, which handle $5\frac{1}{4}$ - and 8-in. floppy drives.

The line consists of four parts: the 1761, -63, -65 and -67. They cover all combinations of singleand double-density, true- or inverted-data-bus and single- or double-sided drives. Single-density format is compatible with IBM's 3740; double density, with IBM's System/34. The parts can also use a non-IBM format for increased density.

Designed for soft-sectored systems, the devices feature automatic track seek with verification, DMA or programmed data transfers from a double-buffered 8-bit bidirectional data bus and eight control



Operating at 1 MHz, 176X-family 5¹/₄-in.-mini-floppy controller chips are compatible with 179X-family controllers for 5¹/₄- and 8-in. drives. But they cost less—\$25.30 (100) in plastic.

lines for μP compatibility. Additionally, all inputs and outputs are TTL compatible, and as in the 179X family, two VFO signals are available.

The devices output writeprecompensation signals, allow

NEXT TIME

EDN's September 30 issue will feature a Special Report on gate-array ICs, plus articles on a variety of additional topics:

- Optimizing flash A/D-converter operation through the use of track/hold amplifiers
- The theory and application of tonedecoder ICs
- The use of memory segmentation in Intel's iAPX 432 32-bit μP

... and much more. Also look for Technology Update pieces on solid-state relays and voltage regulators, plus our regular Design Ideas and A Question of Law departments. You can't afford to miss this issue!

EDN: Everything Designers Need

window extension and incorporate encoding, decoding and address-mark circuitry. In Read mode, they can either perform single- or multiple-sector read with automatic search or read the entire track. Likewise, they support single- or multiplesector write with automatic sector search or can write the entire track for diskette formatting. They accept 11 commands and feature on-chip track and sector registers plus comprehensive status information.

The devices are available in 40-pin ceramic or plastic packages. Operating temperature spans 0 to 70°C, and power dissipation equals 600 mW max. Power-supply requirements stand at 5 and 12V. \$25.30 in plastic, \$36 (100) in ceramic.

Western Digital Corp, Box 2180, Newport Beach, CA 92663. Phone (714) 557-3550. Circle No 459

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CIRCLE NO 38

Editor's Choice: New Products

Low-cost development system operates over STD bus

Providing a Z80 or 8085 CPU card that plugs into an STD Bus mainframe to simplify switching between devices, the Basis/80 development system costs less than \$10,000. Yet it includes the memory, control and in-circuitemulation features of more expensive systems.

Using the CP/M (Version 2.2) operating system from Digital Research Corp for disk-file management, the development system allows you to program in FORTRAN, BASIC, PASCAL or FORTH as well as assembly language. Development software includes a screen-oriented editor with menu-select options; the editor lets you examine 24 lines of code and make changes or additions by positioning the CRT's cursor and entering data.

The system handles devices other than Z80 and 8085 types by means of cross assemblers, which feature full macro capability, cross-reference map, algebraic-expression processor and link-file structures.

In-circuit emulation

Basis/80 includes in-busemulation capability for development of products designed around the STD Bus. An emulation card plugs into the target system in place of the system's CPU card, giving system control to the Basis/80.

Emulation allows you to debug hardware and software on the target system, which can address as many as 254 input and 254 output ports and 58k bytes of PROM or RAM without conflict with the emulator's workspace. Emulation features



An STD Bus mainframe packs the hardware you need to develop software on the Basis/80 for Z80 and 8085 μ Ps. Cross software handles 8080, 6502 and 680X devices.

include real-time execution of program code with breakpoints set for the occurrence of either a particular input/output instruction or a memory reference to a single location within the target system. Additionally, program trace permits single-instruction execution and dumping of register contents to the CRT.

Symbolic debugging

You can also perform symbolic debugging of Z80 and 8085 programs. You download executable object files for the other supported microprocessors through an RS-232C port to either a PROM programmer or a target system for debugging.

The debugger allows you to set unlimited breakpoints and as many as eight passpoints, providing a means of monitoring program flow through code sections and examining register contents. Other single-key commands in the debugger provide for altering memory, examining registers, displaying memory contents, moving blocks of code and executing code.

Basis/80 hardware includes a Z80 or 8085 CPU, PROM bootstrap, 32k to 58k bytes of RAM and 499k bytes of disk storage on dual 8-in. drives. You also get a 15k-baud memorymapped CRT controller providing a 25-line×80-character scrolling display, alphanumeric keyboard with cursor-control and numeric keypad and frontpanel controls to reset or interrupt program execution and (via keylock) apply power to the mainframe.

\$6110 to \$8405; a typical system, consisting of mainframe, disk drives, terminal, 48k bytes of RAM and 132column impact printer, costs \$7495.

Antona Corp, 13600 Ventura Blvd, Sherman Oaks, CA 91423. Phone (213) 986-6651. Circle No 460 The DILOG DQ130 and DU130 are μ P based intelligent 1/2 " Tape Couplers for your LSI-11, 11/2, 11/23 or PDP-11

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The Couplers emulate the DEC TM-11/TS-03 and you'll get full software compatibility with RT-11, RSX-11, RSTS, IAS and MUMPS.

As for tape drive compatibility, both the DQ130 and DU130 interface drives from the following manufacturers:

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> VISIT DILOG AT SYSTEMS '81' BOOTH 57 HALL 2 U.S. SECTOR



NUMBER 1 FOR DEC-11 EDN SEPTEMBER 16, 1981

Editor's Choice: New Products

Development system for Z80, 3870 operates from time-shared host

For use with a host computer (including time-shared units), the Radiµs development system provides software-development capability via that host plus hardware development and hardware/software integration via in-circuit-emulation modules. It supports Z80s and 3870s.

You install the \$2995 Radiµs (Remote Access Development and Integration Microcomputer System) between a CRT terminal and the host via RS-232 serial interfaces. While software development is performed on the host as usual, you can download programs to Radiµs for hardware debugging and software integration, using optional E Series AIM in-circuitemulation modules.

In Transparent mode, the CRT has its usual access to the host. In Local mode, Radiµs can perform self diagnostics and be set for any of 11 baud rates from 50 to 9600. You can also set control characters in this mode.

In Utility mode, Radiµs can run utility programs for such tasks as in-circuit emulation, printer handling and PROM programming. Debugging and integration routines are also available in this mode.

Once AIM and user programs are downloaded to Radiµs, you can disconnect the host, saving time-sharing costs. However, the host's file-management utilities are then not available.

You can configure Radiµs for single or multiple-user environments and connect several AIM units to one host for simultaneous operation. This mode also allows you to perform separate



Tied to your time-sharing or other host computer, the Radiµs development system aids in the design of Z80- or 3870-based hardware and its integration with software.

or multiprocessor tasks.

Radiµs comes with a host communications-software package for DEC PDP-11 computers working under the RSX-11M operating system (Version 2.3 or later) or on DEC VAX-11 systems working under VMS (Version 2.3 or later).

Hardware includes a structural-foam cabinet, CPU/memory board and power supply. AIM-Z80BE, AIM-7XE or future AIM modules, local PROM programming and local printing are optional. The cabinet's processing compartment houses as many as five boards: the CPU/memory board, two AIMmodule boards and two expansion slots.

The CPU/memory board includes a Z80 CPU, 64k bytes of RAM and four serial I/O ports: one dedicated to the user terminal, one to the host and two for the optional printer and PROM programmer.

A translator is available to convert Tektronix 3870 and Intel hexadecimal object formats to absolute-binary form.

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It's not as hard as you think. Forget complex designs. And two-year waits.

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For some simple reasons. The 8088 runs at full speed with slower speed memories than you need for other 8-bit microprocessors.

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But don't think you have to stop there. With any of our iAPX 88 multiprocessor configurations, you can give performance an added boost—and still keep the cost and simplicity of an 8-bit system.

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Computer Graphics	1.0	0.1	0.05
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Full details of ti	hese bench	marks	available

Full details of these benchmarks available in the iAPX 88 Book.



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Personal Scientific Calculators

Alphanumeric displays and keyboards and high-level-language programming combine in the newest hand-held machines.

Jim McDermott, Special Features Editor

Highlighting personal programmable scientific calculators this year is the emergence of a new generation of hand-held machines featuring extended horizontal alphanumeric displays and full-alphanumeric keyboards. Additionally, these calculators (some call them computers) are programmed not in the efficient machine language associated with standard scientific calculators, but in high-level BASIC.

Offered by Radio Shack, Sharp, Casio, Panasonic and Quasar, the horizontally stretched machines feature

Alphanumeric capabilities and BASIC programming characterize programmable pocket computers. (Photo courtesy Radio Shack) dot-matrix LCD screens that display 20 to 24 characters. Furthermore, such alphanumeric displays are also appearing in new lower priced scientific programmables with 11- or 13-character readouts.

Most familiar of the BASIC machines is the Radio Shack \$230 TRS-80 Pocket Computer, which has been available for some time. Sharp, which manufactures the machine for Radio Shack, introduced it recently under its own label as the PC-1211 Pocket Computer. The dot-matrix display on both of these devices is remarkably like that of Sharp's EL-5100 (introduced in mid-1979), the first scientific programmable calculator into which a user could write alphanumeric formulas without first translating them into machine language (EDN, June 20, 1979, pg 97). The -5100's display also prompts the user during program runs. (Actually, the

Keyboard configurations vary; units aim at typewriter ease

-5100 is only pseudoprogrammable: It can't handle independent subroutines or loops.)

Although the EL-5100 and Pocket Computer displays can present 24 characters at a time, their display register holds up to 80. As you enter more than 24 characters, the display scrolls off screen to the left to provide space for the new input. You can recall all characters, however, whenever needed. And when you're using angle and operational modes (Deg, Rad, Grad, Run, Pro, Reserve and Def), they are flagged by

Calculators handicap horse races

Statistical analysis is traditionally boring, even if you're using a powerful statistical machine such as the Casio FX-702P. But four other statistical programmable calculators on the market guarantee to keep you wide awakethey're all programmed to handicap thoroughbred horseracing. The four are Mattel's \$125 Horse Race Analyzer, APF's \$100 Kel-Co Horse Racing Computer and Leisure Time Development's \$50 Starshine Race Track Computers II and III (the latter for international handicapping).

If you're a programmable-calculator buff, you'll be very enthusiastic about Mattel's sophisticated machine. It's the Hewlett-Packard HP-41-equivalent in its class, providing 20 data-input keys and requiring 31 entries for each horse in a race. As you input each factor, the calculator's elaborate LCD prompts you to enter the next one in sequence. To obtain a sufficient statistical base, Mattel advises using it only for races in which at least 60% of the 3-yr-old (or older) horses have at least five races in their past performances listed in the handicapper's equivalent of EDN, the Daily Racing Form.

Statistics called for on the Mattel Analyzer for each horse include purse, race, distance, post position, days since last race, races run since a 30-day (or more) rest, current and previous years'

small segmented LCD characters at the top of the main matrix display.

Other new hand-held computers have similar display characteristics. Casio's FX-702P Programmable Calculator displays as many as 20 alphanumeric characters, while the HHC (Hand Held Computer) from both Panasonic and Quasar shows a maximum of 26. (The HHC is marketed by both companies under their own brand names.)

Keyboard configurations in the new machines show more variety than the displays. The alphanumeric keyboards of the Radio Shack/Quasar units are laid out in typewriter-keyboard format, for example. No doubt the original idea was to pattern these keyboards after those of desktop computers, but the space allocated is

> performances (number of races, wins, places, shows and earnings), data on performance in the last three races and the two best speed ratings. Once you enter all this information, you press NEXT and repeat the process until you've completed it for all horses in a race. Then you press ANA-LYZE, and the display shows five numbers: the first two are post positions; the last three, rating numbers for the top horse. You record these numbers and repeat the procedure three more times until you've collected the five numbers for the second-, third- and fourth-rated horses.

> At this point you're on your own. If the computer ratings for the top four horses are widely separated,





A sophisticated programmable machine requiring 31 inputs for each horse in a race, the Mattel Horse Race Analyzer includes an elaborate LCD that prompts the handicapper with the name of his next required entry.

The simplest handicapping computer, from Leisure Time Development, requires only four entries to provide a rating.
so compressed that you can't use them with both hands like a desk machine. It's also confusing to pick out an alphabetic sequence in a word when you "hunt and peck." And unfortunately, BASIC requires considerable amounts of word entry. Casio, on the other hand, lays its keyboard out in a 5-row A-to-Z sequence, making it easier to pick out individual letters.

Peripherals add capability

All of the newer machines provide optional peripherals. The Radio Shack and Sharp Pocket Computers, for example, furnish a $150 \ 11 \times 3.5$ -in. printer/cassette interface in which the calculators mount. The interface serves two functions: to provide an on-board printer and to allow the machine to interface with a cassette recorder for data storage and retrieval.

The printer produces as many as 16 columns per line on small standard paper rolls. The special set of adapter cables supplied with the interface connects it to the recorder. Radio Shack recommends its CTR-80A recorder for automatic program control and transfer of information because other units might not interface properly with the cables.

Casio's \$200 FX-702P also allows you to store and retrieve programs on tape and provide printer output. For those functions, you need the optional \$50 FA-2 adapter and the \$90 FP-10 miniprinter (available next month). The FA-2 is not compatible with the firm's FA-1 adapter, which is used interchangeably with the older -502P and the new lower cost -602P.

the selection seems obvious, but when they're close together, you must input other factors (discussed in Mattel's instruction book) in the *Daily Racing Form.*

Mattel claims that in a sample of 500 races, the computer's toprated horse finished first, second or third some 57% of the time. However, a limitation of the product is the time required to make all entries: For a 10-horse race, you must enter 310 inputs.

To speed up selection, try a calculator such as APF's Horse Racing Computer. The programming in this machine is adopted from a slide rule (the Kel-Co Class Calculator) first marketed in 1969. Running on a custom version of a Texas Instruments TMS 1100 µP, the APF machine's program is based on the "principle of established class ratings" for thoroughbred racehorses. It assumes that a thoroughbred class is best measured by the size of the purses for which a horse has successfully competed in the recent past. The calculator determines a horse's class rating as a function of the track on which the horse is running and its finish positions and earnings (taken from past-performance charts in the Racing Form).

The unit has four track keys $(T_{c1}-T_{c4})$ and four finish-position keys (1st, 2nd, 3rd, 4th). Only 12 or 13 entries are required for each horse to obtain an E/R (earnings rating). Specifically, a horse en-



Requiring six data inputs for each horse in a race, this APF Electronics machine computes established class ratings—a statistically proven handicapping method.

tered in a race with a lower purse value than called for by its established class rating is a strong potential bet. On the other hand, a horse with a lower class rating than the purse size would indicate it is seldom a serious contender.

The simplest handicapping calculator, the Race Track II, picks winners by calculating a horse's median average. Specifically, it requires that you input (from the *Daily Racing Form*) two median ratings from the results of the horse's last three races: the speed rating and the horse's position at the finish. Then you need only two more inputs: the jockey's weight and the specific speed rating of the horse's last race. Only four data-entry keys are required: MSR (median speed rating), RC (race weight carried in today's race); LSR (speed rating for the last race run) and PAF (median position at finish). Pressing an RSMR key then gives the horse's rating, which you can compare with those of others in the race.

This 5-step procedure is fast and simple, and according to a testing-laboratory report, one of the three highest rated horses (in a 100-race sample) finished first 55% of the time, or first, second or third 95% of the time. The highest rated horse finished first only 20% of the time.

How do the pros view these computers? Says Tom Flanagan, author of Beat the Races (Arco Publishing): "Studying the [Daily Racing Form] ... gives the opportunity to apply [your] mind to something really worthwhile, because predicting the winner of a horse race is an intellectual inquiry of amazing depth and difficulty. Nowadays the PhDs and the mathematicians, armed with computers, are studying the racing game, but they'll find out that it isn't as easy as making an atom bomb."

Some units furnish extensive peripheral support

When it comes to peripherals, though, Panasonic's RL-H1000 HHC represents the most ambitious systemdevelopment program. Originally announced more than a year ago, it is now scheduled for delivery near the end of this year.

Panasonic has embarked on an extensive program of providing support peripherals, the basic philosophy behind the RL-H1000 being to provide a portable business computer with the power of a desktop system. And although packaged in an attache case, the RL-H1000 is not intended to be a low-cost system: The HHC machine itself costs about \$600, but when it's configured with a full set of peripherals its price jumps to about \$2500.

Even though the H1000's architecture is oriented primarily toward business users, the machine can be adapted for scientific or engineering applications with plug-in software modules. These 24-pin ICs plug into the H1000 main unit (it holds three) and add such specialized features as BASIC and/or scientific/engineering number crunching. Panasonic plans to offer approximately 12 of these specialized-application capsules within several months.

As you might have guessed, the H1000's generic operating system is not written in BASIC. Rather, it uses a language named SNAP, a derivative of FORTH. (A detailed description of the language and machine architecture appears in *Byte* magazine, January 1981). The firm chose SNAP because the language achieves a 2:1 data-compression advantage over assembly language; thus, it's fast running. Another factor in the language's favor: It permits the machine to mate easily with a wide variety of peripherals. Panasonic proposes to offer

• An acoustic telephone modem for full- or halfduplex communication via public telephone lines, spec'd at 110 or 300 bps and using asynchronous bit streams. Data is five to eight bits wide (selectable) and available with or without a parity

A software club for pocket computers

Publications of independent calculator-software clubs such as the PPC Club in Santa Ana, CA (for years publisher of a monthly PPC Calculator Journal devoted to Hewlett-Packard machines) and the TI Programmable Calculator Club (regular producer of TI PPC Notes), are now joined by the Pocket Computer Newsletter (Seymour, CT). Appearing 10 times a year, this newsletter chronicles developments and provides program listings and commentary from subscribers. Although previous issues have given extensive coverage to the Radio Shack/Sharp Pocket Computers, the publication will also be passing on tips on the Panasonic/ Quasar HHCs and Casio FX-702P.

All the publications contain a prodigious amount of valuable information. Members of the PPC Club and the TI Programmable Calculator Club, for example, have produced and exchanged valuable software not available from the calculator manufacturers.

Richard Nelson, founder of the PPC Club, reports that syntheticprogramming efforts by members with HP-41C/CVs continues to expand machine capabilities. With synthetic programming you discover surprising new features that the designers of the original machine never dreamed of.

For example, one HP-club member has discovered that he can produce 83 display characters rather than the 59 alphanumeric characters and symbols described in the owner's manual. And another member, astrophysicist William C Wickes, has produced a superb example of synthetic programming. When the -41C is digesting a problem, it lets its user know it's alive by propelling a cartoon "goose" from left to right across its display. Wickes has not only gotten a goose to face backwards, but also fly backwards, shed droppings, flap its wings, stream by in flocks of as many as nine and even collide head on with its factory-hatched predecessor. (Wickes is now an HP employee.)

Other pending software-club developments include 4k and 8k EPROMs that will complement the HP-41C/CV's 64k-ROM addressing capability. And another project, initiated in August 1979 and now about to reach fruition, is the development of a programmer's ROM that contains 153 short, efficient routines that you can call up in writing programs. Some 5000 of these ROMs, produced in collaboration with HP, have just become available to the members. The user's manual documenting the routines is 500 pgs long. For more information, contact Nelson.

Maurice Swinnen, who runs the TI Programmable Calculator Club, reports that members have discovered a Fast mode for the TI 59. In this mode, program execution occurs without calling the program into the display register. Bypassing this C register increases speed by a factor of two. However, the price you pay is that everything must be directly addressed; you can't use labels.

Another new discovery submitted to the TI club from an overseas member is an expanded Graphics mode that allows you to address all of the individual dots of the thermal-printer dot matrices. Use of this graphic programming provides control of some 300 character and symbol variations. For information, contact Swinnen. check. The 5V power required comes from the HHC mainframe.

- A programmable CMOS memory protected by an internal battery backup. It has a standard capacity of 4k bytes and is expandable to 8k.
- A capsule-extender interface that allows you to connect four ROM capsules in addition to those already in the HHC. Each capsule can provide as many as 128k bits.
- A 5×8 dot-matrix thermal microprinter with a 16-character column width.
- An RS-232C serial interface using 5- to 8-bit asynchronous data and ASCII. Data-transfer rates are standard, ranging from 110 to 9600 bps.
- An I/O-driver unit that allows you to connect as many as six peripheral units through a 44-pin edge connector in the HHC main unit. (You can connect only one without the I/O adapter.)
- A cassette adapter that allows you to attach two recorders spec'ing transfer rates of 1200 bps.
- A TV adapter, termed a video RAM, that interfaces with a color TV—either indirectly through an RF terminal or directly to the video signal. With it you can display 16 lines of 32 alphanumeric characters using a 5×7-dot matrix. Other graphic display modes are also available.

Despite the HHC's extensive capabilities, though, its intrinsic calculating capability comes from a simple 4-function calculator with only percent and memory features. But for mathematical applications, an 8k capsule that converts the machine to Microsoft-BASIC operation will be available. It will provide all the trigonometric and scientific functions that BASIC offers. (The Microsoft BASIC in the HHC is a full BASIC language equal in power to that of the Apple II, Panasonic says.)

Back to BASICs

Simpler in scope than that of the Panasonic machine, the Radio Shack and Sharp Pocket Computers' BASIC capitalizes on the machines' use of an on-board calculator chip as well as a processing chip. With these chips, the machines can provide trigonometric functions and their inverses; natural and common logs; natural antilogs; square roots; decimal-to-degree/ minute/second conversion (and its inverse); and integer, signum and absolute-value functions—all keyboard accessible in BASIC.

Interestingly, the Integer function in these machines converts a displayed positive nonintegral value to the next lowest integer, which is what you'd expect. However, for negative numbers you'll be surprised to find that unlike the case with most other standard personal scientific calculators, taking the integer function of -2.45 produces -3 rather than -2. In the same vein, you can raise a number to a power with simple BASIC commands, but you can't take the yth root of x without using a special subroutine. Close examination shows that Radio Shack and Sharp have sacrificed several other functions included on most powerful EDN SERTEMBER 16, 1081





A full-alphanumeric dot-matrix display capability is designed into the Casio FX-602P (a). Both upper- and lower-case characters are available in its set of 86 keyboard-accessible letters, numbers and symbols (b), which get displayed 11 characters at a time.



An ambitious effort to produce an extensive system of peripherals and a capable hand-held computer, Panasonic's RL-H1000 is aimed at business use.

Is BASIC best for extensive calculations?

scientific machines in favor of the convenience of BASIC (see **box**, 'Who needs BASIC?').

Swap program steps for data storage

An interesting feature of the Radio Shack/Sharp Pocket Computers is a variable program memory of 1424 steps max and a fixed data memory of 26 registers (A to Z). A 16-stage function stack and an 8-stage data stack, both transparent to the user, temporarily store instructions and data for processing. However, you can call upon unused program memory to store data; hence, the memory is designated "flexible."

These machines also provide a very useful feature in their ability to tell, at any time and in any operating mode, exactly how many program steps and registers are available for data storage. When you key in a MEM command and then press the Enter key, XXXX STEPS YYY MEMORIES appears in the display. (However, the readout does not include the 26 data registers (seven characters per register) that store sequences of characters, including letters, blanks, numbers and special symbols. This MEM ENTER command works in all four of the machines' operational modes: Pro (program), Run, Def (definable) and Reserve. Pro and Run are typical operational modes used for writing and running programs. Def and Reserve, on the other hand, exhibit powerful new features. One is the ability to assign just one key for a function or for an entire program that you use frequently.

Eighteen keys (A, S, D, F, G, H, J, K, L, =, Z, X, C, V, B, N, M, SPC) can be reserved for a particular function (or program), and once reserved, they are available for both manual calculations and programs. Forty-eight program steps are allocated for the reservable keys, and if the contents of the key allocations exceed 49 steps, the machine signals an error. You can readily check the assigned keys by reviewing them in Reserve mode. You can also assign programs to any of the 18 keys in Pro mode and execute them in Def mode.

The Panasonic/Quasar machines' programmable-key capability is less extensive than that of the Radio Shack/Sharp calculators. The HHC machines are limited to three special assignment keys (f1, f2 and f3) that you can allocate to any sequence of keystrokes, including most function keys. Pressing one of these keys produces the sequence of operations assigned to it. The keys find use in SNAP and BASIC programs.

Debugging made easy

The Radio Shack/Sharp machines use a DEBUG command in Run mode and a LIST command in Pro mode, along with the Step Forward (\downarrow) and Step Backward (\uparrow) keys, for program debugging and

FEATURES	RADIO SHACK/SHARP POCKET COMPUTERS	CASIO FX-702P
COMMANDS/STATEMENTS	RUN, NEW, MEM, LIST, CONT, CLEAR, INPUT, PRINT, PAUSE, USING, LET, STOP, REM, BEEP, FOR, TO, STEP, NEXT, GOTO, GOSUB, RETURN, IF, THEN, AHEAD	RUN, VAC, LIST, DEFM, INP, PRT, WAIT, FOR, TO, STEP, NEXT, IF, THEN, GOTO, GSB, RET, SET, STOP, END, PASS, LIST V, LIST ALL, CLR, CLR ALL, DEL, LEN, MID
CASSETTE CONTROL	CSAVE, CLOAD, CLOAD?, PRINT#, INPUT#, CHAIN	SAVE, SAVE ALL, LOAD, LOAD ALL, PUT, GET, VER
OPERATIONS	$\begin{array}{l} +,-,^{\star},l,(\),>,<,>=,\\ <>=,=\end{array}$	+ , - , *, /, (), <, >, ≤, ≥, ≠, =
FUNCTIONS	SIN, COS, TAN, ASN, ACS, ATN, EXP, LN, LOG, INT, ABS, $$, DEG, DMS, SGN, DEGREE, RADIAN, GRAD, π , $^, \%$	SIN, COS, TAN, ASN, ACS, ATN, HSN, HCS, HTN, AHS, AHC, AHT, EXP, LN, LOG INT, FRAC, ABS, SQR, RND(, DEG(, DMS, SGN RPC, PRC, RAN# [DEGREE, RADIAN, GRAD]*, π , (\times)!, \uparrow (STATISTICS): MX, MY, SDX, SDY, SDXN, SDYN, LRA, LRB, COR, EOX, EOY, CNT, SX, SY, SX ² , SY ² , SYX.
VARIABLES	A~Z, A (), A\$~Z\$, A\$ ()	A~Z, A (), A\$~Z\$, A\$ ()
OTHER	,;:"?#!	,;:"?#!



The printer cradle for the TRS-80 Pocket Computer also serves as an interface to a cassette recorder that preserves programs on tape or loads them into the machine.

Full keyboard labeling of BASIC statements and math functions along with single-key entry of both make this Casio FX-702P programmable calculator easy to use.

editing. The DEBUG function executes a program one line at a time, verifying not only the calculation, but also the instructions for it. LIST calls up the program, beginning with the first step, and you then step through it using the Step Forward key. Alternatively, you can call out a particular line number and go

Who needs BASIC?

Like the controversy that raged a few years ago debating the merits of reverse Polish notation vs algebraic notation, a new one questions whether BASIC is an effective language for scientifical and mathematical programming. The results of the debate aren't yet in.

BASIC is oriented toward data and information processing, and it uses a conversational language for its inputs. On the other hand, the calculator user who is programming extended numerical computations wants to concentrate on the intricacies of the solution; that is, he wants action, not words. Additionally, BASIC reduces the amount of memory space available for data storage and manipulation because a large amount of the machine memory gets used up in handling the language-compiler chores. For example, one designer tried a filter program on his Radio Shack TRS-80. He found that there was insufficient memory for that program in the TRS-80, but he was able to fit it into a TI 59 in about half that machine's memory space.

BASIC is, nevertheless, an easy-to-use language and has some advantages. And in minimizing the workload of inputting BASIC, Casio's FX-702P is superior to the other BASIC machines because Casio designers have merged the codes not only for the scientific and math functions, but also for BASIC statements. Thus, one key entry gives you both the math function and the BASIC statement. In fact, the resulting operation is very close to that of a standard scientific programmable calculator.



backward or forward from there. By the same token, you can readily list programs via the printer.

To edit and merge programs stored on magnetic tape, you merely transfer them into the Pocket Computer, perform the necessary operations and then transfer them back onto the tape. Radio Shack plans to expand its current software library of tape-cassette programs over the next few months.

Casio packs the most math power

The most powerful math capability of the currently available horizontally stretched hand computing machines resides in Casio's FX-702P. Although programmed in BASIC, this machine offers several functions not usually found in that language. Indeed, it has all of the functions of the Radio Shack/Sharp Pocket Computers and several others besides (table). For example, you get hyperbolic and inverse hyperbolic functions, fractionalization (FRAC-removal of the integer part of a number), coordinate conversions from rectangular to polar and vice versa, a round-off feature (ROUND), a random-number generator (RAN#) and X factorial (X!). In addition, the -702P has 17 preprogrammed functions for statistical analysis, nine of which are single-key accessible, with the other eight requiring 2- or 3-letter inputs.

The -702P also features an excellent man-machine interface. For example, the surface of its keyboard's alpha section is loaded with information that guides you when you enter either math functions or BASICcommand statements.

This information appears in the form of three types of key inscriptions associated with 28 of the 35 alphasection keys. The first is the letter, punctuation mark or BASIC symbol that's on the face of the key itself. The second is the BASIC mnemonic for the math functions, printed in red just above the keys. The third is a BASIC command printed in blue, just below the keys. You gain access to the red functions (SIN, COS, TAN, etc) by first pressing a red F1 shift key, and you call up the blue statements (FOR, TO, STEP, GOTO, etc) via a blue F2 shift key.

Swap space between program and data storage as needed

You can enter BASIC functions and statements either the hard way—by spelling them out on the keyboard or the easy way—by using the red or blue shift keys and then pressing the key at which the red or blue function or statement is located. The latter approach is not only easier, but with all of the BASIC information spelled out in front of you, it helps shorten the learning period each time you press a key and reinforces the lesson each time you use the machine. You learn fast!

The FX-702P sports a program capacity of 1680 steps

and 26 A to Z data registers. However, in a manner similar to that used in the Radio Shack/Sharp machines, you can convert program steps to data registers in groups of 10 registers, with each register taking eight program steps. Therefore, if the number of data registers is increaseed to a maximum of 226, the program steps decrease to a minimum of 80.

A DEFM (blue) command expands the data-memory bank, but should an insufficient number of program steps be available for the call, an error message appears to protect programs already written. Backup power for all registers and program memories prevents loss of data and program information.

Casio has carried over the efficient program-control architecture of the older FX-502P (EDN, June 20,

Battery life up, battery life down

In the days of LED-display calculators, an annoying problem was the constant care required by rechargeable NiCd batteries. Then along came CMOS and LCDs, and battery drain dived to permit an unheard-of but very welcome 1000 hrs or more of continuous use with silver-oxide button cells. As a result, you could forget the battery for a year.

But the battery tide is shifting again: Battery life has decreased in the new hand-held computing machines. The Radio Shack/ Sharp Pocket Computers, for example, use a 5.4V source of four Type 674 mercury cells and achieve an estimated operating life of 300 hrs. Casio's FX-702P employs two CR2302 3V lithium cells, providing an expected life of 200 hrs. And Casio's FX-602P, successor to the 1000-hr FX-502P, uses the same two CR2302 cells but achieves an expected life of 500 hrs with the FA-1 adapter.

The Panasonic and Quasar HHC main units, meanwhile, supply power to most of their peripherals and as a result require five NiCd rechargeable cells. Additionally, the thermal printers for the calculators discussed in this article also use rechargeable NiCd batteries because of their relatively high drain.

The silver-oxide cells' high cost has created an expanding interest in designing new calculators and



The rising cost of silver is pressuring calculator designers to substitute mercury, manganese-dioxide or lithium cells for a wide variety of these silver cells from Union Carbide Corp.

other electronic devices around manganese-dioxide cells, according to Gilbert Merritt Jr, manager of battery engineering at Union Carbide. Alternatively, some calculator manufacturers approve the substitution of these alkaline manganese cells for the silveroxide units in their machines. For example, Sharp calls for either three LR44 manganese-dioxide cells or three G13 silver-oxide cells in the EL-5103. (However, note that the LR44s provide only about 450 working hours, compared with 1400 for the G13 cells.)

Considering the high price of silver-cell, replacement (on the order of \$3.25 to \$3.50), owners of other calculators might also be tempted to replace them with the manganese cells instead. But Merritt warns of possible problems if your calculator also has a clock circuit. Specifically, although most calculator circuits operate down to 1V or less, such clock circuits have a higher cutoff voltage. Additionally, although silver cells maintain a relatively constant voltage throughout their life, the voltage across manganese cells drops off gradually. Thus, with a manganese cell, the clock circuits stop working before the calculator quits. As a result, Merritt suggests staying with the silver cells if you own a clock/calculator; they're more cost effective anyway.

1979, pg 97) into the -702P. For instance, you can assign 10 program keys (P0 to P9) as labels for as many as 10 programs or subroutines. Additionally, you get transparent stacks for 10 levels of subroutines, eight levels of FOR-NEXT loops, 10 levels of temporary storage for numerical values and 20 for calculation elements.

Program checking and editing occur through LIST and TRACE commands, as well as with a special DEBUG command that specifies the type of error in a specific line of the program. To check and edit programs in Run mode, a LIST command automatically steps through the program, dwelling about 2 sec on each line in sequence. In Wrt mode, a LIST command allows you to step through the program one line at a time using the Exe key.

Unfortunately, the machine has no Backstep key. To accomplish this function, you must clear the line from the display and reinsert a LIST command with the desired line number.

The -702P also provides a useful feature that shows you which of the 10 program areas contains information and which are available for programs. For example, assuming that P1, P3 and P7 store programs but the remaining areas are free, if you initiate the Wrt mode, the readout displays READY P0: 0.2_456_89. Additionally, the number of program steps available appears in a small 4-digit display at the far right of the screen. As programming proceeds, the number displayed decreases with each step used, thus providing a constant check on space available for program or data allocation.

As an added feature, the -702P accepts preprogrammed ROM cartridges to extend its programming capabilities. The firm expects to offer 10 such cartridges by the first of next year. The FX-702P lets you protect your programs by providing the ability to assign passwords or code names to them. When you don't want others to know a program's contents, or if you don't want anyone else to change a program, you assign to it a scrambled code word of as many as eight letters, numbers or symbols. These passwords are effective for each program and are attached only to P0-P9 programs.

You would use the following format to attach a password, enclosing the password in quotes:

PASS	"#\$"	EXE
PASS	"GLUBZ"	EXE
PASS	"AZ-1"	EXE

You can clear the password by clearing the entire program or by reinputting it. When checking a program, if you input a password following LIST, it is temporarily canceled for that LIST command.

Older calculators are improved

Overshadowed by the interest in the new BASIC hand-held machines are two other new scientific alphanumeric programmables that use machine language: Casio's FX-602P and Sharp's EL-5103, both updated versions of earlier machines.

The -602P includes upper- and lower-case letters in its 86-character/symbol dot-matrix display repertoire. But because it's packaged in a more conventional vertical design, it can display only 11 characters at a time. However, all input commands are written on the display, simplifying program checking, correction, addition or deletion. The -602P, an improved version of the well-known -502P, plugs into the same FA-1 cassette adapter; thus, you can load -502P programs into the -602P from cassette tape. Although the

Calculator manufacturers and additional sources of programmable-machine information

For more information on personal scientific calculators and related products and activities, contact the following manufacturers or software clubs directly or circle the appropriate numbers on the Information Retrieval Service card.

APF Electronics Inc 1501 Broadway New York, NY 10036 (212) 869-1960 Circle No 655

Canon Inc 10 Nevada Dr Lake Success, NY 11040 (516) 488-6700 Circle No 656

Casio Inc 15 Gardner Rd Fairfield, NJ 07006 (201) 575-7400 Circle No 657

Hewlett-Packard Co 1000 NE Circle Blvd Corvallis, OR 93770 (503) 757-2000 Circle No 658 Leisure Time Development Corp 1931 Mott Ave Far Rockaway, NY 11691 (212) 327-1119 Circle No 659

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Protect programs with special passwords

converse isn't true, the lack isn't very important.

The FX-502P's keyboard is relatively unchanged in the -602P, except that Casio has added to the keyboard-face markings new letters and symbols that you can call into the display via the keys. You gain access to these new characters by putting the machine in Alpha mode, one of three new ones. (A second new mode partitions the data registers, and the third verifies partitioning upon demand.)

You can transfer programs and data from the calculator through the FA-1 adapter and reload them using microcassette, standard cassette and open-reel recorders. And for the -502P music-lover owner who programs tunes on tape, the -602P extends the repertoire from 20 to 80 notes over three octaves.

The FX-602P doubles the size of the -502P's program memory to 512 steps. All of these steps can divide into 10 programs or subroutines by means of the P0 to P9 keys. Because of its highly merged codes, the -602P minimizes effective step numbers; thus, one step generally corresponds to one function. As a result, you can easily manage 3-dimensional equations, parenthetically nested numbers and other complex formulas.

As in the -702P, the -602P's 22 data registers can be increased to a maximum of 88 by transferring unused program steps to them. And with an algebraic hierarchy similar to that of TI's Algebraic Operation System, you can nest 33 levels of parentheses in the -602P.

The FX-602P also provides the capability of designating special-function keys. You can assign the P0 to P9 keys as labels for 10 programs and digits 0 to 9 as labels for unconditional jump (GOTO) destinations. As many as nine subroutines can be called in a main program using the GSB key followed by a P1 to P9 key.

Conditional jumps for X=0 and $X\ge 0$ judge the display-register contents; X=F and $X\ge F$ compare the contents of the X and MF registers. Two other conditional jumps (IDZ and DSZ) control repeated operations running in a loop. Indirect addressing designates a jump designation.

The -602P has the same password feature as the -702P. And its calculating speed is higher than the -502P's. For example, decomposing the prime number 379721 into other primes requires 37 sec, compared with 1 min, 15 sec on the -502P.

The other new machine-language-programmable calculator, Sharp's EL-5103, furnishes a 13-character scrolling alphanumeric display. It's a lower priced repackaged version of the EL-5100, which, as noted, set the format for today's generation of pocket computers. The number of steps storable in the display register equals 80 for both machines, but data memories are reduced from 10 in the -5100 to six in the -5103. You can input expressions with as many as 15 levels of parentheses and eight levels of pending operations in



A vertically styled wallet-type version of its manufacturer's *EL*-5100, Sharp's *EL*-5103 has a scrolling display of 13 characters. The display buffer can hold 80 characters, however.

the -5103.

Sharp has managed to package all 61 of the -5100's scientific and math functions into the -5103's more conventional vertically oriented 2.75×5 -in. form factor. Power drain is reduced: You get an estimated 1400 hrs of continuous use from three silver cells, compared with 1000 hrs on the older machine.

Article Interest Quotient (Circle One) High 479 Medium 480 Low 481

NEXT TIME

EDN's September 30 issue will feature a Special Report on gate-array ICs, plus articles on a variety of additional topics:

- Optimizing flash A/D-converter operation through the use of track/hold amplifiers
- The theory and application of tonedecoder ICs
- The use of memory segmentation in Intel's iAPX 432 32-bit μP

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Add the FFT to your box of design tools

Implementing the fast Fourier transform and its inverse on your personal µC can increase your productivity.

Robert H Cushman, Special Features Editor

The three previous articles in this series have focused on how LSI and VLSI devices are allowing-even forcing-OEM design engineers to make greater use of number-crunching techniques. We've pointed out that number-crunching functions such as simulation, signal processing and numerical analysis will become commonplace in all aspects of designers' professional lives: They will be part of design analysis and laboratory testing and will be embodied in all sorts of products, from space-ship guidance computers to children's talking toys. Here, we wind up our miniseries on digital processing by expanding on the subject of the last article (Ref 1): the fast Fourier transform (FFT) and its inverse (IFT).

These tools, implemented as algorithms on your personal computer, allow you 'to switch between the time and frequency domains with minimal effort. They are particularly suited to personal-computer use because, unlike the concepts in other areas of digital processing, they apply primarily to one design task. Once you have this task computerized as part of your disk- or cassette-based library of design-aid programs (Fig 1), you'll be able to use it throughout your OEM design work.

Two FFT listings start you off

The program listings for FFTs and IFTs shown in Figs 2 and 4 are only two of the many available. We have been running them for familiarization and thus know that they work. Note that each uses different symbols; we have retained the authors' notation because we didn't want to risk introducing errors.

These programs, which come from Refs 2 and 3, consist of FFT and IFT subroutines callable from a main program. In Fig 2, the subroutine runs from line 500 to 1060; in Fig 4, from line 3000 to 3228. The remainder of each program consists of short main programs that prepare for the use of the subroutines. They take care of such tasks as dimensioning the arrays to hold the data and defining the main parameters. We have written these main programs so they interactively EDN SEPTEMBER 16, 1981



Fig 1-Personal µCs for an engineer's use in design analysis need not be expensive. The author's system costs approximately \$1000. It consists of a Rockwell Aim-65 µC with 4k RAM (\$600), an Epson MX-80 printer (\$400) and an audio cassette recorder (\$50). It can run the FFT/IFT programs shown in Figs 2 and 4 with as many as 128 points in about 50 sec.

ask you for the necessary parameters and give you a painless way of learning about FFTs and IFTs.

Note that in each case the same subroutine serves for both the FFT (time domain to frequency domain) and the IFT (frequency domain to time domain). The only difference is a sign bit, which you set up by your choice of FFT or IFT at lines 11, 12 and 13 in Fig 2 or lines 102, 103, 104 and 105 in Fig 4.

Both of the programs are written in Microsoft BASIC (to run on our Aim-65 μ C). If your μ C uses a BASIC other than the Microsoft version, you might have to make minor modifications in notation, but they shouldn't prove difficult. Some of the textbooks on BASIC for µPs provide guidelines for such conversions. For background on the programs themselves, see **Refs** 2 and 3; Ref 3, especially, gives a detailed explanation of FFT mechanics.

The programs occupy approximately 1700 bytes of RAM; each array element requires an additional five

Two BASIC-programmed FFT/IFT algorithms provide experience

bytes. These requirements limit us to 128-point transforms in our Aim-65, which has just 4k of RAM. It takes us approximately 50 sec to execute a 128-point FFT or IFT—far faster than the 1 hr a 128-point transform would take with the discrete-Fourier-transform (DFT) algorithm.

Today's typical personal μ C has 8k or 16k of RAM and therefore should be able to execute FFTs and IFTs as large as most engineers would want—to 512 or 1024 points. These larger transforms should take approximately 5 or 10 min, respectively. (Actually, even for our shorter FFTs and IFTs, we have found that the chore of entering the input data and the long wait for results printout become annoying when we attempt transforms with more than 32 points. For larger transforms, we assume that most engineers would want to incorporate automatic data acquisition and display the results graphically on a CRT. However, the programs as presented are adequate for their primary purpose—providing a vehicle for your initial selfeducation in FFTs and IFTs.) Figs 3 and 5 show demonstration runs of the two programs. These runs repeat the short 8-point FFT example from **Ref 2**, obtaining essentially the same answer (except for the imaginary sign). You can use them as a check.

If you've never used the FFT/IFT, we suggest several exercises using the **Fig 2** or **Fig 4** programs (**Fig 6**). For each exercise, we advise performing both the FFT and the IFT on the waveforms and spectra so that you can see to what degree you can go back and forth between domains.

First, perform an FFT on an elementary dc "wave" and observe that a dc level in the time domain produces only an amplitude at N=0 in the frequency domain. Then, using the IFT, try positive and negative and zero levels for both the real and imaginary values of the dc or N=0 frequency, leaving all other points zero.

Second, try the same operations on pure sine waves. You'll find that the easiest way to obtain a time-domain sine wave is to enter the spectral-line magnitude in the frequency domain and then use the IFT to plot the time-domain wave shape. Shift the time wave in phase and use the FFT to see what happens to the spectrum; observe the changes in the magnitudes of the real and imaginary components, indicating that the resultant vector is rotating in phase.

4 PRINT" <<7161X>>" 8 FRINT"****************** 9 INPUT"DATE"; DA\$ 10 INPUT"HR":HR\$ 11 INPUT"FWD-OR-INV"; AN\$ 12 IF AN\$="F" THEN D=0 13 IF AN\$="I" THEN D=1 20 INPUT"M=";M 30 N=2^M 31 PRINT"N=" N 32 DIM X (N. 2) 35 IF D=0 THEN PRINT"INPUT TIME DOMAIN DATA" 36 IF D=1 THEN PRINT"INPUT FREQ DOMAIN DATA" 40 FOR I=1 TO N 41 PRINT" 44 PRINT"INPUT X("I;",0) X("I;",1)" 45 INPUT X(I.O), X(I.1) 50 NEXT I 55 IF D=0 THEN PRINT"TIME DOMAIN INPUT DATA ARRAY IS:" 56 IF D=1 THEN PRINT"FRED DOMAIN INPUT DATA ARRAY IS:" IMAG" 57 PRINT"POINT REAL 60 FOR I=1 TO N 70 PRINT I:" ":X(I.O):" ":X(I,1) 80 NEXT I 110 GOSUB 500 112 IFD=0 THEN PRINT NOW IN FREQ DOMAIN!" 113 IF D=1 THEN PRINT"NOW IN TIME DOMAIN!" 114 PRINT"XFRMD DATA IS:" 115 PRINT"POINT REAL IMAG" 120 FOR I=1 TO N 130 PRINT I;" ";X(I,0);" ";X(I,1) 140 NEXT I 145 PRINT" -DONE-" 150 END 500 REM*************** 501 REM FFT/IFT SUBROUTINE 502 REM*************** 550 N=2^M 560 REM***DO BIT SHUFFLE*** 570 N2=N/2 580 N1=N-1 590 J=1 600 FOR I=1 TO N1 610 IF I>=J THEN 680

640 T2=X(J.1) 650 X(J.O)=X(I.O) 655 X(J,1)=X(I,1) 660 X(I,0)=T1 670 X(I.1)=T2 680 K=N2 690 IF K>=J THEN 730 700 J=J-K 710 K=K/2 720 GOTO 690 730 J=J+K 740 NEXT I 750 REM***END OF SHUFFLE*** 760 51=-1. 770 IF D=0 THEN 790 780 51=1 790 P1=3.1415926535898 800 FOR L=1 TO M 810 L1=2^L 820 L2=L1/2 830 111=1 840 U2=0 850 W1=COS(P1/L2) 860 W2=S1*SIN(P1/L2) 870 FOR J=1 TO L2 880 FOR I=J TO N STEP L1 890 I1=I+1 2 895 REM***DO BUTTERFLY*** 900 V1=(X(I1,0)*U1-X(I1,1)*U2) 910 V2=(X(I1,1)*U1+X(I1,0)*U2) 920 X(I1,0)=X(I,0)-V1 930 X(I1.1)=X(I.1)-V2 940 X(I,0)=X(I,0)+V1 950 X(I,1)=X(I,1)+V2 960 NEXT I 970 REM***DO TWIDL FACTOR*** 975 U3=U1 976 U4=U2 980 U1=(U3*W1-U4*W2) 990 U2=(U4*W1+U3*W2) 1000 NEXT J 1010 NEXT L 1020 IF D=1 THEN 1060 1030 FOR I=1 TO N 1040 X(I,0)=X(I,0)/N 1045 X(I,1)=X(I,1)/N 1050 NEXT I 1060 RETURN

630 T1=X(J.O)

Fig 2-This FFT/IFT program, from Ref 2, was created for use in instrumentation evaluations.

1 PRINT" -6261A"	
2 POKE4,113:POKE5,232:X=USR(X)	INPUT X
3 LIST	7 1
4 PRINT" <<7161X>>"	?? 0
5 PRINT"************	
6 PRINT" FFT/IFT"	INPUT X
PRINT" AFTER WAGGENER"	7 1 77 0
<<7161X>>	INPUT X
*****	23
FFT/IFT	22 0
AFTER WAGGENER	
*****	INPUT X
DATE? 7/25/81	? 2
HR? 10.17 A	77 0
FWD-OR-INV? F	
M=7 3	INPUT X
N= 8	7 1
INPUT TIME DOMAIN DATA	22.0
INPUT X(1 ,0) X(1 ,1)	INPUT X
7 1	? 2
?? 0	77 0
2 2	
22.0	

(3,0) X(3,1) (4,0) X(4,1) (5,0) X(5,1) (6,0) X(6,1) (7,0) X(7,1) (8,0) X(8,1)

TIME DOMAIN INPUT DATA ARRAY IS: POINT REAL IMAG Ō 1 2 1 2 0 1 3 Ō 4 5 6 7 1 3 Ō 0 2 0 1 Ō 2 8 0 1111111111111111111 NOW IN FREQ DOMAIN! NOW IN FREQ DOMAIN! XFRMD DATA IS: POINT REAL IMAG 1 1.625 0 2 -.161611652 3 .25 -.12 4 -.338388347 .0883883476 5 -.125 0 6 -.338388348 -.0883883476 7 .25 .125 8 -.161611653 125 -.0883883476 _____ -DONE-

Fig 3—A trial of Fig 2's program performs a short 8-point FFT.

2011 N=2^K 2020 DIM D1(N) 2021 DIM D2(N) 2050 NEXT I 2110 GDSUB 3000
 2113 PRINT"/////////
 3112 N2=N-1

 2114 PRINT"RESULTS: REAL & IMAG"
 3113 FOR N3:

 2115 IF FI=-1 GOTD 2200
 3114 N4=N
 2115 IF FI=-1 GOTO 2200

2230 NEXT I 2240 PRINT"================== 2250 PRINT" -DONE-" 3110 N=2^K 3111 N1=0 3113 FOR N3=1 TO N2

3116 IF N1+N4>N2 GOTO 3115 3117 N1=N1-INT(N1/N4)*N4+N4 3118 IF N1<=N3 GOTO 3125 3200 REM***DO CMPLX FFT*** 3200 REM***D0 CMPLX FFT*** 3210 N4=1 3211 N6=2*N4 3212 FOR N3=0 TO N4-1 3213 A=F1*N3*3.14159265359/N4 3214 C=COS(A) 3215 S=S1N(A) 3216 FOR N7=N3 TO N-1 STEP N6 3217 N8=N7+N4 3218 T1=C*D1(N8)-S*D2(N8) 3219 T2=C*D2(N8)+S*D1(N8) 3220 D1(N8)=D1(N7)-T1 3221 D2(N8)=D2(N7)-T2 3222 D1(N7)=D2(N7)+T2 3223 D2(N7)=D2(N7)+T2 3224 NEXT N7 3225 NEXT N3 3226 N4=N6 3227 IF N4<N GOTO 3211

3228 RETURN

Fig 4—This FFT/IFT program, from Ref 3, was produced for use in music-synthesis applications.

**************************************	FOR POINT, 2 REAL? 1	//////////////////////////////////////	RESULTS: MAG VECT
AFTER CHAMBERLIN	IMAG? O		
*****	FOR POINT, 3	0 1.625 0	V 0 = 1.625
7031D - USOFT BASIC	REAL? 1	and and been been and any	
ON ROCKWELL AIM-65	IMAG? O	1161611652	V 1 = .18420322
**************	FOR POINT, 4	0883883475	
DATE: 7.7/15/81	REAL? 3	and the last the one are see the last and has been been and the set	$\vee 2 = .279508497$
HOUR:? 12.1.01 P	IMAG? O	2 .25 .125	
FWD-OR-INV? F	FOR POINT, 5	and the set has not and the set	\vee 3 = .349741582
FI = 1	REAL? 2	3338388348	and and and some the set of the
RUN DESCR? WAGGENER SAMPLE	IMAG? O	0883883476	\vee 4 = .125
*****************	FOR POINT, 6	and the set of the set	
SET FFT/IFT SIZE, N	REAL? 1	4125 0	V 5 = .349741582
K=? 3	IMAG? O		
N= 8	FOR POINT, 7	5338388348	V 6 = .279508497
INPUT DATA	REAL? 2	.0883883475	
FOR POINT, O	IMAG? O		V 7 = .18420322
REAL? 1	-7031B-	6 .25125	
IMAG? 0			-DONE-
FOR POINT, 1	FFT/IFT SUBR	7161611652	
REAL? 2	(CHAMBERLIN)	.0883883476	
IMAG? 0	**************		

Fig 5—A trial run of Fig 4's program, like the trial run in Fig 3, performs an 8-point FFT.

Try some basic exercises to familiarize yourself with FFT/IFTs

Third, try combinations of multiple cosine and/or sine waves. Here, too, the easiest way to construct these waveforms is to start in the frequency domain, draw in magnitudes at various harmonics and then use the IFT to generate the time-related amplitudes for the composite wave. Here, you'll see now neatly the algorithm can handle multitone signaling, such as that used in Touch-Tone dialing.

Fourth, try square waves, both single pulses and in pulse strings. Determine what size FFTs you need to handle them, the test being whether the IFT will reproduce the original square wave.

Fifth, substitute some statements to have your inputs automatically generated by equations for various curves. We found the exponentially decaying waveform from **Ref 4** quite instructive in this regard because it was backed by the rigor of that authoritative reference.

Sixth, try arbitrary waveforms, sketched by hand or obtained from an A/D converter. This exercise provides the challenging assignment of generally interpreting FFT/IFT results. It raises several questions:

- When have you exceeded the Nyquist cutoff bandwidth?
- What is the interpretation of aperiodic signals? (The FFT/IFT in theory only applies to periodic signals.)
- What is the effect of window distortion (briefly covered in **Ref** 1)?

You will soon see that although the FFT/IFT is readily usable and obviously very valuable, its exact interpretation can often be a puzzlement. At this point, your intellectual curiosity will be properly whetted, and you'll be primed to study the many excellent references on FFT/IFT theory and practice. We suggest that you start by obtaining the IEEE list of publications, which contains some of the best recent texts on the subject.

About this time you might also begin to wonder how the FFT relates to similar analysis techniques, particularly correlation (**Ref 5**). The answer is that correlation, which only works in the time-to-frequency direction (it has no IFT equivalent), can sometimes be superior for analyzing the periodicity of simpler time-domain signals. However, the FFT/IFT combination proves best for complex waveforms and is the only tool for working in both directions.

Using the FFT/IFT

To illustrate how you might use **Fig 2** and **4**'s tools, examine how three engineers have already used them. The first two are the authors of the programs; the third, a research engineer with RCA.

William Waggener, Fig 2's program's author and an engineer with Sangamo Weston (Sarasota, FL), uses the FFT for evaluating the frequency response of instrumentation tape recorders. He records a known signal and then plays it back, digitizes the waveform and performs the FFT to obtain amplitude and phase response. He likes the FFT because it can be performed automatically and rapidly.

A distinct advantage of the FFT is that it allows "1-shot" tests in which you examine several frequencies of interest simultaneously. The recorded test signal can be a composite of several frequencies (perhaps constructed with the aid of the IFT), and the response spectra via the FFT show the magnitudes and phases for each of them. (Alternatively, a time-domain waveform rich in harmonics, such as a square wave, can serve as the test input.)

Waggener agrees with our experience that the printout, rather than the FFT calculation itself, is the tedious part of this analysis. His 256-point FFTs take only about a minute or so to calculate. He recommends plotting the results graphically: Even though this plotting takes time, the resulting human interpretation of the plot can be rapid. Sangamo's goal, reports Waggener, is to fully automate the test using IEEE-488-connected instruments such as a digital storage scope, HP 85 computer and plotters.

Hal Chamberlin, **Fig** 4's program's author, explains that his prime interest in the FFT/IFT is for its use in musical analysis and synthesis. Such direct digital synthesis of music with the FFT/IFT is used by leading musical experimenters at Bell Laboratories and Stanford University.

Although music exists only in the time domain, it is best analyzed and synthesized in the frequency domain, says Chamberlin. He uses the FFT to transform musical passages into the frequency domain, then analyzes and creatively alters them, then uses the IFT to return them to the time domain to be played.

Chamberlin divides musical passages into a series of 10- to 50-msec windows and performs 128- to 512-point FFTs on these windows. The more rapidly changing the sound, the narrower the windows must be, but for a given window duration, there must be enough FFT points (enough A/D conversion samples) to provide the desired frequency resolution.

Fig 7 shows our diagramatical interpretation of the tradeoffs. The extremes go from crude fidelity at the lower left-hand corner to high fidelity at the upper right-hand one. In the lower left-hand corner, wide 50-msec windows and short 128-point transforms produce unacceptable results—only 1.28-kHz Nyquist bandwidths. At the upper right-hand corner, narrow 10-msec windows and longer 512-point transforms produce excellent 25.6-kHz bandwidths. We also plot a point for a 20-msec window and a 1024-point transform; this combination might be a goal for use in future high-fidelity music systems.

Chamberlin's company, Micro Technology Unlimited (Raleigh, NC), sells software based on the Fourier transform (currently using the slower discrete version) that allows μ C owners to create multipart music. When creating compositions in the frequency domain, it's easy to specify the spectrum for more than one instrument



Fig 6—Perform these familiarization exercises to gain expertise in FFT/IFT operations. By transferring back and forth between the time and frequency domains on simple, elementary curves like these, you can gain an initial familiarity with the FFT and IFT and ready yourself for more serious study of the underlying theory.

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FFT/IFT algorithm helps simulate music digitally

and then have all instruments play simultaneously in the time domain. It's also easy in the frequency domain to define the characteristics of the individual instruments so that they either sound like conventional instruments or have entirely original characteristics.

Chamberlin's software is used to create time-domain look-up tables, which, when scanned by a μ P and fed to a DAC in real time, "play" the composition. His book (**Ref 3**) provides a good general discussion of the direct digital synthesis methods in contrast to analog ("Moog synthesizer") approaches. Even readers not interested in music will learn more about the uses of the FFT and IFT from it.

We speculate that in the future, when fast FFT/IFT

chips become available at low cost, you'll see electronic musical instruments that make use of the FFT and IFT in real time. For example, you can imagine an instrument in which the keyboard inputs represent frequency-domain choices (as indeed they now do with most instruments) which are converted in real time by IFT algorithms into time-domain waveforms that drive speakers. You can also imagine how easy it will be to add software-driven real-time signal processing to further alter the waveforms being played, and perhaps to automatically generate accompanying instruments.

An impressive FFT application

Our third example of FFT/IFT use comes from Stu Perlman of RCA's Princeton, NJ Laboratories, who over a 3-yr period developed a complete digitalcomputer simulation for TV systems for use as a design tool. Described in **Ref 6**, Perlman's simulation covers everything from the initial light entering the TV



Fig 7—FFT-parameter tradeoffs for audio applications reveal the combinations of window width and sampling frequency most useful in those applications.

camera at the studio to the light coming out of the home viewer's set. It models the camera, broadcast link and receiving set.

The FFT and IFT are used 11 times in this computer simulation to transfer back and forth between the time and frequency domains. Such transfers are essential, because certain computations along the signal path can only be done in the time domain and others only in the frequency domain. (For example, it is only possible to check on the depth of broadcast modulation if the signal is in the time domain, but filtering can best occur in the frequency domain.)

Perlman's choice of FFT/IFT window duration and number of points involved a tradeoff that pushed him well beyond the limits of most personal- μ C systems. He wanted to capture the basic periodicity of the TV signal, and that meant using a window spanning two TV horizontal lines or 127.11 μ sec. Then, to achieve adequate bandwidth he was forced to a very large 4098-point FFT/IFT (resulting in a 16.11-MHz Nyquist or cutoff bandwidth). To perform these large transforms, he used an IBM 370 mainframe with 900k words of core memory.

The 370, programmed in FORTRAN IV, provides virtually instant simulation runs. Perlman believes that current 8-bit μ Ps, especially if programmed in interpreted BASIC like that of our **Fig 2** and 4 programs, would be impossibly slow and would not have the memory capacity to hold his large array (approximately 4M bytes, we estimate). However he acknowledges that the coming generation of 16/32- μ Ps might be able to handle this degree of simulation.

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Noise-property analysis enhances PLL designs

You can calculate phase noise based on loop-component specs and thus determine the worst-case performance of PLL systems.

Larry Martin, Consultant

With the mathematical and graphical techniques presented here for predicting phase noise in your phaselocked-loop (PLL) output, you can cost effectively specify the required performance when evaluating PLLs. This capability proves important because the phase-noise performance of subsystems such as indirect frequency synthesizers in receiver systems can determine system performance.

Review puts PLL fundamentals in perspective

Two equally valid sets of nomenclature—phasedomain or frequency-domain terms—can be used to describe PLL parameters (**Fig 1a**). The phase-domain definitions of interest are:

 $\begin{array}{l} \theta_R(s){=}\mathrm{input} \ phase \ to \ the \ loop \ (rad) \\ \theta_0(s){=}\mathrm{output} \ phase \ of \ the \ loop \ (rad) \\ \theta_E(s){=}\mathrm{phase} \ error \ in \ the \ loop \ (rad) \\ \theta_V(s){=}\mathrm{phase} \ error \ in \ the \ loop \ (rad) \\ \theta_V(s){=}\mathrm{phase} \ correction \ to \ the \ VCO \ (rad) \\ K_P(s){=}\mathrm{phase} \ detector \ gain \ (V/rad) \\ A(s){=}\mathrm{loop}{-}\mathrm{amplifier} \ gain \ (V/V) \\ K_V(s){=}VCO \ transfer \ gain \ (rad/sec/V) \\ K_0(s){=}VCO \ phase{-}\mathrm{transfer} \ gain \ (rad/V). \end{array}$

In Laplace-transform terms, VCO phase-transfer gain relates to VCO voltage-transfer gain through

$$K_0(s) = K_v(s)/s$$

Then, in control-theory terms, the loop's output phase in terms of its input phase is specified by

$$\theta_0(s)/\theta_R(s) = G(s)/[1 + G(s)H(s)],$$

where

$$G(s) = K_{P}(s)K_{O}(s)A(s) = K_{P}(s)K_{V}(s)A(s)/s$$

and H(s)=1/N. Here, G(s) equals system forward gain (Fig 1b), and H(s) represents feedback-path gain.

Frequency-domain notation, on the other hand, requires some additional definitions:

 $\omega_0(s) = \text{loop output frequency (rad/sec)}$

 $\omega_R(s) = \text{loop input frequency (rad/sec)}$

 $f_0(s) = loop output frequency (Hz)$

 $f_R(s)$ loop input frequency (Hz)

 $K_{\Phi}(s)$ =phase-detector transfer gain (V/Hz).



Fig 1—Two sets of nomenclature—one relating to the frequency domain and the other to the phase domain—can describe a PLL system (a). In (b), G(s) represents the system's forward gain and H(s) equals the feedback gain.

PLL-subsystem phase-noise level can determine system performance

In terms of frequency, the loop equation now reads

$$f_0(s)/f_R(s) = \omega_0(s)/\omega_R(s) = G'(s)/[1 + G'(s)H(s)],$$

where

$$G'(s) = K_{\Phi}(s)K_{V}(s)A(s) = K_{P}(s)K_{V}(s)A(s)/s$$

and $K_{\Phi}(s) = K_{P}(s)/s$. Thus, G(s) = G'(s), and the transfer functions are identical.

Next, recognize the loop characteristic equation:

$$1 + \mathrm{G}(\mathrm{s})\mathrm{H}(\mathrm{s}) = 0.$$

The highest degree of this equation determines the loop order, and the number of poles of the open-loop transfer function, G(s)H(s), located at the origin determines loop type. (PLLs are generally Type 1 loops because of the finite gains of loop amplifiers and other real-world components.)

With this nomenclature background, note that to change PLL parameters (**Refs 1**, 2 and 3 review loop parameters) you can usually only modify A(s). **Fig 2** illustrates typical circuit configurations for changing loop type or order.

Time-domain terms describe phase noise

The output of an oscillator in the time domain is

$$\mathbf{v}(t) = [\mathbf{V}_0 + \mathbf{V}_A(t)]\cos[\boldsymbol{\omega}_0(t) + \boldsymbol{\theta}(t)],$$

where V_0 is the average signal amplitude, ω_0 is the signal's average radian frequency, $V_A(t)$ is the signal's instantaneous amplitude fluctuation and $\theta(t)$ is the

signal's instantaneous phase fluctuation. Because this article focuses on signal phase properties, assume small amplitude fluctuations—usually a safe assumption because an oscillator's phase noise usually greatly exceeds its amplitude noise at small frequency offsets from the carrier. Furthermore, assume small phase fluctuations.

Now consider a signal with the small phase deviation ϕ_m , phase modulated by a sine wave of frequency ω_m :

$$\mathbf{v}(t) = \mathbf{V}_0 \cos(\omega_0 t + \phi_m \sin \omega_m t).$$

This equation expands trigonometrically to

$$\mathbf{v}(t) = \mathbf{V}_{0}\{(\cos\omega_{0}t) [\cos(\phi_{m}\sin\omega_{m}t)]$$

$$- (\sin\omega_0 t) [\sin(\phi_m \sin \omega_m t)] \}$$

and, by Bessel functions of the first kind, to

$$\begin{aligned} \mathbf{v}(t) &= \mathbf{V}_0 \{ \mathbf{J}_0(\boldsymbol{\phi}_m) \mathbf{cos} \boldsymbol{\omega}_0 t + \mathbf{J}_1(\boldsymbol{\phi}_m) [\mathbf{cos}(\boldsymbol{\omega}_0 + \boldsymbol{\omega}_m) t \\ &- \mathbf{cos}(\boldsymbol{\omega}_0 - \boldsymbol{\omega}_m) t] + \mathbf{J}_2(\boldsymbol{\phi}_m) [\mathbf{cos}(\boldsymbol{\omega}_0 + 2\boldsymbol{\omega}_m) t \\ &+ \mathbf{cos}(\boldsymbol{\omega}_0 - 2\boldsymbol{\omega}_m) t] + \cdots \}, \end{aligned}$$

where ϕ_m is the modulation index and $J_0(\phi_m)$, $J_1(\phi_m)$ and $J_2(\phi_m)$ are the Bessel functions. For $\phi_m < 0.2$, these equations yield

$$J_1(\phi_m)/J_0(\phi_m) \approx \phi_m/2$$
 for $\phi_m < 0.2$.

Because the modulation index $\phi_{\rm m}$ equals

 $\phi_{\rm m} = \Delta f/f_{\rm m},$

where Δf denotes peak frequency deviation,

 $J_1(\phi_m)/J_0(\phi_m) = \Delta f/(2f_m).$

This expression gives the amplitude of the modulation sidebands in the frequency domain.

If the frequency deviation remains constant and independent of the modulating frequency, sideband



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Fig 3—If frequency deviation remains constant and is independent of modulating frequency, sideband amplitude is inversely proportional to the modulating frequency. Here, (a) shows the frequency deviation; (b), the sideband amplitudes; (c), the single-sideband amplitude.





amplitude is inversely proportional to the modulating frequency (Fig 3). For each frequency f_m , a pair of sidebands—equal in amplitude but opposite in phase—appears symmetrically about the carrier f_0 . When amplitude modulated, the carrier has sidebands equal in amplitude and phase. Thus, if a modulated carrier has unsymmetrical sidebands, it's being amplitude and phase modulated simultaneously.

So far this article has dealt with a signal's sinusoidal modulation. To generalize the discussion to noise modulation, note that mathematically noise is a summation of independent components with different frequencies and amplitudes. The average value of noise at any frequency is expressed in rms terms. Thus, you'll find a one-to-one correspondence for noise measured at a given frequency to the noise at that frequency offset from a noise-modulated carrier. This relationship holds true so long as the frequency deviations are sufficiently small and the previous assumptions permitting the Bessel-function expansion thus remain valid.

The usual method of measuring a signal with EDN SEPTEMBER 16, 1981

low-deviation phase modulation is to measure one sideband (because the sidebands have identical amplitudes) in a 1-Hz bandwidth. This signal is referred to by $\mathcal{L}(f_m)$, the ratio of the single-sideband power of the phase or frequency noise in a 1-Hz bandwidth, offset by f_m from the carrier frequency, to total signal power, or, in logarithmic terms

$$\mathscr{L}(\mathbf{f}_{\mathrm{m}}) = 20\log[\Delta f/(2f_{\mathrm{m}})] = 20\log[J_1(\phi_{\mathrm{m}})/J_0(\phi_{\mathrm{m}})].$$

This equation expresses signal amplitudes in terms of voltage rather than power.

VCO noise spectra yield frequency deviation

You can measure the phase noise of an oscillator using many different techniques (**Refs 4, 5, 6** and 7). Here, assume that you already know the oscillator phase noise; **Fig 4** shows an example of such noise. Once you know this noise spectrum, you can calculate the frequency deviation with the foregoing equations. Furthermore, because you know the VCO's input-

Frequency deviation depends on oscillator noise spectra

tuning voltage sensitivity K_v , you can compute an equivalent noise voltage at the VCO input and at a particular offset frequency f_m using

$$\overline{\mathbf{e}_{\mathbf{V}}} = \Delta \mathbf{f}_{\mathbf{RMS}} / \mathbf{K}_{\mathbf{V}}.$$

Figs 4b and 4c show the results of these computations.

With this information, you can model the VCO as a noise-free oscillator with a noise-voltage source at its input. **Fig 5** shows the phase-locked loop with this noise source. The loop's output frequency is given by

$$f_{Q}(s) = \underbrace{\frac{NK_{V}(s)K_{P}(s)A(s)}{sN + K_{V}(s) K_{P}(s)A(s)}}_{\text{DESIRED TERM}} f_{R}(s)$$
$$+ \underbrace{\frac{sNK_{V}(s)}{sN + K_{V}(s)K_{P}(s)A(s)}}_{\text{CONTAMINATING TERM}} (1)$$

where the desired term represents the output in a noise-free environment and the contaminating term results from VCO noise.

If you look at only the contaminating term and let $s=j\omega$, you can define frequency deviation as

$$\Delta f_{0}(j\omega) = \frac{j\omega N K_{v}(j\omega)}{j\omega N + K_{v}(j\omega) K_{P}(j\omega) A(j\omega)} \overline{e_{v}}(j\omega)$$

or $\frac{\Delta f_{0}(j2\pi f_{m})}{f_{m}}$
 $= \frac{j2\pi N K_{v}}{j2\pi f_{m}N + K_{v}(j2\pi f_{m}K_{P}(j2\pi f_{m})A(j2\pi f_{m}))} \overline{e_{v}}(j2\pi f_{m})$







For a phase-locked VCO, this equation yields phasenoise sideband amplitudes of

$$\mathcal{L}_{0}^{v}(f_{m}) = 20 log \left[\left| \frac{j \pi N K_{v}}{j 2 \pi f_{m} N + K_{P} K_{v} A f_{m}} \right| \overline{e_{v}}(f_{m}) \right].$$

Here, the subscript 0 indicates loop output noise, and the superscript V refers to the VCO's noise contribution. Thus, loop properties modify an unlocked oscillator's phase noise.

Now note that

$$\overline{\mathbf{e}_{\mathbf{v}}}(\mathbf{f}_{\mathbf{m}}) = \Delta \mathbf{f}(\mathbf{f}_{\mathbf{m}})/\mathbf{K}_{\mathbf{v}} = \mathscr{L}_{\mathbf{v}}(\mathbf{f}_{\mathbf{m}})2\mathbf{f}_{\mathbf{m}}/\mathbf{K}_{\mathbf{v}}.$$

where $\mathbf{z}_{v}(f_{m})$ is the open-loop VCO noise. You can substitute this equation into the preceding phase-noise equation to vield

$$\begin{aligned} \mathscr{L}_{O}^{V}(\mathbf{f}_{m}) &= 20 \log \left[\left| \frac{j 2 \pi \mathbf{f}_{m} \mathbf{N}}{j 2 \pi \mathbf{f}_{m} \mathbf{N} + \mathbf{K}_{P} \mathbf{K}_{V} \mathbf{A} \mathbf{f}_{m}} \right| \right] \mathscr{L}_{V}(\mathbf{f}_{m}) \\ &= 20 \log \left[\frac{1}{\left| 1 + \mathbf{G}(\mathbf{f}_{m}) \mathbf{H}(\mathbf{f}_{m}) \right|} \right] \mathscr{L}_{V}(\mathbf{f}_{m}). \end{aligned}$$

$$(2)$$

This equation says that the noise outside the loop bandwidth (defined as the frequency at which G(s)H(s)=1 and also the -3-dB point of the loop's frequency response, assuming no peaking) equals the open-loop VCO noise, and that the oscillator's phase noise inside the loop bandwidth is reduced by the amount of loop gain available at any offset frequency fm.

Fig 6 shows an example of this effect. Many oscillators in the VHF and higher frequency ranges have low-frequency phase noise with a 30-dB/decade slope. For Type 1 loops, the noise inside the loop bandwidth still has a 10-dB/decade slope. Thus, you might choose a Type 2 loop, which has higher gain at low frequencies, to further reduce oscillator noise. However, if you choose a Type 2 or higher order loop, be careful when placing the loop's poles and zeroes to avoid any loop-gain peaking, which can degrade loop noise performance.



check the effects of noise currents when loop-amplifier

To summarize, you can reduce open-loop VCO noise only by the amount of loop gain. Noise performance outside the loop bandwidth equals that of an unlocked VCO unless the loop gain has peaking; in this case, the noise is higher.

Low-frequency references provide stability

Because most high-frequency oscillators lack adequate long-term stability, they can't serve as primary oscillators in many frequency synthesizers. Therefore, they are usually phase locked to a lower frequency oscillator designed for good long-term stability. Unfortunately, such oscillators have phase noise that might determine loop noise properties. Consider a reference oscillator: It has some phase noise-expressed in the frequency domain (Eq 1) as:

$$\Delta f_0(s) = \frac{NK_VK_PA(s)}{sN \,+\, K_PK_VA(s)}\,\Delta f_R(s). \label{eq:deltaformula}$$

Thus, the loop's output-frequency deviation becomes

$$\frac{\Delta f_{0}(s)}{f_{m}} = \frac{NK_{V}K_{P}A(s)}{sN + K_{P}K_{V}A(s)} + \frac{\Delta f_{R}(s)}{f_{m}}$$

After manipulation, the output sideband level as a function of both loop gain and reference noise equals

$$\mathscr{L}_{O}^{R}(f_{m}) = 20\log\left[\frac{|NK_{V}K_{P}A(f_{m})|}{|j2\pi f_{m}N + K_{P}K_{V}A(f_{m})|}\right]\mathscr{L}_{R}(f_{m}).$$
(3)

 $\mathcal{L}_{R}(f_{m})$ refers to the phase noise of the reference oscillator.

This expression says that at low offset frequencies the output noise is merely the reference noise multiplied by the division number N. However, outside the loop bandwidth, noise is not zero but instead the multiplied reference noise reduced by the attenuation provided by the loop outside the loop bandwidth. This attenuation usually has a 1/f term because A(s) is usually independent of frequency for those outside the loop bandwidth. Thus, for a large f_m ,

$$\mathscr{L}_{O}^{R}(f_{m}) \approx 20 \log \left[\frac{K_{v}K_{P}}{2\pi f_{m}} \middle| A(f_{m}) \right] \mathscr{L}_{R}(f_{m}).$$
 (4)

You must, therefore, consider not only the loop gain necessary to provide for VCO noise reduction inside the loop bandwidth, but also the effects of the reference noise on the VCO outside the loop bandwidth.

Frequency dividers generate noise

The noise inherent in the frequency divider also contributes to the noise in phase-locked loops. This noise comes from the divider's active devices, but vendors unfortunately seldom specify it. You can measure the noise, but regard your measurements at best as typical, because vendors probably exercise little control over this spec during manufacturing.

Once you estimate the values, though, you can easily see whether the noise affects loop performance. Note that the loop cannot determine whether this noise comes from the phase detector's reference or divided-

impedance levels are high.

Set loop bandwidth to optimize noise at a given offset frequency

VCO input; thus, if divider noise is less than reference noise, the former is not a prime noise contributor. However, if divider noise is greater than reference noise, it might constitute a prime contributor to loop noise. If they are approximately equal, the resultant noise equals their rms sum.

Mathematically, the divider's noise contribution to the loop's output noise is

$$\mathcal{L}_{O}^{D}(f_{m}) = 20\log\left[\left|\frac{NK_{V}K_{P}A(f_{m})}{j2\pi f_{m}N + K_{P}K_{V}A(f_{m})}\right|\right]\mathcal{L}_{D}(f_{m}),$$

where $\mathcal{L}_{D}(f_{m})$ is the additional phase noise the divider causes, referred to the divider's output.

Check phase-detector and loop-amplifier noise

Until now, this article has expressed output noise contributions in terms of input- and output-noise spectral densities. This section, however, presents an expression that describes output contributions to loop phase noise based on the measured noise voltages at the phase-detector-output and loop-amplifier-input noise sources. Here, the loop-amplifier model has only a voltage noise source—usually a reasonable assumption, although you should compute the effects of noise currents when the loop amplifier's impedance levels are large. **Fig 7** illustrates a loop with these noises lumped together; all other components are assumed noise free.

The output frequency of such a loop is

$$\begin{split} \omega_{0}(s) &= \underbrace{\frac{NK_{V}K_{P}A(s)}{sN + K_{V}K_{P}A(s)} \omega_{R}(s)}_{DESIRED \ TERM} \\ &+ \underbrace{\frac{sK_{V}A(s)N}{sN + K_{V}K_{P}A(s)} \overline{e_{nT}}(s).}_{UNDESIRED \ TERM} \end{split}$$

If you let $s = j\omega$, define the noise term as

$$\Delta \omega_0(s) = \frac{sNK_VA(s)}{sN + K_VK_PA(s)} \overline{e_{nT}}(s).$$

At a particular frequency offset $f_{m}, \mbox{ you can express}$ output noise as

$$\mathcal{L}_{0}^{P}(\mathbf{f}_{m}) = 20 \log \left[\frac{1}{2} \left| \frac{j N K_{V} A(\mathbf{f}_{m})}{j 2 \pi f_{m} N + K_{V} K_{P} A(\mathbf{f}_{m})} \right| \overline{e_{nT}}(\mathbf{f}_{m}) \right].$$

This equation shows that for large loop gains (and low frequency), the noise floor is independent of loop gain, as shown by

$$\mathscr{L}_{0}^{p}(f_{m}) \approx 20 \log \left[\frac{N}{2K_{P}} e_{nT}(f_{m}) \right] \text{ for small } f_{m}.$$
 (5)



Furthermore, for frequency offsets greater than loop bandwidth, the noise falls off at only a 20-dB/decade rate for a flat \bar{e}_T , as shown by

$$\mathscr{L}^{P}_{O}(f_{m}) = 20 log \left[\frac{K_{V}}{4\pi f_{m}} \left| A(f_{m}) \right| e_{nT}(f_{m}) \right]$$
for large f_{m} .

If this noise limits the loop's noise floor, you can reduce it using three methods: by finding an amplifier with lower input noise or a phase detector with lower noise; by finding a phase detector with a higher gain constant; or by changing the loop's diagram to meet specs.

Example shows noise effects

Thus far, this article has described all major PLL noise contributors. However, many loops include additional components such as circuits to linearize the VCO tuning curve or pretuned circuits to tune the VCO closer to its final value. You can analyze these circuits' noise sources in a manner similar to that described or lump them together with those already reviewed.

Consider an example that shows how the equations presented in this article can predict loop output noise. **Fig 8** shows a block diagram of a frequency synthesizer. The VCO operates at 240 MHz, and frequency step size equals 1 MHz. The **table** shows the measured noise data for the loop components. Assume that the phase detector and op amp have a noise floor of 30 nV/Hz.

To predict loop output noise, first plot the phase noise of the VCO and the frequency reference, both referred to 240 MHz (Fig 9a). Notice that the two curves intersect at 4 kHz. Loop bandwidth is usually chosen to make these curves intersect at the loop bandwidth. The loop is assumed to be a Type 2, because the VCO noise falls at a 30-dB/decade rate. Now plot loop gain on the same curve as VCO noise (Fig 9b). You can determine VCO closed-loop noise by subtracting loop gain from VCO phase noise. Note the rise in noise inside the loop bandwidth below 800 Hz, until the extra gain of the Type 2 loop comes into effect (from Eq 2). Place the zero in the gain function at about one-fifth of the loop bandwidth, thus achieving a fair compromise between high gain at low frequencies and minimizing loop peaking (which would be caused by placing the zero at any higher frequency).



You could plot similar curves for the reference oscillator, based on Eqs 3 and 4 (Fig 9c). Here, loop gain has no effect inside the loop bandwidth: however. the noise outside the loop bandwidth can only be attenuated by the loop attenuation. Calculate the rms sum of the two closed-loop curves-because the noises are uncorrelated-to obtain loop noise performance assuming the rest of the loop is noise free; this represents the best performance for a given loop bandwidth. You can also move the loop bandwidth to optimize noise at a particular offset frequency (Fig 9d).

Unfortunately, the rest of the loop contributes noise. The divider has a negligible effect, as the **table** shows. However, the noise from the phase detector and loop amplifier (assumed to be 30 nV/Hz and flat with no 1/f

NOISE

10,000

TOTAL CLOSED-LOOP NOISE (REFERENCE

AND VCO ONLY)

TOTAL PLL NOISE

10,000

100,000

40

30

20^(Bp)

10

0

100,000

100,000

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NQ75	5V @ 8A	5,12,15,24V @ 3A	5,12,15,24V @ 1.5A	5.12.15.24V @ 1.5A	75W	182.00	138.00
NQ130	5V @ 20A	5,12,15,24V @ 1.5A	5,12,15,24V @ 1.5A	5.12.15.24V @ 4A	130W	259.00	187.00
NQ150	5V @ 20A	5,12,15,24V @ 3A	5,12,15,24V @ 3A	5,12,15,24V @ 4A	150W	282.00	196.00
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Loop attenuation can reduce noise outside loop bandwidth

contribution) result in a loop noise floor of 91 dBc (**Eq** 5). Fig 9e shows this effect along with the VCO and reference noise. The phase-detector noise dominates loop noise. You can add these noise curves to find the total noise expected.

Again, to optimize noise at a particular frequency, adjust the loop bandwidth. If the noise performance of this simple loop does not suffice, select lower noise components or design a more complicated loop.

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Larry Martin is a consultant dealing with analog and digital circuit and system design. During preparation of this article, he was project manager responsible for spectrum-analyzer design and development at Hewlett-Packard's Santa Rosa Div (Santa Rosa, CA), where he worked for 13 yrs. He holds an MSEE from Stanford University and a BSEE from Kansas State University. In his spare time, Larry enjoys tennis, photography and electronics.

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Operating systems cost more – but they also do more

Updated and recently introduced operating systems reflect their suppliers' efforts to maintain performance parity with advances in 8- and 16-bit µC hardware.

George Kotelly, Senior Editor

Like many other products, microcomputer operating systems (OSs) are more expensive than they were a year ago. But the operating systems listed in this second annual directory also reflect augmented processor, peripheral, memory and file-management capabilities. Thanks to refinements in older versions and increased versatility in new offerings, these 80 operating systems have kept pace with the improved computational power of 8- and 16-bit μ Cs.

These OSs reflect several trends when compared with the 71 products documented last year (EDN, November 5, 1980, pg 301):

- In processor allocation/management, a swing to multitasking, multiuse and multiprocessing
- In peripheral management, the added capability of handling hard-disk drives
- In memory management, increased system storage capacity along with a focus on memoryprotection features
- In file management, increased availability of data security and protection
- In system support, increased accommodation of networking
- In language support, a preference for BASIC, FORTRAN, PASCAL, COBOL and C in that order, with small usage gains or losses for each.

Price is up

Despite the importance of these trends, though, price increases account for the most noticeable change in the operating systems covered again this year. Nearly one-third of these repeats carry a higher price tag. For the majority, the suppliers' increased cost of doing business has merely taken its toll. But in several instances, offerings exhibit extra performance along with their extra cost.

Previously not available in many OSs, such features as network support, hard-disk I/O and storage, multitasking, and additional support languages and target μ Cs have been incorporated in more than half of the EDN SEPTEMBER 16, 1981



Termed the Apple Disk II housekeeper, the DOS 3.3 operating system from Apple Computer allows turnkey operation under Apple BASIC. It automatically catalogs files by name; saves, loads, runs, renames, deletes and verifies files; permits sequential and random data access; and helps make backup diskette copies.

returnees that underwent price increases. For example, network support now comes standard in MICRO COBOL BOS, MP/M II and XENIX; hard-disk I/O in RTE-XL, HDOS and SDOS; multitasking in KOS 5.2 and UCSD P-System; and BASIC and FORTRAN support in SP/ and MSP/8086/Z8000/6800.

Additionally, some OS manufacturers provide added capability at no increase in price. For example, AMIX 3.0 supports seven more μ Cs than it did last year, CDOS now supplies processor allocation and memory management as standard features, and UMDS supports PASCAL as well as five additional μ Cs.

More bits for more work

Not surprisingly, operating systems for 16-bit μ Cs constitute many of the 18 new entrants in the directory. Besides bearing higher prices than OSs available a year ago, they reflect a definite trend toward 16-bit- μ C use. Their increased performance entails a small price increment but satisfies users' needs to handle computation and communications simultaneously. Additionally, they represent a move from single-task, single-user versions (such as CP/M and ISIS) to multitask,

New operating systems support more users, tasks and processors

multiuser and—in a few cases—multiprocessor types (such as MP/M and iRMX86).

In fact, 80% of the new entrants feature multitasking capability, whether for 8- or 16-bit μ Cs. To demonstrate the diversity of multitasking variations available, consider RMS68K, a 16-bit- μ C OS. In theory, it handles an unlimited number of tasks, although memory capacity and overhead obviously dictate an upper limit. Another 16-bit- μ C OS, ZEUS, accommodates as many as 200 tasks. And yet another offering, REX-80, serves 8- and 16-bit μ Cs while providing multitasking limited only by memory constraints.

Following on the heels of multitasking as a standard OS capability comes multiple-user support—a characteristic of more than half the new entrants. Again, implementation variations abound. For example, TMS, an 8-bit- μ C OS, handles as many as five users and

provides at least 1k bytes of RAM for each. ZEUS, however, suits as many as 64 users and furnishes nearly 64k bytes of RAM for each. Another 16-bit- μ C offering, CTOS, accommodates as many as 16 users and furnishes a huge 128k bytes min of RAM for each.

Although not as prevalent as multitasking and multiple-user capability, multiprocessing has also made noticeable inroads in OSs. Some 20% of the latest OS introductions support more than one processor. The wave of the future, these OSs allow master-to-master and master-to-intelligent-slave CPUs to conduct traffic over parallel buses.

For example, CTOS supports 8086- and 8087-based μ Cs using a hardware synchronizing scheme. Embodying even greater capability, REX-80 works with as many as eight processors by means of test-and-set functions and interrupt synchronization. Performance advantages abound in these products because the application splits into more manageable segments for separate and more efficient CPU handling.

Following the same trends established in the directory's upgraded entries, the percentage of recently

Glossary of essential operating-system terms

Allocation (dynamic)—The reassignment of peripherals within a given program

Allocation (static)—The assignment of peripherals to a job

Allocation technique—The method of providing a process with access to a shared resource

Binding—The act of assigning absolute addresses to a program

Blocked list—A catalog of the processes waiting for μ P time or for completion of an I/O operation

Blocking—The process of combining more than one record into one block to make data transfers more efficient

Buffering—The process of using areas of memory to isolate I/O devices from one another and from the CPU

Chaining—The ability of an executing program to call another program that resides on disk

COMMON—An area of memory maintained for the purpose of passing data or parameters

Constrained allocation—A resource-allocation strategy that specifies all resources a process will need but does not prevent execution unless a deadlock might occur **Contiguous allocation**—An allocation method that assigns adjacent sectors to a file

Deadlock—A condition that exists when a process is blocked in a state and in all future states that the system can reach

Deadly embrace—A situation in which two processes each unknowingly wait for resources held by the other

Device independence—An OS feature that frees the user from considering device-specific details. It employs mnemonics to refer to specific devices; changing these mnemonics redirects I/O to another device

Direct memory access (DMA)—A means of providing fast peripherals with access to memory without going through the CPU

Directory—A file containing information concerning the other files on a mass-storage device; also termed a catalog

Executive—An operating-system routine responsible for decision making

File-control block (FCB)—A data structure in main memory for keeping track of files in use

File-management system—

The part of an OS that controls the organization and allocation of disk files, which might consist of one or more sectors

Index—A number representing the relative position of a byte in either a record or file

Interrupt—A break in the normal flow of a system or routine from which flow can resume later

I/O supervisor—The portion of an OS that provides routines for I/O procedures

Job—The collection of activities needed to accomplish a specified amount of work

Linked list—A list formed by tying together (with pointers) several items on a disk

Lock byte—An entity used to represent a resource in synchronization schemes; also termed a semaphore

Memory protection—A method of ensuring that the contents of main memory within certain variable limits are not altered or inadvertently destroyed

Noncontiguous allocation— An allocation method that assigns physically nonadjacent sectors to a file

Nucleus—The most basic level

introduced operating systems incorporating hard-disk support capability exceeds 50%. Additionally, the percentage of new OSs with network support and file protection totals slightly less than 50%; with memory protection, just under 25%.

A move toward 16-bit hardware notwithstanding, most operating systems still serve the large 8-bit- μ C marketplace. In fact, 8-bit- μ C OSs in the directory outnumber their 16-bit counterparts by 2:1. Additionally, among the new OS entrants, almost half are 8-bit types. In other words, operating systems serving 8-bit μ Cs still dominate this OS directory and should continue to do so in the near future.

Less popular languages make a move

The breakdown of languages supported by this directory's operating systems shows small losses by the popular languages and small gains by the less commonly used ones. Specifically, BASIC continues to lead the pack; it's available for 66% of the listed OSs—a 2% decrease from last year's total.

Next in popularity, FORTRAN and PASCAL have

also dropped slightly in usage: FORTRAN decreased by 2% to 50%, PASCAL by 3% to 48%.

Usage gains, however, occurred in the less popular languages, such as COBOL and C. Rising to 33% usage from 25%, COBOL has apparently benefitted from growth in small-business-system applications. Also reflecting increased user interest, C usage has jumped from 16 to 20%. (This latter increase probably arises because of PASCAL's standardization and portability limitations.) Another less popular language, FORTH, also reflects higher use: it has nudged upward to 13% usage from 11%.

A look around the corner

What do all these developments portend? During the 1980s, VLSI manufacturing techniques will mature and permit the production of μ C chips with extremely high densities and many built-in processing functions. As these performance benefits slide into silicon, however, they will present users with untold operational problems. Specifically, with the advent of additional μ C processing parameters, functional modes and interface

of an operating system; creates and destroys software processes used to implement abstract processes

Operating system—An organized collection of procedures for operating a computer

Overlaying—The technique of repeatedly using the same blocks of internal storage during different stages of a program; eg, when one routine is no longer needed, another routine can replace all or part of it

Polling procedure—A routine for checking each I/O device sequentially to determine whether it requires servicing

Primitive—An operation provided by a nucleus for use in synchronization

Priority—A parameter designating a task's or process's relative urgency

Process—A computation that can occur concurrently with other computations; an OS's basic unit of computation

Process - control block (PCB)—A data structure that uniquely defines a given process

Program (code)—A set of instructions that tells a computer step by step exactly how to handle a job

Re-entrant code—A program task or routine that can be executed simultaneously by more than one process

Relocation (dynamic)—The act of assigning absolute memory addresses when a program is loaded into memory

Relocation (static)—The act of assigning absolute addresses at linking time

Resource—Any device or item used by a computer, including areas of memory such as buffers

Rotational ordering—A method of organizing I/O requests to a disk to reduce total service time

Segmentation—A technique for managing variable-sized areas of memory, termed segments, that contain logical program parts

Service request—The appeal by a process or task for access to a system resource

Single contiguous allocation —A memory-allocation scheme that assigns all available memory as one block

Spin block—A loop created when a process keeps checking the state of a flag or status bit while waiting for an event to occur

SPOOLing—Simultaneous peripheral operations on line; used to convert a dedicated device into a shared one

Swapping—A technique similar to overlaying; involves moving processes between main memory and auxiliary storage in order to multiplex main memory

Sysgen—System generation, the process by which an operating system is configured out of individual system components to accommodate a particular hardware configuration

Task—A routine that forms the lowest self-contained unit of a job or process

Time slicing—A technique that shares μP time among several processes. The quantum of time allocated to a process is termed a time slice

Transient area—The space in memory available for user programs and system utilities

Urgency—The degree to which a task or process requires attention; determined by the task's or process's priority

Utilities—Routines used in housekeeping functions and I/O.

Leading support languages show no clear trends in preference

multiplexing, users will face virtually insurmountable problems when coupling designs to the outside world.

The solution? Future operating systems will be designed into VLSI devices and provide features and architectures that will insulate users from potential application pitfalls. According to Peter Palm, product marketing manager at Intel Corp, these OSs should provide modularity and configurability in the form of standard modules, layers and interfaces. For example, Intel's iRMX86 operating system currently employs object-oriented common-format interfaces to its primitives to manage jobs, tasks and messages. At a higher layer, this operating system offers common deviceindependent interfaces to device drivers that handle smart floppy- and hard-disk controllers. For an operating system with these built-in capabilities, VLSI implementation thus becomes merely a matter of improving manufacturing capability to a point where silicon fabrication becomes practical.

At a still higher layer, operating systems will soon provide a universal development interface (UDI) to popular languages for program development. They will also furnish a universal run-time interface (URI) to execute these developed programs. Such standard interfaces will permit common μ C support languages to run on top of any UDI/URI-compatible operating system. In other words, the interfaces will serve as a standard software bus for different languages and applications.

Operating systems will also soon support local-area networks (such as Ethernet) and global-area networks (such as X.25). They will provide high-level data-link



Influenced by its manufacturer's FLEX and Bell Labs's UNIX, the UniFLEX operating system from Technical Systems Consultants serves large multitasking and multiuser 6809- or 68000- μ P-based systems. It supports a hierarchical file system, permitting files of 1G bytes and disk capacities exceeding 8G bytes.

interfaces to an Ethernet controller on the Multibus via an interprocessor protocol, for example, and support standard interfaces with standard modules. Such modules, layers and interfaces should pave the way to overcoming the potential problems of VLSI technology.

Reference

Hemenway, J E, "EDN μ C Operating Systems Directory, Chapters 1 through 5," *EDN*, November 5, 1980, pgs 275-300.

Article Interest Quotient (Circle One) High 473 Medium 474 Low 475

Operating systems come in three key types

This directory classifies OSs in terms of user function. A **development OS**, for example, produces software to run either on the host μ C or on another target μ C. The target need not incorporate the same μ P type if the user develops the software by means of cross assemblers or compilers. Examples of development OSs include Intel's ISIS, Omnibyte's ODOS and Digital Research's CP/M.

A real-time or process-control OS governs industrial processes that place timing constraints on its responses: Interrupts from these external processes signal the μ C system, and if the system doesn't respond in a specified time, the

processes become impaired or degraded. Intel's iRMX80 and iRMX86 exemplify such operating systems.

General-purpose OSs usually deal with business or scientific applications. Digital Research's CP/M, for example, finds use in word processing, accounts-receivable generation and mailinglist maintenance.

These OS categories are arbitrary; many OSs in the directory provide capabilities in all three areas. Within each of the three categories, we list the operating systems in alphabetical order.

Another classification cuts across the three categories: You

can further describe an OS as a multiuser or single-user system.

To evaluate any of these OS types' suitability for your particular application, look at its ability to carry out its primary management activities: allocating the four main system resources (processor time, memory, peripherals and files) on the basis of user needs and system capabilities. By fully understanding the management features and capabilities listed in the directory for each operating system, you can focus on a few solid candidates. Then contact the OS manufacturers for decisionmaking details.

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• Compactness: MTOS-86 requires 8KB of storage; MTOS-86MP requires 10KB. (drivers, file system, require additional storage).

SERVICES

- Allocate (de-allocate) memory block
- Enter or exit controlled program
- Change priority
- Perform discrete I/O
- Pause for a given time
- Cancel pause
- Terminate task with timed re-start

TIMINGS FOR SERVICES IN MILLISECONDS

Allocate memory block 0.46
Send message 0.48
Receive message 0.54
Release memory block 0.56
Pause
Discrete I/O 0.44
Test semaphore 0.51
Change priority 0.48

THE MTOS THE MOS FAMILY FAM

- Terminate task with no re-start
- Start task; queue task if active
- •Start task if dormant
- Send message to mailbox
- Receive message from mailbox
- Set (reset, test) event flag group
- •Set event flag group after elapsed time
- Wait for event flags to be set
- •Set (reset, test) semaphore
- Request I/O
- •Get Date and time
- Set Date and time

LANGUAGE

All MTOS products are distributed in source program form.

LICENSING POLICY

A licensee is entitled to embed object versions of MTOS in licensee's products without further charge.

Other members of the MTOS family are MTOS-68, MTOS-80, MTOS-80MP, MTOS-68K

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Lead	VP22	50	2400-3900	180-5600
	VP23	100	2400-10,000	4700-15,000
	VP23	50	11,000-15,000	4700-22,000
CHIP	VJ0504		10-150	1-390
onn	VJ0805		1-680	1-1000
	VJ0905		10-680	1-1200
	VJ0907		620-1100	10-1800
	VJ1505		680-1300	47-2200
	VJ1805		620-1600	180-2700
	VJ1210		1300-3900	220-4700
	VJ1808		1500-3900	680-5600
	VJ1812		1500-6800	47001μF
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4K	TBP28S42 TBP28SA42	512W x 8B	35 ns	500 mW
	TBP28S46 TBP28SA46	512W x 8B	35 ns	500 mW
	TBP24S41 TBP24SA41	1024W x 4B	40 ns	475 mW
8K	TBP28S86-60 TBP28SA86-60	1024W x 8B	35 ns	625 mW
	TBP28S86 TBP28SA86	1024W x 8B	45 ns	625 mW
	TBP28L86	1024W x 8B	65 ns	275 mW
	TBP24S81-55 TBP24SA81-55	2048W x 4B	35 ns	625 mW
	TBP24S81 TBP24SA81	2048W x 4B	45 ns	625 mW
	TBP28S166-55 TBP28S166	2048W x 8B 2048W x 8B	35 ns 45 ns	675 mW 675 mW
DLLECTOR; L = LOW F	POWER		55166	
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16-BIT CPU DEVELOPMENT **GENERAL-PURPOSE** 8086/68000/Z8000/PDP-11 OPERATING SYSTEM **OPERATING SYSTEM XENIX** RELEASE DATE: 3rd gtr 1981 PRICE: OEM contracts TARGET MODEL: PDP-11 Series, Z8000, 8086 and 68000 Microsoft SUPPORT LANGUAGES: C compiler included; other Microsoft 10800 NE 8th St, Suite 819 language compilers available Bellevue, WA 98004 SYSGEN PROGRAM: Yes SOURCE CODE: No Phone (206) 455-8080 LANGUAGE SYSTEM: C NETWORK SUPPORT: Yes SYSTEM RESIDENCY: RAM ROMABLE SYSTEM: No MINIMUM HARDWARE NEEDED: 192k bytes RAM **PROCESSOR ALLOCATION/MANAGEMENT** MEMORY MANAGEMENT System vs User mode Segmentation Multitasking: 100 tasks, restricted by table size, can start/stop/ Swapping suspend other tasks via interprocessor message buffers and . Dynamic relocation Binding done during assembly/compilation, linking and loading software asynchronous interrupts . Multiusage: one to 25 users times Synchronizing scheme: file structure with user-implemented . Memory protection locks FILE MANAGEMENT PERIPHERAL MANAGEMENT Named file system Supports CRTs, character and line printers, floppy- and . Multilevel directory . cartridge-disk drives, modems and magnetic- and paper-tape . Sequential organization drives Allocation type: linked list of sectors . Provides device independence and user writable device driver . Password/security protection Uses interrupts and I/O multibuffering . COMMENTS: XENIX is a Level 7 UNIX operating system

Accommodates a mix of different mass-storage devices that support multiple file systems and device drivers

GENERAL-PURPOSE

OPERATING SYSTEM

LANGUAGE SYSTEM: Z80 assembler

CIRCLE NO 680

CDOS

Cromemco Inc 280 Bernardo Ave Mt View, CA 94043 Phone (415) 964-7400

8-BIT CPU

Z80

SYSTEM RESIDENCY: RAM ROMABLE SYSTEM: No MINIMUM HARDWARE NEEDED: 32k bytes RAM

PROCESSOR ALLOCATION/MANAGEMENT Not Available

PERIPHERAL MANAGEMENT

- Supports CRTs, character and line printers, floppy- and . hard-disk drives and modems
- **Provides DMA**
- Accommodates a mix of floppy- and hard-disk drives

MEMORY MANAGEMENT

- Single contiguous allocation
- Overlays

FILE MANAGEMENT

RELEASE DATE: 1977 PRICE: \$95

SYSGEN PROGRAM: Yes

NETWORK SUPPORT: No

- Named file system
- . Sequential and random organizations
- . Indexed sequential access method (ISAM)
- Allocation type: linked list of sectors
- . Can access file system from HLL containing constructs

SUPPORT LANGUAGES: Z80 Macro assembler, BASIC and LISP

SOURCE CODE: No

interpreters, FORTRAN, COBOL and RPG II compilers

COMMENTS: CDOS is upwardly compatible from CP/M

CIRCLE NO 682



	OFENALING STSTEM
romemco Inc 30 Bernardo Ave t View, CA 94043 hone (415) 964-7400	RELEASE DATE: September 1980 PRICE: \$595 SUPPORT LANGUAGES: Z80A macro assembler; BASIC and LISP interpreters; FORTRAN, COBOL, RPG II and C compilers SYSGEN PROGRAM: Yes SOURCE CODE: No LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: No
OMABLE SYSTEM: Yes INIMUM HARDWARE NEEDED: 128k bytes RAM	
 System vs User mode Multitasking: seven tasks can start/stop/suspend other tasks via intertask communication Multiusage: seven users with 64k bytes (min) RAM per user Multiprocessing: unlimited number of processors via interrupt-driven synchronizing scheme ERIPHERAL MANAGEMENT Supports CRTs, character and line printers, floppy- and hard-disk drives and modems Provides device independence, DMA and spooling Uses interrupts and I/O multibuffering Accommodates a mix of floppy- and hard-disk drives 	
16-BIT CPU	GENERAL-PURPOSE
16-BIT CPU 8086 TOS Invergent Technologies 00 Augustine Dr inta Clara, CA 95051 ione (408) 727-8830 STEM RESIDENCY: RAM and disk MABLE SYSTEM: No	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: October 1980 PRICE: Bundled TARGET MODEL: Firm's desktop minicomputers SUPPORT LANGUAGES: 8086 ASM; BASIC interpreter; PASCAL, COBOL and FORTRAN compilers SYSGEN PROGRAM: Yes SOURCE CODE: No LANGUAGE SYSTEM: PL/M-86 NETWORK SUPPORT: Yes [2-16 workstations and remote host(s)]

6502	
DOS 3.3 Apple Computer Inc 10260 Bandley Dr Cupertino, CA 95014 Phone (408) 996-1010 SYSTEM RESIDENCY: RAM and disk ROMABLE SYSTEM: No	RELEASE DATE: July 1980 PRICE: \$200 TARGET MODEL: Apple II SUPPORT LANGUAGES: 6502 assembler; floating-point BASIC and integer BASIC interpreters SYSGEN PROGRAM: No SOURCE CODE: No LANGUAGE SYSTEM: 6502 assembler NETWORK SUPPORT: No
PROCESSOR ALLOCATION/MANAGEMENT	
 PERIPHERAL MANAGEMENT Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems, A/D converters, IEEE-488 interfaces, digitizers, plotters, voice-recognition devices and speech and music synthesizers Provides device independence and DMA Uses I/O multibuffering Accommodates a mix of mass-storage devices using associated controllers 	 Single conliguous allocation Overlays Chaining Memory protection FILE MANAGEMENT Named file system Sequential and random organizations Allocation type: linked list of sectors Can access file system from HLL containing constructs CIRCLE NO 737
16-BIT CPU CS/10 Systems	GENERAL-PURPOSE OPERATING SYSTEM
16-BIT CPU CS/10 Systems	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: May 1977 PRICE: \$2500 TARGET MODEL: DG CS/10
16-BIT CPU CS/10 Systems ICOS Data General Corp 440 Computer Dr Westboro, MA 01580 Phone (617) 366-8911	RELEASE DATE: May 1977 PRICE: \$2500 TARGET MODEL: DG CS/10 SUPPORT LANGUAGES: COBOL compiler SYSGEN PROGRAM: NO LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: NO
16-BIT CPU CS/10 Systems ICOS Data General Corp H40 Computer Dr Westboro, MA 01580 Phone (617) 366-8911 SYSTEM RESIDENCY: Disk ROMABLE SYSTEM: No MINIMUM HARDWARE NEEDED: 64k bytes RAM, disk or diskette, pri	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: May 1977 PRICE: \$2500 TARGET MODEL: DG CS/10 SUPPORT LANGUAGES: COBOL compiler SYSGEN PROGRAM: No LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: No
16-BIT CPU CS/10 Systems ICOS Data General Corp 40 Computer Dr Westboro, MA 01580 Phone (617) 366-8911 SYSTEM RESIDENCY: Disk ROMABLE SYSTEM: NO MINIMUM HARDWARE NEEDED: 64k bytes RAM, disk or diskette, print PROCESSOR ALLOCATION/MANAGEMENT • Multitasking: up to four tasks can start/stop/suspend other tasks via intertask communication • Multitusage: up to four users • Synchronizing scheme: monitor	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: May 1977 PRICE: \$2500 TARGET MODEL: DG CS/10 SUPPORT LANGUAGES: COBOL compiler SYSGEN PROGRAM: NO SYSGEN PROGRAM: NO LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: NO Inter and CRT MEMORY MANAGEMENT • Overlays • Swapping and chaining • Segmentation and dynamic relocation • Binding during assembly/compilation time • Memory protection
16-BIT CPU CS/10 Systems Data General Corp 400 Computer Dr Westboro, MA 01580 Phone (617) 366-8911 SYSTEM RESIDENCY: Disk 2000 Mable System: No: SYSTEM RESIDENCY: Disk 2000 Mable System: No: Multitasking: up to four tasks can start/stop/suspend other tasks a intertask communication Multitasking: up to four tasks can start/stop/suspend other tasks a intertask communication 9. Synchronizing scheme: monitor PCIPHERAL MANAGEMENET 9. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 9. Provides device independence and spooling 9. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 10. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 10. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 10. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 10. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 11. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 11. Supports CRTs, character and line printers, floppy- and cartridge-disk drives, modems and magnetic-tape drives 12. Supports CRTs, character and line prin	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: May 1977 PRICE: \$2500 TARGET MODEL: DG CS/10 SUPPORT LANGUAGES: COBOL compiler SYSGEN PROGRAM: NO SYSGEN PROGRAM: NO SYSGEN PROGRAM: NO ANGUAGE SYSTEM: Assembler ANGUAGE SYSTEM: Assembler NETWORK SUPPORT: NO Inter and CRT MEMORY SUPPORT: NO Support Language System interlocation Binding during assembly/compilation time Binding during assembly/compilation ti

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Glass Passivated	Yes	No		
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Overvoltage Protection	20%	Not listed in 1980 catalog		
Thermal Impedance	1.5°c/w	Not listed in 1980 catalog		
High Temp. Leakage @ 100°C	50μΑ	Not listed in 1980 catalog		
Peak Surge Current (½ cycle, non-rep.)	150A	Not listed in 1980 catalog		
Glass Passivated	Yes	Not listed in 1980 catalog		

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CIRCLE NO 62

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Z80	
Computer Design Labs 42 Columbus Ave renton, NJ 08629 thone (609) 599-2146 YSTEM RESIDENCY: RAM and disk OMABLE SYSTEM: NO IINIMUM HARDWARE NEEDED: 32k bytes RAM 780 and disk control	RELEASE DATE: February 1979 PRICE: \$79.95 TARGET MODEL: S-100, TRS-80 SUPPORT LANGUAGES: QSAL and Z80/8080 Macro assemblers; BASIC, APL and LIST interpreters; BASIC, FORTRAN, COBOL and PASCAL compilers SYSGEN PROGRAM: Yes LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: No olier (>15 types supported)
 ROCESSOR ALLOCATION/MANAGEMENT Not Available ERIPHERAL MANAGEMENT Supports CRTs, character and line printers, floppy- and cartridge-disk drives, moderns and magnetic- and paper-tape drives Provides device independence, DMA and spooling Accommodates a mix of mass-storage devices with table-driven approach; only available memory limits number of devices 	MEMORY MANAGEMENT • Single contiguous memory • Overlays • Swapping • Chaining FILE MANAGEMENT • Named file system • Random organization • Allocation type: extents CIRCLE NO 694
16-BIT CPU Z8001	GENERAL-PURPOSE OPERATING SYSTEM
16-BIT CPU Z8001 ZEUS* Mog Inc 0460 Bubb Rd upertino, CA 95014 hone (408) 446-4666 YSTEM RESIDENCY: Disk OMABLE SYSTEM: No INMULM HARDWARE NEEDED: 256k bute memory and Z-I AB 9000	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: November 1981 PRICE: NA TARGET MODEL: Z-LAB 8000 SUPPORT LANGUAGES: C, PASCAL, PLZ/SYS and COBOL compilers; Z8, Z8001 and Z8002 PLZ/ASM assemblers SYSGEN PROGRAM: Yes SYSGEN PROGRAM: Yes SURCE CODE: No LANGUAGE SYSTEM: C and PLZ/ASM NETWORK SUPPORT: Yes, UUCP
16-BIT CPU Z8001 ZEUS* ilog Inc 0460 Bubb Rd upertino, CA 95014 hone (408) 446-4666 YSTEM RESIDENCY: Disk OMABLE SYSTEM: No INIMUM HARDWARE NEEDED: 256k byte memory and Z-LAB 8000 ROCESSOR ALLOCATION/MANAGEMENT • System vs User mode • Multitasking: 200 tasks can start/stop/suspend other tasks via intertask communication • Multitusage: 16 users with 64k bytes (approx) RAM per user • Synchronizing scheme: pipes and signals	GENERAL-PURPOSE OPERATING SYSTEM RELEASE DATE: November 1981 PRICE: NA TARGET MODEL: Z-LAB 8000 SUPPORT LANGUAGES: C, PASCAL, PLZ/SYS and COBOL compilers; Z8, Z8001 and Z8002 PLZ/ASM assemblers SYSGEN PROGRAM: Yes SYSGEN PROGRAM: Yes SUPCE CODE: NO LANGUAGE SYSTEM: C and PLZ/ASM NETWORK SUPPORT: Yes, UUCP OCPU MEMORY MANAGEMENT • Single contiguous allocation • Overlays and swapping • Static relocation • Static relocation • Memory protection • Binding done during linking time



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CIRCLE NO 66





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8-BIT CPU MC6809	REAL-TIME OPERATING SYSTEM
otorola Semiconductor Products Inc 02 N 56th St noenix, AZ 85018 none (602) 244-5714	RELEASE DATE: 1980 PRICE: \$2700 SUPPORT LANGUAGES: Macro assembler; MPL compiler SYSGEN PROGRAM: Yes SOURCE CODE: Request quotation LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: No
/STEM RESIDENCY: RAM DMABLE SYSTEM: Yes INIMUM HARDWARE NEEDED: 8k bytes RAM and M68MM19 or Mi	68MM19A Monoboard Microcomputer Module
OCESSOR ALLOCATION/MANAGEMENT Multitasking: 256 tasks can start/stop/suspend other tasks Synchronizing scheme: event-wait	MEMORY MANAGEMENT Single contiguous allocation Static relocation Provide the days during lipking time.
Supports CRTs and character printer Provides device independence	FILE MANAGEMENT Not Available
Uses interrupts	COMMENTS: RMS09 does not support compilation CIRCLE NO 709
16-BIT CPU	REAL-TIMF
16-BIT CPU 68000	REAL-TIME OPERATING SYSTEM
16-BIT CPU 68000 MS68K	RELEASE DATE: November 1980 PRICE: \$5000 TARGET MODEL: Versamodule 01
16-BIT CPU 68000 MS68K MS68K Morola Semiconductor Products Inc 02 N 56th St oenix, AZ 85018 one (602) 244-5714	RELEASE DATE: November 1980 PRICE: \$5000 TARGET MODEL: Versamodule 01 SUPPORT LANGUAGES: Structured macro assembler; PASCAL compiler SYSGEN PROGRAM: Yes (requires Exormacs) SOURCE CODE: Request quotation LANGUAGE SYSTEM: Assembly
16-BIT CPU 68000 MS68K MS68K Morola Semiconductor Products Inc 02 N 56th St oenix, AZ 85018 one (602) 244-5714 STEM RESIDENCY: RAM MABLE SYSTEM: Yes NIMUM HARDWARE NEEDED: Versamodule 01	RELEASE DATE: November 1980 PRICE: \$5000 SUPPORT LANGUAGES: Structured macro assembler; PASCAL compiler SYSGEN PROGRAM: Yes (requires Exormacs) SOURCE CODE: Request quotation LANGUAGE SYSTEM: Assembly NETWORK SUPPORT: No
16-BIT CPU 68000 MS68K MS68K Morola Semiconductor Products Inc 02 N 56th St oenix, AZ 85018 one (602) 244-5714 STEM RESIDENCY: RAM DMABLE SYSTEM: Yes NIMUM HARDWARE NEEDED: Versamodule 01 ROCESSOR ALLOCATION/MANAGEMENT System vs User mode Multitasking: unlimited number of tasks can start/stop/suspend other tasks via intertask communication	RELEASE DATE: November 1980 PRICE: \$5000 PRICE: \$5000 SUPPORT LANGUAGES: Structured macro assembler; PASCAL compiler SYSGEN PROGRAM: Yes (requires Exormacs) SOURCE CODE: Request quotation LANGUAGE SYSTEM: Assembly NETWORK SUPPORT: No NETWORK SUPPORT: No
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16-BIT CPU **GENERAL-PURPOSE** REAL-TIME TMS9900 **OPERATING SYSTEM OPERATING SYSTEM Component Software OS RELEASE DATE: July 1979** PRICE: \$1000 per component SUPPORT LANGUAGES: 9900 assembler; Power BASIC and Texas Instruments Inc PASCAL interpreters; Microprocessor PASCAL compiler Box 1443, MS 6404 SYSGEN PROGRAM: No SOURCE CODE: Yes Houston, TX 77001 LANGUAGE SYSTEM: PASCAL: 96%, assembler: 4% Phone (713) 778-6690 NETWORK SUPPORT: Multidrop synchronous communication using HDLC protocol SYSTEM RESIDENCY: RAM and disk **ROMABLE SYSTEM: Yes** MINIMUM HARDWARE NEEDED: 6k bytes ROM and 3k bytes RAM MEMORY MANAGEMENT **PROCESSOR ALLOCATION/MANAGEMENT** Multitasking: unlimited number of tasks can start/stop/suspend Segmentation . . . Static and dynamic relocations other tasks via intertask communication . Synchronizing scheme: semaphore, mailbox and message . Binding done during assembly/compilation, linking and loading channels times FILE MANAGEMENT PERIPHERAL MANAGEMENT Named file system and multilevel directory Supports CRTs, character and line printers, floppy-disk drives Sequential, contiguous and random organizations and modems . Allocation type: extents and single contiguous . Provides device independence and DMA . Can access file system from HLL containing constructs Uses interrupts and I/O multibuffering . Accommodates a mix of floppy-disk drives Password/security protection **CIRCLE NO 703 GENERAL-PURPOSE** 8-BIT CPU **REAL-TIME OPERATING SYSTEM OPERATING SYSTEM** 8080/8085 **MFTOS** RELEASE DATE: June 1979 PRICE: Depends on configuration TARGET MODEL: Ontel OP-1 **Ontel Corp** SUPPORT LANGUAGES: 8080 and 8085 assemblers; OPL and 250 Crossways Park Dr **BASIC** interpreters Woodbury, NY 11797 SOURCE CODE: No SYSGEN PROGRAM: Yes Phone (516) 364-2121 LANGUAGE SYSTEM: Assembler NETWORK SUPPORT: Local-16 terminals using standard IOS calls; Remote-VHM, MDOS/VF and HDOS/VF OSs SYSTEM RESIDENCY: RAM and disk ROMABLE SYSTEM: No MINIMUM HARDWARE NEEDED: 32k bytes RAM MEMORY MANAGEMENT PROCESSOR ALLOCATION/MANAGEMENT Dynamic relocation Multitasking: up to 64 tasks can start/stop/suspend other tasks Binding done during loading time using intertask communication Multiusage: up to eight terminals share hard-disk drives; up to 16 FILE MANAGEMENT terminals share master station; 350 bytes (min) RAM per user Synchronizing scheme: semaphore and mailbox • Named file system Sequential organization PERIPHERAL MANAGEMENT • Random organization and ISAM (OPL only) Allocation type: linked list of sectors Supports CRTs, line printers, floppy- and cartridge-disk drives, Can access file system from HLL containing constructs modems and, via subroutines (not OS drivers), magnetic-tape drives Provides device independence, DMA and spooling **CIRCLE NO 704 Uses** interrupts Accommodates a mix of hard-disk drives and various floppydisk-drive capacities and densities



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That's the fascinating subject of the 100-page editorial special section in EDN's 25th Anniversary issue.

EDN has asked more than thirty authors, each a leader in the field - as scientist, engineer, entrepreneur, author - to take on the role of visionary. Each has used his own experience as a database to project an acutely personal view of the electronic future. Some of the articles are serious, some lighthearted. Few authors are in agreement and, considering the problems inherent in making predictions even one year in advance in this field, many are likely to arouse considerable controversy.

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16-bit-µP benchmarks an update with explanations

A benchmark exercise is **not** your normal performance comparison. It develops a life of its own as faster μPs are introduced and better code is written. With market shares at stake, manufacturers fight fiercely to improve their showings and to make the implementations equivalent.

Walt Patstone, Editor

When EDN benchmarked the 8086, LSI-11/23, MC68000 and Z8002 (April 1, pgs 179-265), in the issue's accompanying Editorial (pg 39) we proclaimed "no winner in this contest—save you." Nevertheless, ads soon appeared declaring the 68000 the winner.

Reader feedback to the article was heavy and positive. And of course, Motorola was highly pleased with our results. By contrast, Zilog was displeased because we reported the times for its 6-MHz part when it had a 10-MHz version under development. Worse, Intel informed us that we had erred: The data suite used by the 8086 in Benchmark I (Quicksort) differed from that used by the other competitors; thus, the 8086's execution time for that benchmark was overly long by comparison.

Because subsequent investigations revealed additional difficulties with the April 1 article, EDN reopened the benchmark project, soliciting new data from Intel, Motorola and Zilog. The effort—a most interesting one—has produced generally better code, more comparable algorithms and fewer timing inconsistencies, plus strong areas of disagreement over the "proper" interpretation of benchmarks and major differences of opinion over proper coding practices.

During the updating project we also discovered, learned, invented, acquired, relearned or verified beyond a reasonable doubt (take your pick), **The Three Not-So-Golden Rules of Benchmarking:**

- Rule 1—All's fair in love, war and benchmarks.
- Rule 2—Good code is the fastest possible code.
- Rule 3—Conditions, cautions, relevant discussion and even actual code never make it to the bottom line when results are summarized.

It's impossible to get three strong competitors to agree on all aspects of a series of benchmarks. Nevertheless, EDN, Intel, Motorola and Zilog all devoted considerable effort to pointing out and resolving differences or possible errors in the seven tests. Phone calls and Express Mail packages were supplemented with a face-to-face meeting on July 31. One of the most memorable quotes of that meeting (from an IC manufacturer) was, "The history of benchmarks is one of finding ways to cut corners." Anything goes—so long as the required functions are performed and the techniques used aren't specifically forbidden.

In EDN's original benchmark exercise, we kept our guidelines somewhat vague and allowed deviations from the strictest interpretation of the Carnegie-Mellon specifications. Why? Because we wanted the manufacturers to be able to showcase the architectures of their μ Ps to the best advantage. "Microprocessors aren't minicomputers or mainframes," we reasoned, so we gave the contestants more flexibility than Carnegie-Mellon University did in its 1976 tests. To some extent we now regret this decision for two reasons: Because implementations weren't as comparable in the April 1 article as they could have been, and because we experienced major disagreements over the manner in which the benchmarks were implemented.

Benchmark H (Linked-list insertion) illustrates the latter problem. Intel coded this benchmark with data in a 64k-byte space because it thought this a reasonable implementation. Motorola argued that because the 8086 can address 1M bytes, it should use that larger data space. Intel's position, which EDN allowed, held that "this particular implementation demonstrates how to manipulate data that's contained in a single data segment." Subsequently, Motorola recoded its Benchmark H to also operate in a 64k space, reducing its execution time from 153 μ sec (for the 68000's full 16M-byte space) to 121 μ sec for a 64k space.

By contrast, in Benchmark I (Quicksort), Intel chose to demonstrate the use of the 8086's data-segmentation

Even the tightest rules won't eliminate discrepancies

capability to handle large data structures, recognizing that this benchmark's data suite exceeded one segment. However, Intel's code makes each record a segment, taking advantage of the fact that EDN specified records that measure exactly 16 bytes long. Although all three programs require modifications to work with other record lengths, the Intel code may not be optimum for some of those lengths. For example, 17-byte records would be noncontiguous in memory; that is, there would be gaps between each record.

At this point, an important philosophical question arises: Are such code variations in the true spirit of the EDN benchmarks? After all, they do create inequities among the scores, making comparisons somewhat akin to judging peaches and pears. But we couldn't give flexibility to the contestants with one hand, then arbitrarily take it back with the other. **Rule 1** holds. But to minimize confusion or possible misinterpretations, we note the discrepancies in Benchmark I in our data summary.

Go by the book, or go to win?

Rule 2 (Good code is the fastest possible code) should probably have a corollary: "If it works, it's good—by definition." A great many benchmarkers believe in this philosophy, arguing that the benchmark process traditionally implies that you fine tune the code to the maximum extent permitted. At minimum, EDN can attest that this practice makes it extremely difficult to referee benchmark tests.

Here again we have specific examples in mind. First, all of the new code for Benchmark I is optimized to some extent for the data suite that EDN used. Rather than doing comparisons on two records in memory a character at a time, Zilog, Motorola and Intel load the first character into a register, then perform a fast compare. Most of the time this comparison tells the μP whether it should do a sort on this iteration or jump immediately to the next record. This method speeds up execution times for the EDN data, but it might produce slower than optimum times with other data.

Second, also in reference to Benchmark I, Motorola noted that Intel's code makes each record a segment, then quoted from the programming guidelines in *The* 8086 Family User's Manual, 1979 Edition, pg 2-96: "Segment registers should only contain values supplied by the relocation and linkage facilities. Segmentregister values may be used to and from memory, pushed onto the stack and popped from the stack. Segment registers should never be used to hold temporary values, nor should they be altered in any other way."

In rebuttal, Intel argued that "The manual states that this method is not a recommended procedure for general usage. However, if you're constructing a base to a segment, this is a perfectly acceptable technique. You do not want to redefine your segment selector to point to somewhere in the middle of your data segment. You don't, ad hoc, change the segment-register value. In our Benchmark I we do define each record as being its own segment. Therefore, we can use a segment selector to point to the base of every record we are using." Intel further explained, "The technique works, and works well. It's represented within our RMX operating system through the concept of a "Token.' A Token is issued to pass a segment base between tasks and the operating system for access to code or data."

Finally, a disagreement arose over Intel's code for Benchmark A (FIFO interrupt handler), where the memory locations incremented by the interrupt-service routines reside within the code segment. Motorola cried "Foul!" reading from the programming guidelines on pg 2-97 of The 8086 Family User's Manual that "...variable data should not be placed in a code segment ... First, programs are simpler to understand if they are uniformly subdivided into segments of code, data and stack. Second, placing data in a code segment can restrict the segment's position independence. This is because, in general, the segment base address of a data item may be changed, but the offset (displacement) of the data item may not. This means that the entire segment must be moved as a unit to avoid changing the offset of the constant data. If the constant data were located in a data segment or an extra segment, individual procedures within the code segment could be moved independently." Motorola then emphasized, "In quality programming, counters are data and belong in data segments; code belongs in code segments."

In turn, Intel replied that the memory locations incremented by the interrupt-service routines are not code and are never executed. It further stated, "This is a simple implementation that is perfectly acceptable for the 8086. There is no reason why we shouldn't be allowed to demonstrate this capability." Intel also noted, "The point of disagreement here concerns the dummy service routine. This routine isn't relevant to the intent of the benchmark, which is to measure interrupt response time."

These three examples make one very important point: When studying benchmarks, beware of the influence of **Rule 2** and its corollary—the benchmark code may be too specialized to be useful in a general application without modification.

A benchmark is much more than just one number

It should be obvious to you by now that the results of even a single benchmark test are likely to contain many important pieces of information besides the execution time. Yet **Rule 3** reflects a basic truism: Whenever suites of benchmarks are run, winners invariably tend to reduce all of the explanations and cautions—not to mention the many lines of code—down to a few simple comparative performance ratios, perhaps even just one number (obtained by some form of averaging). This practice makes no sense to EDN at all. At best, it's

When faster µPs are built...

Zilog heated up the benchmark race considerably when it introduced a 10-MHz version of its Z8002 at Wescon/81. Motorola added fuel to the fire by announcing a 12-MHz 68000.

As the April 1 article pointed out, faster chips decrease execution times. Thus, it's definitely in the best interests of each manufacturer to claim the availability of a "hot" µP. But you can easily see that the fire could be just smoke if the announced product exists only in the form of a promised future

BENCHMARK TIMES FOR FASTER µP VERSIONS

	EXECUTION TIME (µs					
BENCHMARK	10-MHz Z8002	12-MHz 68000				
Α	26	26.7				
В	225	268				
E	114	187.9				
F	74	58				
н	122	100.8				
Ι.,	13,300	14,456				
к	338	305				

mask shrink or in a nearly empty selection bin at the end of a busy production line.

EDN has attempted to verify that both the 10-MHz Z8002 and 12-MHz 68000 are "real." We have obtained data sheets and have asked for-and receivedwritten assurances that sample quantities of both machines are now available on distributors' shelves. Thus, we feel obliged to include in this article the improved benchmark execution times that these two chips deliver (table).

misrepresentative and overly simplified; at worst, it's grossly misleading.

In the April 1 article, we tried to discourage such interpretations by breaking the individual benchmark results into small tables, rather than combining them into one summary table. We scattered these individual results throughout the explanatory text, giving each its own caption and explanatory notes. Nevertheless, reports of our results focused only on execution-time data, ignoring all of our caveats.

Taking the philosophical view that Rule 3 is unbreakable, we have summarized all of our revised and

updated benchmark data in expanded tabular form. This table includes columns headed CLOCK SPEED. MEMORY SPACE ADDRESSED and COMMENTS: note this data carefully; we doubt that you will see it repeated elsewhere.

Finally, for those of you who are looking for some rather interesting reading, albeit with a rather dry dialog, we have included all of the code that has changed since the April 1 article. To the best of our knowledge this code is thoroughly debugged; however, time constraints have prevented us from thoroughly checking it. EDN

BENCHMARK	μP	CLOCK SPEED	CODE BYTES*	MEMORY SPACE ADDRESSED	EXECUTION TIME*	COMMENTS
A I/O INTERRUPT KERNEL	8086	10 MHz	24	1M BYTES	46.4 µsec	PROGRAM MAINTAINS, WITHIN THE 64k BYTES OF CODE, THE MEMORY LOCATIONS TO BE INCREMENTED BY THE INTERRUPT-SERVICE ROUTINES THIS TECHNICIJE. IS NOT RECOMMENDED FOR CONERAL USE
KENNEL	68000 Z8002	10 MHz 6 MHz	24 18	16M BYTES 64k BYTES	32 μsec 42 μsec	THIS LEGINIQUE IS NOT RECOMMENDED FOR GENERAL USE.
B I/O KERNEL WITH FIFO PROCESSING	8086 68000 Z8002	10 MHz 10 MHz 6 MHz	185 130 124	1M BYTES 16M BYTES 64k BYTES	402 μsec 321.6 μsec 375 μsec	
E CHARACTER-STRING SEARCH	8086 8086 Z8002	10 MHz 10 MHz 6 MHz	44 44 66	1M BYTES 16M BYTES 64k BYTES	211 μsec 225.2 μsec 190.4 μsec	NEW DATA, SO NEW EXECUTION TIME. NEW DATA, SO NEW EXECUTION TIME.
F BIT SET, RESET, TEST	8086 68000 Z8002	10 MHz 10 MHz 6 MHz	42 36 44	1M BYTES 16M BYTES 64k BYTES	119 μsec 69.6 μsec 124 μsec	
H LINKED-LIST INSERTION	8086 68000	10 MHz 10 MHz	115 100	64k BYTES 64k BYTES	210 µsec 121 µsec	THIS IMPLEMENTATION DEMONSTRATES HOW TO MANIPULATE DATA THAT'S CONTAINED IN A SINGLE 64k SEGMENT. THIS BENCHMARK WAS RECODED TO RUN IN 64k, THE FIRST AND LAST 32 OF THE MEMORY SPACE. CODED FOR A 16M-BYTE SPACE, IT TAKES 106 CODE BYTES AND EXECUTES IN 153 (1990)
	Z8002	6 MHz	84	64k BYTES	203 µsec	
I QUICKSORT	8086	10 MHz	276	1M BYTES	38,254 µsec	CODE IS OPTIMIZED FOR 16-BYTE RECORDS ONLY. USES PROGRAM TECH- NIQUES NOT RECOMMENDED IN 8086 FAMILY USER'S MANUAL.
	68000 Z8002	10 MHz 6 MHz	276 334	16M BYTES 64k BYTES	17,348 μsec 22,211 μsec	
K BIT-MATRIX	8086	10 MHz	95	1M BYTES	523 µsec	SUBROUTINE WILL FAIL IF THE BIT MATRIX RESIDES ABOVE A BYTE DISPLACEMENT OF 8k IN A DATA SEGMENT.
TRANSPORTATION	68000 Z8002	10 MHz 6 MHz	74 106	16M BYTES 64k BYTES	366.2 µsec 563 µsec	

N THE BOX, "WHEN FASTER µPs ARE BUILT ...

Consider ALL the relevant data before naming a victor in EDN's updated benchmark tests. Note in particular the memory space addressed by each machine in each test and the comments relating to some of the code-they could be critically important to your application. Observe also that Zilog benchmarked the Z8002 rather than the segmented Z8001.

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Background photo A computer-enhanced coronagraph displays the multicolored Afro of the normally invisible outer corona of the sun. Photo courtesy Marshall Space Flight Center



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0018	C70608004A00	R	52		MOV	TYP2OFF, OFFSET (ISR2)
0024	C7060C005000	R	54		MOV	TYP3OFF, OFFSET(ISR3)
002A	C7060E00	R	55 56		MOV	TYP3SEG, CODE	¥
0030	BAFCFF BB0100		57		MOV	DX, OFFFCH	; START TIMING COUNTER
0036	EF		59		OUT	DX, AX	
0037	CDOO		60 61		INT	0	; ; SIMULATE TYPE O INTERRUPT
0039	B80000		62		MOV	AX, OH	; STOP TIMING COUNTER
0030	EF		64		OUT	DX, AX	
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003E	2EFF065600	R	77 78	; ISRO:	INC	CS: COUNTO	; INCREMENT COUNT FOR INTERRUPT O
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0049	CF		83		IRE I		
004A 004F	2EFF065A00 CF	R	84 85	ISR2:	INC IRET	CS: COUNT2	; INCREMENT COUNT FOR INTERRUPT 2
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BENCHMARK A-8086 (continued)

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		18	;	HAS BE	EN INTEL'	'S INTERPRETATION OF THE REQUESTED TEST SUITE.
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		23	;			
		24 25	; THIS R	OUTINE A	SSUMES AN	N 8259A PIC PROGRAMMED IN THE AUTOMATIC END
26 ; 32 THRO 27 ; FIFO AN 28 ; INTERRUF				0UGH 35	HEX. THE	E ROUTINE QUEUES I/O INTERRUPTS IN A 128 WORD
				PTS OF EACH TYPE. EACH I/O HAS ITS OWN 16 BIT COUNT REGISTER.		
		29				한 이 것이 안 하는 것이 같은 것이 같이 같이 가지 않는 것이 같이 했다.
		31	i	REGIST	ER USAGE:	AX = TEMPORARY
		33	;			BX = FIFO OUT POINTER DI = DEVICE ID
		34	1			DS = QUEUE DATA SEGMENT
		36	,			
		37 38	1	THIS I FOR TH	MPLEMENTA E DUMMY I	ATION ASSUMES THE COUNTING RECISTERS
		39	1	THE SA	ME DATA S	SEGMENT AS THE QUEUE.
		41	,	THE QU	EUE AND I	INTERRUPT SERVICE ROUTINES MAY BE LOCATED
		42 43	1	ANYWHE	RE IN THE	E 8086'S 1 MEGABYTE ADDRESS SPACE.
		44	FOUNTE	0		
		45	, EQUATE			
0000		47 48	DEV32		EQU	
0004		49	DEV34	ID	EQU	04H
OOFF		51	DEV35_ DN	10	EQU	OGH OFFH
		52 53				
0090		54	INTR_POINTERS	000 00	SEGMENT	т
0000	- 0	56		URG 32	8:4	Charles March 19
0080 0000	R	57 58	TYPE_3 TYPE 3	2 3		DEV32_INTR DEV33_INTR
0088 4E00	R	59	TYPE_3	4	DD	DEV34_INTR
0000 / 000	Pr.	61	IYPE_3	2	DD	DEA35 INIK
ana ana ana		62 63	INTR_POINTERS		ENDS	
		64				
		65 66				

				BENCH	MARK B-808	6 (con	tinued)	
			57	DATA		SEGMENT	WORD PU	JBLIC 'DATA'
0000	(128 0000		68 69		QUEUE	DW	128 DUP(0));I/O FIFO AREA
0100	00 (5)		70		RUNFLAG	DB	2 DUP(0)	RUNFLAG
0102) ????		71		QUEUE_IN	DW	?	POINTER TO NEXT QUEUE ENTRY
0104	(4 0000)		72		INTR_COUNTERS	DW	4 DUP(0)	; I/O INTERRUPT COUNTERS
			73	DATA		ENDS		
			75					
			76	CODE	SEGMENT	PARA	PUBLIC 'C	ODE '
			78		ASSUME US: CODE:	US: DATA		
			79					
0000	50		80		DEV32_INTR	PROC FAR	2	CAUE DEGICILOC
0001	50		82		PUSH	AX		, SAVE REGISTERS
0002	57		83		PUSH	DI		
0003	1E		84		PUSH	DS		
0004	BF0000		86	7	MOV	DI, DEV32	2 ID	LOAD DEVICE ID
			87	į				
0007 000A	BB BEDB	R	88 89		MOV MOV	AX, SEG (DS, AX	QUEUE	LOAD DATA SEGMENT ADDRESS
000C 000F	A10201 8808	R	91 92		MOV MOV	AX, QUEUE BX, AX	E_IN	GET POINTER 10 THE NEXT FIFD ENTRY.
0011	893F		93	j	MOV	EBX1, DI		PUT 1/0 ID IN THE FIFO.
0013	0402		95		ADD	AL, 2		ADJUST FIFO INPUT POINTER.
0015	A30201	R	96		MOV	QUEUE_IM	N, AX	SAVE UPDATED QUEUE_IN PNTR.
0018	BOFF		98	i	MOV	AL, ON		TUST AND SET THE RUNFLAG
001A	86060001	R	99		XCHG	AL, RUNFL	_AG	
001E	ABFF		100		TEST	AL, ON	NEVT	DO OCOUTOS TUTS INTERDURT
0020	747A		101		JZ	SERVICE.	_NEXT	IF NO OTHERS IN THE QUEUE.
			103	;				
0022	1F		104		POP	DS		RESTORE REGISTERS
0023	58		105		POP	AX		
0025	5B		107		POP	вх		
0026	CF		108		IRET	ENDP		
			110					
0007			111		DEUDO INTO		2	
0027	53		112		PUSH	BX		SAVE REGISTERS
0029	50		114		PUSH	AX		
0029	57		115		PUSH	DI		
UUZA	IC		117	;	1 OGAT	20		
005B	BF0200		118		MOV	DI, DEV3	J_ID	LUAD DEVICE ID
002F	B8	R	120	;	MOV	AX, SEG (QUEUE	LOAD DATA SEGMENT ADDRESS
0031	8ED8	2.0	121		MOV	DS, AX	anna an Francis (1977)	OF THE FIFO
0000			122	;	MOU		E TN	OFT POINTED TO THE NEXT
0033	8808	R	123		MOV	BX, AX	L_114	FIFO ENTRY.
			125	,	NOU	EDV3 DI		DUT TO IN THE FIED
0038	893F 0402		126		ADD	AL, 2		ADJUST FIFO INPUT POINTER.
0030	A30201	R	128		MOV	QUEUE_I	N, AX	; SAVE UPDATED QUEUE_IN PNTR.
0005	DOCE		129	,	MOV			TUST AND SET THE RUNELAG
0041	86060001	R	131		XCHG	AL, RUNFI	LAG	
0045	ABFF		132		TEST	AL, DN	NEVT	OR CEDUICE THIS INTERPURT
0047	/453		133		JZ	SERVICE.		IF NO OTHERS IN THE QUEUE.
0049	1F		136		POP	DS		; RESTORE REGISTERS
004A	5F		137		POP	DI		
004B	58 58		138		POP	BX		
004D	CF		140		IRET			
			141		DEV33_INTR	ENDP		
			143					
004E			144		DEV34_INTR	PROC FAI	R	CAUE DEGISTERS
004E	53 50		145		PUSH	AX		DAVE REGISTERS
2011								

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BENCHMARK B-8086 (continued)

					,	
0050	57		147	PUSH	DI	
0051	1E		148	PUSH	DS	
0052	BF0400		149) MOV	DI DEV34 ID	LOAD DEVICE ID
	2.0100		151	1	D1; DE 034_10	LOND DEVICE TD
0055	B8	R	152	MOV	AX, SEG QUEUE	, LOAD DATA SEGMENT ADDRESS
0058	8ED8		153	MOV	DS, AX	OF THE COED.
005A	A10201	R	154	, MOV	AX, QUEUE IN	GET POINTER TO THE NEXT
005D	SBDS		156	MOV	BX, AX	FIFO ENTRY.
			157	i		
005F	893F		158	MOV	CBX3, DI	, PUT I/O ID IN THE FIFO.
0061	0402		159	ADD	AL, 2	ADJUST FILD INPUT POINTER.
0063	A30201	R	160	MUV	QUEUE_IN, AX	SAVE UPDATED QUEUE_IN PNTR.
0066	BOFF		162	MOV	AL, ON	TEST AND SET THE RUNFLAG
0068	86060001	R	163	XCHG	AL, RUNFLAG	
0060	ABFF		164	TEST	AL . ON	
006E	7420		165	JZ	SERVICE_NEXT	GO SERVICE THIS INTERRUPT
			166			; IF NO OTHERS IN THE QUEUE.
0070	1F		168	, POP	DS	RESTORE REGISTERS
0071	5F		169	POP	DI	
0072	58		170	POP	AX	
0073	5B		171	POP	BX	
00/4	CF		172	IRET	ENDD	
			174	DEV34_INTR	ENDP	
0075			175	DEV35 INTR	PROC FAR	
0075	53		176	PUSH	вх	SAVE REGISTERS
0076	50		177	PUSH	AX	
0077	57		178	PUSH	DI	
00/8	1E		179	PUSH	DS	
0079	BE0600		180	, MOU	DI DEV35 ID	LUAD DEVICE ID
			182	1	017 BE 400_1D	TECHD DEVICE ID.
0070	B8	R	183	MOV	AX, SEG QUEUE	LOAD DATA SEGMENT ADDRESS
007F	8ED8		184	MOV	DS, AX	OF THE FILD.
0081	A10201	P	185) MOLL		
0084	8BD8	R	188	MOV	BY AY	GET PUINTER TO THE NEXT
			188	;	20,00	TOTO ENTRY.
0086	893F		189	MOV	EBXJ, DI	PUT 1/0 ID IN THE FIFO
0088	0402		190	ADD	AL, 2	ADJUST FILD INPUT POINTER.
0084	A30201	R	191	MOV	QUEUE_IN, AX	SAVE UPDATED QUEUE_IN PNTR.
0080	BOFF		192	; MOU	AL 051	
008F	86060001	R	194	XCHG		THEST AND SET THE RUNFLAG.
0093	A8FF		195	TEST	AL, ON	
0095	7405		196	JZ	SERVICE_NEXT	GO SERVICE THIS INTERRUPT
			197			IT NO OTHERS IN THE QUEUE.
0097	1F		198	; pnp	nc	
0098	5F		200	POP	DI	RESTORE RECISTERS
0099	58		201	POP	AX	
009A	5B		202	POP	BX	
009B	CF		203	IRET		
			204	DEV35_INTR	ENDP	
			205			
			207			
			208			
0090			209	SERVICE_NEXT	PROC NEAR	
			210	1		
0090	ODOE		211	CONTINUE_SERVIC	CING:	OFF LO ID
009C	FR		212	STI	DI, CBX1	FNARLE INTERRIDIES
			214	011		
			215			
0005			216			
0095	EE050401	D	217	DUMMY_ID_SERVIC	CINC:	
0071	11000401	R	219	INC	INTR_COUNTERSEDED	
00A3			220	RETURN FROM ID	SERVICING	
00A3	FA		221	CLI		DISABLE INTERRUPTS
00A4	800302	-	222	ADD	BL,2	DELETE THIS I/O REQUEST
00A7	3B1E0201	R	223	CMP	BX, QUEUE IN	OD BACK IE MODE I O DEOUTOT
OOAB	/ JEF		225	JNE	CONTINUE_SERVICING	, OU BACK IF MURE 1/U REQUESTS
			226			
OOAD	3300		227	XOR	AX, AX	NO MORE I/O REQUESTS, RESET
OOAF	A20001	R	228	MOV	RUNFLAG, AL	RUNFLAG.
OORD	1F		229	808	DS	
OOBB	5F		231	POP	DI	RESTORE MACHINE STATE
00B4	58		232	POP	AX	

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EDN SEPTEMBER 16, 1981

CIRCLE NO 71

B5 5B	233		POP	вх	
B6 CF	234		IRET		RETURN TO INTERRUPTED PROGRAM
	235				
	236		SERVICE_NEXT	ENDP	
	237				
	238				
	239	CODE	ENDS		
	240				
	241		END		

	BEN	СНМА	RK B-MC68000	
1		O'P T	BRS,FRS	
3	*		MC68000 FDN BENCHMARK	В
5	* * FIF	0 I/0 INT	ERRUPT HANDLER, FOUR I	NTERRUPT LEVELS
7 8 9 0 1 2 3 4	* NOT * * * *	ES: 1) FO PO 2) TH CY AC 3) IN TH	UR INTERRUPT VECTORS A INT TO THE INTERRUPT SE E MC68000 INTERRUPT SE CLES WITH AN ASSUMED I KNOWLEDGE BUS CYCLE OF TERRUPTS ARE TAKEN FRC E MC68000 16 MEGABYTE	ARE ASSUMED TO NTRY POINTS. QUENCE TAKES 44 NTERRUPT - 4 CYCLES. M ANYWHERE IN ADDRESS SPACE.
15 16 17 18	* * *		LINES: 44 BYTES: 130	
9 0 1	* * *	MC68000L1 MC68000L1	0 BENCHMARK TIME: 268 2 BENCHMARK TIME: 224	3.800 MICROSECONDS 4.000 MICROSECONDS
2 3 4 5 6	* REG *	ISTER USE	: AO - ADDRESS POINTE	ER
27 28 29 0 00000000 2F 30 0 00000002 30 31 0 00000006 30 32 0 00000000 54 33 0 000000012 6A 34 0 00000012 6A 35 0 00000014 20 36 0 00000016 4E	* 078008A 08008A 080082 438008B AF8028C A4C 05F E73	INTERRUP MOVE.L MOVE ADD.B TAS BPL MOVE.L RTE	T HANDLERS AO,-(SP) QUEUEIN,AO #COUNTER1,(AO) #2,QUEUUEIN+1 FLAG PROCESS (SP)+,AO	SAVE WORK REGISTER FIND NEXT ENTRY IN QUEUE PLACE COUNTER ADDRESS IN UPDATE TO NEXT QUEUE ENTRY TEST FOR NESTED INTERRUPT BRANCH IF NOT TO PROCESS RESTORE REGISTER RETURN FROM INTERRUPTS
/ 9 0 0000018 2F 9 0 000001A 30 0 0 000001E 30 1 0 0000022 54 2 0 0000022 64 3 0 000002A 6A 4 0 000002A 26 5 0 000002E 4E	F08 INTRPT2 078008A 0BC0084 478008B AF8028C A34 05F E73	MOVE.L MOVE ADD TAS BPL MOVE.L RTE	AO,-(SP) QUEUEIN,AO #COUNTER2,(AO) #2,QUEUEIN+1 FLAG PROCESS (SP)+,AO	SAVE WORK REGISTER FIND NEXT ENTRY IN QUEUE PLACE COUNTER ADDRESS IN UPDATE TO NEXT QUEUE ENTRY TEST FOR NESTED INTERRUPT BRANCH IF NOT TO PROCESS RESTORE REGISTER RETURN FROM INTERRUPTS
6 7 0 0000030 2F 8 0 0000032 30 9 0 0000036 30 0 0 000003A 54 1 0 000003E 4A 2 0 000003E 4A 3 0 0000042 6A 4 0 0000044 2E	F08 INTRPT3 078008A 08C0086 478008B AF8028C A1C 05F E73	MOVE.L MOVE ADD TAS BPL MOVE.L RTE	AO,-(SP) QUEUEIN,AO #COUNTER3,(AO) #2,QUEUEIN+1 FLAG PROCESS (SP)+,AO	SAVE WORK REGISTER FIND NEXT ENTRY IN QUEUE PLACE COUNTER ADDRESS IN UPDATE TO NEXT QUEUE ENTRY TEST FOR NESTED INTERRUPT BRANCH IF NOT TO PROCESS RESTORE REGISTER RETURN FROM INTERRUPTS
35 0 00000048 2F 57 0 00000044 30 58 0 0000004E 30 59 0 00000052 54 50 0 00000056 4A 51 0 00000056 4A 52 0 00000052 54 53 0 00000055 4E 54 0 00000055 4E	F08 INTRPT4 078008A 08C0088 478008B 478028C 404 05F E73	MOVE.L MOVE ADD TAS BPL MOVE.L RTE	AO,-(SP) QUEUEIN,AO #COUNTER4,(AO) #2,QUEUEIN+1 FLAG PROCESS (SP)+,AO	SAVE WORK REGISTER FIND NEXT ENTRY IN QUEUE PLACE COUNTER ADDRESS IN UPDATE TO NEXT QUEUE ENTRY TEST FOR NESTED INTERRUPT BRANCH IF NOT TO PROCESS RESTORE REGISTER RETURN FROM INTERRUPTS
55 66 57 0 00000060 3F 58 0 00000062 46 59	* PROCESS F08 PROCESS 6FC2000	NEXT INT MOVE MOVE	ERRUPT A0,-(SP) #\$2000,SR	SAVE QUEUE LOCATION ON STACK ENABLE INTERRUPTS
70 71 0 00000066 30 72 0 00000068 52 73	* SIMULAT 250	E DEVICE MOVE ADD	HANDLER (AO),AO #1,(AO)	LOAD COUNTER'S ADDRESS INCREMENT IT BY ONE
74 75 0 0000006A 46 76 0 0000006E 54 77 0 00000072 30	* FINISH 6FC2700 42F0001 05F	INTERRUPT MOVE ADD.B MOVE	PROCESSING #\$2700,SR #2,1(SP) (SP)+,A0	DISABLE INTERRUPTS GO TO NEXT ENTRY IN THE QUEUE LOAD ITS ADDRESS

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BENCHMARK B-MC68000 (continued)

78	0	00000074	BOF8008A	
/9	0	00000078	00E0	
00	0	0000007A	42300200	
81	0	0000007E	2056	
02	0	00000080	4E/3	
03				
84	0	00000000	0000	
85	0	00000082	0000	
80	0	00000084	0000	
87	0	00000086	0000	
88	0	00000088	0000	
89				
90				
91	0	A8000000	0080	
92				
93				
94	0	0000008C	00000000	
95				
96				
97	0	00000280	00	
98				
99				

CMP QUEUEIN, AO BNE PROCESS CLR.B FLAG MOVE.L (SP)+,A0 RTE * INTERRUPT COUNTERS COUNTER1 DC COUNTER2 DC COUNTER3 DC 0 0 0 COUNTER4 DC * QUEUE POINTER QUEUEIN DC QUEUE * QUEUE PROPER 256,0 QUEUE DCB * INTERRUPT IN PROGRESS FLAG FLAG DC.B 0

END

TEST END OF LIST PROCESS IT IF NOT SHOW NO ELEMENTS QUEUED RESTORE WORK REGISTER RETURN FROM INTERRUPT

INTERRUPT COUNTER ONE INTERRUPT COUNTER TWO INTERRUPT COUNTER THREE INTERRUPT COUNTER FOUR

NEXT ENTRY TO USE

DEFINE THE QUEUE

INTERRUPT IN PROGRESS INDICATOR

BENCHMARK B-Z8002

		!Example B: I/O Interrupt Ker	cnel, FIFO Processing!
		In this benchmark, the four vectors for interrupts. The diasy chain is irrelevant, a done in the FIFO processing	devices each have unique order of the devices on the as the priority processing is routine.
0000	0.2.771	INTRPTL:	I Come unablight series in t
0000	93FL	LD ADDET OUTIN	1) Addross of port optry 1
0002	0012	ND ADRF1, QUEIN	:Address of next entry :
0006	0D15	LD @ADRPT, #COUNTER1	!Counter adr on queue !
0008	00031		
A000	6801	INCB QUEIN+1,#2	!Update QUEIN to next entry !
000C	10013	TSETB FLAC	Image if negted interrupt 1
0010	0010		itest if nested interrupt :
0012	ED26	JR PL, PROCESS	!No, process current one !
0014	97Fl	POP ADRPT,@SP	!Restore working register !
0016	7800	IRET	!Return from interrupt !
0019	0351	INTRPTZ:	Isawa working register 1
0014	6101	LD ADRPT OUEIN	Address of next entry !
001C	0012	no Abker, goura	.Address of next energy .
OOLE	0D15	LD @ADRPT, #COUNTER2	!Counter adr on queue !
0020	000A		
0022	5801	INCB QUEIN+1,#2	!Update QUEIN to next entry !
0024	0013		
0025	4006	TSETB FLAG	!Test if nested interrupt !
0028	EDIA	TR PL. PROCESS	INO process current one
002C	97F1	POP ADRPT. ASP	Restore working register !
002E	7800	IRET	!Return from interrupt !
		INTRPT3:	
0030	93F1	PUSH @SP, ADRPT	<pre>!Save working register !</pre>
0032	6101	LD ADRPT, QUEIN	!Address of next entry !
0034	0012	LD AADDET #COUNTERS	Counter adr on gueve
0038	0000	DD GRDRET, #COUNTERS	:councer auf on queue :
003A	6801	INCB QUEIN+1,#2	!Update QUEIN to next entry !
003C	0013		a sole sund allere — charactere inder sundpaties. Encontrol es ay
003E	4005	TSETB FLAG	!Test if nested interrupt !
0040	0010		
0042	EDUE	JR PL, PROCESS	No, process current one !
0044	97FL 7B00	LEET	Restore working register :
0040	1000	INTRPT4:	. Reculti from incertape .
0048	93F1	PUSH @SP, ADRPT	!Save working register !
004A	6101	LD ADRPT,QUEIN	!Address of next entry !
004C	0012		
004E	UDL5	LD @ADRPT, #COUNTER4	!Counter adr on queue !
0050	6801	INCB OUEIN+1 #2	Update OUEIN to next entry 1
0054	0013	1000 200100 2012	. opadee gobin to deve entry :
0056	4C05	TSETB FLAG	!Test if nested interrupt !
0058	0010		
005A	ED02	JR PL, PROCESS	!No, process current one !
BENCHMARK B-Z8002 (continued)

0050	97FL	POP ADRPT,@SP	!Restore working register !
005E	7B00	IRET	!Return from interrupt !
	PI	ROCESS:	
0060	93F1	PUSH @SP.ADRPT	Save gueue location !
0062	7C05	EIVI	!Enable interrupts !
0064	2111	LD ADRPT. @ADRPT	!Get counter's adr from queue !
0066	2910	INC @ADRPT	!Increment counter !
0068	7C01	DIVI	!Disable interrupts !
006A	97F1	POP ADRPT. @SP	!Restore last saved ADRPT !
0060	A891	INCB ADRPTL. #2	De-gueue entry !
006E	4B01	CP ADRPT. OUEIN	!End of gueue? !
0070	0012		1
0072	EEF6	JR NE. PROCESS	!No, keep processing !
0074	4C08	CLRB FLAG	!Yes, show no elements queued !
0076	0010		transfer and the subscreamed Articles
0078	97F1	POP ADRPT, @SP	!Restore working register !
007A	7800	IRET	!Return from interrupt !
0070	er	nd KERNEL	

BENCHMARK E-8086

			1	NAME CE	ADCH		
			2	NAME SE	ARCH		
			2	DORDUR	CROUP	DATA	
			3	DGRUUF	GROOF	DUDUTO	(DATA (
			4	DATA	SEGNENT	FUBLIC	DATA
0000	303030303030303030		5	TABLE_S	TART	DB	· 00000000000000000000000 ·
	30303030303030303030303030303030303030)					
001E	30303030303030303030303030303030303030))))	7	S1		DB	\ouddooooooooooooooooooooooooooooooo
0030	303030303030303030	, ,	0	60		DD	(UEDE00000000000000000000000000000000000
0030	48455245303030 303030303030303030 3030303030303)	0	52		DB	HERE00000000000000000000000000000000000
005A	48455245204953 2041204D415443 4830303030303030 3030303030303030 3030	3	9	53		DB	'HERE IS A MATCHOOOOOOOOOOOOOOO
0078	00		10	TABLE E	ND	DB	0
			11				
0079	48455245204953 2041204D415443 48	3	12	STRING	START	DB	'HERE IS A MATCH'
0088	00		13	STRING	END	DB	0
0000	00		14	omino_	12142		
			15 16	; THE D ; IS FO	NATA TABLI	E IS 120 DSITION 6	CHARACTERS IN LENGTH. A PARTIAL MATCH 0. THE ACTUAL MATCH IS IN POSITION 90.
			17				
			19	DATA	ENDS		
			20				
			21	CGRUUP	GRUUP	CUDE.	
			22		ASSUME	CSCCROU	P; DS: DGROUP; ES: DGROUP; SS: DGROUP
			23	PUBLIC	BNCHPRO	G	
			24	CODE	SEGMENT	POBLIC	'CODE'
			25				
0000			26	BNCHPRO	G	PROC	
			27	; SETUP	POINTERS	FOR SEAR	СН
0000	DO	P	20		MOU	AV SEC T	ADIE CTADT EC. DI LE TADIE DTU
0000	0500	R	27		MOU	EC AY	ADLE_START SES DI IS TABLE FIR
0003	BECO		30		MUV	ESI AA	
0005	BF0000	к	31		MUV	DT, UFFSE	I TABLE START
0008	897900	P	32		MOU	CY DEESE	T TARLE END
0008	577000	A	34		ΠUΥ	SATUFF DE	GET START ADDRESS OF SEARCH
			35				TABLE
OOOB	81E90000	R	36		SUB	CX, OFFSE	T TABLE_START
			37				CX IS TABLE LENGTH
			38				
000F	8ED8		39		MOV	DS, AX	DS: SI IS STR_PTR
0011	BE7900	R	40		MOV	SI, OFFSE	T STRING_START
			41				

EDN SEPTEMBER 16, 1981

BENCHMARK E-8086 (continued)

		DLILO			00,000		(4)
0014 BB8800	R	42		MOV	BX, OFFSE	ET STRING	END
0017 81EB7900	R	43		SUB	BX, OFFSE	T STRING	_START
		45					; BX IS STR_LNGTH
		46	CTART		4		
		42) DIARI	THE CLUCK			
001B BAFCFF		49		MOV	DX, OFFFC	сн	; INITIALIZE PORT ADDRESS
001E B80100		50		MOV	AX, 1		CONTROL WORD TO START COUNTER
0021 EF		51		OUT	DX, AX		START COUNTER
		52	TUE	ENCLUMADIZ	DDOCEDU		
		54	; THE BI	ENCHMARK	PROCEDUR	ΥC.	
		55					
		56	;		EDN BENG	CHMARK FO	R IAPX 86
		57	;		CHARACTE	ER SEARCH	
		58	1				
		59	,	ASSUMPT	TONS: 1 1		A FOR SPOH NOTH
		61	1	Haadiii I	10140. 1 4	AND MINLN	GTH (SRCHLNGTH)MINLNGTH)
		62	;		2 F	PARAMETER	S ARE PASSED IN RECISTERS AS FULLOWS
		63	i				ES: DI TABLE_PTR
		64	;				DS: SI STR_PTR
		65	;				CX TABLE_LNG1H
		66	1			THE LOCAT	TON OF THE STRING IS DETURNED IN DI
		68	;		4 1	WORKING R	EGISTERS (AX & DX) ARE PUSHED
		69	22.			AND POPPE	D
		70	;				
		71	;				
		72	CALE		CTEDC		
0022 50		73	SAVE W	PUSH	AX		
0023 52		75		PUSH	DX		
0024 51		76		PUSH	CX		SAVE LENGTH
0025 FC		77		CLD			
0026 BA04		78		MOV	AL, [SI]		LOAD FIRST CHAR
0028 2BCB		79		SOB	CX, BX		FLENGTH DIFFERENCE
002A 41		81	FIND M	ATCH TO I	EIRST CH	ARACTER	PUSSIBLE SEARCH CHONT
		82	/1 1112 11	inten ie i	i inor on		
002B		83	TRYNXT				
002B F2		84	REPNE	SCASB			SCAN WHILE NOT EQUAL
002C AE		05					
002D /406		85	NOTEND	JE	MAICH1		JUMP UN MATCH
0032 EB1790		87	NOTENO.	JMP	DONE		EXIT
		88					
		89	FIRST	CHARACTE	R MATCH H	HAS BEEN	FOUND
		90	; COMPARI	E THE RE	ST OF THE	E STRING	
		91	MATCHIA	MOU	DV CV		CAUE DOCCTOLE CEADOUL COUNT
0037 57		72	MAICHI	PUSH	DI		SAVE PUSSIBLE SEARCH COUNT
0038 8BCB		94		MOV	CX, BX		LOAD STR LNGTH
003A 56		95		PUSH	SI		SAVE STR PTR
003B 4F		96		DEC	DI		RETEST FIRST (IN CASE LEN=1)
003C F3		97	REPE	CMPSB			COMPARE STRING
003D A6		00					
		99	DROP TI	ROUGH T	F THE STR	RING DOFS	NOT MATCH OR WHEN
		100	; CX=0	THE ENT	IRE STRIN	NG MATCHE	(5)
		101	× *	3		4	
003E 5E		102		POP	SI		RESTORE STR.PTR
003F 5F		103		POP	DI		RESTORE PLACE IN TABLE
0040 BBCA		104		MUV	CX, DX		RESTURE PUSSIBLE SEARCH COUNT
0044 E3E9		105		JCX7	NOTEND		END OF STRING, NO MATCH
0046 EBE3		107		JMP	TRYNXT		TRY NEXT BYTE IN TABLE
		108					
0048 5F		109	FOUND:	POP	DI		GET TABLE_LENGTH
0049 2BFA		110		SUB	DI, DX		COMPUTE PTR TO STR IN TABLE
		112	RESTOR	F RECIST	FRS		
		113	ALCO UR				
004B 5A		114	DONE	POP	DX		
004C 58		115		POP	AX		
0040 03		116		DET			DETUDN TO CALL THE DOUT THE
0040 03		11/	BNCHPPD	REI G ENDP			FRETURN TU CALLING ROUTINE
		119	District RO				
		120	CODE	ENDS			
		121					
		122		END			

			E	BENCHMARK	K F-8086
	1	i	CARNE	GIE-MELLON BENCHM	1ARK SERIES [F]
	2 53	; ;	BIT T	EST, SET, OR RESE	T FOR 8086
	45	; SEGA	SEGME	NT	2. FS SECA. SC SECA
	7	1	HUDON	E CO. DECRI DO. DECR	
	8	;	THREE	PARAMETERS ARE F	ASSED TO THE ROUTINE IN THE FOLLOWING REGISTERS:
	10	,	A1=P0	INTER TO BIT STRI	ING IN REG. BX
	11	;	N=NUM F=FUN	BER OF ADDRESSED	BIT (OC=NC=1000) IN REG. CX
	13	;	1 1 0,4		
	14 15	1 1	IT IS THE O	ASSUMED THAT THE RIGINAL BIT STATE	E BIT ARRAY IS LOCATED WITHIN THE CURRENT DS REG. E (O DR 1) IS RETURNED IN REG. AX
	18	; BENCHF	PROC		
0000	18		PUSH	SI	WILL BE USED FOR ARRAY ACCESSING
0000 00	20	;	PUSH		IF FUNCTION CODE MUST BE RETURNED UNALTERED
0001 0001	21		MOV	AX, CX	;LOAD BIT ADDRESS FOR FIELD SEPARATION
0003 D1F8	22		SAR	AX, 1 AX, 1	SHIFT RIGHT ONE BIT WITH ZERO FILL
0005 D1F8	24		SAR	AX, 1	
0007 D1F8	25		MOV	SI, AX	STORE ENCOMPASSING BYTE ADDRESS IN INDEX REG.
000B 80E107	26		MOV	AL, [BX][SI]	ACCESS SI'TH ELEMENT OF ARRAY BX (BIT STRING)
000E 8A00	28		ROR	AL, CL	;ROTATE LOW BYTE CIRCULARLY BY (CL) BITS
0010 0508	29	;	BIT T	O BE TESTED ALTER	RED NOW IN USB OF REGISTER A
	31	i i	511 1		
0012 4A	32		DEC	DX	;REDUCE FUNCTION CODE TO 0 (=SET) OR 1 (=RESET)
0013 4A	34		CMP	DX, 1	; CHECK BOUNDS OF ARGUMENT (NO ACTION IF >1)
0014 83FA01	35		JA	NOCHANGE	SAUE DIT BATTERN FOR LATER USE AS RETURN CODE
0019 BAE0	36		OR	AL, 1	FORCE ADDRESSED BIT (STILL IN AL) SET
001B 0C01	38		XOR	AL, DL	COMPLEMENT BIT TO O IF FUNCTION CODE = RESET
001F D2C0	39		ROL	AL, CL	REALIGN ORIGINAL DATA BYLE WITH MUDIFIED BIT
0021 8800	41		MOV	AL, AH	RESTORE ADDRESSED BIT TO LSB OR AL
0023 BAC4 0025	42	NOCHANG	E	AX 0001H	MACK TRRELEVENT BITS SO RETURN CODE = 0 OR 1
0025 250100	43	;	POP	DX	RESTORE FUNCTION CODE IF REQUIRED
	45	i	POP	CX	RESTORE ACCESSED BIT ADDRESS IF REQUIRED
0028 5E	46		RET	51	RESTORE REGISTER USED FOR MARAT ELEMENT ACCESS
0029 C3	48	j			
	50	; ;	ENDP		
	53	i	TEOT		
	54		IESI :	SEQUENCE FUR ABOV	E ROOTINE.
002A BB7F0090	56		MOV	BX, OFFSET T_AR	
002E B90A00	57		MOV	CX, 10 DX, 1	FUNCTION CODE = TEST
0034 E8C9FF	59		CALL	BENCHE	
0037 B90B00	60		MOV	CX, 11 DX, 1	; BIT NUMBER = 11 ; FUNCTION CODE = TEST
003D EBCOFF	62		CALL	BENCHF	
0040 897800	63		MOV	CX, 123	; BIT NUMBER = 123 ; FUNCTION CODE = TUST
0043 BA0100 0046 E8B7EE	65		CALL	BENCHF	
0049 B90A00	66		MOV	CX, 10	BIT NUMBER = 10
004C BA0200	67		CALL	DX, 2 BENCHF	FONCTION CODE = 3ET
0052 390800	69		MOV	CX, 11	BIT NUMBER = 11
0055 BA0200	70		CALL	DX,2 BENCHE	; FUNCTION CODE = 34 :
005B B97B00	72		MOV	CX, 123	BIT NUMBER = 123
005E BA0200	73		MOV	DX, 2 BENCHE	;FUNCTION CODE = SET
0061 E89CFF 0064 B90A00	75		MOV	CX, 10	; BIT NUMBER = 10
0067 BA0300	76		MOV	DX, 3	; FUNCTION CODE = RESET
006A E893FF 006D B90B00	78		MOV	CX, 11	BIT NUMBER = 11
0070 BA0300	79		MOV	DX, 3	; FUNCTION CODE = RESET
0073 E88AFF 0076 B97800	80		MOV	CX, 123	BIT NUMBER = 123
0079 BA0300	82		MOV	DX, 3	; FUNCTION CODE = RESET
007C E881FF	83 84	;	CALL	BENCHE	
	85	;	TEST	DATA STRUCTURE FO	DR BIT ARRAY:
	86	i			

		BENC	HMARK F-	8086 (continu	ed)
007F (125 AA		87	T_ARRAY DB	125 DUP(1010101	OB)
,		88	;		
		90 90	;		
		91	END		
			BENCHMA	RK H-8086	
	1 ;	CARNEG	IE-MELLON BEN	CHMARK SERIES [H]	
	2;	LINKED	LIST INSERTI	ON FOR 8086	
	4 ; 5 SEGA 6	SEGMEN	IT CS: SEGA, DS: S	EGA, ES: SEGA, SS: SEG	GA
	7; 8;	TWO PA	RAMETERS ARE	PASSED TO THE SUB	ROUTINE IN THE FOLLOWING REGISTERS:
	9; 10;	BX=POI	NTER TO LIST	COMMAND BLOCK:	HEAD (2-BYTE POINTER)
	11 ;				TAIL (2-BYTE POINTER) NUMENT (2 BYTES)
	13 ; 14 ; 15 ;	DI=POI	NTER TO NEW R	ECORD TO INSERT:	KEY (32-BIT SIGNED VALUE) NFXT (2-BYTE POINTER) PKEY (2-BYTE POINTER)
	16 ; 17 ; 18 ;	IT IS ARE AL	ASSUMED THE C L IN THE ACTI	URRENT LIST, CONTI VE DATA SEGMENT	ROL BLOCK, AND NEW DATA
	19 ; 20 CONTRI	L STRUC		CONTROL BLO	CK STRUCTURE
0000	21 HEAD	DW	?	FIRST WORD	DF CONTROL BLOCK = LIST HEAD
0004	23 NUMEN 24 CONTRO	DW DL ENDS	?	; THIRD WORD	NUMBER OF ENTRIES IN LIST
	25 ; 26 ENTRY	STRUC		; DEFINITION	DF EACH ENTRY DATA STRUCTURE
0000	27 KEY_LI 28 KEY_H		?	; FIRST WORD (; SECOND WORD	DF RECORD = LOW ORDER DATA = HIGHORDER DATA
0004	29 NEXT	DW	?	; THIRD WORD	= NEXT RECORD POINTER
	31 ENTRY	ENDS	1	FOORTH WORD	- PREVIDOS RECORD FOINTER
REG	32 ; 33 NEW	EQU	DI	POINTER TO	RECORD TO BE INGERTED
REG REG	34 LIST_ 35 PRESE	B EQU	BX SI	; POSITION OF ; POSITION IN	LIST CONTROL BLOCK SEGMENT OF RECORD BEING TESTED
0000	36 ; 37 BENCH				
0000 50	38	PUSH	AX	REGISTER WI	LL BE USED FOR KEY(HIGH) COMPARISON
0002 51	40	PUSH	CX	USED TO COU	NT CYCLES THROUGH KEY TEST SEQUENCE
0003 56	41	PUSH	SI	REGISTER WI	LL BE USED FOR RECORD ACCESSING
0004 BB4F04	43	MOV	CX, ELIST_CB	1. NUMENT + LOA	D COUNT OF RECORDS IN LIST
	44 ; 45 ;	INITIA	LIZE LIST ENT	RY AND CONTROL BL	OCK IF LIST EMPTY:
0007 E35A	46 ; 47	JCXZ	EMPTY	VER	IFY THAT RECORD LIST NOT EMPTY
	48 ;	LIGT	NOT EMPTY SO	INITIAL ITE PEOLET	FRS FOR KEY TEST SEQUENCE
0000 000-	50			1111110L12E RE9131	END FOR RET TEST SEQUENCE.
0009 8837 0008 FF4704	52	INC	WORD PTR (ST_CB1. HEAD ; POI IST CB1. NUMENT	NT TO FIRST RECORD
000E 884502	53	MOV	AX, ENEWJ. KE	Y_HI ;LOA	D HIGH-ORDER PORTION OF NEW KEY
0013 EB03	55	JMP	SHORT TSTKE	Y LOA	D LUW-ORDER PORTION
0015 8B7404	56 ; 57 LNKNX	T: MOV	PRESENT, LPR	ESENT]. NEXT ; FOL	LOW LINK TO NEXT RECORD
	58 ; 59 ;	COMPAR	REV DE NEW	RECORD WITH KEY O	
	60	WHILE	NEW. KEY >= PR	ESENT. KEY & PRESE	NT. NEXT>O DO PRESENT: =PRESENT. NEXT;
0018 3B4402	62 TSTKE	Y: CMP	AX, [PRESENT	J. KEY_HI ; PER	FORM SIGNED-COMPARE OF HIGH WORD
001B 7F06 001D 7C06	63 64	JG	DONCHK	BRA	NCH IF NEWKEY <current key<="" th=""></current>
001F 3B14	65	CMP	DX, LPRESENT	J. KEY_LO ; PER	FORM UNSIGNED-COMPARE OF LOW WORD
0021 7202 0023 E2F0	67 DONCH	CB K: LOOP	LNKNXT	; BRA ; REP	NCH IF NEWKEY>CURRENT KEY EAT LOOP IF NOT AT END OF LIST
0025	68 ; 69 INSER	T:			
	70 ;	AT THI	IS POINT, THE	CONTENTS OF CX IN	DICATE HOW TEST LOOP WAS EXITED
· ·	72 ;	(CX=0	IF NEW. KEY >=	PRESENT. KEY, CX>	O IF NEW. KEY < PRESENT. KEY)

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The light heavyweight

BENCHMARK H-8086 (continued)

		73	;	IF PRES	ENT. PREV = 0 AND NEW. KEY	< PRESENT. KEY THEN "NEW LIST HEAD"
0025	3300	74	;	YOR	AY. AY	CLEAR AN REGISTER
0027	384406	76		CMP	AX. [PRESENT] PREV	CLEAR AN REGISTER
002A	750F	77		JNZ	ELSE1	BRANCH AHEAD IF PRESENT PREV > 0
0020	E30D	78		JCXZ	ELSE1	; OR IF NEW. KEY >= PRESENT. KEY
		79	;	THOSE T		
		80	,	INSERT	NEW AT HEAD UP LIST	
002E	893F	82	,	MOV	LIST CBL HEAD, NEW	
0030	894506	83		MOV	[NEW]. PREV, AX	NOTE THAT AX=0
0033	897006	84		MOV	[PRESENT]. PREV, NEW	
0036	897504	85		MOV	[NEW]. NEXT, PRESENT	
0039	EB23	86		JMP-	SHORT LST_RET	
003B		88	FLSE1			
0000		89	;	IF NEW.	KEY >= PRESENT. KEY THEN	"NEW LIST TAIL"
		90	;			
003B	OBC9	91		OR	CX, CX	; TEST CONTENTS OF CX
003D	750E	92		JNZ	ELSE2	BRANCH AHEAD IF CX>0
		94	,	INSERT	AT TALL OF LIST	
		95	;	Indent		
003F	897004	96		MOV	[PRESENT]. NEXT, NEW	
0042	897F02	97		MOV	[LIST_CB]. TAIL, NEW	
0045	894504	98		MOV	[NEW]. NEXT, AX	; NOTE AX=0
0048	677306 FR11	100			CUOPT I ST PET	
0010		101	;	U.I.	SHOKT LOT_KET	
004D		102	ELSE2:			
		103	;	INSERT	IN MIDDLE:	
0040	007504	104	;			
0040	884404	105		MOV	AY [DECENT] DECU	
0053	894506	107		MOV	[NEW], PREV, AX	
0056	897006	108		MOV	[PRESENT]. PREV, NEW	
		109	;			
		110	;	BACK UP	AND LINK WITH PREDECESS	OR:
0059	BREO	111	;	MOU	PRESENT AV	AV LOADED WITH PRESENT PREV ABOVE
005B	897004	113		MOV	[PRESENT], NEXT, NEW	TAX LUADED WITH PRESENT. PREV ABOVE
		114	;			
005E		115	LST_RET:			
005E	5E	116		POP	SI	
0056	54	117		PUP		
0061	58	119		POP	AX	
0062	CЭ	120		RET		
		121	1			
0063	893F	122	EMPTY:	MOV	LIST_CBJ HEAD, NEW	
0065	FF4704	123		INC	WORD PTR LLIST CRI NUME	NT
006B	894D04-	125		MOV	[NEW], NEXT, CX	CLEAR POINTER FIELDS (NOTE CX=0)
006E	894D06	126		MOV	[NEW]. PREV, CX	
0071	EBEB	127		JMP	LST_RET	
		128	; RENCHH	ENDO		
		130	BENCHA	ENDP		
		131	; ======	=		
		132 +1	\$EJECT			
0073	90	133		EVEN	; ALIGN	DATA ON WORD BOUNDARIES
		134	,	DATA CT		
		136	;	SHIE OF	NOTIONED AVAILABLE TO TE	ST ABOVE ALGORITANT
0074	????	137	TBLOCK	DW	?	
0076	7777	138		DW	?	
0078	0000	139		DW	0	
0074	4523	141	TREC 1	DW	2345H	
0070	0100	142	INCO_1	DW	0001H	
007E	????	143		DW	?	
0080	7777	144		DW	?	
0082	0022	145	; TREC O	DU	22001	
0084	0100	147	INEC_E	DW	0001H	
0086	????	148		DW	?	
0088	????	149		DW	?	
0004	4400	150			22441	
0080	0100	151	IREC_3	DW	3344H	
008E	????	153		DW	?	
0090	????	154		DW	?	
		155	;			
0092	4523	156	TREC_4	DW	2345H	
	() 1 () ()			LW	00010	
0096	2222	158		DW	?	

BENCHMARK H-8086 (continued)

0098 ????	159		DW	?
	160	;		
009A 2641	161	TREC 5	DW	4126H
0090 0300	162	_	DW	0003H
009E ????	163		DW	?
00A0 ????	164		DW	?
	165	;		
	166	;	TEST	SEQUENCE TO VERIFY ABOVE ALGORITHM:
	167	;		
00A2 BB7400	168	TEST_H:	MOV	BX, OFFSET TBLOCK
00A5 BF7A00	169		MOV	DI, OFFSET TREC_1
00A8 E855FF	170		CALL	BENCHH
00AB BF8200	171		MOV	DI, OFFSET TREC 2
OOAE E84FFF	172		CALL	BENCHH
OOB1 BF8A00	173		MOV	DI, OFFSET TREC 3
00B4 E849FF	174		CALL	BENCHH
00B7 BF9200	175		MOV	DI, OFFSET TREC 4
OOBA E843FF	176		CALL	BENCHH
OOBD BF9A00	177		MOV	DI, OFFSET TREC_5
00C0 EB3DFF	178		CALL	BENCHH
OOC3 EBFE	179		JMP	\$
	180	;		
	181	SEGA	ENDS	
	182	;		
	183		END	

BENCHMARK H-MC68000

1			OPT BRS
23			*
4			* MC68000 EDN BENCHMARK H
5 6			* LINKED LIST INSERTION (SHORT ADDRESSES)
7			*
8			* ATTRIBUTES: * 64K BYTES ADDRESSING RANGE * * POSITION INDEPENDENT
.0			* * REENTRANT
2			* * NO REWRITE NEEDED FOR DIFFERENT ADDRESSING * RANGE SINCE THE MC68000 HAS NO CUMBERSOME
3			* SEGMENT HANDLING REQUIREMENTS
.4			* * INPUT: AD - LIST CONTROL BLOCK
6			* A1 - NEW LIST ENTRY POINTER
.7			* OUTPUT: THE NEW ENTRY IS PROPERLY CHAINED IN THE LINK
.9 20			* ALL OTHER REGISTERS ARE TRANSPARENT OVER THIS ROUTINE
21			* IINES+ 33
3			* BYTES: 100
24			<pre>* MC68000110 BENCHMARK TIME: 121.000 MICROSECONDS</pre>
26			* MC68000L12 BENCHMARK TIME: 100.833 MICROSECONDS
27			*
29			
30		0000004	* DEFINITION OF LIST CONTROL BLOCK NUMENTRY FOUL 4 COUNT OF ENTRIES
32		00000002	TAIL EQU 2 CURRENT TAIL
33		00000000	HEAD EQU O CURRENT HEAD
35			* DEFINITION OF LIST ENTRY
36		00000006	NEXT FOUL 4 NEXT ENTRY IN CHAIN
88		00000000	KEY EQU O 32 BIT BINARY KEY
10			* LIST INSERT SUBROUTINE
1 0	00000000	4A680004	INSERT TST NUMENTRY (A0.) TEST IF LIST IS EMPTY
12 0	00000004	0000	BNE NUIEMPIT BRANCH IF NUI
14	00000000	2000	* LIST IS EMPTY - START IT UP
6 0	00000008	3009	MOVE A1, (AO)+ SET FIRST TAIL
17 0	A000000A	5250	ADD #1, (AO) INCREMENT ENTRY COUNT
19 0	0000000C 00000010	42A90004 4E75	CLR.L NEXT(AL) CLEAR NEW.NEXT AND PREV RTS RETURN TO CALLER
51			* REGISTER USAGE:
2			* DO - NEW KEY VALUE AO - LISTCB POINTER
53			 * D1 - NEXT CURRENT A1 - NEW ENTRY POINTER * A2 - CURRENT ENTRY POINTER
55 56 0	00000012	48470020	NOTEMPTY MOVEM DO/D1/A2(SP) SAVE WORK REGISTERS
57 0	00000016	52680004	ADD #1,NUMENTRY(AO) INCREMENT ENTRY COUNT
SQ 0	0000001A	2011	MOVE.L KEY(A1),DO LOAD NEW KEY

BENCHMARK H-MC68000 (continued)

59 (00000010	3450		MOVE	HEAD(AO),A2	START LIST SCAN
60 (0000001E	B092		CMP.L	KEY(A2),DO	TEST IF IN VERY FRONT
61 (00000020	6C1A		BGE	SEARCH	BRANCH IF NOT NEW FIRST
62						
63			* ADD TO	VERY BEGI	INNING	
64 (00000022	3089		MOVE	A1.HEAD(A0)	SET NEW HEAD
65 (00000024	35490006		MOVE	A1, PREV(A2)	OLDFIRST.PREV TO NEW
66 (00000028	334A0004		MOVE	A2.NEXT(A1)	SET NEW.NEXT TO OLD FIRST
67 (00000020	42690006		CLR	PREV(A1)	ZERO NEW.PREV
68 (00000030	602C		BRA	FINISH	GO FINISH UP
69						
70			* ADD TO	TAIL END		
71 (00000032	31490002	ADDEND	MOVE	A1 TAIL(A0)	NEW ENTRY IS NOW TAIL
72 1	00000036	23440004		MOVE	A2 NEXT(A1)	SET NEW NEXT ZERO AND NEW PREV
73 1	00000034	601F		RRA	FINISHI	GO FINISH UP
74	0000000A	UUIL		DICK	1 INTONE	
75			* SFARCH	FOR CORRE	ECT PLACEMENT	
76 1	0000030	32240004	SEADCH	MOVE	NEYT(A2) D1	TO NEXT LIST ENTRY ADDRESS
77	000000000	6750	JEARON	BEO	ADDEND	ADD NEW TO END IE NO MORE
70	00000040	2441		MOVE		DEADY NEW CURDENT DOINTED
70	00000042	D002		CMP	VEV(A2) DO	TEST TE DEVOND KEV VALUE
90	0 00000044	6052		DCF.L	SEADCH	LOOD TE ODEATED OD EOUNI
91	00000040	0674		DUL	SEARCH	LUOP IF GREATER OR EQUAL
01			* THEFOT		C DEFORE CUORENT ENTRY	
02	0 00000040	22440004	~ INSERI	IN MIDDLI	A2 NEVT (A1)	SET NEW NEXT TO CURRENT
03	0 00000048	334A0004		MOVE	AZ, NEXT(AI)	SET NEW.NEXT TO CORRENT
84	0 00000040	336A00060006		MOVE	PREV(AZ), PREV(AI)	SET CURRENT EARLIER TO NEW.PREV
85	0 00000052	35490006		MOVE	AI, PREV(AZ)	SET CURREN.PREV TO NEW
86	0 00000056	34690006		MOVE	PREV(AI), A2	LOAD CURRENT EARLIER ADDRESS
87	0 0000005A	35490004	FINISHL	MOVE	AI,NEXI(A2)	SET EARLIER.NEXT TO NEW
88						
89			* RESTOR	E REGISTE	RS AND RETURN	
90	0 0000005E	4C9F0403	FINISH	MOVEM	(SP)+,D0/D1/A2	RESTORE REGISTERS
91	0 00000062	4E75		RTS		RETURN TO CALLER
92						
93				END		

BENC	НМА	RK H	I-Z8002)
------	-----	------	---------	---

BENC	HMARK_H module
!Exa	mple H Insertion in a doubly linked list.
	CALL INSERT with the following arguments: R5 = Pointer to List Control'Block R4 = Pointer to element to be inserted
1	
cons	tant
	HEAD := 0 ! Structure of list control block ! TAIL := 2 NUM := 4
	KEYI := 0 ! Structure of each entry ! NEXT := 4 PREV := 6
	KEY := RRO ! Register allocation ! NEXTAD := R2 PREVAD := R3
	NEWENTRY := R4 ! Address of element to be linked ! LISTCB := R5 ! Address of list control block ! SP := R15
91ob 0000 \$rel entr	al INSERT procedure 0 v
0000 91F0 0002 91F2	PUSHL @SP,RR0 ! Save work registers ! PUSHL @SP,RR2
0004 8333 0006 4D54 0008 0004	SUB PREVAD, PREVAD ! Clear back ptr. ! TEST NUM(LISTCB) ! Check for first entry !
000A EE05	JR NZ, NOTFIRST
000C 8322 000E 2F54 0010 6F54	SUB NEXTAD, NEXTAD ! Clear forward ptr. ! LD @LISTCB, NEWENTRY! Set head in LCB ! LD TALL(LISTCB), NEWENTRY ! Set tail in LCB !
0012 0002 0014 E818	JR UPNEW
NOTE	IRST.
0016 1440	LDL KEY, @NEWENTRY ! Get the new key !
0018 2152	LD NEXTAD, @LISTCB ! Start scan at head !

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BENCHMARK H-Z8002 (continued)

		SCAN:		
001A	1020		CPL	KEY,@NEXTAD ! Compare keys !
001C	E906		JR	GE, TRYNEXT
001E	8D34		TEST	PREVAD
0020	EEOE		JR	NZ, UPMID
0022	2F54		LD	@LISTCB, NEWENTRY
0024	6F24		LD	PREV (NEXTAD), NEWENTRY
0026	0006			
0028	E80E		JR	UPNEW
		TRYNEXT		
002A	A123		T.D.	PREVAD.NEXTAD ! Goto next in the list !
0020	6132		L.D	NEXTAD, NEXT (PREVAD)
002C	0004		ШО	ABA (ID) ABA (I ABA ID)
0030	8024		TEST	NEXTAD ! At tail ? !
0032	EEF3		JR	NZ.SCAN
0034	6F34		LD	NEXT (PREVAD) . NEWENTRY
0035	0004			
0038	6F54		LD	TAIL(LISTCB), NEWENTRY
003A	0002			
003C	E804		JR	UPNEW
		UPMID:		
003E	6F24	ornib.	T.D	PREV (NEXTAD) . NEWENTRY
0040	0006		30	
0040	6F34		L.D	NEXT (PREVAD), NEWENTRY
0042	0004		10	
		UDNEW.		
0016	6950	OF NEW.	TNC	NUM(LISTCR) Undate count field in LCB
0040	0004		INC	Non(Distes) : Opdate count rieta in des :
0045	5042		LDL	NEXT (NEWENTRY) BR2 Set ptrs in new entry
0040	0004		0.00	ADAT (ADADATAT), ARE . See Sets in new energy
004C	9572		POPL	RP2 ASP Restore registers
0050	9550		POPL	RRO ASP
0052	9510		DET	KKO, SSE
0052	91300		KD1	
0054		end INS	ERT	
		and DEM	CUMARK U	
		end priv	Cumatin II	

		BEN	CHMAR	K I-8086			
	1		name	test_benchmark_I			
	2	i i					
	3	i	For th	ne EDN algorithm and d	ata:		
	4	1					
	5	; 27.	6 bytes	38.254 msec with 80	86-1 at 10	Mh 2 O	wait
	6	;					
	7	code	segner	nt public 'code'			
	6		assume	e cs:code			
	9	;					
	10	; De	fine local	i values for records			
	11	1					
0007	12	key_length	equ	7			
E000	13	key_offset	equ	3			
0010	14	record_size	equ	16			
	15	1					
	16	; Qu	icksort fi	unction			
	17	;					
	18	; Fo	ur paramet	ters are passed in the	registers		
	19	i					
	20	, n	number	of elements O < N <=	10000	C X	
	21	; rec	pointe	er to start of record	series	ds	
	22	i m	transf	er point to insertion	sort	b x	
	23	;					
	24	; A11	registers	are transparent excep	t for the	lags.	
	25	;					
	26	; De	fine abbre	viations commonly use	d .		
	27	7					
8000	28	word_rec_siz	e equ	8			
OOFF	29	largest_key	equ	Offh			
	30	,					
	31	, 1h	e followir	ng local variables are	initialize	ed and	restored
	32	, with	pushes an	nd pops			
	33	j					
COOAE 3	34	rec ptr	equ	word ptr [bp+10]	; Save	area	for rec pt
000CE3	35	n	equ	rec ptr+2	; Save	area	for n
000E[]	36	m	equ	n+2	i Save	area	for m
-0010[]	37	temp area	equ	bute ptr [bp-record	sizel		ra unapóliti dell's
	38	;	- 1 -	- , - , , ,			

BENCHMARK I-8086 (continued)

		39	;	Start	; of sort	function	
0000		40	1				
0000		41	dnick"e	ort	proc	far	
0000 5	55	43		push	bo		; Establish stark addressibilitu
0001 5	53	44		push	bx		; Set m in local area
0002 5	51	45		push	C X		; Set n in local area
0003 1	E	46		push	ds		; Set rec_ptr in local area
0004 5	50	48		push	ax		: Save working registers
0005 5	52	49		push	dx		, save working registers
0006 5	56	50		push	si		
0007 5	7	51		push	di		
0008 0	BEC	52		push	es bo co		· Identify have of some and
		54		110 V	nh, 2h		, identify base of save area
000B E	BCDB	55		mov	bx,ds		; Form . re((O)
000D 4	3	56		inc	bх		i bx = .ret(1)
0010 0	309	57		vom bbc	dx, bx		$j dx_1 = .rec(1)$
0012 4	·B	59		dec	bx, cx		r = rec(N)
0013 3	300	60		XOT	ax, ax		; Indicate empty r,l save stack
0015 5	0	61		push	ax		; Will be popped before insertion sort
		62	,	Outon	loop of	avisheant before	the inclusion and
		64	,	Docer	1000 04	doicksone before	the insertion sort.
		65	;	Regis	ter usage	e :	
		66	i				
		67	;	1	dx	Note: r >= 1 +	m
		68	,	г	DX	rec(1-1)	$\leq rec(1) \leq rec(r+1)$ for $1 \leq 1 \leq r$
0016		70	outer 1	000:			
		71					
0016 5	5	72		push	bp		; Save stack base
0017 5	3	73		push	bx		; Save r for later ; Famm , c will in by
0019 8	BEA	75		mov	bp, dx		; Set i =]
001B		76	restart	_i_loop:			
001B B	80600	77		mov	ax, key_]	length-1	
001E 8	EC2	78		mov	es,dx		i es = .ret(1)
		80	,	Skip	over left	t part of subfile	
		81	;	P		· part at source	
		82	;	Registe	r usage:		
		83	,		es = 55		
		85	1		р ру	. rec(1)	
		86	;		ax	length-1 of key	
		87	;		d x	.rec(1)	
		88	,		ij	is pushed on sta	ck holding either 1 or J
0020		89	; i loon:				
0020 4	5	91	1_1000	inc	bp		; i = i+1
0021 8	EDD	92		mov	ds, bp		i ds = . re((i)
0023 B	E0300	93		mov	si, key_c	offset	
0028 4	BFE 4	94		mo∨ const	d1,51		; Set office for V ; Look at Sivet byte of Lou
0029 7	2F5	96		ib	i 1000		, LUOK at First byte of Key
002B 7	706	97		ja	j_loop		
		98					
002D 8	BCB	99		mov	cx, ax		; Else examine the rest of the key
0030 A	6	100	repe	cmpso			, compare rectif - rectif
0031 7	2ED	101		Jb	1_100p		; Continue while rec(1) - rec(1)
		102	7				
		103	i	Assert:	i 🖙 j	€S = . T €	c : 1)
		105	,	Skip	over rigt	nt part of subfil	e.
		106	;	Registe	rs same a	as before except	ax,ds = .rec(j).
0033		107	<i>i</i> 				
0033 4	B	108	1_100b	der	hx		i i = i-1
0034 8	EDB	110		mov	ds, bx		ds = .rec(j)
0036 B	E0300	111		mov	si, key_c	offset	
0039 8	BFE	112		mav	di, si		; Set offset for V ; look at the first bute of the key
0036 7	7E5	113		cmpsp	1 1000		, LOOK at the first byte of the key
003E 7	205	115		JD	compare	_i	
		116					
0040 8	BCB	117		mov	cx,ax		; Else look at the rest of the key ; Compare rec(1) - rec(1)
0042 F	5	118	тере	cmpsb			, compare rec(j) - rec(i)
0044 7	7ED	119		ja	j_loop		; Continue while rec(j) > rec(l)
		120	;				
		121	;	Assert:	J >= i−1	es = . re	c(1) ds=bx
		166	,				

BENCHMARK I-8086 (continued)

		123	1	Comp	are j and i for	swap test.	
0046		124	,	i			
0046	3354	125	compare_	YOF	ci. ci		Prenare for exchange of records
0048	BBEE	120		001	51/51 di.si	,	riepare for exchange of feetier
0040	890800	128		mov	cx, word rec si	ize ;	Get word size of a record
004D	3BEB	129		cmp	bp, bx		
004F	730E	130		jae	swap_loop2	į	Jump if i >= J
		131					
0051	8EC5	132		mov	es, bp	;	es = .rec(i) ds = .rec(j)
		133	;				
		134	i	Exch	ange rec(i) with	h rec(j).	
and server		135	;				
0053		136	swap_lo	op 1 :			
0053	268805	137		mov	ax, es: Ldij		
0056	8/04	138		xcng	LSIJJAX		Rump course pointer
0058	40	137		inc	51	<i>.</i>	bomp source pointer
0054	40	140		stosw	51		Auto hump of destination pointer
0058	F2F6	142		1000	swan loon1		
		143					
005D	EBBC	144		Imp	restart i loop	p i	Continue preorder loop
		145	;	• •			
		146	;	Save	subfile defini	tions on the	e stack area.
		147	;	But fi	rst exchange rea	c(1) with re	ec(j).
		148	1				
005F		149	swap_lo	op2:			
005F	268B05	150		mov	ax,es:[di]		
0062	8704	151		xchg	[si],ax		
0064	46	152		100	51		Bump source pointer
0065	40	153		inc	51		Auto humo of destination pointon
0068	FOFA	154		loop	swap loop2		Auto bump of descination pointer
0007	2210	156		1000	smap_roops		
		157	;	Assert	ds, bx = rec(1)	
		158	;		dx/es = .rec()	1)	
		159	;				
		160	;	Comp	are the subfile	sizes of j	-l and r-j to determine the
		161	;	the ne	xt subfile to se	ort. Note:	Subfiles do not include j!
		162	;				
0069	8BC3	163		mov	ax, bx		s Save j
006B	5B	164		pop	bx	1	Get bx=r
0060	8BF3	165		mov	si, bx	1	si, bx = 1
006E	2BE0	166		SUD	51, ax	i	51 = r-j
0070	BBFB	140		mov	di, ax	1	
0072	2DFA 5D	160		500	01, 0x		; ol = j~j . Destass stask sidessins
0075	SBAFOF	170		mov	ор с х . п		Restore stack addressing
0070	ODTEVE	171	i	ino t	C X / 10		
		172	;	Regi	ster usage:		
		173	;	_	dx, es . rec ()	1)	
		174	;		bx .rec(1	r)	
		175	i		ax .rec(J) ·	
		176	;		cx m		
		177	;		si subfi	le size of 1	r – j
		1/8	i		di subfi	le size of	J-1
0079	2050	1/9	,	6.000	di cu		
0074	7700	181		La	ul bt m		lump if in 1 5 m
0078	//00	182		19	J1_00_m		00mp 14 J-1 > m
0070	3BF1	183		cmp	si,cx		
007E	771A	184		ja	set new l		Jump if r-1 > m
		185	;				
		186	,	Both	subfile sizes	C= m.	
		187	;	Get ne	xt r,l pair from	n the stack	if not empty
		188	;				
0080	5B	189		pop	bx	i i	See if the stack is empty
0081	OBDB	190		OT	bx, bx		Fest r value
0083	741B	191		JZ	end_outer	1	; Do insertion sort if empty
		192		Cat	1 and a face the		
		194	,	Stack	and r from the	e stack.	
		195	,	SUALK	ordering is rai	15 15	
0085	5A	196		pop	d x		Get 1 from stark
0086	EBBE	197		Jmp	outer loop	,	
		198	,		and the second sec		
		199	;	J−1	> m, See if r-j	> m	
		200	;		,		
0088		201	jl_bt_m				
0088	3BF1	202		cmp	Si, CX	i	Compare r-j with m
008A	7606	203		Jbe	set_new_r	i.	; Jump if r~j <= m
		204	,	C			
		205		bee	which subfile is	s largest, l	both are larger than m
0090	BREE	207	,	cmp	di. si		Company with service
008F	7208	208		ib	stack li		compare j~i with t∽j compare j~i with t∽j
JUUL				9 -			

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BENCHMARK I-8086 (continued)

	209	;			
	210	;	Push	lower and upper limits	of j-l, (the larger subfile).
	211	;	Stack	ordering is: Tolorolo	
0090 52	212	,	nush	d x	: Stark 1 : 1
0091 50	214		push	ax	; Stack r = 1
0092	215	set_new_	_r:		
0092 8BD8	216		mov	bx, ax	; Set new r ≔ j-1
0094 4B	217		dec	bx	; l remains same
0095 E97EFF	218		Jmp	outer_loop	
	219	;	D		
	220	,	Push	lower and upper limits	of r-j, (the larger subfile).
0099	222	, stark 1	12		
0098 52	223	Journa	push	dx	; Stack 1 = 1
0099 50	224		push	ax	; Stack r = j
009A	225	set_new_	1:		•
009A BBDO	226		mov	dx,ax	; Set l as j+l
0090 42	227		inc	dx	; r remains same
009D E976FF	228		Jmp	outer_loop	
	229	;	0 6		the action around enter
	230	,	Ferre	orm an insertion sort on	the entire record array.
0000	232	end out	PT :		
00A0 83EC10	233	c	sub	sp, record size	; Allocate space for temp
00A3 885E0C	234		mov	bx, n	; Get original array length
00A6 035E0A	235		add	bx, rec_ptr	; Form i = .rec(n)
00A9	236	enter_la	ast_loop	p :	
00A9 B80600	237		mov	ax, key_length-1	; Set key length
00AC BA0300	238		mov	dx, key_offset	; Set key offset
	239	1	N-L-		
	240		Note	DX = 1 + 1	
OOAF	242	last loo	n n ·		
OOAF 4B	243		dec	bx	; Form i = i - 1
OOBO 385EOA	244		cmp	bx, rec ptr	; Test for .rec(0) implying i = 0
00B3 7653	245		jbe	done	
	246				
OOB5 8EDB	247		mov	ds, bx	; ds = .rec(i)
00B7 43	248		inc	bx	
OOB8 SEC3	249		mov	es, bx	; es = .rec(i+1)
OOBA 48	250		dec	bx	; Restore i
OOBD BBF2	251		mov	51, 0X	; Set source and destination offset
OOBE A6	253		consh	u1, ux	: Company let butos of kous
00C0 72ED	254		ib	last loop	, compare ist bytes of keys
00C2 7706	255		18	move down	
	256				
00C4 8BC8	257		mov	cx,ax	; Examine rest of key
00C6 F3	258	тере	cmpsb		; Compare rec(i) - rec(i+1)
00C7 A6					
00C8 72E5	259		JÞ	last_loop	; Loop while rec(i) < rec(i+1)
	260		Maria		
	201		nove	the entire subfile down	one element until a record >= rec(1)
	263	, ,	15 7001	iu.	
OOCA	264	move dou	un:		
00CA B80800	265		mov	ax, word rec size	; Get word count of a record
00CD 53	266		push	bx	; Save i
OOCE 8CD2	267		mov	d x , 5 5	; Save rec(i)
OODO BEC2	268		mov	es, dx	
00D2 8D7EF0	269		lea	di,temp_area	; Set address of temp area
0005 33F6	270		XOT	51,51	
0009 53	2/1		mov	cx, ax	; Set move count
OODA A5	2/2	rep	movsw		v = rec(1)
OODB BEC3	273		mov	es, bx	; 1-1 becomes i in by
	274		ind v	23/07	, j'i becomes i in bx
	275	;	Use e	s = ds = .rec(1-1)	
	276	;	Assert:	d x=55	
	277	;			
OODD	278	mo∨e_dow	m_loop:		
0000 051000	279				
00E0 33EE	280		mov	si, record_size	; s1 is offset for rec(j)
00E2 8BC8	282		X OT	u1, 01 CY. 3Y	; oi is offiset for rec(j-1) ; Set move length
00E4 F3	283	Ten	movsw	LA, di	; per move length ; per (1-1) = per (1)
00E5 A5	200	i e p			/ (EC() I) - PRC()/
	284	;			
	285	,	Note:	si is offset for rec(j-	-1) now.
	286	;			
00E6 43	287		inc	b x	; j ≕ j + 1
00E7 8EC2	288		mov	es, dx	; es:di = .v
00E9 8D7EF3	289		lea	di,temp_area+key_offse	; Set address of temp area
OOEC 830603	290		add	si, key_offset	; si has offset for rec(j) key
OUEF \$90700	291		mov	cx, key_length	; Set size of compare string

			BEN	CHM	ARK I-8086 (c	ontinue	d)
00F2 F3 00F3 A6		292	тере	cmpsb		į	Compare rec(j) with v
OOF4 BEC3		293		mov	es, bx	, , ,	Set new base address
00F8 8EDB		294 295		ma∨ ıb	ds,bx move down loop	j.	Continue while rec() < v
		296	;	5-			
		297	;	Сору	v to rec(old j).		
OOFA 33FF		299	,	XOT	di, di	;	Set offset to rec(j-1)
OOFC BEDA		300		mov	ds,dx	;	Get address of v in ds:si
0101 BBC8		302		mov	cx,ax	;	Set move length
0103 F3 0104 A5		303	тер	movsw		;	тес(ј-1) ∷ ∨
0105 5B		304		рор	b x	i	Restore i
0106 EBA1		305		Jmp	enter_last_loop		
		308	;	A11	done, restore req	isters.	
0100		308	1				
0108 8BE5		309	done:	mov	so, bo	;	Clear stack area
010A 07		311		pop	es		
010B 5F		312		pop	di		
010D 5A		314		рор	d x		
010E 58		315		рор	аx		
010F 1F		316		рор	ds	;	Restore rec ptr
0110 59		318		рор	C X	į	Restore n
0111 5B 0112 5D		319		pop	b x b p	;	Restore m
0113 CB		321		ret			
		322	auick s	ort	endo		
		324 +1	\$eject	0.0	c nup		
		325	;	Defi	no EDN data chara	stanistics	
		327	;	Dell			
0064		328	n_value		equ 100		
0007		330	i varoe		equ /		
		331	1	Defi	ne local stack ar	еа.	
		333	stack		segment		
0000 (96		334			dw 96 dup	(?)	; I,R values are saved here
)							
0000		335	stack_t	op	label word ends		; Start of stack area
		337	;		LING S		
		338	1	Defi	ne local data are	Э.	
		340	data		segment		
0000 (1632		341			db (n_valu	e+2)∦recor	d_size dup (?)
>							
		342	data		ends		
		344	;	Main	line function to	initialize	memory, invoke sort, and
		345	1	test r	esult.		
0114		347	, start				
0114 B8	R	348		mov	ax, stack	j	Setup stack space
0119 BCC000		350		mov	sp, offset stack	top	
O11C FB		351		sti		;	Allow debugging interrupts
		353	;	Run	the benchmark		
0110		354	; 				
011D B8	R	355	restart	mov	ax, data	;	Get start of data segment
0120 8ED8		357		mov	ds, ax		
0124 33FF		358		xor	es,ax di,di	;	Clear starting address
0126 8BC7		360		mov	ax, di	;	Clear initial value
0129 396006		361		mov	cx,record_size*	; (n_value+2); Zero out all the entries
012C F3		363	тер	stosb			
VIED HM		364	;				
		365		Init	ialize all the da	ta entries	in reverse order.
012E BOFF		367		mov	al,Offh	;	Largest key entry
0130 B96400		368		mov	cx, n_value	i	Set loop count
0136		370	init_lo	op:	ari Lecolo"2ris	,	rorm address or FIFSt entry

BENCHMARK I-8086 (continued)

0136	8805		371		mo∨	[di],al	;	Set flag entry
0138	884503		372		mov	[di+key offset],al	;	Set first bute of keu
013B	48		373		dec	ax	;	Bump to next lowest key
0130	830710		374		add	di, record size	;	Go to next record
0100	5055		275		1000	init loop		aa aa muxe ruucra
UISF	LEFU		375		1000	1010_1000		
			370	,	Sot	last element in annau to	0 1 21	raest kan nossible
			370	,	260	rast erement in allay t	0 14	gest key pussible.
0141	000700		370	,	add	di kou offrot		Point at key entry
0141	830703		3/7		auu	cr key length	<i>.</i>	Cot lopath of key
0144	B90700		380		mov	cx, key_rengen	,	Lengen ut key
0147	BOFF		381		mov	al, largesc_key	,	Cat walke
0149	F-3		385	rep	STOSD		,	Set Value
014A	AA							
			383	;				
			384	i	Setu	p registers for function	n par	rameters
			385	;				
014B	B96400		386		mov	cx, n_value	i	Set record count
014E	BB0900		387		mov	bx, m_value	;	Set subfile sort length
			388	;				
			389	;	Ti	me the function with SDI	K-86	counter.
			390	1				
0151	BAFFFF		391		mov	dx, OFFFFH		Initialize counter
0154	B89292		392		max	ax, 9292H		
0157	FF		202		out	dy av		
0150	DAFOFF		204		000			Church another
0158	BAFCFF		374		mov		,	Start counter
0158	880500		395		mov	ax, 2		
015E	EF		396		out	dx, ax		
015F	B80100		397		mov	ax, 1		
0162	EF		398		ðut	dx, ax	;	Go!
			399					
0163	9A0000	R	400		call	far ptr quick_sort	;	Do the benchmark
			401					
0168	3300		402		XOT	ax, ax	;	Timer stop command
016A	EF		403		out	dx, ax	1	Stop timer'
			404				<i>.</i>	oop oint.
			405		Calc	ulate the elapsed time	in c	locks
			406		COIL	blate the elapsed time	111 6	IUCKS
01/0	DACOCC		400	,				
0165	BAF 7FF		407		mo∨	ax, OFFF9H	;	Get counter value
OIGE	ED		408		in	ax, dx	;	Read bits 31-24
016	SAF 8		409		mo∨	bh, al	;	Save value
01/1	BAF8FF		410		mov	dx, OFFF8H		
0174	ED		411		in	ax, dx	;	Read bits 23-16
0175	8AD8		412		mov	bl,al		
0177	BAFBFF		413		mo∨	dx, OFFFBH		
017A	ED		414		in	ax, dx	;	Read bits 15-8
017B	BACB		415		mov	clal		
017D	BAFAFF		416		mov	dx, OFFEAH		
0180	FD		417		in	ax, dy		Road bits 7-0
0191	PAE 1		A10				,	70 hit sluck sount in dy by
0101	ORDI		410		mov		,	Se bit clock count in ux.ax
0163	0003		417		mov	dx, bx		
			420	j				
			421	;	lest	results to see if ever	ythi	ng is in order
			422	i				
0185	FC		423		cld		;	Autoincrement direction
0186	BB	R	424		mo∨	bx, data)	Get starting address
0189	BD6500		425		mov	bp,n_value+1	;	Set loop count
018C			426	compare	loop:			
0180	SEDB		427		mov	ds, bx	;	Set record addresses
018E	43		428		inc	bx		
018F	8EC3		429		mov	es, bx		
0191	B90700		430		mov	cx, key length		
0194	BE0300		431		mov	si, keu offset		
0197	8BFE		432		mov	di,si		
0199	F'3		433	rene	consh			
0194	AA							
0198	7709		434		1.3	avit		Out of order!
0170	/////		405		Ja	EXIC	,	bot of ofder.
0100	415		430					Task free and
0190	7650		430		dec	p)	,	lest for end
DIAF	/ JEC		43/		Jnz	compare_roop		
	0000		438					
01A0	3309		439		XOT	сх, сх	;	Indicate all is well
01A2	CC		440		int	З	j	All doneenter monitor
01A3	E977FF		441		Jmp	restart	;	Restart benchmark
01A6			442	exit:				
01A6	B9FFFF		443		mov	cx, OFFFFH	;	Indicate misordered items
01A9	CC		444		int	3	;	All doneenter monitor
01AA	E970FF		445		Jmp	restart	į	Restart benchmark
are tracks			446					
			447	code	ends			
			448					
01	14		449		end	start		
	C1 / C1							

BENCHMARK I-MC68000

					DLIN		0000
1					OPT	BRS	
34				*		MC68000 EDN BENCHMARK	I
5 6				*		QUICKSORT	
7 8 9				* ATTRII *	BUTES: *	16 MEGABYTES ADDRESS POSITION INDEPENDENT	RANGE
11 12 13				* * INPUT *	: D0 - " D1 - "	N" RECORD COUNT M" THRESHOLD FOR INSER	TION SORT
14				*	A0 - "	REC" ADDRESS OF THE SO	RT ARRAY
17				* OUTPU *	DECISTS	RE DATA ARRAY IS SURTE	
19 20				* *	. REGISTE	LINES: 93	K INIS KOULINE
22				* * MC68(00110 BF	NCHMARK TIME: 17.348.	200 MICROSECONDS
24 25 26				* MC680 *	000L12 BE	NCHMARK TIME: 14,456.	833 MICROSECONDS
27 28 29 30 31 32			00000010 00000003 00000007	* MISCELI ENTRYLEN KEY KEYLEN	ANEOUS E EQU EQU EQU	QUATES 16 3 7	SORT ENTRY RECORD LENGTH OFFSET TO KEY WITHIN RECORD SORT KEY LENGTH
33 34 35 36 37 38 39 40 41 42		00000000 00000004 00000008 00000008 00000000	48E7FFFE 2400 E988 43F008F0 E989 2C41 48E7A040 42E7	* QUICK	MOVEM.L MOVE.L LSL.L LEA LSL.L MOVE.L MOVE.L CLR.L	QUICKSORT SUBROUTINE D0-D7/A0-A6,-(SP) D0,D2 #4,D0 -ENTRYLEN(A0,D0.L),A1 #4,D1 D1,A6 D0/D2/A1,-(SP) -(SP)	SAVE ALL REGISTERS COPY NUMBER OF RECORDS OVER CALCULATE POINTER TO LAST RECORD A1 <- POINTER TO LAST RECORD = R FIND TOTAL SIZE OF M RECORDS KEEP VALUE IN A6 FOR LATER SAVE DUMMY, COUNT, AND TOP ON STACK MARK SORT STACK EMPTY
43 44 45 46 47 48				* * REGISTI *	ER USE:	QUICKSORT PHASE AO - FIRST RECORD OF S A2/A3 - KEY POINTERS A6 - LENGTH OF "M" REC	UBFILE A1 - LAST RECORD OF SUBFILE A4/A5 - WORK POINTERS ORDS SP - RECURSIVE CALL ARGUMENTS
49 51 52 54 55 55 55 50 61		00000016 000001E 00000022 00000024 00000028 0000002A 0000002E 0000002E 00000022 00000032	45E80003 47E90013 49E80003 1E14 45EA0010 BE12 62F8 650C 2A4A 7006 B90D 56C8FFFC 62FA	SORT LOOP1 LOOP1A CMP1	LEA LEA MOVE.B LEA CMP.B BHI BLO MOVE.L CMP.B DBNE BHI	KEY(AO),A2 ENTRYLEN+KEY(A1),A3 KEY(AO),A4 (A4),D7 ENTRYLEN(A2),A2 (A2),D7 LOOPIA LOOP2 A2,A5 #KEYLEN-1,D0 (A5)+,(A4)+ D0,CMP1 LOOP1A	A2 -> KEY(I) = REC(L) A3 -> KEY(J) = REC(R+1) A4 -> V FOR CURRENT RECORD D0.B = FIRST BYTE OF KEY I <- I+1 COMPARE FIRST KEY BYTE IF REC(I) <v comparing<br="" continue="">IF REC(I)<v direction<br="" other="" scan="">A5 TEMP FOR I D0-LOOP COUNTER COMPARE V-REC(I) LOOP WHILE EQUAL IF REC(I)<v comparing<="" continue="" td=""></v></v></v>
62 63 64 65 66 66 66 66 71 72 73 74 75 77 78 79		0000003A 00000042 00000042 00000042 00000044 00000048 00000048 00000048 00000048 00000044 00000044 00000044 00000044 000000	47EBFFF0 BE13 65F8 620C 2A4B 7006 BB0C 56C8FFFC 62EA B5CB 6436 4CEA000FFFFD 48EB00FFFFD 48EB00FFFFD 48EB00FFFFD 60B0	LOOP2 CMP2 LOOP2A	LEA CMP.B BLO BHI MOVE.L CMP.B DBNE BHI CMP.L BCC MOVEM.L MOVEM.L MOVEM.L BRA	-ENTRYLEN(A3),A3 (A3),D7 LOOP2 LOOP2A A3,A5 #KEYLEN-1,D0 (A4)+,(A5)+ D0,CMP2 LOOP2 A3,A2 END1ST -KEY(A2),D0-D3 -KEY(A2),D4-D7 D0-D3,-KEY(A2) D0-D3,-KEY(A2) LOOP1	J <- J-1 COMPARE FIRST KEY BYTE LOOP WHILE REC(I)>V BRANCH REC(I) <v A5 = TEMP FOR J LOOP COUNTER COMPARE REC(J)-V LOOP WHILE EQUAL IF REC(J)>V CONTINUE COMPARING I >= J BRANCH IF I >= J SWAP . REC(J) . WITH . REC(I) CONTINUE</v
80 81 82 83 84 85 86 87		0000006E 00000070 00000072 00000074 00000076 00000078	B28E 6F08 B481 650A 2F09 2F0B	* DECIDE NEWLRO	SUBFILE CMP.L BLE CMP.L BCS MOVE.L MOVE.L	DIRECTION AG,D1 NEWR D1,D2 STACK1 A1,-(SP) A3,-(SP)	(R-J) <= MSIZE? (R-J) SUBFILE SMALLER? BRANCH IF SO DETERMINE SMALLER SUBFILE BRANCH IF (J-L) IS SMALLER STACK R STACK J (R-J) SUBFILE SMALLER. SET L & R TO
88 89 90 91	0	0000007A 0000007E	43EBFFF0 6096	* NEWR *	L E A B R A	-ENTRYLEN(A3),A1 SORT	LARGER SUBFILE LIMITS R <- J-1, L STAYS THE SAME CONTINUE SORT (J-L) SUBFILE SMALLER, SET L & R TO
92 93 94 95	0 0 0	00000080 00000084 00000088	48E70090 41EB0010 608C	* STACK1 NEWLR1	MOVEM.L LEA BRA	AO/A3,-(SP) ENTRYLEN(A3),AO SORT	LARGER SUBFILE LIMITS PUSH L & J ONTO SORT STACK L <- J+1, R STAYS THE SAME CONTINUE SORT

BENCHMARK I-MC68000 (continued)

96 97 98 99 100 101 102 103 104 105 106 107 108 109 110 111 112 113	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	000008A 000008C 0000094 0000098 0000092 00000092 00000042 000000A2 000000A2 000000A2 000000A2 000000A2 000000A2 000000A2 000000A2	578B 4CD0000F 48D300F0 48D3000F 2209 240B 9282 9488 B48E 62C6 B28E 62D6 B28E 62D8 4CDF0300 2008 6600FF62	* NEW SUF	BFILE FOU SUB.L MOVEM.L MOVEM.L MOVEM.L MOVE.L SUB.L SUB.L CMP.L BHI CMP.L BHI MOVEM.L MOVE.L BNE	ND, NOW DETERMINE NEXT #KEY,A3 (A0),D0-D3 (A3),D4-D7 D0-D3,(A3) D4-D7,(A0) A1,D1 A3,D2 D2,D1 A0,D2 A6,D2 NEWLR0 A6,D2 NEWLR1 (SP)+,A0/A1 A0,D0 SORT	STAGE -KEY TO GET TO BEGINNING OF RECORD SWAP . REC(L) . AND . REC(J) D1 <- R D2 <- J D1 <- R-J D2 <- J-L COMPARE (J-L) <= MSIZE BRANCH IF NO COMPARE (R-J) <= MSIZE BRANCH IF NO POP NEXT L AND R FROM STACK TEST IF STACK IS EMPTY CONTINUE SORT IF NOT EMPTY
115				* FALL II	NTO INSER	TION SORT AS ALL SUBFI	LES BELOW OR EQUAL M RECORDS
117				*		INSERTION SORT PH	ASE
118 119 120 121 122 123 124				* REGIS * * * *	TER USE:	DO - LOOP CONTROL DI - COUNTER AND SWAP D2/D4 - SWAP REGISTER D5/D7 - "V" SAVE REGI	AO - REC(I) REGISTER A1 - REC(J) S A2/A3 - WORK REGISTERS STERS A4 - REC(J-1) A5 - "V" SAVE REGISTER A6 - FRAME POINTER
125				* N	OTE: STA	ACK SPACE IS RESERVED	FOR "V" KEY COMPARE RECORD COPIES
127				*			
128 129 130 131	0 0 0	000000B6 000000BA 000000BE	4CDF0101 4E56FFF0 5540		MOVEM.L LINK SUB	(SP)+,D0/A0 A6,#-ENTRYLEN #2,D0	RELOAD RECORD COUNT AND TOP RECORD ALLOCATE "V" KEY COPY AREA ON STACK DO RANGES FROM N-2 THROUGH O
132 133 134 135 136 137 138 139	0 0 0 0 0 0	000000000 0000000000000000000000000000	41E8FFF0 45E80003 47E80013 7206 B508 56C9FFFC 6332	LOOPOUT CMPII1	LEA LEA MOVE.L CMP.B DBNE BLS	-ENTRYLEN(A0),A0 KEY(A0),A2 ENTRYLEN+KEY(A0),A3 #KEYLEN-1,D1 (A3)+,(A2)+ D1,CMPII1 ENDIF	I <- I-1 A2 -> KEY(I) A3 -> KEY(I+1) LOOP COUNTER FOR COMPARE COMPARE KEY(I)-KEY(I+1) LOOP WHILE EQUAL BRANCH IF KEY(I) <= KEY(I+1)
140 141 142 143 144	0 0 0	000000006 00000000A 00000000E 0000000E2	4CD020E0 48D700E0 43E80010 2848		MOVEM.L MOVEM.L LEA MOVE.L	(AO),D5-D7/A5 D5-D7,(SP) ENTRYLEN(AO),A1 A0,A4	V <- REC(I) AND ON STACK FOR KEY COMPARE A1 -> REC(J) = REC(I+1) PRIME A4 -> REC(J-1)
145 146 147 148 149 150 151 152 153 154 155		000000E4 000000E8 000000EC 000000F2 000000F2 000000FA 000000FC 000000FE 000000FE	4CD1001E 48D4001E 2849 43E90010 45EF0003 47E90003 7206 B50B 56C9FFFC 62E0	LOOPIN CMPVJ	MOVEM.L MOVEM.L LEA LEA LEA MOVE.L CMP.B DBNE BHI	(A1),D1-D4 D1-D4,(A4) A1,A4 ENTRYLEN(A1),A1 KEY(SP),A2 KEY(A1),A3 #KEYLEN-1,D1 (A3)+,(A2)+ D1,CMPVJ LOOPIN	TEMP <- REC(J) REC(J-1) <- TEMP A4 -> NEXT REC(J-1) J = J+1 A2 -> KEY(V) A3 -> KEY(J) LOOP COUNTER IN D1 COMPARE KEY(V)-KEY(J) LOOP WHILE EQUAL IF KEY(V) > KEY(J) CONTINUE LOOP
157	0	00000104	48D420E0		MOVEM.L	D5-D7/A5,(A4)	REC(J-1) <- V
158 159 160	0	00000108	51C8FFB6	ENDIF	DBRA	D0,L00P0UT	CONTINUE LINEAR INSERT
161 162 163 164 165	0 0 0	0000010C 0000010E 00000112	4E5E 4CDF7FFF 4E75		UNLK MOVEM.L RTS	A6 (SP)+,D0-D7/A0-A6	FREE AND RESTORE STACK RESTORE REGISTERS RETURN TO CALLER
166					END		

BENCHMARK I-Z8002

BENCHMARK I-Z8002 (continued)

	! Inser !Genera	MLEN := Rl4 !Length L := Rl3 !(=REC) R := Rl2 !Right NEWLR := Rl2 !L and KI := Rl1 !Key po KJ := Rl0 !Key po KIJ := Rl0 !I and CNT := R9 !Count Wl := R8 !Work r W2 := R7 VKEY := R6 !Key po VVAL := RH5 !First !(R0 - R7 used for exch tion sort phase: ! I := Rl4 !Pointe JM1 := Rl2 !Pointe JM1 := Rl2 !Pointe UKEY1 := Rl1 LCNT := R9 (as in !W1 := R9 (as in !W2 := R7! !(R0 - R7 used for movi !1 = R10 !Counte SIZE := 16 !Bytes KEY := 3 !Positi ENT	<pre>h (bytes) of M records! Left boundary of range! boundary of range! R as a pair! pinter for REC(J)! J as a pair! register for block operations! registers! biter for REC(V)! byte of VKEY ! hanging items)! er to REC(J)! r to REC(J)! r to REC(J)! r for outer loop! a Quicksort phase)! a Quicksort phase)! a Quicksort phase)! ng items)! per entry! on of key in entry! per key!</pre>
	ITnitia	KEYLEN := 7 !Bytes	per kev!
0000 0000 030F 0002 001E	global	QUICK procedure entry SUB SP,#30	!Save RO - RL4!
0004 1CF9		LDM @SP, R0, #15	
0005 0002 0008 A103 000A AB30 000C 1902		LD R3.N DEC R3 MULT RR2,#ESIZE	!Compute adr of last item!
0010 A13C		LD R,R3	
0012 81DC 0014 A113		ADD R, REC	Compute size of M items!
0016 1902		MULT RR2, #ESIZE	Compute Size of M flems:
0013 0010 001A A13E		LD MLEN B3	
001C 93FC		PUSH @SP,R	!Save top!
001E 93F0 0020 9200 0022 91F0		PUSH @SP,N SUBL RRO,RRO PUSHL @SP,RRO	!Save number of items! !Mark sort stack empty!
0024 94CA	SORT:	LDL KIJ,NEWLR	
0026 A9B2 0028 010A		INC KI, #KEY ADD KI, #KEY+ESIZE	!KI points at key for I! !KI points at key for I!
002A 0013	10000		
002C A1D6	L0050!	LD VKEY.L	!VKEY points at key for pivot!
002E A962		INC VKEY, #KEY	WWAL holds first buts of W kow
0032 A9BF	LOOP1:	INC KI, #ESIZE	!I gets I+l!
0034 0AB5		CPB VVAL, @KI	<pre>!Compare first byte explicitly ! ! REC(I) < V !</pre>
0038 E706		JR ULT, LOOP2	! REC(I) > V !
003A AL68 003C A187		LD W1,VKEY	!WL points at V key! !Copy I for block comparison!
003E BD97		LDK CNT, #KEYLEN	!Count for comparison!
0040 BA86 0042 097E		CPSIRB, @W2, @W1, CNT, NE	!Compare I,V!
0044 E7F6	10000	JR ULT, LOOPL	!REC(I) < V!
0046 ABAF	L0022:	DEC KJ, #ESIZE	IJ gets J-l!
0048 0AA5 004a E7ED		CPB VVAL, @KJ	
004C EB06		JR UGT, LOOP2A	All the state of the state of the
004E A1A7 0050 A168		LD W2,KJ LD W1,VKEY	Set up block comparison!
0052 BD97		LDK CNT, #KEYLEN	1.0
0054 BA75 0056 098E		CPSIRB WUL, WW2, CNT, NE	ICombare V,JI
0058 E7F6	LOOPAL	JR ULT, LOOP2	IV < REC(J)!
005A BBAB 005C EF19	LOOP2A:	JR UGE, ENDIST	!Done if I >= J!
0058 5001	!Exch	ange REC(I), REC(J)!	$\mathbf{P}A = \mathbf{K}\mathbf{F}\mathbf{Y}(\mathbf{K}\mathbf{T}) + \mathbf{A}$
0060 0003		UDM RU, - NEI (KU), #4; LDM	N4, -NDI (N1), #4
0062 FFFD			
0066 0403			
0068 FFFD			

BENCHMARK I-Z8002 (continued) 006A 5CA9 LDM -KEY(KJ), R4, #4; LDM -KEY(KI), R0, #4 006C 0403 006E FFFD 0070 5CB9 0072 0003 0074 FFFD 0076 5CAl LDM R0, ESIZE/2-KEY(KJ), #4; LDM R4, ESIZE/2-KEY(KI), #4 0078 0003 007A 0005 007C 5CB1 007E 0403 0080 0005 0082 5CA9 LDM ESIZE/2-KEY(KJ), R4, #4; LDM ESIZE/2-KEY(KI), R0, #4 0084 0403 0086 0005 0088 5CB9 003A 0003 008C 0005 008E E8CE JR LOOPO !New subfile found - now determine next stage! ENDIST: DEC KJ, #KEY !Exchange REC(J), REC(L)! 0090 ABA2 !Point at REC(J)! 0092 1CA1 LDM R0, 0KJ, #4; LDM R4, 0L, #4 0094 0003 0095 1CD1 0093 0403 009A 1CA9 009C 0403 LDM @KJ,R4,#4; LDM @L,R0,#4 009E 1CD9 00A0 0003 00A2 5CA1 LDM R0, ESIZE/2(KJ), #4; LDM R4, ESIZE/2(L), #4 00A4 0003 00A6 0008 00A3 5CD1 00AA 0403 00AC 0008 00AE 5CA9 LDM ESIZE/2(KJ), R4, #4; LDM ESIZE/2(L), R0, #4 00B0 0403 00B2 0008 00B4 5CD9 00B6 0003 00B8 0008 00BA ALCO LD RO.R !RO gets R-J! 00BC 83A0 SUB RO,KJ OOBE ALAL LD RL.KJ !Rl gets J-L! 0000 9301 SUB R1,L 00C2 8BEL CP R1,MLEN !J-L <= M? ! 00C4 EA05 00C6 8BE0 JR GT, NEWLRO ! No - trv R-J! ! Yes - try R-J! ! R-J > M! CP RO,MLEN 00C8 EA0F JR GT, NEWLRL 1 !Both <= M - pop another range! !Sort stack empty?! 00CA 95FC POPL NEWLR, OSP 00CC 8DC4 00CE EEAA TEST R JR NZ, SORT ! No - continue! ! Yes - do insertion phase! 00D0 E30E JR INSORT !Decide subfile direction! NEWLR0: CP R0,MLEN 00D2 8BE0 !R-J <= M? ! 00D4 E204 JR LE, NEWR ! Yes - right range done! 00D5 8B10 CP RO,RL !R-J <= J-L? ! 00D8 EA05 JR GT, STACKL ! No - left range smaller! 00DA 93FA 00DC 93FC PUSH @SP,KJ ! Yes - right is smaller, stack PUSH @SP,R 00DE ALAC NEWR: LD R,KJ !New range is (L,J-L)! 00E0 ABCF DEC R, #ESIZE 00E2 E8A0 JR SORT 00E4 93FA STACK1: PUSH @SP,KJ !Stack (L, J) range! 00E5 93FD PUSH @SP,L NEWLR1: LD L,KJ INC L,#ESIZE 00E8 A1AD !New range is (J+1,R•! 00EA A9DF 00EC E89B JR SORT !Insertion sort phase! 00EE 97FA INSORT: POP LCNT, @SP DEC LCNT !Saved N, minus 1, becomes !
! outer loop count!
!Saved "R" becomes I! 00F0 ABA0 00F2 97FE POP I,@SP INC I. #KEY !point I at key! 00F4 A9E2 00F6 ABFF DEC SP, #ESIZE !Allocate V on stack! 00F8 AlE7 00FA ABEF OUTLP: LD W2, I !W2 points at KEY(oldI)! DEC I, #ESIZE !I gets I-l! OOFC ALE8 LD Wl,I !Wl points at KEY(newI)! 00FE BD97 LDK CNT, #KEYLEN !Count for key comparison! 0100 BA75 CPSIRB @W1, @W2, CNT, NE !Compare KEY(I), KEY(I+1)! 0102 098E 0104 E7LD JR ULT. ENDIF KEY(I) < KEY(I+1)!0106 5CE1 LDM R0,-KEY(I), #ESIZE/2 !V gets REC(I)! 0108 0007 010A FFFD 010C 1CF9 LDM @SP.R0. #ESIZE/2

BENCHMARK I-Z8002 (continued)

010E	0007			
0110	ALFB		LD VKEYL.SP	<pre>!point VKEY1 at key!</pre>
0112	A9B2		INC VKEY1, #KEY	
0114	ALED		LD J,I	!J gets I+l!
0115	A9DF		INC J, #ESIZE	
0118	ALEC		LD JML, I	!J-l gets I!
011A	5CD1	LOOPIN:	LDM R0, -KEY(J), #ESIZE/2	!REC(J-1) gets REC(J)!
0115	FFFD			
0120	5009		LDM -KEY (TML) DO HESTZE	/2
0122	0007		104 - REI (04L), RO, #ESISE)	
0124	FFFD			
0125	ALDC		LD IML J	J-1 dets II
0128	A9DF		INC J. #ESIZE	J gets J+1!
012A	ALD7		LD W2.J	W2 points at KEY(J)!
012C	ALB8		LD W1.VKEY1	!Wl points at KEY(V)!
012E	BD97		LDK CNT. #KEYLEN	
0130	BAS6		CPSIRB @W2, @W1, CNT, NE	Compare KEY(J), KEY(V) !
0132	097E			
0134	E7F2		JR ULT, LOOPIN	! KEY(V) > KEY(J)!
0136	LCFL	INSRT:	LDM RO, @SP, #ESIZE/2	!REC(J-1) gets V!
0138	0007			
013A	5CC9		LDM -KEY(JM1), RO, #ESIZE,	/2
013C	0007			
013E	FFFD			
0140	FAA5	ENDIF:	DJNZ LCNT, OUTLP	!Keep looping if more!
0142	A9FF		INC SP, #ESIZE	<pre>!Done - give back V allocation!</pre>
0144	lCFl		LDM R0, 9SP, #15	!Restore all registers!
0146	000E			
0148	010F		ADD SP,#30	!Give back register stack space!
014A	001E			
014C	9E08		RET	
014E		end QUIC	СК	
		end QUI	CKSORT	

BENCHMARK K-8086

	1	;	CARNEGIE-MELLON BENCHMARK LKD
	2	;	
	3	;	MATRIX TRANSPOSE FOR 8086
	4	; 1234	5
	5	: 22	XB = X BIT OFFSET X = X OFFSET
	6	3 3	YB = YBIT OFFSEI Y = YOFFSEI
	~	: <u> </u>	
	ó	. 5	5 BO = BIT OBIGIN OF MAIRIX (A2)
	0		5 - b0 = b11 or 10110 or 101110 1027
	10	· LOGIC FOR :	CHARE MATRIX INVERSION:
	4.4	, LOOLG FOR .	EQUIVE TO V = 1 TO V = 1
	4.4	<i>'</i>	
	1.4.	,	
	1.5	,	
	14	;	
	10	;	WHILE (AB NUT ESONE 157 DO
	16	;	SWAP LAB, YBJ
	17	i	XB = XB + N
	18	i	YB = YB + 1
	19	i	t: NJJ
	20	;	END
	21	i	
	22		
	23	NAME	BENCHK
	24	i	
	25	SEGA SEGME	NT AT OIOH
	26	ASSUM	E CS: SEGA, ES: SEGA, DS: SEGA, ES: SEGA
	21	;	
	28		
	29		
	30	; DEFINITION	OF PASSED PARAMETERS:
000000	31	A2 EQU	WORD FIR LBP+121 (BIT OFFSET FOR FIRST MATRIX BIT
000860	32	A1 EQU	DWORD PIR EMP+81 ; ADDRESS FOR FIRST BYTE OF MAIRIX
000651	33	N EQU	WORD PIR LEP+61 ; MAIRIX SIDE SIZE (NXN=TOTAL BITS)
000211	34	RETADR EQU	DWORD PTR EBP+20 (CALLERS RETURN ADDRESS
	35		
	36	: CREATE ERA	ME POINTER TO ADDRESS PARAMETERS
0000 55	37	PUSH	BP SAVE CALLERS BP
0001 8BEC	39	MOV	BP.SP CREATE FRAME FOINTER
	29	: SAVE REGIST	FRS
0003 50	40	PIICH	AY SAVE AY
0004 53	41	prou ·	RY SAVE RY
0005 51	42	PUON PLICE	
0006 52	11.2	phon Dion	
0007 54	1.0	ruon preu	
0009 57	44	DUCH	
	4.0	nuom	NA CHVE NA

BENCHMARK K-8086 (continued)

0009	16	4.4	PUSH	DS.	: CAVE TIC:
0009 000A	C54608	47	LDS	AX, A1	SETUP US REGISTER WITH MATRIX SEGMENT
		48			
0000	*****	49	; RUN X INDEX F	ROM 1 TO N - 1	AN APPENDANT OF AN INC. SALES AND
0010	50	50	MUV LOOPX: PUSH		START MATKIX CULUMN CUUNT (X) SAVE INDEX ON STACK
0011	SEUS	52	MOV	BX, AX	DUPLICATE X FOR Y CALCULATION
0013	F76606	53	MUI	N	; COMPUTE START OF ROW (Y)
0016	034600	54	ADD.	AX, A2	CORRECT FOR MATRIX BIT OFFSET (YB)
0019	035FOC	55	ADD	BX7 A2	CORKECT FOR MATRIX BIT OFFSET (XB)
		57	: SAVE ROW AND	COLUMN BIT POST	LONS
0010	50	58	NEXTBIT: PUSH	AX	; SAVE ROW (YB)
001D	53	59	PUSH	EX	;SAVE COLUMN (XB)
		60	: NEW CALCHEATE	ABSOLUTE ADDRES	SES FOR ATTS INVERSION AND SUDD
		62	7 10000 0010-0000 0111	. HANNING THE PRODUCT	SECTOR HATO INVESSION HAD SWH
		63	GOMPUTE ROW F	HYSICAL ADDRESS,	LOAD BYTE, AND FORM MASK
001E	8AC8	64	MOV	CL. AL	COPY ROW BIT ADDRESS LOW BYTE
0020	SOE107	60 44	ANU. MOU	CLE OZH STE AY	STADING DOW INTO ST
0025	DIEL	67	SHR	SL 1	FIND
0027	D1EE.	68	SHR	SI, 1	; BYTE
0029	DIEE	69	SHR	S1, 1	; ADDRESS
0028	037608	/()	ADDJ MCC	SLEWORD PIR A1	RESOLVE BYTE ADDRESS
0030	D2E4	72	SHL	AFD CL	SET AH HIGH BIT TO DESTRED ONE
0032	80E480	73	ANU	AH, OSOH	; ISOLATE THE BIT
0035	BOZH	74	MOV	AL., ZEH	FREPARE TO MAKE ROW MASK BYTE
0037	D2C8	75	ROR	AL, CL.	SET ALL BUT DESIRED BIT ON
0039	SACE	76	Mav	CL BL	BAVE RUW SELFT VALUE MOVE IN COLUMN LOW ADDRESS BYTE
003D	80E107	78	AND.	CL. 07H	ISOLATE BIT OFFSET
0040	D1EB	79	SHR	BX7 1	JSOLATE THE
0042	DIEB	80	SHR	BX, 1	; COLUMN BIT
0044	035608	82	SHR	BX, WORD PTP A1	; BYTE AUURESS : RESOLVE RYTE ANDRESS
0049	8A37	83	MOV	DH/ LBX1	LOAD OPPOSITE AXIS COLUMN BYTE
004B	D2E6	84	SHI.,	DH7 CL	SHIFT OPPOSITE TO BIT ZERO
0040	80E680	85	AND	DH, SOH	SISTER BIT OF INTEREST
0052	D206	87	ROR	加力プロロ	SET ALL BUD DESIDED DID ON
		88	; NOW AH = ROW	BIT AL = ROW BYT	E MASK CH = ROW BYTE SHIFT COUNT
	-	89	i DH = COL	BIT DE = COL BYT	E MASK CL = COL BYTE SHIFT COUNT
0054	DZEC	90	SHR	AH, CL.	SHIFT BACK COLUMN'S REPLACMENT BIT
0058	DREE	92	SHR	DHACL	SHIFT BACK ROW'S SHIFT COUNT SHIFT BACK ROW'S REPLACEMENT RIT
005A	2017	93	AND	LEXID DL.	FORCE OFF COLUMN BYTE BIT
0050	0827	94	0R	CBX1, AH	; OR IN OPPOSITE AXIS VALUE
005E	2004	95	ANJ	CS10, AL	FORCE OFF ROW BYTE BIT
0060	0654	20	UR	TST P DH	FUR IN COLUMN BYTE BIT VALUE
		98	CONTINUE ROG	AND COLUMN ADVA	NCEMEND TILL DIAGONAL REACHED
0062	58	99	POP)∺X	FRESTORE COLUMN BIT (XB)
0063	58	100	POP	AX	RESTORE ROW BIT (YB)
0067	40	102	1 NC	AX	DUWN TU NEXT CULUMN POSITION
0068	3BC3	103	CMP	AX, HX	REACHED DIAGONAL?
006A	7580	104	UNE:	NE.XTELT	(BRANCH).F MORE RANGE HERE
		105	: LOOD DACK UND	THE V DEACHERS N	
0060	58	107	POP	AX A REHUMES N	RESTORE X INDEX
006D	40	108	1 NC	AX	O NEXT X VALUE
0066	3B4606	109	CMP	AX, N	CHECK AGAINIS MAIRIX SIZE
0071	15500	110	-013	LOOPX	CONTINUE IF STILL BELOW
		112	; FINISHED		
0073	1F	113	POP	DS	RESTORE DS
0074	SF	114	POP	L) I	FESTORE D1
0075	56 - 56	115	POP	51	RESTORE SI
0077	59	117	POP	CX	RESTORE CX
0078	5B	118	POP	БΧ	RESTORE BX
0079	58	119	POP	AX	RESTORE AX
007H	0.3	120	POP	BP.	RESTORE BP
		122	IML I		THE FORMET DEGREE EN
#		123	SEGA ENDS		
		124	C.KIP.		
		120	ENL		

BENCHMARK K-Z8002

MATRI	X module			Т	:=	R4	!temp for bits !
IFram	pla K. Deeler	Matain margaret		TH	:=	RH4	
: DXall	bre v: Boores	an Matrix Transpose!		TL	:=	RL4	
				IJBYTE	:=	RH5	!byte at I,J !
const	ant			JIBYTE	:=	RL5	!byte at J,I !
				BYTES	:=	R5	! combined pair of bytes!
:proc	edure argumer	nts !		IJBX	:=	R6	!index of bit at I,J !
				JIBX	:=	R7	!index of bit at J.I !
N	:= R0	! size of N * N Matrix	1	JBX	:=	RR6	! combined J bit ptrs !
OFF	:= R1	loffset of first bit	1	IJWX	:=	R8	!index of byte at I,J !
A	:= R2	laddress of first word	!	JIWX	:=	R9	!index of byte at J.I !
				JWX	:=	RR8	! combined J byte ptrs !
work	ing registers	s (preserved over call) !		IROW	:=	RLO	!index of bit A[I,1] !
				ICOL	:=	R11	!index of bit A[1,I] !
				IBX	:=	RRLO	! combined I bit ptrs !
				ICNT	:=	R12	!I loop counter (N-I) !
				MASK	:=	R13	!temp for mask bits !
							1. Contract of the second s

!stack pointer !

SP := R15

0000		global	BMTRAN p	rocedure entry		
0000	030F		SUB	SP,#20	<pre>!save registers</pre>	1
0002	0014			-		
0004	1CF9		LDM	@SP,R4,#10		
0006	0409					
		! FOR I	:= 2 TO	N !		
0008	ALOC		LD	ICNT, N	! ICNT := N-1	1
000A	ABCO		DEC	ICNT		
000C	AllB		LD	ICOL, OFF	!I := 1. ICOL := OFF!	
000E	AllA		LD	IROW, OFF	! IROW := OFF!	
		ILOOP:			<pre>!new I value !</pre>	
0010	810A		ADD	IROW, N	!IROW to next row	1
0012	A9B0		INC	ICOL	!ICOL to next col.	1
		! FOR J	:= 1 TO	I-1 !		
0014	94A5		LDL	JBX, IBX	!set inner loop ptrs!	
		JLOOP:			!new J value !	
		! A[I,J	<-> A[J,I] !		
0016	9468		LDL	JWX, JBX	<pre>!compute byte addrs</pre>	1
0018	B381		SRL	IJWX, #3		
001A	FFFD					
001C	B391		SRL	JIWX, #3		
001E	FFFD					
0020	8344		SUB	Ψ.Ψ	Iclear temp for mask!	
0022	2406		SETB	TH. IJBX	!mask bit for IJ	1
0024	0400		0010	111,100.		
0026	8889		CP	XWX. T.TWX	ITT. IT same byte?	1
0028	E60D		JR	EO.SAMELJ	l ves	i
002A	8128		ADD	T.TWX . A		
002C	2085		LDB	LIBYTE . @LIWX	llbad A[I_J]	
002E	8129		ADD	JTWX A	. Louid all 101	
0030	2090		L.DB	TIBYTE . G.TIWX	I Dad A[I.I.] !	
0032	2407		SETR	TT TTBY	Image hit for IT	1
0034	0000		0.510	10,0154	imast bit for of	•
0034	1140		T.D.	MACK	Lagree mark	
0030	0754			MASK, I	isave mask :	
0030	0/04		NORR		lextract bits	•
0034	00C4		AURB	DE NEVEL	Isame (partity even ::	
0030	E4UC		JR	PE,NEATJ	1 Same: none :	
0036	3505		AOR	ATTWY TIDYTE	latere buted	:
0040	2690		UDB TD	CHODELI	iscore oyces :	
0042	0120	CAMPTT.	ADD	STOREIS	I TT and TT in some but	~ 1
0044	2095	SAME IU :	ADD LDD	TTRYME ATTMY	Llosd NIT THE L	e .
0040	2007		CEMP	TUBILE, GIUWA	Image hit for IT	1
0040	2407		3613	1H, J1BA	imask bit Lor Ji	•
004A	0400 A14D		T.D.	MACK	Lanua maak	
0040	OCE A		ANDR	MASK, I	isave mask :	
0046	5034		ANDB	DE NEVUT	lextract fits :	
0050	E402		JR	PE, NEALO	1 Same (partty even) 1	
0052	8905	CHODRTT	XOR	BYTES, MASK	! airretent: thio olds	
0054	2005	STOREIJ	:			
0054	2685		LDB	GIJWX, IJBYTE	store IJ byte !	
0056	A960	NEXTJ:	INC	IJBX	imove I,J across	:
0058	8107		ADD	JIBX,N	!move J, I down	1
005A	8876		CP	IJBX, JIBX	thit diagonal?	1
005C	EEDC		JR	NE, JLOOP	! no: Loop	1
		NEXTI:			istep outer Loop to nex	t 1 !
005E	FCA8		DJNZ	ICNT, ILOOP	dec & test Loop count	+
0050	LCFL		LDM	R4,@SP, #L0	!restore registers	!
0062	0409					
0064	OLUF		ADD	RL5,#20		
0066	0014		DDM		tand to the	
0068	3608	1	RET		:exit !	
006A		ena BMT	KAN			
			DTV			
		ena mar	KIX			

EDN SEPTEMBER 16, 1981

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No.	MHz	Тур.	Min.	Тур.	Max.	Max.	Max.	Each	Qty.
PSCQ-2-1.5	1.4-1.7	29	25	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-3.4	3.0-3.8	30	25	0.4	0.7	3.0	1.2	16.95	(5-49)
PSCQ-2-6.4	5.8-7.0	30	25	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-7.5	7.0-8.0	35	25	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-10.5	9.0-11.0	25	20	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-13	12-14	29	25	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-14	12-16	30	25	0.3	0.6	3.0	1.8	16.95	(5-49)
PSCQ-2-21.4	20-23	30	25	0.4	0.7	3.0	1.2	12.95	(5-49)
PSCQ-2-50	25-50	30	20	0.3	0.7	3.0	1.5	19.95	(5-49)
PSCQ-2-70	40.70	25	20	0.3	0.7	3.0	1.2	19.95	(5-49)
PSCQ-2-90	55-90	30	20	0.3	0.7	3.0	1.2	19.95	(5-49)
PSCQ-2-120	80-120	25	18	0.3	0.7	3.0	1.5	19.95	(5-49)
PSCQ-2-180	120-180	23	15	0.3	0.7	4.0	1.2	19.95	(5-49)
PSCQ-2-250	150-250	23	18	0.4	0.8	4.0	1.5	19.95	(5-49)
PSCQ-2-400	250-400	22	16	0.4	0.9	4.0	1.5	19.95	(5-49)
PSCQ-2-450	350-450	22	16	0.4	0.9	4.0	1.5	19.95	(5-49)
ZSCQ-2-50	25-50	30	20	0.3	0.7	3.0	1.5	39.95	(4-24)
ZSCQ-2-90	55-90	30	20	0.3	0.7	3.0	1.2	39.95	(4-24)
ZSCQ-2-180	120-180	23	15	0.3	0.7	4.0	1.2	39.95	(4-24)
ZMSCQ-2-50	25-50	30	20	0.3	0.7	3.0	1.5	49.95	(4-24)
ZMSCQ-2-90	55-90	30	20	0.3	0.7	3.0	1.2	49.95	(4-24)
ZMSCQ-2-180	120-180	23	15	0.3	0.7	4.0	1.2	49.95	(4-24)
*	alad automatic	. I	JD	Imme	Jamas	O alere all m	adala		

Optocoupler saves battery-backed RAMs

Dan Garcia

Pellerin Milnor Corp, Kenner, LA

When backing up a μ P system's RAMs, you must ensure that the μ P's memories can't be inadvertently selected or undergo a read/write operation when the system's power supply is failing or completely off. This design (**figure**) not only isolates the RAMs from the μ P, it further transient-protects the ICs by using an optocoupler as a mains-failure sensor.

By directly monitoring the mains, this optocoupler provides the additional advantage of allowing you to initiate the RAMs' isolation before the system's supply voltage actually starts failing. The ac line gets rectified and filtered to provide the drive current to the optocoupler's input LED. Thus, so long as an ac line voltage exists, the LED is ON. This condition via the optocoupler's phototransistor—drives the Darlington device ON and grounds the 7407 TTLtype buffer. And when the buffers are ON, the μ P's Chip Select (CS) and Read/Write (R/W) signals get passed to the CMOS RAMs for normal usage.

When an ac-mains power failure occurs, however, the process reverses: The LED's bias disappearsafter a period determined by the R_2C time constant —and the TTL buffer disconnects the RAMs from the μP . (Note how the optocoupler's phototransistor also connects to the μP 's Reset function.)

The time constants you employ depend upon several factors; the ac input level, optocoupler and Darlington transistor all enter into the picture. For the devices shown in the **figure**, $R_1=470\Omega$, $R_2=1 k\Omega$ and $R_3=47 k\Omega$ with an ac input voltage of 8V rms. This combination disables the RAMs within 15 msec after an ac input loss.

Only two considerations apply in selecting the active devices. First, the Darlington transistor's β should be very high (1000 in this case) at 50 mA. Second, you should account for the optocoupler's transfer characteristics: A highly sensitive (ie, high- β) device might not shut off as rapidly as a less sensitive unit. Why? The LED's drive current might not drop far enough soon enough to isolate the RAMs before a dropout by the system's dc power supply. Optimize the resistors' values to meet your application's and the devices' requirements.

To Vote For This Design, Circle No 452



EDN SEPTEMBER 16, 1981

Pipeline scheme speeds slow memories

Steven Bennett

Harris Semiconductor, Melbourne, FL

Employ a pipelining technique—normally used to enhance instruction-throughput rate or maximize the usage of bus bandwidth—to permit high-speed operation of low-speed memories in ordinary μ Cbased designs. Although the scheme shown in the **figure** conforms to an 8085A, you can adapt this approach to other processors, especially those that require fast read-LOW-to-data-valid memories. With the scheme as implemented here, a 2708 EPROM's effective read-access time drops from 120 to 6 nsec.

This improvement arises when the address/data bus (AD_0-AD_7) is demultiplexed by an address latch (IC_1) and fed with the high-order address bits (A_8-A_{15}) to the 16-bit comparator (IC₆ and IC₇). That device compares the new address with the previous address plus one, and the result latches into IC₁₀ on the trailing edge of ALE.

If the two addresses are arithmetically equal, nothing happens until the μC issues a Read command, causing a 3-state buffer (IC₈) to gate the already accessed data onto the system's data bus. If, however, an address inequality exists, the Q output of the equality latch (IC_{10}) causes the Wait-state generator (IC_{11}) to parallel-load a hardwired number of states.(This version uses three single-clock states.)

The Wait-state circuit's LOW output extends the Read period, resets the equality latch and causes a 16-bit address counter (IC₂₋₅) to parallel-load a new address. This trick allows you to access noncontiguous memory locations. When the Wait state clocks out, the Read signal again gates data onto the system bus. Thus, by employing a program counter external to the CPU and incrementing this counter with the Read pulse's trailing edge, you can make the memory produce instruction N + 1 while the μC is executing instruction N.

As an example, the 5-MHz 8085A-2 is usually limited to 4-MHz operation when interfaced to 2708 EPROMs using standard methods. With this pipeline scheme, however, you can achieve a 5-MHz operating speed and could reach 6.7 MHz if a faster 8085 becomes available.

To Vote For This Design, Circle No 453



Slow memories act faster when the next-to-be-accessed location is pipelined, stored and acquired before the system expects the data. Then, when the system's μ C (not shown) issues a Read command (RD), the already available data is gated onto the system data bus.

Pulser provides variable start, stop times

Marian Stofka

Bratislava, Czechoslovakia

When testing a digital circuit design, you're apt to need a pulse generator whose turn-on and -off times you can delay by a precise and programmable amount. The scheme shown in the **figure** accomplishes this function with a resolution of one part in 256, and it's easily expandable to even higher accuracies.

First, enter the output pulse's start and stop times into two 16-bit MUXs via four rotary switches. Then set both start and stop times independently with switches for coarse (\times 16) and fine (\times 1) values in hexadecimal format. (You could also realize a decimal format by using the first nine inputs to the MUXs.)

Thus, for example, to start a pulse at position 56, enter three into the $\times 16$ MUX (giving 48) and eight into the $\times 1$ MUX. Also note how the open-collector inverters isolate the start and stop signals (Q and \overline{Q}) from each other, allowing you to set equal or overlapping times without interference.

The output pulse starts (goes HIGH) when both counter-driven MUXs' preset inputs are decoded and the MUXs' outputs trigger the JK flip flop. The counter continues until reaching the appropriate stop code and the flip flop's output goes LOW. (The flip flop's clock-preset requirement is satisfied because both the flip flop and the counter respond equally to the clock's positive-going edge.) Note that the output pulse's change of state is delayed by one clock period relative to the counter's state.

In the configuration shown, the output pulse's start and stop times can be resolved to within $\pi/128$ radians and not overlap. You can increase the setting's resolution by cascading additional MUXs and counters. Additionally, you can employ the flip flop's otherwise unused JK inputs—pulled HIGH in the **figure**—to further control the output pulse. **EDN**

To Vote For This Design, Circle No 454



appropriate code. With this design, you can start the output during any of the first 128 time slots and stop it during any of the succeeding 128 positions. Note how the Q output is delayed by one clock period.

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Single one-shot senses frequency limits

Rudy Schneider Carco Electronics, Menlo Park, CA

Unlike a previously published Design Idea ("Oneshots detect frequency levels," January 21, pg 148), this frequency-discriminator scheme (**figure**) requires only a single one-shot IC and its associated timing components. You set the frequency detector's threshold by selecting a single RC combination:

$T_2 = 0.45 RC.$

Thus, for example, with $R=100 \text{ k}\Omega$ and $C=0.022 \mu F$, $T_2=990 \mu \text{sec}$ and the discriminator's threshold frequency is $1/T_2=1010$ Hz. (Note, however, that the 0.45 factor applies only if you use the indicated LS Series one-shots. If you employ a standard 74122 instead, the factor becomes 0.28.)

You can extend this technique to realize bandpass sensing. Use a double one-shot IC such as a 74LS123 and set up two different time constants: one at each frequency limit. (The 7474 D flip flop is itself a dual unit and thus can be used as is.) Then, by adding the appropriate AND/OR gates to the outputs of both flip flops, you can flag under-, over- and in-band frequencies.

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Input-frequency discrimination occurs when the unknown signal's period (T_1) exceeds that of the retriggerable one-shot (T_2). The output signal (E_3) stays LOW so long as the input frequency is lower than the one-shot's frequency and goes HIGH when the input frequency is HIGH.

μ **C Design Techniques**

RAM failure analysis speeds test

Herb Perten

Irex Medical Systems, Ramsey, NJ

The memory-testing code presented in Software Note #62 (EDN, February 4, pg 90) runs slowly because it performs all tests serially. But if you analyze the ways RAMs can fail, you can speed the algorithm by using just two WRITE and two READ instructions for each memory location.

RAMs fail in two areas: the data section and the address section. Data errors result in stuck bits. If you write and then read first a ONE and then a ZERO to each bit of every memory location, you'll identify every data error. Address errors result from stuck bits; they cause access to one location by two or more addresses. If, for example, the least significant address bit were stuck at ZERO, each odd address would map to the even address immediately preceding it.

Because addressing is a binary process, any incorrect address mapping results in the overlay of 2^n locations (n is the byte size) onto another 2^n locations. To catch this error, write a sequence of non- 2^n words (such as three different values) to successive memory locations until the RAM is full. Then, when you read the RAM (in the same order), you'll see the error. If the RAM has less than 2^n locations, load each location with its relative address.

The **figure** shows sample coding of this test, written for a Z80.

;EACH L ;EACH L ;EACH L ;AND IS	OCATIO OCATIO OCATIO READ	N OF THE RA N IS READ T N IS LOADED FOR CORRECT RESSING OR	IM IS LOADED WITH ITS POSITION NUMBER.THEN, 10 SE IF IT HAS THE CORRECT CONTENTS.NEXT, 10 WITH THE 1'S COMPLEMENT OF ITS POSITION NUMBER NESS. THESE TESTS WILL PICK UP ANY PROBLEMS DATA SECTIONS OF THE PAM MUN ITS BUSSES	RAMLDC:	LD LD LD LD	A,OFEH HL,RAM B,64 (HL),A	;LOAD RAM WITH 1'S COMPLEMENT OF PREVIOUS TEST ;LOAD RAM LOCATION
RAMTEST	:LD	A,1 HL.RAM	START OF RAM		DEC INC DJNZ	A HL RAMLDC	
RAMLD:	LD LD INC	B,64 (HL),A A	SIZE OF RAM LOAD RAM LOCATION XEXT VALUE		LD LD LD	A,OFEH HL,RAM B,64	;CHECK CONTENTS
	DJNZ	RAMLD	, MEAT LUCATION	RDRAMC:	CP JR DEC	(HL) NZ,RAMNG A	;CORRECT VALUE? ;JP IF NOT
	LD LD	HL,RAM B.64	; READ THE RAM LOCATIONS FOR CORRECTNESS		DJNZ	HL RDRAMC	
RDRAM:	CP JR	(HL) NZ,RAMNG	;IS CONTENTS OF LOCATION OK? ;JP IF NO	AMOK:			;RAM OK
	INC INC	A HL	;NEXT VALUE ;NEXT LOCATION	RAMNG:			;RAM BAD
	DJNZ	RDRAM		1>			

Memory controller handles 16M bytes

Steven Bennett Harris Semiconductor, Melbourne, FL

Is there life after 64k? If your answer is no, you might be considering a costly move to a 16-bit machine. But a less traumatic solution is available. With a handful of TTL devices and a spare I/O port, you can build a memory controller that permits global jumps and calls within a 16M-byte address space. (Don't confuse this technique with the "pageboundary crossing only" afforded by some memorymanagement ICs.)

The circuit shown in the **figure** implements the technique for the 8085. To use it, you must first program the HM-7610A opcode-decode PROM so that outputs Y_1 , Y_2 and Y_3 are LOW when addressed by JUMP unconditional and CALL unconditional opcodes. Similarly, program Y_4 LOW for RETURN unconditional opcodes. The PROM then serves to detect these opcodes on the data bus. It gets strobed

μ C Design Techniques



Expand system RAM on an 8-bit µC with a handful of TTL devices and a spare I/O port.

by the OPCODE FETCH signal, which is decoded from the 8085 status-bus signals.

When the circuit detects a JUMP/CALL opcode on the data bus, a pulse from the PROM clears the 74F161 ALE-pulse counter, which then increments on the trailing edge of ALE. The resulting count gets decoded by the 74F138 cycle decoder. When the counter has counted three ALE pulses (JUMP/ CALL instructions are three bytes long), the μ P contains a 16-bit branching address, which it starts outputting on the address bus.

The same ALE pulse that outputs this 16-bit JUMP/CALL address also loads the two 74116 high-order address latches with an 8-bit address

µC Design Techniques

supplied by port A of the 8255 peripheral interface. Therefore, before executing a global JUMP or global CALL instruction, the μ P should load the segment address to the appropriate port of the 8255. Executing a JUMP or CALL instruction without first reloading the 8255 merely results in a jump or call within the current segment. (The system supports 256 segments, each 64k bytes long.)

Note that any memory-mapped I/O or RAM accesses must occur within the 64k segment that is currently running the program—otherwise the program becomes lost.

To return to the interrupted or called main program, the μ P must merely execute an unconditional RETURN. This command gets detected by the opcode-decode PROM, which issues a pulse on its Y_4 output to reload the high-order address latch from port A of the 8255. The segment number at port A must not get changed by the interrupt-handler subroutine; otherwise, the program will become lost. For this reason, all interrupt handlers and subroutines must reside within the 64k of segment 0.

		P	ROM O	UTPU	TS
	PROM ADDRESS	Y ₁	Y ₂	Y ₃	Y4
JUMP UNCONDITIONAL	C3	0	0	0	1
CALL UNCONDITIONAL	CD	0	0	0	1
RETURN UNCONDITIONAL	C9	1	1	1	0
ALL OTHER ADDRESSES	XX	1	1	1	1

Program the PROM as shown so that it works in the figure's circuit.

You can safely use all JUMP, CALL and RE-TURN instructions except the unconditional forms within a segment, because they will not precipitate a global branch.

You can modify this basic system to suit most applications for a large memory controller. View the system shown as a guideline and develop your own variants. The **table** shows how to program the HM-7610A for the circuit presented.

EDN Software Note #73 Access routines increase total system ROM

David M Gardner

Tekno Industries Inc, Bensenville, IL

When your 8-bit μ C lacks sufficient ROM address space, you can implement a software-controlled ROM-bank selection mechanism that pages-in a portion of the total system ROM. This process is analogous to loading an overlay from a mass-storage device (such as a floppy disk) but provides much shorter access time because it doesn't involve a mechanical device.

When developing software mechanisms to manage this additional ROM, pay attention to the operating environment and program-interface considerations. Specifically, choose an access method that's easy to use and that, depending on conditions, works in an environment where you can initiate bank selection with interrupts. Additionally, the bank-selection process shouldn't affect the CPU registers.

The code shown in the **figure** meets these requirements for the 8080/85. It is based on the assumption that an always available—or common—

LOC OBJ LINE SOURCE STATEMENT 1 \$NOPAGING PAGEWIDTH(80) MACROFILE PRINT(:TO:) 3 RBREG EQU 27FF 27FFH FREAD/WRITE 4 ; REGISTER FOR ROM BANK SELE 5 ; 6 ;REENTRANT ROM-BANK LINKAGE MACRO REGISTER FOR ROM BANK SELECTION ; FLACED ON NON-BANKED SELECTED ROM. ; COMPLETELY INVISIBLE TO CALLED & CALLING ; FROCEDURES--NO REGISTERS MODIFIED. NOTE NOTE 10 ; REQUIRES 264 8085 T-STATES TO PERFORM LINK REQUIRES 264 8085 T-STATES TO PERFORM LINK & UNLINK. BO80/85 1-BYTE RESTART INSTRUCTIONS ARE USED IN FLACE OF 3-BYTE CALLS TO 'RSTRTI' & 'RSTRT2' TO REDUCE EACH LINKAGE ROUTINE TO 9 BYTES EACH. ACCESS FOINTS AND ROUTINES REFERENCED: ROUTINE 'CLGRTN' IS CALLING ROUTINE 'TARGET' (LOCATED ON ROM BANK 'BANK') VIA A LINKAGE ROUTINE GENERATED BY MACRO'LINK' & UTILIZED BY A CALL TO 'LINK'S. 11 12 13 ; 14 ; 16 17 18 ; 19 ; 20 ; 21 ; 22 LINK UTILIZED BY A CALL TO 'LIN MACRO LINKPT, BANK, TARGET "LINKPT" EXTRN 23 TARGET 24 PUBLIC LINKPT 25 LINKPT: PUSH L . BANK 26 MVI 27 II SAVE CURRENT ROM BANK - SELECT NEW ONE 28 RST 1 ##SAVE CURRENT BANK ON STACK 29 30 CALL TARGET 31 # RESTORE OLD ROM BANK AND RETURN 32 RST 2

MODULE

FAGE

1

ISIS-II 8080/8085 MACRO ASSEMBLER, V4.0

Paging ROM into a \muC system provides access to larger amounts of total-system ROM. (Listing continues on pg 212)

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μ C Design Techniques

	33	ENDM		
0008	35	ORG	8H	
0000	36 RSTRT1:	WRITE	(L) TO	RBREG TO SELECT 'TARGET'
	37 ; BANK.	RETUR	N WITH (H)="CLGRTN'S" BANK.
	38 # WORD	@(SP)=R	ETURN AD	DRESS TO "LINKPT"
	39 # WORD	@((SP)+;	2)= OLD	(HL)
	40 ; WORD	@((SP)+4	4)=RETUR	N ADDRESS TO "CLORTN"
0008 F5	41	PUSH	PSW	SAVE A & F
0009 3AFF27	42	LDA	RBREG	FCURRENT BANK
000C 67	43	MOV	H,A	
000D C34000	44	JMP	RST1	FCONTINUED
	45 ;			
0010	46	ORG	10H	
	47 RSTRT2:	FRESTOR	RE *CLGR	TN'S' BANK & RETURN
	48 # WORD	@(SF)="L	_INKPT*	RETURN ADDRESS
	49 # BYTE	@((SP)+;	3)="CLGR	TN'S" ROM BANK
	50 # WORD	@((SP)+4	4)="CLGR	TN'S' RETURN ADDRESS
0010 E3	51	XTHI_	# DUMP	"LINKFT" RET
0011 E1	52	POP	н	
0012 E3	53	XTHL	;(H)=0	LD PAGE
0013 F5	54	PUSH	PSW	ISAVE A & F
0014 /0	55	MOV	ATH	10001710055
0015 134600	56	JWF	RS12	FCUNTINUED
0040	50	OPC	404	
0040	38 50 DCT1+	1 DECTA	40H	TIMUED
0040 70	60	MOU	A.1	TROED
0041 32FF27	61	STA	RBREG	SELECT NEW BANK
0044 F1	62	POP	PSW	FRESTORE
0045 C9	63	RET		
	64 ;			
	65 RST2:	FRESTAR	RT 2 CON	TINUED
0046 32FF27	66	STA	RBREG	
0049 F1	67	POP	FSW	FRESTORE
004A E1	68	POP	н	FRESTORE (HL)
004B C9	69	RET		
	70	END		
UBLIC SYMBOL	S			
000000000000000000000000000000000000000				
EXTERNAL SYME	OLS			
JSER SYMBOLS				
INK + 0000	RBREG A	4 27FF	RST1	A 0040 RST2 A 0040
RSTRT1 A 0008	RSTRT2 6	0010		

block of ROM exists to service at least the interrupt vectors. For each routine in banked ROM, the VECTOR macro generates nine bytes of code. (Restarts one and two are used to save space.)

The code is easy to use; accessing the TARGET routine requires only a call to the proper LINKPT. Because the call and its associated return modify no registers and are themselves re-entrant, the code is invisible to both the called and calling routines.

One final note: Because this macro's execution time is relatively long, you should locate short, frequently used utilities and fast-response interrupt handlers in the common ROM.

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AT-6	6	$\pm 0.3 dB$	DC-1500	0.6dB	0.8dB	1.3:1	1.5:1	1W
AT-10	10	$\pm 0.3 dB$	DC-1500	0.6dB	0.8dB	1.3:1	1.5:1	1W
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Single pulse, or self-index to any position. Uni- or bi-directional action.

Open frame, packaged, and hermetically sealed units available from stock. Custom assemblies also available for prototype and production requirements.

Ledex Inc., P.O. Box 427, Vandalia, Ohio 45377. Phone: 513-898-3621.



COMPUTER-SYSTEM SUBASSEMBLIES

ANALOG INPUT SYSTEM. The wide-range isolated Model LDT2765 features four differential input channels that withstand ±250V common-mode voltages and support a 60-Hz CMRR of



Make Impossible Measurements Easy... with Unprecedented Accuracy



measurement conditions where other instruments simply do not work. Use the 3100 on continuous and burst signals. Measure transfer functions. Analyze signals, networks, and components. In ATE, use it in manufacturing and quality testing of transformers, chokes, servos, filters, sonar and communications equipment, and many other applications. In stand-alone, or IEEE-488 mode, the 3100 quickly and easily calculates (where appli-

cable) fundamental, total, harmonics to the 14th, for all of the following:

Phase angle Harmonic Phase angle Thd	VRMS (OR I) RATIOS: RMS & COMPLEX IMPEDANCE, ADMITTANCE	VA VARS REAL POWER	PF GROUP DELAY FREQUENCY
	INT EDATOL, ADMITTATOL	KEAL I OWEN	TREGOLINOT

SPECIFICATIONS:

- Accuracy: \pm 0.1%, \pm .03 degrees.
- Frequency Range: 1 Hz to 500 kHz.
- Dynamic Range: 70 dB in any range, 120 dB between channels.
- Harmonics: Any combination to the 14th.
 Input Channels: Two, with 12 full scale
- Input channels: two, with 12 full scale ranges from 1 mV to 300V, plus autoranging.

FEATURES:

- Programmable Sampling: 16, 64, 256 samples/measurement.
- Programmable Averaging: 1, 16, 64 measurements/reading.
- Trigger Choices: Internal, external.
- Frequency Reference: Internal, external.
- Printer: 20 column, front panel control.
- Communications: RS-232C. IEEE-488
- optional.

The remarkable 3100 - only from Dranetz, where we make impossible measurements easy. For more details, request 12-page bulletin 3100.



DRANETZ ENGINEERING LABORATORIES, INC. 1000 New Durham Rd., Edison, NJ 08817 (201) 287-3680 TWX: 710-997-9553

126 dB. It functions with the manufacturer's Lab-Datax LSI-11-based data-acquisition systems. An optional panel-mounted ambient-temperature compensation circuit provides thermocouple cold-junctioncompensation capabilities. The companion LDT2775 isolated input expander features eight isolated differential input channels. As many as seven expanders can augment each LDT2765 for a total 60 isolated channels. LDT2765, \$965; LDT2775, \$720, including front panels. Data Translation, 100 Locke Dr, Marlboro, MA 01752. Phone (617) 481-3700. Circle No 148



MEMORY SYSTEM. Using array boards mounting 288 64k dynamic-RAM chips, MMS3000 accommodates as much as 32M bytes of memory. The standard package includes a card cage, power-supply module, interface card, mother board, addresscontrol card, error-correction card, two terminator boards, interconnect cables and 2M bytes of RAM. A 64M-bytes/sec data-transfer rate can be established through use of parallel read with sequential addressing. At the memory-bus level, the system exhibits an access time of 350 nsec with error correction, 275 nsec without. \$30,700 for basic system; additional 2M-byte card, \$16,800. Motorola Semiconductor Products Inc, 3501 Ed Bluestein Blvd, Austin, TX 78721. Phone (512) 928-6776. Circle No 149

ADC achieves high-speed conversion

Operating at a 1-MHz clock rate, the ADC-5212 resolves an analog input ($\pm 10V$ max) to a corresponding digital output in just 13 µsec. A 12-bit successive-approximation hybrid design, it limits nonlinearity to $\pm \frac{1}{2}$ LSB.

At 25°C, converter absoluteaccuracy error specs at $\pm 0.05\%$ FSR and is guaranteed not to exceed ± 10 ppm/°C over temperature. Two versions are available: a commercial type that operates over 0 to 70°C and a military model, processed to MIL-STD-883 method 5088.

Pin compatible with similar parts from Micro Networks and Analog Devices, the -5212 is housed in an industry-standard



HYBRID TRANSCEIVER. For use in automatic test equipment requiring a variable transmitter output, the BUS-8559 is housed in a 1.4×0.8×0.2-in. 24-pin DIP and weighs 0.4 oz. Meeting MIL-STD-1553A and -B, it operates over -55 to +125°C and from ± 12 to $\pm 15V$ and $\pm 5V$ power supplies. Its transmitter section accepts biphase TTL data at the input and produces a 0 to 27V (nominal) p-p differential signal across a 145 Ω load. The module can be coupled to the data bus with the manufacturer's BUS-25679 transformer. \$325. Delivery, 4 to 8 wks ARO. ILC Data Device Corp, 105 Wilbur PI, Bohemia, NY 11716. Phone (516) 567-5600. TWX 510-228-7324. Circle No 155



Aimed at high-speed applications, the ADC-5212 A/D converter features a 13-µsec conversion time. It provides a $\pm 0.05\%$ absolute-accuracy error at 25°C and comes in commercial and military versions.

24-pin DIP and operates from 5 and $\pm 15V$ supplies.

\$190 to \$485. Delivery (production qty), stock to 8 wks.

CONNECTORS Designed to terminate 0.050 - in. - center round-conductor flat cable and mate with 0.062-in.-thick pc boards with pads on 0.1-in. centers, Edge-Card II connectors come in 11 sizes with 10 to 64 positions. Bifurcated contacts permit redundant connection to the pc board, and 0.013-in.-thick beryllium-copper contacts maintain spring characteristics and high normal force after repeated insertion and withdrawal. The units come in three styles: with mounting ears, with mounting slots and without mounting ears. Du Pont Berg Electronics Div, Rte 83, New Cumberland, PA 17070. Phone (717) 780-2044. Circle No 156

CONNECTOR. This socketheader eliminator (SHE) connector features a footprint identical to that of standard 0.1×0.1 -in. headers and suits applications not requiring the mateability benefits of headers and sockets. Intech Inc/Microcircuits Div, 2270 Martin Ave, Santa Clara, CA 95050. Phone (408) 727-0500. Circle No 154



For 50-µm flat ribbon cable, it comes in nine sizes with 10 to 60 contacts. Positive connection between the U contact and 28-gauge stranded or 30-gauge solid round conductors is ensured by a double-action slot design utilizing two cutting surfaces. Insulation surviving the first cut is displaced by the second cutting edge, with a gas-tight connection formed by subsequent abrasion of the conductor by the slot. Gold-overnickel plated contact areas are provided. \$4.12 for 34-position unit. Belden Corp. 2000 S Batavia Ave, Geneva, IL 60134. Phone (312) 565-1200. Circle No 157

COMPONENTS & PACKAGING



DIRECTIONAL COUPLERS. For use as taps or feeds in multiterminal local networks, multiplexing and other applications, these 3- and 4-port optical directional couplers accommodate digital and analog transmission. They permit full-duplex operation over one fiber and



CODI's Voltage Regulator Diodes Do the Job...Where Others Can't

CODI's Voltage Regulation Diodes offer voltages from 3.3V to 10V and are designed for applications where ordinary zeners can't provide the required combination of low noise, low leakage, sharp knee, low dynamic impedance, and reliability. Among these applications are ultrastable regulators, low ripple series regulators, Op Amp regulators, wave shaping, and comparator references.

This CODI series of diodes from IN5518B to IN5530B is available in JAN, JANTX and JANTXV versions providing up to 10V where MIL reliability is required. All diodes are supplied in hermetically-sealed DO-7 glass packages. Higher voltage units are available on special request.

To find out how CODI Voltage Regulator Diodes can solve your circuit problems, call Joe La Bruna, CODI Semiconductor, Inc., 350 Hurst Street, Linden, N.J. 07036; telephone: 201-862-8484; telex: 844796.



exhibit low insertion loss, high directivity and passive operation, according to the manufacturer. Available with Corning SDF fiber and a variety of graded-index fibers, the $1 \times 4^{1/4} \times ^{3/6}$ -in. units feature a broad range of splitting ratios and can operate at all standard transmission wavelengths. <\$200 (OEM qty). Phalo Optical Systems Div, 9240 Deering Ave, Chatsworth, CA 91311. Phone (213) 998-3177. Circle No 158



LATCHING RELAY. Featuring bifurcated cross-bar contacts and a card-lift-off operating system, the polarized Model BZB incorporates flux-free construction and dual-in-line pitch terminals. Equipped with goldoverlay silver-palladium stationary contacts and silver-palladium movable ones, it has a life expectancy of five million mechanical operations and one million electrical operations. Contact arrangements are 4pdt (B-M), dpdt (B-M) and dpdt (M-B). Maximum current flow equals 2A; at resistive load the maximum switching power equals 50W; maximum switching voltage, 60V dc; and maximum switching current, 2A dc. Designed for direct pc-board mounting on a 0.1-in. grid spacing, the relay operates over -30 to +80°C. 4pdt unit, \$7.75 (1000). Delivery, 8 to 10 wks ARO. ITT Components, Box 2197, Santa Ana, CA 92707. Phone (714) 751-3900.

Circle No 159

EDN SEPTEMBER 16, 1981

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Quad-output 100W switcher series features small size, low cost

Claimed the smallest, lightest and least expensive 100W 4-output switchers available, Series 4100 supplies suit μ C-system, CRT-terminal, disk-drive and modem applications.

Mounted on a pc board, the switchers furnish rated output over a 0 to 40°C ambient-temperature range with 2%/°C derating to 71°C.

The four models in the series provide the following ratings:

- +5V at 10A, ±12V at 1.5A and -5V at 1A
- +5V at 10A, ±15V at 1.5A and -5V at 1A
- +5V at 10A, ±12V at 2A and -5V at 1A



Small size (4×8×1.7 in.) and light weight (24 oz) highlight 4100 Series switchers. The \$159 4-output supplies deliver 100W outputs from 85 to 130 or 170 to 250V ac inputs.

 +5V at 10A, ±15V at 2A and -5V at 1A.

Pin-strappable inputs allow the supplies to operate on 85 to 130 or 170 to 250V (47 to 440 Hz) voltage ranges. And Schottky rectifiers combined with a halfbridge configuration give them 70% min efficiency and ripple and noise specs of 50 mV p-p, 15 mV rms.

Other specs include $\pm 0.1\%$ line regulation, load regulation of $\pm 0.2\%$ for the primary output and $\pm 1\%$ for the other outputs, a 0.02%/°C TC, and standard current limiting, soft starting, 15A max input surge current and convection cooling.

The 24-oz supplies measure $4 \times 8 \times 1.7$ in. and furnish a 30,000-hr min MTBF, per MIL-HDBK-217B. \$159.

Power General, 152 Will Dr, Canton, MA 02021. Phone (617) 828-6216. Circle No 128



INSTRUMENTATION & POWER SOURCES

EMULATOR/LOGIC ANALYZ-ER. Model 4009 combines features of a real-time 68B09/E emulator and a 12/20-MHz, 18-channel logic analyzer. Its menu-oriented display allows a



user to disassemble a program in mnemonic form. A terminal or



Placing Series RL1328/1329 Renco common mode chokes at the inputs of electrical equipment or circuits is by far the **lowest-cost** way to meet US and international requirements for safety and suppression of feedback EMI. They are available in such an

elephantine range of current ratings (up to 35 amps) and inductances (6.8 microhenries to 39 millihenries) that it's difficult to imagine an application that cannot use one of our standard chokes. (If you have one, however, we'll be glad to make up custom chokes for you.) Our chokes range in price from \$2.13 to \$3.10 per 1,000-stock, are extremely compact, have low profiles, (as small as 0.657"H, 1.312"W, 1.687"D), and are very easy to mount on pc boards. They offer 5,000 volts dielectric isolation, and meet UL, CSA, and VDE specifications. Windings are balanced to within 1%. MIL spec and encapsulation available. We design and manufacture in the USA and ship world-wide.

Call or write Bruce Rensing, Renco Electronics, Inc., 60 Jefryn Boulevard East, Deer Park, NY 11729. 516/586-5566.



host computer can control the unit through three generalpurpose communication ports; two RS-232C communication cards and one cassette interface are provided. GPIB and Centronics printer-interface communication cards are optional. Other features include four break events (40-bit-wide trigger conditions) and a real-time, $2k \times 56$ -bit trace memory, configured so that the operator can examine the trace while in emulation. \$4995. Advanced Digital Technology Inc, 13400 Northrup Way, Bldg 15, Bellevue, WA 98005. Phone (206) 643-2382. Circle No 129



SYSTEM POWER SUPPLY. An IEEE-488 dc power supply with a bidirectional interface and autoranging for systems applications, HP 6034A combines an internal µP-based HP-IB programmer with FET switching technology to provide laboratory-grade performance specs and autoranging capability. Its firmware permits programming of the output voltage and current directly in volts and amps with 12-bit resolution. The unit also provides remote output voltage and current metering over the bus with 15-mV and 2.5-mA resolution, respectively. An overvoltage-protection circuit can be directly programmed in volts with 8-bit resolution. Other features include built-in diagnostics and a removable front panel for access to the calibration board. \$2700. Hewlett-Packard Co, 1507 Page Mill Rd, Palo Alto, CA 94304. Phone local office. Circle No 130

INSTRUMENTATION & POWER SOURCES



250W SWITCHERS, 5F Series open-frame dc units feature a dual input range of 90 to 132 and 180 to 264V ac and 16-msec input carryover. Ripple and noise equal 40 and 75 mV p-p max typ, respectively, at full load. Line and load regulation spec at 0.15% for all outputs except the 24V output of the 5-output Model 5FXMP, where they equal 8%. Overvoltage protection, foldback current limiting, remote sensing, outputvoltage adjustment, enable/inhibit function and LED status indicators for each dc output are provided. From \$249 for singleoutput units; from \$379 for multiple-output models. Delivery, 6 to 8 wks ARO. Sierracin/ Power Systems. 20500 Plummer St, Chatsworth, CA 91311. Phone (213) 998-9873. Circle No 131

IN-CIRCUIT TEST SYSTEM.

Including a high-speed Nova 4X minicomputer with 128k words of MOS memory and an enhanced test executive. Series 30/303S test system provides automatic test-program-generation software that offers near-total-faultdetection production programs. Features include advanced test algorithms, an LSI debugger, QA-check program and pin-tonode identifier. The software package includes the PIN-CHECK program, which verifies complete interconnection between the test fixture and the board under test. It is executed before each board test begins, identifies pins not contacting the board and halts the test sequence to permit corrections. Typical system, \$180,000; foreground/background programming option, \$4100. Fairchild Corp Subassembly Test Systems, 299 Old Niskayuna Rd, Latham, NY 12110. Phone (415) 962-3533. Circle No 132



POWER ANALYZER. Model 636 multifunction power analyzer measures ac voltage, current and time. Using those measurements, it can calculate and display watts, watt-hours, VARs. VAR-hours, volt-amps, phase angle, power factor and frequency. Features include high resolution and true-rms measurements with crest factors of 3 for current and 2 for voltage. \$5670. Delivery, 6 to 8 wks ARO. RFL Industries, Powerville Rd. Boonton, NJ 07005. Phone (201) 334-3100. Circle No 133

OPEN-FRAME SUPPLIES. With

a shielded transformer, socketed semiconductors, dual ac input. barrier-block terminals and an MTBF to 100,000 hrs, HVQ Series single-output linear units achieve current ratings to 3A. Input ratings equal 105 to 125 or 210 to 250V, 47 to 440 Hz; outputs include 5V/3A, 12V/ 1.7A, 15V/1.5A and 24V/1.2A, adjustable ±5%. Line and load regulation equal 0.1%. Ripple and noise spec at 1.0 mV rms, 5 mV p-p. Remote sensing and reverse voltage protection come standard. \$21. Deltron Inc. Box 1369, North Wales, PA 19454. Phone (215) 699-9261. TWX 510-661-8061. Circle No 134



CIRCLE NO 90

225

ICs & SEMICONDUCTORS

Low-cost speech-synthesizer IC speaks in as many as five languages

You can now give your product some "say so" in its usage by incorporating a Custom ROM Controller (CRC) voice-synthesizer IC into its design. It could then speak in an assortment of English vocabularies, including one for calculators (24 words) plus standard (64 words), ASCII (64 words) and 119-word basic sets. The calculator voice is also available in Arabic, French, German and Japanese.

When the CRC combines with the vocabulary RAM, a simple passive filter and an op amp, the resulting speech is an emotionless, nonhuman-like robotic sound.



Voice output occurs when the Custom ROM Controller (CRC) IC decodes a 6-bit data word, fetches the digital equivalent from memory and reconstructs the desired word(s). The resulting robotic-sounding words are easily concatenated without conflicting inflections.

The CRC performs two functions: It's a speech synthesizer and a speech-data controller. In a typical application, you input a 6-bit data word to it. It then retrieves the corresponding word(s) from memory and reconstructs the message.

Based on the techniques developed by Dr Forrest Mozer, algorithms convert the original human speech into digital data to yield approximately 1k bits per speech-second. Thus, because the CRC can directly address up to 32k-byte-wide ROMs, you can generate approximately 30 sec max of speech (64 sec max with extra decoding).

The CRC voice-synthesizer IC costs \$65 at the sample level or approximately \$20 (5000).

Telesensory Speech Systems, 3408 Hillview Ave, Palo Alto, CA 94304. Phone (415) 856-8255. Circle No 125



ICs & SEMI-CONDUCTORS



12-BIT DAC. A self-contained hybrid unit, DAC 1280A provides feedback resistors, output op amp and reference on three dice. Output current equals 0 to 2 mA, and settling time to full-scale accuracy equals 300 nsec in Current mode and 2.5 usec in Voltage mode. Power dissipation in either mode specs at 500 mW. Internally supplied resistor options provide low-drift bipolar output-voltage ranges of ± 2.5 , ± 5 and $\pm 10V$ and unipolar ranges of 0 to 5 or 0 to 10V. \$22.95 (100) in 24-pin DIP. National Semiconductor, 2900 Semiconductor Dr, Santa Clara, CA 95051, Phone (408) 737-5000. TWX 910-339-9240. Circle No 126



MONOLITHIC PWM. A monolithic pulse-width modulator for dc motor control, the SG1731 provides bidirectional pulse-train output in response to the magnitude and polarity of analog input signals. It features externally programmable deadbands to control power consumption, stiffness and stability and an internal amp. Its triangle-waveform oscillator requires only one external capacitor to set frequency as high as 350 kHz; a summing/scaling network permits level-shifting the triangle waveform for pulse-width modulation. Supply voltage to the output drivers can come from dual positive and negative supplies or from single-ended ones. Output voltage equals $\pm 35V$; supply-voltage range specs at ± 3.5 to $\pm 15V$. The SG1731 operates over -55 to +125°C; the SG2731, -25 to +85°C; the SG3731, 0 to 70°C. SG3731J, \$7 (1000) in a 16-pin Cerdip. Delivery, 10 wks ARO. Silicon General Inc, 11651 Monarch St, Garden Grove, CA 92641. Phone (714) 892-5531. TLX 692411. TWX: 910-596-1804. Circle No 127

The Hecon with the Hopper.

HECON

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HECON

The Hecon A0542 impact dot matrix ticket printer with hopper feed. Load up to 75 tickets in the easily accessible hopper. When you are ready to print, the A0542 automatically feeds, prints and transports the ticket for removal. You can even reinsert a ticket for additional printing thru the unique reprint feed slot.

The highly visible Time and Date feature is standard and can be printed with a single command.

The A0542 can print the 96 character ASCII set bidirectionally at 120 characters per second. The standard print head is rated at 200 Million characters minimum for long, dependable service.

It's got to be good. It's a Hecon.



Hecon Corporation, 31 Park Road, Tinton Falls, NJ 07724 • (201) 542-9200

CIRCLE NO 92

A Question of Law

Be sure of a device's patent status before incorporating the part in a design

David Pressman, Attorney at Law San Francisco, CA

If you want to incorporate a competitor's circuit into your design, can you do so without being sued? How can you determine a product's patent status and whether you can copy the product without liability?

That the circuit or device doesn't appear to be patented provides no guarantee of safety: It could be the subject of a pending—and secret—patent application. However, several rules and guidelines can help you determine a device's patent status and if it's relatively safe to manufacture. Thus, this second article in a 3-part series on aspects of patent law focuses on the procedures involved in obtaining clearance for copying a manufactured product.

First, remember that patent professionals do not consider it immoral or unethical to copy any circuit or device not patented or on which the patent has expired. The patent laws' purpose is to disseminate new developements to the public by inducing inventors to reveal the details of their inventions with the promise of a limited-term monopoly. Once a patent expires, therefore, the public is free to use the patent specifications to make and use formerly patented devices.

Thus, if the circuit or device you're interested in is not currently patented, the patent probably has expired and it's in the public domain. And by copying it you're doing just what the law intended: using and building upon the knowledge disseminated by a patented invention.

Unpatented device open to copying

Even if the circuit was never patented, you're still within your rights in copying it. By producing a commercial product without patenting it, the inventor (or the inventor's company) has, in effect, said: "I don't want a monopoly on this product; anyone interested in it is free to use it, provided that he takes the trouble to reverse-engineer the device."

Next, remember that the law prohibits you from copying any nonfunctional aspects of an unpatented

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product, such as its novel shape, color or design. These aspects could be considered a trademark or the equivalent of a trademark. And nonfunctional features not serving as a trademark are often protected under the law of unfair competition (EDN, July 22, pg 390).

The law in this area, though, is currently in a state of flux, so it's impossible to offer definitive rules or guidelines. Generally, however, you'll be safe if you make your equipment's exterior design (shape, color and other nonfunctional features) sufficiently different so it won't be confused with your competitors'.

You can see that although it's morally and legally permissible to copy an unpatented device in public use, determining a product's patent status is not always easy.

The first step is to examine the circuit's or device's enclosure, instruction manual, advertising literature and package to see if they contain any indication of patent status. (A patent owner or applicant, though, has no legal obligation to label a product with this information.) In this regard, every invention has three possible patent statuses: patent pending, patent in force and patent expired.

"Patent pending" confers no rights

If the circuit is marked "patent pending" or "patent applied for," it means that a patent application has been filed in the Patent and Trademark Office but no patent has yet been issued (or the application hasn't yet been abandoned if the device is found unpatentable). But note that a patent application and patent-pending status confer no rights; *technically* you're free to make and sell any invention whose patent is pending. You'd be unwise to do so, though, because a patent might eventually be issued and you'd then infringe it.

You're not relegated, however, to copying at your peril with a patent-pending invention. If you're interested enough in it, you can make a Patent Office patentability search and obtain a patent attorney's opinion to determine whether the invention is patentable. If so, its owner will likely obtain a patent; in this case, then, don't waste your capital tooling up because you'll likely be charged with infringement once the patent issues.

But if you discover that the invention is old and not

A Question of Law

covered by an in-force patent, you're free to use it. In this case, you'll merely be practicing the "prior art," and the patent application's owner won't be able to obtain a valid patent on his invention.

One word of caution: Patent law isn't always black and white, so you should consult a patent attorney before you copy a product to make sure you haven't missed any important points.

Name search can determine patent's status

If the invention of interest simply carries the label "patented," you can't be sure whether it's covered by an in-force patent—one issued within the past 17 yrs—or by an expired patent that places the device in the public domain.

An invention in use for approximately 21 yrs (17 yrs for its patent term, plus about 4 yrs comprising the 1-yr grace period between first commercial use and a patent application and the patent-pending period) can almost certainly be manufactured with impunity. If you can't be sure, however, that the invention has been publicly available for 21 yrs, you can have a patentability or name search conducted in the Patent Office to determine the exact status.

A name search pulls all the patents issued in the name of the company manufacturing the product (or its inventor, if you know his identity). This procedure is not generally recommended, though: There could be simply too many patents issued in the company's name to make an identification practical, or the patent you're interested in might not be issued in the manufacturing company's name at all.

If there's no patent marking on the device or its housing or packaging (as is frequently the case), and it hasn't been publicly available for 21 yrs, you run a definite risk if you copy or manufacture it—it could be covered by an in-force or pending patent. In this case, then, follow the aforementioned procedures outlined for a patent-pending invention.

Trying to break a patent is not immoral

If an in-force patent covers the circuit or device you want to manufacture and it can't be designed around, only three courses of action remain: breaking the patent, a "damn the torpedoes" approach or obtaining a license.

You can try to break the patent by making an extended validity search and study of the Patent Office's file on it. This process, however, requires an experienced patent attorney and could cost several thousand dollars. And although it's been said that given enough money almost any patent can be broken, most patent attorneys would disagree. In fact, hundreds of patents are held valid every year after extended and extremely expensive court challenges. It wouldn't be a bad idea, though, to carefully study any patent you're interested in and make a regular patentability search before considering the alternatives previously noted; even a preliminary study can point out potentially fatal flaws.

As to the morality of seeking to break a patent, remember that a patent grants a valuable 17-yr monopoly. Thus, finding a good reason why the monopoly should not have been granted in the first place (the Patent Office makes mistakes like everyone else) constitutes a public service in helping to rescind an improperly granted monopoly.

Under the patent-law amendments recently adopted (EDN, June 24, pg 133), if you've found a good reason to challenge a patent, you can cite pertinent prior art to the Patent Office and have it placed in the patent's file or even request that the Patent Office re-examine the patent. The re-examination fee runs \$1500 plus attorney fees, but this sum is still far cheaper than a full-blown court test.

As an alternative to trying to break the patent, you can go full speed ahead and "damn the torpedoes" by simply making and selling the patented invention and hope that the patent's owner won't catch you. If caught, you can then try to break the patent or negotiate a license. This approach isn't considered the most moral of positions, but it's followed frequently in industry. And it's adopted particularly with inventions not readily identifiable from an infringer's product, such as electronic circuits or semiconductor devices, especially if they can be incorporated in an IC.

If you do follow this approach, though, be sure to set aside a reserve fund equal to a reasonable patent royalty on the device you're going to use—a sum usually 1 to 10% of its factory price, depending upon the invention's value and importance to the final product. And be aware that if your infringement is discovered and you're sued, the patent owner can obtain an injunction prohibiting you from further manufacture or sale of the device. He can also collect damages equal to reasonable royalties for the past use of his product.

Asking for a license can be risky

The third method of copying a patented invention is the most moral of all: Ask the patent owner for a license to make and sell the device. But unless you know he's willing to license (eg, if he's already granted licenses to others), this approach can be risky because he can refuse to grant a license or can offer one only on very expensive terms. Thus, by inquiring about a license, you could tip your hand needlessly and lose most of the possible advantages if you decide to finally "damn the torpedoes."

Delivery from stock in Production Qtys. **TO-5 TRIACS** and **SCRS**



- 3A Sensitive Gate TRIACS 3 to 25mA (I_{GT})
- 6A TRIACS
- 4A Sensitive Gate SCRs 200µ A and 1mA (I_{GT})
- 7A SCRs
- 50 to 600V (V_{DRM}) (Higher voltages on request)

These highly reliable, hermetically sealed metal can TO-5-packaged Triacs and SCRs are still available for immediate delivery in production quantities from Hutson. Sensitive-gate logic Triacs have all-quadrant gating and are designed to be driven directly from ICs. These TO-5 devices have been produced by Hutson for 15 years in hermetic packages designed for long-life applications requiring high reliability.

HUTSON INDUSTRIES

P. O. Box 90 • Frisco, TX 75034 (214) 377-2402 CIRCLE NO 93

Order today or call or write for samples. A Question of Law

Most companies, however, are delighted to grant licenses on their patented inventions because they provide immediate extra income without risk or capital outlay. And the disadvantage of having you as an additional competitor is usually outweighed by the other considerable advantages of licensing; the company is probably already the market leader, and having a second source helps sales.

Finally, if the circuit or device you want to copy carries a patent number (eg, "Patent Nr 4,205,483"), your course is simplified. Simply order the patent by number for \$0.50 from the Patent Office, Washington, DC 20231 or photocopy it in a Patent Depository Library—listed in the front of any current issue of the Official Gazette.

When you get the patent, note its date of issue; if it's more than 17 yrs old, the invention is now in the public domain. If not, you'll have to determine with the help of a patent attorney whether your circuit would infringe the patent's claims. (See the next article in this series for guidance.) If your circuit would infringe, you're left with one of the three alternatives just discussed.

Don't make your copy too literal

If you find, happily, that you can copy a device with impunity, remember not to make your copy too literal. One manufacturer sent a device to the Orient to be inexpensively copied—in quantity. It came back in huge quantities faithfully reproduced down to the last detail—including the competitor's embossed trademark, which of course had to be obliterated at great expense before the device could be legally sold.

David Pressman, JD, BSEE, received the Juris Doctor degree from George Washington University and a BSEE from Penn State University. Formerly a field engineer at Philco-Ford Corp, a patent examiner with the US Patent Office and a patent attorney for Philco-Ford, Elco Corp and Varian Associates, Pressman is currently in private practice specializing in patent law.



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ical design effort. The 15.75" high units are available with up to 26 card slots complete with backplane and power supply connections. Multibus™Intel Corporation. Contact ELECTRONIC SOLUTIONS, 5780 Chesa-

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CIRCLE NO 113

Literature



Specifying interlocking switch assemblies

This 6-pg brochure details Series 30 Interlock switch systems, actuators, switching elements, spacers and accessories. Its line drawings enhance technical data. A dimensional outline, mounting diagram and pad of order forms conclude the booklet. **EAO Switch Corp**, 255 Cherry St, Milford, CT 06460. **Circle No 135**

Fold-out chart highlights resin uses

This epoxy-resin guide details products for encapsulation, impregnation, potting or casting applications. Providing specs for 26 1- and 2-part systems, it also contains a cure guide and temperature classification chart. **Acme Chemicals and Insulation Co,** Box 1404, New Haven, CT 06505. **Circle No 136**

Data details statistical MUXs

Bulletin 5264 describes features and applications of the DCX836, -840 and -850 statistical multiplexers. Photos and callout diagrams detail the operation of the MUXs' various diagnostic and networking modules, and block diagrams show how to incorporate them into different networks. A spec chart differentiates models by such features as number of input channels and composite links, buffer size and automatic-repeat-request capability. **Rixon Inc,** 2120 Industrial Parkway, Silver Spring, MD 20904. **Circle No 137**

Shopping for μC software

Listing more than 50 media formats, CP/M-compatible diskoperating systems, hard-disk integration modules, languages, language and application tools and word-processing systems. this 35-pg guide catalogs singlesource tested and servicesupported microcomputer software. Data-management and mail-list systems, financial accounting packages, numerical problem-solving tools and professional and office aids are also referenced. Lifeboat Associates. 1651 Third Ave. New York. NY 10028. Circle No 138



Utilizing a keyboard/display card

This 88-pg manual details the 7303 STD Bus keyboard card, a general-purpose control-panel unit providing data-input and display capability. Separate sections focus on the card's features, its operation and programming, installation and specifications, software and maintenance. An appendix describes the unit's front-paneling mounting. **Pro-Log Corp**, 2411 Garden Rd, Monterey, CA 93940. **Circle No 139**



Designing with LCDs

Highlighting principles of operation, driving techniques, surface treatments, sealing, cost and reliability, a 20-pg handbook details liquid-crystal displays. In addition, it provides data on multiplexing drive techniques. Field-reliability information, 7-yr life data and graphs and illustrations explain the devices' operation. **Seiko Instruments USA Inc,** 2990 W Lomita Blvd, Torrance, CA 90505.

Circle No 140



A look at IC packaging solutions

This literature kit includes a 152-pg catalog and 24-pg price list for microelectronic packaging systems and accessories. It features a μ C-panel family, which serves prototyping and interface applications compatible with DEC hardware, including PDP-11 and LSI-11 systems. A spec table detailing rack assemblies, terminals, cable types and pc boards concludes the catalog. **Mupac Corp**, 10 Mupac Dr, Brockton, MA 02401. **Circle No 141**

Literature



Data on more than 80 telecomm units

Featuring a line of video, voice and data-transmission systems, this 36-pg catalog details microwave radio transmitter/receivers and subsystems, fiber-optic transmission systems, multiplex systems, FDM cable-carrier systems, N-type repeatered line equipment, PCM digital multiplex equipment and cable-carrier systems. It also provides specs and illustrations of auxiliary data equipment, supervisory and control systems and voicefrequency and signaling equipment. Specs outlined include number of channels, frequency range and channel frequency response. GTE Lenkurt Inc, Dept C720, 1105 County Rd. San Carlos, CA 94070.

Circle No 142

Data illustrates power-line filters

This 16-pg catalog covers a line of RFI power-line filters, highlighting 3, 6 and 10A filters at 115/250V ac rated voltage, for common- and differential-mode operation in linear and switching power supplies. It also discusses FCC and VDE emission limits, noise modes, insertion loss, terminology and cost-effectiveness factors. A cross-referenced chart compares various manufacturers' units. **Curtis Industries Inc,** 800 W Tower Ave, Milwaukee, WI 53223.

Circle No 143

Books

On surviving in a technical hierarchy

Putt's Law and the successful technocrat, by Archibald Putt; ix+165 pgs; \$9.25; Exposition Press, Smithtown, NY, 1981.

Addressing himself directly to technology-oriented industries, the author of this book provides insights into the nature of their hierarchies. Not content with Dr Peter's famous management principles, he applies the same type of observation to research and production facilities and finds some exciting differences between technological hierarchies and the rest of the world.

One of Putt's most innovative sections deals with the laws of failure. Failure isn't inherently a problem, he says. You must understand how to fail, however, if you expect to become a successful technocrat.

Using fictional case histories and a fictional model technocrat named Dr I M Sharp, Putt explores the mysteries of innovation management, the art of giving advice, decision making and how to communicate.

For those of you who are thinking of venturing out as consultants, Putt offers a stern warning. Most technical consultants fail, he says, because they think that their function is to give information and advice. You'll have to read his book to see the naivete of this notion.

– Ed Teja

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Work with BNR to advance the Technology of Telecommunications on the San Francisco Peninsula

The success that BNR has achieved in the development of new software controlled telecommunications systems has increased our need for experienced electronics and software engineers. At the moment, we require a variety of professionals to advance the state-of-the-art in computing science, to develop new products, and to guide their applications. Outlined below are the major areas in which we have need for software and electronics professionals. Each area represents several immediate openings. If you have a BS/MSEE CS, Physics, or Math, or equivalent, and related professional experience, join us, and experience the innovative freedom, technical challenge, and the professional growth inherent in pioneering the telecommunications systems of the future.

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Looking Ahead: Trends and Forecasts

'80s' F-O gov't sales to top \$1.9 billion

The 1980s will see total US production of fiber-optic components for government/military applications skyrocket to more than \$1.9 billion, fueled by rapidly rising sales of point-topoint analog and digital communications equipment. Governdata-bus fiber-optic ment applications-including radar, data-processing, guidance/control, sonar and electronic-warfare systems—will account for a \$23 million market by 1985, predicts Gnostic Concepts Inc (Menlo Park, CA). And production in these five equipment categories should reach \$99 million in 1990.

Standardization of components used for government applications will be completed by 1983 in time for broad-scale fiber-optics usage, says Bill Walsh, Gnostic Concepts military analyst. As fiber-optic architecture grows more complex, optical-frequency and multiplexing techniques will be employed, and wavelength dividers will utilize planar and concave diffraction gratings and wavelength-sensitive fibers, in-

Mass-produced electric cars by 2000?

Long promised but never delivered, practical electric vehicles (EVs) (EDN, September 5, 1980, pg 105) could finally start rolling down American roads in significant mass-production quantities soon after the turn of the century, says Harry W Mathews Jr, consulting engineer at Arthur D Little Inc (Cambridge, MA).

Limited mass production of this country's first generation of modern electric cars is sched-



tegrated on substrates with other components.

Walsh also expects data-bus architectures to emerge by 1985 and foresees increased usage of 1.3- to 1.6- μ m devices in the latter half of the decade to capitalize on the lower attenuation and dispersion possible at those wavelengths. Development of long-wavelength sources and detectors using quarternary III-V compounds should additionally permit repeater spacings of tens of kilometres and possibly 100 km—by the end of the decade.

Production by the mid-1980s of fibers and components using fluoride-based glasses will result in low-loss optical transmission lines utilizing the longer wavelengths, Walsh predicts.

uled for 1986, with 2-seater General Motors passenger EVs expected to be ready for the 1986-7 model year. GM electric vans are due on the market in 1983.

The greatest obstacle to widespread electric-car use is the battery: Today's models last only 30,000 mi (500 recharges) and cost \$1500 to \$2500 to replace.

However, by the early 1990s, Mathews predicts, powersource improvements should result in a power plant lasting the life of the car and providing a 150-mi range between charging cycles.

Early EVs will cost \$3000 to \$6000 more than their gasolinepowered counterparts, although this price differential should be halved once 250,000-unit-per-yr production levels are reached.

Material for this page developed from *Electronic Business* magazine and other sources by Jesse Victor, Assistant/New Products Editor, and Joan Morrow, Assistant Editor.

rld's widest selection of matching ratios 10KHz-800MHz...balanced, DC isolated, center-tapped 46 off-the-shelf models from Mini-Circuits from \$295



Select from the economical, microminiature T-series (plastic case) or TMO series (hermetically-sealed metal case) covering 10 KHz to 800 MHz. These models operate from 12.5 to 800 ohms with insertion loss typically less than 0.5 dB.

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DC ISOLATED PRIMARY & SECONDARY	Model No. Imped. Ratio Freq. (MHz) T Model (1049) TMO model (1049)	T1-1 TMO1-1 1 .15-400 \$2.95 \$4.95	1 8-300 \$4.95	T1.5-1 TMO1.5-1 1.5 .1-300 \$3.95 \$6.75	T2.5-6 IMO2.5-6 2.5 .01-100 \$3.95 \$6.45	T4-6 TMO4-6 4 .02-200 \$3.95 \$6.45	T9-1 TMO9-1 9 .15-200 \$3.45 \$6.45	T9-1H 9 2-90 \$5.45	T16-1 IMO16-1 16 .3-120 \$3.95 \$6.45	16 7-85 \$5.95
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UNBALANCED PRIMARY & SECONDARY	Model No. Imped. Ratio Freq. (MHz) T model (1049) TMO Model (1049)	T2-1 TMO2-1 2 .025-600 \$3.45 \$5.95	T3-1 TMO3-1 3 .5-800 \$4.25 \$6.95	T4-2 TMO4-2 4 .2-600 \$3.45 \$5.95	T8-1 TMO8-1 8 .15-250 \$3.45 \$5.95	T14-1 TMO14- 14 .2-150 \$4.25 \$6.75	1			
FT FTB · ↓ ↓ · ↓ ↓	Model No. Imped. Ratio Freq. (MHz) (1-4)	FT1.5-1 1.5 .1-400 \$29.95	FTB1-1 1 .2-500 \$29.95	FTB1-6 1 .01-200 \$29.95	FTB1-1-79 1 .5-500 \$29.95	5				

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