

Roger Ross on RISC



How much can Design-for-Test reduce the need for testing?

A new long-word architecture could outshine RISC

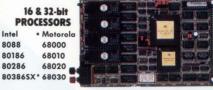
> DSP chips stalk industrial buses

16-bit MCUs diversify to survive

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• Intel



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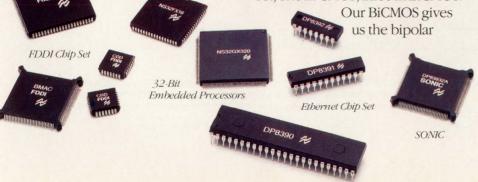
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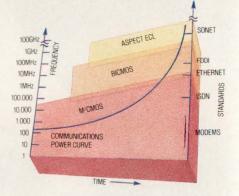
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NEWS BRIEFS NEWS BRIEFS NEWS BRIEFS NEWS BRIEF

FPGAs make AT&T first with complete ASIC line; TI to follow suit

This month the first field-programmable gate array (FPGA) from AT&T (Berkeley Heights, NJ) will hit the market—with more expected in October and November—as the result of an agreement with Xilinx (San Jose, CA). That makes AT&T the first semiconductor vendor to offer standard-cell, gate array (through a recent agreement with NEC) and FPGA technologies.

On the first of next month, Texas Instruments (Dallas, TX) will become the second vendor to offer these technologies when it begins shipping FPGAs as a result of its agreement with Actel (Sunnyvale, CA). TI, in fact, will be the first to offer standard cells, gate arrays, FPGAs and PALs. With ASIC designers looking to

With ASIC designers looking to prototype with FPGAs and explore implementation trade-offs, it's likely that other semiconductor vendors will be scrambling to expand the breadth of their product offerings. They'll be motivated not only by a desire to gain a piece of the action in FPGAs, but also by the fear of losing market share to a competitor that's migrating from one ASIC technology to another.

-Barbara Tuck

IBM and Sun settle RISC patent dispute

IBM (Armonk, NY) has recently cast a long shadow over the RISCbased processor vendors. The giant has reviewed the patents resulting from John Cocke's pioneering mid-'70s work on the 801 computer project, and concluded that a number of RISC vendors were violating IBM patents. The potential implications for the industry are, of course, enormous.

The first company to publicly respond to the IBM initiative is Sun Microsystems (Mountain View, CA). Sun has entered a cross-licensing agreement with Big Blue that will result in the workstation vendor paying royalties to IBM, presumably for revenues on Sparc products. It remains to be seen whether the Sun agreement will cover other companies that produce Sparc-based products. And an even bigger question looms over the fate of vendors that have created other RISC architectures—some of whom may choose, for financial or political reasons, to resist IBM's claim.

-Ron Wilson

IEEE takes another shot at the VHDL standard

A working group of the IEEE Computer Society has once again begun the task of producing a standard VHDL Language Reference Manual. Under IEEE regulations, an institute standard must be recertified every five years, and time is growing short for the original VHDL document, which was issued in December 1987.

The working group, laboring under the catchy title VHDL Analysis and Standardization Group (VASG), must produce a definition of language requirements and a language design, and then submit the results for balloting. They expect the balloting to begin in the fourth quarter of 1991.

Unlike the original round of VHDL work, which was driven primarily by the U.S. Department of Defense, the new version will include thoughts from European and Japanese sources-at least that's what VASG hopes. To this end, the group has included precisely one non-U.S. company in the membership of its six-member steering committee. Given this overture and the overwhelming indifference that European and Japanese managers have shown toward VHDL in the past, one is perhaps less than optimistic about the internationalization of the language.

-Ron Wilson

Futurebus + profiles: everyone wants one

One of the big virtues of the Futurebus + specification is that it allows for an unlimited number of profiles, or physical/electrical implementations. First came the A profile, strongly backed by the VME Industry Trade Association.

Then Digital Equipment Corp (Maynard, MA) came along with its own ideas. DEC pushed the Futurebus + working group into adopting an I/O-only profile of the bus—profile B. VITA has subsequently adopted both the A and B profiles. In addition, a profile for a desktop version of Futurebus + has reached the status of a working group.

But neither the A nor the B profile dictates how fast the bus should run—it's implementationdependent. John Theus at Tektronix (Beaverton, OR) believes a profile should exist that specifies minimum performance; he's now heading up a working group for a profile F—for fast. Profile F, now raised to the status of a working group, is looking to develop a specification for a bus with a minimum transfer rate of 500 Mbytes/s.

At the same time, the Navy (one of the movers in the early adoption of Futurebus +), decided it should have its own profile, and so has come up with a profile M—for, guess what? The Navy's looking at SEM E (approximately 6×6 in.) and SEM F ($6U \times 160$) board sizes.

And not to be left out, the telecom makers, headed by Ameritech (Rolling Meadows, IL), are looking for their own profile T, which will probably fit on some largersized card to accommodate all the redundancy that will certainly be part of the profile. Both the M and T profiles have been raised to working-group status. —*Warren Andrews*

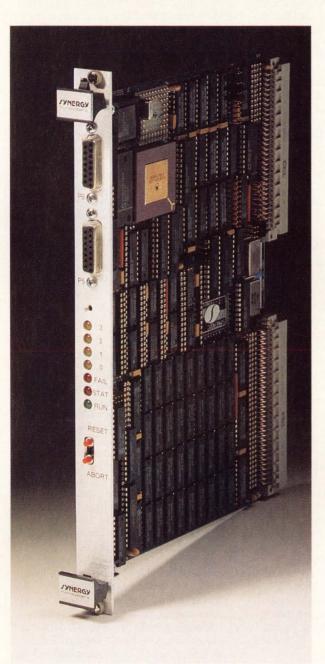
Mixed-signal ASIC market to explode in the '90s

The Mixed-Signal ASIC Market Study recently released by Electronic Trend Publications (Saratoga, CA) reports that total worldwide sales for mixed-signal ASICs will increase from \$557 million in 1989 to \$2.8 billion by 1994, with the United States forecasted to hold the lead.

While continuing to be the largest market sector, telecommunications will absorb a smaller portion of the total, with roughly 30 percent of the mixed-signal ASICs (down from 35 percent in 1989) going into modems, fax machines and LANs. Consumer, medical and automotive markets will be the fastest growing and will account for 28 percent of

(continued on page 10)

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(continued from page 8)

sales by 1994, followed by computer peripherals at 27 percent. The remaining percentage of mixedsignal ASICs will be in the rather stagnant military/space and industrial control markets.

Designers of mixed-signal parts report, though, that their most pressing requirements still remain. Among those requirements are the ability to simulate all interaction between analog and digital circuitry, including accuracy for analog; good modeling tools for chip and system simulation; mixed-signal testers; and a test methodology from ASIC vendors. -Barbara Tuck

WinSystems breaks price barrier with STD PC

Amidst the mad rush for higher performance and more features, at least one company is turning the other way, making a low-cost, PCcompatible STD Bus-based board as an inexpensive drop-in solution for many embedded-control application problems.

Designed to operate either as a stand-alone single-board computer or as a host CPU supporting additional STD Bus I/O cards, the new board from WinSystems (Arlington, TX) is designed to sell for under \$200 in OEM quantities, making it one of the lowest-priced PC-compatible single-board computers.

Although the new board doesn't have the sparkle of the company's full-featured 286- and 386-based versions, it has enough performance and I/O to tackle a variety of control applications normally relegated to far more-expensive devices, according to Bob Burckle, WinSystems vice-president. The board is based on NEC's V40 processor and features three memory sockets for up to 1 Mbyte of storage. -Warren Andrews

DEC offers third-party database for CAE

Digital Equipment Corp (Maynard, MA) continued its foray into the software marketplace by agreeing to jointly market Objectivity/DB, an object-oriented database management system (OODBMS) from Objectivity (Mountain View,

CA). The move gives DEC a software option to complement its Rdb/VMS relational database management system, while opening up DEC's distribution network for Objectivity.

The OODBMS also gives DEC a software product to offer to CAD/ CAE/CASE customers along with its PowerFrame package, a framework technology that DEC acquired when it purchased EDA Systems (Santa Clara, CA) earlier this year. Objectivity/DB has already made inroads into the CAD marketplace, particularly since being adopted by Valid Logic Systems (San Jose, CA) as the OODBMS for its Design Process Framework. -Mike Donlin

TI seeks to license new 3-D display technology

Texas Instruments (Dallas, TX) is looking for partners to help develop applications and markets for a new laser-based true spatial 3-D display technology it calls Omni-View. OmniView lets viewers observe an image from any angle within the display volume.

The system consists of a translucent double-helix disk mounted at an angle on a shaft and rotated to create the display volume. A lowpower laser scans two dimensions and shines its beam on the disk. A spot of light appears where the beam strikes the disk. The distance of the disk's surface from the light source, and hence the position of the spot in the third dimension, is determined by the rotational position of the disk.

In the prototype shown by TI, the disk rotates at 600 rpm, and the laser scans a raster of 750×750 pixels. Larger displays are feasible, and color displays can be made by using red, green and blue lasers.

-Tom Williams

Sematech discovers Malcolm Baldrige

Sematech, the often-controversial consortium to boost U.S. competitiveness in semiconductors, has begun beta testing a new management program called Total Quality. The program consists of a series of assessments and training programs intended to focus an entire organization on the process of meeting customer needs. It's interesting that the structure of the program is based on the application guidelines for the Malcolm Baldrige National Quality Award. Coincidentally, the terminal step in the Total Quality process as outlined by Sematech is to apply for the award.

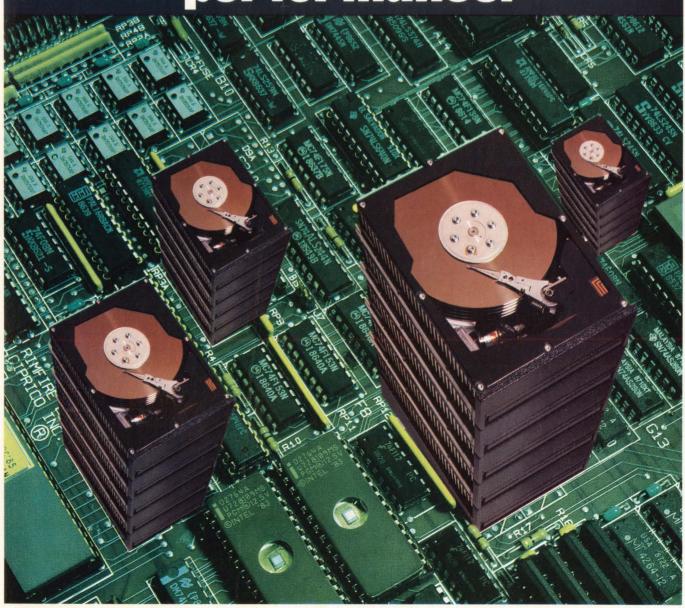
Apparently Sematech has come to believe that an organization's ability to partner with its customers and to produce quality productsby the customer's definition-are at least as significant to competitiveness as modern equipment and the latest processes. As the Total Quality program moves from Sematech into the industry, it will be interesting to see whether a qualitynurturing culture can be imposed on organizations by cookbook, and if so, whether the Baldrige Award application form has the right -Ron Wilson recipe.

New RAMDAC enhances VGA resolution

Image quality of VGA color displays can be enhanced with an antialiasing RAMDAC jointly developed by Edsun Laboratories (Waltham, MA) and Analog Devices (Norwood, MA). The digital-to-analog converter, called a continuous edge graphics D-A converter (CEG/ DAC), comes in a triple 6-bit version; a triple 8-bit version with a 256×24 -bit color lookup table; and a version with a 256×18 -bit color lookup table. All are completely VGA- and PS/2-compatible.

With only a modified software driver, the D-A converters can look at the transition between two screen colors and place interpolated color values into the pixels along the edge so that the eye perceives a smooth line without "jaggies." Analog Devices claims that a 320×200 pixel VGA display has an apparent resolution enhancement of 1.280×1.024 pixels. But no additional information is on the screen, as there would be with an actual increase in pixel resolution. The parts are pin-compatible with RAM-DACs now used in VGA graphics board designs. -Tom Williams

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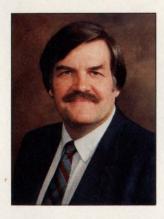
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Our why-to editorial attempts to place options in perspective and provide insights into technology and design directions.



John C. Miklosz Associate Publisher/ Editor-in-Chief

Touting our uniqueness

his issue of *Computer Design* boasts a new look. Or the cover, at least, boasts a new look. While we have a lot of fun coming up with the ideas for covers, we didn't change the look of the cover just for fun. We changed it because we had something to say.

For a few years now, *Computer Design*'s covers have borne some variation of the tag line "The first magazine of system design, development and integration." A magazine's tag line is intended to summarize, in as few words as possible, what's at the heart of the magazine—its reason for being, if you will. The words "The first magazine of system design, development and integration," emphasizing our focus on hardware design, software development and hardware/software integration, accomplished just that. The problem, however, is that there are other publications, some of which you may receive, that cover much of the same territory.

Having conceived *Computer Design* 30 years ago, we like to believe that we were the first publication to tackle the hardware, software and hardware/software integration problems associated with the design of computer-based systems. Today, most of those systems are microprocessor-based, and *Computer Design* has stayed in synch with this evolution, bringing its system-level viewpoint to bear on the design of all sorts of products based on microprocessors and other ICs, single-board computers and even OEM computers. And while the tag line "The first magazine of system design, development and integration" defines the subject matter we cover, it doesn't say anything about *how* we cover it.

The many publications that serve your information needs fall essentially into three categories. On one hand, there's news, which provides the fundamental information of who, what, when and where. On the other hand, there's "how-to" editorial, which provides implementation-level detail. And then there's what we like to call "why-to" editorial. In contrast to news and how-to, why-to editorial attempts to make comparisons, place options and tradeoffs in perspective and provide some insights into technology and design directions.

As a regular reader, you already know that *Computer Design* is firmly in the why-to category. That's what makes us unique, and we've decided to start touting that uniqueness. The key part of our new tag line, "Technology and design directions," is what whyto editorial is all about. And just as why-to editorial and technology and design directions are an integral part of our editorial approach, we've now made technology and design directions an integral part of our masthead.

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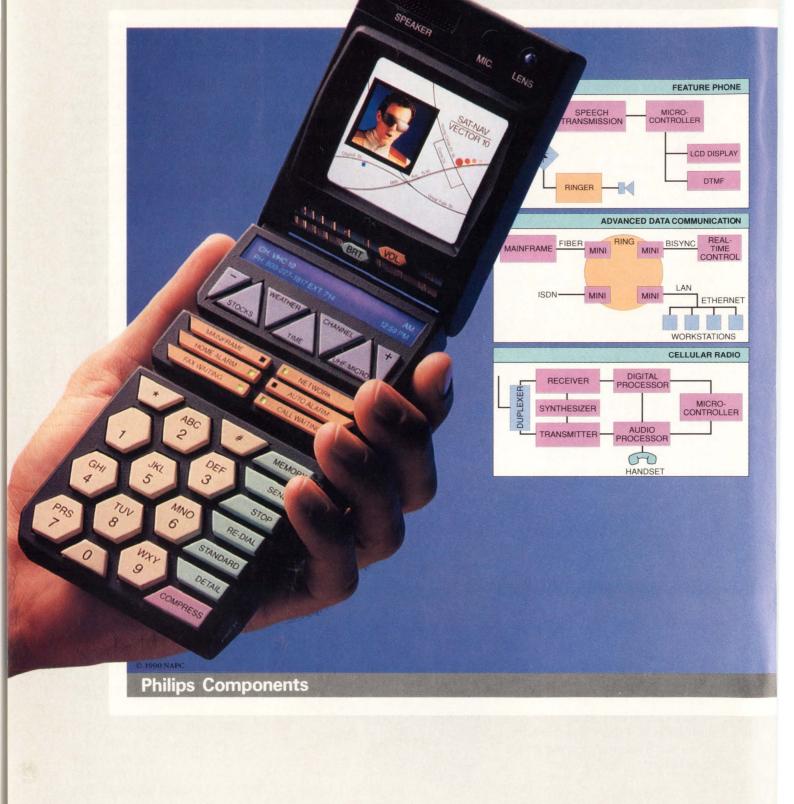


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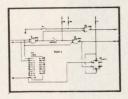
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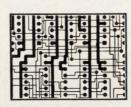
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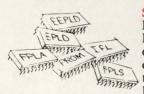
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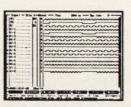
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October 15-18 Buscon/90-East

Royal Plaza Trade Center, Marlborough, MA. This conference for bus board and systems-level technology will highlight issues and applications for embedded-systems programming, VME, Multibus II, PC bus platforms, emerging architectures and military applications. The exhibit will include over 200 booths featuring board- and systems-level components and software. Information: Conference Management Corp, 200 Connecticut Ave, Norwalk, CT 06856, (203) 852-0500. Circle 368

November 6-9 Software Development '90-Fall

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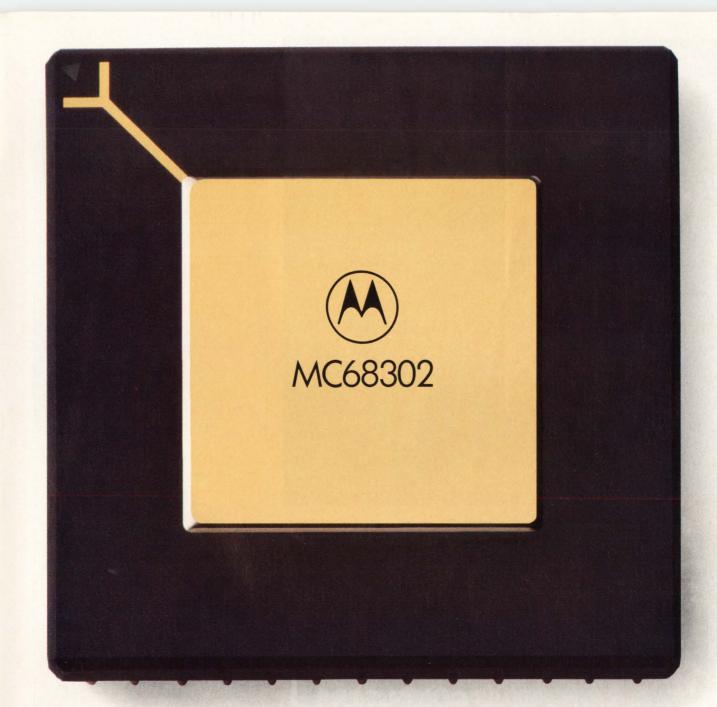
ference will offer over 60 lectures and workshops in four areas: object-oriented programming, management, design methodologies and Clanguage. A exhibition of software and development products and services will also be featured. An optional one-day seminar will focus on how to build, organize and manage more-effective project teams. Information: Software Development Seminars, 500 Howard St, San Francisco, CA 94105, (415) 995-2472. Circle 369

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November 14-16 PROCIEM '90

Hyatt Regency Westshore, Tampa, FL. "Surviving in the '90s: CIEM in a New World Marketplace" is the theme of this year's conference on Productivity through Computer-Integrated Engineering and Manufacturing. The technical program will include panels on industrial applications in CIEM and NFS strategic marketing initiatives. Sessions will address issues of flexible manufacturing and knowledge-based systems, and design for manufacturability. Information: PROCIEM '90, Box 25000, Orlando, FL 32816-0177, (407) 249-6100. Circle 372



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Roger Ross on RISC

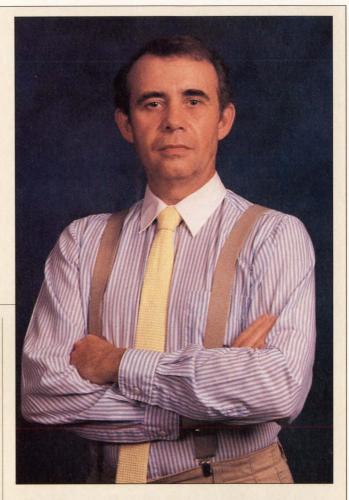
Much has been written about RISC's superiority over CISC. Many authors, myself included, have espoused the inherent strengths of RISC's instruction-set architecture strengths that are now leading to rapid market share growth for RISC at the expense of CISC. Without exception, however, the many articles written about RISC from an applications perspective have been incomplete and somewhat disjointed. This is unfortunate, since the applications perspective is, in fact, the perspective of the end user.

The real question to be addressed isn't, "Which applications will RISC architectures penetrate?" but rather, "At what rate will RISC penetrate applications currently using CISC?" It's possible to break down the latter question along structured lines, first by reviewing the applications currently served by CISC architectures, and then by discussing the current and projected associated levels of penetration by RISC architectures.

RISC has penetrated five major applications areas to date: large-scale central processors (mainframes, supercomputers and massively parallel computers); medium-scale central/node processors (minicomputers, servers and fault-tolerant on-line transactionprocessing systems); small-scale personal processors (desktop and laptop systems); embedded control for computer peripherals (laser printers, copiers, highend disk and tape control, datacommunications control, X-terminals, circuit switching, add-in boards, imaging and graphics control); and specialized embedded control (automotive systems, such as engine control and antilock braking; cellular phones, pagers and telephone handsets; smartcards; cameras and other consumer electronics goods; and robotics).

Least obvious market

Large-scale central processors are the least obvious applications to be penetrated by RISC. That's because the majority of the revenue in this area currently comes from sales of IBM's mainframes and the IBM plug-compatible mainframes, and the IBM machines are modeled on a classical CISC architecture. Nonetheless, RISC has already begun to reshape the



mainframe market, both through market dynamics and through architecturally transparent applications software methods.

Many market researchers have stated that growth in the classical mainframe market has slowed over the last 10 years to the point of virtually stopping. Much of this slowdown can be attributed to the change in computing away from batch processing on isolated, centralized mainframes and toward interactive computing on client-server networks. In this new computing structure, client systems (small-scale systems such as personal computers and workstations) are networked to server systems (such as file servers, network servers and compute servers), and almost all new growth in new applications is occurring at the the client-system level.

Recognizing this fundamental change, mainframe manufacturers first attempted to reposition their systems as central file servers, but purchasers responded with mixed interest. Like all value-conscious consumers, these purchasers wanted to maximize price/performance and utility within their budgets. With amazing frequency, companies that would normally have purchased CISC mainframes for their central file servers chose high-end RISC-based computers instead.

So manufacturers of classical CISC mainframes are now responding to the price/performance assault of high-end RISC-based servers by themselves moving to RISC. The mainframe manufacturers, however, must strive to keep binary compatibility so that they can keep their customers locked into their proprietary application software bases. CISC mainframe manufacturers, therefore, have begun the move to RISC by using RISC technology at any and all points within the mainframe where this can be accomplished in a transparent manner. This hybrid approach, however, is less cost-effective and will lose market share in the long run.

Unlike the mainframe market, the market for medium-scale central/node processors has been conspicuously penetrated by RISC. Such mainstream medium-scale system suppliers as IBM, Digital Equipment Corp and Hewlett-Packard have already introduced, or will introduce in the next 18 months, RISC-based systems that significantly overlap their CISC products. In addition to offering more aggregate performance than their CISC products, these vendors' RISC products have price/performance ratios that are 5 to 100 times better than those of their CISC offerings. But IBM and DEC, when their RISC systems are fully in place, may find themselves facing the precarious situation of potential revenue collapse, since they replaced expensive low-performance systems with significantly less expensive high-performance systems.

Besides IBM, DEC and HP, many other, more-aggressive companies have targeted the medium-scale computing area. These companies realized right from start that systems based on inexpensive, commercially available RISC microprocessors would dramatically out-price and out-perform proprietary CPU architecture-based systems. They're all rapidly moving to RISC, having designed their systems with an open architectural migration in mind. Companies in this category include Sun Microsystems, which is developing a RISC central file server; Sequent Computer Systems, which is developing a RISC multiprocessor database server; and Solbourne Computer, Stratus Computer, ICL and Pyramid Technology, which are producing RISC multiprocessor servers. This list is by no means exhaustive, but it's significant that all of these vendors have endorsed RISC.

From a segment market share perspective, more than 75 percent of medium-scale central/node processors will be served by RISC architectures by 1995.

Aggressive growth predicted

Several market researchers reported this year that small-scale computers have become the single largest revenue-producing segment of the entire computer industry. Coincidentally, this segment produces the largest amount of aggregate revenue for suppliers of 16-/32-bit CISC VLSI semiconductor products if one takes into account both the shipments of microprocessors and the shipments of all the central processor chip set functions: integer and floating-point units, memory-management units, cache control and firstlevel cache subsystems.

To date, the aggregate of RISC system unit shipments has amounted to less than 1 percent of the total system shipments within this segment; but this situation is changing rapidly. According to Ross Technology, RISC system shipments as a percent of the total small-scale system shipments segment are estimated to grow by more than 5 full percentage points annually for the next 10 years, resulting in RISC systems' constituting over 50 percent of the small-scale systems market segment by the end of the decade.

Several factors play a role

There are six factors facilitating the rapid market share gains of RISC system shipments in this market segment: the saturation and maturation of the IBMcompatible PC industry; the IBM-compatible industry's reliance on Intel's proprietary CPU architecture; the adoption of RISC by nearly all of the major computer manufacturers; the advent of open RISC architectures; the movement of RISC systems to the desktop; and the availability of shrink-wrapped RISC software.

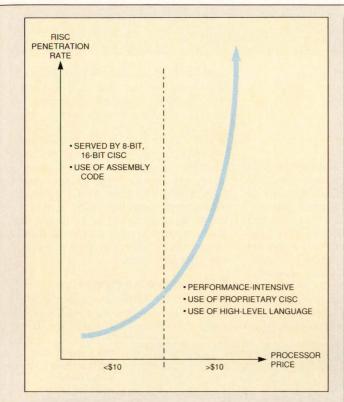
As the IBM and compatibles PC industry nears its tenth year of existence, it's clear that this industry's growth rate has slowed dramatically and that profit margins have been strained accordingly, resulting in an inevitable industry shakeout. The majority of IBM PC and compatible suppliers' market share has coalesced around less than 10 companies. As a result, new companies aren't participating in this market subsegment and are migrating to RISC.

Regarding the second factor, the 80386 and 80486 processor introductions demonstrate Intel's strategy to provide the market with sole-sourced, proprietary microprocessor products. While this approach ensures Intel extraordinary profits in the short term, it also results in lost profits (and lost reinvestment potential) for IBM-compatible manufacturers, whose system selling prices are determined and strictly limited by the market. Intel's strategy also serves to stifle competition and innovation: system vendors are unable to differentiate themselves by producing various 80X86 implementations. The end result is that Intel's strategy is facilitating a more rapid adoption of RISC than might naturally occur.

In fact, there can be no more clear evidence of the movement toward RISC than the wholesale adoption and endorsement of RISC by nearly every major manufacturer of computer systems. In the context of small-scale computers, this movement in itself is a facilitator of the further adoption of RISC architectures by this segment. In other words, offering RISC systems in this market segment is quickly becoming a market requirement.

The availability of open RISC architectures in general, and Sparc in particular, will lead to "microarchitectural" competition: that is, many microprocessor suppliers will be designing RISC implementations in parallel. This explosion in innovation dramatically benefits not only the smallscale market segment by providing system suppliers with multiple, binary compatible choices for the system CPU, it also benefits the other market segments discussed in this article, as there will be a natural market segmentation among microprocessor designs. The combined R & D investment of suppliers designing to open RISC architecture standards is quickly beginning to dwarf the investment that is affordable by proprietary microprocessor suppliers.

Within the past 12 months, the industry has seen the introduction of RISC systems priced for the mass market. Though the majority of these products are in



RISC architectures will have their greatest impact in sophisticated, high-performance systems, rather than in the embedded control area, which is amply served by inexpensive 8- and 16-bit microcontrollers.

the \$5,000 to \$10,000 range, they are also quickly moving to sub-\$5,000. This price point will be crossed within the next 12 months. As was shown by the personal computer industry, computer shipments increase logarithmically in relation to decreases in selling price. RISC system shipments in 1990 will increase approximately 5 times over unit shipments in 1989, in part due to the decrease in average RISC systems selling price.

Today, the most expensive aspect of computer system development is the cost of porting application software. To establish an application software base with a breadth large enough to significantly penetrate the small-scale systems market, however, requires an investment of billions of dollars. Certainly, this is impossible for any one company to afford.

Because of this fact, several RISC vendors are attempting to create a shrink-wrapped software market for their architectures, analogous to that available for the Intel 80X86 architecture. So far, only the Sparc RISC architecture has successfully demonstrated a shrink-wrapped application software base that can run unchanged on the machines of multiple small-scale system vendors.

Cracking embedded control

In the past year, there has been a tremendous amount of discussion about the movement of RISC into embedded control applications. Many microprocessor vendors are exclusively targeting embedded applications and ignoring the central processor chip market. These vendors claim that the embedded control market dwarfs the central processor market. This is absolutely the case in unit terms, but it's not true in aggregate revenue terms, when one includes the revenue obtained from sales of the entire central processor chip set.

Another fact demonstrating the fallacy of exclusively targeting embedded control is that the majority of embedded applications (97 percent of the units and 83 percent of the revenues) are served by 8-bit microcontrollers whose average price is less than \$3.50. At current semiconductor learning curves, it will take through this decade for RISC implementations to achieve prices in this range. It therefore seems likely that microprocessor vendors choosing to exclusively target embedded control do so out of an inability to successfully penetrate the central processor market. In reality, architectural standardization flows out from the central processor. To win in embedded control, a microprocessor supplier must first win in central processing.

Of course, this doesn't make embedded control a virtual nonmarket for RISC architectures. The point of these comments is simply to reinforce the fact that accurate market penetration projections should be based on the actual underlying market situation.

In the short term, RISC will successfully penetrate the computer peripheral portion of the embedded control market. This portion is the high end of this market segment, and typical applications share the characteristic that performance is a higher-priority criterion for system designers than price.

A significant number of the applications in this area are also sensitive to "central CPU architectural pullthrough"; that is, designers of computer peripheral embedded subsystems (such as disk or datacomm controllers) are often influenced in the architectural selection for the embedded controller by the architecture used in the central processor of the system to which the peripheral will be interfaced. This phenomenon is largely a matter of convenience, since designers can significantly boost their productivity if they develop software on a system based on the same architecture that the embedded target system will use.

RISC architectures have received much press exposure in this market segment and, in fact, provide optimal solutions for these applications, easily surpassing the price/performance offerings of CISC in these areas. This market segment will be largely penetrated by RISC within the next three years.

On the other hand, RISC will be less quick to penetrate the market for specialized embedded control applications. In these applications, the embedded controller acts as the central processor of a self-contained system. The primary selection criteria for the central embedded control designer are price and available peripherals. Over 500 million central embedded controllers are sold each year at an average selling price below \$3.50.

RISC's penetration of this market segment will be slow, picking up speed only toward the end of the decade. At that point, RISC chips will be sold in the sub-\$5 price range, and will support the type of onchip peripherals needed for these applications.

Roger D. Ross is president and chief executive officer of Ross Technology (Austin, TX).

INTEGRATED CIRCUITS

New long-word architecture threatens to outshine RISC

Ron Wilson, Senior Editor

he struggle between RISC and CISC has degenerated into trench warfare, with both architectural concepts holding on to well-defended application segments. But now an agreement between Atmel (San Jose, CA) and technology start-up Teraplex (Champaign, IL) promises a new microprocessor architecture, perhaps two generations beyond RISC, that could outflank both of the foes. The Minimum Instruction Set Computer (MISC) may be able to execute both RISC and CISC binaries faster than the CPUs for which they were written.

On the surface, the Atmel/Teraplex agreement seems like a simple technology exchange. Teraplex, a company primarily engaged in parallel-processing research, is looking for a vendor with both a hot CMOS process and excellent packaging technology to fabricate its pinhungry computing elements. Atmel is a growing CMOS house without a major CPU in its product line.

But why would Atmel, generally a low-profile, conservative firm, venture off into parallel computing? The industry is, after all, strewn with the remains of exciting parallel-processor architectures that died looking for a profitable application. And why should a busy engineering manager care what Atmel builds for a research company? A coherent answer to these questions requires a close look at the Teraplex architecture.

Two steps from RISC

Perhaps the best way to understand the MISC architecture is to think of it as an evolution from RISC theory. From RISC, the new thinking draws at least two important concepts. First, RISC introduced the idea of short, simple instructions that could execute in a single machine cycle. Second, the RISC advocates proposed instruction scheduling—rearranging instructions in a program to keep the pipeline full as long as possible.

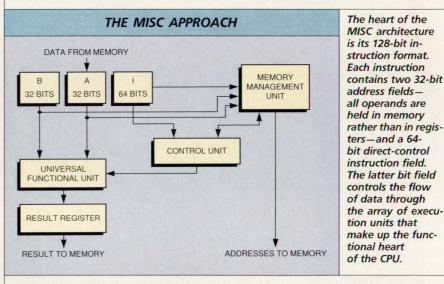
These two concepts fit nicely into the next stage of evolution, the socalled superscalar architectures. In these machines, a number of independent RISC pipelines are combined into one CPU. Hardware in the control unit fetches instructions—often several at a time—and decides which of the available pipelined execution units can accommodate which of the pending instructions. Thus under ideal conditions the CPU can execute several instructions on each machine cycle.

A refinement of the superscalar approach has received a lot of atten-

achieve high levels of parallelism. The compiler can pack operations into the long instruction words in such a way that most pipelines are full most of the time. But in practice, VLIW machines have demanded complex compilers, have had trouble running at high clock rates, and have been unable to get much benefit out of more than three or four concurrent execution units. The latter problem seems to be inherent in the structure of computer programs, rather than caused by hardware or compiler limitations.

Opening up the pipeline

In a way, the MISC architecture is a blend of superscalar and VLIW concepts. Like the VLIW machines, Ter-



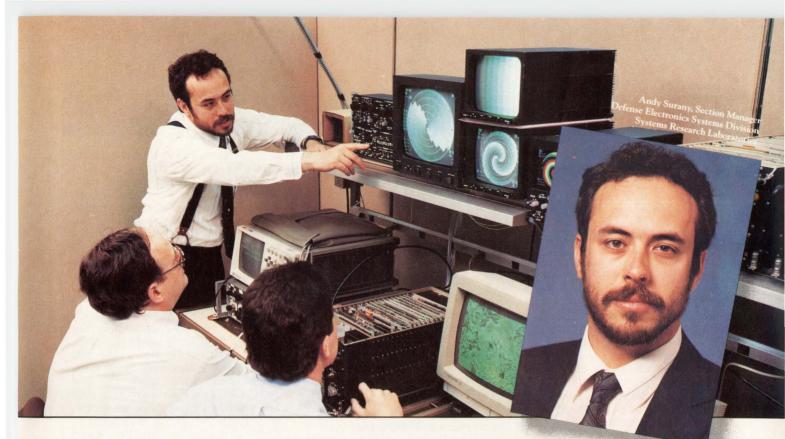
tion in academic circles. Some architects point out that in a superscalar machine the sequence of instructions has great influence over the amount of parallelism the CPU can achieve. So it doesn't make much sense to leave the instruction scheduling to chance. The advocates of this school suggest that, instead of a whole series of short instructions that get assigned to pipelines at run time, the machine use very long instructions containing one opcode for each execution unit in the CPU. The compiler can then pack operations into the long instructions at compile time, coming closer to optimum use of the execution units. These very long instruction words give the architecture its name: VLIW.

In theory VLIW machines should

aplex's MISC uses a long-128-bitinstruction to control a number of execution units simultaneously. But the MISC architects have simplified the execution units until they perform rudimentary tasks that Teraplex calls "atomic instructions."

"We use only nine generic operations," says Teraplex president Philip McKinney. "Essentially, there is a functional unit in the CPU for each type of operation. In each instruction, a 64-bit field determines how data will flow through the functional units on that clock cycle. The instruction bits control the hardware directly and therefore there is no decoding delay."

This arrangement gives the compiler control not only of instruction ordering, but of the sequence of the



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TECHNOLOGY UPDATES

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operations that would make up the pipeline in a RISC machine. With this much control, and with the atomic operations carefully defined to be nonoverlapping, the architecture virtually eliminates the possibility of resource contention within the CPU.

Thus the MISC CPU executes code as a series of tiny, direct-control operations fed in parallel to all the functional units. "You can think of the machine as running at the microcode level," suggests McKinney. Because the functional units are simple, flow-through devices, many of the register, gate and clock-skew delays encountered in RISC pipelines simply don't exist. This allows the MISC machine to operate at extremely high clock frequencies, and at least potentially to achieve far greater performance than CISC or RISC machines doing the same tasks on the same technology.

But there is also a clear disadvantage to the technique-it is memoryintensive with a vengeance. What in a RISC machine would be one 32-bit instruction may in the MISC machine balloon into several 128-bit instructions. Of course a good compiler will be able to pack portions of several different instructions into those few big words, so a one-to-one comparison is difficult. But Atmel marketing vice-president Jeff Katz admits, "Memory size requirements go up by a factor-something bigger than one and less than 10. But memory speed requirements aren't that great. We envision reasonably fast conventional SRAM caches and then a large pool of DRAM somewhere."

Parallelism and emulation

One of the most unique things about the MISC architecture is that the CPU is designed to be an element in a massively parallel computer system. The processor chips can be used in arrays, connected by crossbar-like global switching chips, with what McKinney describes as "a revolutionary method for addressing global and local memory." One facet of the scheme is that the CPUs have no registers—all operands are stored in memory.

This means that an array of MISC CPUs would have two remarkable characteristics. First, all CPU hardware would be exposed to the compiler at the pipeline stage level. Second,



Philip McKinney, president of Teraplex, examines simulation runs on the company's CPU chip. "One thing we've done in simulations," he says, "is to take foreign binaries, break them into atomic instructions and run them on our chip. One MISC chip can execute 80386 code 4.5 times faster than a 33-MHz 386 can."

all operands, including temporary results, would be exposed to all CPUs via the switching net. The combination of these two attributes makes possible a unique capability, according to McKinney: "We can do parallel scheduling at the instruction level."

In effect, the compiler can break a program down into CISC-level or even RISC-level instructions, then schedule different instructions to different CPUs in the system. In many cases, the compiler could even spread parts of a single CISC instruction across several CPUs. The power of this capability shows up quickly in an example.

"One thing we've done in simulations," McKinney says, "is to take foreign binaries, break them into atomic instructions and run them on our chip. One MISC chip can execute 80386 code 4.5 times faster than a 33-MHz 386 can. And in a multiple-MISC system, we can schedule pieces of 386 instructions to run in parallel on separate CPUs, and achieve speed improvements just short of the theoretical bound. All this is possible because we're doing the parallel extraction at the atomic instruction level, not the source instruction or subroutine level."

A range of promises

There are clearly several potential uses for the MISC machine. First, there is the application probably intended by the designers: massively parallel computers. Because of its extremely fine granularity and simple hardware, MISC parallel computers should be able to achieve both a higher parallel-performance multiplier and a higher operating frequency than those of most parallel architectures.

Second, and more intriguing for most designers, is the possible application to workstations. A MISC workstation could theoretically straddle the fence between IBM PC and RISC compatibility, executing binaries from both sources. Again, because of the compiler power and high clock frequency, the MISC CPU might well outrun both PC and RISC CPUs on their own code. And the workstation would be moderately scalable by simply adding more CPUs and recompiling. Users could expect nearly linear performance gains even on single-task systems.

But such promises are far from sure things. While MISC seems to be leading in the direction in which RISC and VLIW pointed, excellent architectures have failed to deliver the goods before. And any widespread acceptance of MISC is clearly predicated on continued erosion in memory costs. A PC five times faster than a 33-MHz 386 but with eight times the memory cost might not be a clear winner.

Finally, there are the issues that militate against the success of any new architecture: unfamiliarity, lack of tools and support, and lack of application code. Atmel will be working to overcome these. "Teraplex will originate the technical support for the chip, but we have time to get a strong organization in place by the time chips come out next year," says Atmel's Katz.

From Atmel's point of view, and from the perspective of design managers in the PC, workstation and server businesses, MISC represents far more than a fab agreement. Potentially, the new architecture could be the vanguard of the next generation in computing technology. \Box

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INTEGRATED CIRCUITS

Denser, faster FPGAs encroach further on masked gate arrays

Barbara Tuck, Senior Editor

n a market where a product can be a dinosaur 18 months after it's first shipped, design teams are being encouraged to explore alternative, cost-effective technologies to speed product development. Considering the limited number of users having the expertise to design masked gate arrays within a tight time schedule and budget, it's not surprising that the market for desktop-configurable field programmable gate arrays (FPGAs) is exploding.

Indications are that the programmable parts are striking ever deeper into masked gate array territory. Denser devices about to be shipped by Actel (Sunnyvale, CA) and Xilinx (San Jose, CA), along with the first FPGA device offered by Plessey Semiconductors (Scotts Valley, CA), are likely to fuel that activity. Advances in technology make this second generation of FPGAs an even more feasible design alternative to masked gate arrays, especially as prototype vehicles and for small production runs.

Actel confirmed last month that

it's in beta test with a new family of 1.2-µm CMOS nonvolatile FPGAs, to be shipped next quarter. Like earlier devices, the ACT 2 family is based on PLICE antifuse programming links and channeled gate array architecture. In comparison to the company's earlier devices, the new family's densest device, the A1280, is four times larger and has twice the speed (system-level performance up to 60 MHz) and twice the I/O capacity. The A1280 has 8,000 masked-gate-array-equivalent gates and 750,000 tiny PLICE antifuse elements.

Basic logic modules have been enhanced to accommodate functions that have up to seven inputs, and a new logic module optimized for configuring sequential macros accommodates a latch or flip-flop and/or many combinatorial macros of one to seven inputs. State machines with up to five five-input product terms require only two module delays with the enhanced architecture.

Actel has also increased routing resources by boosting the number of

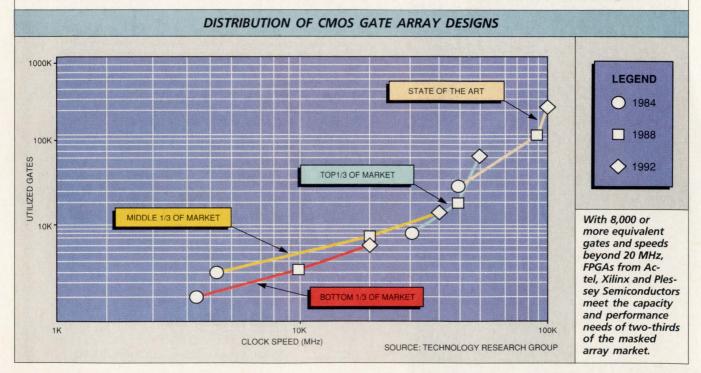
horizontal routing tracks per channel to 36 and vertical tracks per column to 15. To make performance more predictable, the vertical routing architecture has been modified to reduce from four to three the maximum number of antifuse elements required to make a connection. Speed-critical module-tomodule connections involve only two antifuse elements.

Higher-density FPGAs of up to 16,000 equivalent gates are being developed by Actel and Hewlett-Packard in HP's 0.8-µm process. HP will use the FPGAs as prototype vehicles for its standard-cell designs. No estimate of availability has been given.

Gate-counting games

Formidable competition for Actel parts will continue to come from FPGA market leader Xilinx, also preparing to ship a new generation of programmable parts. Compared to earlier Xilinx parts, the XC4000 submicron CMOS Logic Cell Array family, to be available next month, has twice the density, twice the speed (60 to 70 MHz), plus on-chip data SRAM. The densest of the new RAM-based reprogrammable Logic Cell Arrays is 20,000 gates.

Actel counts its gates in such a way that the number of gates of an



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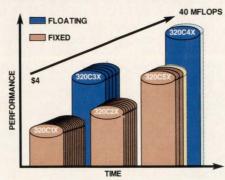
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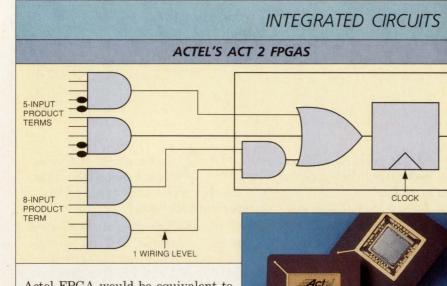
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TECHNOLOGY UPDATES



Actel FPGA would be equivalent to the number of gates of a masked gate array of the same gate count from LSI Logic (Milpitas, CA). Actel claims that architecture and routability differences between Actel and Xilinx parts make a 20,000-gate Xilinx device comparable to Actel's 8,000-gate device. But Chuck Fox, Xilinx director of IC marketing, counters that claim. "Though density is application-dependent," Fox says, "customers have gotten 20,000 gates out of the device."

Among enhancements to the Xilinx Logic Cell Arrays is an increase from five to nine combinatorial inputs for each configurable logic block. (Metal lines of programmable switching points and switching matrices connect logic blocks.) Two separate groups of four inputs each drive their own function generator, actually a small ROM lookup table. A third function generator can combine the outputs of the first two with the ninth input. Each trio of function generators can be programmed 32 billion different ways. Moreover, each four-input function generator can be configured as a two-bit adder with a built-in hidden carry that can be expanded to any length.

This fast carry logic can put two counter bits into each configurable logic block and run them at a clock rate of up to 50 MHz (for 16 bits), regardless of whether the counters are loadable. For a 16-bit loadable counter, that translates to three times the speed of XC3000 parts in half the number of logic blocks. Furthermore, the speed of the dedicated carry circuitry makes it possible for a 16-bit adder/accumulator, requiring eight configurable logic blocks, With the ACT 2 FPGA family from Actel, users can configure a section of a state machine in five modules for up to 70-MHz performance. The A1280, the densest member of the ACT 2 family, contains more than 750,000 antifuse programming elements, 1,232 logic modules, up to 994 flip-flops and 140 user I/Os.

to have a combinatorial delay of only 20 ns. That's in contrast to 30 blocks and a 60-ns delay—or 41 blocks and 33 ns—for the same implementation in the earlier XC3000 family. Xilinx has also doubled the number of horizontal and vertical long lines that carry signals across the length or width of its Logic Cell Array.

Since the Logic Cell Arrays are based on a RAM process and all Xilinx circuits store their configurations in RAM, Xilinx has given users of the XC4000 family access to these distributed memories. The user determines whether configurable logic blocks are dedicated as RAM (organized in arrays of 32×1 bit or 16×2 bits) or as ROM-based logic. Read access time for the on-chip memory is the same as logic delay, about 5 ns, and write time is about 10 ns. This distributed RAM can be used for registered arrays of multiple accumulators, DMA counters, and FIFO buffers. A 32-byte FIFO, for instance, would use eight configurable logic blocks for storage, six for address counting, and one for arbitration.

While Actel promotes its FPGAs

for prototyping and small-production runs, Xilinx targets a different customer, according to Lee Farrell, Xilinx vice-president of marketing. "Xilinx is in business to sell production volumes. We have customers buying thousands of Logic Cell Arrays a month-the per-unit cost is higher than a gate array, but there is no NRE. But if you prototype with one, it's not that easy to take it out and plug a gate array in. Customers have to ask themselves whether they want to redesign their previous project or go to work on their next design."

A new player

The already heated FPGA market has a new entry—Plessey Semiconductors—with its sea-of-gates Electrically Reconfigurable Arrays (ERAs). Like the Xilinx Logic Cell Arrays, they're RAM-based solutions. Plessey is now shipping the

The time is ripe for believing in FPGAs that don't involve resimulation and reiteration, not to mention endless test vectors.

1.4- μ m 10,000-equivalent-gate 60100, and the company says that its three-layer-metal 1.4- μ m process with stacked vias and equal pitch on all metal layers—will later be used for a 40,000-gate part. Beyond that, Plessey plans to shrink the same architecture into a 1- μ m process for 80,000 gates, and then down to 0.8 μ m for up to 160,000 gates. Since the Plessey parts offer cell libraries compatible to the company's CMOS masked gate arrays, they may appeal to designers looking for an easy migration path.

The density of the Plessey parts is attributed to the granularity of the logic. Each cell in the matrix is programmable as a single NAND gate or latch. "Higher gate counts are possible with ERA technology," says Steve Brightfield, ERA market-

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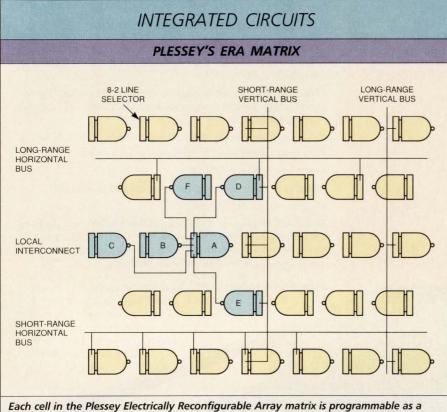
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Each cell in the Plessey Electrically Reconfigurable Array matrix is programmable as a single NAND gate and has access to a number of input interconnects. For example, gate A can connect directly to gates B, C, D, E or F via the local interconnect. Each gate also has access to short-range and long-range vertical and horizontal bus resources for interconnecting macros and higher-level functions.

ing manager in North America, "because its fine-grained architecture obtains a packing density that is four times greater than previously available RAM-based programmable architectures."

But the Xilinx reaction to Plessey's density claims is that the company is "making rather generous projections over time and confusing the market in doing so," says Fox. The fine-grained Plessey architecture may have a lot of gates, but the user will benefit from only about 30 percent of them, Fox claims. Plessey doesn't refute the claim that useful density will be limited to roughly one-third of the gates in its ERAs.

A feature unique to the ERAs that could be appealing to certain users is their ability to be partially or entirely reconfigured in-circuit. Even Xilinx's Fox admits that dynamic reconfigurability is an interesting technical feature, but adds the qualification, "If they can get it to work and anyone wants to use it, that is."

Designers exploring technology alternatives to masked gate arrays will no doubt be studying the new Actel, Xilinx and Plessey FPGAs very closely. The time is ripe for believing in a worthwhile design solution that doesn't involve resimulations and reiterations, not to mention endless test vectors, as well as NRE charges that are likely to be multiplied if you're not a veteranand maybe even if you are. Agreement on a standard way to count gates, though, would very likely increase designers' faith in FPGAs. And the establishment of performance benchmarks would most likely boost that faith further. FPGAs have been around long enough to be taken seriously after all.

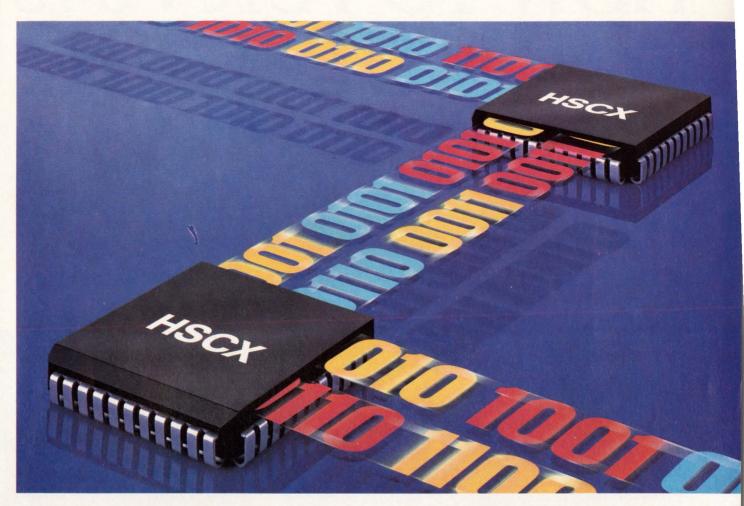
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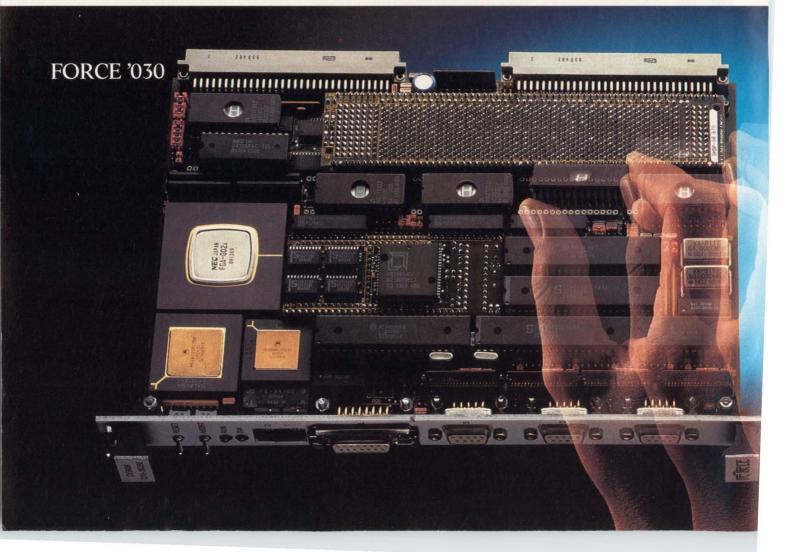
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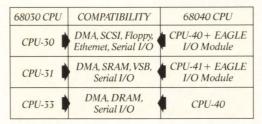
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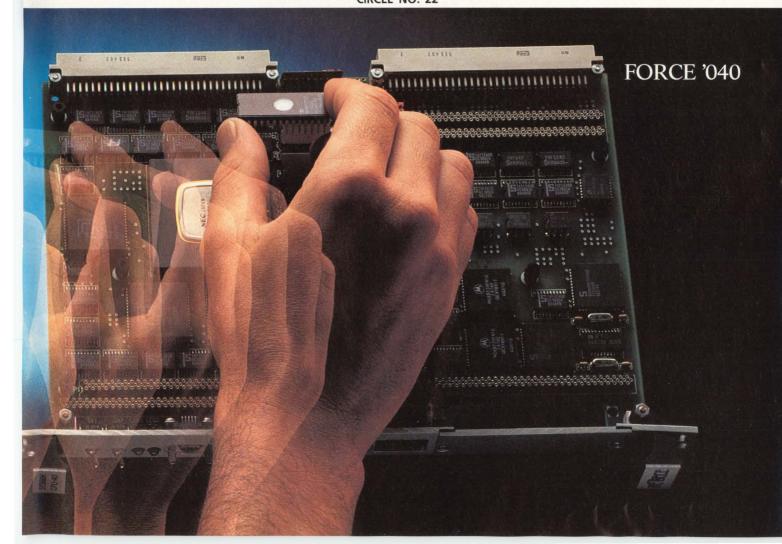
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INTEGRATED CIRCUITS

Creative use of PLLs solves clock skew problem

Ron Wilson, Senior Editor

he mundane problem of getting clock signals to the synchronous chips in a computer seems like an implementation detail. But as clock periods shrink to a few tens of nanoseconds, clock skew allowance-added time in the machine cycle to make sure that all the clock signals have arrived at their destinations-is becoming a major limitation to system performance.

It may be possible to get a CMOS RISC CPU, cache memory subsystem and floating-point processor that all run at 40 MHz. But-as some design teams have found to their horror-if you have to wait 5 or 6 ns for all the various clock inputs to trigger, you may end up with a 25or 30-MHz processor board. The degradation becomes even worse when critical parts are distributed across several boards and the clock is routed over a backplane.

Two semiconductor vendors-Motorola (Phoenix, AZ) and Gazelle Microcircuits (Santa Clara, CA)-have announced low-skew clock distribution chips that can ease some of the more harrowing of these nightmares. The parts aren't based on fast, powerful drivers that try to overwhelm clock loads; that approach simply increases system noise problems. Instead, the two companies have used one of the fundamental properties of phase-locked loops (PLLs) to reproduce or manipulate clock signals with nearly zero skew.

Tracking the input clock

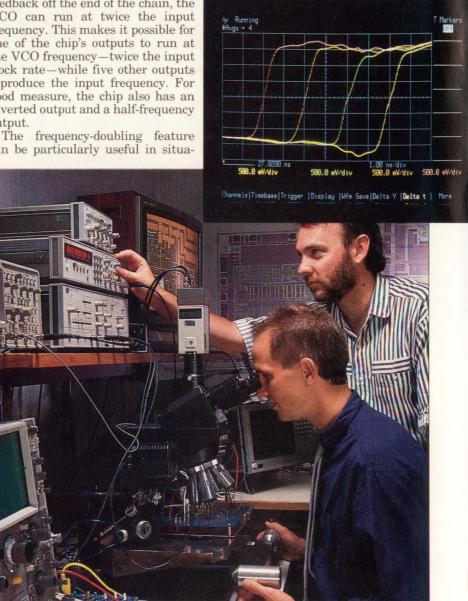
A sufficiently stable PLL can lock its output to the phase of an input signal with better than 1-ns accuracy. This idea can be applied directly to clock drivers—if the driver is a PLL, the device can have many clock outputs locked in phase to a single input clock. This is the principle used in the new parts from both companies.

Motorola's device, the MC88915, uses a 40- to 80-MHz CMOS PLL to accomplish its purpose. The device takes in a clock signal at TTL levels and reproduces its phase within a 1µs window on five CMOS outputs. But the part has more tricks up its sleeve than just mimicking the input clock. Motorola uses the PLL's voltage-controlled oscillator (VCO) to drive a counter chain. By picking the feedback off the end of the chain, the VCO can run at twice the input frequency. This makes it possible for one of the chip's outputs to run at the VCO frequency-twice the input clock rate-while five other outputs reproduce the input frequency. For good measure, the chip also has an inverted output and a half-frequency output.

can be particularly useful in situa-

tions where a master clock has to run over a backplane. It would be hopeless to try to synchronize a system to a 40-MHz backplane clock. But with the new chip, you can distribute a 20-MHz clock and multiply it up to 40 MHz on each board in the system, with the phase of each 40-MHz local clock locked to the master within 1 µs or so.

Gazelle's concept is similar to Motorola's, but a big difference in pro-



Gazelle designers Gary Gouldsberry, standing, and Bob Burd examine the phaseshifting characteristics of Gazelle's PLL-based clock distribution chip (inset). It locks TTLcompatible clock outputs to a master signal, but with phase shifts programmable in 2-ns increments. The company claims the accuracy of the phase shift is typically ± 100 ps.



Take a look at National's new RS-485 quad transceiver.

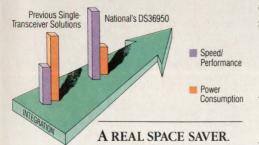
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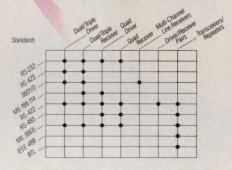
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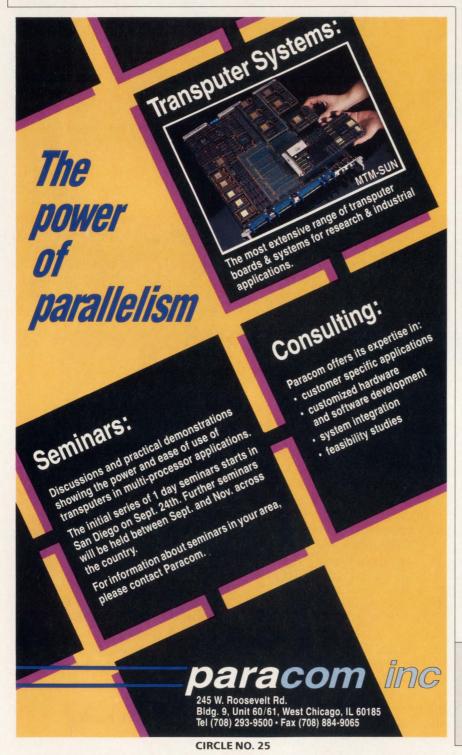
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cess technology gives Gazelle's parts quite different features. Using a proprietary gallium-arsenide PLL based on the design in Gazelle's 1-GHz HotRod communications chip, the GaAs designers have been able to get outputs running as fast as 160 MHz at TTL levels, with better than 500-ps phase accuracy between clock input and any output.

The additional speed also gives Gazelle the freedom to play more games inside the chip, resulting in two parts with different feature sets.



The first part is a six-output clock frequency multiplier not unlike the Motorola part, except that by proper choice of feedback and programming pins, outputs can be anywhere from one-quarter to eight times the input frequency, all locked to the input within 0.5 ns.

Phase-shifting abilities

The second Gazelle part uses the fast internal circuitry not for a counter chain, but as a digital delay line. The result is an entirely unique capability—the ability to program a forward or backward phase shift on the outputs in precise 2-ns increments. The six outputs can be set to provide many different mixtures of phase relationships over a range of 6 ns in each direction from an input clock as fast as 60 MHz.

Thus, while one output pin is exactly tracking the input, another might be 2 ns ahead of the input, another 4 ns ahead, and one pin a full 6 ns ahead. As in the frequencymultiplying part, this device maintains clock-to-output alignment within 500 ps maximum, and 100 ps typical, of the requested phase shift.

"The part gives you the opportunity to manage the clock distribution problem across a board," says Gazelle product marketing engineer Jonathan Zierk. "You can use the phase-shifting ability of the chip to compensate for the loading on various clock paths and get close-to-simultaneous operation of paths with very different clock loads."

The potential to remove much of the layout iteration, hand-selection of parts, manual measuring and loading of individual clock lines on individual boards and other such black magic could be an enormous boon to system designers. If these chips can help, either by eliminating skews in the clock source or by actually putting compensating skews into the clock drivers, much of the battle in high-frequency CPU design will be won.

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32K x 8 32K x 9	MCM6206 MCM6205 ⁺	17, 20, † 25, † 30, 35 17, 20, 25ns	PDIP, PSOJ PDIP, PSOJ	
				A
64K x 1	MCM6287	12, 15, 20, 25	PDIP, PSOJ	
16K x 4 16K x 4 OE	MCM6288 MCM6290	12, 15, 20, 25 12, 15, 20, 25	PDIP PDIP. PSOI	
8Kx8	MCM6264	12, 13, 20, 25	PDIP, PSOJ	
8Kx9	MCM6265	15, 20, 25, 35ns	PDIP, PSOJ	
4Kx4	MCM6268	20, 25, 35, 45	PDIP	
4Kx4CS	MCM6269	20, 25, 35ns	PDIP	E
4Kx4OE	MCM6270	20, 25, 35ns	PDIP, PSOJ	
	Cache Tag RA	AM Comparators		
4K x 4	MCM4180	18, 20, 25ns	PDIP, PSOJ	0
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4K x 4	MCM62351	20, 25ns	PDIP	L
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4x64Kx1	MCM62981/3	15, 20ns	PSOJ	I
16K x 16	MCM62990 ⁺	20, 25ns	PLCC	C
16K x 4	MCM6293/4/5	20, 25, 30ns	PDIP, PSOJ	H
4K x 12	MCM62973/4/5	20, 25, 30ns	PLCC	1
		PRAM™		-
8K x 24	MCM56824	25, 35ns	PLCC]
		st Static RAMs		-
8K x 20	MCM62820 ⁺	23, 30ns	PLCC	K
16K x 16	MCM62995 ⁺	17, 20, 25ns	PLCC	I
		stRAM™		-
32K x 9* 32K x 9*	MCM62940 (68040)	50, 40, 33 MHz 50, 40, 33 MHz	PLCC	N
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SOFTWARE

Industry group initiates object-oriented software standards

Tom Williams, Senior Editor

nteroperability of applications is a level of standardization that goes well beyond operating-system or protocol compatibility. It's the ability of one vendor's word processor to use the data created by another vendor's spreadsheet running under a different operating systemwithout having to resort to conversion routines, modular production of software, reuse of code or porting across many platforms. Interoperability is among the goals of the Object Management Group (Framingham, MA), a fast-growing association of companies formed to promote adoption of standards for object-oriented software technology.

OMG has produced its first document in what is hoped to be a comprehensive effort to standardize interfaces for object-oriented systems. OMG invites industry comment on the document, which defines an abstract object and reference model. "Application technology must be object-oriented to provide interoperability," says president Christopher Stone. "The promises of Unix, RPC (remote procedure calls) and other standards don't provide true interoperability of applications."

It's a rare but happy situation when a technology-standards effort starts to gather steam well before major players have committed substantial resources to producing and marketing proprietary versions of it. One need only think of the plethora of graphics or networking "standards" and the pains taken to coax vendors and users away from proprietary paths. "We're early enough in this technology for people to see that they can find a framework for cooperation without giving up competi-tive advantage," says OMG's vice-president of marketing, John Slitz. It seems to be true. OMG boasts over 80 members and is adding one new member a week.

Agreeing on terminology

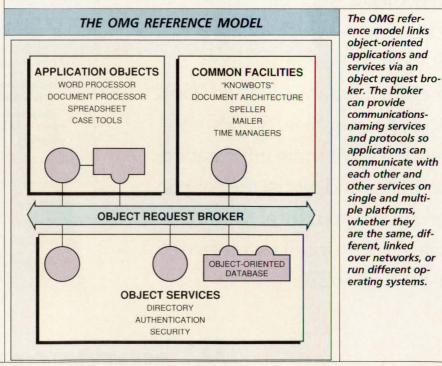
OMG's efforts are aimed at defining an overall Object Management Architecture (OMA). It will bring object-oriented technology beyond its already-acknowledged usefulness in programming—modular design, inheritance and reusable code—to the broad world of networked architectures and global computing. As a first step, the OMG technical committee has developed a document describing an abstract object model and a reference model for an OMA. "You must have an abstract object concept," says Stone. "Everybody has to agree on what an object is, what requests are, how a common request mechanism is passed from one object to another and so on."

In the OMG object model, as in all object-oriented technologies, objects are defined as a state and a set of operations that can be performed on that state. These operations are called methods. Objects perform services that are requested by clients. A client sends a request to an object along with parameters for the requested operation. The object then performs the requested service using one or more of its associated methods and returns the results to the client. Clients can be other objects, a user acting through a user interface object or an application program. Requests specify the particular operation (method) they want performed and the parameters for that operation. In other object-oriented systems, such as Smalltalk, requests are known as messages. Requests are passed from clients to objects using a message format.

The OMG object model is somewhat more generalized than the classical object model, in which a request identifies an object and zero or more parameters (which may also be objects) upon which the object is to perform some action. In the OMG model, method selection can be based on multiple objects; the method-the operation to be performedmay be selected from any object named in the request, even if the object is contained in the request as a parameter. The OMG definition of an object model sets forth a set of definitions to be used with all OMGcompliant software, which will eliminate ambiguous terms.

Classifying discrete components

The next step, and the first basic specification offered by OMG, is a reference model that defines a classification of components within the OMA. These components are identi-



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fied as major separable components of the total OMA. The document further characterizes the functions of each component and lays out the relationships between them and with the external environment. Finally, the document identifies the primary protocols and interfaces for accessing the components.

"We believe the software marketplace is on the wrong track, trying to do everything in layers-interface layer, data management layer and so on. We believe software should be classified as a series of discrete objects called object services," says Stone. As examples he cites database directory services, network-management services and userinterface services. These services have to be available for applicationoriented objects such as spellers, mailers and time managers. "We're not going to tell Wordperfect how to write Wordperfect, but we're going to tell it how to talk to that speller it wants to use," he says.

The reference model for the OMA starts with a request broker component. The object request broker provides the mechanisms for objects to transparently make and receive requests and responses. The request broker will be able to operate over networks connecting different platforms and operating systems. It addresses the issues of request dispatch and delivery, parameter encoding, synchronization, exception handling and object name.

The object request broker doesn't impose constraints on how objects themselves are to accomplish their tasks. A request to "print layout 312 laser_plotter," for example, might be sent as a request to the object "layout 312" whose "print" method would then print layout 312 on "laser_plotter." Alternatively, the same request could go to the object laser-_plotter, whose print method would access layout 312. Or the request broker itself could select a print method jointly owned by layout 312 and laser_plotter to accomplish the task. This ability to select a method from an object originally named as a parameter illustrates the flexibility of the OMG object model.

Other components

The other three major components of the OMA-object services, common

facilities and application objectsinteract via the request broker. Object services provides for the basis of object functionality-the logical structuring and physical storage of objects. It manages the creation, deletion and modification of object

classes-categories that can be instantiated to create objects that have some shared initial behavior or characteristics. Object services also handles storage of objects and their components (data and methods).

Some examples of object services



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are object database management systems, query facilities and directory services. Regarding storage in general within the OMA, Stone notes that the whole idea is to be independent of a particular data structure. "A language might store

data in its own format, but the idea is to define the interface to that format so that other languages and applications can get to the data," he says. OMG proposes that object services also be able to handle security and to define and enforce access con-



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trol for objects.

The common facilities is an optional component of the OMA in that it can be used to aid developers of OMA-compliant applications by providing facilities called "knowbots" that are commonly used and shared by applications. The developer of a compliant CAD package, for instance, might want to take advantage of the common OMG help facility. Other common facilities could include spellers and thesauri, printing and spooling, interfaces to external systems and electronic mail facilities. Developers could also create subclasses to enrich any of these for their applications.

The application object component of the OMA defined in the reference model consists of all normal user applications that are OMA-compliant-that is, they conform to the interface specifications and can communicate with other objects and object services within a system. Not only applications that are specifically written to be OMA-compliant can fit into this category; existing applications can be fitted with an OMAcompliant wrapper to fit into the architecture. Some applications that provide a general type of service such as an ASCII text editor or a database lookup program might be able to migrate to the status of common facilities and be generally available to other applications.

Projects still ahead for the OMG include definition of an object-oriented applications interface, distributed object management over networks and different operating systems, and an interface to object-oriented databases. Stressing that the group isn't defining the types of objects but is concentrating on the interfaces, Stone says, "We're not going to build, sell or have anything to do with the code that implements these concepts. That allows the proprietary nature of the implementation to stay paramount and lets the basic business of vendors stay untouched by the standardization effort."

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DESIGN AND DEVELOPMENT TOOLS

Speed and flexibility help PCB layout tools gain respect

Mike Donlin, Senior Editor

he age-old competition between man and machine is often demonstrated in the world of CAD tools. Certainly in printed circuit board design, the debate about which is better, engineer or autorouter, has been waged for at least 20 years. And in the early days of autorouting, the human-designed board was almost always cleaner, more aesthetically pleasing and manufacturable, even if the autorouter was faster. But the newest autorouters and editors, several of which were unveiled at the recent Design Automation Conference, are combining speed with flexibility to win the confidence of even the most diehard designers.

"Autorouters generally have the reputation of increasing the cost of manufacturing the board," says Steve Chidester, product manager at Teradyne (Santa Clara, CA). "Traditionally, they use vias more liberally and don't use layers efficiently. Remember, autorouters can only do one trace at a time, then go back and rip up and retry. A human designer can constantly decide to change tactics for a more efficient layout."

Faced with this reputation of producing a speedy but sometimes inefficient tool for printed circuit board design, autorouter vendors are turning their attention to developing products that will rival the handiwork of an experienced designer, while maintaining all of the traditional speed advantages. The latest release of Teradyne's Vanguard PCB layout system, Version 5.1, includes an autorouter that posts a bench-mark performance of routing a 400equivalent-IC board to 100 percent completion in just 90 minutes. The router, called AutoTrak, addresses the inefficiency issue through a unique grid system, which accommodates any repeating grid pattern. Because the tool isn't restricted to traditional square grids, AutoTrack can create special grids to minimize unused layout paths for a more efficient board design.

AutoTrak's flexible grid selection

not only makes more efficient use of board space; it also gives engineers a freer hand in selecting ICs for a particular application. "One of the complaints about autorouters in general, and gridded autorouters in particular, is that they put limitations on a design," says Chidester. "This is especially troublesome when a designer needs to use some surfacemount and analog devices, many of which have unusual pin spacings that don't fall in a traditional grid. We set up a different grid for those components so that users can set up any spacing they want."

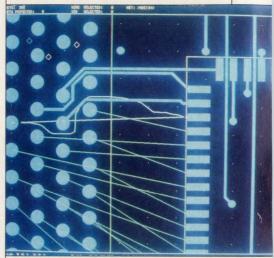
To grid or not to grid

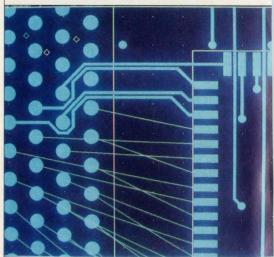
Though innovative grid handling allows gridded autorouters such as Teradyne's to work with mixed-technology printed circuit boards, some vendors claim that only a true gridless autorouter has the flexibility to handle complex, fine-pitch architectures. Start-up Cooper & Chyan Technology (San Jose, CA) has recently introduced a gridless router that uses a shape-based approach for laving traces. "Ours is a new type of architecture," says Richard Noreika, vice-president of sales and business development at Cooper & Chyan. "True gridless routing is a byproduct of the shape-based architecture. Our autorouter looks at a line across the screen, for instance, as a rectangle that's so many millimeters wide by so many millimeters long. While a gridded router sees hundreds of points on a line, we treat it as one shape.'

The advantage of such an approach, explains Noreika, is that it provides the routing flexibility needed for high-density boards, while using far less memory than gridded autorouters do. Cooper & Chyan claims that its autorouter, called Specctra, uses only 16 Mbytes of system memory to route a board with 13,000 connections, compared to 30 to 40 Mbytes for the same task on a gridded tool. In addition, the autorouter can route with a grid as a constraint specified by the user if the

board design so dictates. "The advantage there," Noreika says, "is that a user can control a design with a specified grid, but the system doesn't have to deal with a grid map. The user-defined grid points are purely a frame of reference."

Proponents of the gridless approach also boast about the ability of their routers to pack more components onto limited board real estate. The Freedom gridless router from Harris Scientific Calculations (Fishers, NY) is a clearance-based tool





The Advanced Dynamic Editor from Mentor Graphics lets the user interact with an automatic router. The designer indicates with the thin curved white line the approximate path he wishes the tool to follow (top). The editor completes the interconnect (bottom), shoving aside the other traces. Mentor claims that this tool lets the designer place a trace in about 30 seconds.

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Product Family	Size (Total)	(Bits)	(ns)	DIP	P ZIP		PLCC	TSOP	PQFP	Features	Availability	Qualified
SRAMs	1MEG	x1,x4,x8	25-45	Х		X				x4 option: GE	Now	2H90
S	256K	x1,x4,x8	20-45	X	X	X				x4 option: OE	Now	Х
and ball	64K	x1,x4,x8	12-45	X		X				x4 options: Separate I/O, OE	Now	Х
	16K	x1,x4,x8	12-45	X		X				x4 options: Separate I/O, OE	Now	Х
Cache Data SRAMs	288K	x9	14-34				X			486 Compatible, Self-timed write, Fast toe 7ns, 486 Burst and extended burst support	Samp: 1H91, Prod: 2H91	
	144K	x18	20-35				X	-	X	386/486 Compatible, Fast toe 8ns, Auto write completion, Parity bits	Now	
Sector Sector	128K	x16	20-35				Х		Х	386 Compatible, Fast toe 8ns	Now	
Synchronous	288K	x18	15-25	1			X			Registered address, chip enables and write	Samp: 2H90.	Samp:
SRAMs	256K	x16	15-25				x			control; Data latch, Fast toe 6ns, Byte write capability	Samp: 2190, Prod: 1191	1H91
SRAMs with	288K	x18	15-35				x	1		Address, data and chip enable latches: Byte		
Address Latch	256K	x16	15-35				x			write capability, Fast toe 6ns, 3.0 Volt output buffer option	Samp: 2H90, Prod: 1H91	Samp: 1H91
	16K	x10 x8	100	x		X	^			Intel 8051 and 8096 compatible	Now	X
	16K	x8	15-35	X		X			-	Compatible with high end micro controllers	Now	X
	10112				-	^				compatible with high end micro controllers	144.4	
FIFOs	18K	2Kx9	15-35	X	-	-	X	-		Family options:	Samp: 1H91	2H91
	9K	1Kx9	15-35	X			X			300 mil DIP package, Programmable flags	Samp: 1H91	2H91
	4.5K	512x9	15-35	X			X				Samp: 1H91	2H91
DRAMs	4MEG	x1,x4,x8,x16	60-100	x	x	x		x		x4,x8 options: Write per bit x16 options: 2 WE/1CAS; 1WE/2CAS and 1WE/1CAS with write per bit	x1,x4 Samp: Now, Prod: 1H91; x8,x16 Samp: 1H91	Samp: 1H91
2-24	1MEG	x1,x4,x16	70-120	X	X	X		X		x16 options: Byte write or write per bit	Now	Х
Contraction of the	256K	x1,x4	100-120	X	X	X	Х				Now	Х
	64K	x1	100-150	X			Х				Now	X
Quad	4MEG	x4	60-100			X				Separate CAS control for each DQ input/	Samp: 1991	
CAS DRAMs	1MEG	x4	70-100			X				output, Enhanced write per bit capabilities	Now	
Pseudo Static DRAM	1MEG	x8	80-120	х		x		x		Unmultiplexed addresses, Simple refresh control	Samp: 2H90, Prod: 1H91	
Dual Port DRAMs (VRAMs)	1MEG	x4,x8	80-120	9.41	x	x				CMOS, Fully static SAM, Serial input, Split read transfer	Now	Samp: 1H91
	256K	x4	100-120	X	X					CMOS, Fully static SAM, Serial input	Now	X
Triple Port DRAMs	1MEG	x4,x8	80-120			x	x	20		CMOS, Two fully static SAMs, Transfer mask, Split t.ansfers, Functional superset of 1MEG VRAM	Samp: Now, Prod: 2H90	
Module Product Family*	Word Size (Words)	Org. (Bits)	Speed (ns)	DIP	ZIP	Pa SIP	ckage SIMM	1		Special Features	Availability	Military Qualified
DRAM Modules	2MEG, 1MEG, 512K, 256K	x36	70-120	011	X	un	X			Industry standard pin-out	256K, 512K: Now; 1MEG, 2MEG Samp: 2H90	
	4MEG, 1MEG, 256K	x9	70-120			x	x	1		Industry standard pin-out	256K, 1MEG: Now; 4MEG Samp: 2H90	100
	4MEG, 1MEG, 256K	x8	70-120			x	x			Industry standard pin-out	256K, 1MEG: Now; 4MEG Samp: 2H90	
SRAM Modules	256K, 128K, 64K, 16K	x32	15-45		x					Industry standard pin-out with OE	16K, 64K: Now; 128K,256K: 2H90	1H91
	64K,32K	x16	30-45	X	-		1			Industry standard pin-out with OE	Now	1H91
	128K	x8	30-45	X						Compatible with 1MEG monolithic	Now	1H91

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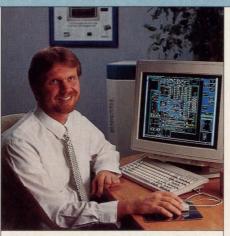
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TECHNOLOGY, INC.

DESIGN AND DEVELOPMENT TOOLS

that addresses the complex pin and component architectures of tightly packed boards. The router lets designers place components anywhere on the board, and then it weaves a trace that can have an unlimited number of diagonal bends between the pads. Traces that can't find an orthogonal path can be angled to hug objects along the route. An automatic cleanup feature reduces via count and eliminates hooks or loops to shorten trace lengths.

Though gridless routers seem to have the upper hand when the issue of flexibility is foremost, those partial to gridded routers claim that their tools are faster. "So far the gridless technology hasn't beat a gridded router in a fair fight," says Teradyne's Chidester. "It's important when comparing autorouters to make sure that both tools are working on the same design. Some board designs are more suited for gridless



Though autorouters don't always finish a complicated design to 100 percent completion, they can still trim valuable time off a board's development cycle. "Designers will probably always want to finish a layout by hand," says Steve Chidester, product manager at Teradyne. "But even if they spend a couple of days cleaning up a router's mistakes, it's still weeks faster than a totally manual design." and others for gridded routers. We feel that overall, our router wins more often than not."

His claim is challenged, however, by Racal-Redac (Westford, MA). Racal's router, dubbed Bloodhound, uses a proprietary algorithm to boost gridless routing performance to levels that rival gridded autorouters. "We believe that Bloodhound can match the performance of a gridded autorouter over the broad spectrum of design tasks," says Keith Felton, technical marketing manager for CAD products at Racal-Redac. "And because our interactive editor uses the same algorithm as our autorouter, it allows users to reroute particular traces in a very hightechnology bracket-fine-pitch, mixed-technology applications.

Keeping control

The interactive editor is yet another feature that autorouter vendors are

1990 Computer Design Magazine Edition **UPCOMING ISSUES**

ISSUE	SPECIAL REPORT	TECHNOLOGY FOCUS	PRODUCT FOCUS	INDUSTRY EVENTS
October 1	Real-time operating systems	High-speed PLDs CAD frameworks	EPROMs	NORTHCON, Oct 9-11, Seattle, WA BUSCON/East, Oct 16-18, Marlboro, MA NEPCON/Northwest, Oct 31-Nov 1, San Jose, CA
November 1	Designing PLDs, PGAs and gate arrays	Cache controller ICs ISDN	Memory boards	ELECTRONICA, Nov 6-10, Munich, W. Germany COMDEX, Nov 12-16, Las Vegas, NV WESCON, Nov 13-15, Anaheim, CA
December 1*	Multiprocess- ing in a standard-bus	Design entry techniques special-purpose DRAMs	High-resolution A-D converters	*Starch readership study issue

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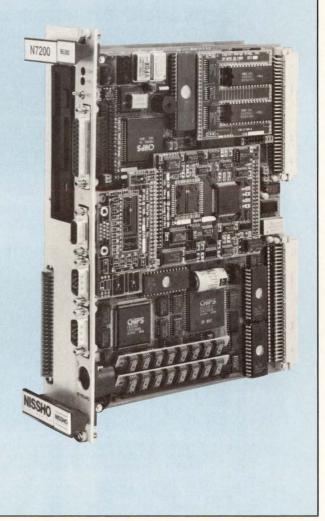
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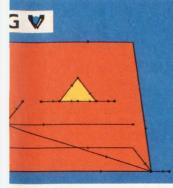
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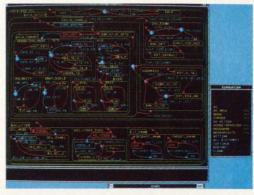




Verilog LOGISCOPE: Automated testing of source code analysis for reverse engineering.

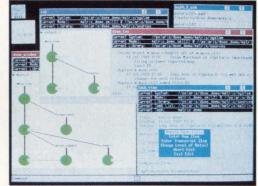


Ada: A development environment that allows real-time symbolic debugging, available from multiple vendors.

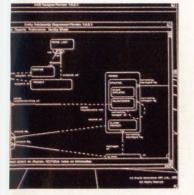


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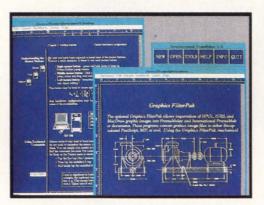
SE scenario.



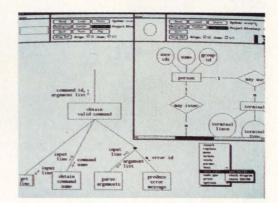
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touting to win over reluctant board designers. These tools, used after the autorouter has finished the design, allow users to either add traces that the autorouter couldn't place, or to modify the board for manufacturing or testability reasons. Racal-Redac's Visula Route Editor provides an interactive environment for the design engineer. The user simply traces the approximate path that he wants the route to go, and the editor will stitch in the route by pushing aside all obstacles, while observing all the

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CIRCLE NO. 35

design rules in the defined path. Trace by trace, the designer can switch back and forth from manual to semiautomatic routing. "The beauty of an interactive editor is that it gives the user the control of manual design combined with the power of an autorouter," says Felton. "If, for example, the designer knows that some traces have to pass through specific points on the board, he can just specify them and the router will figure out how to get the trace to pass that way."

In addition to the control that an editor gives an engineer, the tools can cut days or even weeks off the design cycle. The Advanced Dynam-

"A gridless autorouter hasn't yet beaten a gridded autorouter in a fair fight."

-Steve Chidester, Teradyne

ic Editor from Mentor Graphics (San Jose, CA) is an interactive design tool that the company claims offers a tenfold performance improvement over existing editing techniques. "This is a new class of tool, not just 'let's speed the router up a bit'," says Russ Henke, general manager of Mentor's printed circuit board division. "This tool is aimed at the board designer who's used an autorouter, but who may have 4 or 5 percent of the board left to do by hand. On a complex board, it may take an hour to lay a trace because there are a few thousand already there. With our editor, a designer can place a trace

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in 30 seconds or so."

The Mentor editor, like the one from Racal-Redac, lets the designer sketch the path of the trace to be routed and then makes the interconnect according to the design rules. The tool uses squeeze-through and shove-aside techniques to route the trace, and can work with either gridded or gridless designs. Though the interactive capabilities of both the Mentor and Racal-Redac editors are similar to other editors on the market, the way they handle trace placement is different. "Other interactive tools allow the user to place traces," says Fred Smith, technical market-ing engineer at Mentor, "but they first have to digitize all the points along the way. Ours simply looks at the design constraints and obstacles in the path and works around them. The result is almost instantaneous trace placement."

The need for near-instantaneous

results is at the heart of the increasing acceptance of the latest autorouters and interactive editors. "The challenge that autorouter vendors face is giving engineers a tool that will turn a design around quickly and not take a lot of time to learn,"

"Autorouter vendors must give engineers tools that will turn a design around quickly and are easily learned."

-Jack Hendren, Cadam

says Jack Hendren, vice-president and general manager of the EDA division of Cadam (San Jose, CA). "Though many of the current design tools are good in the hands of a layout specialist, they can be confusing to an engineer who's concerned primarily with board design and performance. The trick is to get an engineer to produce a basic design that's manufacturable in the shortest amount of time. Some of our customers have only six weeks to design a product. That's an extreme example, of course, but that's where things are headed."

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CIRCLE NO. 37

Fiber network supports distributed real-time systems

Tom Williams, Senior Editor

s applications put ever-increasing demands on realtime systems, there is a need to add hardware power in terms of multiple CPUs, as well as operating system services beyond those offered by most embedded kernels. But interprocessor communications, especially over networks, tends to muddy the rigid determinism often required by real-time applications.

Ethernet, for example, is typically nondeterministic because it uses collision detection and retry to resolve conflicts for the media. Thus there is a statistical probability that messages may conflict and have to be retried, and therefore the time needed to ultimately get on the network and transmit isn't predictable. Even processors that are communicating across a backplane can run into buscontention problems that break down determinism.

To be useful for difficult real-time applications, a network scheme must be fast and reliable, as well as offer rigidly predictable timing. To address the needs of distributed realtime systems, Systran (Dayton, OH) has developed a shared-memory network technology based on a fiberoptic waveguide media. Called SCRAMNet (Shared Common RAM Network), the scheme combines the best attributes of message-passing networks and shared-memory architectures for interprocessor communications. It eliminates costly software protocol overhead associated with most networks, and since it's a ring topology, it also eliminates uncertainties caused by contention. And it provides speed-a data rate of 150 Mbits/s, which is 50 percent faster than even FDDI (Fiber Distributed Data Interface).

How it works

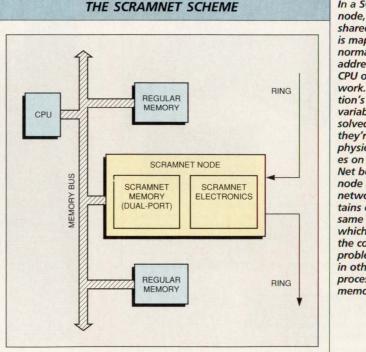
The architecture consists of up to 256 computers connected via the fiber link. At each node there is a SCRAMNet interface board with the network interface electronics and from 8 kbytes to 2 Mbytes of shared memory.

The shared memory could also be described as reflective or replicated memory because the contents are exactly the same at each node. A write to any processor's shared memory space is automatically transmitted to the same address in every shared memory board on the network; and this is accomplished without any software overhead. The network electronics monitor the writes from their local CPU to their respective shared memories. Any write results in an automatic ring transmission.

SCRAMNet isn't a token-passing ring like FDDI; instead, it's a register-insertion ring in which the ring appears as a giant circular shift register. Nodes placing a message on the ring simply add the bits of their message to the bits that are being serially shifted around the ring. According to Systran's manager of R&D engineering, Gary Warden, SCRAMNet differs philosophically from FDDI in that FDDI "is a packet-switching network. We have optimized our network for short bursts of data."

Data is transmitted as a fixed 83byte message containing, among other information, a 32-bit data word and its address. The message is received and retransmitted by each node in the ring, and the data word is placed at exactly the same relative physical address in every node. Interrupts are passed in exactly the same way as other data. For one CPU to interrupt another, it writes the appropriate data word (REAC-TOR_FLOOD, for example) to its shared memory. The network controller has an auxiliary control RAM (ACR), and if this RAM has been set to generate an interrupt for the location where REACTOR_FLOOD is stored, an interrupt bit will be sent over the network along with the address and the data word. Any node whose ACR is set to receive interrupts at that memory location will be interrupted when REACTOR FLOOD is written to its shared memory.

Thus one CPU can compute results that will trigger an interrupt in another CPU. By the same token, an external event received by one CPU can automatically cause interrupts in other nodes on the network, which is useful for redundancy as well as



In a SCRAMNet node, the dual-port shared memory is mapped into the normal memory address space of a CPU on the network. The application's global variables are resolved so that they're stored in physical addresses on the SCRAM-Net board, Each node board on the network contains exactly the same data, which eliminates the contention problems inherent in other multiprocessor sharedmemory schemes.

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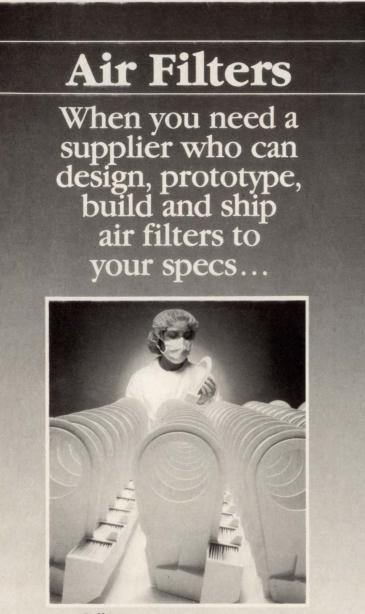
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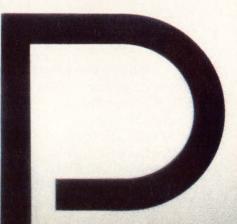
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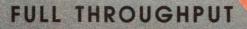
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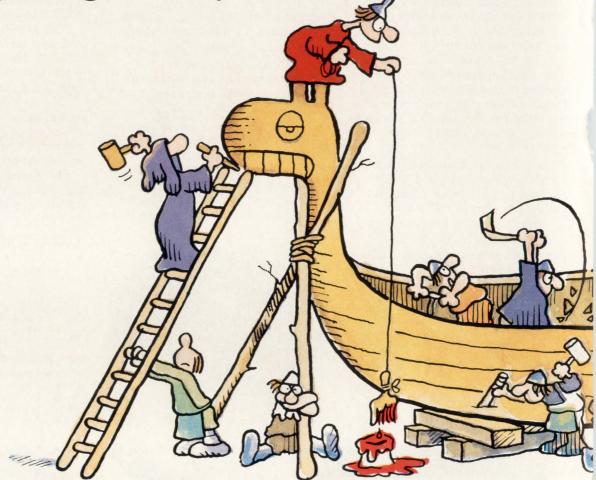
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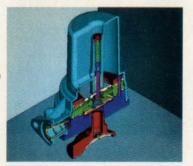
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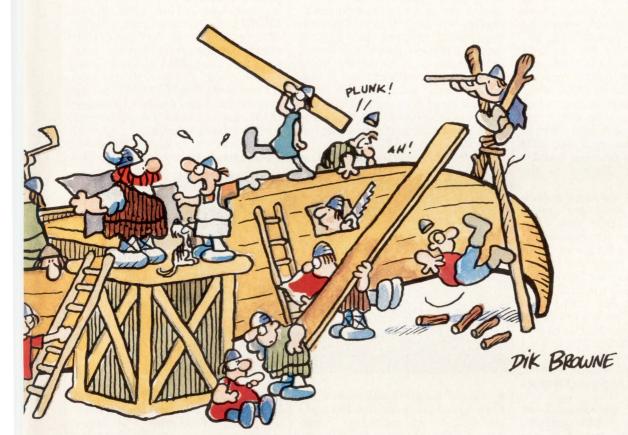


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Small, reliable STD SBCs move into PC territory

Warren Andrews, Senior Editor

S TD Bus, with and without the 32-bit extension, continues on a roll as demand surges for small, reliable PC compatibles. The latest round of STD Bus products reflects that demand—80286 and 80386 SX machines have entered the market, rivaling the best of the desktop units in performance while exceeding them in reliability, ruggedness and compact size. What's more, 386 DX and even 486 STD boards are on the drawing board—and in one case, already in the breadboard stage.

"Customers are looking for compact solutions to embedded control problems in both DOS and Unix environments," says Jim Eckford, director of marketing for Ziatech (San Luis Obispo, CA). According to Eckford, some customers are looking for a complete system in a small card cage with only a few slots, while others are looking for a single board they can embed in their products. "Either way, customers are looking for smaller yet more powerful STD solutions," he says. "Size is turning out to be the most important feature of STD Bus."

As a result of the demand, an entire new family of STD products has been emerging over the past year, sporting high-performance processors, memory, and as much assorted I/O as will fit on the small form-factor card. In addition, many of these boards provide hard and/or floppy disk interfaces, some kind of video port, some digital I/O, a keyboard interface and at least a serial or parallel port.

Kurt Priester, president of Computer Dynamics (Greer, SC), one of the many companies offering highperformance PC-compatible machines on STD, agrees with Eckford about the rising demand for small form-factor PC compatibles, but adds that "the other critical component in the formula is quality." Priester maintains that many PC applications fall from grace as the PCs prove unreliable.

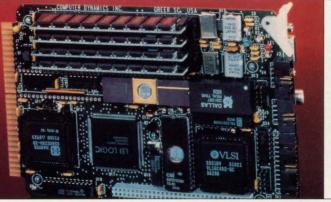
"It's not uncommon," says Pries-

ter, "for companies to develop systems based on a conventional desktop PC only to have downtime wipe out all the gains made by automating a process. So many designers are turning to STD for the added reliability—the reduced size is simply an added bonus. With the latest generation of high-performance machines available on STD, there's no need to sacrifice performance or features to switch to STD."

WinSystems (Arlington, TX) is

compatibles differ only slightly. Computer Dynamics, for example, in its CPU-AT provides a 25-MHz 286based board with up to 4 Mbytes of memory, and the company claims that the CPU-AT is 100 percent PC/AT compatible. In addition to the processor and memory, the board has room for a 256-kbit EPROM, two RS-232 ports, a printer port, a floppy disk controller, an IDE hard disk interface, a battery-backed real-time clock and CGA, EGA or VGA video. Furthermore, Priester claims that it's one of the few STD CPUs set up to drive flat-panel displays including LCD, plasma, electroluminescent and vacuum fluorescent.

The entire system, however, doesn't reside on only one card. The



The CPU-AT STD board from Computer Dynamics provides full PC/AT functionality, including a 20or 25-MHz 80286 processor, 4 Mbytes of DRAM, and serial and parallel I/O. A daughterboard provides floppy and hard disk interfaces, and CGA, EGA or VGA video.

another of the STD makers that has been one of the leaders of the highperformance PC-compatible bandwagon. "The advanced PC chip sets provide the necessary functionality and space savings to allow complete PCs to reside on a single STD board," says Bob Burckle, WinSystems director of marketing. "The Chips and Technologies chip set that we use not only provides the housekeeping and peripheral functions for the PC but also provides clock signals to allow the processor to zip along at its top speed internally, while the backplane is allowed to operate at another speed. This means that the processor's performance isn't impaired by the relatively slow STD Bus, which isn't the case with some other solutions," he says.

Slight differences

Interestingly, the various approaches taken by STD vendors making PC

processor, memory, I/O ports and EPROM reside on one board, while the video, Winchester and floppy controllers reside on a daughtercard that plugs directly onto a connector on the host processor board. "This dual-board approach was taken for two reasons," says Priester. "First, there just isn't enough room on the processor board for the rest of the functions and the mother/daughterboard is a good way to make more room. Second, many customers simply want to embed the processor and memory functions with or without a card cage. The CPU-AT processor module permits that without the expense of including the disk and video interface functions.

"Right now, we're using the 286 processor because it offers equivalent—or better—performance than the 386 SX at a lower price," Priester says. "Unless the advanced memory features offered by the 386 SX are critical, there's no reason that I

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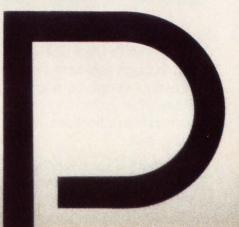
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can think of to use the SX." But the 386 DX is a different story, according to Priester, and he expects his company to develop a 386 DX machine soon.

WinSystems also provides a highperformance 286-based machine with similar functions. And this company, unlike Computer Dynamics, offers a board using a 16- or 20-MHz 386 SX. WinSystems' 386 SX board allows for automatic switching between 8- and 16-bit transfers and, like other approaches, separates the disk and video interface from the main processor board. A specially modified Phoenix BIOS allows the board to boot off either disk or ROM.

STD 32

Ziatech, not unexpectedly, used the company-developed STD 32 for its latest 386 CPU board. STD 32 has been on a popularity roller coaster since Ziatech first announced it al-

100 MFLC

most a year ago. It still has only a limited following, and some supporters who had initially expressed a favorable response, such as Computer Dynamics' Priester, have recently displayed considerably less enthusiasm. Further, the STD Manufacturers Group appears to be no closer to endorsing the concept than it was six months ago.

Despite the ups and downs, Ziatech and a small group of vendors calling themselves Task Group 32 have gone ahead and finalized the specification, provided nonrecurring engineering expense monies for the manufacture of the connector, designated a connector manufacturer, and set up licensing rules. In addition, the group has cleared the use of the EISA specification and settled other legal issues that could have been obstacles. Still, reception to STD 32 has been cool at the STD vendor level due to what Priester describes as "political problems."

Though connectors and backplanes for STD 32 won't be available until October, Ziatech has been making its CPU board for some time. "You have to remember that STD 32 is fully compatible with all existing 8-bit backplanes and systems," says Eckford. Ziatech's 386 SX-based CPU approach is similar to Computer Dynamics' and WinSystems' in that it uses two boards: one for processor/memory and another for video and disk control.

Ziatech's processor/memory board is a full 32-bit 386 SX with 8 Mbytes of memory, a pair of serial ports, a parallel port, a keyboard interface and all the other features normally found on a CPU. A companion card includes the floppy disk and hard disk controllers and VGA port. "These two boards combined with a floppy disk drive and a 40- or 105-Mbyte Winchester make an attrac-

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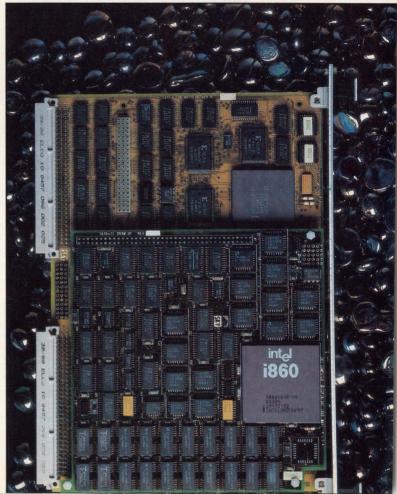
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tive package," says Eckford, "and it fits in a five-board STD card cage. Complete, the package is 7 in. wide."

Looking ahead

Ziatech's existing package is only the tip of the iceberg, according to Eckford, who says his company realizes that board compactness is critical to many applications and is compacting its designs even further. Ziatech will soon unveil a 286-based card with even more I/O than existing cards. To squeeze in the addi-



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tional functionality, the company is taking advantage of its recently developed ASIC I/O chip designed to provide high-density, high-current digital I/O.

The 286 board is expected to boast 48 digital I/O points in addition to memory, serial and parallel I/O. "The digital I/O chip we developed is just the first of many we plan to develop to increase functionality on the postcard-sized STD form factor," says Eckford. "Even though the chip was used in a few current products and will be incorporated into several emerging products, it was really a test-bed for our ASIC strategy, and we expect to be developing more custom chips."

While STD vendors are looking to compact more functions on their boards, they also have an eye toward boosting performance. Computer Dynamics and WinSystems are running 286-based machines at 20 and 25 MHz, and WinSystems and Ziatech are running 386 SX boards at 16 and 20 MHz. Computer Dynamics, as mentioned, is planning to develop a high-speed 386 DX machine soon, while Ziatech may well jump the gun and offer a 486 machine in the not-too-distant future.

"Right now, it's too early to tell whether—or when—a 486 STD product will emerge," says Eckford, "but we have a breadboard of a full 486 EISA machine already completed. Since STD 32 operates on a subset of the EISA specification, an STD 32/EISA design could become a reality in a relatively short time."

And some vendors that are looking to stretch the performance envelope are also looking to put STD/PC power in customers' hands at increasingly lower prices. "WinSystems has just announced a new low-priced CPU for those embedded applications calling for moderate PC performance at a moderate price," says Burckle. Based on an 80188 processor, the WinSystems board is priced under \$200. □

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DSP chips stalk industrial buses

Ripe for new roles, DSP chips are slowly making their way onto VME and Multibus boards. But system designers are tentative about the prospects.

Warren Andrews Senior Editor

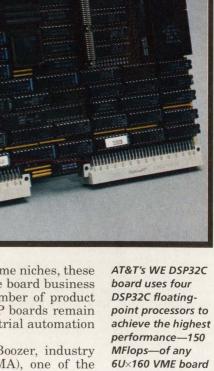
Not too many years ago, when the first single-chip digital signal processing devices became available, they were heralded as the second coming of the microprocessor. Now, several years later, the blush seems to have paled somewhat even though the latest generation of floating-point chips has recently become

available. Though having found a home in many high-volume niches, these chips still have failed to realize their anticipated use. The board business has followed a similar trajectory. Despite a growing number of product offerings on personal computer and industrial buses, DSP boards remain more of a laboratory curiosity than the backbone of industrial automation and control systems.

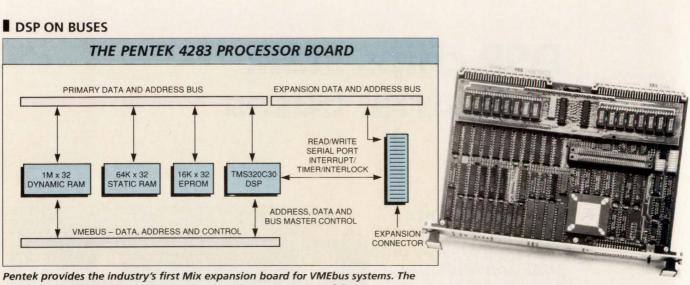
Why? "There are a lot of reasons," says Cimarron Boozer, industry marketing manager for Sky Computers (Chelmsford, MA), one of the leaders in industrial DSP boards. "A main one is that there are a lot of designers who prefer to roll their own DSP boards to suit a particular application," he says. "The business for DSP is largely fragmented, calling for a lot of different and specialized designs."

But more important, there seem to be other obstacles. DSP is still relatively new and system designers are somewhat tentative about jumping into the unknown. Astute observers point out that the term "signal processing" may itself account for some designer reticence. Signal processing has traditionally been the domain (no pun intended) of analog designers who turned to digital techniques to solve what are essentially analog (signal) problems. Therefore, the high-powered mathematical techniques available as part of DSP technology are most often found solving typical signal processing/conditioning chores such as switching from a frequency to a time domain, modifying the result and swapping back to the frequency domain or vice versa.

But the capabilities of DSPs and the techniques and algorithms they employ extend beyond those tasks normally associated with analog signal processing. Yet few designers have taken advantage of these capabilities. Instead, designers have walked around DSP solutions, finding more conventional solutions to DSP-like problems.



performance—150 MFlops—of any 6U×160 VME board on the market. The board comprises four major sections—two DSP clusters, the VMEbus interface and the shared DRAM area.



Pentek provides the industry's first Mix expansion board for VMEbus systems. The baseboard, a TMS320C30 DSP processing board, can accept any of the company's 320C30 coprocessor, A-D converter or other expansion cards stacked up to three deep.

Aside from the fact that the concept of signal processing might intimidate designers, there is also some confusion as to what DSP is, compared with array processing or simply specialized accelerators (see "Choosing the right accelerator technology," p 75). The idea of DSP has developed such a narrow focus that these other names have been appended to basically the same functions and capabilities used in signal processors but with, perhaps, a somewhat wider scope.

History intervenes

Another factor hindering the advancement of DSP techniques into other areas of processing is the traditional development and programming environment that has surrounded DSP. To understand that environment, it's important to look at DSP with some historical perspective. DSP functions are highly iterative manipulations crunching through relatively small amounts of code very fast, and many times over. In any look at price/performance, the emphasis in DSP has always been on performance. As a result, DSP programs have traditionally been written in assembly code to fit into the relatively small on-chip memory that DSP chips provide and to speed execution.

Thus, many of the development tools for the DSP chips have evolved independent of, and totally different from, traditional system design tools. Such tools include everything from compilers and debuggers and assemblers to in-circuit emulation devices. The maxim was, DSP designers aren't system designers, so there's no need for DSP designers to operate in the Unix or real-time operating system world. Consequently, development environments tended to focus on the individual chip rather than on the system.

But as system designers' demands change, so do DSP approaches. And though chip makers such as AT&T (Murray Hill, NJ), Texas Instruments (Dallas, TX), Motorola (Austin, TX), Analog Devices (Norwood, MA) and others recognize the needs of system designers, there has been little movement to integrate DSP into nonsignal applications.

Even at the board level, where tools are more readily available and hardware designs well polished, "most of the applications are in conventional signal-processing applications such as speech processing, radar, medical imaging, sonar and communications," says Rodger Hosking, vice-president of Pentek (Rockleigh, NJ), maker of both VME and Multibus DSP boards.

One approach

While many of the offerings of DSP hardware are conventional boards operating within the confines of a host system bus, there is a growing tendency toward using mezzanine or daughterboards. Two of the most distinctive of these offerings are from Io (Tucson, AZ) and Pentek.

Io's daughterboard, the Math-COP2 floating-point coprocessor, is a full-sized 6U VME board that plugs into a standard VMEbus slot in a card cage next to an Io CPU card. The MathCOP2 daughterboard, though plugged into the host P1 connector, draws only power and ground from the host system and is connected directly to the adjacent CPU board. Therefore, the board uses no VMEbus bandwidth and occupies only a single VME slot.

lo's MathCOP2 is based on the 2100 floating-point chip set from **Bipolar Integrated Technology** (Beaverton, OR) and is designed to operate at better than 30 MFlops. It consists of a multiply/divide component and an adder/Boolean component. Both of these are connected to a four-ported register file providing sixty-four 32-bit operating registers. In addition, there is a local SRAM that can hold up to 64,000 32-bit words of data. Program instructions for the coprocessor reside in a separate microprogram memory, which has capacity for 2,048 80-bit instructions.

Because the board uses two parallel floating-point processors—one for multiply, divide and square root and the other to add, subtract and perform data conversions and Boolean operations—complex operations can be handled with single commands.

The addition of program storage space on the board is as much responsible for its performance as the native speed of the BIT parts, says Tom Sargent, Io's president. The performance of a Motorola 68881 math coprocessor, combined with a 68020/030 processor as the system host, limits the math speed by the rate at which commands can be passed from the host processor to the coprocessor. But being able to download a sequence of instructions into the board's program memory

Choosing the right accelerator technology



ith RISC

chips doubling in performance every 18 to 24 months, workstations have made enormous strides in technical computing power. But despite these

advances, workstations are still a far cry from the supercomputing performance that engineering and scientific users often need for their applications.

When combined with the new class of third-party accelerator products, however, workstations can speed up many technical applications to near-supercomputing levels. But it requires matching the right application with the right accelerator product. Unfortunately for end users, accelerator products come in many guises these days, provoking much confusion and frustration.

There are three types of technologies that are capable of achieving doubleand triple-digit Mips and MFlops performance on the desktop: application accelerators, array processors and digital signal processors. Understanding how they each work will help end users avoid making misguided purchasing decisions.

Application accelerators

Application accelerators are ideal for such applications as computational chemistry, molecular engineering, finite element analysis, computational fluid dynamics, modeling, computer-aided design, simulation and financial analysis. Unfortunately, there's a lot of confusion about what constitutes an application accelerator. The term has been used loosely to market everything from add-on simulation hardware to faster memory boards.

Sky Computers defines application accelerators as a specific technology that transparently accelerates numerically intensive applications without requiring modification to the source code. The technology is a general-purpose solution for working with all types of numeric data—both integer and 32and 64-bit floating-point—and the architecture is balanced to accommodate both scalar and vector processing.

Application accelerators serve as coprocessors that work in parallel with the host computer. If users have complex programs that use a variety of data types organized as scalars or vectors, or if users are concerned about accelerating more than one type of application, then application accelerators are the most efficient, cost-effective solution.

They are supported by a set of programming tools and software, including vectorizing Fortran and C compilers, debugging tools, libraries of often-used routines, simulators and profilers. But users must ensure that the accelerator they select supports their operating system calls. If it doesn't, their programs won't run transparently, and users must develop their own system interface

> code or do "workarounds."

dards, and if ven-

technologies can achieve doubleand triple-digit Mips and MFlops performance on the desktop. For this reason, many accelerators are available for Unix machines. The Unix operating system calls use established stan-

Three

dors support them, they can truly call their products transparent application accelerators.

Array processors

Array processors are best suited for applications involving repetitive arithmetic operations on large data sets or manipulation of floating-point data arranged in vectors, or arrays. Examples of such applications include medical image processing, real-time 3-D graphics, geophysical analysis, automated test, and radar and sonar signal processing.

Array processors accelerate applications by pumping multiple array elements through a highly optimized processing pipeline.

Users of array processors often modify their programs to take advantage of special subroutine libraries, typically vector and matrix routines. Array processors are optimized to do some tasks well, such as fast Fourier transforms and vector operations.

These processors are supported by a library of vector and matrix routines callable from high-level programming languages such as C or Fortran. In operation, the application executes on the host computer and passes data and commands to the array processor. Array processors aren't good at programs that can't easily use subroutine calls, or applications that are scalar in nature.

Array processors offer users the benefit of having ultimate control over their applications. They can control such functions as I/O, dataflow and arithmetic processing. Of course, more effort is required to develop applications for array processors than for application accelerators.

Digital signal processors

For applications dealing with signal processing—radar, sonar, speech/voice processing and real-time control, for example—digital signal processors are a popular solution for increasing application speed. These processors accept large quantities, and often continuous streams, of data. DSP applications typically have small memory requirements because of small algorithms and because applications often perform data reduction.

The architecture of DSPs is optimized in favor of the specialized range of algorithms used in signal processing, such as finite impulse response filters. Software includes a library of signal-processing routines that execute on-board. It also includes host routines that allow a program executing on the host computer to communicate with the board.

Traditional DSPs have been fixedpoint processors. This allowed a fairly low cost chip to be used in embedded systems. The drawback was that algorithms that needed floating-point capabilities had to emulate floatingpoint computations.

Some of the newest DSPs, however, work with 32-bit floating-point data, so users can now program their applications using 32-bit floating-point arithmetic. The 32-bit precision is more than adequate for most DSP applications that involve 12- or 16-bit input data.

In general, for an application accelerator, array processor or DSP to be successful, it should meet one basic criteria: a workstation equipped with one of these products should run a numerically intensive application at least five times faster than a workstation lacking such a product. And on certain types of numeric processing, a 10- to 20-times performance improvement should be achievable.

Bruce Rusch, BSEE, president and chief executive officer, Sky Computers

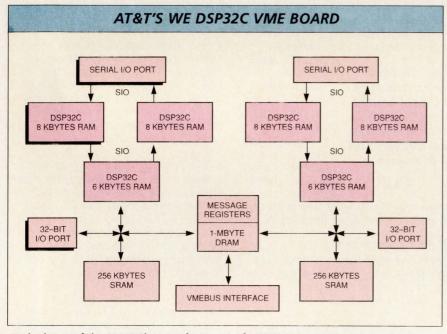
DSP ON BUSES

eliminates this type of overhead. It allows the coprocessor to fetch the instructions for itself automatically, freeing the host CPU to manage the data flow. The board is capable of fetching 20 Mips—many times the rate a host processor could supply them.

Mixing the buses

While Io has taken its full-sized daughterboard approach, Pentek has adopted a totally different tack, stealing some of its Multibus II TMS320C30 Mix daughterboard technology for adoption on VME. Pentek's Multibus II entry, based on Intel's Mix (Modular Interface Exthe Mix modules for Multibus II, and we wanted to avoid reinventing the wheel." According to Hosking, Pentek went to Intel with the idea of developing a VMEbus Mix baseboard, "expecting to get shot down." (Intel hadn't yet fully released the specs for Mix.)

Intel not only gave permission for Pentek to develop the board but, says Hosking, actually helped. The resulting VMEbus baseboard, unlike conventional CPU baseboards, is based on TI's 320C30. The board has, in addition to the C30, 4 Mbytes of dual-ported DRAM, one port of which is connected to the processor and the other to the VMEbus. It also



At the heart of the 150-MFlops performance of AT&T's WE DSP32C VME board are two DSP32C clusters, each containing three devices. Only one of the three devices is connected directly to the DRAM. The others are connected through the chips' 16-Mbit serial ports to the cluster's serial port for pre- and postprocessing.

tension) bus, includes a 320C30 Mix processor module and some advanced 12- and 16-bit A-D converter boards. The 320C30 Mix processor board is designed to operate with Intel's 80386 baseboard. "The ability to stack up to three Mix modules," says Hosking, "lets users create an entire data-acquisition/DSP subsystem on a single Multibus II card. All it takes is an 80386 Mix baseboard, one or two 320C30 Mix processor modules and an A-D module."

"When we first developed our VMEbus DSP card," says Hosking, "we saw a need to tightly couple a second processor and/or an A-D interface. But we'd already developed has 256 kbytes of zero-wait-state SRAM, and 16 kwords of 32-bit EPROM. The Mix connector allows attachment to up to three Mix modules, which can be either additional C30 processing modules or data-conversion modules.

This approach, says Hosking, has been successful in a variety of applications in embedded control where people are doing real-time processing of speech, sonar, radar or other types of communications.

Unlike the Multibus II solution, in which a baseboard and one Mix board occupy only a single Multibus II card-cage slot, the VME solution takes up an extra slot. "Because of the limited space in a VMEbus card cage, three Mix modules plus the VMEbus baseboard occupy four slots," says Hosking.

Other Multibus solutions

Pentek's Mix approach is one of the few DSP solutions available on—or for—Multibus II. One of the few other solutions—and one of the first, in fact—comes from McDonnell Douglas (St. Louis, MO). "This Multibus II DSP board," says senior lab engineer Brian Leger, "was designed early on in the life of Multibus II." Since then, the board has continually been updated from the initial 32020 version, to the 320C25 and the soon-to-be-introduced 320C26 version.

The board was designed to synthesize aircraft sounds for the company's flight simulator. In addition, the board synthesizes special pilot signal tones as well as speech synthesis and analysis. The updated version, says Leger, allows for about three times the on-board RAM, increasing the 16-bit-wide memory from 0.5 to 1.5 kwords. This will allow a monitor to be written for the chips' serial ports. Each of the boards uses four 320C25s now and will share the same complement of C26s. The only other major Multibus II offering comes from Micro Industries (Westerville, OH), which McDonnell has licensed to make the C25 board.

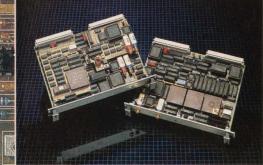
Most target VME

By far, the greatest number of DSP solutions appearing on industrial buses are emerging on VME. According to the 1990 VME Compatible Products Directory, 18 different manufacturers report making DSP VMEbus products. Five of those make products based on TI's 320 family of chips, eight use Motorola's 56000, and six are using some other DSP chip or chip set, including AT&T's DSP16 and DSP32C, Analog Devices' AD 2100, BIT's 2100 chip set or other solution.

Sky Computers offers a complete line of VMEbus-based products for straight DSP applications, array processing and application acceleration, according to Boozer. Sky's latest product is the third generation in its family of 320-based products. Boasting a pair of 320C30 processors, Sky's Challenger-C30 provides up to 66 MFlops and 32 Mips.

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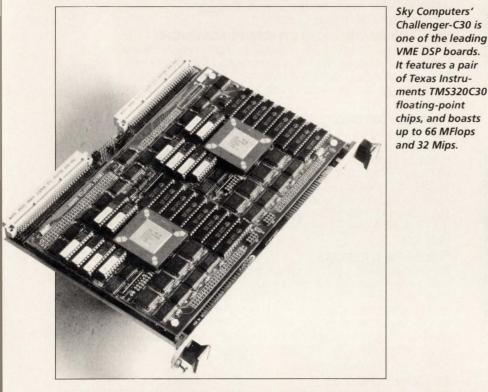
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DSP ON BUSES

the beta site for the product—is Lockheed/Sanders (Nashua, NH), where the card is used in a classified, real-time voice-processing system. According to Lockheed, several similar products recently introduced failed to match the performance, precision and ease of programming of the Sky product.

"Sky's Challenger-C30 uses two DSP processing nodes," says Boozer, "each comprising a 320C30, 256 kbytes of SRAM dedicated to each node, 32 kbytes of SRAM private board memory, and 2, 4 or 8 Mbytes of shared global DRAM." The large shared memory and resultant bandwidth allows each DSP node to perThe parallel port—which can be thought of as a fully programmable high-speed local bus—can be used to daisy-chain multiple boards together or to interface with other high-speed devices such as A-D or D-A converters.

The parallel port—or ports, more often—is a fixture on almost all of the commercially available DSP boards. Obviously, the processor is capable of operating on data far faster than it can be transferred over the host system bus and/or stored in local memory. Furthermore, in many typical applications, multiple processes are going on simultaneously, with one processor



form independent tasks. In addition, multiple nodes can be connected to take advantage of the board's simultaneous processing capabilities.

The two on-board DSP nodes communicate via a high-speed internal bus or through a dedicated serial link. A second serial link provides communication between each node and other external resources, such as A-D converters or additional processors. In addition, each node has its own high-speed bidirectional parallel port, serving as a local bus.

The parallel port is essentially an extension of one of the processor's parallel buses and can be used in a variety of ways to satisfy the requirements of different applications. feeding the results of its calculation to the next and so on down the line.

It's interesting that there is little commonality between the external proprietary ports of various boards. A board being developed by Loughborough Sound Images (Loughborough, UK), which also sports a pair of 320C30s, uses two very fast private buses, according to Bill Meshach, consulting engineer at the company. Meshach says the company looked carefully at other alternatives, including secondary buses such as VSB and 'standard' mezzanine buses, but found that none could provide the type of performance required.

Loughborough Sound has devel-

oped a broad family of DSP boards on both VME and PC buses using the Analog Devices, TI and Motorola DSP chips. Spectrum Signal Processing (Waltham, MA) markets Loughborough's products in North America.

Megafloppage

Local buses take on added significance when tying DSPs together on a single board. While boards based on multiple 320C30s are starting to approach 60 MFlops and beyond, the real performance winner is a VMEbus board from AT&T. The board was designed as a multipurpose development platform to provide raw processing power for analog interface applications and software tools, according to Jim Snyder, member of the technical staff at the Murray Hill signalprocessing research group.

The 6U×160 VMEbus card combines two "clusters" of three 50-MHz DSP32C processors, achieving an unparalleled 150 MFlops. And while Snyder takes justifiable pride in the performance of the AT&T board, he explains that the "megafloppage" claims by themselves aren't what's most important.

What really counts, says Snyder, and what designers are looking for, is a system that can take a signal in the front end, do some serious processing and send it back out the other end in as close to real time as possible. This frequently takes the form of taking information in and doing some kind of transformation on the front end-for example, converting from one standard domain, such as frequency, to another, such as time. The signal is then processed according to some set of routines and then transformed and sent out. Transformation can, for example, take the form of a fast Fourier transform at the front end and an inverse FFT at the other end.

AT&T's VME board, says Snyder, is well equipped to do exactly that. Similar to other high-performance DSP cards, it has a high-speed port on each node, and a bus and memory interconnecting the two clusters of DSPs. The board provides a realtime data path on a serial link to all the DSP32Cs in the system.

Each "cluster" of processors comprises two DSP32C5E processors and one DSP32C. The two processors differ in that the 5E has no external memory-accessing capability. Between the two clusters is up



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DSP ON BUSES

to 4 Mbytes of DRAM, which is accessible to either cluster as well as to the host VMEbus. Each cluster also has its own 256 kbytes of memory, and each processor has 8 kbytes of internal memory.

The need for tools

As each new generation of processor emerges and is harnessed in some board-level implementation, successive boards will continue to leapfrog its precursor in performance. But designers need tools to effectively utilize that performance. "The challenge to the board maker is to provide better packaging, make the product even easier to use, and provide the software tools necessary to let a designer solve a problem," says Boozer.

The basic tools to implement a filter, FFT or other function are provided by the chip makers. But the rest of the pieces to the software puzzle—integration with an operating system such as SPOX, interface to utility routines and documentation—is lacking. "These are the types of things—the value addedthat Sky provides with its hardware platform," Boozer says.

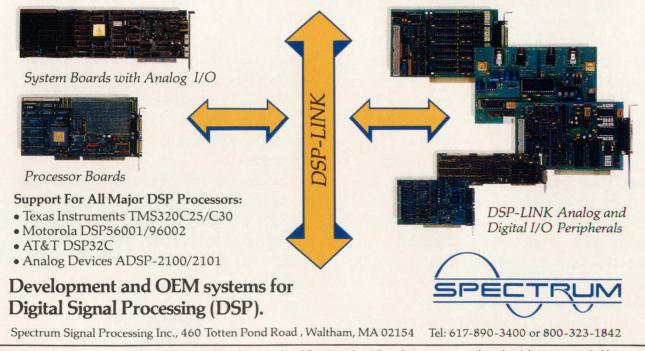
Sky provides full DSP support for Sun-3 and Sun-4 workstations running SunOS. The software consists of host utility routines, C30 usagesupport routines, a multiboard debugger, Sun device driver and the SPOX DSP operating system. The SunOS driver supports up to 16 simultaneously active dual-processor C30 cards. Programs can be written in TI's 320 C and can include assembly-language statements for faster execution. For fine-tuned applications, the entire program can be written in the C30 assembly language. The board uses TI's standard tools to compile, assemble and link programs.

Others have gone even further in providing a development environment. AT&T, for example, has an extensive library of software routines for its DSP32C, but has supplemented them with a variety of other tools including a source-code debugger and a tool called DSPX, which provides library functions in C and provides for direct connection between the DSP function and a Unix-based operating system. \Box

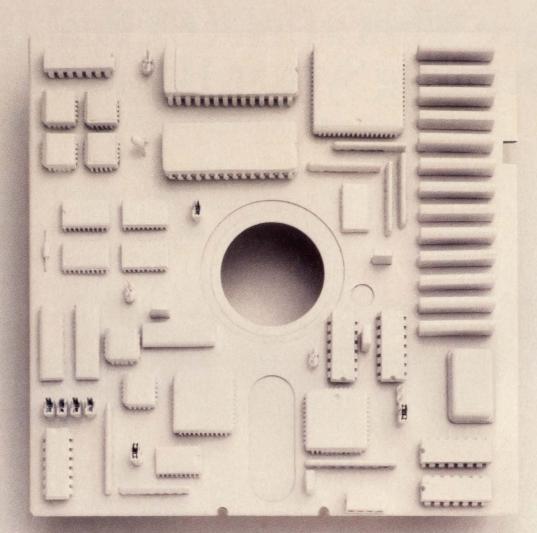
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16-bit MCUs diversify to survive

Seeking to secure their niche in the gap between cheap and powerful, 16-bit architectures take distinct approaches to meeting application demands.

Ron Wilson Senior Editor



ike species struggling against a harsh environment, 16-bit micro-

controller families are seeking out niches where they can survive and prosper. In the process, the chip architectures are diverging from each other, increasingly reflecting their differing origins. Design managers must be aware of these differences if they're going to find the right chip for their application.

"It's amazing how each of these 16-bit chips fits into a different niche," says Nicholas Andrews, president of real-time kernel vendor Byte-BOS Integrated Systems (San Francisco, CA). "Each one has a different blend of cost, power consumption, memory size and peripheral support."

Many of the characteristics of a particular 16-bit architecture follow directly from the vendor's original concept of the market. The earliest 16-bit MCUs, for instance, were point products, designed for—and often with—a particular customer for a particular product. These chip families have grown by elaborating on the original design.

Other families grew out of vendors' notions of product migration. Some predicted that as code grew larger and functions grew more complex, there would be a migration from 8- to 16-bit parts. Hence they concluded that 16-bit architectures should be supersets of popular 8-bit architectures. Other vendors expected just the opposite—that increasing integration would cause a migration from 16-bit and 32-bit microprocessors into singlechippers. These vendors naturally favored chips that resembled 16-bit board-level computers.

Still other vendors attempted to derive an architecture from the design tools and concepts they expected customers to use. They produced designs that emphasized the needs of high-level languages. Each of the four approaches has produced a distinct class of parts, with distinct strengths and weaknesses in a particular application.

The point solutions

The first vendor to find a volume market for 16-bit microcontrollers was Intel (Chandler, AZ) with its 8096 MCU. In the joint development of the part, Intel established a pattern of architectural choices that would be followed, perhaps unknowingly, by several other vendors. From one-off products designed for particular customers, 16-bit microcontrollers are spreading out. The variety of pinouts and packages in National Semiconductor's HPC family demonstrates the degree of diversity these families are achieving.

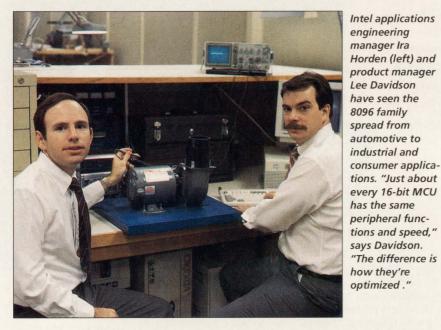
16-BIT MCUs

"The 8096 was designed along with the participation of an automotive industry customer," remembers Intel product manager Lee Davidson. "As in later 16-bit parts, the design emphasized the ability to capture an event, set up an event, perform data conversion and do fast arithmetic."

Intel, already dominant in 8-bit microcontrollers, had to face the fact that its 8-bit architectures simply couldn't be stretched to achieve the to perform event measurement and pulse generation with little cost to the CPU.

Expanding the scope

A similar effort at National Semiconductor (Santa Clara, CA) resulted in a similar product, the HPC. "The HPC was originally biased toward the needs of anti-skid braking systems," says National technical marketing program manager Richard Ahrons. Like the



performance needed by the application. So the company started with a clean sheet of paper. "We chose to go for performance rather than compatibility," says Davidson.

The result of Intel's efforts was an architecture characterized by fast 16-bit arithmetic, a register-to-register instruction set with a large on-chip register file, and semiautonomous peripheral devices—such as analog-to-digital converters, capture registers and pulse-width modulators (PWMs) to handle the most demanding types of I/O transactions without CPU intervention.

At the time, virtually all embedded-control tasks were programmed in assembler, and very few designs approached 64 kbytes in size. These assumptions found their way into the 8096 architecture as well. In sum, Intel produced a compact, inexpensive part—by 16-bit microprocessor standards—that could be hand-coded to produce very high calculating speed and could rely on new, complex I/O modules 8096, the HPC emphasized tight, very fast assembly code in what was then a big 64-kbyte address space. Unlike the 8096, which addresses all of its on-chip RAM as registers, the HPC uses a more-conventional small register file.

After initial successes in the applications for which they were created, the Intel and National chips began to branch out. "The HPC is now used in engine control and in printers," Ahrons says. The 8096 and its slightly expanded, considerably faster offspring, the 80C196, have spread to other automotive applications, to disk drives, and into such unsuspected niches as motor control for air conditioners.

As the chips have diversified, they have shed some of the assumptions that originally shaped them. "The original 8096 part had peripherals that were too customer-specific," says Intel applications engineering manager Ira Horden, "so we modified them before bringing the part to the general market." From there the part evolved through an NMOS- to-CMOS transition, addition of more interrupt sources, and expansion of some internal buses to produce the current 80C196 family.

Ahrons says that the HPC is in the midst of an evolution of its own. "In our 32-bit products, National has customized the CPU cores themselves for faster execution on specific applications, such as laser printers," he says. "That process will also happen on the HPC—it will give the product line some new directions."

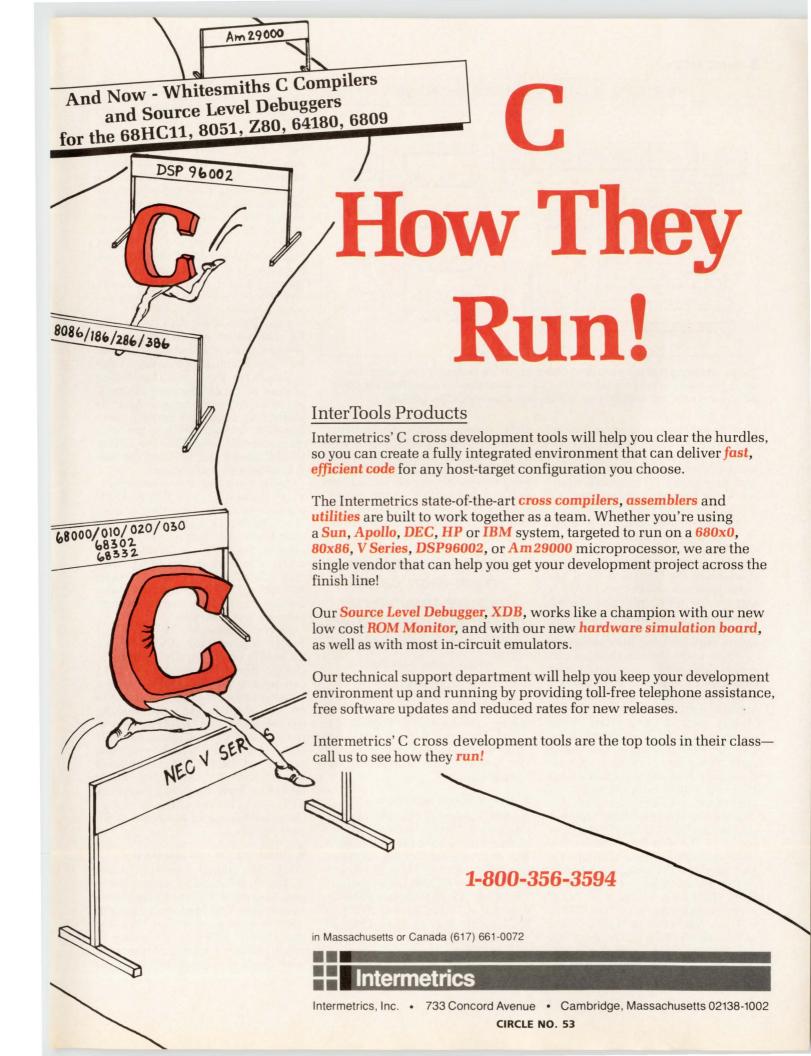
Another issue to which the original 16-bit chips have had to adapt is the increasing use of C in microcontrollers. Both the 8096 and HPC architectures have finely crafted instruction sets, but this crafting was done for speed, not for the benefit of compiler writers. Fortunately for both designs, the distinction didn't turn out to be an insurmountable problem.

In fact, Intel's Davidson argues that having an instruction set chosen for hand coding can be a benefit in today's C-dominated world. "Across all our application segments we see great amounts of code written in C. But the critical routines are still done in assembler—you have to be able to generate tight assembly code. That doesn't get you off the hook for handling the C compiler effectively, though. You have to do both."

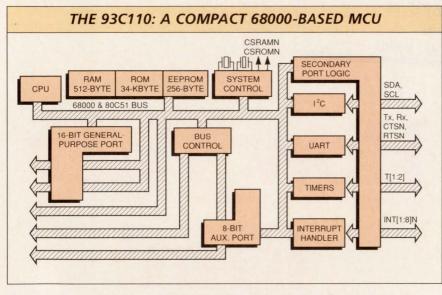
Moving up from 8-bit

As Intel and National were demonstrating the validity of the 16bit MCU concept, other vendors were beginning to look at the market from a different point of view, and with the advantage of more recent CMOS processes. These companies saw the 16-bit opportunity not in isolation, but as an extension of the 8-bit applications they were already servicing. Not unreasonably, the chip designers concluded that the best 16-bit product would be a straightforward extension of successful 8-bit architectures.

The first of these companies to move was Mitsubishi (Sunnyvale, CA). By modeling its 7700-series MCUs on the existing 7400-series 8-bit parts, the vendor aimed at the needs of migrating customers. "We see two kinds of customers," says Ike Saeed, Mitsubishi marketing manager. "Some want to move from 8-bit parts just because they've run out of memory space. These people tend to want the same kinds of instructions and peripherals they



16-BIT MCUs



Philips, believing that users of 68000-based boards are looking for chip-level solutions, has been evolving the old CPU into a microcontroller for some time. The latest edition is the 93C110, a 68000 core with on-chip memory and peripherals.

have now. Others—in motor control and energy management, for example—have run out of time. They need more speed. These people want both more powerful instructions and more sophisticated peripherals to meet their timing requirements."

Mitsubishi took the logical steps to meet these needs. Starting from the 7400 family, the company decided to preserve the very low power dissipation that characterized the older products. Next they began to expand the part, enlarging the address space to 16 Mbytes, addressable in 64-kbyte pages. Then they began enriching the instruction set.

There were obvious changes necessary, like more addressing modes to deal with what would clearly be a memory-intensive machine. Mitsubishi created a total of 38. Additional new instructions were necessary for 16-bit arithmetic, helping out with floating-point, and so forth. But many of the new instructions were created for a specific issue that had come up since the design of the 8096: C. While it probably wouldn't be fair to say the 7700 series was designed to be a C machine, many of the 104 instructions (the 7400 series has 63) are there to support high-level language constructs.

The combination of low power, rich instruction set and large memory space has given the 7700 a unique spot in the 16-bit MCU business. Saeed believes the part will only expand its scope in the future. "We're moving in two directionsfirst, toward higher performance, with 25-MHz parts that carry general-purpose peripherals. Second, we're approaching some areas that require specific peripheral configurations—areas like motor control, printer control, hard disks and automotive. One new part, for in-

"Some customers move from 8-bit parts because they've run out of memory. Others have run out of time."

-Ike Saeed, Mitsubishi

...

stance, will have DSP hardware to accelerate servo loops. Another will carry an on-chip SCSI controller that will run as fast as 3 Mbytes/s asynchronous."

An old friend resurfaces

Another powerful 8-bit player, NEC (Mountain View, CA), has taken a similar approach to the 16-bit arena, but with a more-familiar architecture: that of the Z80. The recently much-touted NEC K series contains the 8-bit K2, 8-bit-internal/16-bit external K3 and the full 16-bit K6 MCUs with cores that are direct descendants of the venerable Z80 microprocessor.

NEC's belief seems to have been

not so much that people wanted to migrate from the Z80 to a more powerful machine, but that the Z80 architecture gave them the tools they needed to address 16-bit issues. For instance, as NEC senior product marketing engineer Marc Birnkrant explains, "The architecture is optimized for multitasking-an important issue in big control systems. By taking the multiple register bank concept (from the Z80) and expanding it, we are able to do extremely fast context switches." The K6 takes the concept to something of an extreme, providing 16 register banks and some hardware task-management instructions as well.

Like Mitsubishi, NEC expanded its instruction set to support the greater needs of 16-bit applications. Full 16-bit math operations, more registers per bank, and elimination of some of the Z80's arcane addressing restrictions all helped. And the underlying hardware became more complex as well, with a prefetch queue and—in the K6—the ability to look ahead and prefetch the targets of branch instructions.

Along with this more powerful and presumably busier—CPU comes a problem. How do you keep the wonderful CPU from being completely absorbed in servicing interrupts from the wonderful peripherals? The answer chosen by NEC, and later by Intel for a recent 80C196 model, is a hardware datamoving engine that operates autonomously from the CPU.

In NEC's case, the device is virtually a processor itself. In the more-advanced family members. the Peripheral Management Unit can not only perform DMA-like data transfers, but can also filter the data on the way through, performing comparisons and Boolean operations. Vahid Ordoubadian, an NEC senior field applications engineer, points out that these capabilities can be used for tasks that would otherwise have to get high-priority CPU time, like searching for immediate commands in a stream of incoming data.

Shrinking the old standard

While Mitsubishi and NEC have looked to 8-bit architectures for a core to expand, Philips Components (Sunnyvale, CA) has been looking in just the opposite direction. "We saw that 16-bit MCUs were trying to solve problems that had formerly been handled by 16-bit microproces-

Choosing the right MCU—a real-time O/S vendor's view

A unique viewpoint for comparing 16-bit is MCUs that of Nicholas Andrews, president of real-time kernel vendor Byte-BOS (San Francisco, CA). In porting his C-based multitasking operating system, Andrews is asking microcontrollers to do things everybody knows the little chips can't do: support an on-chip kernel with formal task management, run compiled code, and execute portable applications software.

Consequently, Andrews has had to produce small, efficient versions of his BOS kernel for a variety of 8-and 16-bit controllers. This process has given him a good look at the hardware decisions, instruction-set choices and design toolsets that characterize major 16-bit families.

One important issue for Andrews is memory space. The first question here is whether the operating system and the application tasks can fit in the part's internal memory. A few years ago, the answer would have been an obvious "no," but this is changing. "Some of the latest versions of the Mitsubishi 7700 have 32 kbytes of EPROM and lots of RAM space," says Andrews. "At that level, you can fit the operating system and a big application into the on-chip memory, and have a single-chip system."

Beyond the physical memory on the chip, Andrews is concerned about the total address space of the device, and how it is organized. As an example he points out, "The Intel 80196 family has excellent peripherals and a fine instruction set, but it's limited to 64 kbytes each for code and data. This almost makes the chip a niche product for people whose code will fit into 64 kbytes." Address spaces of other microcontrollers range from 1 Mbyte for the Hitachi H8 and H16 architectures up to 16 Mbytes for the 7700.

Organization of the address space can also be an issue. Most single-chippers use a segmented address space, presumably to keep the instructions compact. But segmentation imposes its own problems. "If you compare two CPUs of similar performance, maybe the 16-MHz Intel 80C186 and the Motorola 68332 would be head-to-head," he says. "But there's about 30 percent more work involved to support the segmented address space model of the 186."

Peripheral matters matter

It's obvious that memory is a critical resource for an operating system. But at first glance one would think on-chip peripherals—things like timers and analog-to-digital converters—would be purely an applications issue. Not so, in at least one case, according to Andrews.

"One of the things you need to implement a multitasking operating system is a heartbeat timer: a piece of hardware to mark off the basic time interval for task control. Almost all controllers have at least one timer available that I can use for that, but the implementation varies from chip to chip.

"On the 68332," Andrews adds, "you have these very sophisticated timers in the timer processing unit, but you also have a separate programmable interrupt timer that's just right for the heartbeat timer job. The Motorola people seem to have anticipated the problem and solved it. The 7700 may be more typical—it has eight general-purpose timers, and I use one of them, meaning

Andrews is asking 16-bit MCUs to perform the impossible.

it's not available to the application." The most difficult

situation, according to Andrews, comes up on the 80C196 family. Here, there are only two timers, and if the applica-

...

tion requires both of them—which frequently happens—the heartbeat timer ends up being tied to a multiple of some clock frequency used by the application. In addition, the timers lack an auto-reload register, so the operating system must calculate a correction to load into the timer in compensation for the time lost in recognizing the timer interrupt and reloading the device.

Instruction issues

The instruction-set architecture of the microcontroller can also be an important issue for the operating system vendor, for two different reasons. First, a good port depends on a good compiler, which in turn depends on the quality of the chip's instruction set. Second, critical parts of BOS are written in assembly code for performance reasons. This forces Andrews to deal with the ease-ofcoding issue for a chip as well.

Andrews cites the 80196 in particular for the quality of its instructions. "Finally, a good, orthogonal instruction set on an Intel machine," he comments wryly.

Not surprisingly, architectures borrowed from the microprocessor world also rate well for Andrews' needs. "I just can't say enough about the 68332 architecture. There are a lot of tools, and you get really tight C code—and about the best context switch of any microcontroller. The 68332 took the fewest instructions of any chip to implement the BOS kernel—sometimes you can do in one instruction what it would take other machines eight instructions to do."

At the opposite end of his list is the 7700. "The instruction set is very rich, but it's weak in bit-manipulation instructions and not entirely orthogonal," he complains. "That makes the chip very difficult to program in assembler.

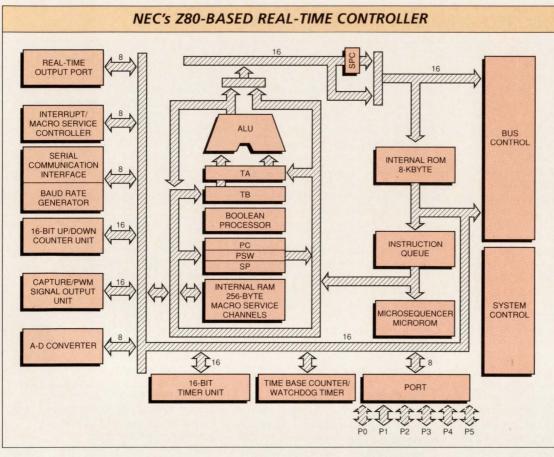
"Fortunately, Mitsubishi's C compiler does a good job of making up for the instruction set," he continues. "For instance, you have to set a control bit in the CPU to determine whether the next instruction operates on a byte or a word. The compiler manages to look through the code and minimize the amount of thrashing it has to do on this control bit. So you end up with reasonably efficient code."

The issue of compiler quality raises the more general question of tool availability. Since the 16-bit parts aren't yet widely used, they can lack the range of third-party development tools that an 8051 or 68HC11 user might expect. "One of the drawbacks of the 7700 right now it that Mitsubishi is the only source of tools," Andrews says. "But so far, the company's support has been great, and I understand there are more tools on the way for the chip."

There seems to be a good correlation between the age of an architecture and the volume of tool support. The 8096 family, for example, has the oldest mainline 16-bit controller architecture. It also boasts excellent tool support from both Intel and third parties.

Yet Andrews sees one trend that could break up this state of affairs. "Motorola sells a \$700 development system for the 68332 that gives you an execution target plus emulation capability. The tools are really inexpensive and very good. There is virtually no cost to get into this chip. As the chips get more powerful, this sort of development tool, using the controller itself, could become a trend." For the software developer on a limited capital budget, that could be as big a consideration as any of the others.

16-BIT MCUs



You might not be able to tell from the feature list, but NEC's new entry into the 16-bit fray-the µpd78312—is based on the Z80 architecture. A vastly improved instruction set, legions of registers and a powerful DMA engine put the chip in a different class from its ancestor.

sors," says Shlomo Waser, marketing manager at Philips. "So it made sense to start with the architecture of the most popular 16-bit embedded microprocessor, the 68000, and reform it as a microcontroller chip."

The first step in this process, taken years ago, was the integration of timers and a Philips I^2C interface onto the 68000 core to form the 68070. Most recently has been the addition of RAM, ROM and more peripherals to create the 93C110 family of full-blown microcontrollers.

Waser recognizes that this isn't the ideal approach for every application. "Fast interrupt response isn't the 68000's strong point. The 93C110 isn't the optimum solution for engine control, for example," he admits. "But for data-driven applications like graphics, a compact 68000-based solution is ideal."

Not surprisingly, Waser sees system architectures somewhat differently than, say, Mitsubishi might. His model involves a concentration of code and processing power in the 68000 device, and a surrounding I²C network of intelligent peripherals, smaller microcontrollers or state machines to reduce the interrupt load on the main CPU. For applications that require large amounts of code, that would benefit from the superb programming tools of the 68000 architecture, or that are being ported from the 68000-based board-level computer, the solution seems to make a great deal of sense.

From a clean sheet

Despite the appeal of arguments that customers of 16-bit MCUs want to work with a familiar architecture, some vendors think that the needs of this market are so unique that they must be met with a fresh start. Among these is Siemens (Santa Clara, CA), whose 80C166 MCU has the distinctions of being the first European 16-bit MCU architecture and the first CMOS MCU to be second-sourced—by SGS-Thomson (Phoenix, AZ).

"The chip was designed with two goals: short interrupt latency and high instruction throughput," says Ash Ahluwalia, senior product specialist at Siemens. The creators of the part achieved these goals by applying some of the latest RISC-ish thinking from the microprocessor world to the design of their MCU core.

The resulting architecture takes ideas from many sources. For instance, the chip uses a branch cache. Like Sparc-and the 8096-the device treats on-chip RAM as banks of registers. It can switch between any of the sixty-four 16-register banks in a single 100-ns machine cycle and do a multiply in less than 1 µs. Also like many RISC machines, most instructions are executed in a single cycle, via a four-stage pipelined execution unit. "But unlike many 32-bit machines, the pipeline has been designed so that it can be flushed elegantly," says product marketing manager Mike Rampelberg.

An important point about the 80C166 is that throughout the design, the architects knew that the chip would be programmed primarily in high-level languages. In fact a compiler team developed the MCU's C compiler while the silicon folks worked on the chip. This close coupling led to such hardware features as a 16-Mbyte address space and the ability to pass parameters through overlapping register windows. On the software side, the teamwork made possible inclusion in the C compiler of commands that exploit

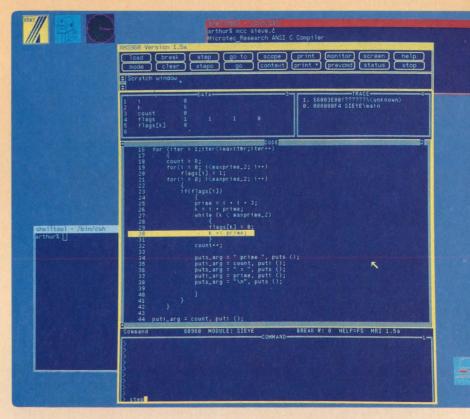
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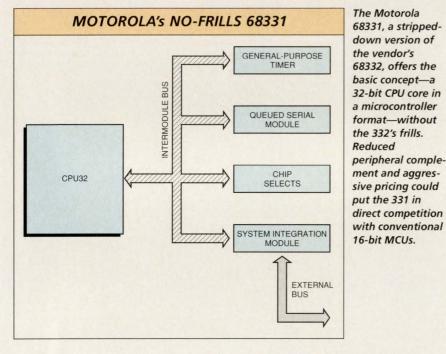
16-BIT MCUs

the chip's fast context switching, and C support for an on-chip cyclestealing data moving engine called the Peripheral Event Controller.

With its fast computation and context switching and excellent linkage to C, the 80C166 should do a fine job of delivering its latent performance to C-language programmers. But perhaps the ultimate effort in this regard has been made by another vendor, Harris (Melbourne, FL), whose RTX MCU pointed Harris. The part, which can use its four buses to simultaneously perform stack, computational and I/O operations, has become an important ingredient in Harris's embedded computing mix, both as an ASIC cell and as several flavors of standard products.

Covering all the bases

The 16-bit world, then, covers a wide range of architectural ideas. Some architectures have grown out of the



family was originally designed specifically to execute Forth.

"Originally the RTX architecture was one of the few ever intended for direct execution of a high-level language," says David Williams, RTX market development manager. "But when Harris looked at acquiring the technology, we saw not just a Forth machine, but a very fast generalpurpose stack architecture, implemented in a very small—about 4,000-gate—core.

"We knew that stack architectures were well suited to executing code from many different language sources. And because stack machines inherently have very little context—no pipelines, no caches and no queues—they are very easy to use in demanding event-driven environments. Also, we knew that a core this size could be just what we needed—a powerful 16-bit MCU that could be an element in our ASIC cell library."

The RTX apparently hasn't disap-

concept of hand-crafted code and application-specific peripherals in an anything-for-speed design. Other parts have been blended from a combination of older architectures and newer ideas. Still other designs have come out of entirely fresh thinking about fast execution of high-levellanguage code in a multitasking environment.

The one major 8-bit player that has remained on the sidelines of this entire debate has been Motorola (Austin, TX). With its externally 8bit 68HC11 family and its full 32-bit 68332 family, the company had bracketed the cost/performance range of 16-bit MCUs without ever actually entering the 16-bit waters. Now that is changing as well. In a series of steps begun last month, Motorola will unveil its midrange strategy.

Initially, Motorola has shown an upgraded 68HC11, sporting improved speed and memory size, and an on-chip memory manager for greater-than-64-kbyte address range. "This part will compete headon against 80C96-class 16-bit MCUs," boasts Motorola director of marketing Steve Marsh.

This month, the company will boost its efforts to promote the 68000 architecture for MCUs by introducing price cuts for the existing 68332 and rolling out an ever lowercost subset of the big part: the 68331. The new device is intended to offer the 68000 architecture and the sophisticated peripheral environment of the 332 at a price competitive with high-end 16-bit parts.

The end of the unveiling will happen next month, with the announcement of Motorola's longawaited true 16-bit MCU. The company won't release architectural details yet, but Marsh is clear about the philosophy behind the chip. "It's our perception that in the migration to more powerful MCUs, 32 bits is the right place to change instruction-set architectures. And 16 bits isn't the right place to make people change."

This sequence of announcements seems to put Motorola firmly in almost everyone's camp. The vendor is supporting the notion of evolution from 8-bit architectures. And it's offering a complex 32-bit architecture originally intended for use with high-level languages and operating systems. Motorola's message—and perhaps the best overall conclusion about the 16-bit parts—is that each approach has its own validity for a particular set of application needs. None is all-powerful, and none is obsolete.

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How much can Design-for-Test reduce the need for testing?

Jon Gabay Contributing Editor

Making a design functional and making it producible have been two different tasks. Now, test standards, tools and embedded circuitry move them closer together—and into designers' hands.

he test issue has plagued engineering ever since the cave man who invented the club accidentally knocked himself out to prove to the tribe that it worked. Many engineering firms are still knocking themselves out to tackle the tough testability problems of today's more advanced and sophisticated designs.

Unfortunately, when a design task is given to an engineer or an engineering team, the foremost concern on their minds is to get a functional implementation of the specific tasks implemented. Testability of functional verification and system-level verification is often not even considered when an engineer sits down to design a circuit, subassembly, assembly or system.

What complicates matters even more is that on large designs, many engineers may be simultaneously working on different sections. In this case, even if each individual engineer has a test philosophy in mind, merging them together later to obtain a system-level test strategy (either for functional verification or fault analysis during debug or production repair) can be a formidable task.

Engineers typically design, debug and implement first, then work on a test strategy. When test philosophy is imposed, it will usually involve another iteration through the design loop. Later, a system-level test philosophy may cause each engineer to iterate yet once again. This is time-consuming, redundant and an ineffective solution to satisfy today's time-to-market demands.

The overburdened engineer

The double-edged sword caused by design automation has left the engineer responsible for yet even more. Since schematics can be captured and edited rather quickly, schematic capture is part of his or her dance card. Likewise, since simulation technology is advanced to a usable point, these tasks are added. Although simulation has taken a bite out of breadboarding, a prototype isn't uncommon—again, something the engineer oversees.

What's more, today's designs are often pushing the limitations of blind printed circuit board designs. The higher clock rates, more functionally dense systems, and mixed analog and digital designs require the engineer to take an active part in the layout of the printed circuit board, instead of merely handing off a schematic to a department or service. On top of all that, the engineer must be responsible for some form of documentation.

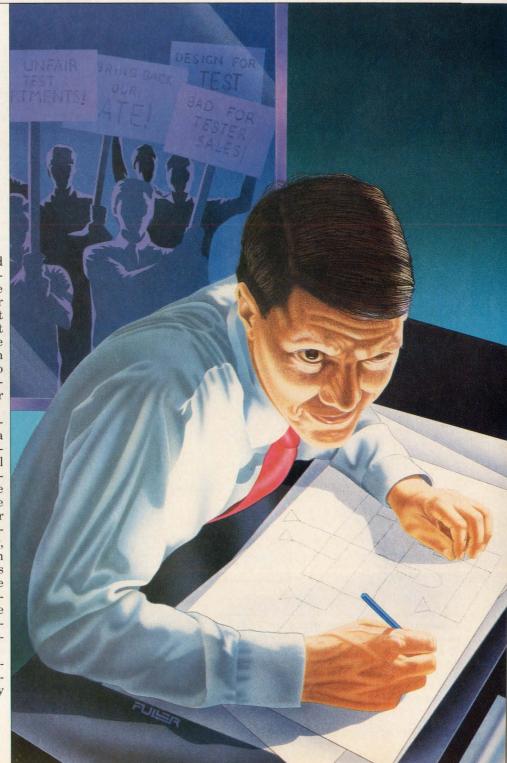
The engineer is tied up even longer when test constraints are imposed after board layout. At larger companies, which often have dedicated test engineers on staff, the test engineer is usually given a blackbox approach to work with, meaning that his or her expertise is injected after the functional portion of the design is in place.

What complicates matters even more is that with many of today's designs, including embedded microprocessors and microcontrollers, software testing for effectiveness, performance and bullet proofing adds even more stress.

The ideal approach

Ideally, test strategy should be mapped out at the time of product conception and definition. This test strategy will vary greatly from company to company, depending on what test and testability tools they have in place. Further, this test strategy will vary within the same company for each project.

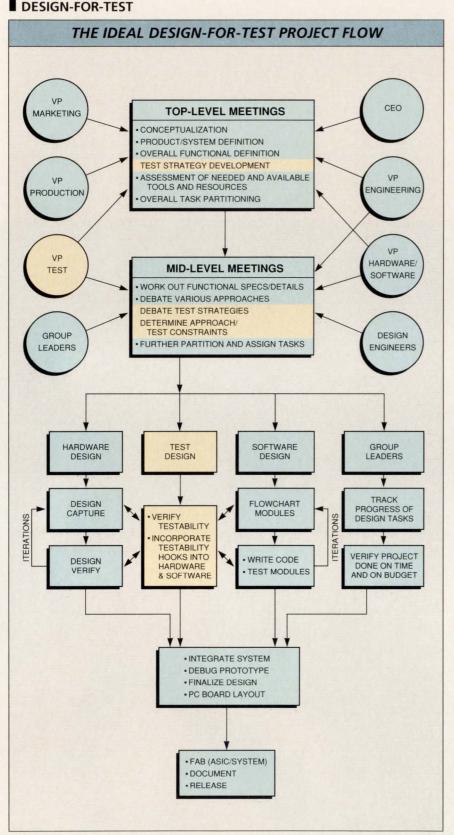
Also in this ideal environment, test engineers work side by side with design engineers, software pro-



grammers and printed circuit board designers. This permits test features to be incorporated at the time of implementation rather than later adding components that may affect critical delay paths or already tight printed circuit boards. A software guru working with the group can also make recommendations as to how to make the hardware implementation more efficient for operation and test.

A design engineer may, for example, have to write to a latch a series of bytes that control the gating and transfers of register-level data. While from the hardware engineer's point of view, any bits of the latch can be assigned as any of the control signals, the programmer may require bit placement in a nonrandom sequence to make masking, state checking and I/O easier from the software point of view. This same philosophy applies when the test engineer and the software engineer work together, since often the most efficient approach is to combine built-in self-test coding with external testing.

While many people may be involved in the loop, it's still the hardware engineer who is ultimately



Engineers typically design, debug and implement first, then work on a test strategy, causing many design iterations. Unnecessary design iterations could by eliminated by mapping out a test strategy during product conception and definition. In that approach, test engineers would work side by side with design engineers, software programmers and printed circuit board designers, incorporating test features at the time of implementation rather than adding components later on that may affect critical delay paths or already tight printed circuit boards.

responsible for a design that can be tested. As a result, the designer's choice of parts greatly affects the outcome. Unfortunately, a global test standard isn't yet in place, and each different chip may have its own proprietary test interface, or none at all. What's more, every different kind of device carries its own set of problems associated with testing and design-for-testability within a system-level environment. The simplest is glue logic.

Discrete-function TTL, SSI- and MSI-level functions have no built-in test incorporated on-chip. This means an engineer must physically connect key signals to some form of decoder or multiplexer to observe critical signals within the system. For the most part, glue logic chips are pretty reliable, but a failed NAND gate in a 300-IC board can still be a bear to troubleshoot.

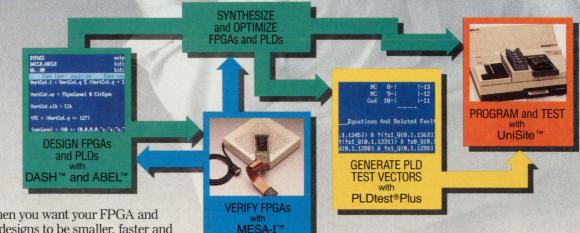
One solution is to take advantage of specialized discrete-function chips that incorporate a test standard. Texas Instruments (Dallas, TX), for example, offers the Scope family of cells as part of its stand-ard-cell library. For discrete implementation, and for designs that need to adapt for scan-path technology, TI also offers octal I/O devices that are compatible with the JTAG (Joint Test Action Group) standard. These devices can be added into scan chains to cover signals and devices not implementing a scan-type test capability. To round off its offering, TI also provides a PC-based development tool called Asset, which helps familiarize, implement and test circuits using the JTAG devices.

PLDs another challenge

Programmable logic devices have gained much popularity and widespread use. But PLDs pose greater quality-control problems than do standard parts, and therefore require a more involved test strategy. With PLDs, more faults are likely to occur and more defects are possible. Testing for only stuck-at-0 and stuck-at-1 faults and intact fuse faults will uncover some faults, but won't uncover many sources of PLDrelated board and system failures.

Fault coverage depends on defining all possible defects for a device and then determining what portion of those faults are detectable through testing. Because PLDs can have so many different types of faults, engineers pick a sample of

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DESIGN-FOR-TEST

defects and measure the detection rates on those sample faults.

In reality, though, what matters is how the measured coverage corresponds to the yield at the next test stage. If, for example, the measured fault coverage at the component test stage is very high, then any defects found at the board- or system-level test stages should be traceable to steps occurring after component programming and testing.

Another concern about PLDs that's not a factor with other logic parts is that programmed functionality may be living in a one-timeprogrammable part or an erasable/reprogrammable part. One-time-programmable parts can't be tested in any incoming inspectional test barrage. Even EPROM-based parts take too much time to program, test and erase enough times to thoroughly verify that part. So only EEPROM- and RAM-based parts can provide some level of incoming assurance before production.

Because PLDs have limited incoming inspection testability, fault grading— the process of evaluating and selecting test vectors for the testing process—is important. When fault-grading tests for PLDs, test designers should include fuserelated faults, particularly faults on blown fuses. Fuse faults are critical because fuses make up most of the physical area on the chip itself. Therefore, most defects appear on fuses.

If a fuse that should be blown is intact, the resulting device behavior can act in a nondeterministic way and can cause symptoms that don't necessarily point to the PLD itself. Consider, for example, a combinatorial circuit that factors in an unused pin as a result of a partially blown fuse, or a fuse that is intact that shouldn't be. If that unused pin is floating, the resulting failure can be intermittent, the worst type of problem to find.

This effect is especially important with the newer architectured PLDs and FPGAs. With so many fuses (or antifuses or EPROM or EEPROM cells), programmable clocks can change polarity, glitch, or acquire enables; macrocells can change types, polarities and functions; product-term sharing can be combined or increase; state machines can lock up, insert new states or skip vital stages; and combinatorial elements can become memory elements. Generally speaking, the more sophisticated the PLD architecture, the more baffling the blown fuse fault can be.

Tools to the rescue

Tools from companies like Data I/O (Redmond, WA) and Anvil Software (Nashua, NH) help detect fuse faults early in the process. "It's important for an engineer doing the design to take time to account for proper and full test-vector coverage, or nightmares and headaches can follow long after the engineer thinks the design is completed," says Stephen King, product marketing manager from Data I/O. "In addition to proper test coverage, it's important to understand how the test coverage is determined, as well as how the programmer will apply these test vectors."

The following fuse faults can be detected.

"It's important for an engineer doing the design to take time to account for proper and full test-vector coverage."

-Stephen King, Data I/O

1) Pin-level faults, including stuck-at faults on all input and output pins of the chip. In-circuit-board testers for standard parts can test for pin faults. Also, properly developed test vectors after programming can detect this.

2) Logic faults, including stuck-at faults on all internal gates, input pins, output pins, column drivers into the fuse array, product term AND gates, OR gates, master and slave latches in flip-flops, threestate enables, set and reset lines, clock lines, and gates inside macrocells. Gates inside macrocells include feedback and output multiplexers, which are faulted at the gate level.

3) Junction faults, including stuck-at faults on each input to each gate. Junction faults differ from logic faults whenever a gate has more than one fanout. That's because a junction fault affects just one or more fanouts, whereas a logic fault affects all its fanouts. The MIL-454 standard primarily addresses junction faults in component fault grading, including PLDs.

4) Intact fuses that are faulted as blown. Each fuse in the fuse array that is supposed to be intact is faulted as though it were blown. This is the same as sticking the fuse junction to a 1 in programmable AND array devices or faulting the input junctions to the product-term AND gates high.

5) Blown fuses that are faulted as intact. Each fuse in the fuse array that is supposed to be blown is faulted as though it were intact. This is the same as causing a short between a column in the fuse array and a product-term line.

Testing semicustom

More than any other form of technology, semicustom silicon in the form of gate arrays, standard cells and silicon compilers has been responsible for pushing testability as a philosophy. If these risky and expensive designs don't work to spec the first time, the engineers have some explaining to do.

In the early days of gate array and standard-cell designs, functionality was fully the driving force. Test vectors verified functionality and didn't trace faulty symptoms back to specific problem areas. Tools and architectural strategies weren't automatically built into the process. As a result, larger companies, and even astute smaller companies, solved the device-testability problem in various and clever ways.

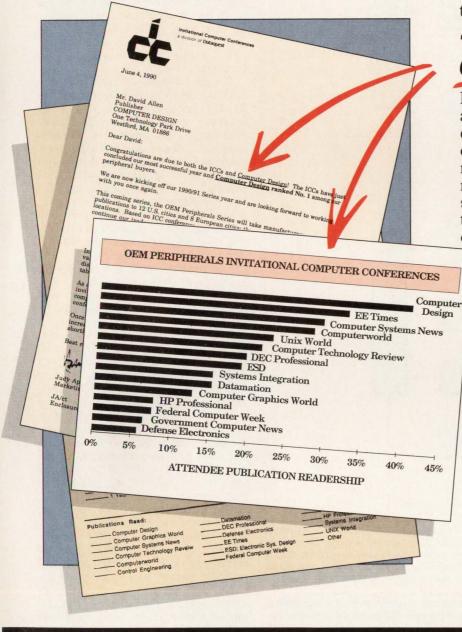
If I/O wasn't the problem, and if test speeds became an issue, parallel dedicated test lines were implemented. In that approach, a proprietary parallel port gave access to whatever internal nodes needed stimulating or observing. In a fashion similar to a microprocessor peripheral chip, each device was addressed, tested and evaluated. But this was inefficient for several reasons.

First, this adds another parallel bus to the circuit board, which may already be tight for space. Also, a proprietary protocol and hardware structure must be implemented in each device. This adds a lot of development time and cost and requires specialized test equipment.

Scan technology is an umbrella term for all the serial protocols and architectures used within a device (or family of devices) to implement

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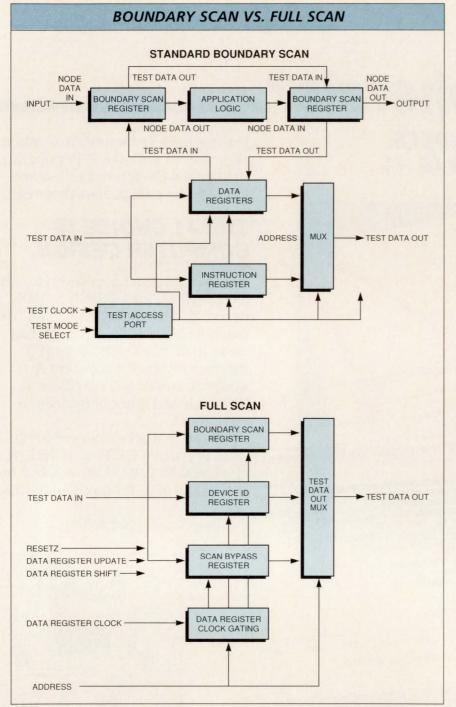
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DESIGN-FOR-TEST



With boundary-scan test techniques, only a few functional logic blocks need be incorporated onto an ASIC to permit complete control of I/O functions. A large shift register encompasses the periphery of the ASIC and, when put in test mode, engineers shift in the applied levels for test, and shift out the results via a test access port, which usually consists of four wires (data in, data out, clock and mode). In full-scan test, a stimulus tap (usually in the form of a multiplexer) is placed on every internal driving signal, and a response tap is placed on every internally driven signal. This approach is faster and more efficient than boundary scan and permits 100 percent controllability and observability.

some form of stimulus and response pertinent to the inner workings of that device (or system). Scan technology is desirable because it provides a window into each device, but requires only a few signals (usually four) to route between devices. Outgrowths of scan technology have diverged into many approaches, the simplest being boundary scan and the most complex being full scan.

Boundary scan is the cheapest and simplest scan approach and introduces the smallest penalties for device performance. Boundary scan involves taking control of all I/O pins, applying test vectors and observing results. Conceptually, a large shift register encompasses the periphery of the ASIC and, when put in test mode, engineers shift in the applied levels for test, and shift out the results via a test access port, which usually consists of four wires (data in, data out, clock and mode). In this way, each ASIC (or device incorporating this test structure) can be effectively isolated and verified.

Boundary scan is increasingly becoming standard practice. The JTAG approach has been gaining interest among the IEEE-P1149 Test Standards Committee, Department of Defense and industry as a workable test solution for device and system-level testing. (See "JTAG testability takes on today's systemtest demands," p 101.) As a result, many semiconductor houses are adopting JTAG support for ASIC customers and providing JTAGcompatible cells or macros.

The problem with this approach, however, is that since only I/O signals are sent and received to and from the devices, test times can be too slow. Consider, for example, a standard ASIC that may implement some type of RAM or FIFO, as well as some other multiregistered and/or pipelined function. Testing memory will require vectors for each location (or each row, if the memory is laid out cleverly), each register, each level in the pipeline and so on. It may take between several hundred and several thousand cycles to see the results of the applied vectors-not an efficient productionline solution.

On the other end of the spectrum is full-scan test, which involves placing a stimulus tap (usually a multiplexer) on every internal driving signal, as well as a response tap (usually routed to a scan latch for observability) on every internally driven signal. This approach is the fastest and most efficient way to test a device and permits 100 percent controllability and observability. But it has other drawbacks.

Full scan introduces a lot of silicon overhead and can almost double the size of a device. Design time is split between functionality and test

JTAG testability takes on today's system-test demands



Advanced technologies are playing havoc with efficient testing of today's morepowerful system designs. Such developments as high pin counts,

submicron processes, tighter package pin pitches, and advanced surface-mount technology stymie the accuracy of traditional test and measurement tools.

But help is at hand. Systems houses can look to JTAG testability for an efficient, up-front test methodology. Test circuitry that conforms to the JTAG IEEE-1149.1 standard test interface and boundary-scan architecture is being implemented in ASICs and other chips to ease board testing.

The key features of the JTAG IEEE-1149.1 standard are a four-wire test bus and boundary scan. Each JTAG-compatible IC has four added pins: two for control (test mode select and test clock) and two for moving serial data in and out of the chip (test data in and test data out). The JTAG architecture includes a test access port for controlling the instruction and data registers. The boundary-scan data register includes a boundary-scan cell at each pin except for the power and ground pins.

During normal operation, the boundary-scan cells are transparent. But in test mode, the cells are linked together to form a serial shift register, thus allowing systems designers to control and observe data at the test data pins.

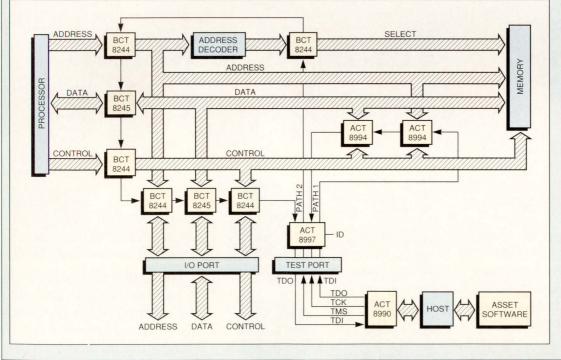
Hierarchical testability

Systems houses are finding that by taking the JTAG route, they can leverage hierarchical testability for higher-quality systems at a reduced cost. This is accomplished because a consistent, structured test approach is used throughout the product life cycle. Test vectors, for example, can be reused throughout the process, from design to manufacturing to field repair and maintenance.

Texas Instruments (Dallas, TX) is the first chip maker to play its JTAG hand, and is promoting the concept of hierarchical testability. Included are special test ICs, ASIC test cells, test controllers, IEEE-1149.1-compatible standard parts, and a computer-aided test-scan-based diagnostic tool. To TI, hierarchical testability means placing control and observation structures into devices for all test and integration levels from ICs to systems. And the heart of TI's hierarchical testability strategy is the JTAG four-wire test bus.

TI pioneered three types of JTAG controllable devices, and they are members of the company's product family named Scope (System Controllability and Observability Partitioning Environment). Scope octals, the first type, are standard busoriented devices with a JTAG interface that serve to create board partitions and add in-circuit testing around VLSI chips, like microprocessors. Scope ASIC cells, the second type, are used in customerdesigned ASICs for 1149.1 compatibility plus access to built-in self-test (BIST). Third, new TI application processors such as the TMS320C50 are 1149.1compatible

The scan-test octals (the devices with the BCT prefix) in the application illustrated below execute such BIST operations as pseudorandom pattern generation and parallel signature analysis. These devices give designers a free hand at isolating specific circuitry within an assembled module, board or system. Through this isolation, engineers can debug circuits, components and connectors without manually probing them. The octals' test capabilities



can also be used to test adjacent devices lacking test structures.

As part of its JTAG commitment, TI recently introduced Asset (Advanced Support System for Emulation and Test). A member of the Scope product line, Asset is a scanbased diagnostic tool for design debugging and hardware testing.

IEEE-1149.1 products should continue to gain acceptance. Such products make sense in light of the poor efficiency that's associated with conventional test methods.

Glenn Woppman, BSIE, product marketing manager, Design Automation Div, Texas Instruments

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CIRCLE NO. 58





DESIGN-FOR-TEST

structure, which is almost always proprietary for each company. Most important, though, is the performance penalty. Every signal is delayed either because it's driving through an extra level of logic, or because it's being driven by a signal, which has to drive an extra load.

A middle-of-the-road partial-scan approach seems to be the most beneficial in terms of device performance, silicon overhead and test effectiveness. With partial scan, a boundary scan can still apply test vectors and monitor responses. In addition, other scan paths can test generators (ATPGs), which produce test vectors that strive to provide total coverage of a design. Test vectors from ATPGs and from other sources are then fault-graded to determine the efficiency of the test vectors regarding how many nodes are accessible and observable.

Fault grading, the process of determining the test coverage, is expressed as a rough percentage of how much of the circuit is stimulatable and observable with a set of test vectors. There are two types of fault graders: probabilistic and deterministic.

Oki Semiconduc-

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The company's scan-test flip-

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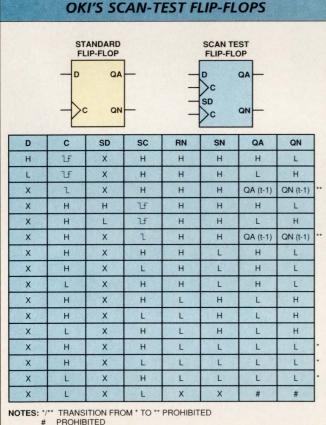
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those problem areas that test vectors either can't, or take too long to, reach. This can provide fast production test with reasonable observability and controllability. More important, it allows engineers to take advantage of the many test pattern generator and fault-grading tools already available.

Tools meet the challenges

Many advances in tools have helped ease the burden of analyzing a device's testability. Now commonplace are automated test vector fast but inexact method that involves statistically extracted results obtained from applying a limited set of vectors. It's useful for getting a quick feel for how good a set of test vectors are at exorcizing and testing the entire device.

Deterministic fault grading is the exhaustive search for coverage of each node as a result of the test vectors. This approach provides an exact number of testable and nontestable circuit elements but takes a lot of computer time. Fault simulation is the umbrella term for applying an exhaustive barrage of test patterns to a device to characterize its failure behaviors. Although limited to the assumption that only one failure will occur at any one time, fault simulation lets engineers work backward from a faulty part to determine the cause.

The problem with fault simulation is that it, too, is very computeintensive. An entire simulation run must be performed for every combination of stuck-at-0 and stuck-at-1 logic states at every node. Concurrent fault simulators speed things up by permitting more than one stuck-at fault to be analyzed in one simulation pass, providing that the stuck-at signals don't interfere with the observable output from each fault. Even so, fault simulation will take time—more time than most are willing to spend.

Improving the design

Design tools such as the Design Advisor from NCR (Fort Collins, CO) and the Design Consultant from Trimeter (Pittsburg, PA) are striving to make the source of the problem better for the process. By improving the design, everything else should improve. These tools, based on expert-system technology, analyze a design and make recommendations on how to increase testability by improving the design structurally without altering it functionally. In addition, these tools can make recommendations on how to increase performance without sacrificing functionality.

Another solution comes from Integrated CMOS Systems (Sunnyvale, CA), which provides a standard-cell library with a twist. In ICS's library, every cell implements a proprietary architecture through which it provides and builds a testable scan path automatically and transparently to the designer, without introducing delay penalties. "A proprietary architecture automatically implements scan-test paths with no delay penalties to every function in a design, including storage elements," says Stephen McMinn, vice-president of marketing and sales at ICS. "We guarantee 99.5 percent minimum fault coverage, and our ATPGs handle the testability task transparently to the designer.' There is still a small penalty in silicon overhead. Typically, though, a 300-pin ASIC can be fully testable at sort time using only 14 pins.

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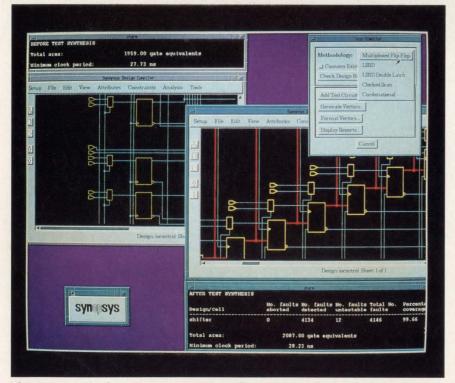
DESIGN-FOR-TEST

Design synthesis tools are starting to flaunt their testability features as well as their design prowess. Newer design compiler tools from Synopsys (Mountain View, CA) and Recal-Redac's ASIC Product Group (Westford, MA), among others, not only generate functional logic but also (transparently to the engineer) make that functional logic testable and automatically provide test vectors with around 99 percent coverage. Since overall, synthesized designs take up to 30 percent less silicon real estate than do gate and macro-level manually produced designs, the addition of another 30 percent to make a design fully testable brings the design close to parity with the silicon real estate of a manual design.

The Silcsyn tool from Recal-Redac (formerly Silc Technologies) provides a register-transfer-level scan capability that lets designers specify the allowable sequential depths of circuits. Silcsyn is an outgrowth of the MacPitts silicon compiler project from the Massachusetts Institute of Technology. The MacPitts compiler was perhaps the first truly behavioral silicon compiler, but its silicon implementation was inefficient. "We have stripped away the siliconspecific aspects of the tool and instead map it into libraries from specific silicon vendors from the proprietary design language notation, VHDL or EDIF netlist source file," says Paul Lindemann, director of marketing of Racal-Redac's ASIC Product Group. "The resulting tool automates design-for-test constraints and provides a flexible input and output mechanism for integrating into a design environment."

The Synopsys Logic Compiler accepts Boolean equations or netlists as inputs and provides synthesis and minimization based on rules for cell mapping, timing, and area constraints specified by the engineer. Synopsys also recently announced Test Compiler, which automatically removes redundant logic from a design, inserts scan elements, connects scan chains, optimizes the design for speed and area and then generates and compacts (by up to 40 percent) test vectors for up to 100 percent of the single stuck-at faults in a circuit.

Another product gaining headway is the Test Design Expert (TDX) from ExperTest (Mountain View, CA). TDX automatically generates test vectors from the same highlevel descriptive language used to



The Test Compiler from Synopsys automatically removes redundant logic from a design, inserts scan elements, connects scan chains, optimizes the design for speed and area and then generates and compacts (by up to 40 percent) test vectors for up to 100 percent of the single stuck-at faults in a circuit.

synthesize the logic. "By incorporating a concurrent fault simulator, TDX gains an advantage in speed over fault simulators, which test one fault at a time," says Ghulam Nurie, director of product marketing. "TDX also speeds up the task by using a proprietary heuristic algorithm linked to a knowledge base of test

"We guarantee a 99.5 percent minimum fault coverage, and our ATPGs handle the testability task transparently."

—Stephen McMinn, Integrated CMOS Systems

information." Valid Logic Systems (San Jose, CA), ViewLogic Systems (Marlboro, MA) and Test System Strategies Inc (Beaverton, OR) have announced support for ExperTest.

There is, however, some resistance to design synthesis from hard-core hardware designers who don't want to become programmers. An HDL or high-level language is just that, a language, and the task of hardware design is transformed into a programmer's task. Furthermore, although known states can be described, random or glitched conditions from power-up can create unknown states in sequencers, which can cause a locked condition in an indeterminate state. Designers must therefore design what they don't want as well as what they do.

Nevertheless, HDLs are quickly becoming commonplace. Most CAE vendors already have in place some form of VHDL support and are moving toward tying design synthesis, simulation and testability into one easy-to-digest pill.

Architectural enhancements

While steps are being taken to make testability easier to deal with on the design front, another approach being considered is the integration of testability into the basic fiber of the device before it becomes personalized by metal interconnect.

An approach for architectural modification that solves the designfor-testability issue comes from Oki Semiconductor (Sunnyvale, CA),

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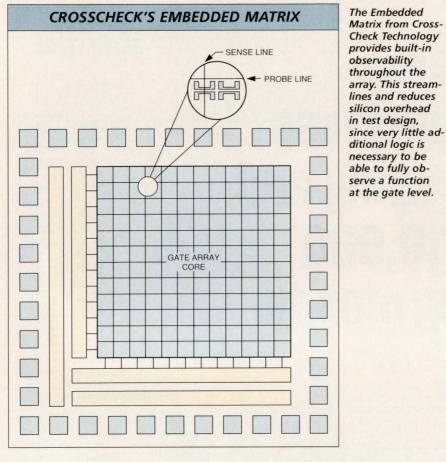
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which has implemented a built-in test structure that results in zero degradation in performance, according to the company.

Oki's MSM10T0000 family of seaof-gates arrays features dedicated locations of hand-crafted sequential blocks used solely for the implementation of scan-test flip-flops. This provides test resources that designers and tools can take advantage of without the silicon overhead associated with dedicated logic for scan implementation.

Oki claims that implementing the same amount of logic discretely would add 77 percent overhead to the size of the chip. What's more, since the test structure is architected directly into the silicon, test pattern generators can generate 95 percent coverage in a matter of hours as opposed to days or more. Designers must still make sure that all devices with internal feedback are patched into the scan logic. They must also make sure that no race conditions exist, and they must add external signal lines for the scan clocks if internally generated clocks are used.

Another solution, from Cross-

Check Technology (San Jose, CA), includes two elements: a patented on-chip test structure, and software tools that let designers take advantage of this unique architecture. "The patented structure includes a grid matrix embedded within the array, which transparently provides a large number of observable points," says Michael Carroll, vicepresident of marketing at Cross-Check. "Typically, this structure adds roughly 10 percent silicon area overhead to the actual die, but allows the designer to observe gatelevel behavior of actual devices for verification and debug." Since the test structure is part of the uncommitted array, it's necessary to fab these uncommitted arrays with the embedded test structure so that the test grid becomes a standard feature of the ASIC vendor's product.

Designers use the same conventional design approach and CAE tools as before, including libraries and simulation models. Timing is unaffected since the embedded test structure provides observability without degradation of signal. Once they're satisfied with the functionality and timing of a design, designers can then run the CrossCheck tools, which automatically generate test patterns with exceptionally high fault coverage as much as 50 times faster than conventional test pattern generators can.

So far, LSI Logic (Milpitas, CA) and Fujitsu Microelectronics (Santa Clara, CA) have licensed Cross-Check's technology and provide this approach to ASIC customers. Harris Semiconductor (Melbourne, FL) and the Advanced Device Center of Raytheon (Mountain View, CA) have also licensed this technology and are supporting it as part of their own design systems.

Simulation vectors

Designers of standard-cell and silicon-compiler ASICs have some special concerns when testability is an issue. Since a designer is designing at a larger functional-block level, the actual gate-level representations of these macro functions won't be available. It therefore becomes imperative that the silicon vendor provide designers with simulation vectors and a patch capability to a scan path or other test structure within the device. Since these macrocells are already characterized, simulation and timing models should exist for each standard cell and should be generated by each silicon-compiler module.

One approach for designers who need to design ultra-reliable devices is to add reconfigurable redundancies. Although this will drastically add to the silicon overhead associated with a specific design, this approach isn't that far-fetched for tactical and survivable designs.

One recent example of such an undertaking came from Motorola (Austin, TX) and TRW Electronics Component Group (La Jolla, CA), which jointly developed the first multimillion-device chip. Although not yet available to the general public, the groundwork has proved successful for future fabrication of highly dense ICs. The 0.5-µm CPUAX SuperChip has successfully been fabricated and tested for military applications.

Containing 4 million discrete devices, the SuperChip is touted as being the fastest floating-point processor yet, capable of performing two hundred 32-bit MFlops.

The most interesting feature of the CPUAX is its ability to repair itself, even during operations. Internal functional macrocells are redun-

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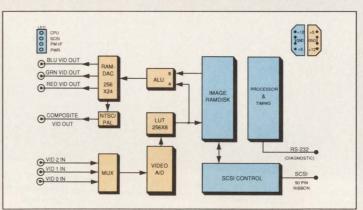
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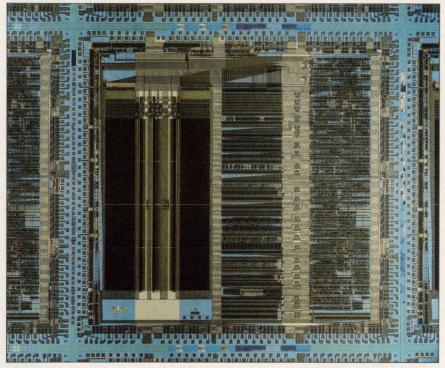
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DESIGN-FOR-TEST



As applications push the limits of the technology, test strategy becomes more important. This 80-MHz B5110 Sparc floating-point controller from Bipolar Integrated Technology would be infeasible to produce without a comprehensive test strategy.

dant internally and are capable of being switched in and out if an internal fault is detected. A powerful housekeeping system separates working from nonworking macrocells and disconnects the nonworking ones. The spares are then automatically patched in, even while the device is in the middle of an operation.

Of the 142 macrocells in the CPUAX, only 61 must be functional for complete operation. In device terms, of the 4 million devices on the chip, 1.7 million must function. Commercial successors to the SuperChip could find use in a wide variety of applications where the high speed, relatively low power, and reliability are necessary, such as advanced CAD/CAE, medical diagnosis, critical plant controls and ultracomplex imaging.

Although quite an accomplishment on its own, this Phase 2 VHSIC success is only the start. The design team plans to eventually build chips 150 times more dense.

Board testability

While ASIC testability continues to make inroads, life for design engineers gets real tricky at the board and system level. Printed circuit boards are shrinking in size, increasing in functional density and using more and more surface-mount components. Although the components may not be pushing limits of technology, the reduced spacings may mean that test points and access points to important signals and buses is getting harder and harder to do.

Take, for example, a typical microcontroller application where a 40-pin DIP lives with a 28- or 32-pin DIP RAM and ROM, a 20- or 24-pin DIP PAL, and other assorted DIP components. The 100-mil lead spacing leaves room for test probes, jumper clips, test headers (for buses and groups of signals) and so on.

When that same design is implemented using surface-mount components, the 25- and 50-mil spacings don't easily allow test clips and probes to effectively look at one signal. What's more, accidentally shorting two signals together while probing is easier to do on a surfacemount board, and if that happens to blow a chip, it becomes increasingly more difficult to perform rework when surface mount is utilized. Another concern is that tight and dense boards often require more than two layers. Blind and buried vias leave no access to signals.

Given these concerns, yet another responsibility is cast toward the design engineer to assure that adequate test points are left on the

printed circuit board that will permit full-function and diagnostic capabilities for debug, production troubleshooting and repair operations. This concern becomes increasingly more important with smaller circuit boards, but also will be of prime concern when the industry starts moving toward multichip modules (MCMs), which will isolate the inner workings of a design even more from the engineer's probing touch. In addition, bed-of-nails test approaches will be increasingly infeasible for verifying board or substrate continuity.

Fortunately, the boundary-scan test strategy works around this. As mentioned, boundary scan lets a compact (usually four-pin) bus serve as the master to a device's I/O lines. As such, boundary-scan devices can be used on a printed circuit board, or MCM for that matter, which will allow engineers to test for continuity between signal points. By driving one set of outputs and verifying that the driven signal is present on all the associated inputs, continuity as well as a device's inner workings can be verified.

This approach does have a few drawbacks, however. A board or MCM must be populated with devices to be able to perform this active test. And power must be applied to the circuit since each boundary-scan element must be alive. This means that some shorts could possibly damage components or crash the test bus.

Nevertheless, scan-compatible standard components are emerging to provide engineers with this option. For example, Bipolar Integrated Technology (Beaverton, OR) has incorporated a scan bus into its 64-bit B3130 floating-point processor, which has more than 55,000 ECL logic gates. The scan bus permits a test sequence to drive I/O and test internal functions. Packaged in a 395-pin pin grid array, the B3130 dissipates 24 W of power and features synchronous and asynchronous output enables for output ports and status flags.

The test manufacturer's view

Tester manufacturers are obviously part of the driving force for test standards and implementation techniques. "If all board networks are accessible to traditional fixturing, a full bed-of-nails in-circuit approach may be used, which provides certain advantages," says Peter

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DESIGN-FOR-TEST

Hansen, applications manager at Teradyne (Boston, MA). "All shorts testing can be done with no power applied to the board, thus saving some components that may be damaged if powered up with a fault. Further, test patterns with 100 percent fault coverage can be easily generated using this approach since all connections are compatible with the netlist."

But Teradyne is also supporting scan continuity testing. The test stimulus applied by automatic test equipment is captured by scaninput cells while the stimulus shifted into boundary-scan output cells is monitored by automatic test equipment. By avoiding the core logic of devices under test, vectors are simplified and continuity can be verified quickly.

For applications where some elements are scannable and some are not, a mixed approach may be the answer. Here, scannable elements are tested exclusively through scan techniques, and fixturing for the test fixture is aimed at verifying the nonscannable elements. While this still requires some nails for a fixture, the nail count is significantly reduced.

Another technique is to cluster the physical implementation of a function so that it's testable as an entire function. A bit of forethought is required here, since some discretely implemented scan logic often must be designed into a function to guarantee controllability and observability of some key verifying signals. But this technique does let even simpler testers perform detailed testing, since larger blocks are being verified with fewer vectors.

The technique that requires the most up-front engineering effort is to use scan exclusively to test the entire functionality of a board or system. Unless partial or full scan is employed, this can be more timeconsuming than just using boundary-scan techniques. What's more, many devices won't incorporate the scan logic on-chip, meaning that discrete scan elements must be added to the circuit.

This does offer some advantages, though. Since scan test requires only a few signal lines to verify a device, testers can get smaller, even though the number of vectors applied is usually deeper. Furthermore, the entire tester operation is, for the most part, synchronous to the scan clock. This, coupled with the fact that the testers can be smaller and less sophisticated, means that simultaneous gang testing is possible since the entire tester will be synchronously transmitting, receiving and comparing.

Teradyne isn't alone in pursuing these new test techniques. Makers of high-end testers such as GenRad (Concord, MA) and LTX (San Jose,

"By eliminating parametric test features and going with 'at-speed' testing using BIST, up to 800-MHz parametrics can be performed."

—David Karpenske, Schlumberger

...

CA), as well as makers of mid-level ASIC verifiers and testers such as Integrated Measurement Systems (Beaverton, OR), Hilevel Technology (Irvine, CA), ASIX Systems (Fremont, CA) and Tektronix (Beaverton, OR) are moving toward more up-front engineered strategic test philosophies.

One example is the collaboration between Motorola and Schlum-

berger Technologies ATE Division (San Jose, CA), which together created the Typhoon architecture.

The Typhoon supports scan-data rates up to 40 MHz and internal built-in self-test (BIST) rates to 800 MHz. Up to 4 Gbytes of local memory can feed its 64 high-speed and 1,024 broadside scan channels of this tester for CMOS, BiCMOS and bipolar devices. "The philosophy behind Typhoon is that only 10 percent of the time available from a tester is needed to do ac parametric testing, and the cost premium for a tester with the ac parametric capabilities was 70 percent," says David Karpenske, vice-president of strategic products at Schlumberger. "By eliminating parametric test features from the tester and going with 'at-speed' testing using BIST, up to 800-MHz parametrics can be performed by the devices." This approach provides accurate testers at a lower cost (\$1,500 per ATE pin, compared to the current \$8,000 to \$10,000 per ATE pin).

Typhoon supports boundary-scan techniques such as JTAG, as well as multiple scan paths with full or partial scan. What's more, Typhoon maintains an 850-ps accuracy on its high-speed scan channels. Each pin still provides the ability to perform dc parametrics, but is much simpler to implement than an ac and dc parametric extraction unit.

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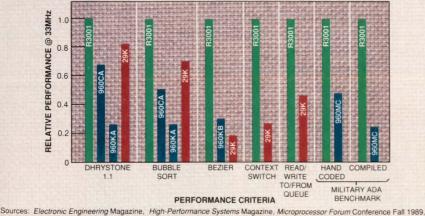
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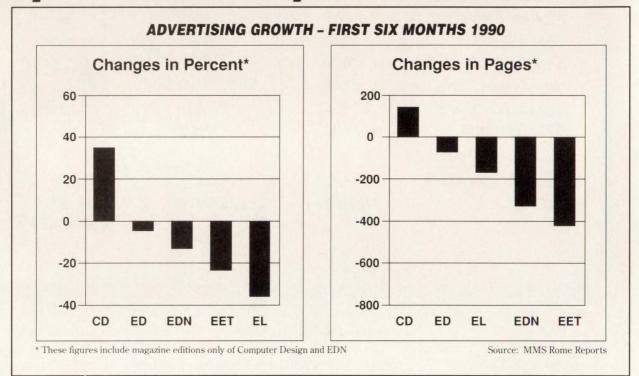


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Standards breathe new life into 2,400-bit/s modem ICs

Jeffrey Child, Associate Editor



Exar's XR-2900 chip set integrates a 2,400bit/s V.22bis data modem with 9,600-bit/s Group 3 send/receive fax capabilities. With analog and DSP circuitry partitioned into a two-chip set, OEMs can combine the XR-2900 with an external controller and memory to form a complete data/fax modem.

The 2,400-bit/s modem is entrenched as the standard in data communications. And though users have long recognized that higher-speed modems reduce time and communication charges, it's widely agreed that the 2,400-bit/s modem won't become outdated as quickly as the slower devices that came before it. When the 1,200-bit/s modem came along, for instance, it quickly replaced its 300-bit/s predecessor. Similarly, the advent of the 2,400-bit/s modem swiftly pushed the 1,200-bit/s modem aside.

But now, in the day of 2,400-bit/s modems, performance enhancement standards have emerged that are giving the 2,400-bit/s modem ICs a new lease on life. Among those standards gaining wide acceptance are Microcom Networking Protocol (MNP) Class 4 and V.42 for error correction and MNP Class 5 and V.42bis for data compression.

Because these standards let modems exchange data at greater throughput rates, they're satisfying users' demands for speed without the need to create a whole new hardware platform. Support for error correction and data compression can be provided right in the firmware. Manufacturers of 2,400-bit/s modem chip sets are integrating these features into their latest designs.

This feature-driven trend has altered the modem IC market. "By offering features like MNP 5, board designers are able to provide a broader product line. They can offer both a low end and a high end by incorporating different combinations of features," says Shyam Dujari, senior marketing manager of Exar (San Jose, CA). This flexibility has inspired modem IC manufacturers to add more and more features to their products. Some have even gone beyond traditional data modem functions and added fax capabilities.

Although modem chip set manufacturers are integrating more new features into their designs, they're still preserving ties to earlier standards, including the venerable Bell 103 standard for 300-bit/s transmission. By having 300-bit/s support, a modem can be configured to shift down to a lower speed if it encounters a bad phone line. Besides, it seems almost no one in the modem industry wants to be the first not to offer Bell 103 compatibility.

Blending modems and fax

The most recent trend among modem IC manufacturers is to combine data modem and fax functions in the same chip set. Sierra Semiconductor (San Jose, CA) makes Sendfax, a line of modem solutions that adds sendonly fax capabilities. Sierra's SC11046 single-chip device adds 4,800-bit/s Group 3 fax capability to a full-duplex, Hayes-compatible, V.22bis, 2,400-bit/s modem. An external controller performs all the handshaking functions, including fax-call setup conforming to the CCITT T.30 standard.

Sierra has found a range of situa-

tions in which a send-only fax capability is sufficient. It allows laptop users in the field, for instance, to use any local fax machine as a printer. In the corporate environment, sendonly fax capability lets PC users transmit faxes without having to first print out a document and then wait to gain access to a fax machine. Sendfax implementation is simple, so it isn't much added cost. It involves only a modification to the analog front end and to the code. For all its added market value, it's a relatively inexpensive feature to add, according to Sierra.

Exar has taken the next step in the integration of fax and data modem functions with its combined fax/data modem in the form of a twochip set. The XR-2900 serves as a modem data pump for both 9,600bit/s V.29 fax and 2,400-bit/s V.22bis data communications requirements. The XR-2900 also supports two other fax and three other data modem standards. This wide range makes the device compatible with MNP options and the proposed V.42/V.42bis compression/correction standard.

The 2900 is made up of a mainly analog front end and a digital back end. In the analog chip, Exar has packed the analog line filtration and amplifiers required for fax use, a 10-bit receive analog-to-digital converter, a 9-bit transmit digital-to-analog converter, a clock phased-locked loop and some interface circuitry. The digital chip includes the signal processing and transform circuitry

Model	Bell compatibility	CCITT compatibility	UART on-chip	AT command set	Interfaces	Power consump- tion (mW)	Packaging	Price/Quantity	Comments
Dallas Sem	iconducto	r 4350 S Beltwo	od P	kwy, [Dallas,	, TX 75	244 (214) 450-04	00	Circle 30:
DS2244T	212A, 103	V.22bis	N	Y	S	200	SIMM 3.5×0.85×0.375 in.	\$78/1,000	Full-function μ C with modem, capable of embedded control and data storage
0S2245	212A, 103	V.22bis	Y	Y	Р	250	SIMM 3.5×0.85×0.375 in.	\$78/1,000	FCC part 68 reg. when used with DS2249 DAA
DS2246	212A, 103	V.22bis	Y	Y	Ρ	250	SIMM	\$78/1,000	MNP5, error correction
Exar 2222	2 Qume Dr	, PO Box 49007,	San .	Jose,	CA 95	161-90	007 (408) 434-640	00	Circle 30
2900	212A, 103	V.21 channel 2, V.22, V.22bis, V.27ter, V.29, V.42, V.42bis	N	Y	S, P	500	DIP, PLCC, QFP	\$27.33/10,000	MNP2-5, AT command set, TR29, T.30 provided
2400	212A, 103	V.22, V.22bis, V.42, V.42bis	N	Y	S, P	400	DIP, PLCC, QFP	\$18.51/10,000	MNP2-5, Exar AT command set provided, V.21/V.23 also supported
ntel 1900) Prairie Ci	ty Rd, FM2-18, Fc	olsom	n, CA	95630) (916)	351-5133		Circle 30
9C024XE	212A, 103	V.21, V.22A/B, V.22bis	N	Y	S	385	28-pin PDIP, 28-pin, 68-pin PLCC	\$26/10,000	2 chips, CHMOS, MNP software available
9C024LT	212A, 103	V.21, V.22A/B, V.22bis	N	Y	S	400	28-pin PDIP, 28-pin, 68-pin PLCC	\$26/10,000	CHMOS, 2 chips in 3 in. ² , sleep and re- sume modes
9024	212A, 103	V.21, V.22A/B, V.22bis,	N	Y	S	1.5 W	28-pin PDIP, 28 pin, 68-pin PLCC	\$16/10,000	2-chip solution
NEC Electr	onics 40	1 Ellis St, Mounta	in Vi	ew, C	A 940	43 (41	5) 960-6000		Circle 30
ιPD77810		V.21, V.22bis	Y	_	S, P	_	68-pin PLCC	-	flexible, user programmable, use any front end
1PDTT811	-	V.21, V.22bis	N	-	S	-	44-pin PLCC	-	gain variable amp, guard-tone generator, 8-bit A-D, D-A converters
uPD77812	-	V.21, V.22bis	Y	-	S	Τ	68-pin PLCC, 74-pin QFP	-	used w/77811, does modulation and tone generation/detection
Oki Semico	onductor	785 N Mary Ave,	Sunn	nyvale	, CA 9	4086-2	2909 (408) 720-19	900	Circle 30
MSM6994-01FE	P 212, 202, 103	V.21, V.22, V.22bis, V.23, V.27, V.29, V.32	N	N	S	150	64-pin mini-DIP, 64-pin FP, 68-pin PLCC	\$20/50,000	meant for use with DSP chip, band limit fi tering, carrier detection, AGC, call progres
Rockwell (comm Syst	tems, Digital Con	nm D	iv 43	311 Ja	mbore	e Rd, Newport Bea	ch, CA 9265	58 (714) 833-6849 Circle 30
RC224AT	212A, 103	V.22, V.22bis	Y	Y	S, P	300	68-pin PLCC	\$24/10,000	single complete modern
RC2324AC	212A, 103	V.21, V.22, V.22bis, V.23, V.42, V.42bis	Y	Y	S, P	650	68-pin PLCC	\$35/10,000	2-chip integrated quad modem with MNP2-
RC2324DP/1	212A, 103	V.21, V.22, V.22bis, V.23	-	-	S, P	500	68-pin PLCC	\$26.50/10,000	single-device quad modem data pump, HDLC framing
RC9624AT	212A, 103	V.21 channel 2, V.22, V.22bis, V.27ter, V.29	Y	Y	S, P	300	68-pin PLCC	-	2-chip set; 9,600-bit/s send/receive G3 fax
SGS-Thoms	son 1000	E Bell, Phoenix,	AZ 85	5022	(602)	867-6:	100		Circle 30
rs75C25	212, 103	V.21, V.22, V.22bis, V.23	N	N	Р	700	1×48 DIP, 1×40 DIP, 1×52 PLCC, 1×44 PLCC	\$18/10,000	2 chips, CMOS
		AND DE COMPANY OF MANY AND DE COMPANY							
Sharp Digit	tal Informa	ation Products 1	6841	1 Arm	strong	Ave, Ir	vine, CA 92714 (7	14) 261-62	24 Circle 30

Model	Bell compatibility	CCITT compatibility	UART on-chip	AT command set	Interfaces	Power consump- tion (mW)	Packaging	Price/Quantity	Comments
Sierra Semio	onductor	2075 N Capito	I Ave,	San	Jose,	CA 951	L32 (408) 263-	9300	Circle 309
SK0611	212A, 103	V.21, V.22, V.22bis	Y	Y	S, P	330	DIP, PLCC	\$18/10,000	basic modem
SK2423	212A, 103	V.21, V.22, V.22bis	Y	Y	Р	260	DIP, PLCC	\$21/10,000	5-V supply, power down, laptop modem
SK2491	212A, 103	V.21, V.22, V.22bis, V.42bis	Y	Y	S, P	270	DIP, PLCC	\$25/10,000	5-V supply, power down, MNP5/V
SK2691	212A, 103	V.21, V.22, V.22bis, V.23, V.42bis	Y	Y	S, P	310	DIP, PLCC	\$26/10,000	MNP5
SK4611	212A, 103	V.21, V.22, V.22bis, V.27ter	Y	Y	S, P	280	DIP, PLCC	\$20/10,000	basic Sendfax 48 modem
SK5421	212A, 103	V.21, V.22, V.22bis, V.27ter, V.29	Y	Y	S, P	280	DIP, PLCC	\$31/10,000	5-V supply, laptop Sendfax
SK5474	212A, 103	V.21, V.22, V.22bis, V.27ter, V.29	Y	Y	S	260	DIP, PLCC	\$32/10,000	5-V supply, power down, smallest foot- print, low parts count, pocket Sendfax
SK5475	212A, 103	V.21, V.22, V.22bis, V.27ter, V.29	Y	Y	Ρ	260	DIP, PLCC	\$34/10,000	5-V supply, power down, smallest footprint low parts count, laptop Sendfax, 2 chips
SK5491	212A, 103	V.21, V.22, V.22bis, V.27ter, V.29, V.42, V.42bis	Y	Y	S, P	270	DIP, PLCC	\$34/10,000	5-V supply, power down, low parts count, Sendfax 96/MNP5
SQ2496	212A, 103	V.21, V.22, V.22bis, V.27, V.27ter, V.29	Y	Y	S, P	720	DIP, PLCC	\$33/10,000	power down; 2,400-bit/s data modem w/ send/receive fax modem
SQ4296	212A, 103	V.21, V.22, V.22bis, V.27, V.27ter, V.29, V.42, V.42bis	Y	Y	S, P	750	DIP, PLCC	\$40/10,000	power down, MNP5/V.42bis data modem w/ send/receive fax modem
SSI 73D2240	212A, 103	V.21, V.22, V.22bis	N N	Y	S, P	125	DIP	\$30/10,000	2 chips, turnkey, high-performance, low- power
SSI 73D2420/21	212A, 103	V.42, V.42bis	N	Y	S, P	-	-	\$40-\$50/10,000	3 chips, MNP2-5
SSI 73D2407	212A, 103	V.22, MNP2-5	N	Y	S, P	600	28, 40-pin DIP	\$35/10,000	4 chips, upgrade to error control, data
SSI 73D2417	212A, 103	V.21, V.22, V.22bis	N	Y	S, P	-	DIP and surface mount	\$25/10,000	compression, pass-thru licensing MNP5 MNP2-5, fax transmit
SSI 73D2291/92	212A, 103	V.21Chr2, V.24ter, V.29	N	Y	S, P	-	PLCC or surface mount	\$35/1,000	2291 fax only, 2292 fax/data, EIA 578- compatible, AT command interpreter
United Micr	oelectron	ics 3350 Scott	Blvd,	Bldg	48 &	49, Sa	nta Clara, CA 9	5054 (408) 72	7-9589 Circle 31:
UM92240/241	212A, 103	V.21, V.22, V.22bis	N	Y	Ρ	300	28-pin DIP	\$12/5,000	2 chips
Xecom 374	1 Turquois	se St, Milpitas, C	A 950	35 (4	408) 9	945-664	40		Circle 31:
XE2400	212A, 103	V.21, V.22, V.22bis, V.54	Y	Y	S	1,000	hybrid module	\$175/25	sync/async, FCC part 68 reg., DTMF/pulse dialing, call progress
XE2400A	212A, 103	V.21, V.22, V.22bis, V.54	Y	Y	S	1,000	hybrid module	\$175/25	async, FCC part 68 reg., DTMF/pulse dialing, call progress
XE2400MNP	212A, 103	V.21, V.22, V.22bis, V.54	Y	Y	S	575	hybrid module	\$250/25	sync/async, MNP1-5, FCC part 68 reg., DTMF/pulse dialing, call progress
XE9624FDB	212A, 103	V.21, V.22, V.22bis, V.27ter, V.29	Y	Y	S	650	hybrid module	\$459/25	sync/async, MNP1-5, FCC part 68 reg., G3 fax, DTMF/pulse dialing, call progress
XE2400A-E	212A, 103	V.21, V.22, V.22bis, V.54	Y	Y	S	880	hybrid module	\$143/25	async, DTMF/pulse dialing, call progress
			V	Y	S	455	hybrid module	\$010/0E	ourselogues MND1 5 DTME/pulse dialing
XE2400MNP-E	212A, 103	V.21, V.22, V.22bis, V.54	Y	1	0	400	nyonu mouule	\$218/25	sync/async, MNP1-5, DTMF/pulse dialing, call progress

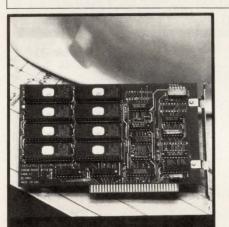
INTEGRATED CIRCUITS

necessary to go between the converter inputs or outputs and a microcontroller interface.

Separating modem functions

Modem IC manufacturers are also differentiating their products by the way they partition modem functions. While some manufacturers combine a data pump and a controller in a set, others use an analog front end and a digital signal processor.

Typical of the latter partitioning style is the T75C25, a V.22bis modem chip set from SGS-Thompson (Phoenix, AZ), consisting of a preprogrammed CMOS DSP plus an analog front end. Together these devices form a modem that can operate at up to 2,400 bit/s, full duplex. The DSP implements the signal processing necessary to send and receive data, plus utilities such as call-progress tone detection and tone generation. The analog front end incorporates the circuits required for programmable gain control, clock generation



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and signal filtering. Because the TS75C25 uses a preprogrammed DSP, it can be customized simply by modifying software.

Separating modem duties into a data pump and controller, the

Although 2,400-bit/s modems won't be outdated overnight, the next jump in speed for modem designs will come—probably at 9,600 baud.

...

RC2324AC from Rockwell International (Newport Beach, CA) integrates the V.42bis data compression algorithm into its chip set. Modems using V.42bis can achieve up to 9,600 bit/s of data throughput. In addition to V.42bis, the RC2324AC has MNP 4 and V.42 error correction and MNP 5 data compression built into its firmware. This CMOS chip set offers adaptive equalization, which lets the modem automatically compensate for telephone line distortions.

The digital domain

Although 2,400-bit/s modem won't be outdated overnight, the next jump in speed for modem designs will come eventually—probably at 9,600 baud. In fact, there are products today that support V.32, the protocol for 9,600-bit/s operation. But to achieve this next jump in speed requires a technology significantly different from traditional analog approaches.

Using this new technology is the MSM6994, the latest offering from Oki Semiconductor (Sunnyvale, CA). It's unique among modem devices in that it operates in the digital domain rather than the analog. The MSM6994 supports up to eight standards including V.32 and fax standards. It's a front-end processor chip designed to operate with a generalpurpose DSP. Separate transmit and receive functions are integrated in this device. At the heart of the MSM6994 is a 5-Mips DSP core providing band-limiting filtering, carrier-detecting and automatic gain control with call-progress tone detection. The chip also contains A-D and D-A converters that replace the switch-capacitor filter usually used in modem front ends.

"When you're doing 9,600 baud, you can't use switch-capacitor filtering," says Jerry Gora, technical marketing engineer at Oki. Switch-capacitor filtering has a lot of phase delay problems. To build a device equivalent to the MSM6994 in the analog domain, says Gora, would require four stages of op-amps and many discrete components. Since the MSM6994 does its processing in the digital domain, it can maintain phase-coherency on all the filters.

Targeting laptops

The laptop arena also demands special features from 2,400-bit/s modem ICs. Whether designed into the motherboard or into an external socket, the total modem circuit in a laptop must be as small as possible while drawing low power. Laptop modems also should support the power-down capability popular in laptops.

With these requirements in mind, Intel (Santa Clara, CA) has created the 89C024LT. Specifically targeted for laptop designs, the 2,400-bit/s 89C024LT consumes 400 mW in normal operation and 5 mW in standby mode. The chip set conforms to MNP classes 1 through 5 while supporting the sleep and resume modes found in most laptops. Controlled by the 89C026LT microcontroller through a high-speed serial data link, the 89027 analog front end handles the complex filtering functions required by the modem. The 68-pin 89C026LT also performs DSP, call monitoring, and Hayes-compatible command-set and user-interface functions.

Another modem solution for laptop configurations is the 73D2240 chip set from Silicon Systems (Tustin, CA). The set includes the main 73K224L modem chip and the 73D600 microcontroller. Combined, these chips offer an AT command interpreter compatible with the Hayes 2400 Smartmodem command set. The modem operates from a single 5-V supply and requires only 125 mW of power, 30 mW in sleep mode. The chip set also offers dual-tone multifrequency dialing, automatic speed detect and terminal autobaud.

120 SEPTEMBER 1, 1990 COMPUTER DESIGN

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NEW PRODUCT HIGHLIGHTS

COMPUTERS AND SUBSYSTEMS

VMEbus accelerator board offers 1.3M fuzzy-rule evaluations/s

Designed for either Unix-based fuzzy-processing applications or stand-alone applications, the FCA-10VME is a four-processor parallel fuzzy-processing VME board from Togai InfraLogic. The board provides four of Togai's custom FC110 digital fuzzy processors (DFPs) arranged to run in flexible combinations, allowing up to 1.3 million fuzzy-rule evaluations/s. Up to 64 boards may be used in the same computer system for a total of 256 fuzzy processors operating in parallel.

The message-passing facilities integral to the FC110 DFP allow each processor independent communication to the host computer system. By using these message-passing features and coupling the processors at the software level, users can create many different architectures for parallel-processing systems without changing the hardware. This lets researchers experiment with disjoint, systolic, mesh, hypercube and hypertorus architectures all in the same development platform.

The vital organs of the board are the four DFPs, each operating at 20 MHz. At this speed, each DFP performs as a 10-Mips fuzzy-computing node. With 128 kbytes of knowledgebased memory exclusive to each node, each processor has uninhibited access to its own knowledge base. In addition, there are 256 bytes of shared variable space between each FC110 and the host computer. This memory is used for passing messages, commands and data between the node and the host computer. With all four processors active, the FCA10VME board provides up to 40 Mips of fuzzy-computing power.

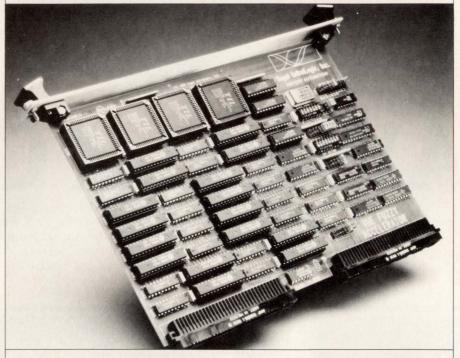
Making optimum use of available memory, the logical addressing on the card is configured to minimize the physical address space. Requiring only 256 kbytes of physical address space in a VME system, the 512 kbytes of knowledge-based memory is switched into physical memory 128 kbytes at a time. This lets the host switch the knowledgebased memory of a node into the physical address space of the system, download the knowledge base, and then switch to the next node. The availability of each node is key to the board's performance, letting the DFPs be used in flexible combinations. Because of this, they aren't switched like the knowledgebased memory; they're mapped into physical memory so there's no unnecessary overhead when accessing them. The control and status registers are also permanently mapped into the physical memory.

The FCA10VME is supported by

system used. The interface depends on whether a "protected" operating system such as Unix is used. A protected operating system is one which blocks an application process from accessing arbitrary memory locations.

When operating in a protected operating system, an application program wishing to access the FCA10VME board must do so via a device driver. For use under Sun O/S Version 4.0.1, the board is supplied with C source code for a simple Unix device driver.

In a stand-alone application a program can access the FCA10VME's fuzzy processors in a more direct man-



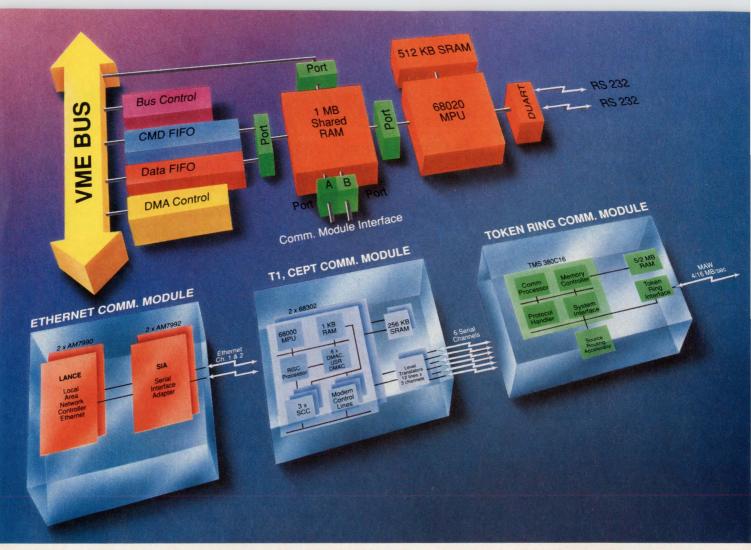
two major software development tools. The TILShell is a graphical tool for creating and modifying expert systems, including ones that will run on the FCA10VME. The FC110 Development System includes a compiler, an assembler and a linker. The complier and assembler produce relocatable object modules. These modules are combined by the linker to produce load images for the FC110 processors and to create C interface code for the expert system.

Unix-based or stand-alone uses

Built to be easily integrated into existing VME systems, the FCA10VME requires different interface methods depending on the type of operating ner: by just reading and writing to locations in the VME address space.

The FCA10VME fits in a single 6U form factor. Hardware jumpers are provided to allow both nonprivileged and supervisor access, letting the FCA10VME function as a generally available embedded peripheral or a system-regulated resource. Available now, the board is priced at \$4,500. -Jeff Child

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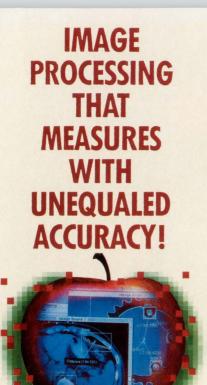
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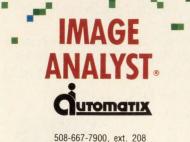
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NEW PRODUCT HIGHLIGHTS

COMPUTERS AND SUBSYSTEMS

68040-based VMEbus board features intelligent I/O subsystem

The 68-41, the latest 68040-based VMEbus single-board computer (SBC) from Radstone Technology, provides multiple microprocessors and dual-ported memories for highperformance real-time applications. A key factor to the 68-41's performance is its on-board intelligent I/O subsystem, responsible for avoiding I/O bottlenecks. Such bottlenecks can seriously hinder the processing strength of multifeatured VME SBCs such as the 68-41, with its multiple local and external buses and various I/O interfaces. To ensure optimum processing power and the free flow of data, the I/O subsystem lets the board operate at full performance even when all its local and external interfaces are in use.

At the heart of the board is the 68040 microprocessor, with up to 16 Mbytes of multiport DRAM. Offering cache-burst-mode support, this DRAM is closely coupled with the 40-MHz 68040. The board's I/O subsystem handles data flow, letting the 68040 work without interruption.

A dedicated 68020 processor, combined with up to 4 Mbytes of I/O memory, forms the core of the 68-41's I/O subsystem. Working with the gateway controller and datapath ASICs, the 68020 initiates DMA-type movements that handle data flow between the 68040 and I/O areas. This eliminates I/O bottlenecks and allows maximum data throughput. An intelligent SCSI containing an internal SCSI processor, on-chip 32-byte FIFO, a built-in DMA controller and SCSI-2 capability is part of this subsystem.

COMPUTER DESIGN

Besides SCSI, the 68-41 also provides additional external interfaces to communicate with the outside world through both serial I/O and a highperformance Ethernet interface.

Serial I/O on the card moves through four RS-232C/442/485 serial ports. These may be configured for either synchronous or asynchronous operation. Additional I/O support is available through the board's 32-bit interface, letting users add standard or custom modules depending on their requirements.

The on-board Ethernet interface is built around an Advanced Micro Devices 79C900. It provides LAN support and includes an on-chip 48-byte FIFO and a 32-bit DMA controller. The interface also provides advanced buffer management and is compatible with both Ethernet 2.0 and IEEE-802.3 10Base5 specifications.

To allow maximum data throughput along user-selectable data paths, the board features two high-performance bus interfaces. First is a 32bit VMEbus, implemented by the VIC068 interface with the aid of a 40-Mbyte/s DMA controller. The other bus interface is the 32-bit VME subsystem bus (VSB), which offloads the data traffic from the main VMEbus. The VSB has a complete 32-bit multimaster interface plus its own DMA controller. The 68-41 is priced starting at \$6,995. — Jeff Child

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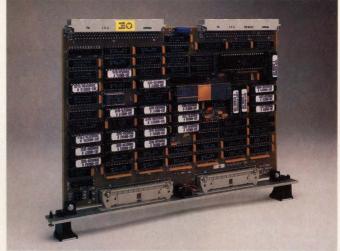
124 SEPTEMBER 1, 1990 COMPUTER DESIGN

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SOFTWARE

VxWorks sports rewritten kernel, enhanced comm and windows features

Wind River Systems has announced a greatly extended version of the VxWorks real-time development and run-time system. Offering a completely rewritten kernel, enhanced connectivity, debugging and X Window System support, VxWorks 5.0 supports the 680X0 family of processors, the Sparc architecture and the 80960, and runs on a wide variety of Unix and VMS host platforms.

The rewrite of the Wind River kernel has resulted in greatly reduced latency and context switch times, according to the company. The interrupt lock/unlock sequence, for instance, formerly 10 to 15 μ s, has been reduced to 2 to 3 μ s. In addition, context switching has been optimized for a constant time, regardless of the number of tasks.

Enhanced floating-point emulation has been added to the kernel. In addition to run-time libraries that support software emulation of floating-point operations in systems without math coprocessors, Vx-Works supports floating-point processor functions. Floating-point registers are saved as part of a task's context. This support is optional.

Enhanced communication

Intertask communication in the kernel has been enriched by adding two more types of semaphores: counting and priority-inheritance semaphores. Counting semaphores are like basic binary semaphores except that they keep track of how many times a semaphore is given. This makes them useful for guarding resources with multiple copies.

Priority-inheritance semaphores eliminate situations in which a highpriority task block is waiting for a semaphore held by a lower-priority task. The higher-priority task could wait an indeterminate amount of time while the lower-priority task is preempted by other tasks. Priority inheritance lets a task temporarily inherit the highest priority of tasks waiting for its semaphore.

VxWorks has traditionally included integrated networking. The new version includes the latest Tahoe release 4.0 of 4.3 BSD Unix Transmission Control Protocol/Internet Protocol for Ethernet. In addition, VxWorks 5.0 supports network connections between CPUs on a backplane and the serial line interface protocol.

In terms of higher-level communications protocols, VxWorks 5.0 has upgraded its remote procedure calls (RPC) to version 4.0. RPC allows Unix or VxWorks processes to invoke procedures executed on remote CPUs on the network. The addition of the ftp file protocol allows twoway access of VxWorks processes to Unix files, and remote Unix or VxWorks access to VxWorks files.

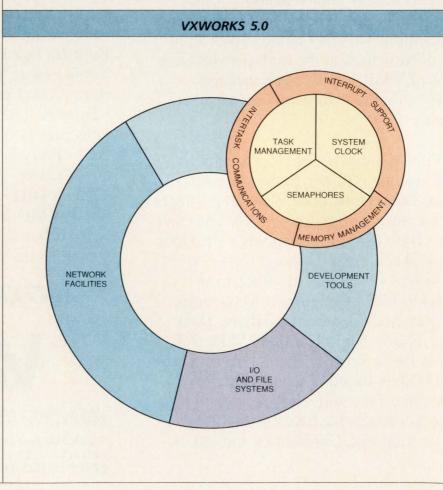
Various options available

New compiler and debugger options are also available. VxWorks 5.0 now supports the GNU C compiler, called gcc, distributed by the Free Software Foundation (Cambridge, MA). The code produced by the compiler is so compact that all VxWorks system source code (except for host executables) is compiled with gcc. The native compilers of host systems will still be supported. VxGDB, a new source-level debugger, is also offered.

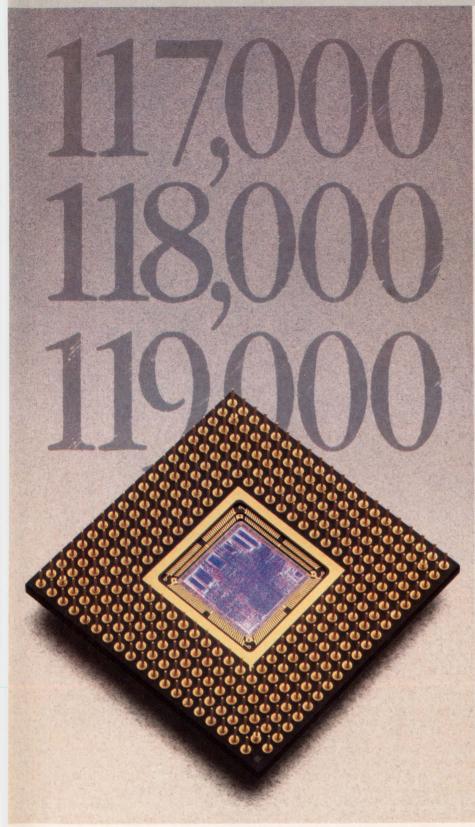
And finally, Wind River offers an optional support package for X Windows, version 11, called windX. WindX lets real-time processes open windows for input and output and display graphics that can be used to design graphical user interfaces for real-time systems.

The price for a single-user development license is \$19,000, which includes the VxGDB debugger. The windX X Window System client-side developer's kit option is priced at \$5,000. — Tom Williams

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NEW PRODUCT HIGHLIGHTS

New version of Abel tailored to device-independent, top-down design

Abel-4, the latest version of Data I/O's Abel Design Software, brings a host of features to designers of field-programmable gate arrays (FPGAs) and programmable logic devices (PLDs). The software is a major departure from previous versions because of the addition of Abel-HDL, a new hardware description language that lets designs be entered and verified with little or no concern for the target device architecture.

"We're answering the needs of the customer who wants the freedom to classes of programmable devices. Designers can, therefore, choose the detail level required for the application. Abel-HDL also supports a variety of behavioral input methods including high-level equations, state diagrams and truth tables.

The Abel-4 package contains an integrated design environment that features a windows-based interactive user interface, enhanced FPGA device support, intelligent device selection, and the first generic fitters for the recently announced Open-

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write a general description of a device and later move down toward specifics," says David Kohlmeir, division engineering manager of the design software business unit at Data I/O. "Abel-4 divides the design task into two parts—the first half allows the designer to work with Abel-HDL in a device-independent mode, while the second half refines the task down to device-specific choices."

Abel-HDL is optimized for, but not limited to, FPGA and PLD designs. The language also lets designers control various device parameters, such as buried flip-flops or configurable macrocells, found in specific Abel concept. Through the Open-Abel program, Data I/O is licensing semiconductor vendors to write specialized device algorithms to match the resources of their silicon to specific design needs. These algorithms, called fitters, will include additional syntax to describe new features, optimization algorithms and additional simulation capabilities, and will include any changes to the algorithm that generates the fusemap. New verification tools include both design- and device-level simulation and automatic logic optimization.

The enhanced user interface provides context-sensitive help wherever the cursor is placed (menu item, dialogue box or keyword), as well as an auto-update capability that tracks the design and processes only the necessary portions. All messages and error notifications are interactively reported, and all interface features can be accessed either through windows, or from the command line.

SmartPart, an intelligent deviceselection capability, automatically generates a list of candidate devices for every design (from a database containing over 6,000 parts) by comparing requirements with device resources. Without any changes, designs can then be tried in multiple device architectures to achieve full optimization. User-definable criteria include device technology, speed, manufacturer and price, all of which can be prioritized according to design requirements. Fields can therefore be set to determine companyspecific parameters such as "in stock" or "company qualified."

Simulation before selection

The tool can also perform designand device-level simulation before device selection—another departure from previous versions. The simulation provides multiple forms of feedback including tabular and waveform formats. Device-level simulation allows full verification before programming and verifies that the design properly fits into the targeted device. This includes full debugging of every fuse, node and pin.

Abel-4 contains four fitters: one for traditional programmable logic and field-programmable logic architectures (this supports 150 device architectures); one for the Altera EP1800; one for the Altera MAX 5032 and 5016; and one for the Cypress programmable sequencers 330, 331 and 332. Data I/O and device vendors will add more device fitters in the future.

Abel-4 is available now and is priced at \$1,995 for the MS-DOS version. The software is also available for Sun-3 and Sparcstation at \$2,695, and for VAX/VMS workstations at \$4,115. -Mike Donlin

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A division of Extrema Systems International Corporation CIRCLE NO. 71 "Innovative Voice Solutions" 10700 Parkridge Boulevard Reston, Virginia 22091 800-347-6007 NEW PRODUCT HIGHLIGHTS

DESIGN AND DEVELOPMENT TOOLS

Open simulation system eases design of mixed-signal ASICs and ICs

A new mixed-signal simulation system from the Analog Division of Cadence Design Systems, the Analog Artist, is tightly tied into a frontto-back-end toolset. Mixed-signal designers can access design-entry, simulation, physical-design and verification tools through the Analog Artist design system, which is integrated within the Cadence Design Framework architecture. Customers who prefer an alternate simulator can use an open simulation socket to integrate additional tools within the environment.

The new mixed-signal tool combines the simulation cores of Verilog-XL and Cadence-Spice. A schematic-entry system supports Verilog and Cadence-Spice primitives, as well as Verilog behavioral models. The system highlights analog and digital partitioning, with visual feedback on the schematic of actual simulation configuration. There are no constraints on mixing analog and digital blocks in a hierarchy. Users can switch the level of a block model for critical-path simulation. Netlists for Verilog and Cadence-Spice are automatically generated.

Design simplified

A mixed analog/digital display system lets users view analog and digital waveforms in the same window and displays them on the same horizontal strip plots. It also displays full transient, parametric and statistical analog waveforms.

To ease both top-down and bottom-up design, the multilevel mixedsignal simulator lets users model each section of the design at the optimum level of detail. Users can simulate logic designs from stochastic, architectural, gate, switch and RTL levels through Verilog-XL and circuits through Cadence-Spice for all combinations of mixed-signal designs and processes.

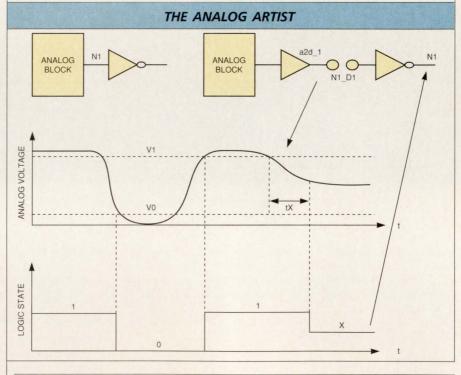
Cadence-Spice supports the use of high-level macromodels as well as transistor models. When systemslevel libraries become available, the Analog Artist Mixed-Signal Simulator will be able to do analog and digital systems design. Interactive simulation control lets mixed-signal designers stop, interactively probe a schematic and continue without needing restart the simulation. Simulation results can be back-annotated directly to the schematic. Users can manipulate simulation outputs to create new variables through a video keypad and a calculator.

Although the database of the Analog Artist Mixed-Signal Simulator can handle 1 million or more transistors, the present release of Cadence-Spice has a computational limit of about 2,500 devices. With circuits larger than that, designers will encounter excessive simulation run times, or may suffer convergence difficulties.

The Analog Artist Mixed-Signal Simulation Interface is priced at \$10,000 per license and requires the Analog Artist Design System (which includes Cadence-Spice), starting at \$30,000 per seat, and the Verilog simulator at \$25,000 per seat. The Analog Artist supports Sun, Apollo and DEC workstations.

-Barbara Tuck

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NEW PRODUCT HIGHLIGHTS

INTEGRATED CIRCUITS

C&T, Opti develop low-cost cache solutions for 386 chip sets

The expanding market demand in the PC arena is pulling cache technology not just onto PC motherboards, but into chip sets as well. For some time, Chips and Technologies has offered its high-end Peak chip set with a built-in two-way set-associative cache controller. But most cache solutions have depended on either proprietary controllers designed by the systems vendor or on separate controller ICs.

Now, in conjunction with its announcement of a 33-MHz version of the original Peak chip set, Chips has also unveiled a new version of the three-chip high-end product. The Peak/DM is essentially identical to the 33-MHz Peak set and includes all the usual modern chip set features: 128-Mbyte memory space, 4-Mbit DRAM support and so forth. But as the name suggests, the new set uses a direct-mapped, rather than a two-way set-associative, cache controller.

Chips is gearing its new chip set toward systems builders looking for less-expensive cache solutions ways to implement some kind of cache on a midrange product. "Until now, about 80 percent of 386 DX systems have been uncached," says Chips' vice-president and general manager Sikander Naqvi. "But that percentage will decline rapidly to almost nothing. We're seeing niches for both high-performance and lowcost cache solutions."

With falling SRAM prices, average cache size is going up, says Naqvi. And as the cache gets larger, the performance benefit of the more complex two-way organization diminishes. "At 64 kbytes, there's only about a 5 percent performance difference between two-way and directmapped caches," he says.

Chips is exploiting this fact to take a bit of the cost out of the chip set. The simpler circuitry of the DM permits the company to offer the set for \$153 (1,000s) for the 33-MHz parts, compared to \$189 (1,000s) for the full Peak set at the same speed. Production volumes for both sets are expected this month.

Expanding the market downward

Meanwhile, Opti, a young Chips spin-off, is aiming even lower with its latest product. Opti has gained some fame by selling single-chip AT bus 486 and 386 DX solutions with on-board cache control. Now the company is introducing the first single-chip 386 SX parts with integral cache control. "So far, vendors have just been gluing a 16-bit interface onto their existing page-interleave DX chip set and calling it an SX product," says Opti vice-president of marketing and sales Raj Jaswa. "We took it as a challenge to come up with a product specifically engineered for the SX and able to compete against both page-interleave and cache-based sets at a reasonable cost."

Except for the single-chip partitioning, the Opti sets have many features in common with the Peak/DM—not surprising, since many of the Opti founders were involved in the design of previous Chips products. The new chips, for example, support 4-Mbit DRAMs.

The essence of Opti's strategy in the excruciatingly cost-competitive SX market is to find a set of memory architecture compromises that will beat existing page-interleave chips on cost/performance. This is a trick, since the Opti sets must bear the added cost of cache SRAMs.

Opti's solution is a pair of singlechip parts with direct-map cache controllers. The high-end part, the 82C281, supports caches up to 128 kbytes and has a write buffer to slightly improve overall memory performance. This device is priced at \$35 (10,000s). This should yield a system cost, after adding a peripheral controller, cache and tag SRAMs and TTL buffers, lower than that of a standard SX chip set with an external cache controller.

The low-end chip, the 82C282, leaves out the write buffer but is otherwise identical. Priced at \$24.50 (10,000s), the part is intended to give system performance much better than that of page-interleaved systems, but at a very comparable system cost. Volume shipments for both sets should begin this month.

-Ron Wilson

 Chips and Technologies

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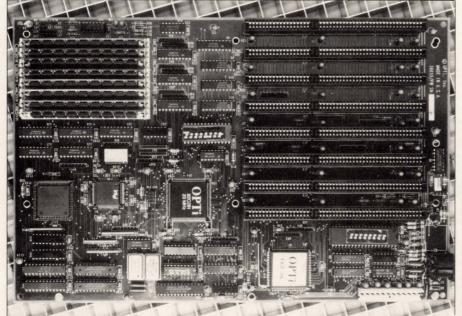
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132 SEPTEMBER 1, 1990 COMPUTER DESIGN

What's the best kept secret in the VME industry?

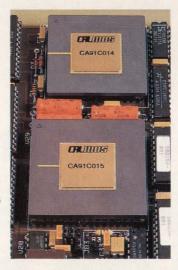


The Calmos VME chipset from Newbridge Microsystems.

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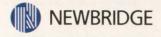
This unique VME chipset offers a versatile, complete solution. It can be used as a two chip set for a full VMEBus interface or as a single chip with external address and data bypass.

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NEW PRODUCT HIGHLIGHTS

INTEGRATED CIRCUITS

Controller expands palette for color LCDs

Now that the first laptop-sized color LCDs are moving out of the research lab and into the hands of OEMs, designers are starting to look around for color LCD controller chips. And after they wire up a controller, the designers are discovering a limitation of the new displays: most existing panels have a repertoire of only eight colors. Even the latest activematrix displays only manage 512 colors—enough for business applications, but inadequate for image-rendering or multimedia applications.

Enter Cirrus Logic, the folks who brought you 64-shade gray scale on a supposedly two-tone monochrome display. With its new CL-GD6340 LCD interface controller, the company offers a palette of several thousand discernible colors on existing LCD panels.

The chip goes between a conventional VGA controller chip and a color panel, essentially replacing the RAMDAC that would be there in a CRT-based system. Taking in the red, green, blue and sync signals from the VGA, the chip produces the unique vertical and horizontal clocks and pixel values needed by the panel. The 6340 also provides the power sequencing necessary to power up, power down and idle the panel without frying it—a delicate business with the active-matrix displays.

But the chip's real claim to fame is its color rendering—the ability to offer users 256 colors from a severalthousand-color palette in VGA mode 13. Three different techniques are used in combination to create the colors, according to Cirrus product marketing manager Mark Singer.

"The techniques are similar to what we do for gray scale on monochrome displays," Singer says. "But the active-matrix panels are much faster—everything is more critical." First, Singer says, the controller manipulates the duty cycle of the cells on the panel to obtain variations in apparent brightness. Second, as the pixels are flashing off and on, the controller can change the colors to create the appearance of different hues.

The third technique takes advantage of the fact that in VGA mode 13, each logical pixel comprises four physical pixels. So the controller can create stipple patterns—different colors in adjacent pixels of the fourpixel group—to achieve additional effects. The chip combines the techniques in a proprietary algorithm that's entirely transparent to the display software—the hardware just looks like a RAMDAC with a very large color palette.

The new chip will be sampled in the fourth quarter in a 100-pin quad flat pack. Sample price will be \$68each (100s). — Ron Wilson

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NEW PRODUCT HIGHLIGHTS

INTEGRATED CIRCUITS

Plessey joins digital synthesizer, I/Q splitter

In the nether reaches of high-precision radio-secure-channel communications, radar receivers and radio test instrumentation-digital techniques are gradually displacing analog circuitry. Already the relatively slow operations such as signal detection, windowing and spectral analysis have migrated into programmable digital signal processors or into dedicated fast Fourier transform chips, convolvers or whatever. Decimation in time and signal filtering functions has been taken over by digital filter chips. Now Plessey Semiconductors is offering another step in the process: a combination of phase accumulator, digital synthesizer and in-phase/quadrature (I/Q) splitting circuitry in a single package.

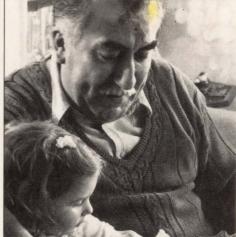
Running at sine/cosine synthesis speeds as fast as 20 Msamples/s and with resolution of .001 Hz, the PDSP16350 permits well-funded developers of precision digital receivers to go directly from digitized intermediate frequency to digital I and Q components ready for filtering and message extraction.

The PDSP16350 starts out with a 34-bit phase accumulator, which drives a cordic processor. The proces-

sor then calculates simultaneous sine and cosine waveforms with 16bit resolution. The digital waveforms are, in turn, fed to a pair of 16-bit multipliers where the sine and cosine components can be applied to an incoming signal. The resulting pair of product waveforms is then fed to the chip outputs.

There's sufficient flexibility built into the part to permit its use in AM, FM or PM environments, according to Plessey. It can serve as a signal generator, modulator or demodulator. Combined with other Plessev DSP building blocks such as dual FIR filters, FFT and Pythagorean processors or convolvers, it can form the basis of a very compact highresolution digital radio system. The CMOS PDSP16350 comes in an 84pin pin grid array package and is available in production quantities for \$395 each (1.000s). A 132-pin ceramic quad flat pack version will be available in the fourth quarter. -Ron Wilson

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RAMDAC supports multiple windows with different color maps

A new true-color window RAMDAC allows applications with different color map requirements to run in multiple windows on one screen. Normally, the color map information loaded in a RAMDAC's lookup tables determines the color map for the entire display screen. But high-performance workstations often need to display a 24-bit true color imaging applications in one window, for example, while at the same time running another window with only 16 colors, or with 256 colors.

To address this problem, Brooktree has announced the Bt463 CMOS window RAMDAC. The Bt463 is designed for high-performance graphics workstations and requires a 32-bit-deep frame buffer. The basic pixel word size is 28 bits, with 24 bits for color information (up to 8 bits each for red, green and blue) and 4 bits for graphic overlay. In addition, each word contains a 4-bit window-type field that's the key to changing color maps on a windowby-window basis.

The Bt463 has three 528×8 -bit color lookup tables each for red, green and blue. But these lookup tables can be partitioned to contain up to 16 different color maps, depending on the size of color map selected. The 4-bit window-type field that comes in with the pixel word determines which color map the pixel data accesses.

The window-type field in the pixel word addresses a 16×24-bit RAM array, called the window-type table, so at any one time one could theoretically have 16 (4 bits of address) types of windows. Each 24-bit window-type word in the array is divided into seven fields that determine the attributes of the window. If only 4-bit color planes (12 bits of color) are to be used, for instance, the upper 4 bits of color data in each plane can be moved down in the word via the shift field, and the rest of the pixel can be discarded. Another field specifies the number of active planes for pixel data, and another the location of overlay data, which can be anywhere in the 24-bit pixel word. And the start-address field specifies the beginning of the physical address of each individual color map within the 528×8 -bit lookup table.

Applications request color maps in the lookup tables on initialization. They also assign window-type words to the window-type array. Then they include the 4-bit address of their type word with the pixel data they store in the frame buffer. As each pixel comes in, its color map is automatically selected based on the window-type information that's associated with it. So color maps are actually selected on a pixel-by-pixel basis. As users size a window, they merely change the boundaries of frame buffer addresses where the pixel data for that window's application is stored; there's no need to change any value in the RAMDAC.

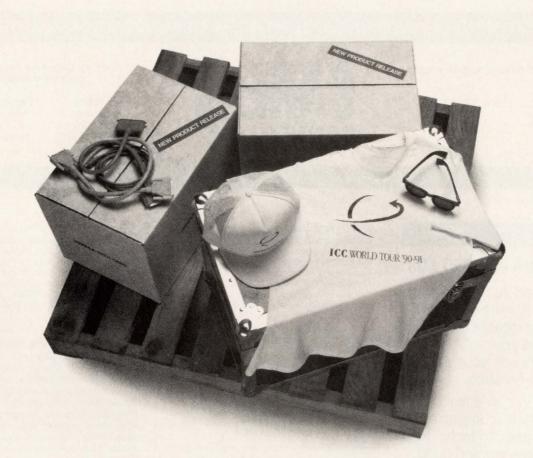
The Bt463 will be available in three speed versions: 110, 135 and 170 MHz. It comes in a 169-pin PGA package. Availability is scheduled for fourth quarter of 1990. Pricing for the 135-MHz part is projected to be \$317 (100s).

-Tom Williams

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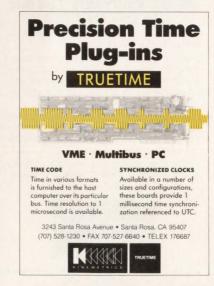
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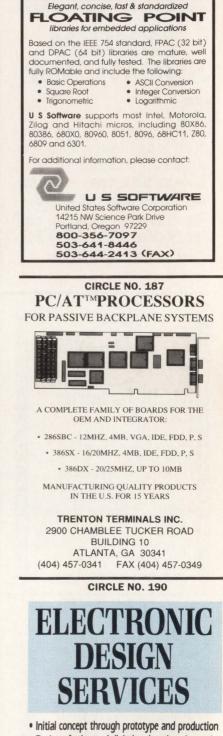
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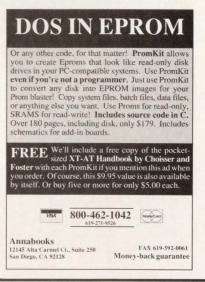


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